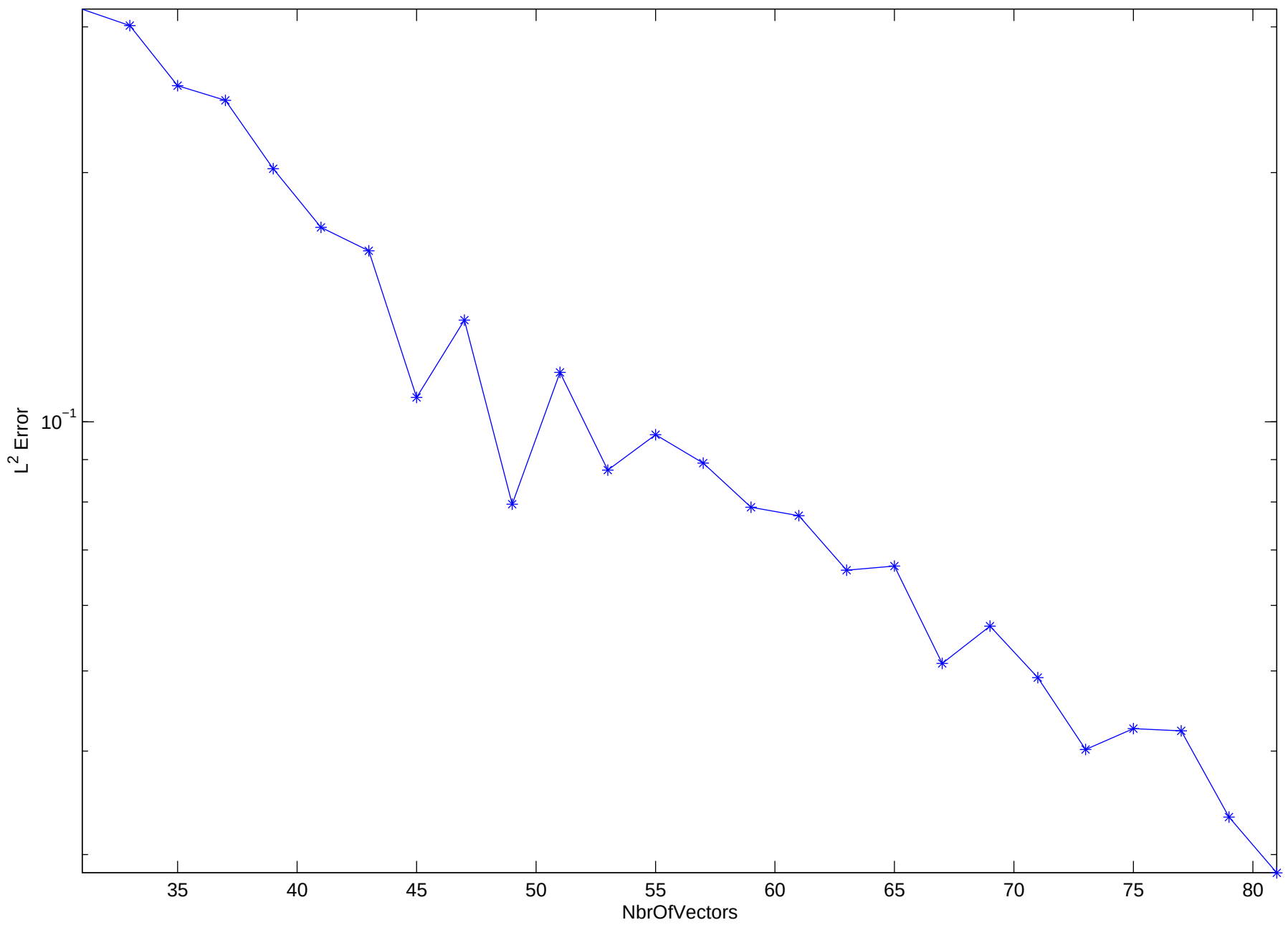
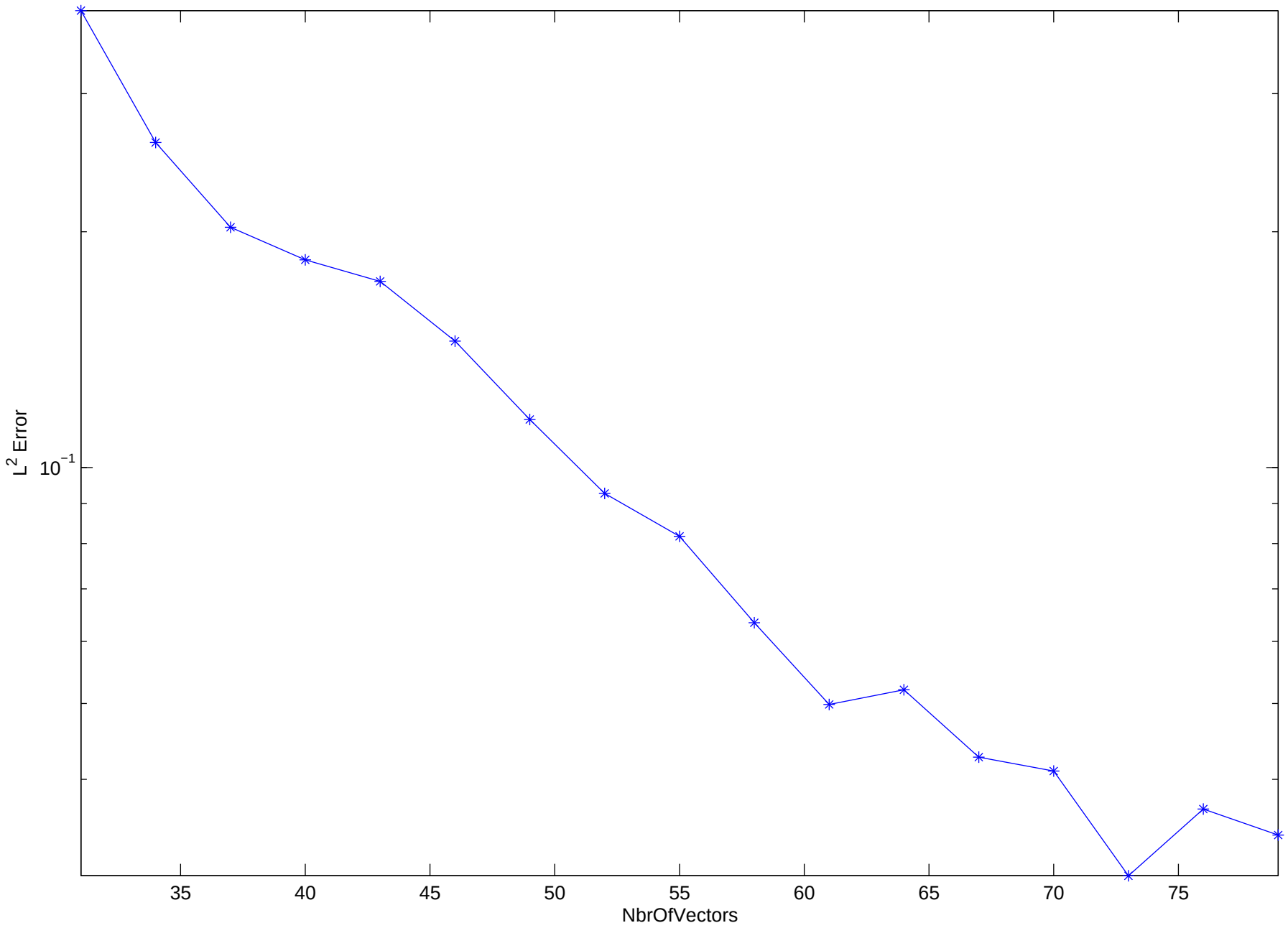
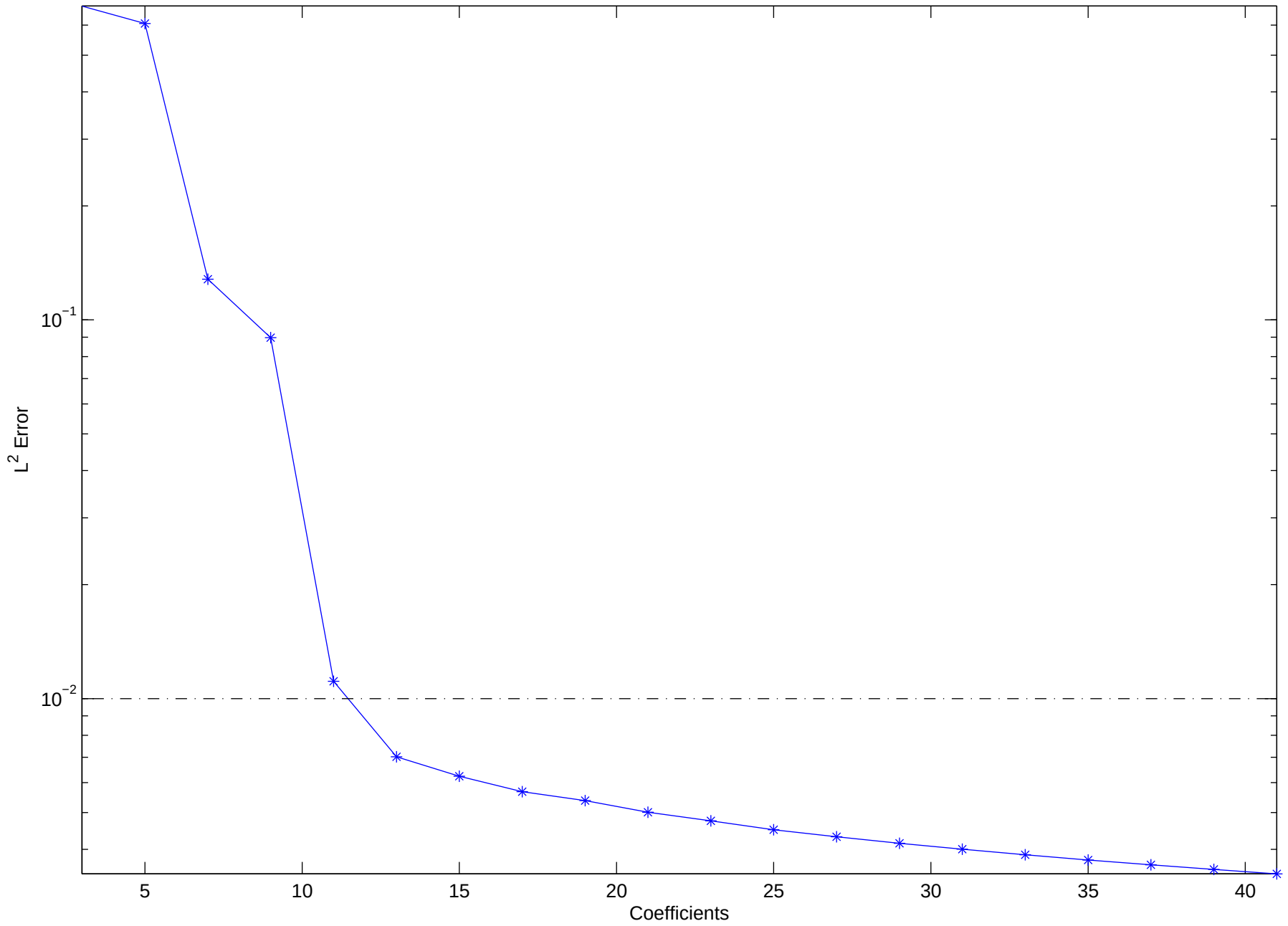
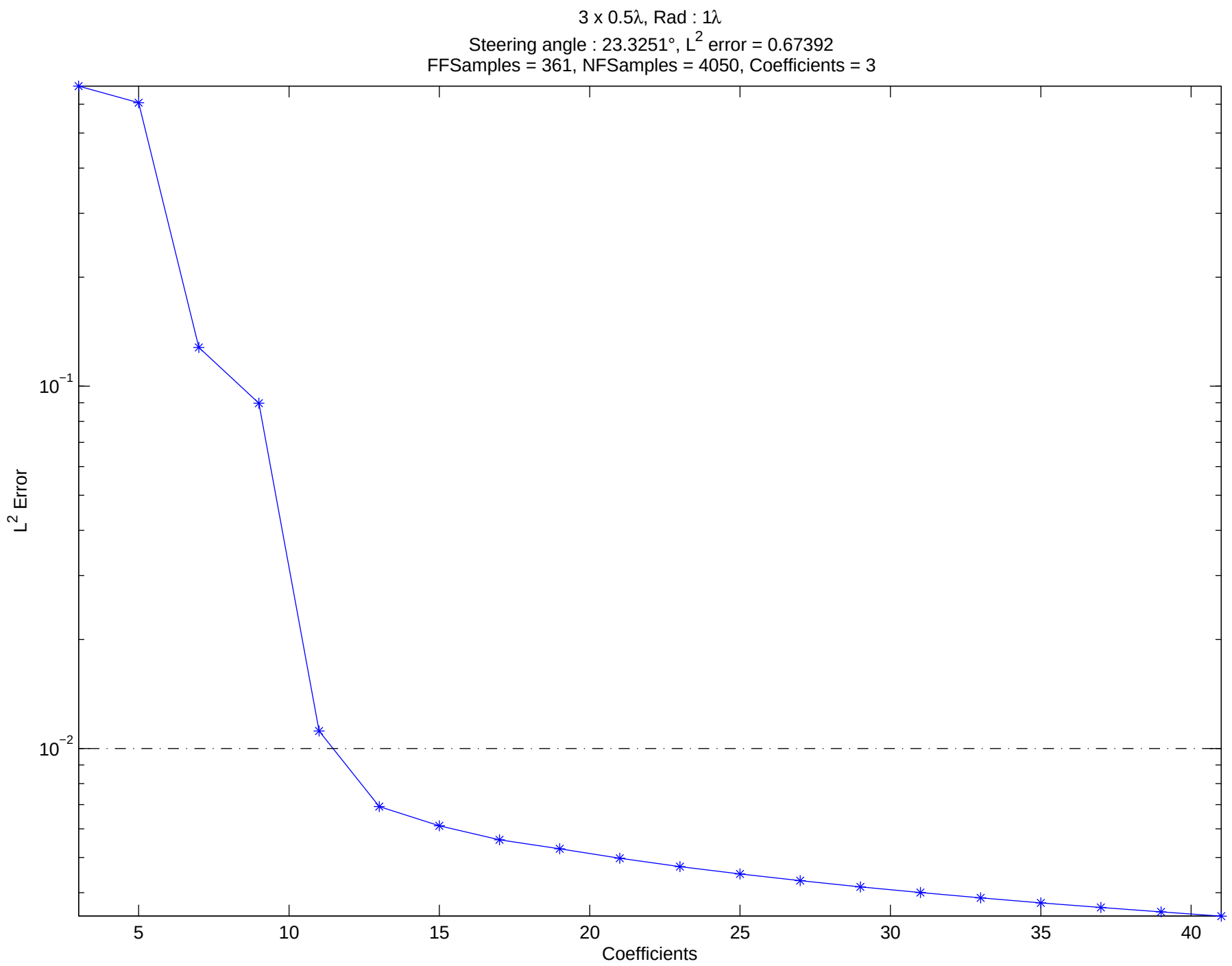
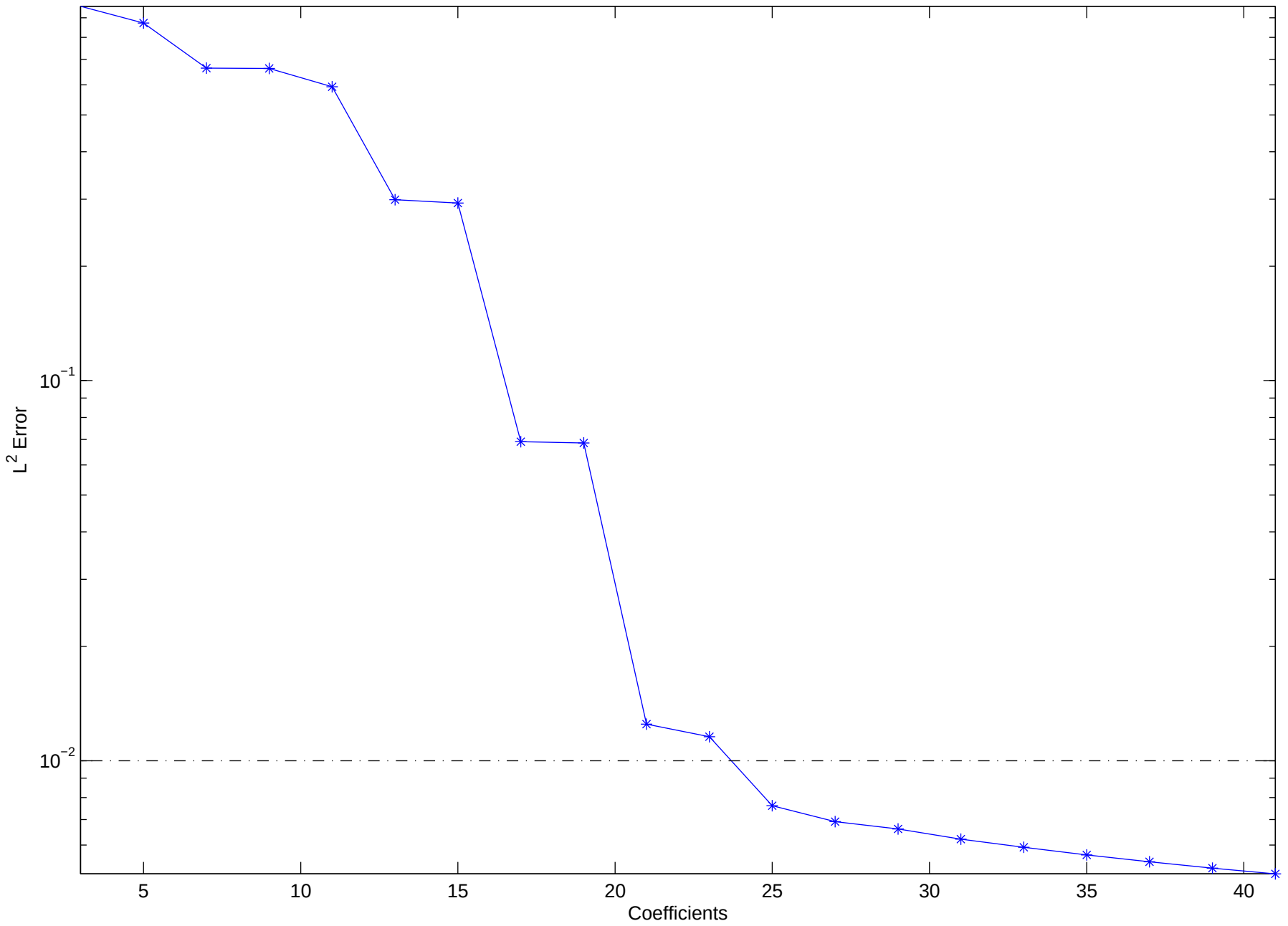
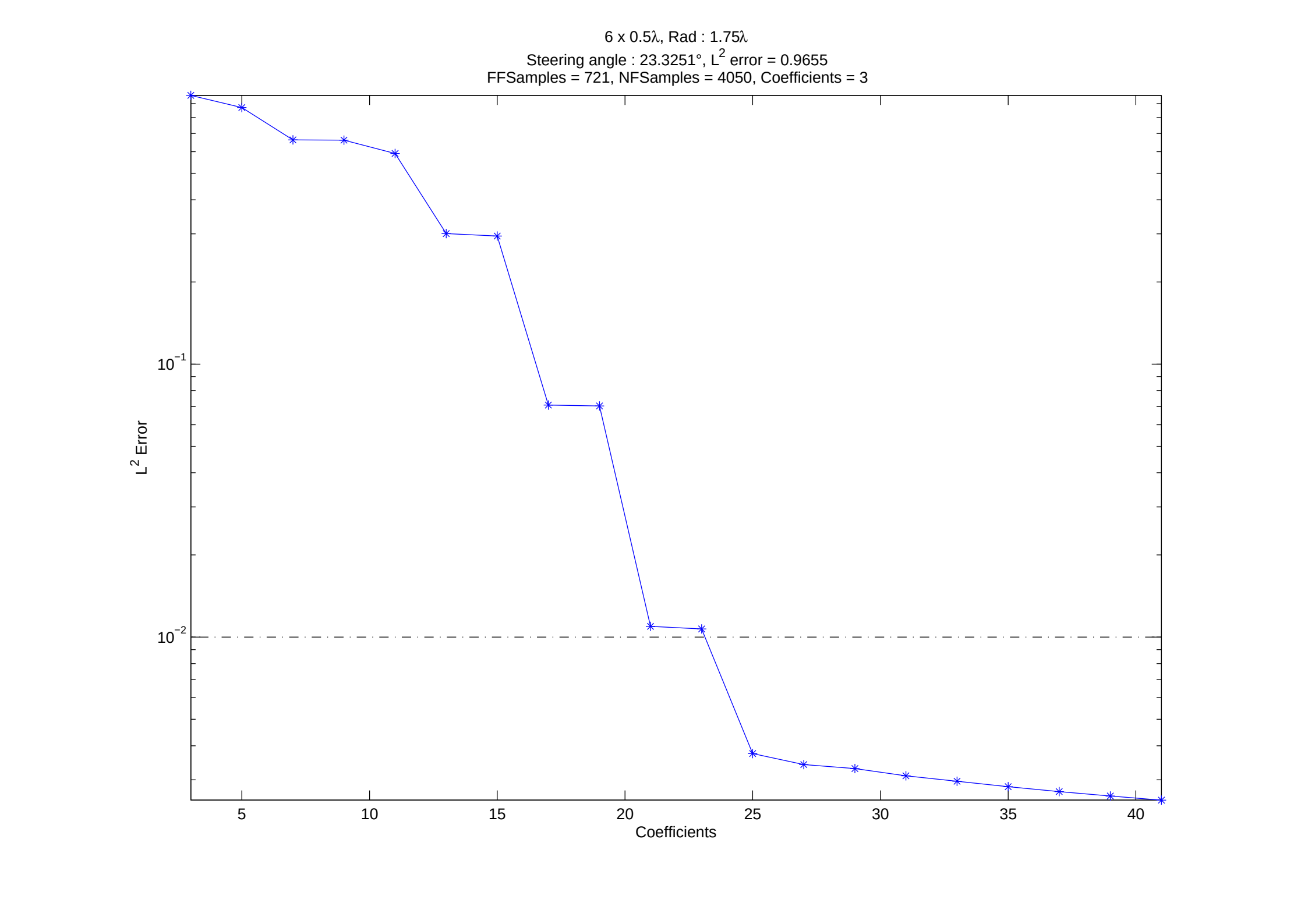

L2 Error. Sphere Radius = 3λ ShapeFuncts : 2
Steering angle : 23.3251°, L2 error = 0.3152
FFSamples = 721, NFSamples = 16200, RowVectors = 31
L2 Error
10−1
35
40
45
50
55
60
65
70
75
80
NbrOfVectors

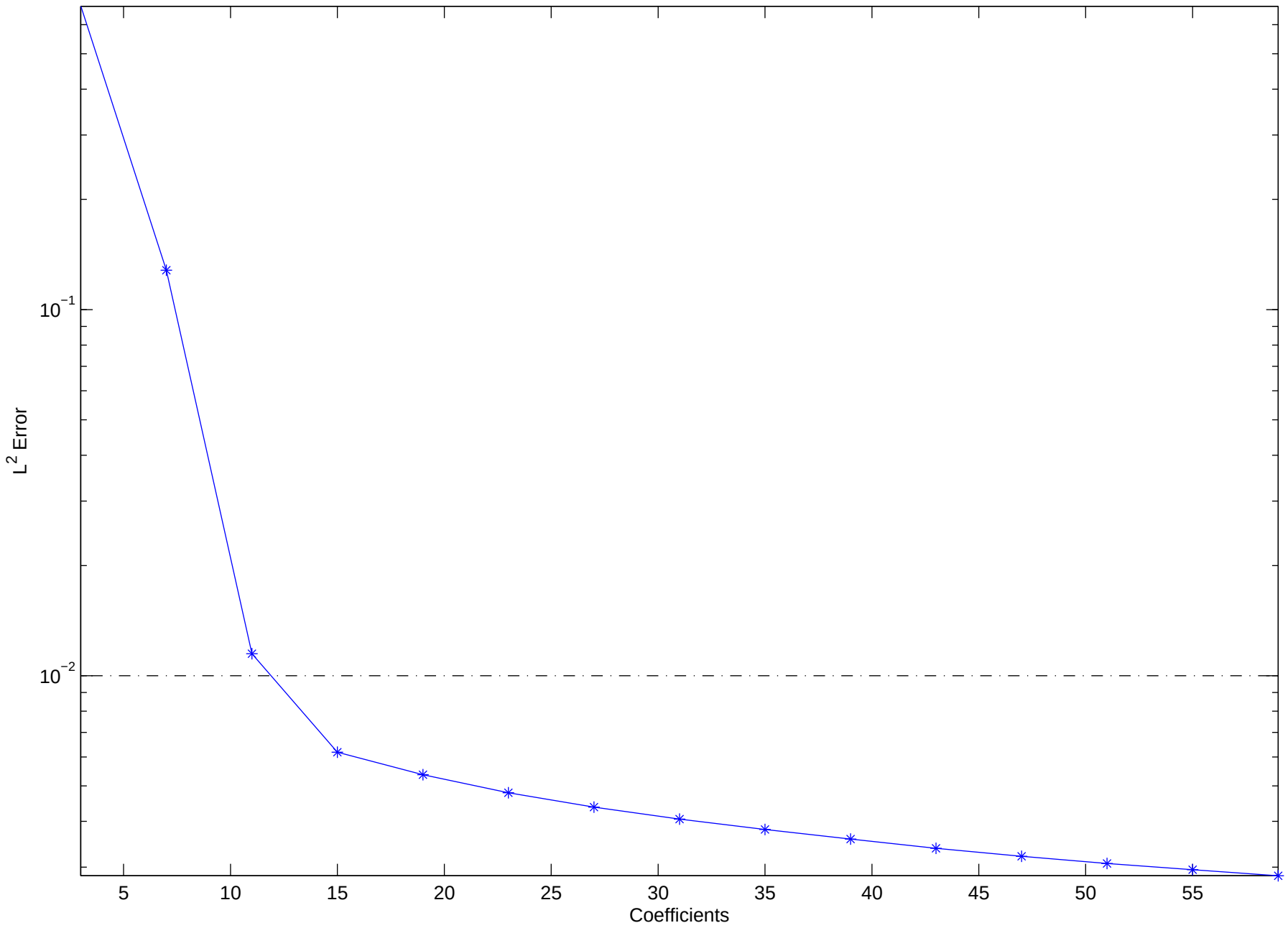

L2 Error. Sphere Radius = 3λ ShapeFuncts : 3
Steering angle : 23.3251°, L2 error = 0.38303
FFSamples = 721, NFSamples = 16200, RowVectors = 31
L2 Error
10−1
35
40
45
50
55
60
65
70
75
NbrOfVectors

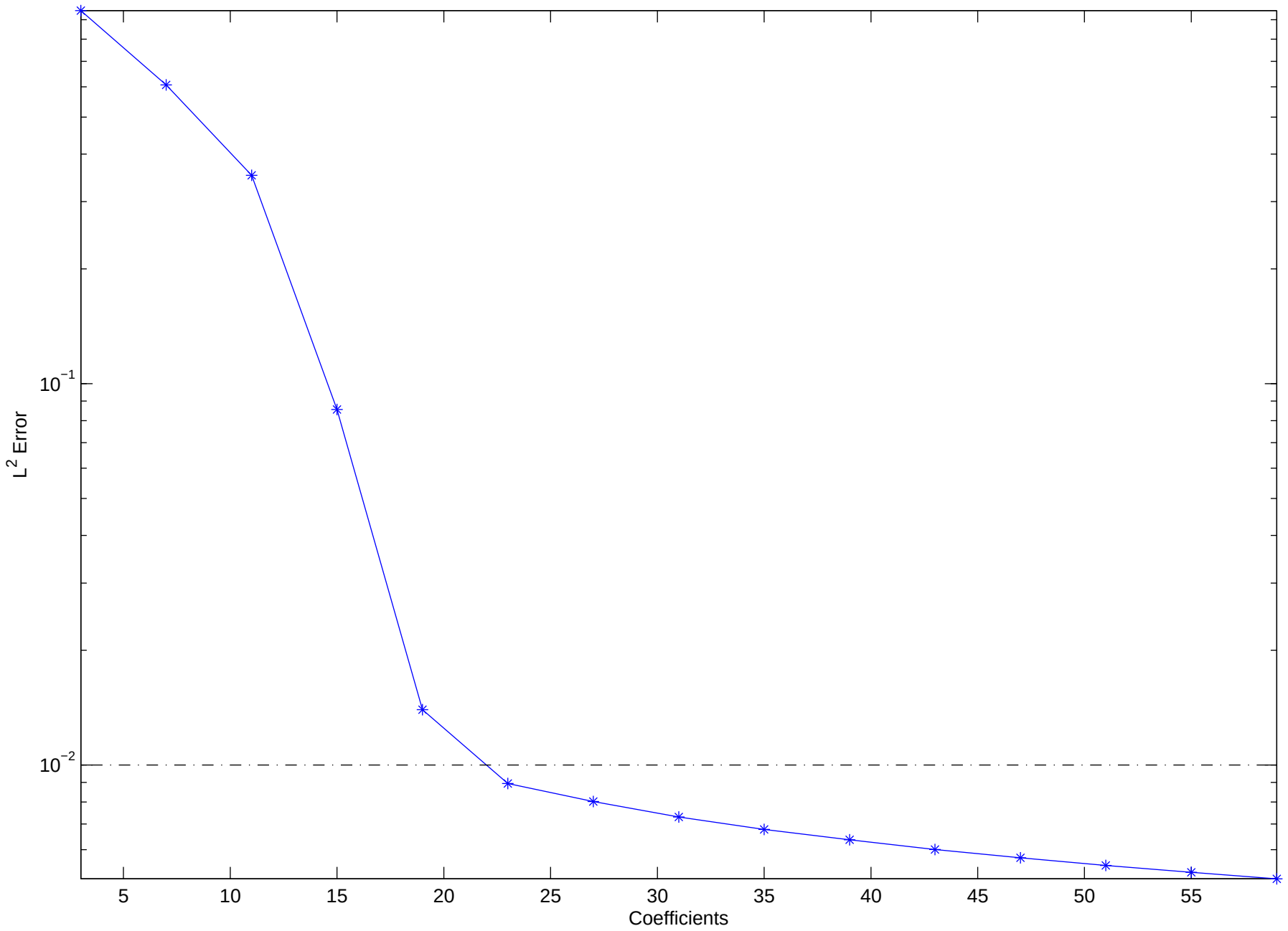

3 x 0.5λ, Rad : 1.75λ
Steering angle : 23.3251°, L2 error = 0.67394
FFSamples = 361, NFSamples = 4050, Coefficients = 3
10−1
10−2
L2 Error
5
10
15
20
25
30
35
40
Coefficients

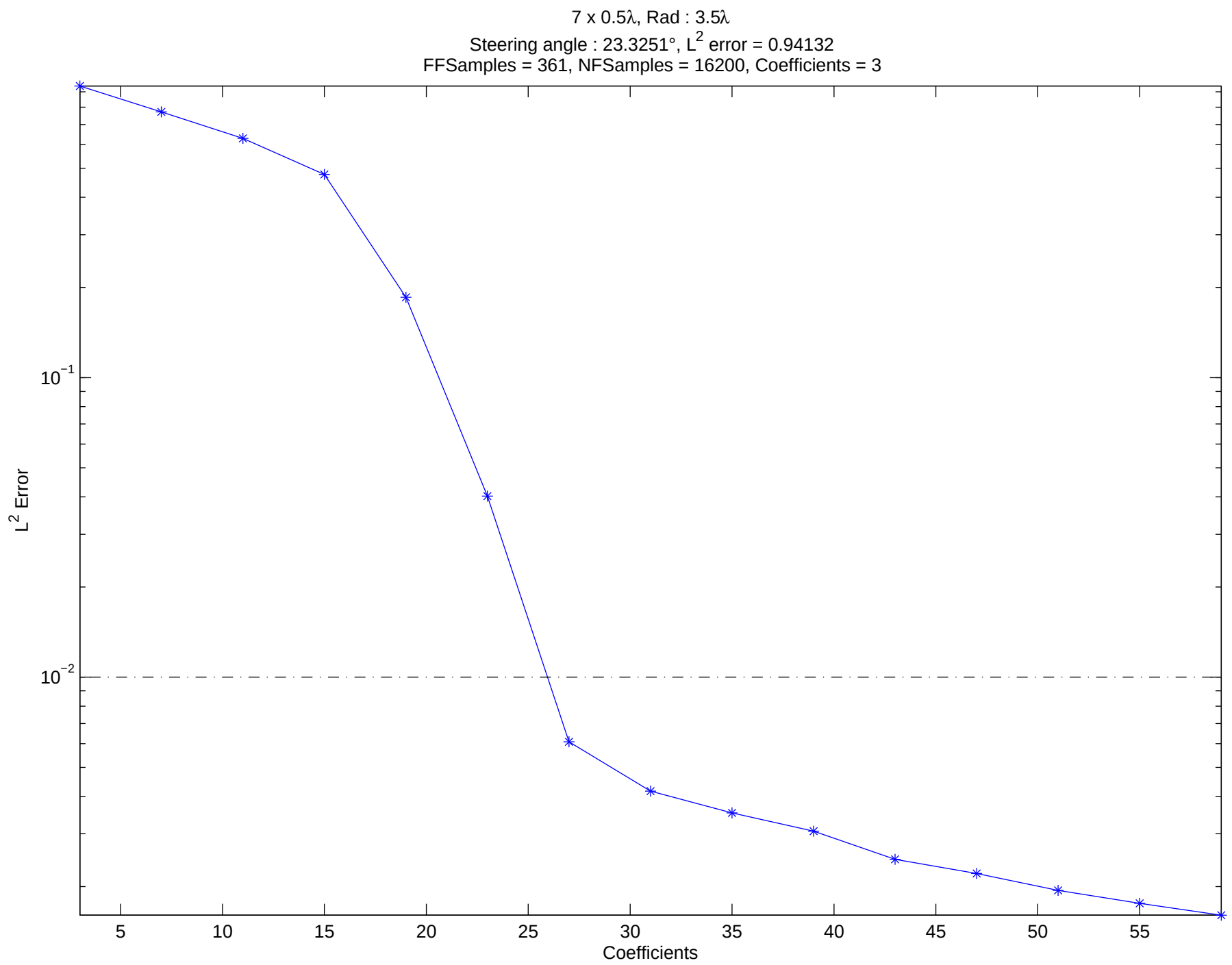

3 x 0.5λ, Rad : 1λ
Steering angle : 23.3251°, L2 error = 0.67392
FFSamples = 361, NFSamples = 4050, Coefficients = 3
10−1
10−2
L2 Error
5
10
15
20
25
30
35
40
Coefficients

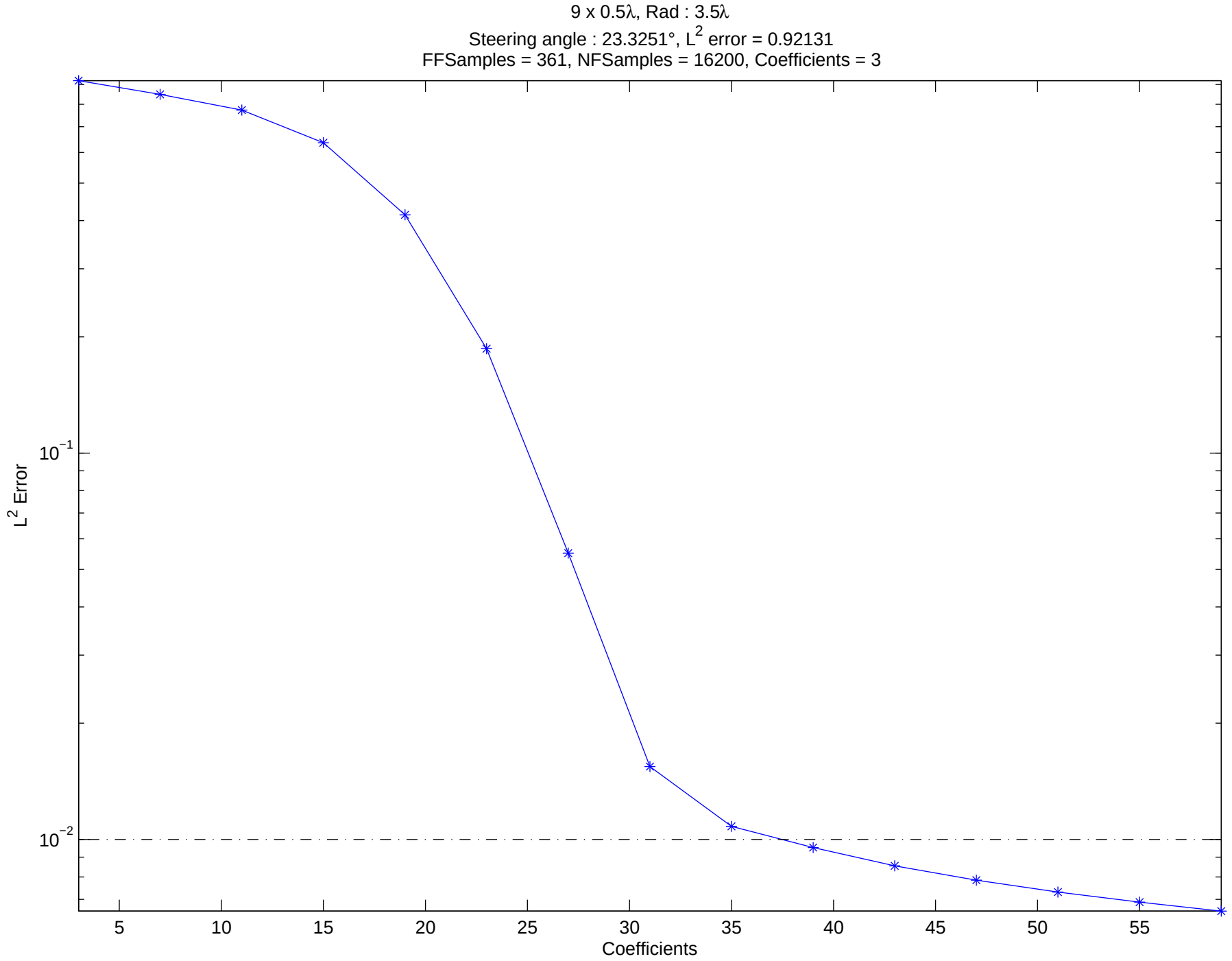

6 x 0.5λ, Rad : 1.75λ
Steering angle : 23.3251°, L2 error = 0.96564
FFSamples = 361, NFSamples = 4050, Coefficients = 3
L2 Error
10−1
10−2
5
10
15
20
25
30
35
40
Coefficients

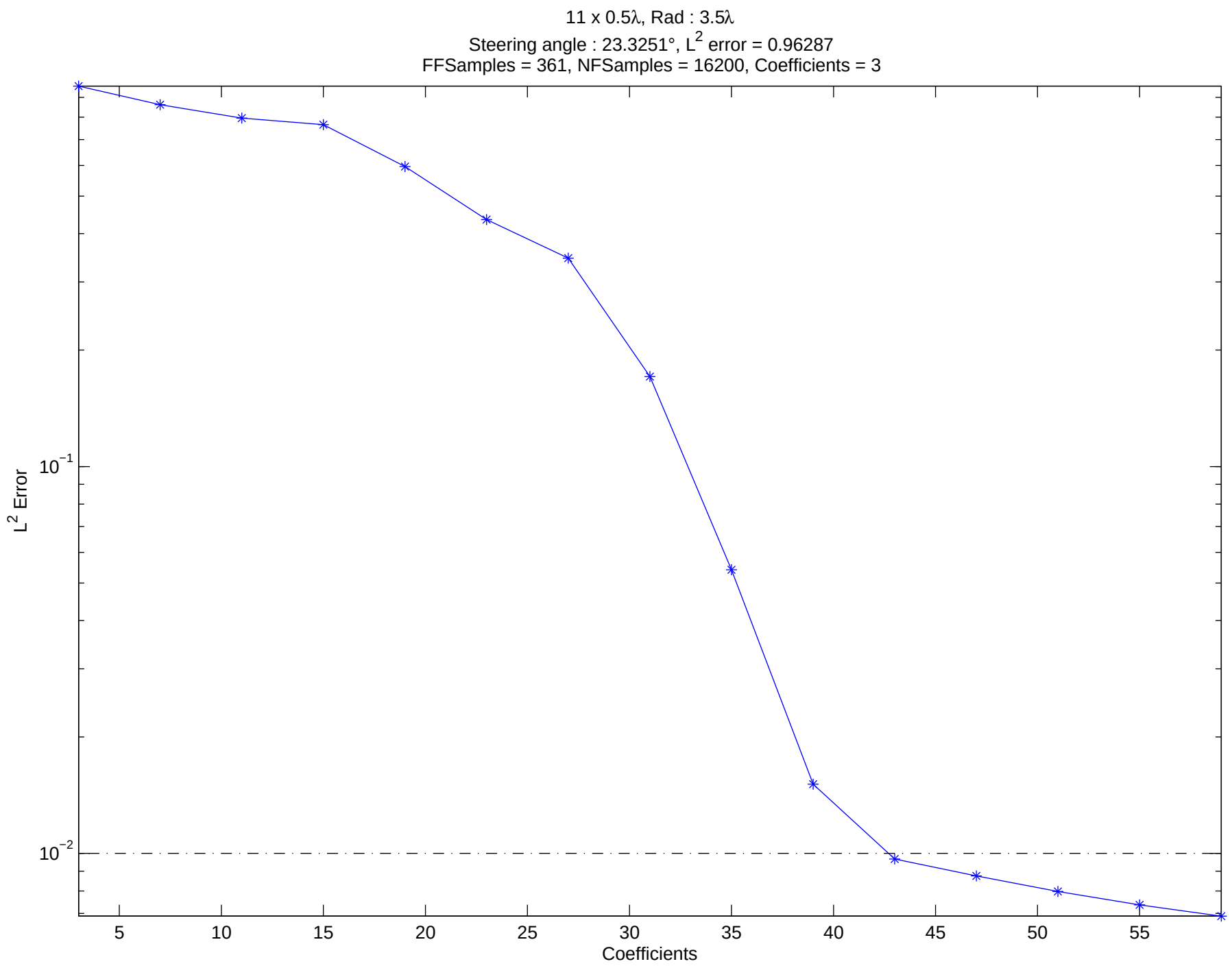

6 x 0.5λ, Rad : 1.75λ
Steering angle : 23.3251°, L2 error = 0.9655
FFSamples = 721, NFSamples = 4050, Coefficients = 3
L2 Error
10−1
10−2
5
10
15
20
25
30
35
40
Coefficients

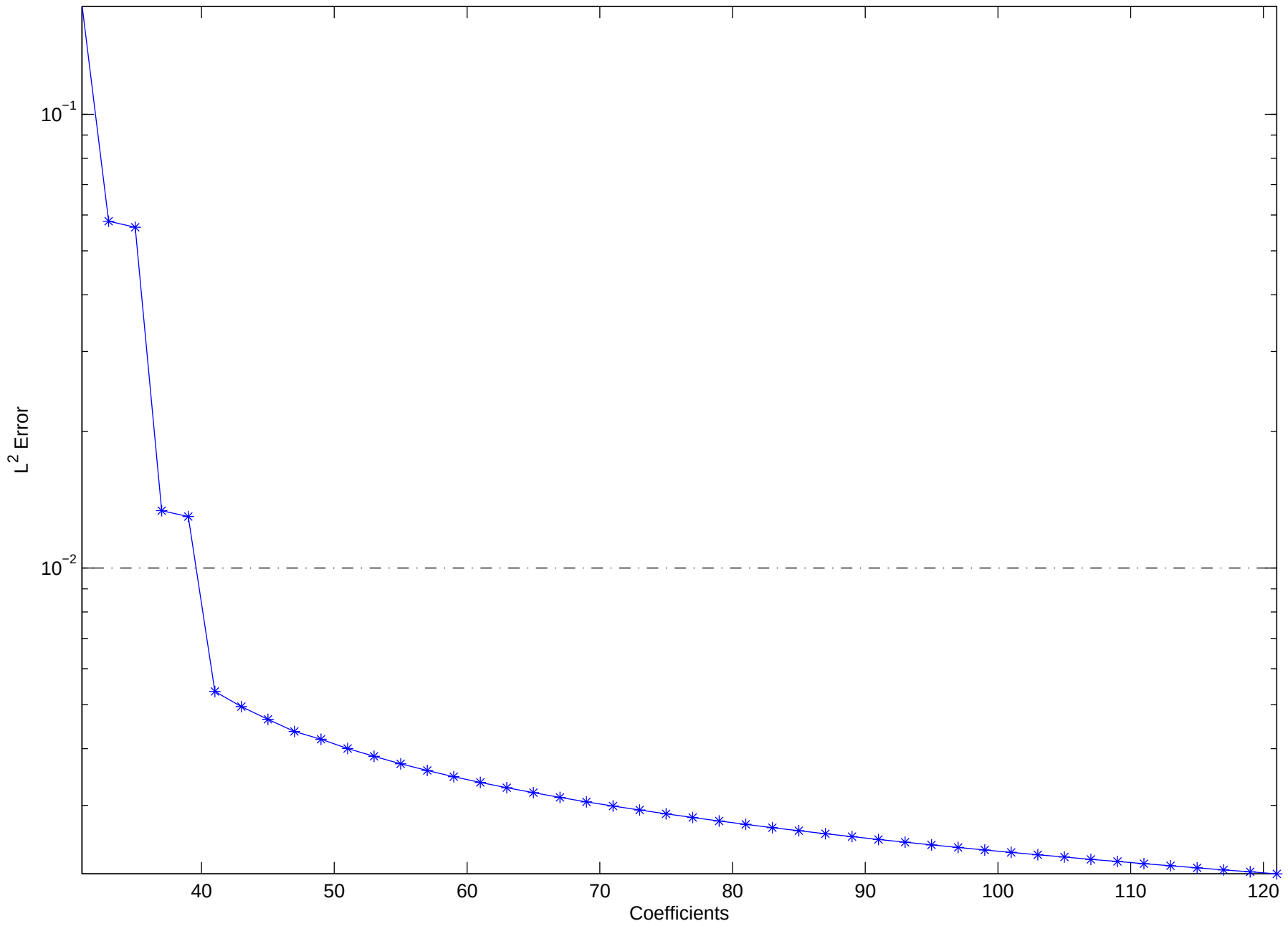

3 x 0.5λ, Rad : 3.5λ
Steering angle : 23.3251°, L2 error = 0.67397
FFSamples = 361, NFSamples = 16200, Coefficients = 3
10−1
10−2
L2 Error
5
10
15
20
25
30
35
40
45
50
55
Coefficients

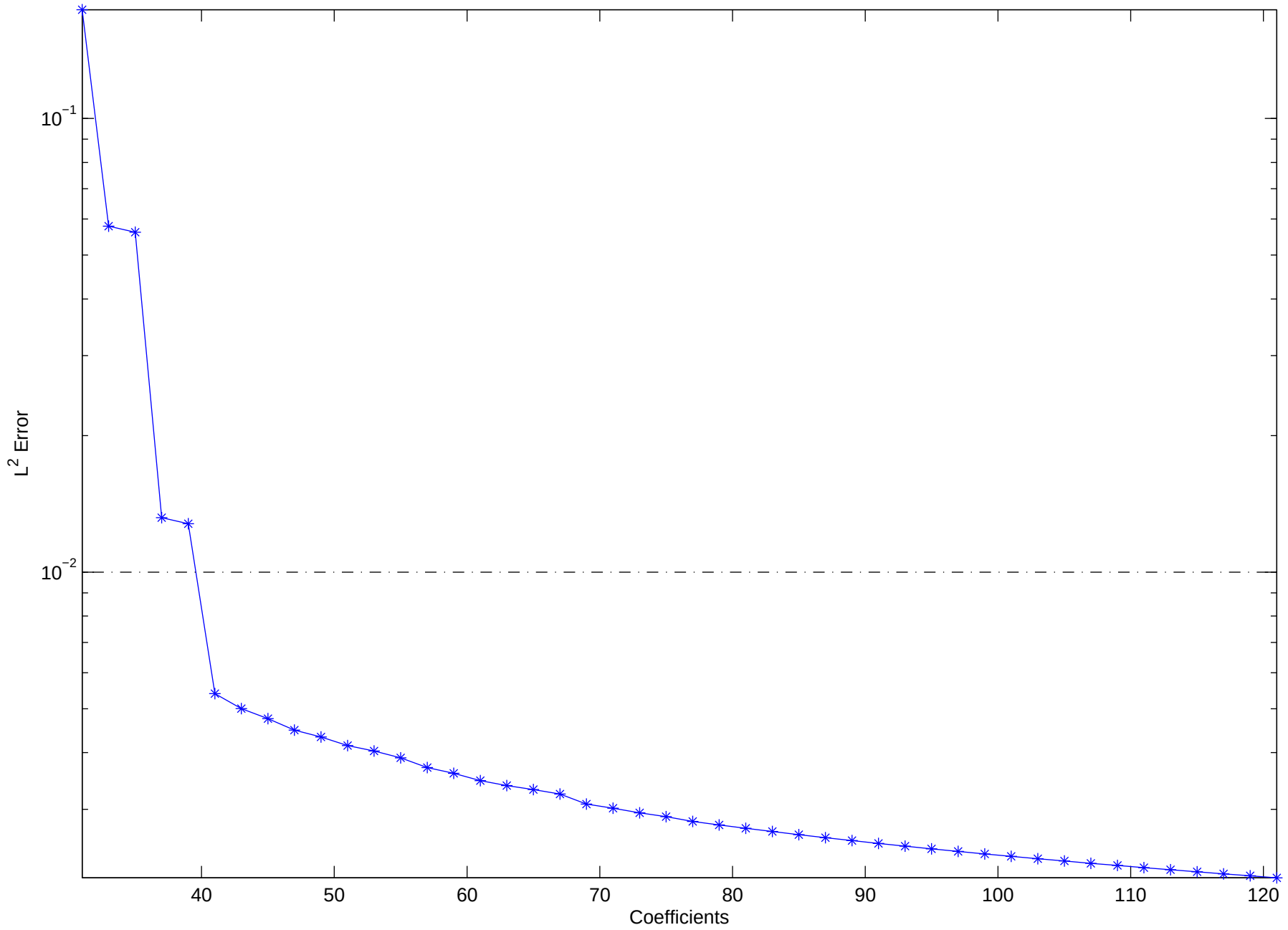

5 x 0.5λ, Rad : 3.5λ
Steering angle : 23.3251°, L2 error = 0.95125
FFSamples = 361, NFSamples = 16200, Coefficients = 3
L2 Error
10−1
10−2
5
10
15
20
25
30
35
40
45
50
55
Coefficients

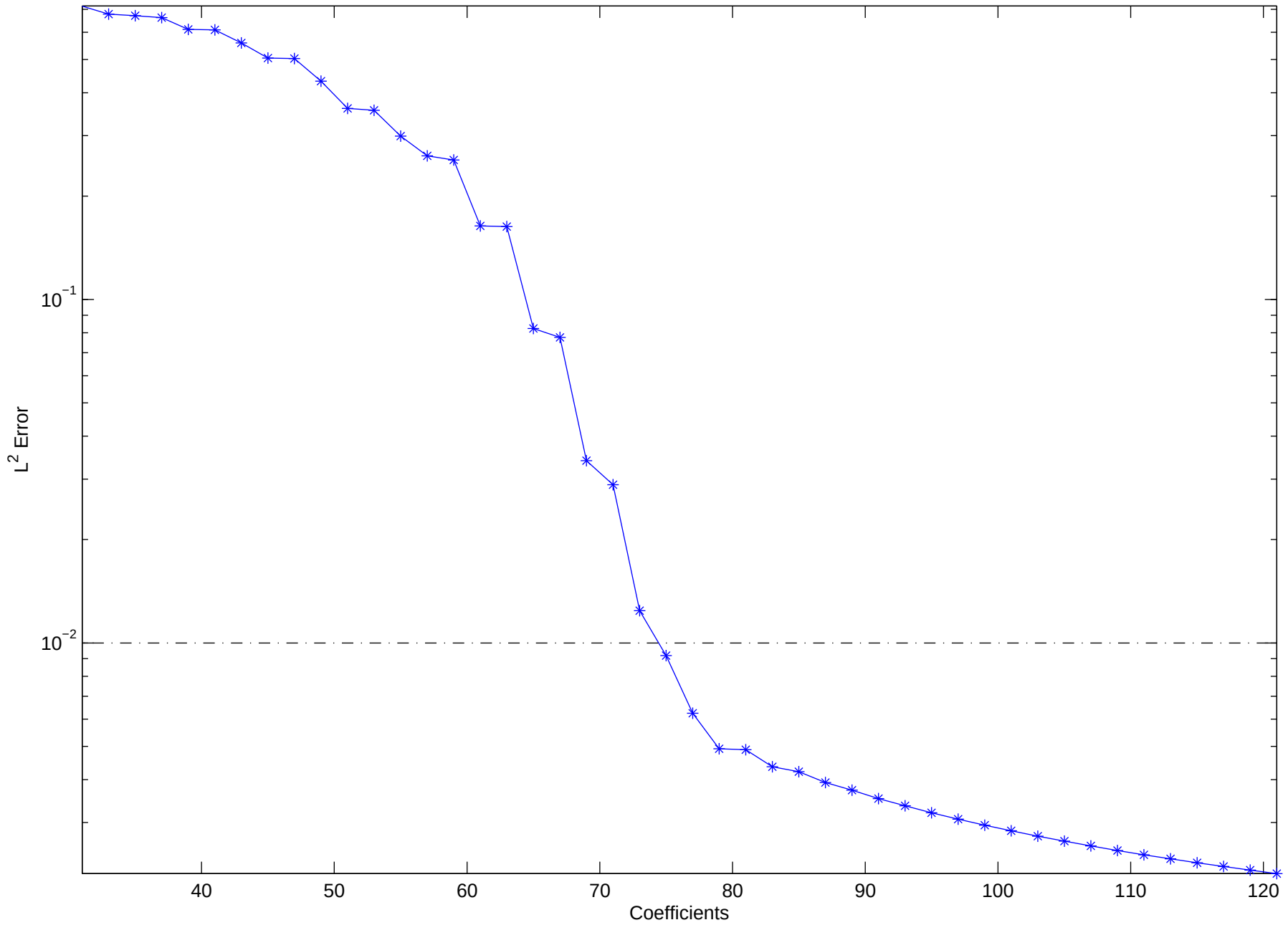

7 x 0.5λ, Rad : 3.5λ
Steering angle : 23.3251°, L2 error = 0.94132
FFSamples = 361, NFSamples = 16200, Coefficients = 3
10−1
10−2
L2 Error
5
10
15
20
25
30
35
40
45
50
55
Coefficients

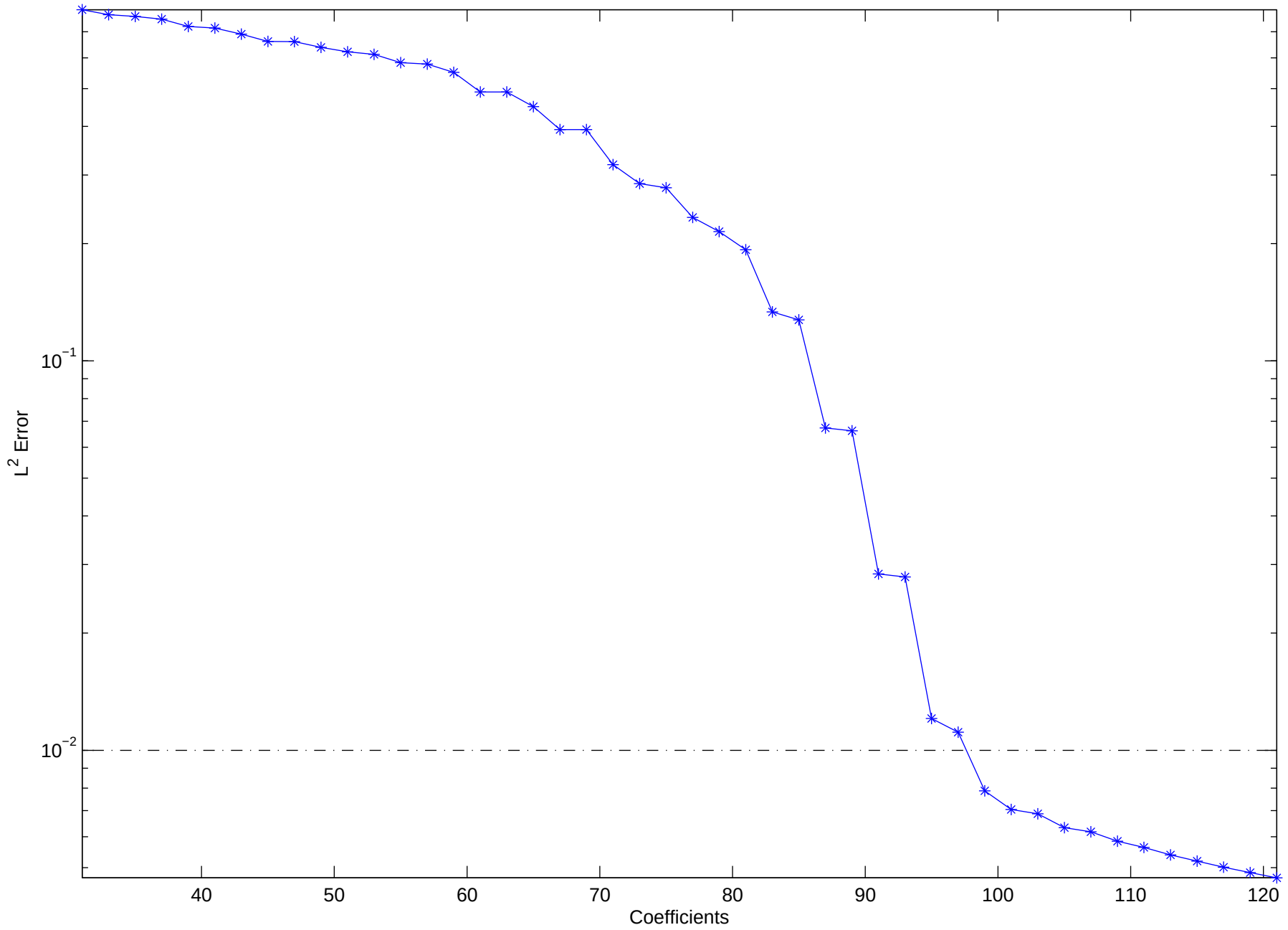

9 x 0.5λ, Rad : 3.5λ
Steering angle : 23.3251°, L2 error = 0.92131
FFSamples = 361, NFSamples = 16200, Coefficients = 3
L2 Error
10−1
10−2
5
10
15
20
25
30
35
40
45
50
55
Coefficients


11 x 0.5λ, Rad : 3.5λ
Steering angle : 23.3251°, L2 error = 0.96287
FFSamples = 361, NFSamples = 16200, Coefficients = 3
L2 Error
10−1
10−2
5
10
15
20
25
30
35
40
45
50
55
Coefficients


11 x 0.5λ, Rad : 3λ
Steering angle : 23.3251°, L2 error = 0.17303
FFSamples = 721, NFSamples = 16200, Coefficients = 31
10−1
10−2
L2 Error
40
50
60
70
80
90
100
110
120
Coefficients


11 x 0.5λ, Rad : 5.75λ
Steering angle : 23.3251°, L2 error = 0.17363
FFSamples = 721, NFSamples = 16200, Coefficients = 31
10−1
10−2
L2 Error
40
50
60
70
80
90
100
110
120
Coefficients


22 x 0.5λ, Rad : 5.75λ
Steering angle : 23.3251°, L2 error = 0.71538
FFSamples = 721, NFSamples = 16200, Coefficients = 31
10−1
10−2
L2 Error
40
50
60
70
80
90
100
110
120
Coefficients


29 x 0.5λ, Rad : 7.5λ
Steering angle : 23.3251°, L2 error = 0.79751
FFSamples = 721, NFSamples = 16200, Coefficients = 31
L2 Error
10−1
10−2
40
50
60
70
80
90
100
110
120
Coefficients