# Detection of Breathing and Heartbeat Through Snow Using a Microwave Transceiver

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4 Abstract—The potential of a continuous-wave microwave trans-5 ceiver as a tool for detecting breathing and heartbeat of people 6 buried in snow has been experimentally evaluated. The breathing 7 has been clearly detected through a 1.8-m-thick snow barrier as 8 well as through the 1.2-m-thick roof of an igloo dugout to simulate 9 the experimental conditions of a human being trapped under an 10 avalanche.

11 *Index Terms*—Biomedical signal detection, radar, remote 12 sensing.

## I. Introduction

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14 N ONCONTACT microwave transceivers for sensing breathing and heartbeat have been proposed since the 16 early 1970s [1]. The current state-of-art in the field of mi-17 crowave technology has made it possible to construct small and 18 simple devices for this purpose [2], [3]. Several applications 19 of noncontact microwave transceivers have been proposed as 20 diagnostic tools in the biomedical field [1], as enforcement tools 21 [4] for detecting human beings behind walls, and as rescue tools 22 for finding survivors trapped under rubble [5].

The latter is a very challenging application for a number of 24 reasons. Rubble can be a very attenuating medium, particularly 25 if metallic grids are embedded. Furthermore, as rubble is a 26 very inhomogeneous medium, local discontinuities can act as 27 backscatterers and therefore can irradiate the operator, thus, 28 preventing the detector from being able to distinguish between 29 the operator's signal and that of the survivor. For these reasons, 30 the application of microwave transceivers in detecting human 31 beings trapped under rubble has often been disappointing.

A step of intermediate difficulty is the use of microwave 33 transceivers for detecting the breathing and/or the heartbeat 34 of people trapped under snow after an avalanche. In contrast 35 to rubble, snow is a rather homogeneous medium, which can 36 almost be transparent to microwave propagation, when it is dry. 37 Although some papers report the use of penetrating radar for 38 localizing people under snow [6], [7], to the best knowledge 39 of the authors of this letter, microwave sensing of breathing 40 and/or the heartbeat through snow has not been reported in the 41 scientific literature.

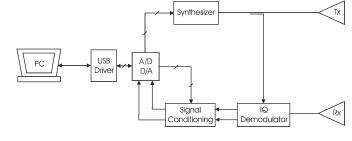


Fig. 1. Block scheme of the transceiver.

## II. Transceiver

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The instrument is a microwave coherent transceiver that 43 irradiates a monochromatic wave in the field of view covered 44 by two directional antennas (transmit and receive). The receiver 45 detects the in-phase (I) and quadrature (Q) components of 46 the backscattered field. This signal can be represented in the 47 I-Q plane as a generic phasor, whose amplitude and phase are 48 sensitive to movement on the order of a fraction of wavelength. 49

Fig. 1 shows the block scheme of the transceiver. It is based 50 on a standard homodyne architecture with a phase-locked loop 51 synthesizer at 2.42 GHz.

The choice of frequency involves a tradeoff between the 53 increased penetration depth of lower frequencies and the in-54 creased phase shift due to breathing and/or heartbeat at higher 55 frequencies. A frequency of some gigahertz can be an effective 56 tradeoff. In particular, we have chosen 2.42 GHz that is in 57 the Instrumental Scientific Medical band and does not need a 58 specific license.

The two antennas are four-element patch arrays. The half- 60 power beamwidth is  $20^{\circ}$ . Fig. 2 shows the transceiver in oper- 61 ating conditions.

The radiated microwave power was 10 mW with 12-dB 63 antenna gain, which meets the International Commission on 64 Non-Ionizing Radiation Protection guidelines [7] even at a 65 distance of a few centimeters from the antennas.

# III. EXPERIMENTAL RESULTS 67

The transceiver was tested in two different experimental 68 setups: a snow barrier and an igloo.

An accumulation of snow was used as a 180-cm-thick snow 71 barrier. After the test, it was sectioned as shown in Fig. 3, and 72 samples of the four identified zones were taken. The densities 73

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Fig. 2. Picture of the transceiver in operating conditions.

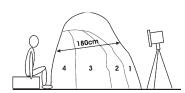


Fig. 3. Experimental setup simulating a snow barrier.

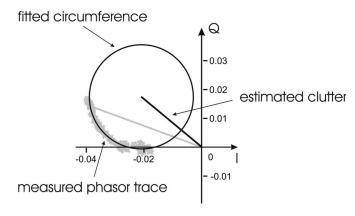


Fig. 4. Phasor of the measured signal.

74 of the four zones were measured by using a short pipe to 75 sample a known volume of snow, and the following values were 76 obtained: 80, 150, 385, and 450 kg/m<sup>3</sup>. The first three layers 77 were fresh and soft snow; the last one was a mix of snow, ice, 78 and rocks.

A volunteer (one of the authors) was sitting on a chair, 80 hidden behind the snow barrier. The volunteer was wearing 81 winter clothes. The transceiver was positioned on a tripod on 82 the opposite side. The measured phasor, shown in Fig. 4, lies on 83 a circumference, whose center is located by the phasor of static 84 clutter, whereas the rotating phasor is the signal to be detected. 85 Since the experimental phasor describes an arc of circumfer-86 ence, the phasor of the static clutter can be removed by finding 87 the center of the circumference that best fits the measured 88 phasor trace. An effective algorithm for this operation is the

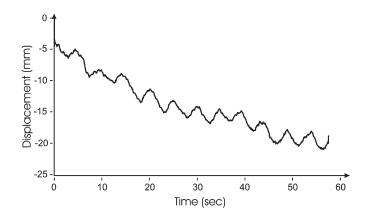


Fig. 5. Displacement versus time in the case of the experimental setup sketched in Fig. 3.

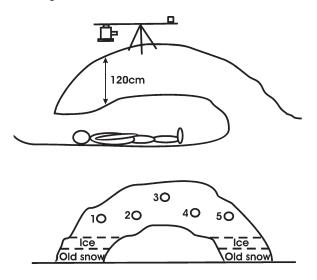


Fig. 6. Experimental setup simulating a human being trapped under an avalanche.

nonlinear minimum square Levenberg–Marquardt method [8], 89 [9] with a parameterization proposed by Chernov–Lesort [10]. 90 After clutter removal, the phase differences  $\Delta \varphi$  were directly 91 related to the displacements  $\Delta s$  of the chest of the volunteer, 92 by the following basic equation:

$$\Delta \varphi = \frac{4\pi}{\lambda} \Delta s \tag{1}$$

where  $\lambda$  is the wavelength. Fig. 5 shows the measured displace- 94 ment. The periodic movement of the chest due to breathing is 95 quite evident. The detected breathing rate is 0.21 Hz. 96

An igloo was built to simulate the condition of a human 98 being trapped under an avalanche. The density of the snow was 99 probed in five points as shown in Fig. 6 and the following values 100 were obtained: 246, 254, 240, 208, and 210 kg/m<sup>3</sup>.

The volunteer laid down and remained immobile. The thick- 102 ness of the snow above the volunteer was about 120 cm. 103 The breathing movement detected by the transceiver, shown 104 in Fig. 7, appears very clearly. The detected breathing rate 105 is 0.24 Hz.

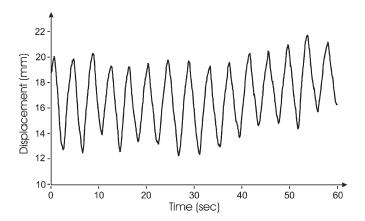


Fig. 7. Breathing detected by the transceiver in the experimental setup sketched in Fig. 6.

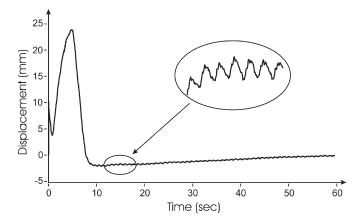


Fig. 8. Trace obtained during an apnoea showing the heartbeat signal.

107 To detect the heartbeat as well, the volunteer was asked to 108 hold his breath for a few seconds (apnoea). The resulting signal, 109 shown in Fig. 8, shows that a heartbeat can also be easily 110 detected through a snow barrier thicker than 1 m. The detected 111 heartbeat rate is 1.08 Hz.

### IV. CONCLUSION 112

The experimental results reported in this letter demonstrate 114 that a continuous-wave microwave transceiver is able to detect 115 breathing and heartbeat through a snow barrier.

Nevertheless, further investigations are needed to simulate 117 more difficult conditions. Indeed, the snow used in the de-118 scribed experiments was rather dry, so the positive results 119 obtained are not particularly surprising. The capability of microwave transceivers to operate through wet snow and snow 120 thickness of several meters should also be investigated and 121 the effective operation depth should be evaluated. Other open 122 questions can be investigated. For example, how the posture, 123 the size, or the gender of the possible victim can affect the 124 detection.

Finally, the effective operability as a rescue tool in real 126 conditions has to be proven. The current conventional methods 127 used to locate buried avalanche victims using wearable trans- 128 ceivers have proven to be highly effective, but of course they 129 require the victim to be wearing a transceiver. The microwave 130 method described in this letter does not require the victim to 131 wear any electronic device, but nonetheless there are severe 132 practical and logistical implications about the deployment of 133 a radar in the very short time available for a successful rescue. 134 Indeed, a transceiver based on the principle described in this 135 communication, surely will never be able to substitute the 136 wearable transceivers, but it can provide a useful help for 137 scouring victims that do not wear equipment for localization.

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