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Operating Systems
ECE-357

# PSET 7

## Problem 1 -- using strace

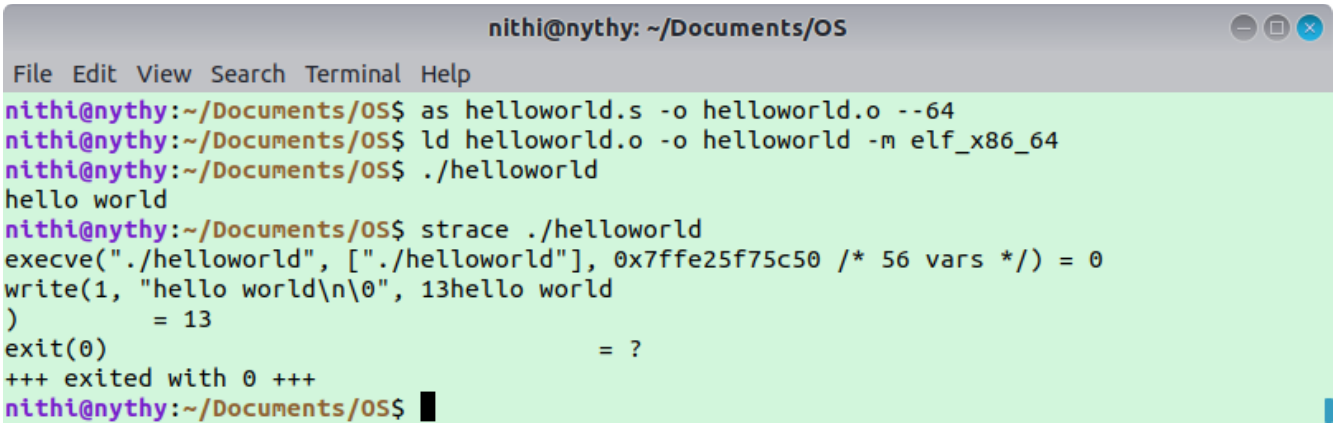
```
#include <stdio.h>
int main()
{
   printf("hello world\n");
   return 0;
}
```

```
nithi@nythy: ~/Documents/OS
File  Edit  View  Search  Terminal  Help
hello worldnithi@nythy:~/Documents/OS$ gcc helloworld.c
nithi@nythy:~/Documents/OS$ ./a.out
hello world
nithi@nythy:~/Documents/OS$ strace ./a.out
execve("./a.out", ["./a.out"], 0x7ffeeacf8da0 /* 56 vars */) = 0
brk(NULL)                               = 0x55d3a8e9e000
access("/etc/ld.so.nohwcap", F_OK)      = -1 ENOENT (No such file or directory)
access("/etc/ld.so.preload", R_OK)      = -1 ENOENT (No such file or directory)
openat(AT_FDCWD, "/etc/ld.so.cache", O_RDONLY|O_CLOEXEC) = 3
fstat(3, {st_mode=S_IFREG|0644, st_size=84107, ...}) = 0
mmap(NULL, 84107, PROT_READ, MAP_PRIVATE, 3, 0) = 0x7f434d52c000
close(3)                                = 0
access("/etc/ld.so.nohwcap", F_OK)      = -1 ENOENT (No such file or directory)
openat(AT_FDCWD, "/lib/x86_64-linux-gnu/libc.so.6", O_RDONLY|O_CLOEXEC) = 3
read(3, "\177ELF\2\1\1\3\0\0\0\0\0\0\0\0\3\0>\0\1\0\0\0\260\34\2\0\0\0\0\0"..., 832) = 8
32
fstat(3, {st_mode=S_IFREG|0755, st_size=2030544, ...}) = 0
mmap(NULL, 8192, PROT_READ|PROT_WRITE, MAP_PRIVATE|MAP_ANONYMOUS, -1, 0) = 0x7f434d52a00
0
mmap(NULL, 4131552, PROT_READ|PROT_EXEC, MAP_PRIVATE|MAP_DENYWRITE, 3, 0) = 0x7f434cf290
00
mprotect(0x7f434d110000, 2097152, PROT_NONE) = 0
mmap(0x7f434d310000, 24576, PROT_READ|PROT_WRITE, MAP_PRIVATE|MAP_FIXED|MAP_DENYWRITE, 3
, 0x1e7000) = 0x7f434d310000
mmap(0x7f434d316000, 15072, PROT_READ|PROT_WRITE, MAP_PRIVATE|MAP_FIXED|MAP_ANONYMOUS, -
1, 0) = 0x7f434d316000
close(3)                                = 0
arch_prctl(ARCH_SET_FS, 0x7f434d52b4c0) = 0
mprotect(0x7f434d310000, 16384, PROT_READ) = 0
mprotect(0x55d3a85be000, 4096, PROT_READ) = 0
mprotect(0x7f434d541000, 4096, PROT_READ) = 0
munmap(0x7f434d52c000, 84107)           = 0
fstat(1, {st_mode=S_IFCHR|0620, st_rdev=makedev(136, 0), ...}) = 0
brk(NULL)                               = 0x55d3a8e9e000
brk(0x55d3a8ebf000)                     = 0x55d3a8ebf000
write(1, "hello world\n", 12hello world
)           = 12
exit_group(0)                           = ?
+++ exited with 0 +++
nithi@nythy:~/Documents/OS$
```

## Problem 2 -- pure assembly

**Source Code:**

```
.text

.global _start

_start:
     mov     $1, %rax
     mov     $1, %rdi
     mov     $message, %rsi
     mov     $13, %rdx
     syscall

     mov     $60, %rax
     xor     %rdi, %rdi
     syscall
     message:
     .ascii  "hello world\n"
```



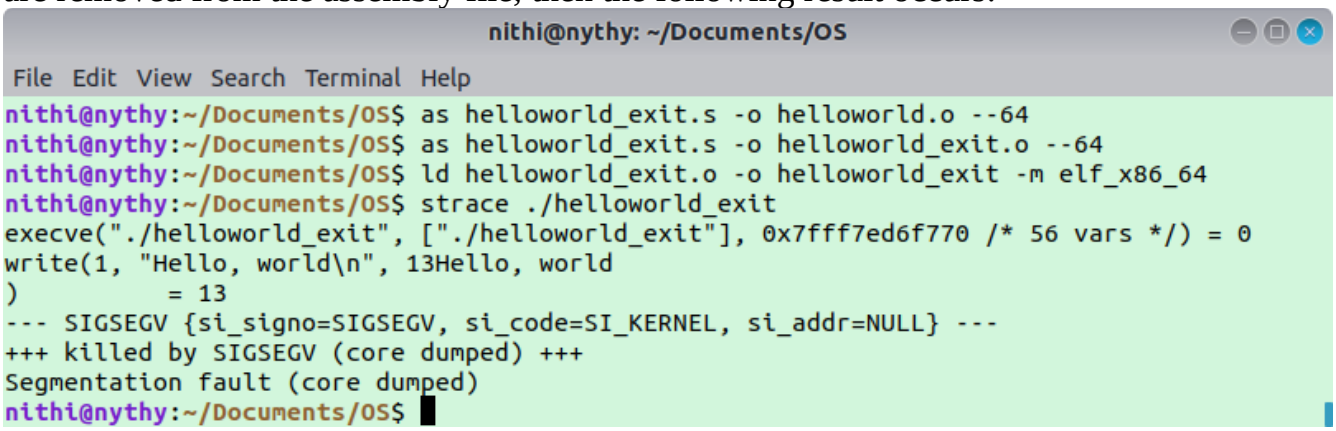
## Problem 3 -- exit code

From observing the strace output after the write system call from the code above, there is a line “exit(0)”. This comes from the lines “mov $60, %rax”, which selects system call 60, the exit system call. The line “`xor %rdi, %rdi`”, sets the return value to 0. Then the line “syscall” invokes the operating system to exit.

If the lines :

```
    mov     $60, %rax
    xor     %rdi, %rdi
    syscall
```

are removed from the assembly file, then the following result occurs:




Here, after the write system call, the kernel returns to userspace but as the text region has nothing, the program continues to try and run unknown unknown random memory and the processor will attempt to execute the values in this memory as instructions. As this memory is unknown, these bytes will likely not be valid instructions, leading to a fault, or cause an error, such as entering an endless loop.

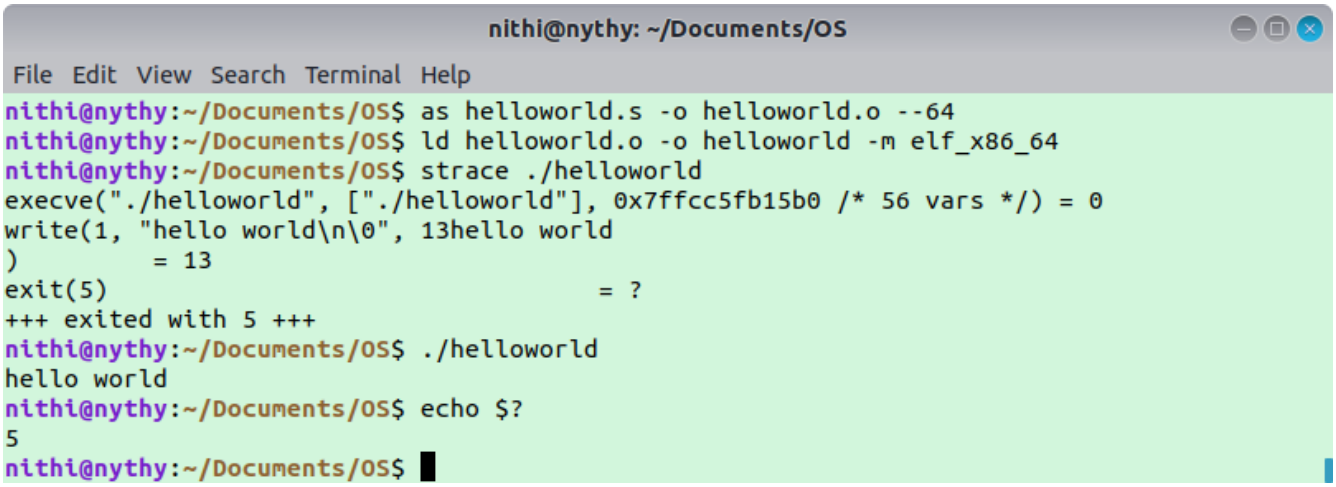
Another version of the program that has the `_exit` system call so that the program exits with a specific non-zero return code:

Source Code:

```
.text

.global _start

_start:
    mov     $1, %rax
    mov     $1, %rdi
```

```
mov     $message, %rsi
mov     $13, %rdx
syscall

mov     $60, %rax
    mov $5, %rdi
syscall
message:
.ascii  "hello world\n"
```

Here the exit code is set to 5, and so echo $? returns a 5 as shown bellow in the screenshot:



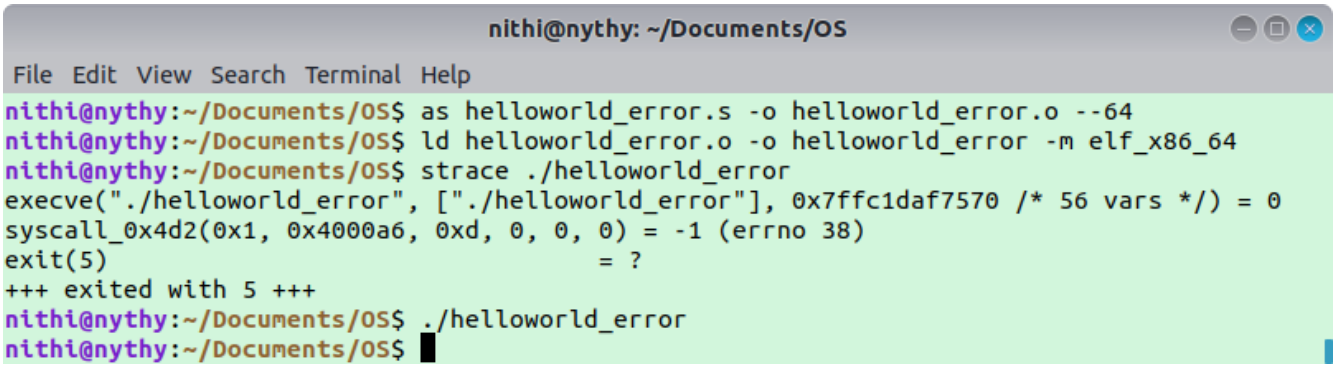

## Problem 4 -- system call validation

Here is a version of the part 3 program that passes an invalid system call number to `write. Shown bellow is the code and t`he strace output. The system call for

1 is write, but here that number of 1 is changed. And therefore, the write system call is not called, but the program exits, as that code is still there.

Source Code:

```
.global _start

.text

_start:
        mov     $1234, %rax
        mov     $1, %rdi
        mov     $message, %rsi
        mov     $13, %rdx
        syscall

        # exit(5)
        mov     $60, %rax
        mov     $5, %rdi
        syscall

        message:
.       ascii "hello world\n"
```




The error 38  /* Function not implemented */ comes up because that system call does not exist.

## Problem 5EC -- scheduling

Write a test program which creates a number of CPU-bound processes.

One of those processes will have a non-default `nice` value. Both the number of processes and the nice value will be command-line flags. After spawning the processes, the parent process will sleep for the specified number of seconds, then kill all the children and collect their respective `rusage` structures. Report the sum total CPU time consumed by the children, and the CPU time by the child which had the non-default nice value. Note: include both system and user CPU time.

Source Code:

```
#define _GNU_SOURCE
#include <stdio.h>
#include <sys/types.h>
#include <unistd.h>
#include <stdlib.h>
#include <sys/wait.h>
#include <sys/time.h>
#include <sys/resource.h>
#include <sys/times.h>
#include <time.h>

int i, j;
int main(int argc, char *argv[]){
        int processCount =atoi(argv[1]);
        int waitTime = atoi(argv[3]);
        int niceNumber =  atoi(argv[2]);

        int count = processCount-1;
        pid_t pid;
        pid_t pidtask0;

        int ret;
        struct rusage usagetask0, usageallchild;

        pid_t cpid, w, w2;
        int status;

        cpid = fork();
        if (cpid == -1) { perror("ERROR: fork failed");
exit(EXIT_FAILURE); }

        if (cpid == 0) {
                printf("Child PID is %ld\n", (long)
getpid());
                ret  = nice(niceNumber);
                printf("nice value: %d\n",ret);
```

```
                for (i=0, j=0; i<1000000; i++) {
                        for (i=0, j=0; i<1000000; i++)
                                j += i;
                }
                if (argc == 1)
                        pause();
                exit(0);
        }


        int count2=count;
        while(count--) {
                if((pid=fork())<0) {
                        printf("ERROR: fork error\n");
                } else if(pid==0) {
                        int i;
                        for (i=0, j=0; i<1000000; i++) {
                                for (i=0, j=0; i<1000000; i+
+)
                                        j += i;
                        }
                        exit(0);
                }
        }

        sleep(waitTime);

        do {
                w = waitpid(cpid, &status, WUNTRACED |
WCONTINUED);
                getrusage (RUSAGE_CHILDREN, &usagetask0);
                if (w == -1) { perror("ERROR: waitpid for
task with change in nice value"); exit(EXIT_FAILURE); }
        } while (!WIFEXITED(status) && !WIFSIGNALED(status));

        count2;
        while(count2--) {
                w2 = wait(NULL);
                if (w2 == -1) { perror("ERROR: wait on
children failed"); exit(EXIT_FAILURE); }

        }

        getrusage (RUSAGE_CHILDREN, &usageallchild);
```

```
        printf("Spawning %d processes and waiting %d seconds,
first child process will have nice %d\n", processCount,
waitTime, niceNumber);

        double childtime = usageallchild.ru_utime.tv_sec +
usageallchild.ru_utime.tv_usec +
usageallchild.ru_stime.tv_sec +
usageallchild.ru_stime.tv_usec;
        double task0time =   usagetask0.ru_utime.tv_sec +
usagetask0.ru_utime.tv_usec + usagetask0.ru_stime.tv_sec +
usagetask0.ru_stime.tv_usec;

        printf("Total CPU time was %lf\n", childtime +
task0time );
        printf("Task 0 CPU time was %lf \n", task0time);
        printf("Task 0 received %f %% of total CPU\n",
(task0time)/(childtime +task0time)*100);

        return 0;
}
```

**Sample Output:**

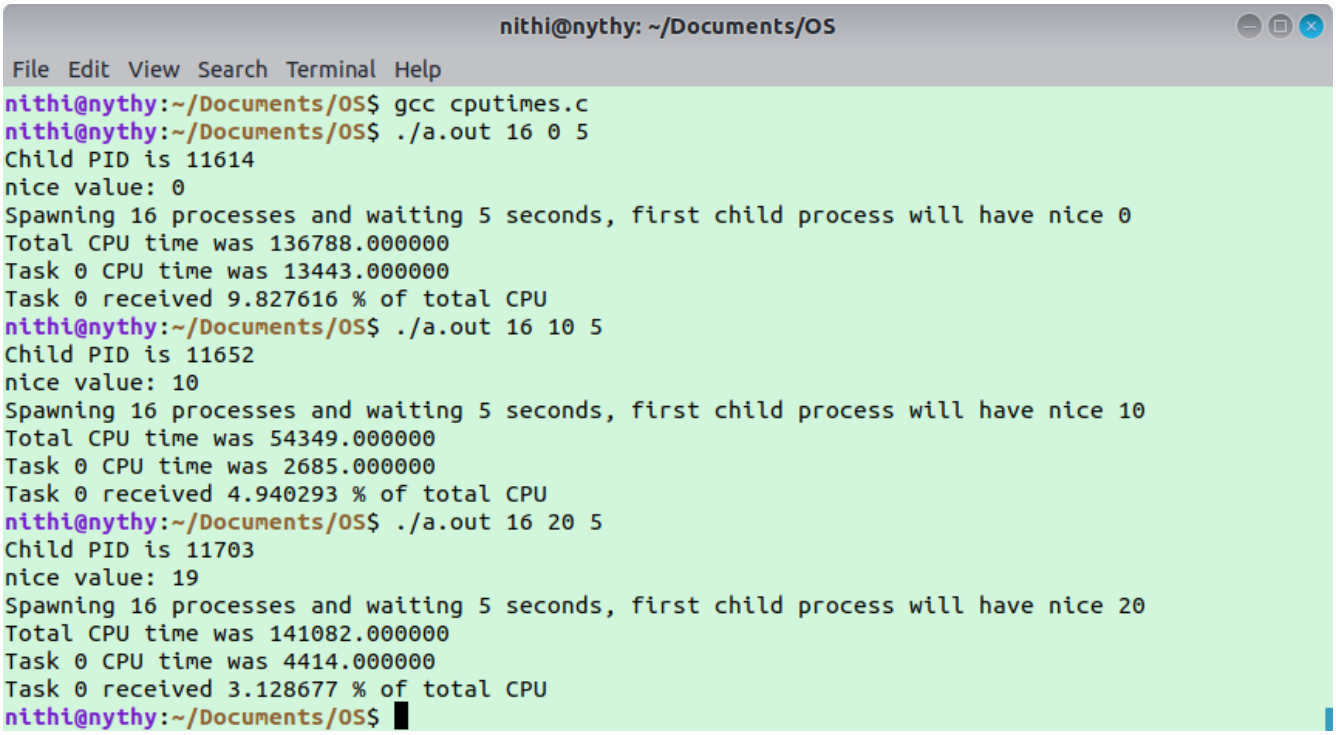



**Table With Changed Values:**

**Average % of total CPU that task 0 received for Parent Sleeping for 5 seconds for 3 runs each:**

| | Nice = 0 | Nice = 10 | Nice = 19 |
|---|---|---|---|
| ProcessCount = 3 | 26.666772 | 25.756703 | 25.770789 |
| ProcessCount = 5 | 17.23830 | 15.12561 | 14.42673 |
| ProcessCount = 16 | 9.827616 | 4.940293 | 3.128677 |
| ProcessCount = 35 | 4.752382 | 2.708152 | 2.110145 |
| ProcessCount = 100 | 2.552680 | 1.676030 | 0.974388 |

I ran the above on a CPU with 4 cores. So using the same logic in the program description, over a 5-second period, the maximum theoretical CPU time would be 20 seconds. The 16 test processes did not get a number that was near this value, only leading me to presume that the system was otherwise not idle, even though I don't have much else running.

The sleep time was set to 5 seconds as because as noted in the program description, that's a minimum so that otherwise brief fluctuations in system load don't drastically affect your answers.

This was then run for various combinations of processes and nice values. Smaller than the number of cores is 3, so the program was run for 3 processes, and the large number of 100

was chosen to see the other end.  The nice value appears to not affect things for small numbers of processes relative to CPU cores. This makes sense because there is less of a need to schedule or prioritize processes because all processes can be computed with the relative process count to the core count.