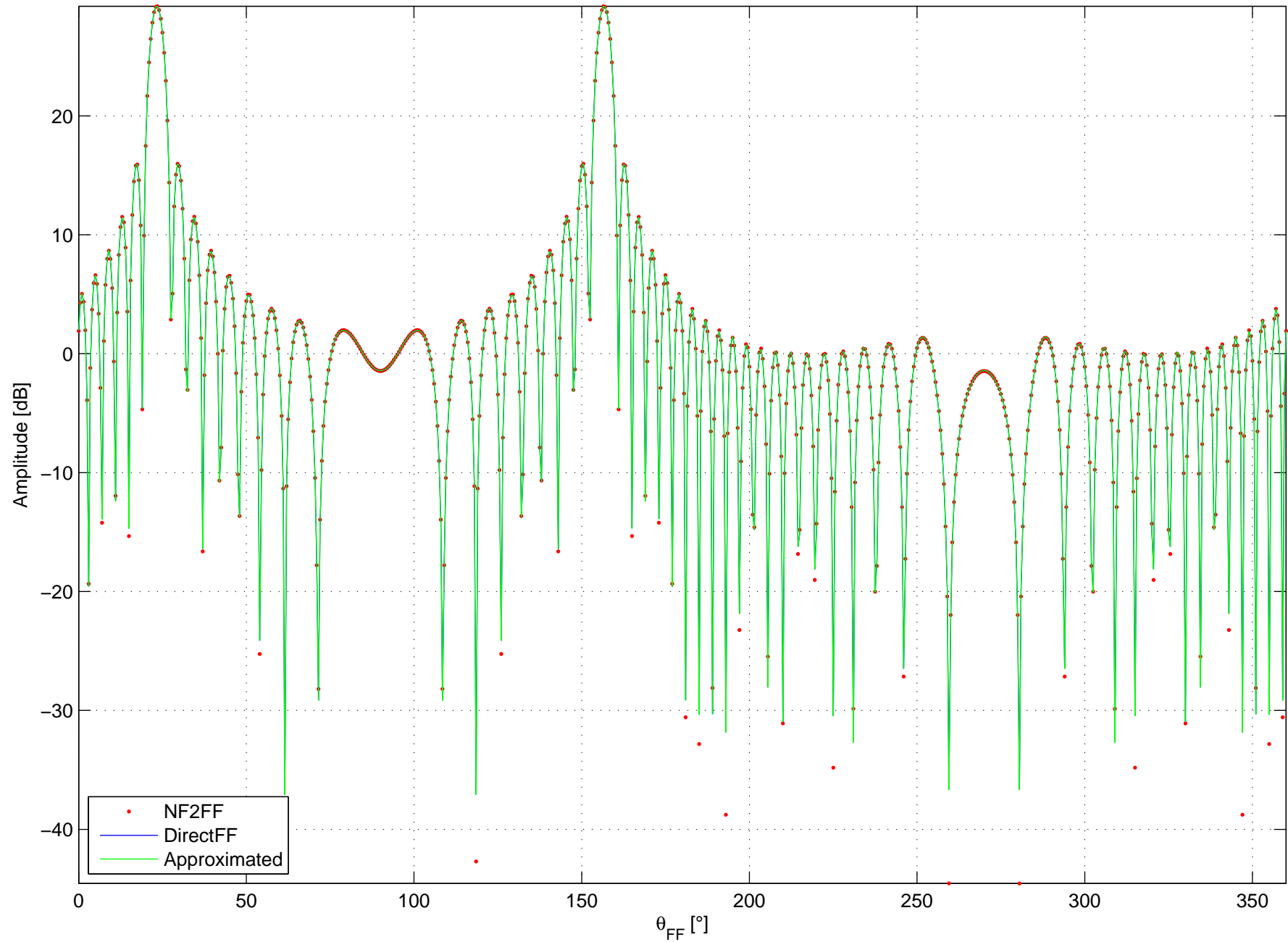
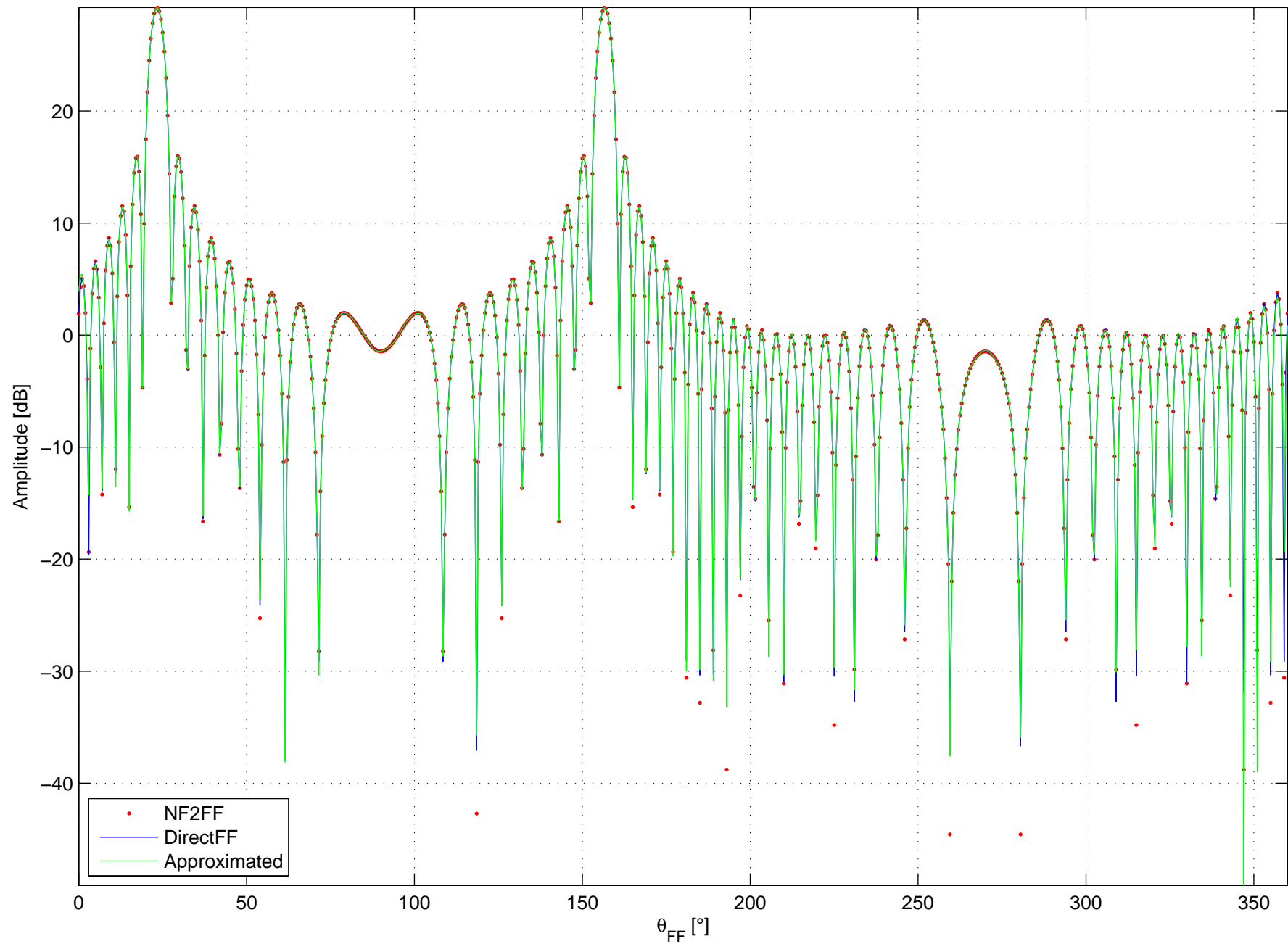


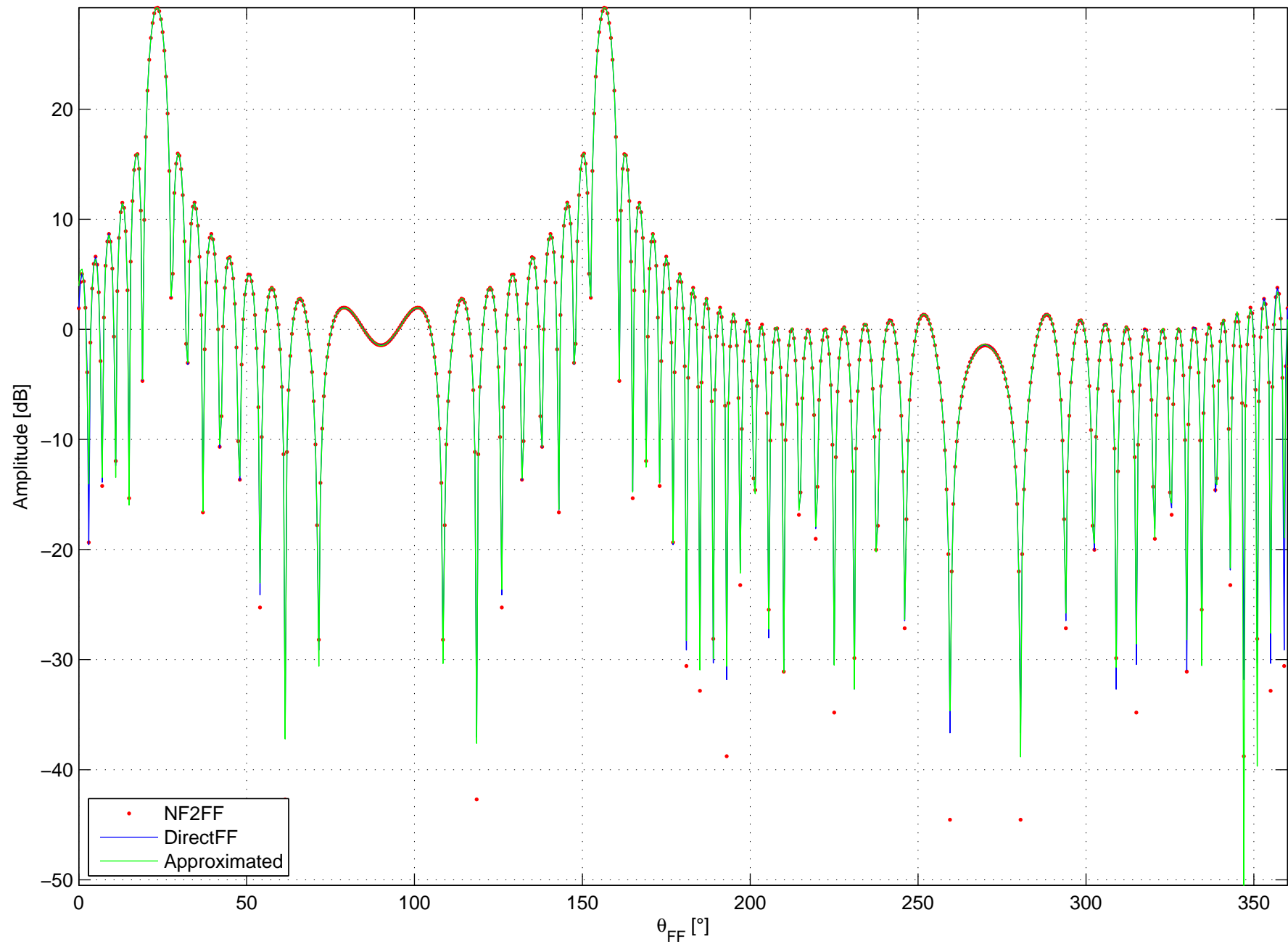
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 2.1339e-015  
FFSamples = 721, NFSamples = 16200, Coefficients = 723



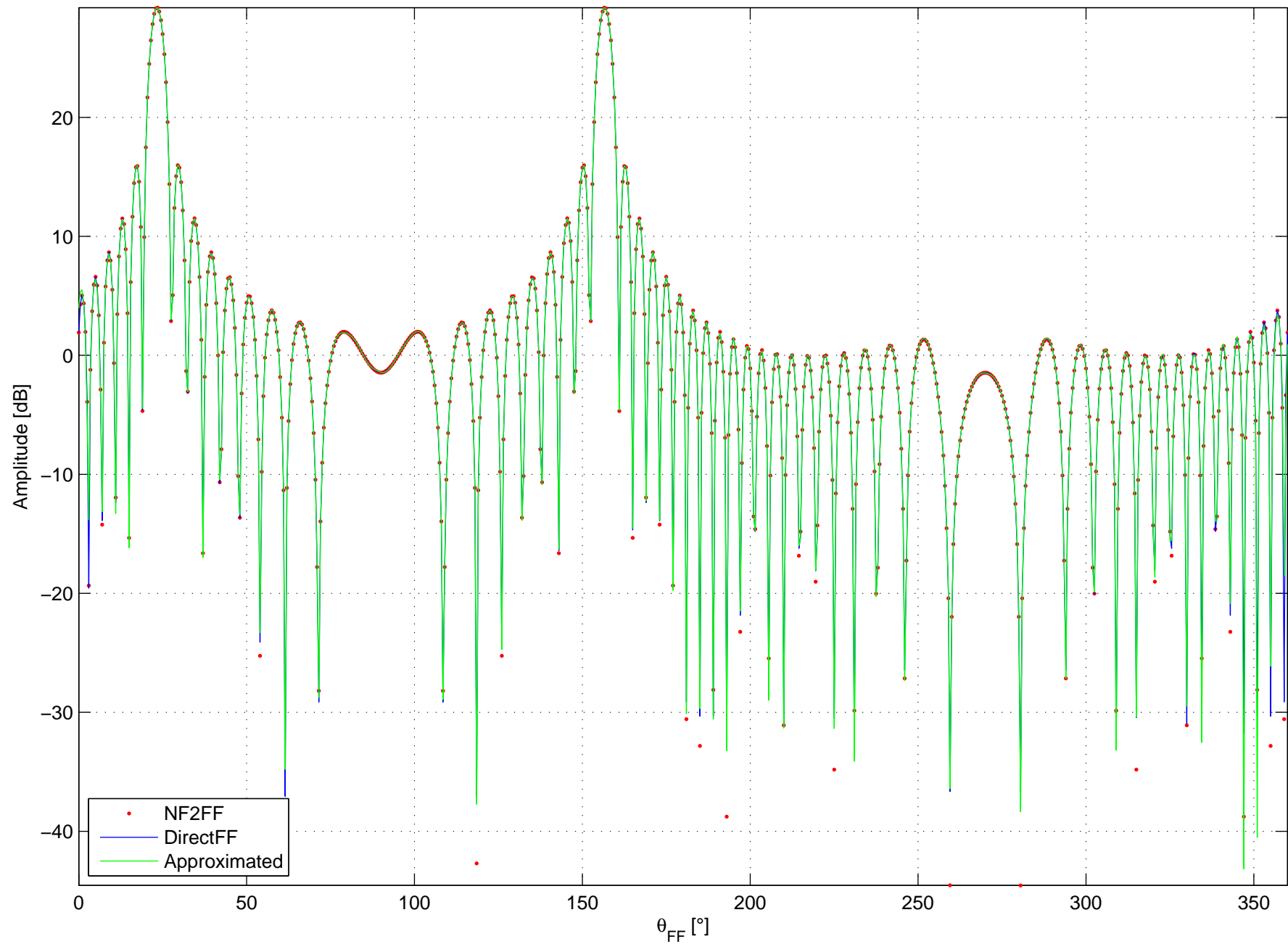
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.0047075  
FFSamples = 721, NFSamples = 16200, Coefficients = 121



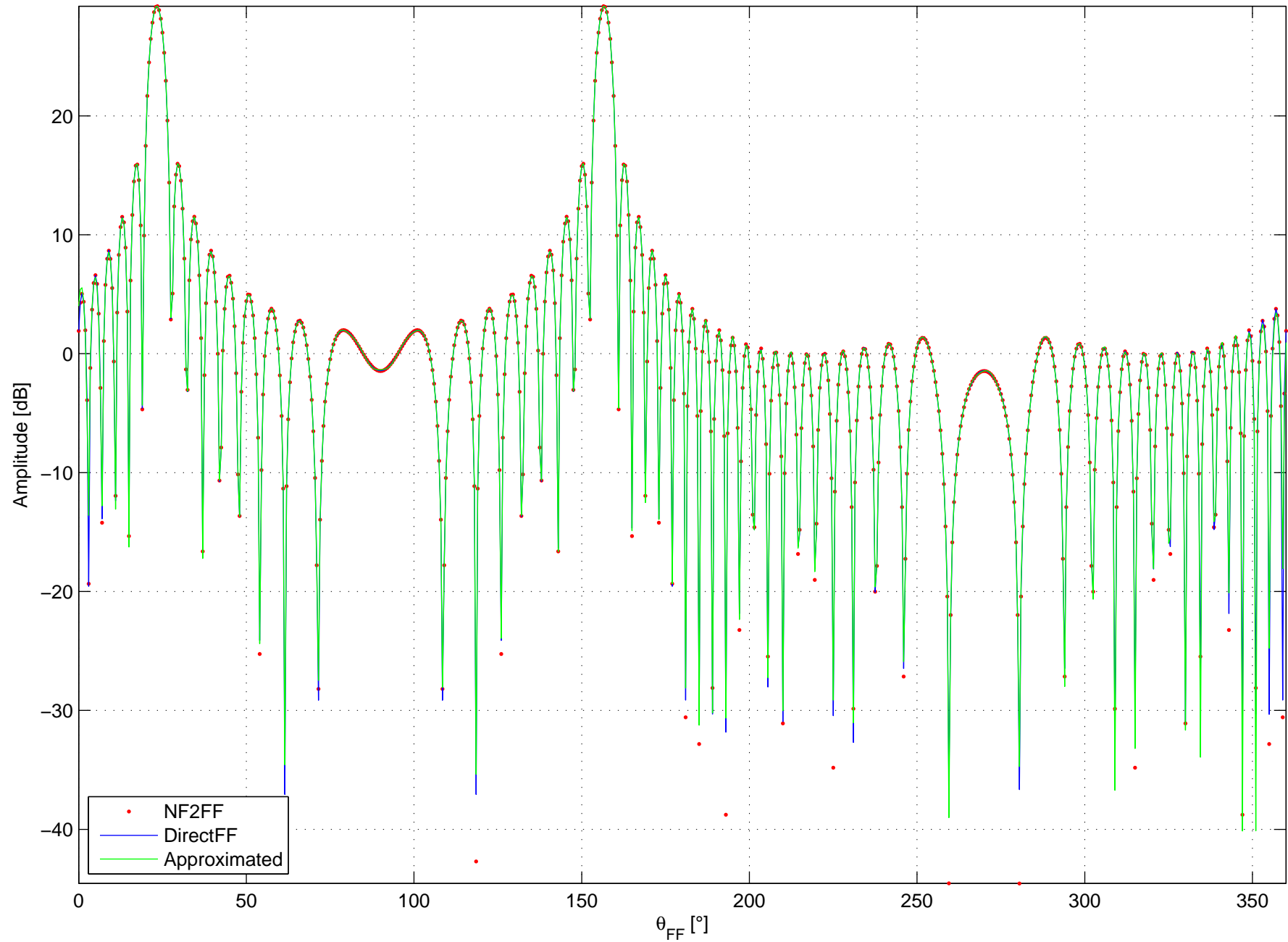
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.0048536  
FFSamples = 721, NFSamples = 16200, Coefficients = 119



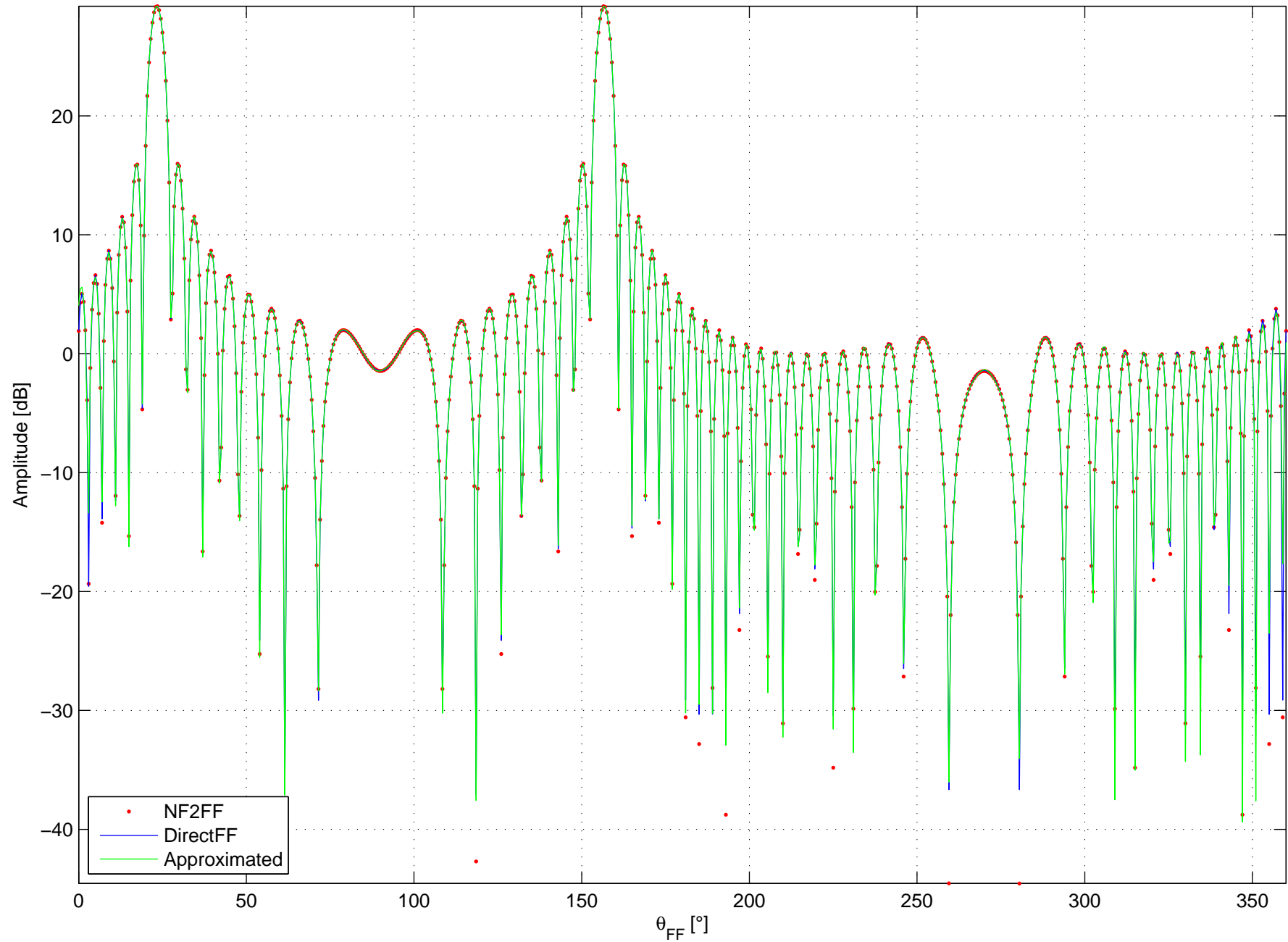
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.0050134  
FFSamples = 721, NFSamples = 16200, Coefficients = 117



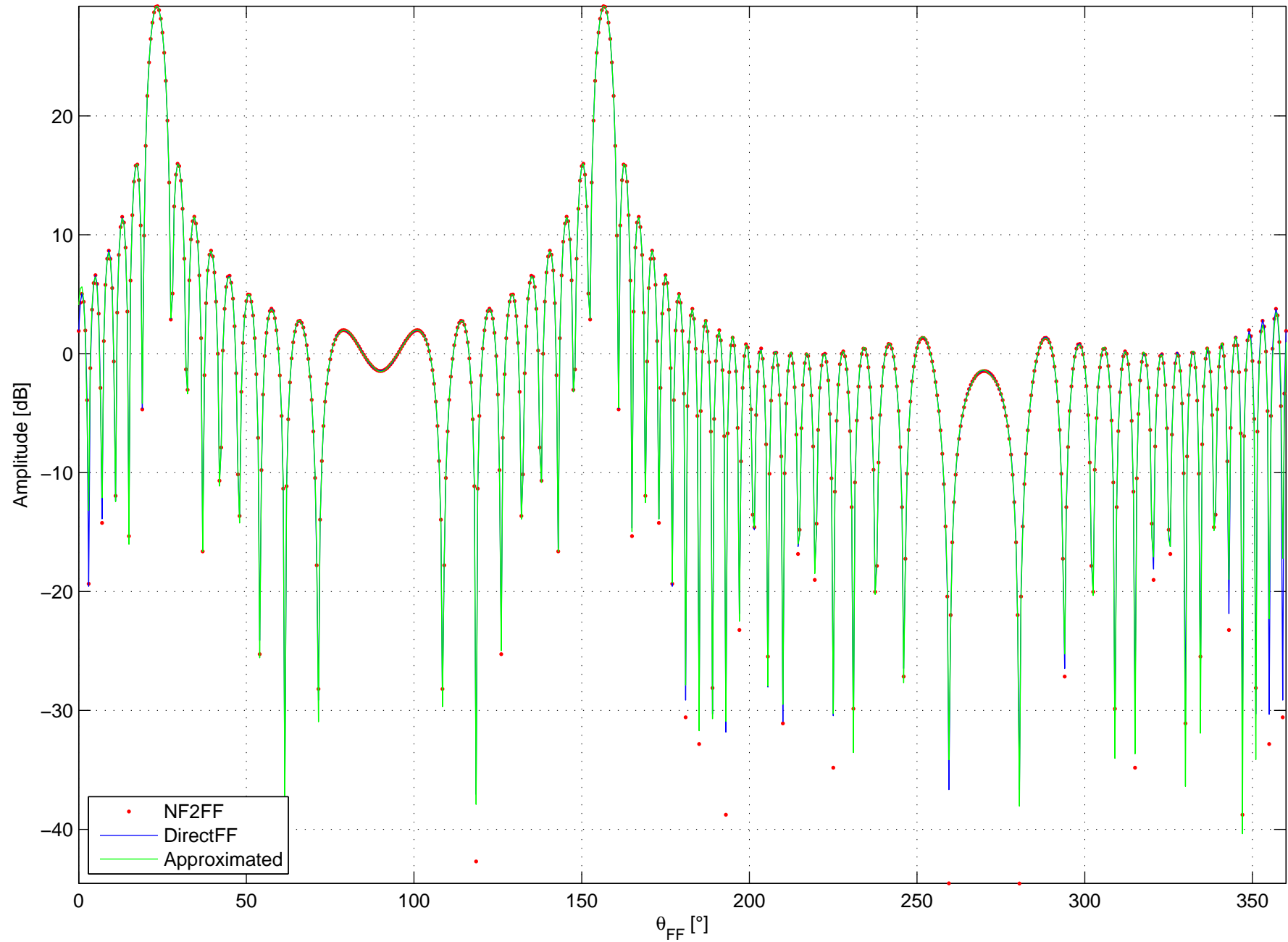
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.0051961  
FFSamples = 721, NFSamples = 16200, Coefficients = 115



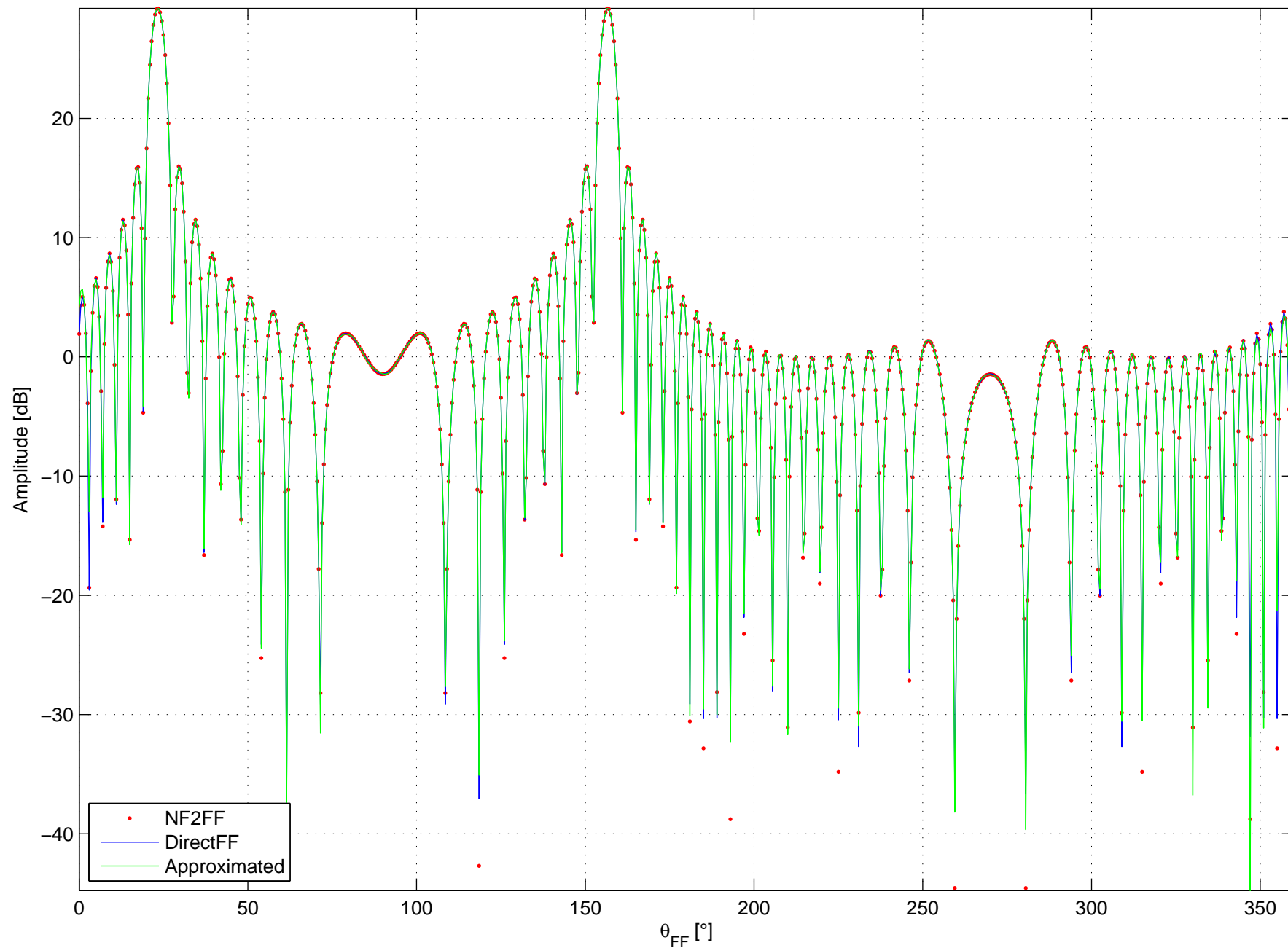
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.0053888  
FFSamples = 721, NFSamples = 16200, Coefficients = 113



29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.0056308  
FFSamples = 721, NFSamples = 16200, Coefficients = 111

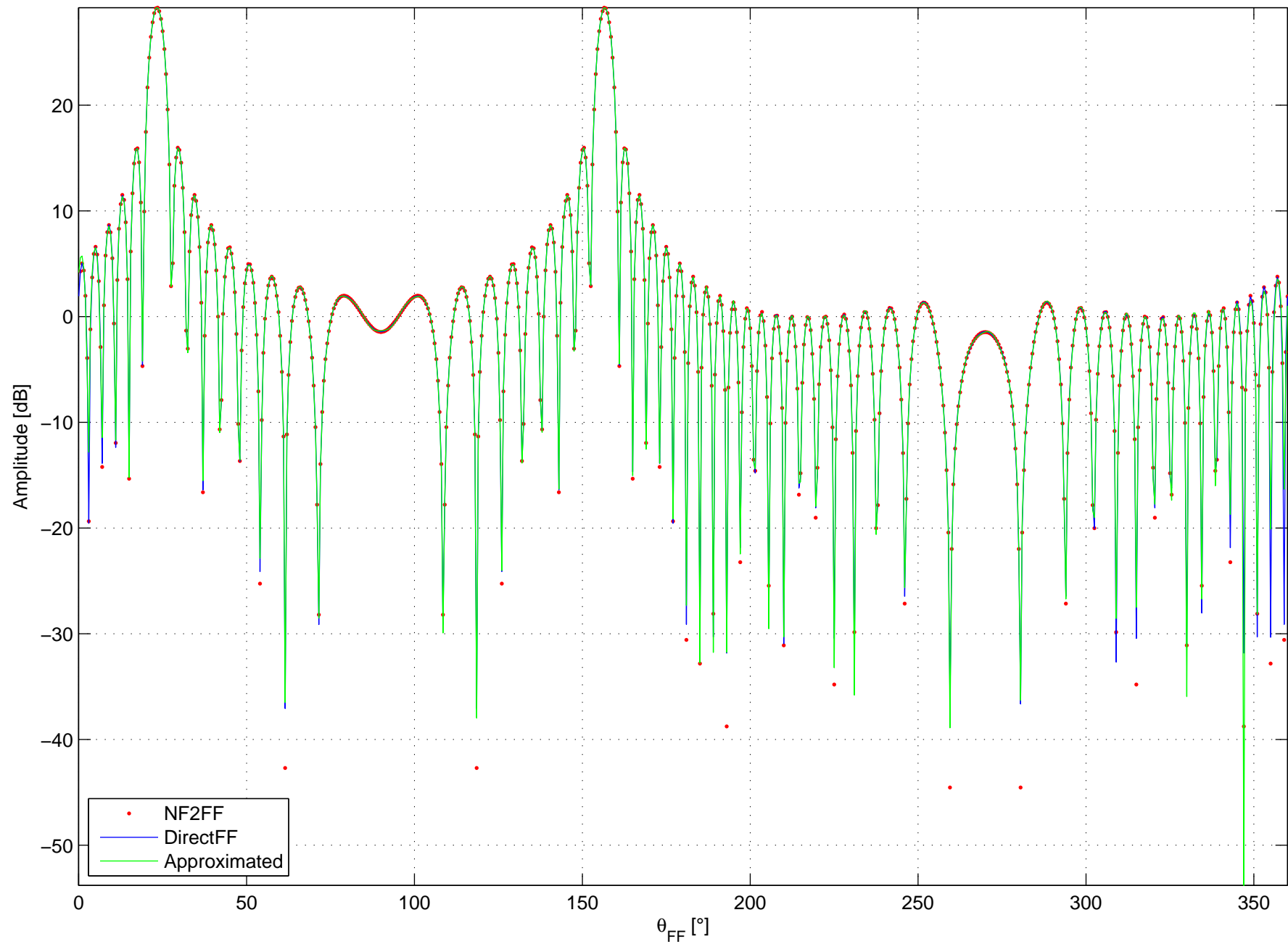


29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.0058432  
FFSamples = 721, NFSamples = 16200, Coefficients = 109

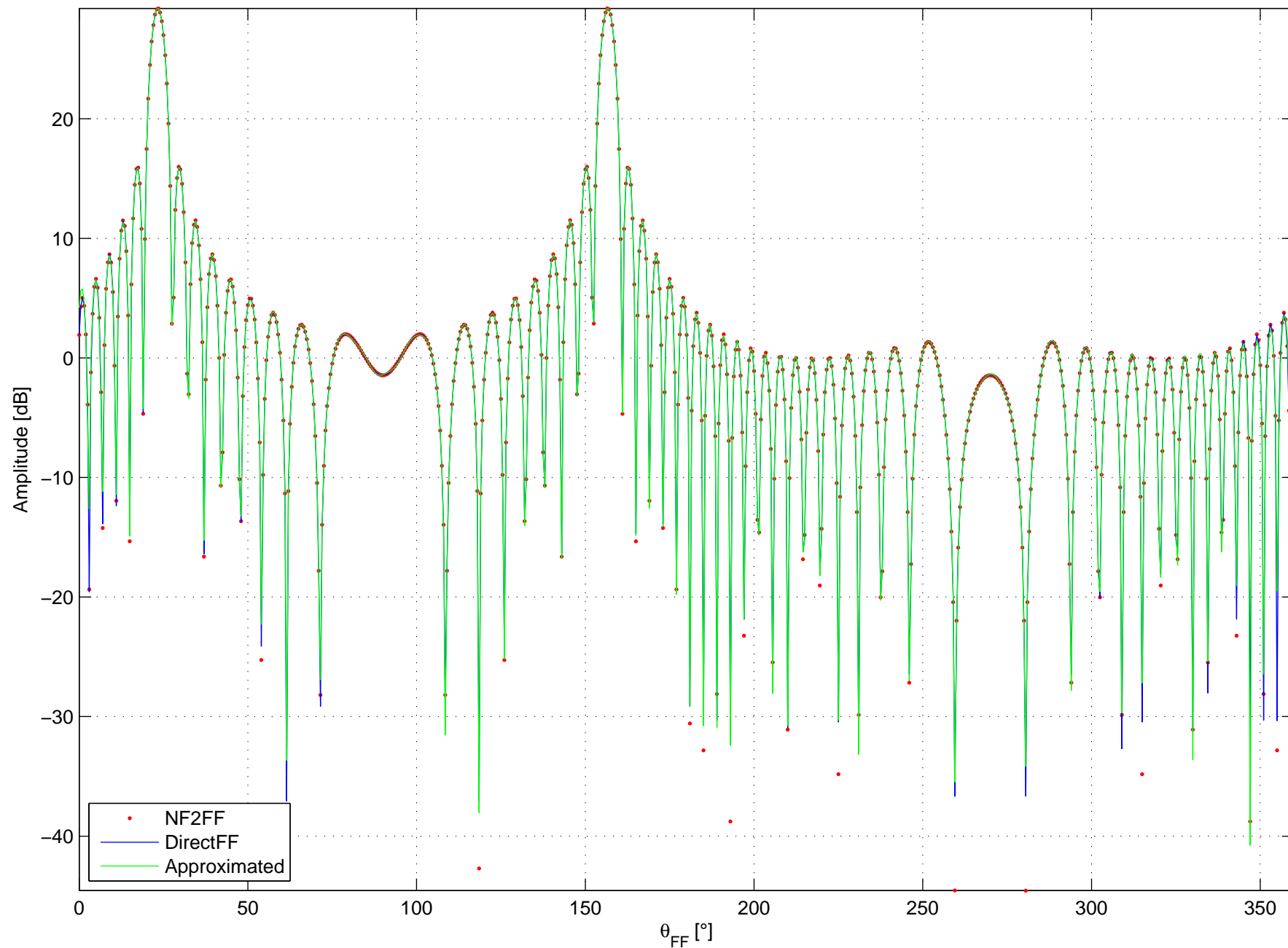




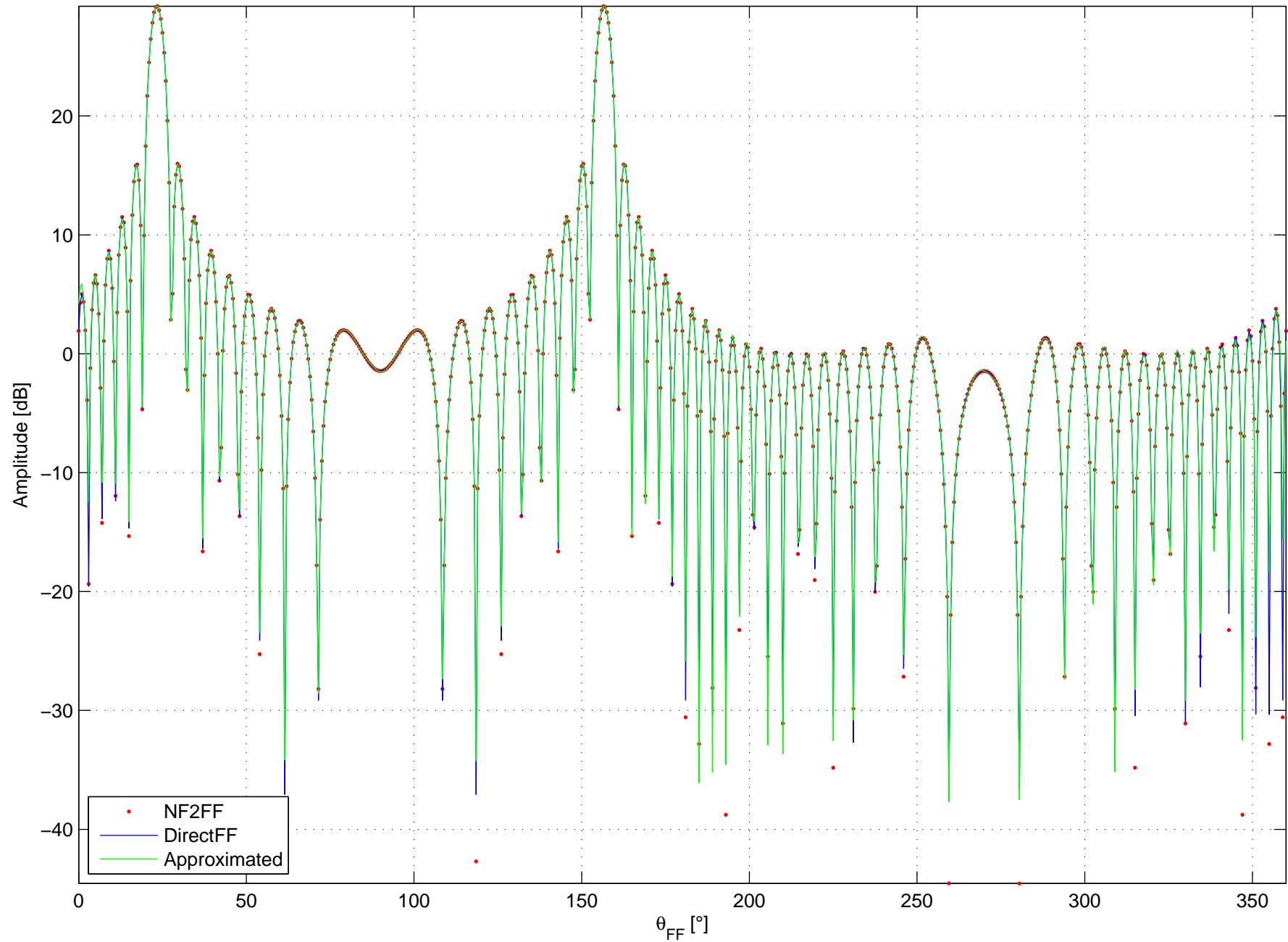
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.0061803  
FFSamples = 721, NFSamples = 16200, Coefficients = 107



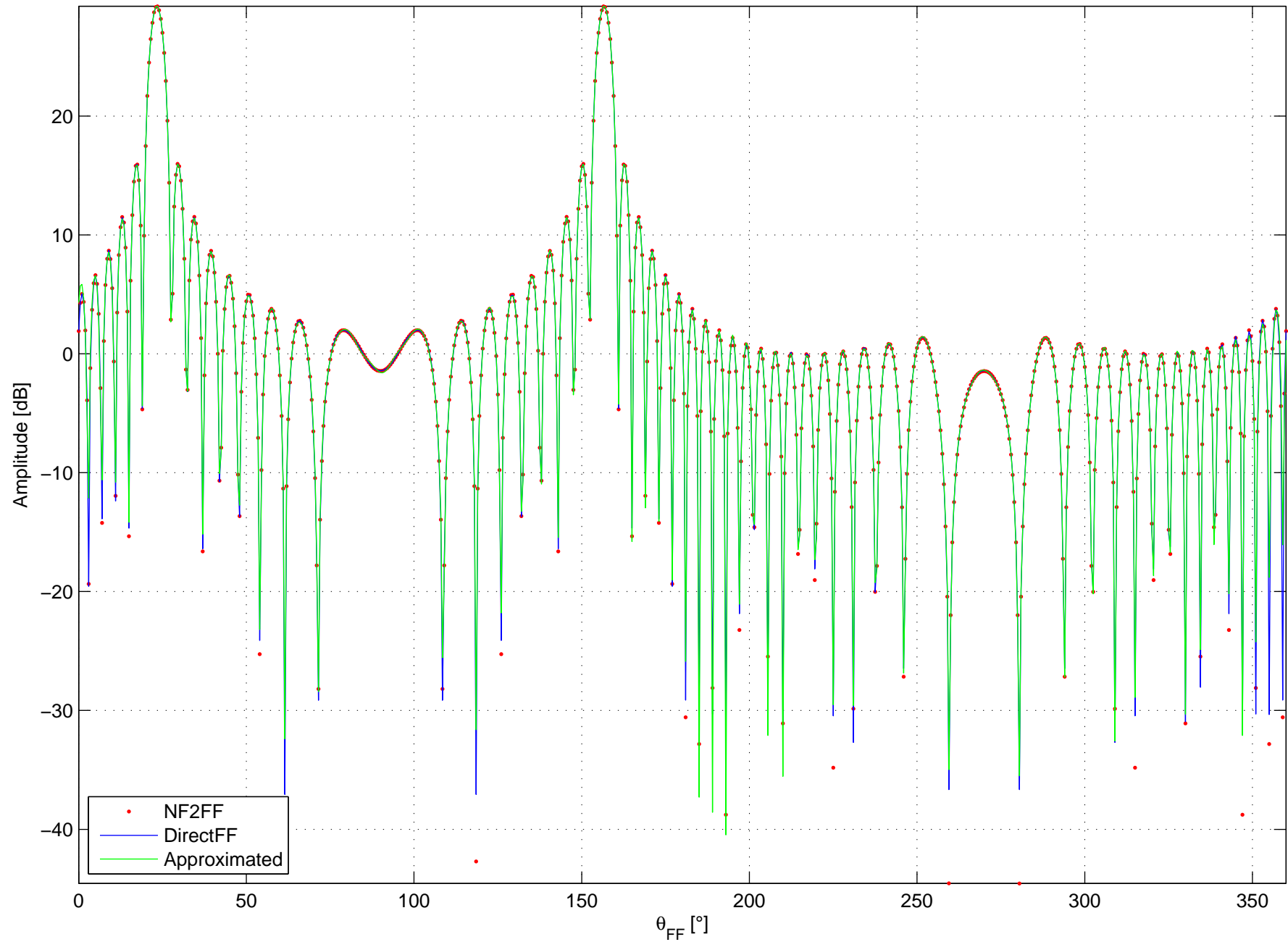
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.006331  
FFSamples = 721, NFSamples = 16200, Coefficients = 105



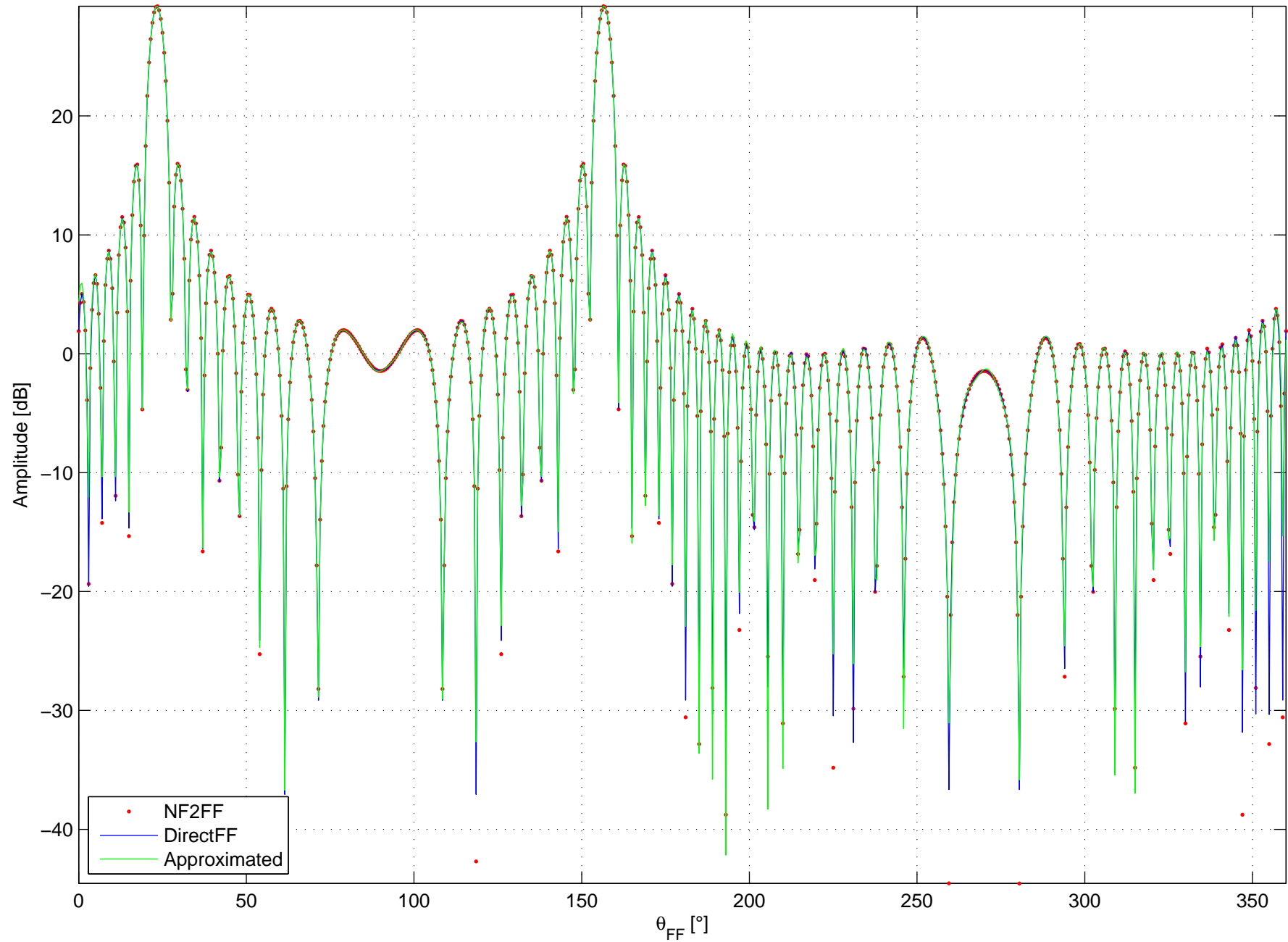
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.0068736  
FFSamples = 721, NFSamples = 16200, Coefficients = 103



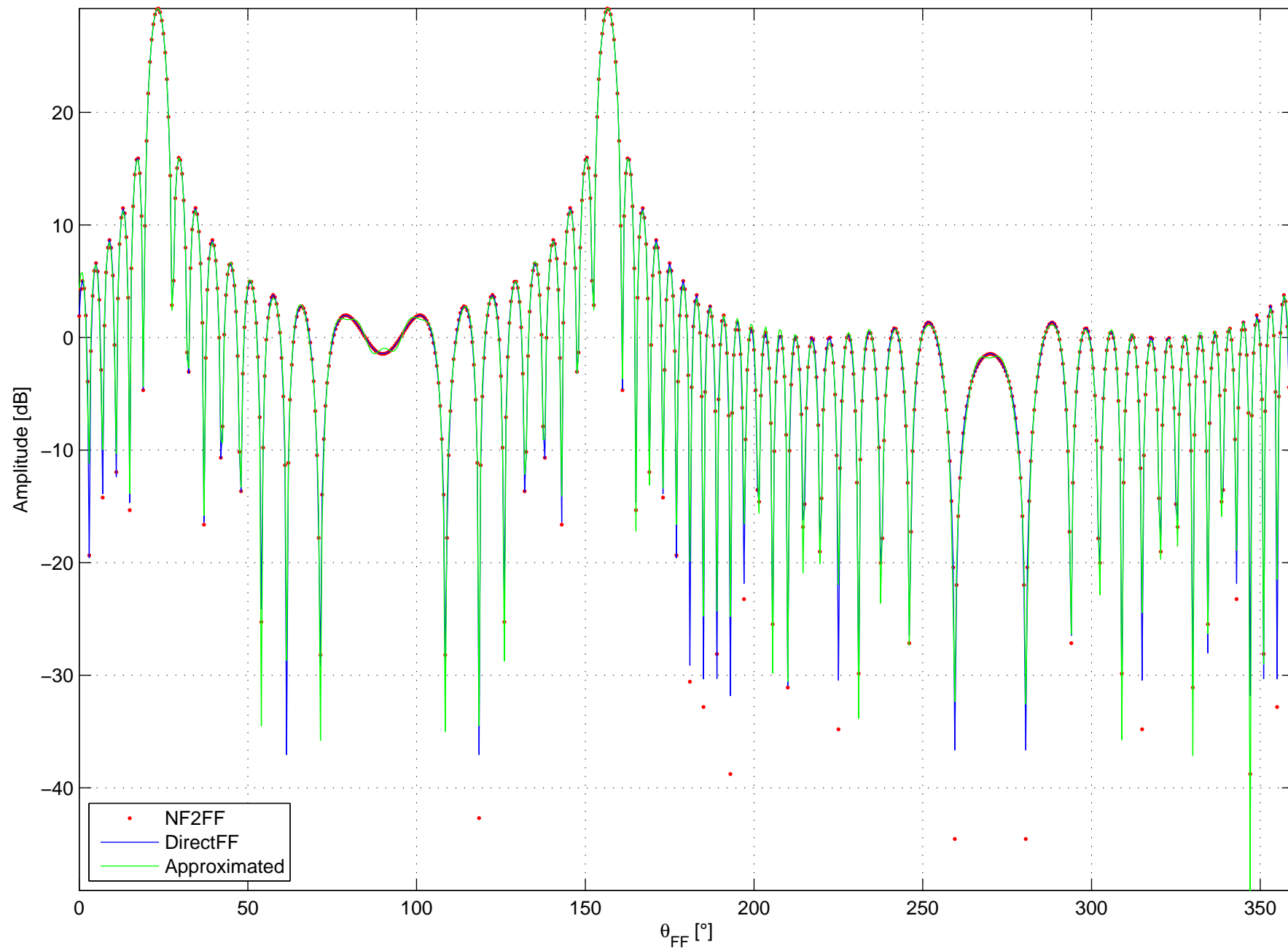
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.0070494  
FFSamples = 721, NFSamples = 16200, Coefficients = 101



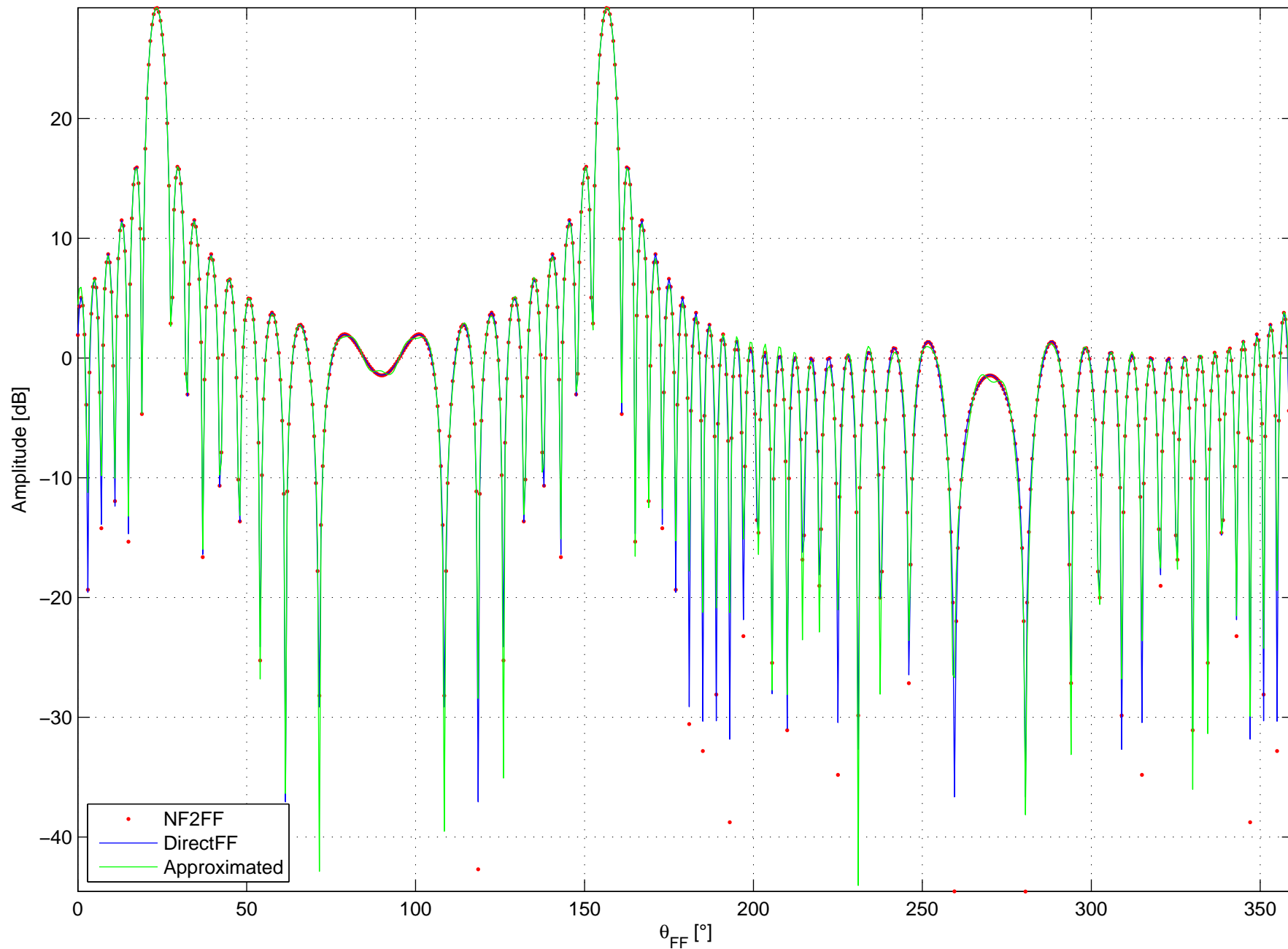
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.0078742  
FFSamples = 721, NFSamples = 16200, Coefficients = 99



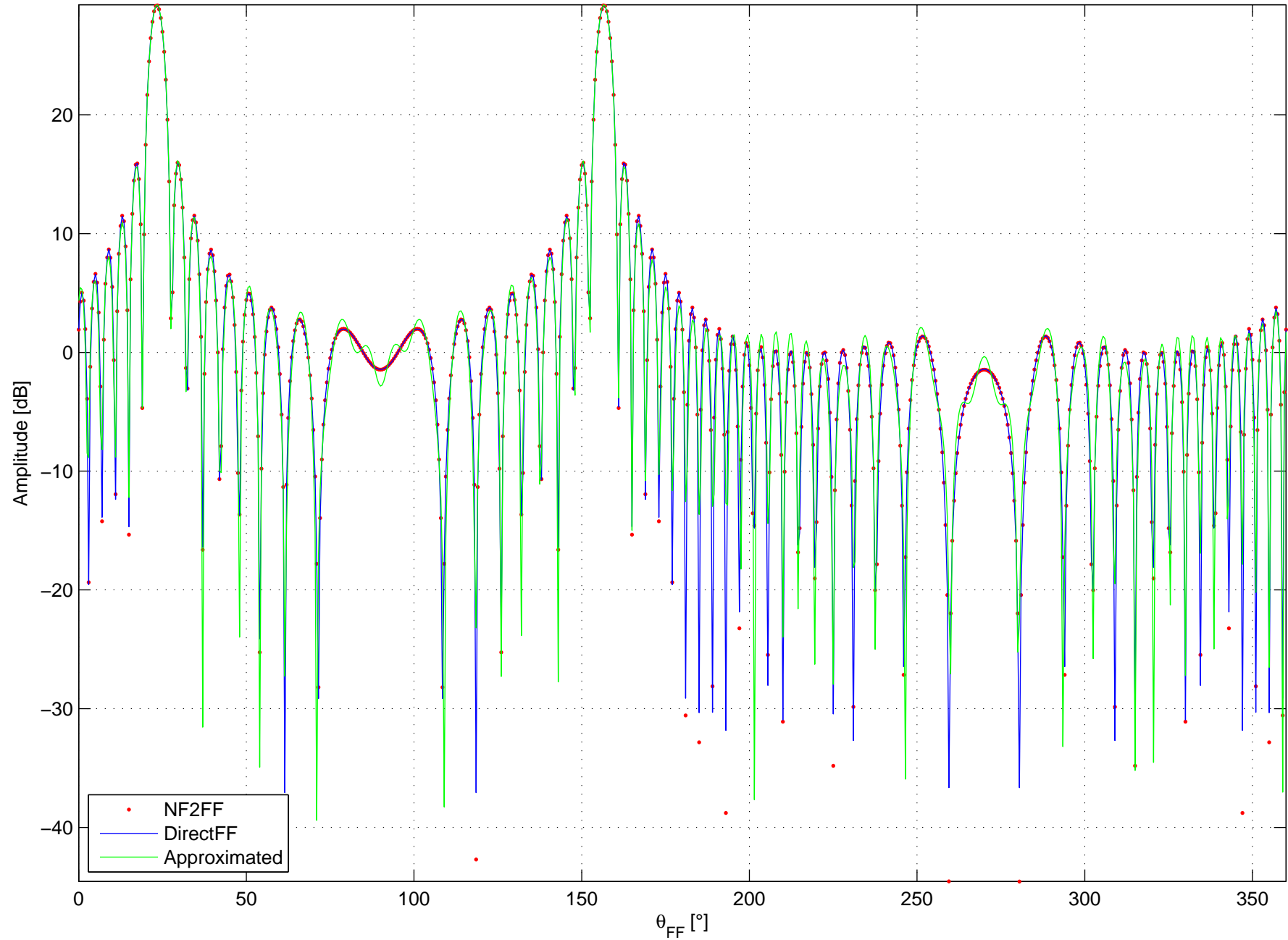
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.011132  
FFSamples = 721, NFSamples = 16200, Coefficients = 97



29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.01207  
FFSamples = 721, NFSamples = 16200, Coefficients = 95

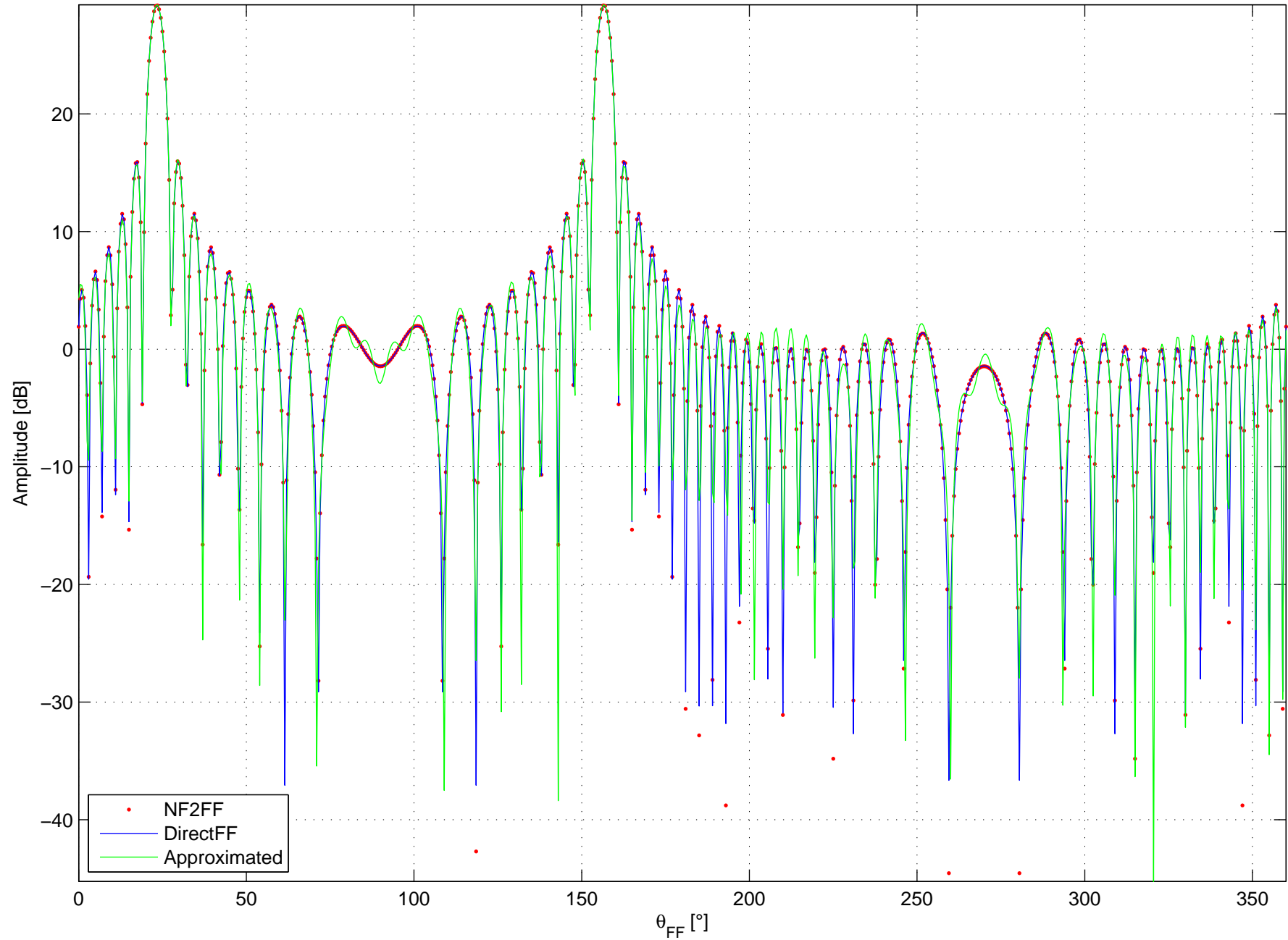


29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.027869  
FFSamples = 721, NFSamples = 16200, Coefficients = 93

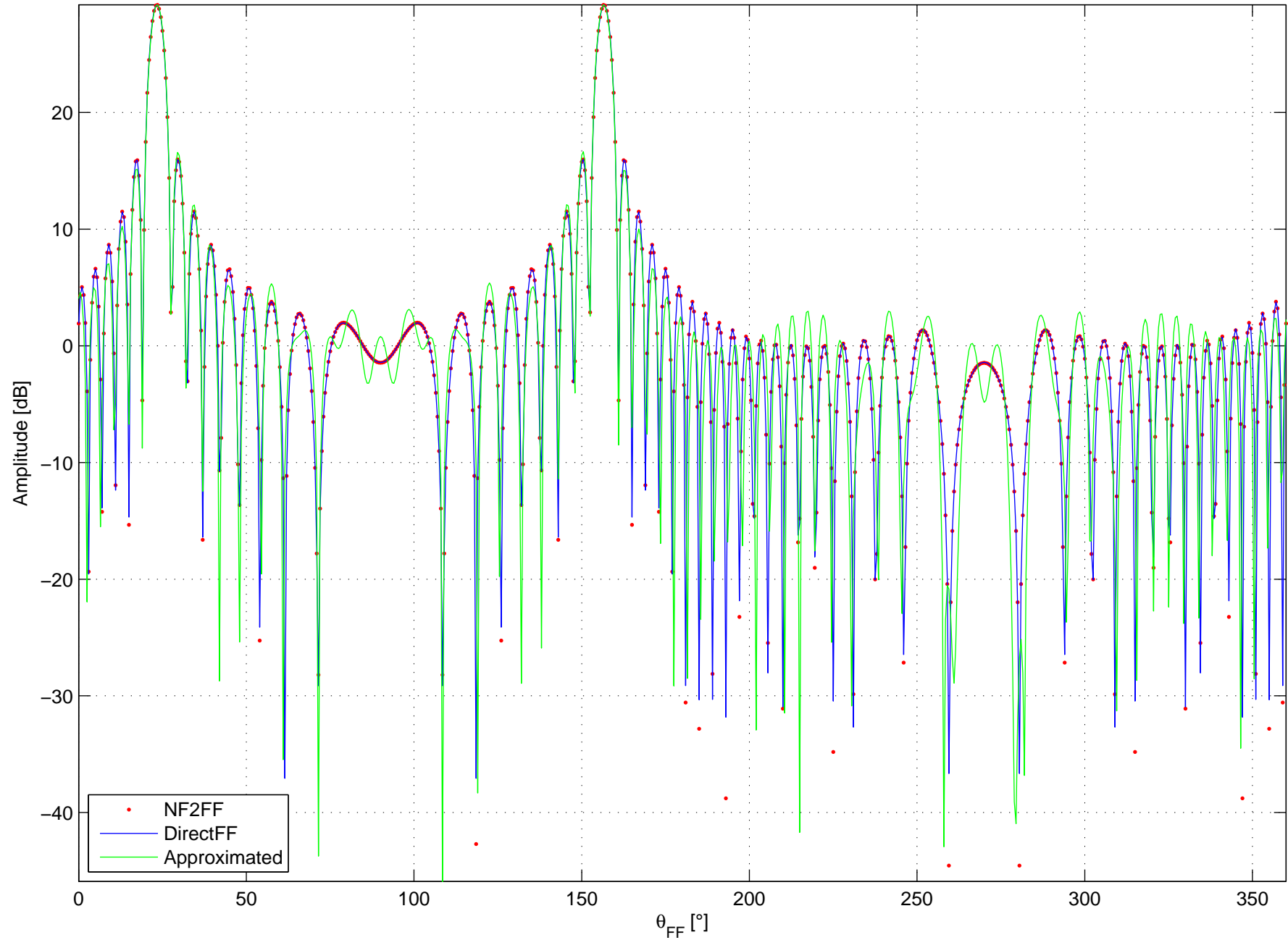




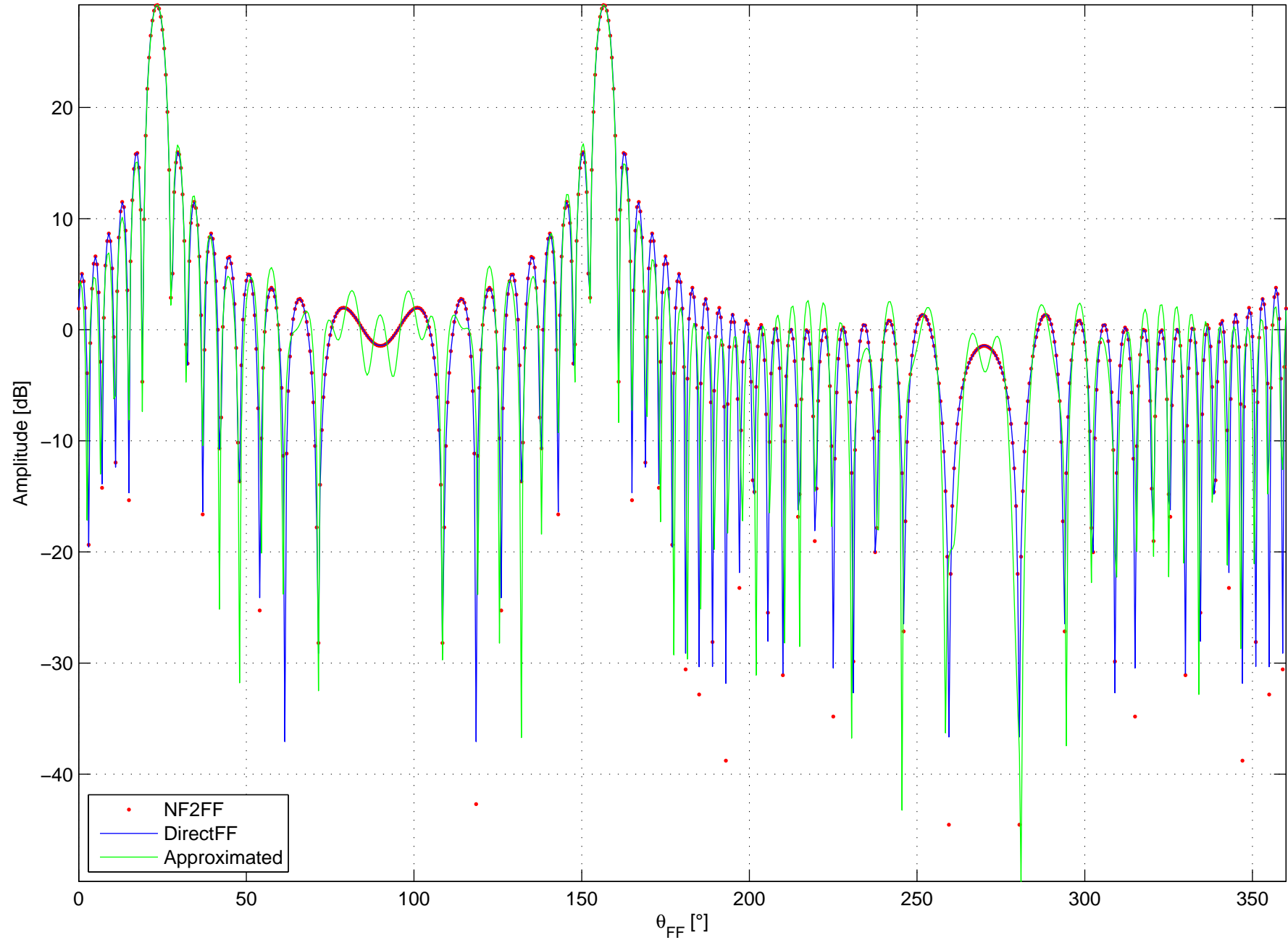
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.028382  
FFSamples = 721, NFSamples = 16200, Coefficients = 91



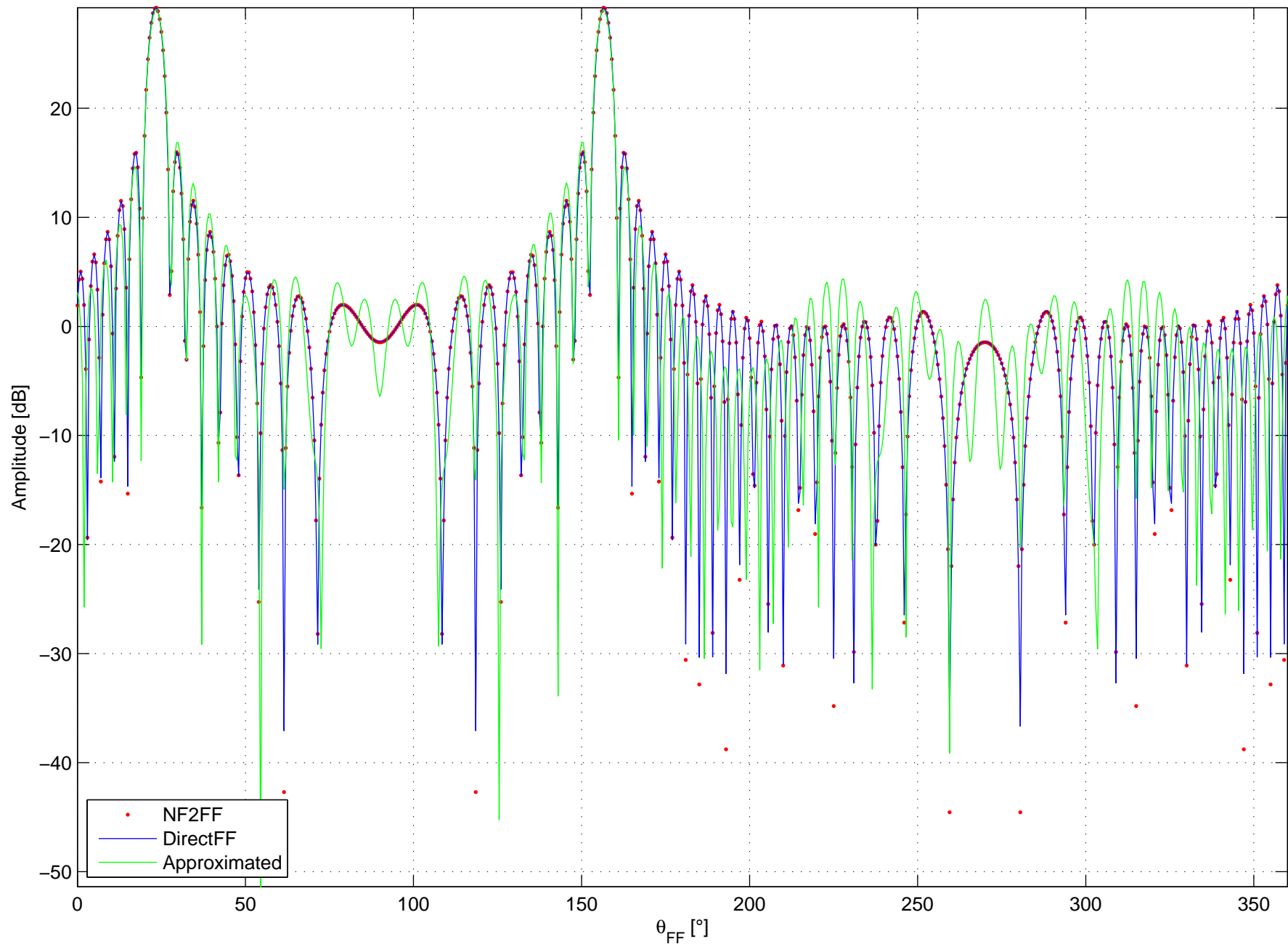
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.066146  
FFSamples = 721, NFSamples = 16200, Coefficients = 89



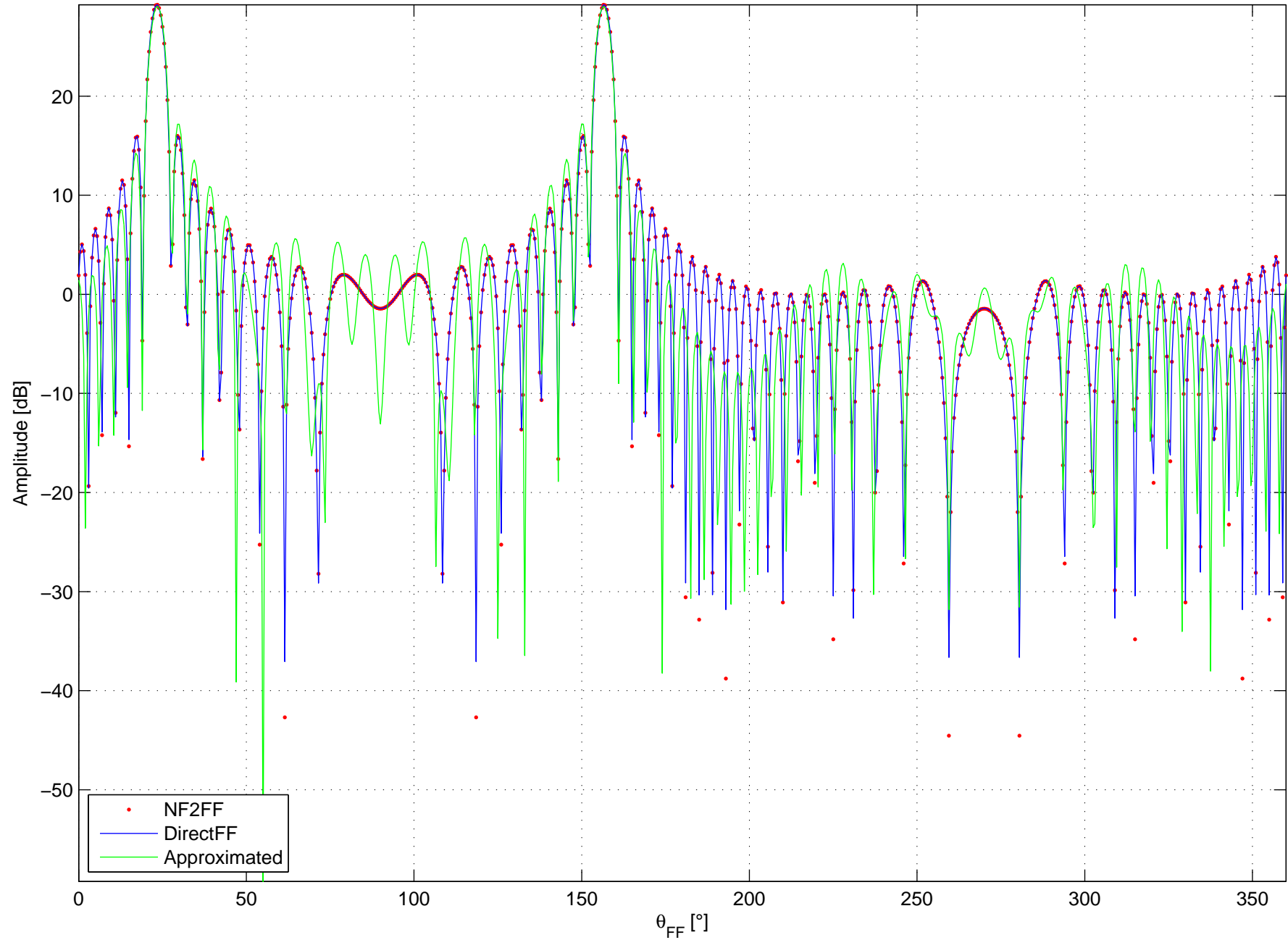
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.067265  
FFSamples = 721, NFSamples = 16200, Coefficients = 87



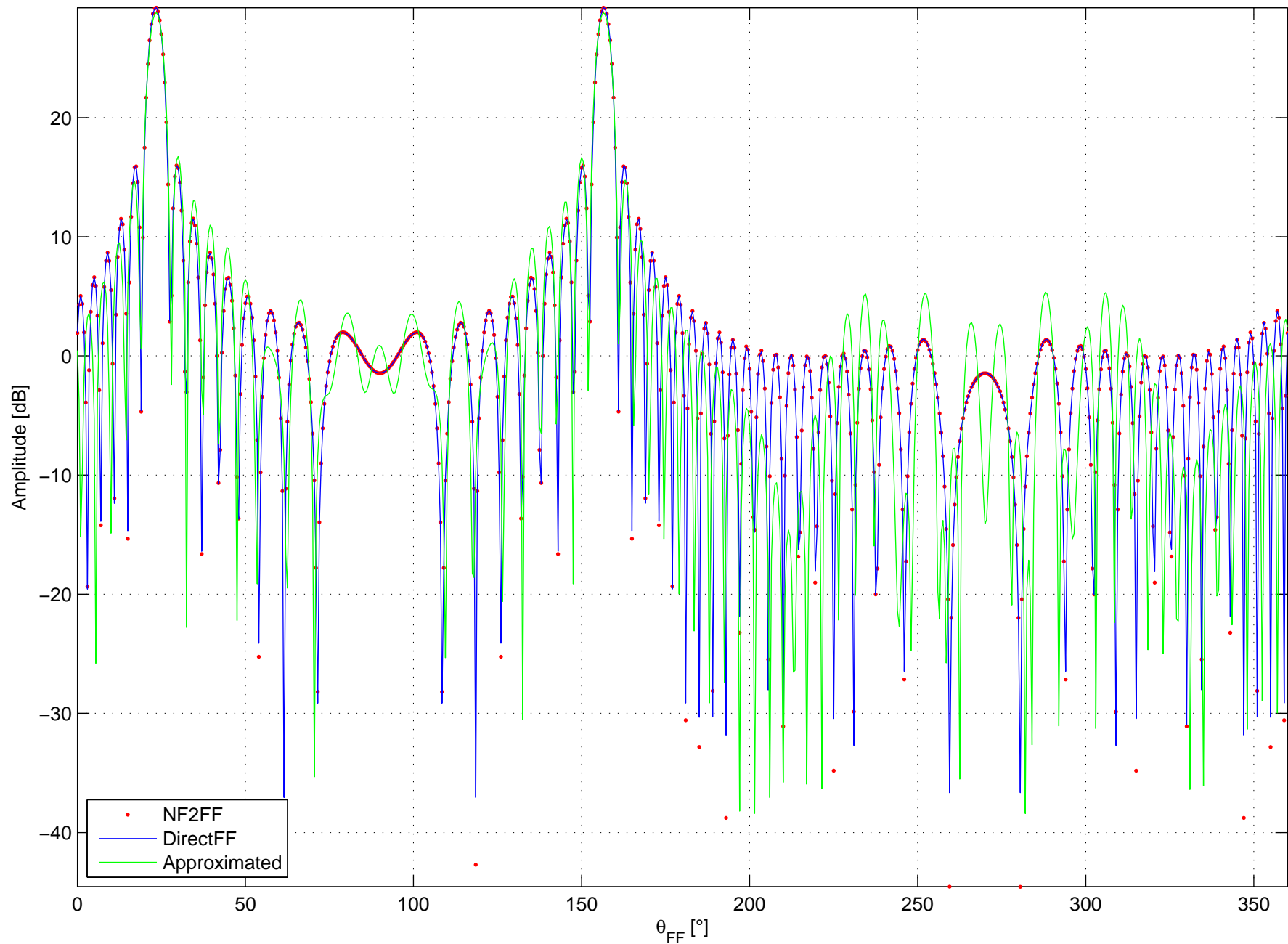
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.1274  
FFSamples = 721, NFSamples = 16200, Coefficients = 85



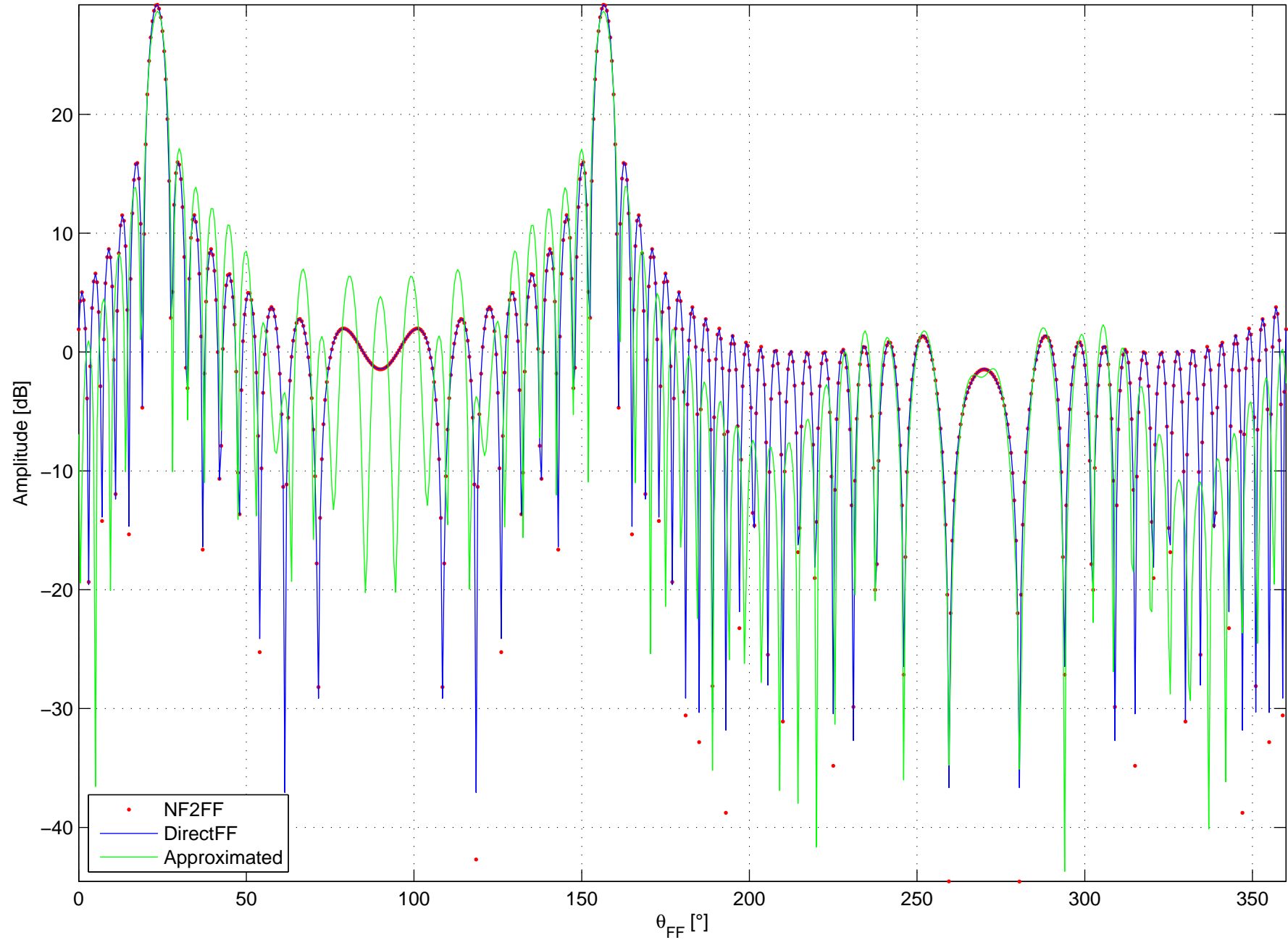
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.13358  
FFSamples = 721, NFSamples = 16200, Coefficients = 83



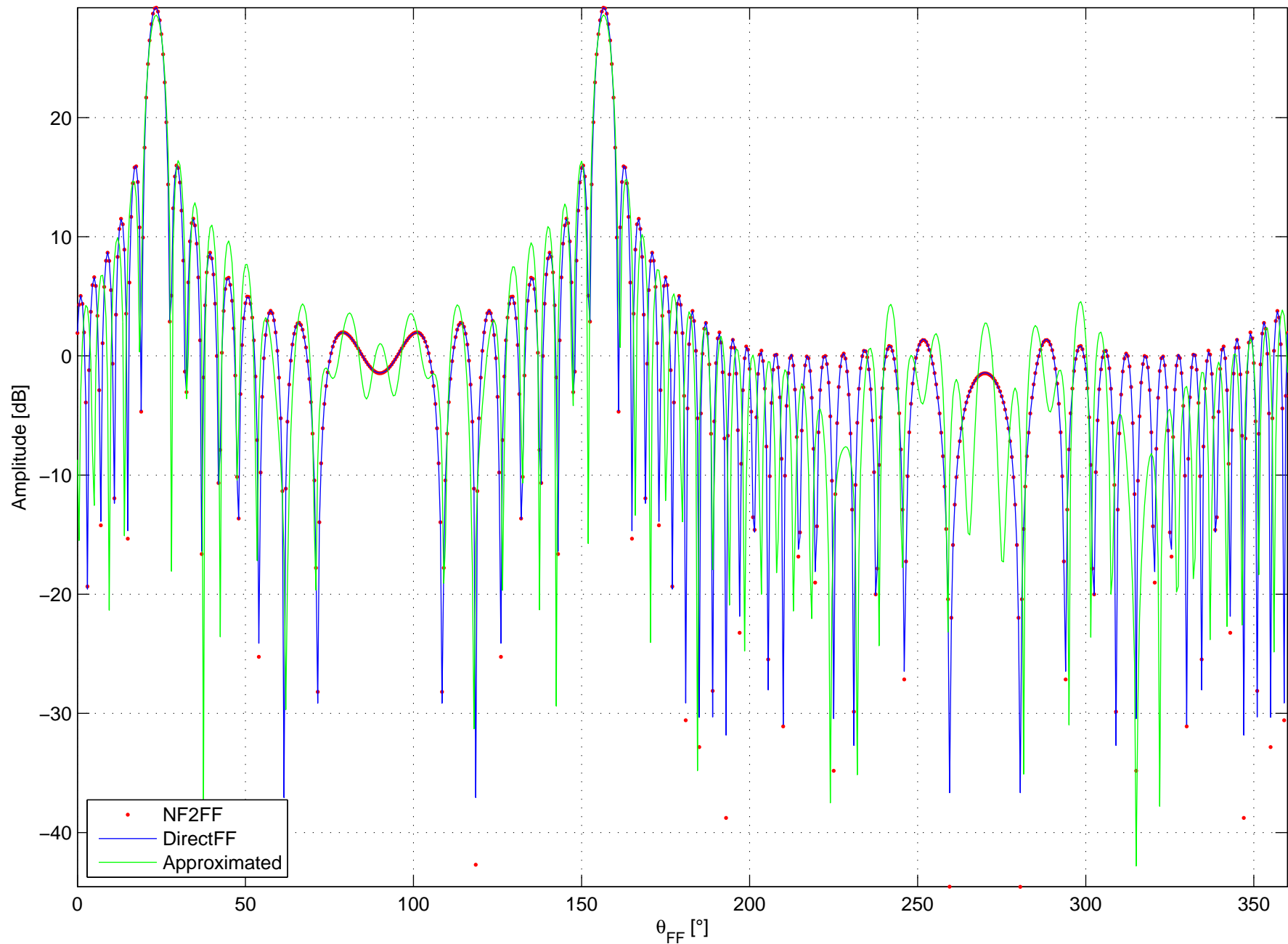
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.19279  
FFSamples = 721, NFSamples = 16200, Coefficients = 81



29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.21474  
FFSamples = 721, NFSamples = 16200, Coefficients = 79

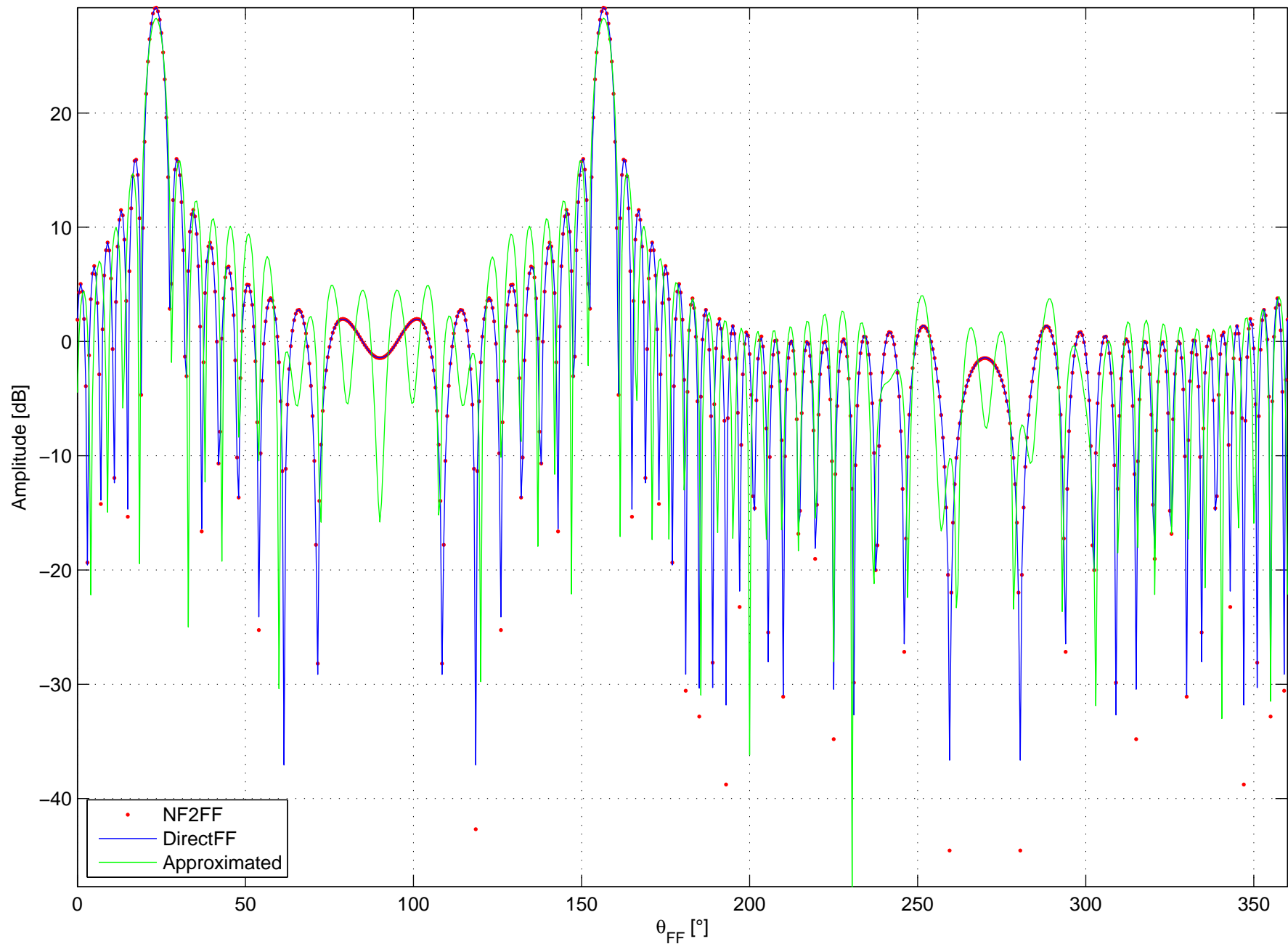


29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.23356  
FFSamples = 721, NFSamples = 16200, Coefficients = 77

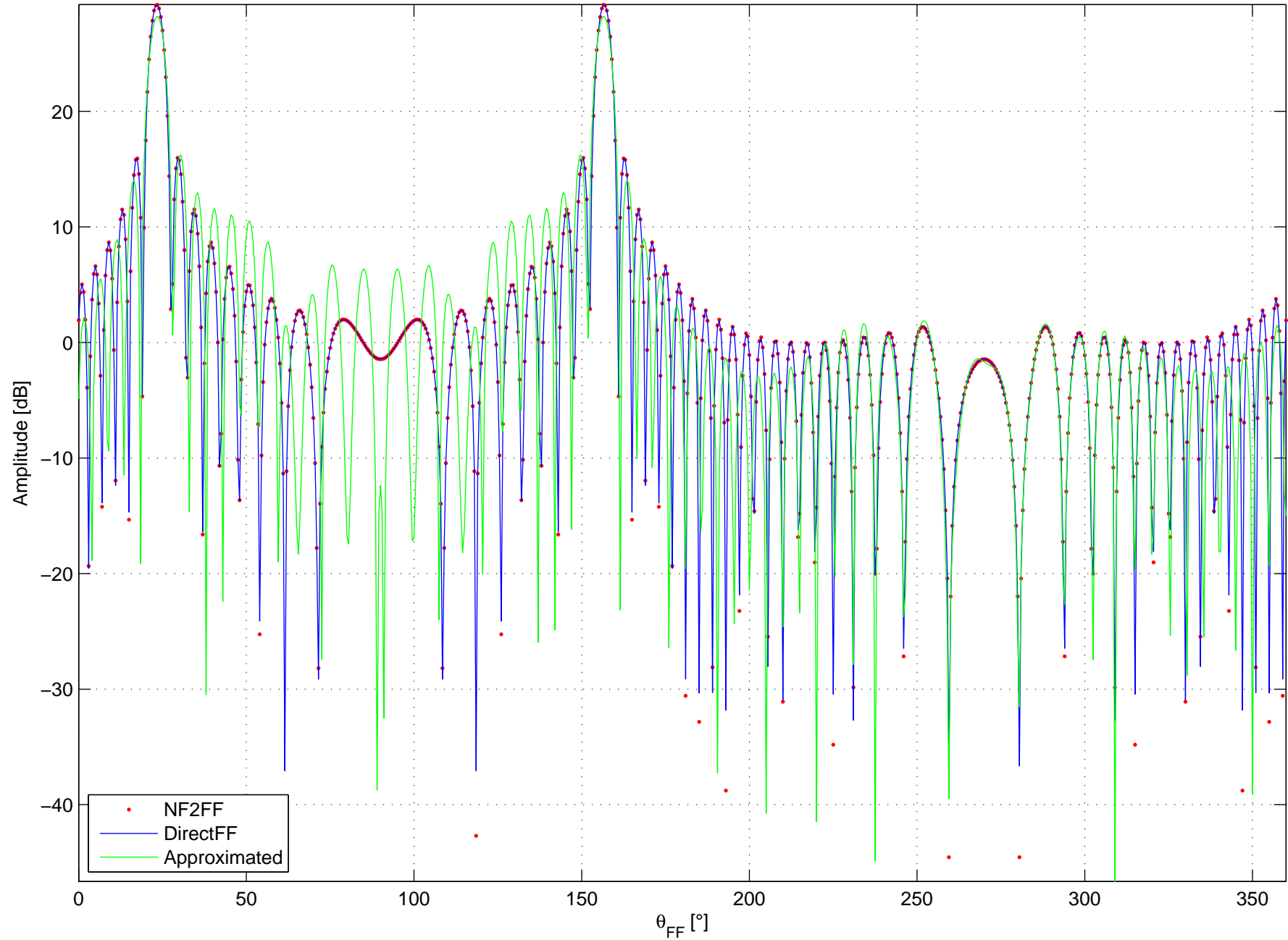




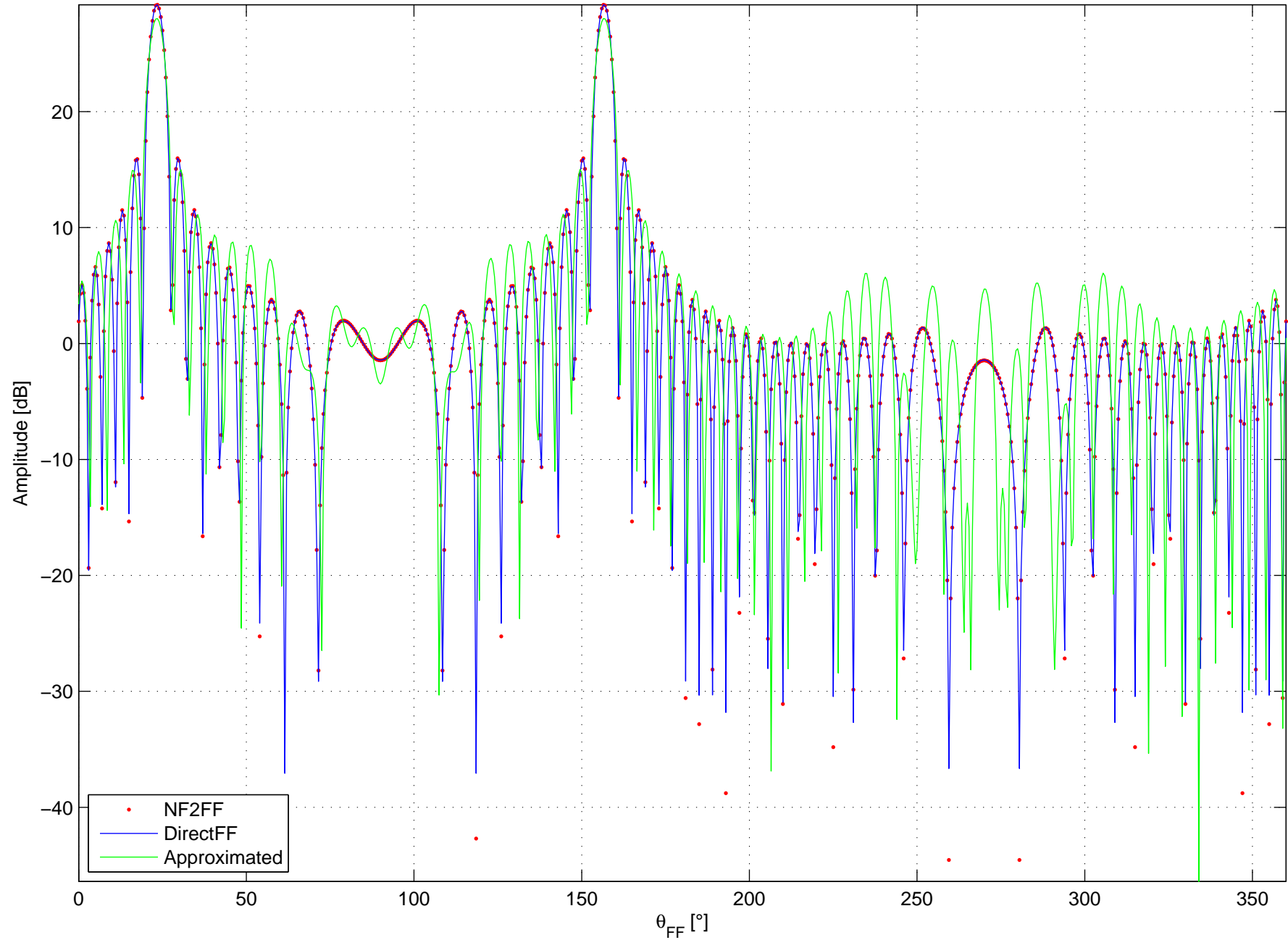
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.27819  
FFSamples = 721, NFSamples = 16200, Coefficients = 75



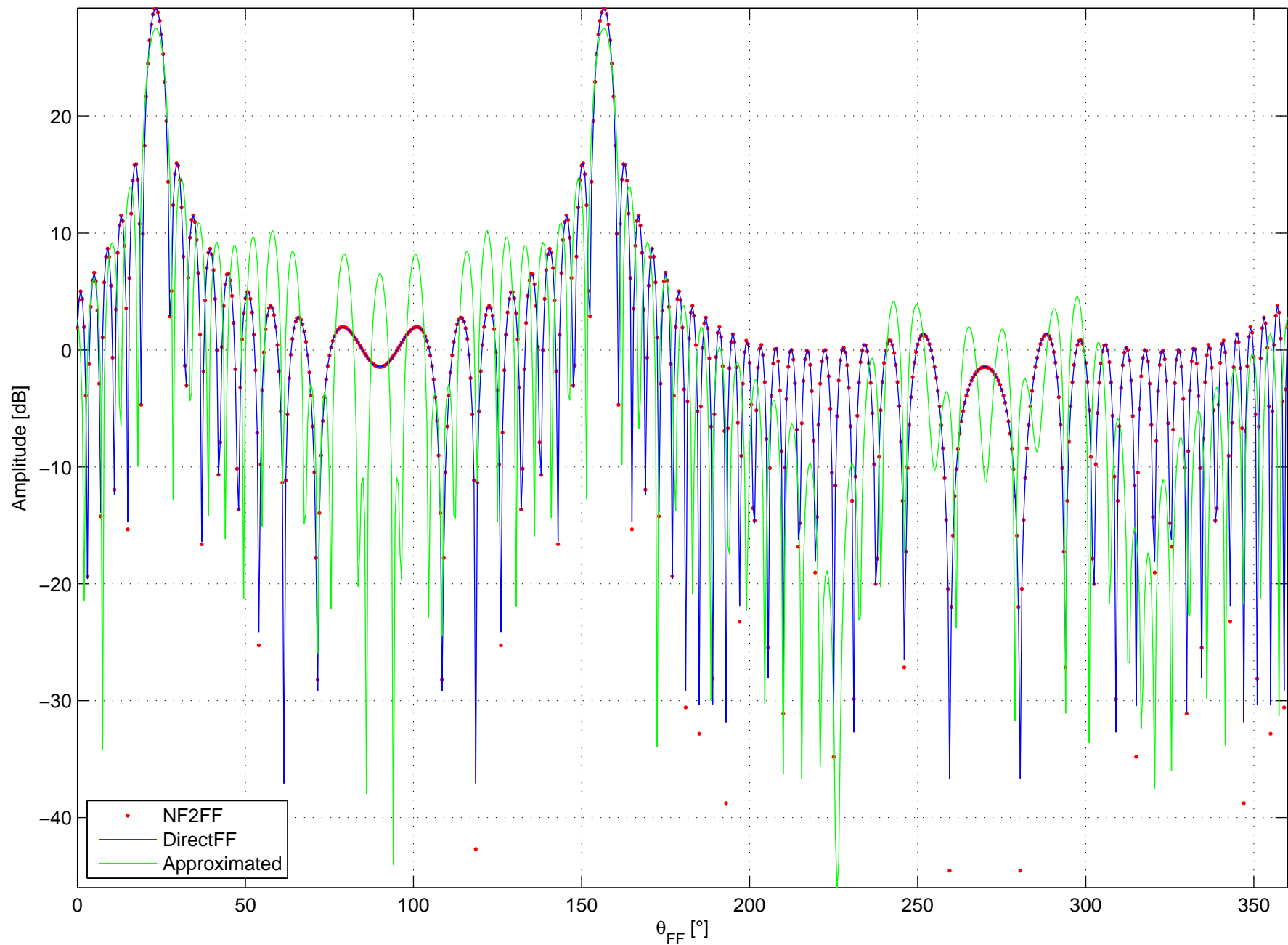
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.28526  
FFSamples = 721, NFSamples = 16200, Coefficients = 73



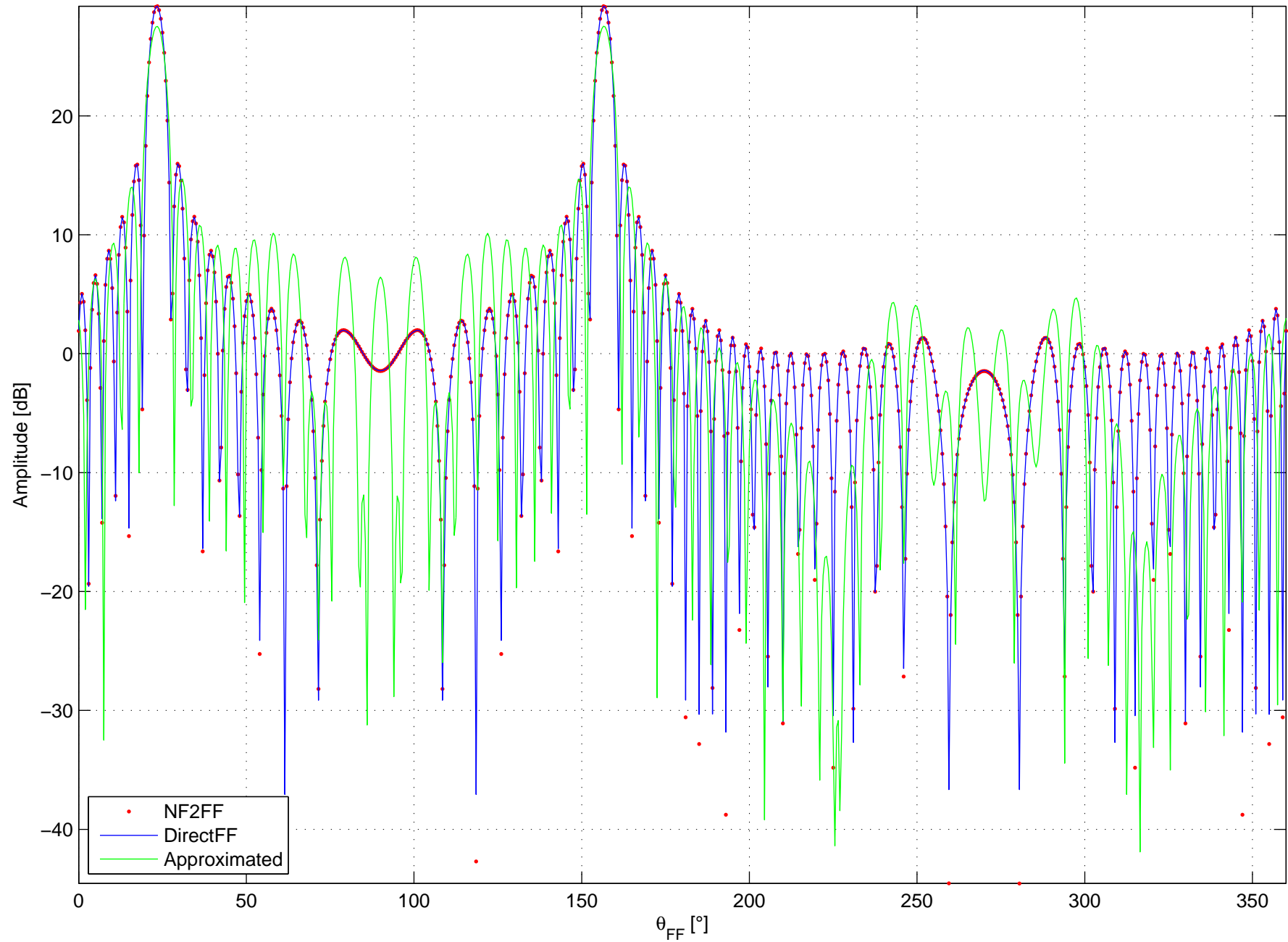
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.3189  
FFSamples = 721, NFSamples = 16200, Coefficients = 71



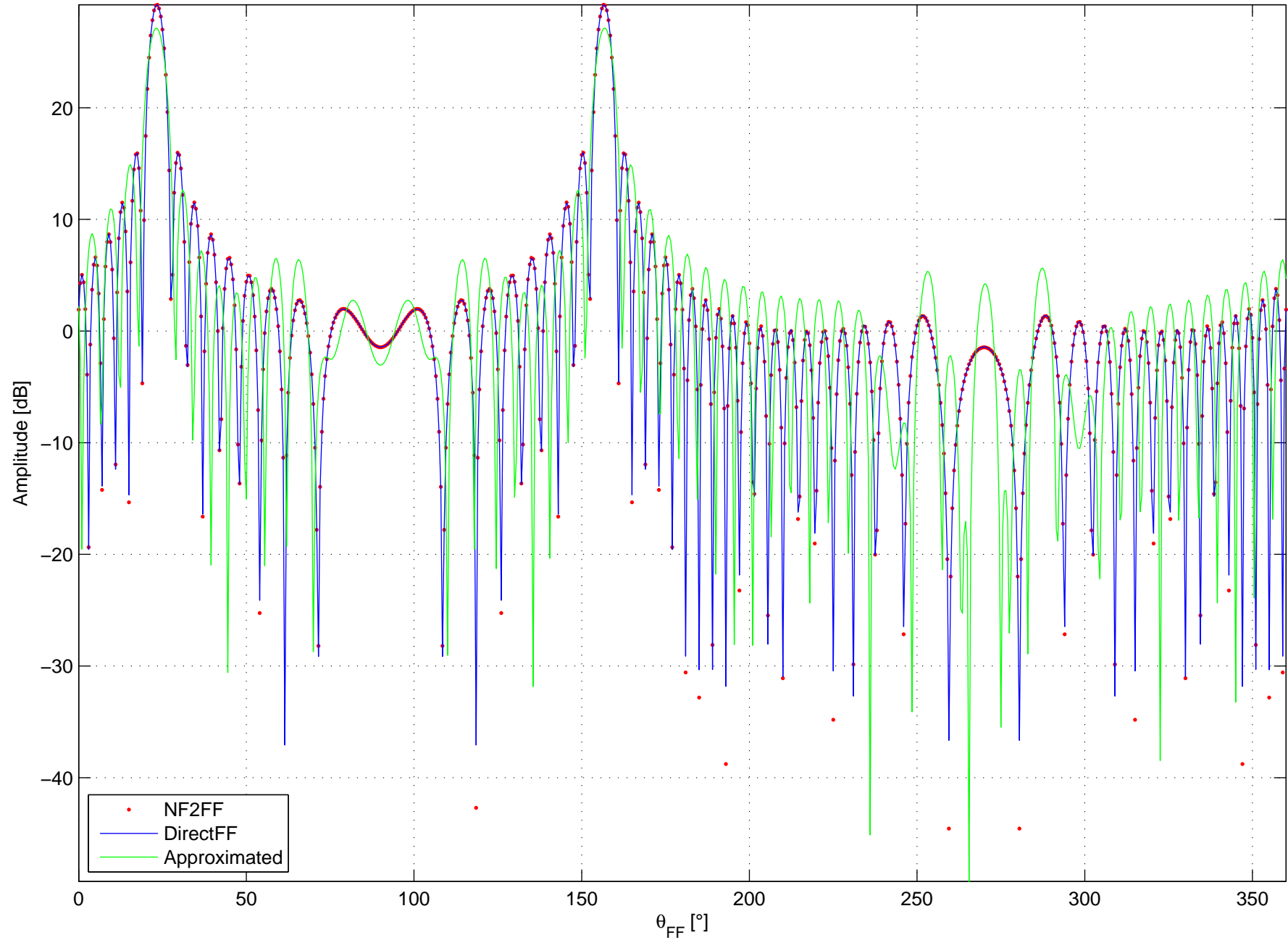
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.3926  
FFSamples = 721, NFSamples = 16200, Coefficients = 69



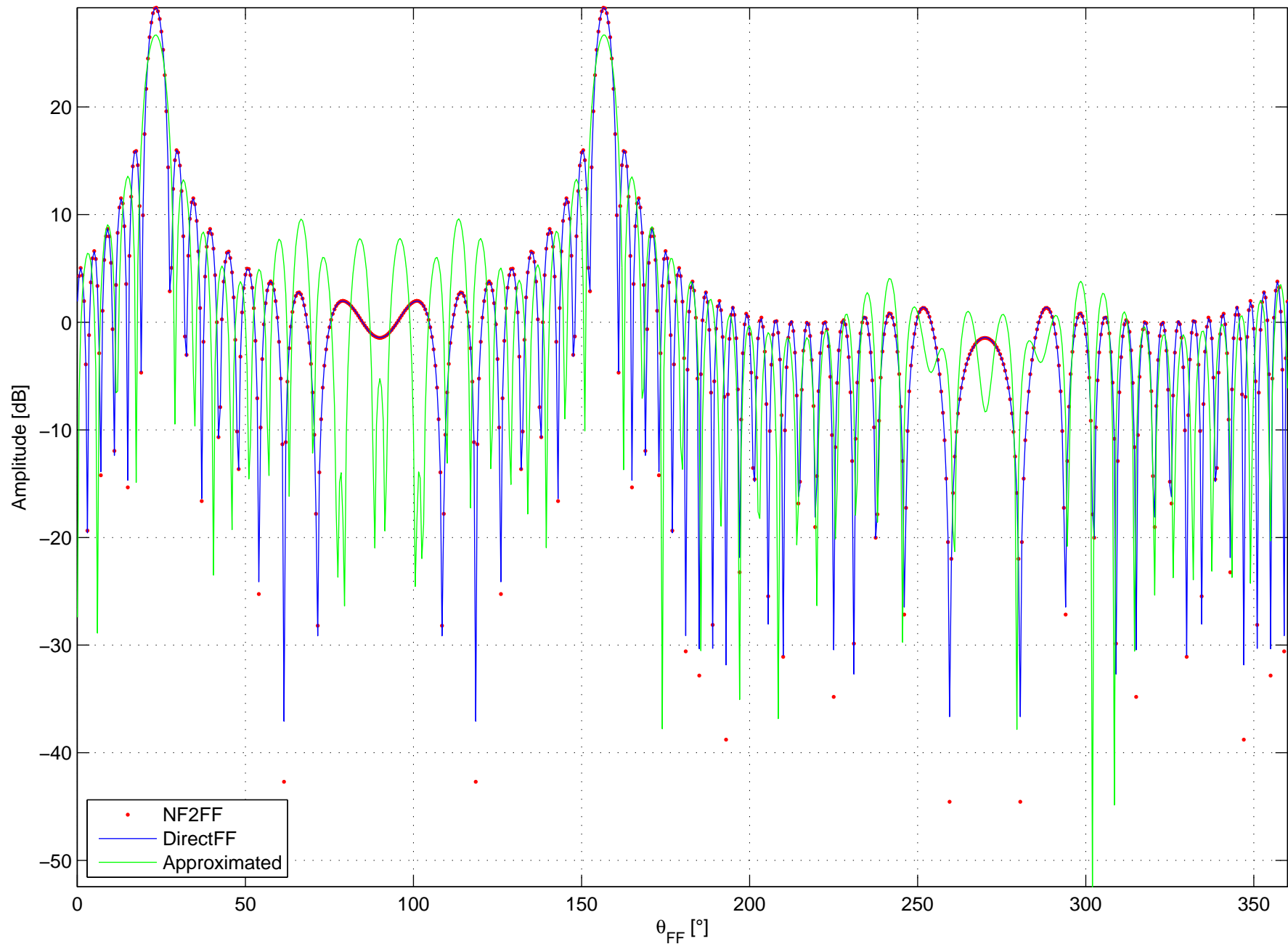
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.39264  
FFSamples = 721, NFSamples = 16200, Coefficients = 67



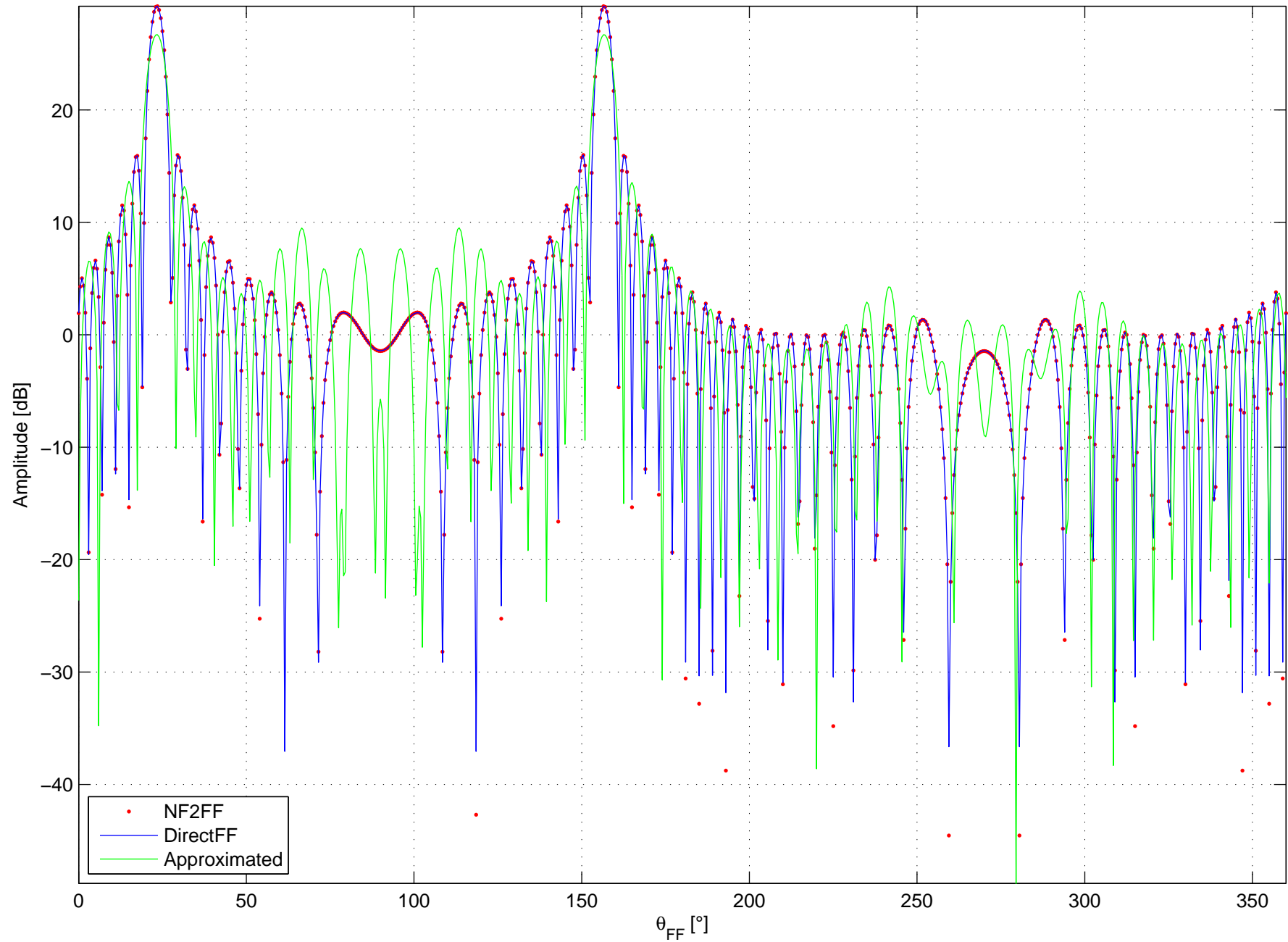
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.44943  
FFSamples = 721, NFSamples = 16200, Coefficients = 65



29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.4903  
FFSamples = 721, NFSamples = 16200, Coefficients = 63

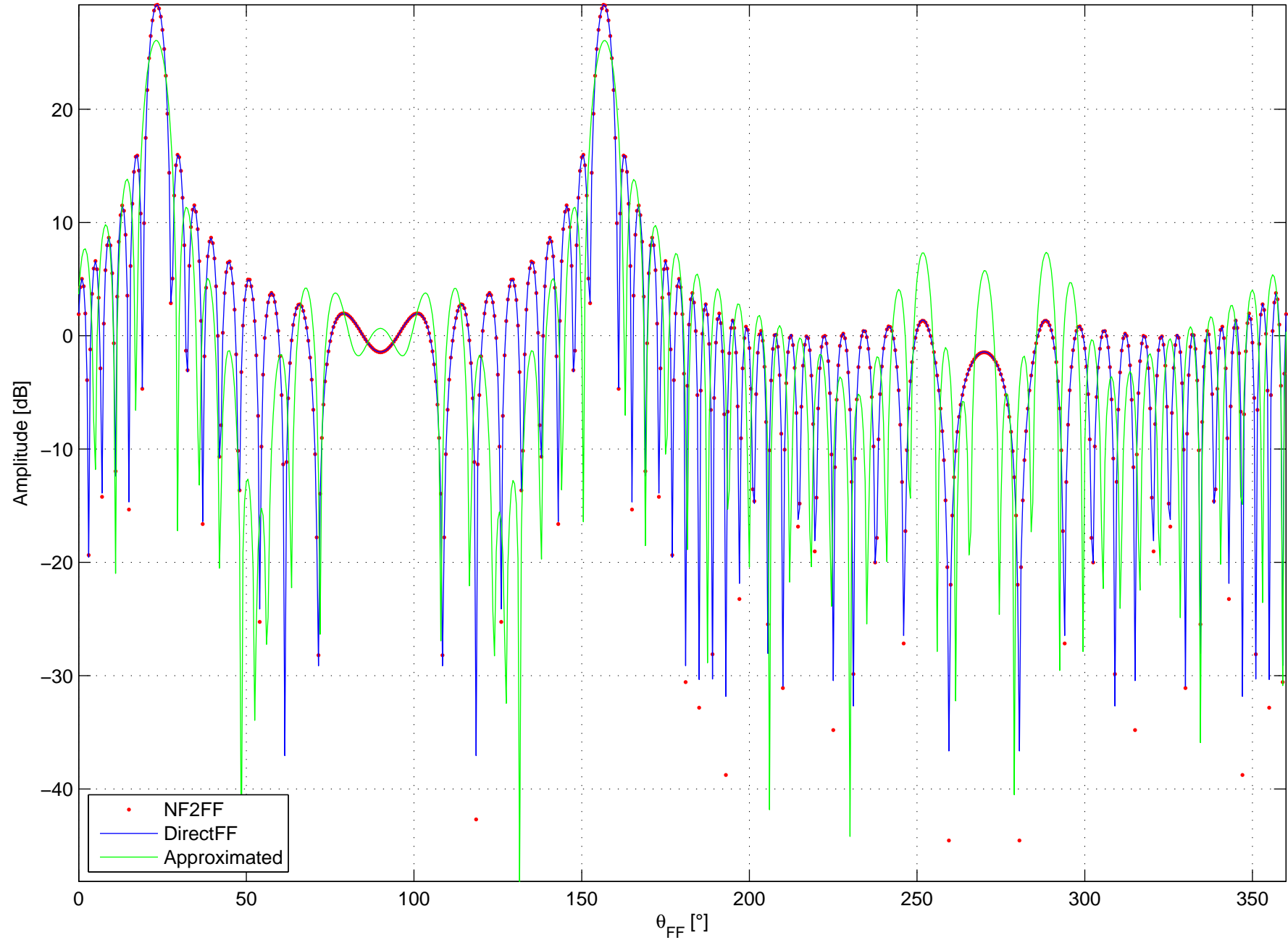


29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.49034  
FFSamples = 721, NFSamples = 16200, Coefficients = 61

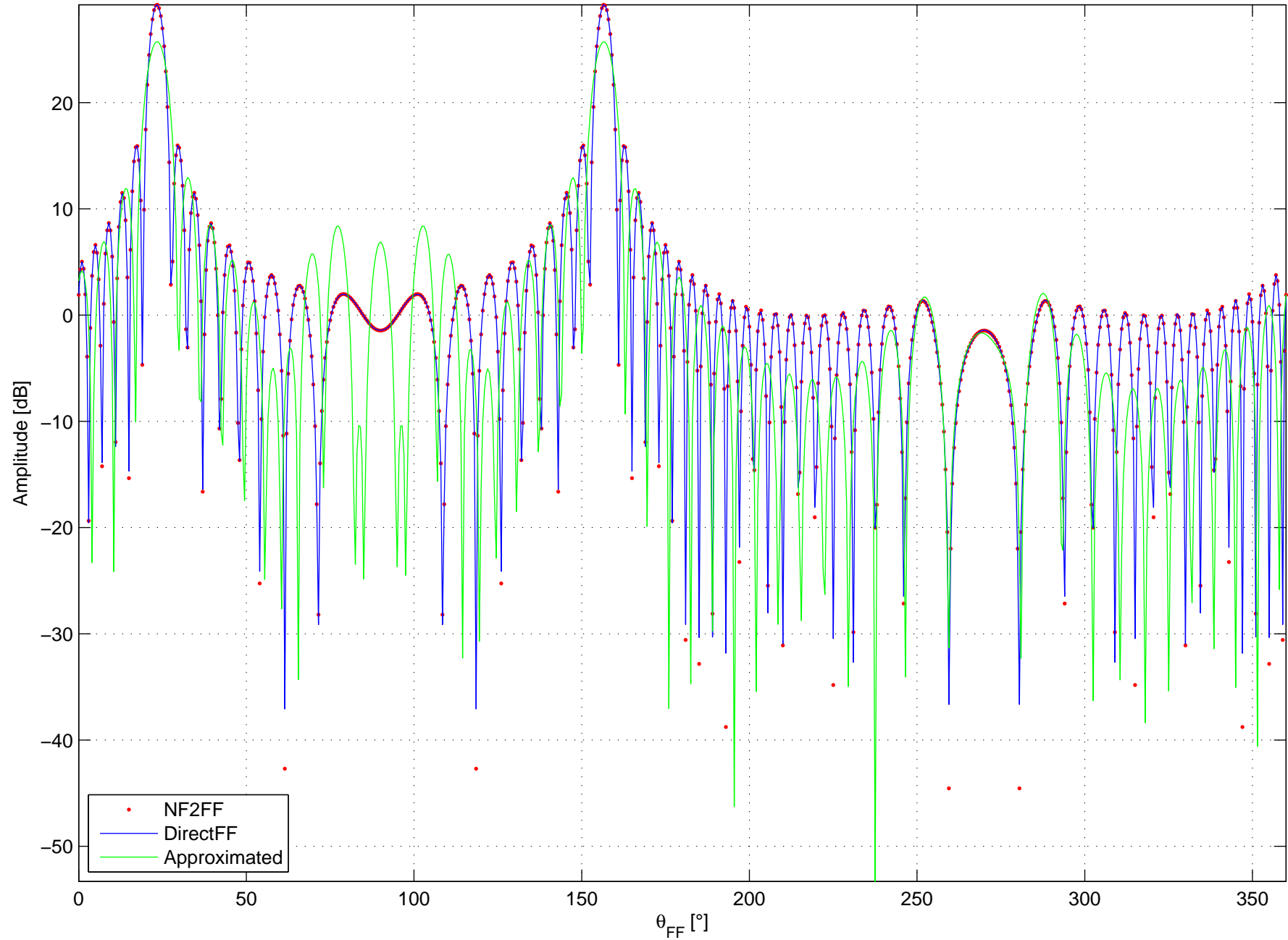




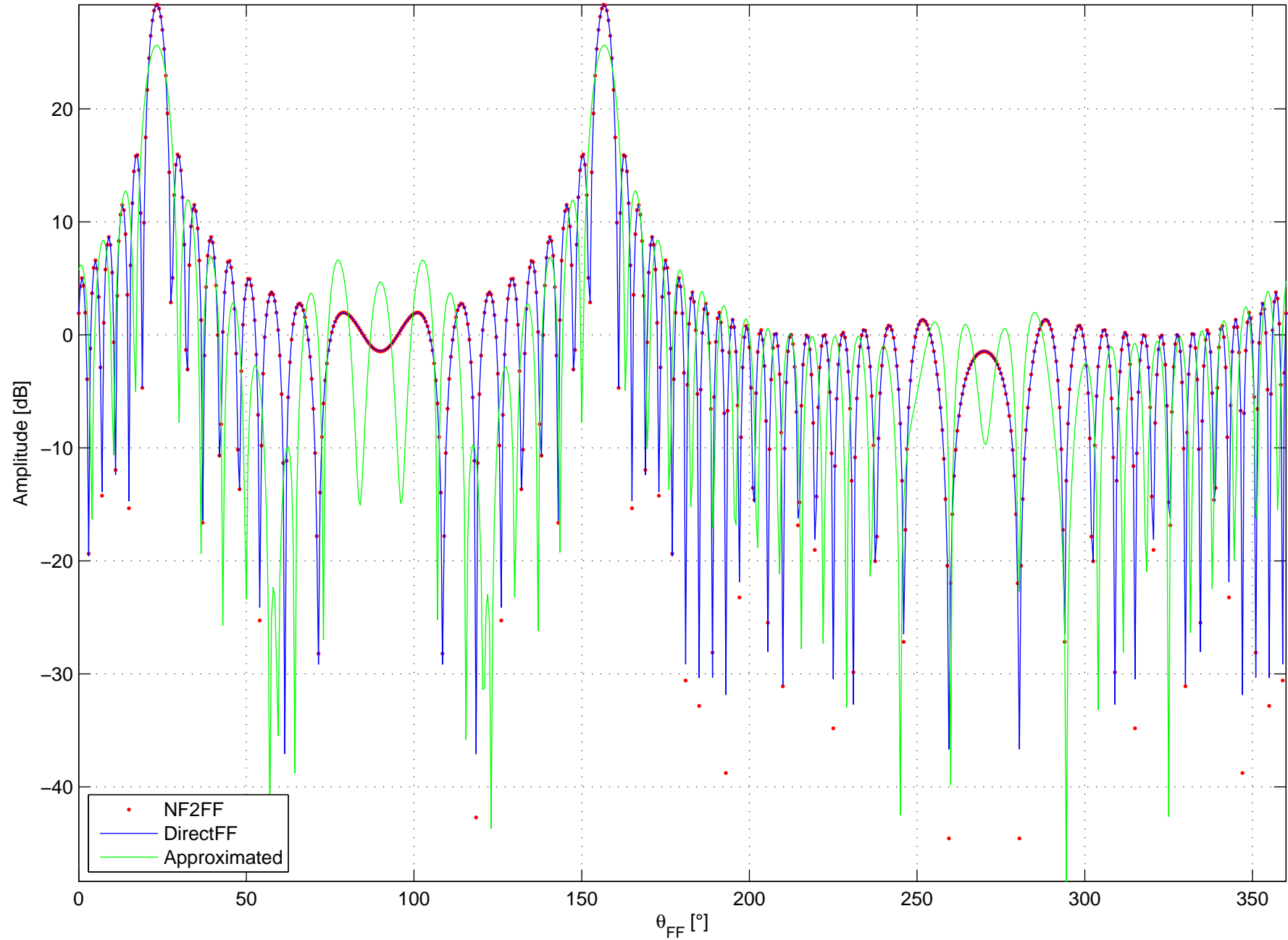
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.55033  
FFSamples = 721, NFSamples = 16200, Coefficients = 59



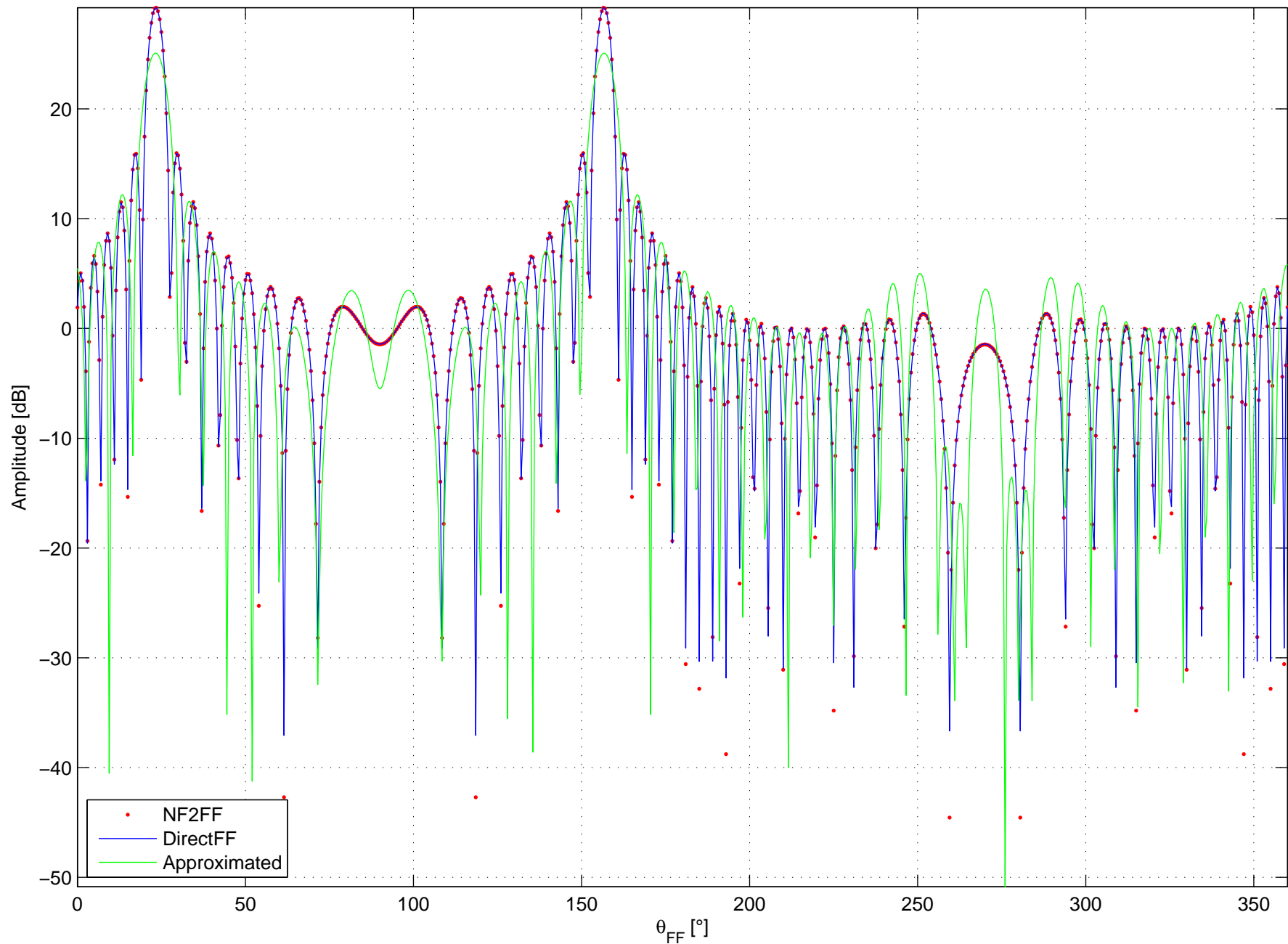
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.57806  
FFSamples = 721, NFSamples = 16200, Coefficients = 57



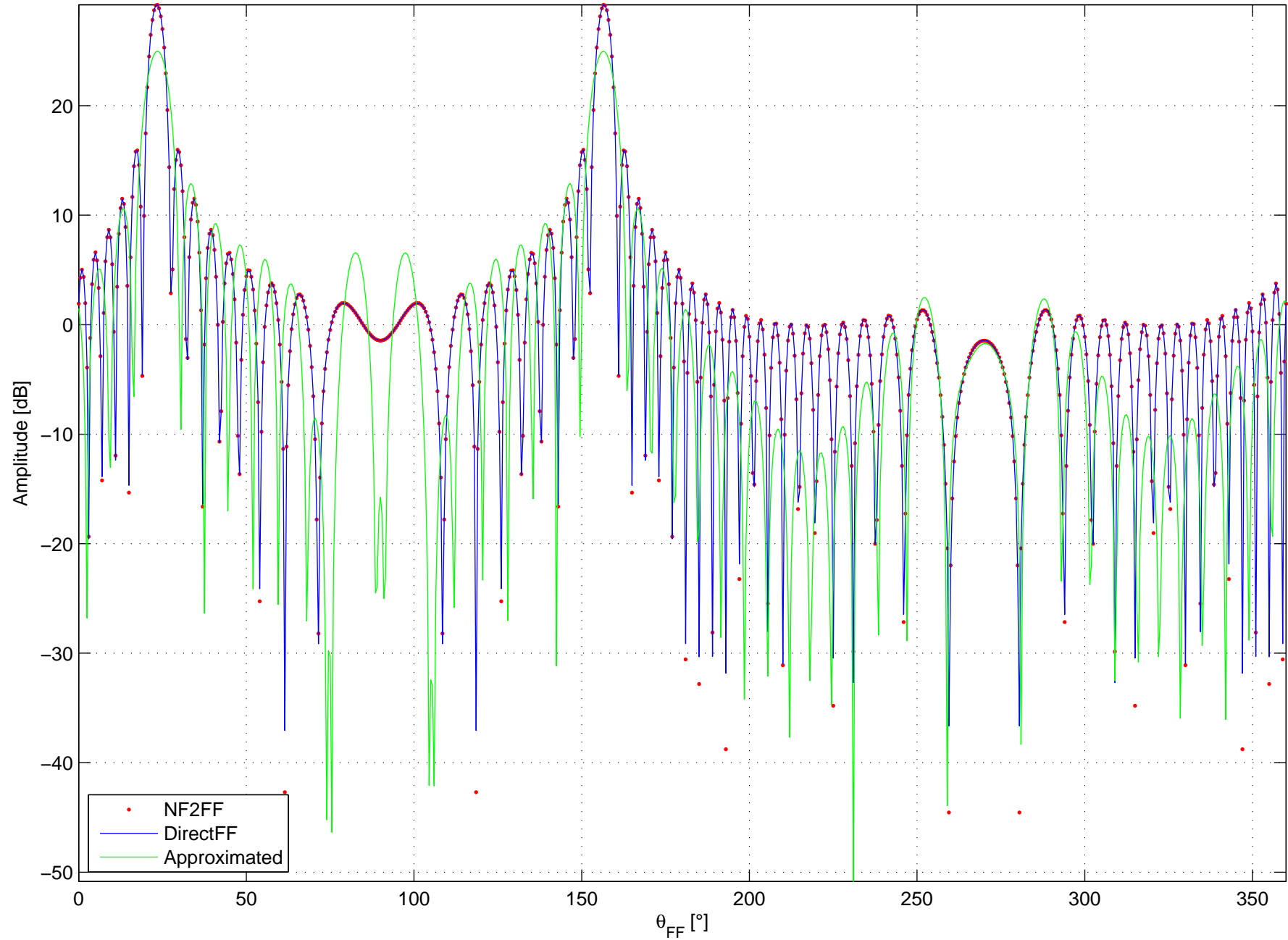
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.58312  
FFSamples = 721, NFSamples = 16200, Coefficients = 55



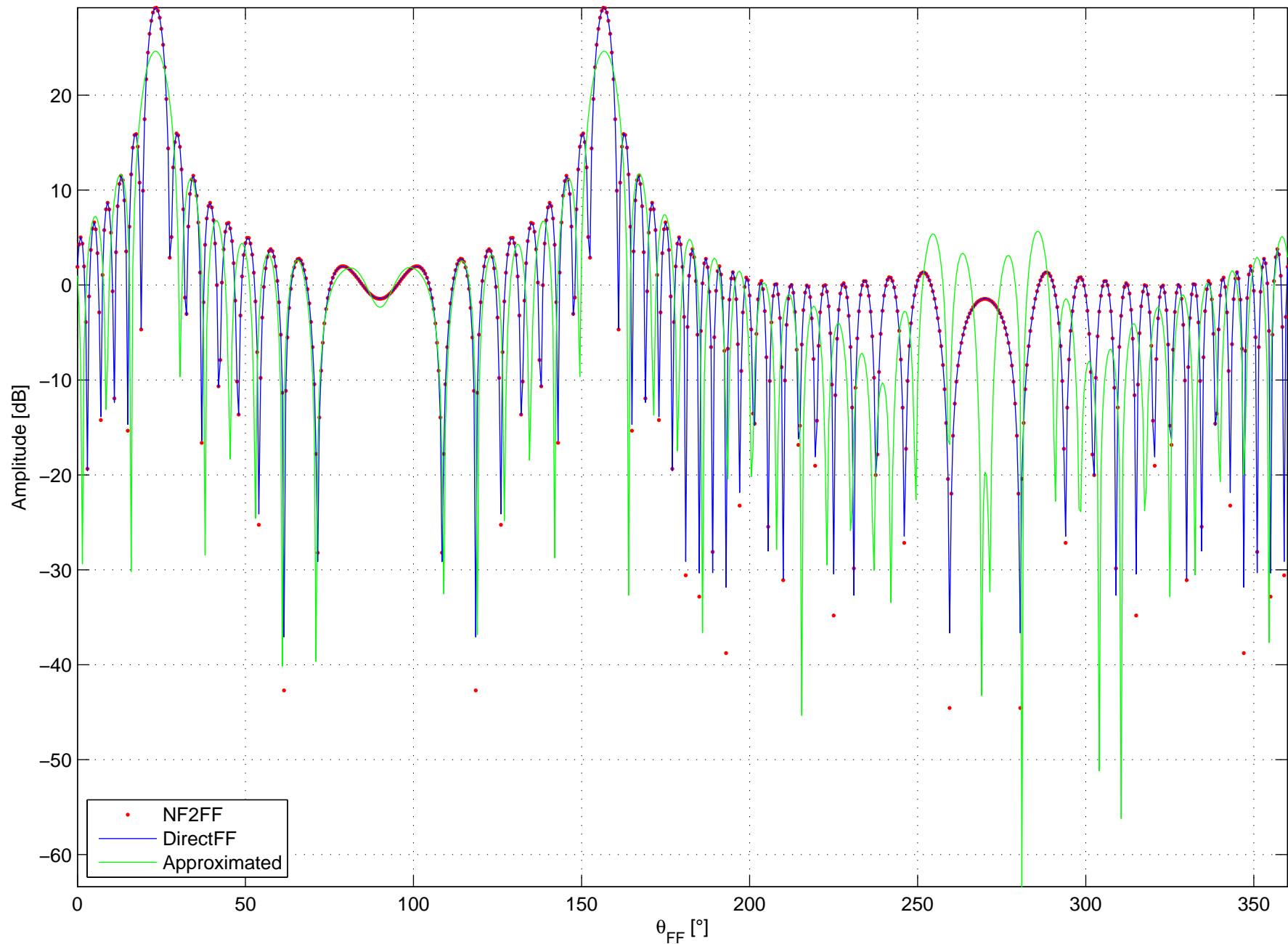
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.61206  
FFSamples = 721, NFSamples = 16200, Coefficients = 53



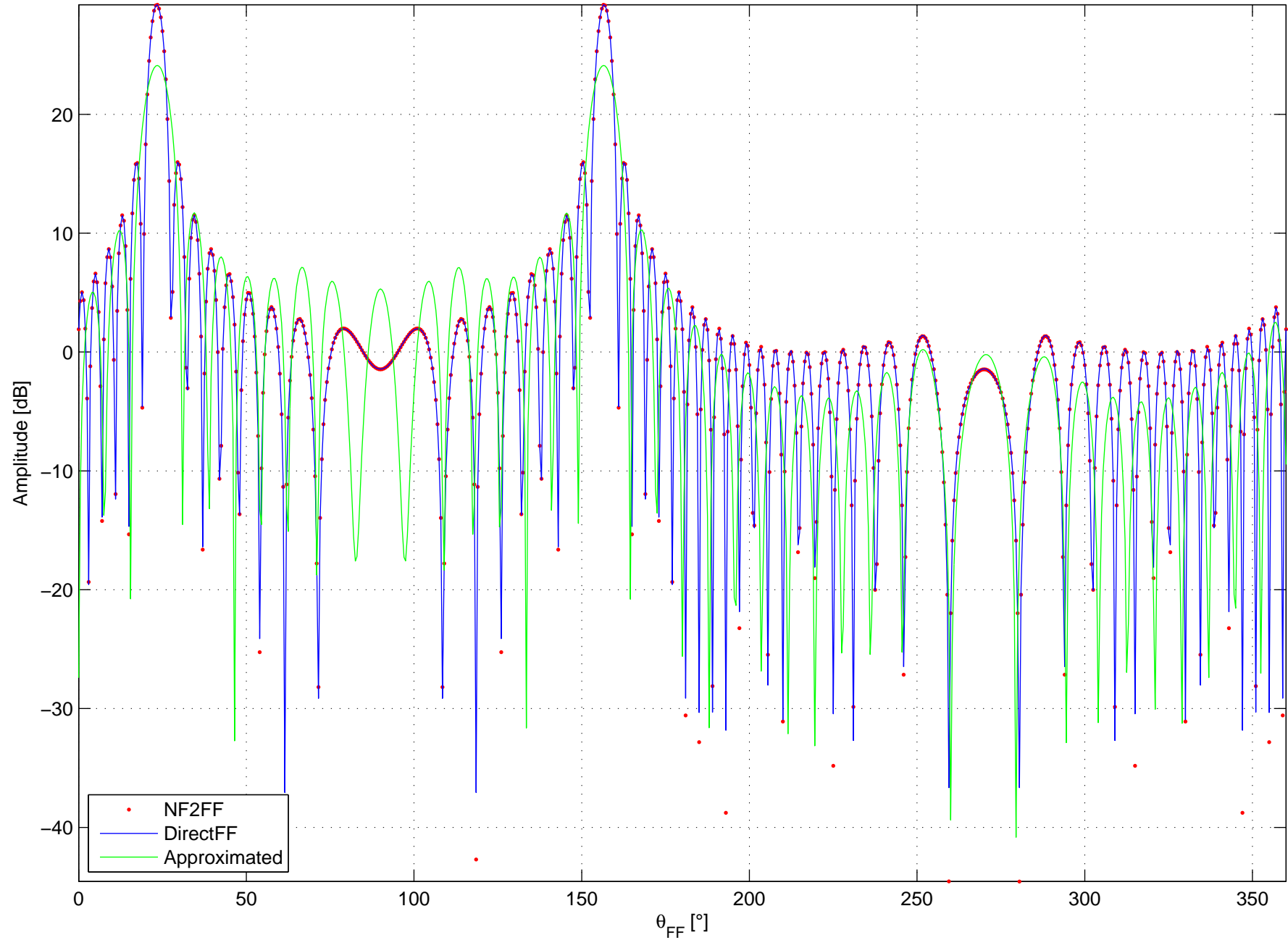
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.62164  
FFSamples = 721, NFSamples = 16200, Coefficients = 51



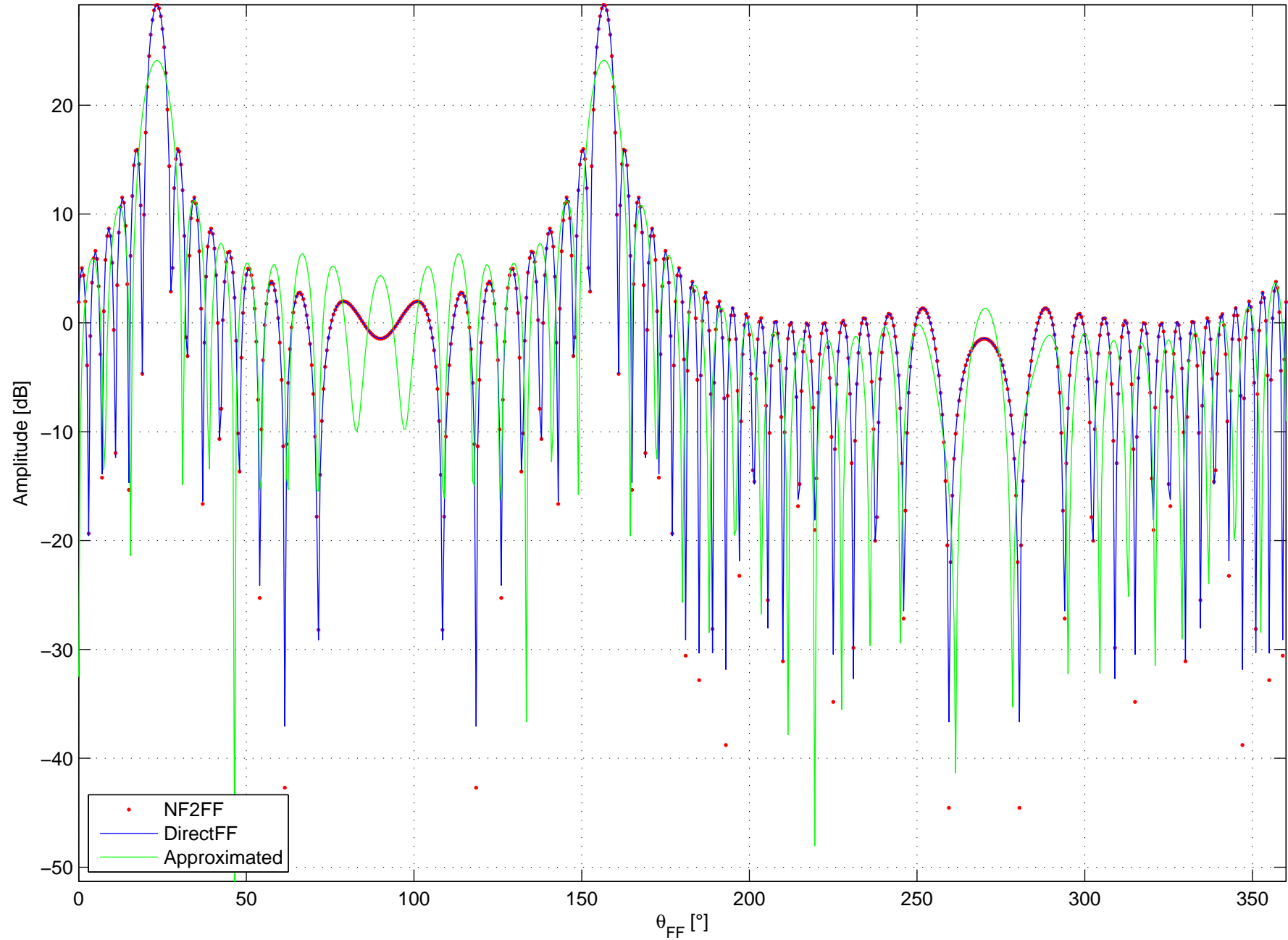
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.63836  
FFSamples = 721, NFSamples = 16200, Coefficients = 49



29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.66041  
FFSamples = 721, NFSamples = 16200, Coefficients = 47

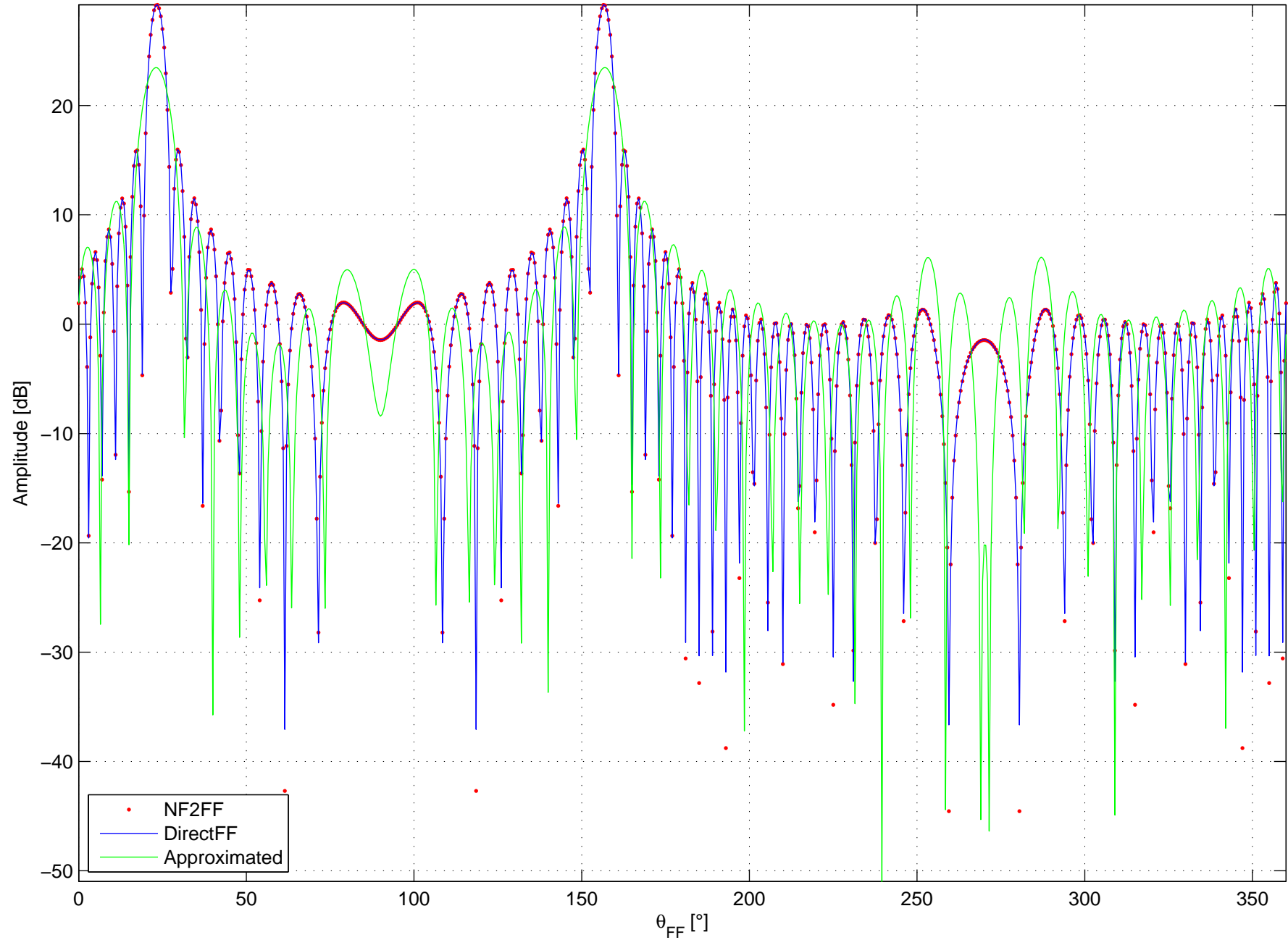


29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.66111  
FFSamples = 721, NFSamples = 16200, Coefficients = 45

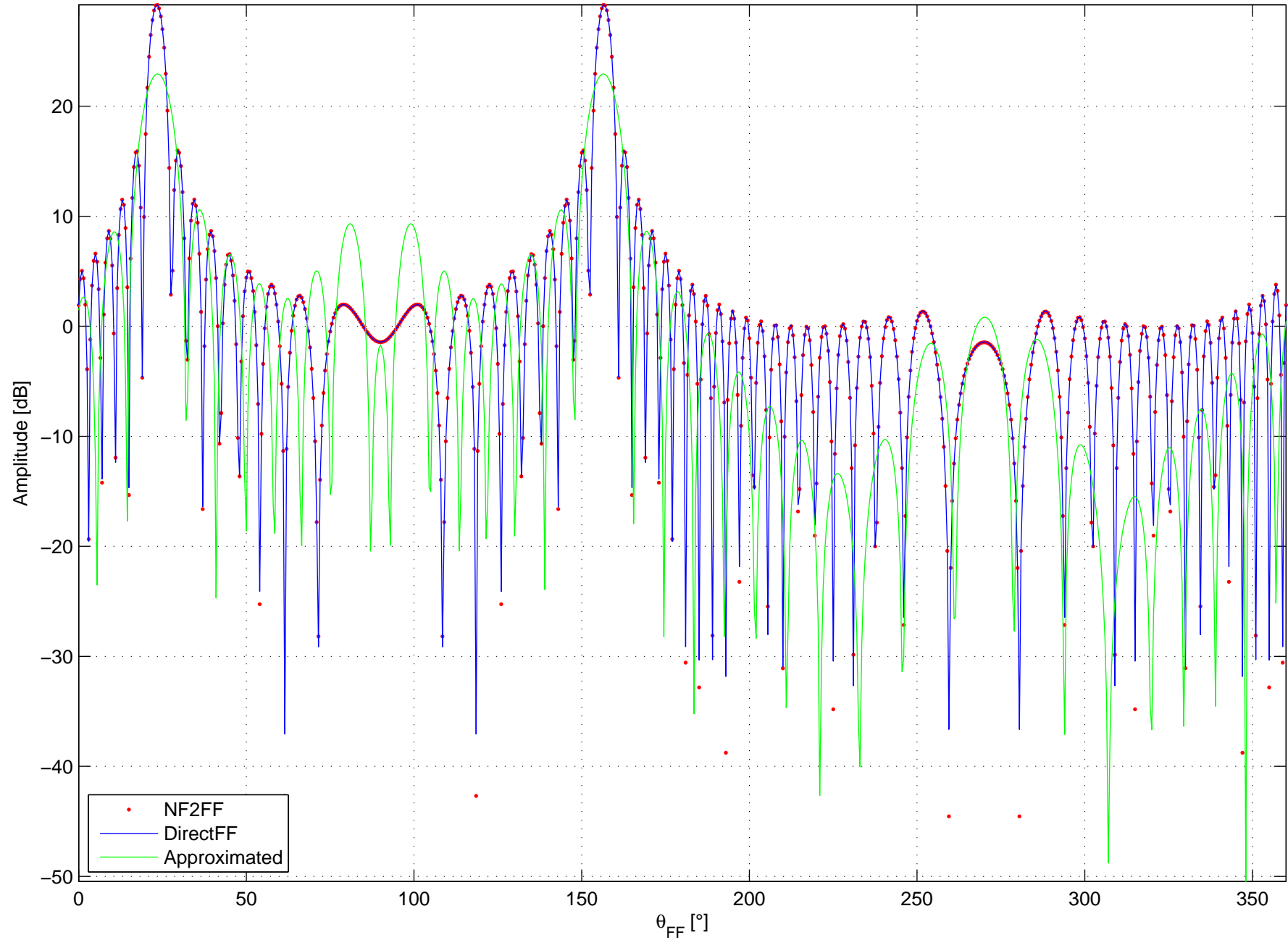




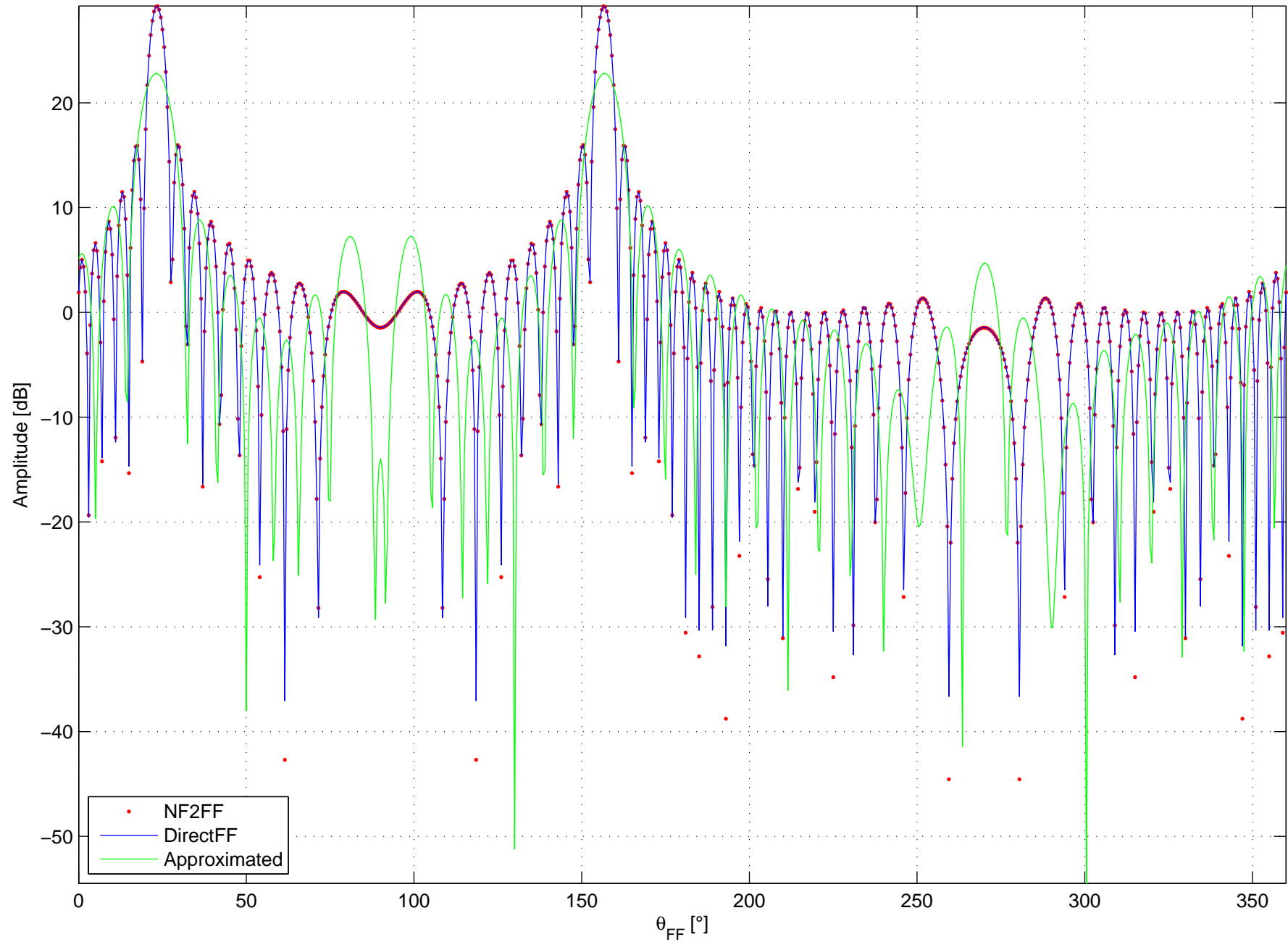
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.6904  
FFSamples = 721, NFSamples = 16200, Coefficients = 43



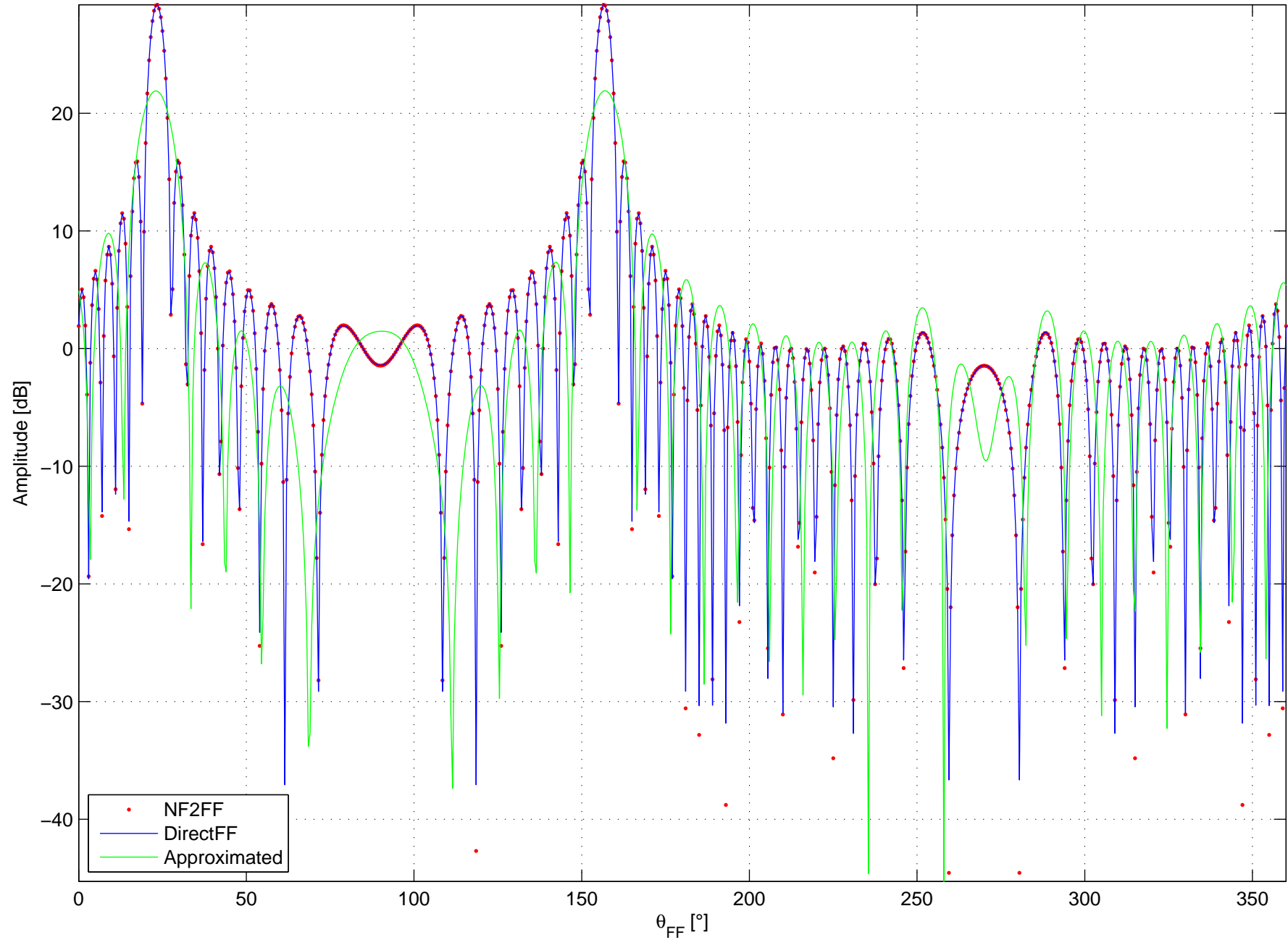
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.71556  
FFSamples = 721, NFSamples = 16200, Coefficients = 41



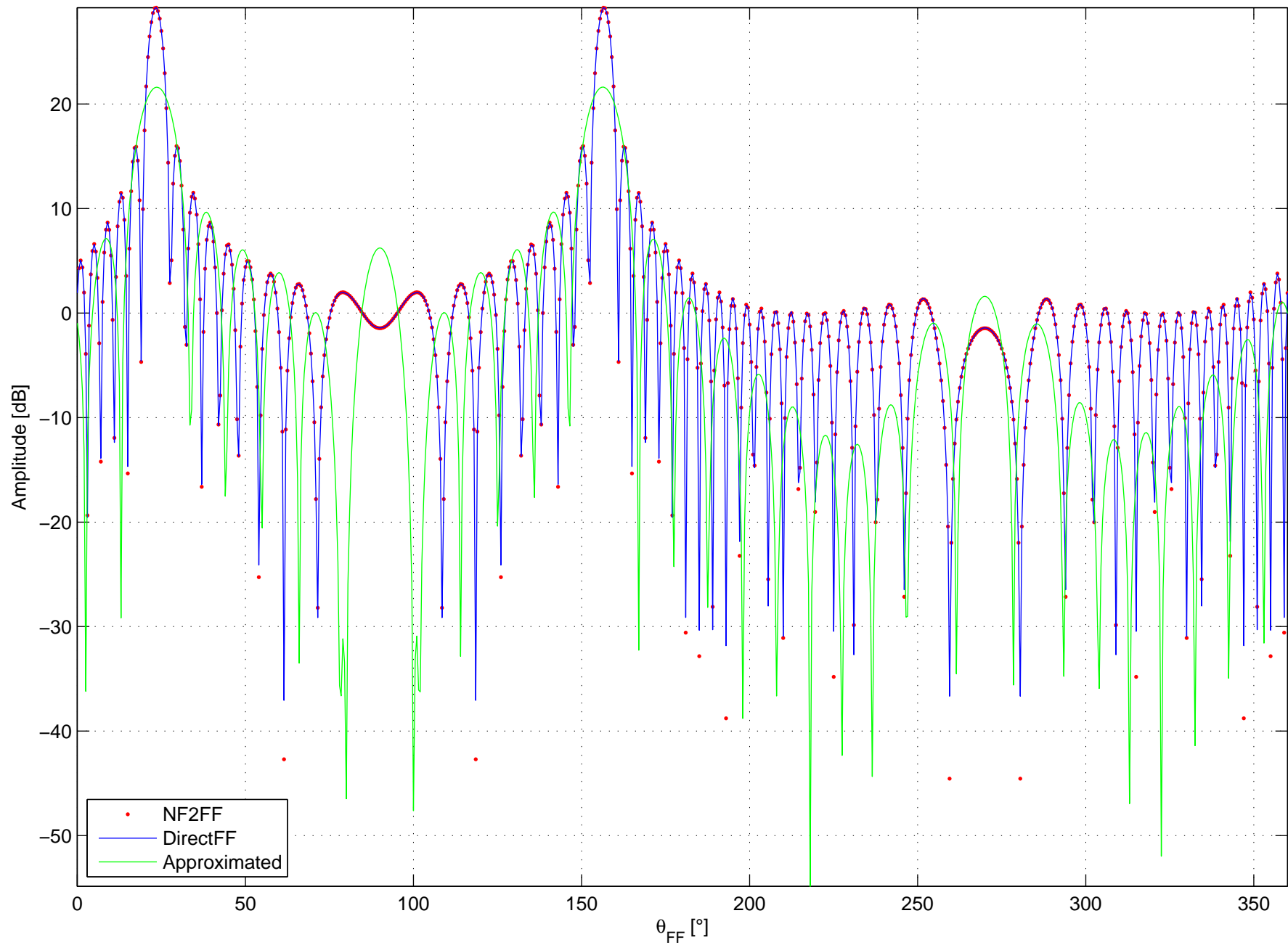
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.72214  
FFSamples = 721, NFSamples = 16200, Coefficients = 39



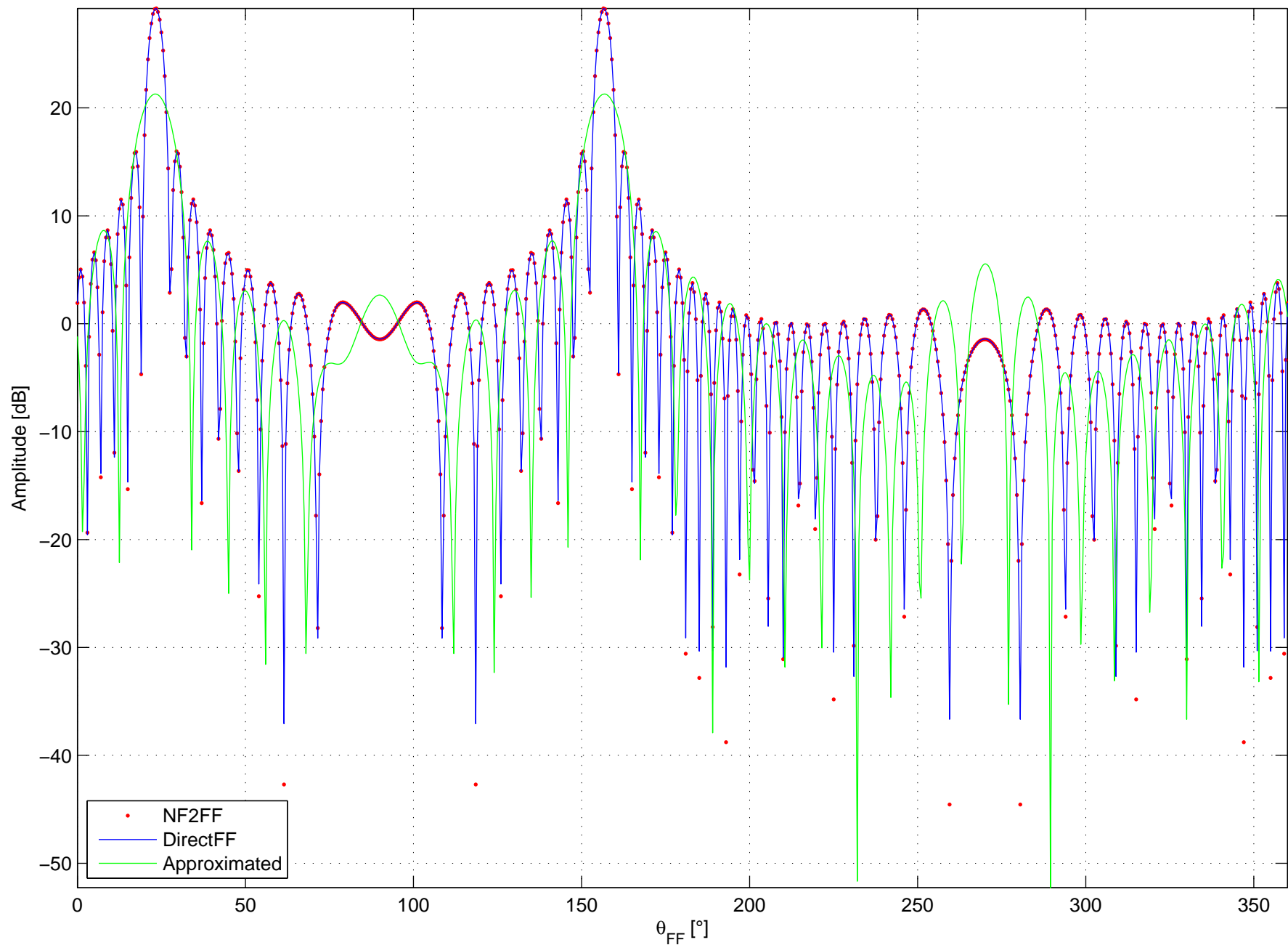
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.75406  
FFSamples = 721, NFSamples = 16200, Coefficients = 37



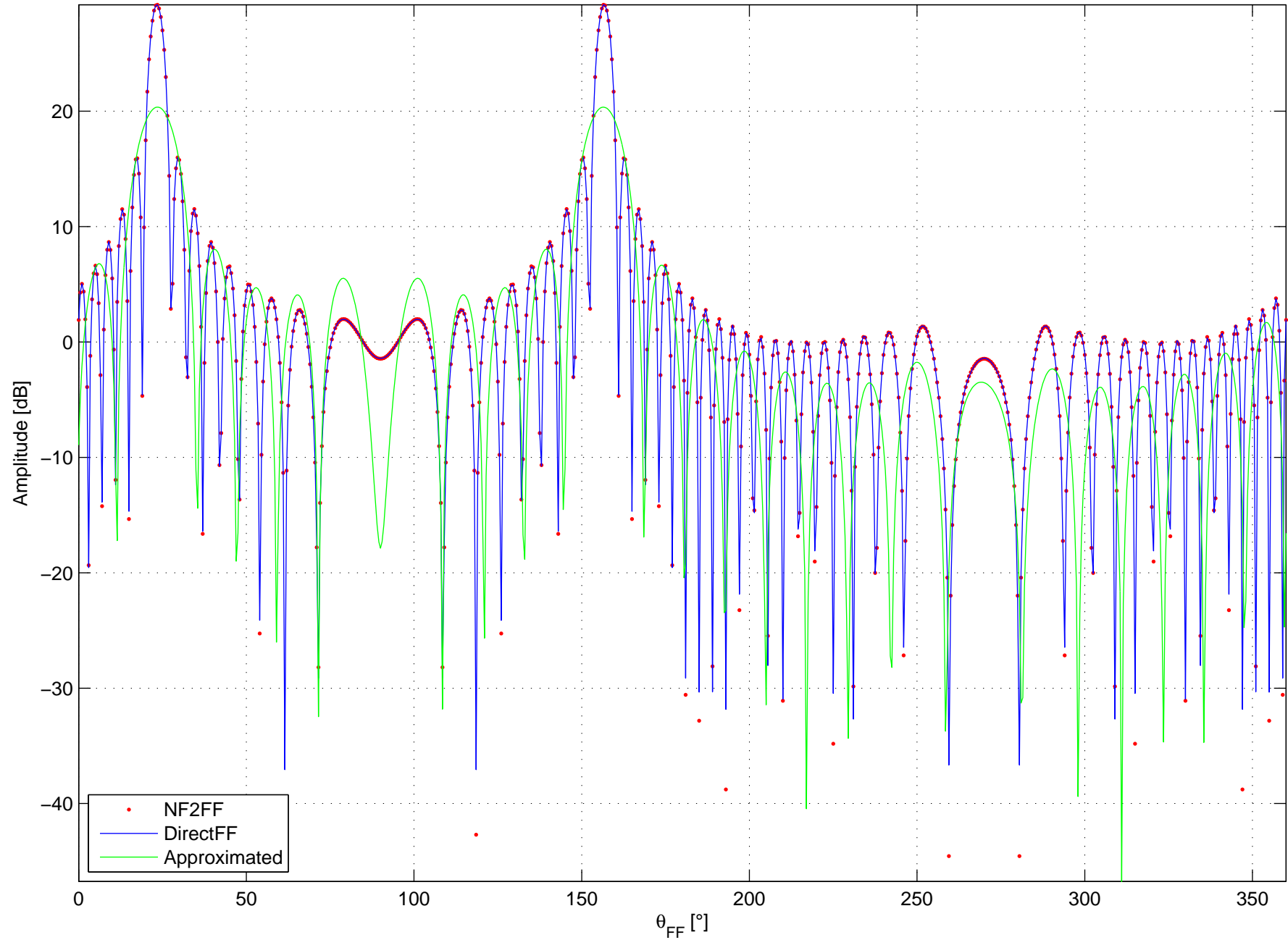
29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.76619  
FFSamples = 721, NFSamples = 16200, Coefficients = 35



29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.77385  
FFSamples = 721, NFSamples = 16200, Coefficients = 33



29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.79751  
FFSamples = 721, NFSamples = 16200, Coefficients = 31



29 x 0.5 $\lambda$ , Rad : 7.5 $\lambda$   
Steering angle : 23.3251°, L<sup>2</sup> error = 0.79751  
FFSamples = 721, NFSamples = 16200, Coefficients = 31

