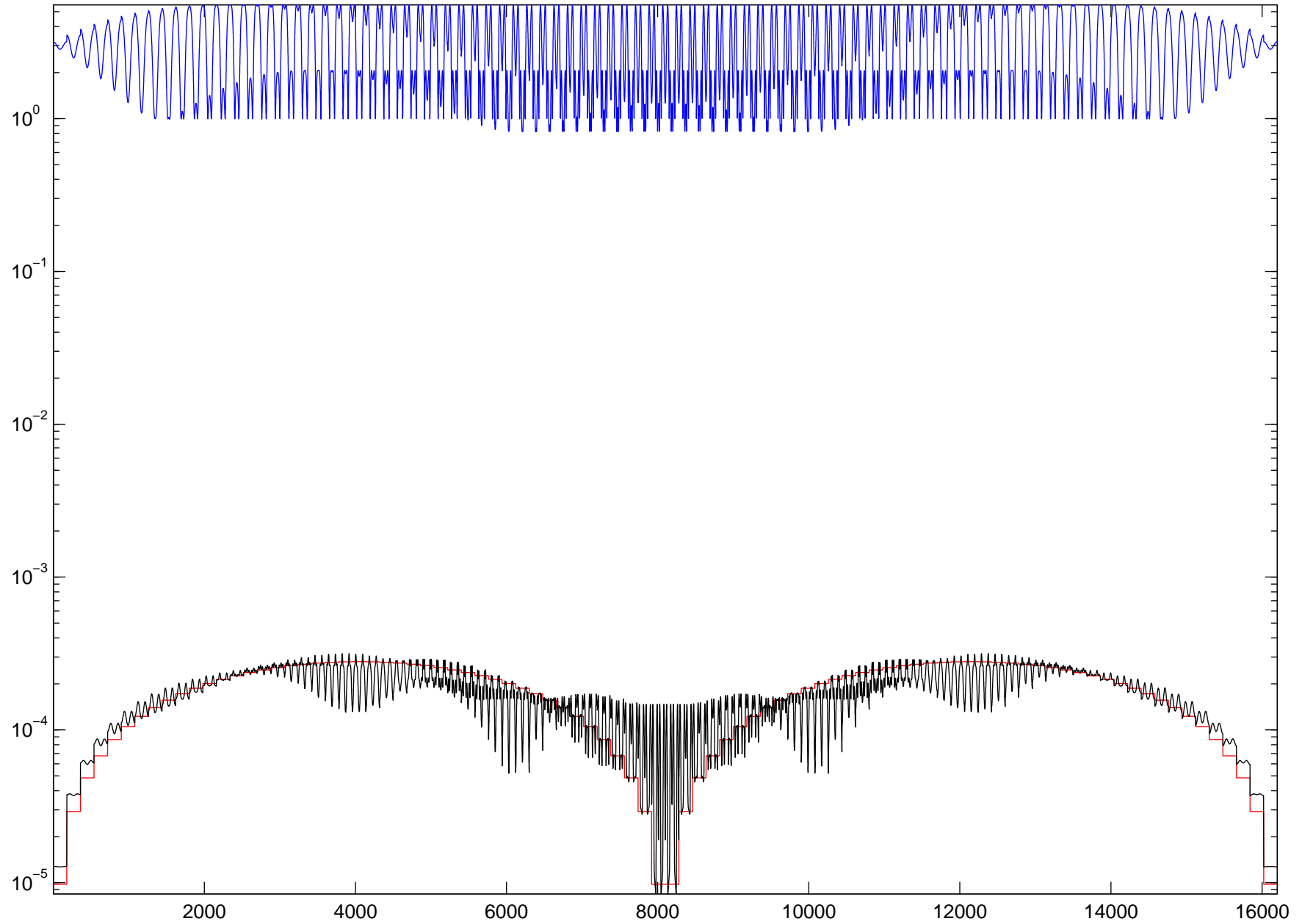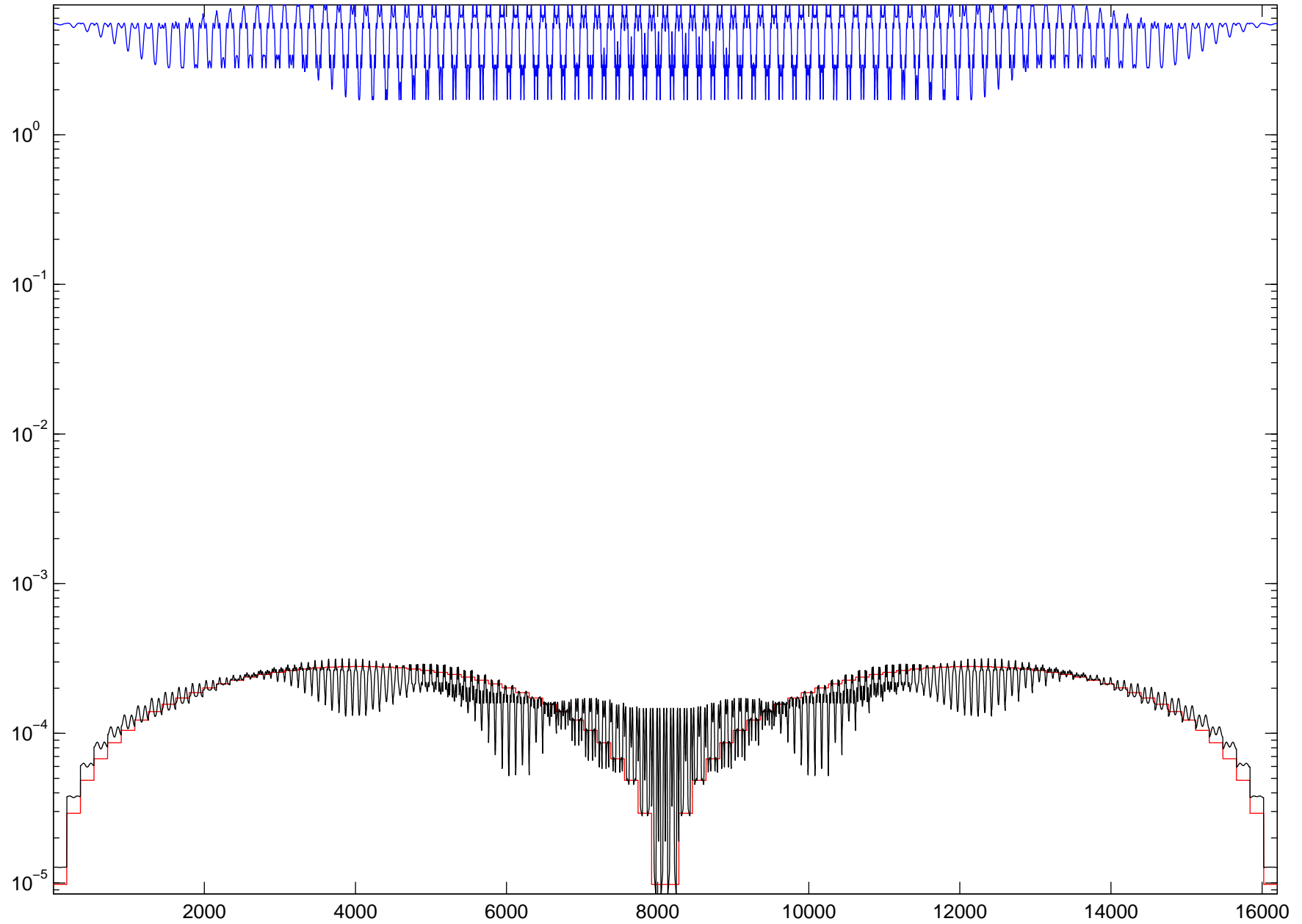θ = 0, 3 x 0.5λ, Rad : 1.75λ
Steering angle : 23.3251°, L^2 error = 0.0061128
FFSamples = 361, NFSamples = 16200, Coefficients = 15

θ = 0, 6 x 0.5λ, Rad : 1.75λ

Steering angle : 23.3251°, L^2 error = 0.29319

FFSamples = 361, NFSamples = 16200, Coefficients = 15

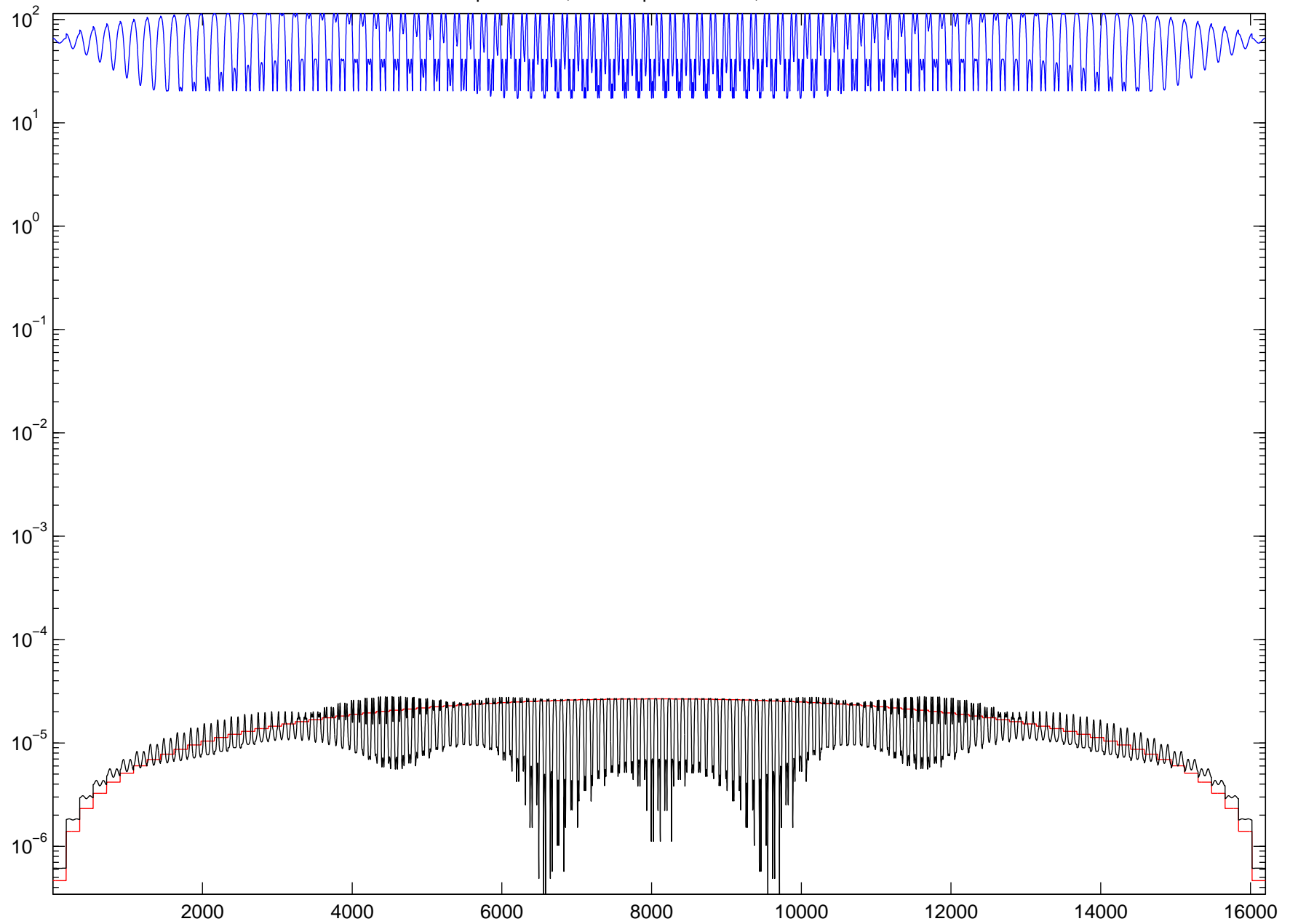θ = 0, 3 x 0.5λ, Rad : 1.75λ

Steering angle : 23.3251°, L^2 error = 0.0061128

FFSamples = 361, NFSamples = 16200, Coefficients = 15

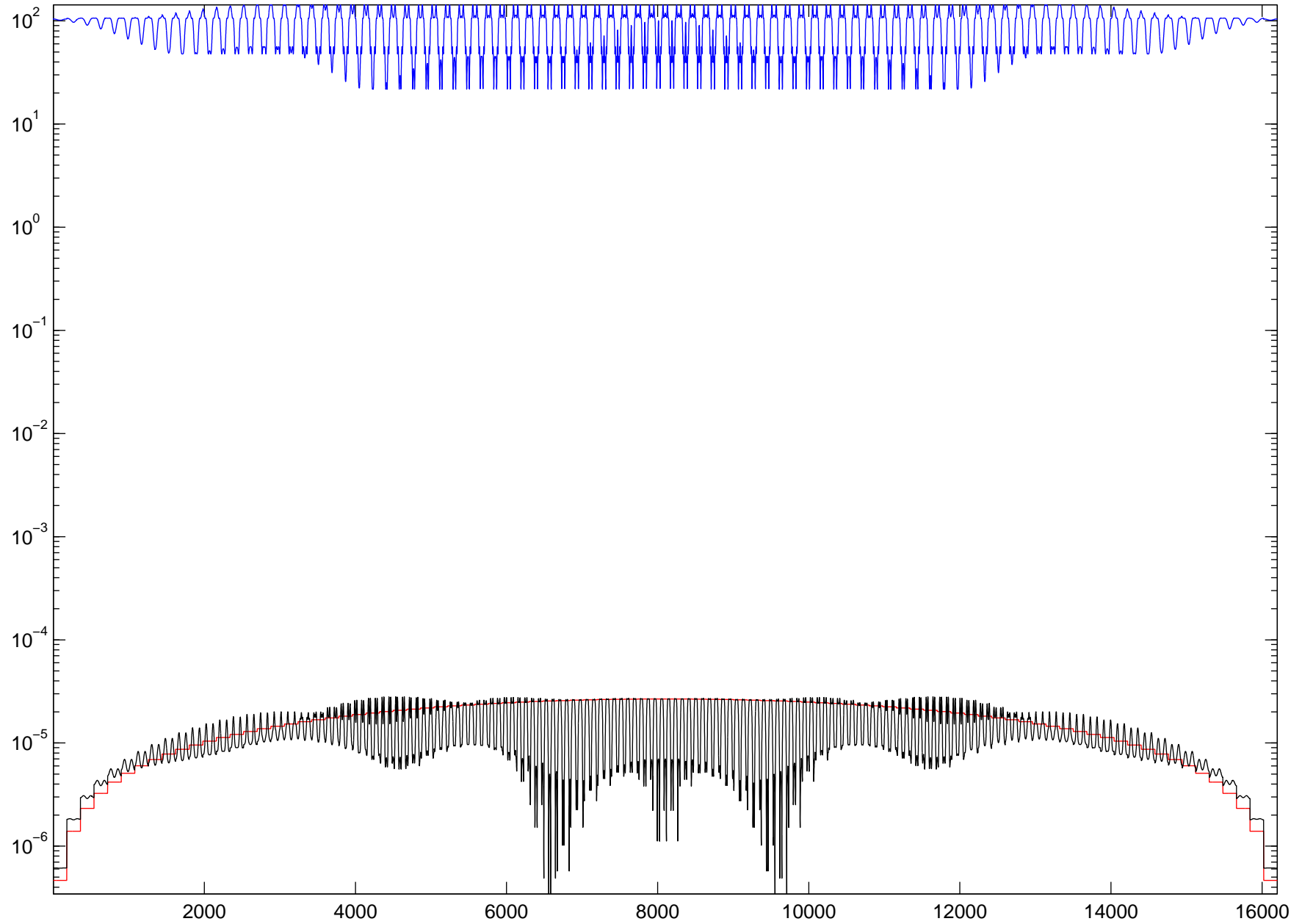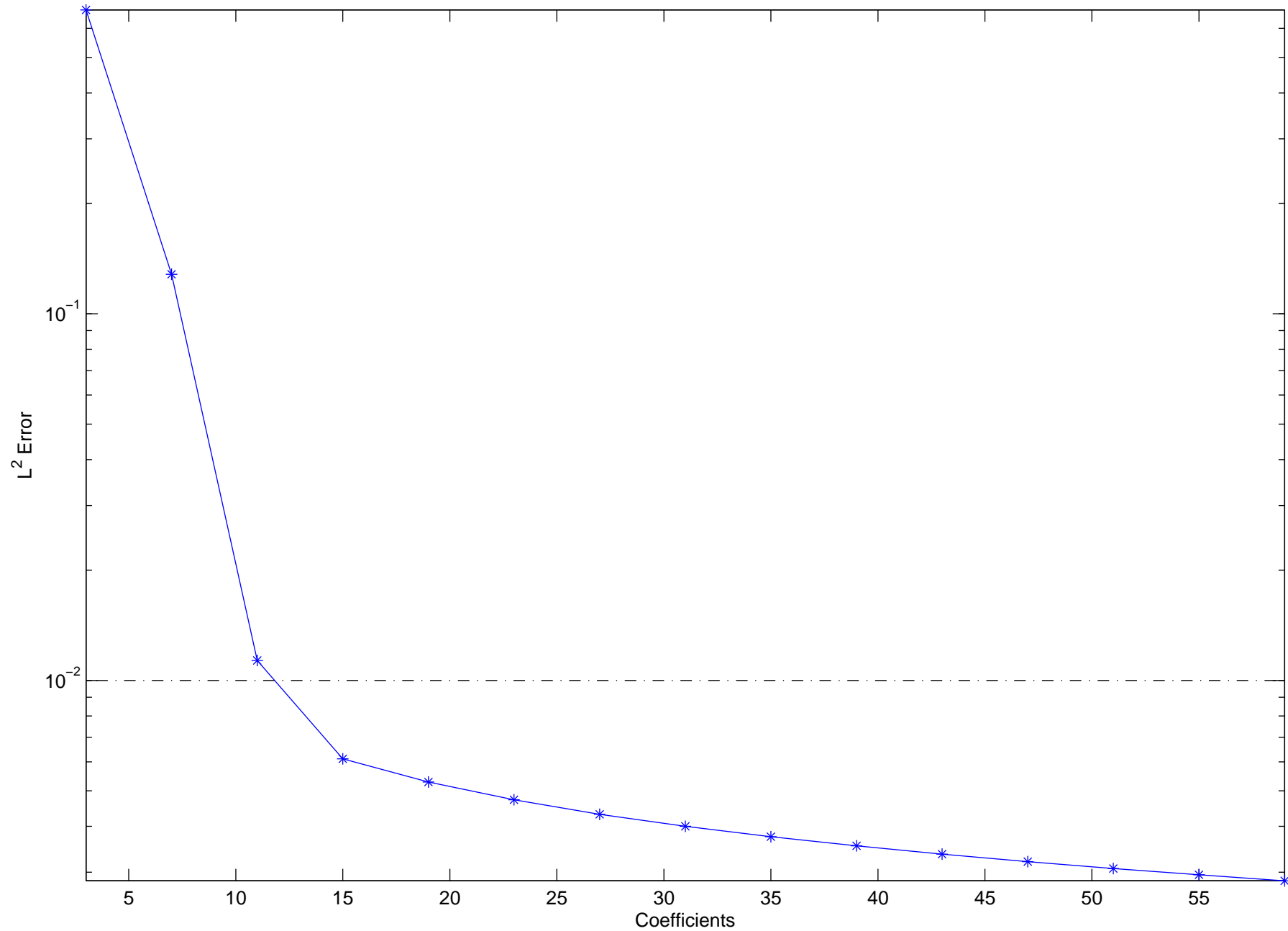θ = 0, 6 x 0.5λ, Rad : 1.75λ
Steering angle : 23.3251°, L^2 error = 0.29319
FFSamples = 361, NFSamples = 16200, Coefficients = 15

3 x 0.5λ, Rad : 1.75λ
Steering angle : 23.3251°, L^2 error = 0.67396
FFSamples = 361, NFSamples = 16200, Coefficients = 3

6 x 0.5λ, Rad : 1.75λ

Steering angle : 23.3251°, L^2 error = 0.96564

FFSamples = 361, NFSamples = 16200, Coefficients = 3