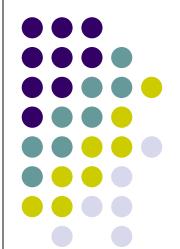
Computer Graphics (CS 543) Lecture 9a: Environment Mapping (Reflections and Refractions)

Prof Emmanuel Agu (Adapted from slides by Ed Angel)

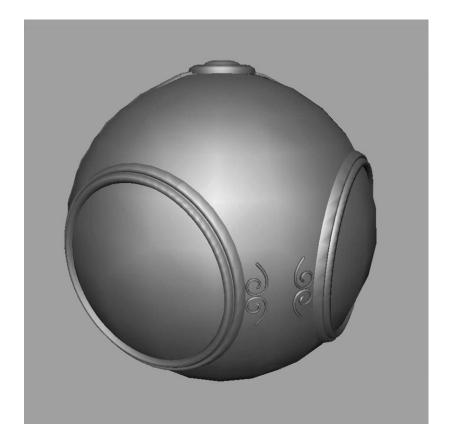
Computer Science Dept. Worcester Polytechnic Institute (WPI)



Environment Mapping



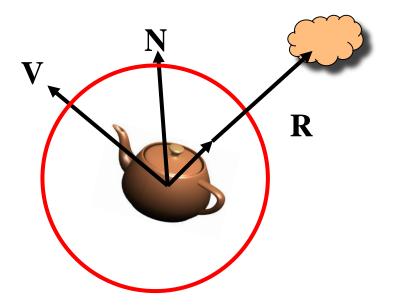
 Environmental mapping is way to create the appearance of highly reflective and refractive surfaces without ray tracing



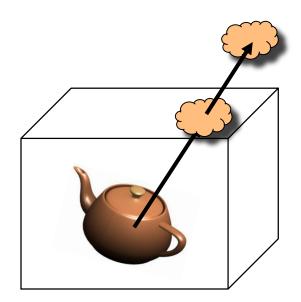


Types of Environment Maps

- Assumes environment infinitely far away
- Options: Store "object's environment as
- a) Sphere around object (sphere map)



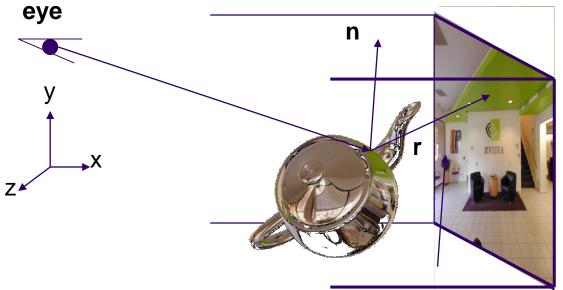
b) Cube around object (cube map)



OpenGL supports cube maps and sphere maps



Cube mapping

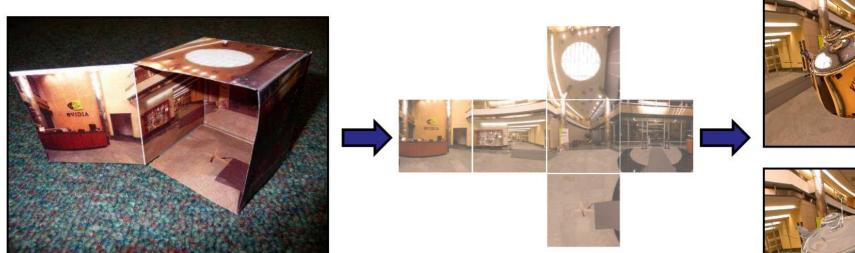




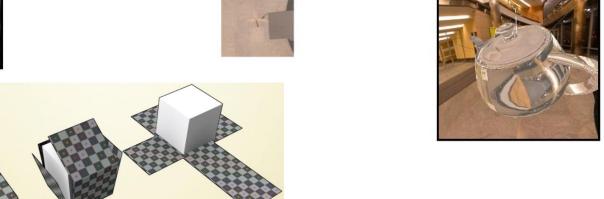
- Need to compute reflection vector, r
- Use r by for environment map lookup

Cube Map: How to Store

- Stores "environment" around objects as 6 sides of a cube (1 texture)
- Load 6 textures separately into 1 OpenGL cubemap





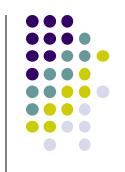


Cube Maps

- Loaded cube map texture can be accessed in GLSL through cubemap sampler
- Compute reflection vector R = 2(N·V)N-V
- Perform cubemap lookup using R vector (texcoord)

vec4 texColor = textureCube(mycube, R);

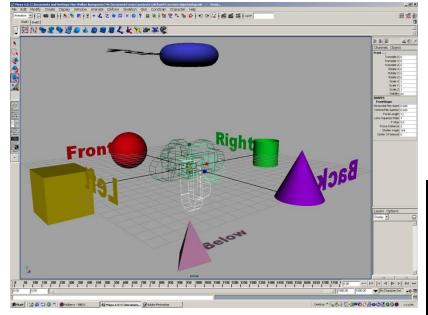
- R is 3D vector, so texture coordinates must be 3D (x, y, z)
- OpenGL figures out which face of cube R hits, to look up
- More details on lookup later



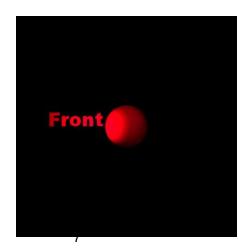
R



- Use 6 cameras directions from scene center
 - each with a 90 degree angle of view





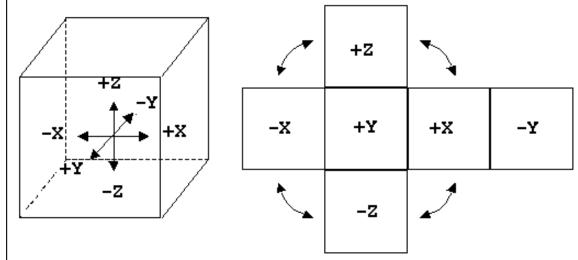


Cube Map Layout



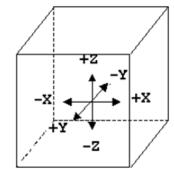


Make 1 cubemap texture object from 6 images



Declaring Cube Maps in OpenGL

Declare each of 6 sides of cube map separately.



E.g. to declare +X image

glTextureMap2D(GL_TEXTURE_CUBE_MAP_POSITIVE_X, level, rows, columns, border, GL_RGBA, GL_UNSIGNED_BYTE, image1)

- Repeat similar for other 5 images (sides)
- Parameters apply to all six images. E.g

```
glTexParameteri( GL_TEXTURE_CUBE_MAP, GL_TEXTURE_MAP_WRAP_S, GL_REPEAT)
```

Cube Map Example (init)

```
// colors for sides of cube
  GLubyte red[3] = \{255, 0, 0\};
  GLubyte green[3] = \{0, 255, 0\};
  GLubyte blue[3] = \{0, 0, 255\};
  GLubyte cyan[3] = \{0, 255, 255\};
  GLubyte magenta[3] = \{255, 0, 255\};
  GLubyte yellow[3] = \{255, 255, 0\};
 glEnable(GL_TEXTURE_CUBE_MAP);
// Create texture object
 glGenTextures(1, tex);
 glActiveTexture(GL_TEXTURE1);
 glBindTexture(GL_TEXTURE_CUBE_MAP, tex[0]);
```

This example generates simple Colors as a texture

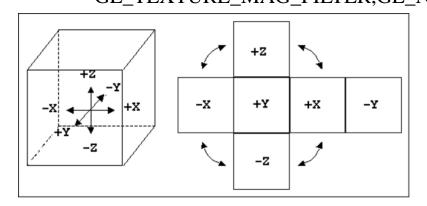
You can also just load 6 pictures of environment

Cube Map (init II)

Load 6 different pictures into 1 cube map of environment



```
glTexImage2D(GL_TEXTURE_CUBE_MAP_POSITIVE_X,
                   0,3,1,1,0,GL_RGB,GL_UNSIGNED_BYTE, red);
glTexImage2D(GL TEXTURE_CUBE_MAP_NEGATIVE_X,
                  0,3,1,1,0,GL RGB,GL UNSIGNED BYTE, green);
glTexImage2D(GL_TEXTURE_CUBE_MAP_POSITIVE_Y,
                  0.3.1.1.0.GL RGB.GL UNSIGNED BYTE, blue):
glTexImage2D(GL_TEXTURE_CUBE_MAP_NEGATIVE_Y,
                  0,3,1,1,0,GL RGB,GL UNSIGNED BYTE, cyan);
glTexImage2D(GL TEXTURE CUBE MAP POSITIVE Z,
                0,3,1,1,0,GL RGB,GL UNSIGNED BYTE, magenta);
glTexImage2D(GL TEXTURE CUBE MAP NEGATIVE Z,
                 0,3,1,1,0,GL_RGB,GL_UNSIGNED_BYTE, yellow);
glTexParameteri(GL_TEXTURE_CUBE_MAP,
                     GL_TEXTURE_MAG_FILTER,GL_NEAREST);
```



Cube Map (init III)

```
GLuint texMapLocation;
GLuint tex[1];
```

```
texMapLocation = glGetUniformLocation(program, "texMap");
glUniform1i(texMapLocation, tex[0]);
```

Connect texture map (tex[0]) to variable texMap in fragment shader (texture mapping done in frag shader)





```
void quad(int a, int b, int c, int d)
   static int i = 0;
   normal = normalize(cross(vertices[b] - vertices[a],
     vertices[c] - vertices[b]));
                                      Calculate and set quad normals
   normals[i] = normal;
   points[i] = vertices[a];
   i++;
// rest of data
```

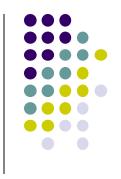
Vertex Shader

```
out vec3 R;
in vec4 vPosition;
in vec4 Normal;
uniform mat4 ModelView;
uniform mat4 Projection;
```



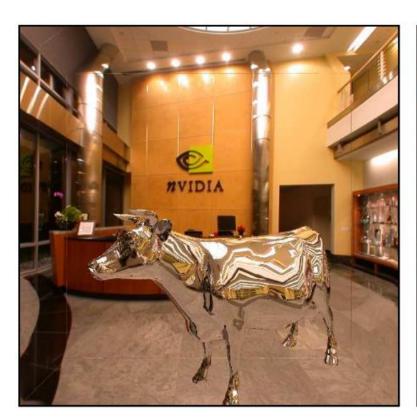








Can also use cube map for refraction (transparent)





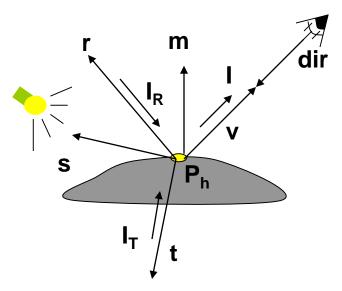
Reflection

Refraction

Reflection and Refraction

At each vertex

$$I = I_{\mathit{amb}} + I_{\mathit{diff}} + I_{\mathit{spec}} + I_{\mathit{refl}} + I_{\mathit{tran}}$$



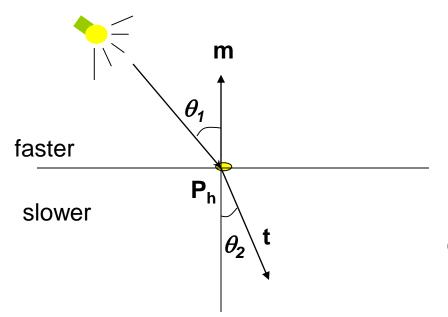




Finding Transmitted (Refracted) Direction



- Transmitted direction obeys Snell's law
- Snell's law: relationship holds in diagram below



$$\frac{\sin(\theta_2)}{c_2} = \frac{\sin(\theta_1)}{c_1}$$

c₁, c₂ are speeds of light in medium 1 and 2

Finding Transmitted Direction

- If ray goes from faster to slower medium (e.g. air to glass), ray is bent towards normal
- If ray goes from slower to faster medium (e.g. glass to air), ray is bent away from normal
- c1/c2 is important. Usually measured for medium-to-vacuum.
 E.g water to vacuum
- Some measured relative c1/c2 are:

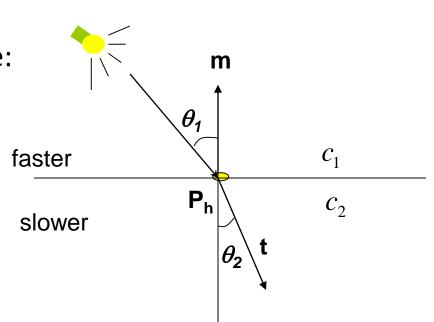
Air: 99.97%

Glass: 52.2% to 59%

Water: 75.19%

Sapphire: 56.50%

Diamond: 41.33%

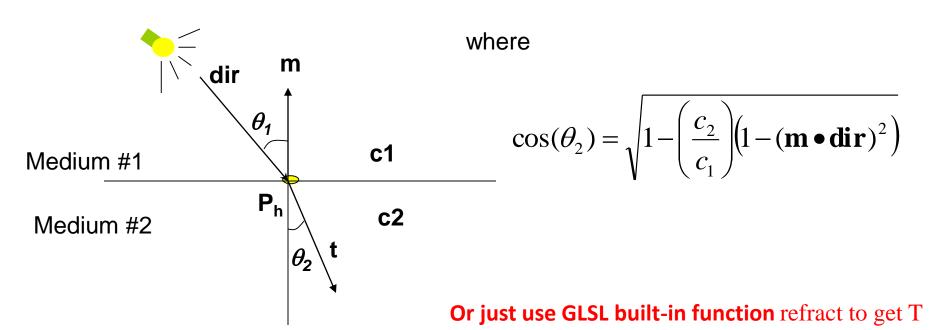






Vector for transmission angle can be found as

$$\mathbf{t} = \frac{c_2}{c_1} \mathbf{dir} + \left(\frac{c_2}{c_1} (\mathbf{m} \bullet \mathbf{dir}) - \cos(\theta_2) \right) \mathbf{m}$$



Refraction Vertex Shader

```
out vec3 T:
in vec4 vPosition;
in vec4 Normal;
uniform mat4 ModelView;
uniform mat4 Projection;
void main() {
  gl_Position = Projection*ModelView*vPosition;
  vec4 eyePos = vPosition;
  vec4 NN = ModelView*Normal: // transform normal
  vec3 N =normalize(NN.xyz);
                              // normalize normal
```

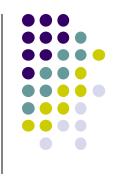


// calculate view vector V

Was previously R = reflect(eyePos.xyz, N);

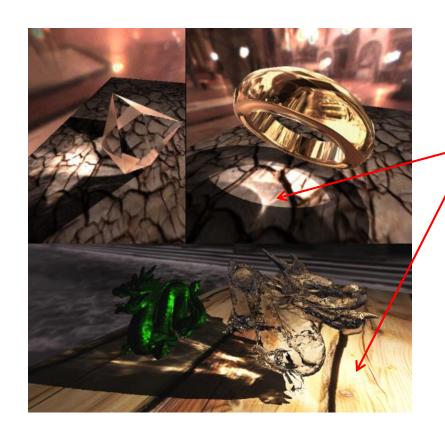
T = refract(eyePos.xyz, N, iorefr); // calculate refracted vector T





Caustics





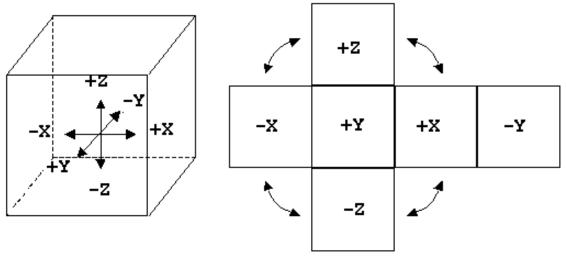
Caustics occur when light is focussed on diffuse surface

Courtesy Chris Wyman, Univ Iowa

Cube Map Layout



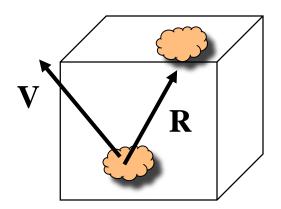




Indexing into Cube Map: How?

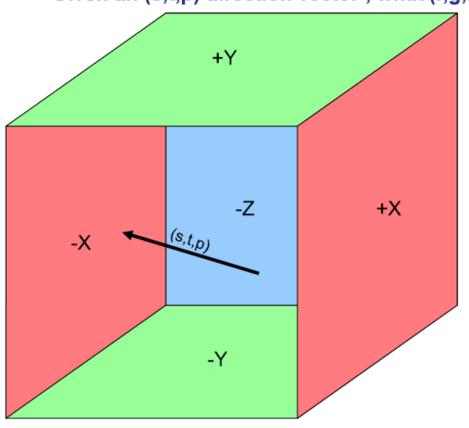


- •Compute $\mathbf{R} = 2(\mathbf{N} \cdot \mathbf{V})\mathbf{N} \mathbf{V}$
- Object at origin
- Use largest magnitude component of R to determine face of cube
- Other 2 components give texture coordinates





Cube Map Texture Lookup: Given an (s,t,p) direction vector, what (r,g,b) does that correspond to?



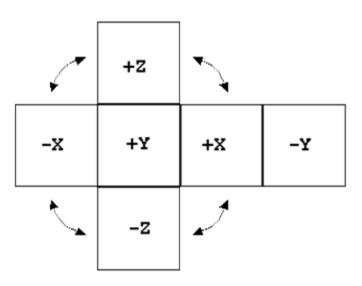
- Let L be the texture coordinate of (s, t, and p) with the largest magnitude
- L determines which of the 6 2D texture "walls" is being hit by the vector (-X in this case)
- The texture coordinates in that texture are the remaining two texture coordinates divided by L: (a/L,b/L)

Built-in GLSL functions

vec3 ReflectVector = reflect(vec3 eyeDir, vec3 normal);

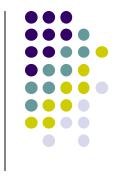
vec3 RefractVector = refract(vec3 eyeDir, vec3 normal, float Eta);

Example





- $\mathbf{R} = (-4, 3, -1)$
- Same as $\mathbf{R} = (-1, 0.75, -0.25)$
- Look up face x = -1 and [y = 0.75, z = -0.25] as tex coords
- Not quite right since cube defined by x, y, z = ± 1 rather than [0, 1] range needed for texture coordinates
- Remap by from [-1,1] to [0,1] range
 - $s = \frac{1}{2} + \frac{1}{2}y$, $t = \frac{1}{2} + \frac{1}{2}z$
- Hence, s = 0.875, t = 0.375



References

- Interactive Computer Graphics (6th edition), Angel and Shreiner
- Computer Graphics using OpenGL (3rd edition), Hill and Kelley
- Real Time Rendering by Akenine-Moller, Haines and Hoffman