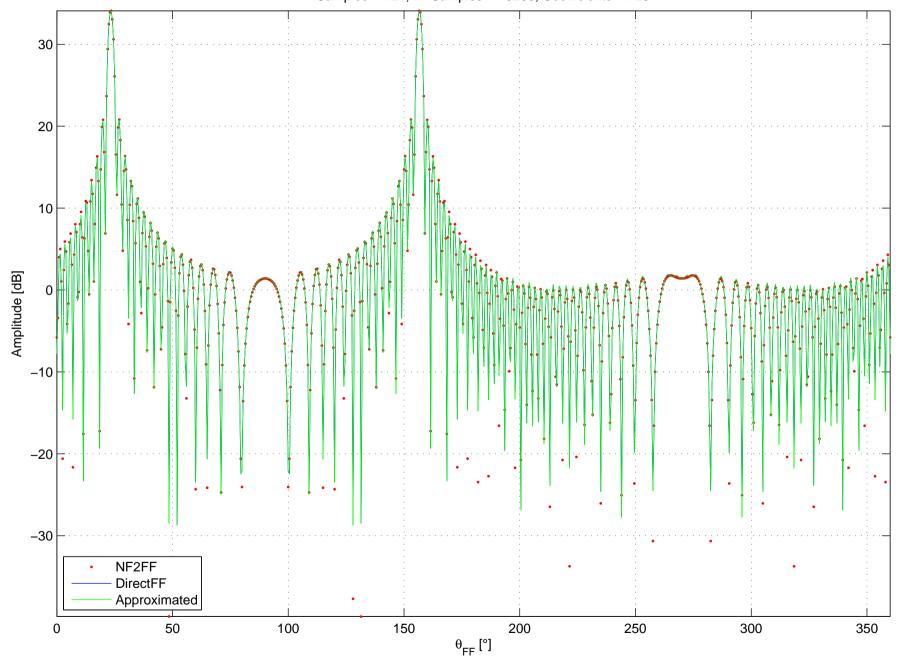
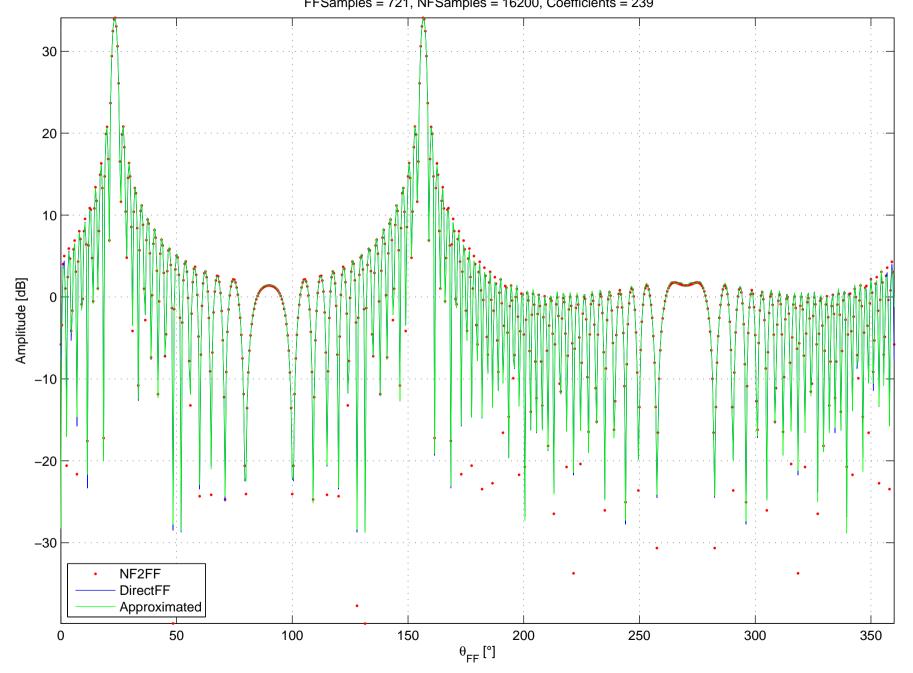
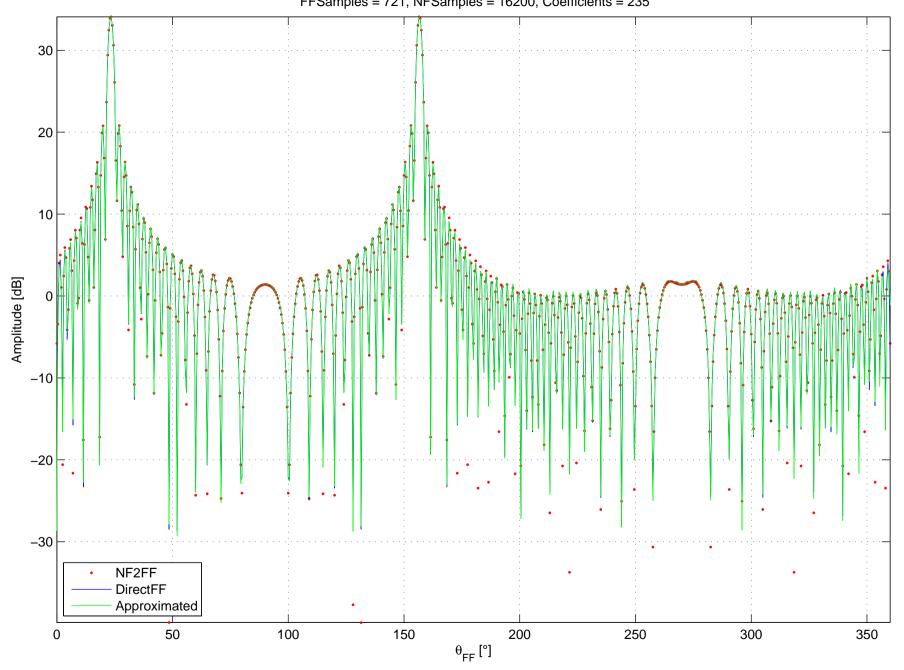
$51 \times 0.5\lambda, \, Rad: 13\lambda$   $Steering \, angle: 23.3251^{\circ}, \, L^2 \, error = 2.6268e-015$   $FFSamples = 721, \, NFSamples = 16200, \, Coefficients = 723$ 



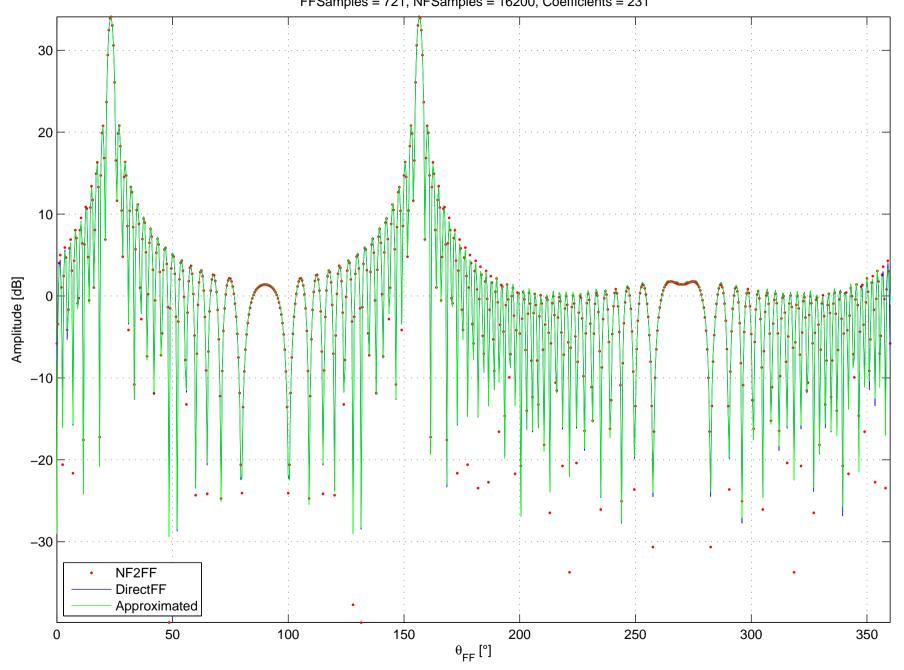
 $51 \times 0.5\lambda, \, Rad: 13\lambda$   $Steering \, angle: 23.3251^\circ, \, L^2 \, error = 0.0045031$   $FFSamples = 721, \, NFSamples = 16200, \, Coefficients = 239$ 



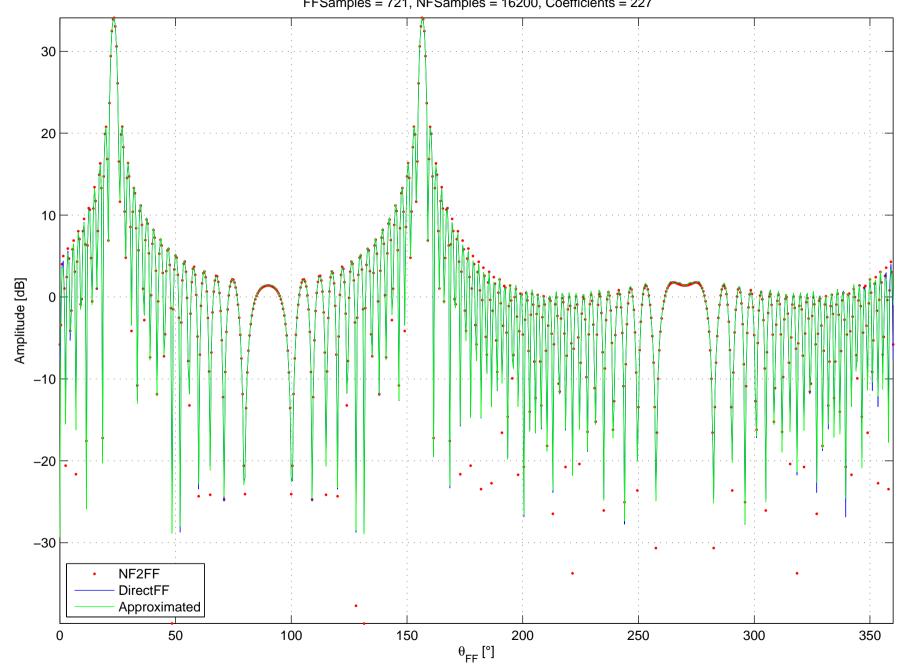
 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.0045955$  FFSamples = 721, NFSamples = 16200, Coefficients = 235



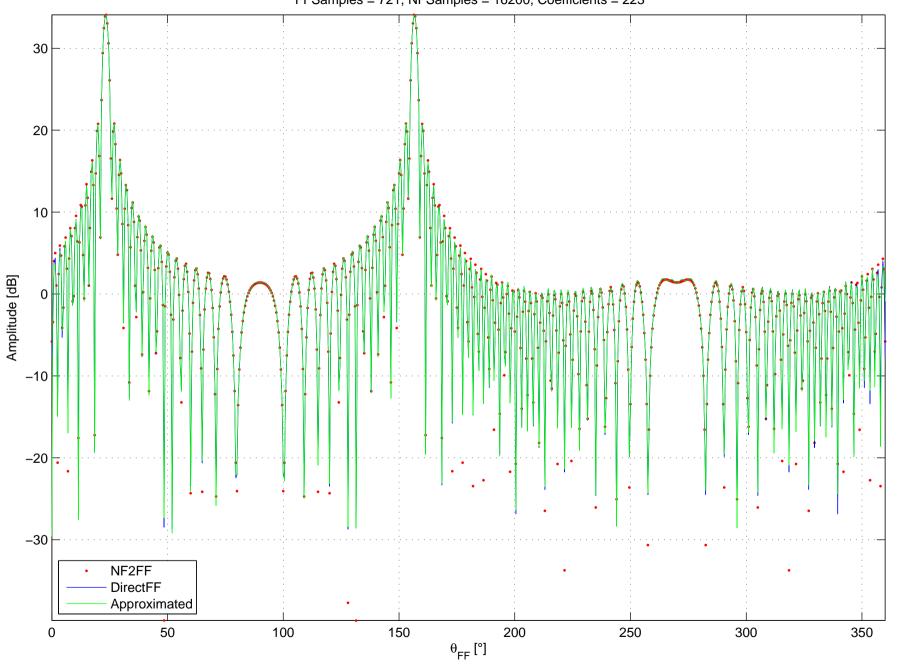
 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.0046945$  FFSamples = 721, NFSamples = 16200, Coefficients = 231



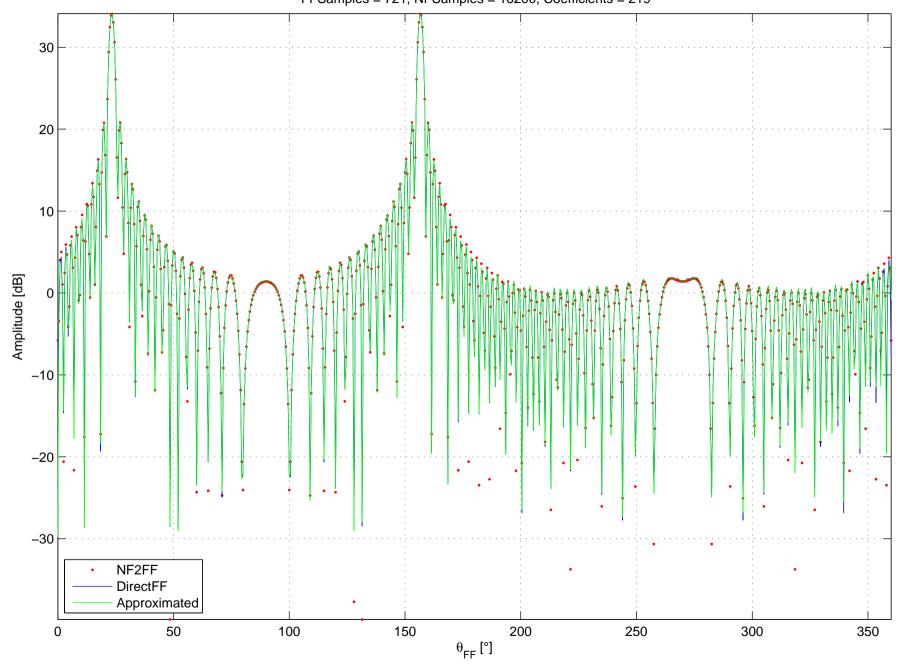
 $51 \times 0.5\lambda, \ Rad: 13\lambda$   $Steering \ angle: 23.3251^{\circ}, \ L^{2} \ error = 0.0048009$   $FFSamples = 721, \ NFSamples = 16200, \ Coefficients = 227$ 



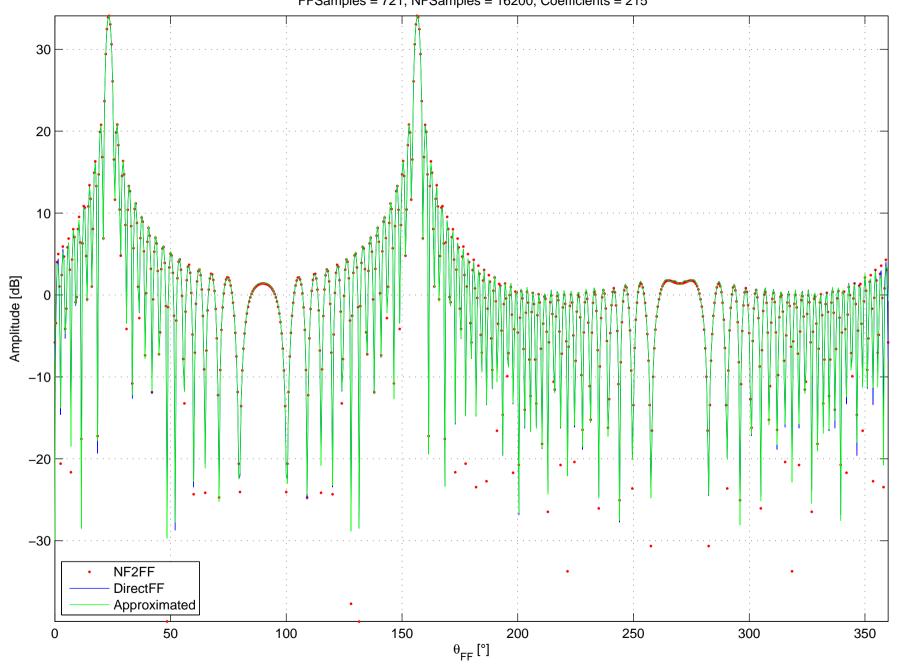
 $51 \times 0.5\lambda, \, Rad: 13\lambda$   $Steering \, angle: 23.3251^\circ, \, L^2 \, error = 0.004916$   $FFSamples = 721, \, NFSamples = 16200, \, Coefficients = 223$ 



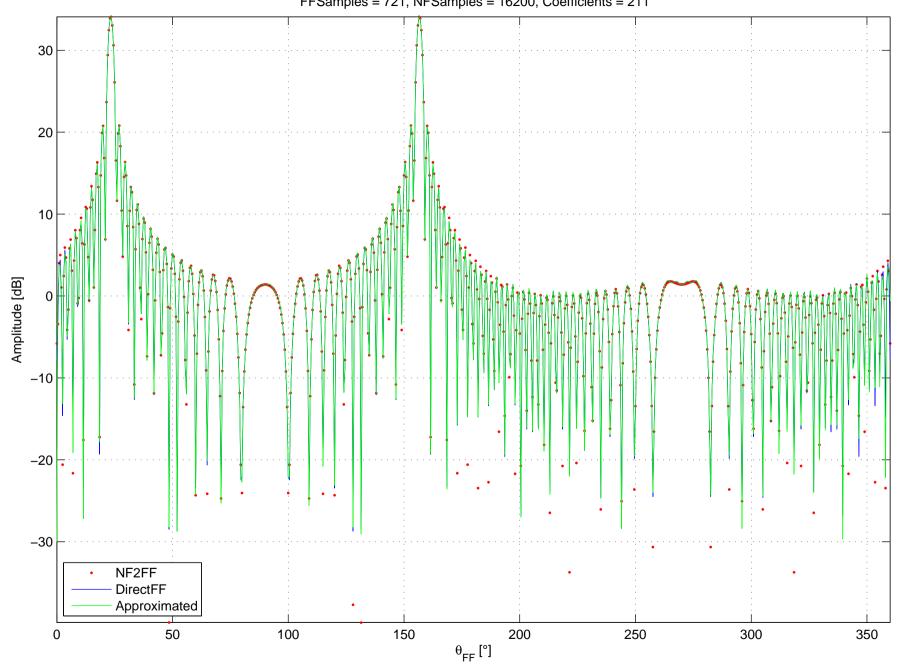
 $51 \times 0.5\lambda, \, Rad: 13\lambda$   $Steering \, angle: 23.3251^\circ, \, L^2 \, error = 0.005041$   $FFSamples = 721, \, NFSamples = 16200, \, Coefficients = 219$ 



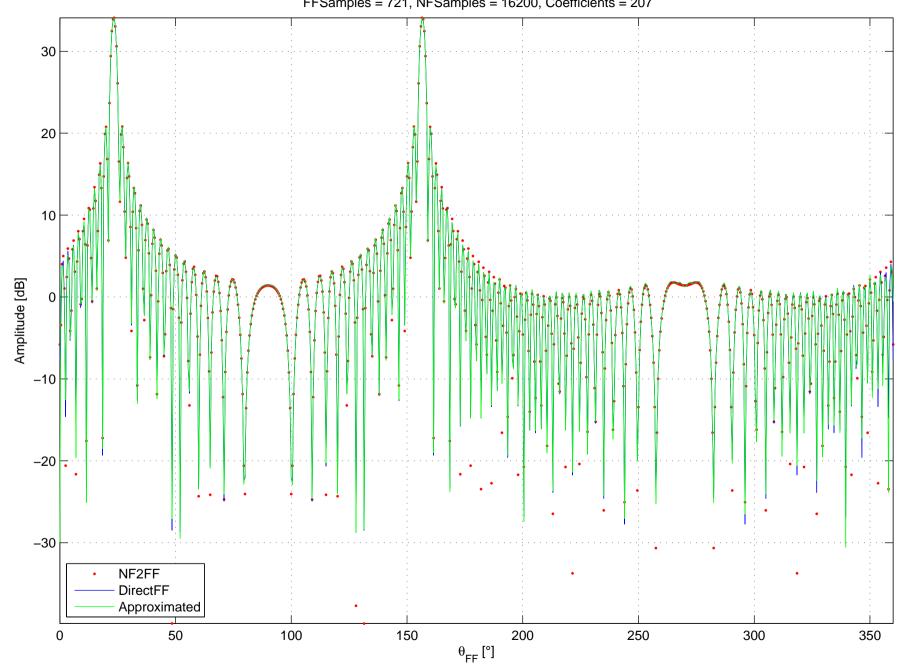
 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.0051779$  FFSamples = 721, NFSamples = 16200, Coefficients = 215



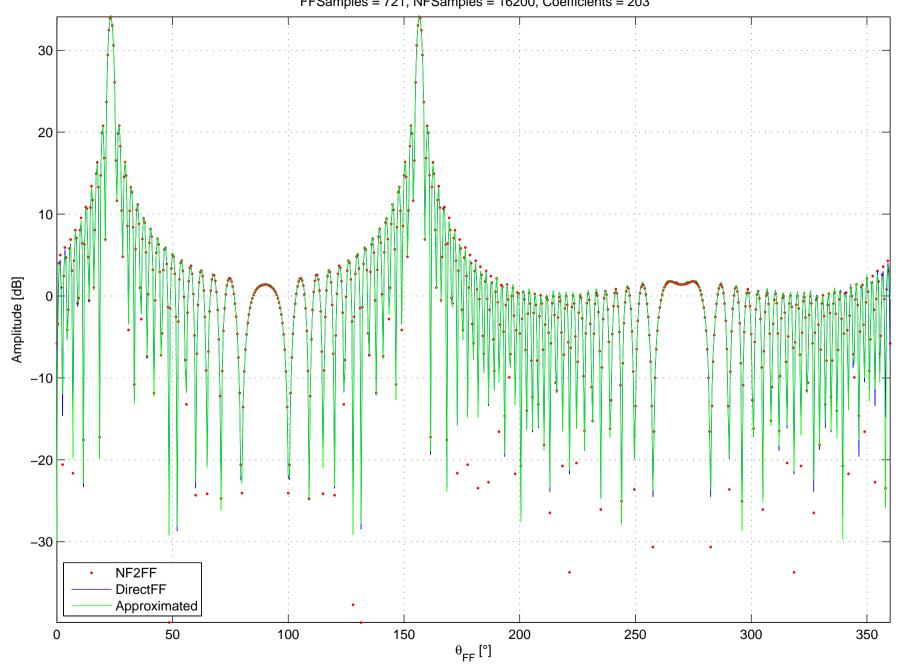
 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.0053287$  FFSamples = 721, NFSamples = 16200, Coefficients = 211



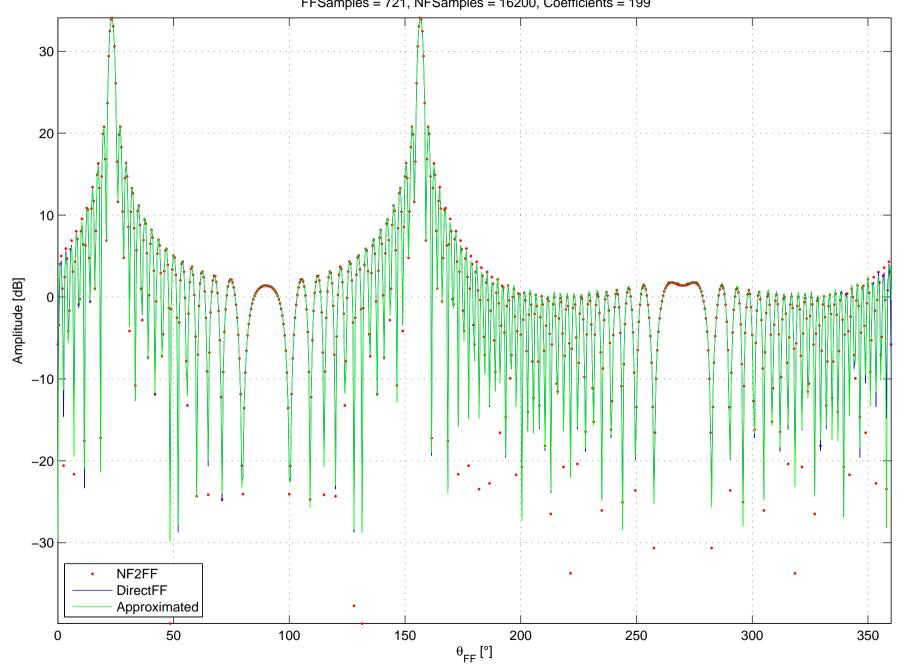
 $51 \times 0.5\lambda, \, Rad: 13\lambda$   $Steering \, angle: 23.3251^\circ, \, L^2 \, error = 0.0054962$   $FFSamples = 721, \, NFSamples = 16200, \, Coefficients = 207$ 



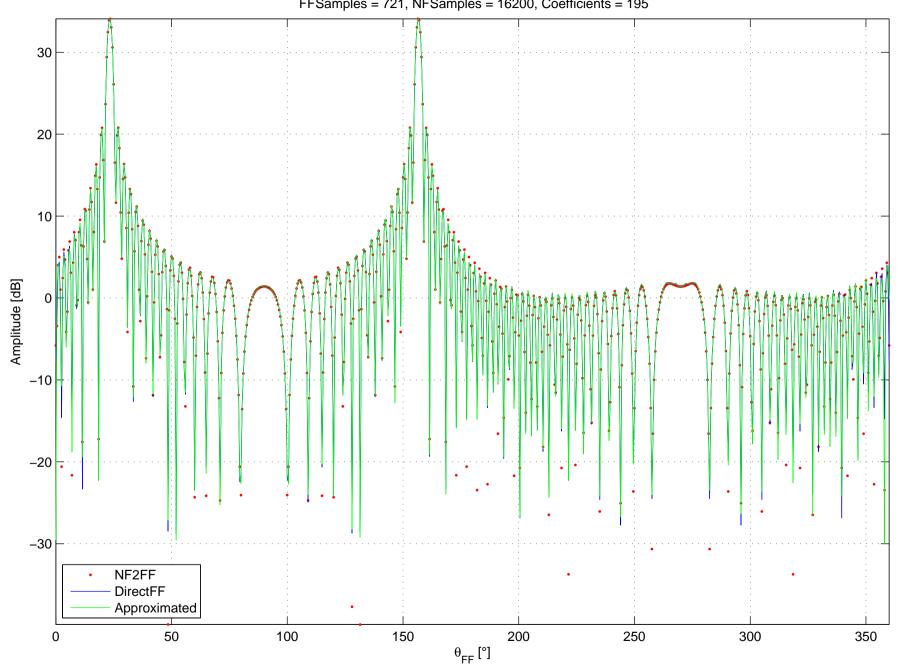
 $51 \times 0.5\lambda, \, Rad: 13\lambda$   $Steering \, angle: 23.3251^{\circ}, \, L^2 \, error = 0.0056843$   $FFSamples = 721, \, NFSamples = 16200, \, Coefficients = 203$ 



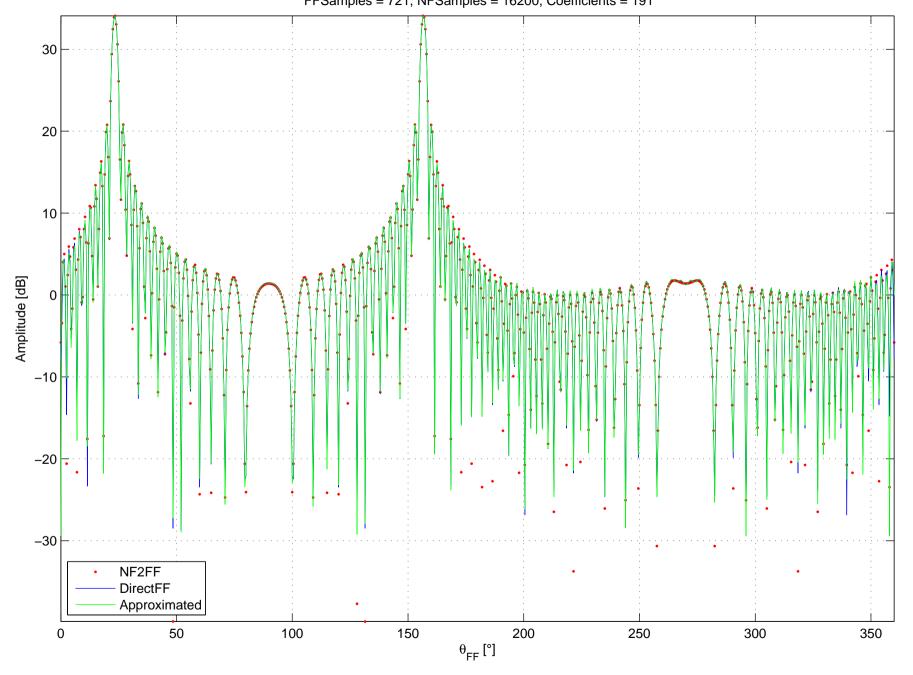
 $51 \times 0.5\lambda, \, Rad: 13\lambda$   $Steering \, angle: 23.3251^\circ, \, L^2 \, error = 0.0058983$   $FFSamples = 721, \, NFSamples = 16200, \, Coefficients = 199$ 



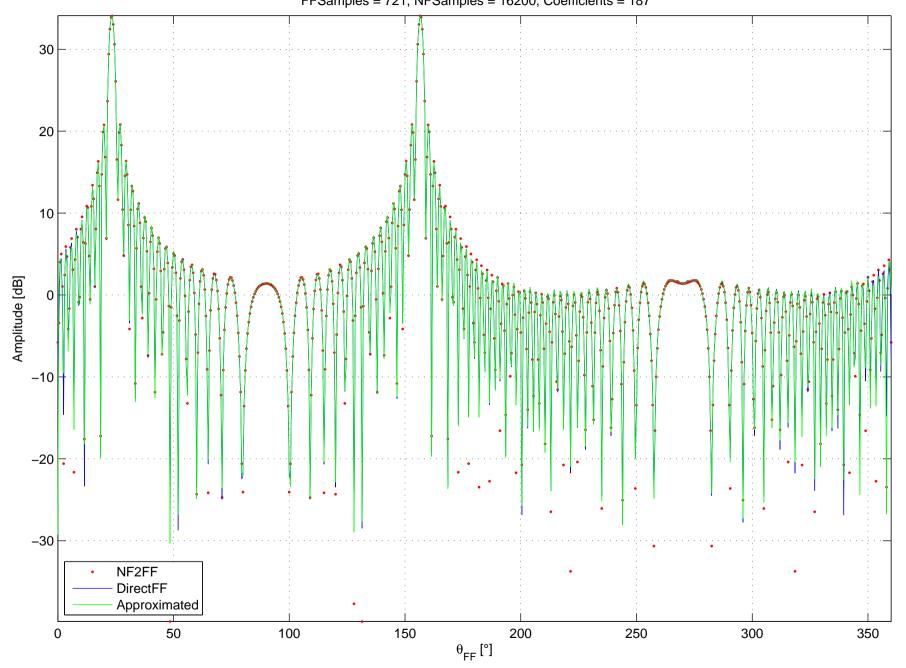
 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.0061467$  FFSamples = 721, NFSamples = 16200, Coefficients = 195



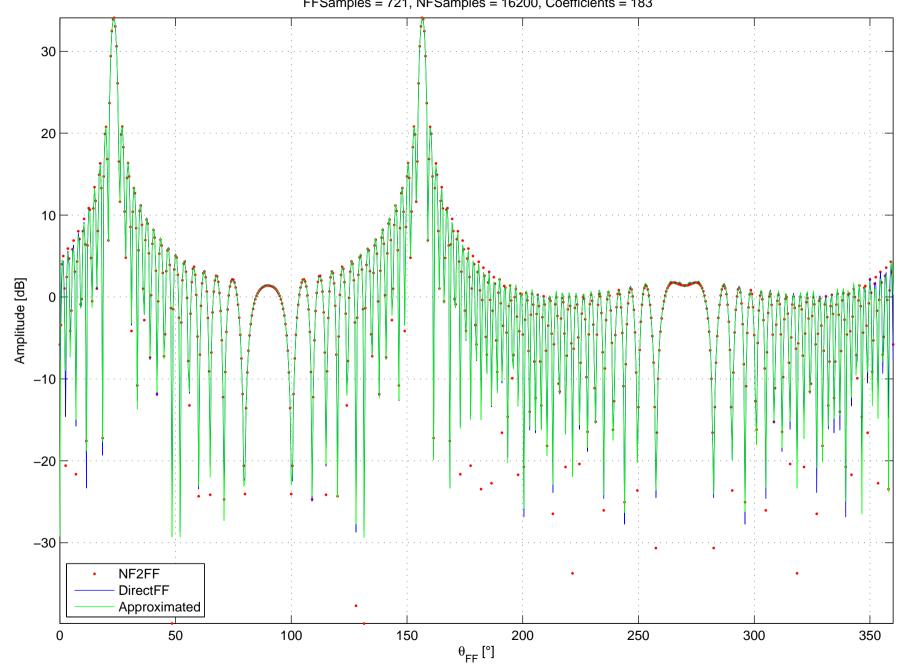
 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.0064404$  FFSamples = 721, NFSamples = 16200, Coefficients = 191



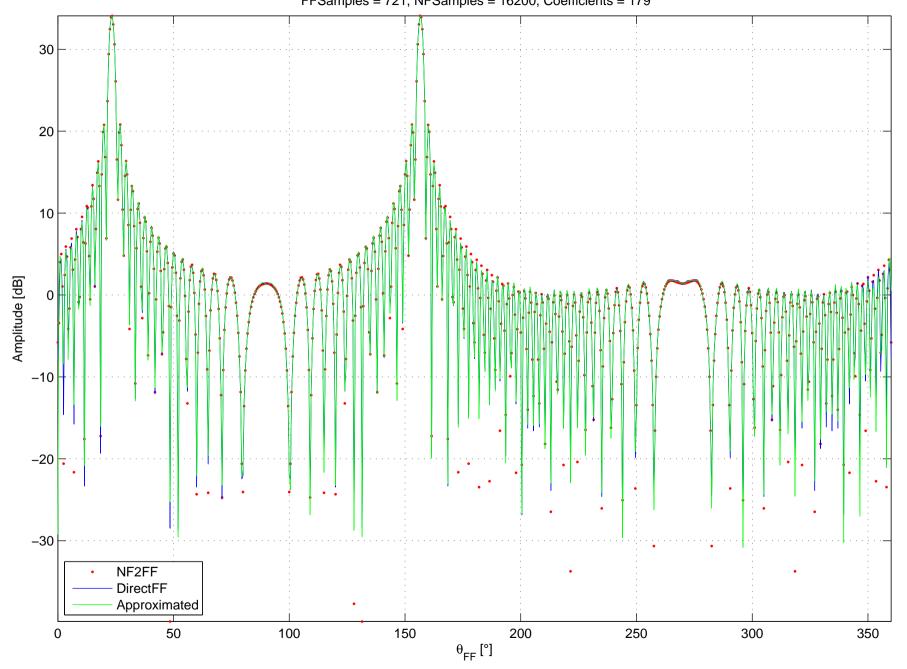
 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.0068003$  FFSamples = 721, NFSamples = 16200, Coefficients = 187



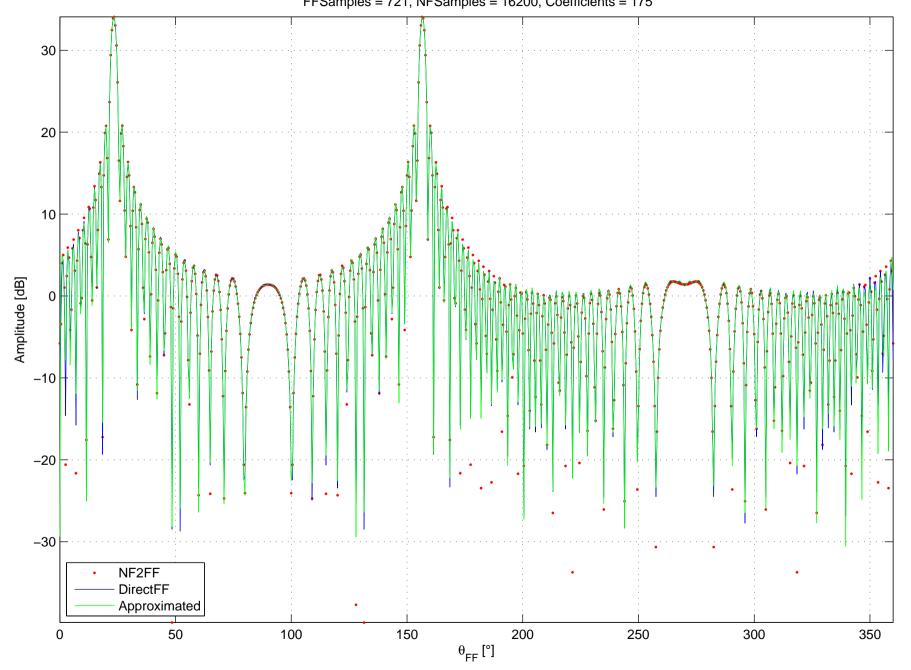
 $51 \times 0.5\lambda, \, Rad: 13\lambda$   $Steering \, angle: 23.3251^\circ, \, L^2 \, error = 0.0072457$   $FFSamples = 721, \, NFSamples = 16200, \, Coefficients = 183$ 



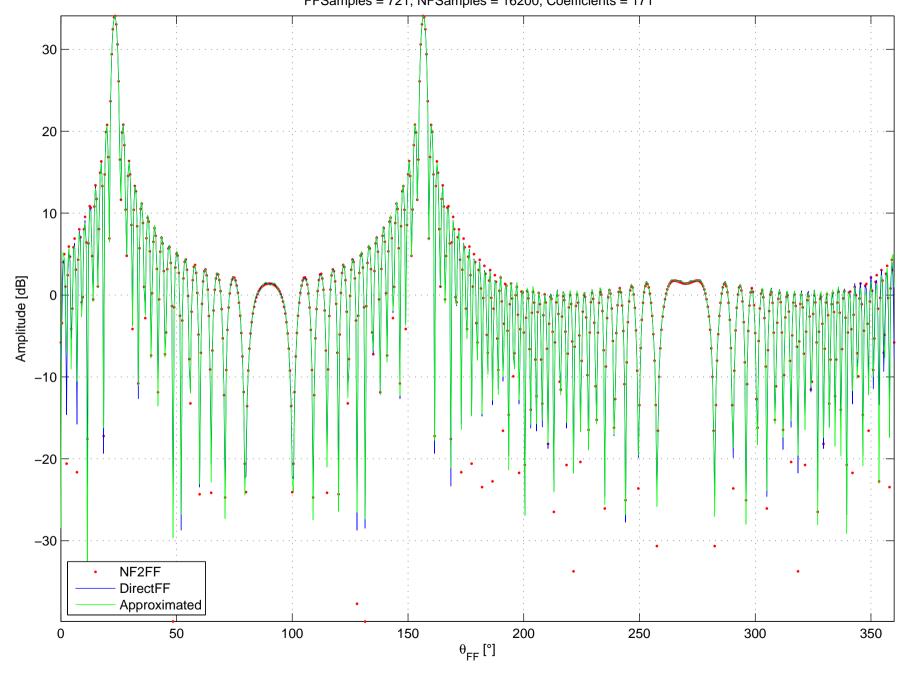
 $51 \times 0.5\lambda, \, Rad: 13\lambda$   $Steering \, angle: 23.3251^{\circ}, \, L^2 \, error = 0.0078344$   $FFSamples = 721, \, NFSamples = 16200, \, Coefficients = 179$ 



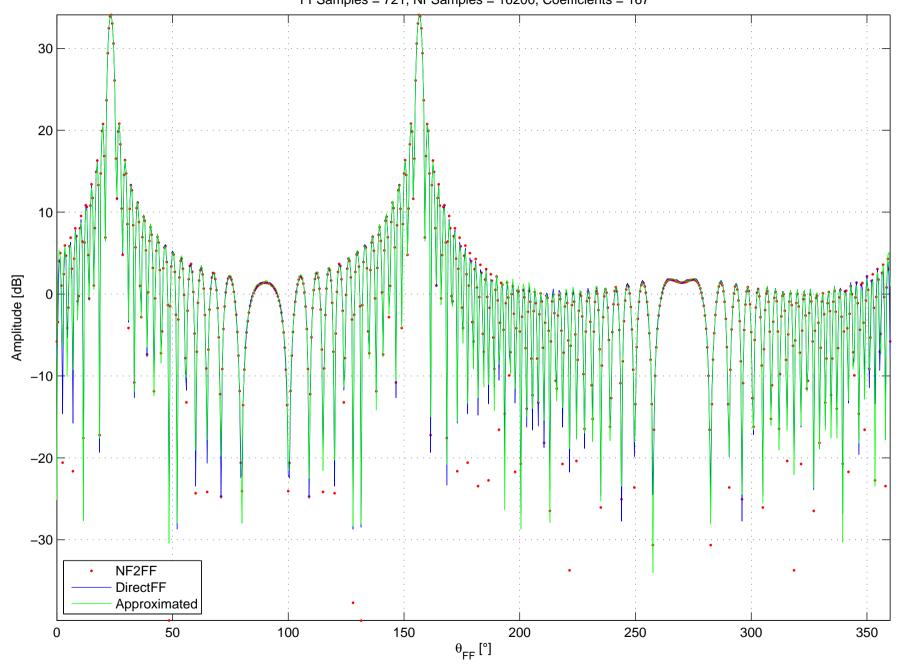
 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.0085341$  FFSamples = 721, NFSamples = 16200, Coefficients = 175



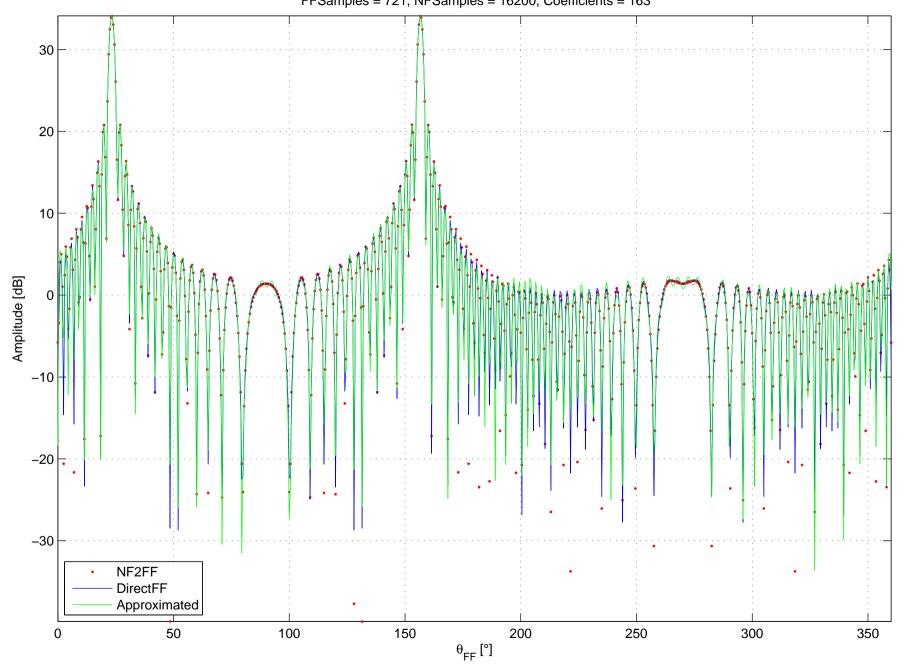
 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.0094402$  FFSamples = 721, NFSamples = 16200, Coefficients = 171



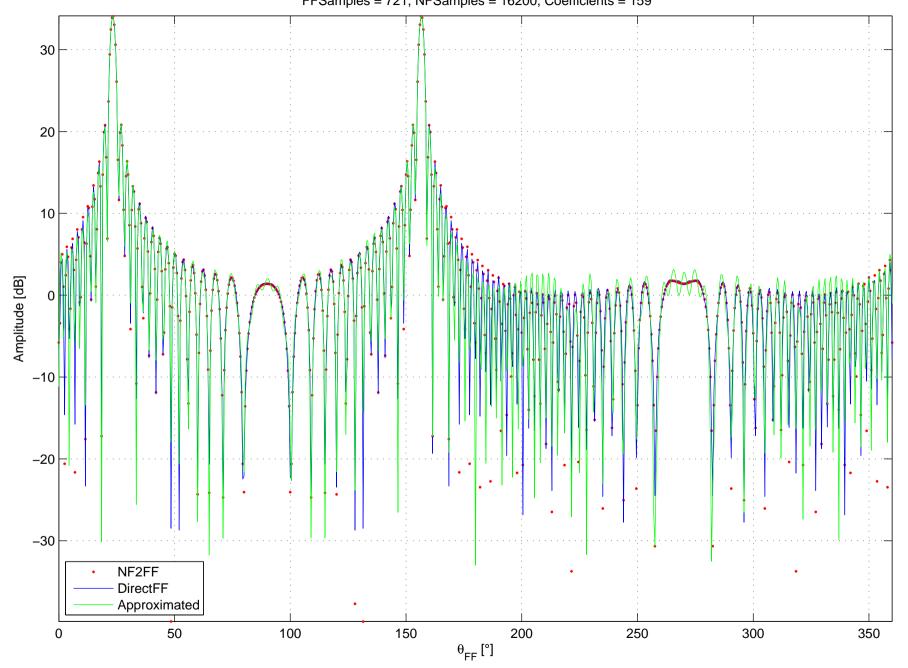
 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.011249$  FFSamples = 721, NFSamples = 16200, Coefficients = 167



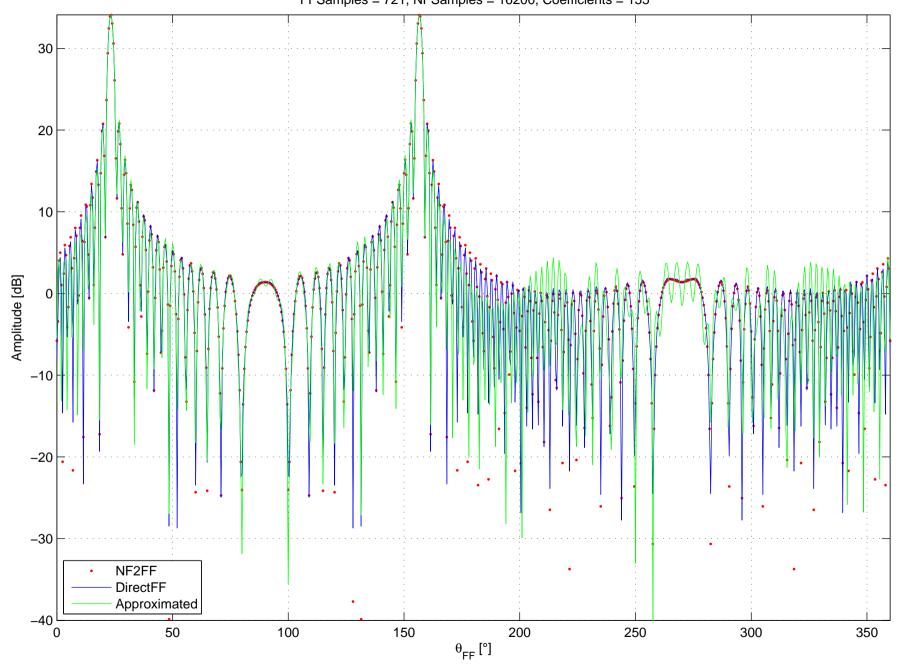
 $51 \times 0.5\lambda, \, Rad: 13\lambda$   $Steering \, angle: 23.3251^{\circ}, \, L^2 \, error = 0.016377$   $FFSamples = 721, \, NFSamples = 16200, \, Coefficients = 163$ 



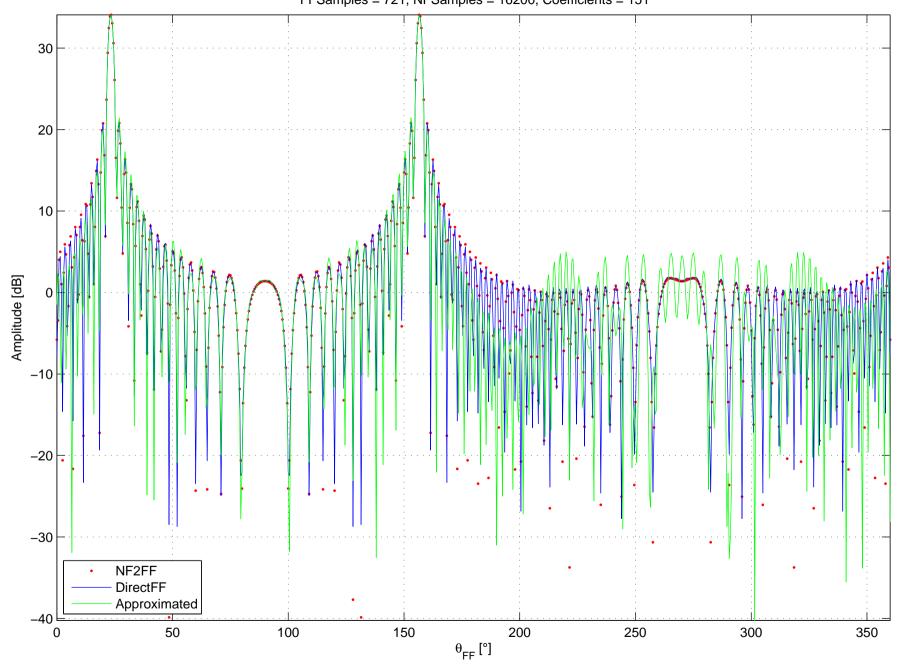
 $51 \times 0.5\lambda, \, Rad: 13\lambda$   $Steering \, angle: 23.3251^\circ, \, L^2 \, error = 0.032257$   $FFSamples = 721, \, NFSamples = 16200, \, Coefficients = 159$ 



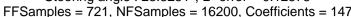
 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.058279$  FFSamples = 721, NFSamples = 16200, Coefficients = 155

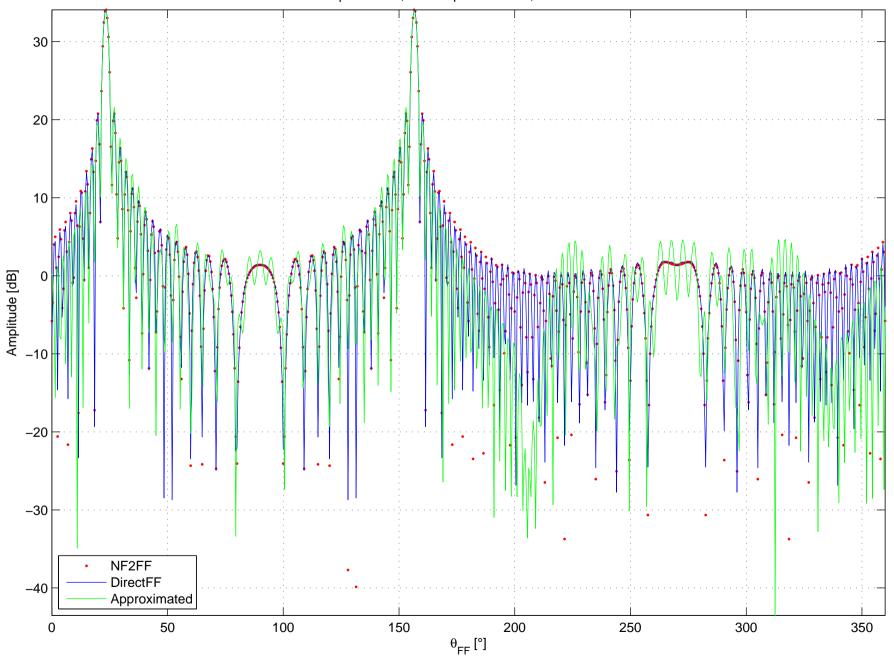


 $51 \times 0.5 \lambda$ , Rad :  $13 \lambda$ Steering angle :  $23.3251^\circ$ , L<sup>2</sup> error = 0.093354FFSamples = 721, NFSamples = 16200, Coefficients = 151

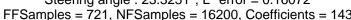


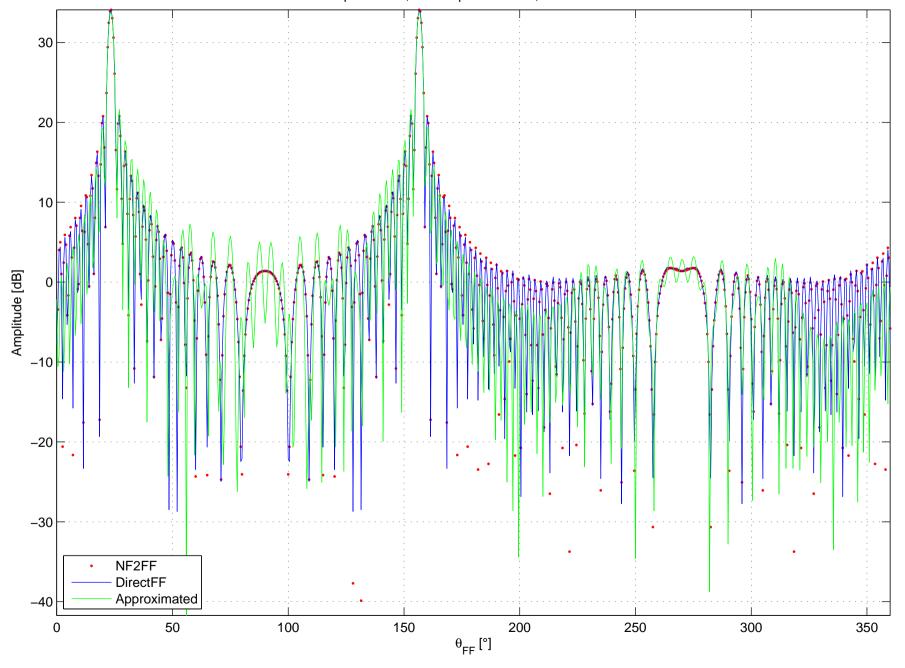
 $51 \times 0.5\lambda$ , Rad :  $13\lambda$ Steering angle :  $23.3251^\circ$ , L<sup>2</sup> error = 0.12873FFSamples = 721, NFSamples = 16200, Coefficients = 147



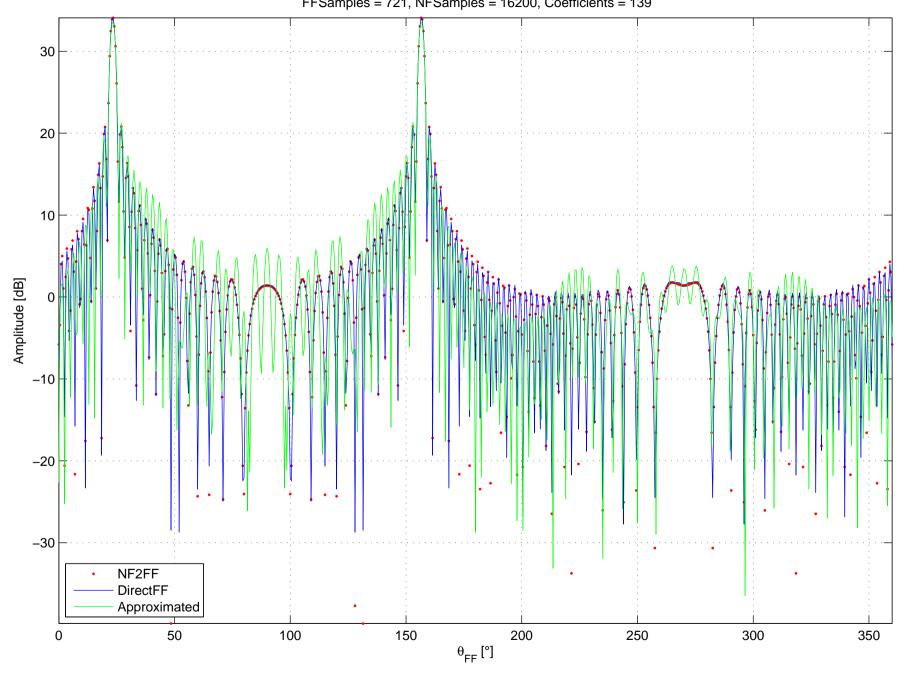


 $51 \times 0.5\lambda$ , Rad :  $13\lambda$ Steering angle :  $23.3251^\circ$ , L<sup>2</sup> error = 0.16072FFSamples = 721, NFSamples = 16200, Coefficients = 143

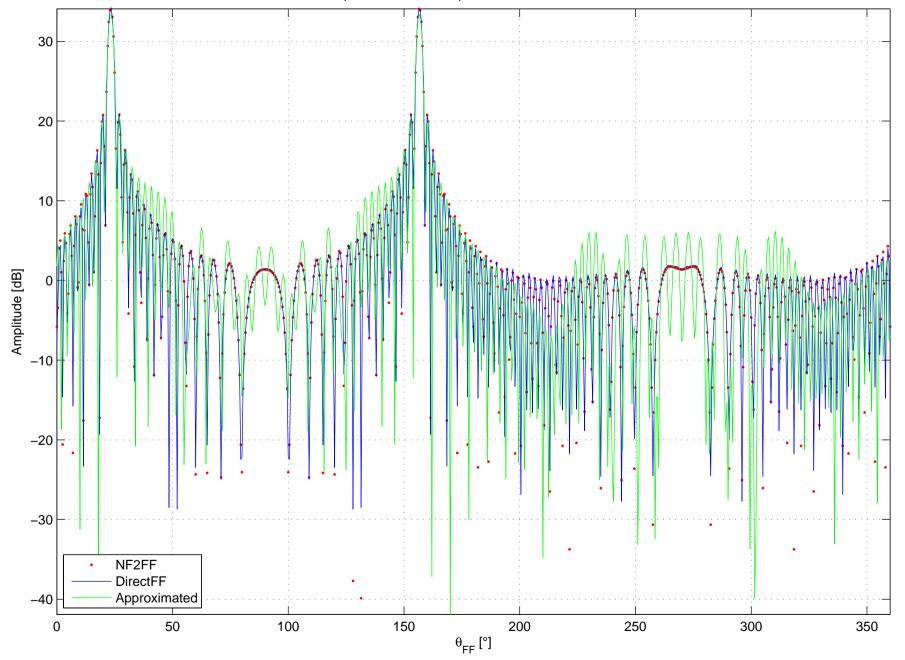




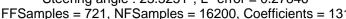
 $51 \times 0.5 \lambda, \, Rad: 13 \lambda$   $Steering \, angle: 23.3251^{\circ}, \, L^2 \, error = 0.20105$   $FFSamples = 721, \, NFSamples = 16200, \, Coefficients = 139$ 

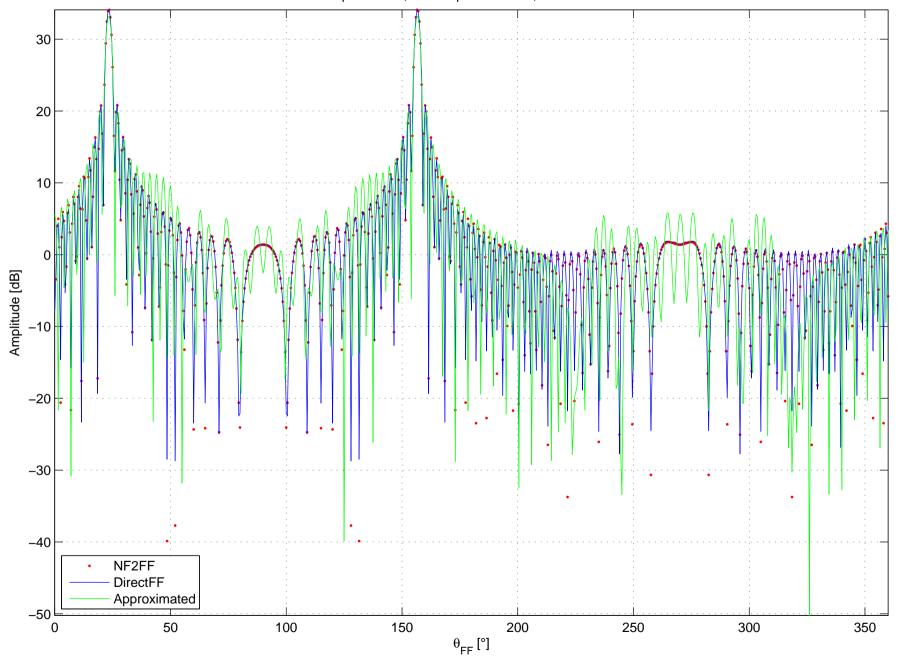


 $51 \times 0.5 \lambda, \, Rad: 13 \lambda$   $Steering \, angle: 23.3251^{\circ}, \, L^2 \, error = 0.24669$   $FFSamples = 721, \, NFSamples = 16200, \, Coefficients = 135$ 

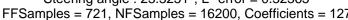


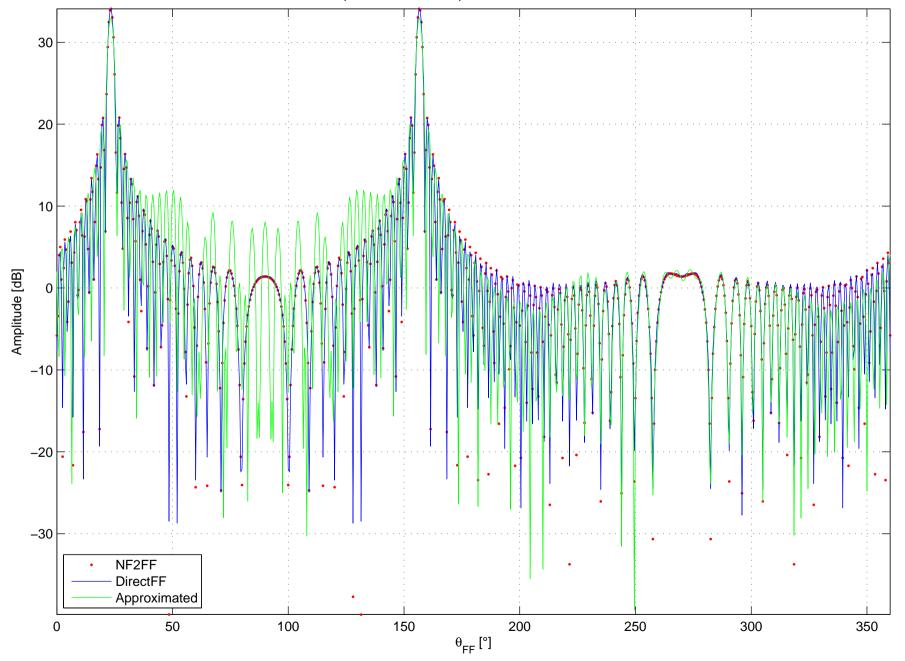
 $51 \times 0.5 \lambda$ , Rad :  $13 \lambda$ Steering angle :  $23.3251^\circ$ , L<sup>2</sup> error = 0.27846FFSamples = 721, NFSamples = 16200, Coefficients = 131



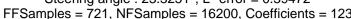


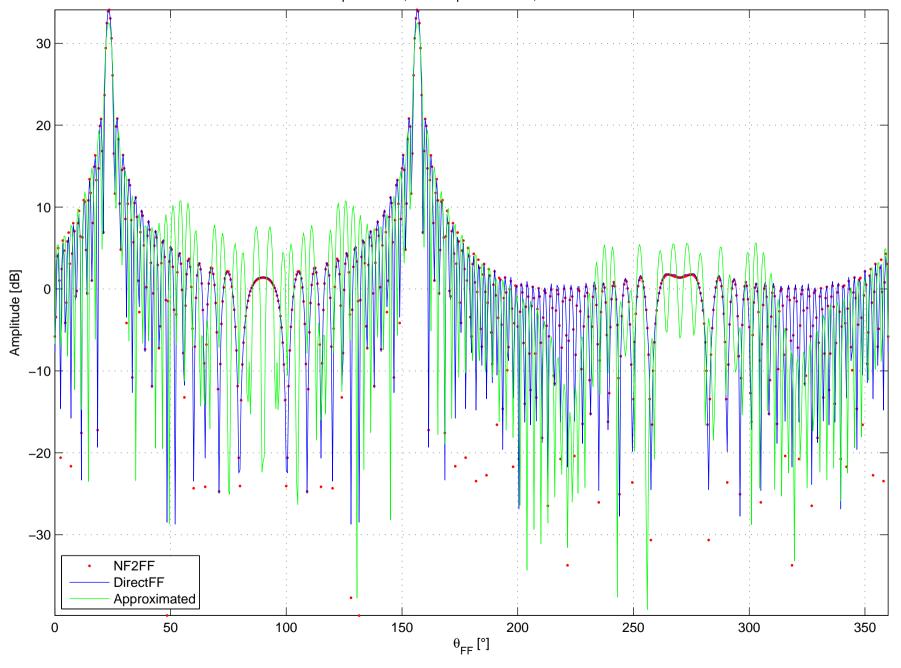
 $51 \times 0.5 \lambda, \ Rad: 13 \lambda$   $Steering \ angle: 23.3251^{\circ}, \ L^{2} \ error = 0.32365$   $FFSamples = 721, \ NFSamples = 16200, \ Coefficients = 127$ 



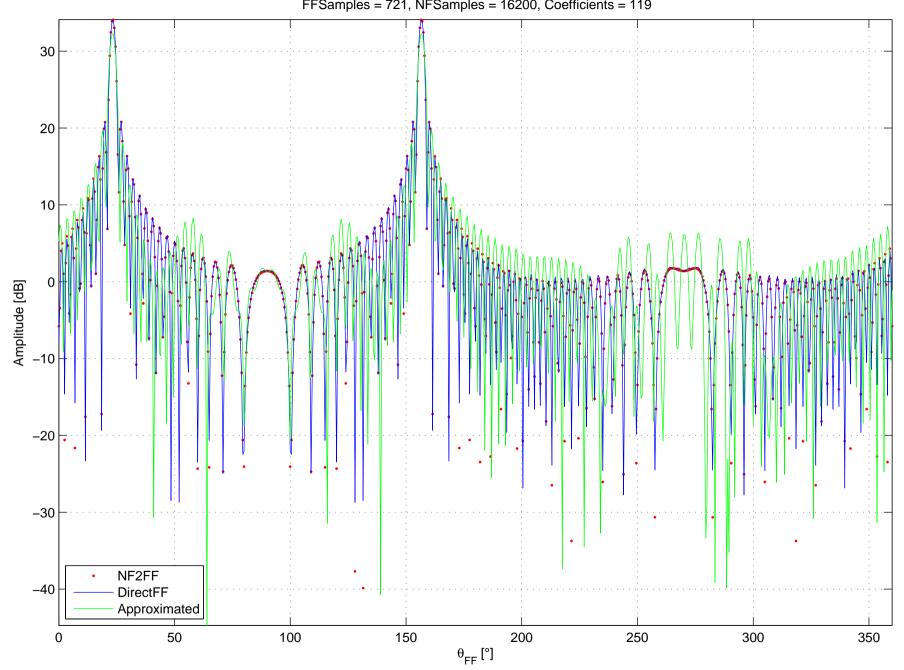


 $51 \times 0.5 \lambda, \, Rad: 13 \lambda$   $Steering \, angle: 23.3251^{\circ}, \, L^2 \, error = 0.39472$   $FFSamples = 721, \, NFSamples = 16200, \, Coefficients = 123$ 

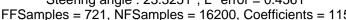


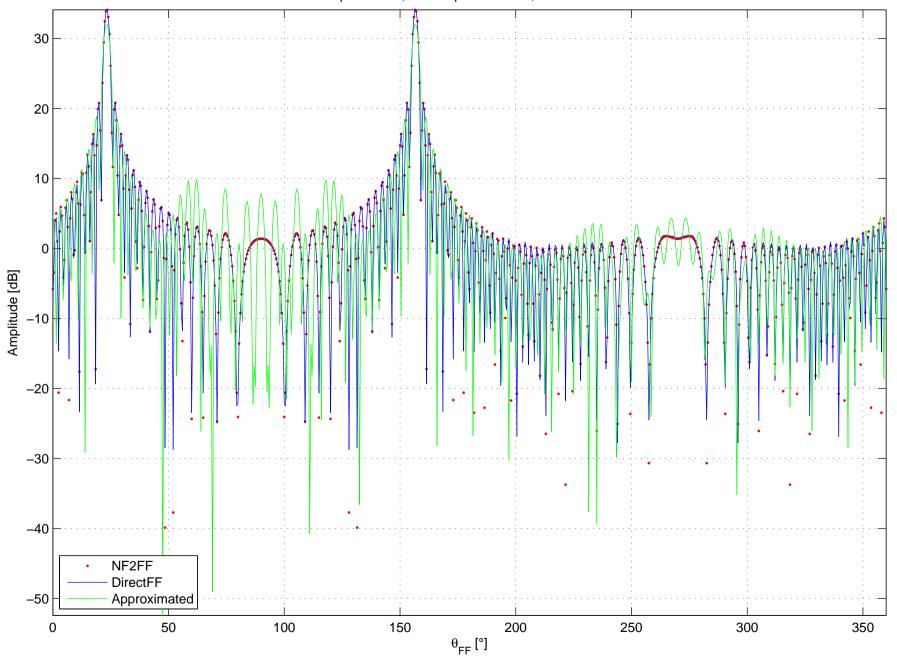


 $51 \times 0.5 \lambda, \ Rad: 13 \lambda$   $Steering \ angle: 23.3251^{\circ}, \ L^{2} \ error = 0.42884$   $FFSamples = 721, \ NFSamples = 16200, \ Coefficients = 119$ 

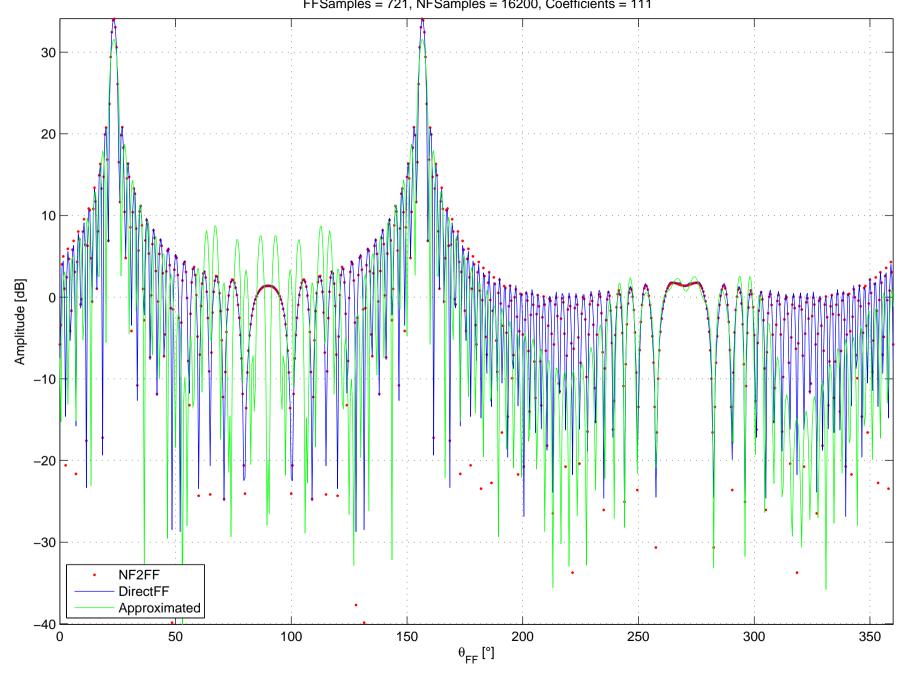


 $51 \times 0.5\lambda$ , Rad :  $13\lambda$ Steering angle :  $23.3251^\circ$ , L<sup>2</sup> error = 0.4561FFSamples = 721, NFSamples = 16200, Coefficients = 115

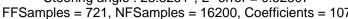


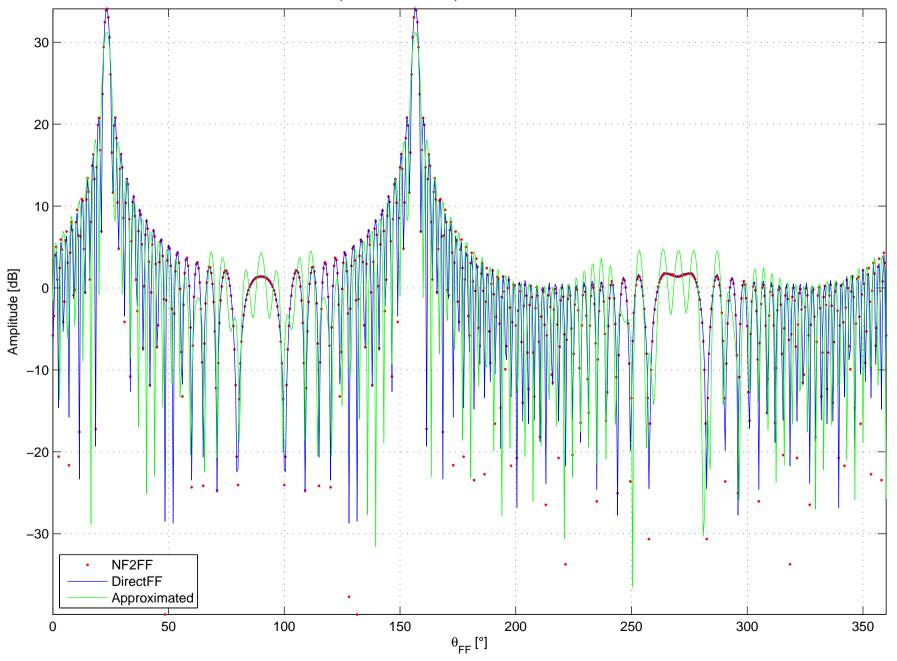


 $51 \times 0.5 \lambda$ , Rad :  $13 \lambda$ Steering angle :  $23.3251^\circ$ , L<sup>2</sup> error = 0.50494FFSamples = 721, NFSamples = 16200, Coefficients = 111

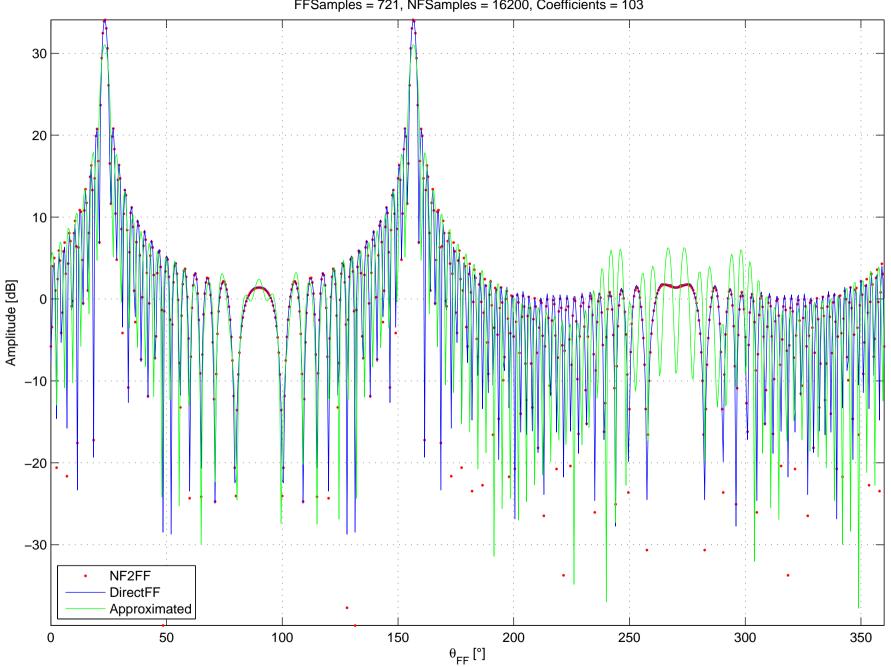


 $51 \times 0.5 \lambda, \ Rad: 13 \lambda$   $Steering \ angle: 23.3251^{\circ}, \ L^{2} \ error = 0.52807$   $FFSamples = 721, \ NFSamples = 16200, \ Coefficients = 107$ 

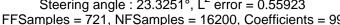


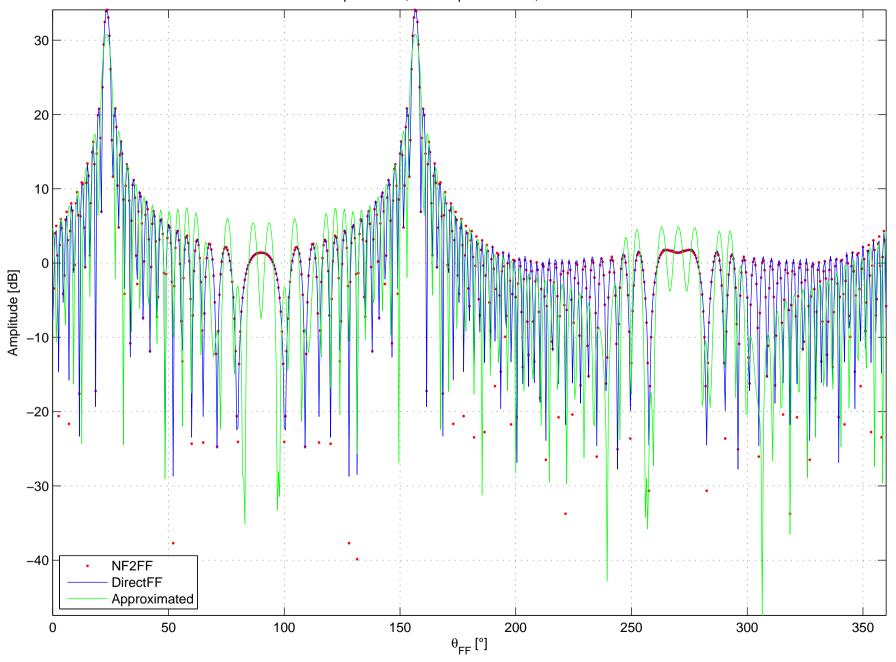


 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.54109$  FFSamples = 721, NFSamples = 16200, Coefficients = 103

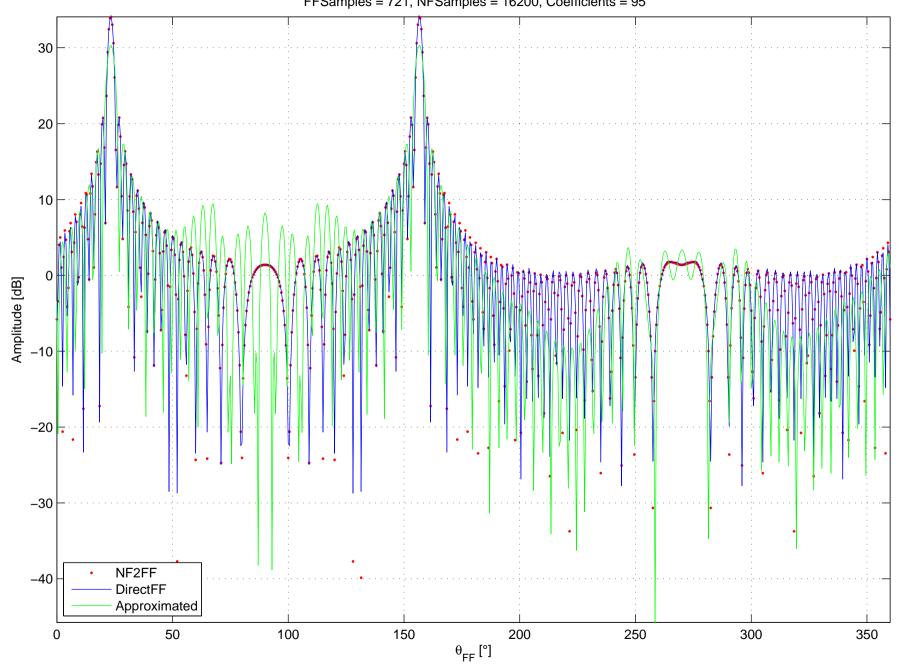


 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.55923$  FFSamples = 721, NFSamples = 16200, Coefficients = 99

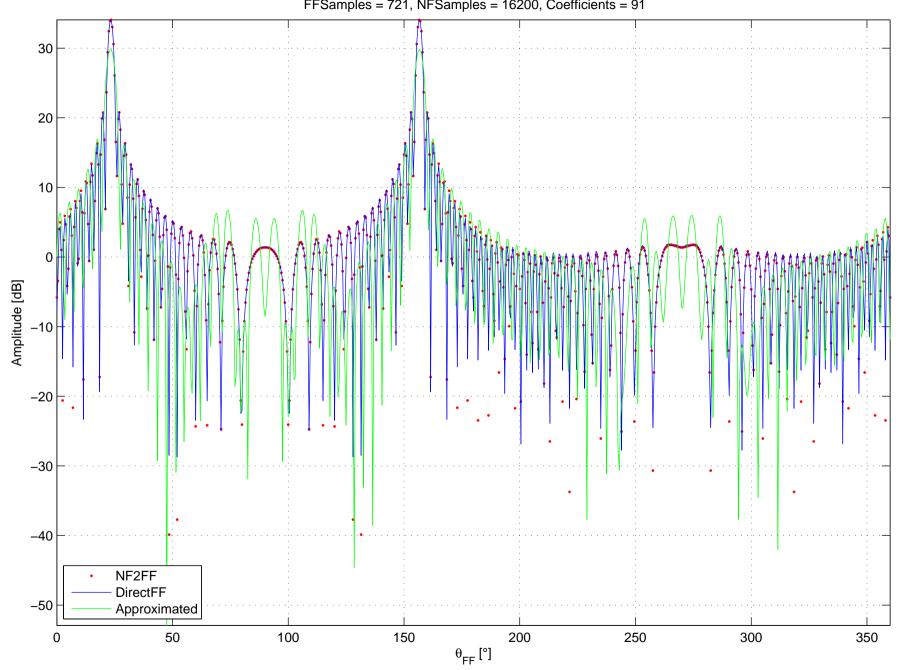




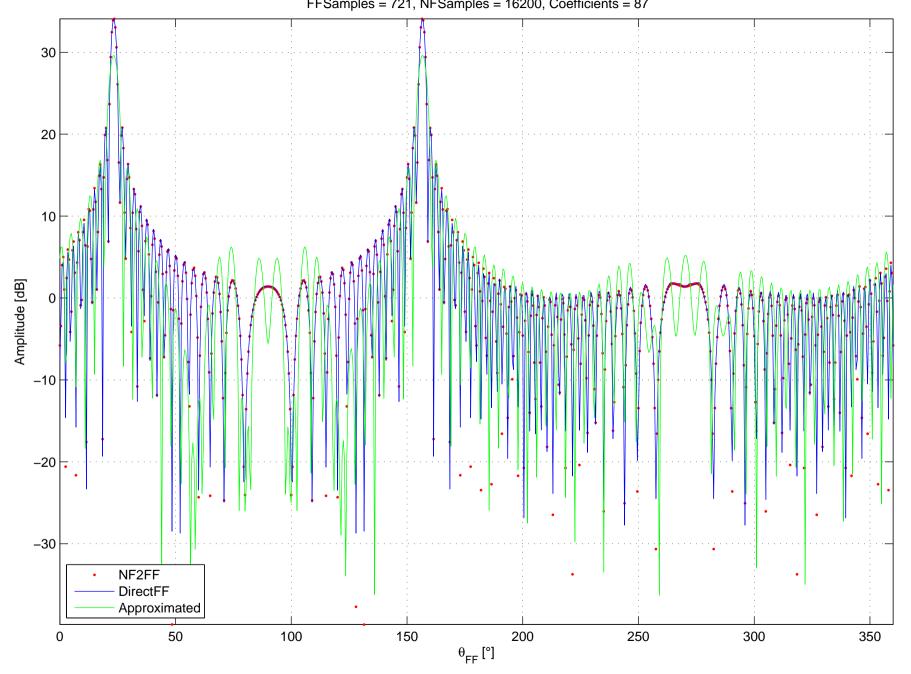
 $51 \times 0.5\lambda, \, Rad: 13\lambda$   $Steering \, angle: 23.3251^{\circ}, \, L^2 \, error = 0.5885$   $FFSamples = 721, \, NFSamples = 16200, \, Coefficients = 95$ 



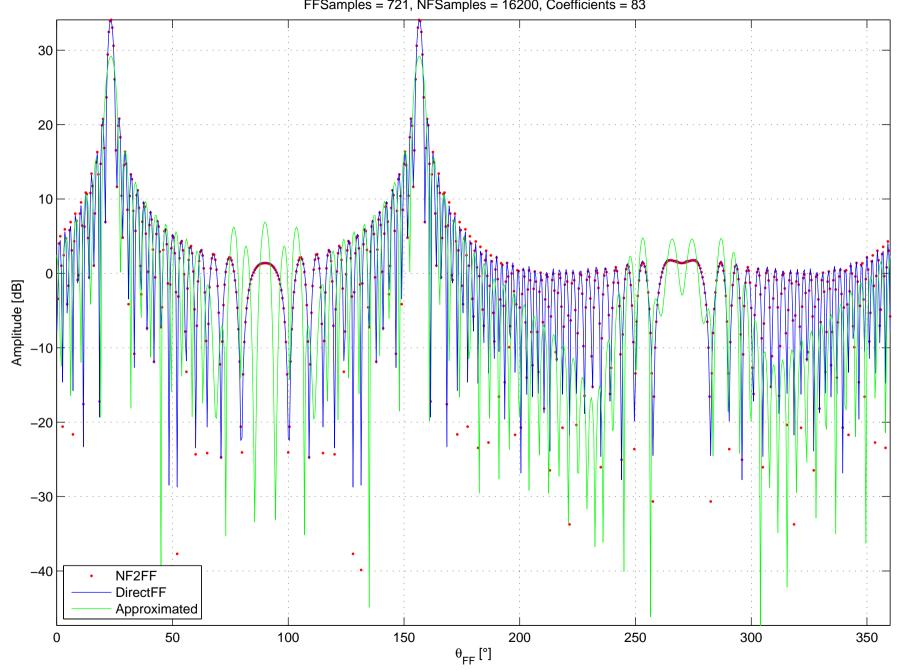
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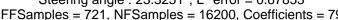
 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.63462$  FFSamples = 721, NFSamples = 16200, Coefficients = 87

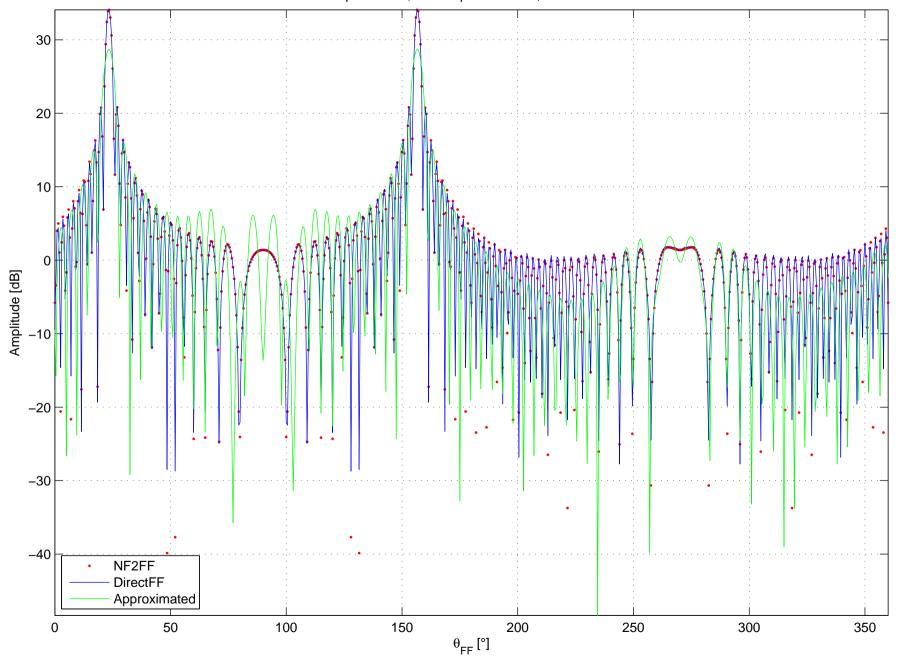


 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.65695$  FFSamples = 721, NFSamples = 16200, Coefficients = 83

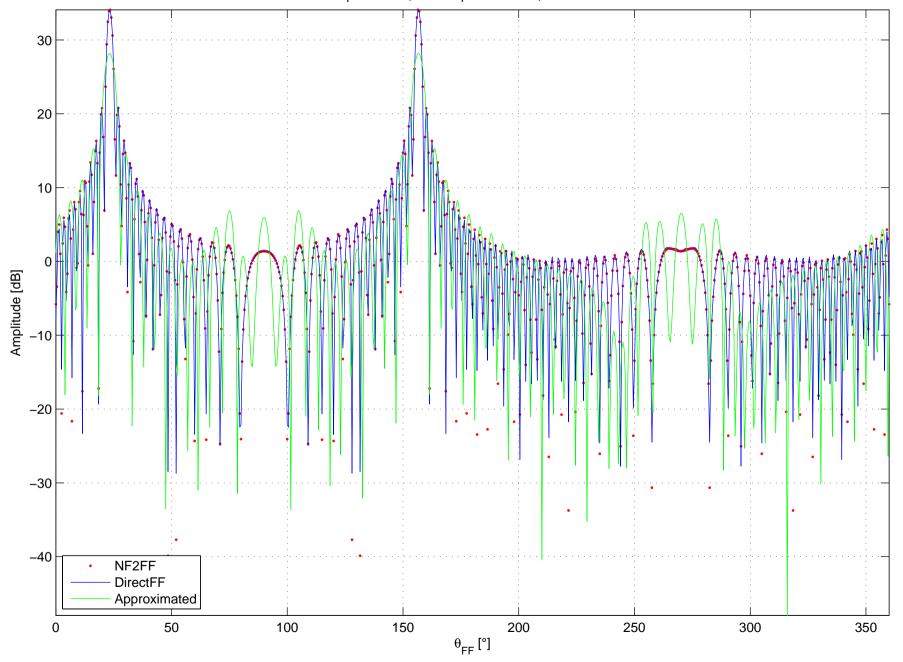


 $51 \times 0.5\lambda$ , Rad :  $13\lambda$ Steering angle :  $23.3251^\circ$ , L<sup>2</sup> error = 0.67853FFSamples = 721, NFSamples = 16200, Coefficients = 79

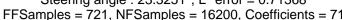


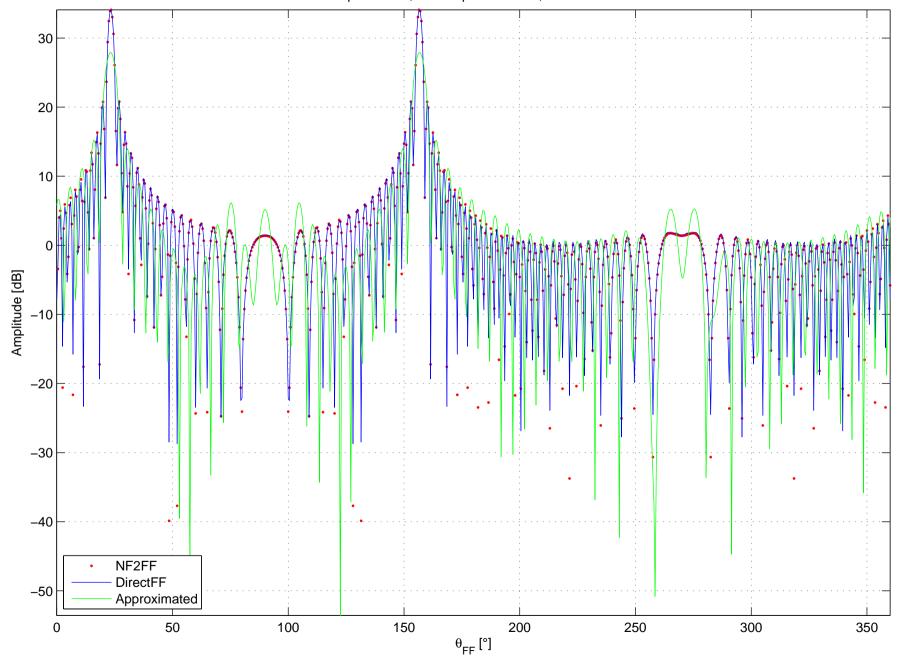


 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.70158$  FFSamples = 721, NFSamples = 16200, Coefficients = 75

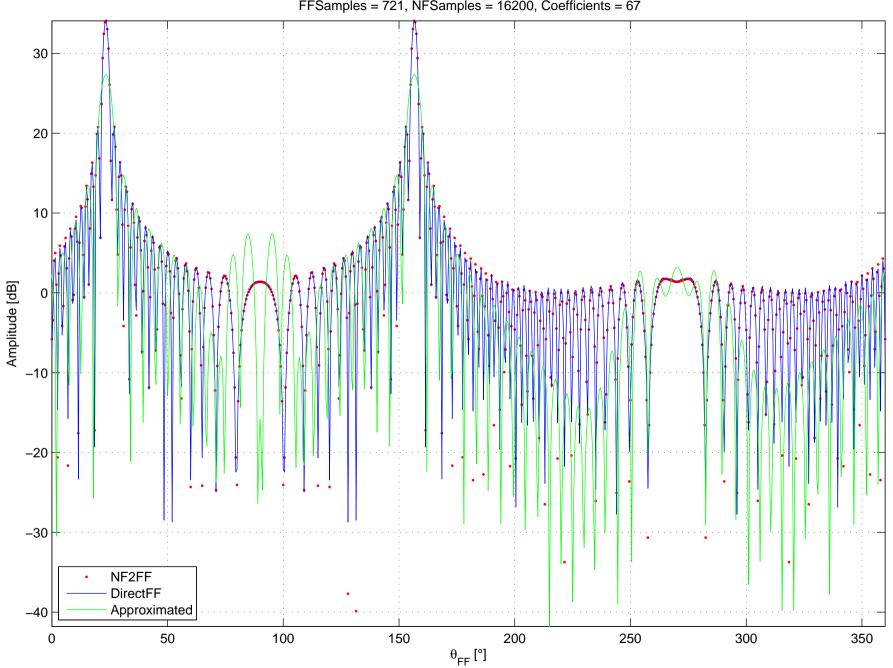


 $51 \times 0.5\lambda$ , Rad :  $13\lambda$ Steering angle :  $23.3251^\circ$ , L<sup>2</sup> error = 0.71368FFSamples = 721, NFSamples = 16200, Coefficients = 71

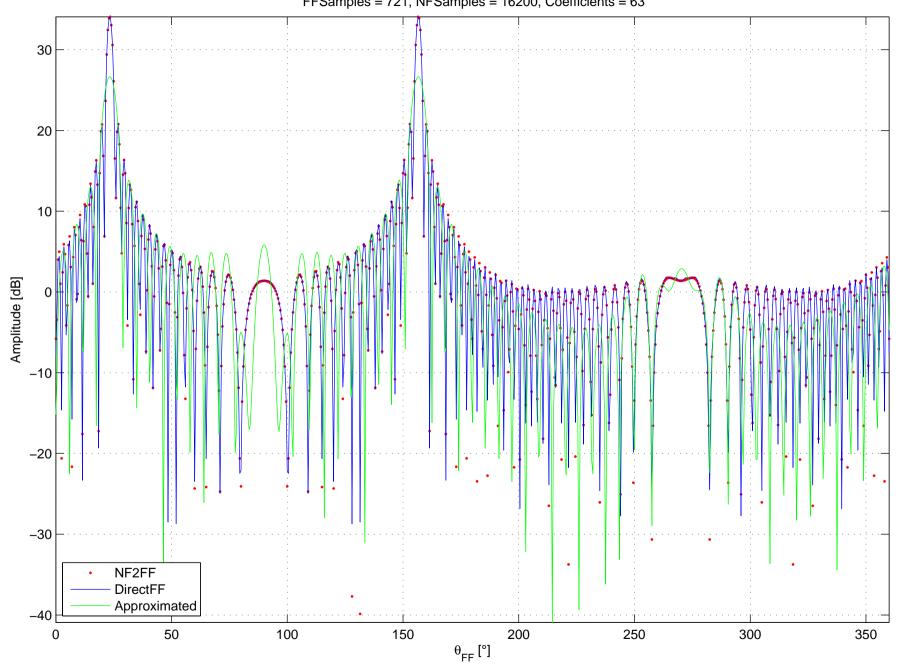


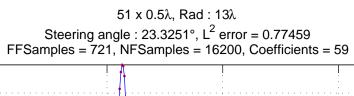


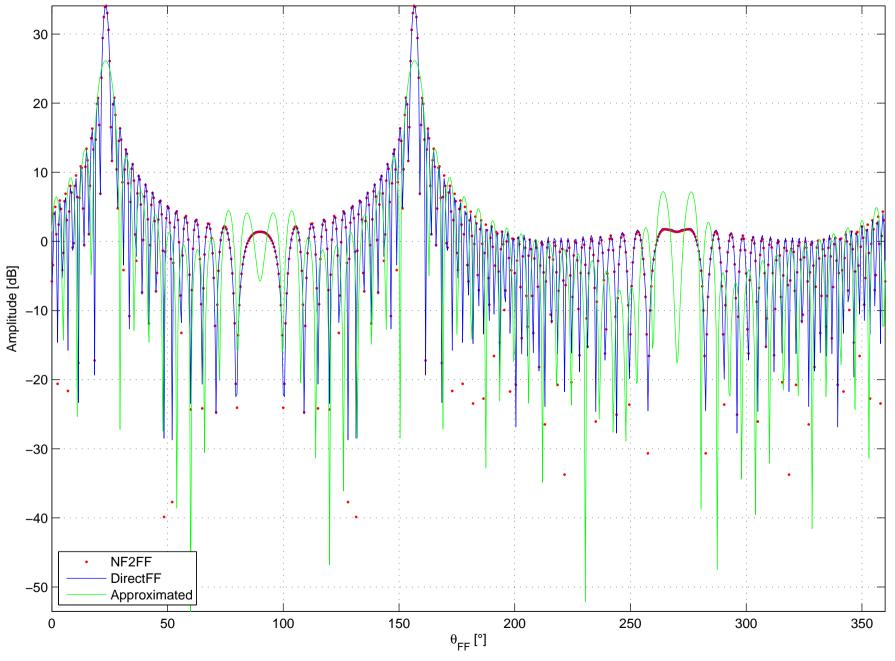
 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.73635$  FFSamples = 721, NFSamples = 16200, Coefficients = 67



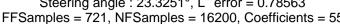
 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.7576$  FFSamples = 721, NFSamples = 16200, Coefficients = 63

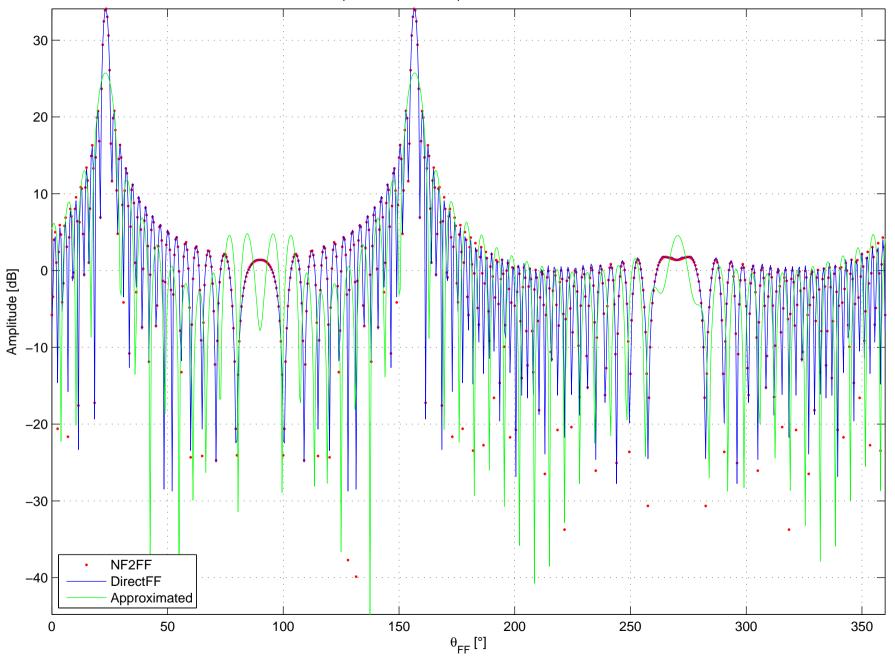




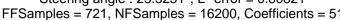


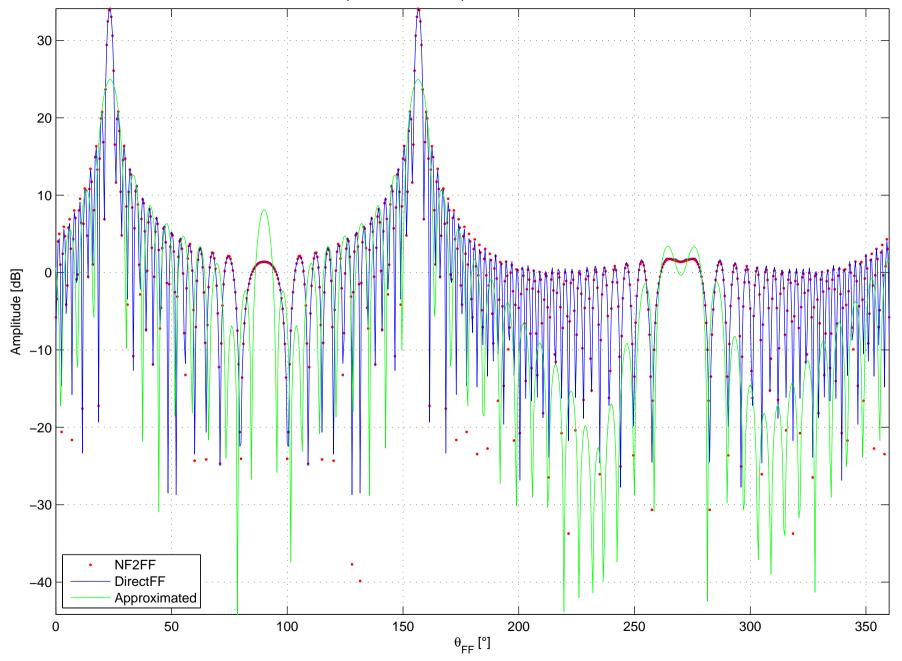
 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.78563$  FFSamples = 721, NFSamples = 16200, Coefficients = 55



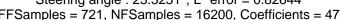


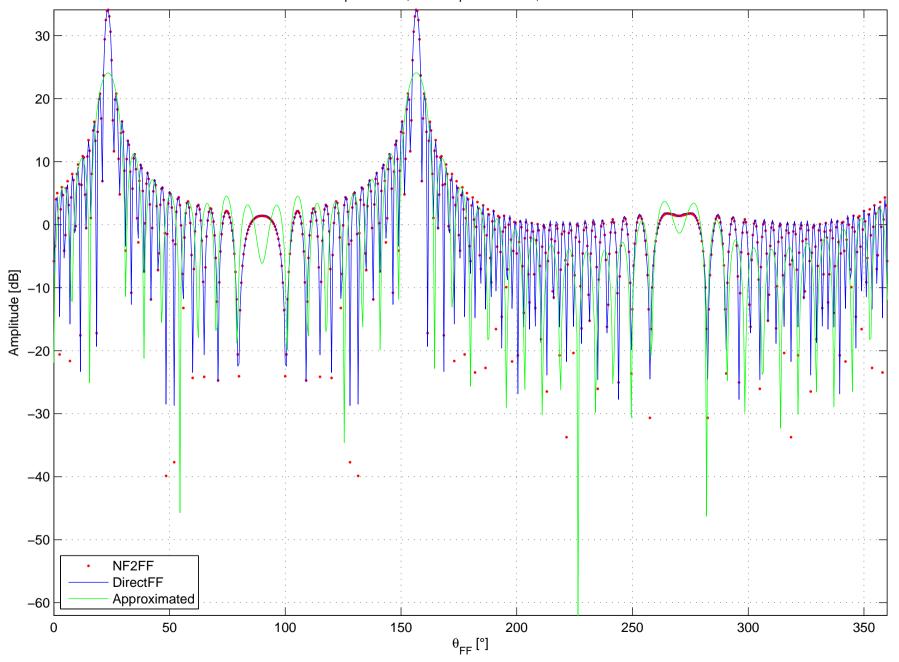
 $51 \times 0.5\lambda$ , Rad :  $13\lambda$ Steering angle :  $23.3251^\circ$ , L<sup>2</sup> error = 0.80821FFSamples = 721, NFSamples = 16200, Coefficients = 51





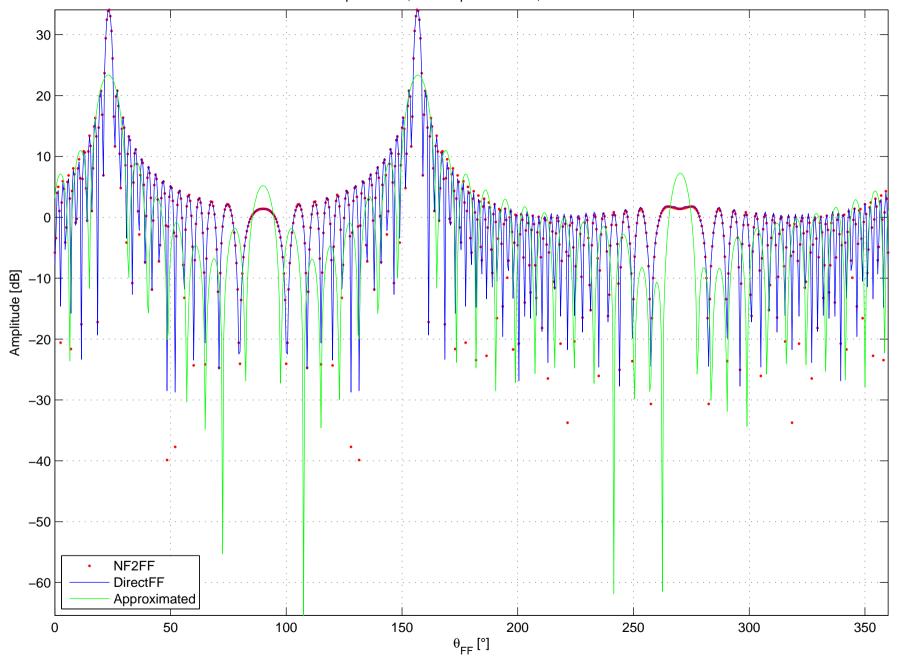
 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.82644$  FFSamples = 721, NFSamples = 16200, Coefficients = 47



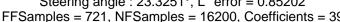


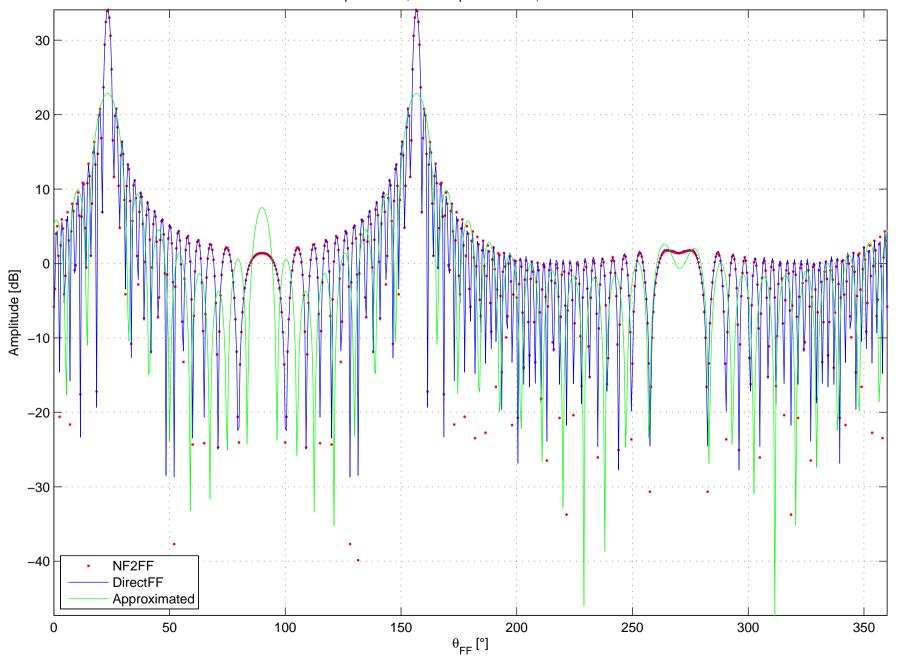
 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.84278$  FFSamples = 721, NFSamples = 16200, Coefficients = 43



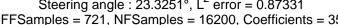


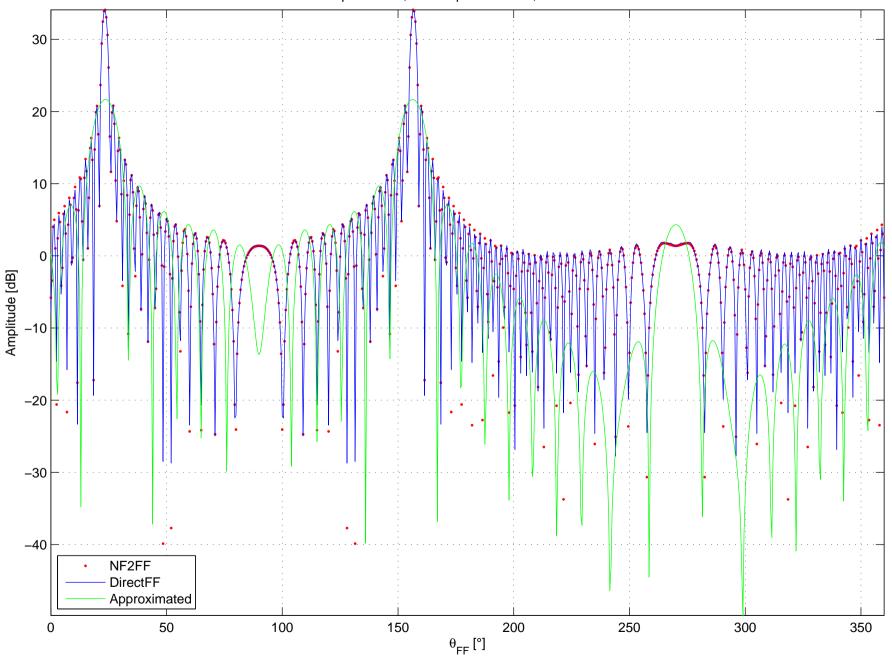
 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.85202$  FFSamples = 721, NFSamples = 16200, Coefficients = 39



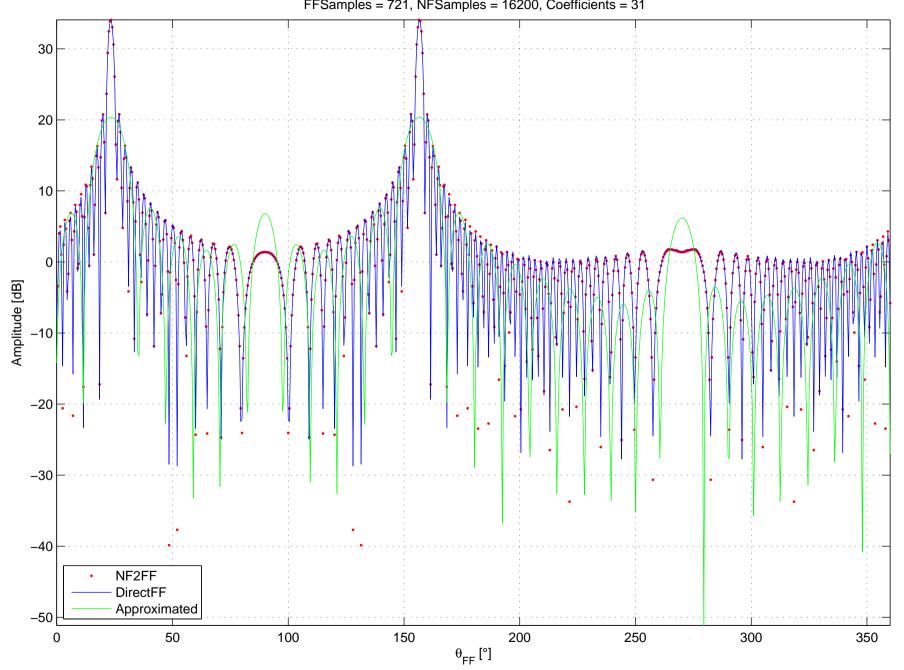


 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.87331$  FFSamples = 721, NFSamples = 16200, Coefficients = 35

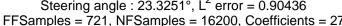


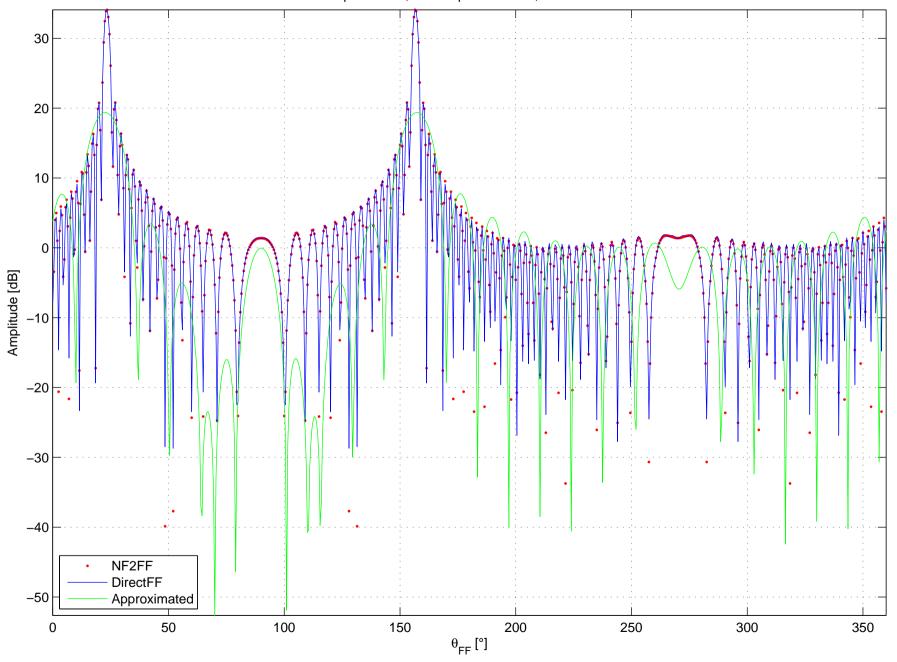


 $51 \times 0.5\lambda$ , Rad :  $13\lambda$ Steering angle :  $23.3251^\circ$ , L<sup>2</sup> error = 0.88958FFSamples = 721, NFSamples = 16200, Coefficients = 31

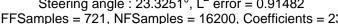


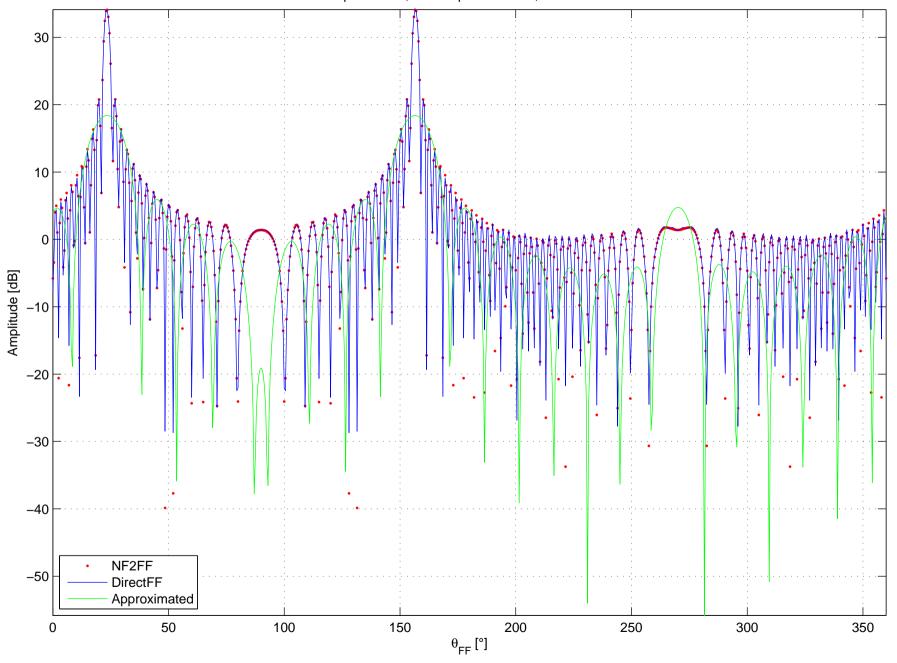
 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.90436$  FFSamples = 721, NFSamples = 16200, Coefficients = 27



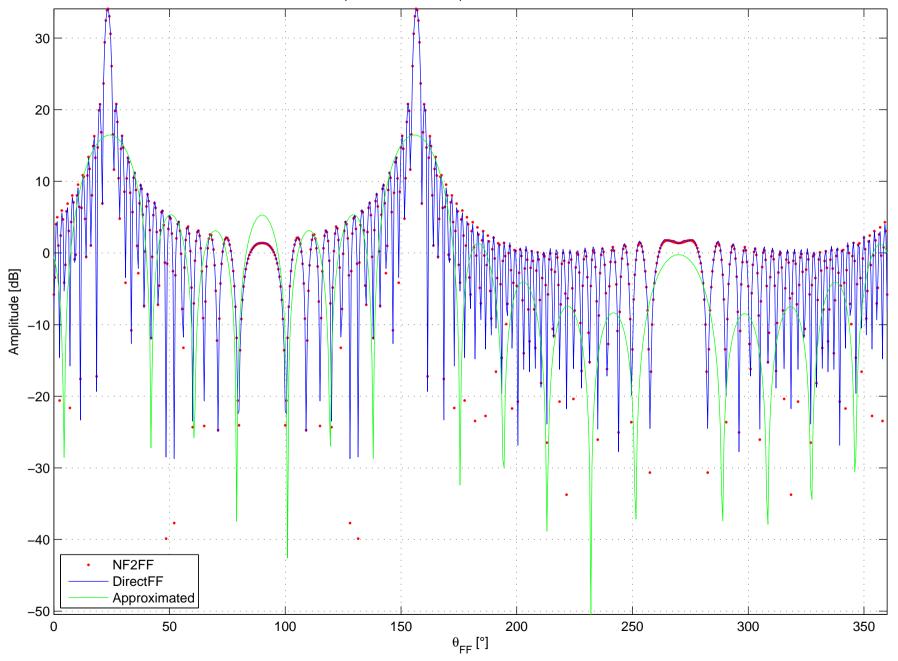


 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.91482$  FFSamples = 721, NFSamples = 16200, Coefficients = 23

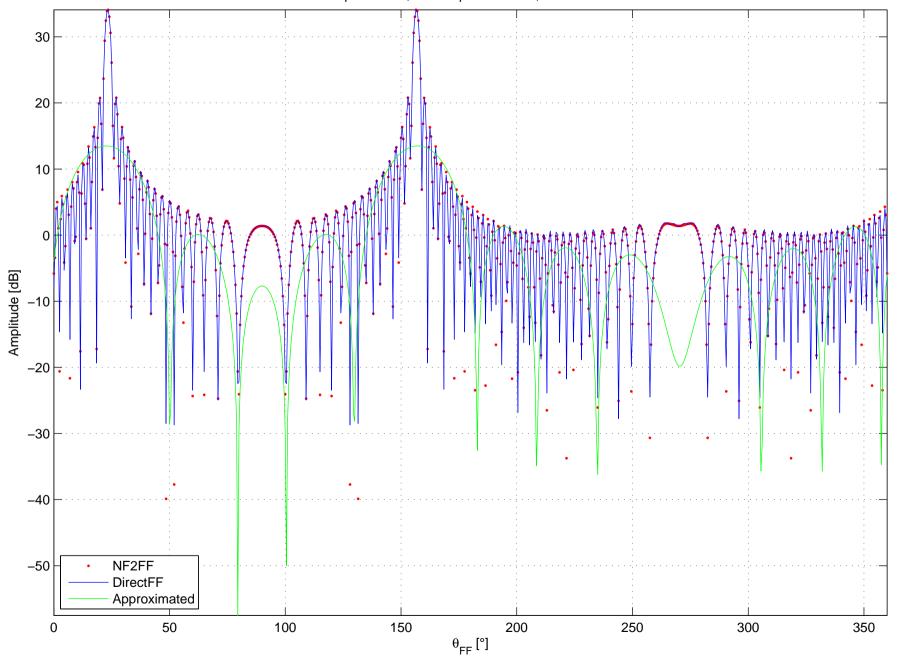




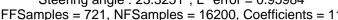
 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.93146$  FFSamples = 721, NFSamples = 16200, Coefficients = 19

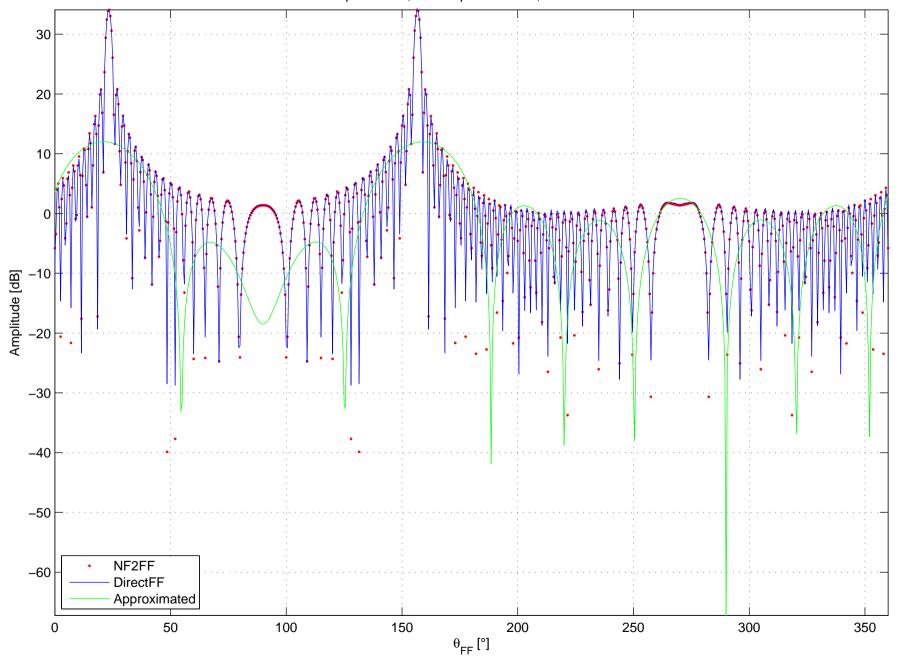


 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.95319$  FFSamples = 721, NFSamples = 16200, Coefficients = 15

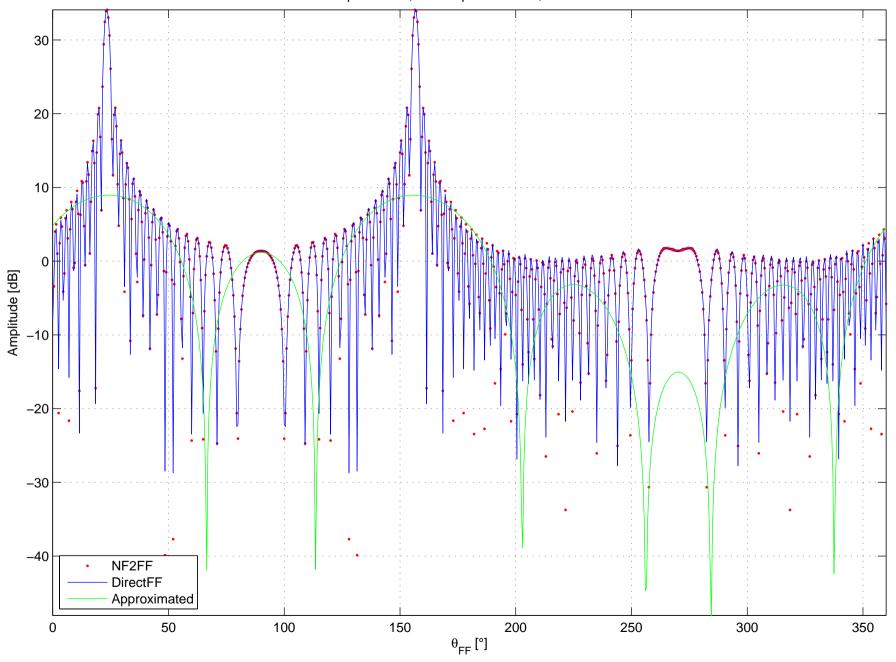


 $51 \times 0.5\lambda$ , Rad :  $13\lambda$ Steering angle :  $23.3251^\circ$ , L<sup>2</sup> error = 0.95984FFSamples = 721, NFSamples = 16200, Coefficients = 11

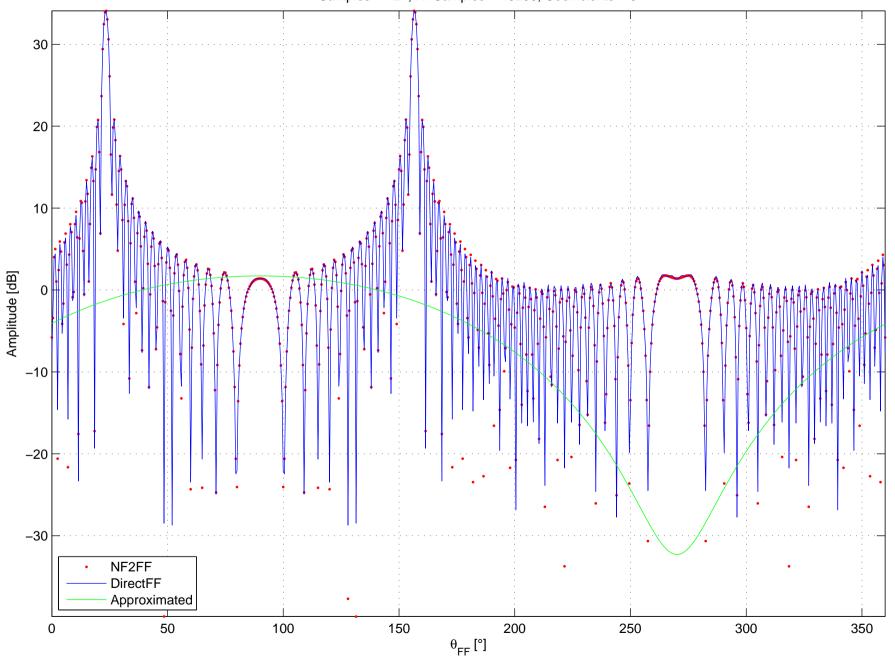




 $51 \times 0.5 \lambda, \ Rad: 13 \lambda$   $Steering \ angle: 23.3251^{\circ}, \ L^{2} \ error = 0.97201$   $FFSamples = 721, \ NFSamples = 16200, \ Coefficients = 7$ 



 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.99205$  FFSamples = 721, NFSamples = 16200, Coefficients = 3



 $51 \text{ x } 0.5\lambda, \text{ Rad : } 13\lambda$   $\text{Steering angle : } 23.3251^{\circ}, \text{ L}^2 \text{ error = } 0.99205$  FFSamples = 721, NFSamples = 16200, Coefficients = 3

