

# qcrab documentation

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## Overlap Integrals

As shown in Ref. 1, the expression for an overlap integral of two primitive Gaussian functions,  $S$ , is given by:

$$S = E_{\mathbf{AB}} S_x S_y S_z, \quad (1)$$

where  $E_{\mathbf{AB}} = \exp\left[-\frac{\alpha\beta}{\alpha+\beta}|\mathbf{A} - \mathbf{B}|^2\right]$  and  $S_x$ , for example, is given by:

$$S_x = \sqrt{\frac{\pi}{\alpha + \beta}} \sum_{i_x=0}^{a_x} \sum_{j_x=0}^{b_x} \binom{a_x}{i_x} \binom{b_x}{j_x} \frac{(i_x + j_x + 1)!!}{[2(\alpha + \beta)]^{(i_x+j_x)/2}} (P_x - A_x)^{a_x-i_x} (P_x - B_x)^{b_x-j_x} \quad (2)$$

As a note,  $|\mathbf{A} - \mathbf{B}|^2$  is the magnitude of  $\mathbf{A} - \mathbf{B}$  ( $\sqrt{\sum_i (a_i - b_i)^2}$ ) squared ( $\sum_i (a_i - b_i)^2$ ), or  $(\mathbf{A} - \mathbf{B}) \cdot (\mathbf{A} - \mathbf{B})$ .

In all of these expressions,  $\alpha$  is the exponent for the first primitive Gaussian function,  $\beta$  is the exponent for the second primitive Gaussian,  $\mathbf{P} = \frac{\alpha\mathbf{A} + \beta\mathbf{B}}{\alpha + \beta}$ ,  $\mathbf{A}$  and  $\mathbf{B}$  are the origins of the basis functions (the Cartesian coordinates of the nuclei they are centered on), and  $a_x$  and  $b_x$  are the  $x$  components of the angular momentum for the Gaussian functions. For example, in an  $s$  orbital,  $l = 0$ , and  $l_x$ ,  $l_y$ , and  $l_z$  are given by the tuple  $(0, 0, 0)$ , while for a  $p$  orbital, there are three combinations for which  $l = 1 = l_x + l_y + l_z$ :  $(1, 0, 0)$ ,  $(0, 1, 0)$ ,

and (0, 0, 1). Consequently, for shells composed of multiple primitive Gaussian functions, we must loop over these combinations, as well as the primitives.

In the code for `overlap_ints`, I first loop over the shells and collect these possibilities, as shown in Listing 1.

Listing 1: Collecting  $l$  values for shells

```
let mut ls = Vec::new();
let mut ss = Vec::new();
for (i, shell) in self.0.iter().enumerate() {
    let l = match shell.contr[0].l {
        0 => vec![(0, 0, 0)],
        1 => vec![(1, 0, 0), (0, 1, 0), (0, 0, 1)],
        2 => vec![
            (2, 0, 0),
            (0, 2, 0),
            (0, 0, 2),
            (0, 1, 1),
            (1, 1, 0),
            (1, 0, 1),
        ],
        _ => panic!("unmatched l value {}", shell.contr[0].l),
    };
    let s = vec![i; l.len()];
    ls.extend(l);
    ss.extend(s);
}
```

With the combinations of angular momenta stored in `ls` and the shells associated with them in `ss`, we can iterate over them, effectively iterating over the orbitals themselves. For each combination of orbitals, we compute the overlap integral for the orbitals,  $S_{ij}$ , as the sum over primitives, where  $N$  is the number of primitives in shell  $i$ , and  $M$  is the number of primitives in shell  $j$ :

$$S_{ji} = S_{ij} = \sum_n^N \sum_m^M c_n c_m E_{\mathbf{AB}} S_x S_y S_z \quad (3)$$

Recall that  $E_{\mathbf{AB}}$  includes  $\alpha$  and  $\beta$ , which are subscripted by  $n$  and  $m$  in this sum, so  $E_{\mathbf{AB}}$  does depend on  $n$  and  $m$ . Similarly,  $\alpha$  and  $\beta$  in Eqn. 2 are  $\alpha_n$  and  $\beta_m$ , and  $\mathbf{P}$  must

also be computed on each iteration, again because of its dependence on  $\alpha$  and  $\beta$ .

## Kinetic Integrals

Like the overlap integrals, the kinetic energy integrals,  $K$ , can be separated into their  $x$ ,  $y$ , and  $z$  components as shown in Ref. 2:

$$K = K_x + K_y + K_z, \quad (4)$$

where the individual components, for example  $K_x$ , can be expressed as combinations of overlap integrals and one new term,  $k_x$ :

$$K_x = E_{\mathbf{AB}} \left[ \frac{\pi}{\alpha + \beta} \right]^{\frac{3}{2}} k_x s_y s_z, \quad (5)$$

where  $E_{\mathbf{AB}}$  has the same meaning as before.  $s_y$  and  $s_z$  are related the  $S_y$  and  $S_z$  defined in the previous section, but without the  $\sqrt{\frac{\pi}{\alpha + \beta}}$  prefactor.  $k_x$  itself is define by the recurrence relation:

$$\begin{aligned} k_x = \frac{3}{4} [ & a_x b_x s_x (a_x - 1, b_x - 1) \\ & - 2\alpha b_x s_x (a_x + 1, b_x - 1) \\ & - 2a_x \beta s_x (a_x - 1, b_x + 1) \\ & + 4\alpha \beta s_x (a_x + 1, b_x + 1) ], \end{aligned} \quad (6)$$

where

$$k_x(0, 0) = 2\alpha \beta s_x(1, 1), \quad (7)$$

$$k_x(a_x, 0) = -a_x\beta s_x(a_x - 1, 1) + 2\alpha\beta s_x(a_x + 11), \quad (8)$$

and

$$k_x(0, b_x) = -\alpha b_x s_x(1, b_x - 1) + 2\alpha\beta s_x(1, b_x + 1). \quad (9)$$

Although Ref. 2 calls this a recurrence relation, it's not clear to me where the recursion is since it's written in terms of overlap integrals, not in terms of recurring kinetic-energy integrals. Also, Ref. 2 uses a factor of  $\frac{1}{2}$  in front of Eqn. 6, but I had to set mine to  $\frac{3}{4}$  to get it to work. I have no idea why this is the case, but it works for the both the STO-3G and DZ basis sets.

## References

- (1) Hô, M.; Hernández-Pérez, J. M. Evaluation of Gaussian Molecular Integrals I. Overlap Integrals. *The Mathematica Journal* **2012**, *14*.
- (2) Hô, M.; Hernández-Pérez, J. M. Evaluation of Gaussian Molecular Integrals II. Kinetic-Energy Integrals. *The Mathematica Journal* **2013**, *15*.