Statistical Mechanical Analysis of Low-Density Parity-Check Codes on General Markov Channel

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Concept

It has been shown that

Large deviations theory (method of types) is useful for understanding the result of the replica method [Mori 2011].

In this work,

Large deviations theory (method of types) for Markov chain is applied to models including a Markov structure.

Types [Csiszár 1977]

- \blacksquare \mathcal{X} : a finite set
- \blacksquare $P_{\mathbf{x}}(a)$: the fraction of $a \in \mathcal{X}$ in $\mathbf{x} \in \mathcal{X}^N$

Example:

For
$$\mathcal{X} = \{a, b, c\}$$
, $\mathbf{x} = [a, a, b, a, c, c, a, b]$,

$$P_{x}(a) = 4/8$$
, $P_{x}(b) = 2/8$, $P_{x}(c) = 2/8$.

$$\mathcal{P}_{N}(\mathcal{X}) := \{ P_{\mathbf{x}} \mid \mathbf{x} \in \mathcal{X}^{N} \}, \qquad |\mathcal{P}_{N}(\mathcal{X})| = \binom{N+|\mathcal{X}|-1}{|\mathcal{X}|-1}$$

Number of sequences of a particular type

$$\mathcal{T}_P(N) := \{ \mathbf{x} \in \mathcal{X}^N \mid P_{\mathbf{x}} = P \}$$

$$|\mathcal{T}_P(N)| = egin{pmatrix} N \ NP(a) & NP(b) & NP(c) \end{pmatrix} := rac{N!}{(NP(a))!(NP(b))!(NP(c))!} \ |\mathcal{T}_P(n)| pprox \exp\{NH(P)\} \end{aligned}$$

Usage:

$$\sum_{\mathbf{x} \in \mathcal{X}^N} f(P_{\mathbf{x}}) = \sum_{P \in \mathcal{P}_N(\mathcal{X})} |T_P(N)| f(P)$$

$$\sum_{\mathbf{x} \in \{\mathbf{0},\mathbf{1}\}^N} f(\mathbf{x}) = \sum_{i=0}^N \binom{N}{i} f(i)$$

Sanov's theorem

$$Q^{N}(\mathbf{x}) = \prod_{a \in \mathcal{X}} Q(a)^{NP_{\mathbf{x}}(a)}$$

$$= \exp \left\{ N \sum_{a \in \mathcal{X}} P_{\mathbf{x}}(a) \log Q(a) \right\}$$

$$= \exp\{-N[H(P_{\mathbf{x}}) + D(P_{\mathbf{x}} || Q)]\}$$

$$\mathbb{E}\left[\exp\left\{Ng(P_{X_1X_2...X_N})\right\}\right] = \sum_{\mathbf{x}\in\mathcal{X}^N} Q^N(\mathbf{x}) \exp\left\{Ng(P_{\mathbf{x}})\right\}$$

$$= \sum_{P\in\mathcal{P}^N(\mathcal{X})} |\mathcal{T}_P(N)| \exp\left\{-N[H(P) + D(P||Q)]\right\} \exp\left\{Ng(P)\right\}$$

$$\approx \sum_{P\in\mathcal{P}(\mathcal{X})} \exp\left\{-N(D(P||Q) - g(P))\right\}$$

$$\approx \sup_{P\in\mathcal{P}(\mathcal{X})} \exp\left\{-N(D(P||Q) - g(P))\right\} \quad \text{(Laplace method)}$$

The second order types

- \blacksquare \mathcal{X} : a finite set
- $P_{\mathbf{x}}^{(2)}(a,b)$: the fraction of a pair of successive symbols $(a,b) \in \mathcal{X}^2$ in $\mathbf{x} \in \mathcal{X}^N$

Example:

For
$$\mathcal{X} = \{a, b, c\}$$
, $\mathbf{x} = [a, a, b, a, c, c, a, b]$

$$P_{\mathsf{x}}^{(2)}(a,a) = 1/7, \ P_{\mathsf{x}}^{(2)}(a,b) = 2/7, \ P_{\mathsf{x}}^{(2)}(a,c) = 1/7, \ P_{\mathsf{x}}^{(2)}(b,a) = 1/7, \ P_{\mathsf{x}}^{(2)}(b,b) = 0/7, \ P_{\mathsf{x}}^{(2)}(b,c) = 0/7, \ P_{\mathsf{x}}^{(2)}(c,a) = 1/7, \ P_{\mathsf{x}}^{(2)}(c,b) = 0/7, \ P_{\mathsf{x}}^{(2)}(c,c) = 1/7.$$

$$\mathcal{P}_{N}^{(2)}(\mathcal{X}) := \{ P_{\mathbf{x}}^{(2)} \mid \mathbf{x} \in \mathcal{X}^{N} \}, \qquad |\mathcal{P}_{N}^{(2)}(\mathcal{X})| \sim d(|\mathcal{X}|) N^{|\mathcal{X}|^{2} - |\mathcal{X}|}.$$

Number of sequence of particular type

$$\mathcal{T}^{(2)}_{P_{X,Y}}(N) := \{ \mathbf{x} \in \mathcal{X}^N \mid P_{\mathbf{x}}^{(2)} = P_{X,Y} \}$$

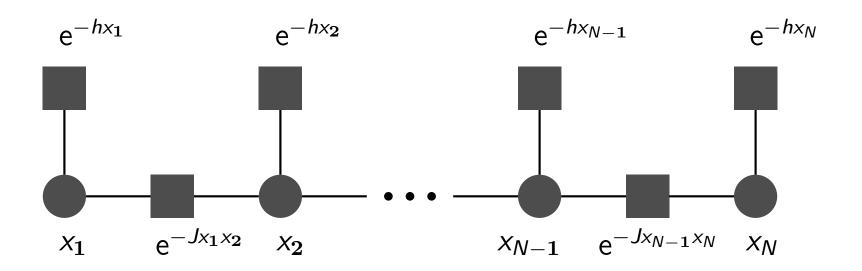
$$|\mathcal{T}_{P_{X,Y}}^{(2)}(N)| = C \prod_{x \in \mathcal{X}} {NP_X(x) \choose {NP_{X,Y}(x,y)}_{y \in \mathcal{X}}}.$$

[Whittle 1955] [Billingsley 1961].

$$|\mathcal{T}_{P_{X|Y}}^n| \approx \exp\{NH(X \mid Y)\}, \qquad P_X \approx P_Y$$

One-dimensional Ising model

$$p(\mathbf{x}) := \frac{1}{Z(N)} \exp \left\{ -J \sum_{i=1}^{N-1} x_i x_{i+1} - h \sum_{i=1}^{N} x_i \right\}$$
$$Z(N) := \sum_{\mathbf{x} \in \{+1, -1\}^N} \exp \left\{ -J \sum_{i=1}^{N-1} x_i x_{i+1} - h \sum_{i=1}^{N} x_i \right\}$$



The method of transfer matrix

$$Z_N(x_1,x_N) := \sum_{\mathbf{x} \in \{+1,-1\}^N} \exp \left\{ -J \sum_{i=1}^{N-1} x_i x_{i+1} - h \sum_{i=1}^N x_i \right\}.$$

$$\begin{bmatrix} Z_{N}(+1,+1) & Z_{N}(+1,-1) \\ Z_{N}(-1,+1) & Z_{N}(-1,-1) \end{bmatrix}$$

$$= \begin{bmatrix} Z_{N-1}(+1,+1) & Z_{N-1}(+1,-1) \\ Z_{N-1}(-1,+1) & Z_{N-1}(-1,-1) \end{bmatrix} \begin{bmatrix} \exp\{-J-h\} & \exp\{+J+h\} \\ \exp\{+J-h\} & \exp\{-J+h\} \end{bmatrix}$$

$$= \begin{bmatrix} \exp\{-h\} & 0 \\ 0 & \exp\{+h\} \end{bmatrix} \begin{bmatrix} \exp\{-J-h\} & \exp\{+J+h\} \\ \exp\{+J-h\} & \exp\{-J+h\} \end{bmatrix}^{N-1}$$

$$Z(N) = \sum_{(x_1,x_N)\in\mathcal{X}^2} Z_N(x_1,x_N) \sim \lambda_{\max}^N.$$

The method of types for Markov chain

$$Z(N) = \sum_{\mathbf{x} \in \{+1,-1\}^{N}} \exp \left\{ -J \sum_{i=1}^{N-1} x_{i} x_{i+1} - h \sum_{i=1}^{N} x_{i} \right\}$$

$$= \sum_{P_{S,T} \in \mathcal{P}_{N}^{(2)}} \left| \mathcal{T}_{P_{S,T}}^{(2)}(N) \right|$$

$$\cdot \exp \left\{ -J \sum_{(s,t) \in \{+1,-1\}^{2}} (N-1) P_{S,T}(s,t) st - h \sum_{t \in \{+1,-1\}} N P_{T}(t) t \right\}$$

$$\lim_{N \to \infty} \frac{1}{N} \log Z(N) = \sup_{P_{ST}, P_S = P_T} \{ H(S \mid T) - J\langle ST \rangle - h\langle T \rangle \}$$
$$= \sup_{P_{ST}, P_S = P_T} \{ H(S, T) - H(T) - J\langle ST \rangle - h\langle T \rangle \}$$

The maximization problem can be solved by the method of Lagrange multiplier.

Free energy of 1d Ising model 1/2

Lemma 1.

$$\lim_{N\to\infty}\frac{1}{N}\log Z_N=\operatorname{supextr}\left\{\log Z_{\mathsf{w}}-\log Z_{\mathsf{v}}\right\}.$$

where supextr stands for supremum among saddle points.

$$Z_{\mathsf{w}} = \sum_{(s,t)\in\{+1,-1\}^2} m_{\mathsf{LR} o\mathsf{v}}(t) m_{\mathsf{LR} o\mathsf{v}}(s) \exp\left\{-Jst - hs - ht\right\}$$
 $Z_{\mathsf{v}} = \sum_{t\in\{+1,-1\}} m_{\mathsf{LR} o\mathsf{v}}(t)^2 \exp\left\{-ht\right\}.$

The saddle point equation is

$$m_{\mathsf{LR} o\mathsf{v}}(t) = rac{1}{Z_{\mathsf{LR} o\mathsf{v}}} \sum_{s\in\{+1,-1\}} m_{\mathsf{LR} o\mathsf{v}}(s) \exp\left\{-Jst - hs\right\}.$$

This is the equation of belief propagation on the 1d Ising model of infinite size!

Free energy of 1d Ising model 2/2

$$\lim_{N\to\infty}\frac{1}{N}\log Z_N=\log Z_{\mathsf{LR}\to\mathsf{v}}$$

where

$$m_{\mathsf{LR} o \mathsf{v}}(t) = rac{1}{Z_{\mathsf{LR} o \mathsf{v}}} \sum_{(s,t) \in \{+1,-1\}^2} m_{\mathsf{LR} o \mathsf{v}}(s) \exp\left\{-Jst - hs\right\}.$$

Here, $Z_{LR\to\nu}$ and $m_{LR\to\nu}$ are eigenvalue and eigenvector of

$$\begin{bmatrix} \exp\{-J-h\} & \exp\{+J+h\} \\ \exp\{+J-h\} & \exp\{-J+h\} \end{bmatrix}$$

which is the transfer matrix. Hence,

$$\lim_{N\to\infty}\frac{1}{N}\log Z_N=\log \lambda_{\max}.$$

The method of types is useful for more complicated problems.

LDPC codes on memoryless channel

$$p(\mathbf{x} \mid \mathbf{y}) := \frac{1}{Z} \prod_{a} f(\mathbf{x}_{\partial a}) \prod_{i=1}^{N} W(y_i \mid x_i)$$

$$Z := \sum_{\mathbf{x} \in \mathcal{X}^N} \prod_{a} f(\mathbf{x}_{\partial a}) \prod_{i=1}^{N} W(y_i \mid x_i).$$

$$f(\mathbf{x}) := \mathbb{I} \left\{ \bigoplus_{j} x_j = 0 \right\}$$

$$p(\mathbf{y}) := \frac{1}{Z_0} \sum_{\mathbf{x} \in \mathcal{X}^N} \prod_{a} f(\mathbf{x}_{\partial a}) \prod_{i=1}^N W(y_i \mid x_i)$$

$$Z_0 := \sum_{\mathbf{x} \in \mathcal{X}^N} \prod_{a} f(\mathbf{x}_{\partial a}).$$

Conditional entropy and free energy

$$p(\mathbf{x} \mid \mathbf{y}) := \frac{1}{Z} \prod_{a} f(\mathbf{x}_{\partial a}) \prod_{i=1}^{N} W(y_i \mid x_i)$$

$$Z := \sum_{\mathbf{x} \in \mathcal{X}^N} \prod_{a} f(\mathbf{x}_{\partial a}) \prod_{i=1}^{N} W(y_i \mid x_i).$$

$$\mathbb{E}[H(X \mid Y)] = \mathbb{E}[\log Z] - \mathbb{E}[\log W(Y \mid X)]$$

Disordered system and replica method

$$\lim_{N \to \infty} \frac{1}{N} \mathbb{E}[\log Z] = \lim_{N \to \infty} \frac{1}{N} \frac{\partial \log \mathbb{E}[Z^n]}{\partial n} \bigg|_{n=0}$$

$$= \lim_{N \to \infty} \frac{1}{N} \lim_{n \to 0} \frac{1}{n} \log \mathbb{E}[Z^n] \stackrel{?}{\longleftarrow} \lim_{n \to 0} \frac{1}{n} \lim_{N \to \infty} \frac{1}{N} \log \mathbb{E}[Z^n]$$

For non-negative integer n,

$$Z^{n} = \left(\sum_{\mathbf{x} \in \mathcal{X}^{N}} \prod_{a} f(\mathbf{x}_{\partial a})\right)^{n} = \sum_{\mathbf{x} \in (\mathcal{X}^{n})^{N}} \prod_{a} \left(\prod_{i=1}^{n} f(\mathbf{x}_{\partial a}^{(i)})\right).$$

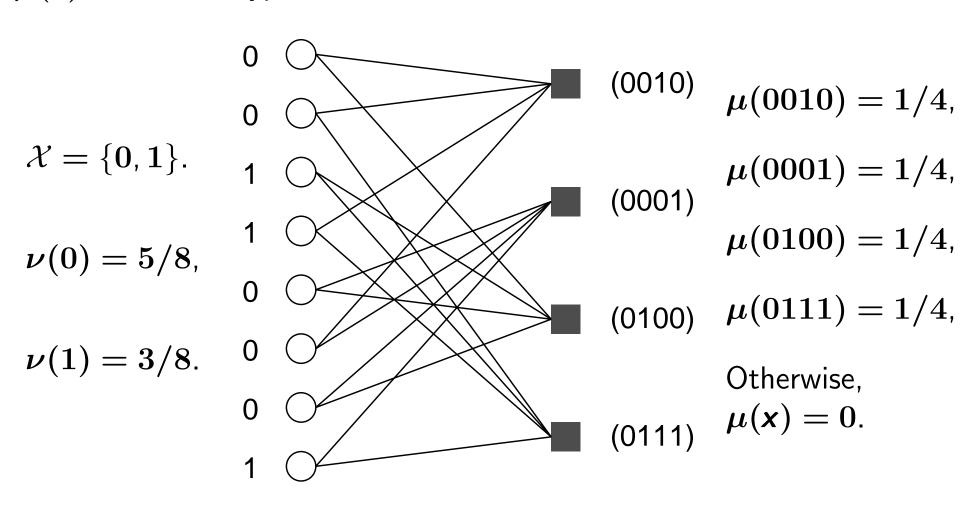
 Z^n can be regarded as a partition function of a new model in which

$$\mathcal{X} \longrightarrow \mathcal{X}^n$$

$$f(\mathbf{x}) \longrightarrow \prod_{i=1}^n f(\mathbf{x}^{(i)}).$$

Types on factor graphs [Vontobel 2010]

 $\nu(x), x \in \mathcal{X}$: a type of variable nodes $\mu(x), x \in \mathcal{X}^r$: a type of factor nodes



There is a constraint between $\nu(x)$ and $\mu(x)$. More precisely, $\nu(x)$ is uniquely determined from $\mu(x)$.

Contribution of particular types to a partition function

$$Z = \sum_{\mathbf{x} \in \mathcal{X}^{N}} \prod_{a} f(\mathbf{x}_{\partial a})$$

$$= \sum_{\nu, \mu} N(\nu, \mu) \prod_{\mathbf{x} \in \mathcal{X}^{r}} f(\mathbf{x})^{\frac{\ell}{r} N \mu(\mathbf{x})} =: \sum_{\nu, \mu} Z(\nu, \mu).$$

$$\mathbb{E}[N(\boldsymbol{\nu},\boldsymbol{\mu})] = \binom{N}{\{N\boldsymbol{\nu}(x)\}_{x\in\mathcal{X}}} \binom{\frac{\ell}{r}N}{\{\frac{\ell}{r}N\boldsymbol{\mu}(\boldsymbol{x})\}_{\boldsymbol{x}\in\mathcal{X}^r}} \frac{\prod_{x\in\mathcal{X}}(N\boldsymbol{\nu}(x)\ell)!}{(N\ell)!}.$$

$$\lim_{N\to\infty} \frac{1}{N} \log \mathbb{E}[Z(\nu,\mu)]$$

$$= \frac{\ell}{r} \mathcal{H}(\mu) - (\ell-1)\mathcal{H}(\nu) + \frac{\ell}{r} \sum_{\mathbf{x}\in\mathcal{X}^r} \mu(\mathbf{x}) \log f(\mathbf{x}).$$

Minus Bethe free energy of of mini (averaged) model [Mori 2011].

Free energy of LDPC codes on memoryless channel

$$\lim_{N \to \infty} \frac{1}{N} \log \mathbb{E}[Z^n] = \sup_{P_X, P_{U_1, \dots, U_r}} \left\{ \frac{1}{r} H(U_1, \dots, U_r) - (I - 1) H(X) + \frac{1}{r} \left\langle \log \prod_{k=0}^n f(\mathbf{U}^{(k)}) \right\rangle + \left\langle \log \left(\sum_{y \in \mathcal{Y}} \prod_{k=0}^n W(y \mid X^{(k)}) \right) \right\rangle \right\} - R$$

Here, X and U_1, \ldots, U_r are random variables on \mathcal{X}^{n+1} satisfying

■ X and U_K have the same distribution where K denotes the uniform random variable on a set $\{1, ..., r\}$.

The saddle point equation for replica symmetric solution is equivalent to the density evolution of the belief propagation [Mori 2011].

LDPC codes on general Markov channel

 \mathcal{S} : a set of states

 $V(t \mid y, x, s)$: a transition probability for $x \in \mathcal{X}$, $y \in \mathcal{Y}$ and $s, t \in \mathcal{S}$

$$p(\mathbf{x} \mid \mathbf{y}) := \frac{1}{Z} \sum_{\mathbf{s} \in \mathcal{S}^{N}} \prod_{a} f(\mathbf{x}_{\partial a}) \prod_{i=1}^{N} W(y_{i} \mid x_{i}, s_{i}) V_{0}(s_{1}) \prod_{i=1}^{N-1} V(s_{i+1} \mid y_{i}, x_{i}, s_{i})$$

$$Z := \sum_{\mathbf{x} \in \mathcal{X}^{N}} \sum_{\mathbf{s} \in \mathcal{S}^{N}} \prod_{a} f(\mathbf{x}_{\partial a}) \prod_{i=1}^{N} W(y_{i} \mid x_{i}, s_{i})$$

$$\cdot V_{0}(s_{1}) \prod_{i=1}^{N-1} V(s_{i+1} \mid y_{i}, x_{i}, s_{i}).$$

Free energy of LDPC codes on general Markov channel

Main result of this work

$$\lim_{N \to \infty} \frac{1}{N} \log \mathbb{E}[Z^n] = \sup \left\{ H(X_1, S_1 \mid X_2, S_2) - IH(X_1, S_1) + \frac{l}{r} H(U_1, \dots, U_r, T_1, \dots, T_r) + \frac{l}{r} \left\langle \log \prod_{k=0}^n f(\mathbf{U}^{(k)}) \right\rangle + \left\langle \log \left(\sum_{y \in \mathcal{Y}} \prod_{k=0}^n W(y \mid X_2^{(k)}, S_2^{(k)}) V(S_1^{(k)} \mid y, X_2^{(k)}, S_2^{(k)}) \right) \right\rangle \right\} - R.$$

- \blacksquare (X_1, S_1) and (X_2, S_2) have the same distribution
- (X_1, S_1) and (U_K, T_K) have the same distribution where K denotes the uniform random variable on a set $\{1, ..., r\}$.

The saddle point equation is equivalent to the density evolution of the belief propagation (joint iterative decoder).

The dicode erasure channel

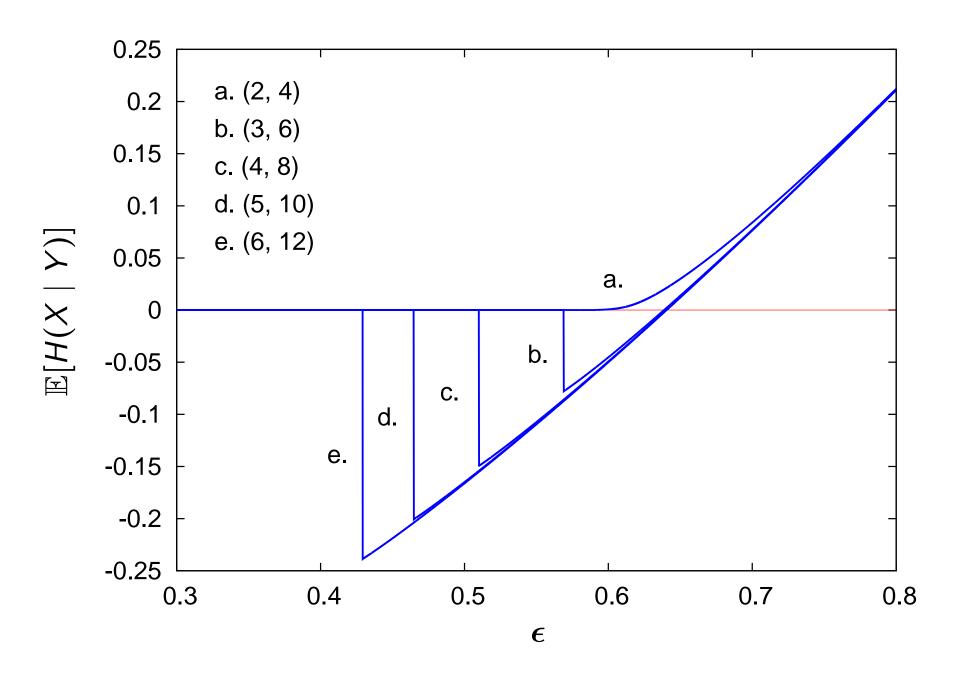
 $\mathsf{DEC}(\epsilon)$ is defined for $\mathcal{X} = \mathcal{S} = \{0,1\}$, $\mathcal{Y} = \{-1,0,+1,*\}$ as

$$W(y \mid x, s) =$$

$$\begin{cases} 1 - \epsilon, & y = x - s \\ \epsilon, & y = * \end{cases}$$
 $V(s' \mid y, x, s) = 1, \quad \text{for } s' = x.$

The density evolution can be described by one parameter [Pfister and Siegel 2008].

Numerical calculation for the DEC(ϵ)



Summary, future works and open problem

Summary

- The method of types is useful for analysis of LDPC codes on memoryless channels (previous result)
- The method of types for Markov chain is useful for analysis of LDPC codes on Markov channels

Future works

- Analysis of IRA/ARA LDPC codes
- Compressed sensing of Markov source

Open problem

Types for two-dimensional Markov chain e.g., two dimensional Ising model.