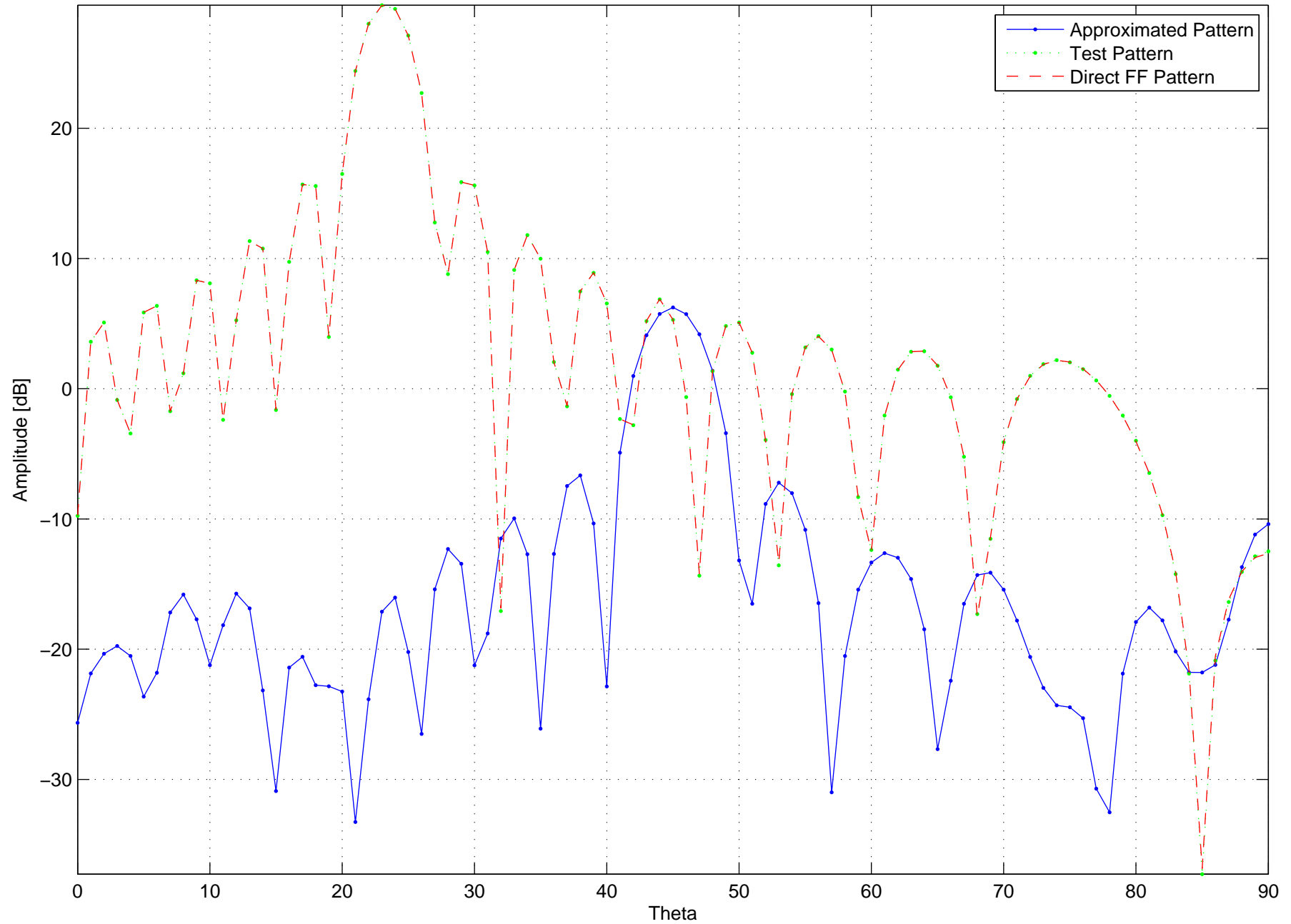
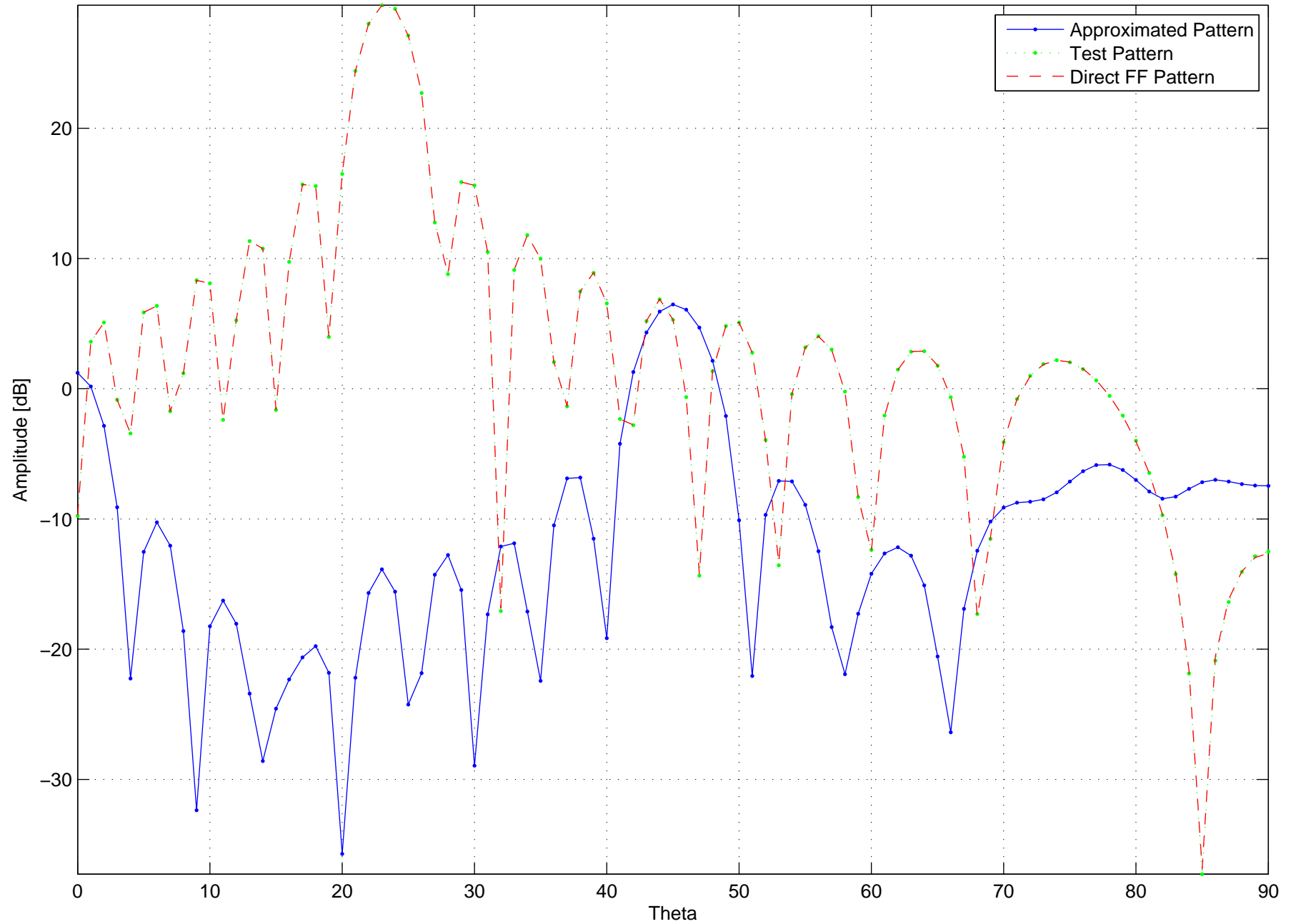


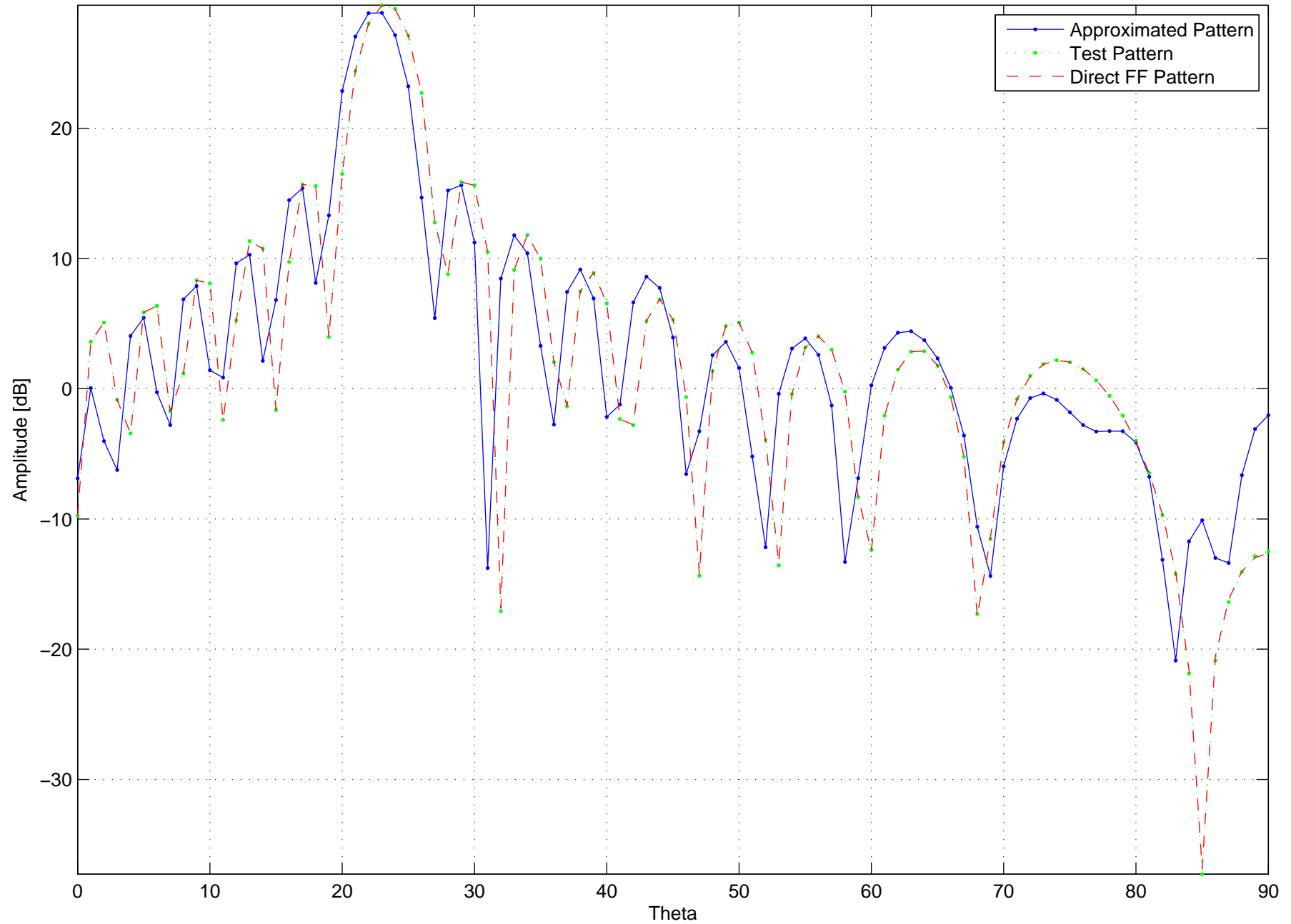
Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 0, Nbr of Vectors : 1
Nbr of point sources : 30 x 0.5



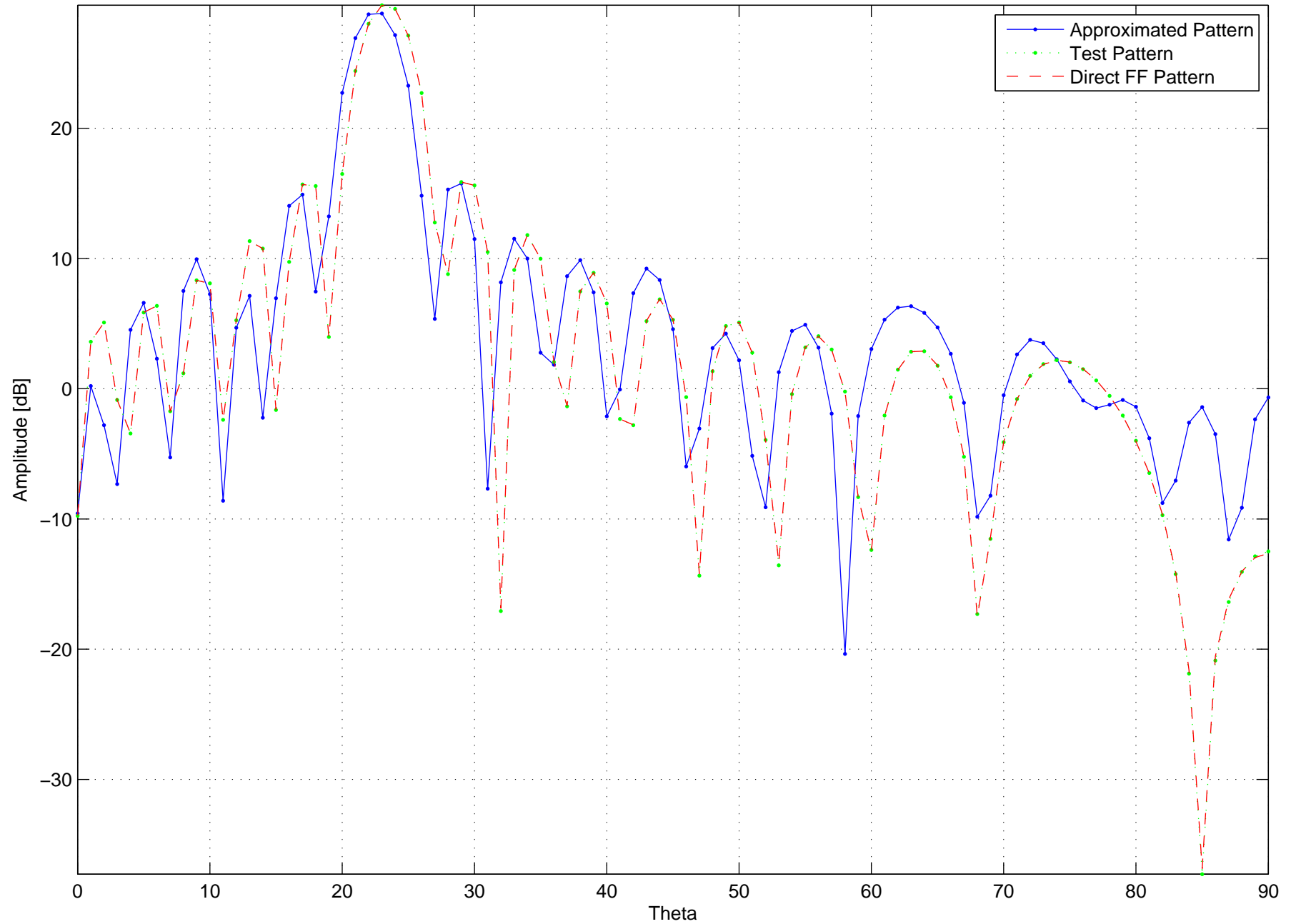
Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 0, Nbr of Vectors : 3
Nbr of point sources : 30 x 0.5



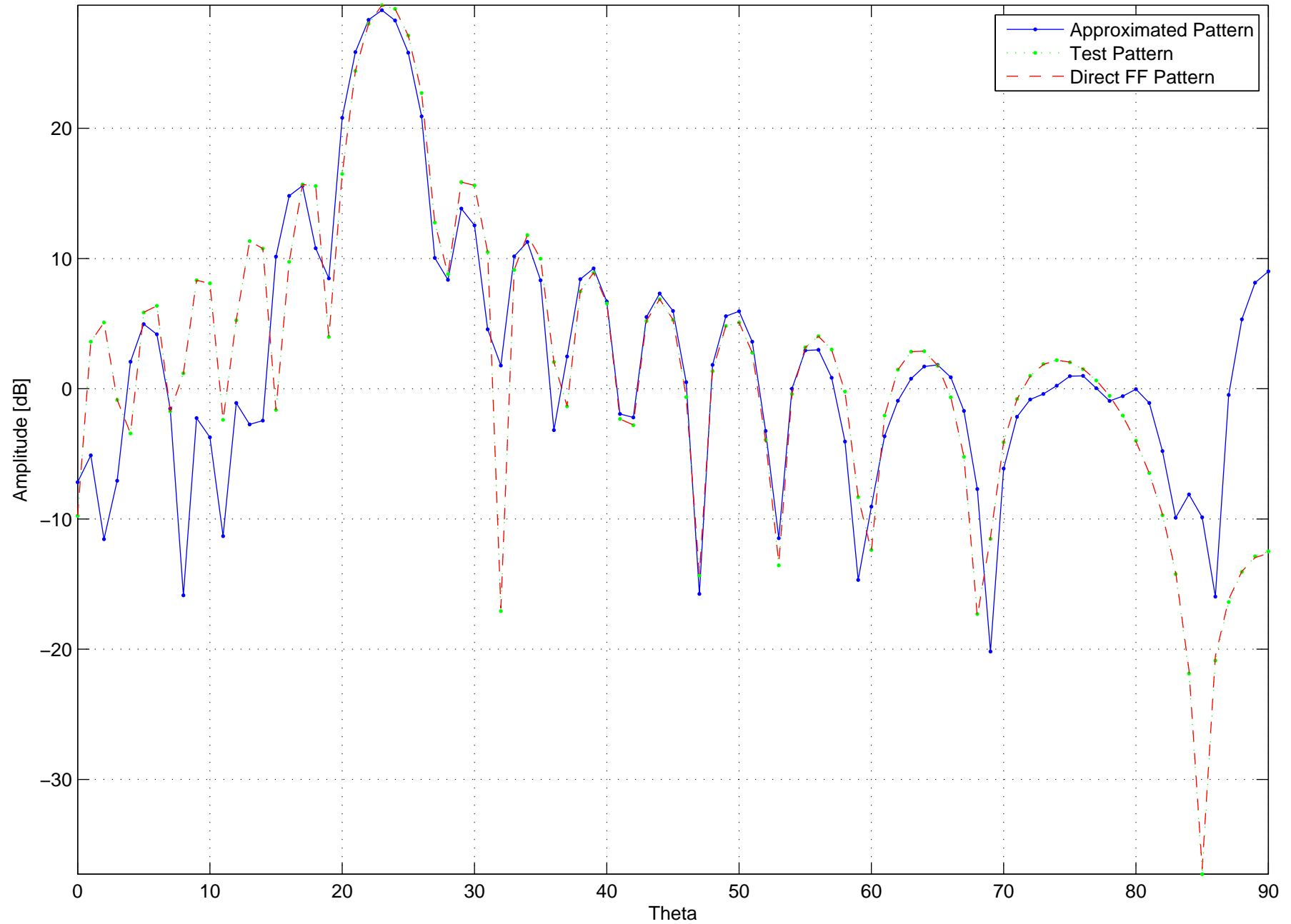
Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 0, Nbr of Vectors : 5
Nbr of point sources : 30 x 0.5



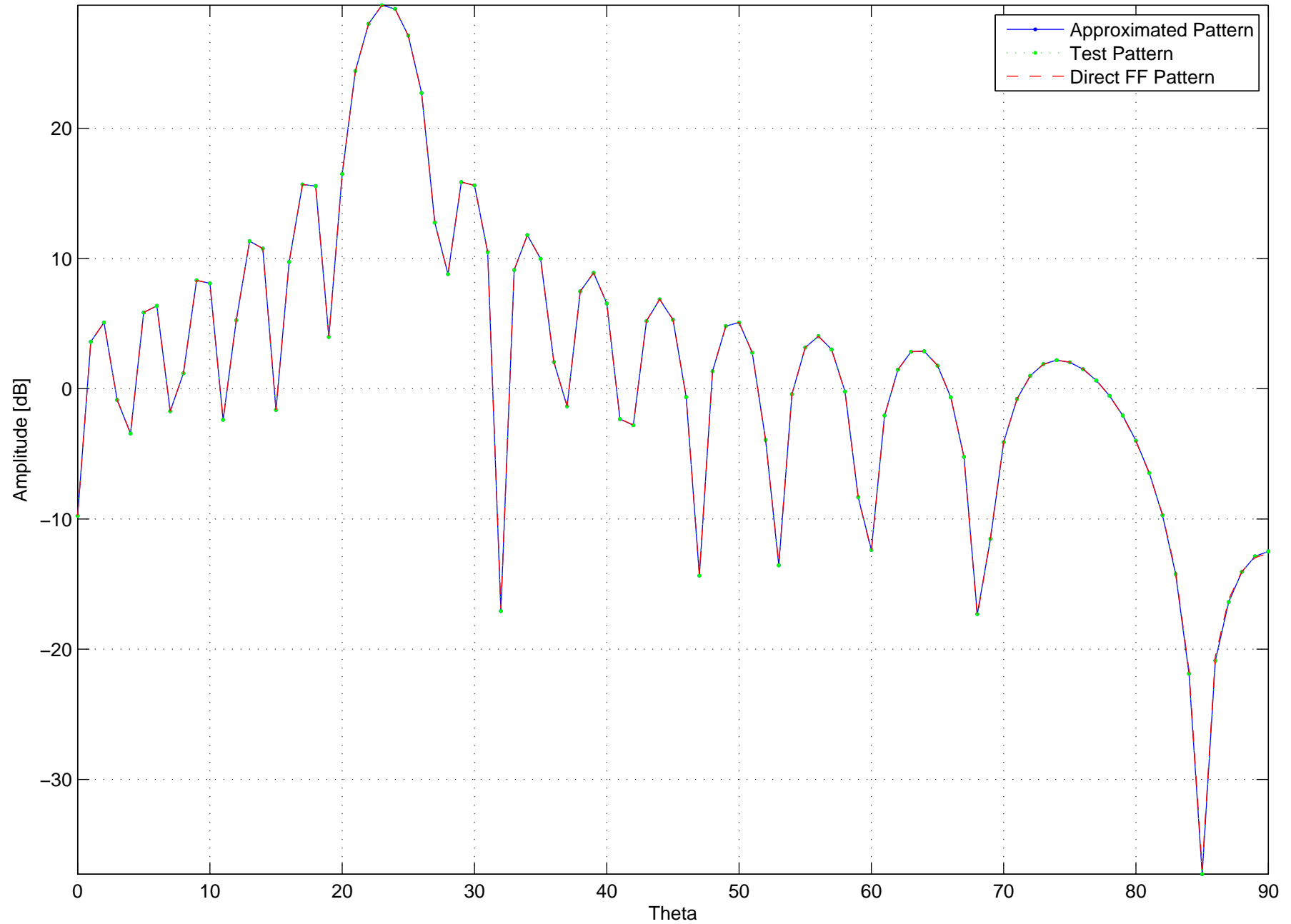
Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 0, Nbr of Vectors : 9
Nbr of point sources : 30×0.5



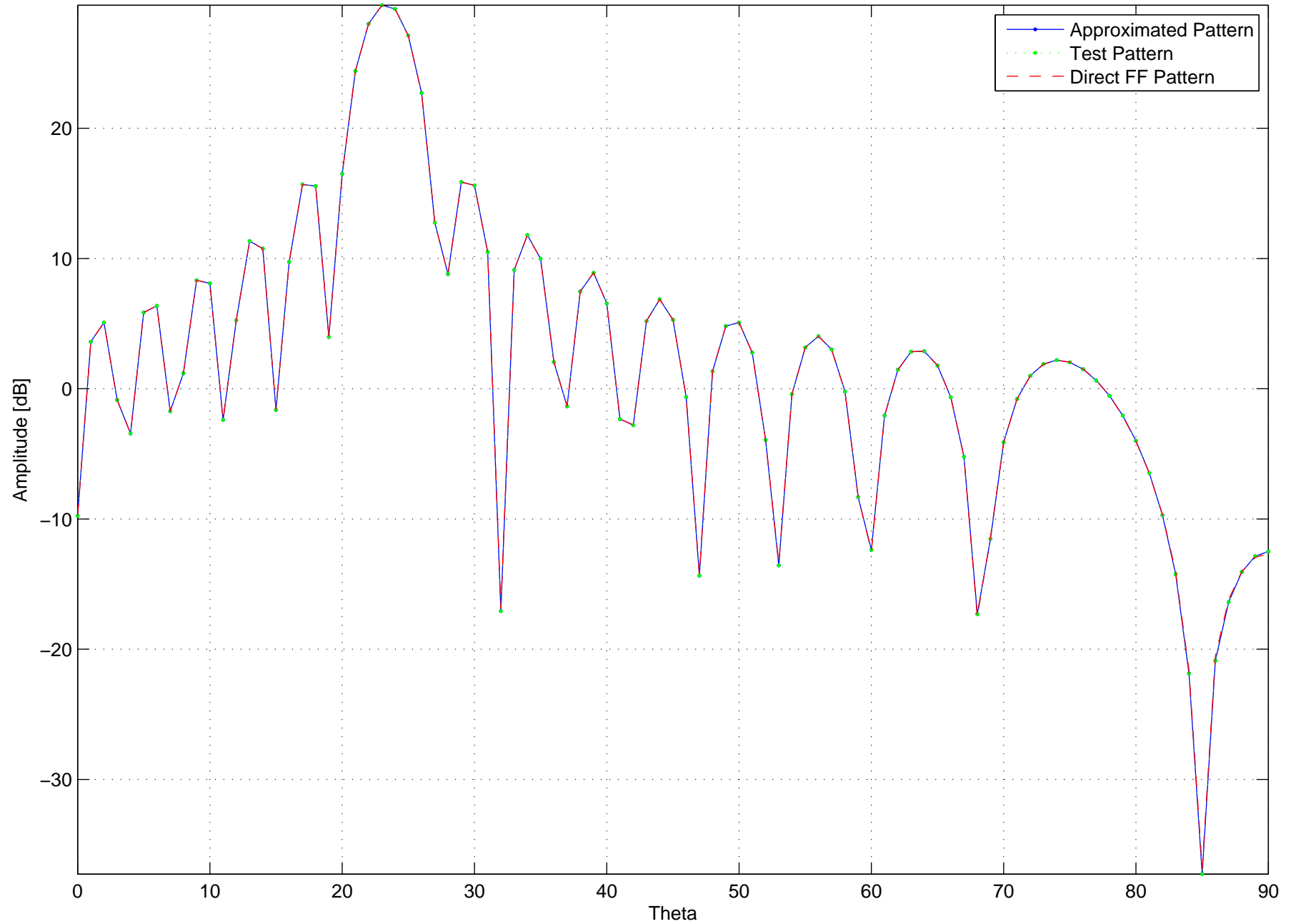
Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 0, Nbr of Vectors : 17
Nbr of point sources : 30 x 0.5

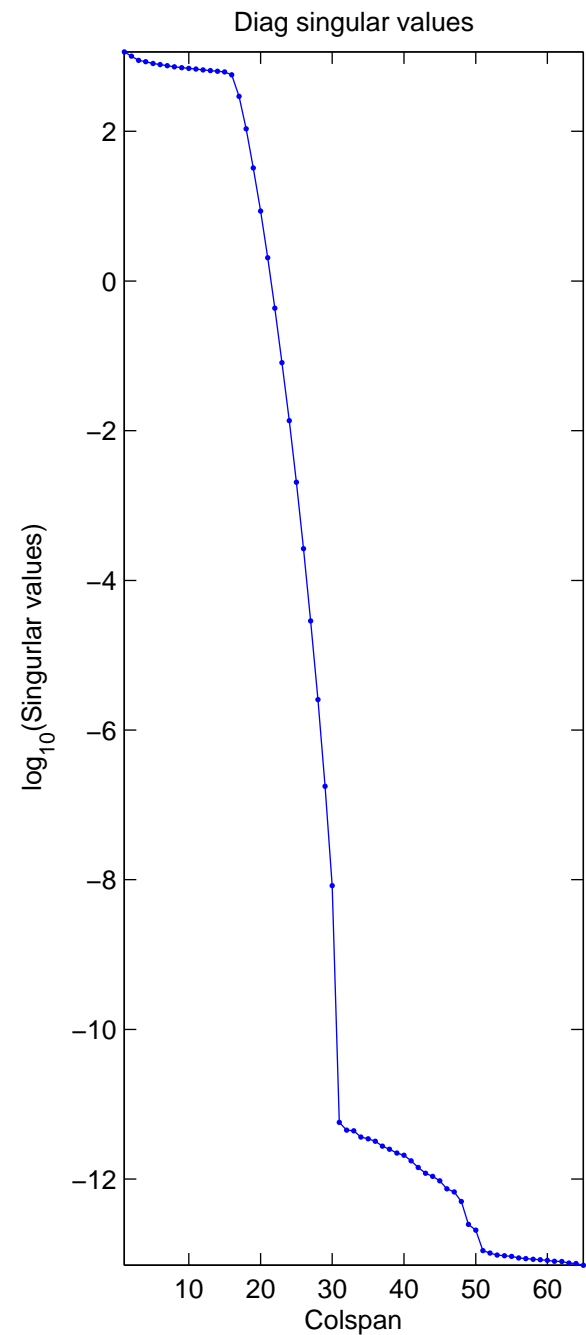
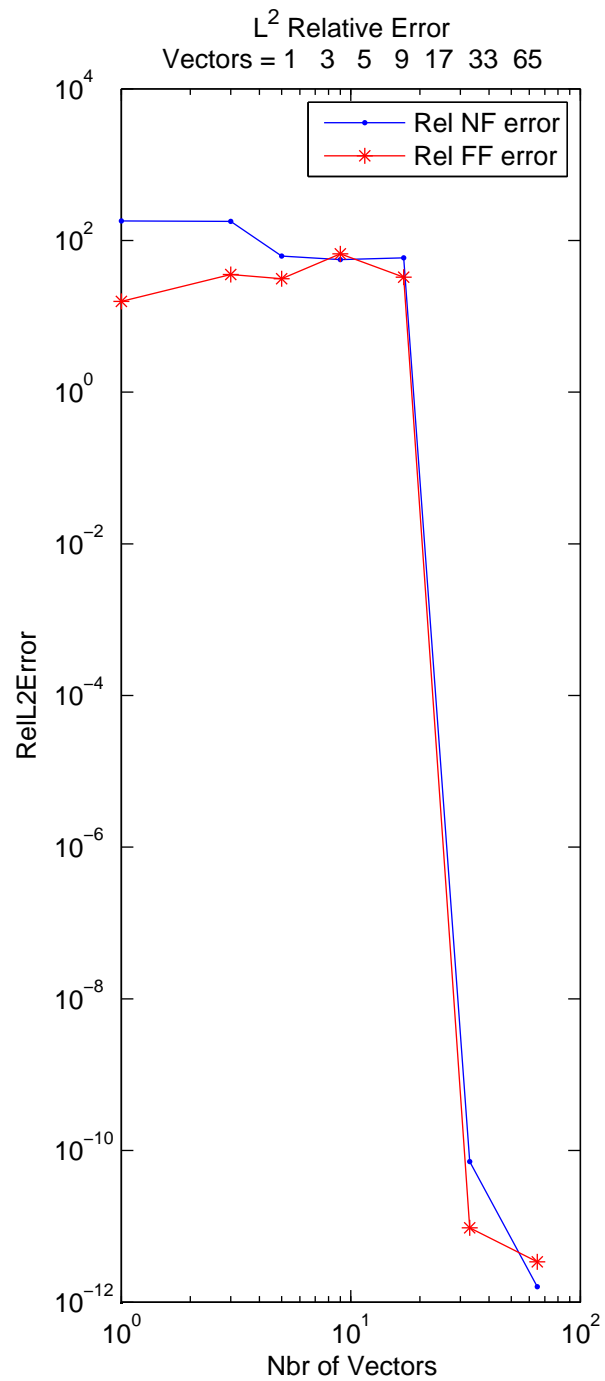
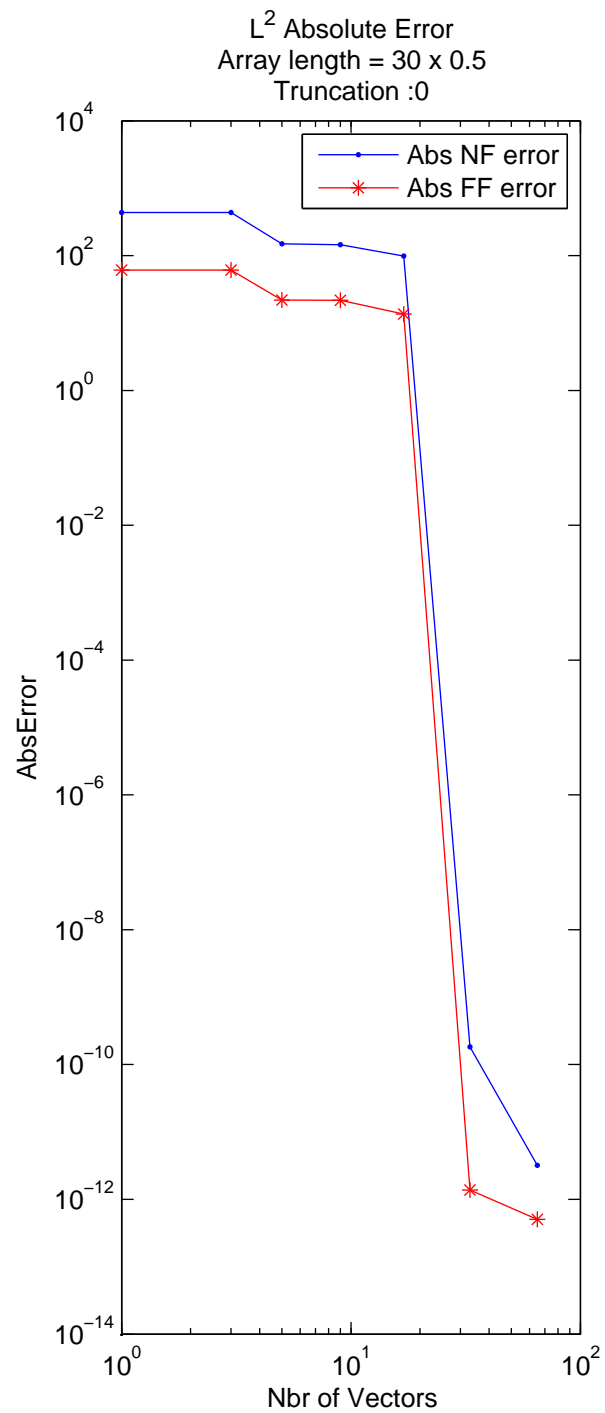


Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 0, Nbr of Vectors : 33
Nbr of point sources : 30×0.5

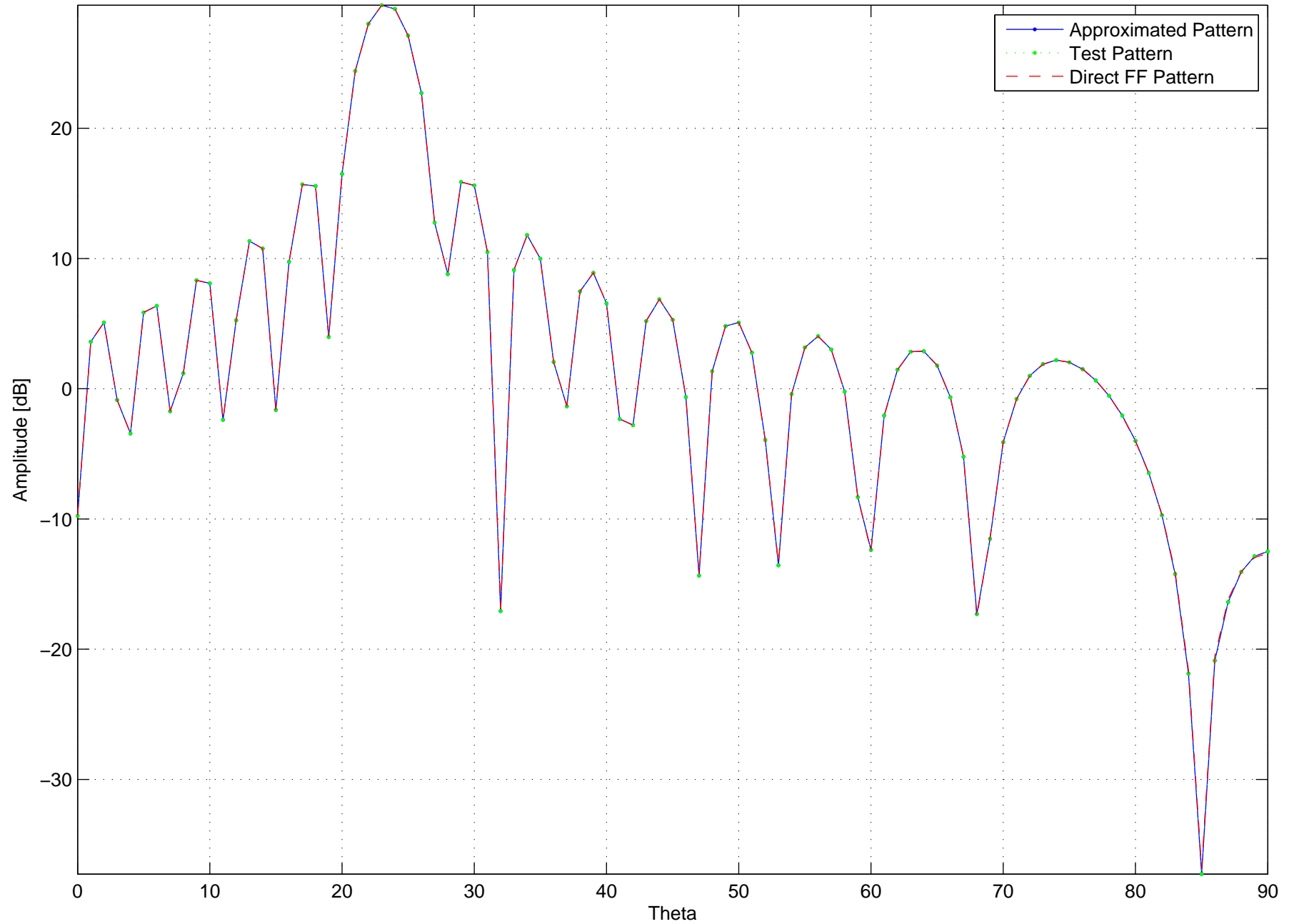


Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 0, Nbr of Vectors : 65
Nbr of point sources : 30×0.5

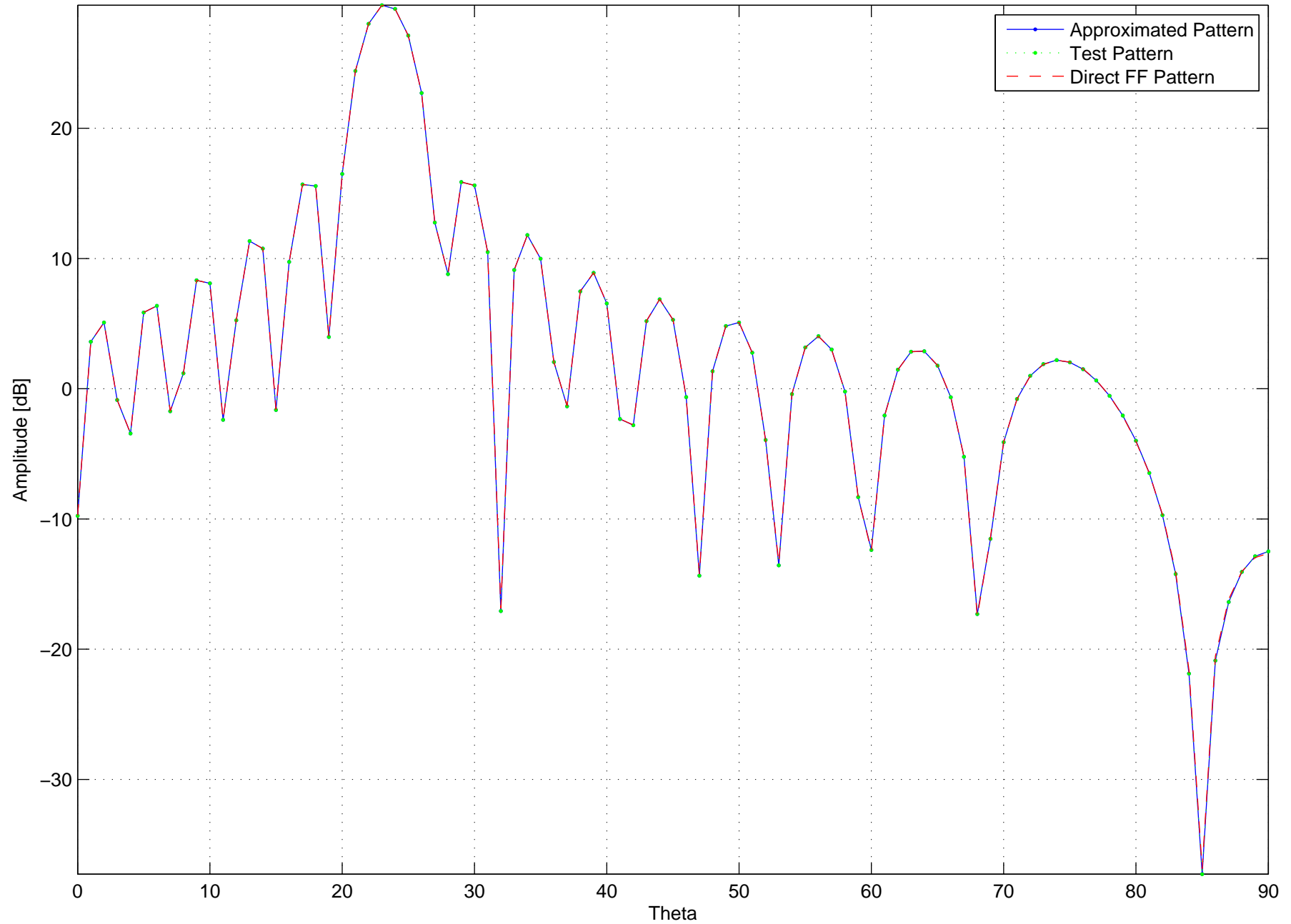


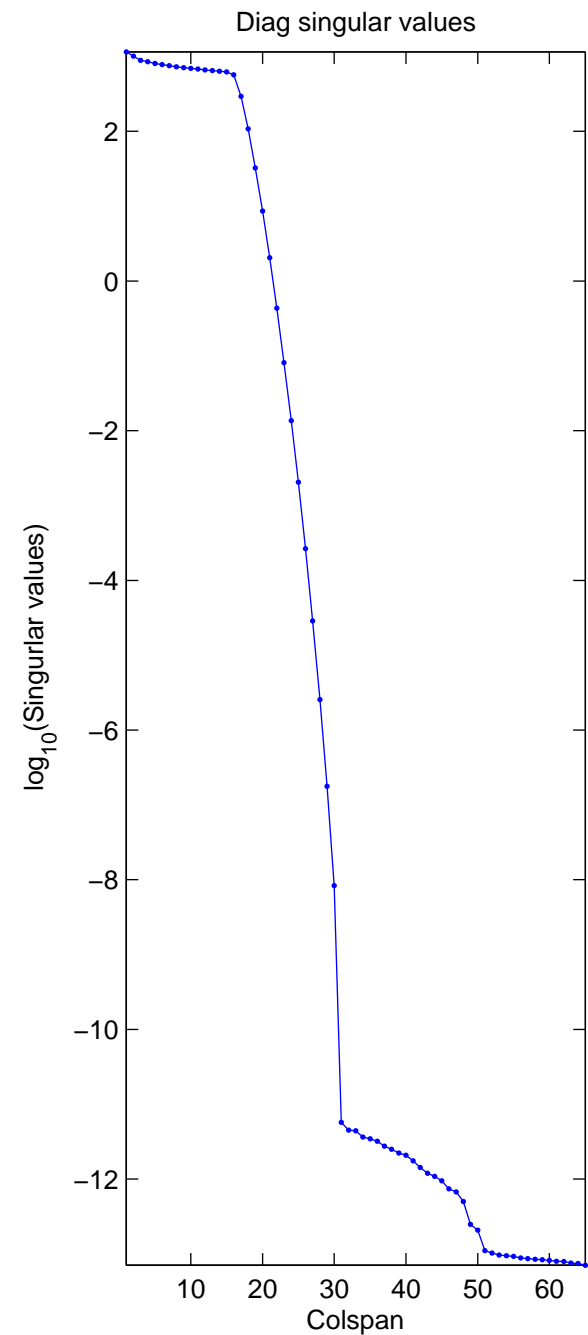
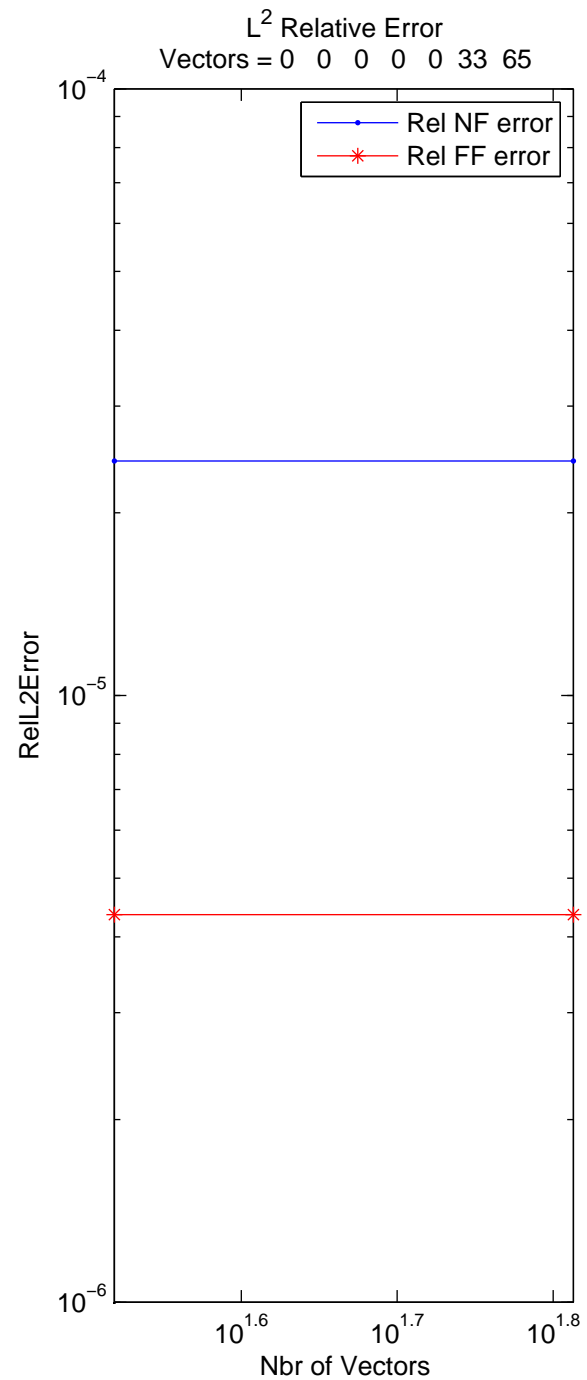
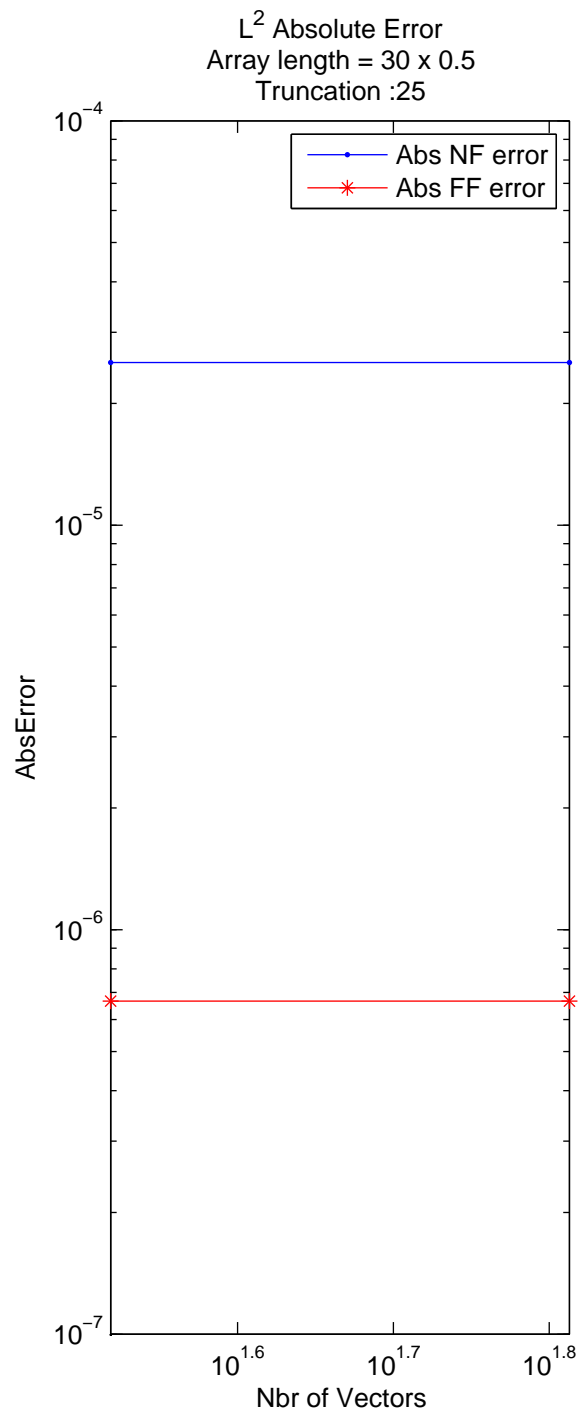


Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 25, Nbr of Vectors : 33
Nbr of point sources : 30×0.5

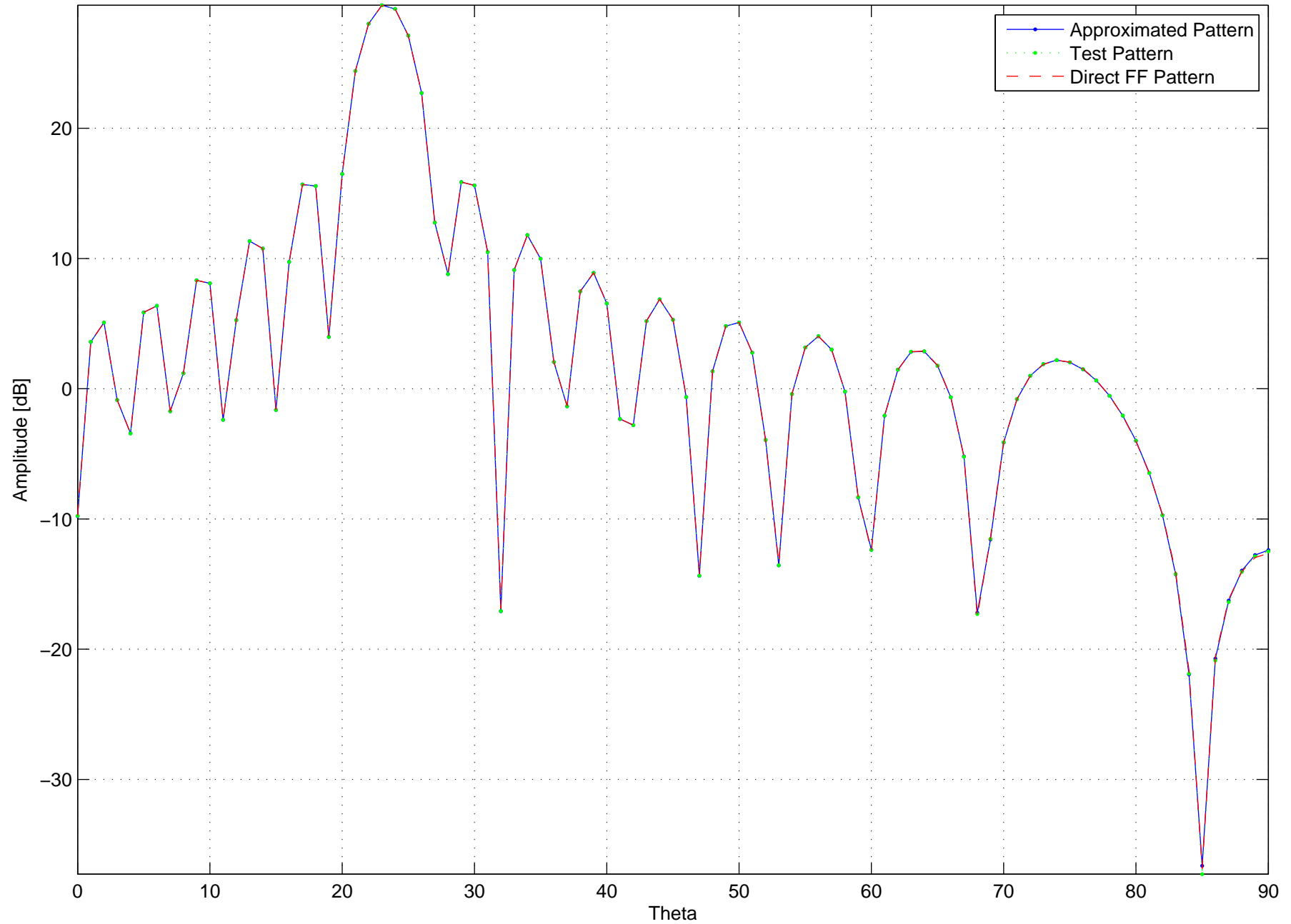


Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 25, Nbr of Vectors : 65
Nbr of point sources : 30×0.5

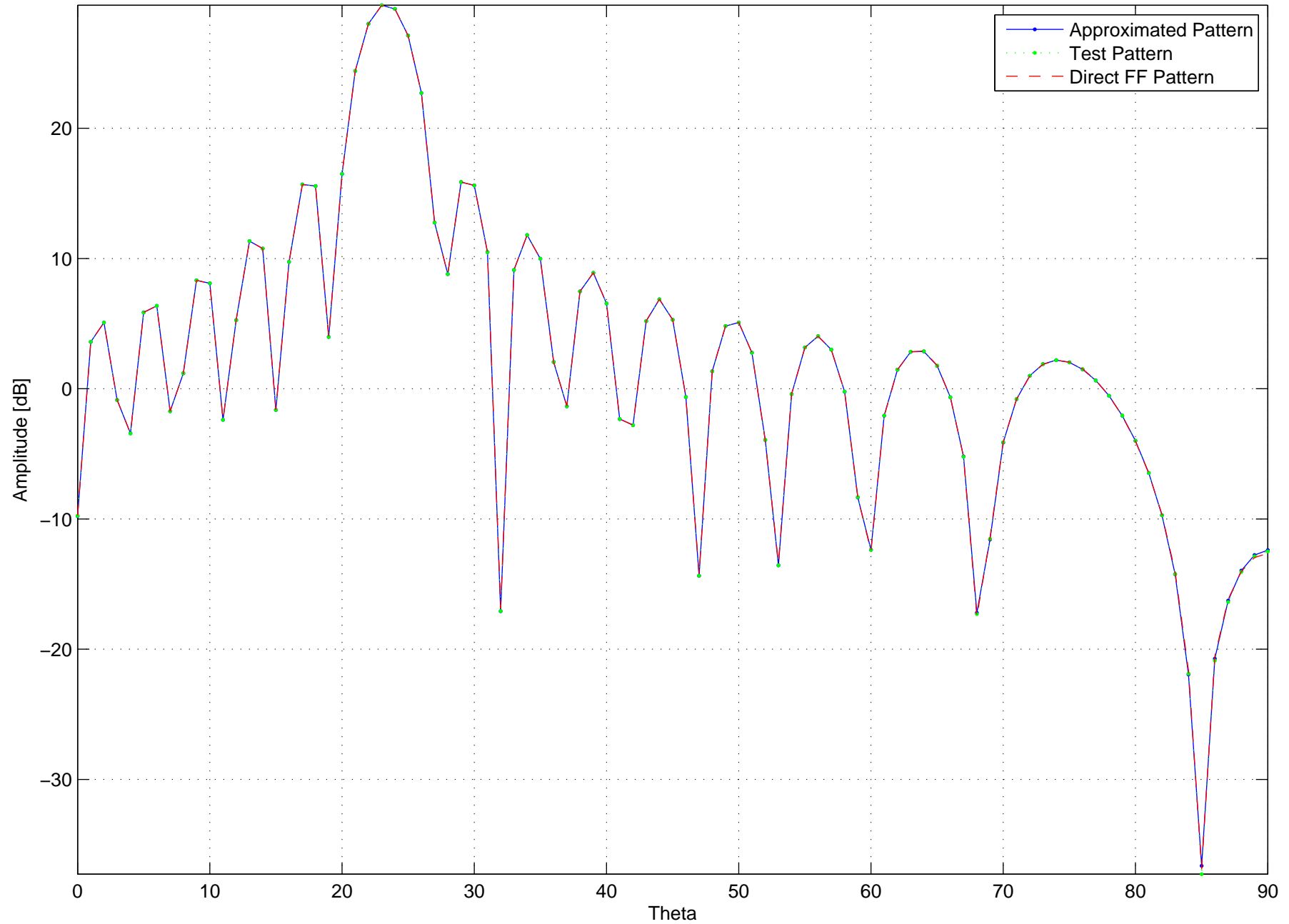


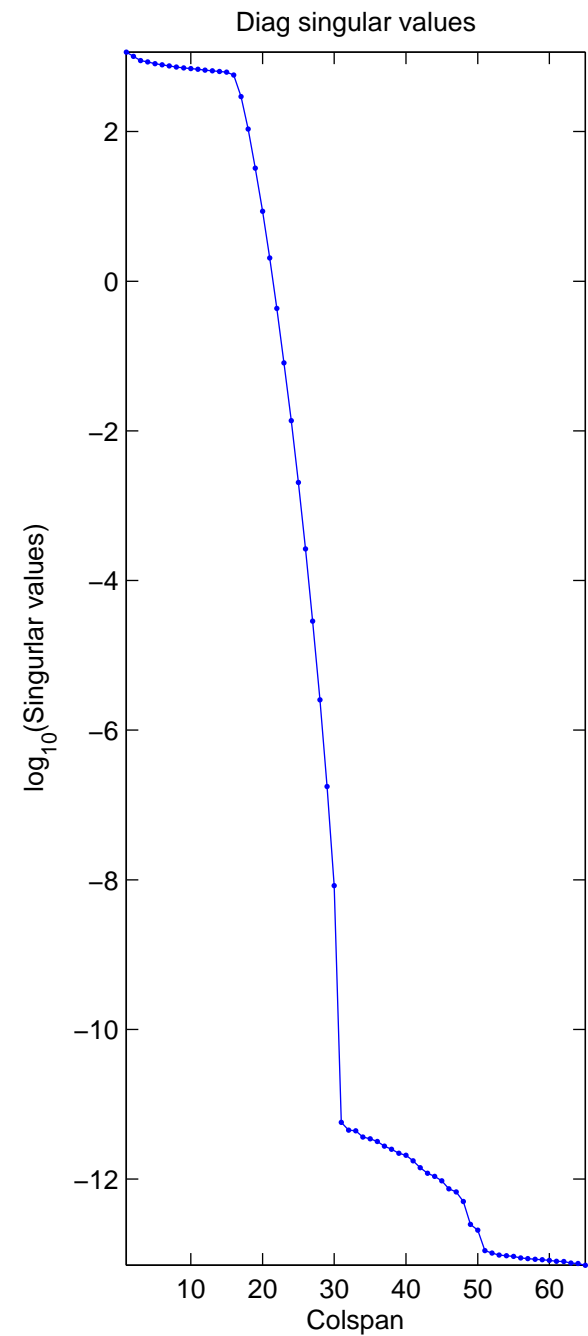
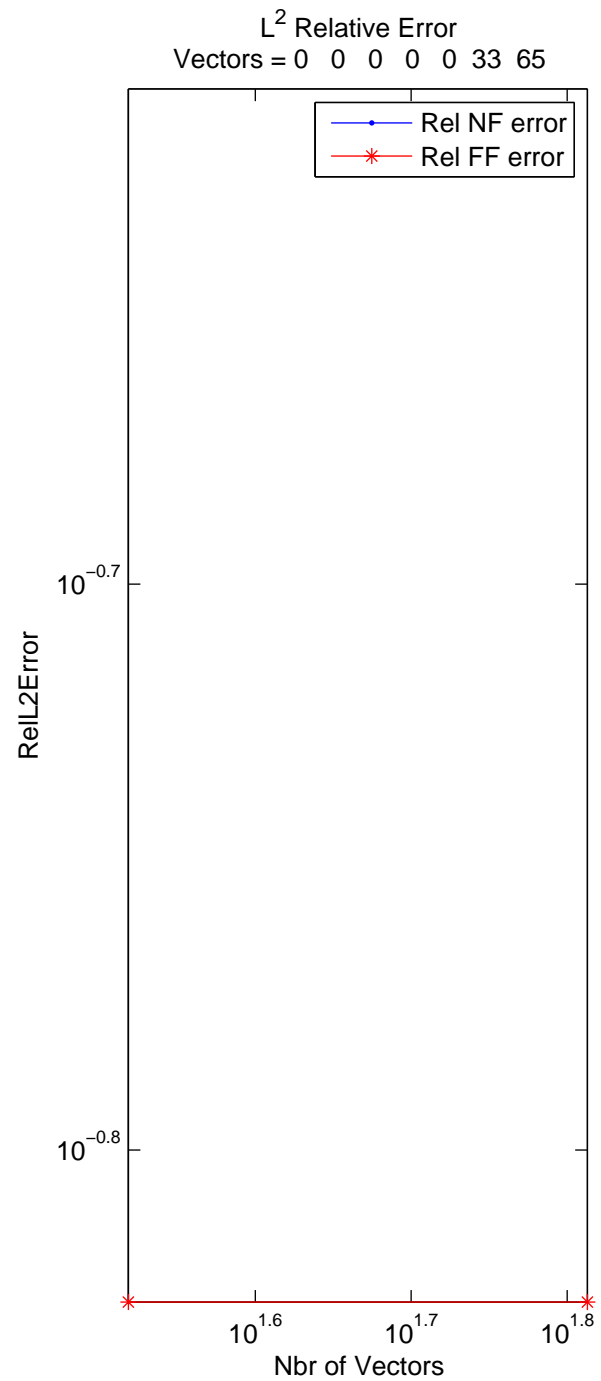
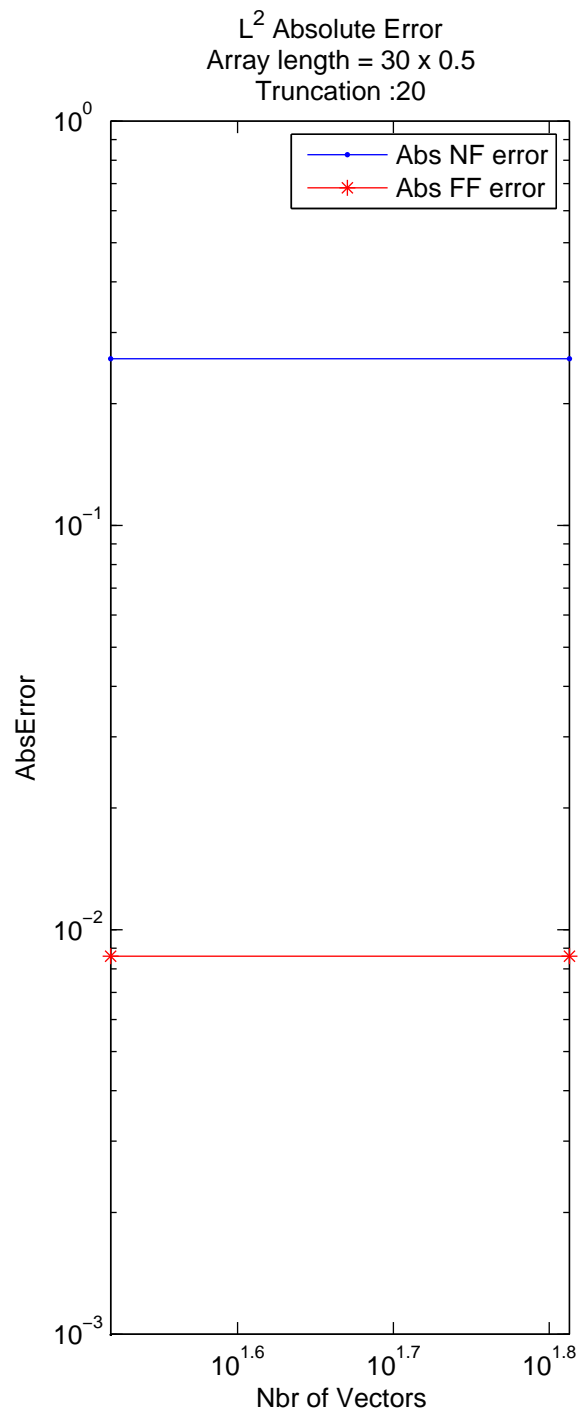


Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 20, Nbr of Vectors : 33
Nbr of point sources : 30×0.5

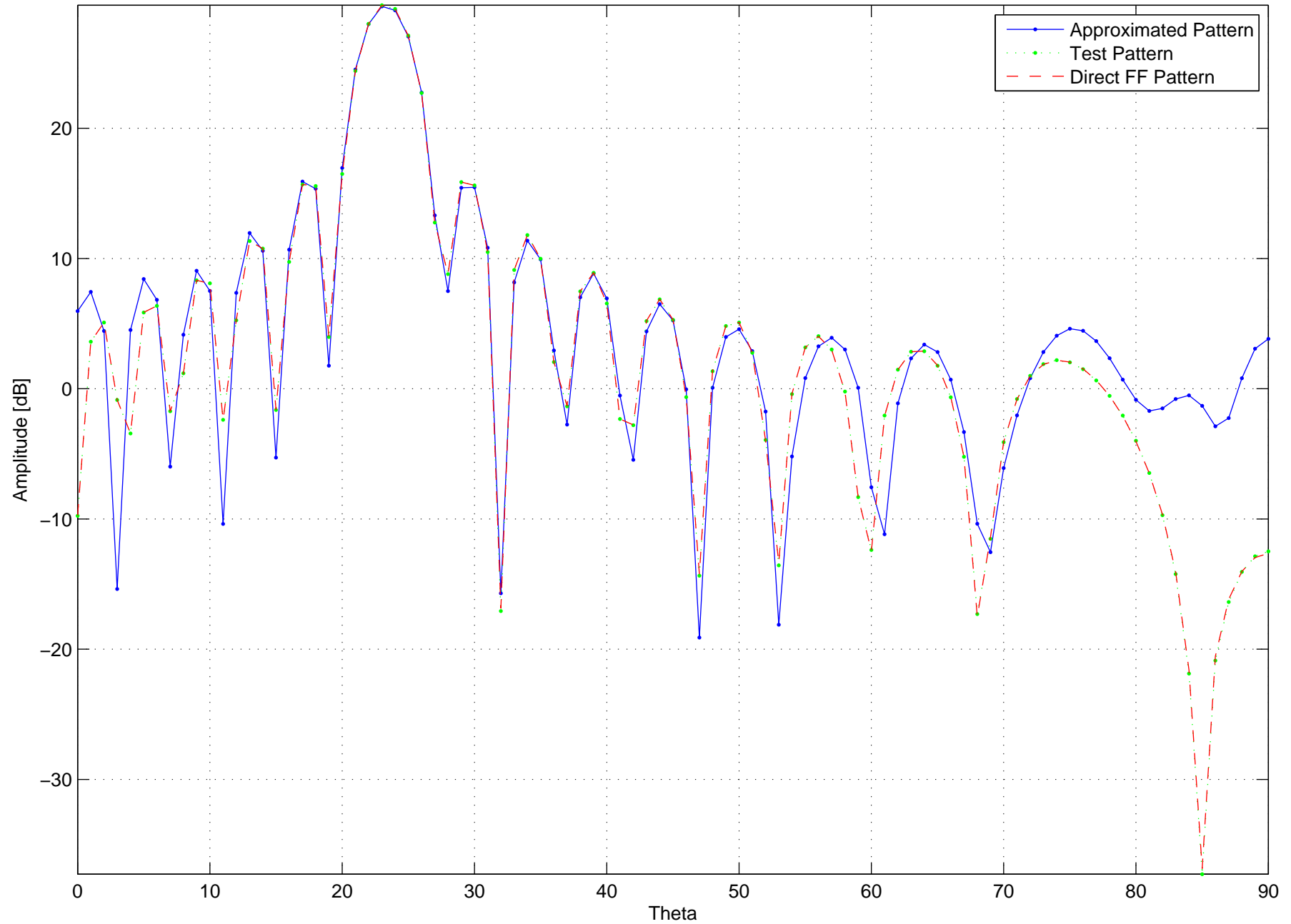


Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 20, Nbr of Vectors : 65
Nbr of point sources : 30×0.5





Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 15, Nbr of Vectors : 33
Nbr of point sources : 30×0.5



Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 15, Nbr of Vectors : 65
Nbr of point sources : 30×0.5

