| Task | term | estimate | std.error | conf.low | conf.high | statistic | p.value |
| --- | --- | --- | --- | --- | --- | --- | --- |
| Handgrip | (Intercept) | -0.07 | 0.55 | -1.18 | 1.04 | -0.13 | 0.897 |
| Handgrip | meanhr\_react\_Handgrip | -0.06 | 0.06 | -0.19 | 0.06 | -1.03 | 0.306 |
| Handgrip | eda.avg\_react\_Handgrip | 0.17 | 0.23 | -0.29 | 0.64 | 0.74 | 0.461 |
| Handgrip | expected\_stress\_Handgrip | 0.01 | 0.02 | -0.02 | 0.05 | 0.73 | 0.468 |
| Handgrip | task\_orderPhysical first | 0.16 | 0.89 | -1.62 | 1.94 | 0.18 | 0.860 |
| N-back | (Intercept) | -0.56 | 0.74 | -2.04 | 0.91 | -0.76 | 0.448 |
| N-back | `meanhr\_react\_N-back` | -0.01 | 0.12 | -0.26 | 0.24 | -0.08 | 0.940 |
| N-back | `eda.avg\_react\_N-back` | -0.61 | 0.36 | -1.34 | 0.11 | -1.69 | 0.097 |
| N-back | `expected\_stress\_N-back` | 0.06 | 0.02 | 0.02 | 0.10 | 2.74 | 0.008 |
| N-back | task\_orderPhysical first | 1.22 | 1.16 | -1.10 | 3.54 | 1.06 | 0.295 |