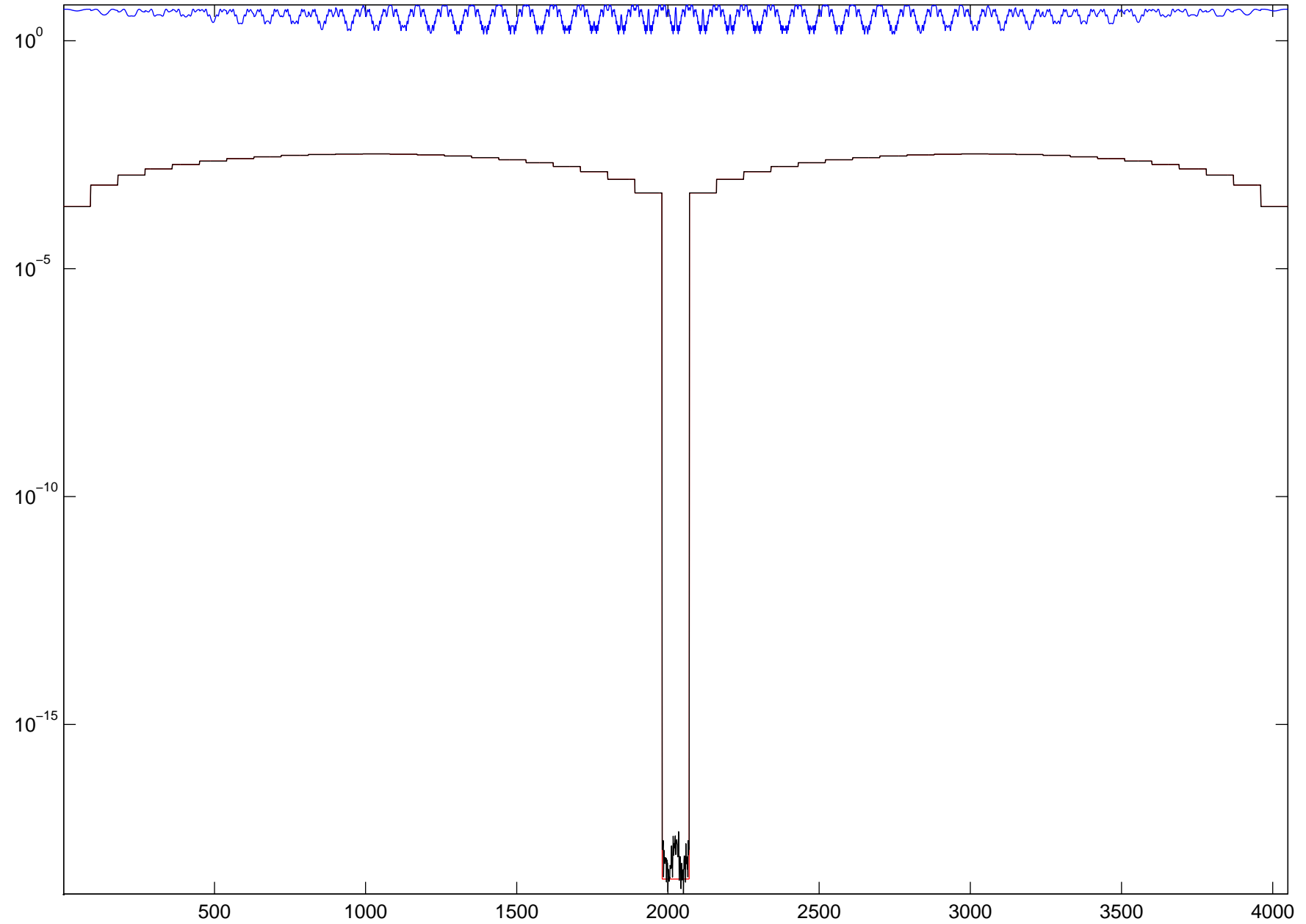
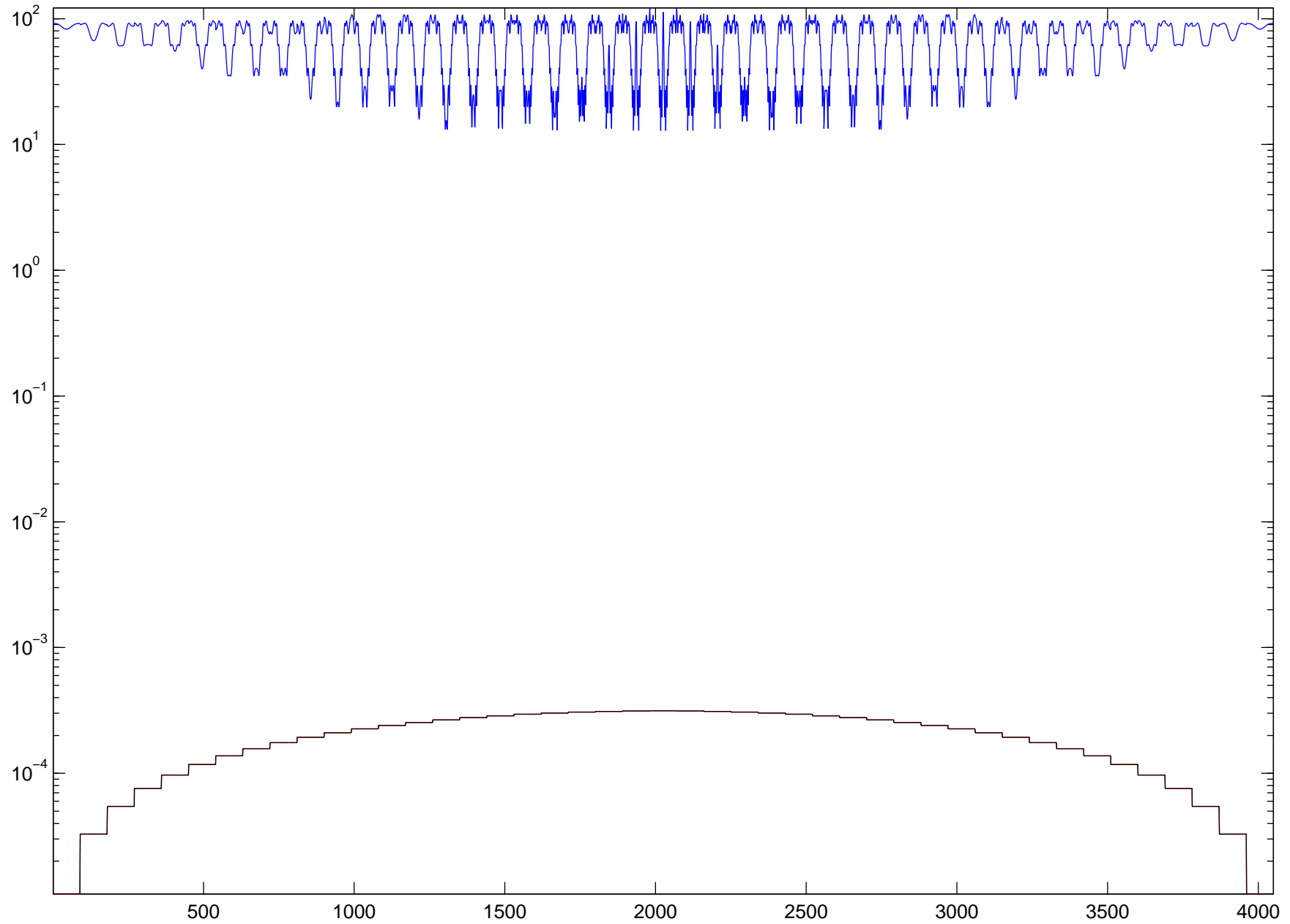


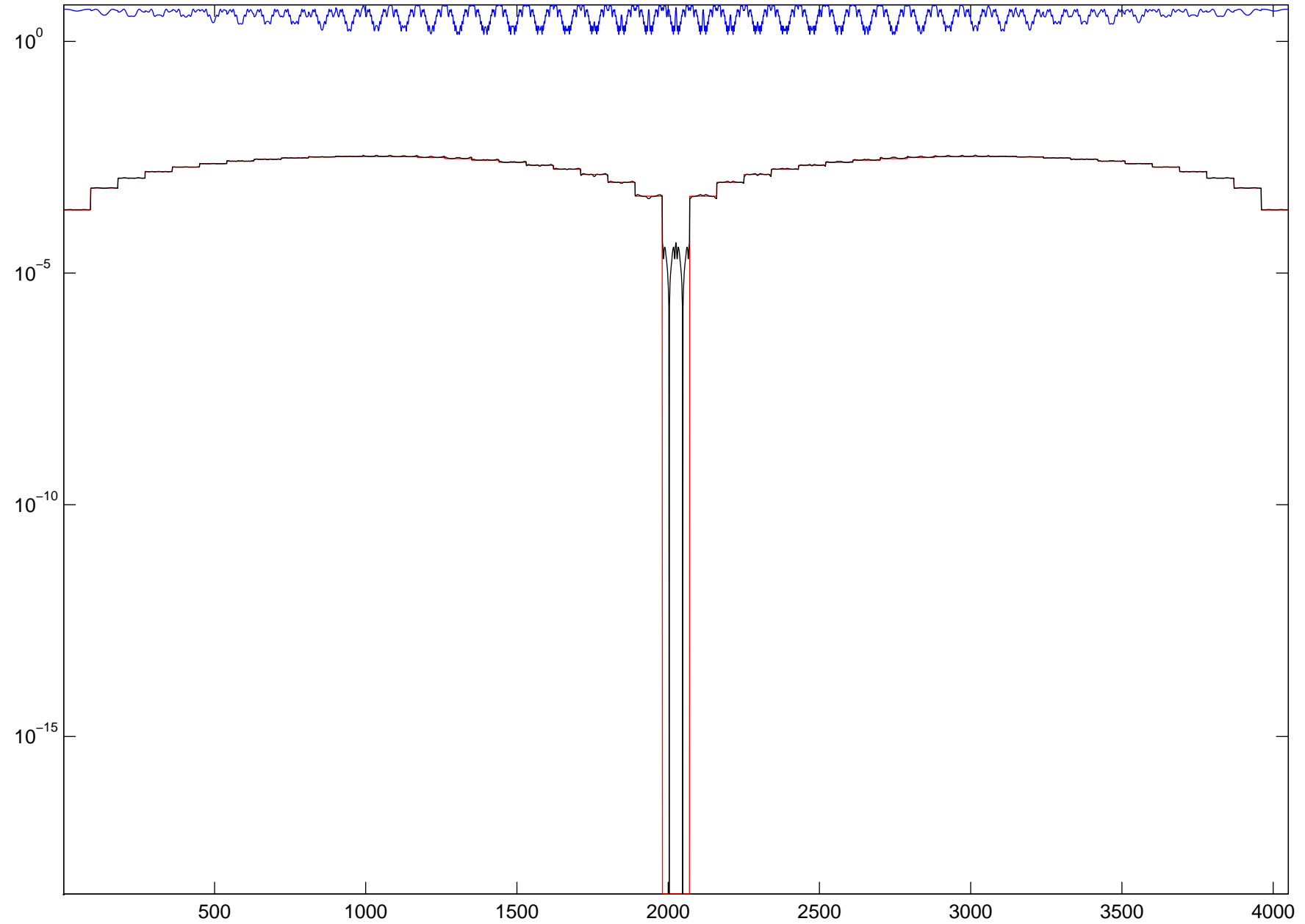
$\theta = 0, 11 \times 0.5\lambda$, Rad : 3λ
Steering angle : 23.3251° , L^2 error = $1.3621\text{e-}015$
FFSamples = 721, NFSamples = 4050, Coefficients = 723



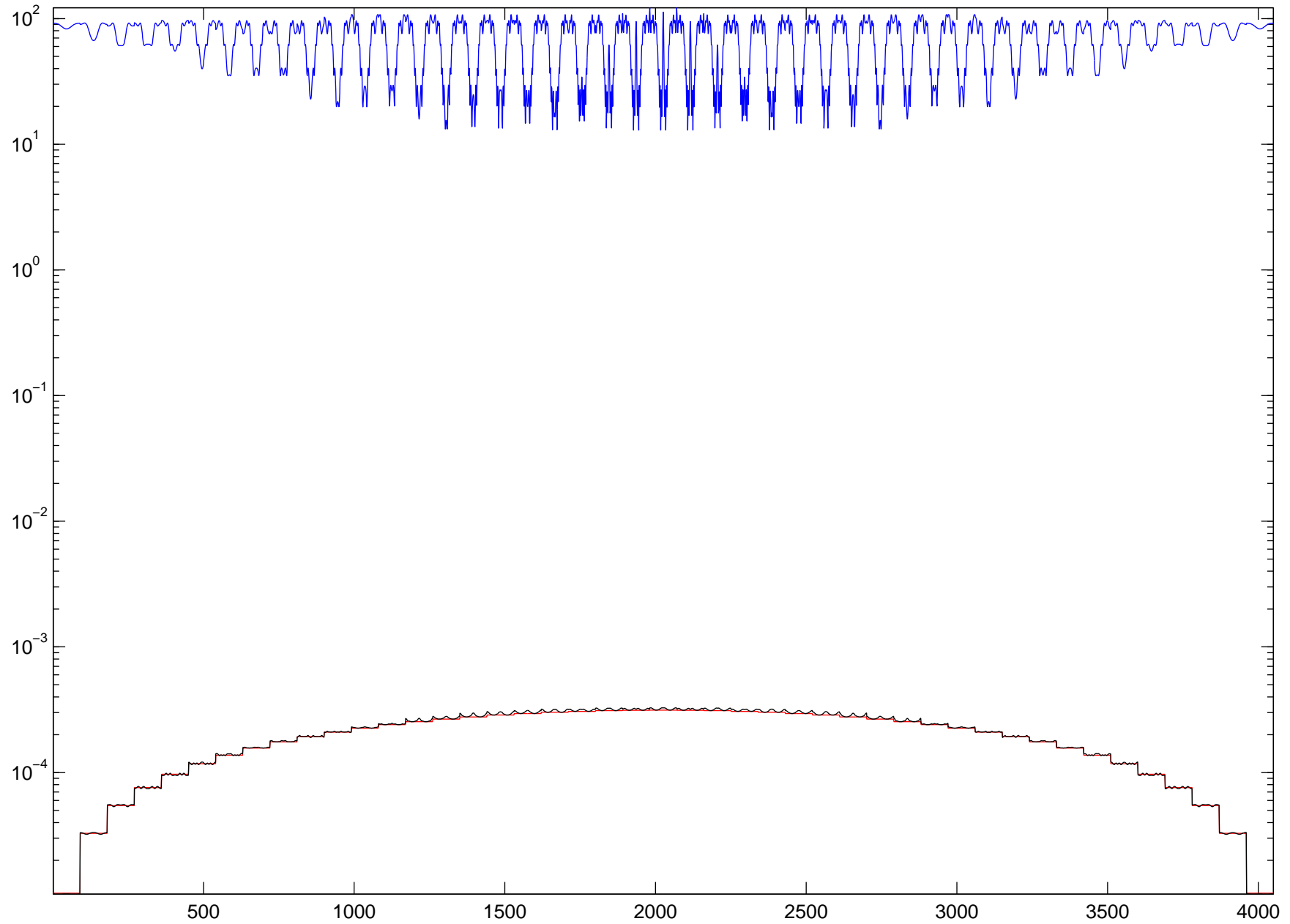
$\theta = 0, 11 \times 0.5\lambda, \text{Rad} : 3\lambda$
Steering angle : 23.3251° , L^2 error = $1.3621\text{e-}015$
FFSamples = 721, NFSamples = 4050, Coefficients = 723



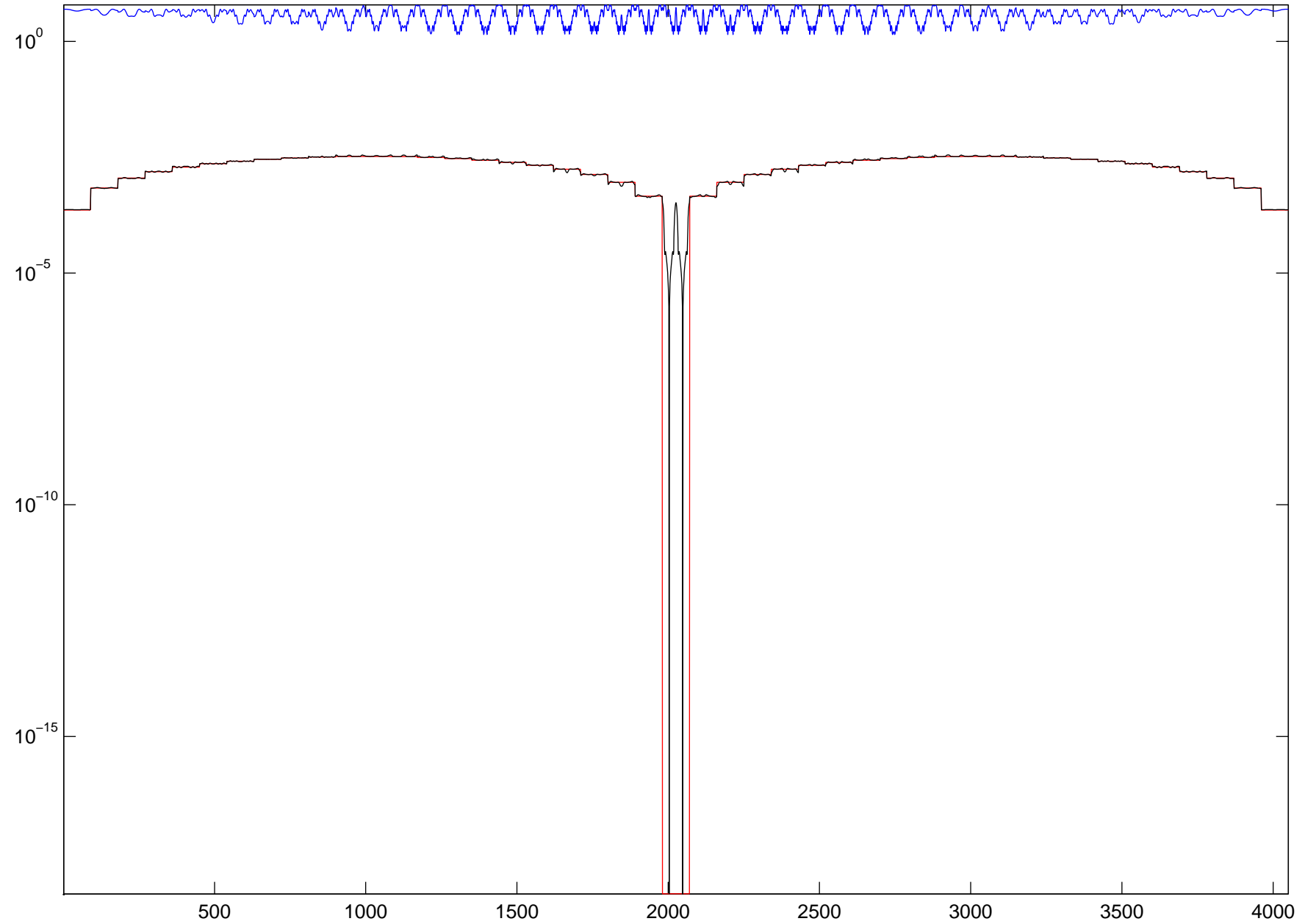
$\theta = 0, 11 \times 0.5\lambda$, Rad : 3λ
Steering angle : 23.3251° , L^2 error = 0.0046387
FFSamples = 721, NFSamples = 4050, Coefficients = 45



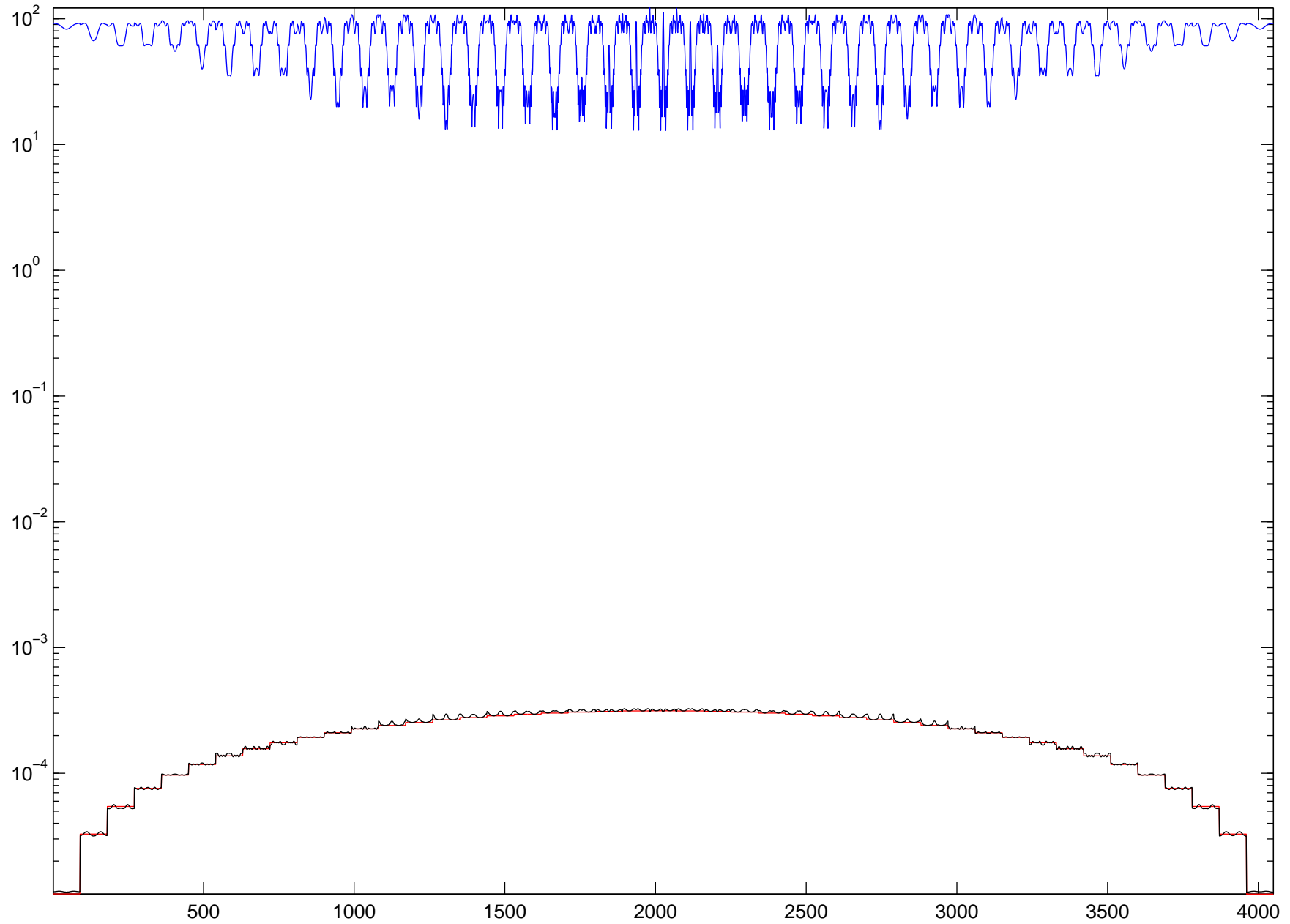
$\theta = 0, 11 \times 0.5\lambda, \text{Rad} : 3\lambda$
Steering angle : 23.3251° , L^2 error = 0.0046387
FFSamples = 721, NFSamples = 4050, Coefficients = 45



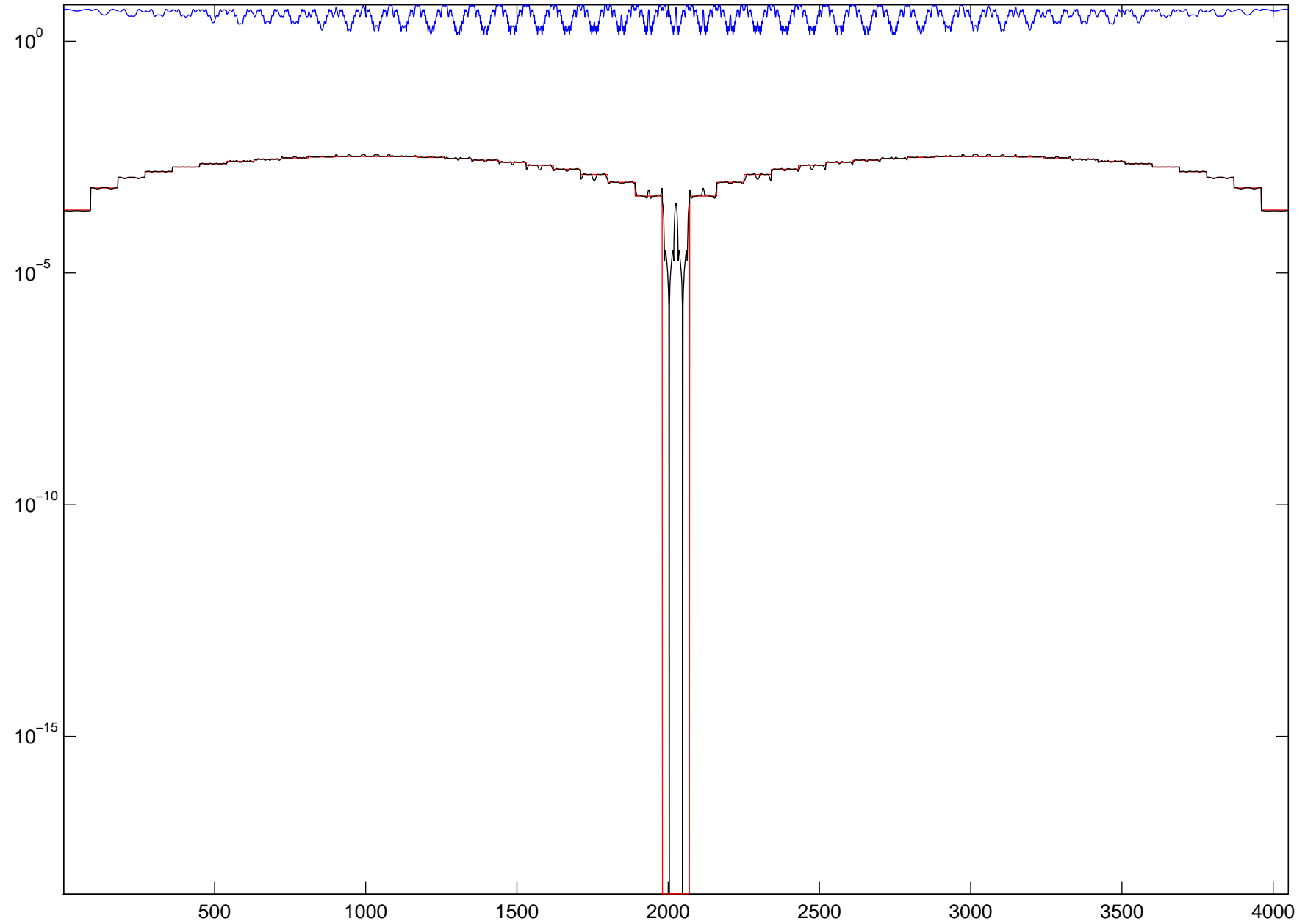
$\theta = 0, 11 \times 0.5\lambda$, Rad : 3λ
Steering angle : 23.3251° , L^2 error = 0.0049753
FFSamples = 721, NFSamples = 4050, Coefficients = 43



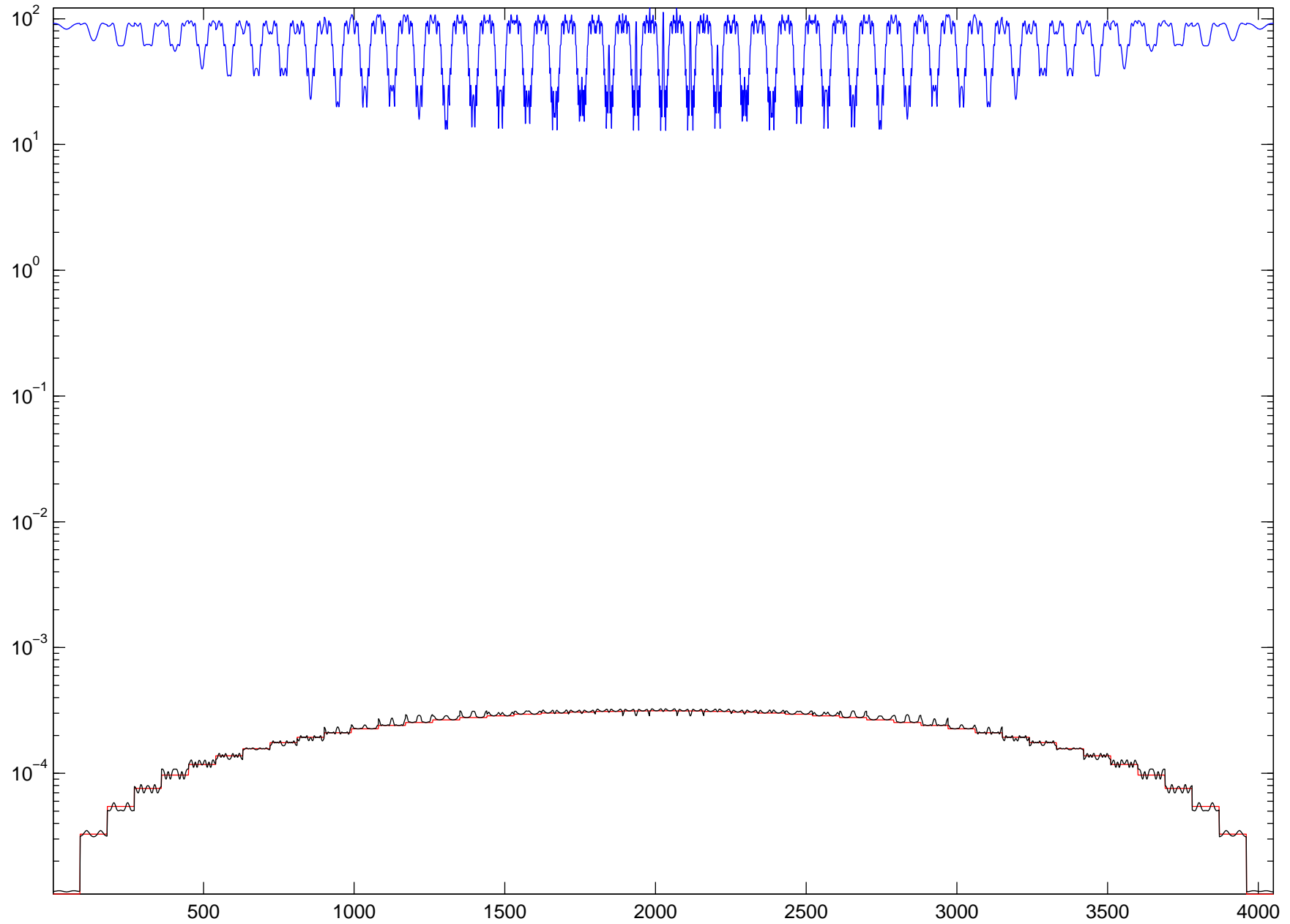
$\theta = 0, 11 \times 0.5\lambda, \text{Rad} : 3\lambda$
Steering angle : 23.3251° , L^2 error = 0.0049753
FFSamples = 721, NFSamples = 4050, Coefficients = 43



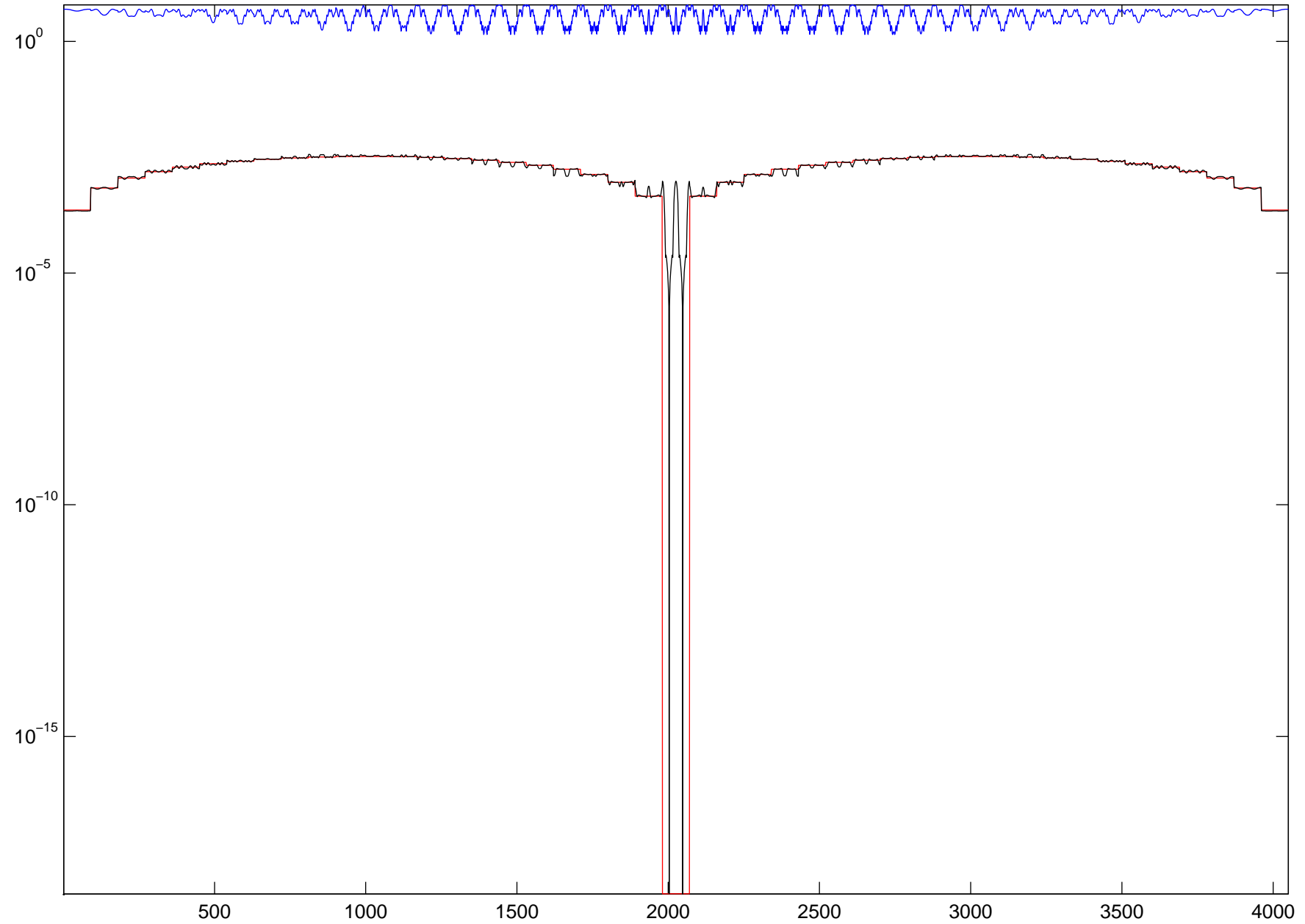
$\theta = 0, 11 \times 0.5\lambda$, Rad : 3λ
Steering angle : 23.3251° , L^2 error = 0.0053708
FFSamples = 721, NFSamples = 4050, Coefficients = 41



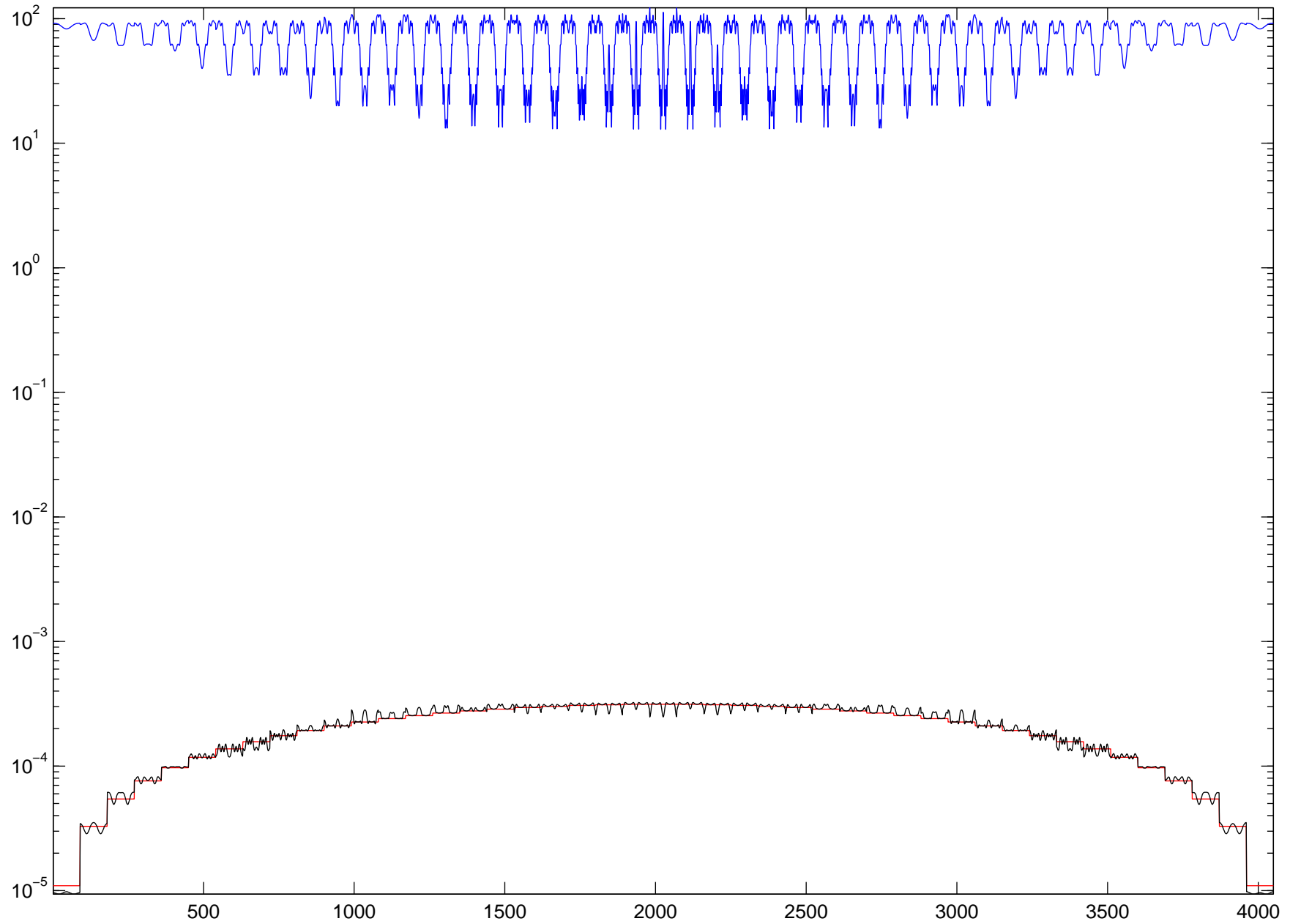
$\theta = 0, 11 \times 0.5\lambda, \text{Rad} : 3\lambda$
Steering angle : 23.3251° , L^2 error = 0.0053708
FFSamples = 721, NFSamples = 4050, Coefficients = 41



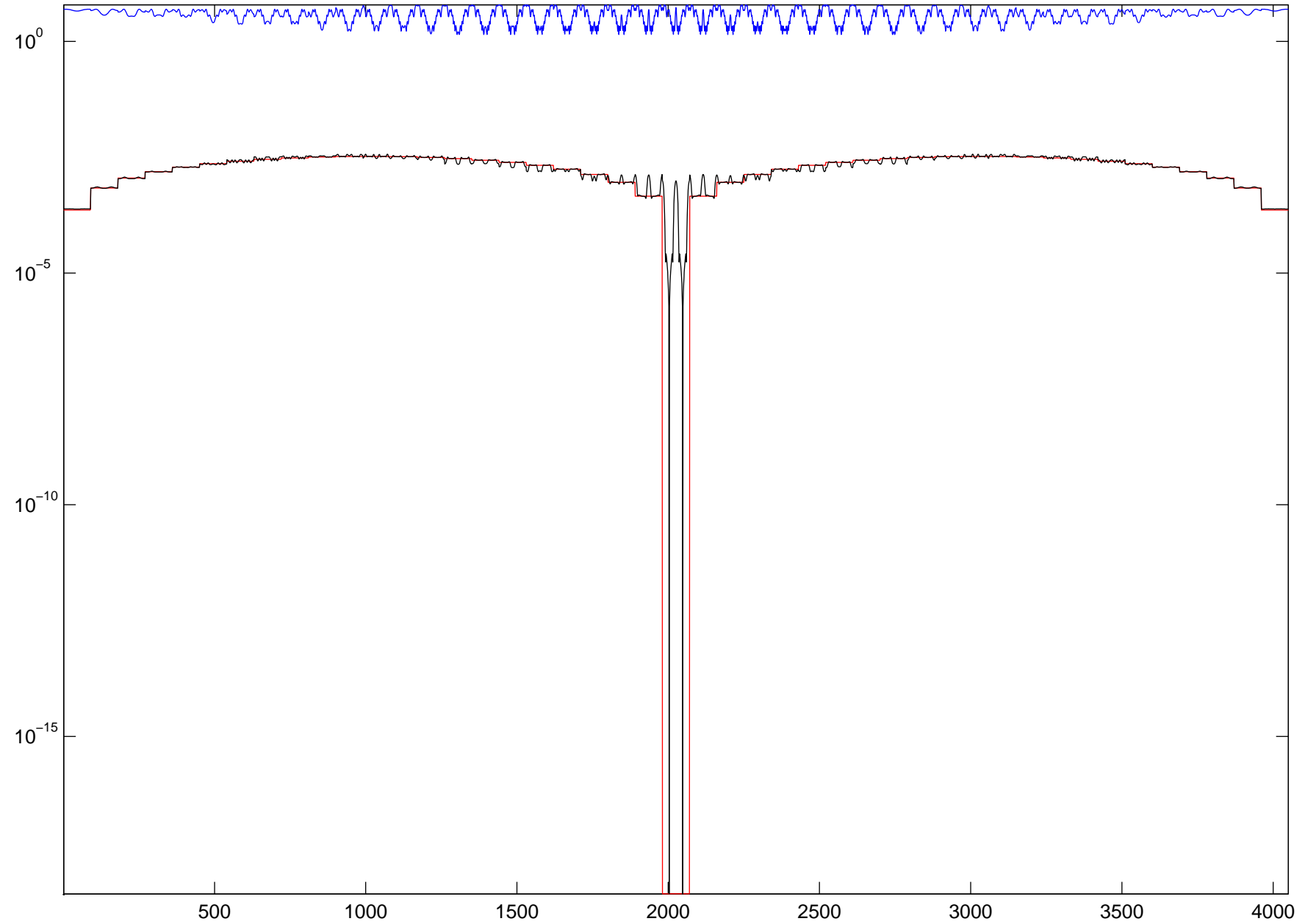
$\theta = 0, 11 \times 0.5\lambda$, Rad : 3λ
Steering angle : 23.3251° , L^2 error = 0.01276
FFSamples = 721, NFSamples = 4050, Coefficients = 39



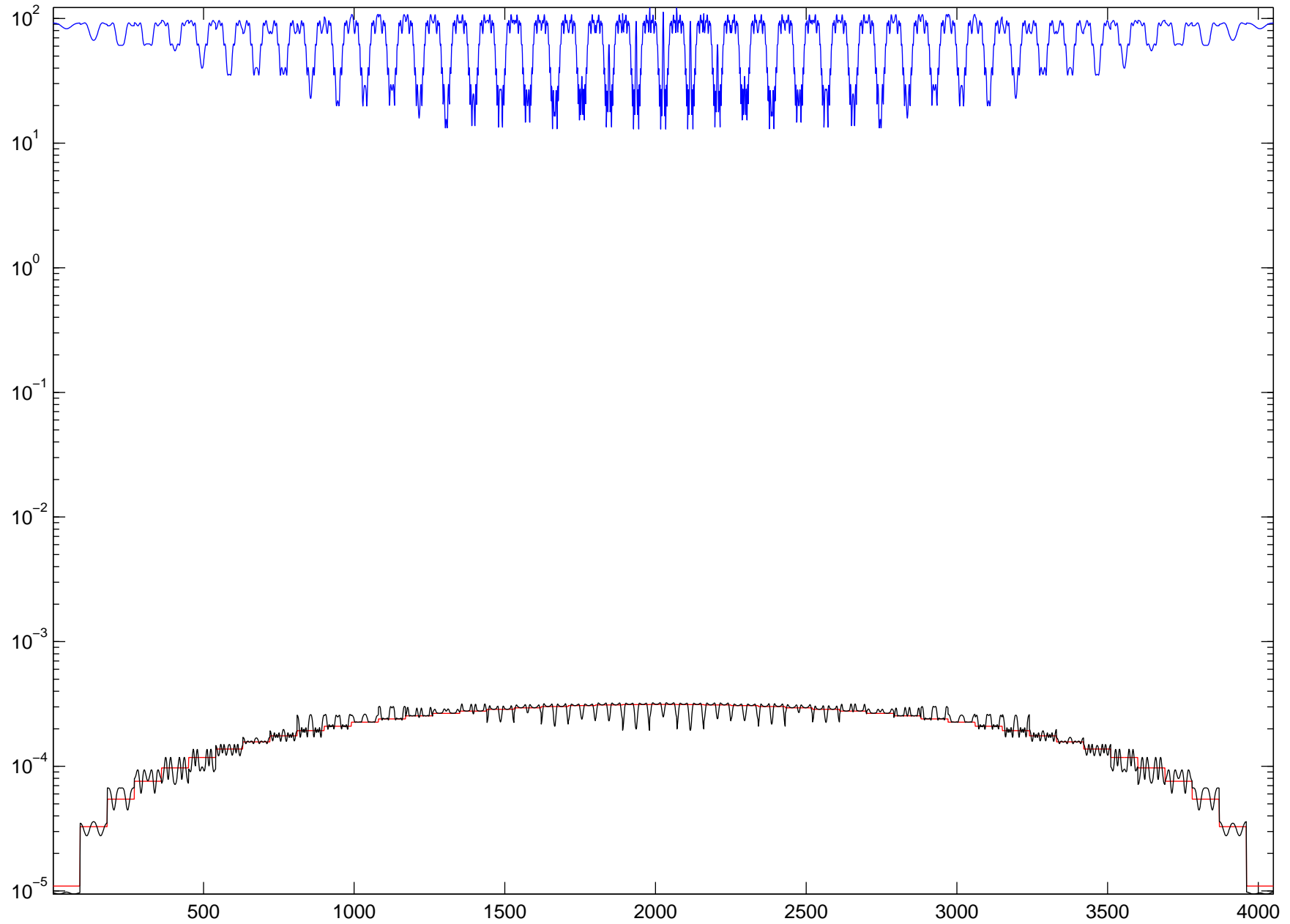
$\theta = 0, 11 \times 0.5\lambda$, Rad : 3λ
Steering angle : 23.3251° , L^2 error = 0.01276
FFSamples = 721, NFSamples = 4050, Coefficients = 39



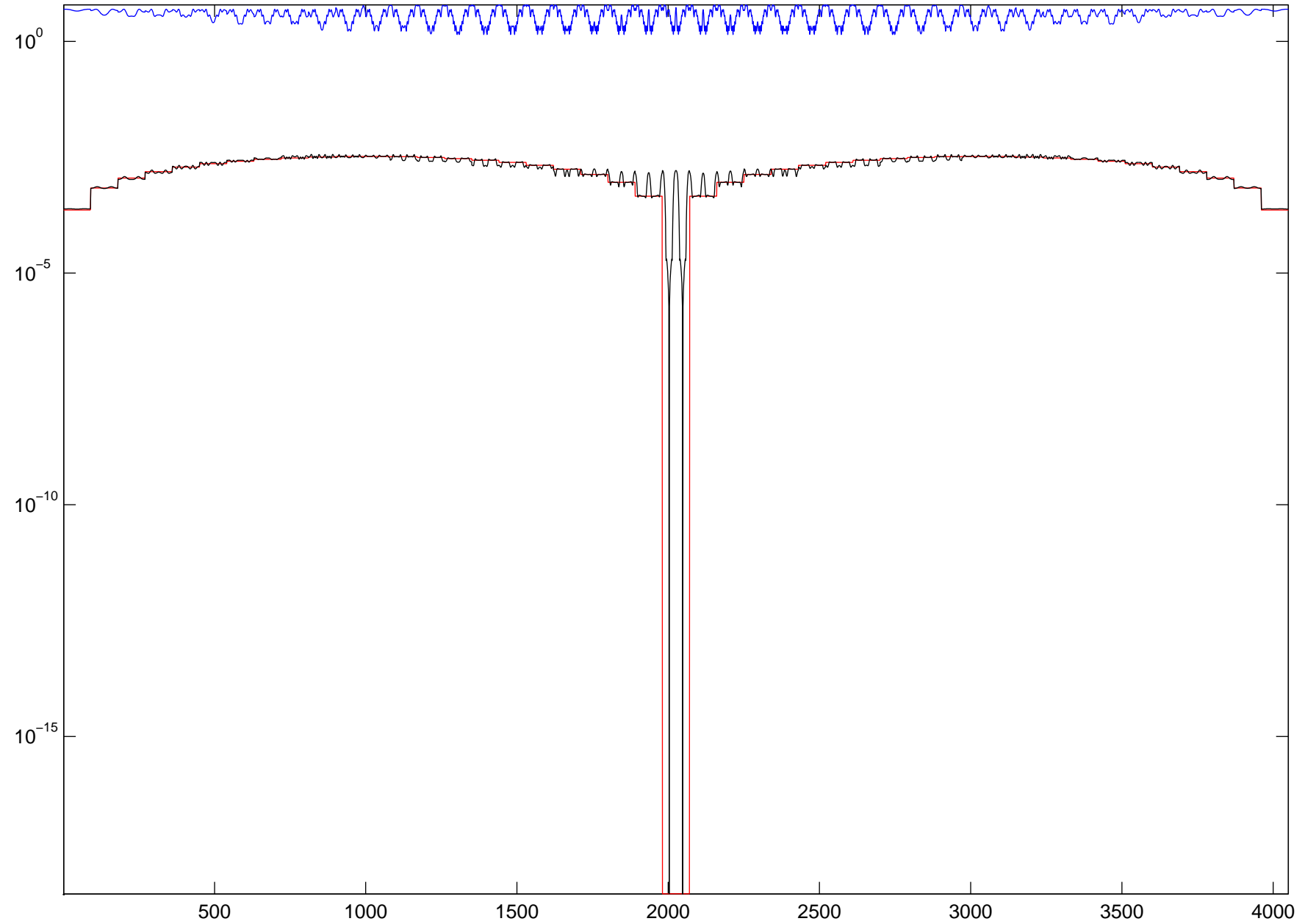
$\theta = 0, 11 \times 0.5\lambda$, Rad : 3λ
Steering angle : 23.3251° , L^2 error = 0.013169
FFSamples = 721, NFSamples = 4050, Coefficients = 37



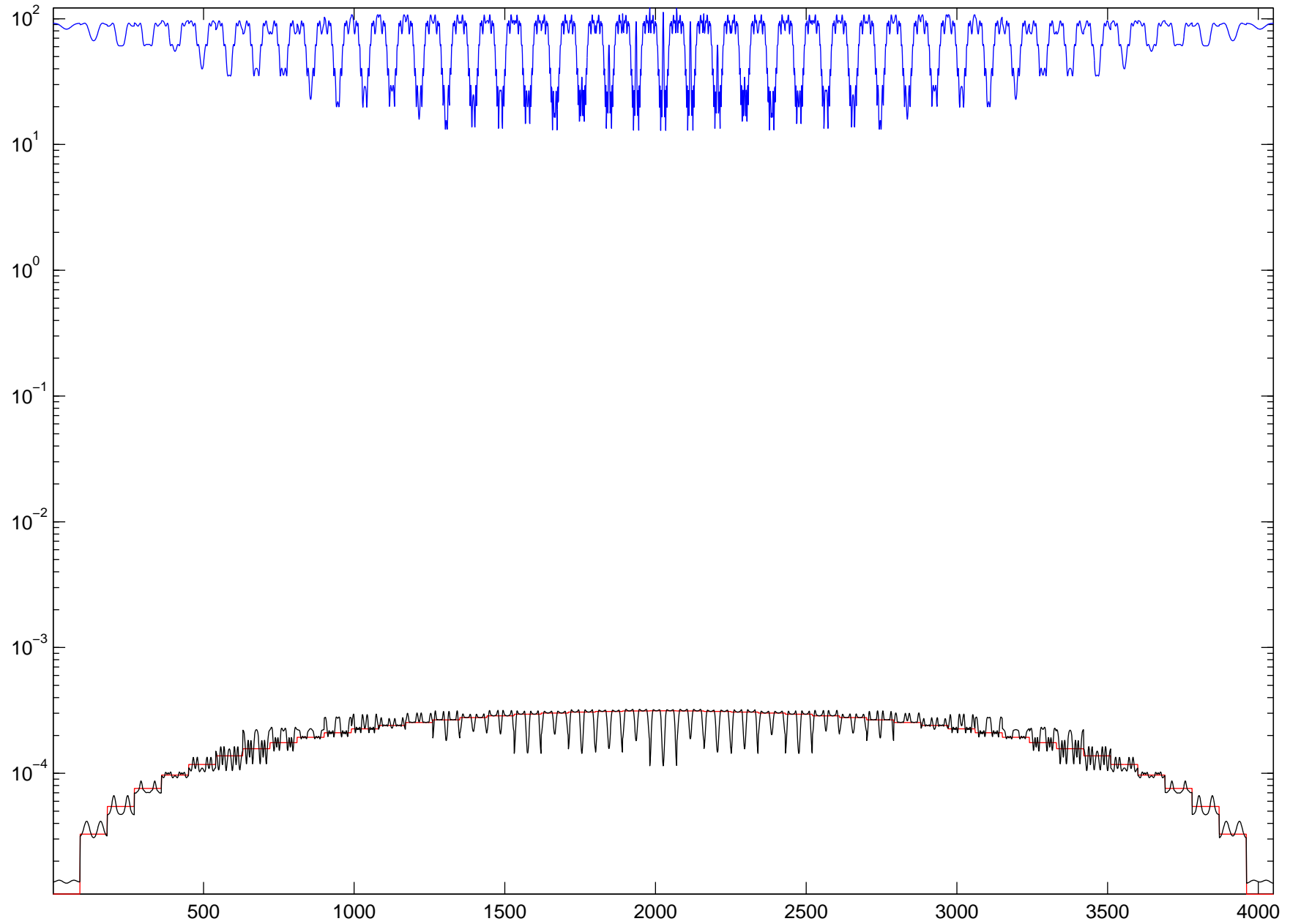
$\theta = 0, 11 \times 0.5\lambda$, Rad : 3λ
Steering angle : 23.3251° , L^2 error = 0.013169
FFSamples = 721, NFSamples = 4050, Coefficients = 37



$\theta = 0, 11 \times 0.5\lambda$, Rad : 3λ
Steering angle : 23.3251° , L^2 error = 0.057098
FFSamples = 721, NFSamples = 4050, Coefficients = 35



$\theta = 0, 11 \times 0.5\lambda$, Rad : 3λ
Steering angle : 23.3251° , L^2 error = 0.057098
FFSamples = 721, NFSamples = 4050, Coefficients = 35



11 x 0.5 λ , Rad : 3 λ
Steering angle : 23.3251°, L² error = 0.057098
FFSamples = 721, NFSamples = 4050, Coefficients = 35

