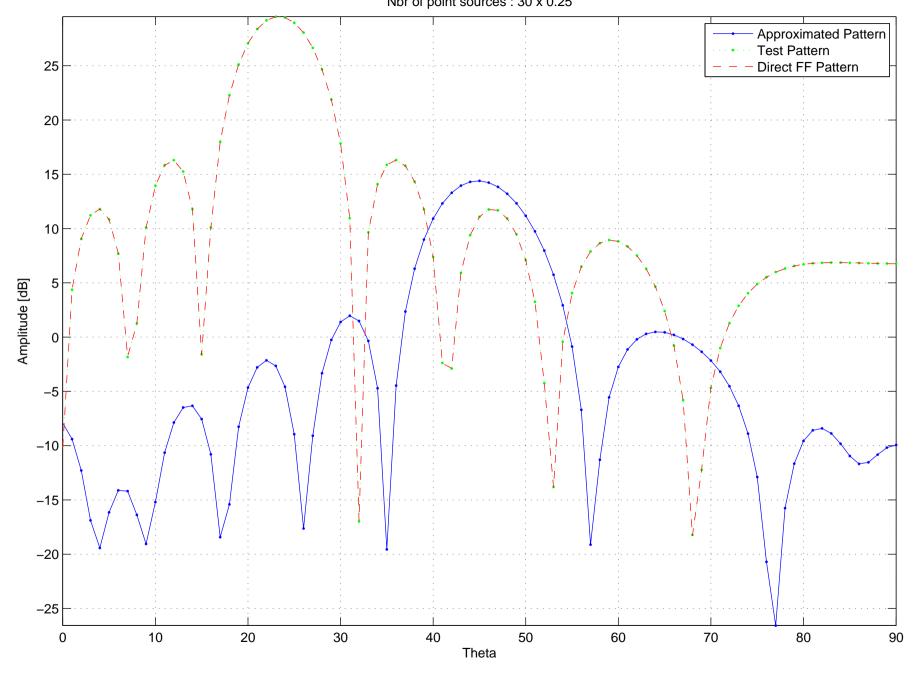
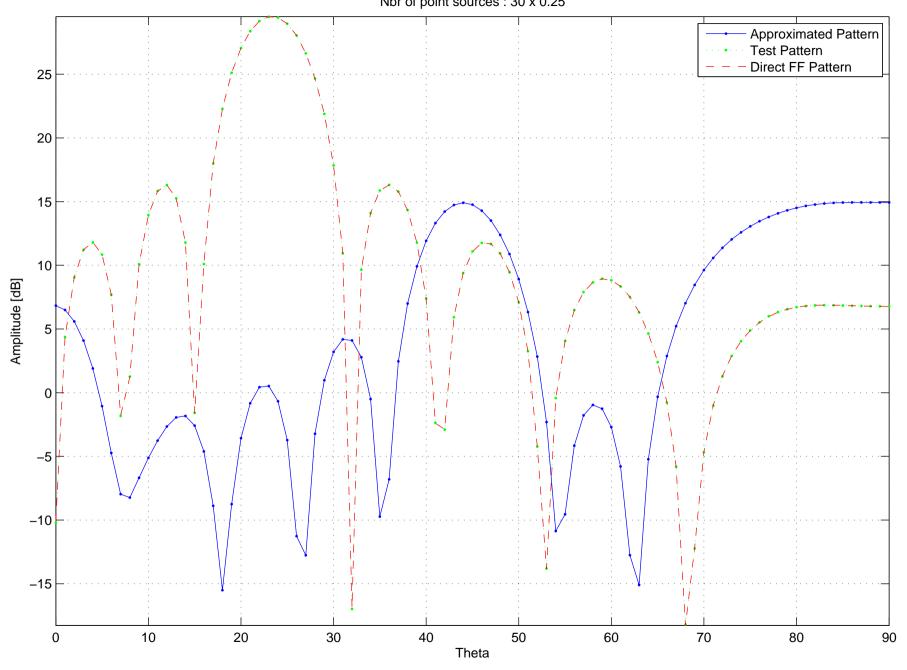
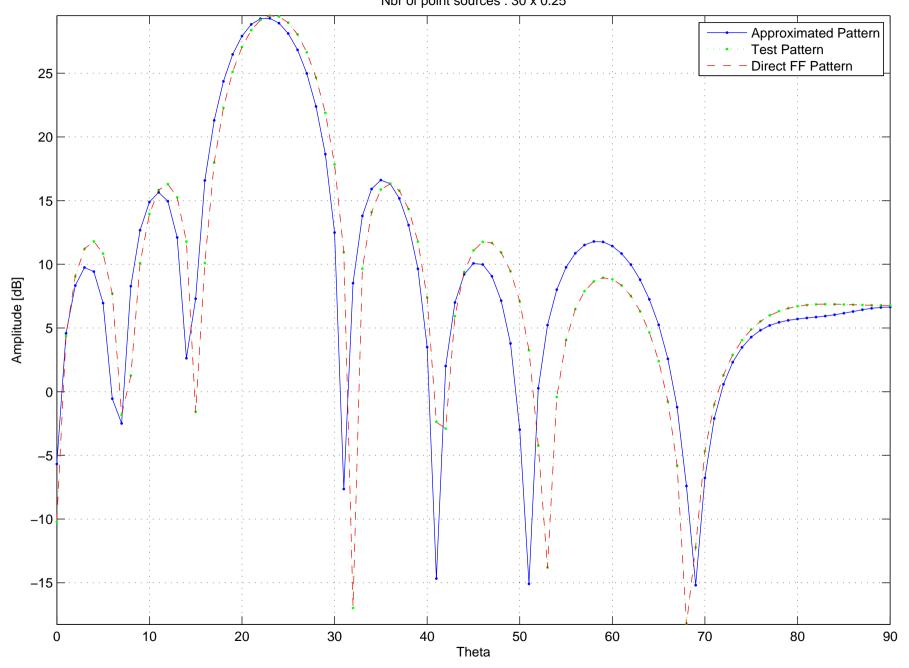
Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 0, Nbr of Vectors : 1
Nbr of point sources : 30 x 0.25



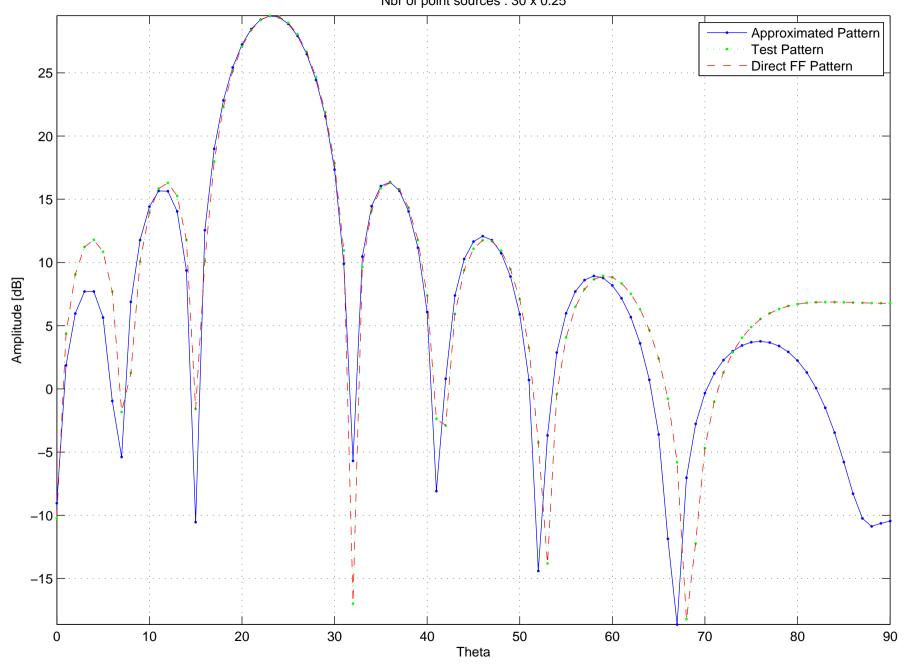
Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 0, Nbr of Vectors : 3
Nbr of point sources : 30 x 0.25



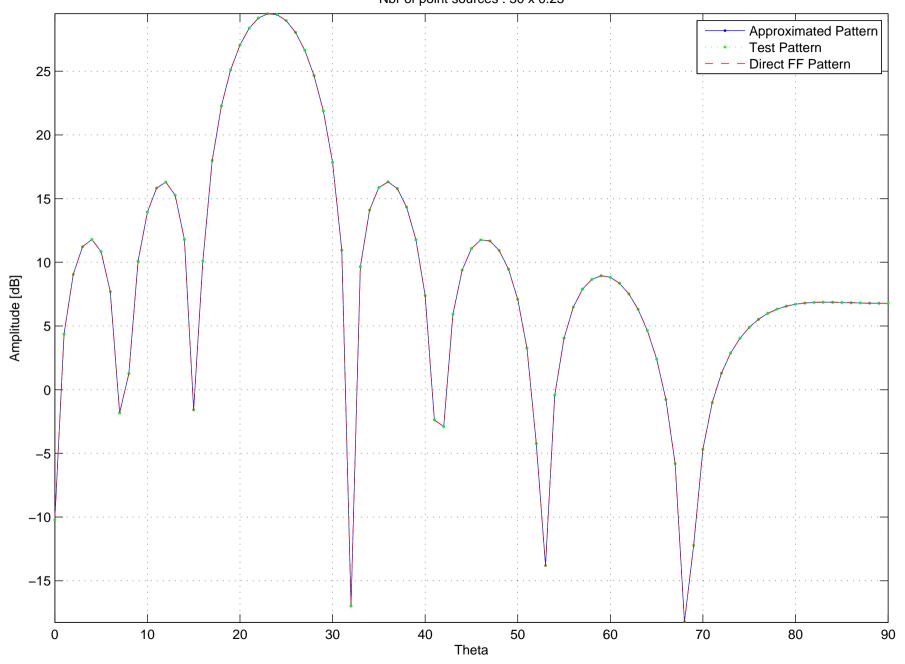
Patterns – Phi = 0°. Steering angle : 23.3251° Truncation : 0, Nbr of Vectors : 5 Nbr of point sources : 30 x 0.25



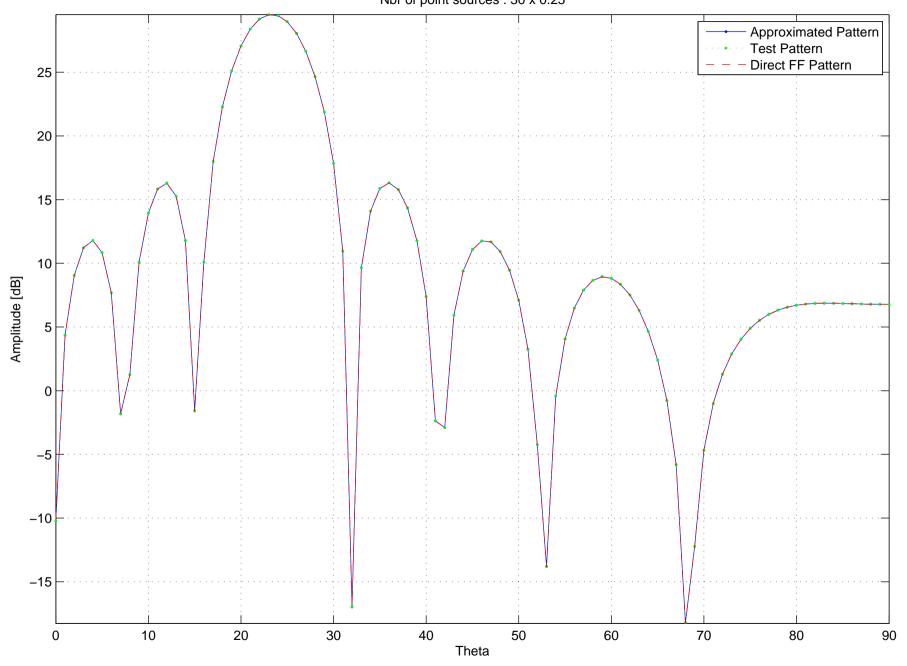
Patterns – Phi = 0°. Steering angle : 23.3251° Truncation : 0, Nbr of Vectors : 9 Nbr of point sources : 30 x 0.25



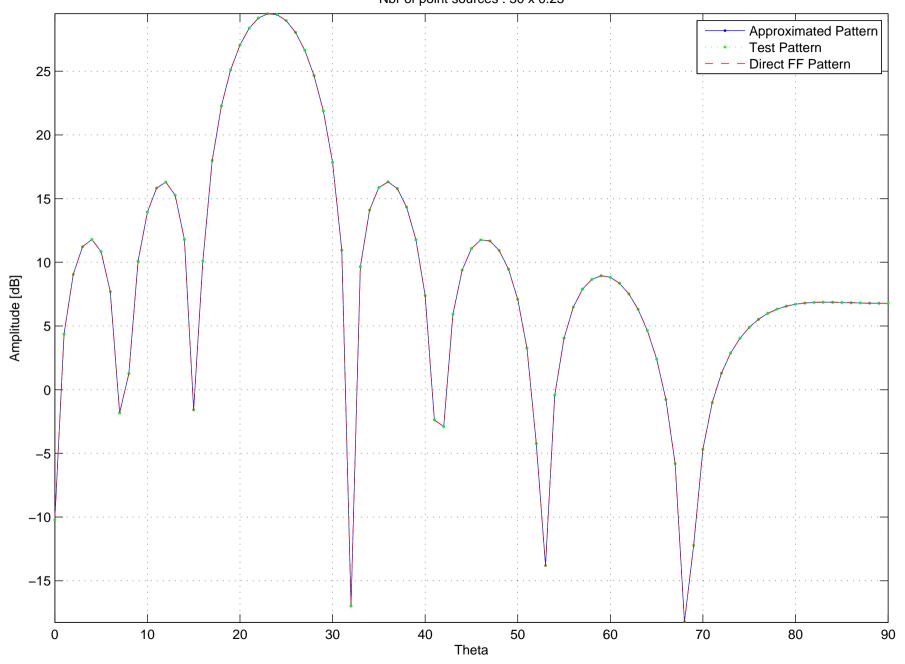
Patterns – Phi = 0°. Steering angle : 23.3251° Truncation : 0, Nbr of Vectors : 17 Nbr of point sources : 30 x 0.25

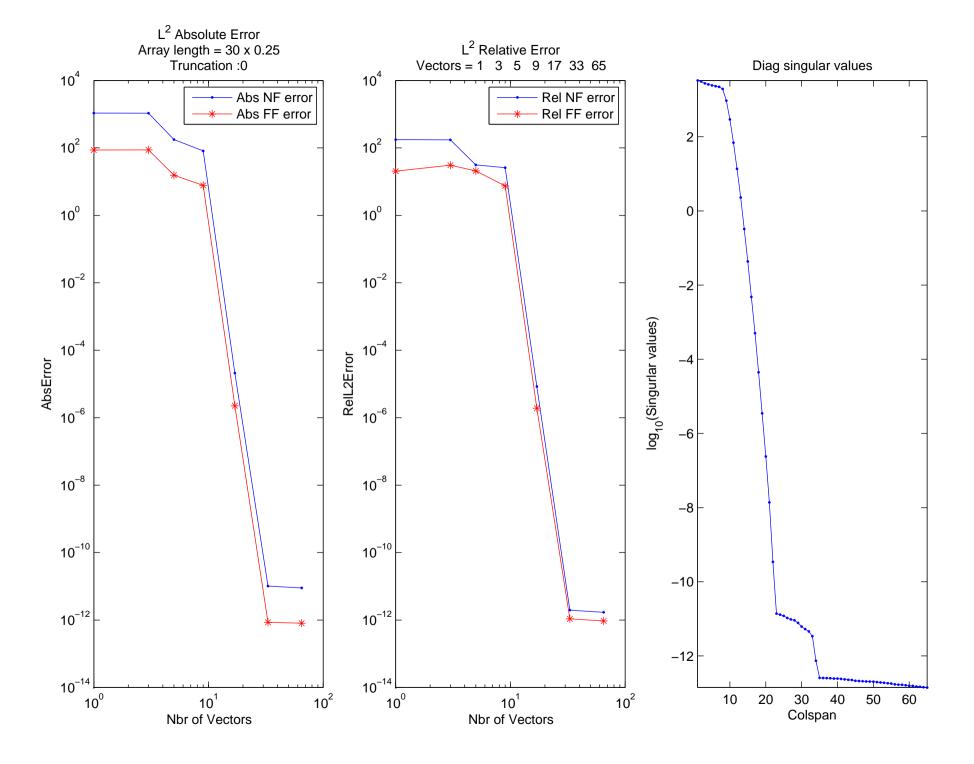


Patterns – Phi = 0°. Steering angle : 23.3251° Truncation : 0, Nbr of Vectors : 33 Nbr of point sources : 30 x 0.25

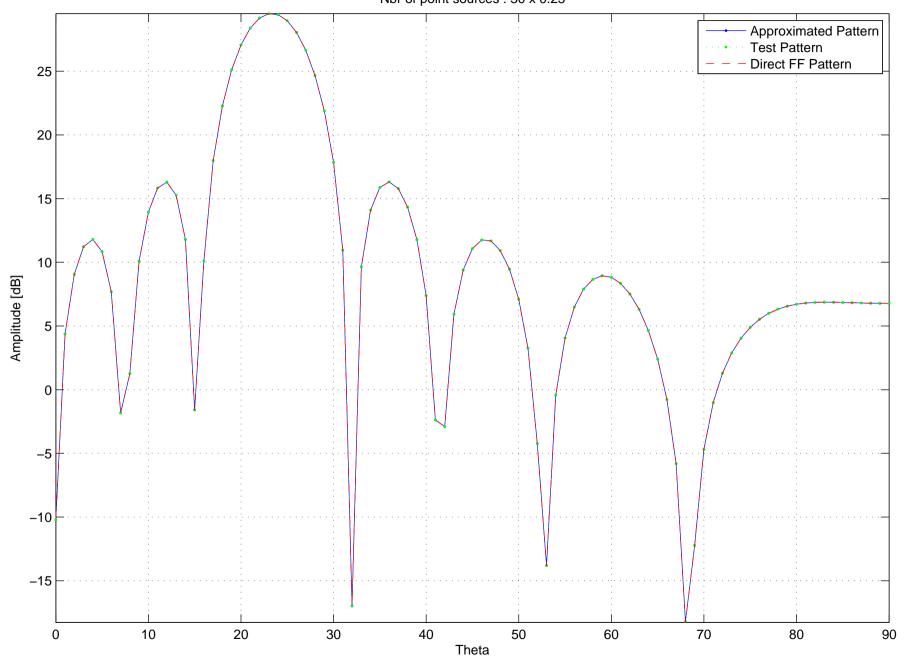


Patterns – Phi = 0°. Steering angle : 23.3251° Truncation : 0, Nbr of Vectors : 65 Nbr of point sources : 30 x 0.25

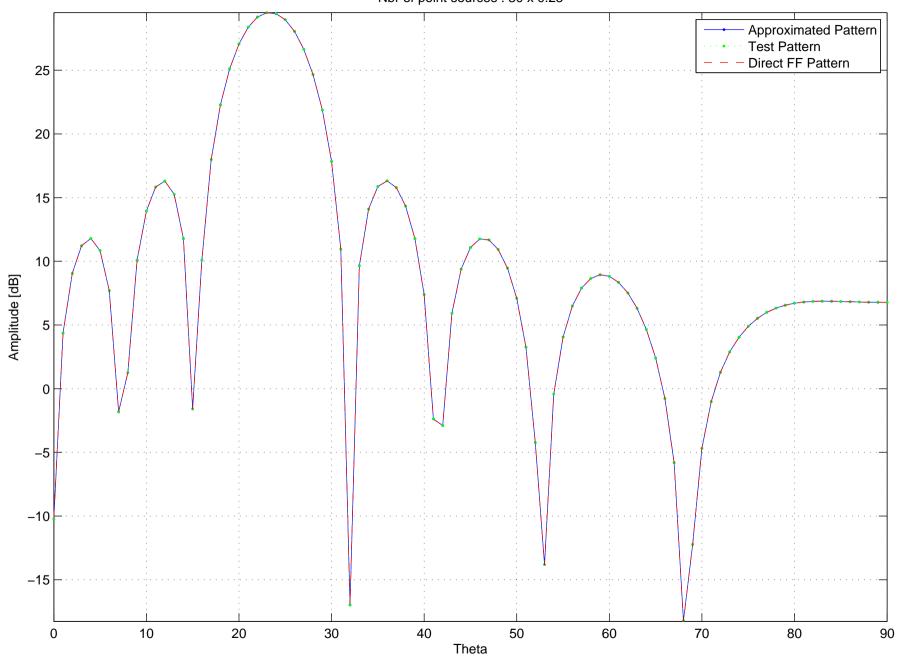


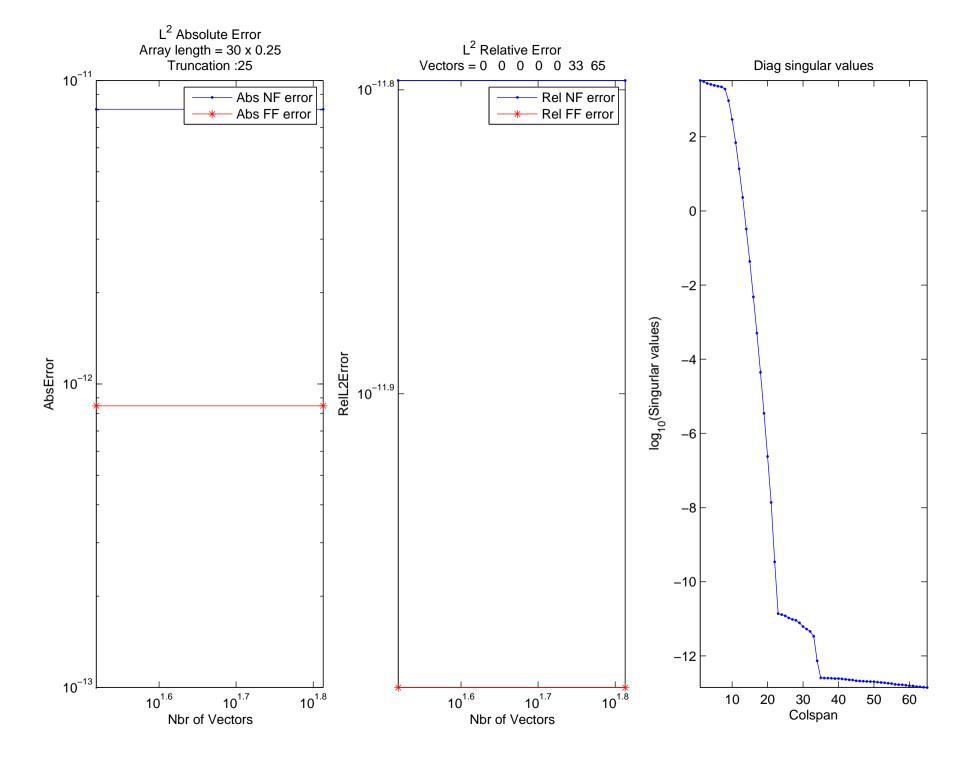


Patterns – Phi = 0°. Steering angle : 23.3251° Truncation : 25, Nbr of Vectors : 33 Nbr of point sources : 30 x 0.25

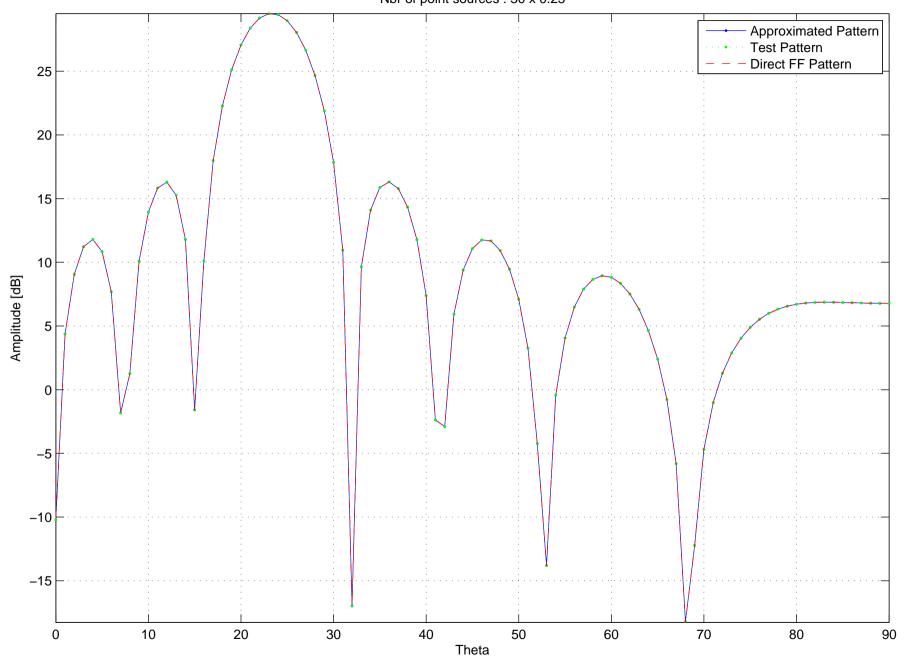


Patterns – Phi = 0°. Steering angle : 23.3251° Truncation : 25, Nbr of Vectors : 65 Nbr of point sources : 30 x 0.25

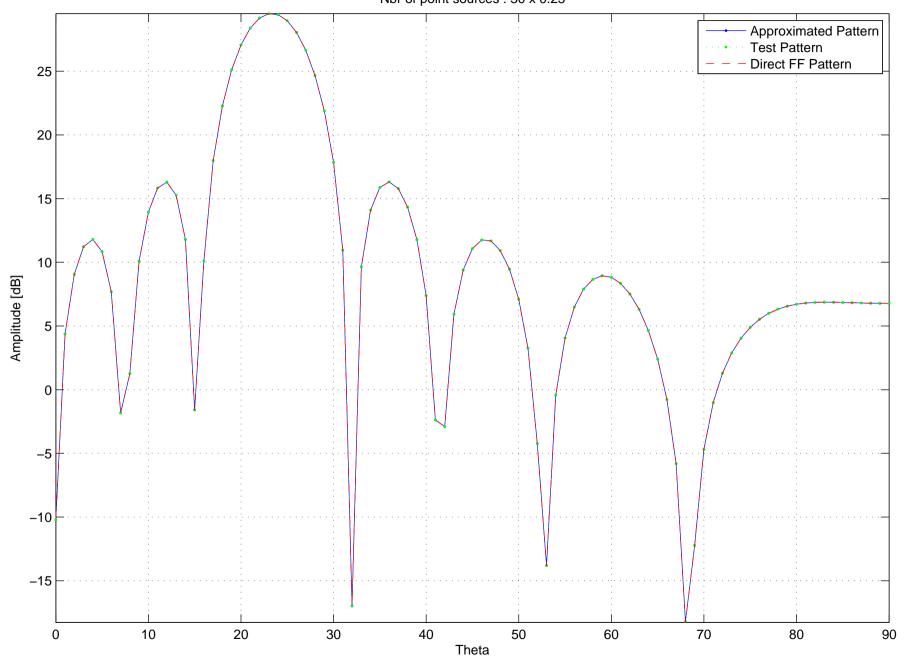


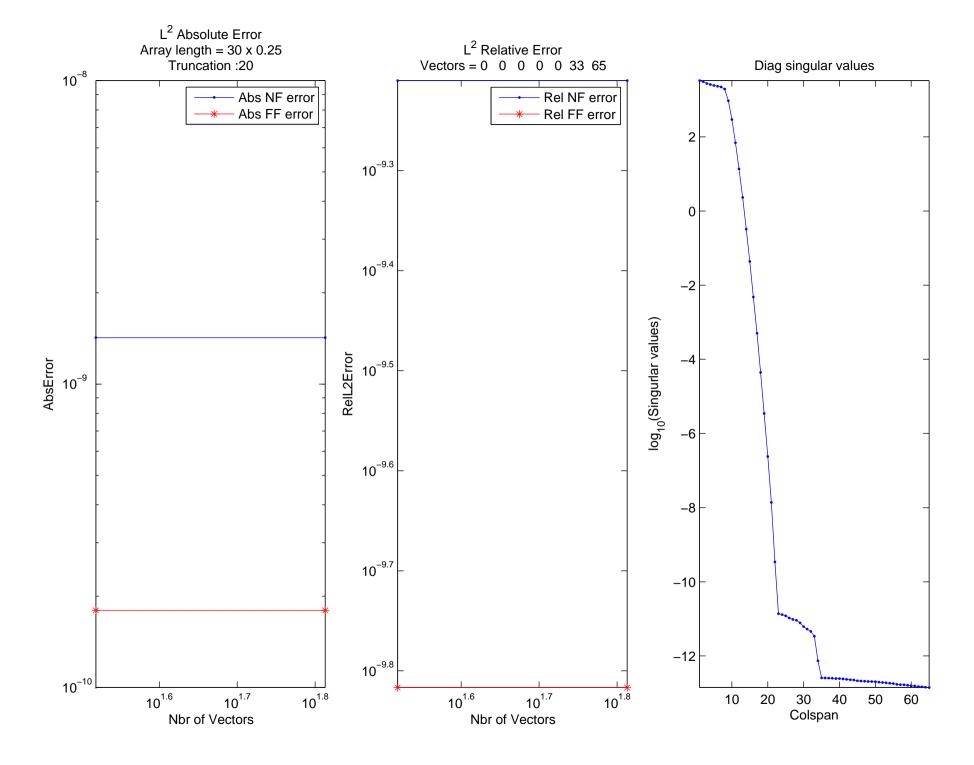


Patterns – Phi = 0°. Steering angle : 23.3251° Truncation : 20, Nbr of Vectors : 33 Nbr of point sources : 30 x 0.25

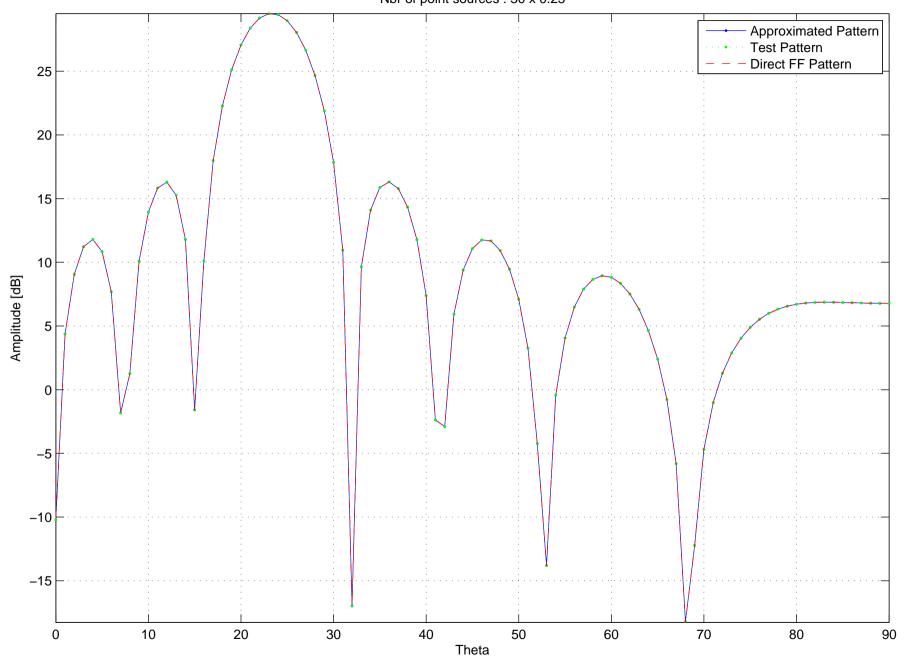


Patterns – Phi = 0°. Steering angle : 23.3251° Truncation : 20, Nbr of Vectors : 65 Nbr of point sources : 30 x 0.25





Patterns – Phi = 0°. Steering angle : 23.3251° Truncation : 15, Nbr of Vectors : 33 Nbr of point sources : 30 x 0.25



Patterns – Phi = 0°. Steering angle : 23.3251° Truncation : 15, Nbr of Vectors : 65 Nbr of point sources : 30 x 0.25

