

Transform and Conquer

Chapter 6

Transform and Conquer

There are 3 Variations:

- Instance simplification
- Representation change
- Problem reduction

Transform and Conquer

- Instance simplification:
 - Transformation to a simpler or more convenient instance of the same problem.
 - Ex:
 - Presorting
 - Gauss elimination, AVL Trees, 2-3 Trees (not discussing now)
- Representation change:
 - Transformation to a different representation of the same instance.
 - Ex:
 - Heaps and Heapsort
- Problem reduction: (not discussing now)
 - Transformation to an instance of a different problem for which an algorithm is already available.
 - Ex:
 - Linear programming
 - Reductions to graph problems

Presorting

- Importance of Sorting
- Efficiency calculations of sorting algorithms

Presorting

ALGORITHM PresortElementUniqueness($A[0\dots n-1]$)

//Solves the element uniqueness problem by sorting the array first.

//Input: An Array $A[0\dots n-1]$

//Output: Returns “true” if A has no equal elements, “false” otherwise.

Sort the array A

for $i \leftarrow 0$ to $n-2$ do

 If $A[i] == A[i+1]$ return false

return true

ALGORITHM *PresortMode*($A[0..n - 1]$)

//Computes the mode of an array by sorting it first

//Input: An array $A[0..n - 1]$ of orderable elements

//Output: The array's mode

Sort the array A

$i \leftarrow 0$ //current run begins at position i

modefrequency $\leftarrow 0$ //highest frequency seen so far

while $i \leq n - 1$ **do**

runlength $\leftarrow 1$; *runvalue* $\leftarrow A[i]$

while $i + \text{runlength} \leq n - 1$ **and** $A[i + \text{runlength}] = \text{runvalue}$

runlength $\leftarrow \text{runlength} + 1$

if *runlength* $>$ *modefrequency*

modefrequency $\leftarrow \text{runlength}$; *modevalue* $\leftarrow \text{runvalue}$

$i \leftarrow i + \text{runlength}$

return *modevalue*

Heap

- Heap is a binary tree with following properties:
- 1. Tree shape requirement: Binary Tree is complete - all levels full except for last level where only some rightmost leaves may be missing
- 2. Parental dominance holds - value at a node greater than or equal to the values of its children
- Traversal from root to leaf is always decreasing
- No order among siblings (no ordering from left to right)

Characteristics of Heap

- 1. Root is largest element
- 2. Heap with n elements can be stored as a list:
 - - Elements in slots $1 \dots n$
 - - Non-leaf nodes in first $\lfloor n/2 \rfloor$ positions
 - - Leaf nodes stored in last $\lceil n/2 \rceil$ positions
 - - Given node in slot i , its children are in slots $2i$ and $2i + 1$
 - - Given node in slot i , its parent is in slot $\lfloor i/2 \rfloor$

Heap Bottom Up Algorithm

- 1. Given n nodes, place them from positions 1 to n
- 2. Starting with last parental node, compare parent with children
- 3. If parental dominance does not hold, exchange parent with largest child and
- repeat checking for parental dominance in the new position for parent

Heap Bottom Up Algorithm

```
Algorithm HeapBottomUp( $H[1..n]$ )  
//Constructs a heap from the elements of a given array  
// by the bottom-up algorithm  
//Input: An array  $H[1..n]$  of orderable items  
//Output: A heap  $H[1..n]$   
for  $i \leftarrow \lfloor n/2 \rfloor$  downto 1 do  
     $k \leftarrow i$ ;  $v \leftarrow H[k]$   
    heap  $\leftarrow$  false  
    while not heap and  $2 * k \leq n$  do  
         $j \leftarrow 2 * k$   
        if  $j < n$  //there are two children  
            if  $H[j] < H[j + 1]$   $j \leftarrow j + 1$   
        if  $v \geq H[j]$   
            heap  $\leftarrow$  true  
        else  $H[k] \leftarrow H[j]$ ;  $k \leftarrow j$   
 $H[k] \leftarrow v$ 
```

Root deletion algorithm

Sorting:

- Swap root with rightmost leaf
- Decrease heap size by 1
- Heapify the smaller tree

The End

Thank You