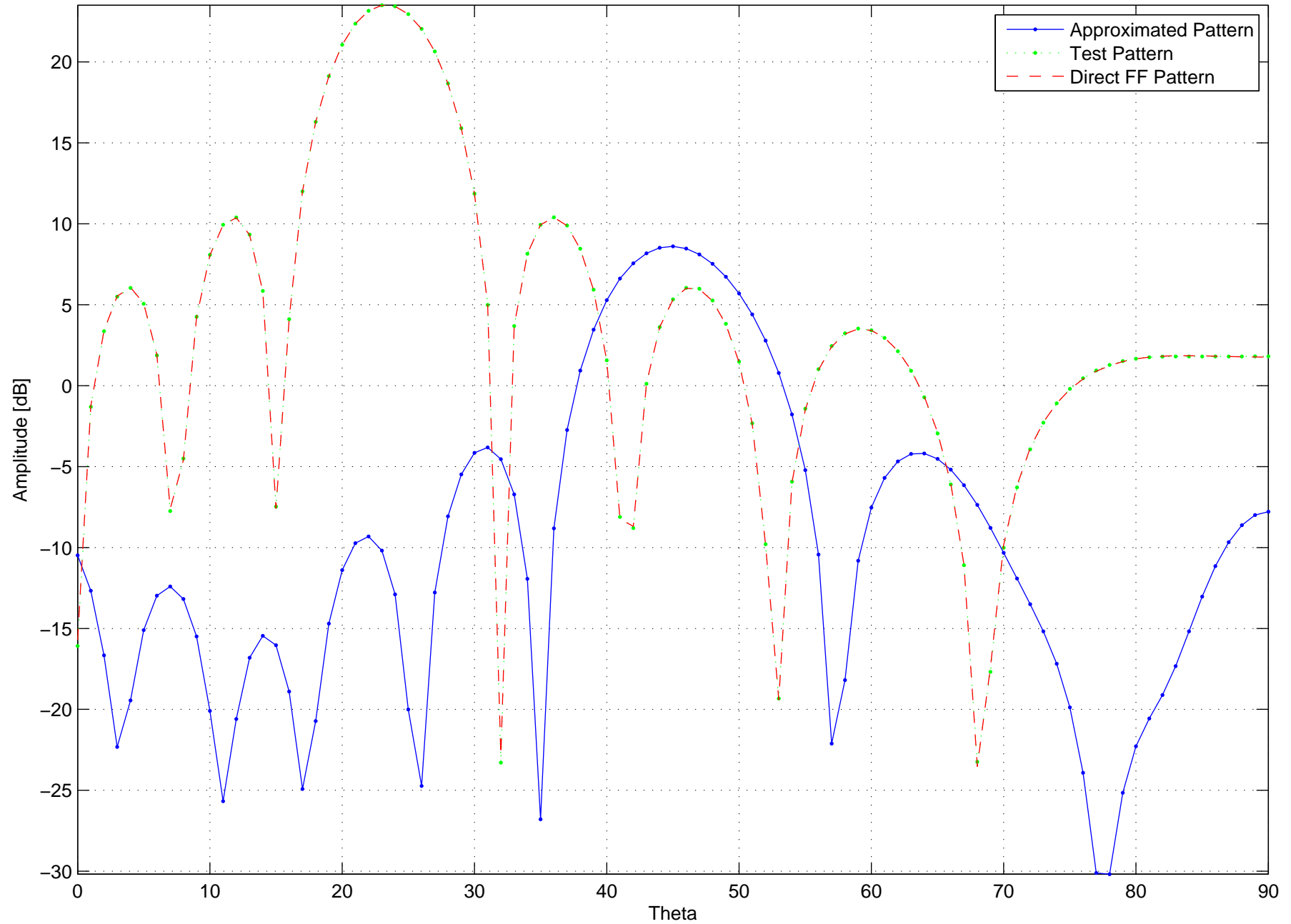
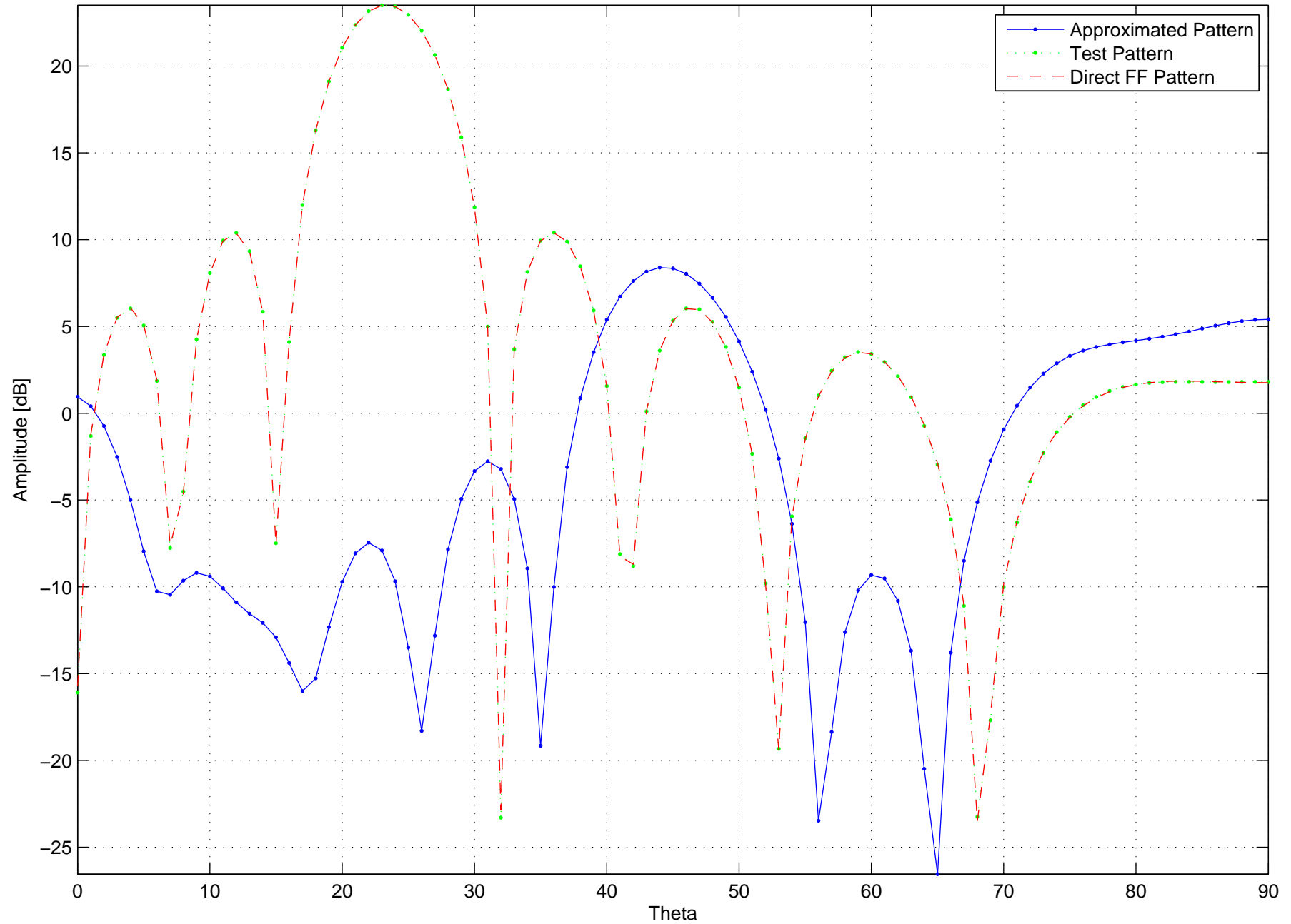


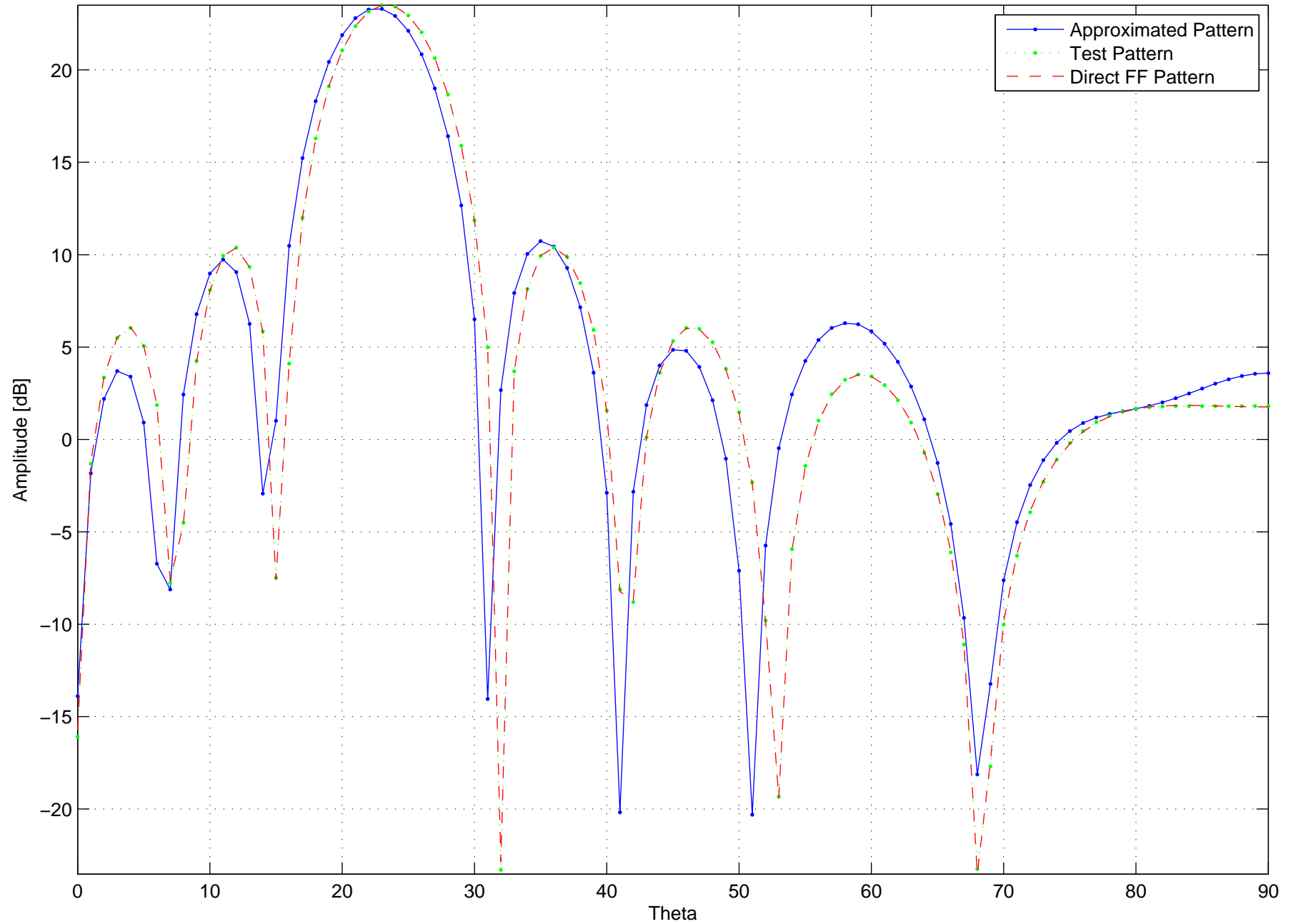
Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 0, Nbr of Vectors : 1
Nbr of point sources : 15



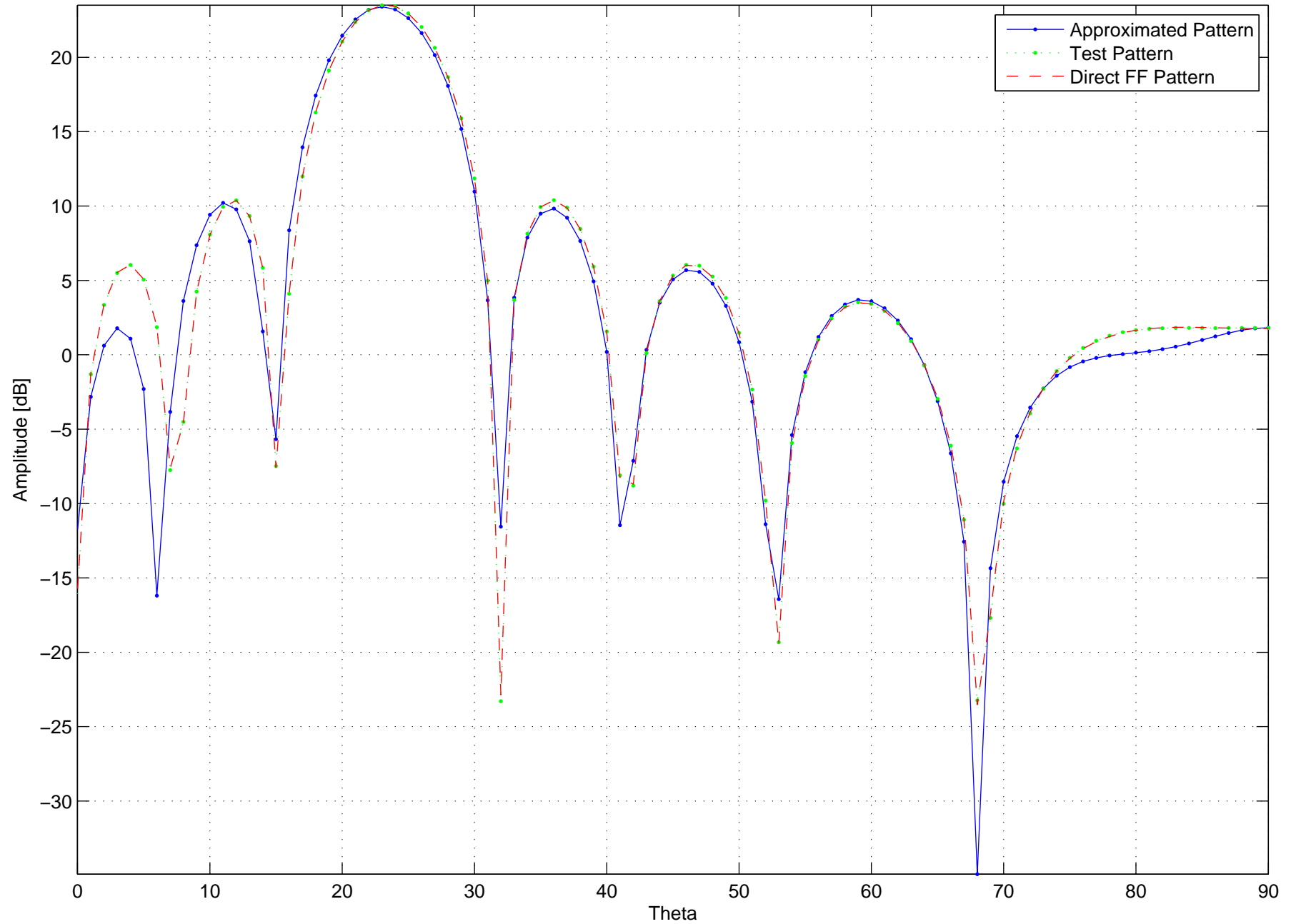
Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 0, Nbr of Vectors : 3
Nbr of point sources : 15



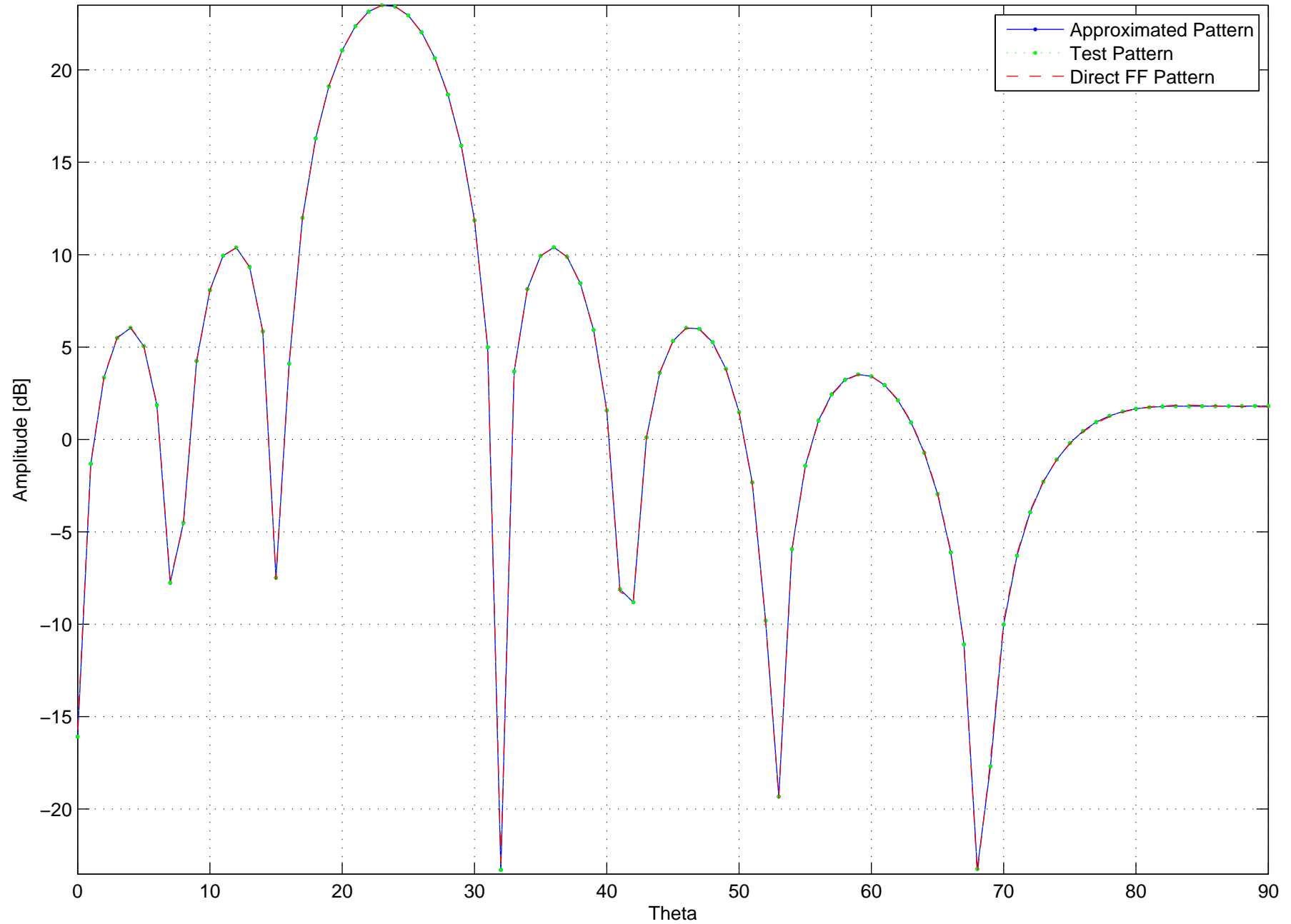
Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 0, Nbr of Vectors : 5
Nbr of point sources : 15



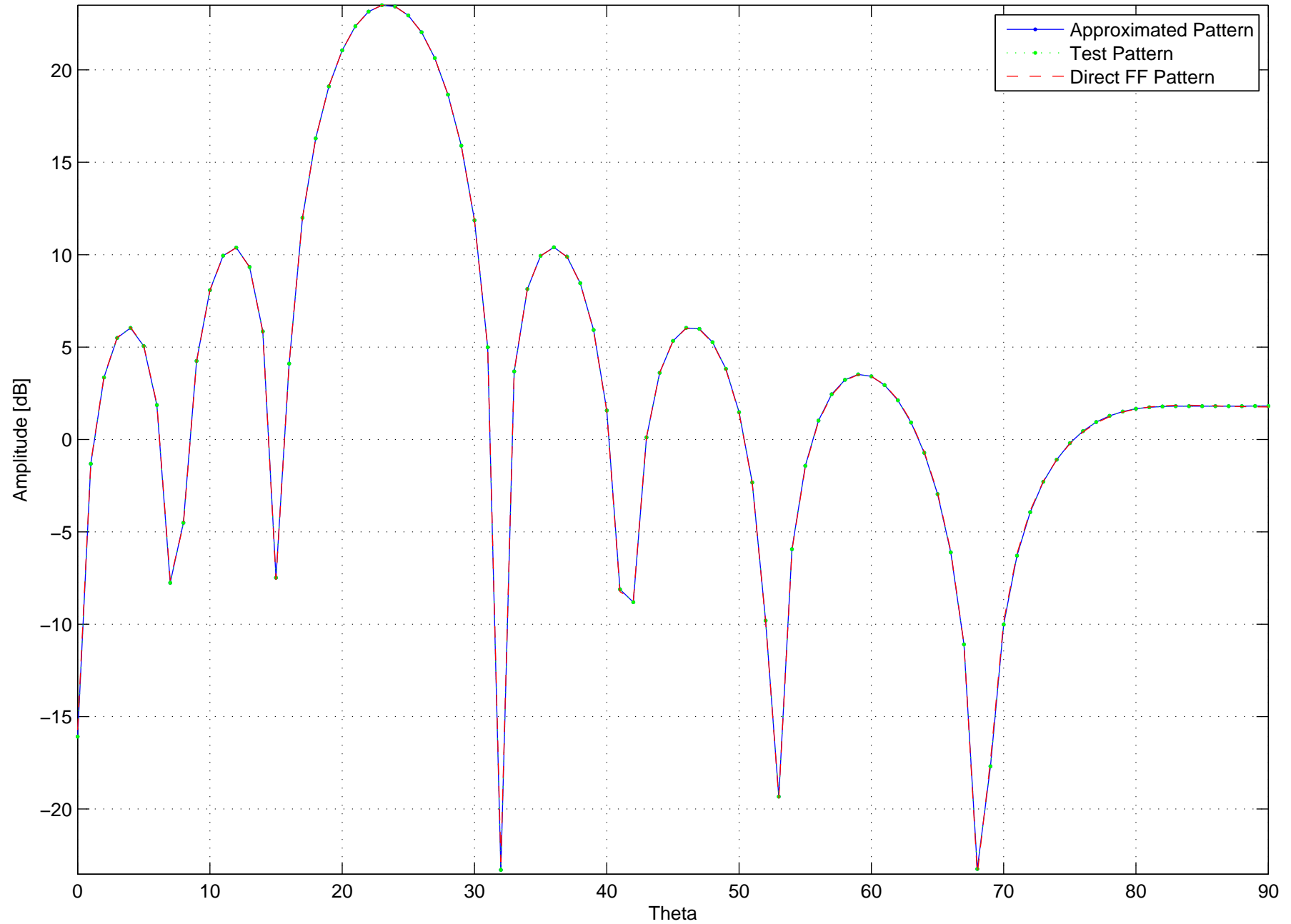
Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 0, Nbr of Vectors : 9
Nbr of point sources : 15



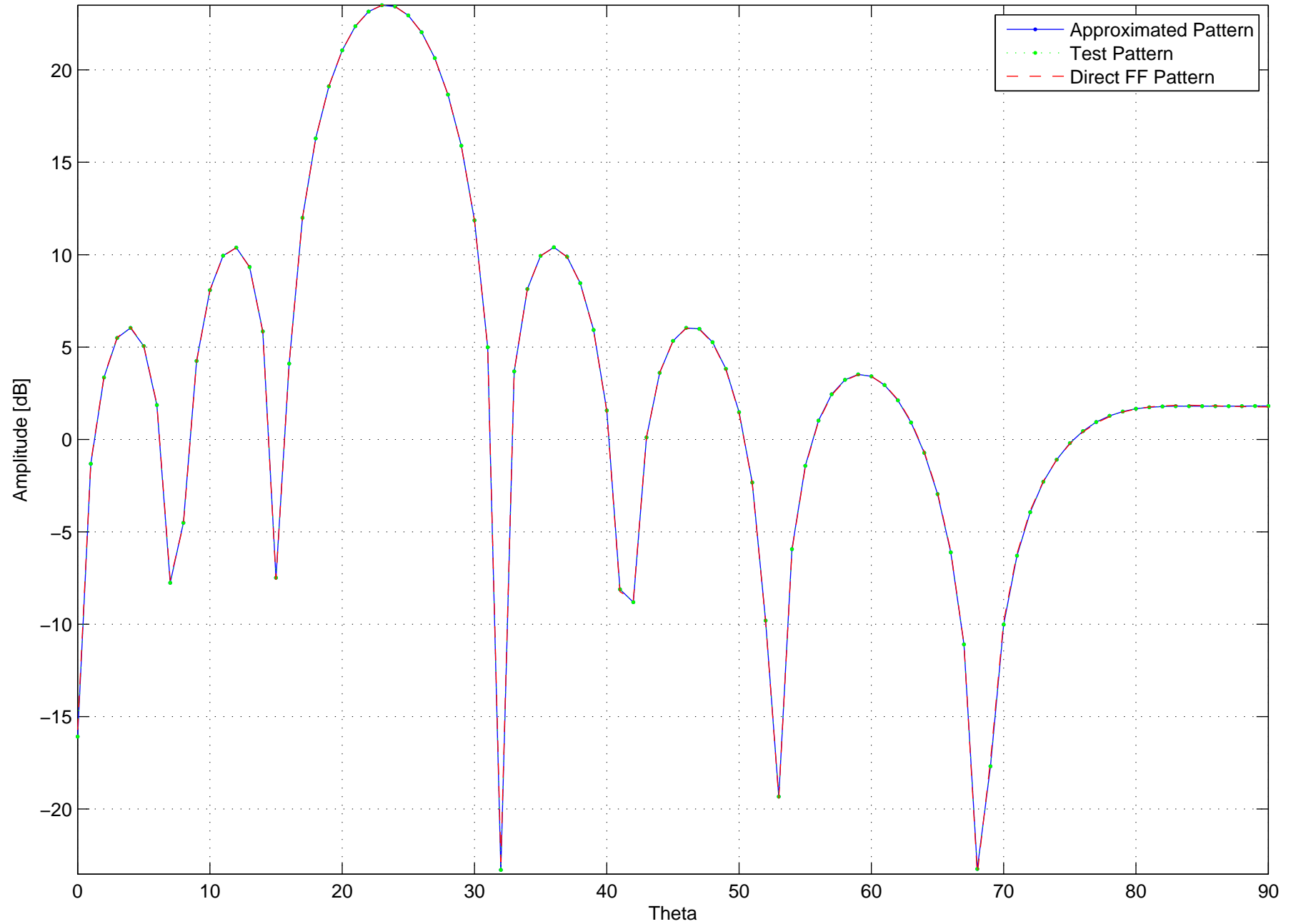
Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 0, Nbr of Vectors : 17
Nbr of point sources : 15

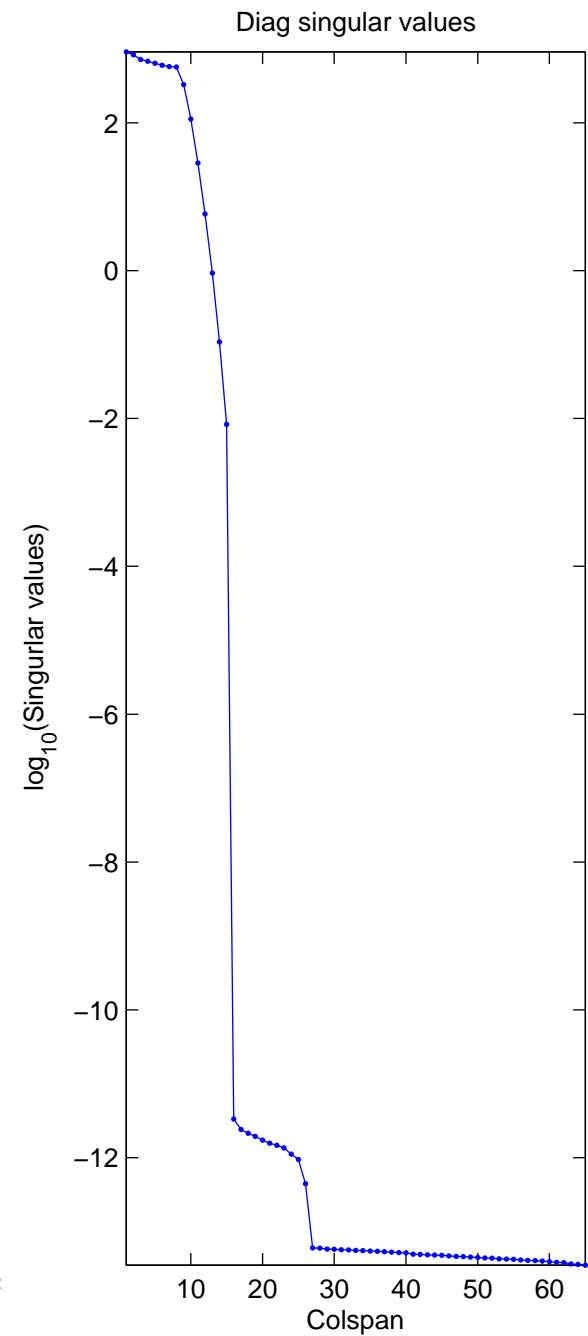
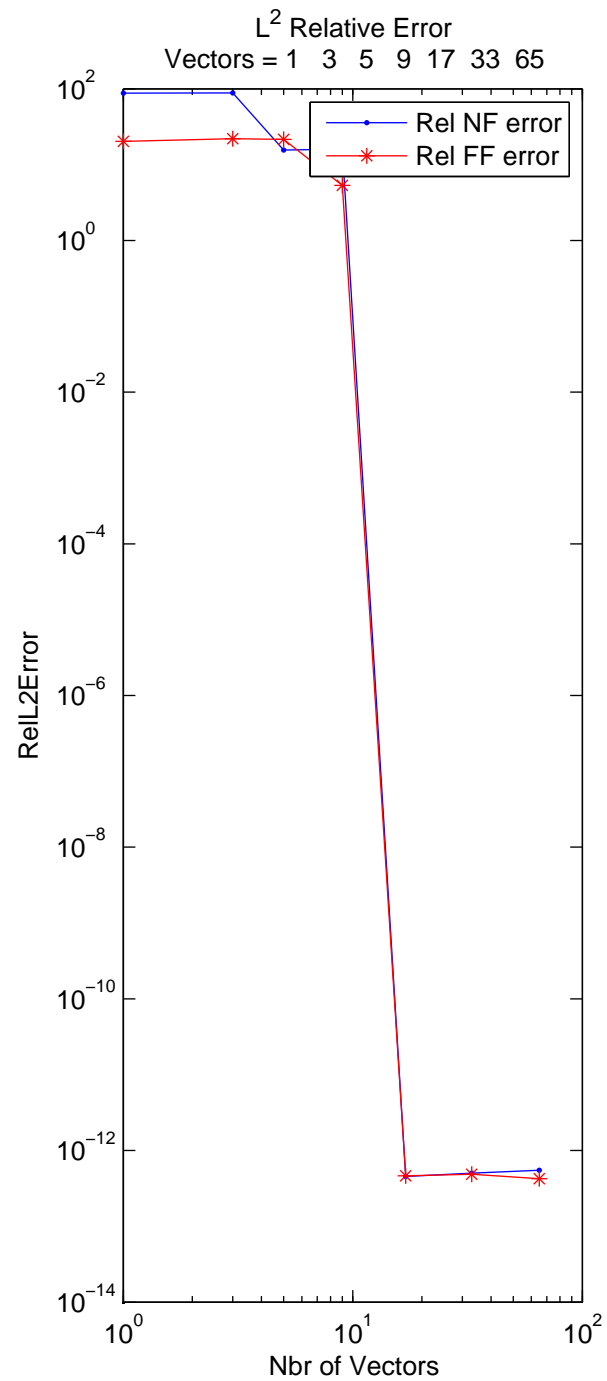
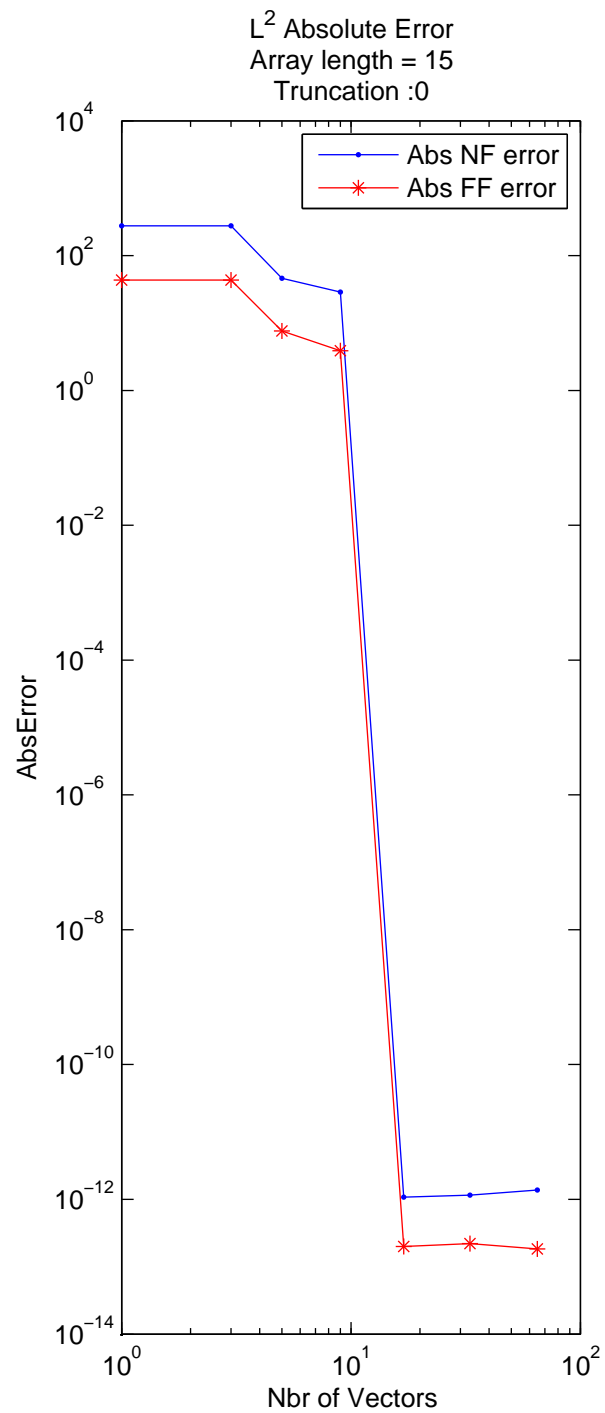


Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 0, Nbr of Vectors : 33
Nbr of point sources : 15

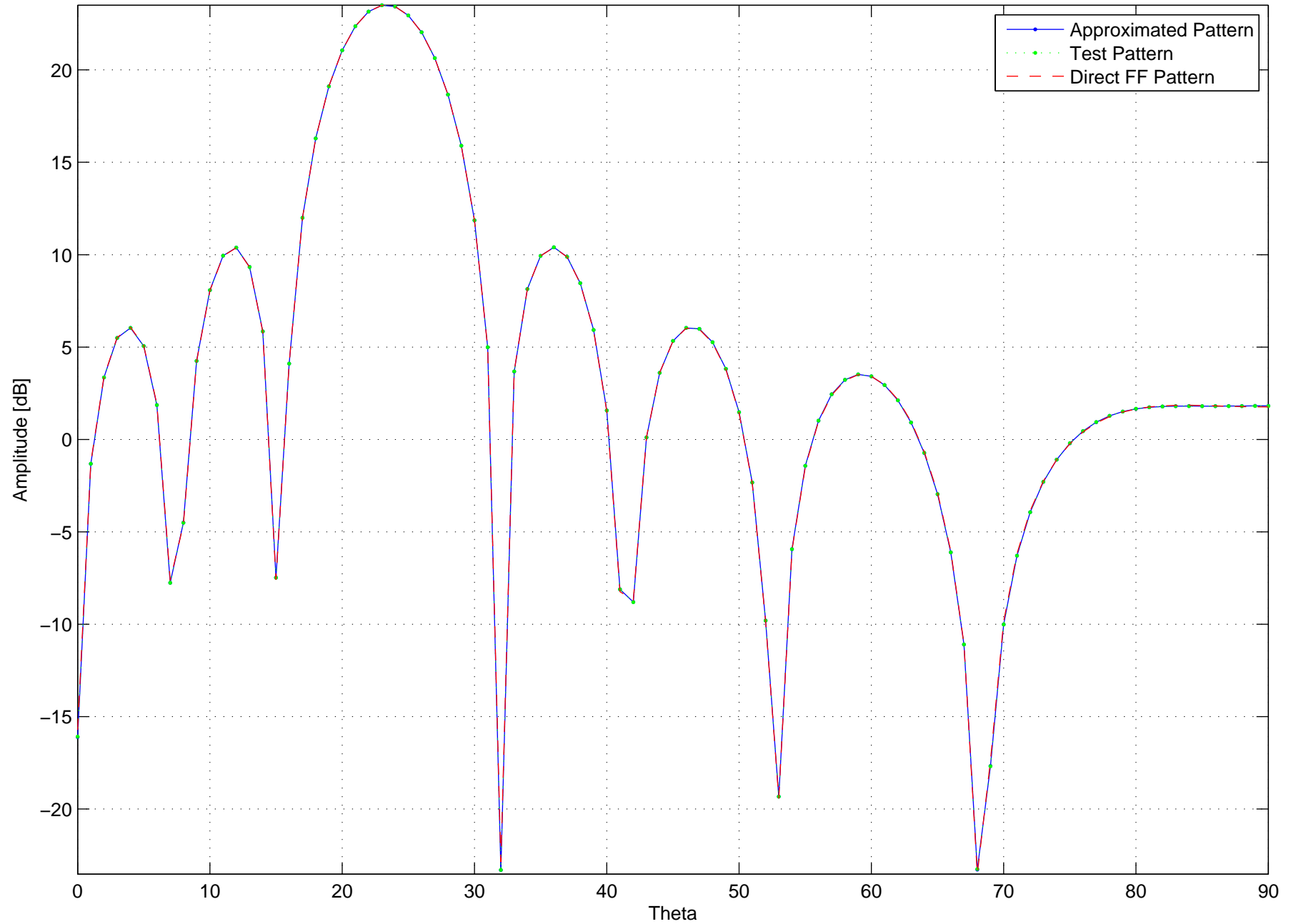


Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 0, Nbr of Vectors : 65
Nbr of point sources : 15

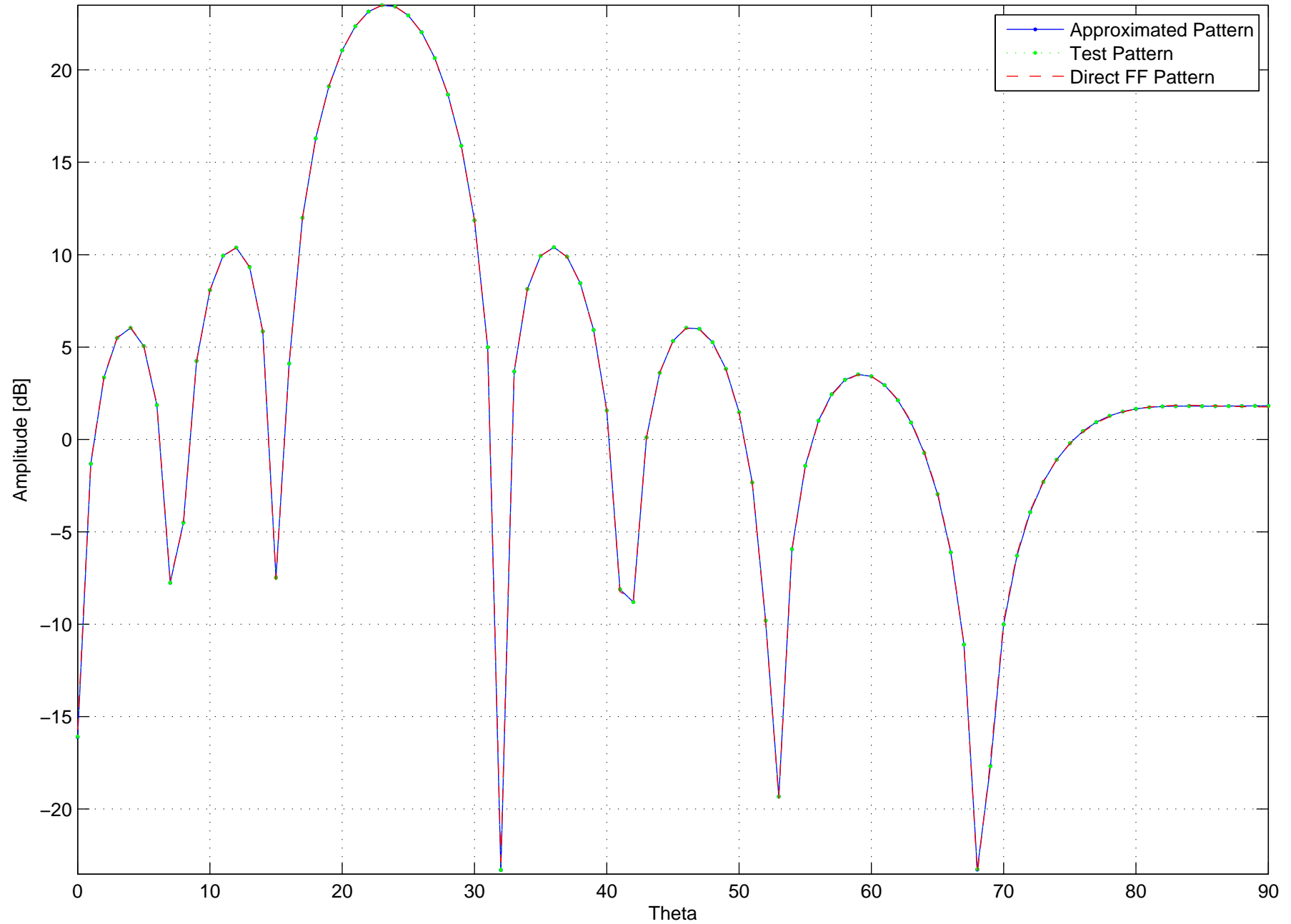




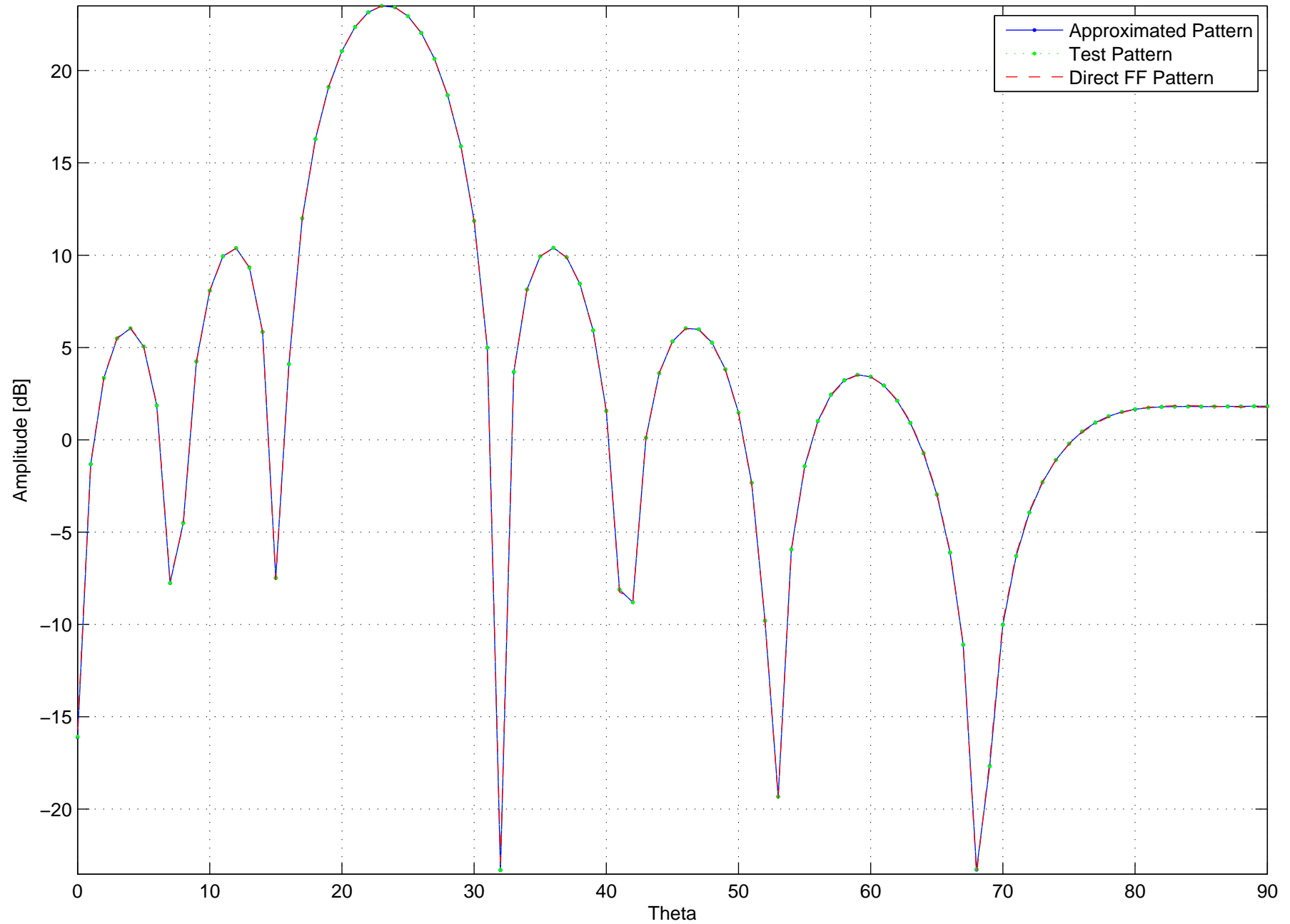
Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 12, Nbr of Vectors : 17
Nbr of point sources : 15

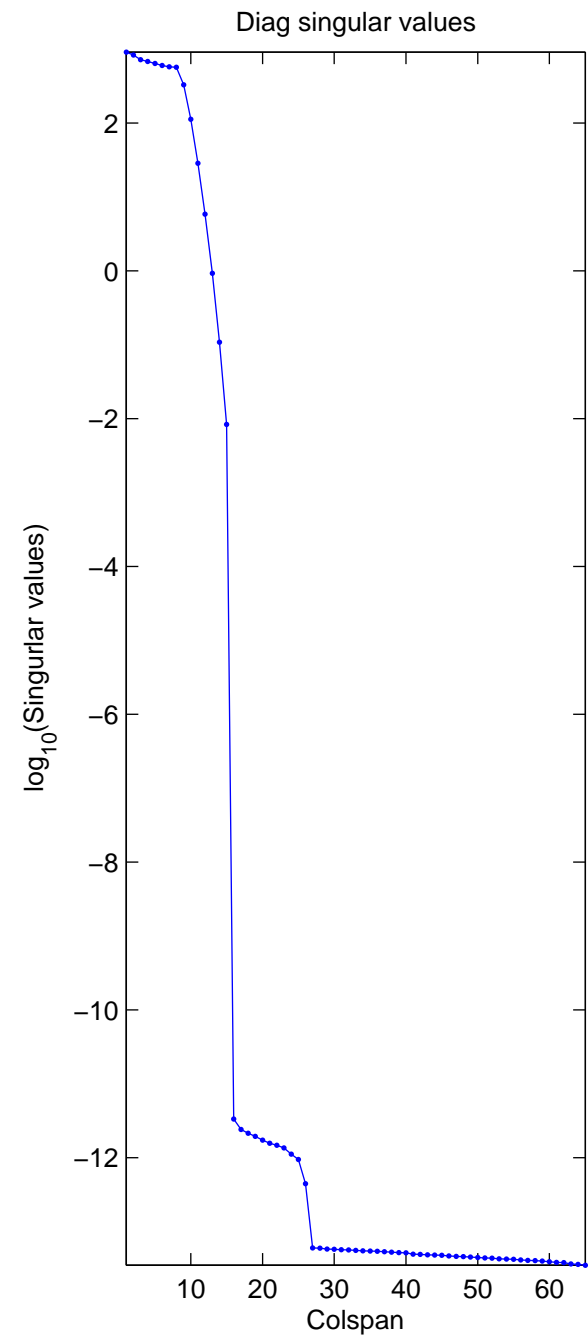
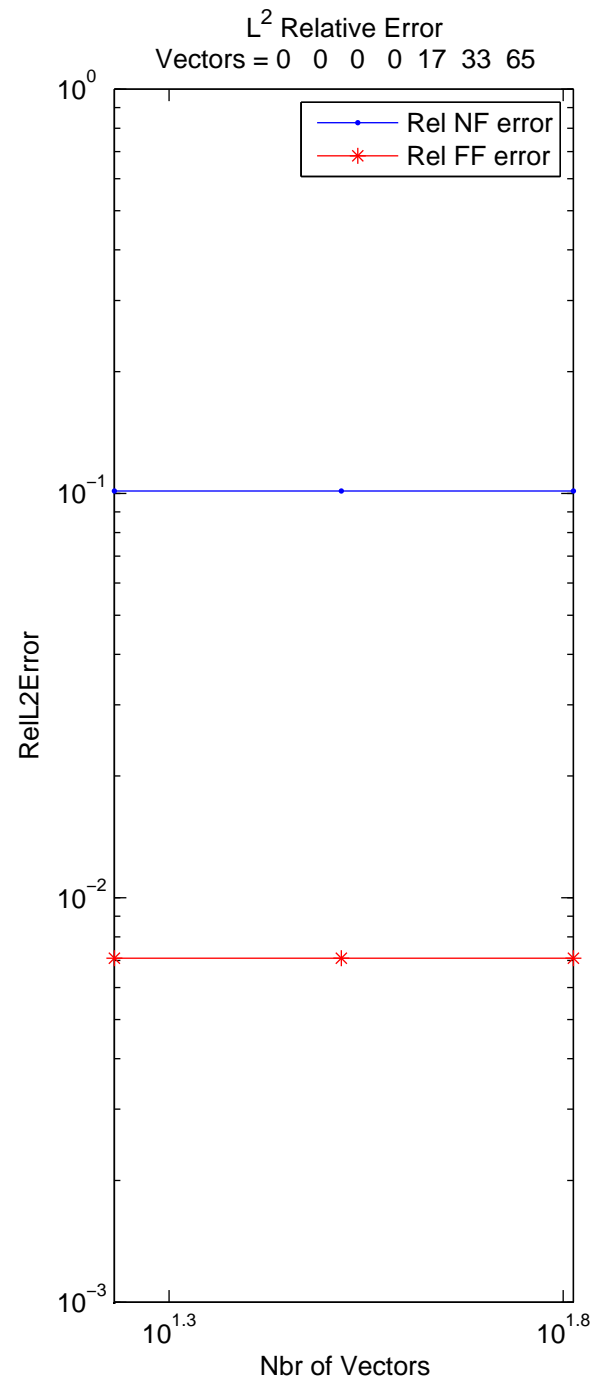
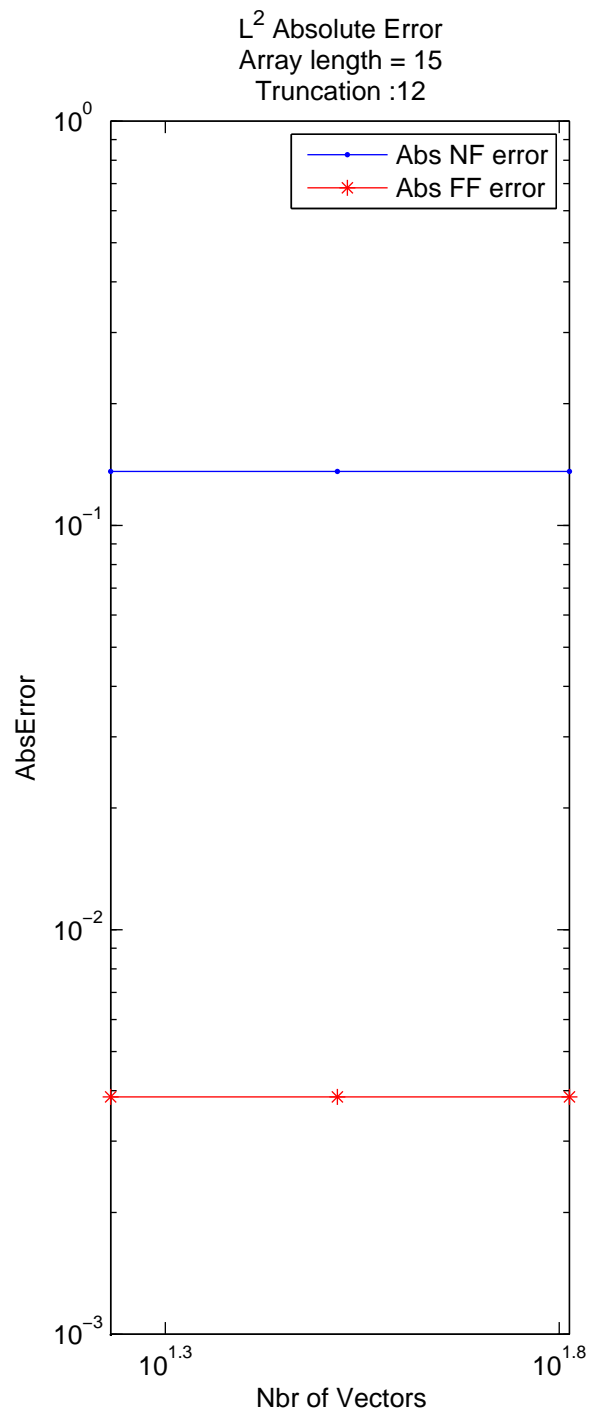


Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 12, Nbr of Vectors : 33
Nbr of point sources : 15

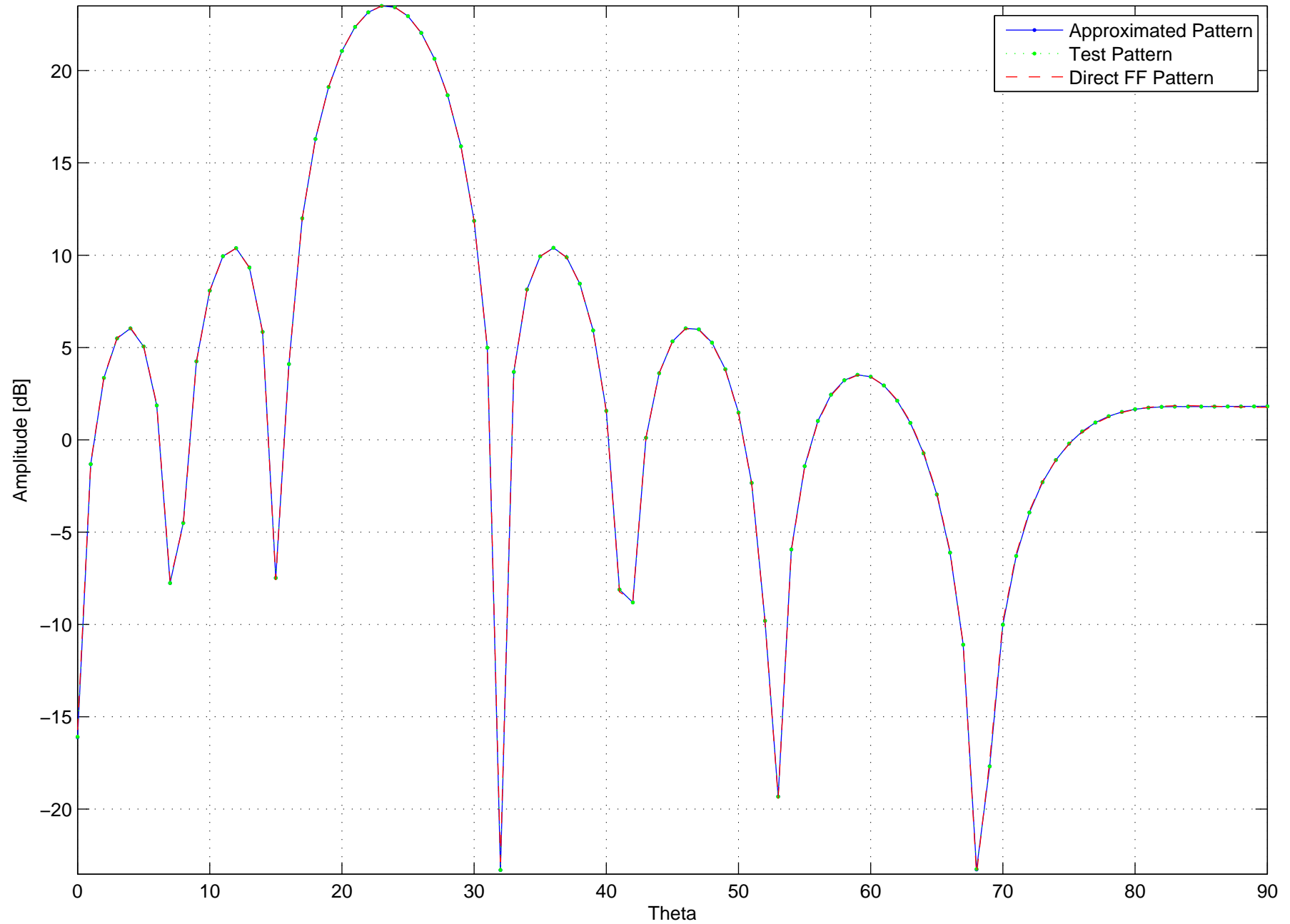


Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 12, Nbr of Vectors : 65
Nbr of point sources : 15

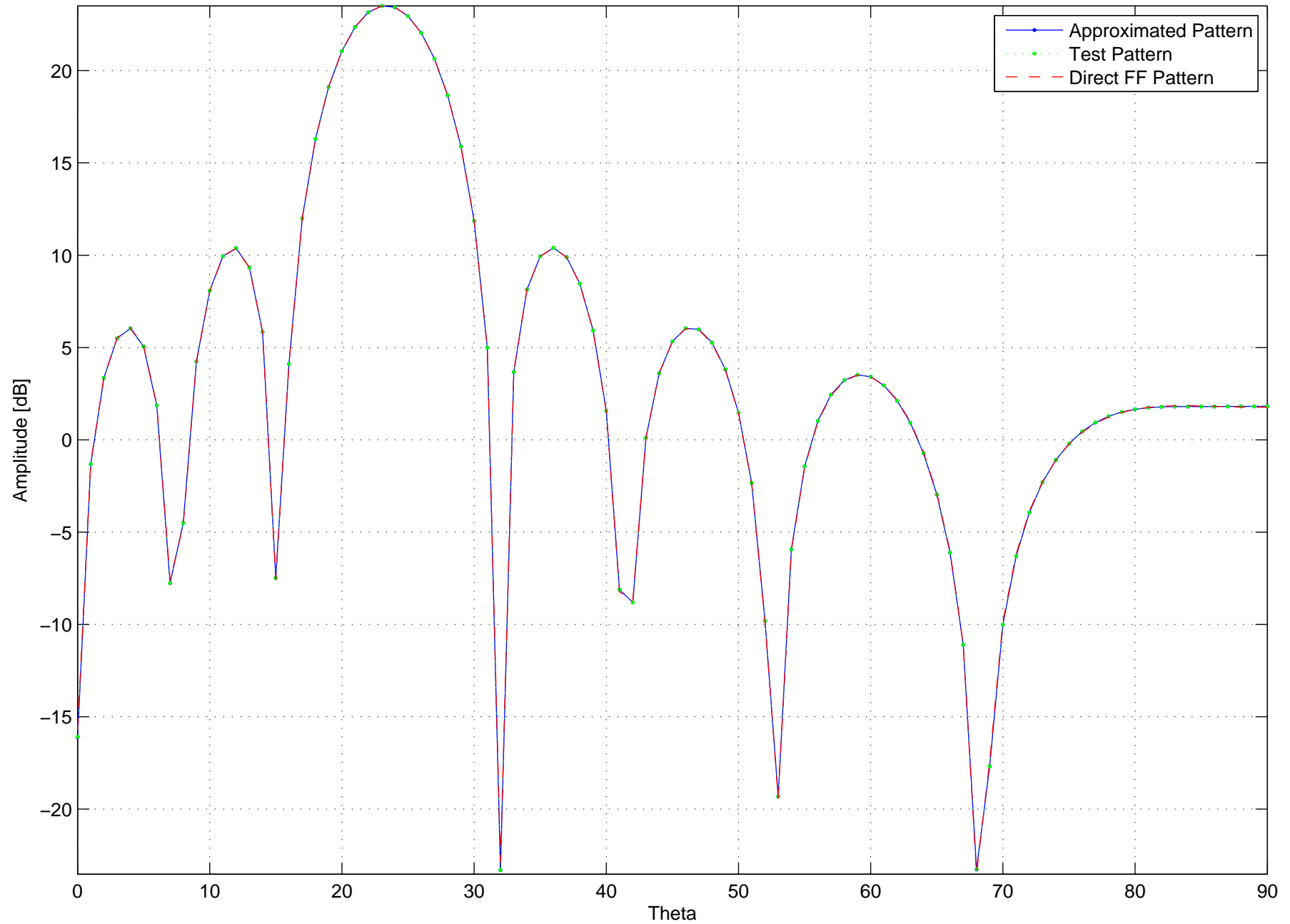




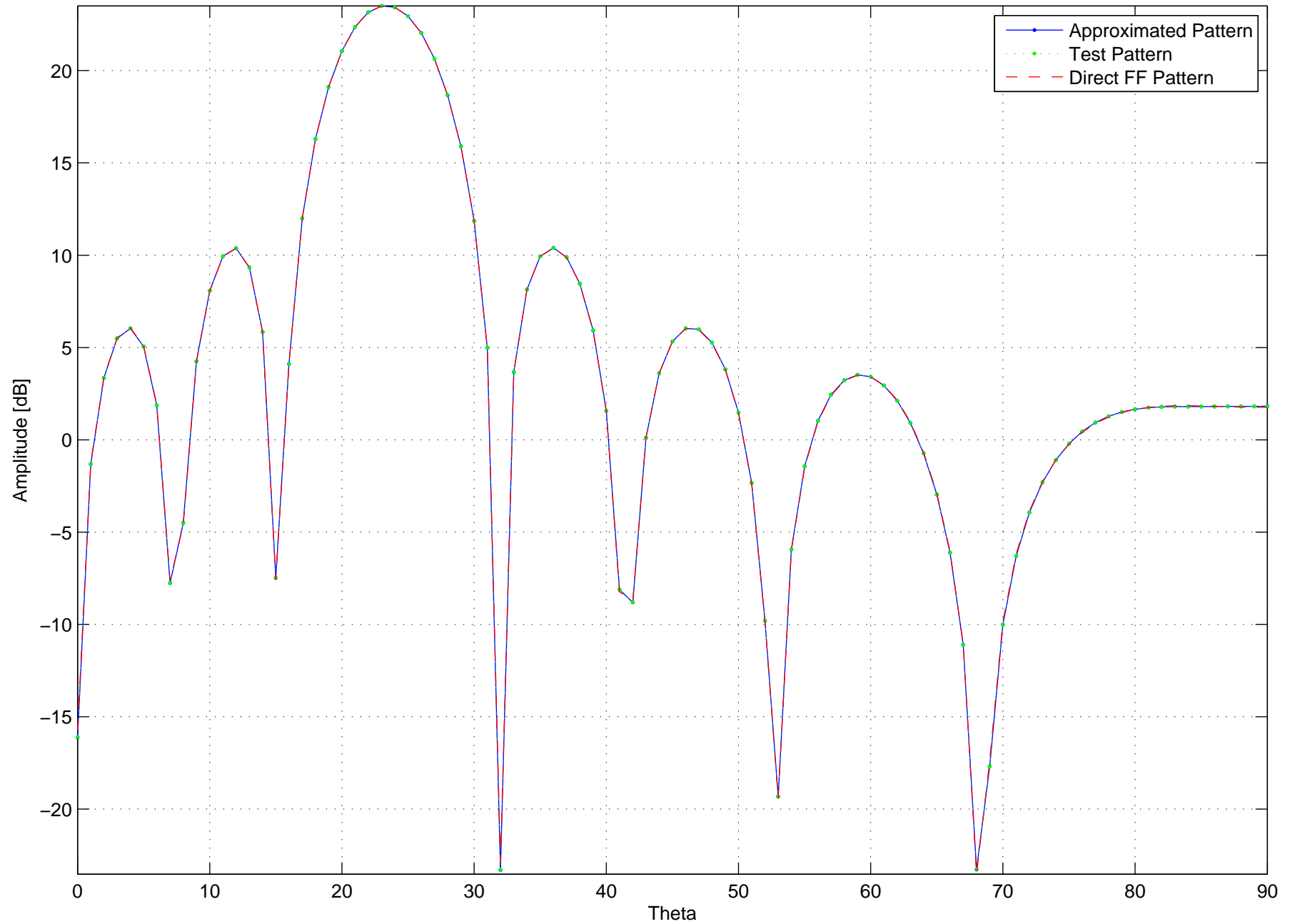
Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 11, Nbr of Vectors : 17
Nbr of point sources : 15

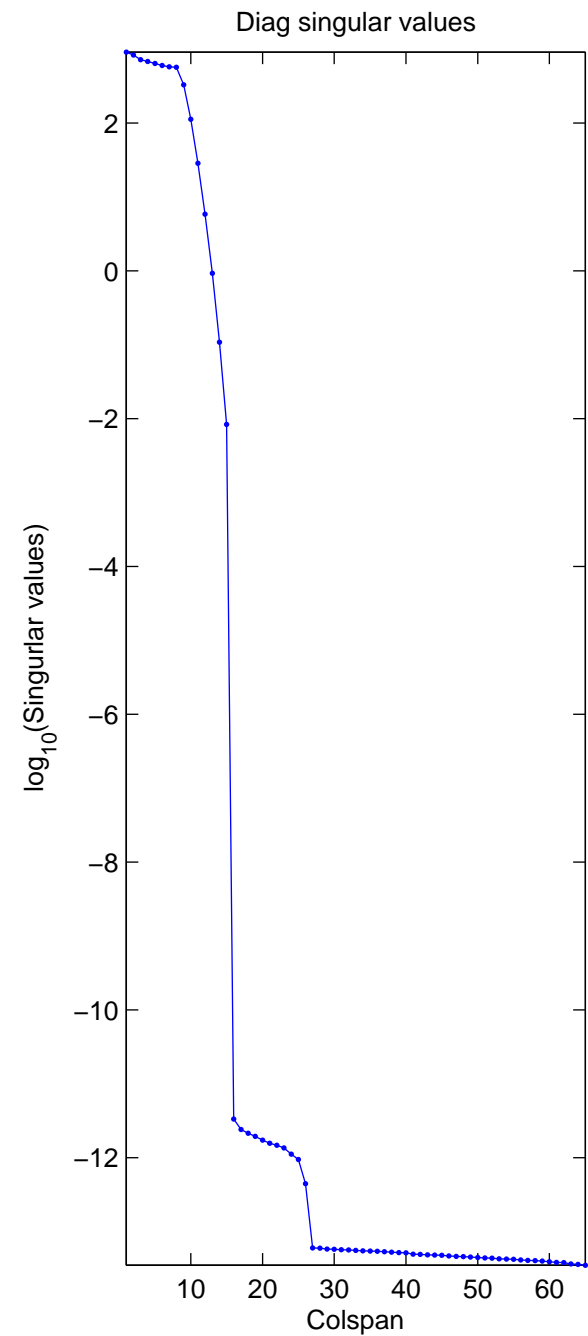
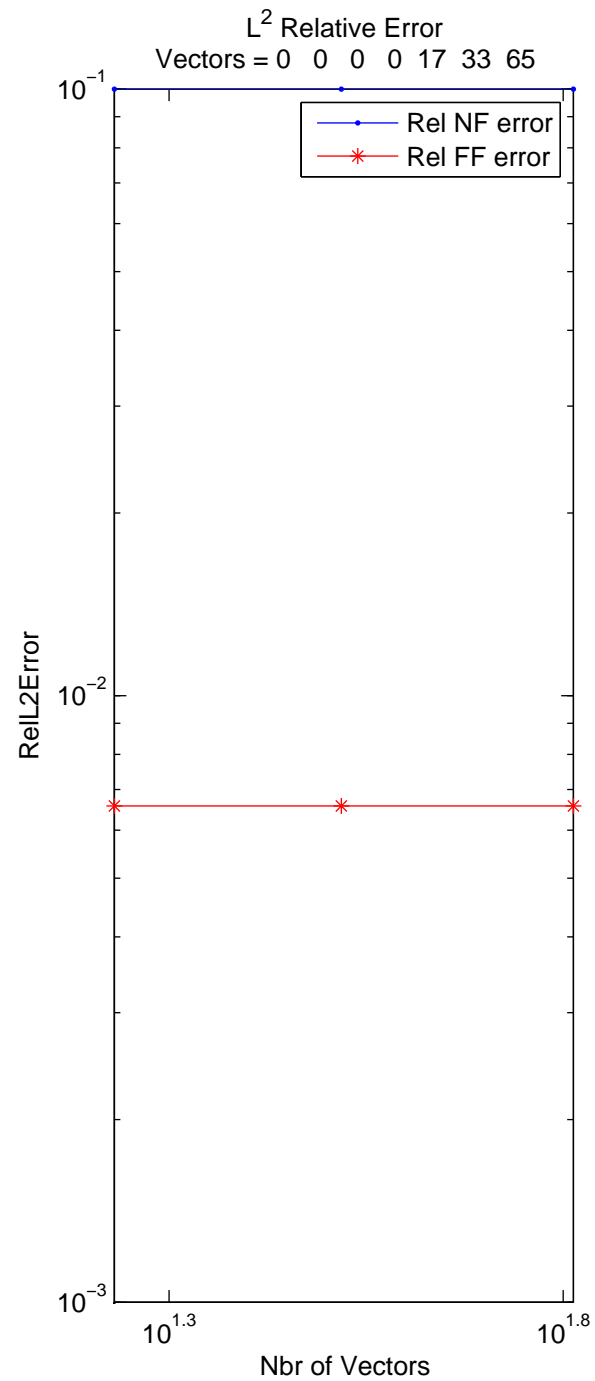
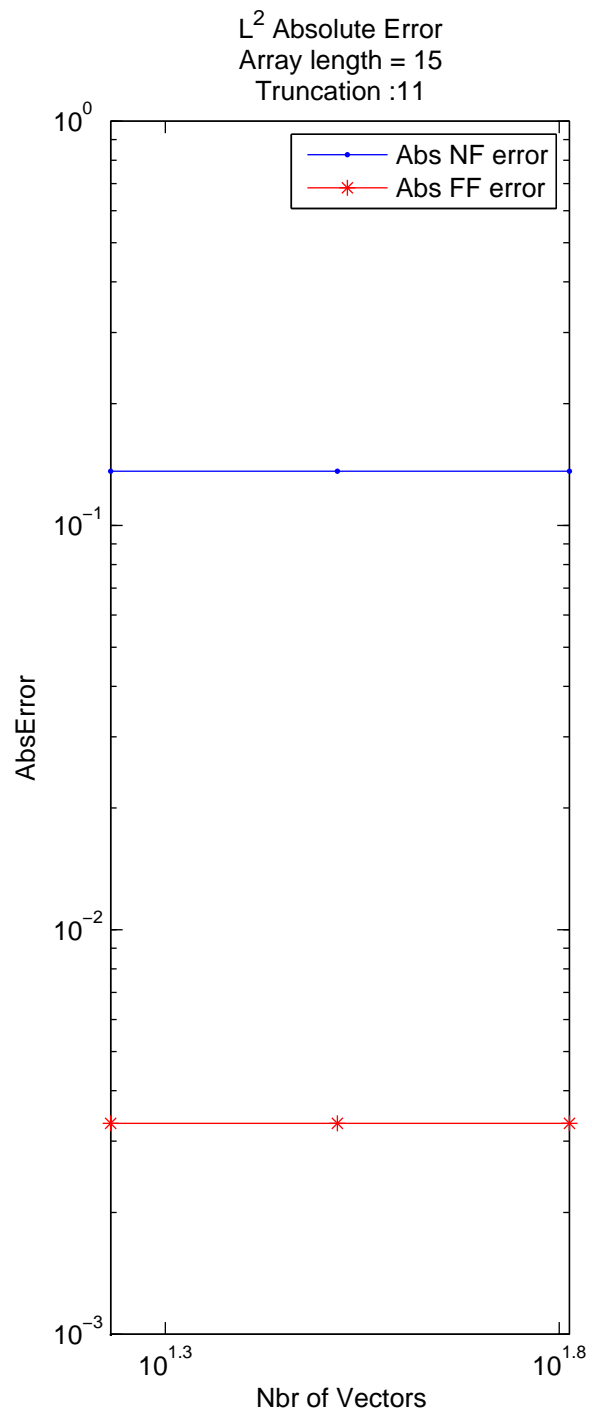


Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 11, Nbr of Vectors : 33
Nbr of point sources : 15

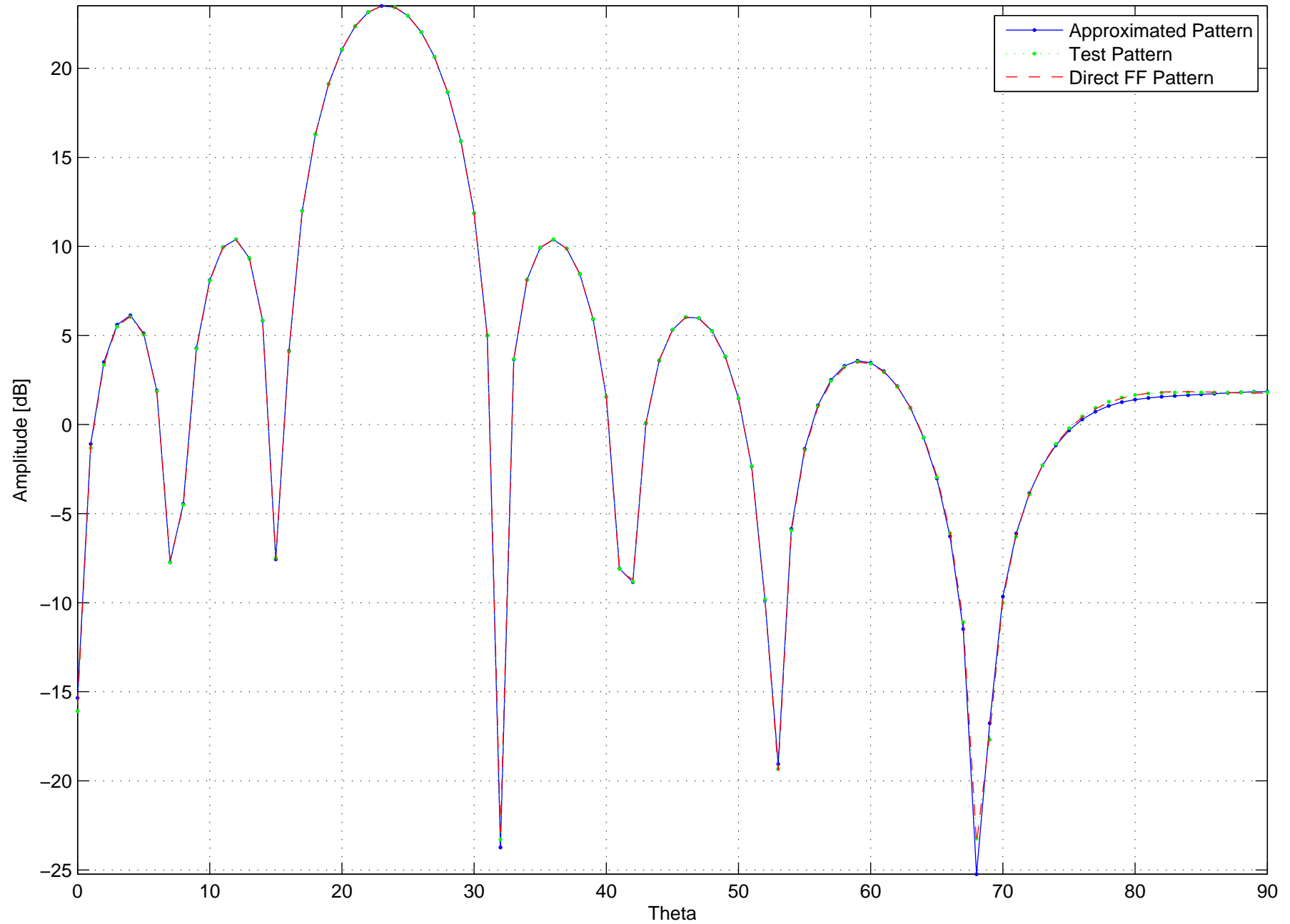


Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 11, Nbr of Vectors : 65
Nbr of point sources : 15

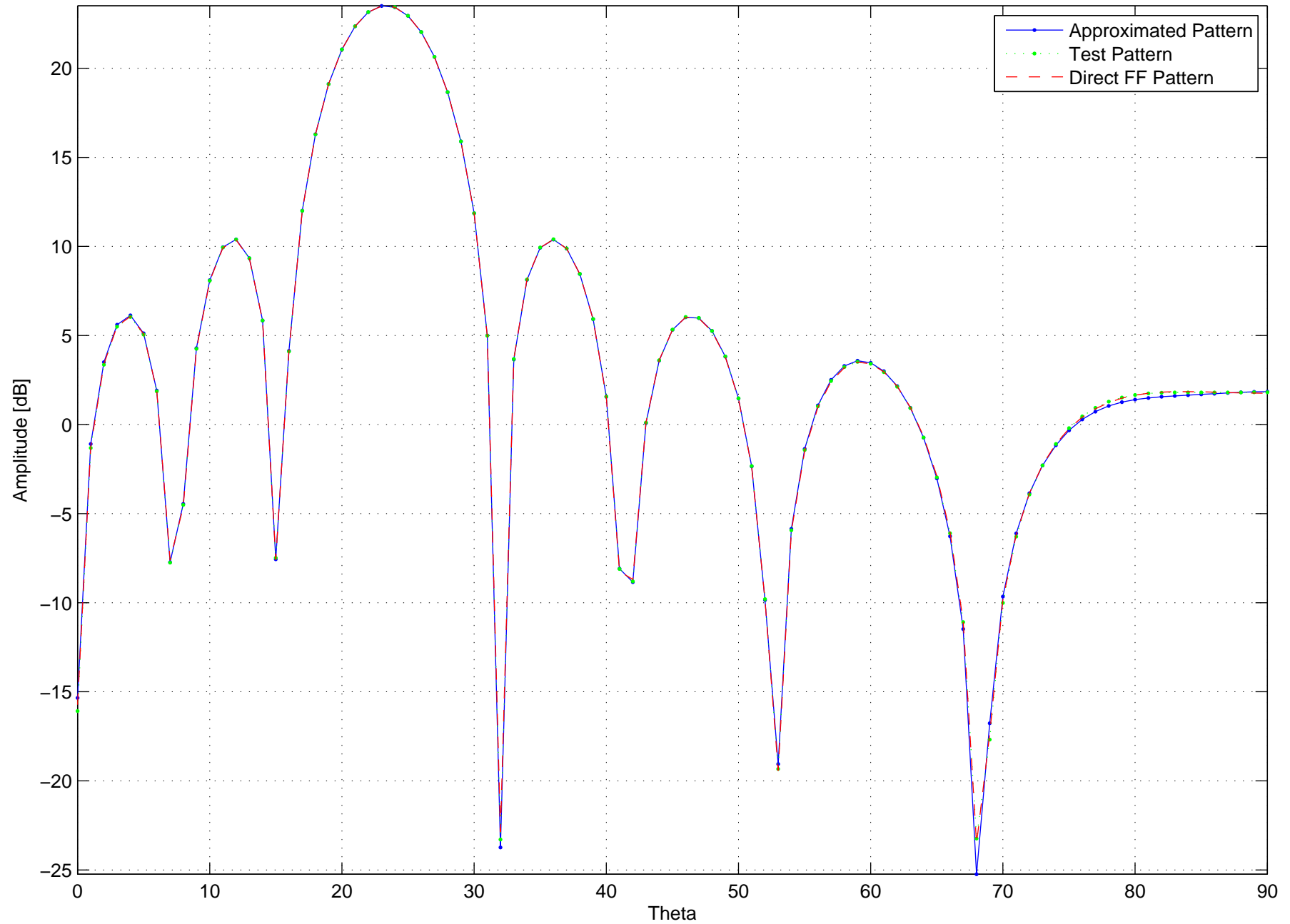




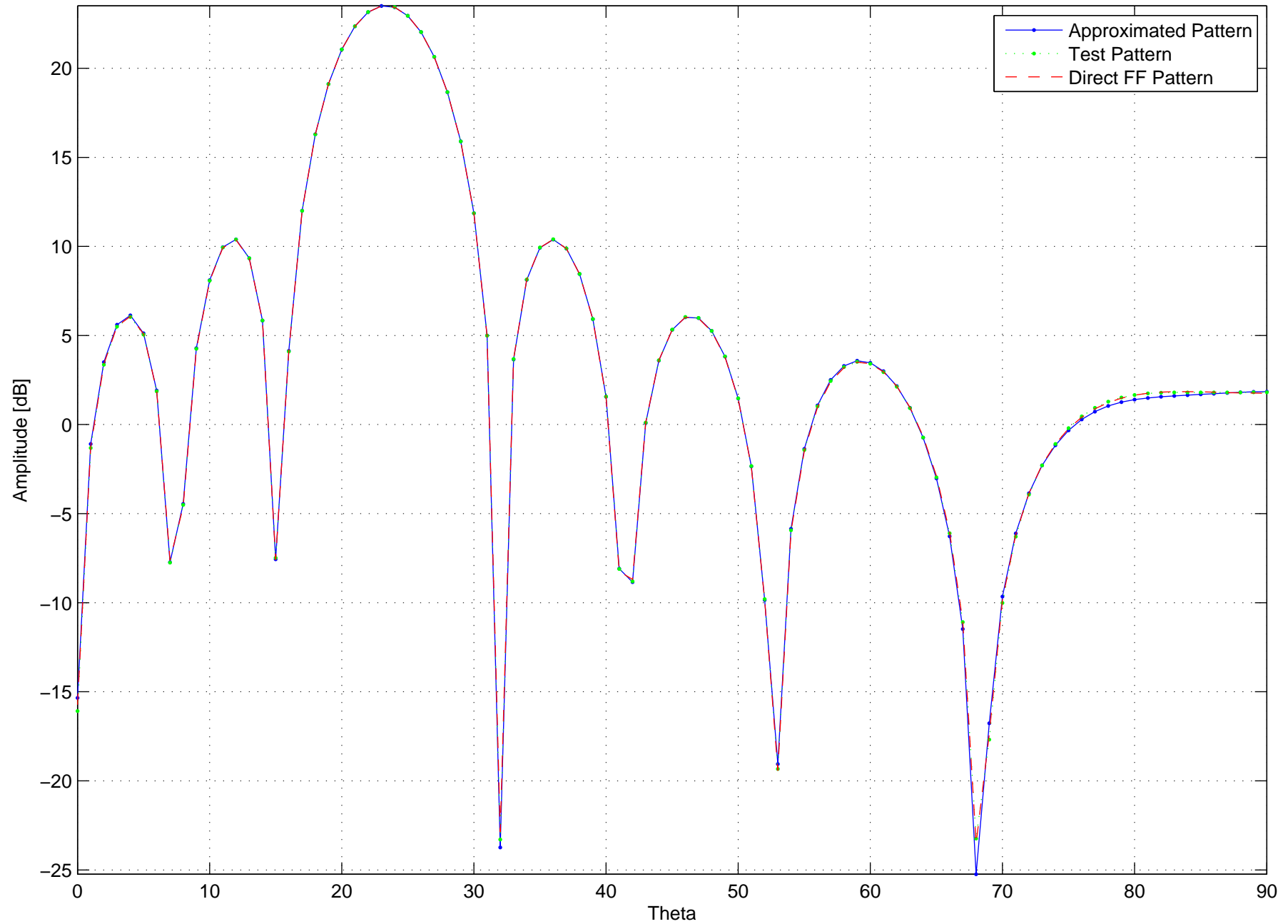
Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 10, Nbr of Vectors : 17
Nbr of point sources : 15

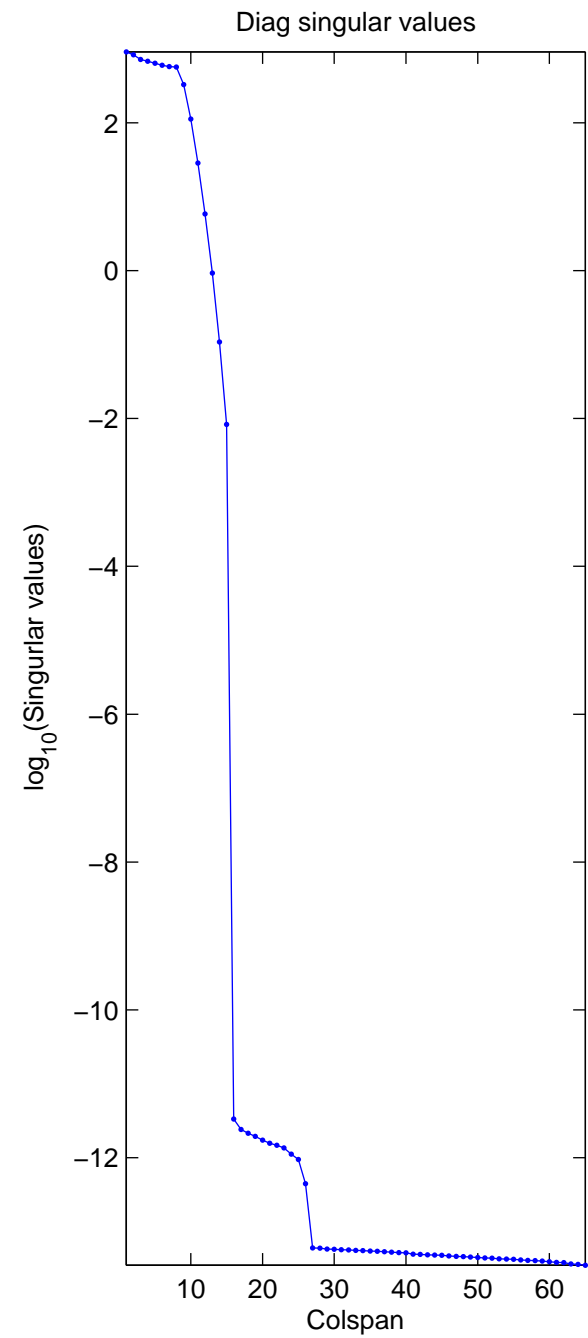
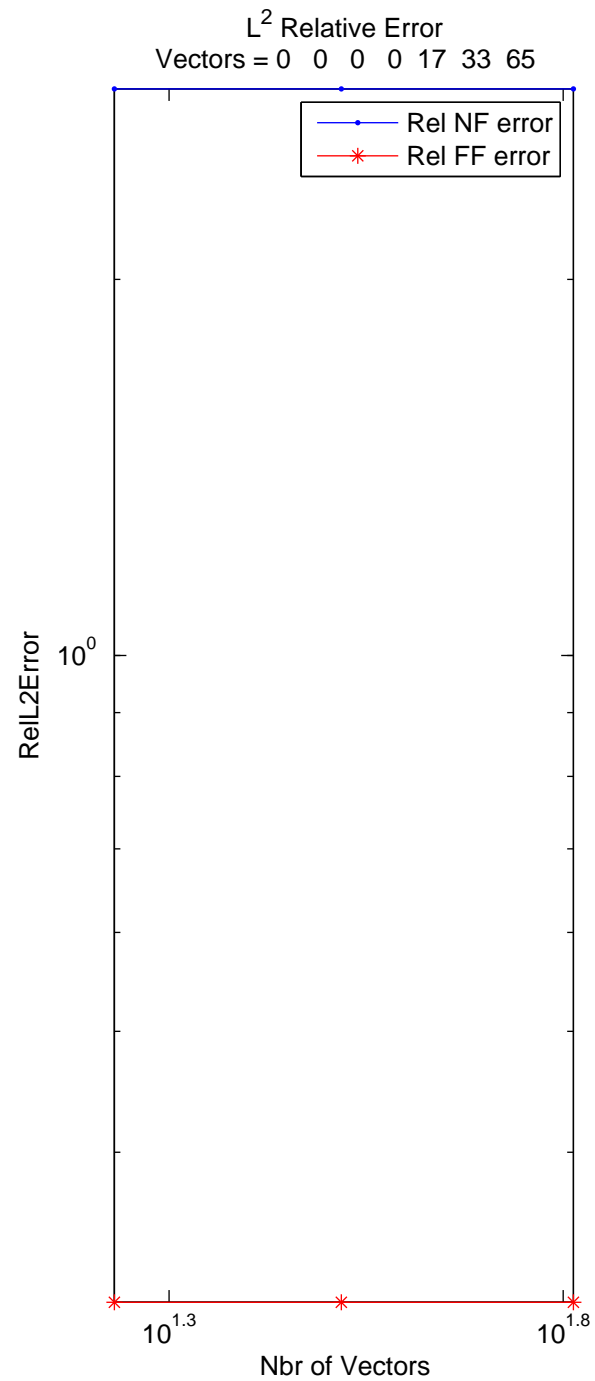
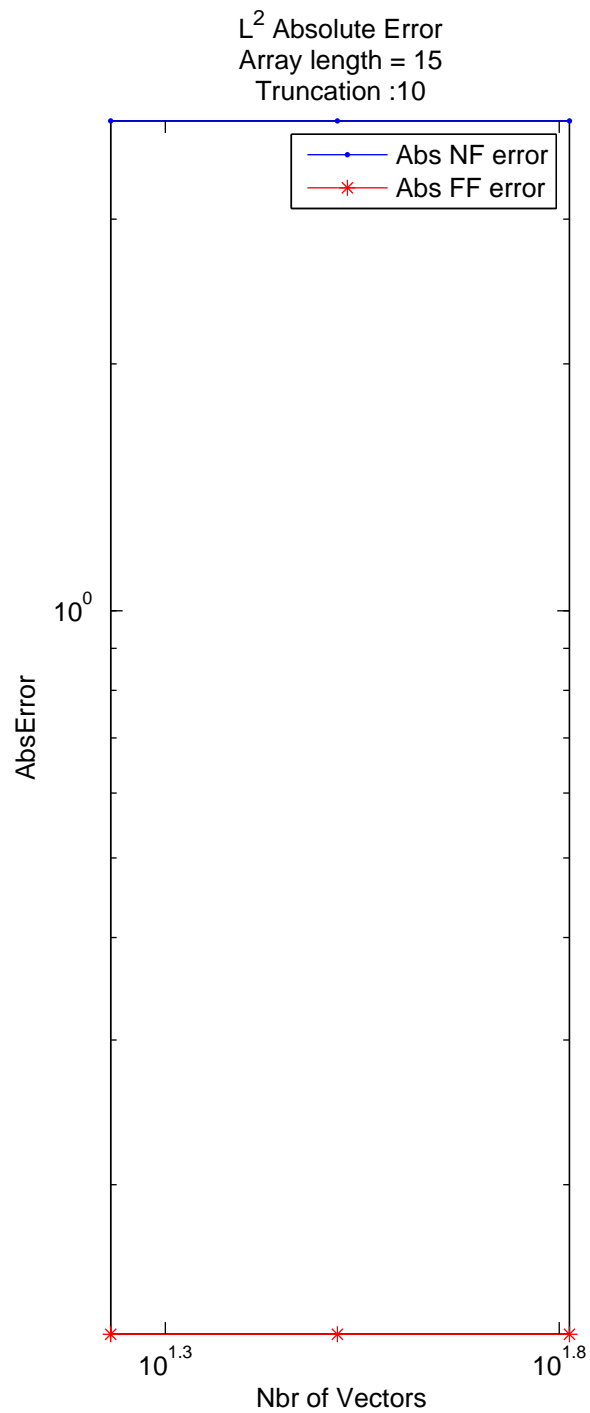


Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 10, Nbr of Vectors : 33
Nbr of point sources : 15

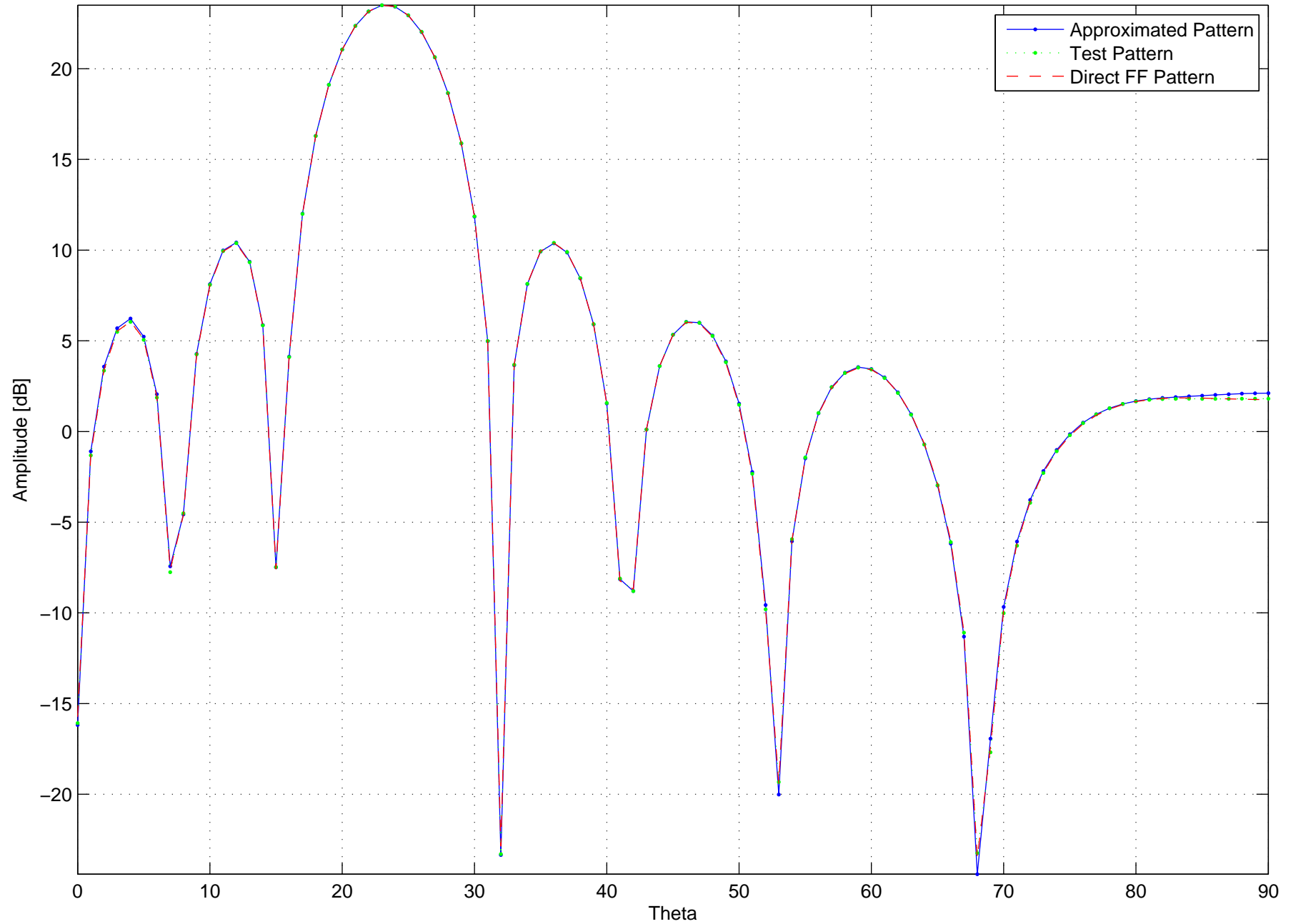


Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 10, Nbr of Vectors : 65
Nbr of point sources : 15

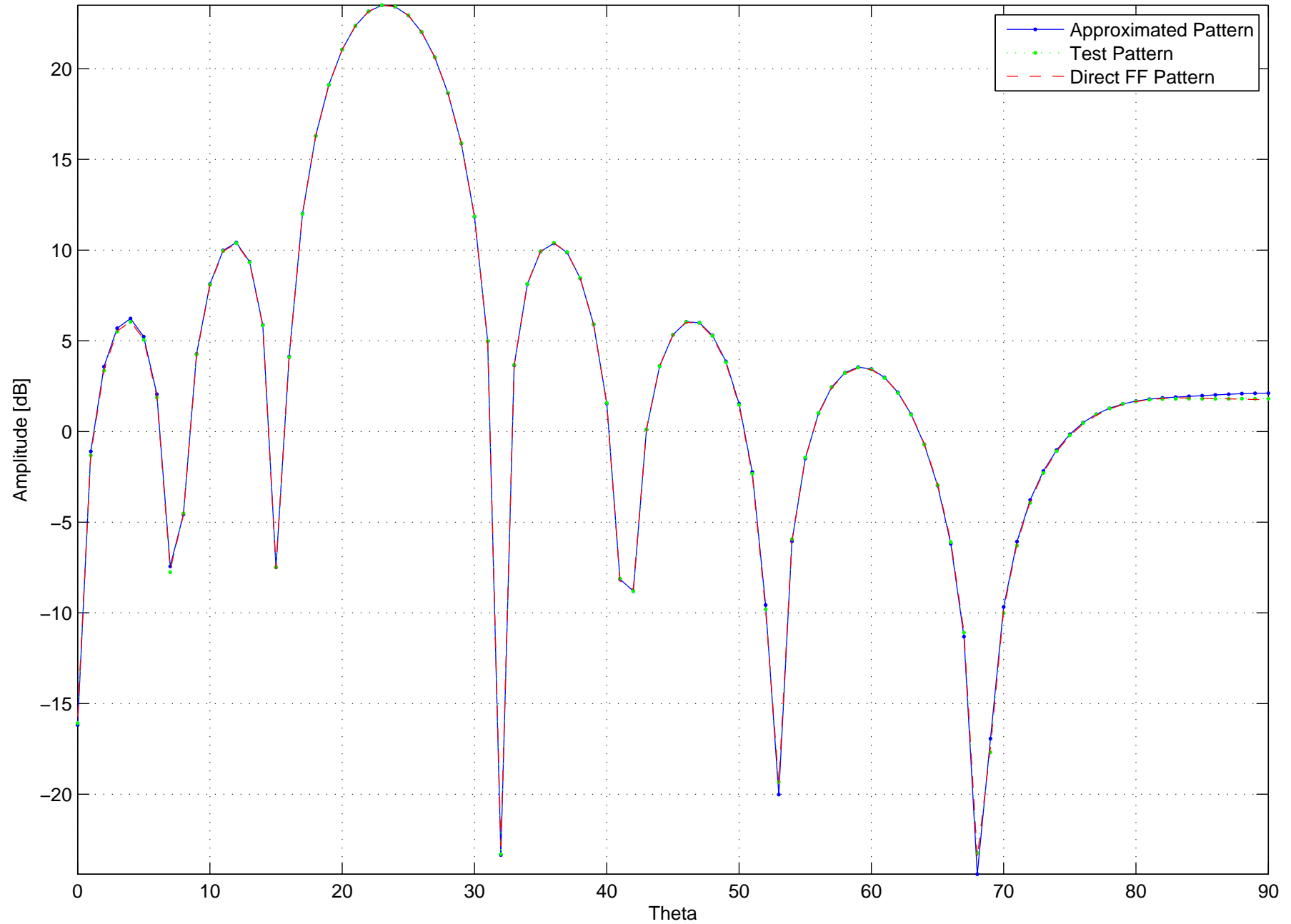




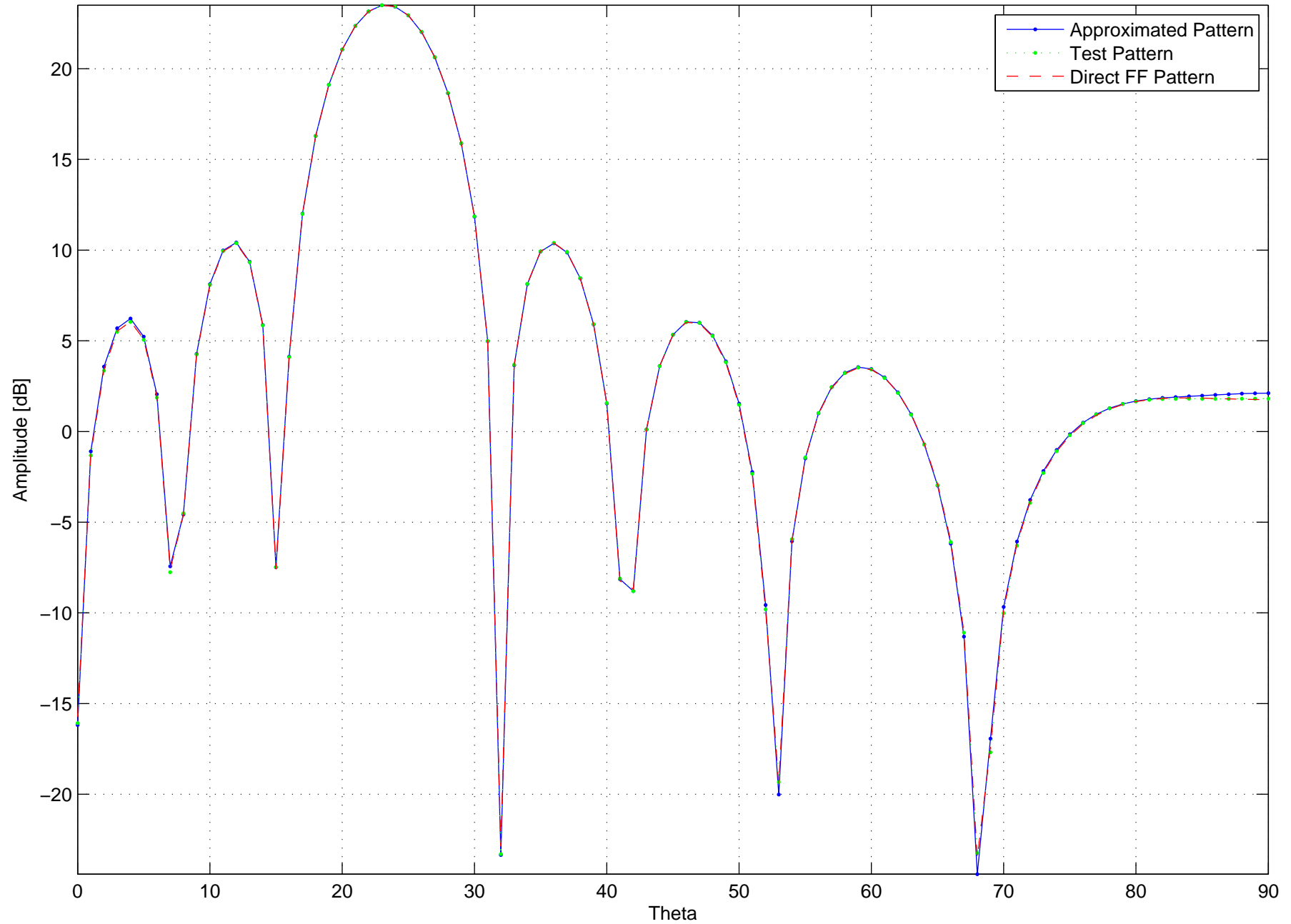
Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 9, Nbr of Vectors : 17
Nbr of point sources : 15



Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 9, Nbr of Vectors : 33
Nbr of point sources : 15



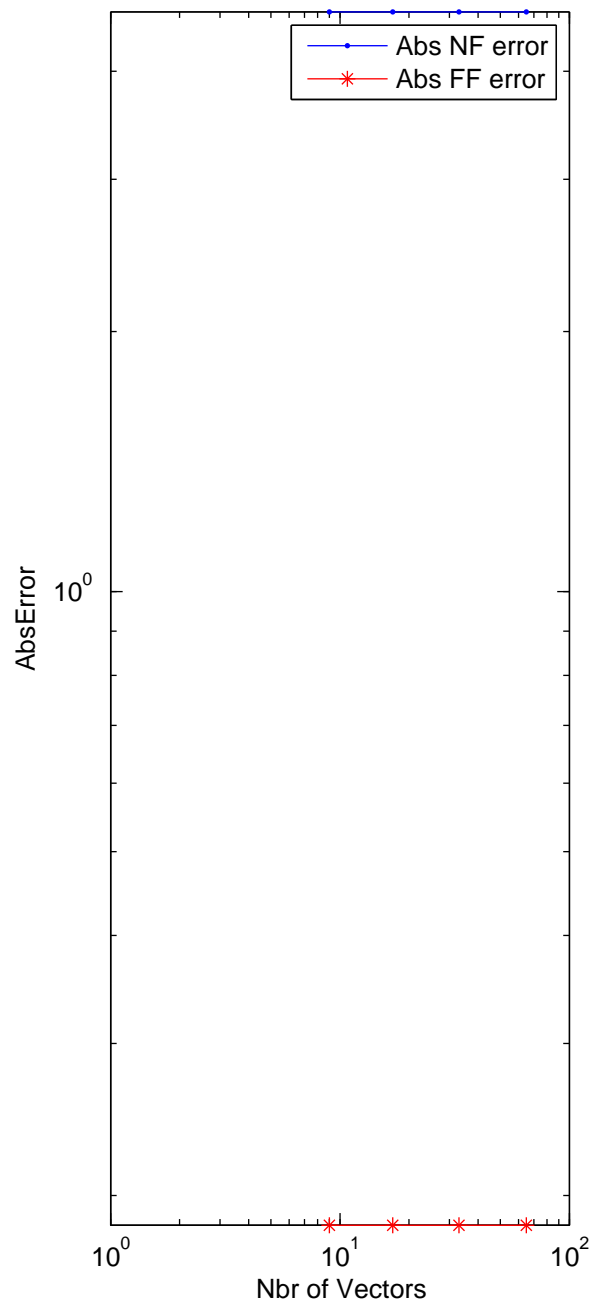
Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 9, Nbr of Vectors : 65
Nbr of point sources : 15



L^2 Absolute Error

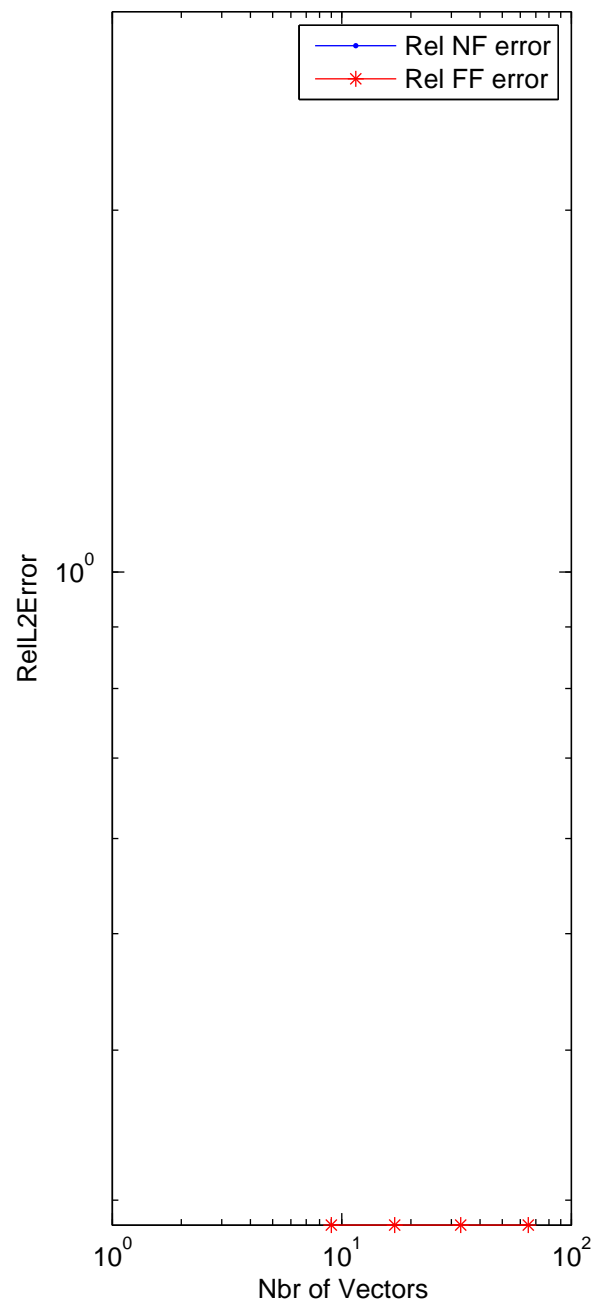
Array length = 15

Truncation :9

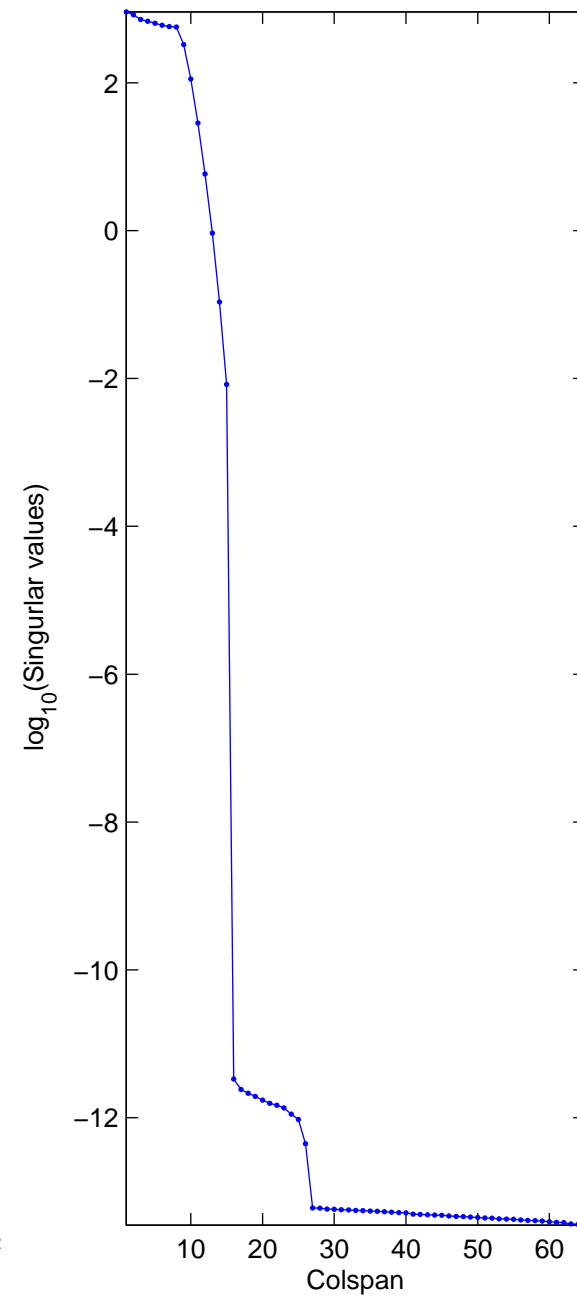


L^2 Relative Error

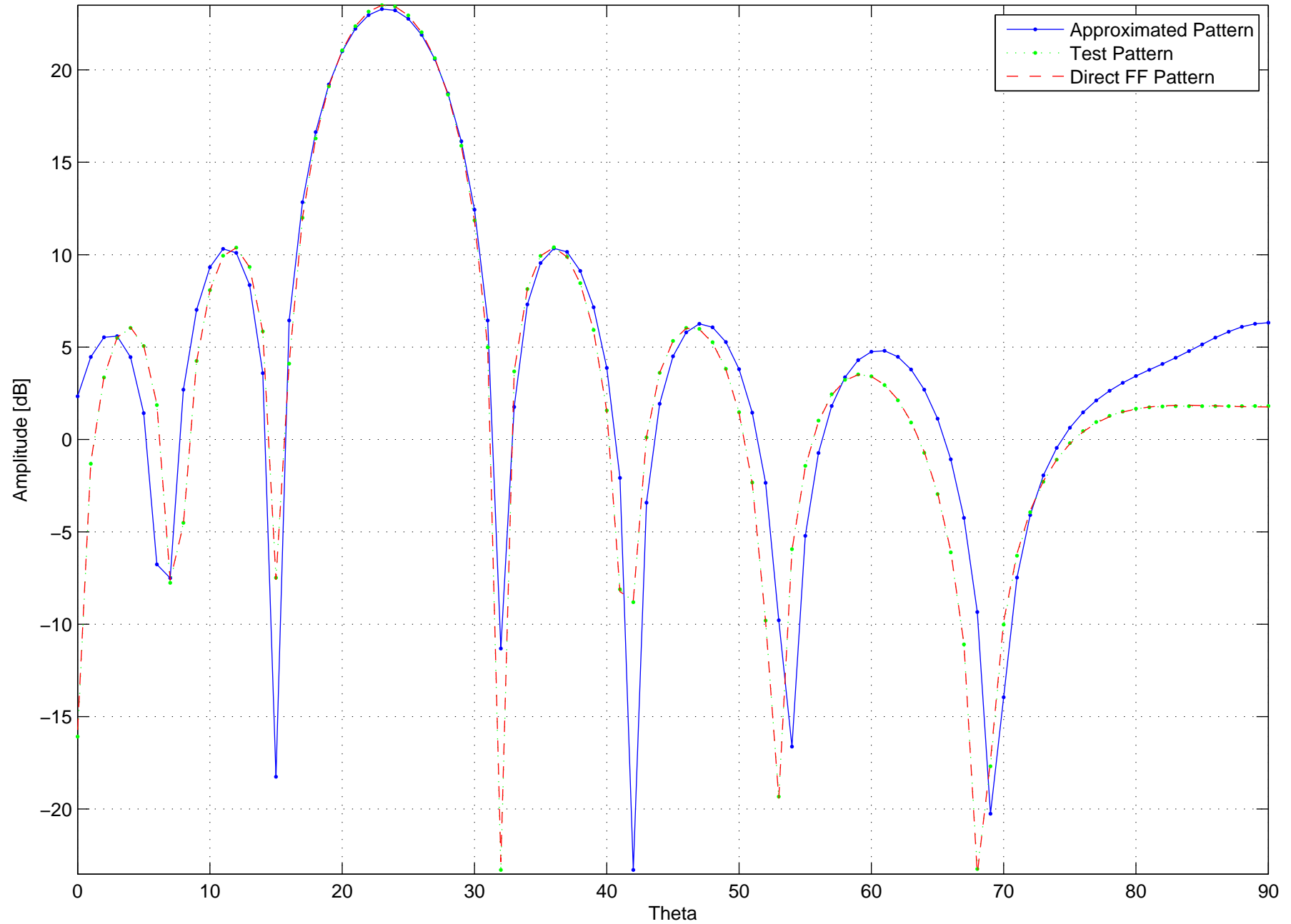
Vectors = 0 0 0 9 17 33 65



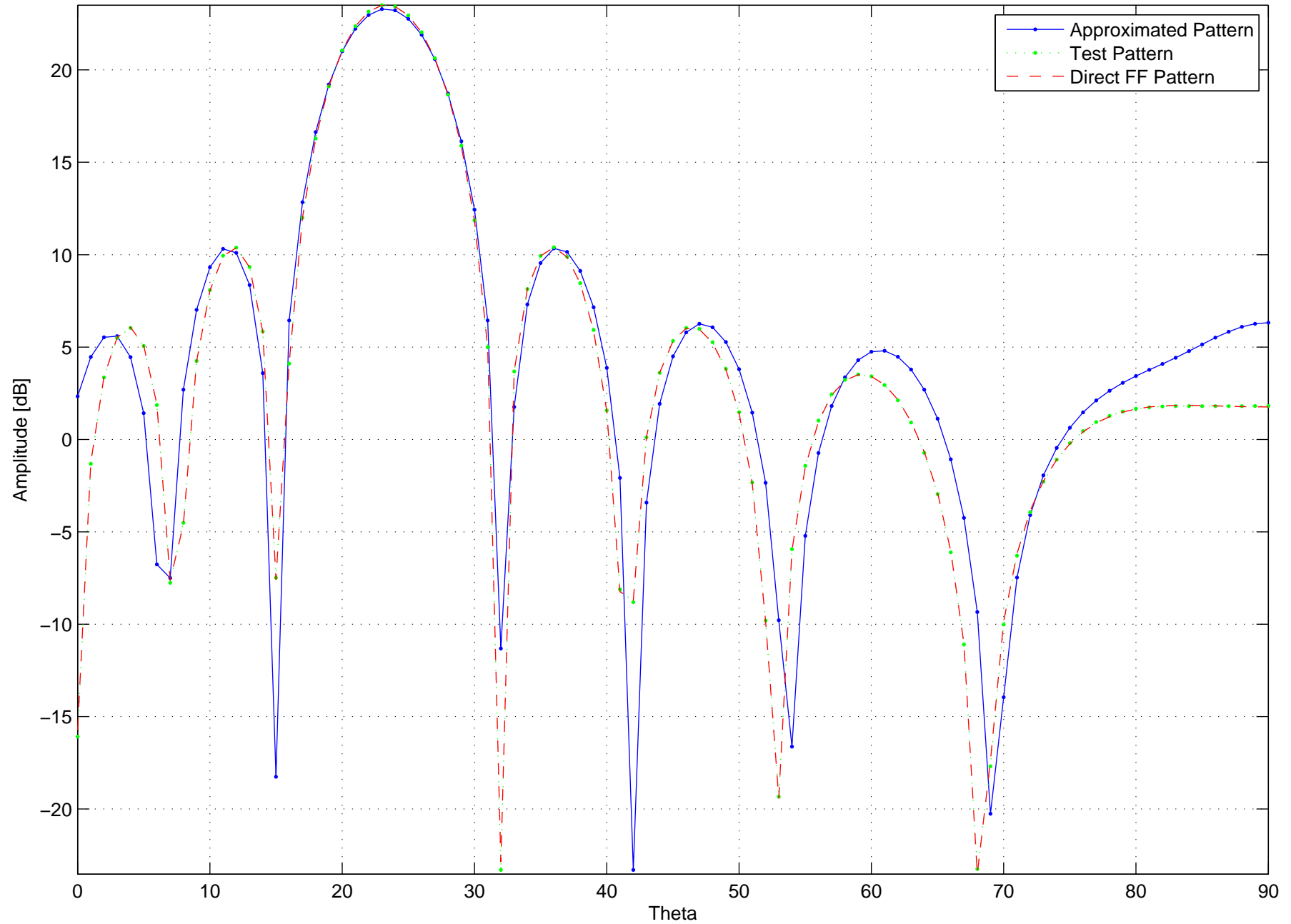
Diag singular values



Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 8, Nbr of Vectors : 17
Nbr of point sources : 15



Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 8, Nbr of Vectors : 33
Nbr of point sources : 15



Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 8, Nbr of Vectors : 65
Nbr of point sources : 15

