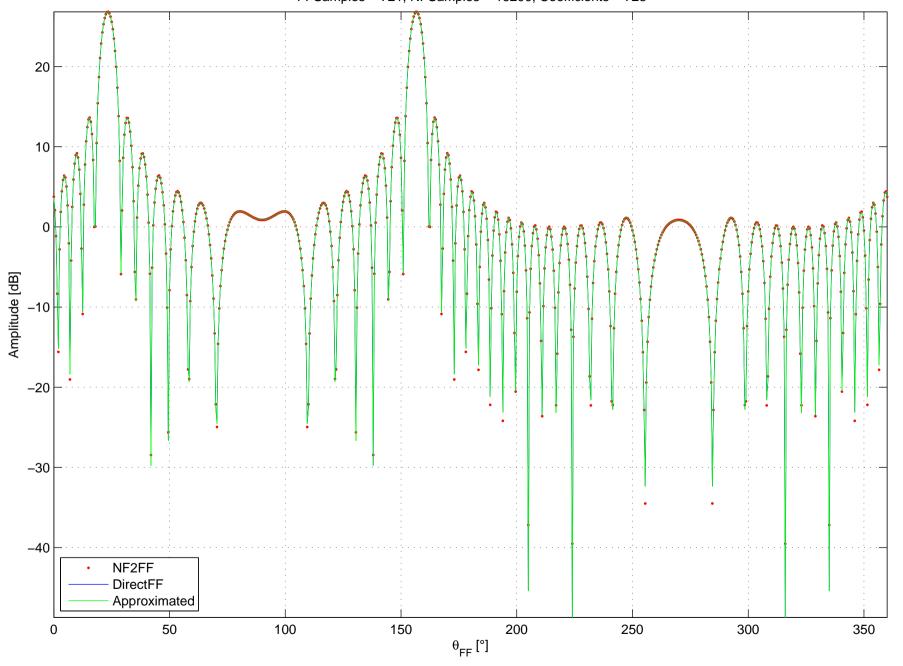
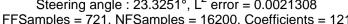
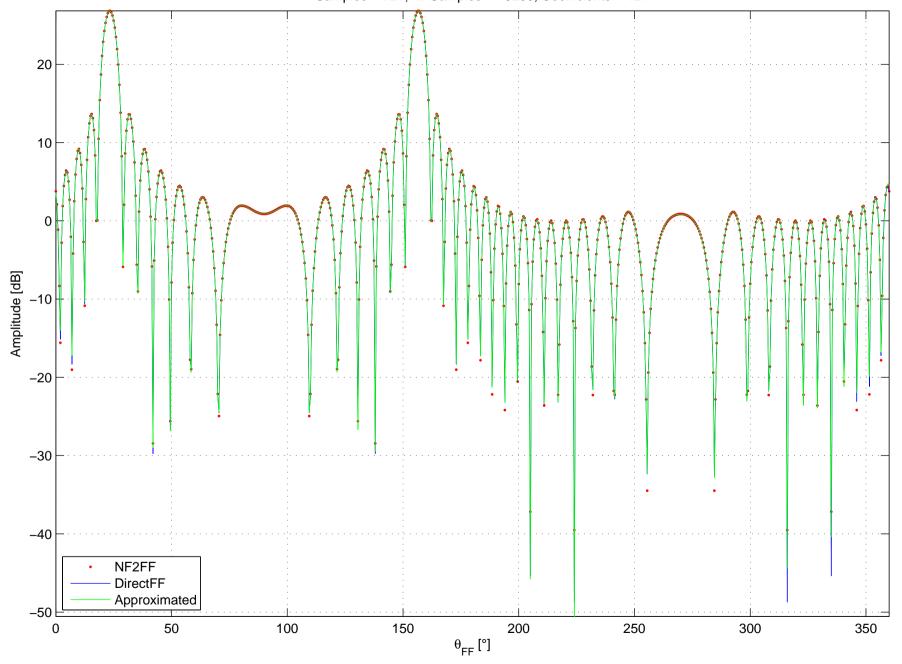
$22 \times 0.5 \lambda$, Rad : 5.75λ Steering angle : 23.3251° , L² error = 1.8781e-015FFSamples = 721, NFSamples = 16200, Coefficients = 723

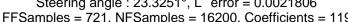


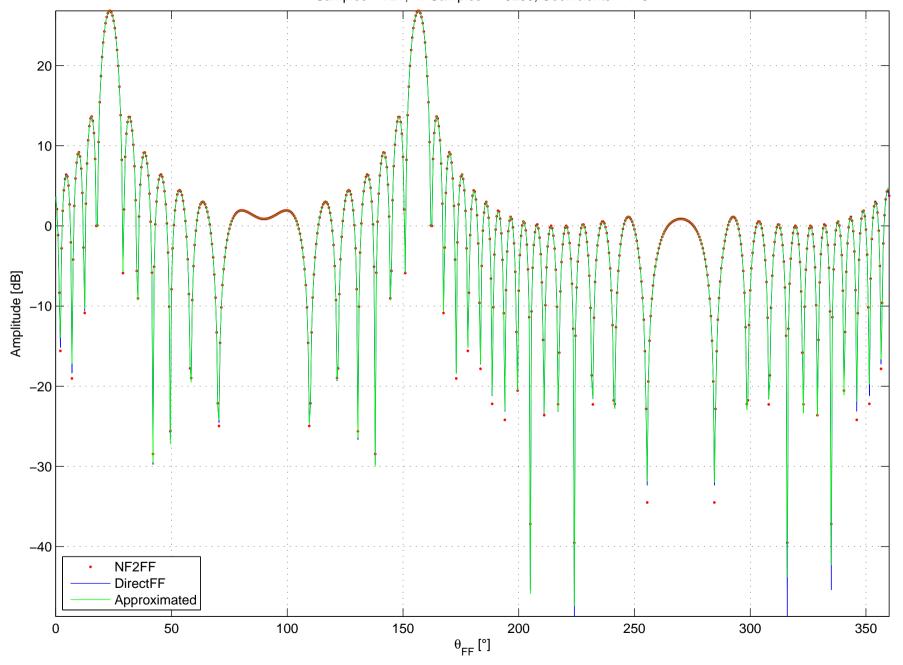
 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.0021308 FFSamples = 721, NFSamples = 16200, Coefficients = 121



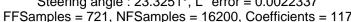


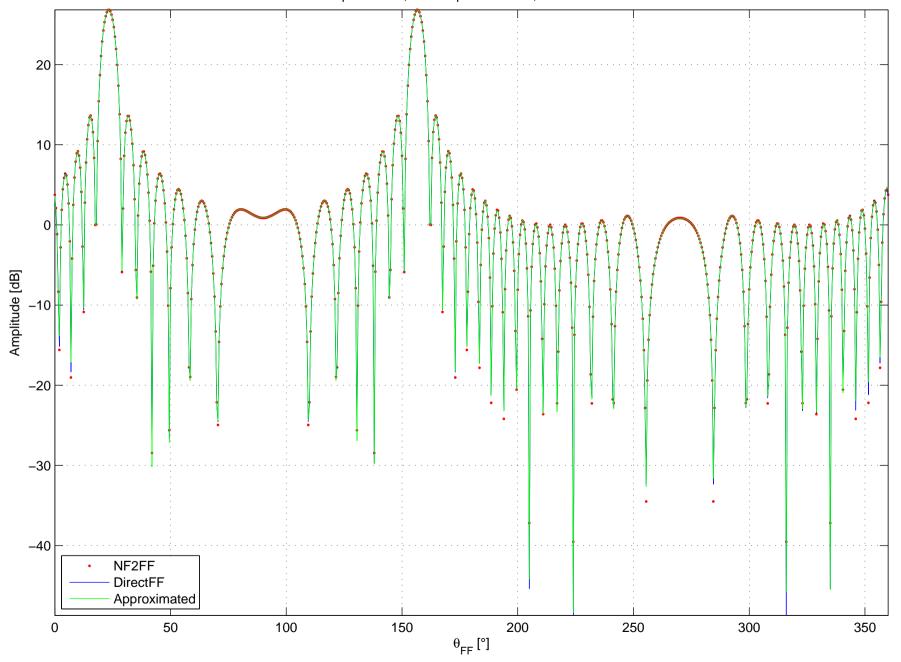
 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.0021806 FFSamples = 721, NFSamples = 16200, Coefficients = 119



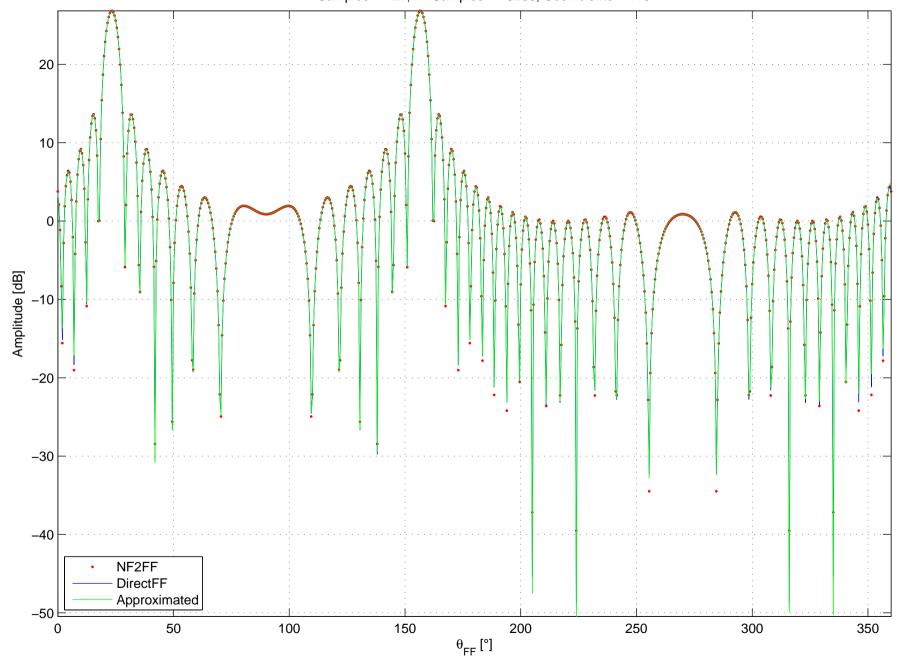


 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ $Steering \, angle: 23.3251^{\circ}, \, L^2 \, error = 0.0022337$ $FFSamples = 721, \, NFSamples = 16200, \, Coefficients = 117$

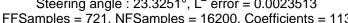


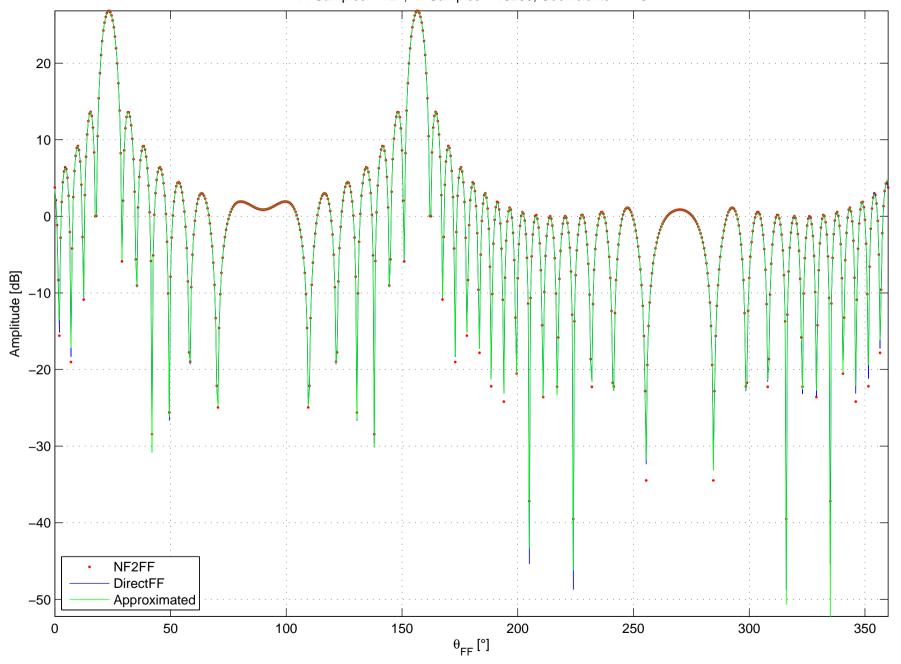


 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.0022905 FFSamples = 721, NFSamples = 16200, Coefficients = 115

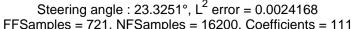


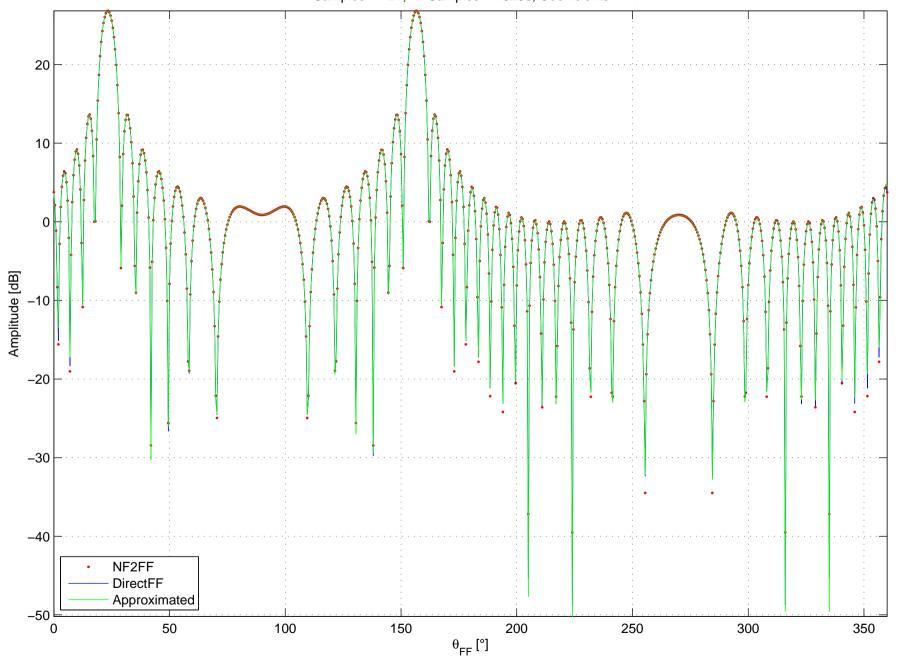
 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.0023513 FFSamples = 721, NFSamples = 16200, Coefficients = 113



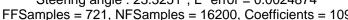


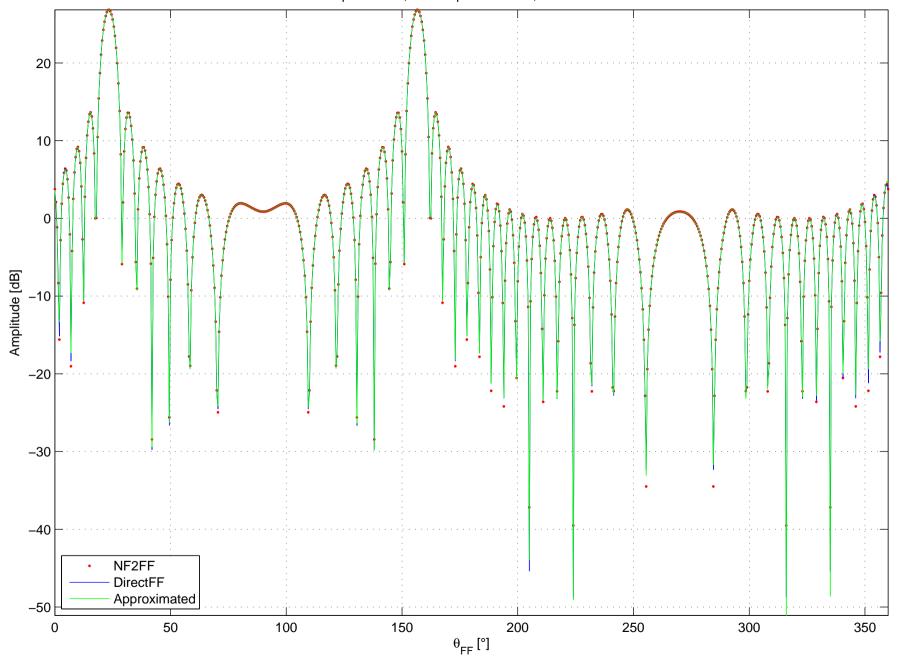
 $22 \times 0.5 \lambda, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.0024168 FFSamples = 721, NFSamples = 16200, Coefficients = 111



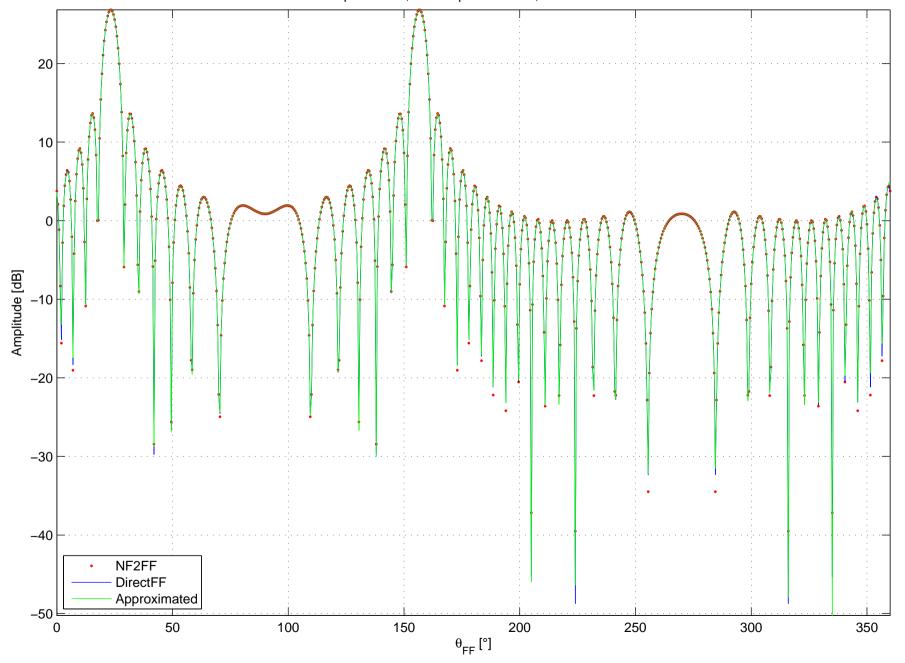


 $22 \times 0.5 \lambda, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.0024874 FFSamples = 721, NFSamples = 16200, Coefficients = 109

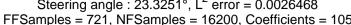


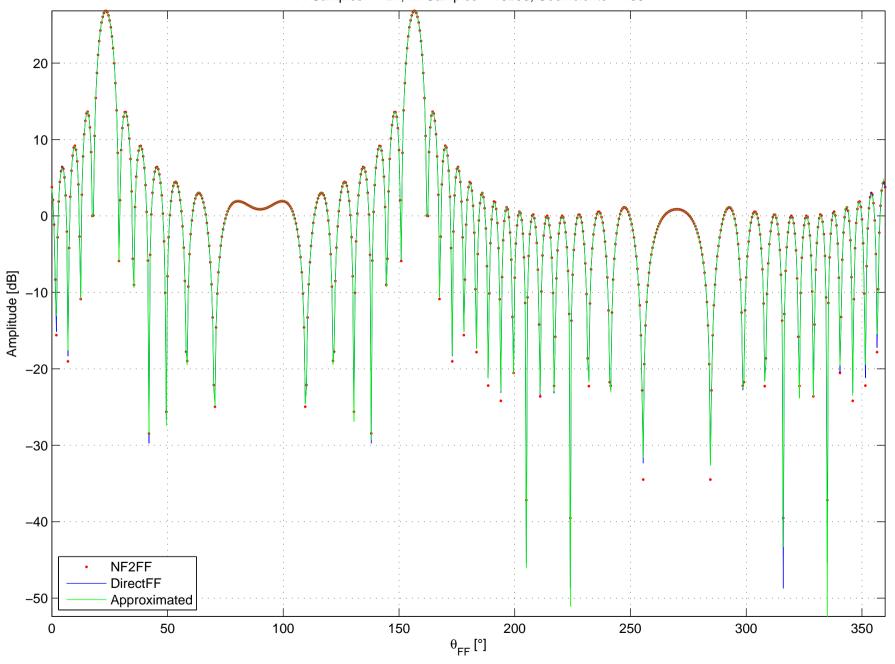


 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ $Steering \, angle: 23.3251^{\circ}, \, L^2 \, error = 0.0025638$ $FFSamples = 721, \, NFSamples = 16200, \, Coefficients = 107$

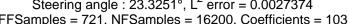


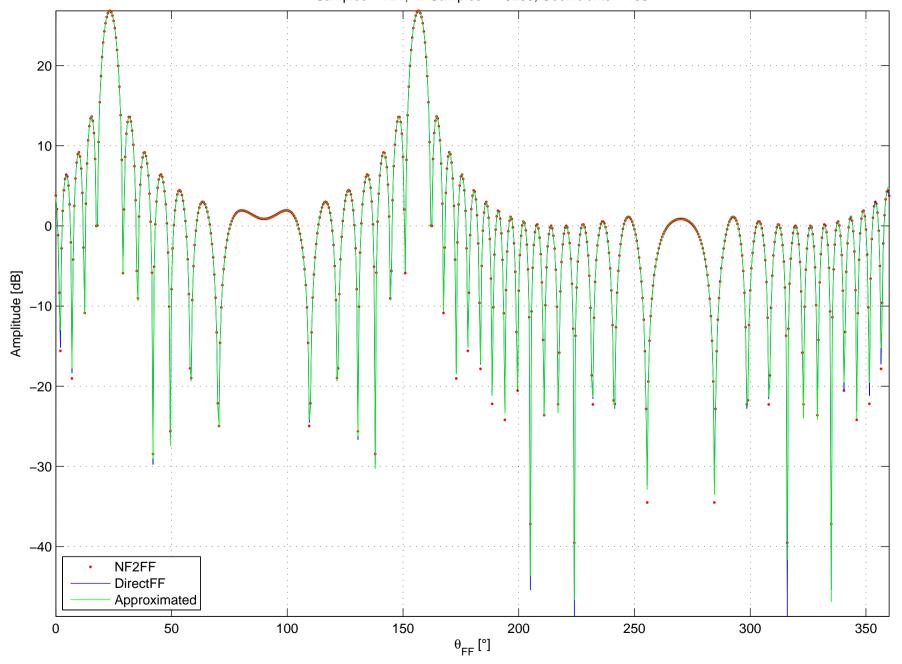
 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ $Steering \, angle: 23.3251^{\circ}, \, L^2 \, error = 0.0026468$ $FFSamples = 721, \, NFSamples = 16200, \, Coefficients = 105$



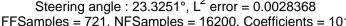


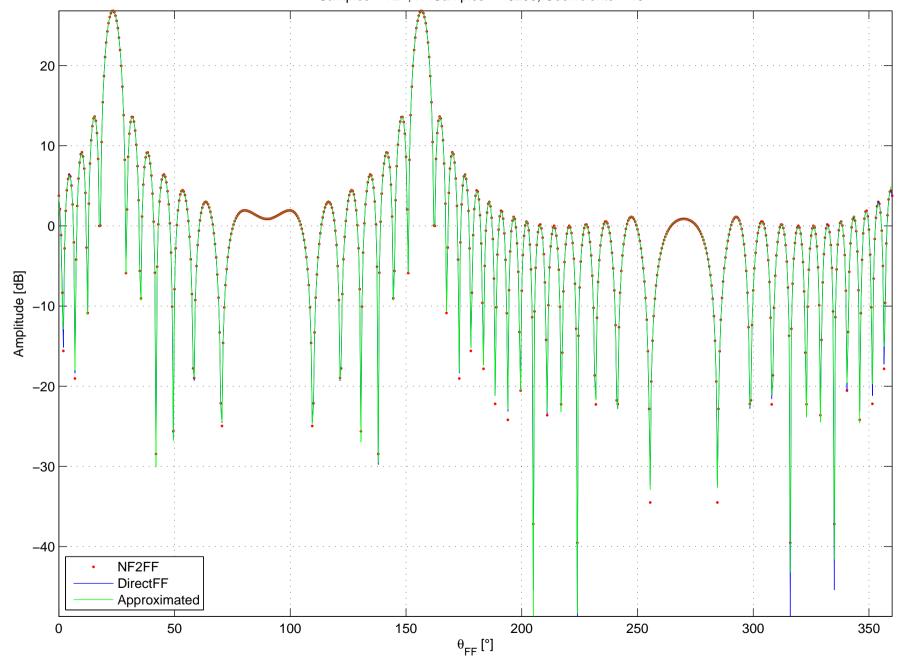
 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.0027374 FFSamples = 721, NFSamples = 16200, Coefficients = 103



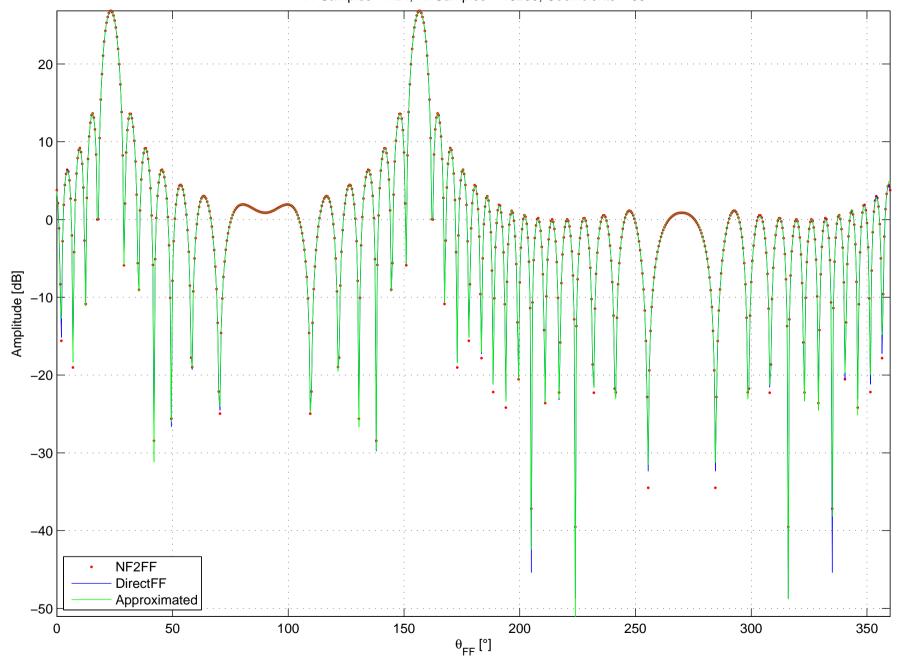


 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.0028368 FFSamples = 721, NFSamples = 16200, Coefficients = 101

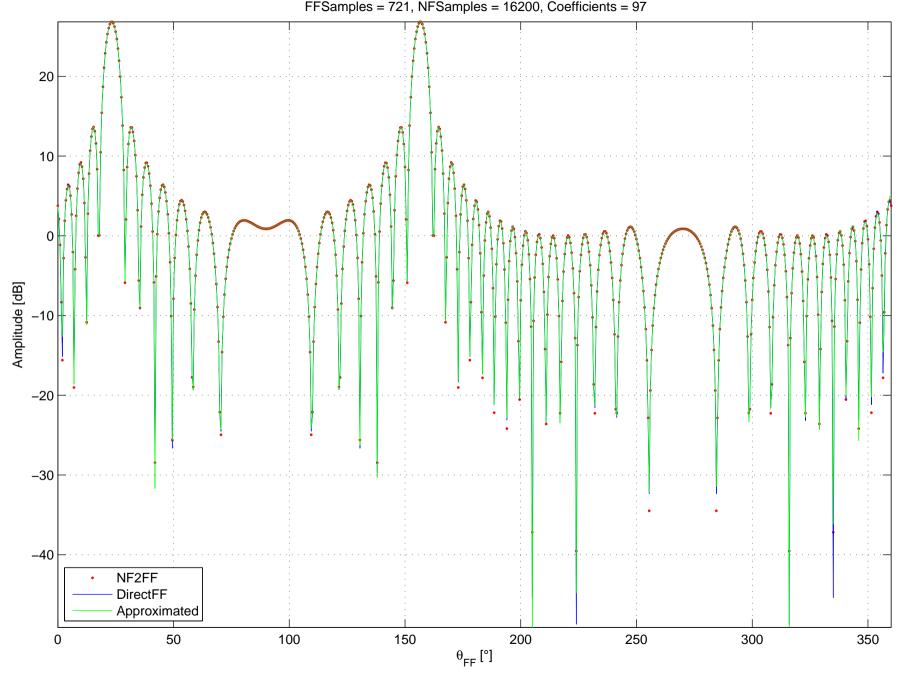




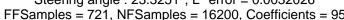
 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.0029462 FFSamples = 721, NFSamples = 16200, Coefficients = 99

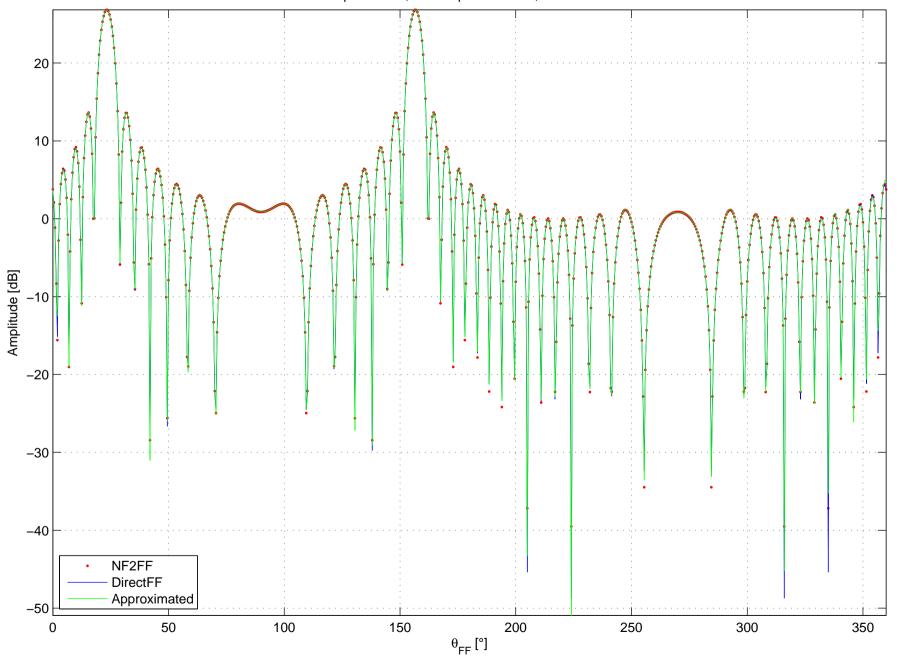


 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.0030678 FFSamples = 721, NFSamples = 16200, Coefficients = 97

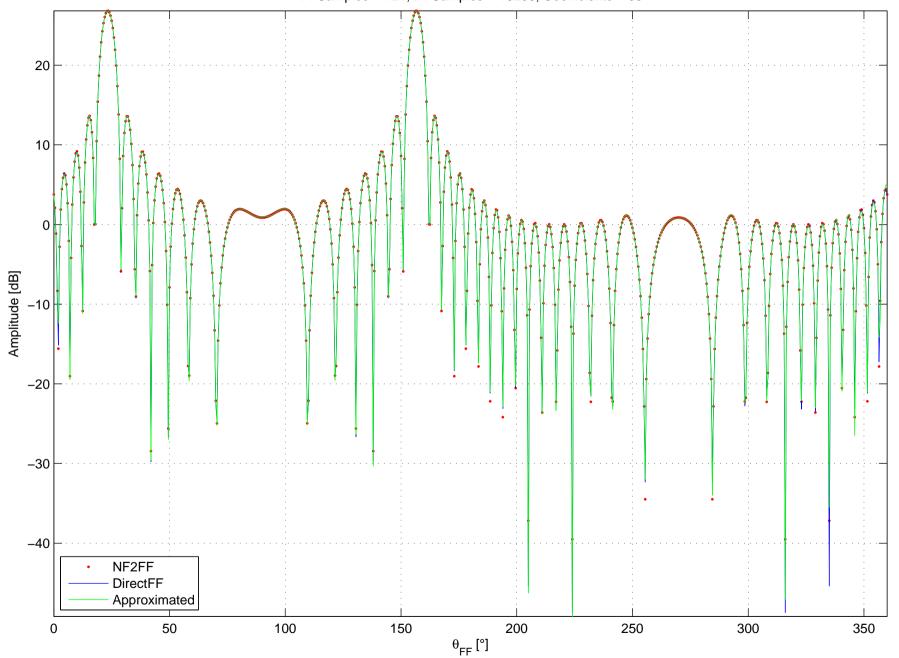


 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.0032026 FFSamples = 721, NFSamples = 16200, Coefficients = 95

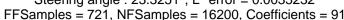


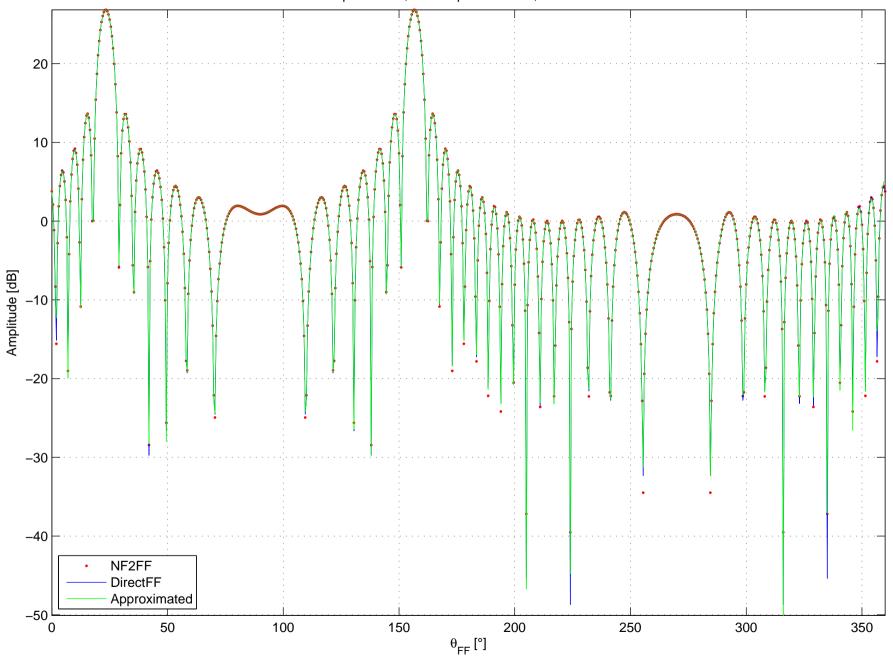


 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.0033563 FFSamples = 721, NFSamples = 16200, Coefficients = 93

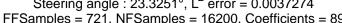


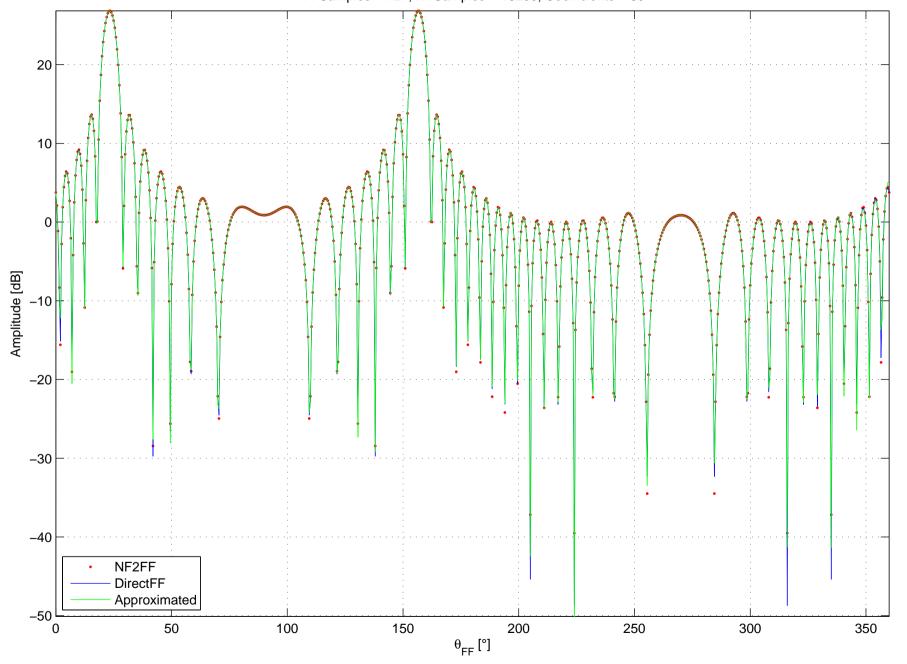
 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.0035232 FFSamples = 721, NFSamples = 16200, Coefficients = 91



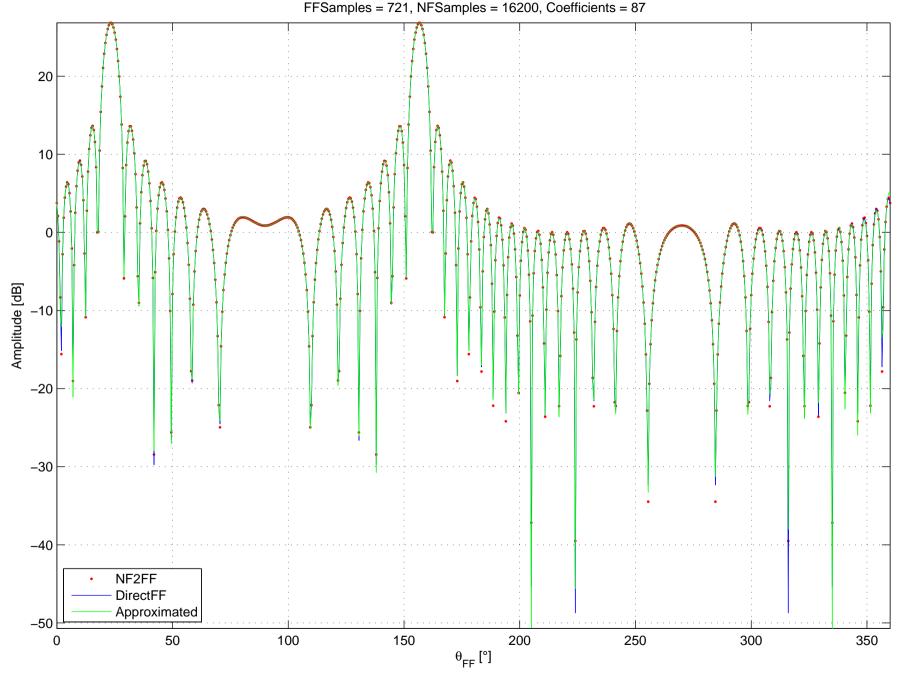


 $22 \times 0.5 \lambda, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.0037274 FFSamples = 721, NFSamples = 16200, Coefficients = 89

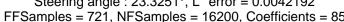


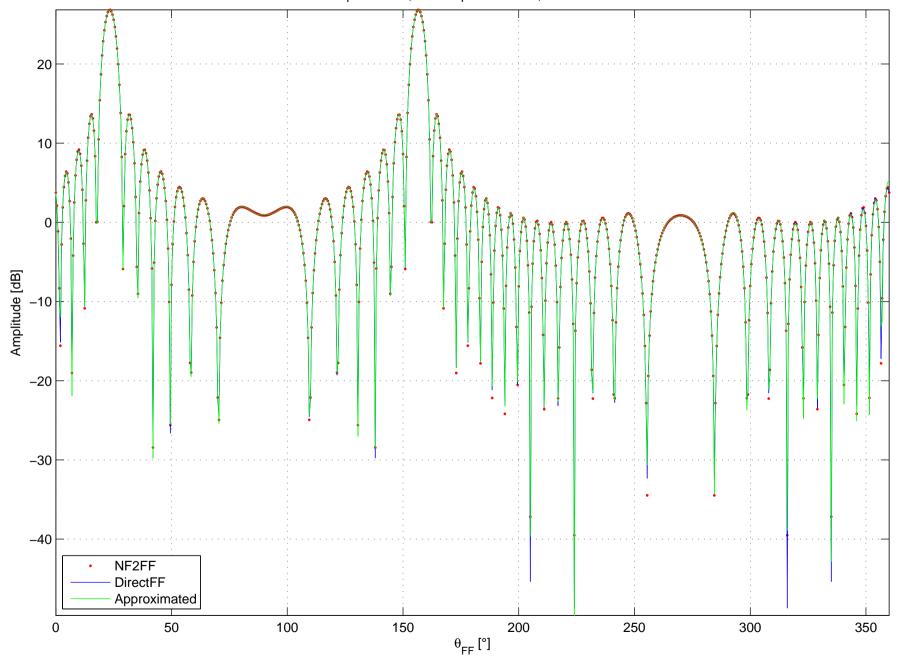


 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.0039208 FFSamples = 721, NFSamples = 16200, Coefficients = 87

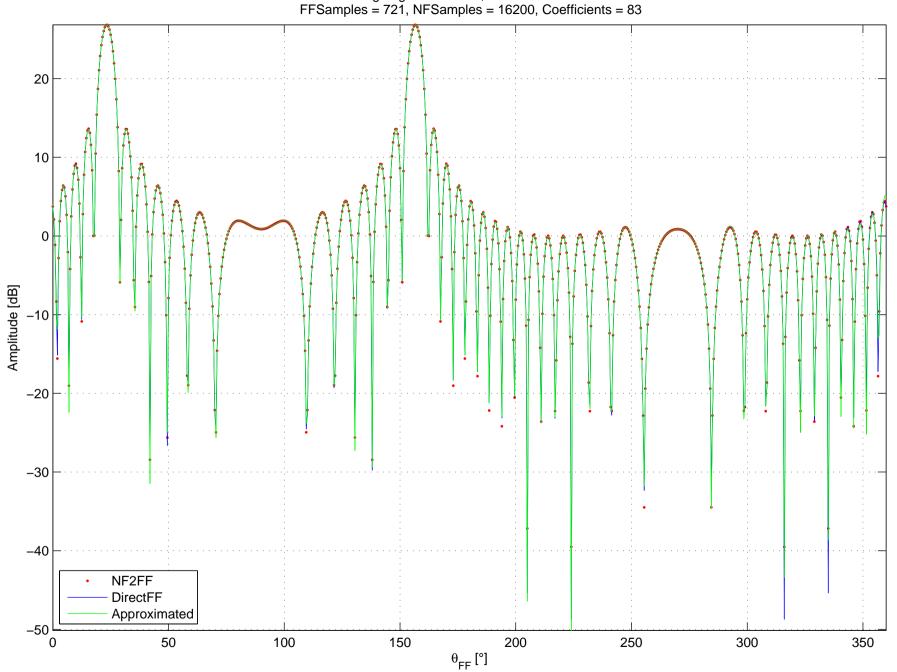


 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.0042192 FFSamples = 721, NFSamples = 16200, Coefficients = 85

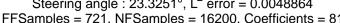


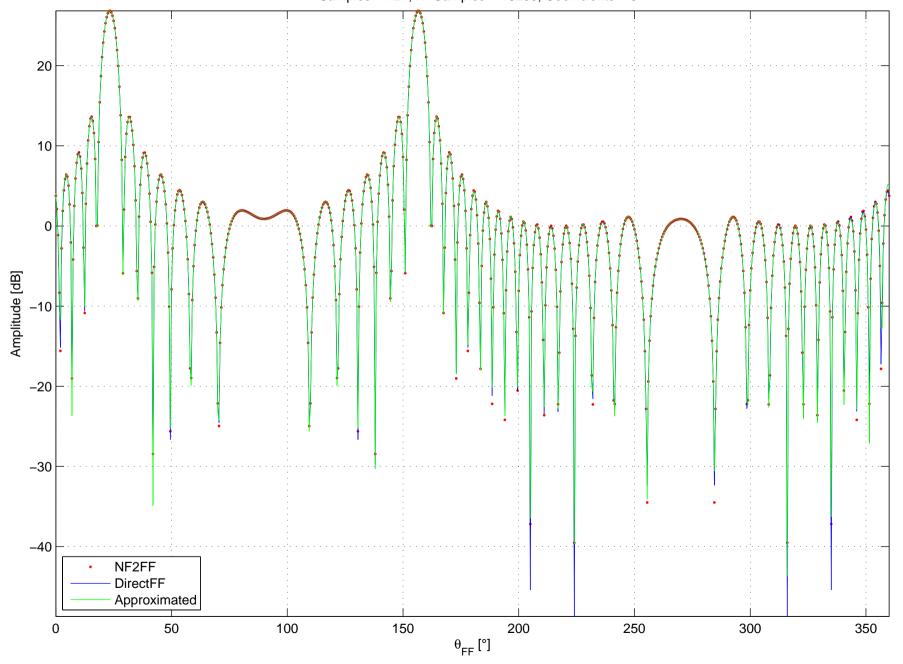


 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.0043577 FFSamples = 721, NFSamples = 16200, Coefficients = 83

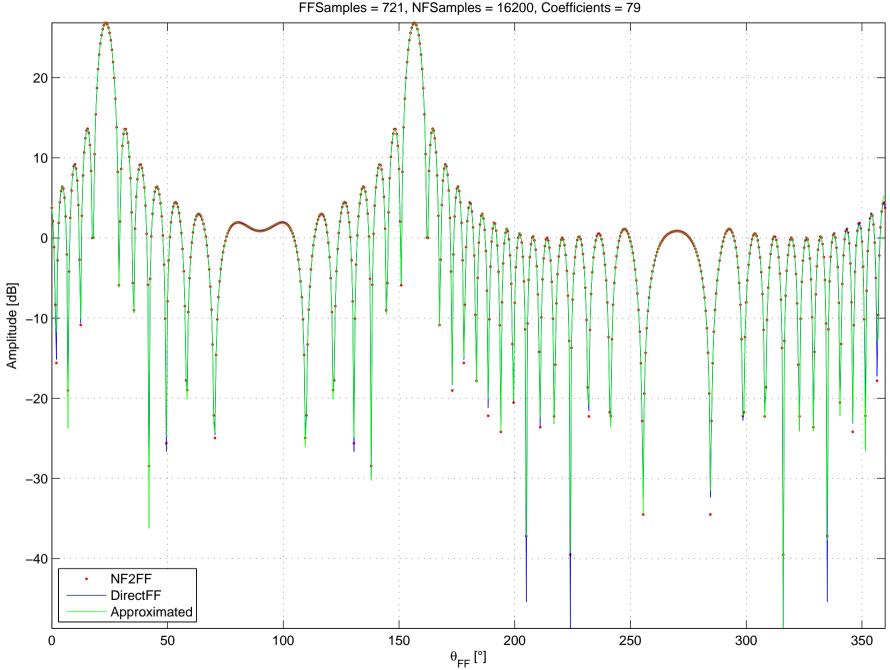


 $22 \times 0.5 \lambda, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.0048864 FFSamples = 721, NFSamples = 16200, Coefficients = 81

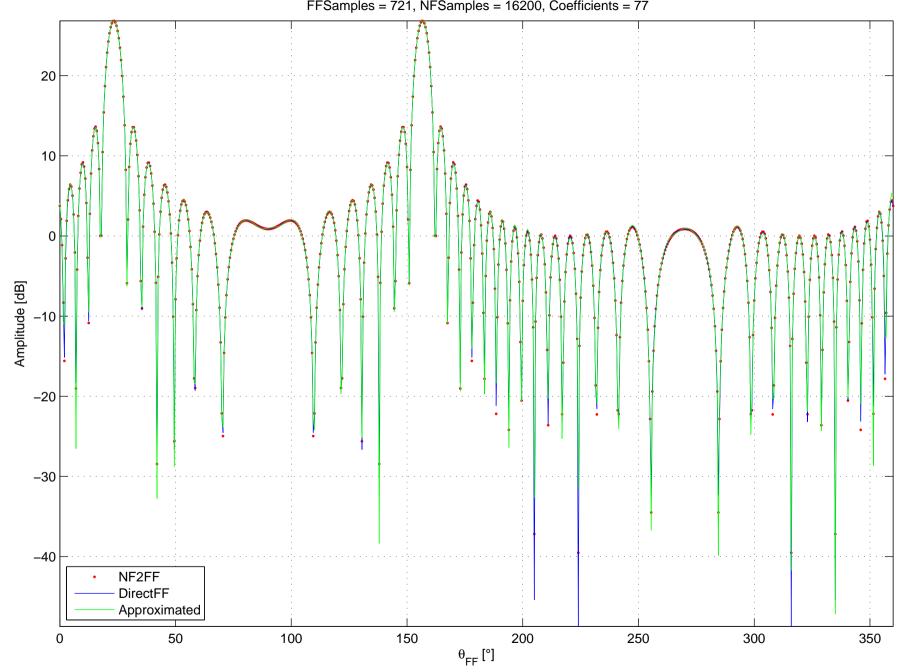


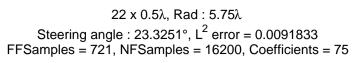


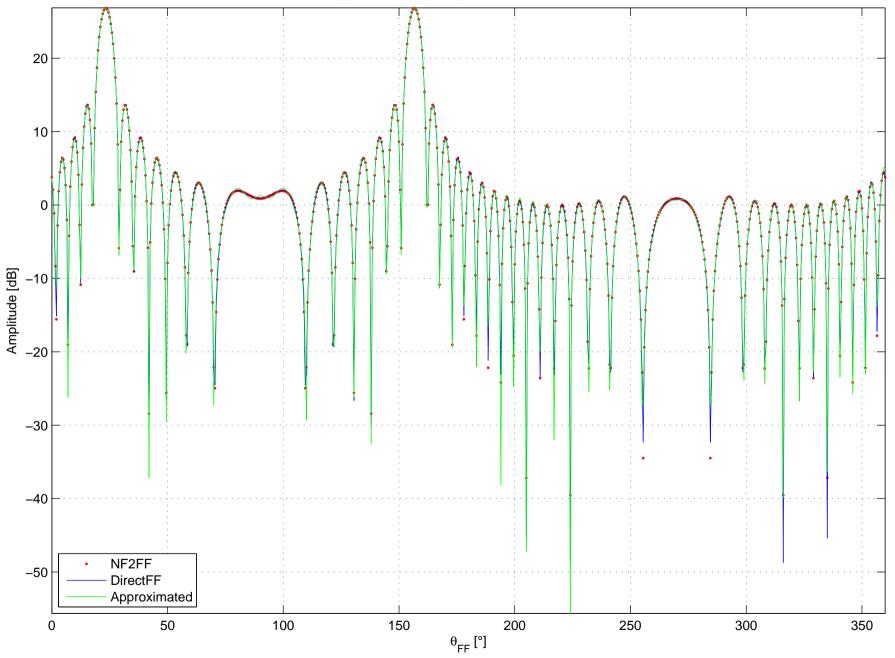
 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.0049184 FFSamples = 721, NFSamples = 16200, Coefficients = 79



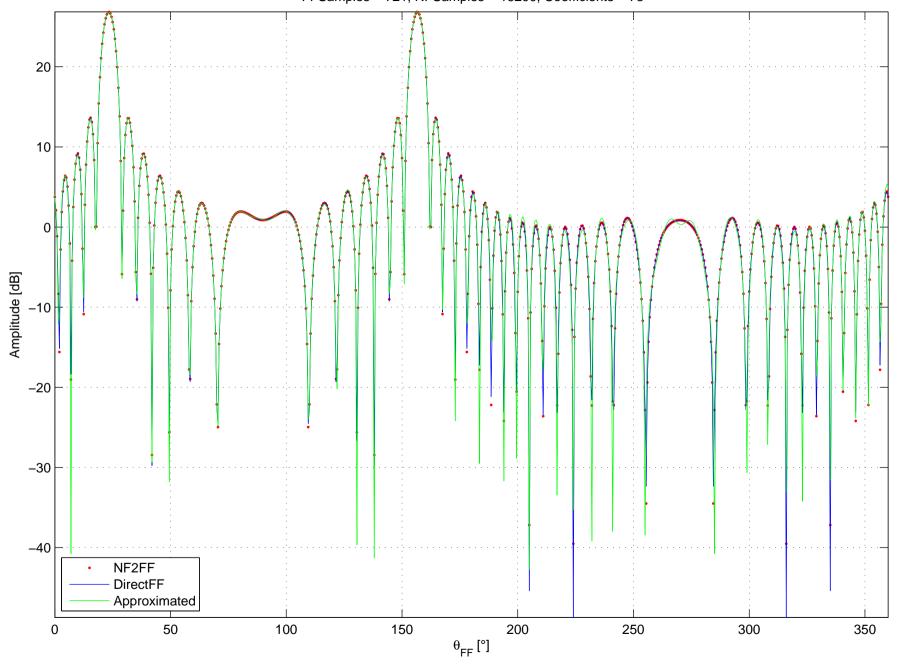
 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.0062441 FFSamples = 721, NFSamples = 16200, Coefficients = 77



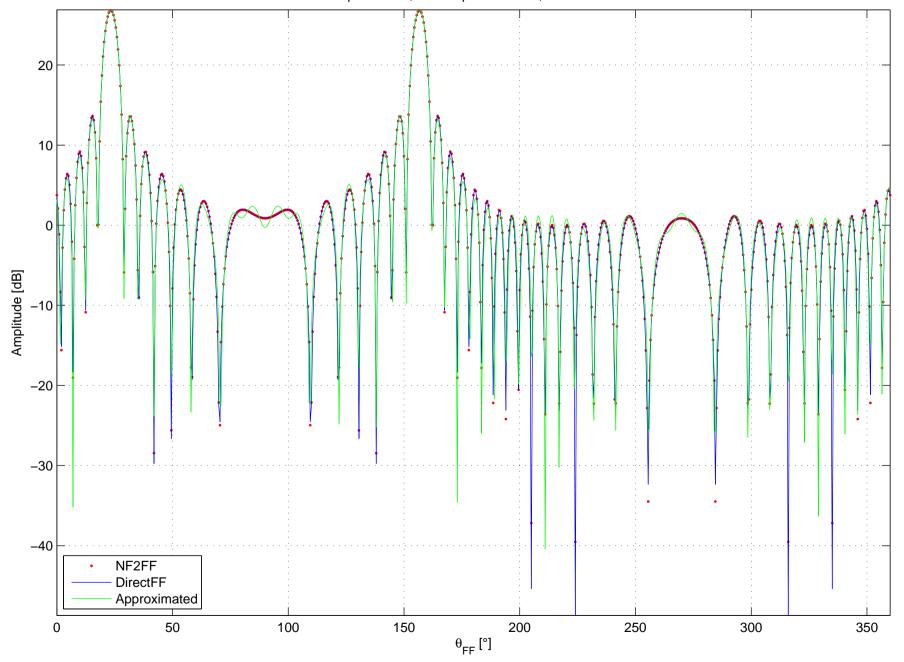




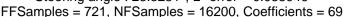
 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.012417 FFSamples = 721, NFSamples = 16200, Coefficients = 73

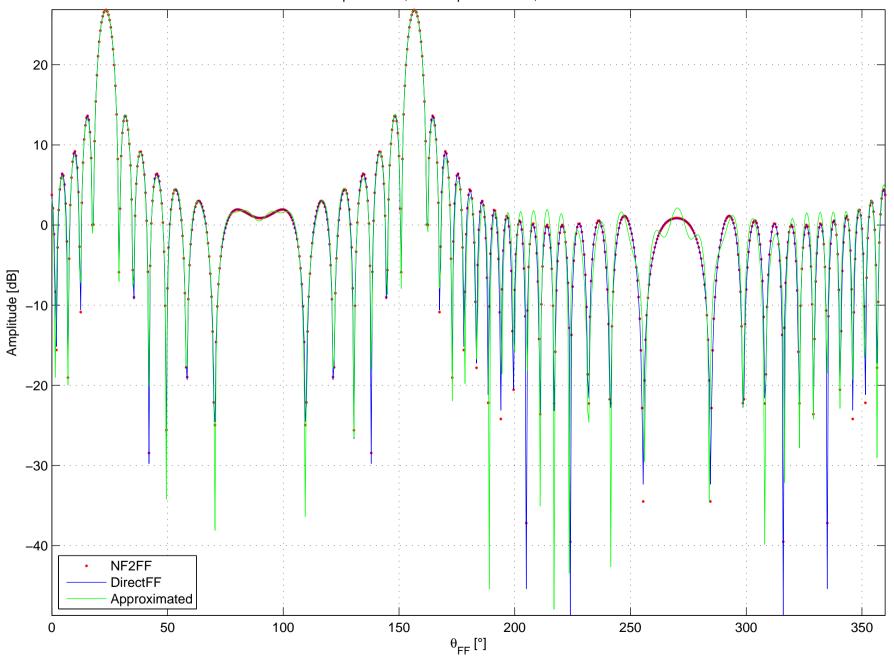


 $22 \times 0.5 \lambda$, Rad : 5.75λ Steering angle : 23.3251° , L² error = 0.028891FFSamples = 721, NFSamples = 16200, Coefficients = 71

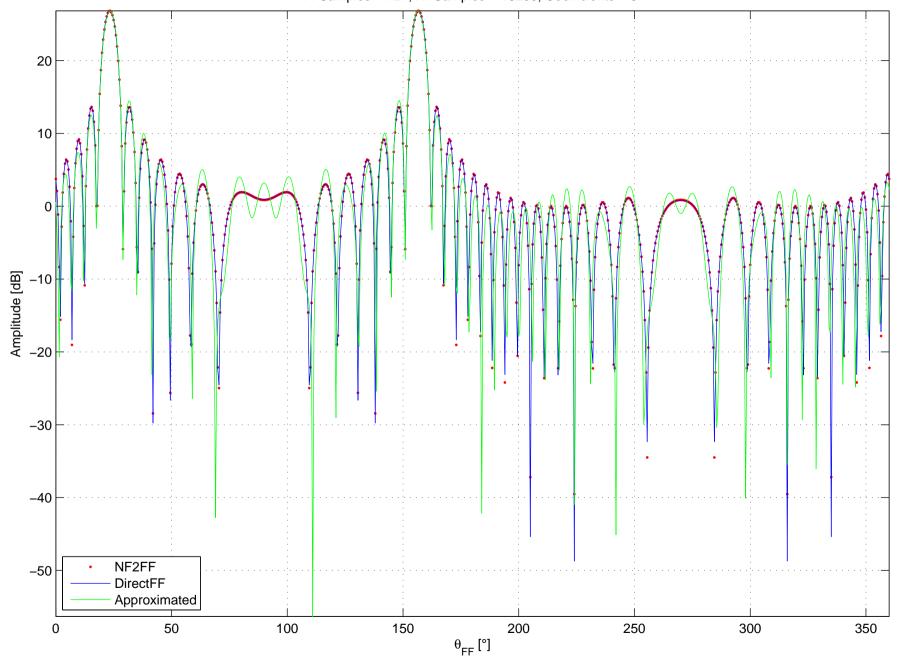


 $22 \times 0.5 \lambda$, Rad : 5.75λ Steering angle : 23.3251° , L² error = 0.033946FFSamples = 721, NFSamples = 16200, Coefficients = 69

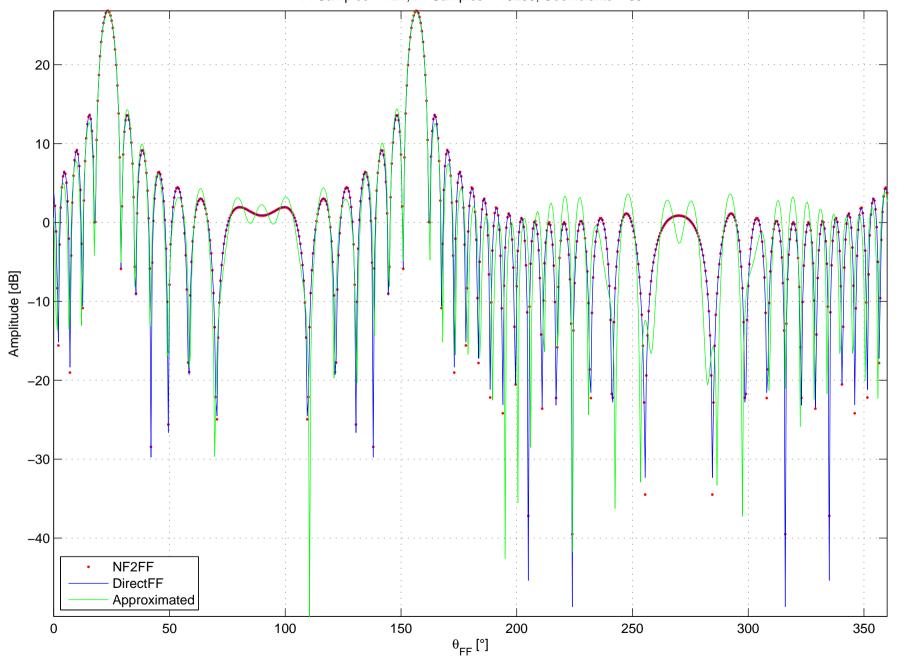




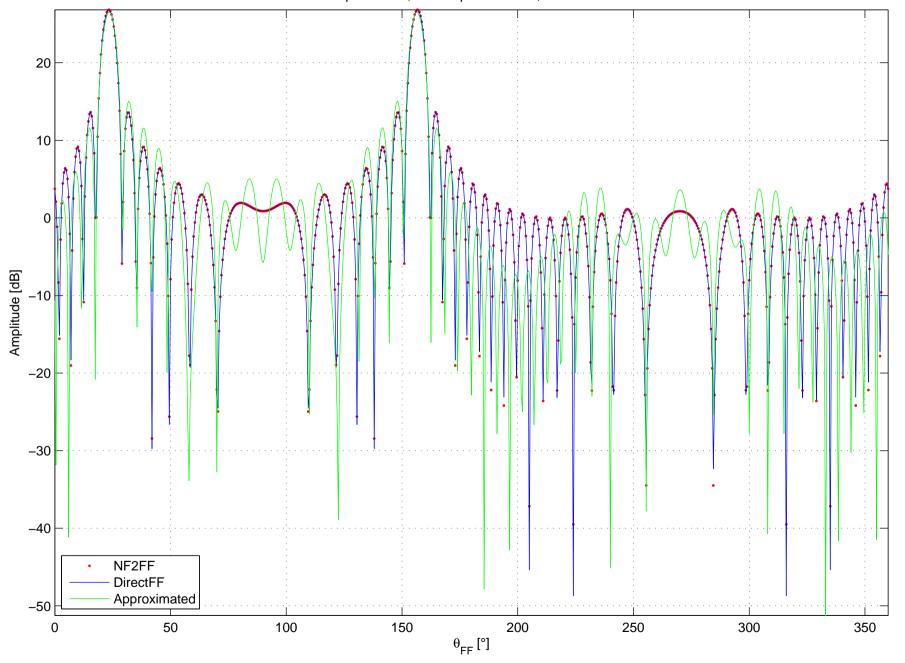
 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.077542 FFSamples = 721, NFSamples = 16200, Coefficients = 67



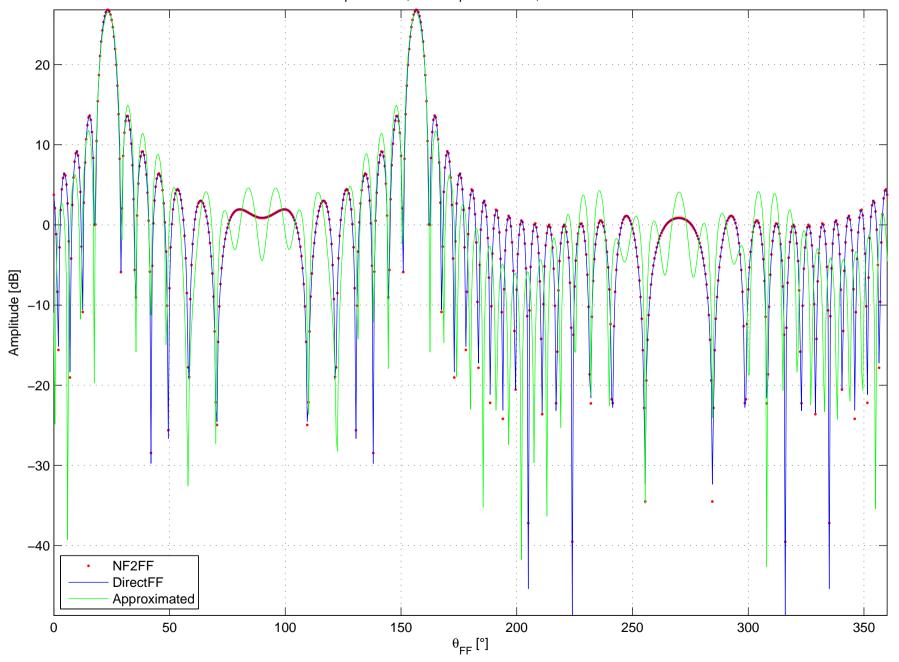
 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.082385 FFSamples = 721, NFSamples = 16200, Coefficients = 65



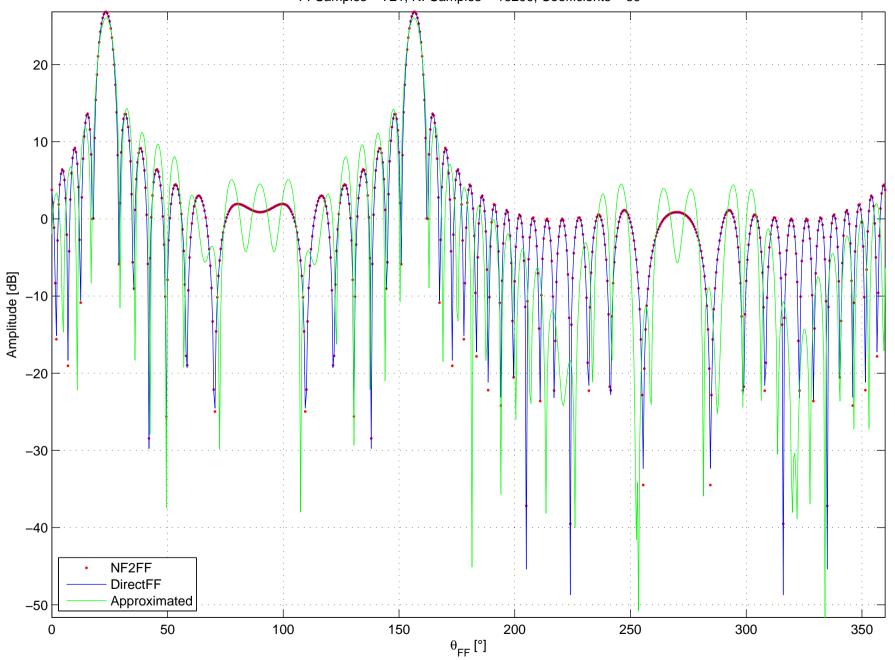
 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.16303 FFSamples = 721, NFSamples = 16200, Coefficients = 63



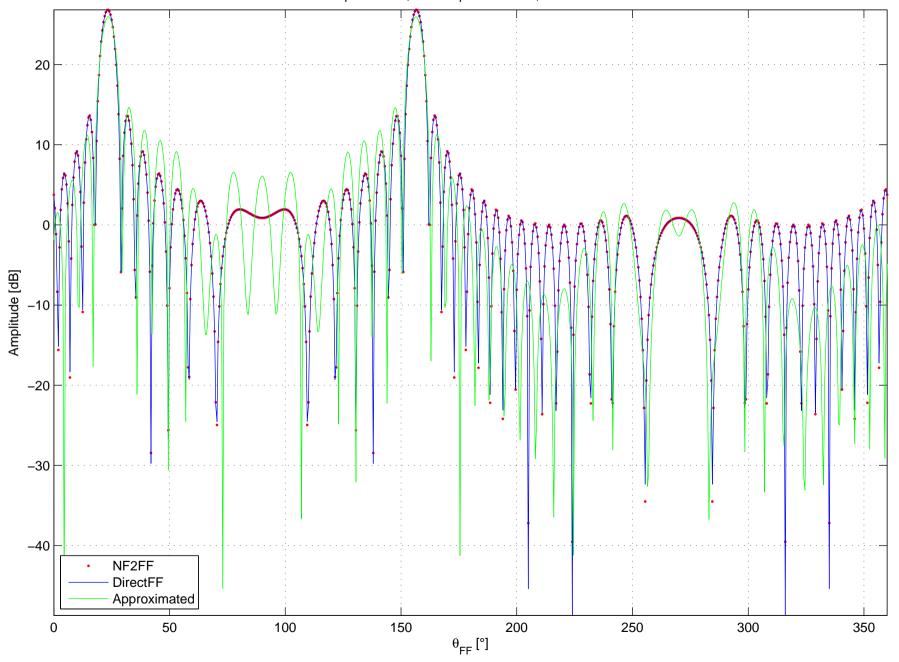
 $22 \times 0.5 \lambda$, Rad : 5.75λ Steering angle : 23.3251° , L² error = 0.16373FFSamples = 721, NFSamples = 16200, Coefficients = 61



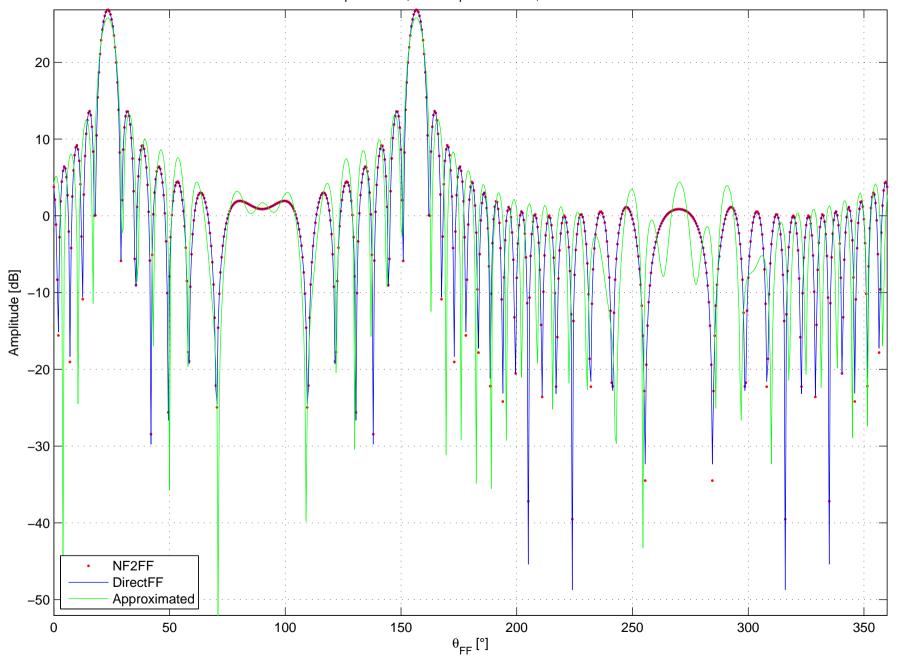
 $22 \times 0.5 \lambda, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.25485 FFSamples = 721, NFSamples = 16200, Coefficients = 59



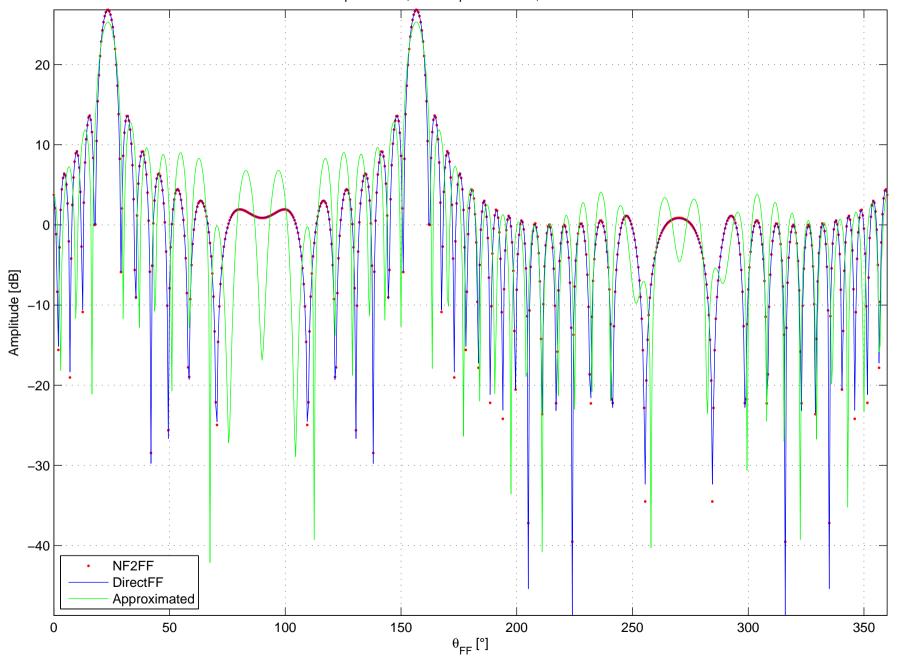
 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.26197 FFSamples = 721, NFSamples = 16200, Coefficients = 57



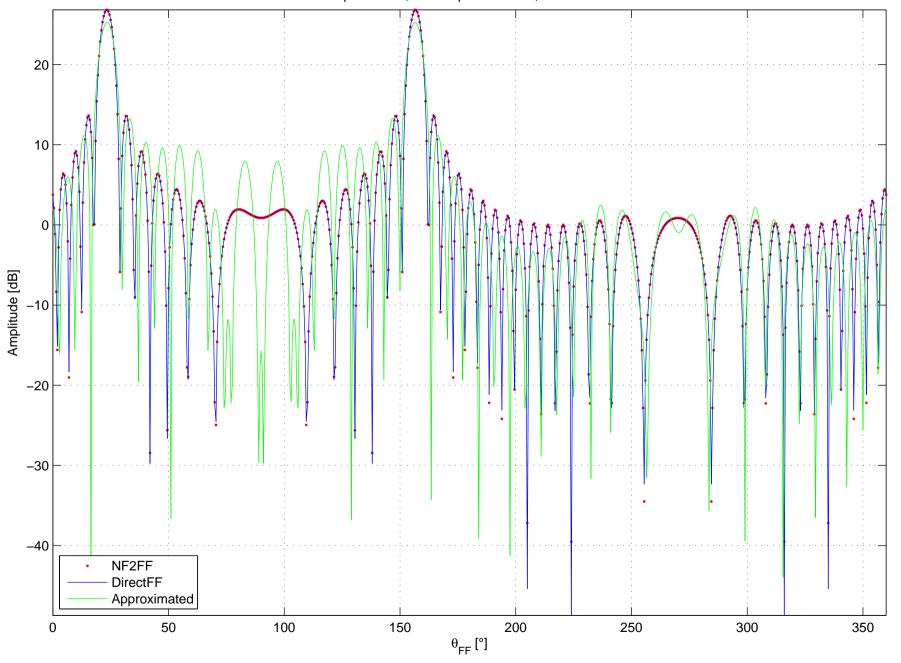
 $22 \times 0.5 \lambda$, Rad : 5.75 λ Steering angle : 23.3251°, L² error = 0.29928 FFSamples = 721, NFSamples = 16200, Coefficients = 55



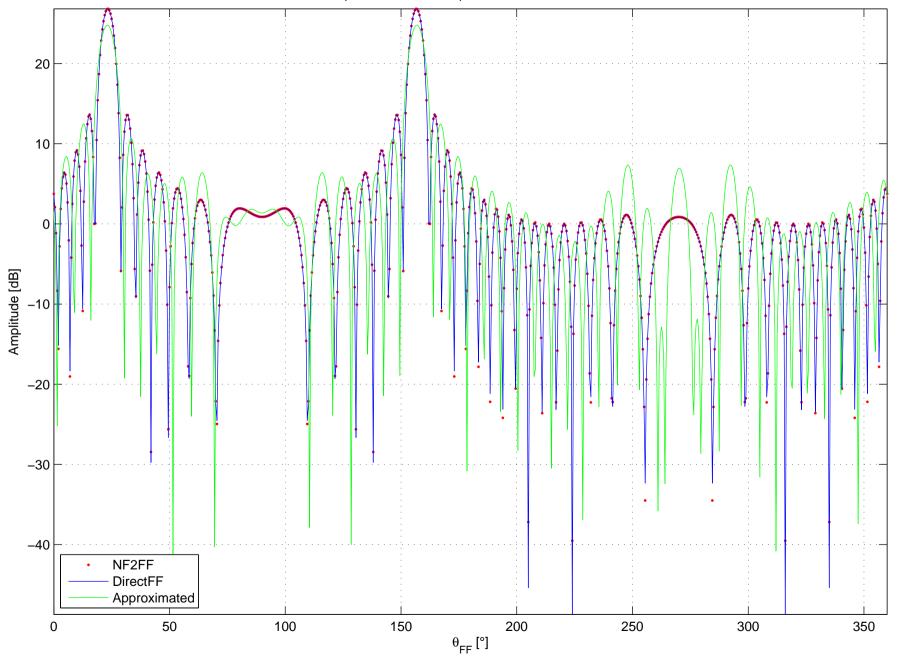
 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.3558 FFSamples = 721, NFSamples = 16200, Coefficients = 53



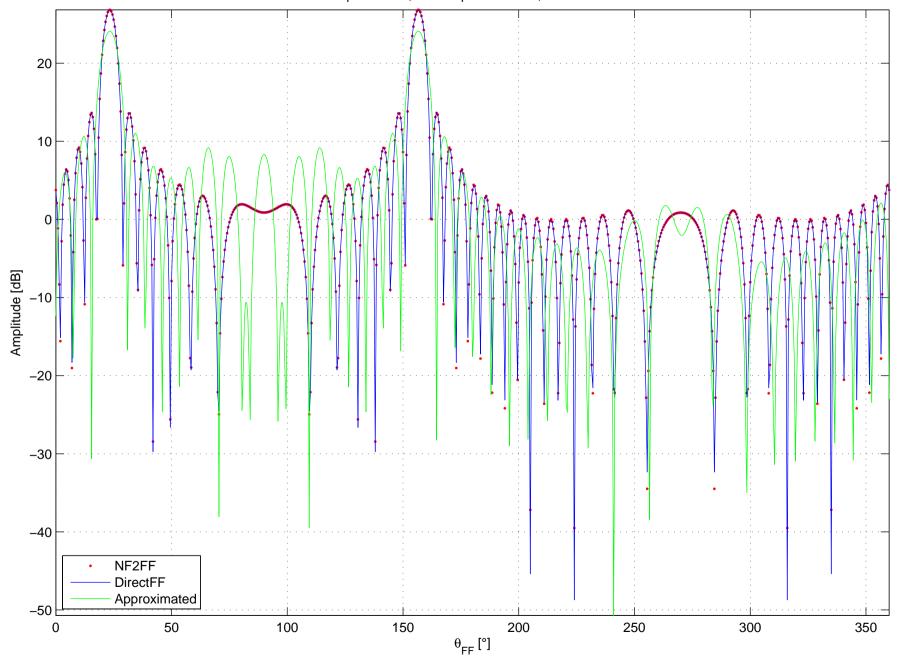
 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.36006 FFSamples = 721, NFSamples = 16200, Coefficients = 51



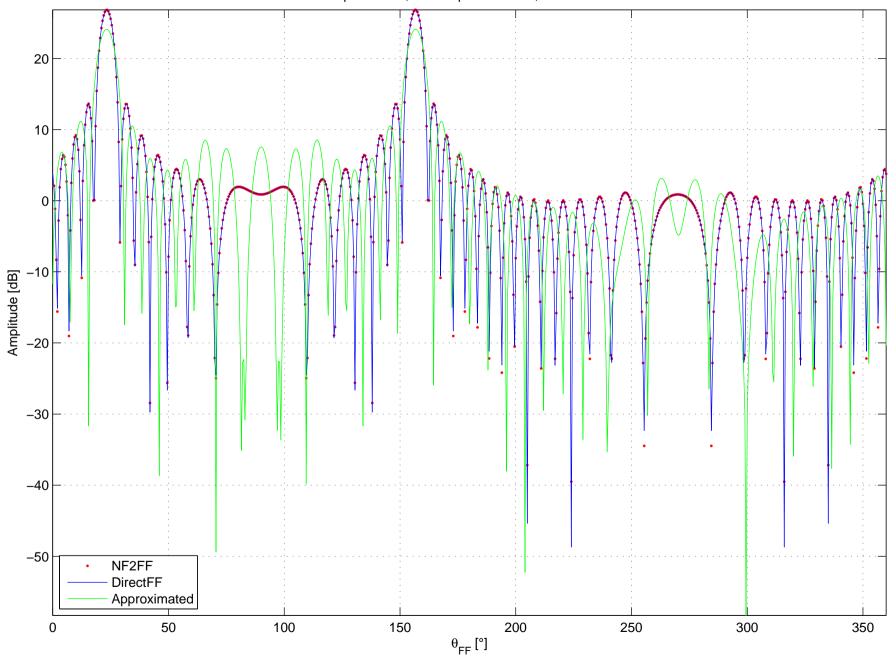
 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.43225 FFSamples = 721, NFSamples = 16200, Coefficients = 49



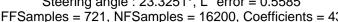
 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.50342 FFSamples = 721, NFSamples = 16200, Coefficients = 47

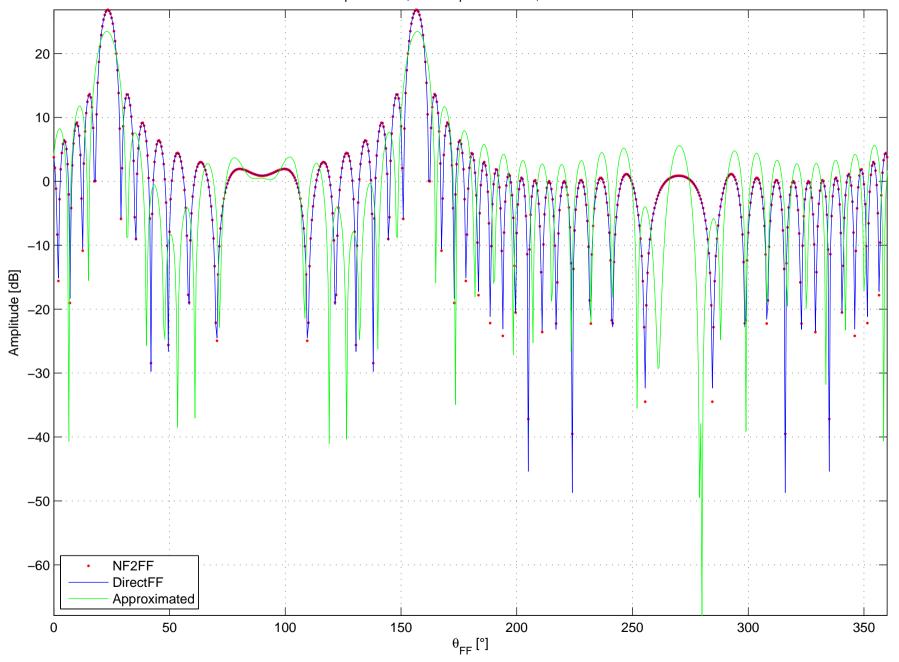


 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.50496 FFSamples = 721, NFSamples = 16200, Coefficients = 45

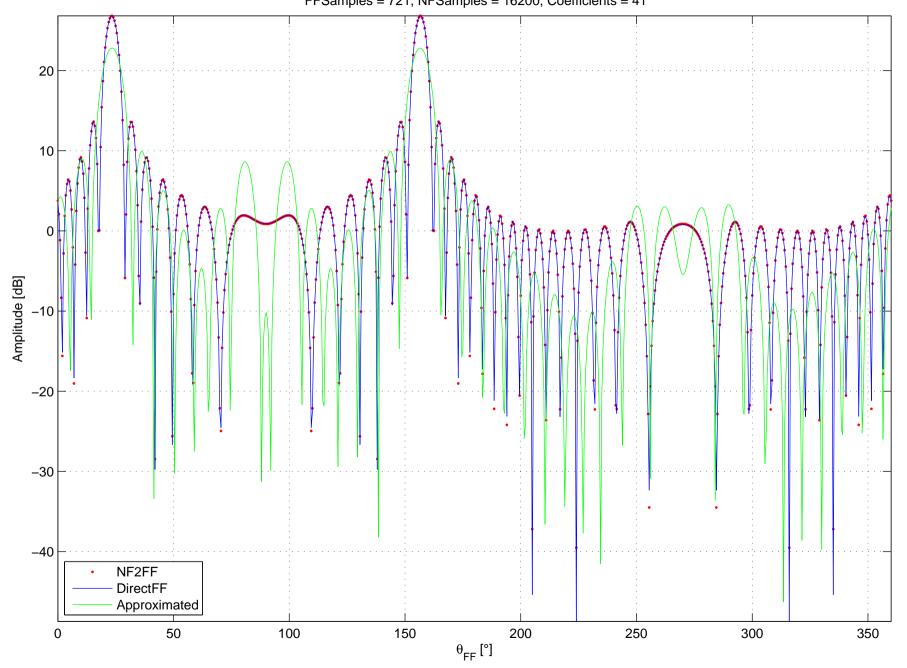


 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.5585 FFSamples = 721, NFSamples = 16200, Coefficients = 43

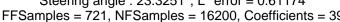


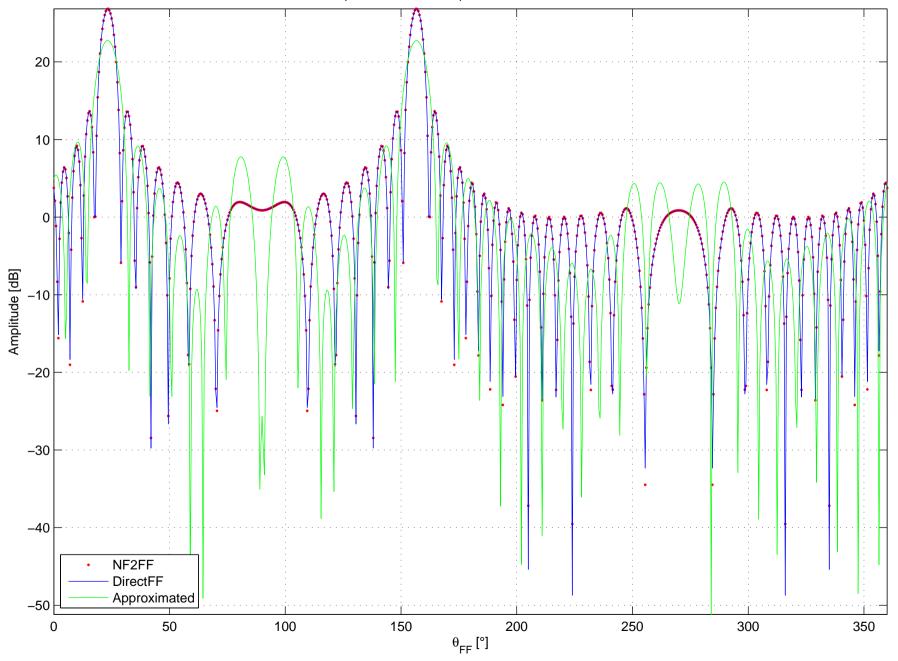


 $22 \times 0.5\lambda$, Rad : 5.75λ Steering angle : 23.3251° , L² error = 0.61FFSamples = 721, NFSamples = 16200, Coefficients = 41

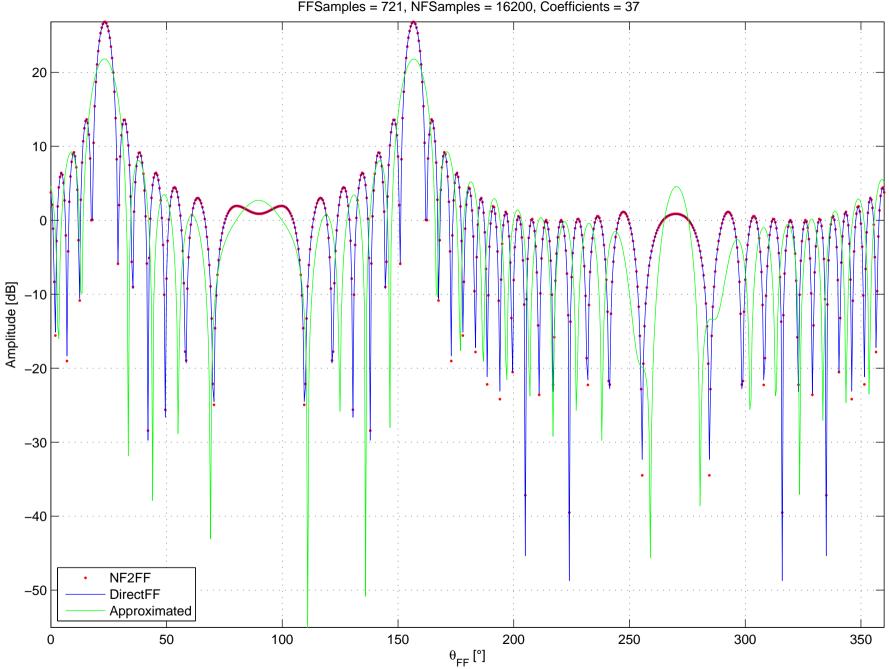


 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.61174 FFSamples = 721, NFSamples = 16200, Coefficients = 39

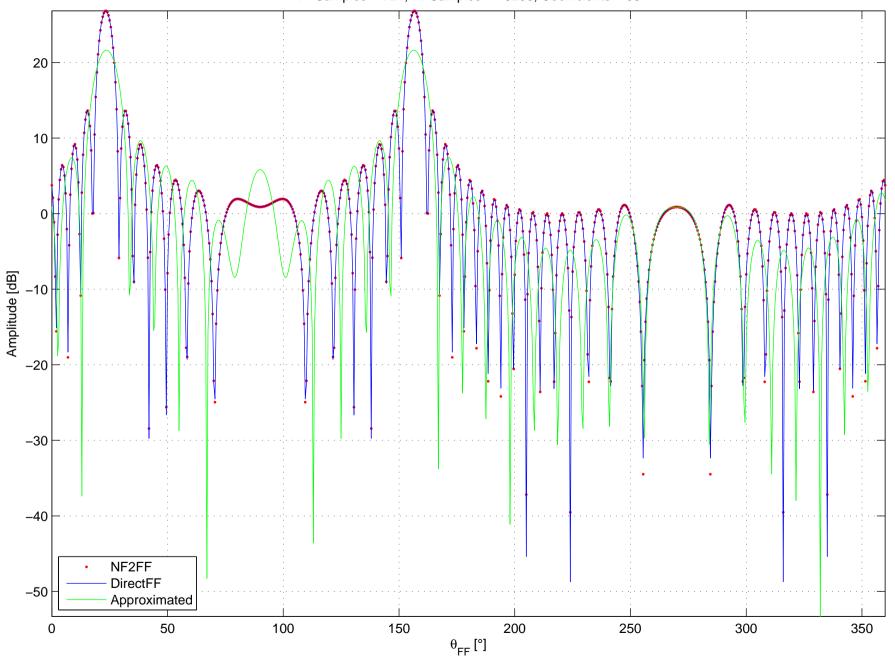




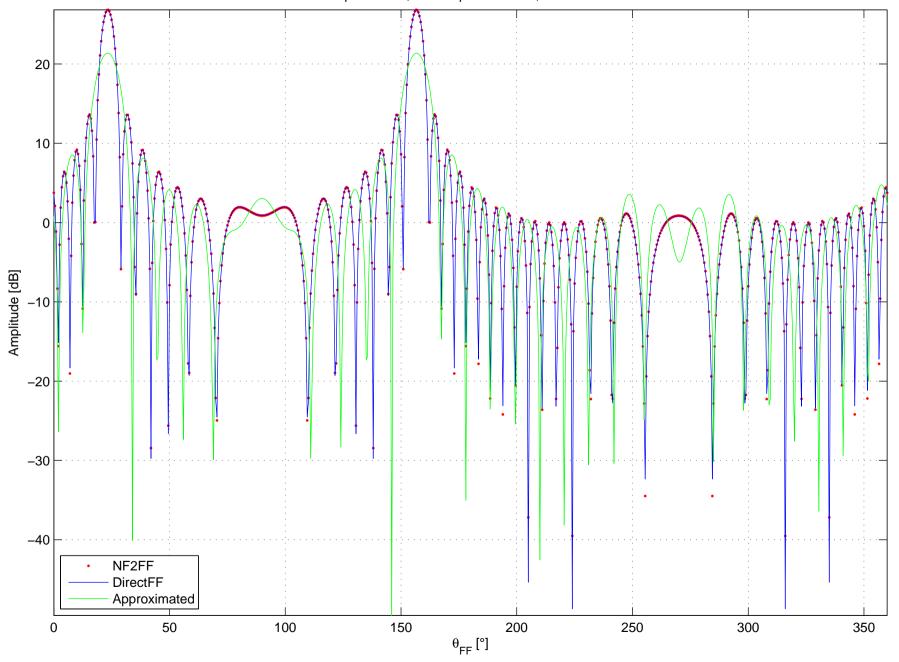
 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.6624 FFSamples = 721, NFSamples = 16200, Coefficients = 37



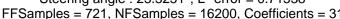
 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.67084 FFSamples = 721, NFSamples = 16200, Coefficients = 35

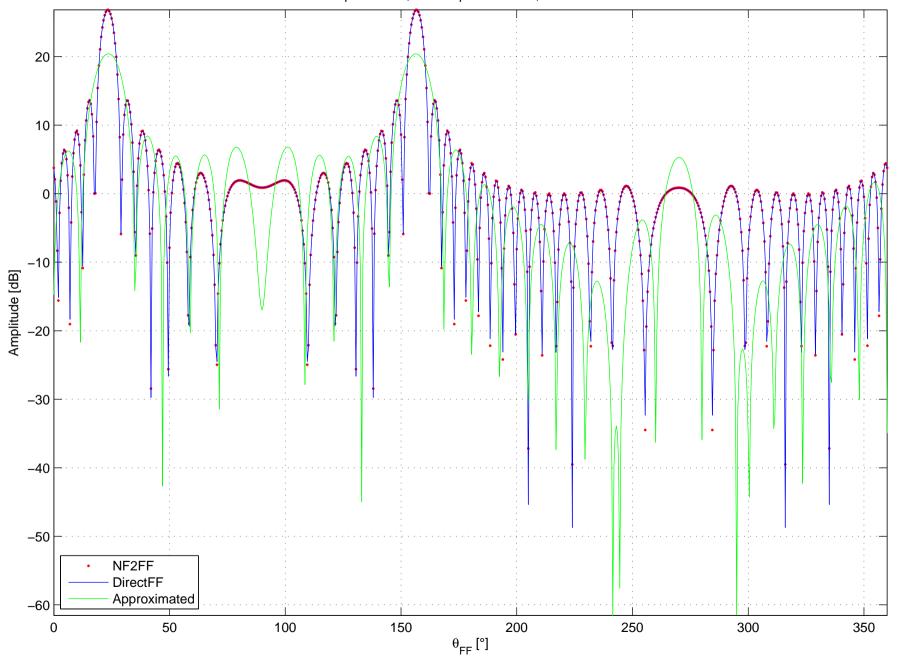


 $22 \times 0.5 \lambda, \, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.67771 FFSamples = 721, NFSamples = 16200, Coefficients = 33



 $22 \times 0.5 \lambda, Rad: 5.75 \lambda$ Steering angle: 23.3251°, L² error = 0.71538 FFSamples = 721, NFSamples = 16200, Coefficients = 31





22 x 0.5λ, Rad : 5.75λ

Steering angle: 23.3251°, L² error = 0.71538 FFSamples = 721, NFSamples = 16200, Coefficients = 31

