

## Part I: Oscillations and Mechanical Waves.

Any particle with a simple restoring force will result in simple harmonic motion:

$$F = -kx \Rightarrow x(t) = A \cos(\omega t + \phi)$$

$$\omega = \sqrt{\frac{k}{m}}$$

Q1 How do you know?

$$F = ma = -kx \rightarrow m \frac{d^2x(t)}{dt^2} = -kx(t)$$

$$\text{try } x(t) = A \cos(\omega t + \phi)$$

$$-m A \omega^2 \cos(\omega t + \phi) = -k A \cos(\omega t + \phi)$$

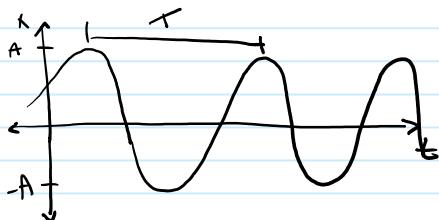
$$A \omega^2 \cos(\omega t + \phi) = \frac{k}{m} A \cos(\omega t + \phi)$$

$$A \omega^2 \cos(\omega t + \phi) = A \omega^2 \cos(\omega t + \phi) \checkmark$$

This kind of force (and hence this kind of motion) is extremely common.

- atoms in a solid
- diatomic molecules
- any elastic motion → (bridges, buildings)

$\omega$  is called the angular velocity of the particle and  $\phi$  is the phase constant.



The Measures of a wave :

- (1) The period : time for a particle to come back to its original position.

$$x(t) = x(t+T)$$

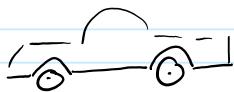
$$\Rightarrow \omega(t+T) - \phi - (\omega t + \phi) = \omega T$$

$$T = \frac{2\pi}{\omega}$$

(2) The frequency: # of cycles per unit time.

$$T = \frac{\text{time}}{1 \text{ cycle}} \Rightarrow f = \frac{1}{T}$$

Example:



$$m_{\text{car}} = 1500 \text{ kg}$$

$$k = 10 \text{ kN/m}$$

$$m_{\text{people}} = 2 \times 160 \text{ kg}$$

↑

4 springs.

Find the frequency of vibration after the car drives over a pothole in the road:

$$F = \sum(-kx) = -(\sum k)x$$

$$k_{\text{eff}} = 80 \text{ kN/m}$$

$$m = 1960 \text{ kg}$$

$$\Rightarrow f = \frac{1}{2\pi} \sqrt{\frac{k_{\text{eff}}}{m}} = 1.18 \text{ Hz}$$

### Energy of a Harmonic Oscillator

$$E = \frac{1}{2} kA^2$$

how do we know?

#1) at the peak amplitude  $x=A$ , there is no velocity so the energy is all potential

$$E = \frac{1}{2} kx^2 = \frac{1}{2} kA^2$$

#2) At the  $x=0$  (equilibrium position), there is only kinetic energy:

$$\begin{aligned} E &= \frac{1}{2} m v^2 = \frac{1}{2} m \left( \frac{d}{dt} [A \cos(\omega t + \phi)] \right)^2 \\ &= \frac{1}{2} m (-A \omega \sin(\omega t + \phi))^2 \\ &\quad -1 \text{ at } x=0 \end{aligned}$$

$$= \frac{1}{2} m \omega^2 A^2$$

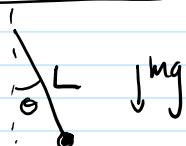
$$= \frac{1}{2} kA^2$$

In general,  $E = \frac{1}{2}mv^2 + \frac{1}{2}kx^2$

$$\begin{aligned} E &= \frac{1}{2}m\omega^2 A^2 \sin^2(\omega t + \phi) + \frac{1}{2}kA^2 \cos^2(\omega t + \phi) \\ &= \frac{1}{2}kA^2 (\sin^2(\omega t + \phi) + \cos^2(\omega t + \phi)) \\ \boxed{E = \frac{1}{2}kA^2} \quad &\therefore \end{aligned}$$

Other examples of Simple Harmonic Motion:

The Pendulum:



$$\frac{d^2\theta}{dt^2} = -\frac{g}{L}\theta \Rightarrow \boxed{\omega = \sqrt{\frac{g}{L}}}$$

$$\Rightarrow \boxed{T = \frac{2\pi}{\omega} = 2\pi\sqrt{\frac{L}{g}}}$$

\*\* the Physical Pendulum



$$\omega = \sqrt{\frac{mgd}{I}}$$

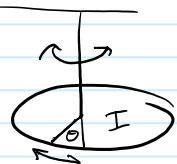
$I$  = moment of inertia

$m$  = total mass

$d$  = distance from axis to CoM.

\*\* Torsional Pendulum

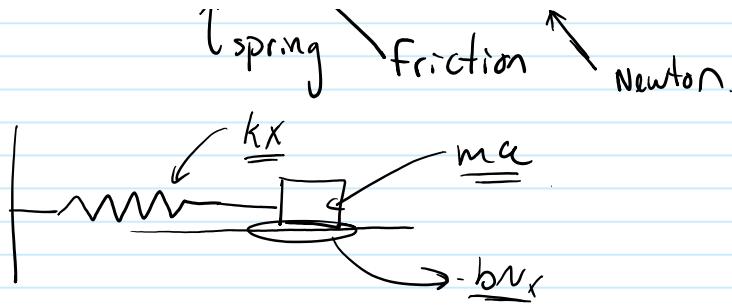
$$\omega = \sqrt{\frac{K}{I}}, \quad T = 2\pi\sqrt{\frac{I}{K}}$$



Damped Oscillations

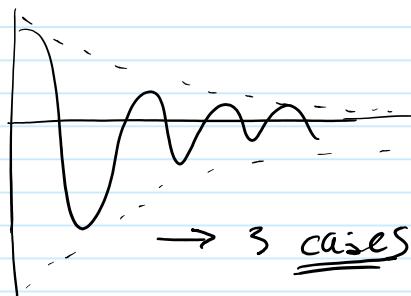
If there is a damping force as well as a restoring force  
the motion becomes "damped oscillation"

$$\boxed{F = -kx - bv_x = ma_x}$$



What is the final motion?

$$x(t) = A e^{(-\frac{b}{2m}t)} \cos(\omega t + \phi)$$



$$\omega = \sqrt{\frac{k}{m} - \left(\frac{b}{2m}\right)^2}$$

$\rightarrow$  3 cases ① if  $\frac{k}{m} > \left(\frac{b}{2m}\right)^2$

\* underdamped  $\rightarrow \omega$  is real

② if  $\frac{k}{m} < \left(\frac{b}{2m}\right)^2$   $\rightarrow \omega$  is imaginary

$\rightarrow$  \* overdamped

③  $\frac{k}{m} = \left(\frac{b}{2m}\right)^2 \rightarrow$  critically damped

### Forced Oscillation

If a particle is additionally driven with a force

$F = F_0 \sin(\omega t)$ , we find, again, simple harmonic motion.

$$x(t) = A \cos(\omega t + \phi)$$

Now, the amplitude is a function of the driving force:

$$A = \frac{F_0/m}{\sqrt{(\omega^2 - \omega_0^2)^2 + \left(\frac{b\omega}{m}\right)^2}}$$

Importantly, this amplitude is largest for a special  $\omega$ .

$$\boxed{\omega = \omega_0}$$

this is

$\text{---} \quad (\text{m})$

$$w = w_0$$

this is  
called reference

## Wave Motion

Two types:

Transverse: disturbance perpendicular to dir. of travel

Ex: light, ocean wave

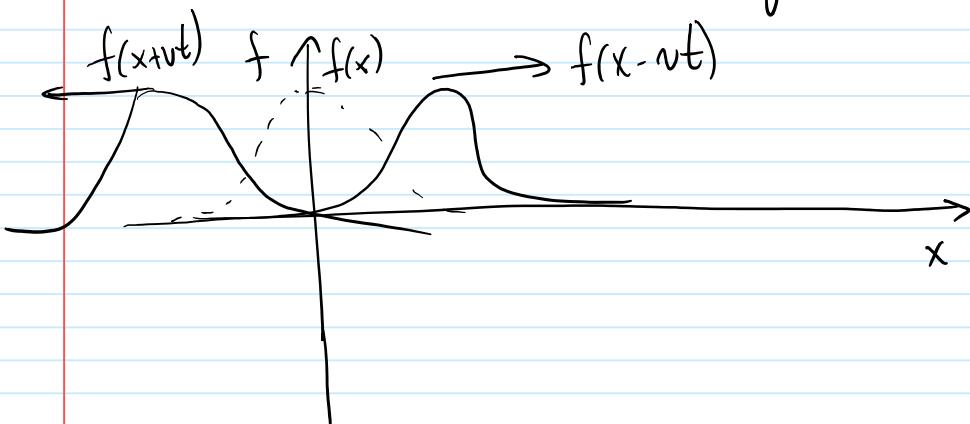
Longitudinal: disturbance parallel to dir. of travel

Ex: compressive wave, sound (sometimes),

Expressed as a function of  $\vec{x}$  and  $t$ :

$f(x-vt)$   $\Rightarrow$  forward moving (right)

$f(x+vt)$   $\Rightarrow$  backwards moving (left)



## Travelling Waves

$$f(x,t) = A \sin(kx - \omega t) + \text{phase...}$$

all of the terminology:

$v$ : velocity

II

v: velocity

k: angular wavenumber

λ: wavelength

ν: wavenumber

w: angular frequency

T: period

f: frequency

The key idea is that the spatial parts and temporal parts are linked by

$$v = \frac{\lambda}{T}$$

### Waves on Strings

the velocity of waves on strings:  $v = \sqrt{\frac{T}{\mu}}$

$\mu$  = mass density

T = tension density

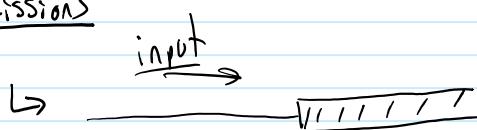
### reflections

↳ at a hard boundary, the pulse on a string is inverted on reflection.

↳ at an "open boundary", the pulse on a string is not inverted

→ the same is true for light

### Transmissions



$\leftarrow$  rect  $tct$

Power Transmitted

$$P = \frac{1}{2} \mu \omega^2 A^2 v$$

Compare with  $E = \frac{1}{2} m \omega^2 A^2 / \theta$  for  
one oscillator

The Wave Equation

$$\nabla^2 f = \frac{1}{v^2} \partial_t^2 f$$

## Sound Waves

Example of a longitudinal wave in pressure.

$$\Delta P(x, t) = \Delta P_{\max} \sin(kx - \omega t + \phi)$$

The velocity  $v$  is  $v = \sqrt{\frac{B}{\rho}}$   $B$  = bulk modulus  $\rho$  = volume density

## Wave Intensity

$$I \equiv \frac{P_{\text{avg}}}{A} \rightarrow I = \frac{P_{\text{avg}}}{\pi r^2}$$

↑ spherical ray

## Decibels

$\beta$ , the sound level is quantity that describes the loudness on a logarithm scale:

$$\beta = 10 \log \left( \frac{I}{I_0} \right)$$

Why a log scale? Human perception seems to work multiplicatively instead of additively.

$I_0$  is the threshold of hearing.

$$I_0 = 1.00 \times 10^{-12} \text{ W/m}^2$$

### Doppler Shift

$$\left| \begin{array}{l} f' = \left( \frac{v}{v - v_s} \right) f \\ \quad \quad \quad \leftarrow (\text{moving towards observer}) \end{array} \right.$$
  

$$\left| \begin{array}{l} f' = \left( \frac{v}{v + v_s} \right) f \\ \quad \quad \quad \leftarrow (\text{moving away from observer}) \end{array} \right.$$

generally

$$f' = \left( \frac{v + v_o}{v - v_s} \right) f$$

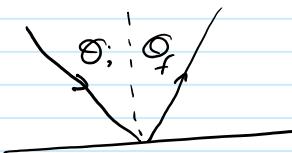
$v_o$  = observer velocity  
 $v_s$  = source velocity

## Part II - Light and Optics

### Ray Optics

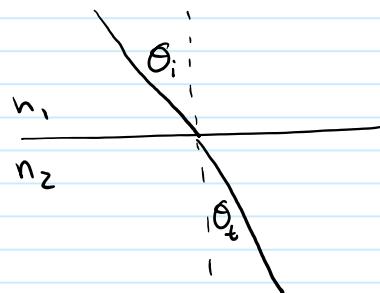
Law of reflection:

$$\theta_i = \theta_f$$



Snell's Law

$$n_1 \sin \theta_i = n_2 \sin \theta_2$$



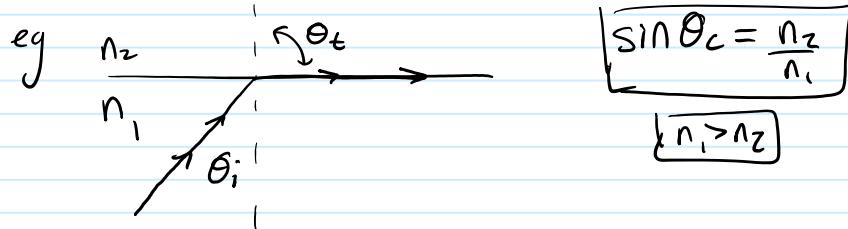
$n$  = index of refraction

$$n = \frac{c}{\lambda}$$

In general, ' $n$ ' is function of the wavelength, leading to a phenomena called 'dispersion'.

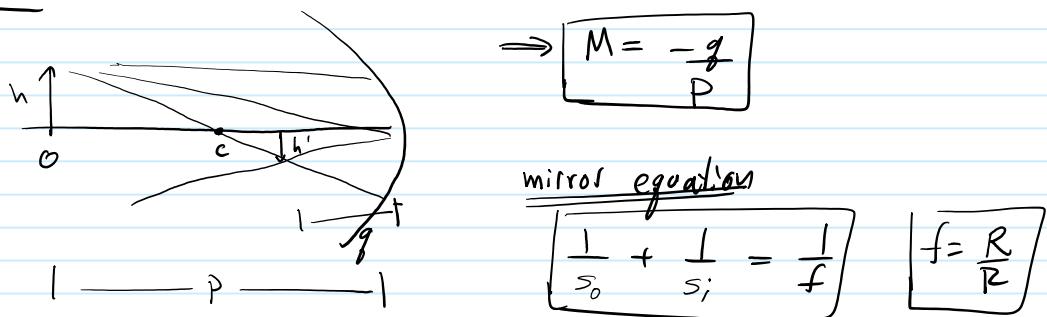
## Total internal reflection

Light travelling from high to low index media can be completely reflected back into the media. This happens when  $\theta_t = 90^\circ$



## Imaging

### Mirrors



### Ray Diagrams

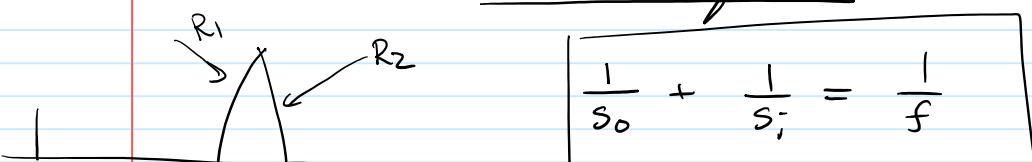
- (1) Parallel ray  $\rightarrow$  through focus
- (2) Ray through ray  $\rightarrow$  out parallel
- (3) Ray through center  $\rightarrow$  straight

↑ center of curvature for mirror  
center of lens for lens.

### Lenses

$$\frac{n_1}{s_0} + \frac{n_2}{s_1} = \frac{n_2 - n_1}{R}$$

$\Rightarrow$  lens maker's equation



$$\frac{1}{s_o} + \frac{1}{s_i} = \frac{1}{f}$$

$$f = (n-1) \left( \frac{1}{R_1} - \frac{1}{R_2} \right)$$

### Adding lenses

$$\rightarrow \frac{1}{f_{eq}} = \frac{1}{f_1} + \frac{1}{f_2}$$

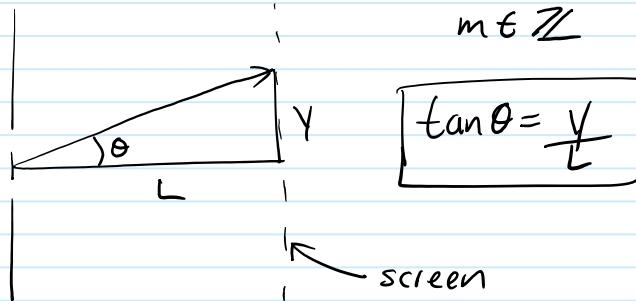
### Wave Optics

#### Young's Double Slit

$$d \sin \theta_{bright} = m\lambda$$

$$d \sin \theta_{dark} = (m + \frac{1}{2})\lambda$$

$\delta \rightarrow$  path difference



#### Intensity

$$I = I_{max} \cos^2 \left( \frac{\pi d \sin \theta}{\lambda} \right)$$

### Thin film interference

#### Constructive

$$2t = (m + \frac{1}{2})\lambda_n$$

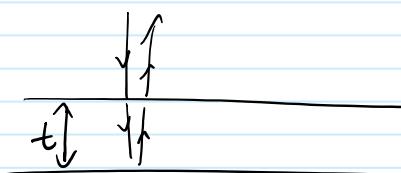
$m = 0, 1, 2, \dots$

#### Destructive

$$2t = m\lambda_n$$

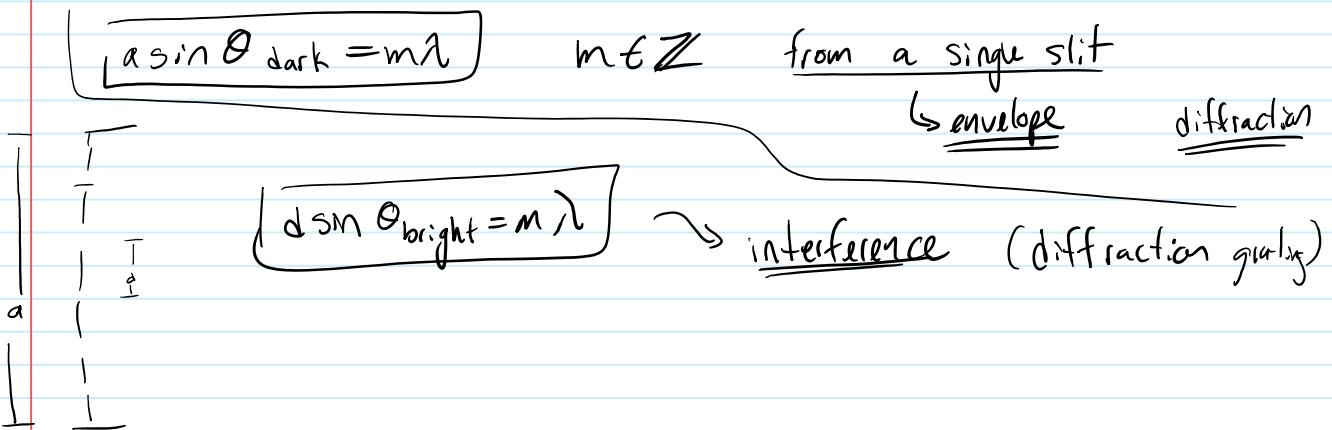
$m = 0, 1, 2, \dots$

$$\lambda_n = \lambda n$$



## Diffraction Patterns and Polarization

### Diffraction Grating



## Part III - "Modern Physics"

### Relativity

$$\begin{aligned} L(v) &= L(0) \sqrt{1 - v^2/c^2} \\ T' &= T \left(1 - \frac{v}{c}\right) \end{aligned}$$

- (1) physics does not depend on velocity of frame
- (2) the speed of light is always " $c$ ".

$$E = mc^2 \quad \text{at rest}$$

### Quantum Mechanics

$$\text{Photons} : E = h\nu = \text{energy of photon}$$

$$E = pc = hf$$

$$p = \frac{h}{\lambda}$$

$$\lambda = \frac{h}{p} \quad \text{deBroglie}$$

### Photo Electric

$$\{ e^- \}$$

$$\frac{1}{2}mv^2 = hf - W$$

Work function

$$\frac{1}{2} \text{ MeV} = h\nu - W$$

Work function

### Blackbody Radiation

$$n(f, T) = \frac{8\pi f^2}{c^3} \frac{hf}{\exp\{hf/k_B T\} - 1}$$

### Bohr Atom

$$E_n = -\frac{\hbar^2}{2ma_0^2} \frac{Z^2}{n^2}$$

$$R_n = \frac{n^2}{Z} a_0$$

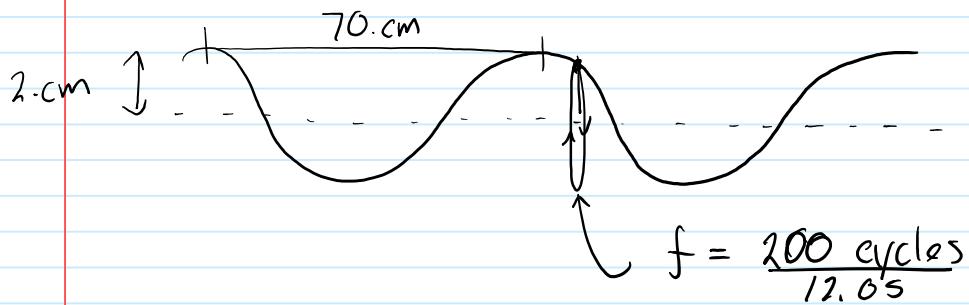
$$a_0 = \frac{\hbar}{mc\alpha}$$

$$\alpha = \frac{e^2}{4\pi\epsilon_0\hbar c}$$

$$E_n = -\frac{1}{2} m \frac{(Z\alpha c)^2}{n^2}$$

## Examples

### Dawson #1



$$\text{a) } V = ? \quad V = \frac{\lambda}{T} \quad T = \frac{12.05}{200 \text{ cycles}} \quad \lambda = 70.0 \text{ cm}$$

$$\Rightarrow V = 8.571 \text{ cm/s}$$

What is the maximum transverse speed?

at a point x

$$x(t) = A \cos(\omega t + \phi)$$

what is  $\omega$ ?

$$\hookrightarrow T = \frac{2\pi}{\omega} \Rightarrow \omega = \frac{2\pi}{T}$$

$$\hookrightarrow \omega = 0.377 \text{ rad/s}$$

$$\hookrightarrow v(t) = -A\omega \sin(\omega t + \phi)$$

$$v_{\max} = A\omega = 2.0 \text{ cm} * 0.377 \text{ rad/s}$$

$$\boxed{v_{\max} = 0.754 \text{ cm/s}}$$

b) Explain

$$\text{c) } \omega = \sqrt{\frac{F}{m}} \rightarrow \mu = \frac{F}{m} = \underline{\text{answer}}$$

U)  $\omega = \sqrt{\mu}$

c)  $w = \sqrt{\frac{F}{\mu}} \rightarrow \mu = \frac{F}{w^2} = \underline{\text{answer}}$

d)  $P = \frac{1}{2} \mu w^2 A^2 V$

Multiple Choice