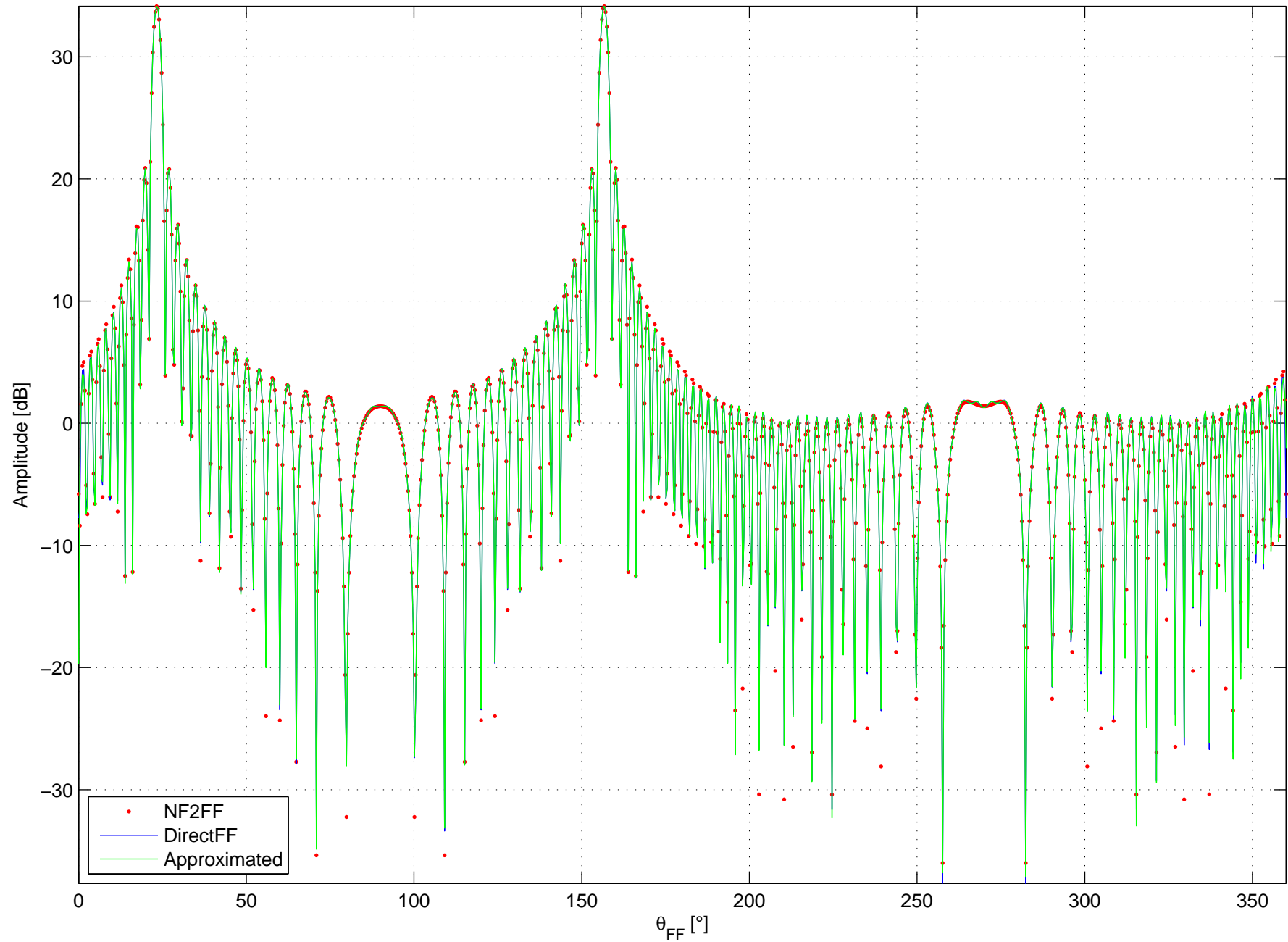
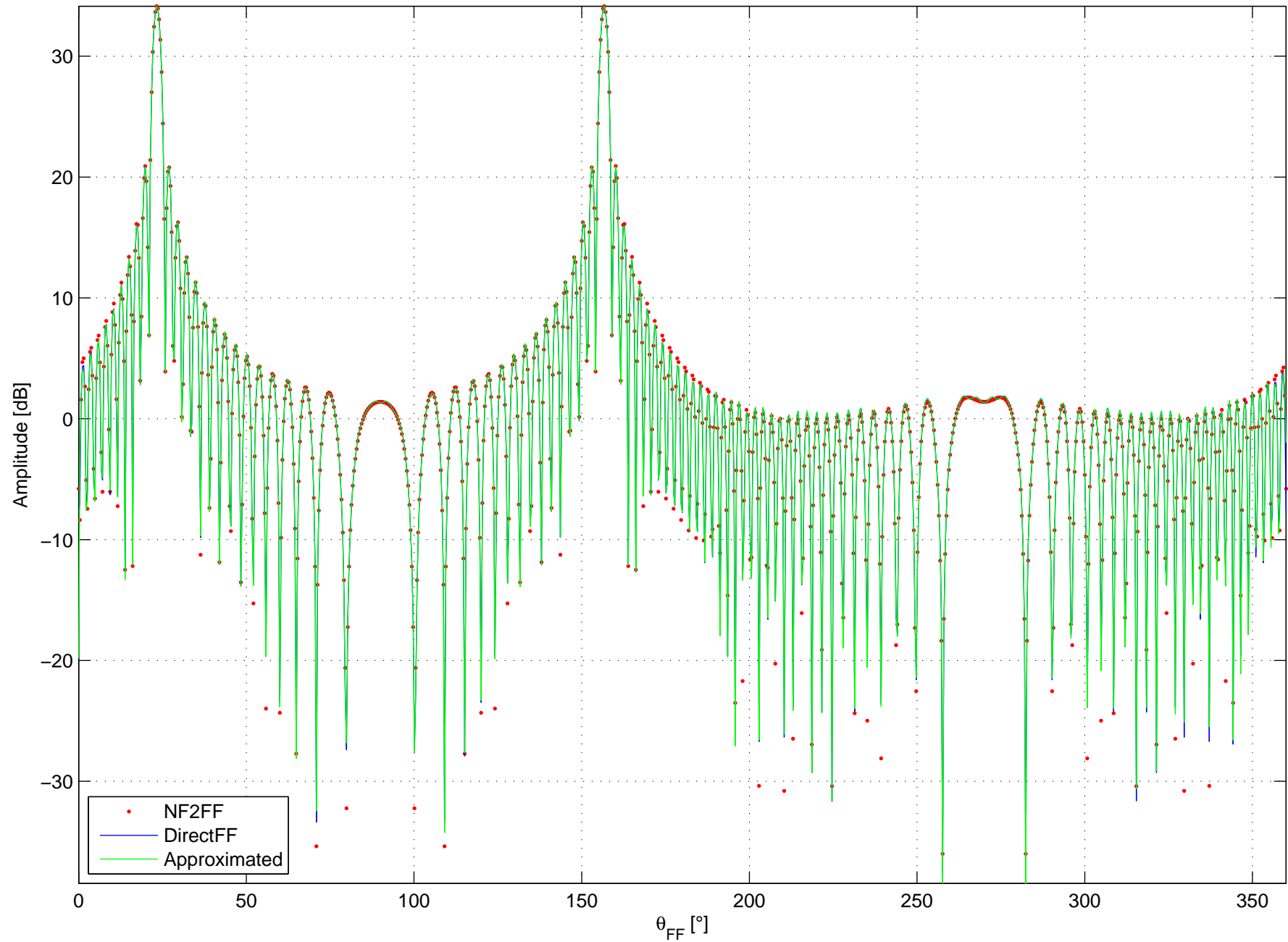


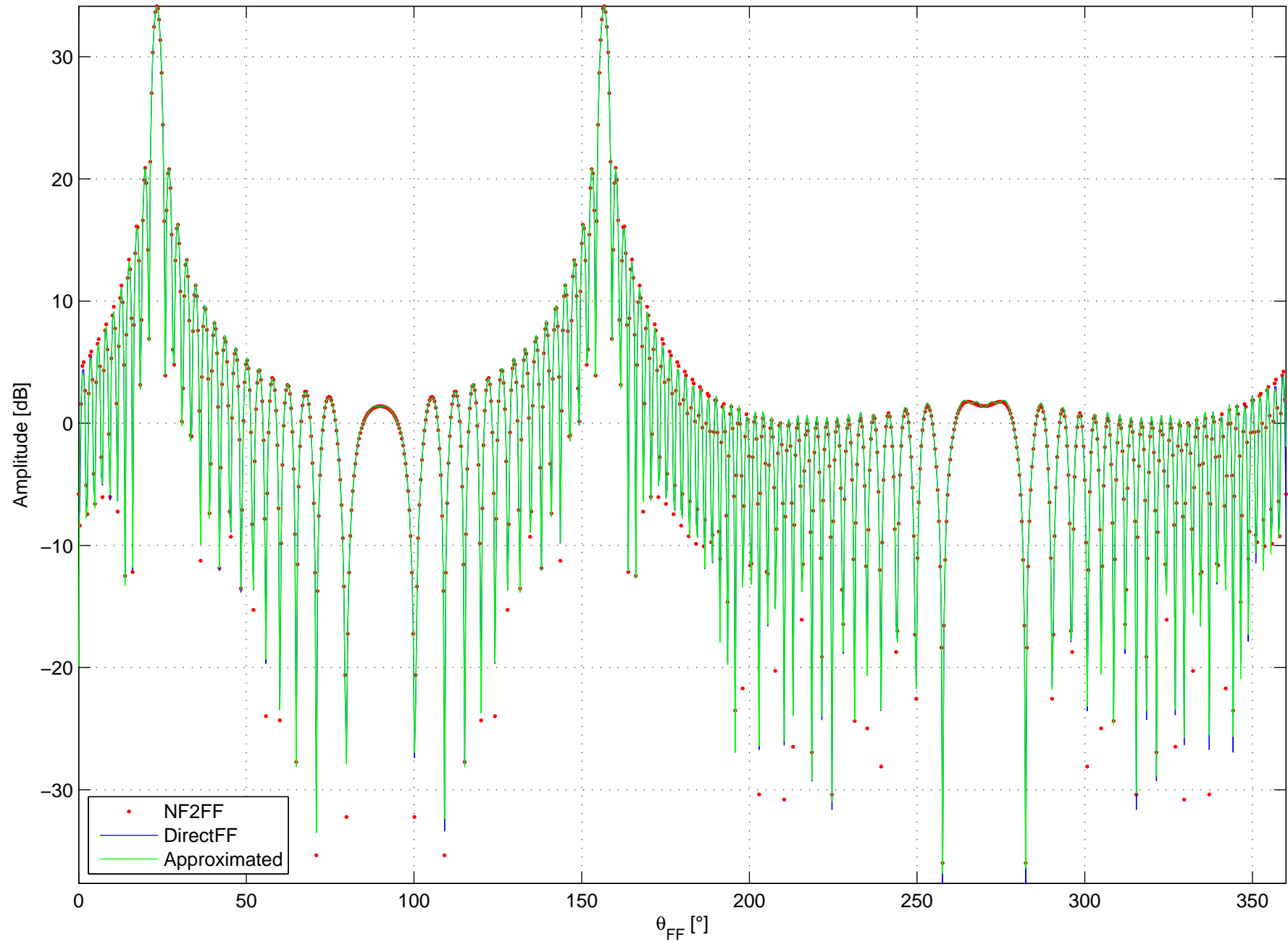
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.0034331
FFSamples = 961, NFSamples = 16200, Coefficients = 239



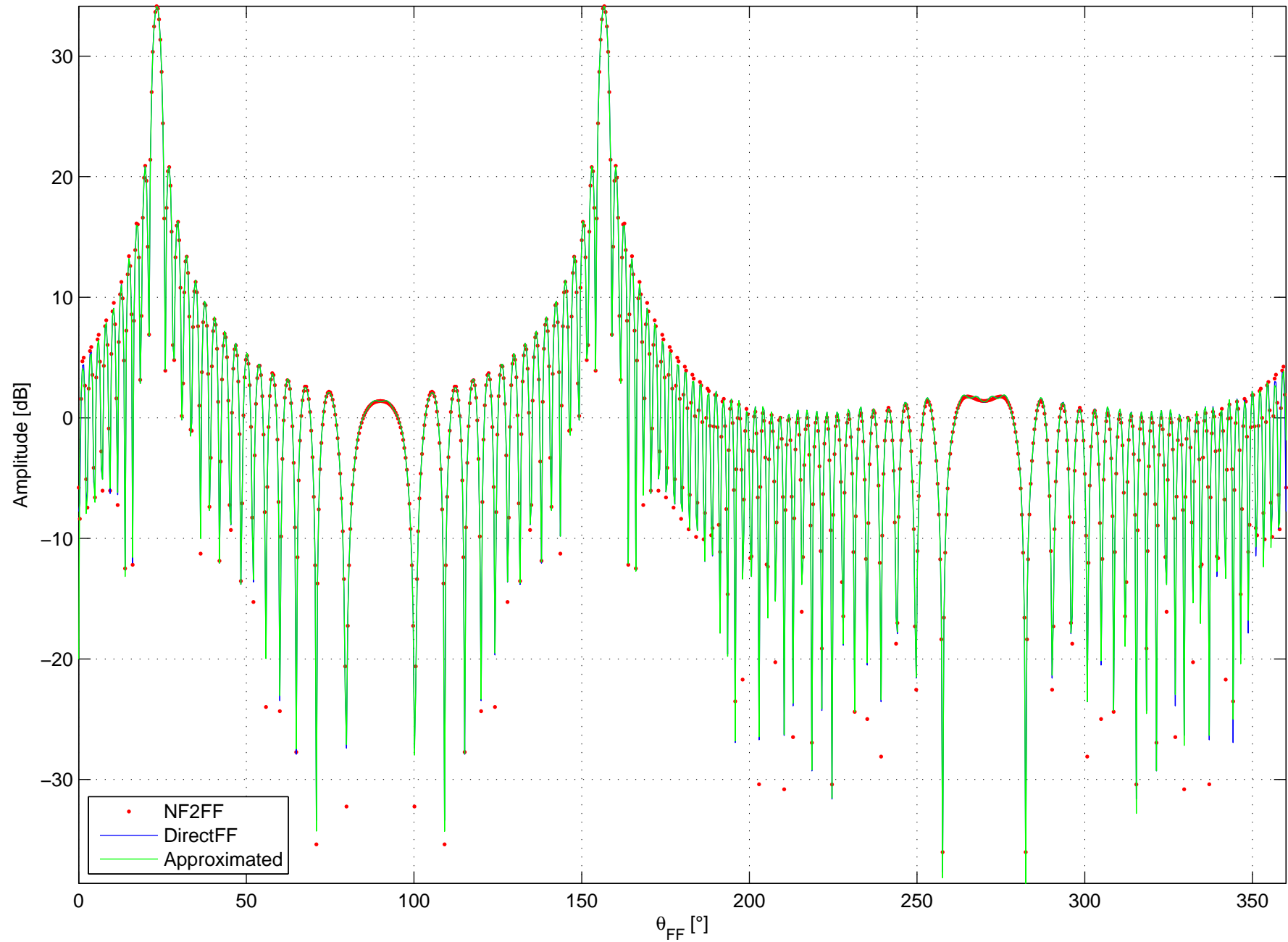
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.003501
FFSamples = 961, NFSamples = 16200, Coefficients = 235



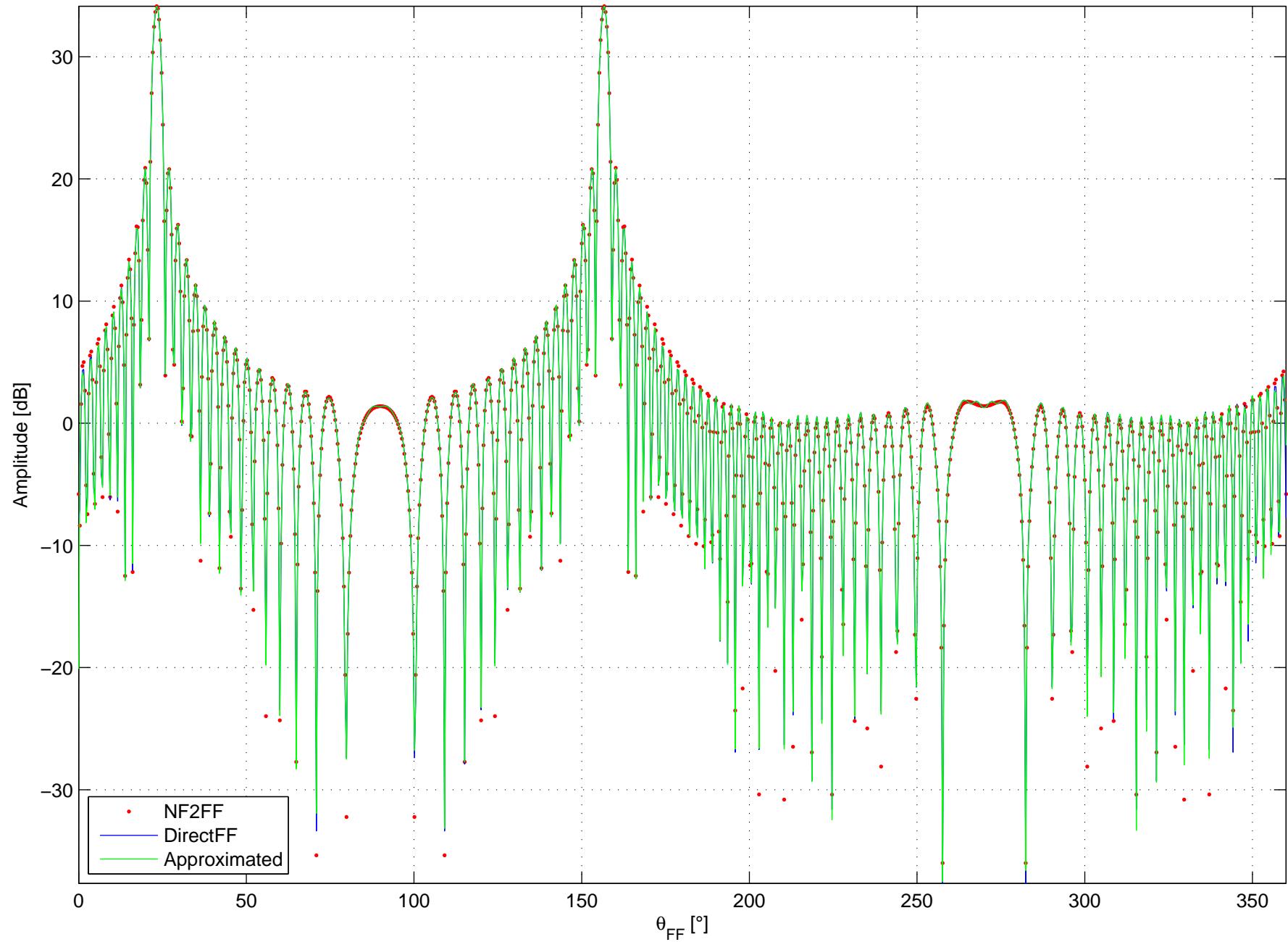
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.0035737
FFSamples = 961, NFSamples = 16200, Coefficients = 231



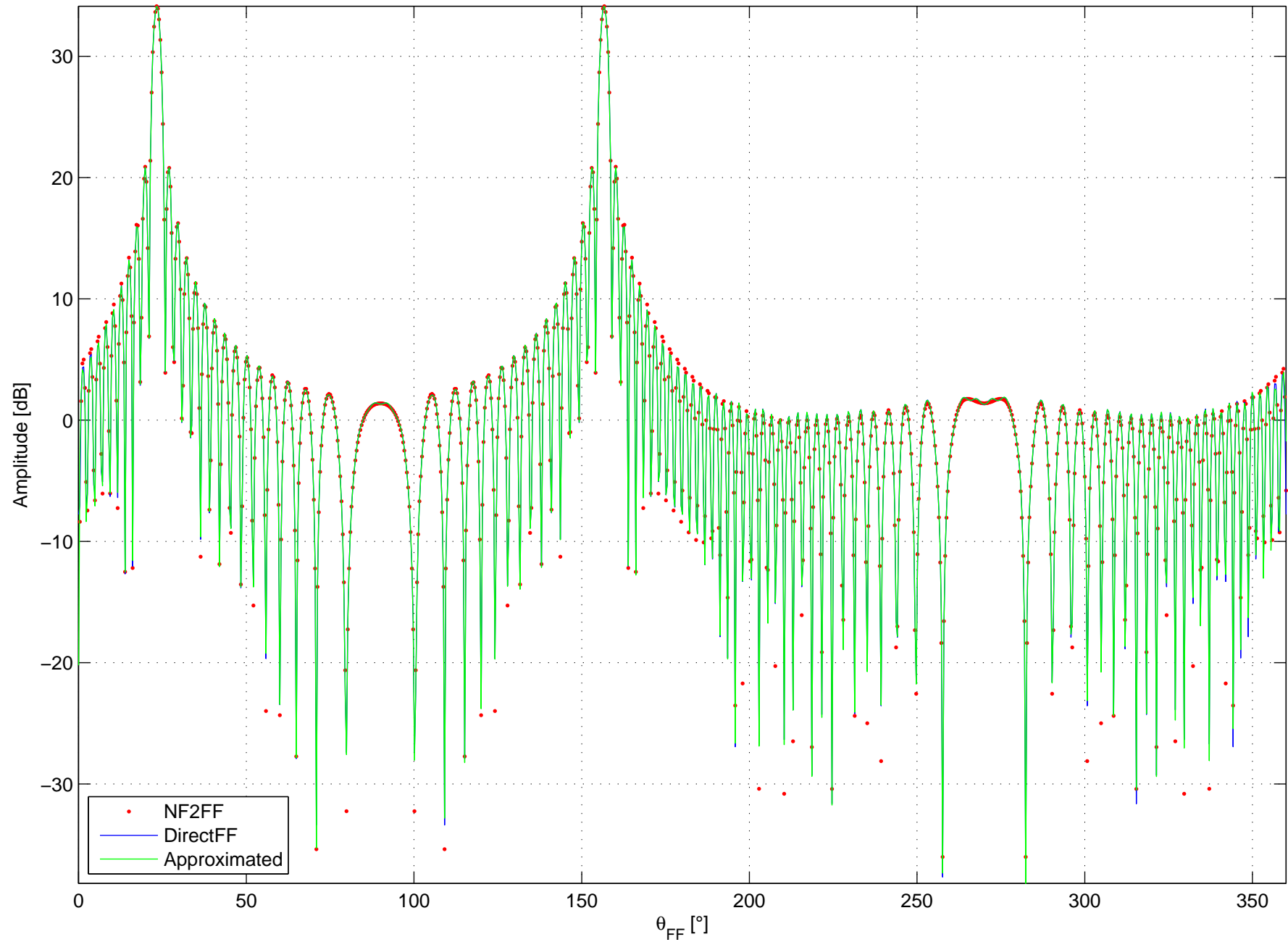
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.0036522
FFSamples = 961, NFSamples = 16200, Coefficients = 227



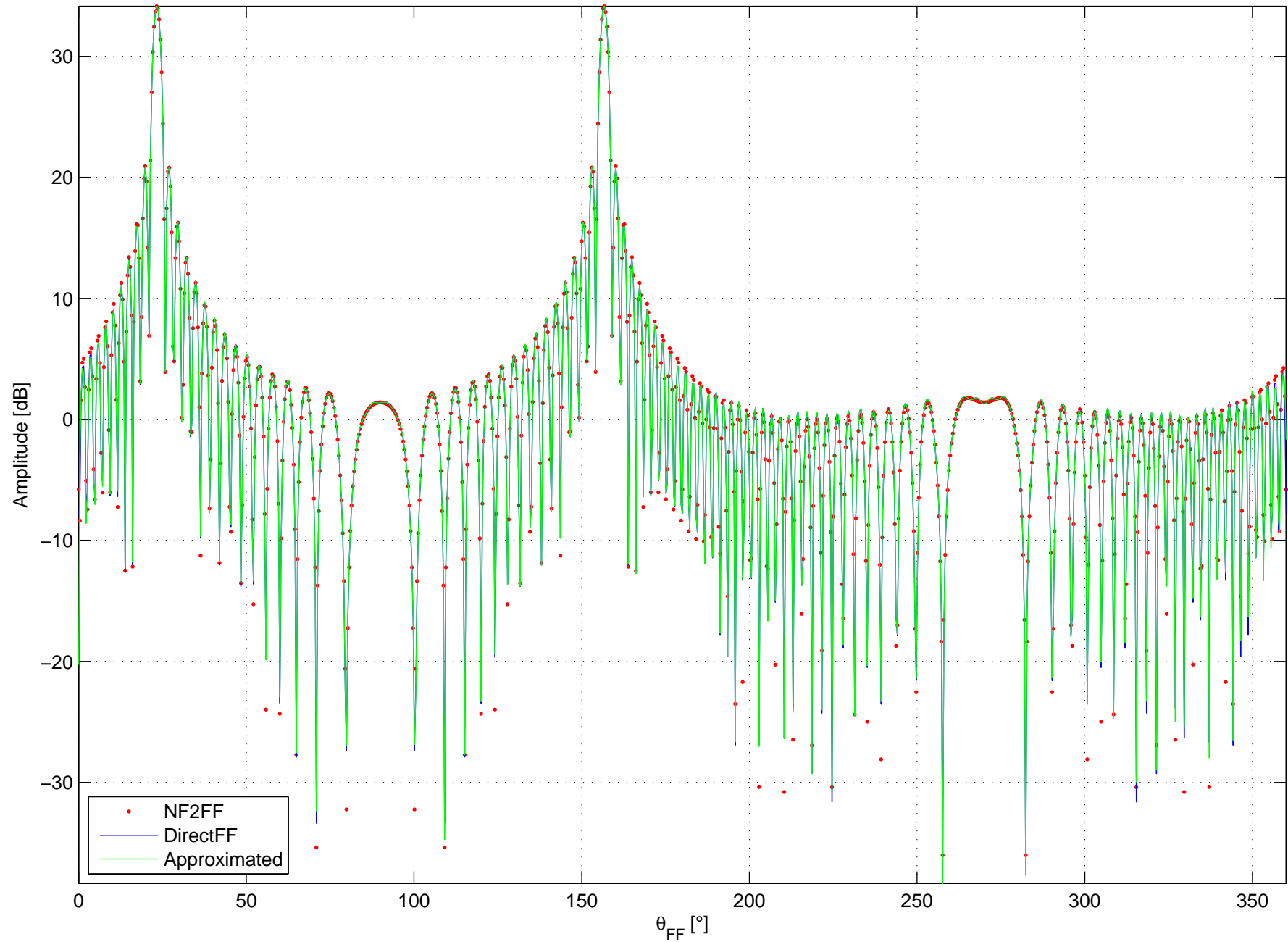
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.0037372
FFSamples = 961, NFSamples = 16200, Coefficients = 223



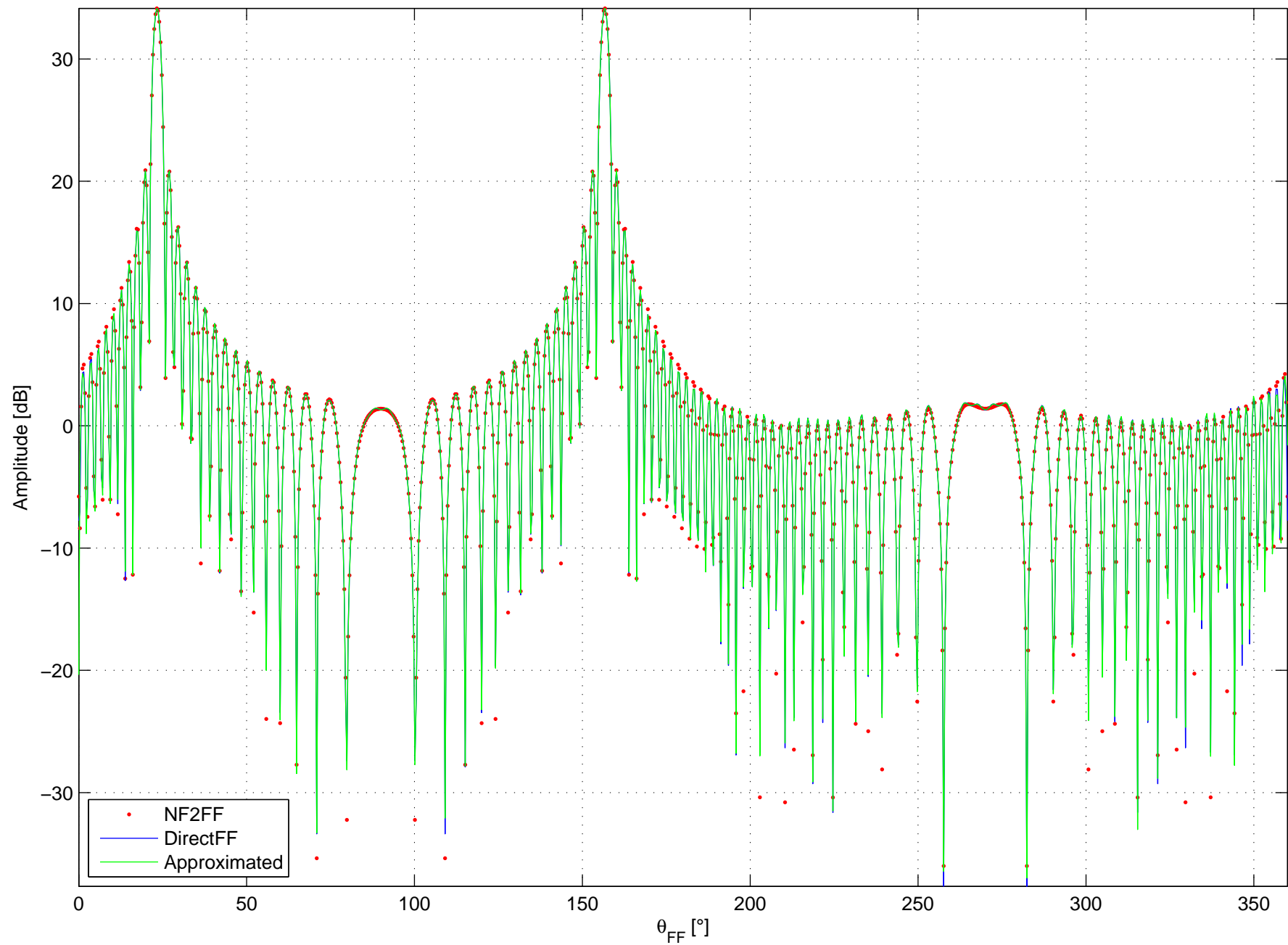
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.0038297
FFSamples = 961, NFSamples = 16200, Coefficients = 219



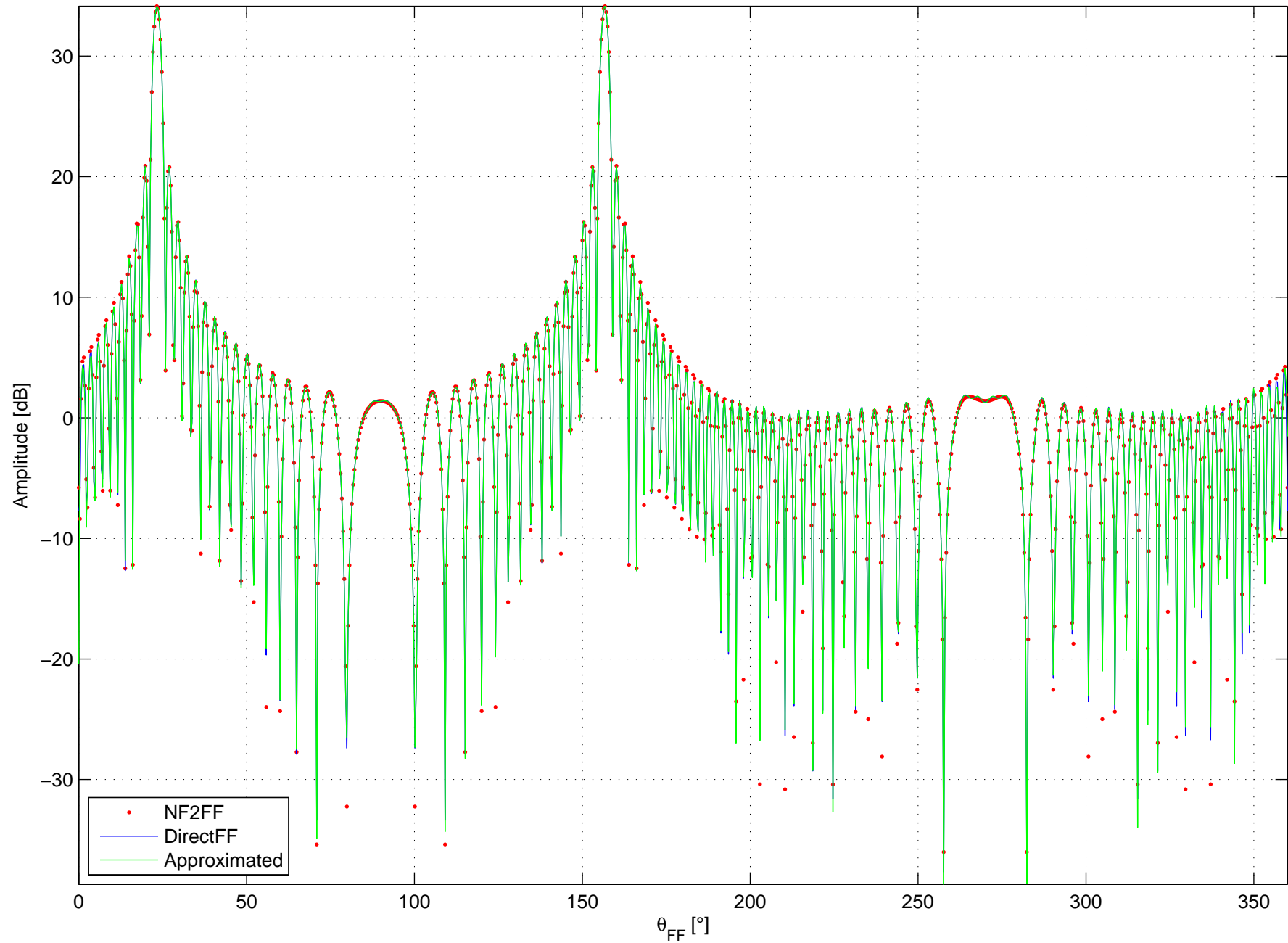
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.0039311
FFSamples = 961, NFSamples = 16200, Coefficients = 215



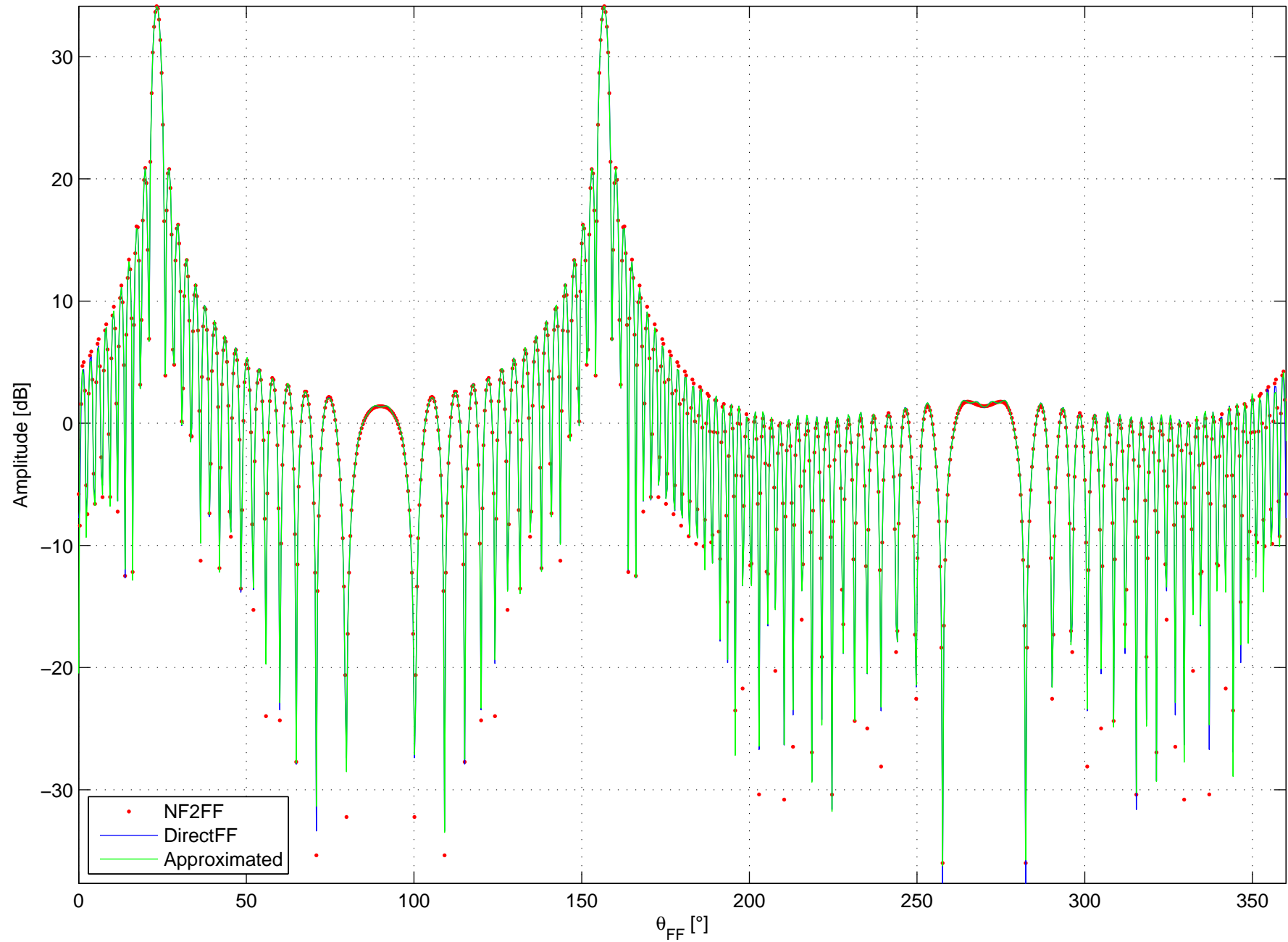
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.0040431
FFSamples = 961, NFSamples = 16200, Coefficients = 211



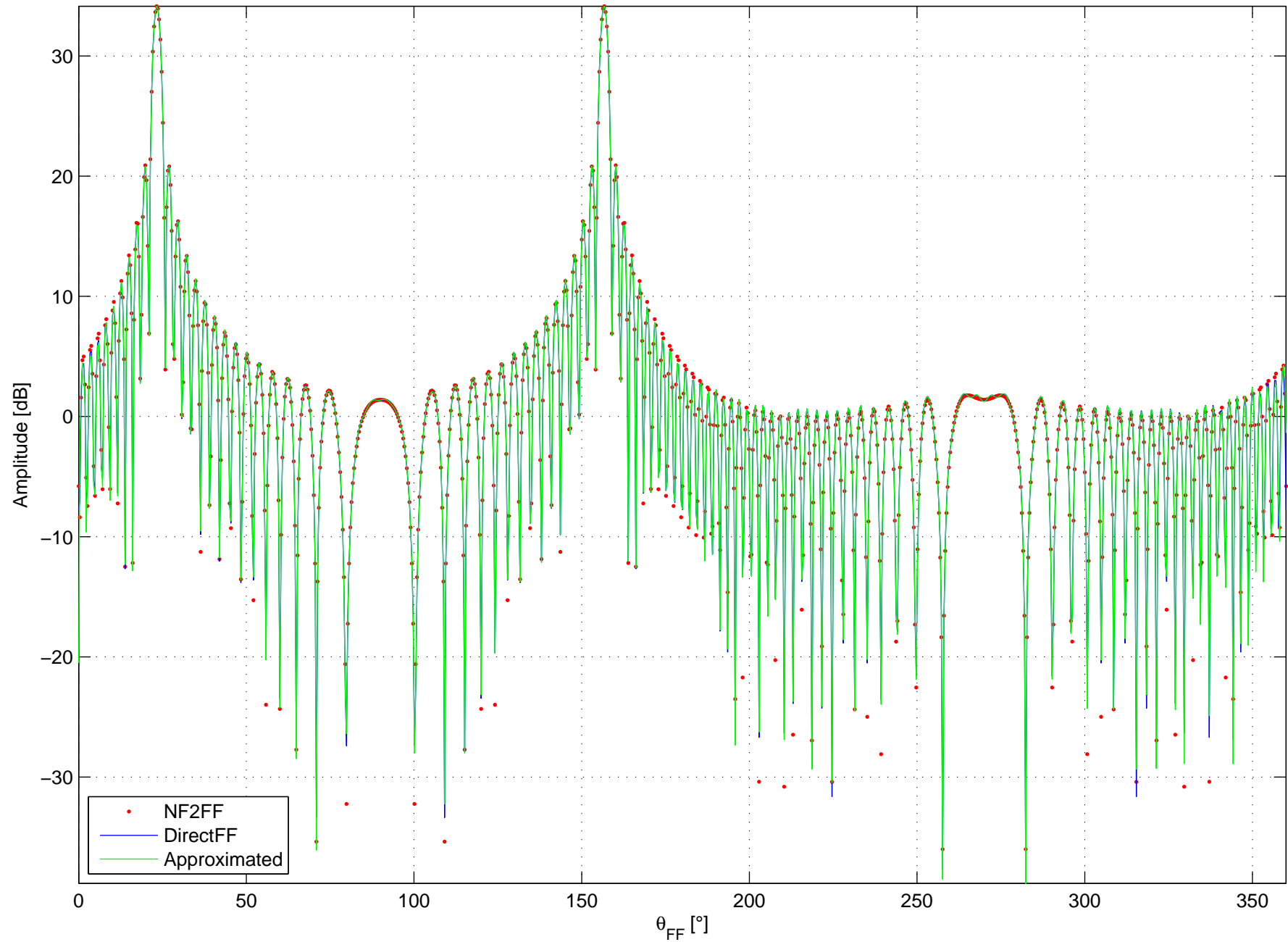
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.0041677
FFSamples = 961, NFSamples = 16200, Coefficients = 207



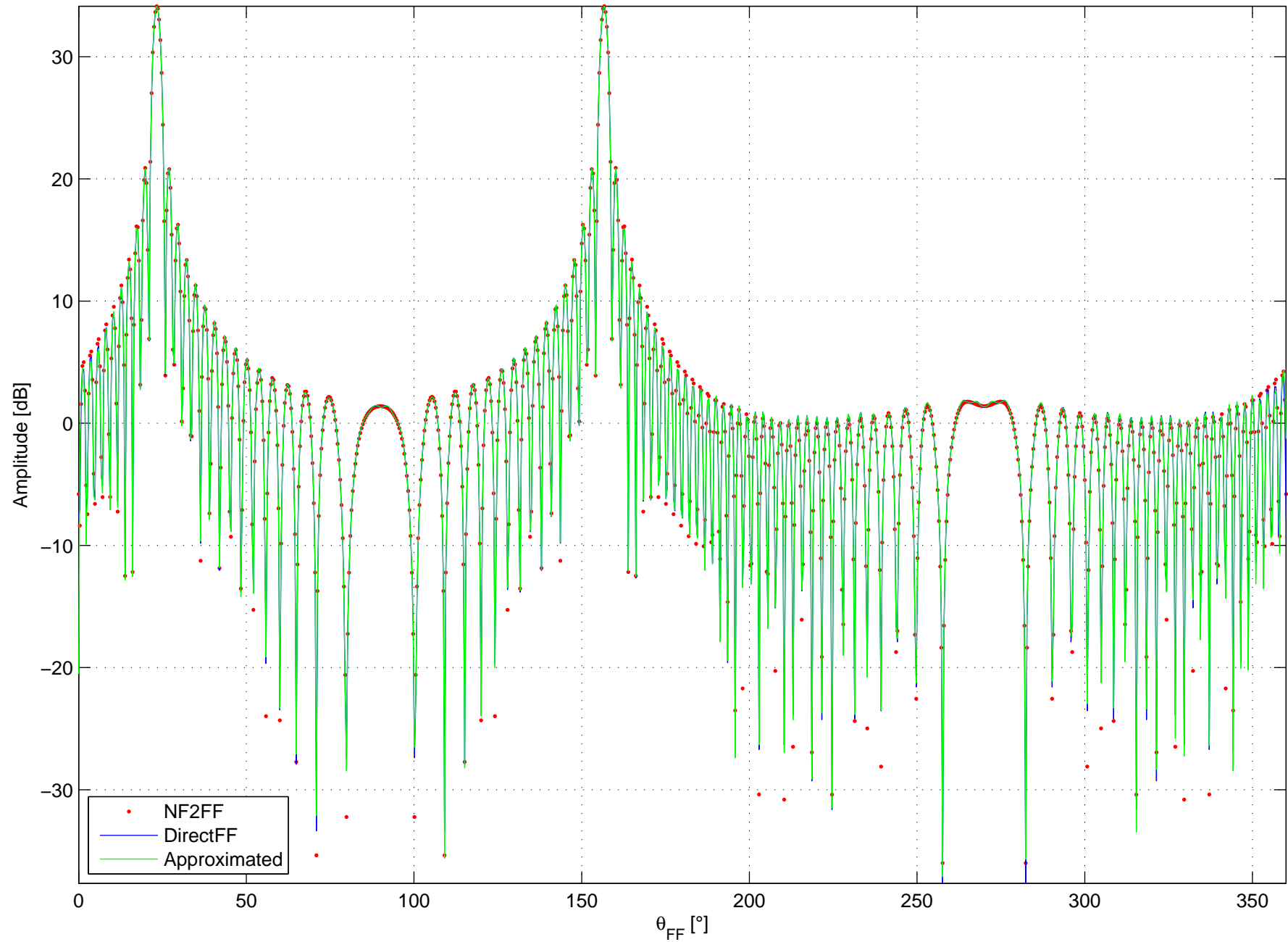
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.0043078
FFSamples = 961, NFSamples = 16200, Coefficients = 203



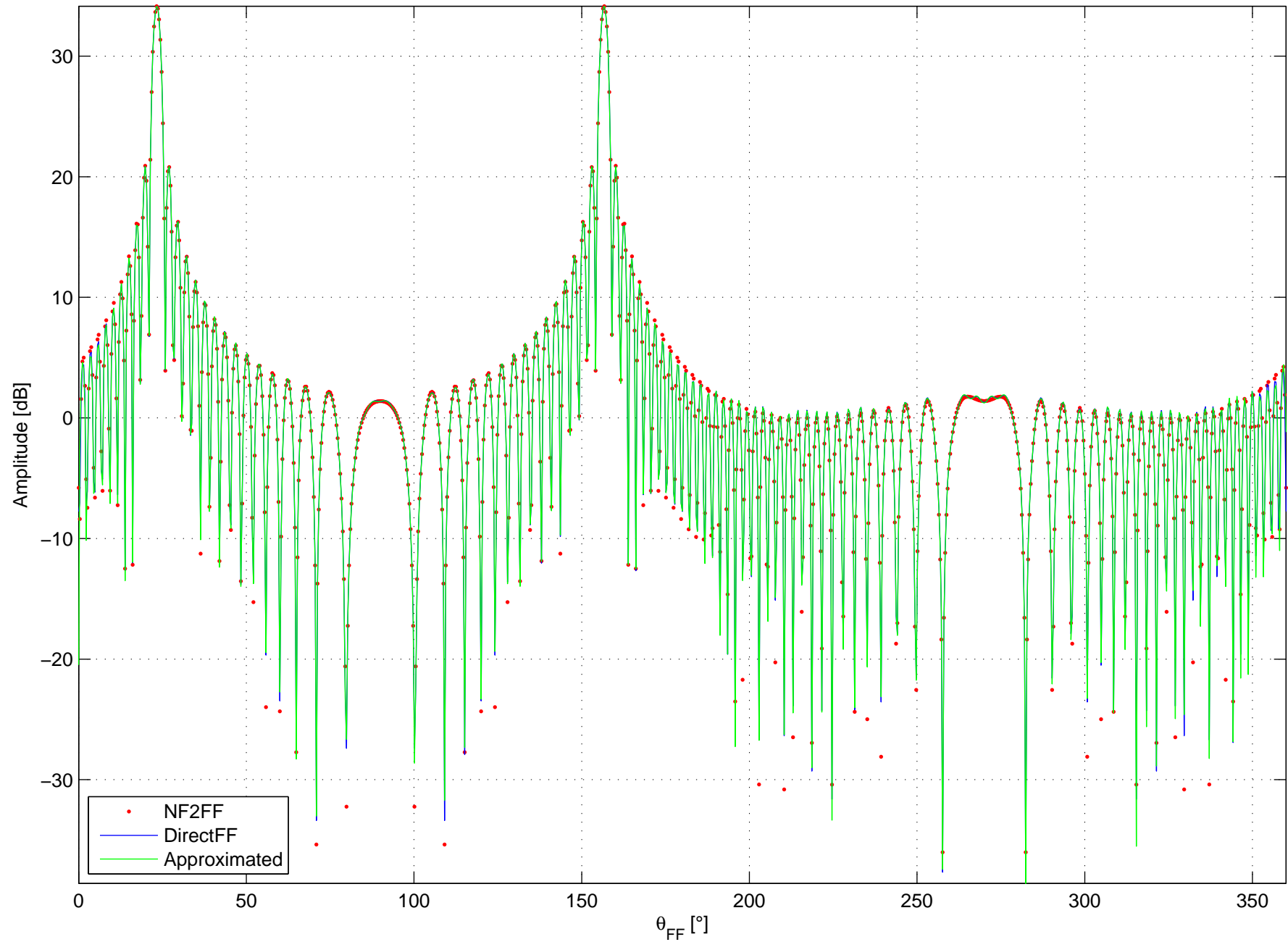
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.0044678
FFSamples = 961, NFSamples = 16200, Coefficients = 199



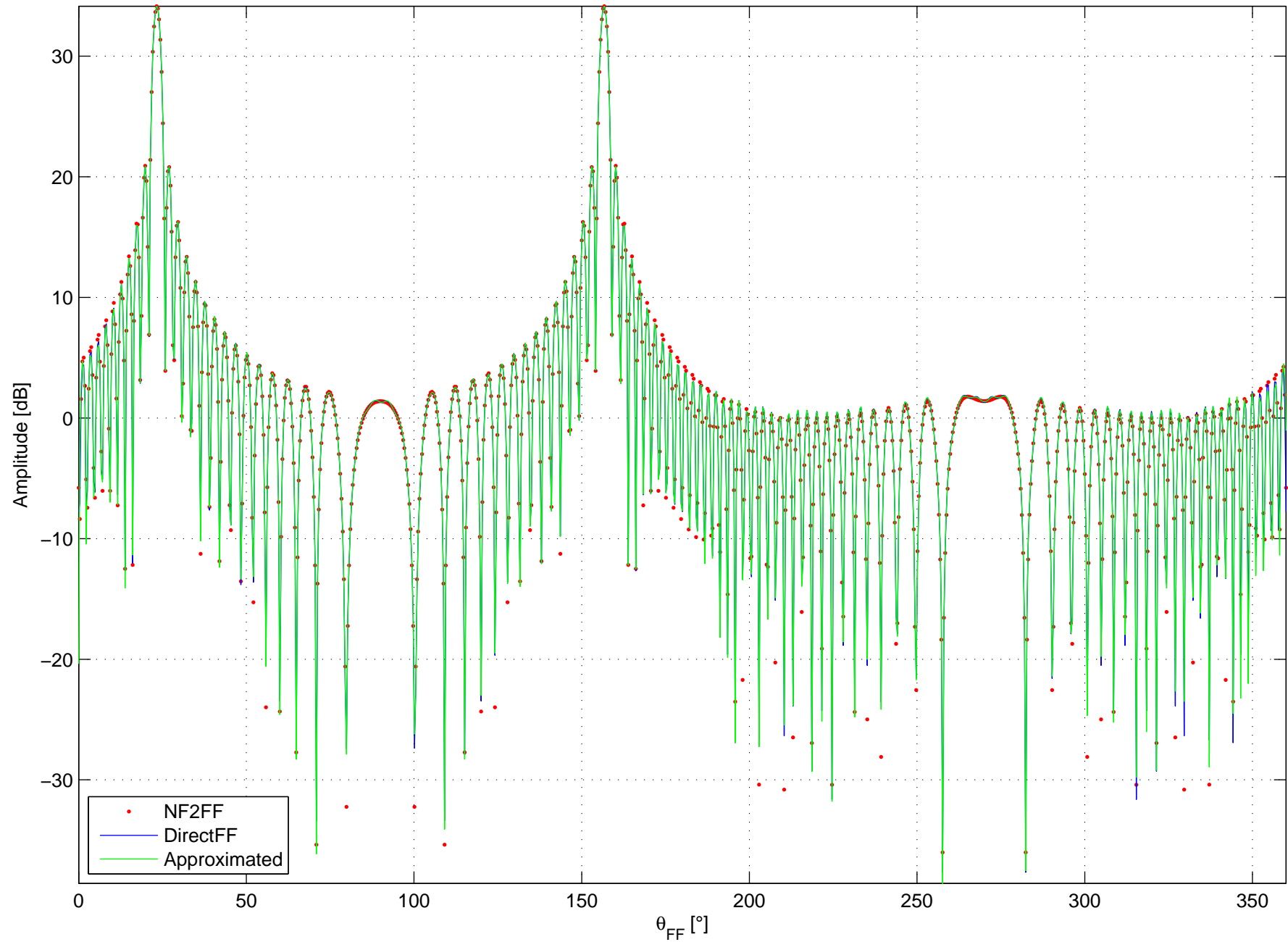
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.0046541
FFSamples = 961, NFSamples = 16200, Coefficients = 195



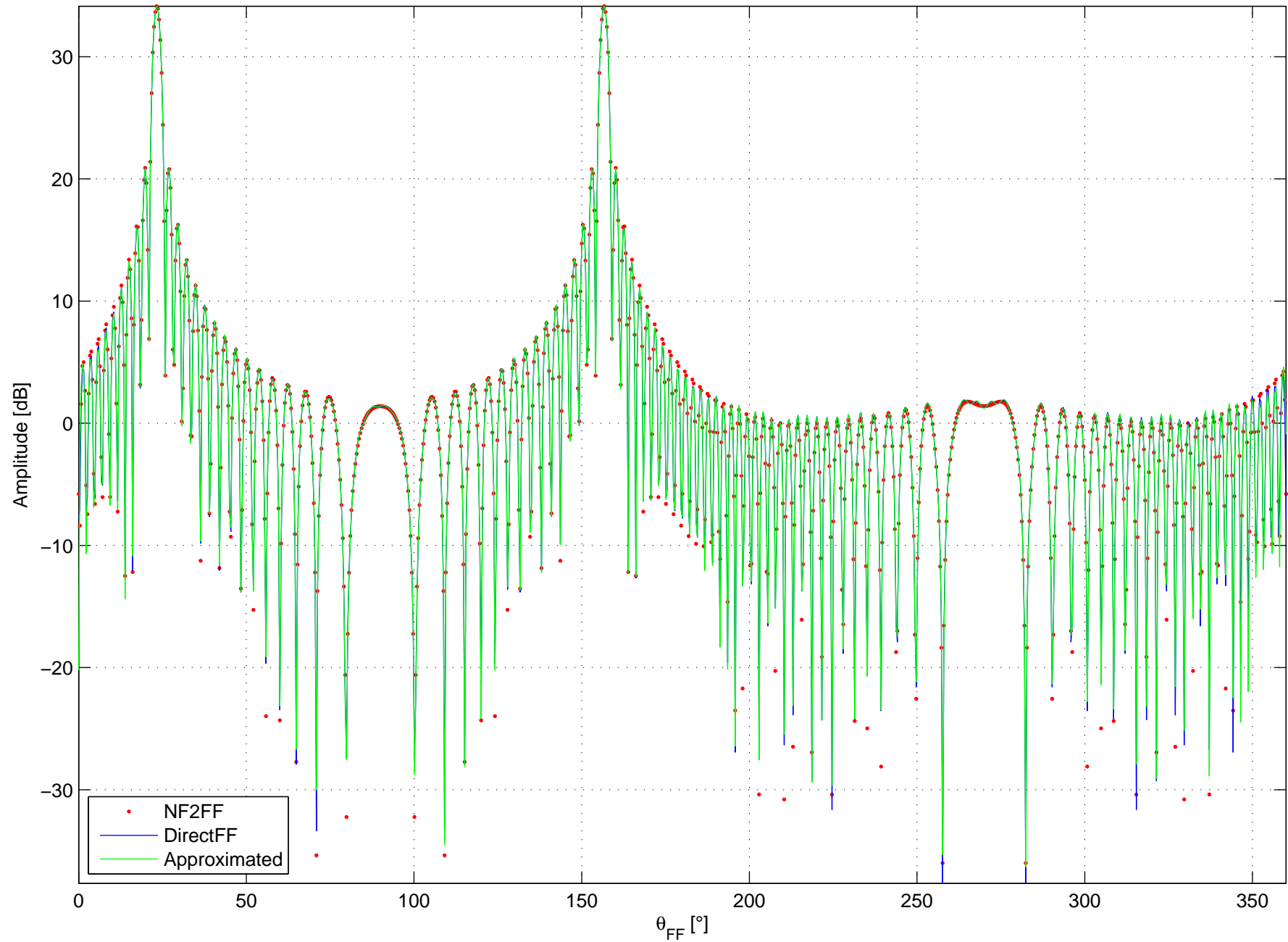
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.0048753
FFSamples = 961, NFSamples = 16200, Coefficients = 191



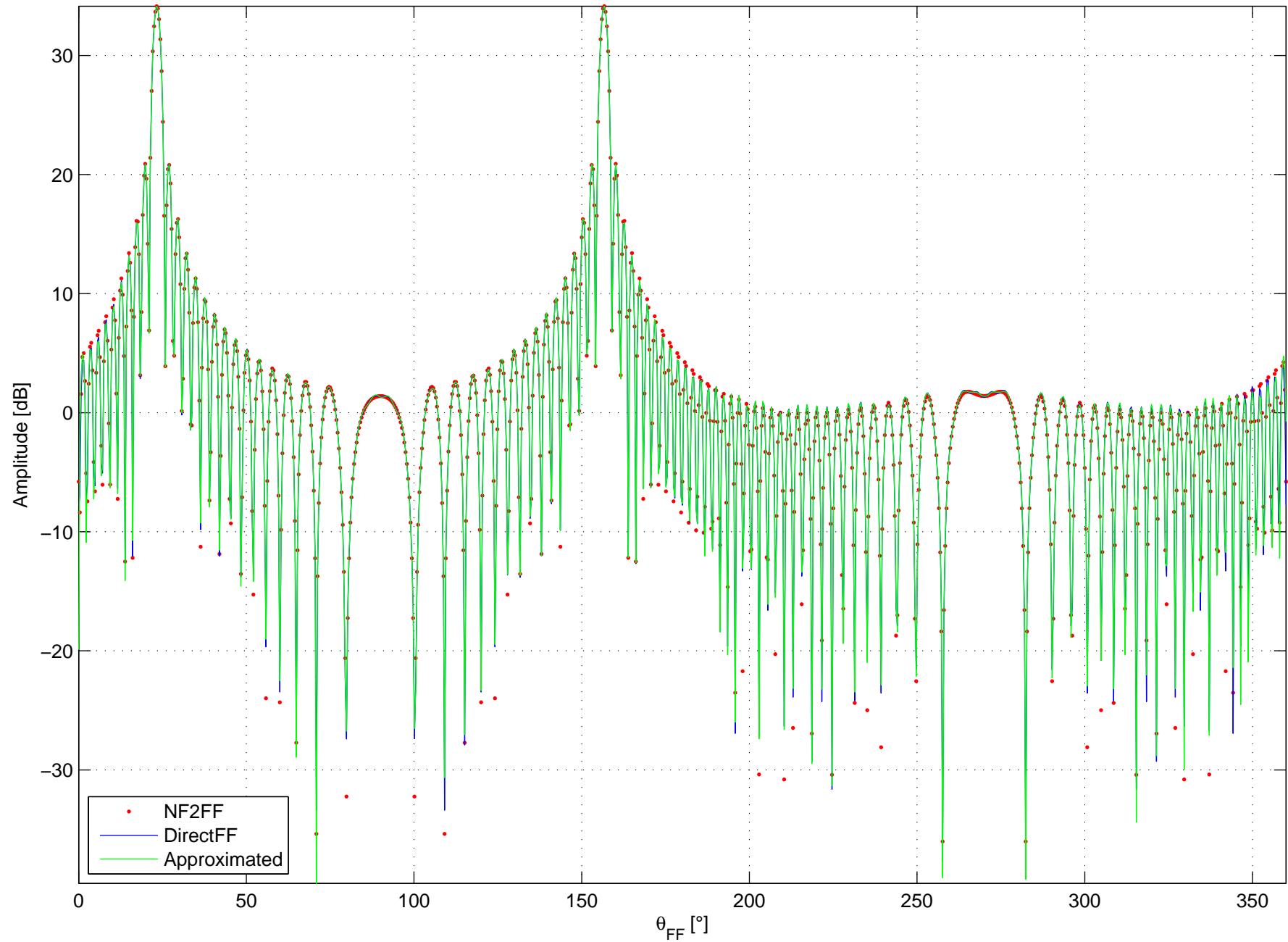
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.0051484
FFSamples = 961, NFSamples = 16200, Coefficients = 187



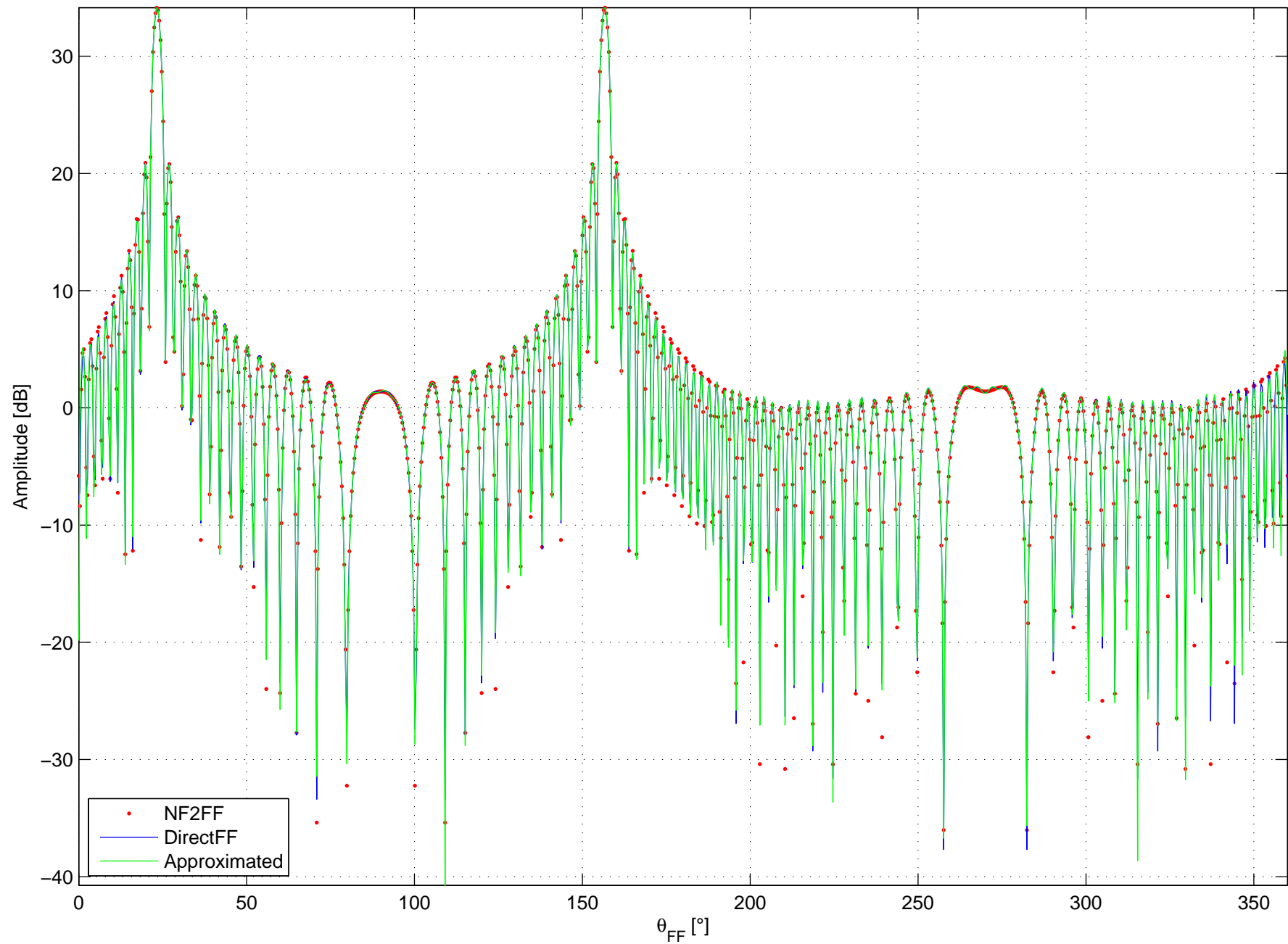
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.0054857
FFSamples = 961, NFSamples = 16200, Coefficients = 183



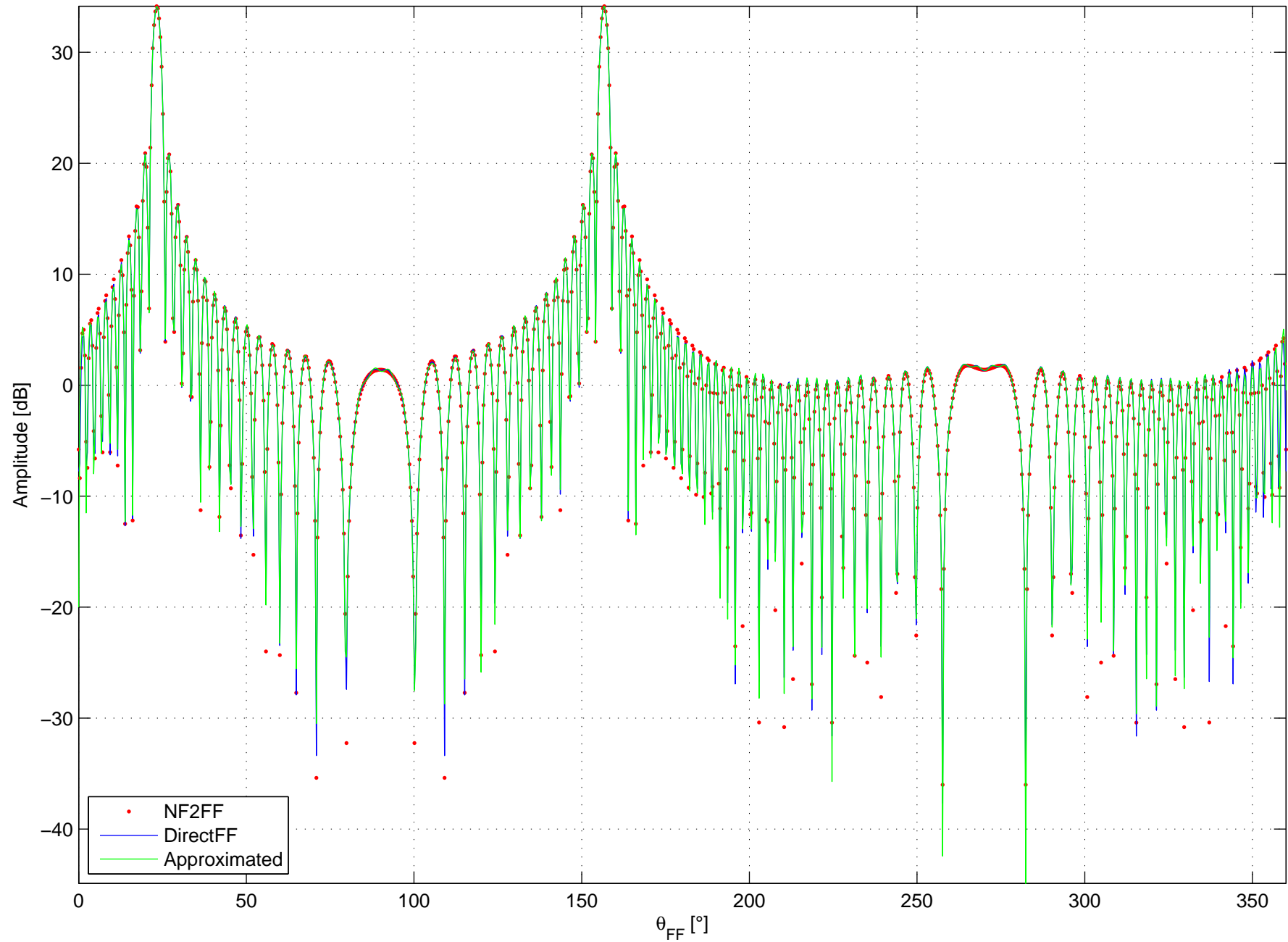
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.0059327
FFSamples = 961, NFSamples = 16200, Coefficients = 179



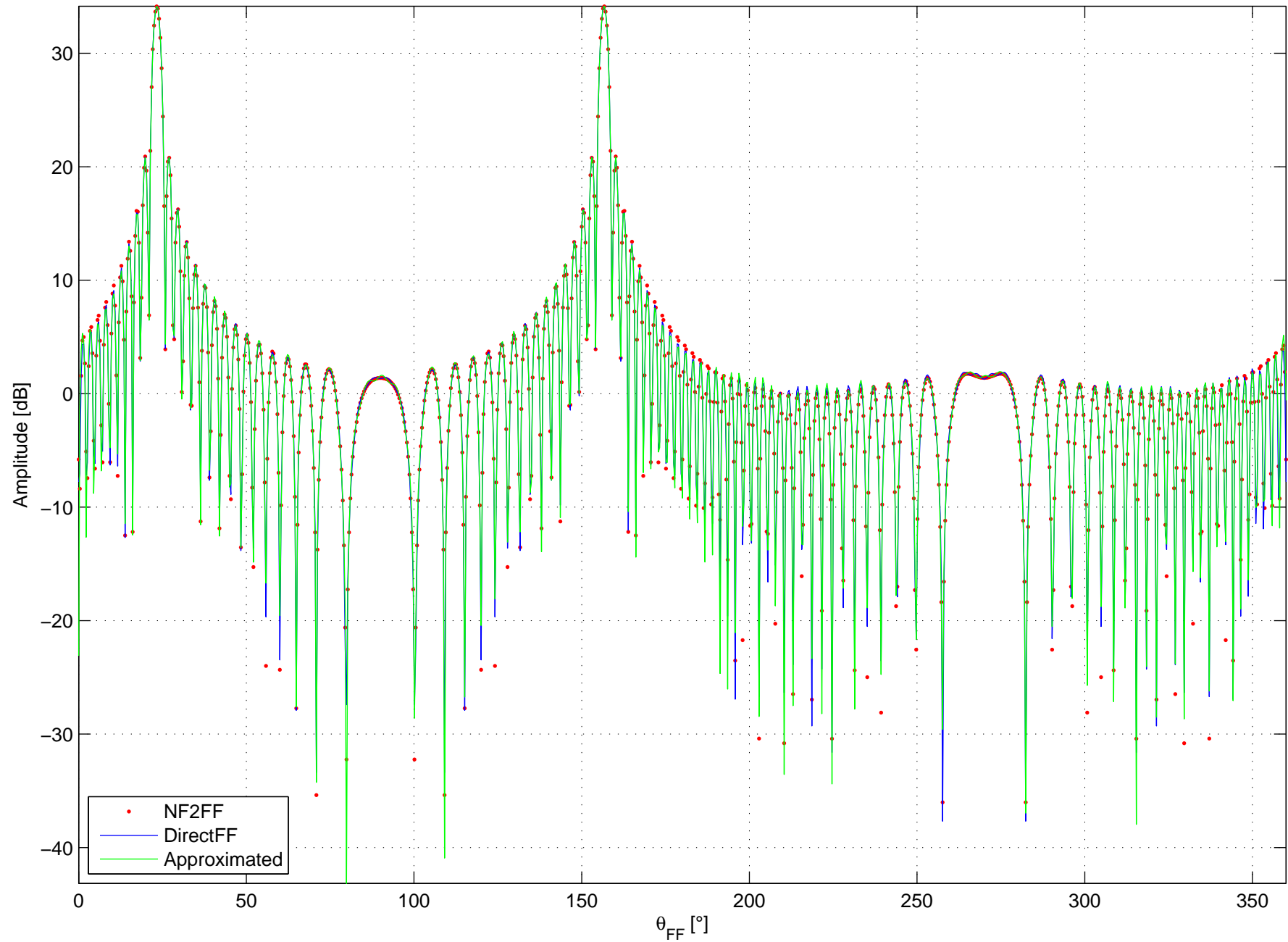
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.0064412
FFSamples = 961, NFSamples = 16200, Coefficients = 175



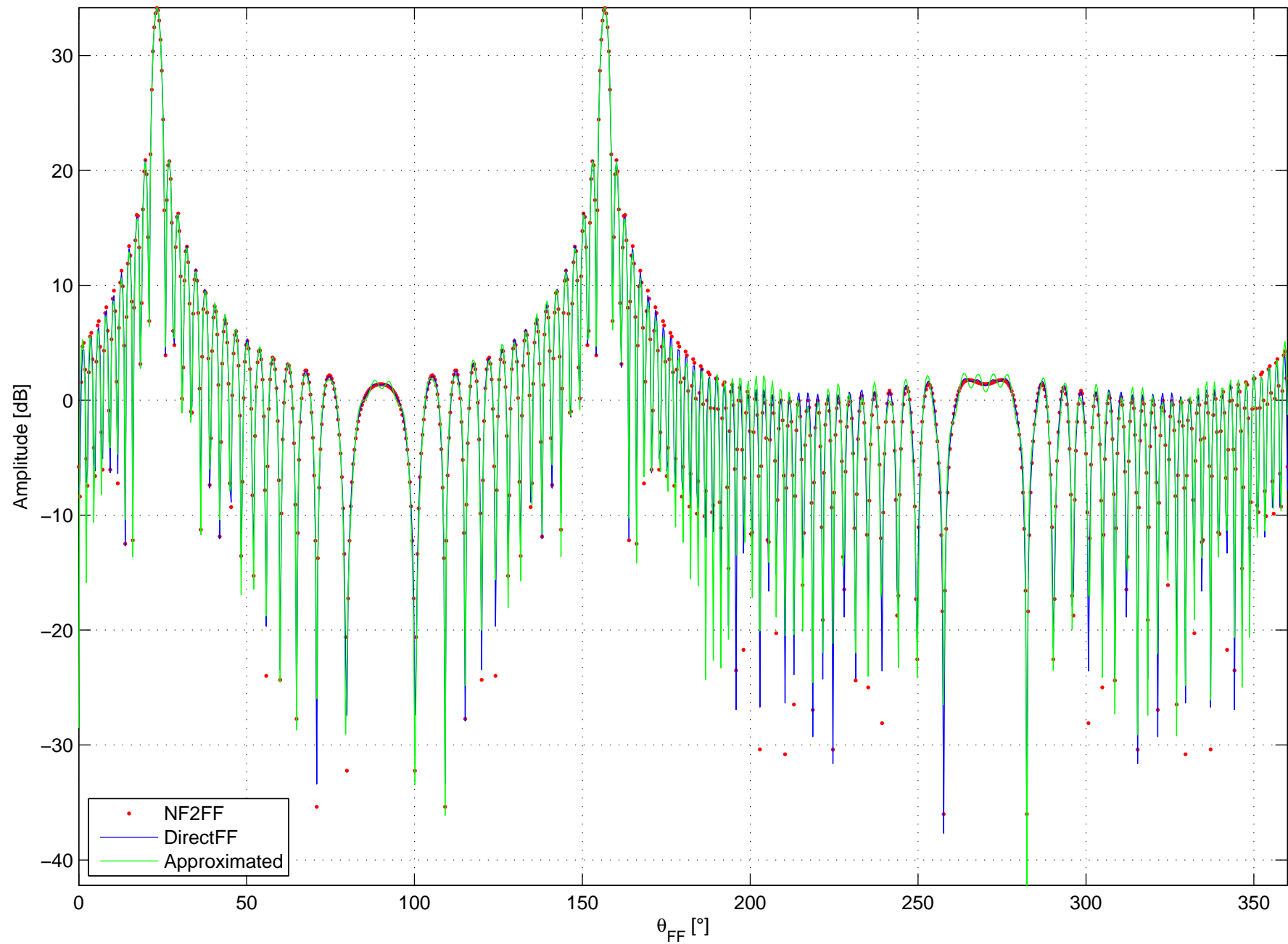
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.0071003
FFSamples = 961, NFSamples = 16200, Coefficients = 171



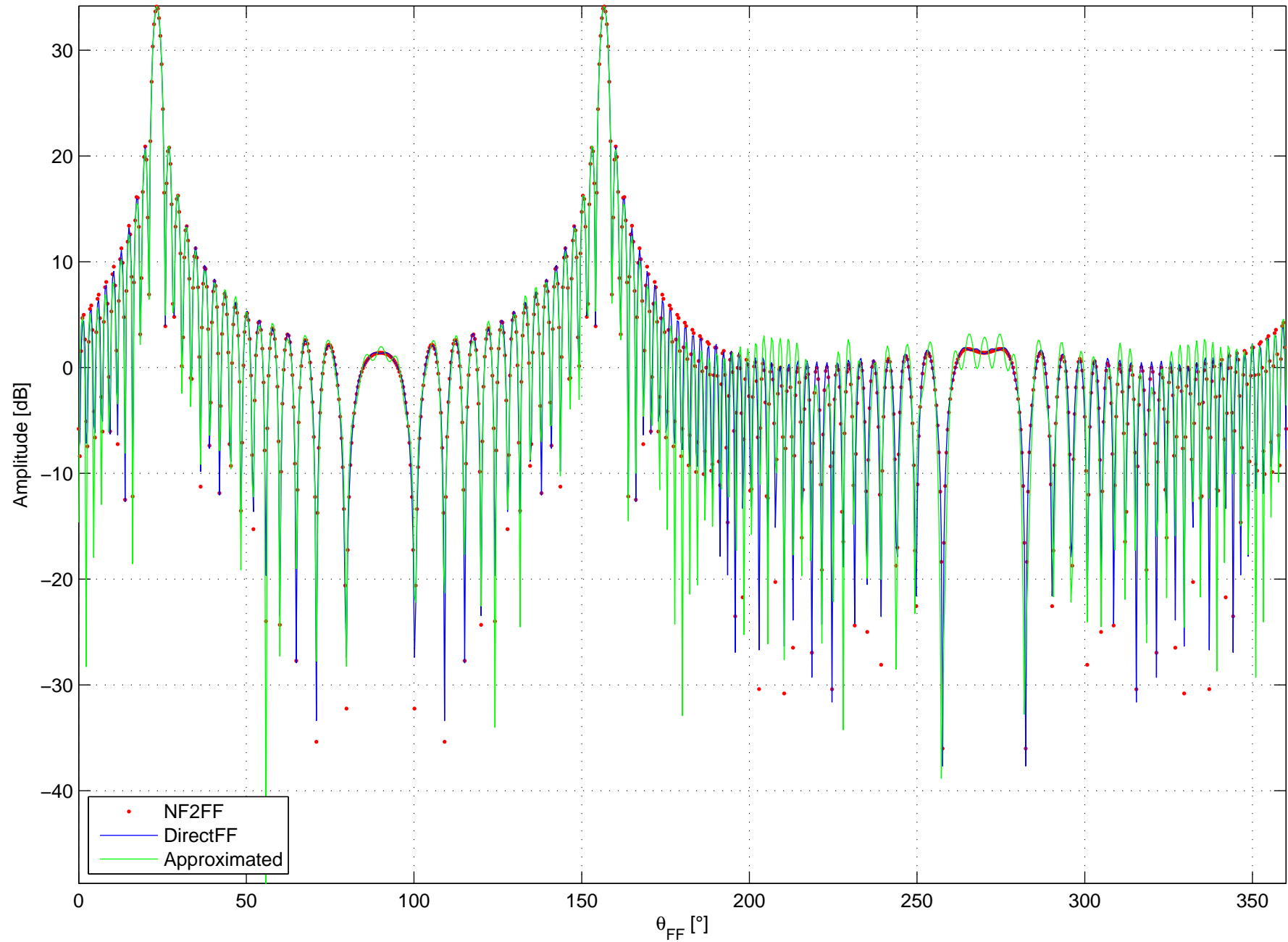
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.0090725
FFSamples = 961, NFSamples = 16200, Coefficients = 167



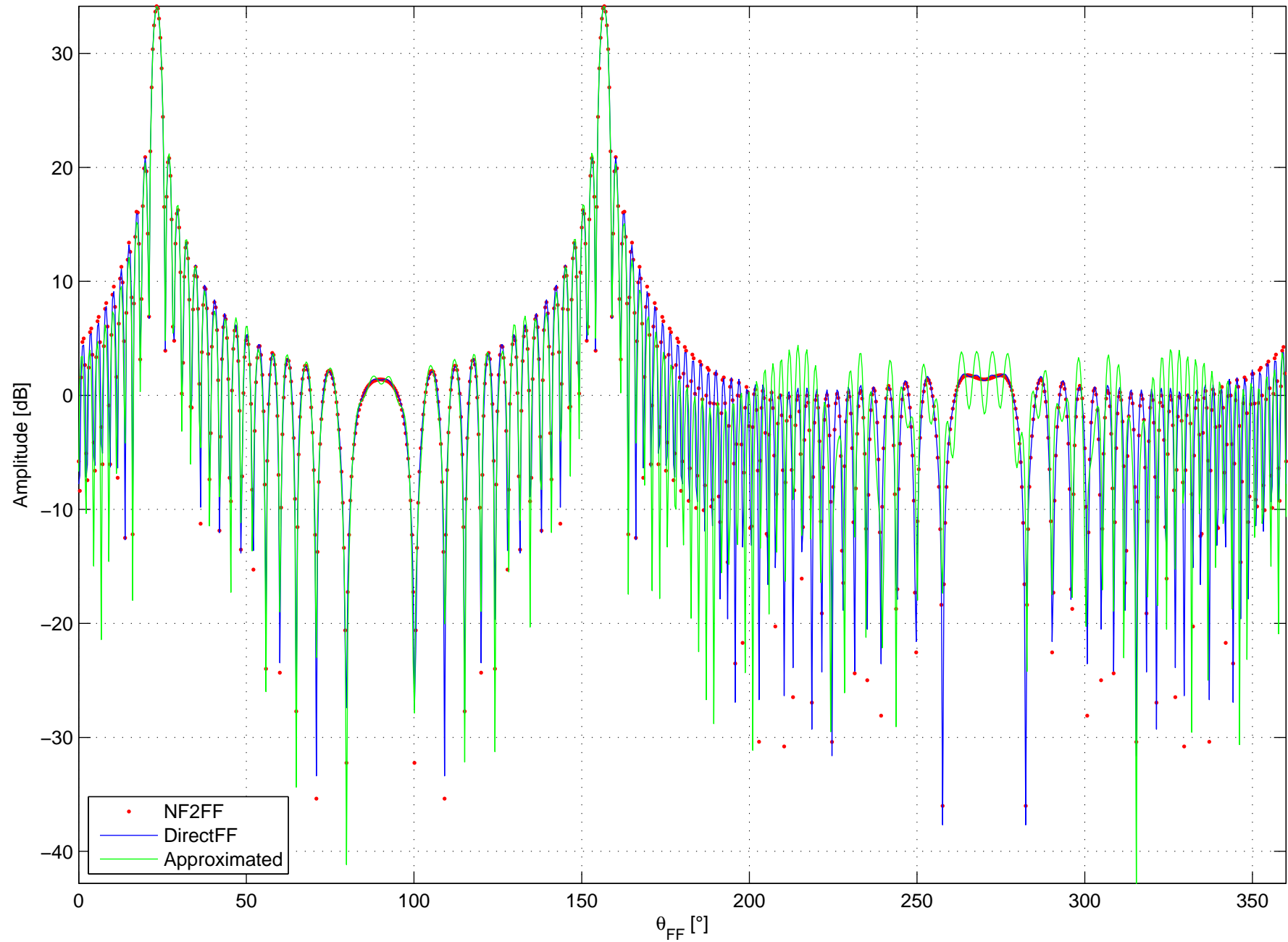
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.015087
FFSamples = 961, NFSamples = 16200, Coefficients = 163



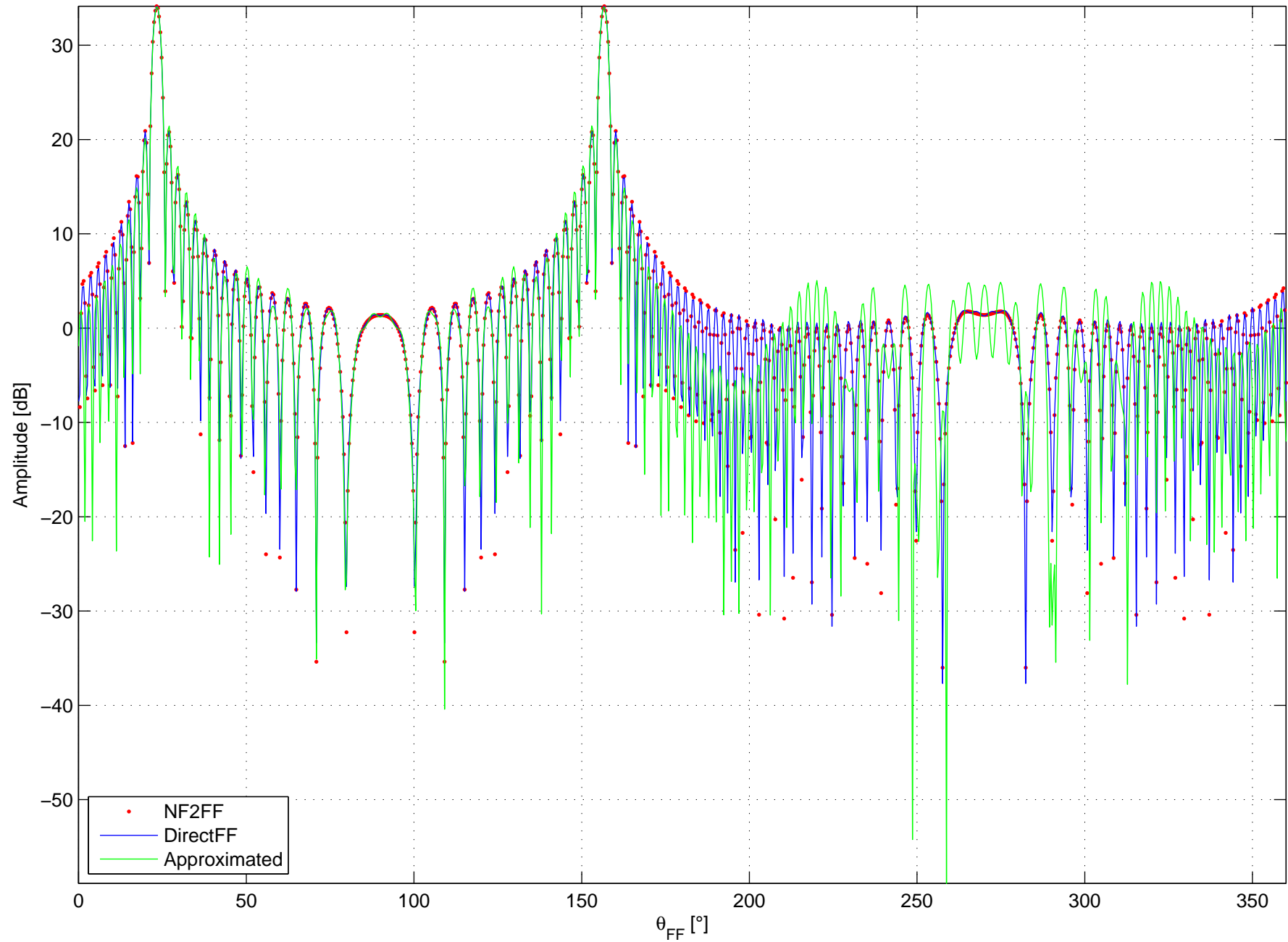
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.032244
FFSamples = 961, NFSamples = 16200, Coefficients = 159



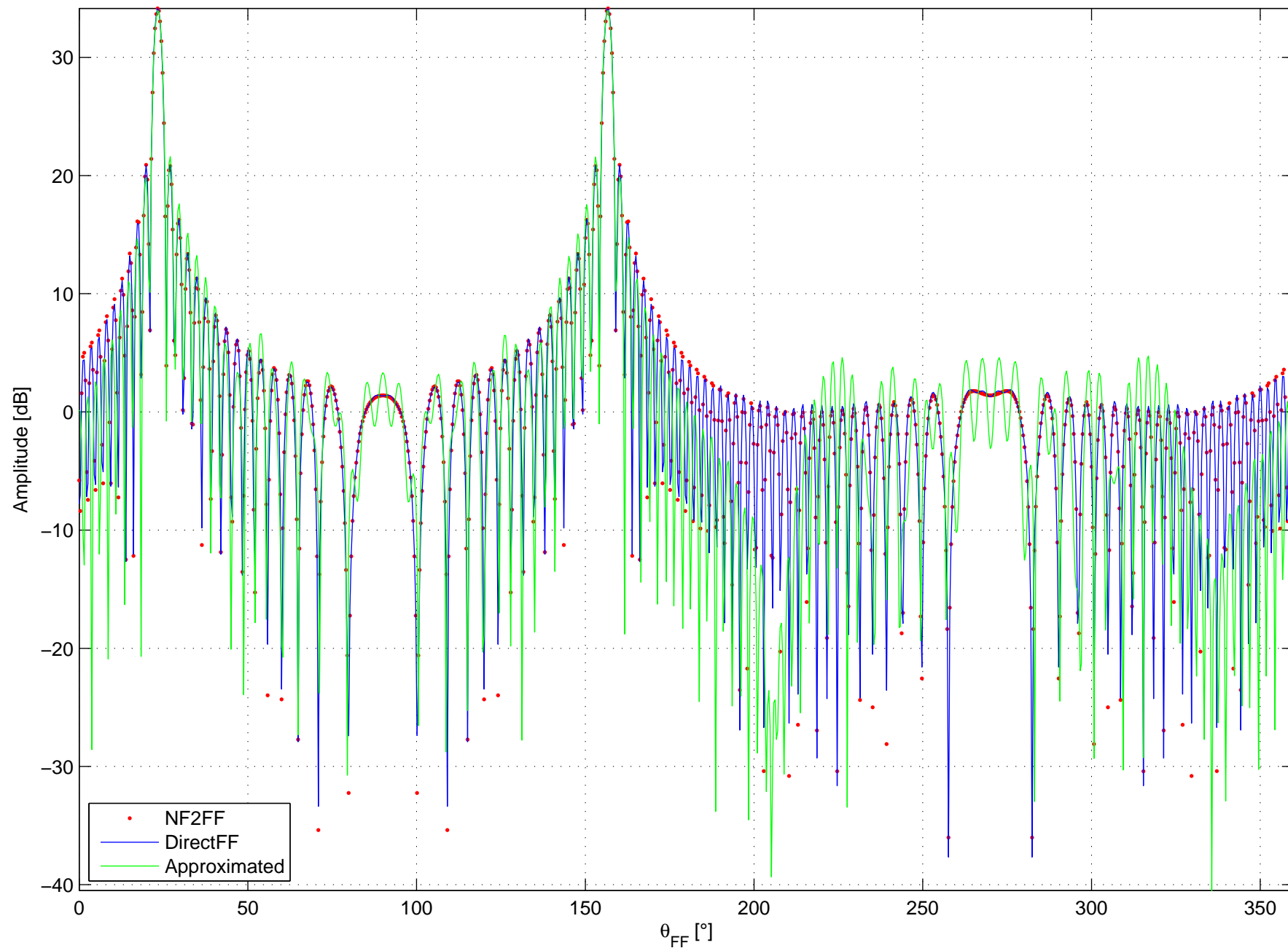
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.058952
FFSamples = 961, NFSamples = 16200, Coefficients = 155



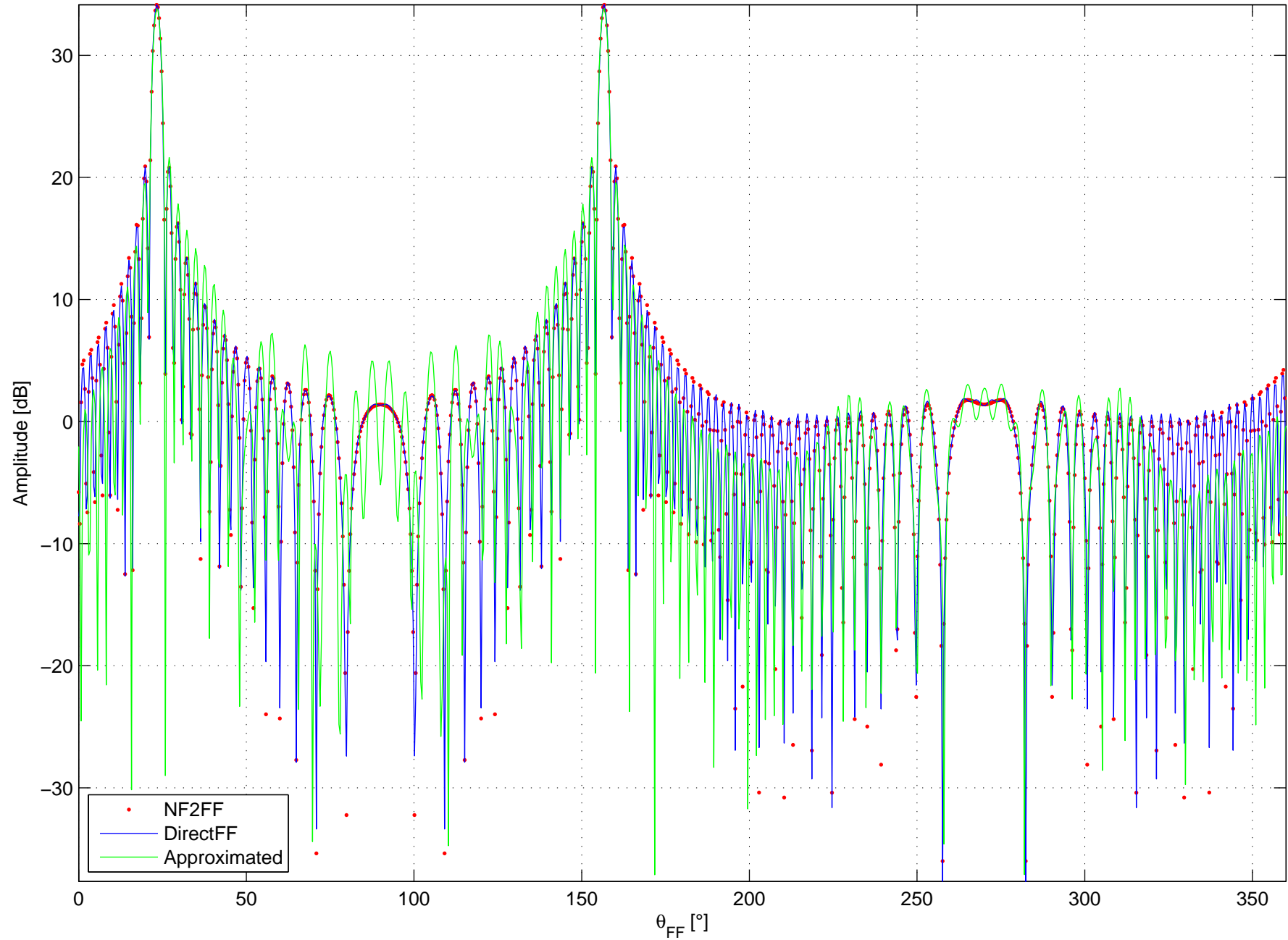
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.094149
FFSamples = 961, NFSamples = 16200, Coefficients = 151



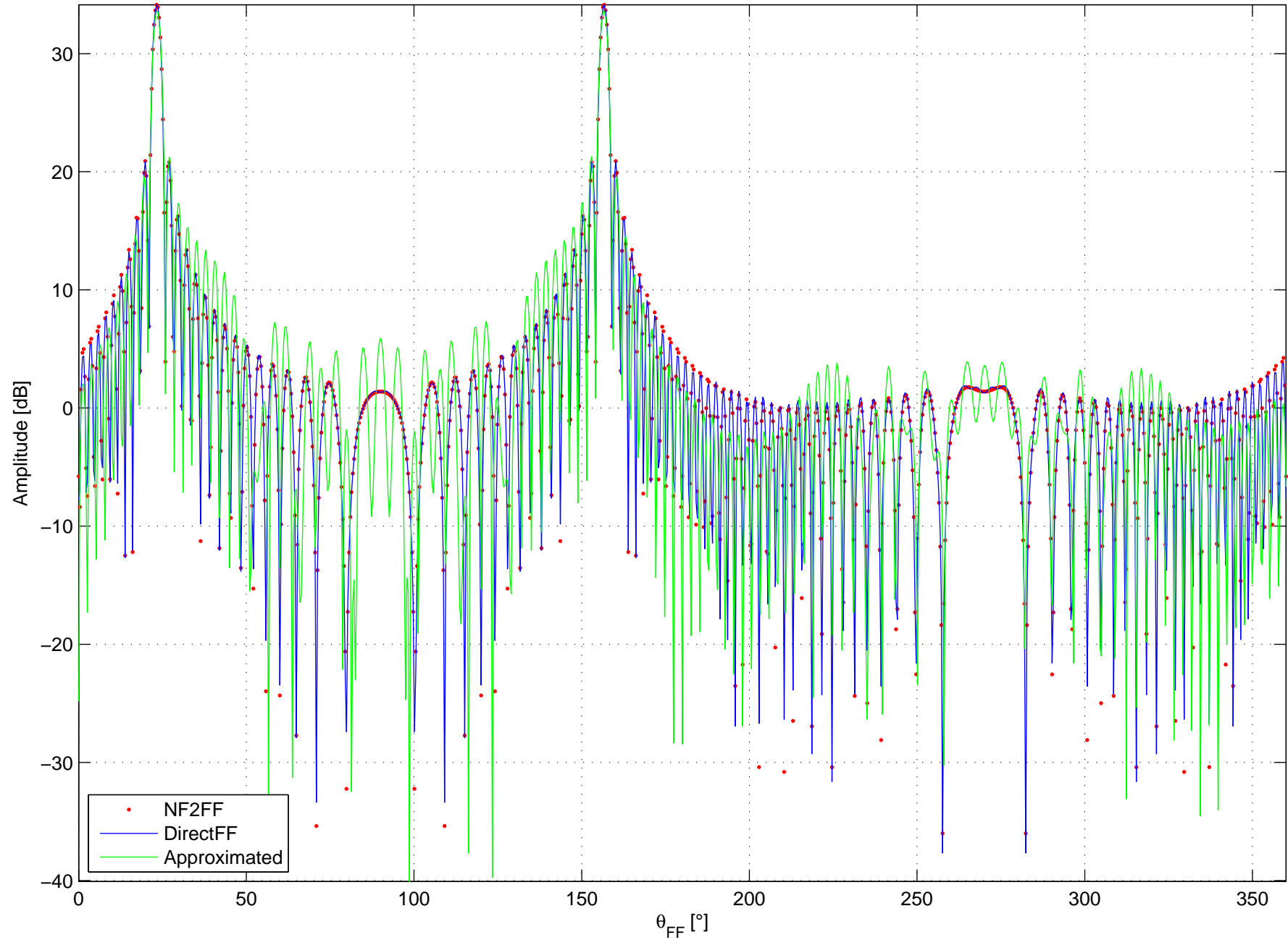
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.1291
FFSamples = 961, NFSamples = 16200, Coefficients = 147



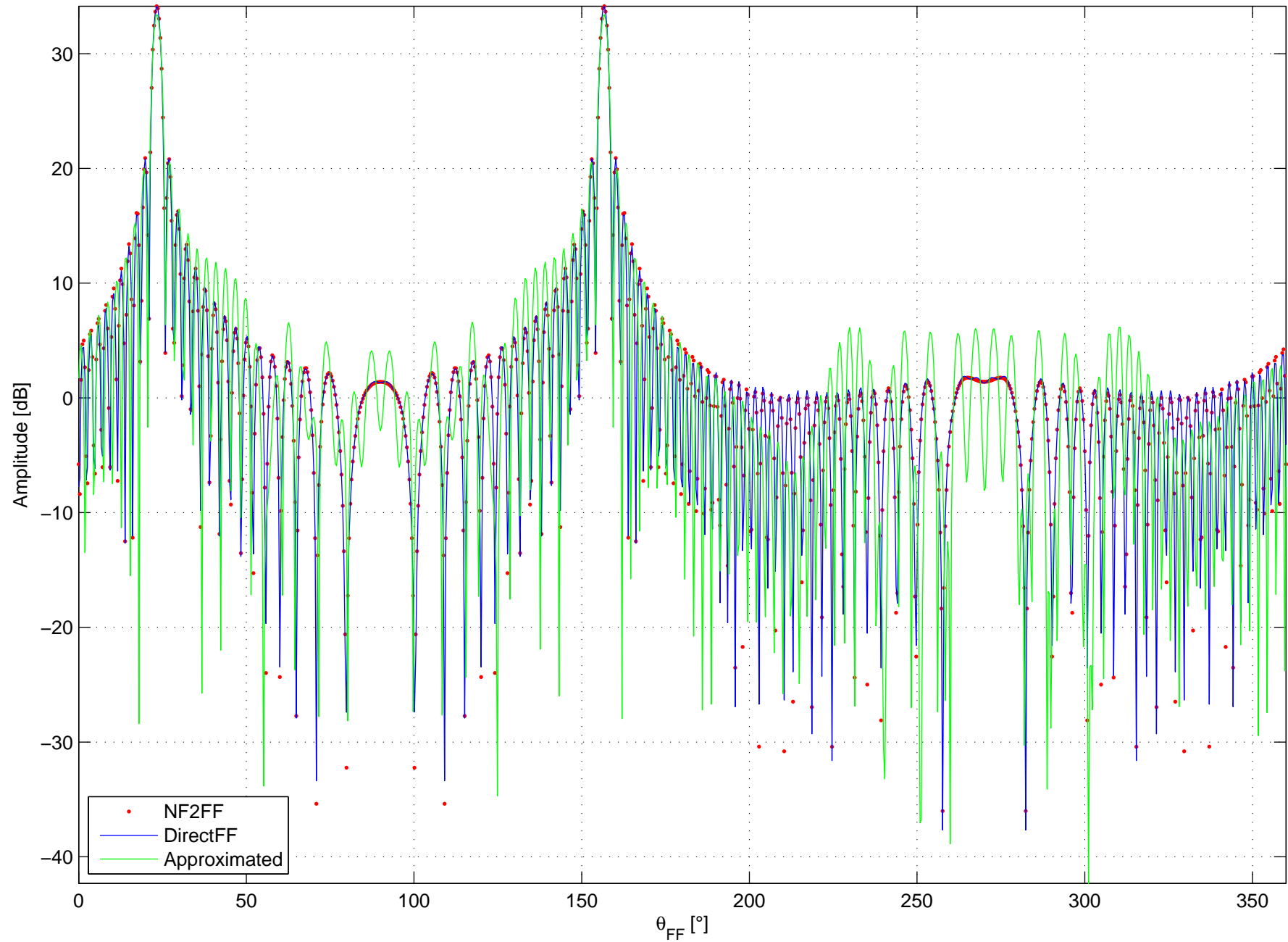
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.16054
FFSamples = 961, NFSamples = 16200, Coefficients = 143



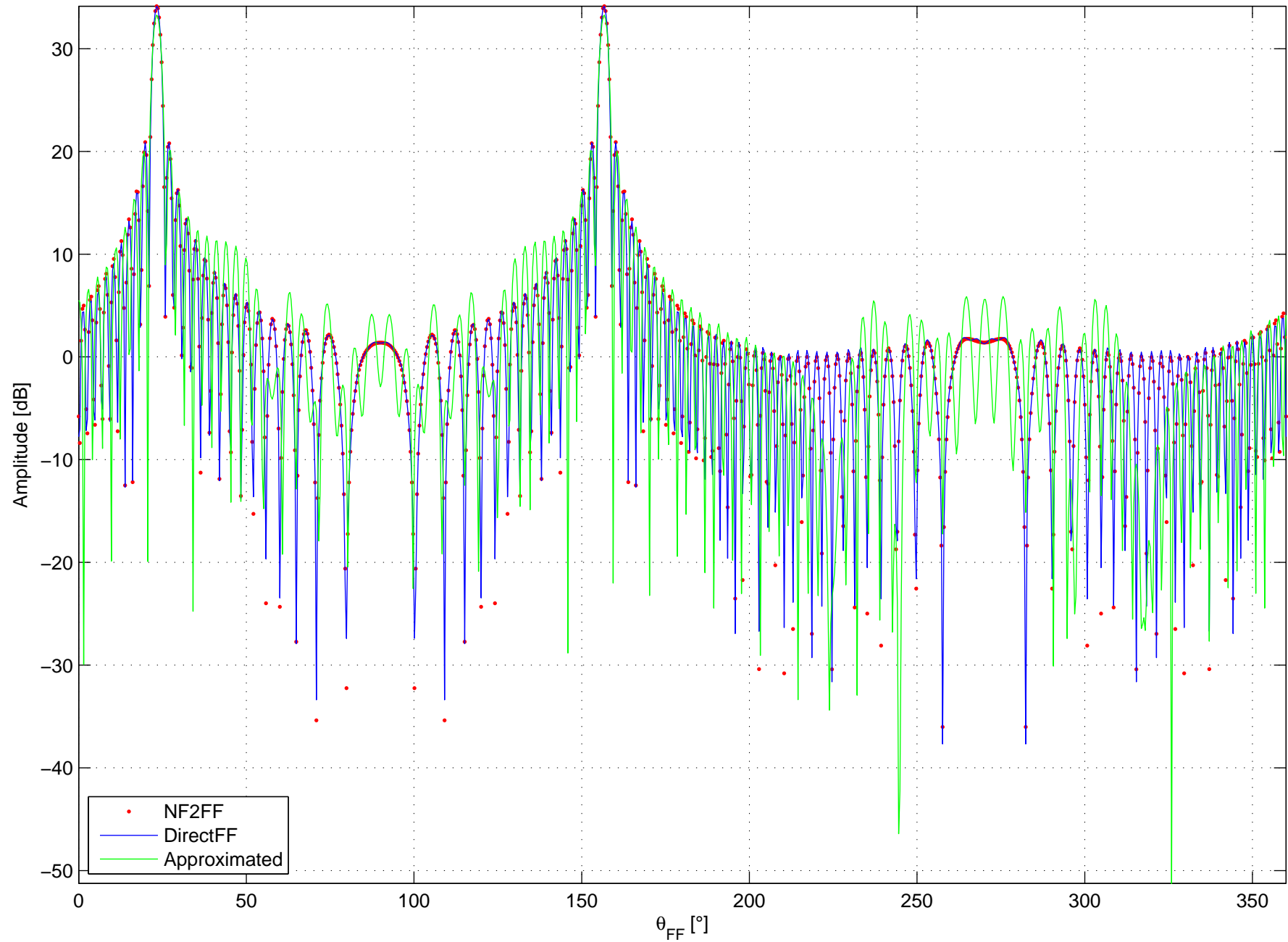
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.20052
FFSamples = 961, NFSamples = 16200, Coefficients = 139



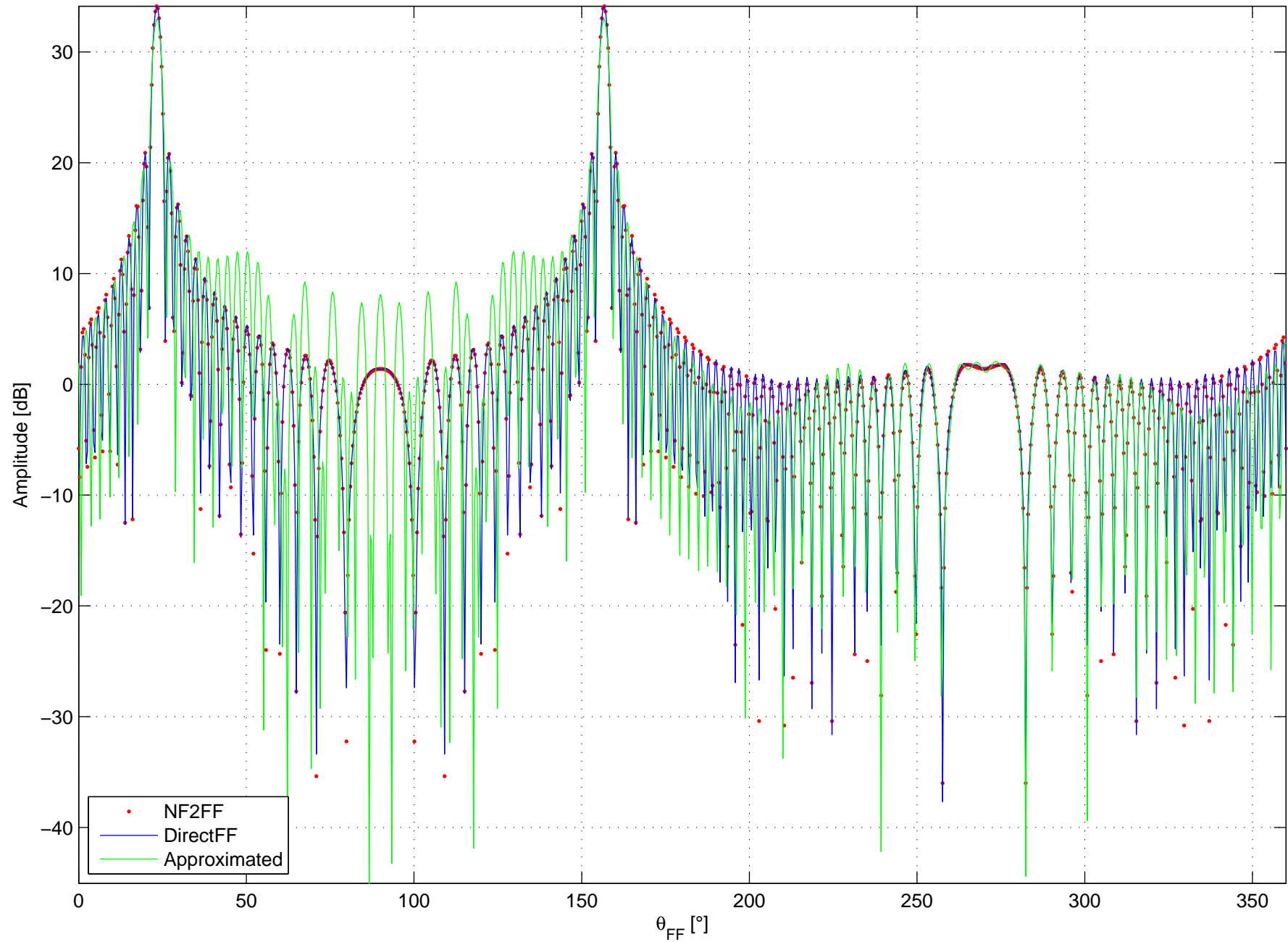
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.24571
FFSamples = 961, NFSamples = 16200, Coefficients = 135



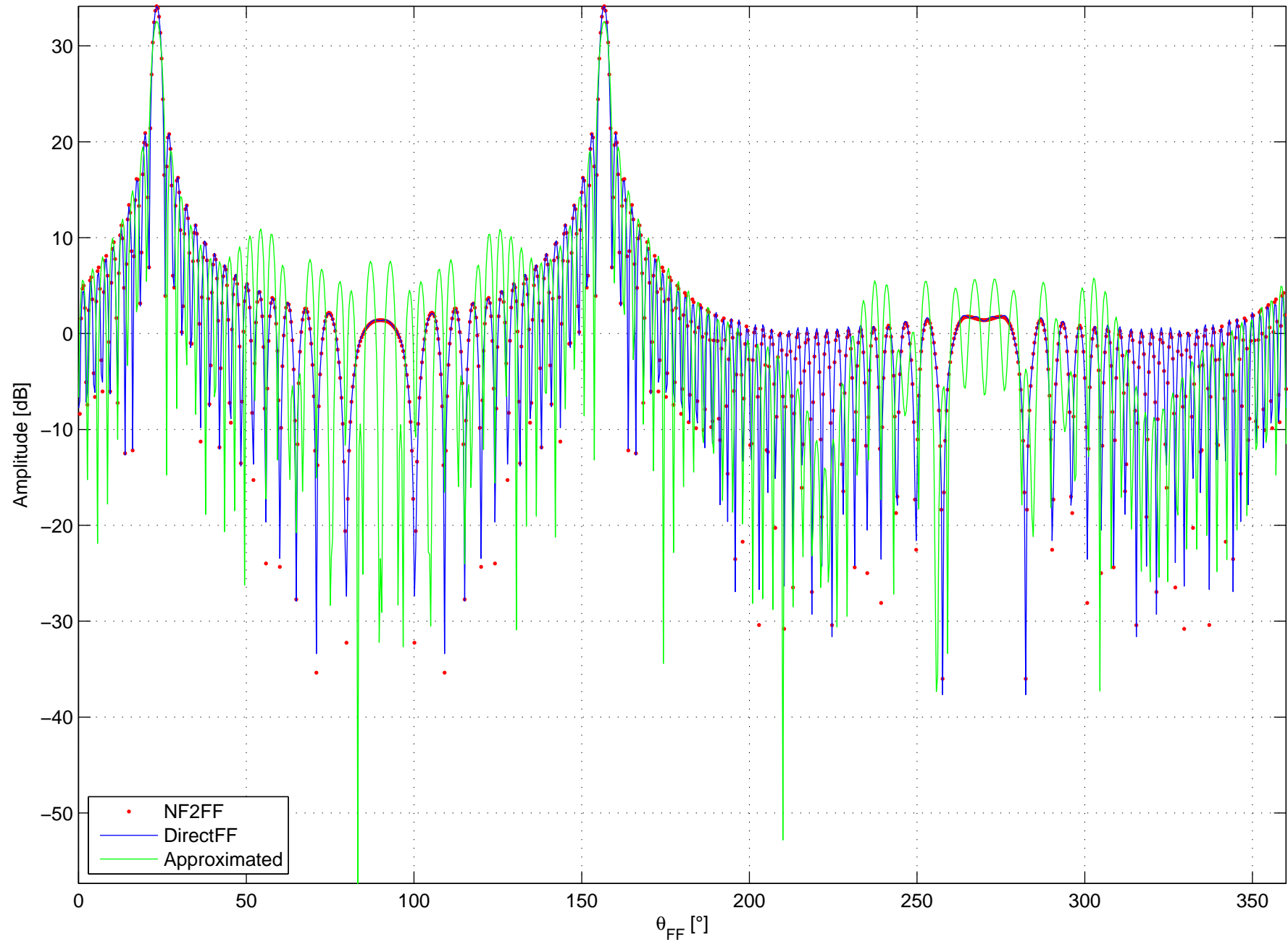
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.27745
FFSamples = 961, NFSamples = 16200, Coefficients = 131



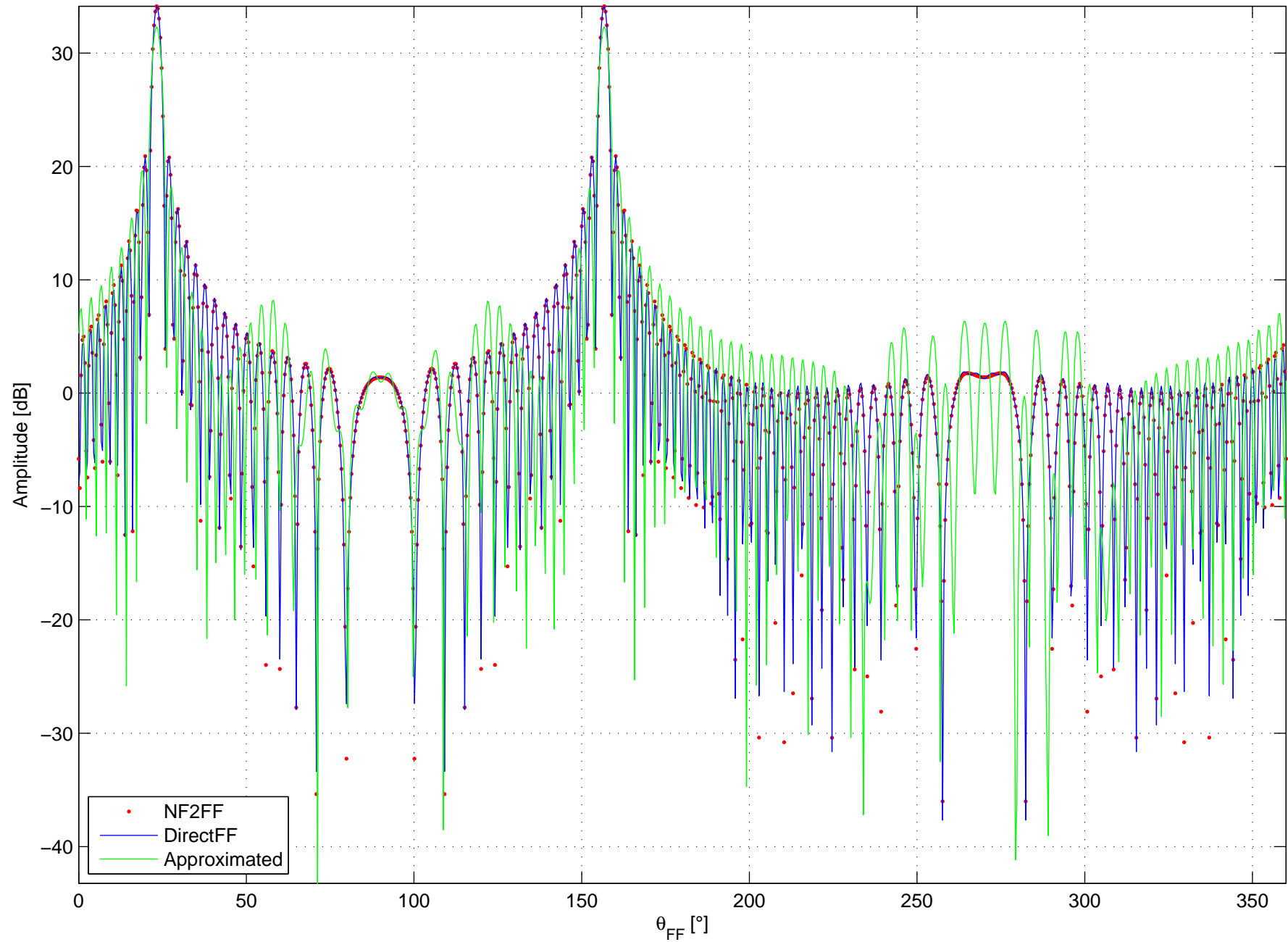
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.32364
FFSamples = 961, NFSamples = 16200, Coefficients = 127



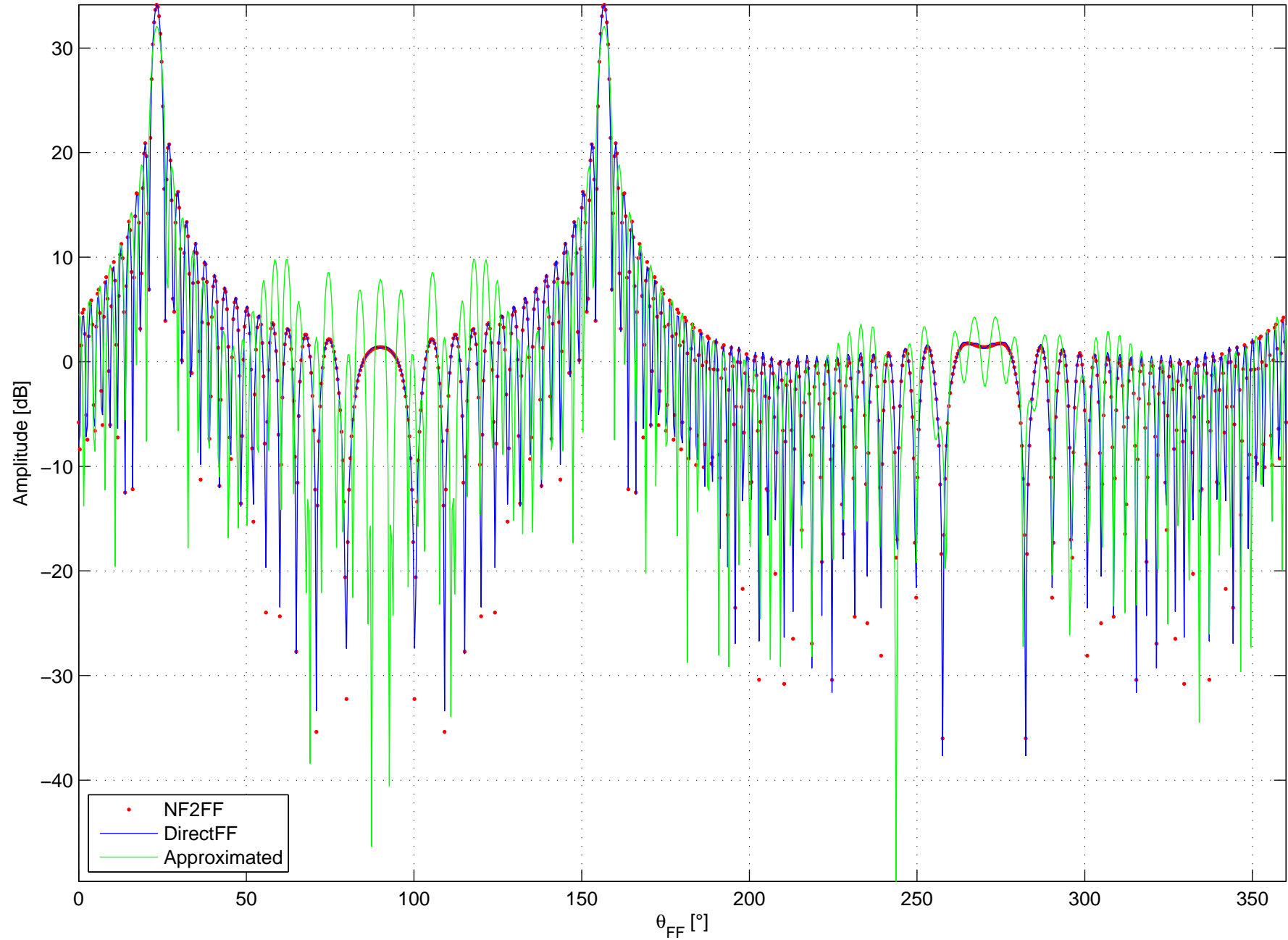
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.3946
FFSamples = 961, NFSamples = 16200, Coefficients = 123



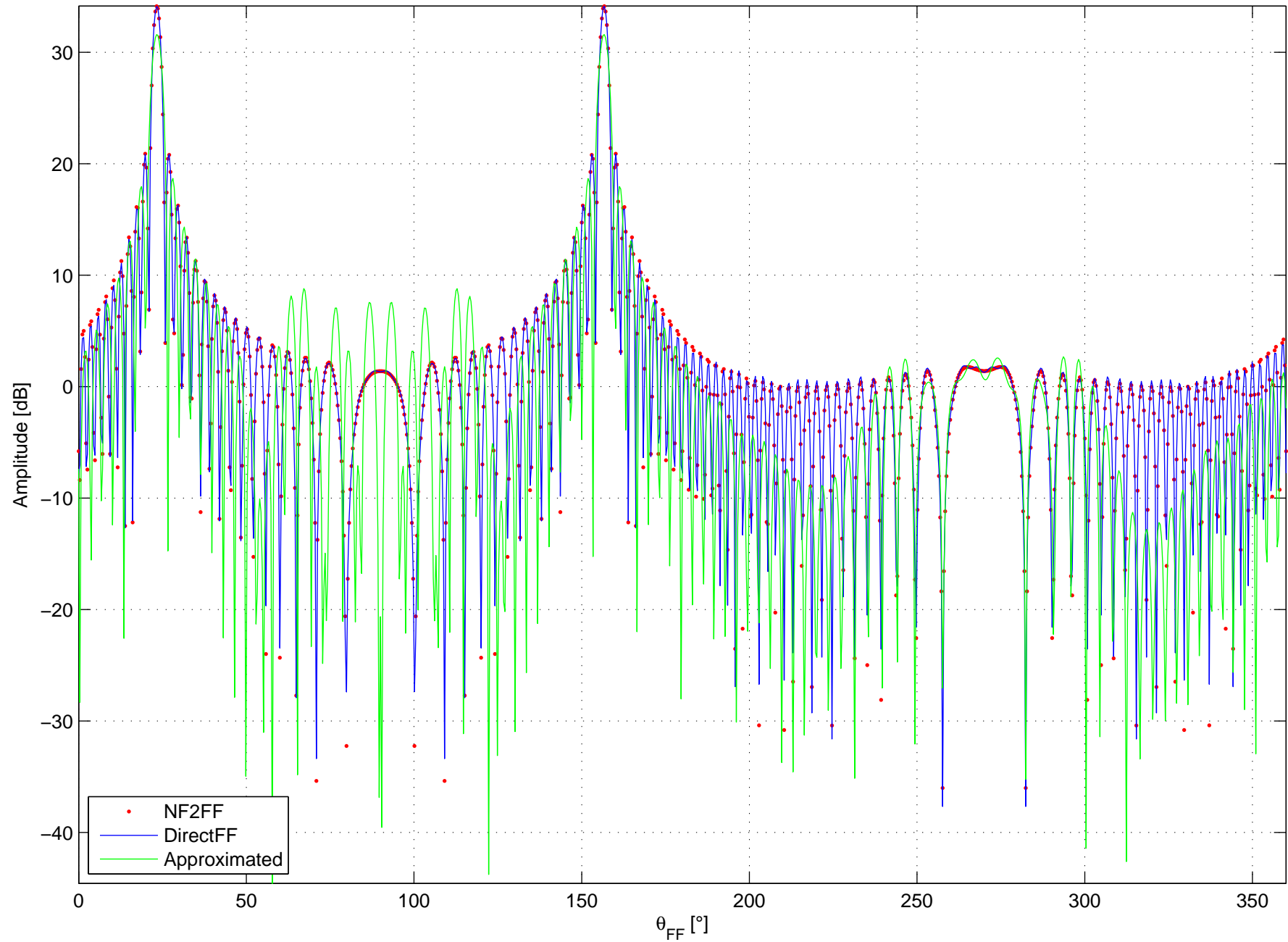
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.4279
FFSamples = 961, NFSamples = 16200, Coefficients = 119



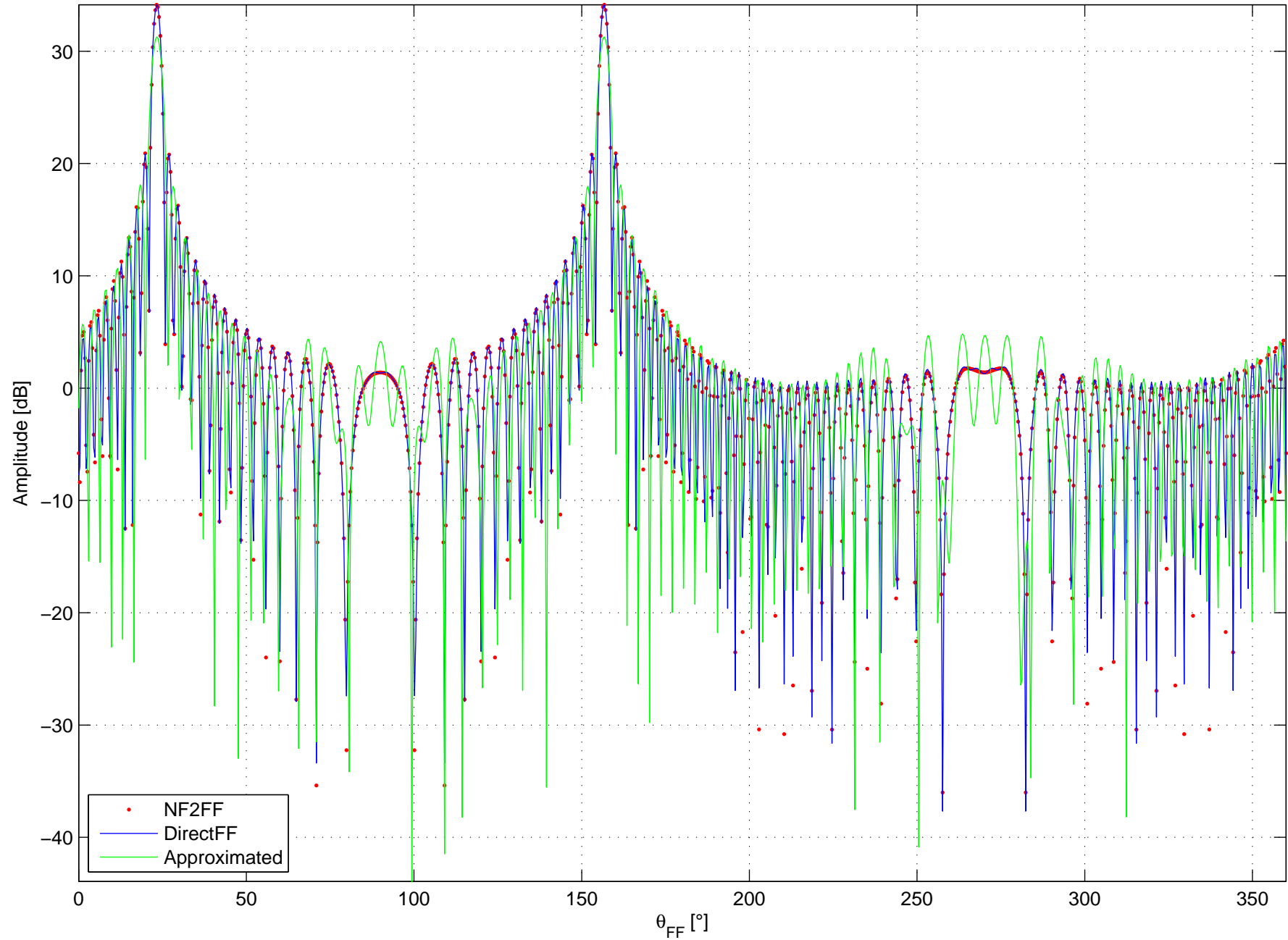
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.45588
FFSamples = 961, NFSamples = 16200, Coefficients = 115



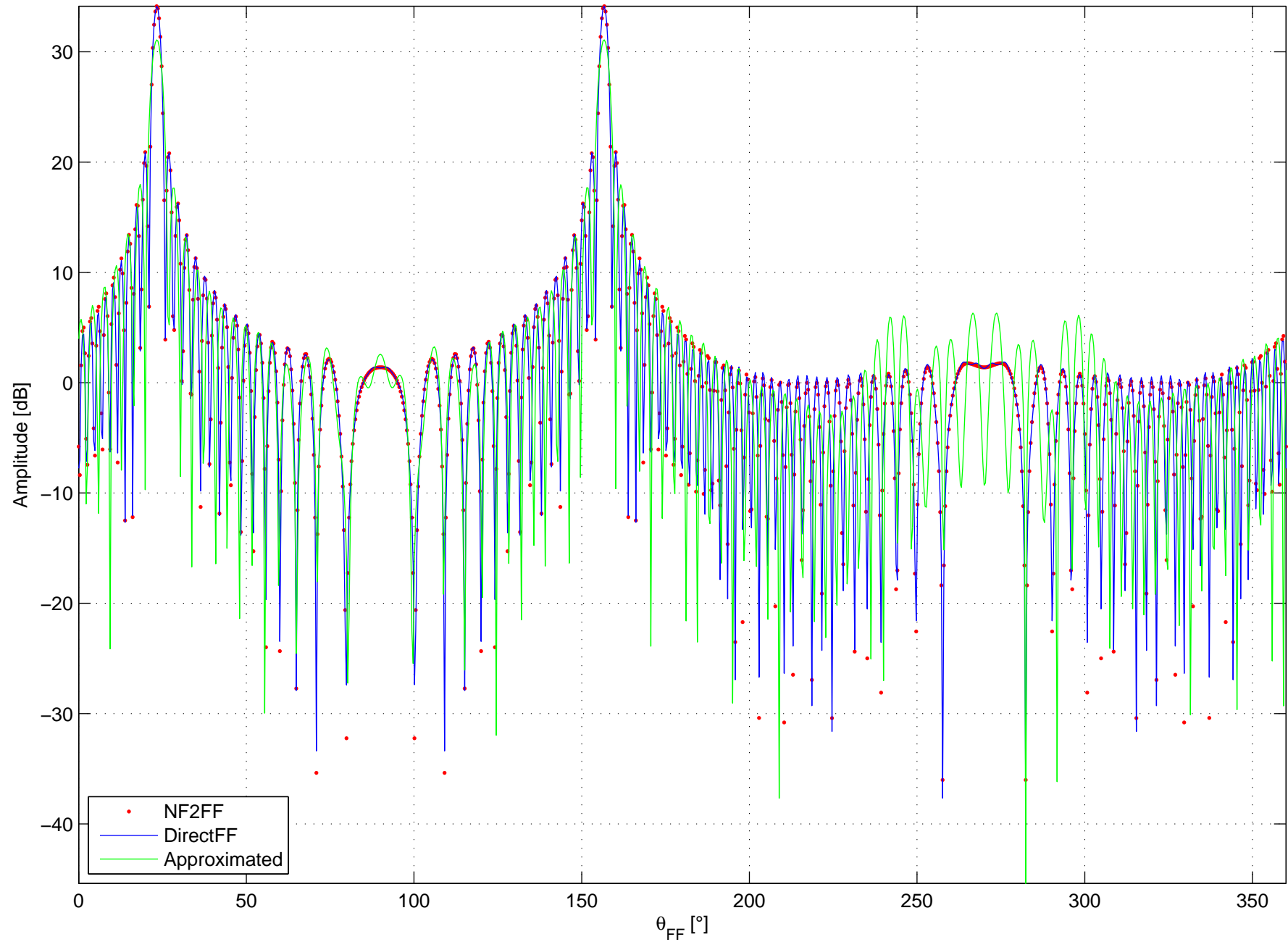
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.50499
FFSamples = 961, NFSamples = 16200, Coefficients = 111



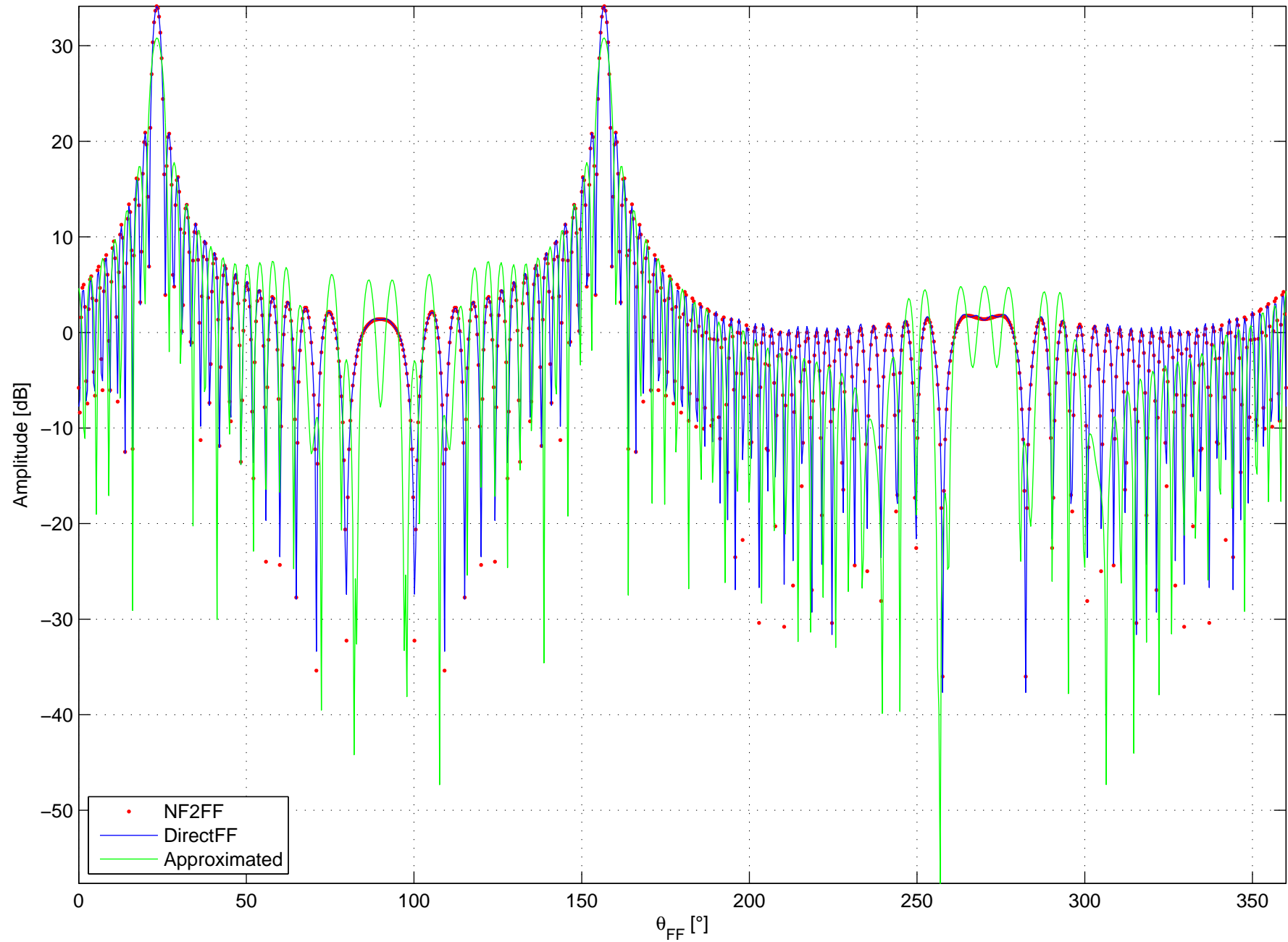
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.52764
FFSamples = 961, NFSamples = 16200, Coefficients = 107



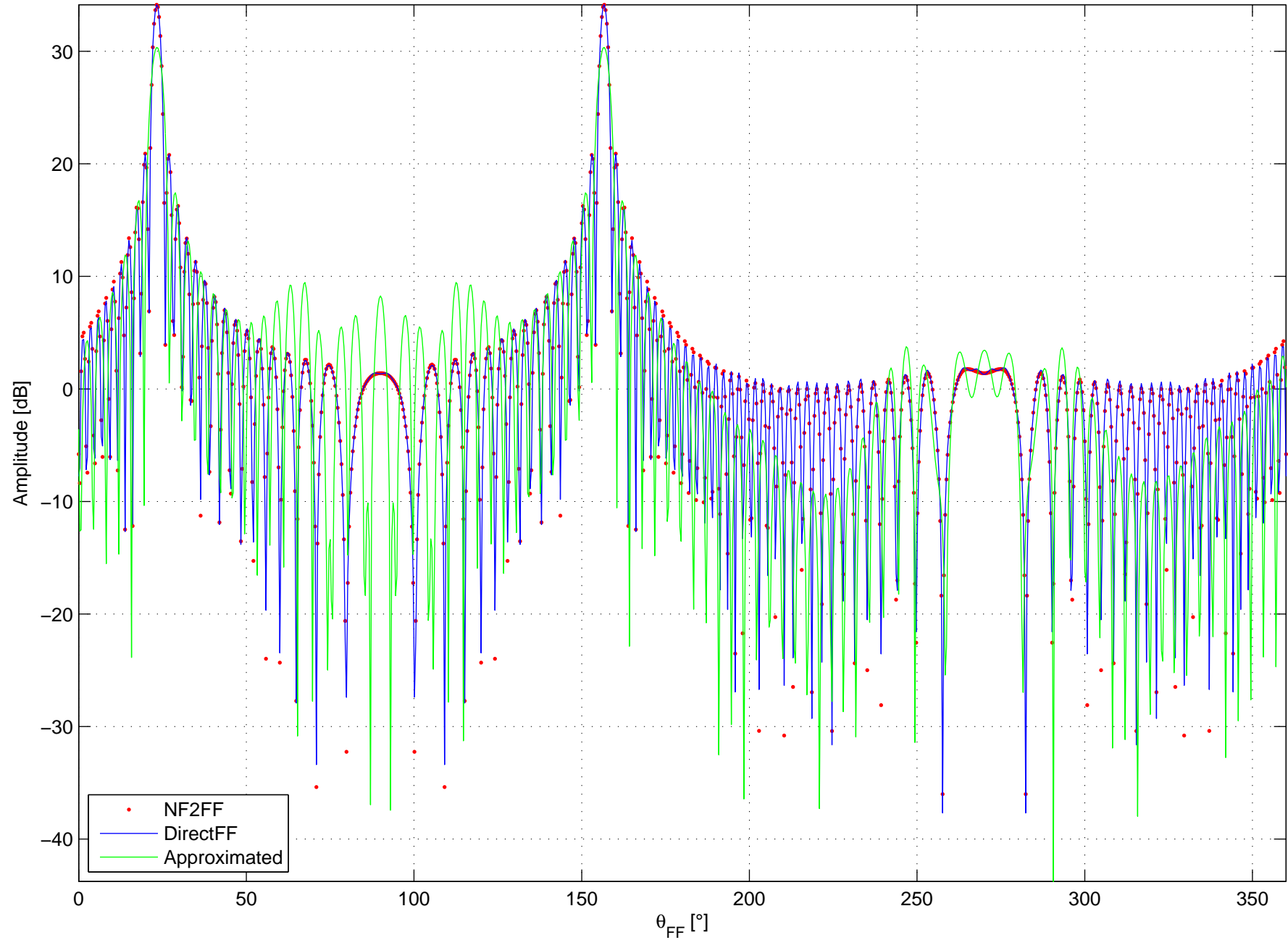
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.5407
FFSamples = 961, NFSamples = 16200, Coefficients = 103



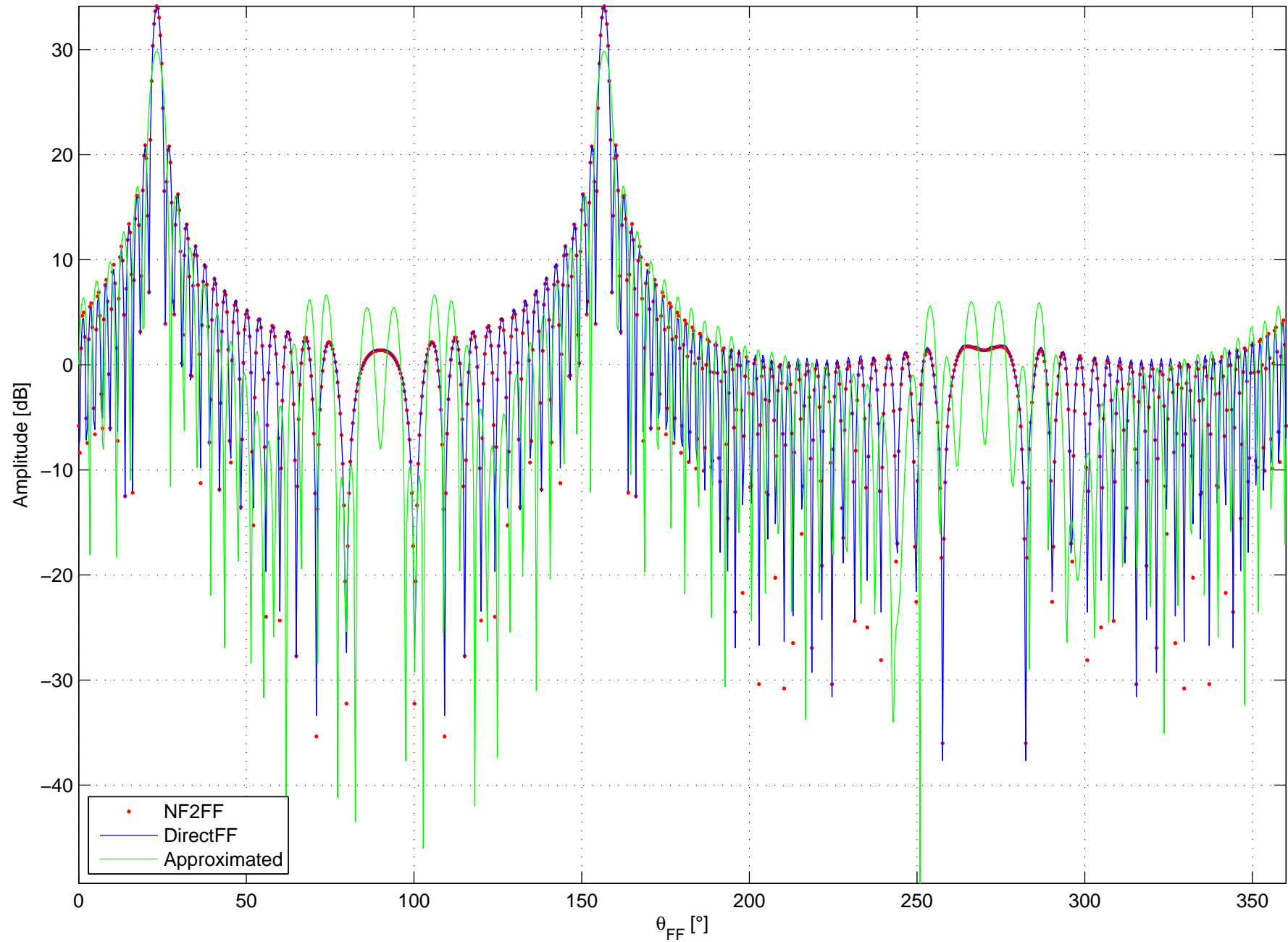
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.55907
FFSamples = 961, NFSamples = 16200, Coefficients = 99



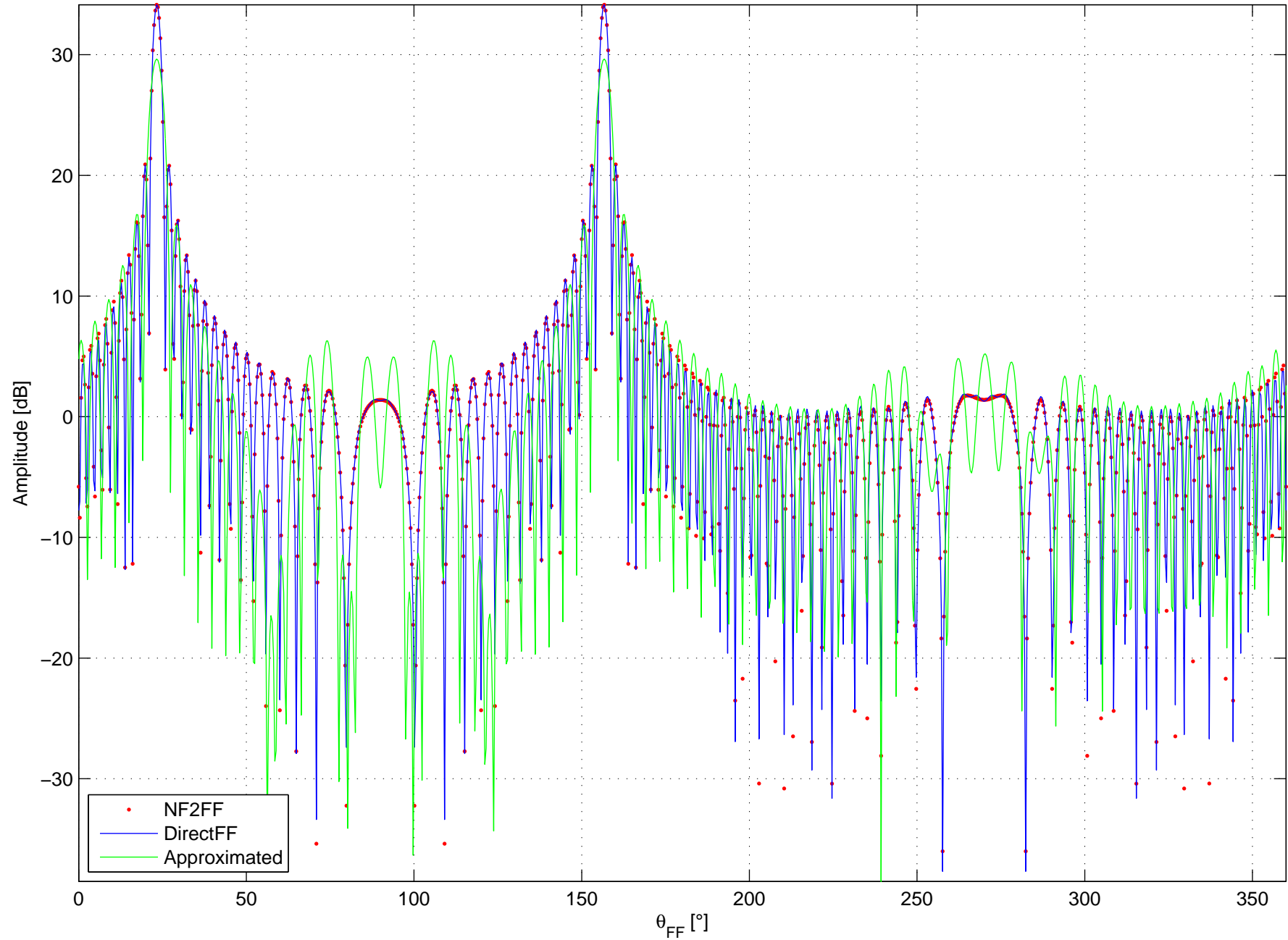
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.58856
FFSamples = 961, NFSamples = 16200, Coefficients = 95



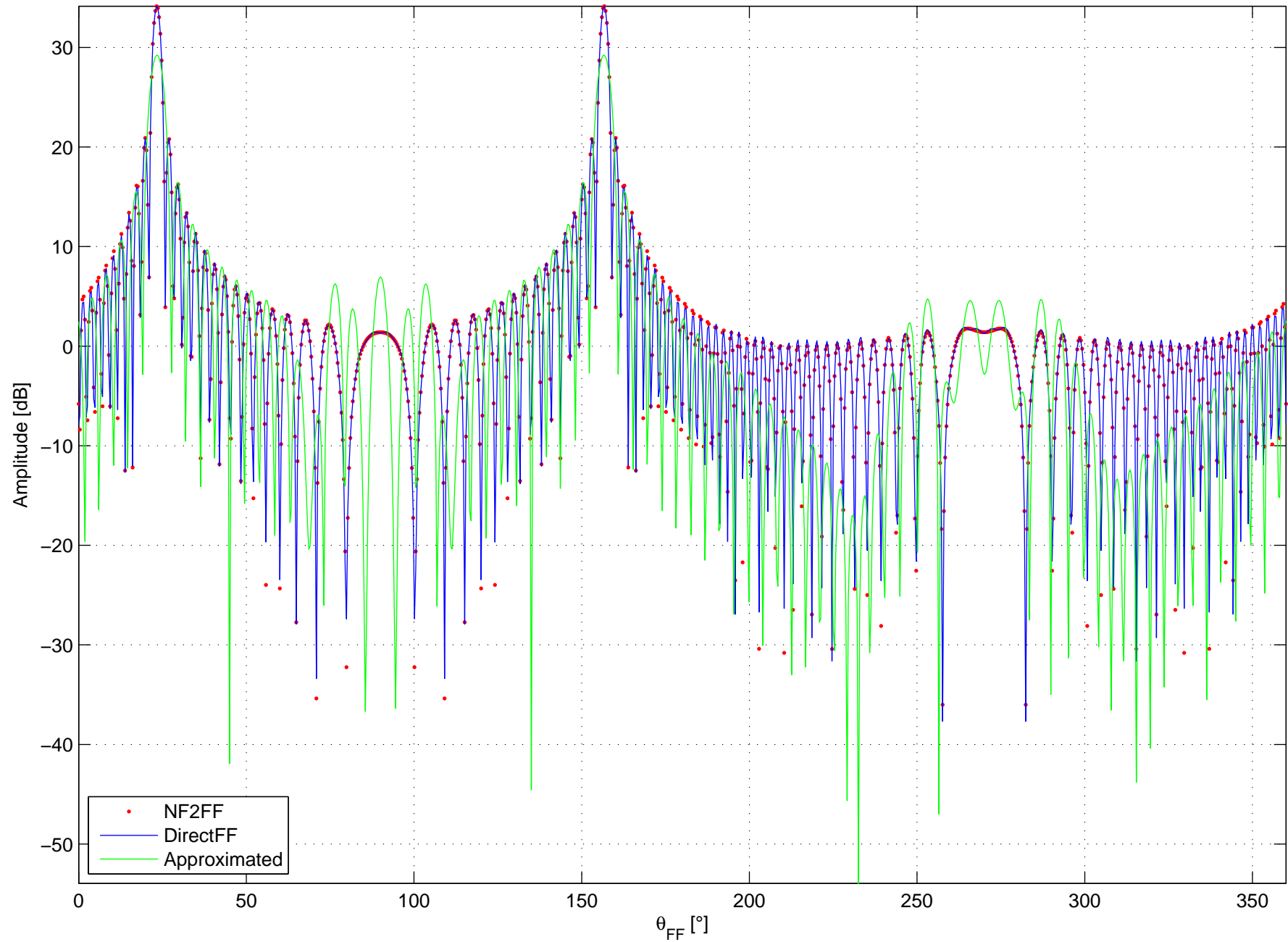
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.62308
FFSamples = 961, NFSamples = 16200, Coefficients = 91



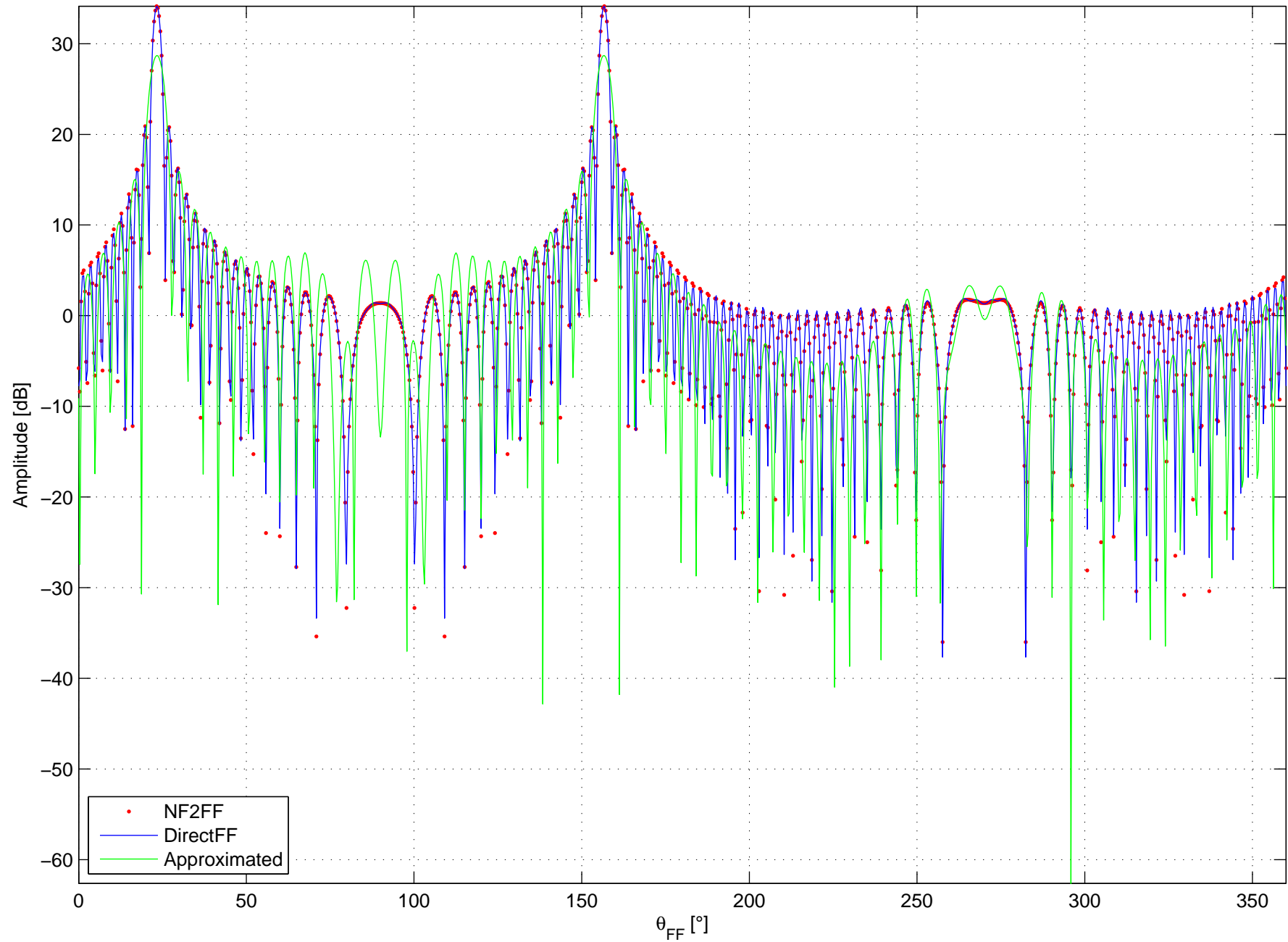
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.63429
FFSamples = 961, NFSamples = 16200, Coefficients = 87



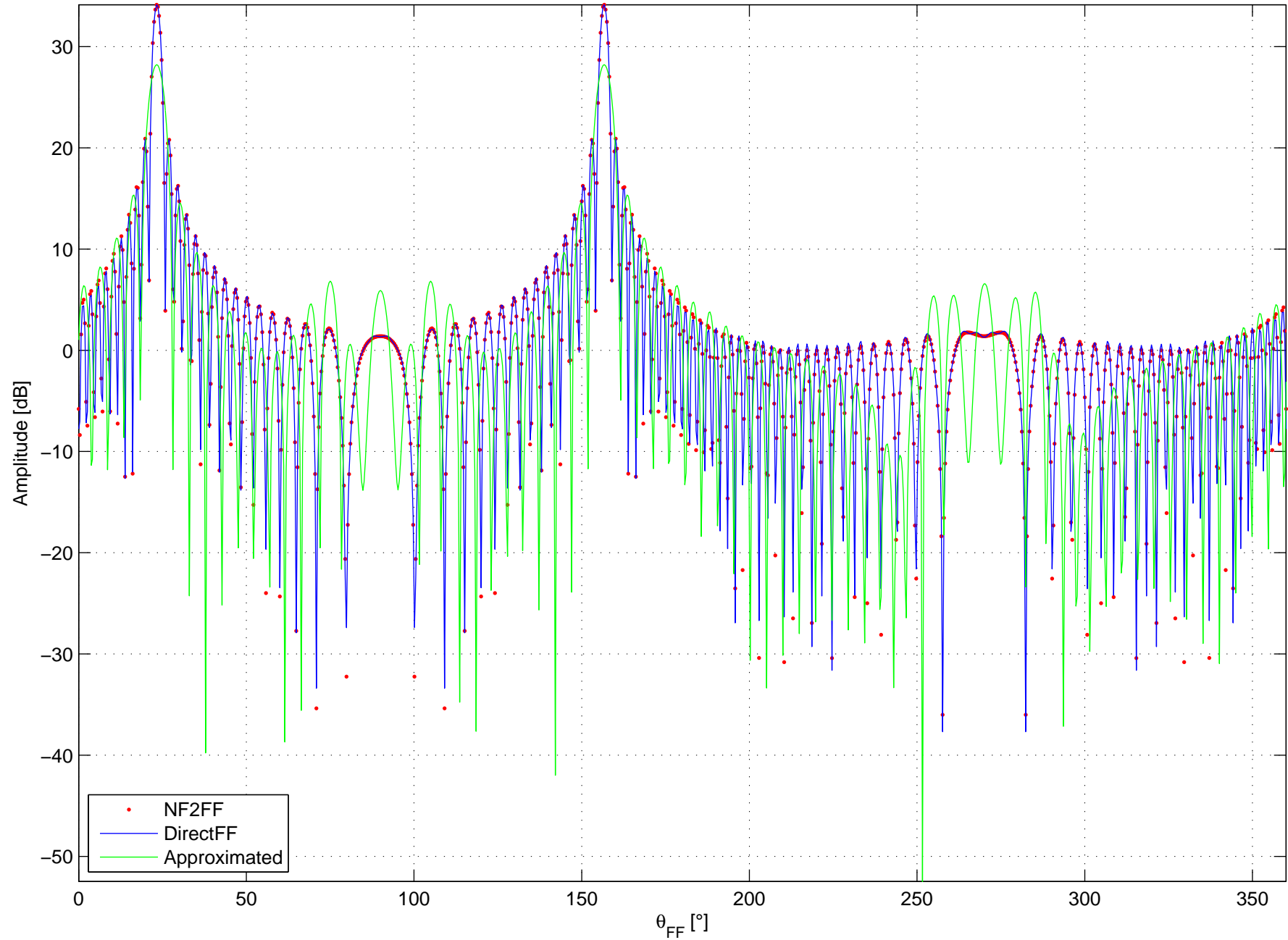
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.65695
FFSamples = 961, NFSamples = 16200, Coefficients = 83



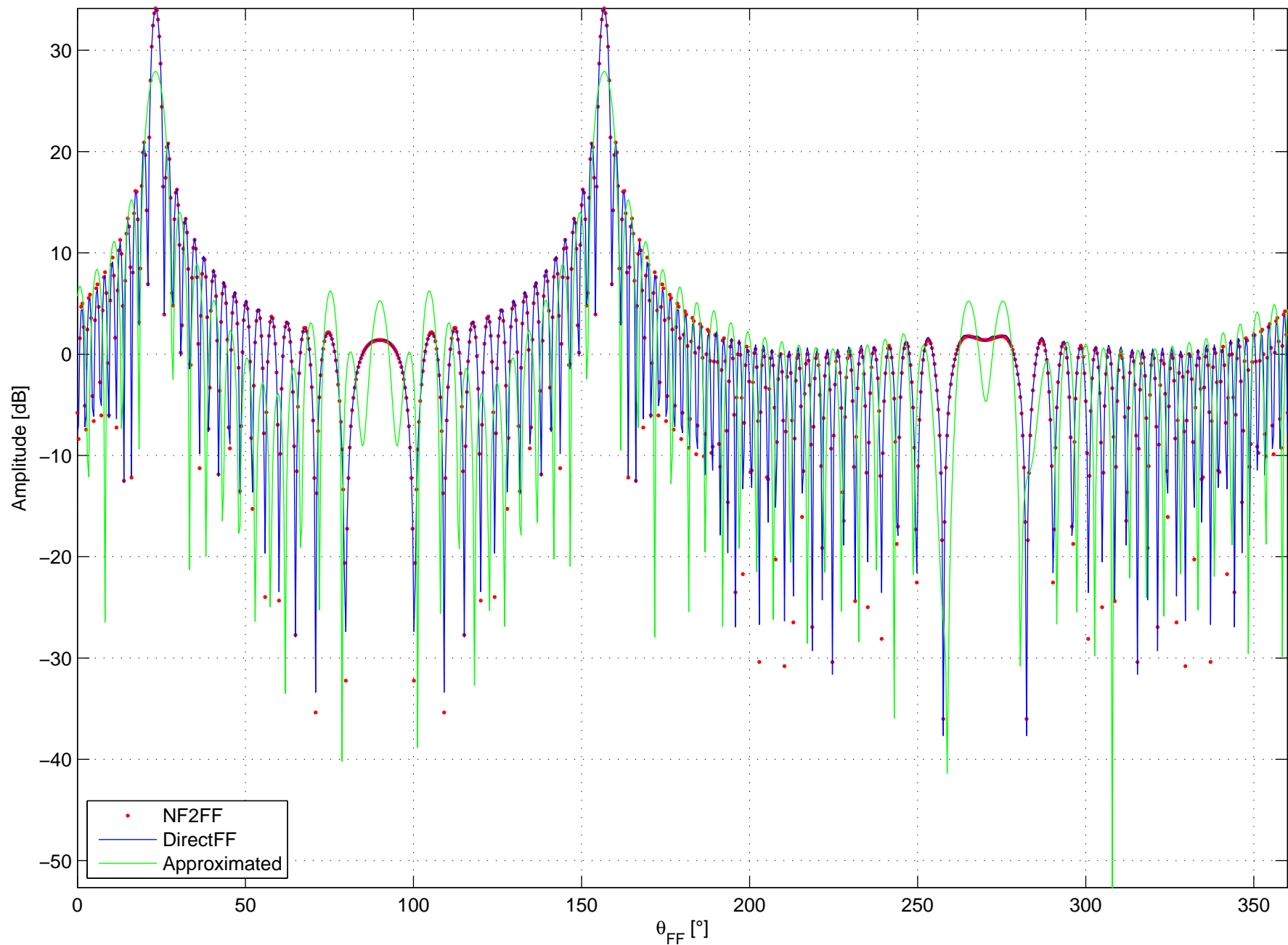
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.67849
FFSamples = 961, NFSamples = 16200, Coefficients = 79



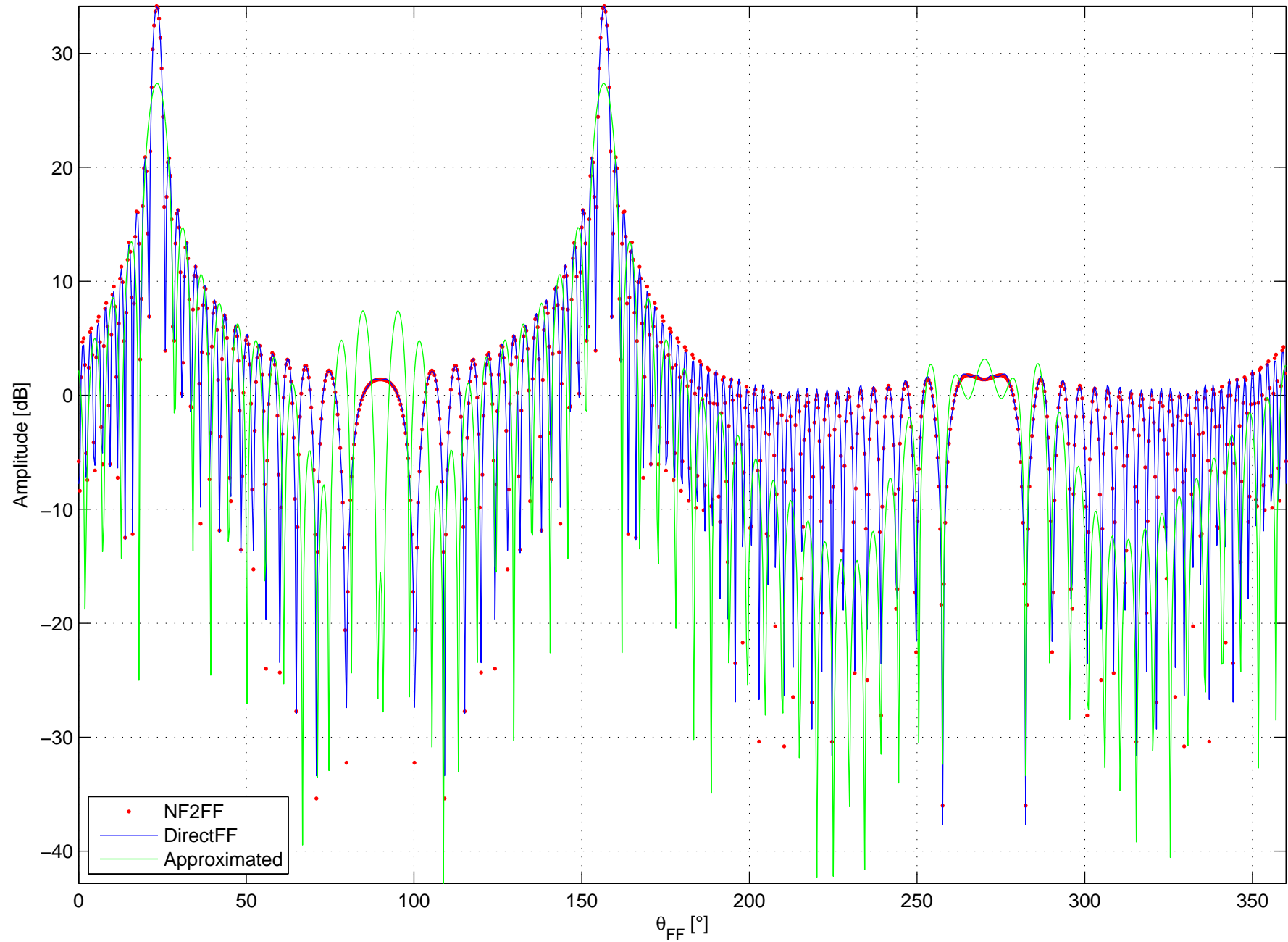
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.70136
FFSamples = 961, NFSamples = 16200, Coefficients = 75



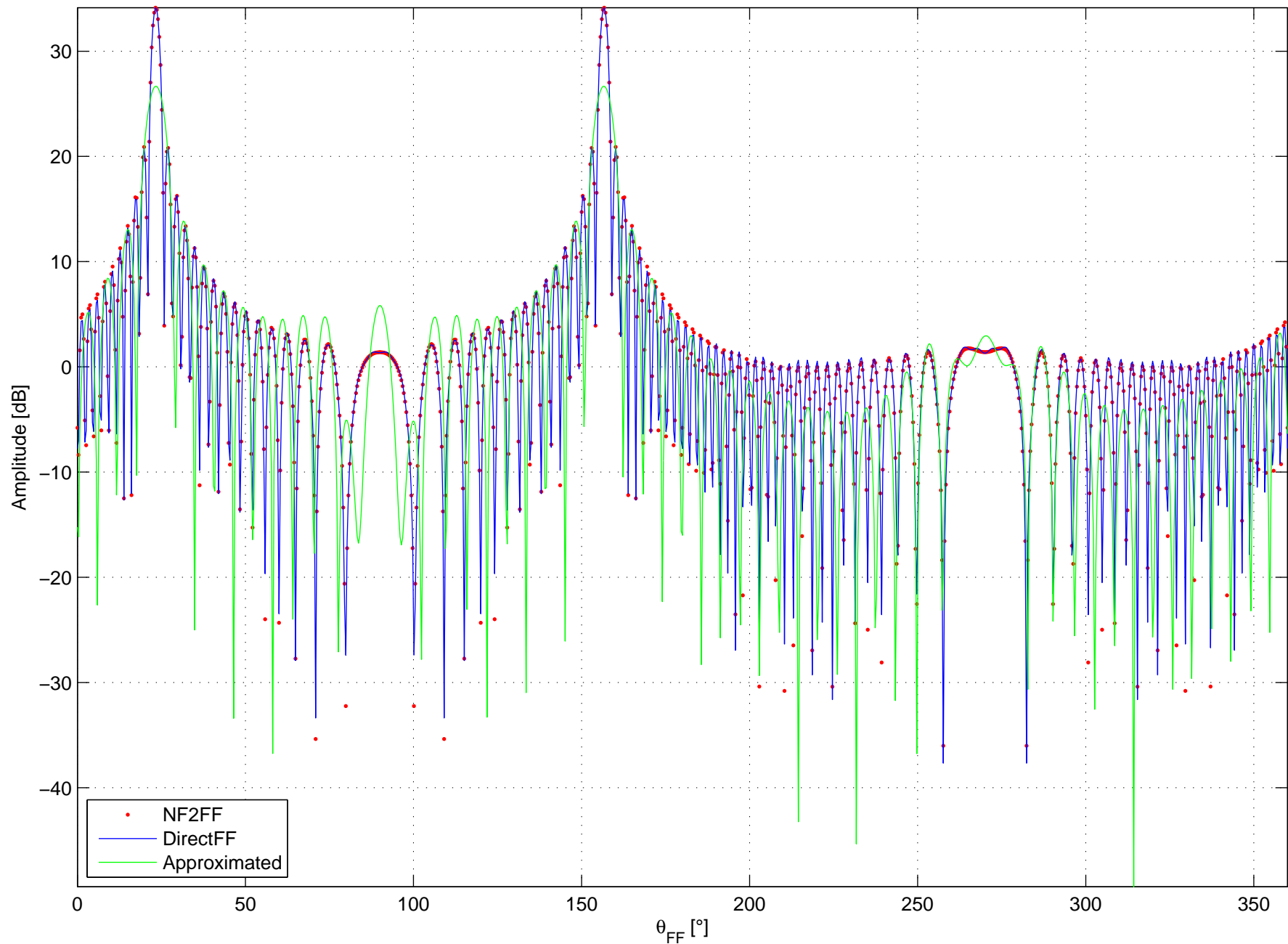
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.71341
FFSamples = 961, NFSamples = 16200, Coefficients = 71



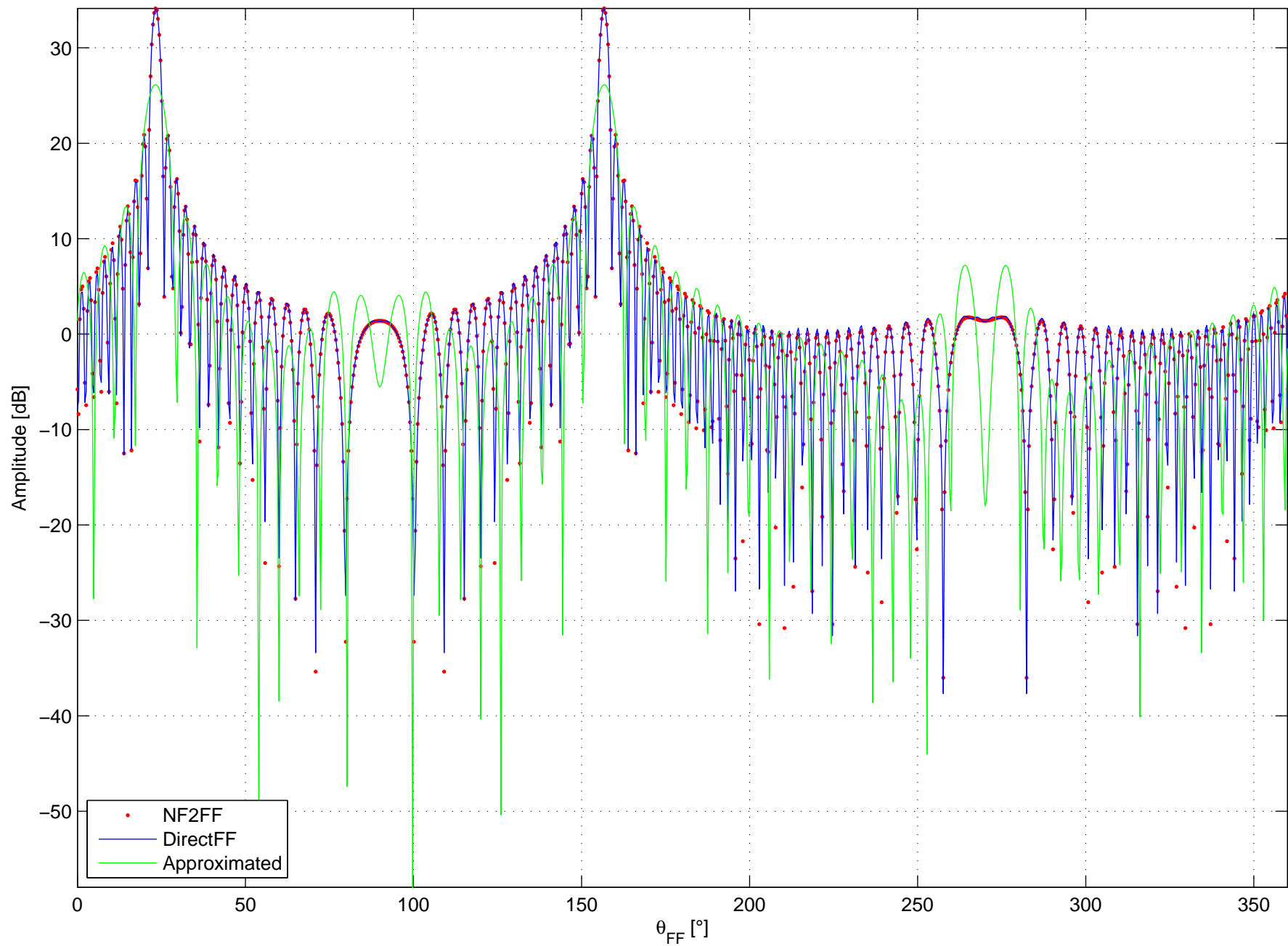
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.73639
FFSamples = 961, NFSamples = 16200, Coefficients = 67



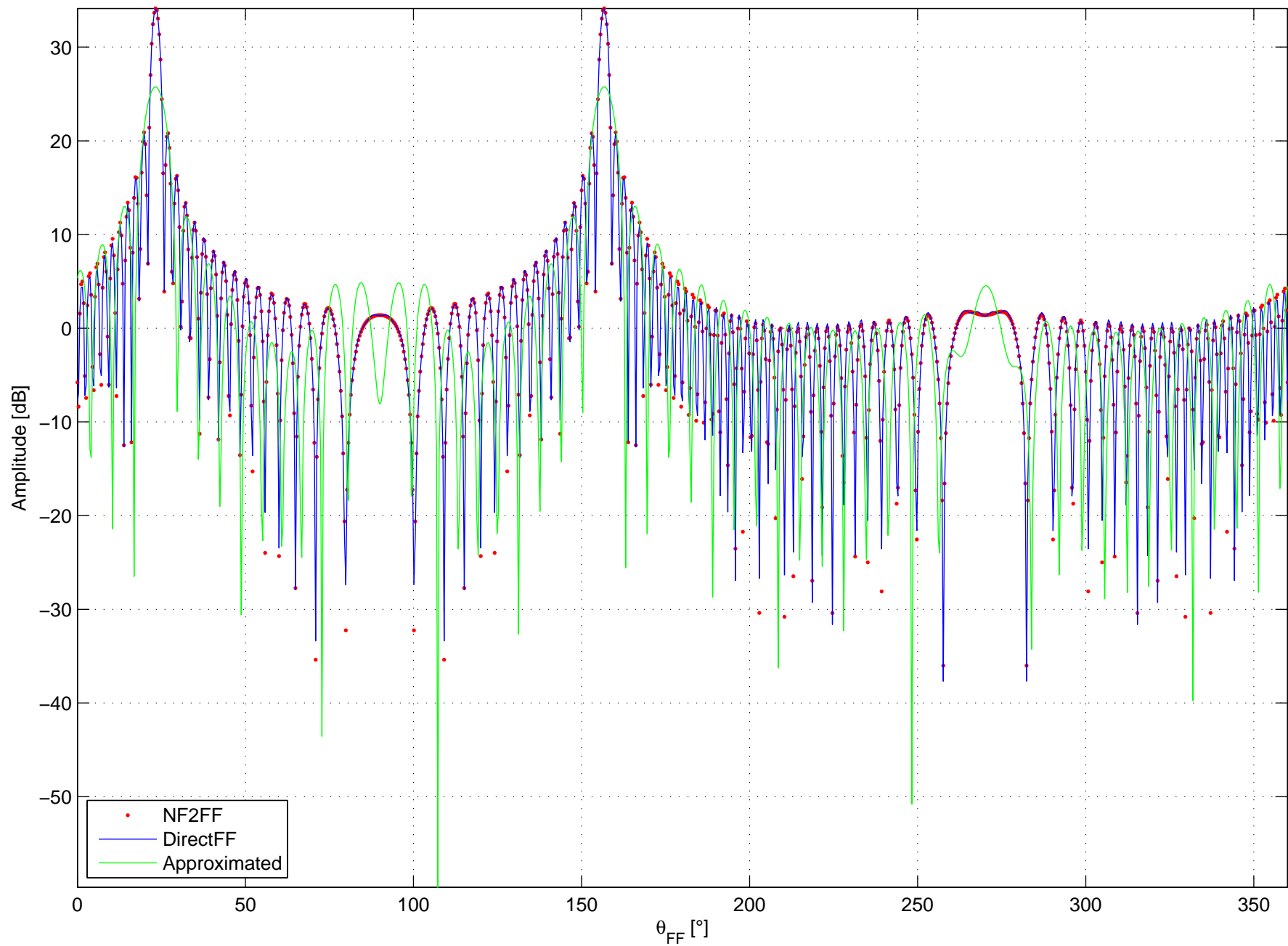
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.75758
FFSamples = 961, NFSamples = 16200, Coefficients = 63



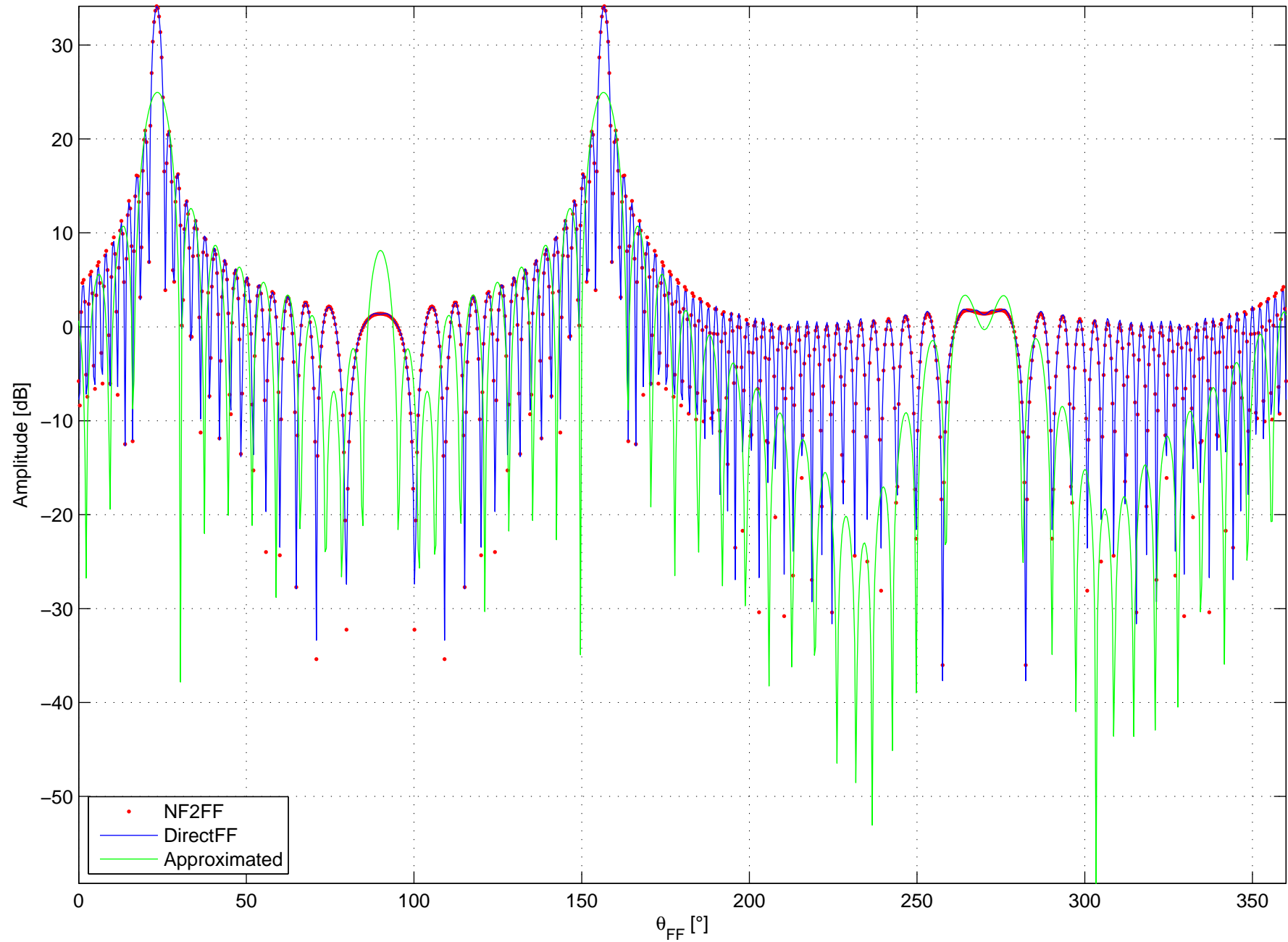
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.77443
FFSamples = 961, NFSamples = 16200, Coefficients = 59



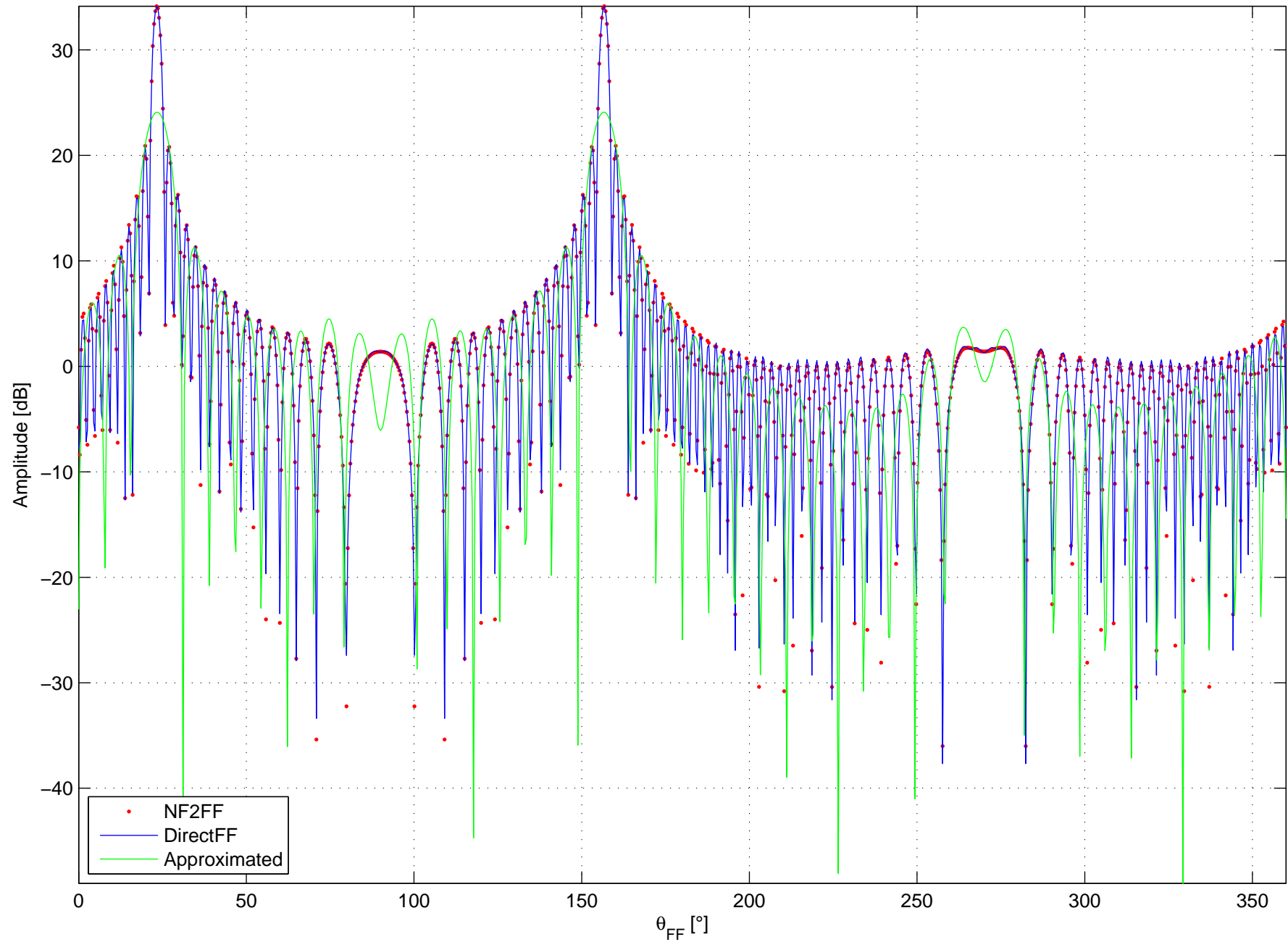
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.78547
FFSamples = 961, NFSamples = 16200, Coefficients = 55



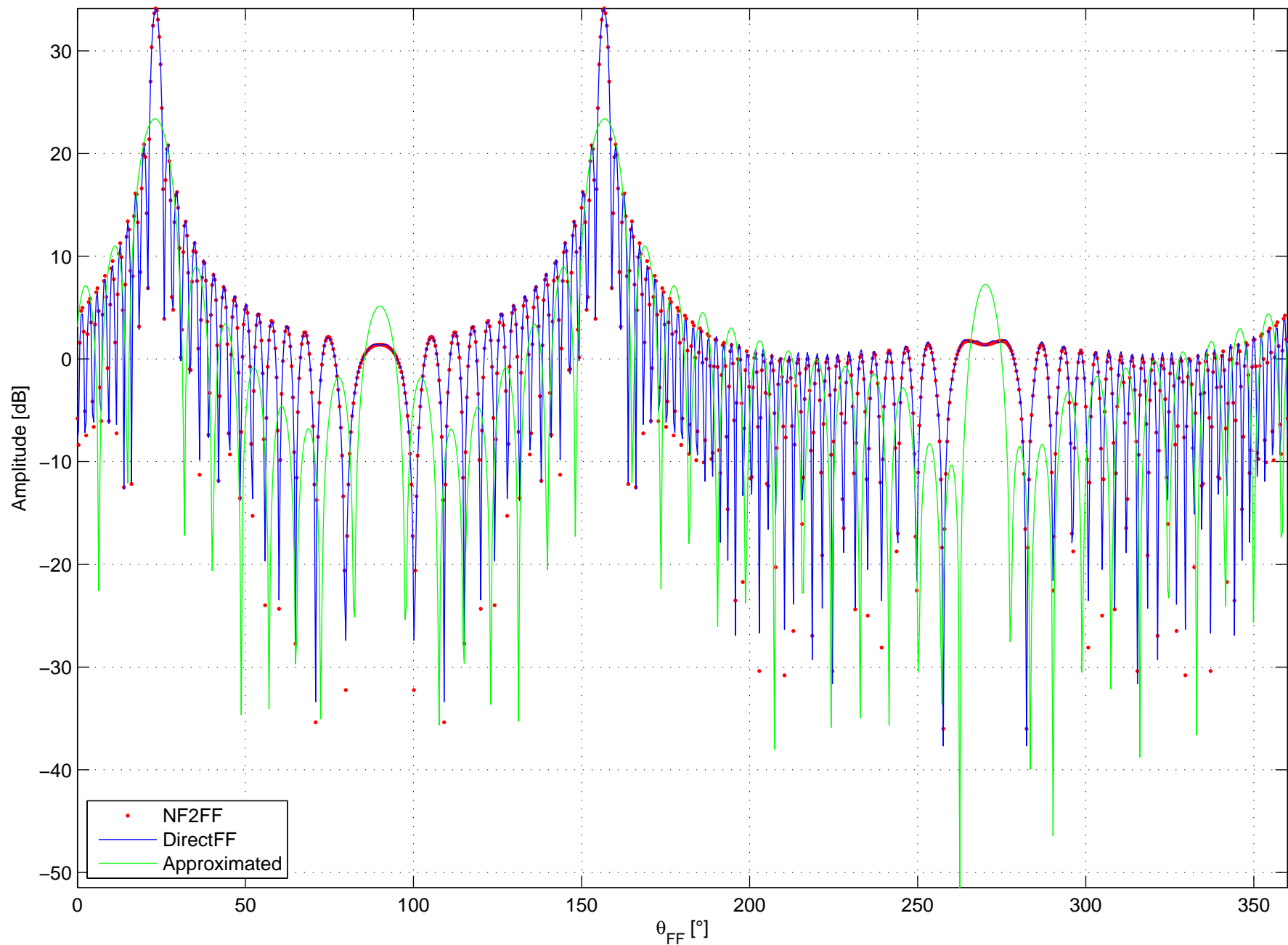
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.80823
FFSamples = 961, NFSamples = 16200, Coefficients = 51



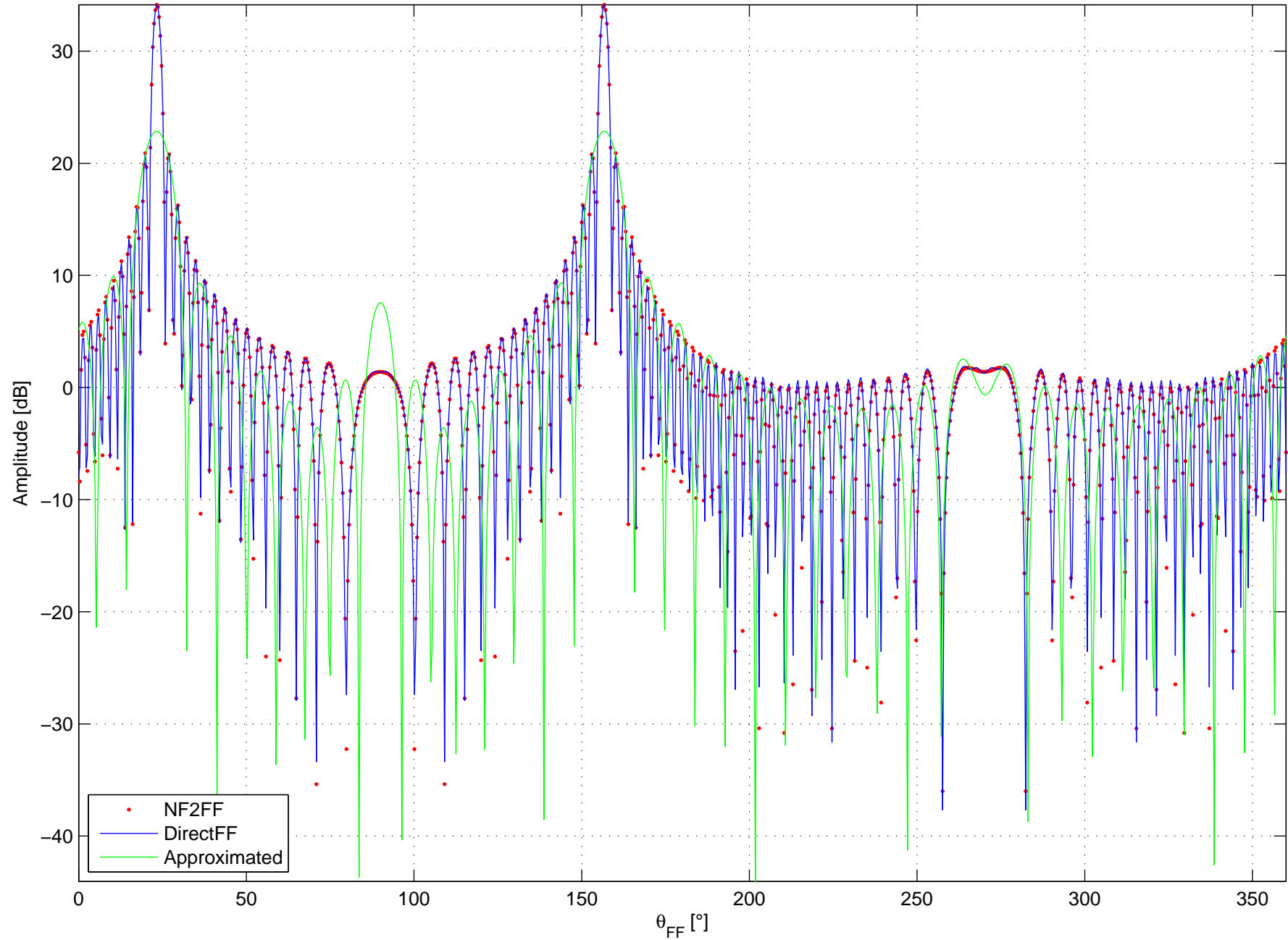
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.82639
FFSamples = 961, NFSamples = 16200, Coefficients = 47



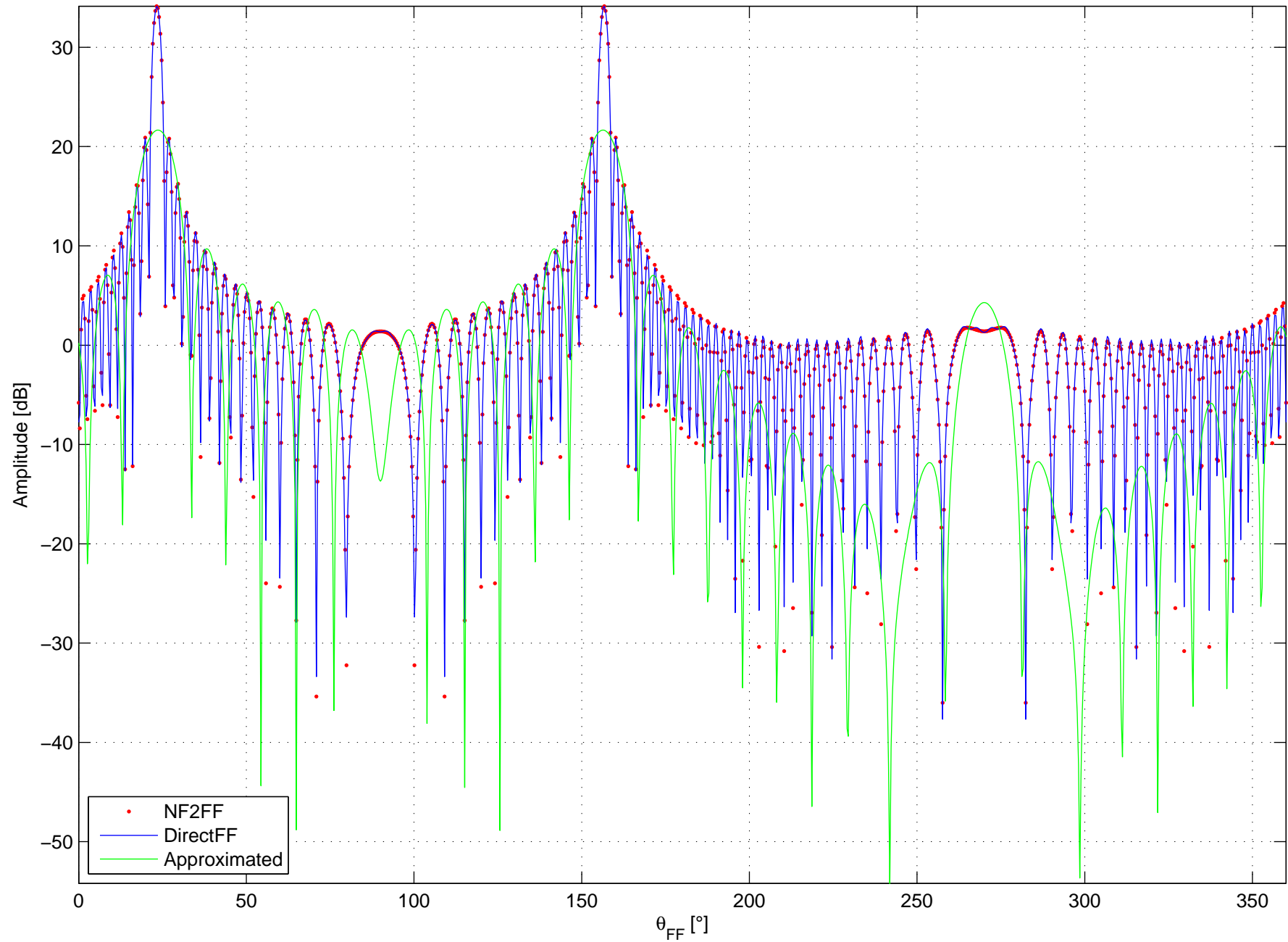
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.84265
FFSamples = 961, NFSamples = 16200, Coefficients = 43



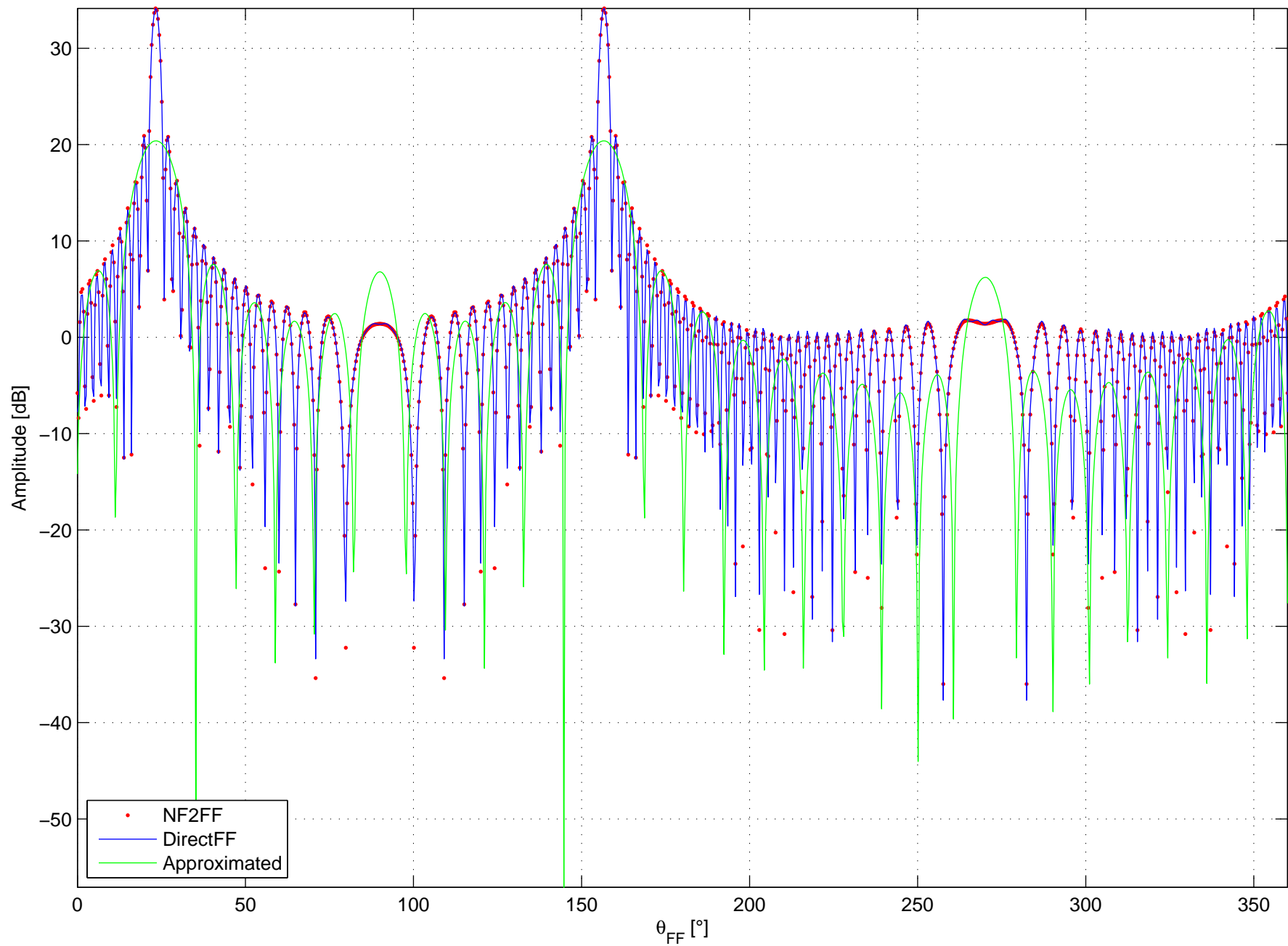
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.85195
FFSamples = 961, NFSamples = 16200, Coefficients = 39



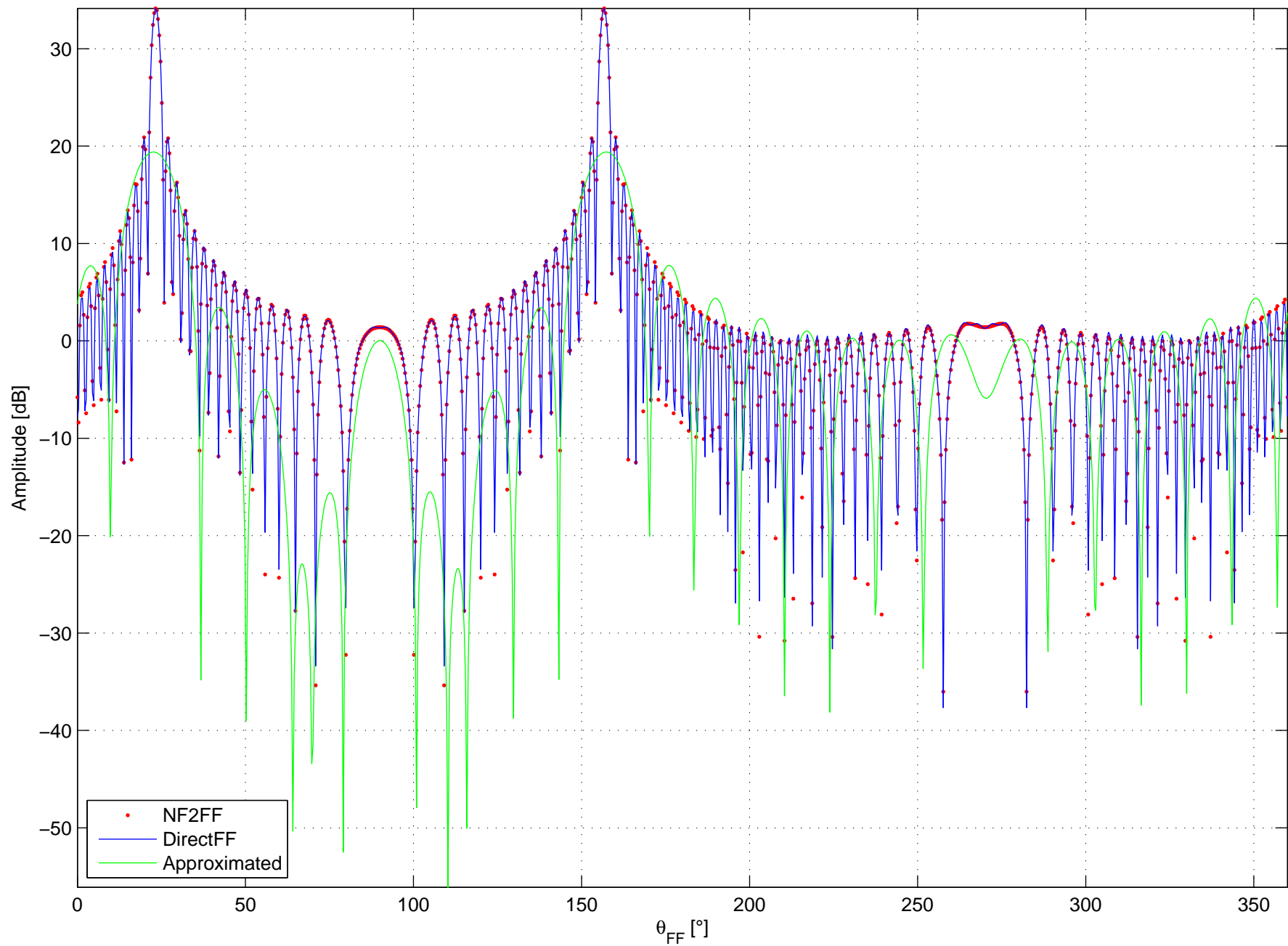
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.87333
FFSamples = 961, NFSamples = 16200, Coefficients = 35



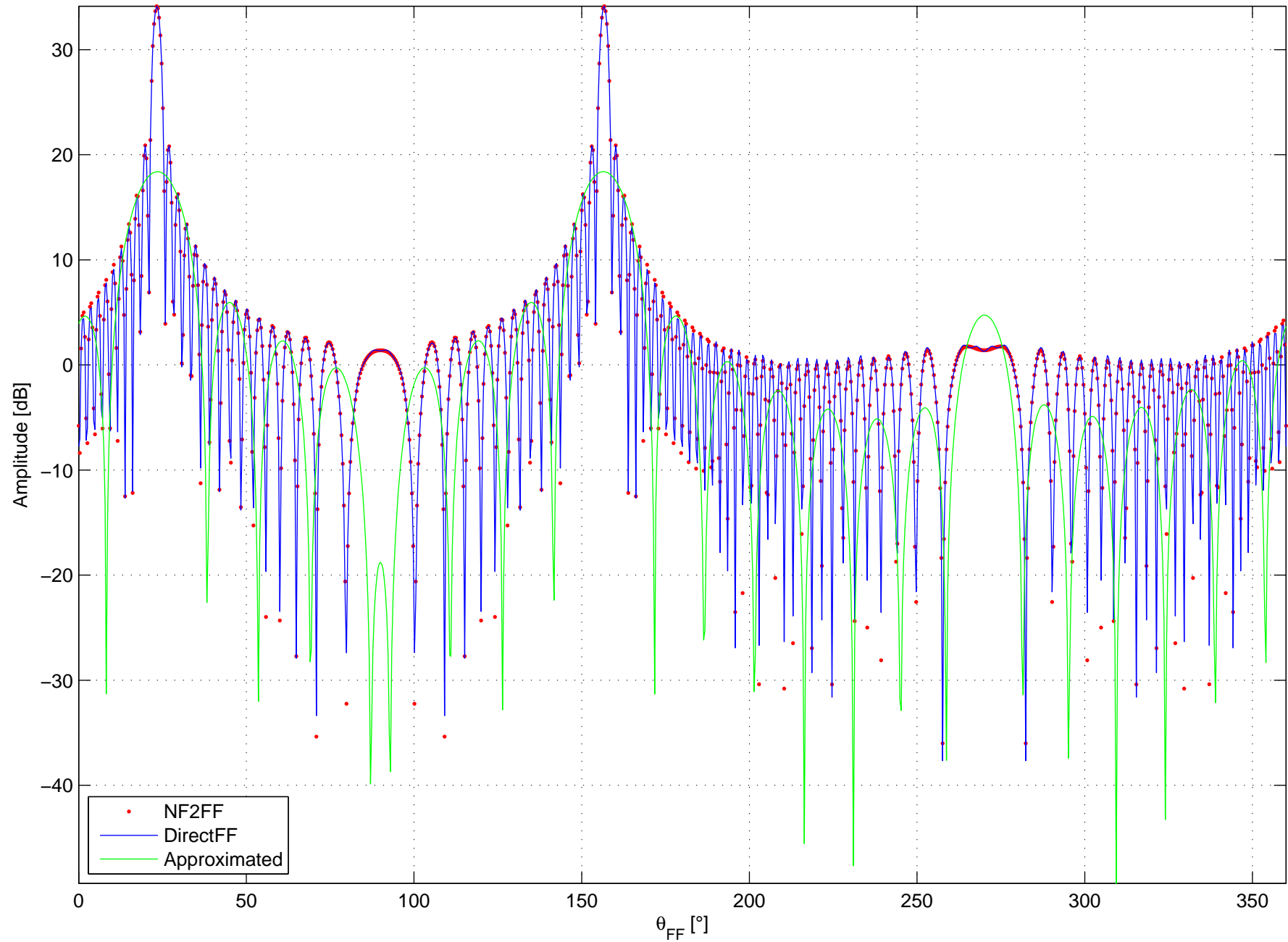
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.88956
FFSamples = 961, NFSamples = 16200, Coefficients = 31



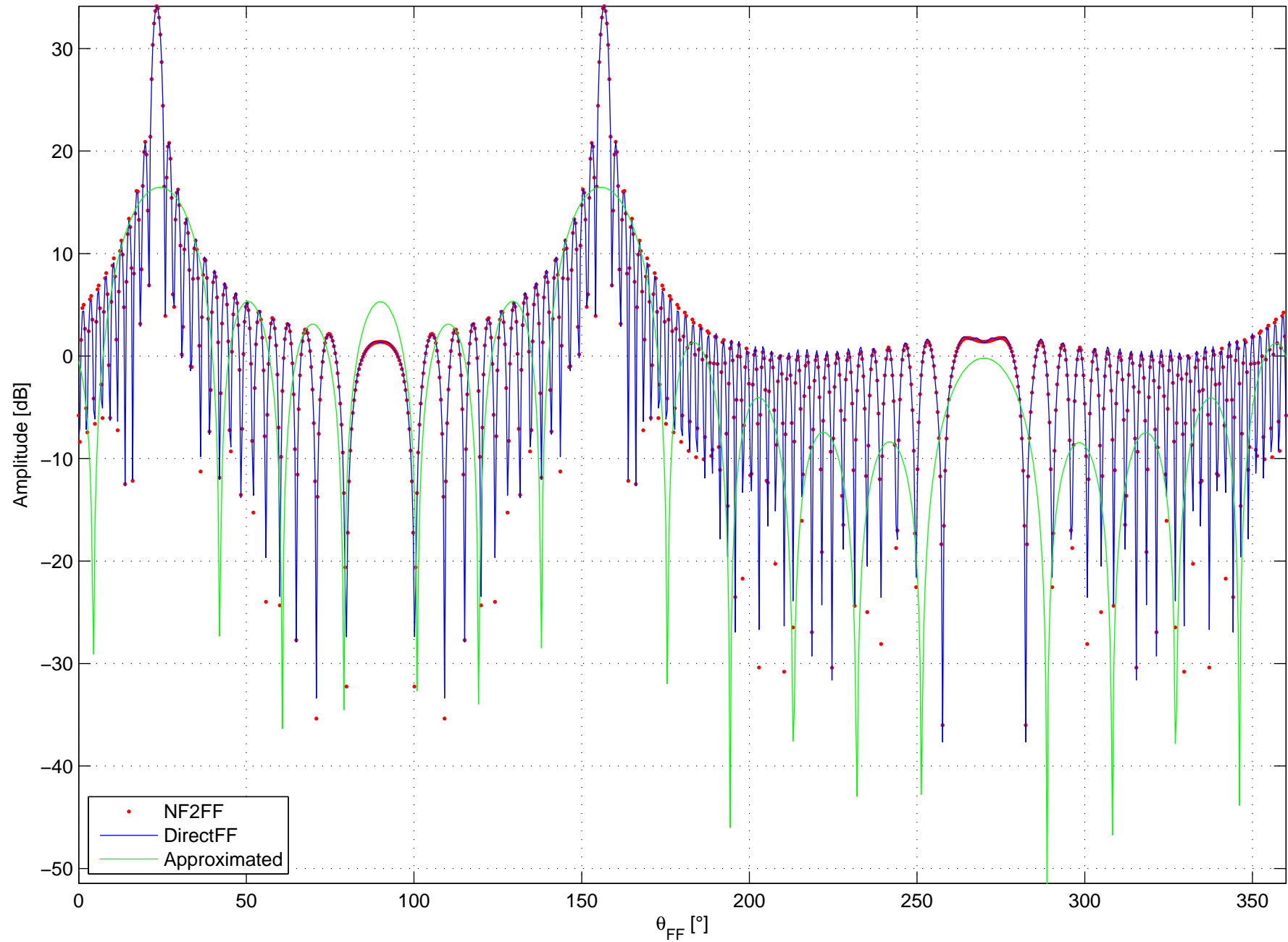
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.90426
FFSamples = 961, NFSamples = 16200, Coefficients = 27



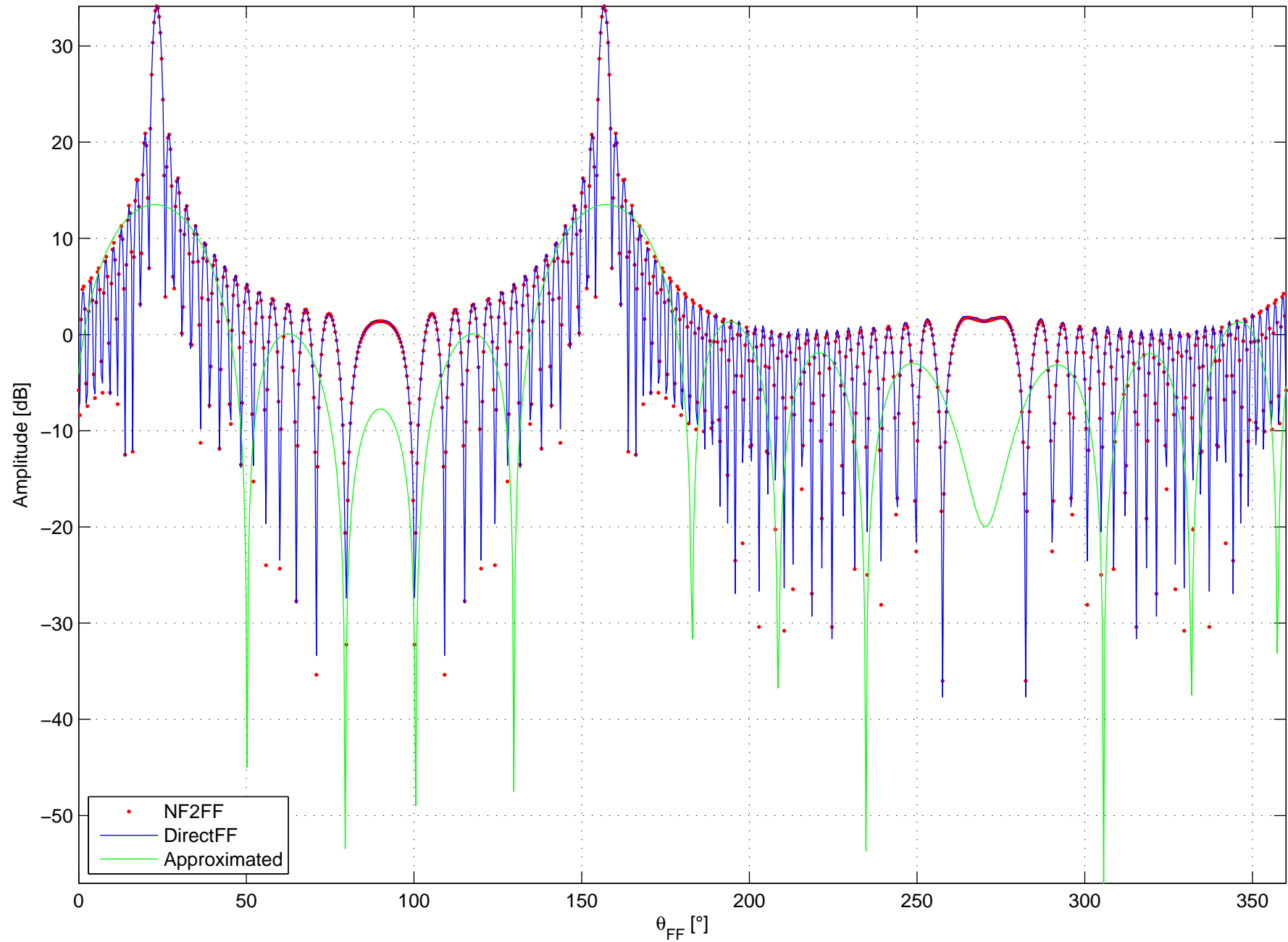
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.9148
FFSamples = 961, NFSamples = 16200, Coefficients = 23



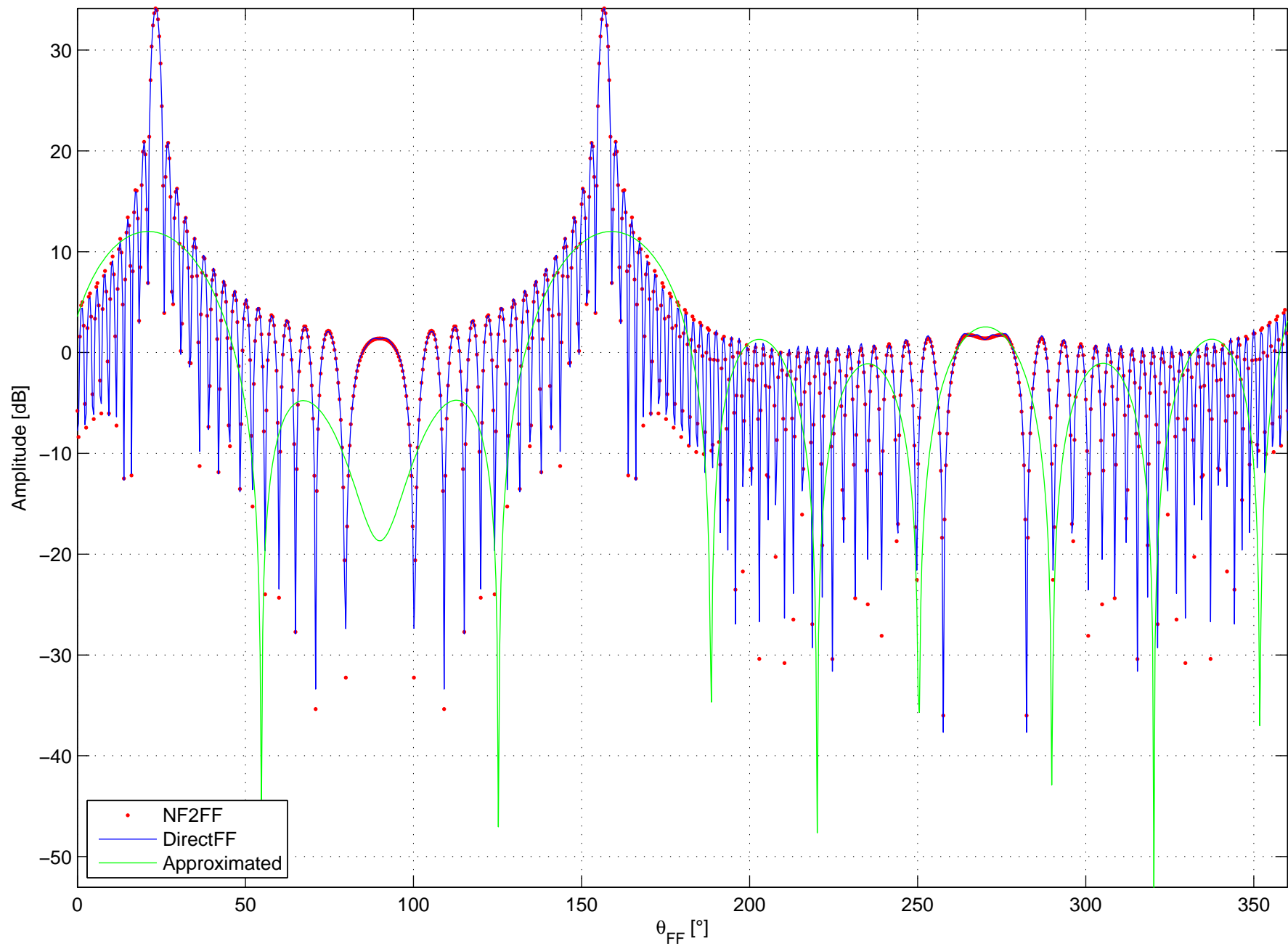
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.93145
FFSamples = 961, NFSamples = 16200, Coefficients = 19



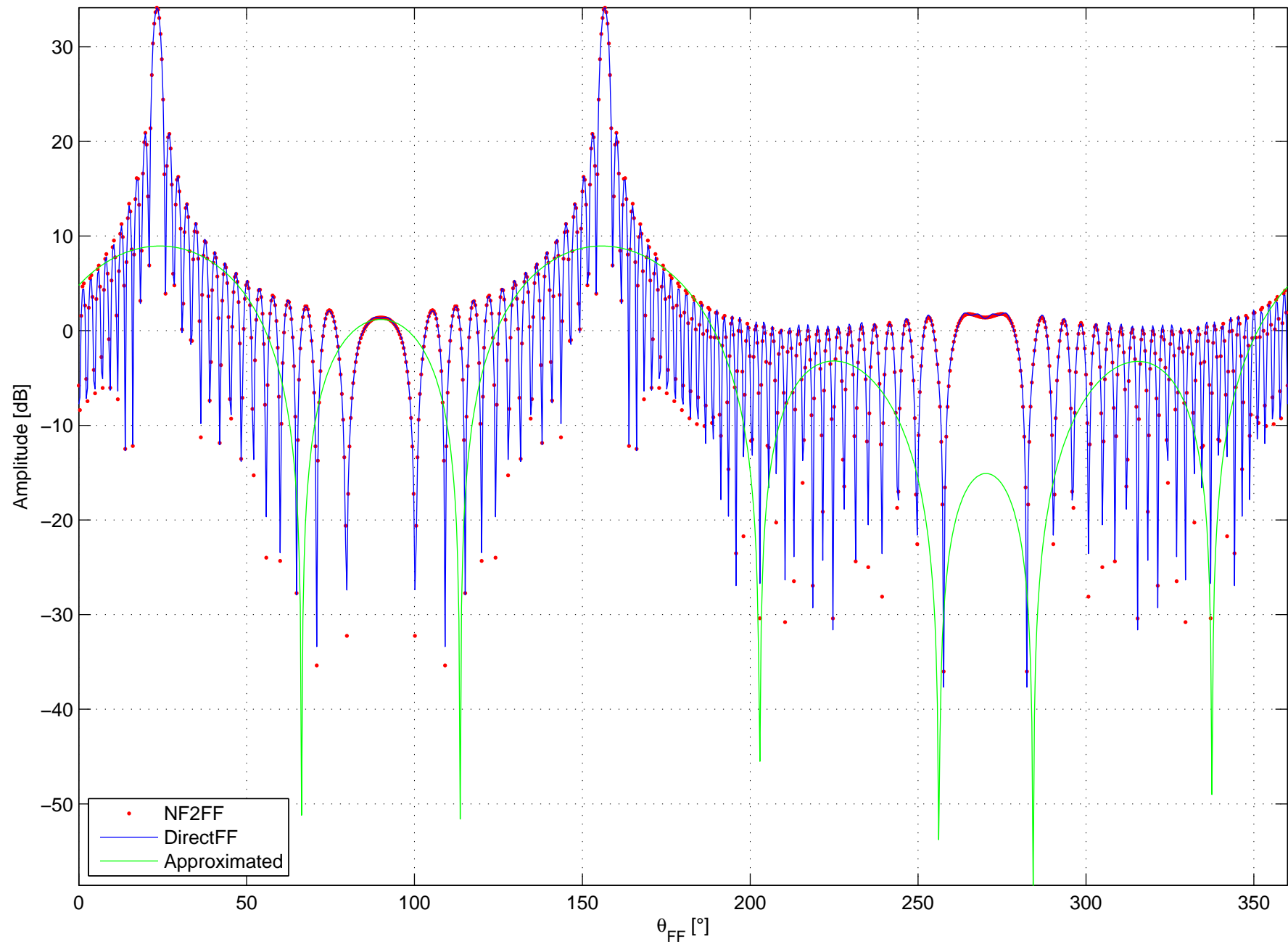
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.95316
FFSamples = 961, NFSamples = 16200, Coefficients = 15



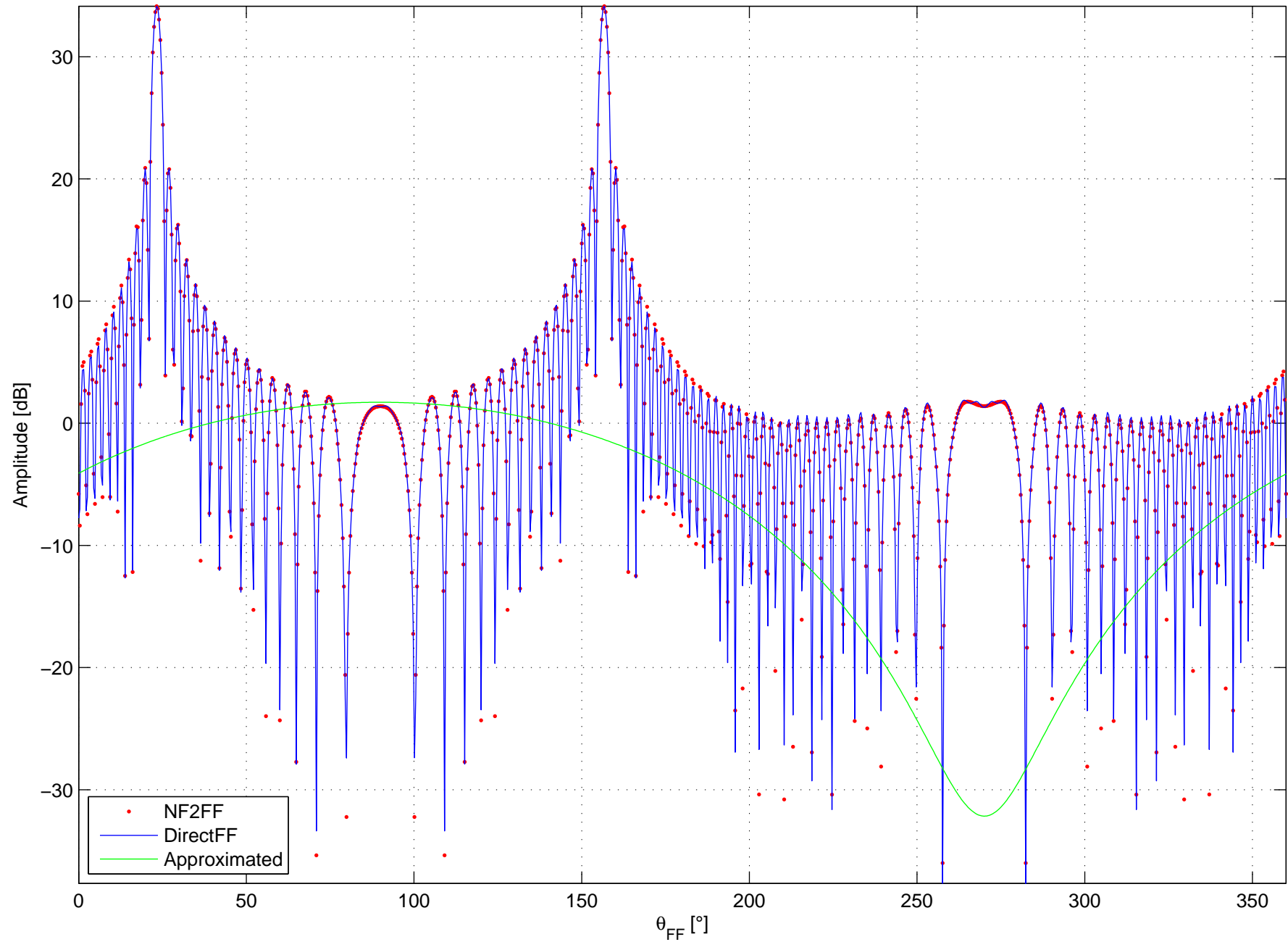
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.95981
FFSamples = 961, NFSamples = 16200, Coefficients = 11



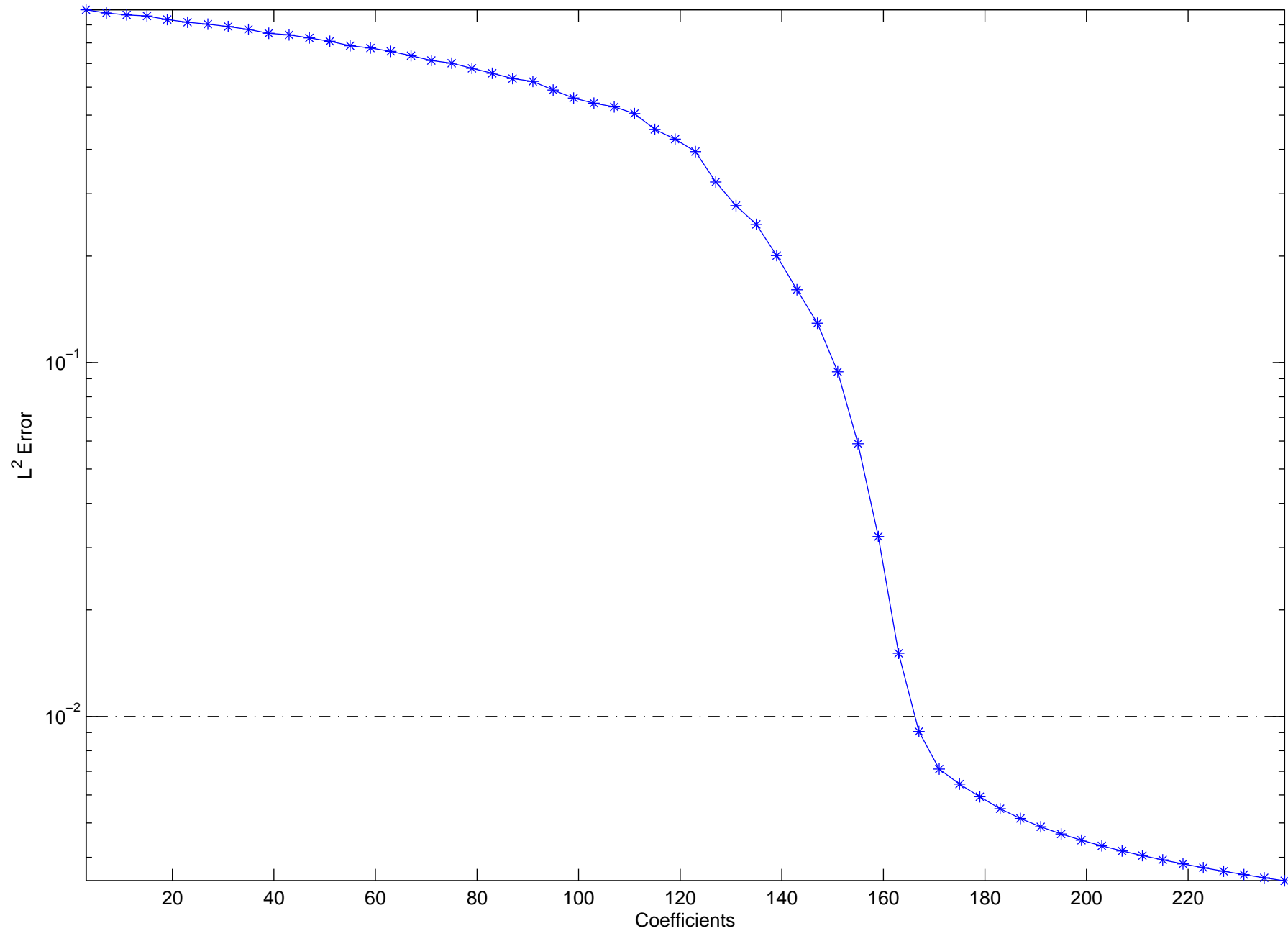
51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.97201
FFSamples = 961, NFSamples = 16200, Coefficients = 7



51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.99206
FFSamples = 961, NFSamples = 16200, Coefficients = 3



51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 0.99206
FFSamples = 961, NFSamples = 16200, Coefficients = 3



51 x 0.5 λ , Rad : 13 λ
Steering angle : 23.3251°, L² error = 2.7253e-015
FFSamples = 961, NFSamples = 16200, Coefficients = 963

