

Comparing the Effectiveness of the Choropleth Map with a Hexagon Tile Map for Communicating Cancer Statistics

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Abstract—The choropleth map display is commonly used for communicating spatial distributions across geographic areas. However, when choropleths are used, the sizes of areas can lead to misinterpretation of the distribution. The visualisation method used to present geospatial data will influence the understanding of the distribution derived by map users. Choosing an effective alternative display could positively influence the communication of the spatial distribution. The hexagon tile map is presented as an alternative display for effectively visualising population related distributions. Visual inference is used to measure the power of design, and the choropleth is used as a comparison. The hexagon tile map display is also tested using a distribution that is directly related to the geography, with values monotonically decreasing from the North West to South East areas of Australia. This study finds the single map in a hexagon tile map lineup that contains a population related distribution is detected with greater probability than the same data displayed in a choropleth map. These findings should encourage map creators to implement alternative displays, and consider a hexagon tile map when presenting spatial distributions of heterogeneous areas.

Index Terms—statistics; visual inference; geospatial; population

I. INTRODUCTION

This study compares the effectiveness of a new type of display, a hexagon tile map, against the standard, a choropleth map, for communicating information about disease statistics. The choropleth map is the traditional approach for visualising aggregated statistics across administrative boundaries. A hexagon tile map forgoes the familiar boundaries, in favor of representing each geographic unit as an equally sized hexagon, placed approximately in the correct spatial location. The hexagon tile map builds on existing displays, such as the cartogram, and tessellated hexagon displays. It differs in that it relaxes the requirement to have connected hexagons, and allows sparsely located hexagons. The algorithm to construct a hexagon tile map is available in the R package *sugarbag* [1]. This type of display may be useful for other countries, and other purposes.

The hexagon tile map was designed for Australia, motivated by a need to display spatial statistics for a new Australian Cancer Atlas. None of the existing approaches for creating

cartograms or hexagon tiling perform well for the Australian landscape, which has vast open spaces and concentrations of population in small regions clustered on the coastlines.

The Australian Cancer Atlas [2] is an online interactive web tool created to explore the burden of cancer on Australian communities. There are many cancer types to be explored individually or aggregated. The Australian Cancer Atlas allows users to explore the patterns in the distributions of cancer statistics over the geographic space of Australia. It uses a choropleth map display and diverging colour scheme to draw attention to relationships between neighbouring areas. The hexagon tile map may be a useful alternative display for the atlas.

The experiment was conducted using the lineup protocol, a visual inference procedure [3], to objectively test the effectiveness of the two displays.

The paper is organised as follows. The next section discusses the background of geographic data display and visual inference procedures. The Methodology Section describes the methods for conducting the experiment and analysing the results. The results are summarized in Section Results.

II. BACKGROUND

A. Population focussed displays

Spatial visualisations communicate the distribution of statistics over geographic space. The most common display for spatial data is the choropleth map. It is used to present aggregated statistics for geographic units such as the population. Creating a choropleth map involves drawing the administrative boundaries and filling them with colour to communicate the value of the statistic. However, using a choropleth map base introduces biases when considering population related distributions [4]. Many sets of Australian statistical areas have a large disparity between the smallest and largest units. The rural communities in Australia operate on a much larger geographic space than small inner-city communities. When a spatial distribution is related to the size of the areas, or the population density, the size of the regions can allow erroneous conclusions to be drawn about the state of the statistic over the entire population,

when presenting the statistics on a geographic map base. This occurs as large regions filled with a consistent colour or pattern can draw the attention of map readers, and small regions are not paid equal attention [5]. An alternative display can be used to honestly communicate a spatial distribution for a set of heterogeneous areas [6]. This work aims to show that a hexagon tile map display is a viable alternative to the geographic map base for presenting population statistics.

A choropleth map is not the only display that can be used for presenting geospatial data. Alternative maps include various cartograms and tessellated tile maps. They allow other variables to be incorporated in the display to highlight the statistical values of various geographic areas.

A cartogram transforms the geographic map base. The transformation begins with a choropleth map, and the values of a statistic such as population, for each geographic unit. There are several algorithms for transformation [7], [4]; they involve shifting the boundaries of geographic units, using the value of the statistic to increase or decrease the area taken by the geographic unit on the map. The changes to the boundaries result in cartograms that accurately communicate population by map area for each of the geographic units. The transformation will keep boundaries of neighbouring areas connected, but the result is unfamiliar shapes for each geographic unit.

Alternative displays make the trade off between familiar shapes and representation of variables using the area of geographic units. The non-contiguous cartogram method [8] keeps the shapes of geographic units intact, and change the size of the shape to communicate the values of statistics. This method disconnects areas when shrinking boundaries, and breaks the spatial relationship between areas. However, the empty space created emphasises the comparative density of the statistic, the difference between the statistic and the amount of land for each geographic unit. The Dorling cartogram [7] is another method that does not retain the boundaries of geographic units. Each unit becomes one circle on the cartogram display; the circles are sized according to the value of a the statistic, such as population. The neighbour relationships can be illustrated by connecting the boundaries of the circles. A similar approach was pioneered by Raisz [9], using rectangles that tile to align borders of neighbours [10]. These cartogram methods all allow two variables to be shown in the single display. These methods are discussed further in XXX cite review paper.

Australia is an extreme case of heterogenous geographic units, with large difference between the smallest and largest geographic units across various granularities. To communicate information regarding the small inner-city geographic units of Australian cities an alternative display must be employed. This will emphasise the value of the statistic for areas with high population. Fig. 1 shows the distribution of the smoothed average amount of Liver cancer diagnoses for Australian Males from 2005-2014. These inner-city areas are not visible on the choropleth map (a). The hexagon tile map (b) shows orange hexagons for the inner-city SA2s with higher than average levels of diagnoses in the capital cities of Melbourne and Sydney. The northern Queensland, and Northern Territory

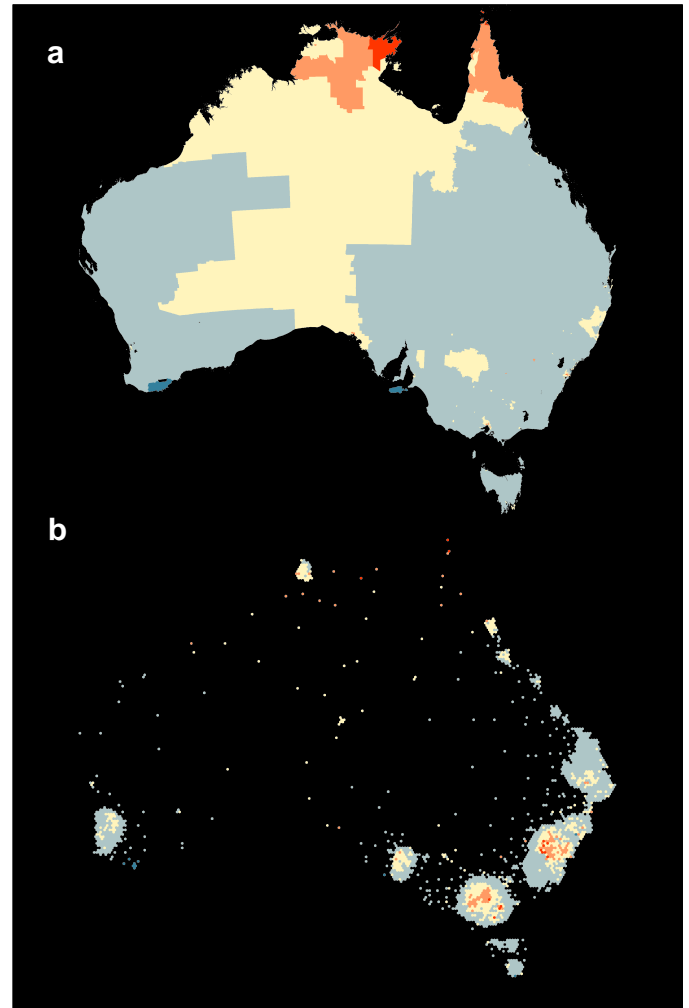


Fig. 1. The smoothed average of liver cancer diagnoses for Australian males. The diverging colour scheme shows dark blue areas with much lower than average diagnoses, yellow areas with diagnoses around the Australian average, orange with above average and red shows diagnoses much higher than average.

SA2's with higher than average rates are still visible but use less map space on the hexagon tile map. There are still many light blue areas in both displays.

B. Visual Inference

The hexagon tile map is suggested as an alternative display. To test the effectiveness of these displays there is a formal testing framework. Visual inference considers the communication of data or data summaries through visualisations. It considers these visualisations to be visual statistics, with observable features.

Classical statistical inference involves hypothesis testing, the process of rejecting a null hypothesis in favour of an alternative. This approach requires appropriate data, with the appropriate distributions and their assumptions. The lineup protocol was formalised as a test for the effectiveness of a visualisation. Rather than use classical statistical tests, human participants are tasked with finding the display that shows

structure between the variables. If the structure is not detected, then it is not significantly different from the null data.

Visual inference uses the general hypothesis structure:

- Null hypothesis: There is NO relationship between the variables,
- Alternative hypothesis: There is a relationship between the variables.

To test these hypotheses, the lineup protocol randomly places a “guilty” data visualisation in a lineup of “innocents”. Where the guilty data set contains structure, and the innocents data sets do not. In a grid of visualisations, an observer is asked to pick the display that is most different, if they select the data set containing structure, they have identified the guilty hidden within the innocents [11]. The guilty data is identified as different from the innocent data with probability $1/m$, where m is the number of null plots plus 1 to account for the guilty data set. When the guilty data set is chosen, the null hypothesis that it was innocent is rejected with a $1/m$ chance or type I error of being wrong.

The lineup protocol can be used in a variety of testing scenarios for visualisations. [3] suggest the choropleth map for testing spatial structure in a data set. The lineup protocol allows for flexibility in the definition of null data. In the case of spatial visualisations it is likely that neighbours are related to some degree. To account for this, null data sets can be generated by sampling from a known model that accounts for spatial covariance.

To contrast the effectiveness of two displays, the data set of null data plots with a hidden real data plot can be produced using the different plot designs. The time taken by participants to evaluate the same data in the different displays can be compared. Their accuracy in detecting the real data plot can also be calculated and contrasted.

III. METHODOLOGY

This study aimed to answer two key questions around the presentation of spatial distributions:

1. Are spatial disease trends, that impact highly populated small areas, detected with higher accuracy when viewed in a hexagon tile map display?
2. Are people faster in detecting spatial disease trends, that impact highly populated small areas, when using a hexagon tile map display?

Additional considerations when completing this experimental task included exploration of the difficulty experienced by participants, and the certainty they felt about their decision.

The mean of the detection rate for choropleth map, denoted as μ_C , and the hexagon tile maps, μ_H will be contrasted. This leads to the following one sided hypothesis:

$$H_0 : \mu_H = \mu_C \quad H_a : \mu_H > \mu_C$$

The detection rate $\hat{\pi}$ is calculated as the amount of people that made the choice of plot that contained the real data, out of the participants who saw data plot in the lineup of the null data plots.

The difference in the detection rates for the two displays will be compared using a two sample unpaired t-test.

A. Participants

Participants were recruited for a survey style task to test the effectiveness of the hexagon tile map display. It was expected that the participants were uninvolved judges that had no prior knowledge of the data, to avoid discrimination or advantages. The Figure-Eight crowd source platform was used to advertise the survey to potential participants that had achieved level 2 or level 3 on the Figure-Eight Platform. The participants were chosen as they have experience with survey tasks that involve evaluating images. They participants on the platform are also required to be at least 18 years old.

Participants were able to choose to participate by selecting this task from the list of tasks available to them. There were 95 participants involved in the study. All of these participants read the introductory materials and viewed example questions before proceeding to the survey. Each participant was trained using three test displays orienting them to the evaluation task, these displays are shown in appendix section regarding [training]. All participants who volunteered to take part were compensated for their time via the payment system of Figure-Eight.

Participants were allocated to either group A or group B when they proceeded to the survey web application, hosted externally from the Figure-Eight website.

B. Variables

The variables that were changed between groups were the type of plot shown and the trend model.

The twenty-four lineup displays were created by a combination of map type, and spatial trend model. This set of displays was split into a collection of twelve displays for Group A and twelve displays for Group B.

Each participant was randomly allocated to either Group A or Group B when they began the survey. This resulted in 42 participants allocated to Group A, and 53 participants allocated to Group B.

The levels of the factors measured in the experiment were:

- Map type: *Choropleth, Hexagon tile*
- Trend: *Locations in three population centres, Locations in multiple population centres, South-East to North-West*

Each Group did not see the same data for both map types. Four simulated sets of data were generated for each treatment. This will generate twenty-four lineups (twelve lineups of geographic maps, and twelve lineups of hexagon tile maps). Participants evaluated twelve lineups, six of each map type. For each of the six geographic displays and six hexagon displays, two of each trend model were shown to participants. The design is outlined in Table. I.

The variables measured as a result of the changes were the probability of detection each display and the time taken to submit responses. To measure the accuracy of the detections, the plot chosen for each lineup evaluated was compared to the position of the real spatial trend plot in the lineup. A correct result occurs when the chosen plot matches the position of the real plot, this was recorded in an additional binary variable; 1

TABLE I
THE EXPERIMENTAL DESIGN RESULTS IN THE FOLLOWING ALLOCATION
OF REPLICATE DATA SETS WITHIN EACH TREND MODEL TO GROUPS A
AND B.

Group	Trend	Choro.	Hex.
A	NW-SE	1, 2	3, 4
	Three Cities	1, 2	3, 4
	All Cities	2, 4	1, 3
B	NW-SE	3, 4	1, 2
	Three Cities	3, 4	1, 2
	All Cities	1, 3	2, 4

= correct; 0 = incorrect. High efficiency occurs when a small amount of time is taken to evaluate each lineup. This will be measured as the numeric variable measuring the length of time taken to submit the answers to the evaluation of each line up.

C. Simulation process

The lineup protocol allows a known model to be imposed on the null data set plots. The underlying spatial correlation model was created to provide spatial autocorrelation between neighbouring areas using the longitude and latitude values for the Statistical Areas.

$$z = 1$$

$$locations = longitude + latitude$$

The null model imposed suggests that neighbours are related. The randomness imposed was smoothed to mirror the practice taken by the Australian Cancer Atlas. This smoothing allowed neighbours to be related to each other and show distributions similar to the Liver cancer distribution shown in 1.

Spatially dependent data sets were simulated using the variogram model on the centroids of each geographic unit. Twelve simulations from the variogram model were created for each of the twelve lineups.

In these 12 sets of data, each of the 144 maps were smoothed several times to replicate the spatial autocorrelation seen in cancer data sets presented in the Australian Cancer Atlas.

For each of the 144 individual maps, the values attributed to each geographic area are rescaled to show a similar colour scale from deep blue to dark red within each map.

A random location was selected for each set of lineup data. In this location, a trend model was overlaid on the null set of spatially correlated data. Each set of lineup data was used to produce a choropleth maps and hexagon tile maps. These matched pairs were split between Group A and Group B.

D. Experiment procedure and data collection

The participant answered demographic questions and provided consent before evaluating the lineups.

Demographics were collected regarding the study participants:

- Gender (female / male / other),
- Degree education level achieved (high school / bachelors / masters / doctorate / other),
- Age range (18-24 / 25-34 / 35-44 / 45-54 / 55+ / other)
- Lived at least for one year in Australia (Yes / No)

Participants then moved to the evaluation phase. The set of images differed for Group A and Group B. After being allocated to a group, each individual was shown the 12 displays in randomised order.

Three questions were asked regarding each display:

- Plot choice
- Reason
- Difficulty

After completing the 12 evaluations, the participants were asked to submit their responses.

Data was collected through a web application containing the online survey. Each participant used the internet to access the survey. The data collection took place using a secure link between the survey web application and the googlesheet used to store results. The application would first connect to the googlesheet using the googlesheets [12] R package, and interacted again at the completion of the survey by adding the participant's responses to the 12 displays as 12 rows of data in the googlesheet.

E. Experimental design

The choropleth map was used as the comparative visualisation for presenting the lineups [13] as this is the common display for spatial cancer data. Geographic distributions usually have some degree of spatial autocorrelation between neighbours. This feature was incorporated in all maps shown in the lineup displays, the map that contained the trend feature shown in only one set of data was also affected by spatial autocorrelation. A line up protocol was implemented to arrange N maps in each display. A reasonable amount of null plots $N - 1$ in the lineup was chosen to ensure the real data map was well hidden. A reasonable number of plots to show in each lineup, $N = 12$ was chosen to not overwhelm participants due to the detailed choropleth maps of Australian SA3 areas.

The hypotheses for each lineup are H_0 : All plots look the same H_a : One plot looks different to the other plots

The same data was visualised on a choropleth map, and on a hexagon tile map, however in this study the participants only saw one of these two displays. The accuracy and times taken were aggregated for Groups and. Comparing the results of participants who see the choropleth to those who see a hexagon tile map will show that population related distributions are spotted more frequently in a hexagon tile map display.

Let n be the number of independent observers and x_i the number of observers who picked plot i , $i = \{1, \dots, m\}$

Then x_1, x_2, \dots, x_m follows a multinomial distribution $Mult_{\pi_1, \pi_2, \dots, \pi_m}(x_1, x_2, \dots, x_m)$ with $\sum_i \pi_i = 1$,

where π_i is the probability that plot i is picked by an observer, which we can estimate as $\hat{\pi}_i = x_i/n$. The researchers compared the length of time taken, and the accuracy of the participants choices. The power of a lineup can therefore be estimated as the ratio of correct identifications x out of n viewings.

F. The methods of data analysis used

The data analysis methods used in order to analyse and collate the results included downloading the survey submissions and opening them into the analysis software R [14].

For each of the 12 lineup displays the researchers calculated:

- accuracy: the proportion of subjects who detected the data plot
- efficiency: average time taken to respond

1) *Visualisations*: Side-by-side dot plots were made of accuracy (efficiency) against map type, faceted by trend model type.

Similar plots were made of the feedback and demographic variables - reason for choice, reported difficulty, gender, age, education, having lived in Australia - against the design variables.

Plots will be made in R (R Core Team 2019), with the ggplot2 package (Wickham 2016).

2) *Modeling*: The likelihood of detecting the data plot in the lineup can be modelled using a linear mixed effects model. The R [14] `glmer()` function in the [15] package implements generalised linear mixed effect models. The model used includes the two main effects map type and trend model, which gives the fixed effects model to be:

$$\widehat{y}_{ij} = \mu + \tau_i + \delta_j + (\tau\delta)_{ij} + \epsilon_{i,j}, \quad i = 1, 2; \quad j = 1, 2, 3$$

where $y_{ij} = 0, 1$ whether the subject detected the data plot, μ is the overall mean, $\tau_i, i = 1, 2$ is the map type effect, δ_j is the trend model effect. We are allowing for an interaction between map type and trend model. Because the response is binary, a logistic model is used. This model can account for each individual participants' abilities as it includes a subject-specific random intercept. As each participant provides results from 12 lineups.

The model specifies a logistic link, this means the predicted values from the `glmer` model should be back-transformed to fit between 0 and 1. They are transformed with the link specified below:

$$\mu = \frac{e^\eta}{1 + e^\eta}$$

$$\eta = f(\tau_i, \delta_j)$$

The feedback and demographic variables will possibly be incorporated as covariates.

Computation will be done using R [14], with the `lme4` package [15].

G. Limitations of the data collection

A pilot study was conducted to determine whether the lineups were appropriate. All lineups in the pilot study were deemed viable as at least one participant detected the real data plot in each lineup. The demographics of the participants showed a skew towards male participants. The randomness of the group allocation also resulted in more participants being allocated to Group B. Due to the allocation of lineup displays the participants all saw six Choropleth displays and six Hexagon Tile Map displays.

IV. RESULTS

Responses from 95 participants were collected. Three participants provided no answers for any task, and their data was removed. Set A was evaluated by 42 participants, and 53 evaluated set B. This resulted in 1104 evaluations, corresponding to 92 subjects, each evaluating 12 lineups, that are analysed on accuracy and speed. The certainty and reasons of subjects in their answers is also examined.

A. Participant demographics

Of the 92 participants, 67 were male, and 25 female. Most participants (56) had a Bachelors degree, 13 had a Masters degree, and the remaining 23 had high school diplomas.

B. Accuracy

Fig. 2 displays the average detection rates for the two types of plot separately for each trend model. Each trend model was tested using four repetitions, evaluations on the same data set were seen as either choropleths or hexagon tile maps by each group as specified in Table. I; the detection rates for each display are connected by a line segment. The Three Cities and All Cities trend models shown in the hexagon tile map allowed viewers to detect the data plot substantially more often than the choropleth counterparts. One replicate for the All Cities group, had similar detection rates for both plot types, and this is discussed in the appendix [Lineups] section. Surprisingly, participants could also detect the gradual spatial trend in the NW-SE group from the hexagon tile map. We expected that the choropleth map would be superior for the type of spatial pattern, but the data suggests the hexagon tile map performs slightly better, or equally as well.

Table. II shows the means and standard deviations of the detection rate for each type of plot and each trend model. This also gives the standard errors, the smallest standard deviation for all sets of replicates is the Three Cities trend model shown in a Choropleth display. This group of displays had a very small detection rate of 0.04. The mean detection rate for the Three Cities trend model shown as choropleth map lineups was also the smallest at 0.39. The North West to South East (NW-SE) trend model unexpectedly had a higher mean detection rate for the hexagon tile map displays, but the difference in the means of detection rate was only 0.10.

Table. III presents a summary of the generalised linear mixed effects model, testing the effect of plot type and trend model on the detection rate. The results support the summary

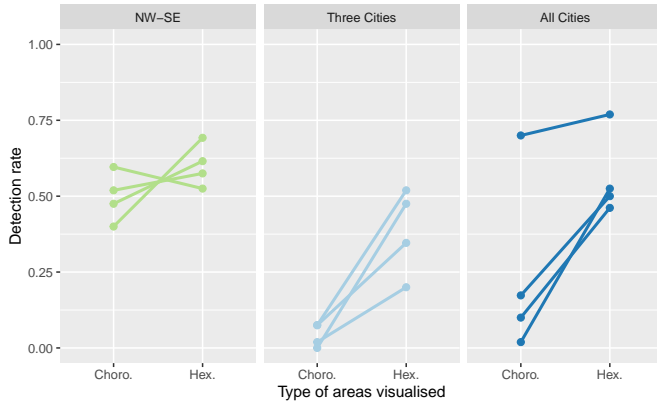


Fig. 2. The detection rates achieved by participants are contrasted when viewing the four replicates of the three trend models. Each point shows the probability of detection for the lineup display, the facets separate the trend models hidden in the lineup. The points for the same data set shown in a choropleth or hexagon tile map display are linked to show the difference in the detection rate.

TABLE II
THE RATE OF DETECTION FOR EACH TREND MODEL HAS BEEN CALCULATE FOR THE CHOROPLETH AND HEXAGON TILE MAP DISPLAYS. THE ASSOCIATED STANDARD ERRORS ARE ALSO INCLUDED.

Type	NW-SE	Three Cities	All Cities
Choro.	0.51 (0.50)	0.04 (0.19)	0.23 (0.42)
Hex.	0.61 (0.49)	0.39 (0.49)	0.57 (0.50)

from Fig. 2 and all terms are statistically significant despite the large standard deviations observed in Table. II. Overall, the hexagon tile map performs marginally better than the choropleth for all trend models, which is a pleasant surprise. Allowing for the interaction effect, the difference in detection rate decreases for population related displays for a choropleth map lineup, but increases for a hexagon tile map display. The log odds of detection show in Table. III can be back transformed using III-F2 after taking the sum of all terms for the trend and type of display that are of interest. For the NW-SE distribution, the predicted detection rate for the hexagon tile map display increases the predicted probability of detection to 0.62 from 0.51 for choropleths, this is almost exactly the difference seen in the table of means and is significant only at the 0.05 level.

When a choropleth map display is used, the predicted detection rate for the Three Cities trend, 0.03; this is extremely low, especially compared to the NW-SE trend of 0.51. When the All Cities trend is presented in a choropleth display the predicted probability of detection is 0.21. The hexagon tile map has a substantially high detection rate for the display of a Three Cities trend 0.38 and All Cities trend 0.58.

TABLE III
THE MODEL OUTPUT FOR THE GENERALISED LINEAR MIXED EFFECT MODEL FOR DETECTION RATE. THIS MODEL CONSIDERS THE TYPE OF DISPLAY, THE TREND MODEL HIDDEN IN THE DATA PLOT, AND ACCOUNTS FOR CONTRIBUTOR PERFORMANCE.

Term	Est.	Sig.	Std. Error	P val
Intercept	0.02		0.17	0.90
Hex.	0.46	*	0.22	0.04
Three Cities	-3.43	***	0.42	0.00
All Cities	-1.35	***	0.24	0.00
Hex:Three Cities	2.46	***	0.47	0.00
Hex:All Cities	1.17	***	0.33	0.00

C. Speed

Fig. 3 shows horizontally jittered dot plots to contrast the time taken by participants to evaluate each lineup when viewing each type of display. The time are also separated by trend model and whether the data plot was detected or not detected. The time taken to complete an evaluation ranged from milliseconds to 60 seconds. The average time taken for type of display is shown as a large colored dot on each plot. when considering the heights of the green and orange dots, there is little difference in the average time taken to read a choropleth or hexagon tile map. Comparing the same coloured dot across each trend model row, there is a slight increase in the time taken to correctly detected the data plot in the hexagon tile map lineup, but little difference in evaluation time for the choropleth display. However, there were substantially less correct detections for choropleth lineups for the Three cities and All Cities trends.

D. Certainty

Participants provided their level of certainty regarding their choice using a five point scale. Unlike the accuracy and speed of reponses that were derived during the data processing phase, this was a subjective assessment by the participant prompted by the question: 'How certain are you about your choice?'. Figure. IV-D shows the amount of times participants provided each level of certainty. This was separated for each combination of trend models and display type, and coloured depending on whether a participant correctly detected the data plot in the lineup. Participants chose 4 or 5 often when viewing the population related trends in the choropelth display, even though they were often incorrect when viewing an All Cities trend and overwhelmingly incorrect for the Three Cities trend. This shows overconfidence in their detection ability when using a choropleth map display. Participants were less likely to be certain when their choice was incorrect and they were viewing a hexagon tile map. For each trend model, participants were more likely to doubt their choice and choose 1 or 2 in the hexagon tile map displays, even though many had made the correct choice.

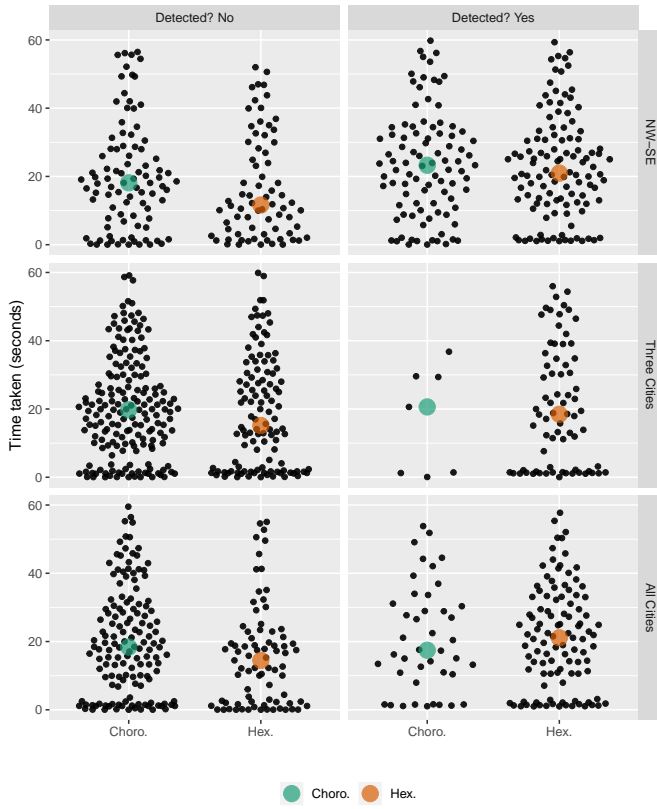


Fig. 3. The distribution of the time taken (seconds) to submit a response for each combination of trend, whether the data plot was detected, and type of display, shown using horizontally jittered dotplots. The coloured point indicates average time taken for each plot type. Although some participants take just a few seconds per evaluation, and some take as much as 60 seconds, but there is very little difference in time taken between plot types.

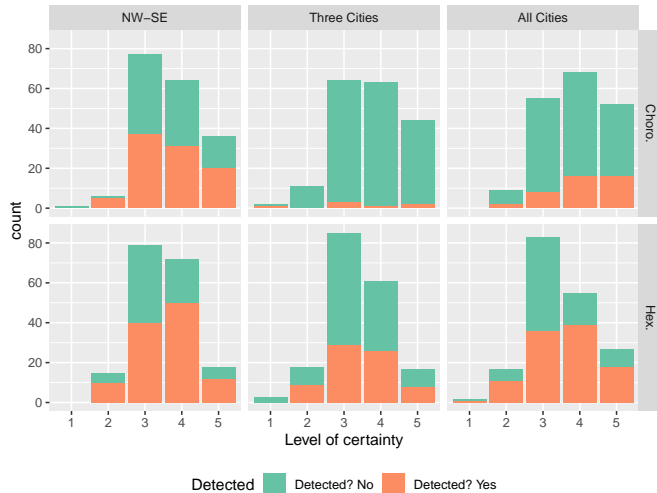


Fig. 4. The amount of times each level of certainty was chosen by participants when viewing hexagon tile map or choropleth displays. Participants were more likely to choose a high certainty when considering a Choropleth map. The mid value of 3 was the default certainty, it was chosen most for the Hexagon tile map displays.

TABLE IV
THE AMOUNT OF PARTICIPANTS THAT SELECTED EACH REASON FOR THEIR CHOICE OF PLOT WHEN LOOKING AT EACH TREND MODEL SHOWN IN CHOROPLETH AND HEXAGON TILE MAPS. THE FACETS SHOW WHETHER OR NOT THE CHOICE WAS CORRECT.

Trend	Detected	Choro.	Hex.
NW-SE	No	trend	clusters
	Yes	trend	clusters
Three Cities	No	trend	clusters
	Yes	consistent	clusters
All Cities	No	trend	clusters
	Yes	clusters, consistent	clusters

E. Reason

Participants were asked why they had made their plot choice and were able to select from a set of suggested reasons. “Colour trend across the areas” was the most common selection for NW-SE trend displays. The colour scaling applied in Three cities and All cities displays resulted in the rural areas of the real data plot appearing more blue or yellow than the other plots in the lineups. Due to the consistent colouring of rural areas in a choropleth display, the choice “All areas have similar colours” was most common reason. The All Cities displays coloured the inner-city areas of all capital cities more red, this was observable to participants and explains the equal choice of the city clusters or rural colour consistency.

The reasons used when viewing choropleth displays varied more than the hexagon tile map reasons. The hexagon tile map displays resulted in “Clusters of colour” as the most common choice made by participants. This response was expected when participants viewed the Hexagon tile map display of the All Cities and Three Cities distributions. It was unexpected that it was also the most common reason for the NW-SE hexagon tile map displays. Due to the spatial covariance introduced in the smoothing, groups of similarly coloured hexagons were present in all of the hexagon tile map displays. All Cities and Three Cities distributions of real data trends had distinctly different patterns or red inner-city areas, while some of the plots in each lineup may have shared similar features.

The choice “None of these reasons” was used as the default value to minimise noise from participants who did not select a response.

V. DISCUSSION

VI. CONCLUSION

The choropleth map display and the tessellated hexagon tile map have been contrasted in a visual inference study. The hexagon tile map was significantly more effective for spotting a real data trend model hidden in a lineup.

This hexagon tile map display should be considered as a visualisation method when communicating distributions that relate to the population in each geographic unit. Cancer Atlas products may benefit from the opportunity to allow exploration

via the traditional choropleth map method as well as an alternative display. The spatial distributions used to test these displays were inspired by the real spatially smoothed estimates of the cancer burden on Australian communities. However, this technique may be extended to other population related distributions, such as other diseases.

The increasing population densities of capital cities despite large land area exasperates the difference in the smallest and largest communities. The population density structure of Australia can be considered similar to that of Canada, New Zealand and many others. Therefore, this display is not only relevant to Australia, but all nations or population collections that experience densely populated cities alongside vast rural expanses.

VII. ACKNOWLEDGMENT

The authors would like to thank the Australian Cancer Atlas team for discussions regarding alternative spatial visualisations. They would also like to thank Kerrie Mengersen and Dr. Earl Duncan for suggestions and comments.

Ethics approval for the online survey was granted by QUT's Ethics Committee (Ethics Application Number: 1900000991). All applicants provided informed consent in line with QUT regulations prior to participating in this research.

VIII. REFERENCES

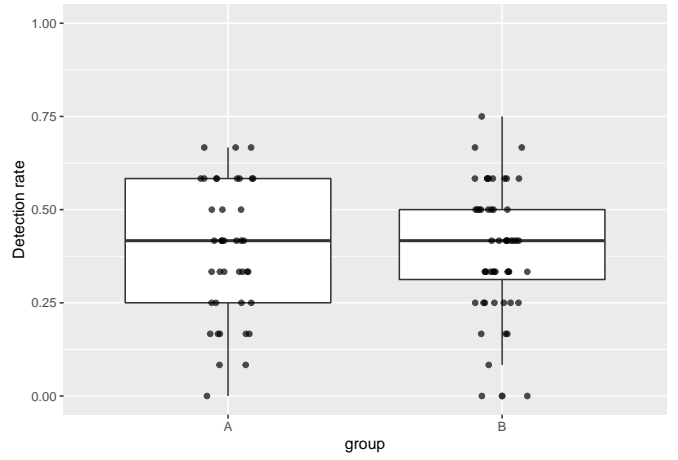


Fig. 5. The probability of detection achieved by the contributors in each group is shown by the points. Group B has a larger range and a smaller inter-quartile range. Group A and both had 3 people who did not find any of the data maps in the displays.

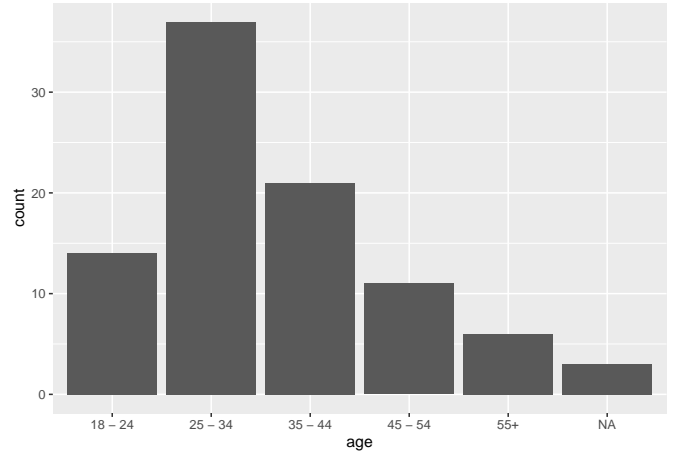


Fig. 6. The distribution of age groups of participants.

IX. APPENDIX

A. Overall Performance

B. Individual performance

C. Demographics:

Gender	Amount
He	67
She	25
Education	Amount
High School Diploma	23
Bachelors Degree	56
Masters Degree	13

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The source code to produce this document can be found on GitHub. Supplementary materials have been included to discuss the survey procedures,

The analysis of the work was completed in R [14] with the use of the following packages: - For document creation: rmarkdown [16], rticles [17], knitr [18]. - For lineup creation and data analysis: tidyverse [19], nullabor [20], ggthemes [21], RColorBrewer [22]. - For image displays: cowplot [23], png [24], grid [25]. - For modeling and presentation of models: lme4 [15], kableExtra [26].

Ethics approval for the online survey was granted by QUT's Ethics Committee (Ethics Application Number: 1900000991). All applicants provided informed consent in line with QUT regulations prior to participating in this research.

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