To synchronize the multiple treads, a condition variable was used. When the maximum number of threads has been created, the main thread waits for the condition variable to be signaled. Before a thread terminates, it signals the condition variable. When this happens, the main thread is alerted and continues. This way busy waiting is avoided.

A mutex was used to lock the buffer. Before the main or a thread accesses the buffer, it tries to lock the mutex. The main thread acquires the lock before setting up a new thread and releases it just before creating the thread. The threads acquire the buffer when starting and release it before signaling the condition variable.

Inspiration was taken from $(Caf, 2011)^1$ about the use of condition variables. Deadlock issues were solved with the help of $(Cat, 2010)^2$.

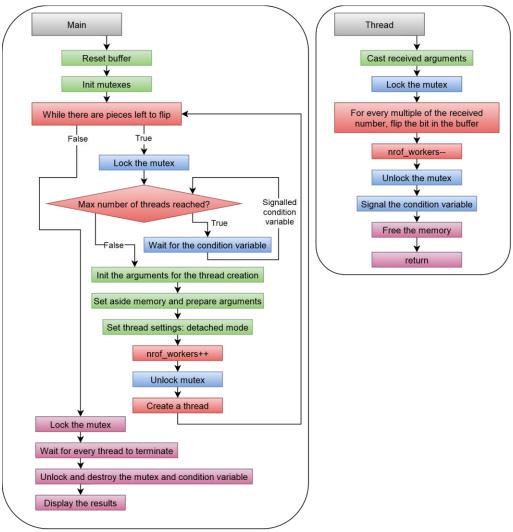


Figure 1 High level flow chart flip.c

2INCO Assignment 2

¹ Caf. (2011, March 1). Keeping number of threads constant with pthread in C. Retrieved December 9, 2020, from https://stackoverflow.com:

² Cat. (2010, December 10). Calling pthread_cond_signal without locking mutex. Retrieved December 10, 2020, from https://stackoverflow.com: https://stackoverflow.com/questions/4544234/calling-pthread-cond-signal-without-locking-mutex