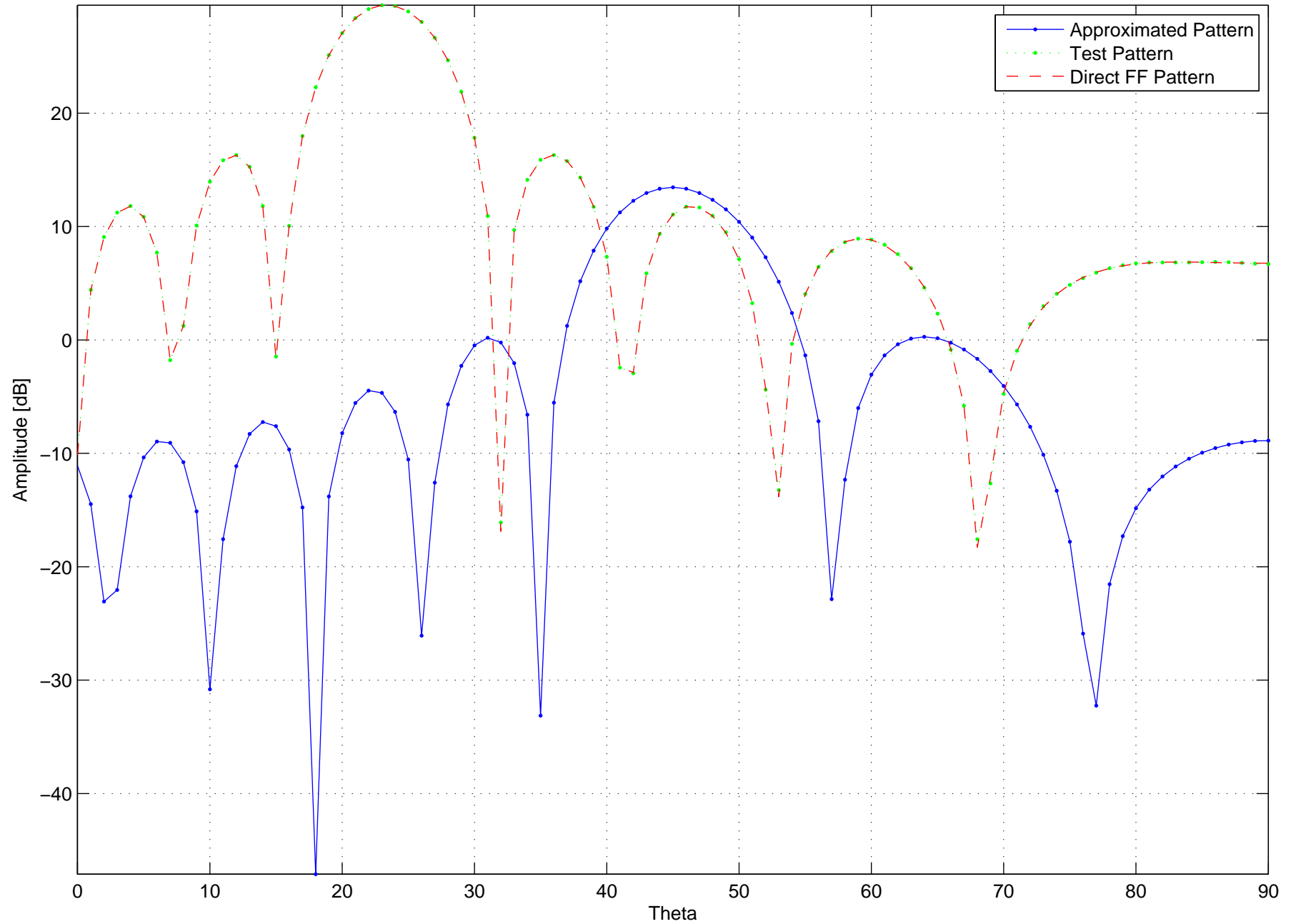
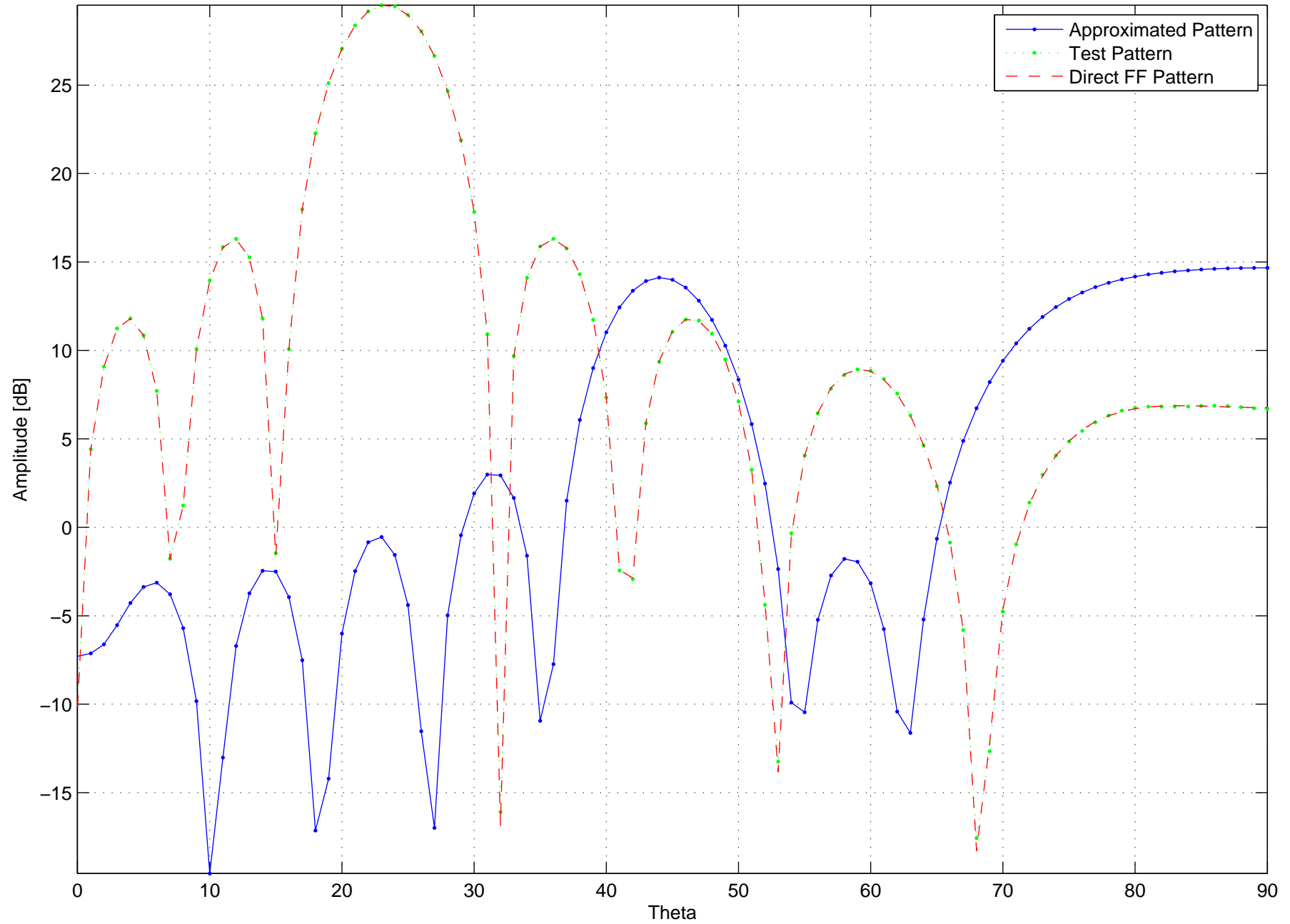


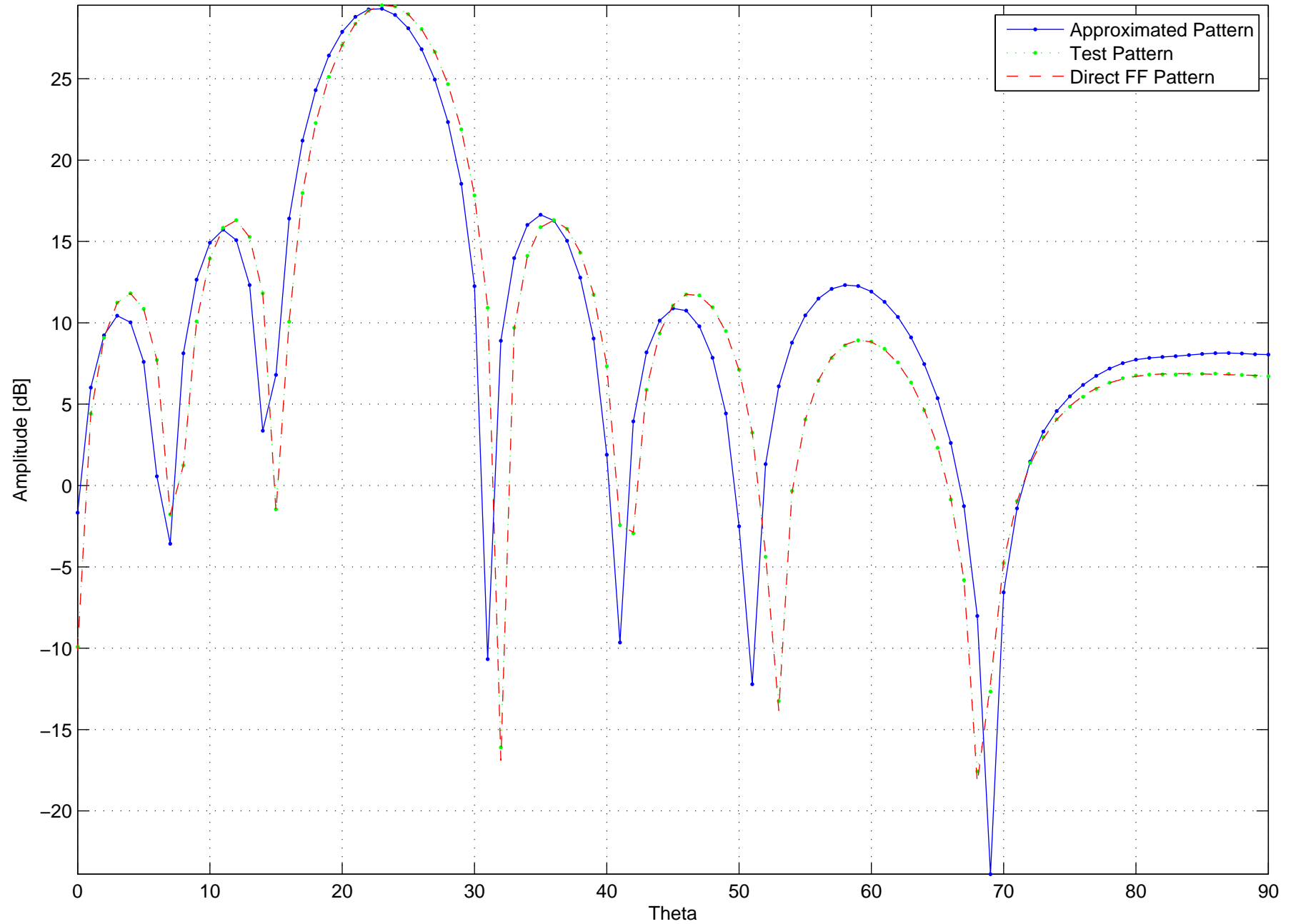
Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 0, Nbr of Vectors : 1
Nbr of point sources : 30



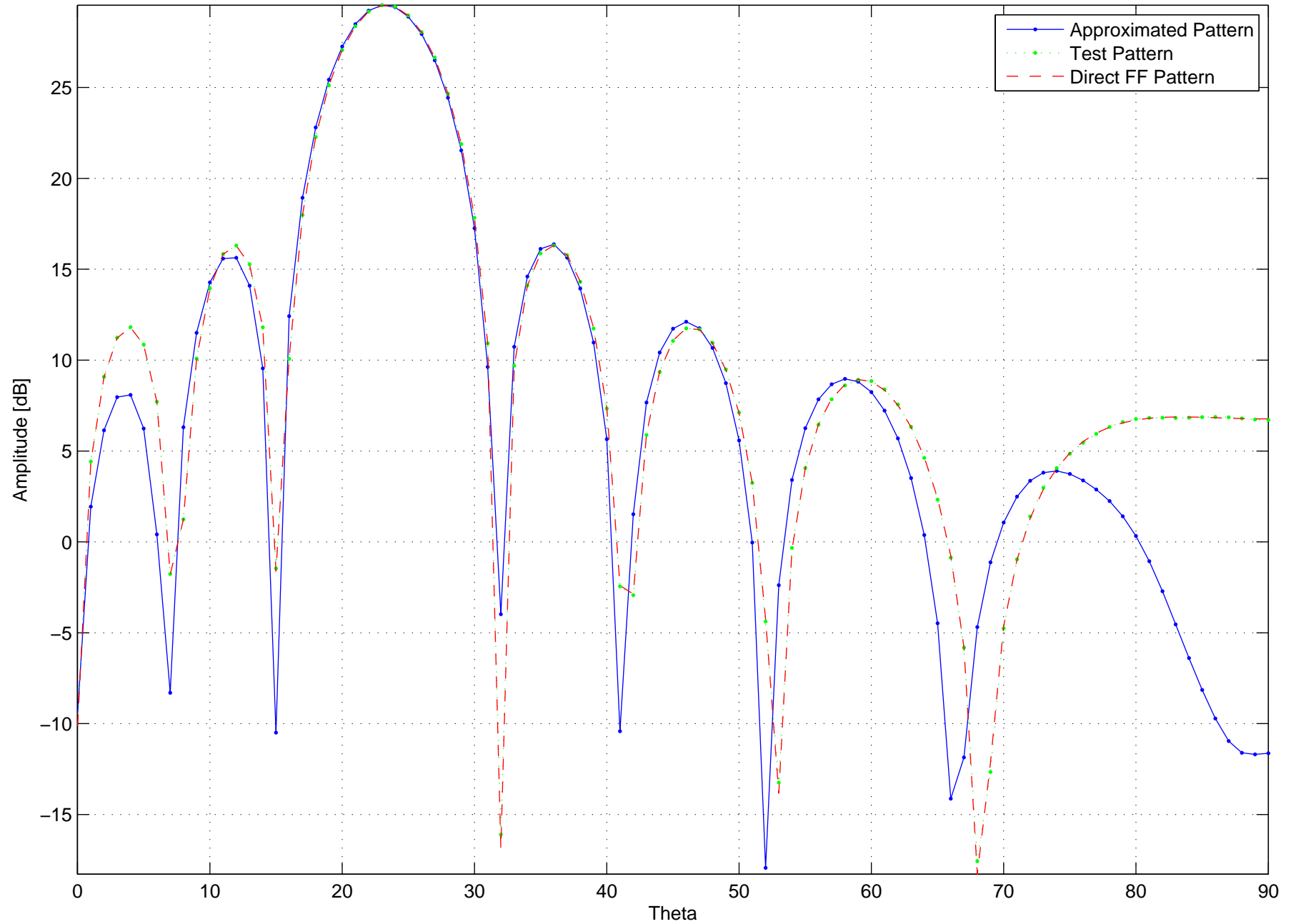
Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 0, Nbr of Vectors : 3
Nbr of point sources : 30



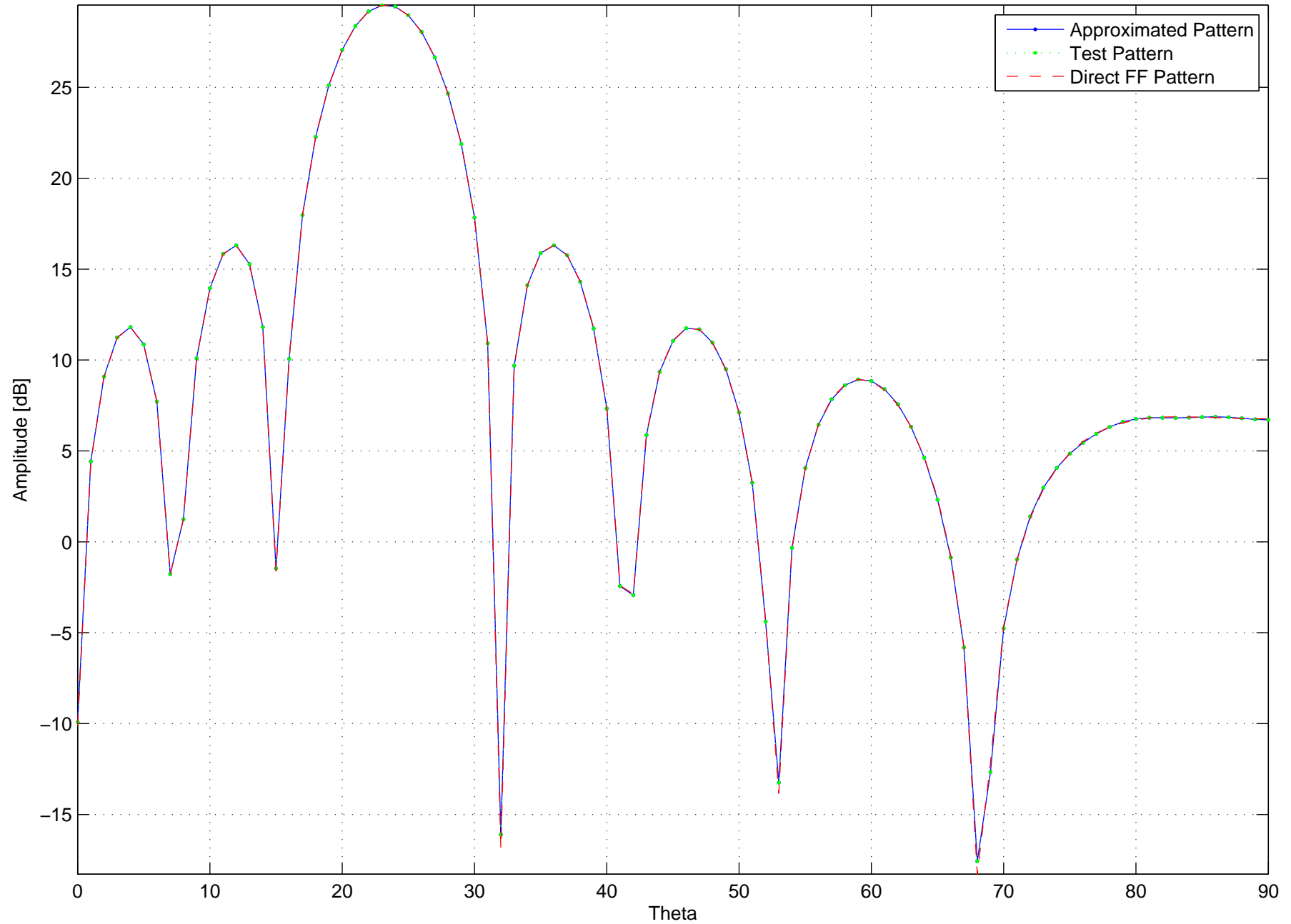
Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 0, Nbr of Vectors : 5
Nbr of point sources : 30



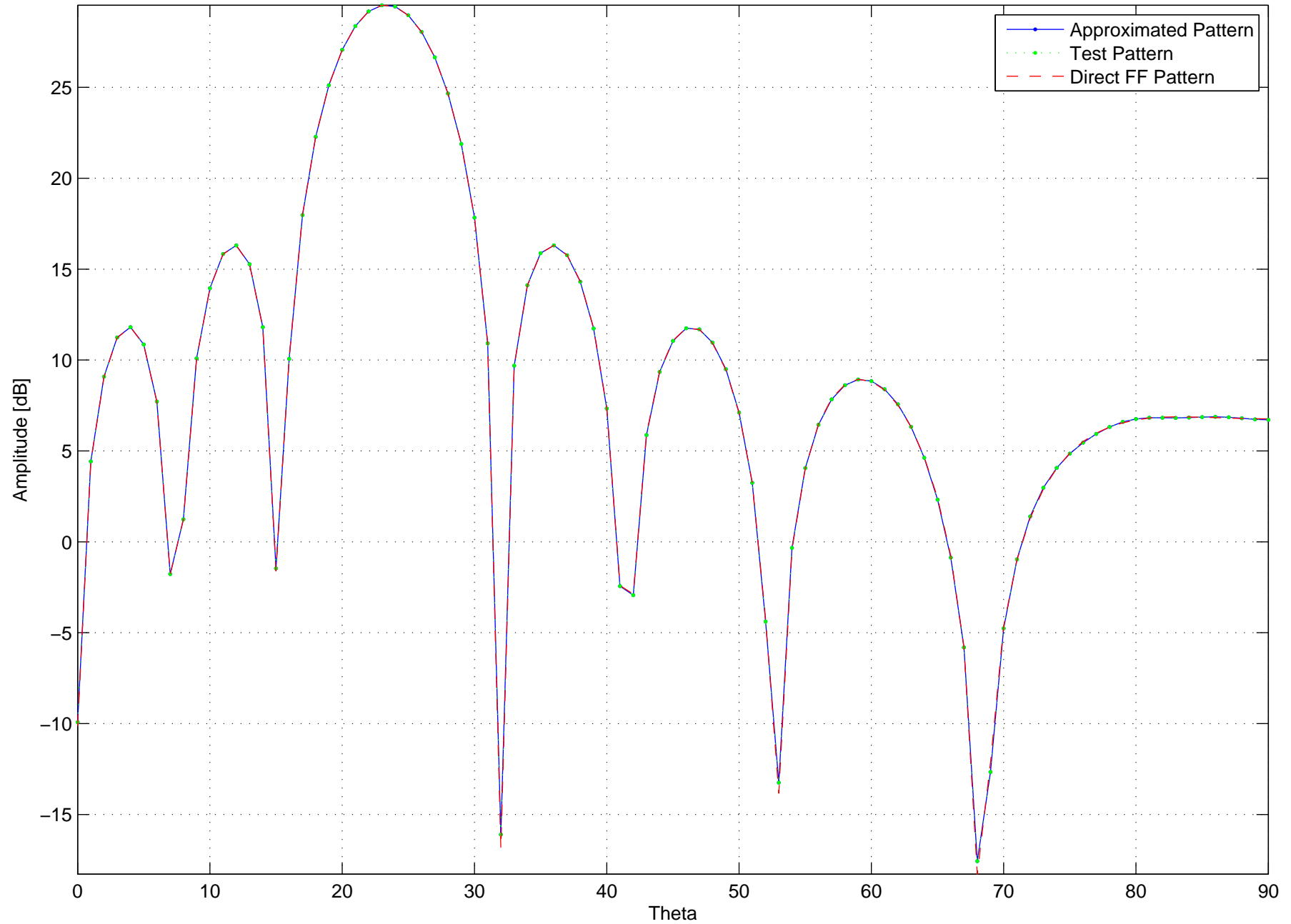
Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 0, Nbr of Vectors : 9
Nbr of point sources : 30



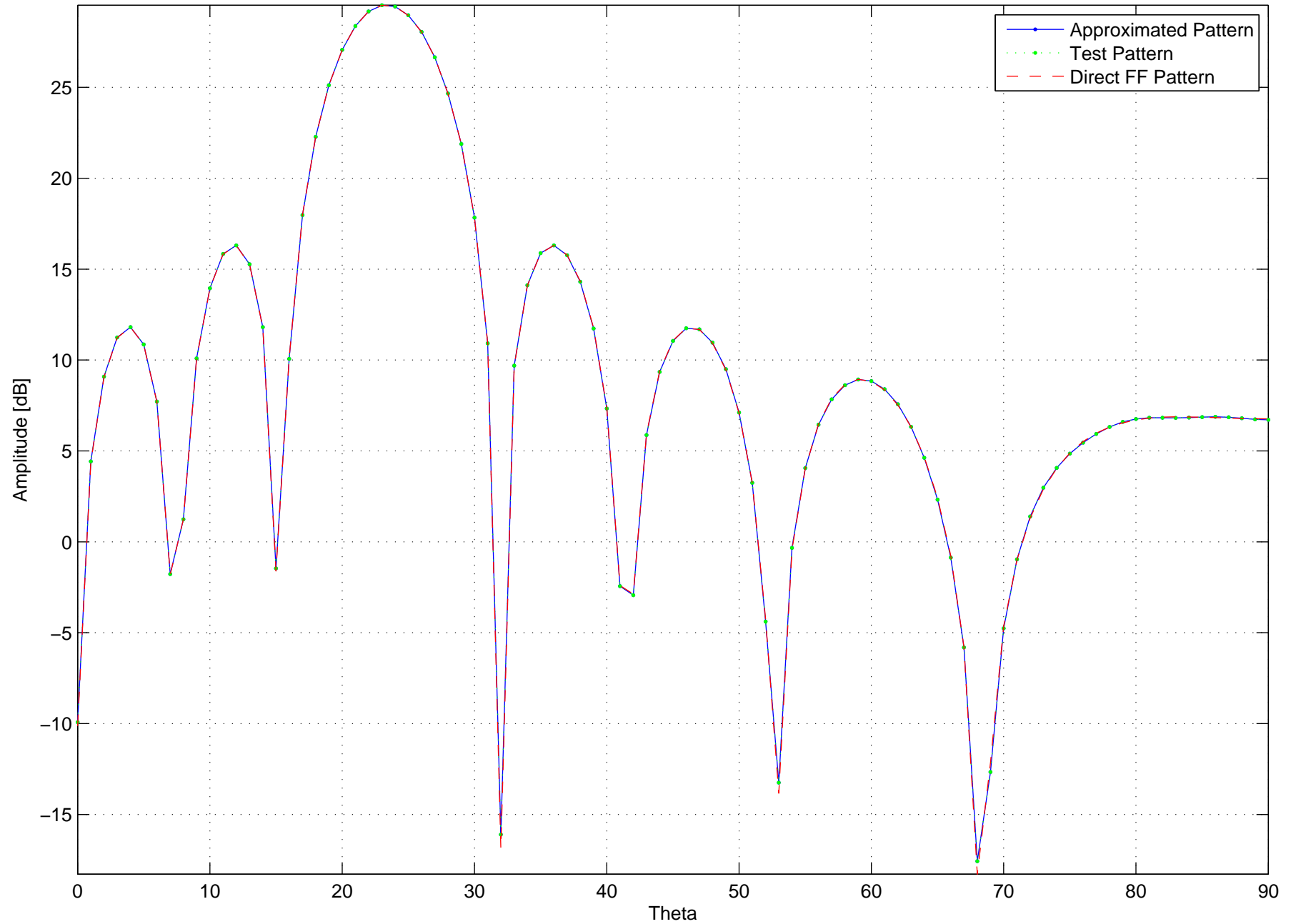
Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 0, Nbr of Vectors : 17
Nbr of point sources : 30



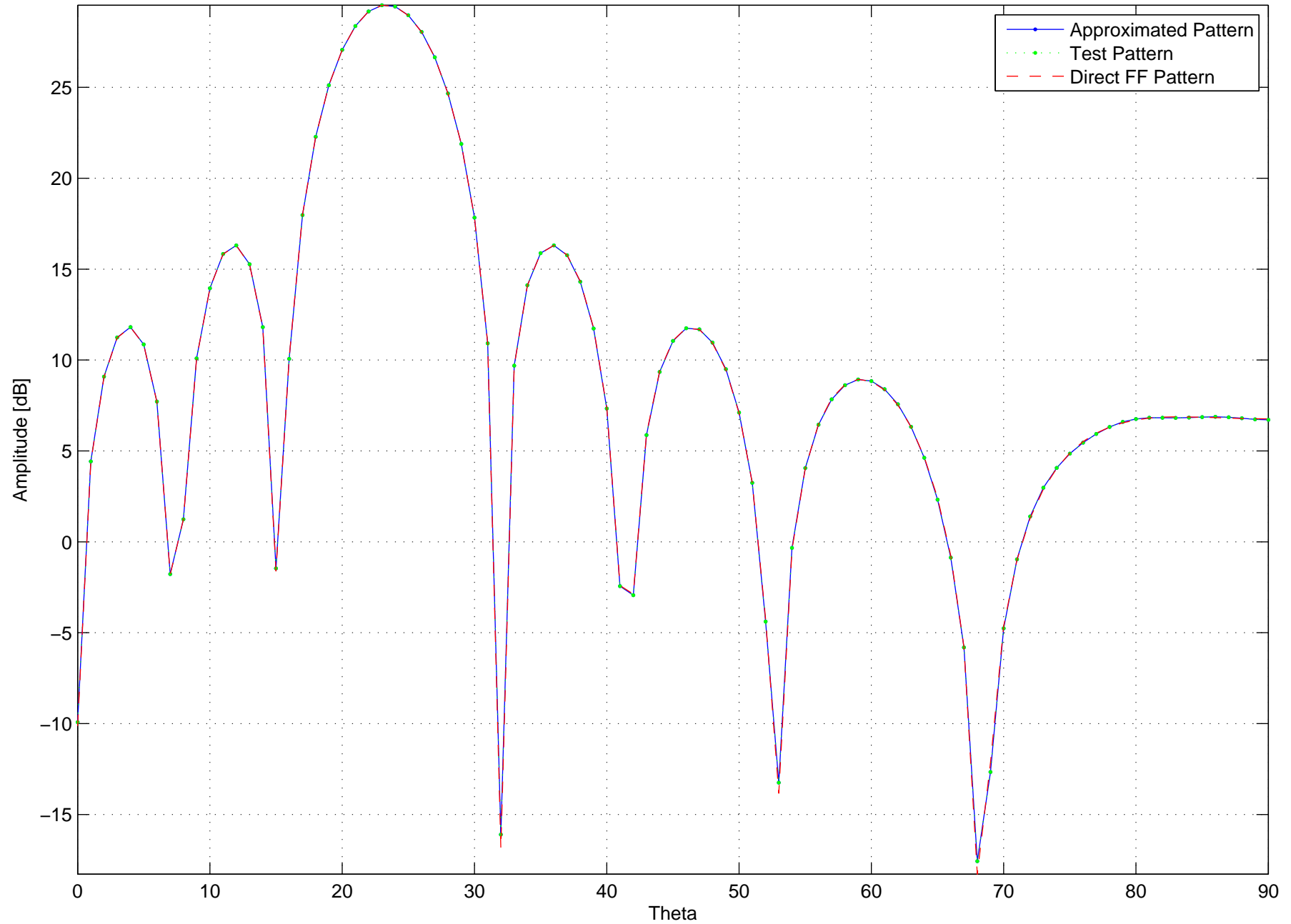
Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 0, Nbr of Vectors : 33
Nbr of point sources : 30

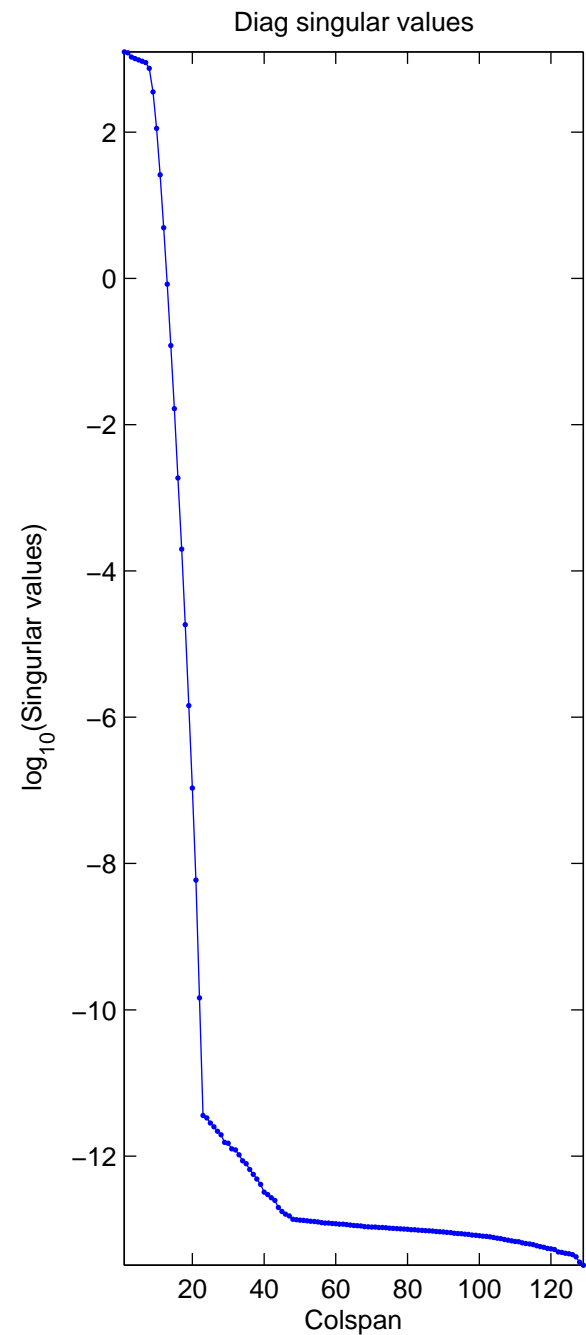
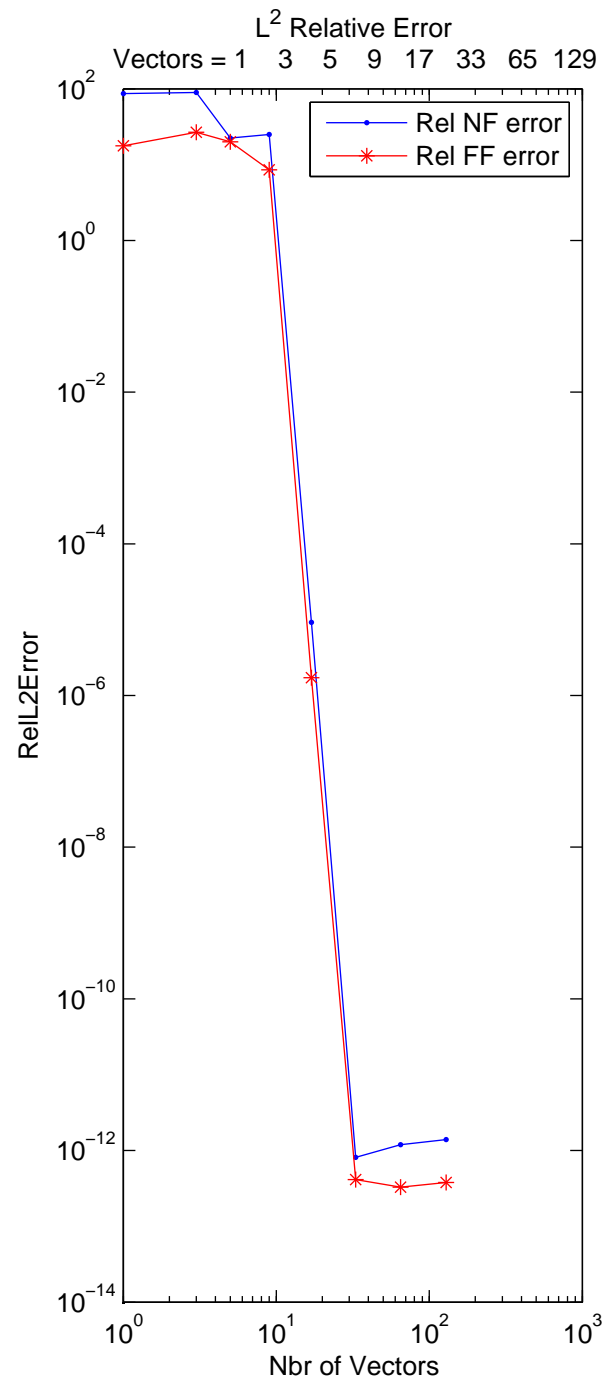
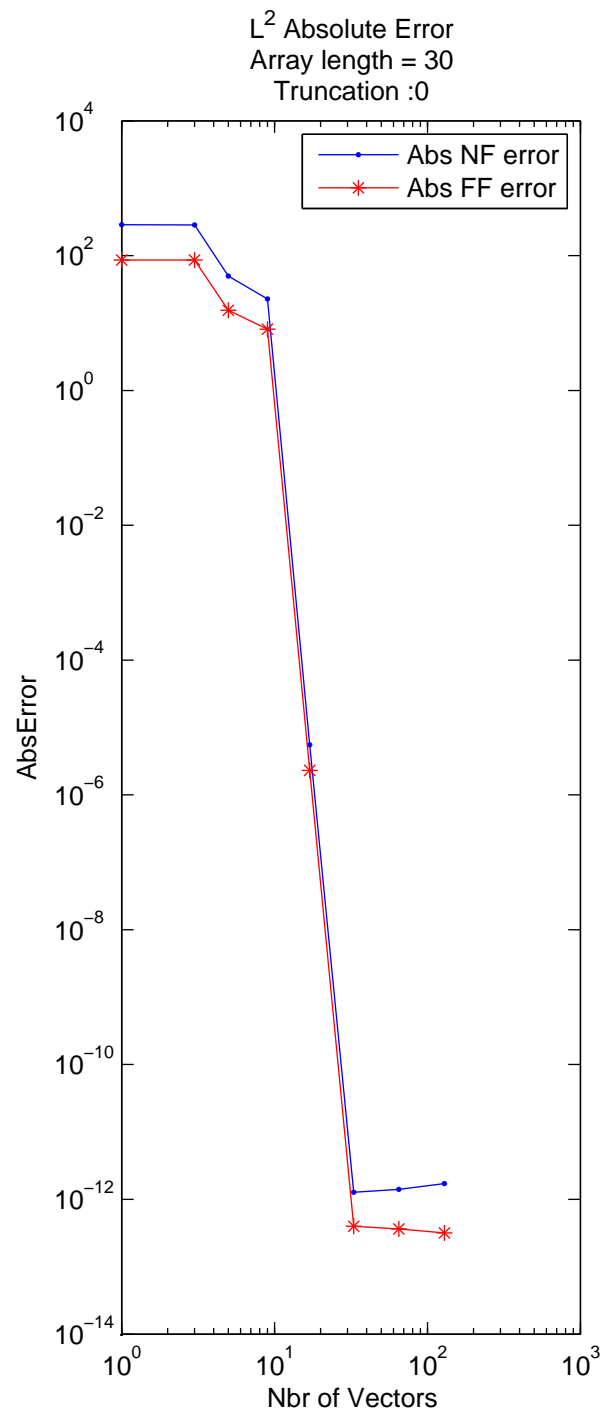


Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 0, Nbr of Vectors : 65
Nbr of point sources : 30

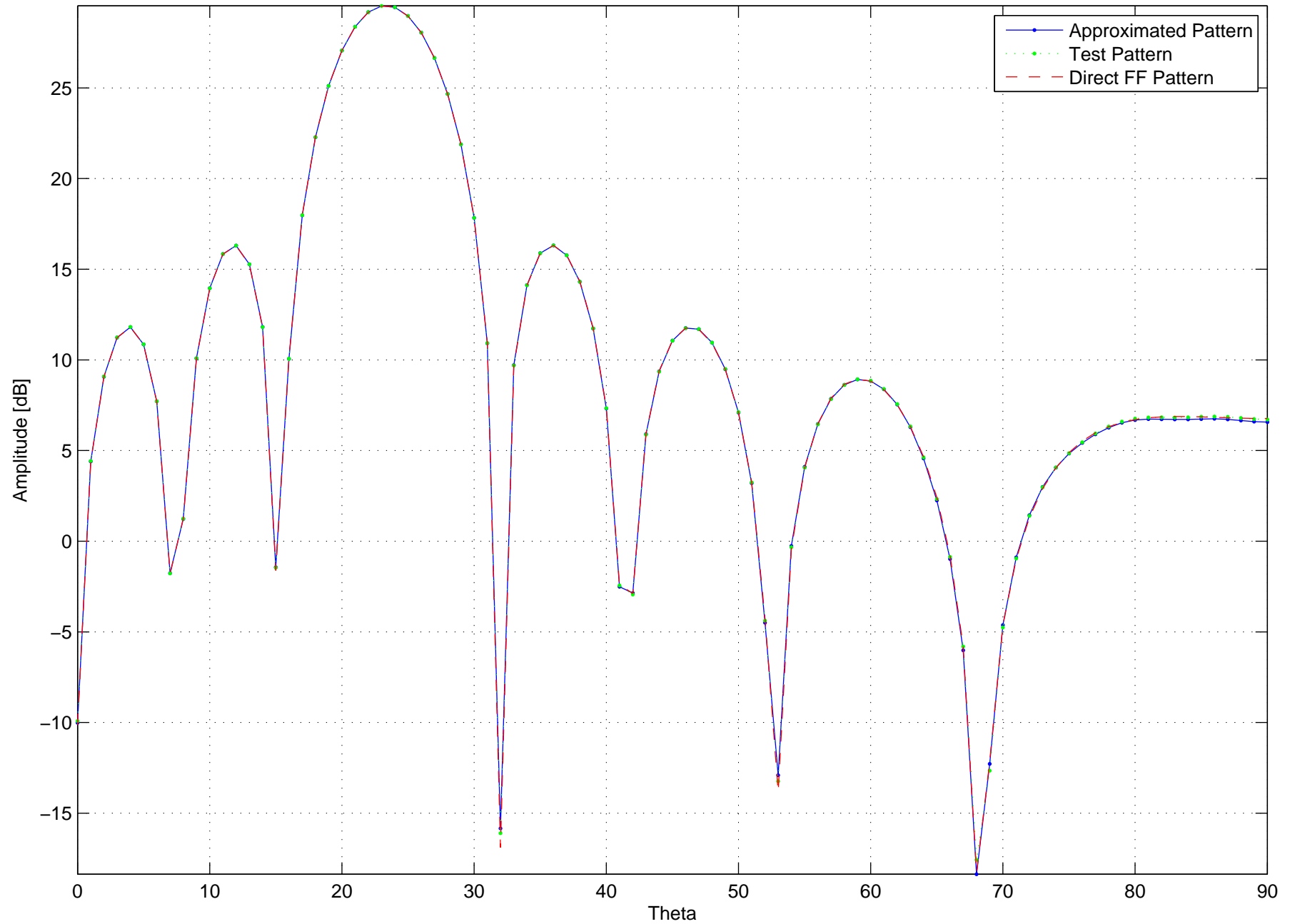


Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 0, Nbr of Vectors : 129
Nbr of point sources : 30

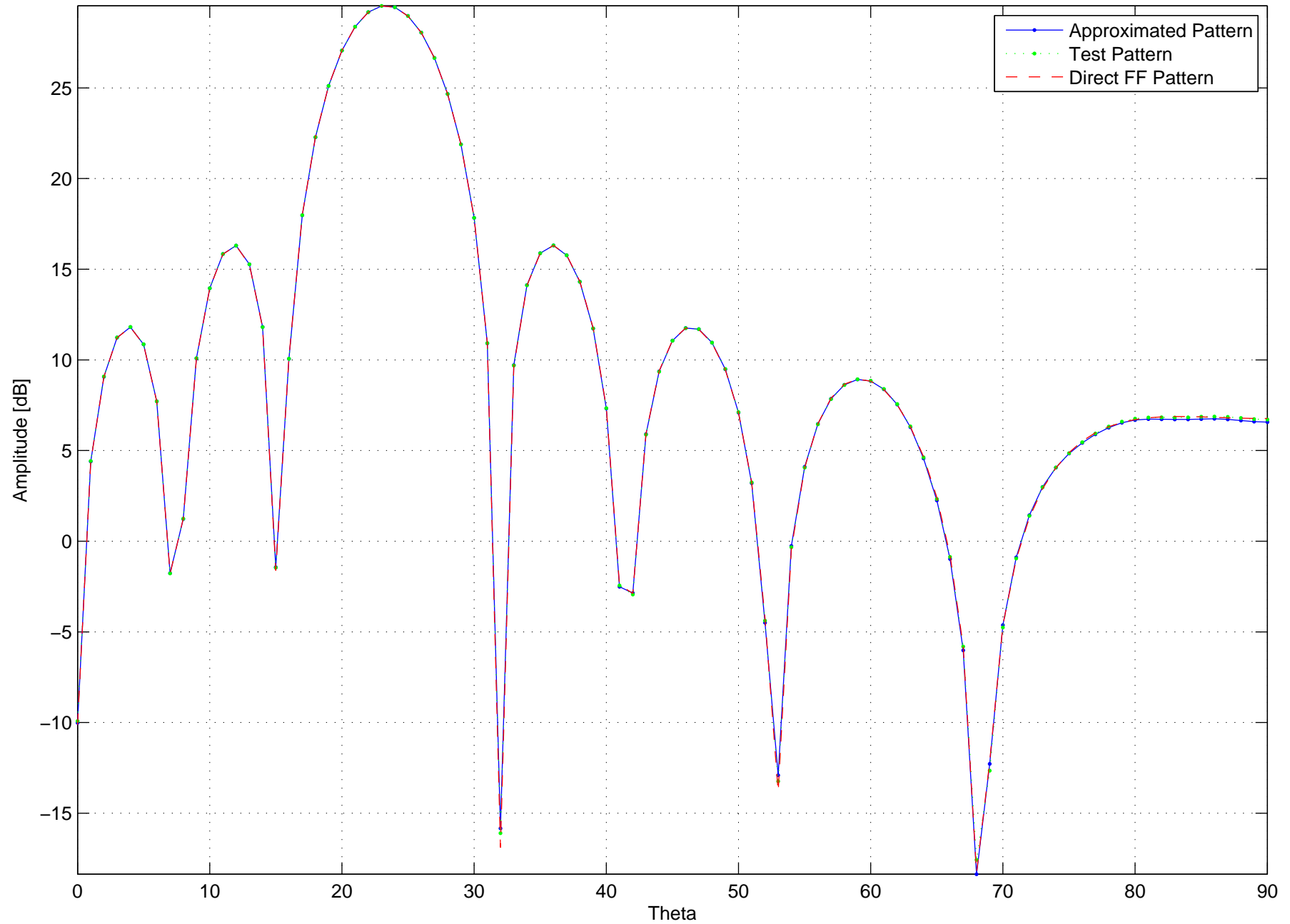




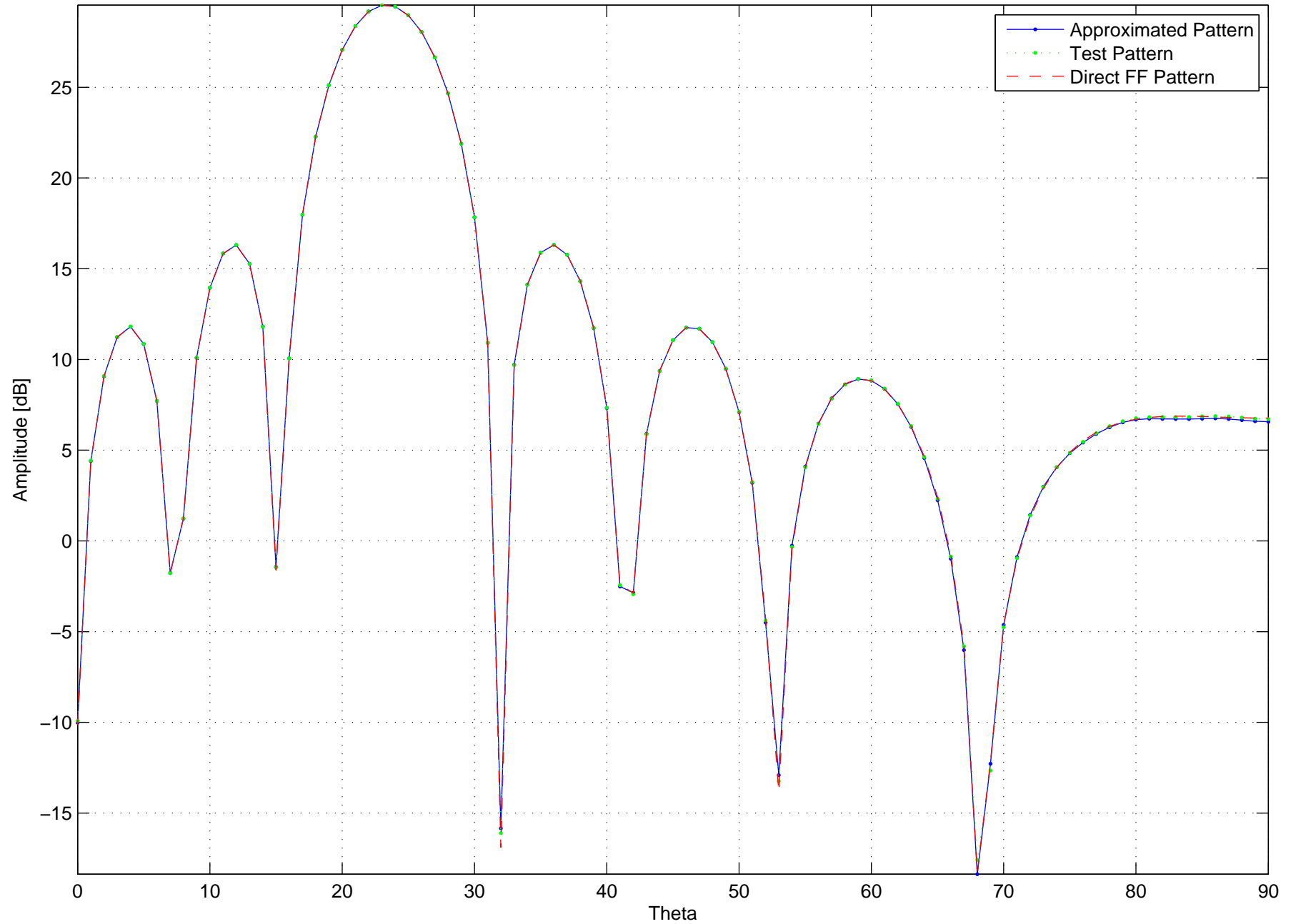
Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 11, Nbr of Vectors : 33
Nbr of point sources : 30

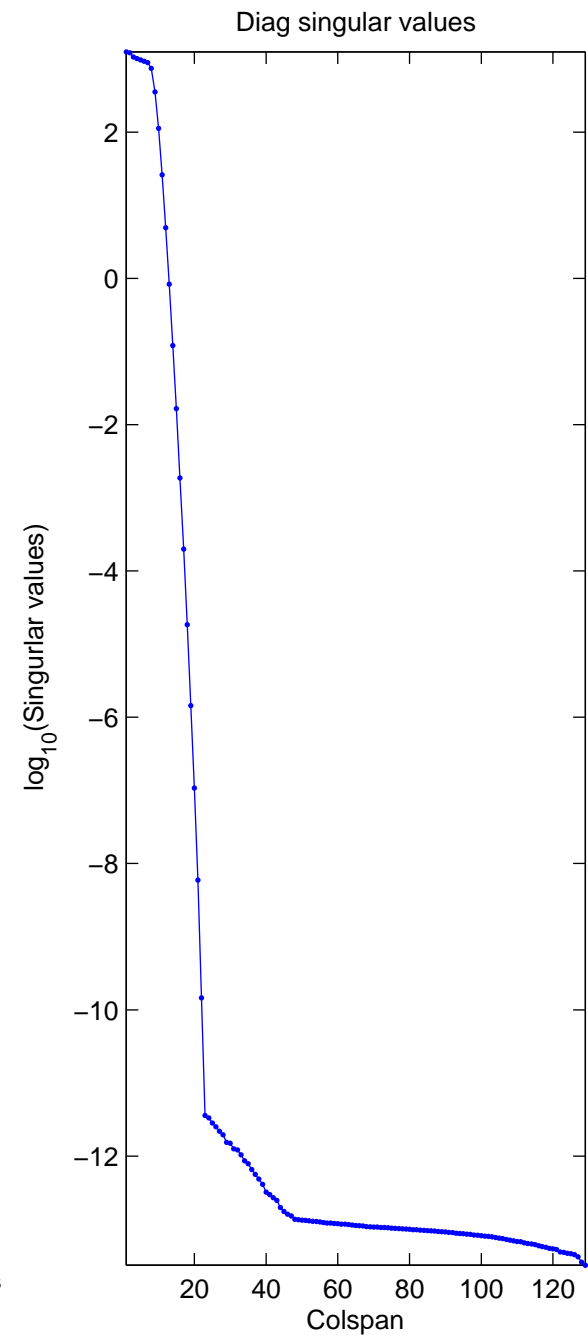
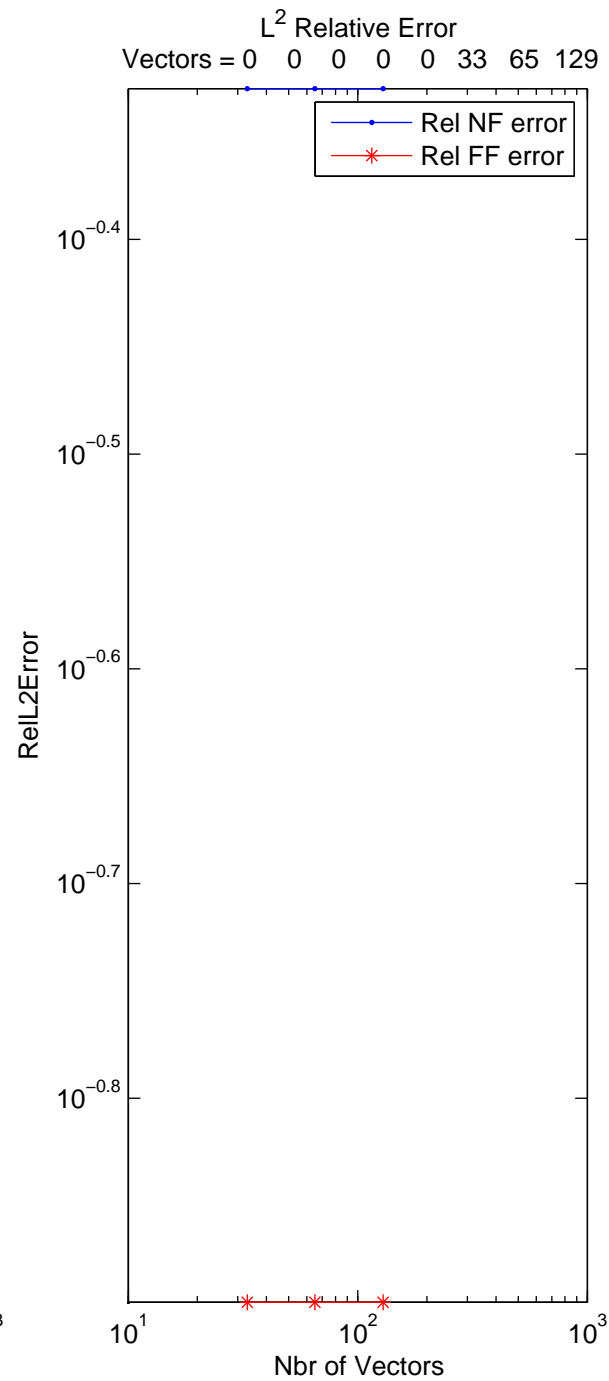
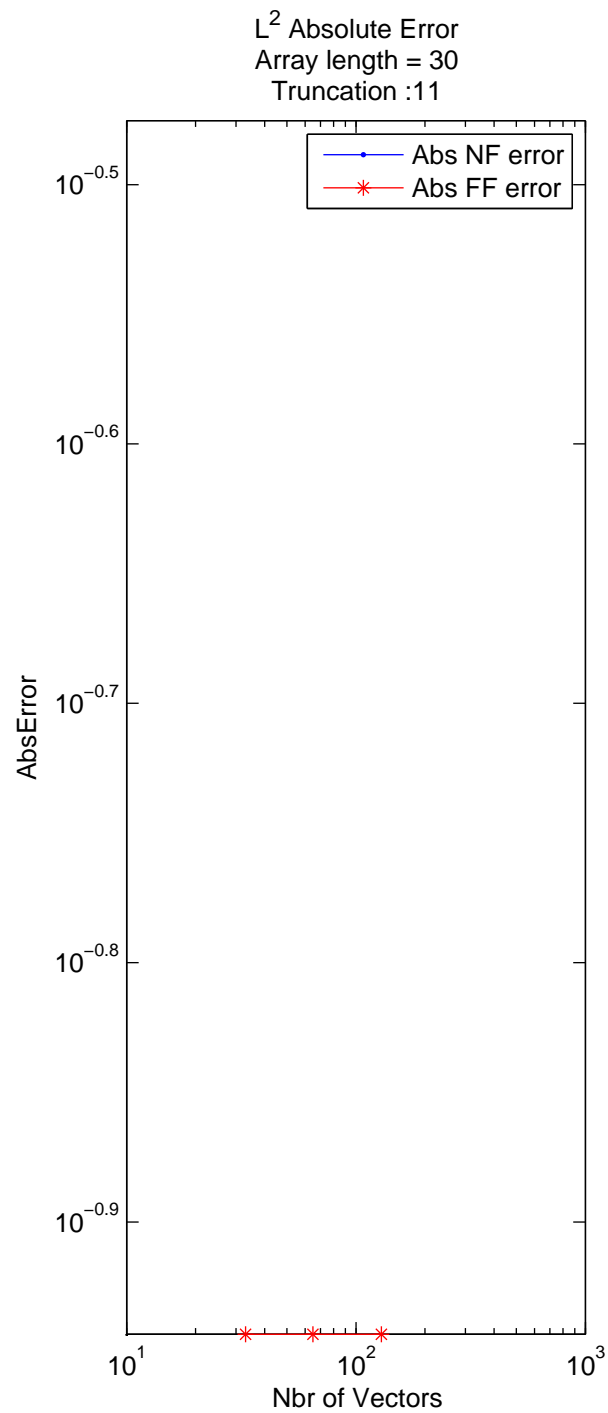


Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 11, Nbr of Vectors : 65
Nbr of point sources : 30

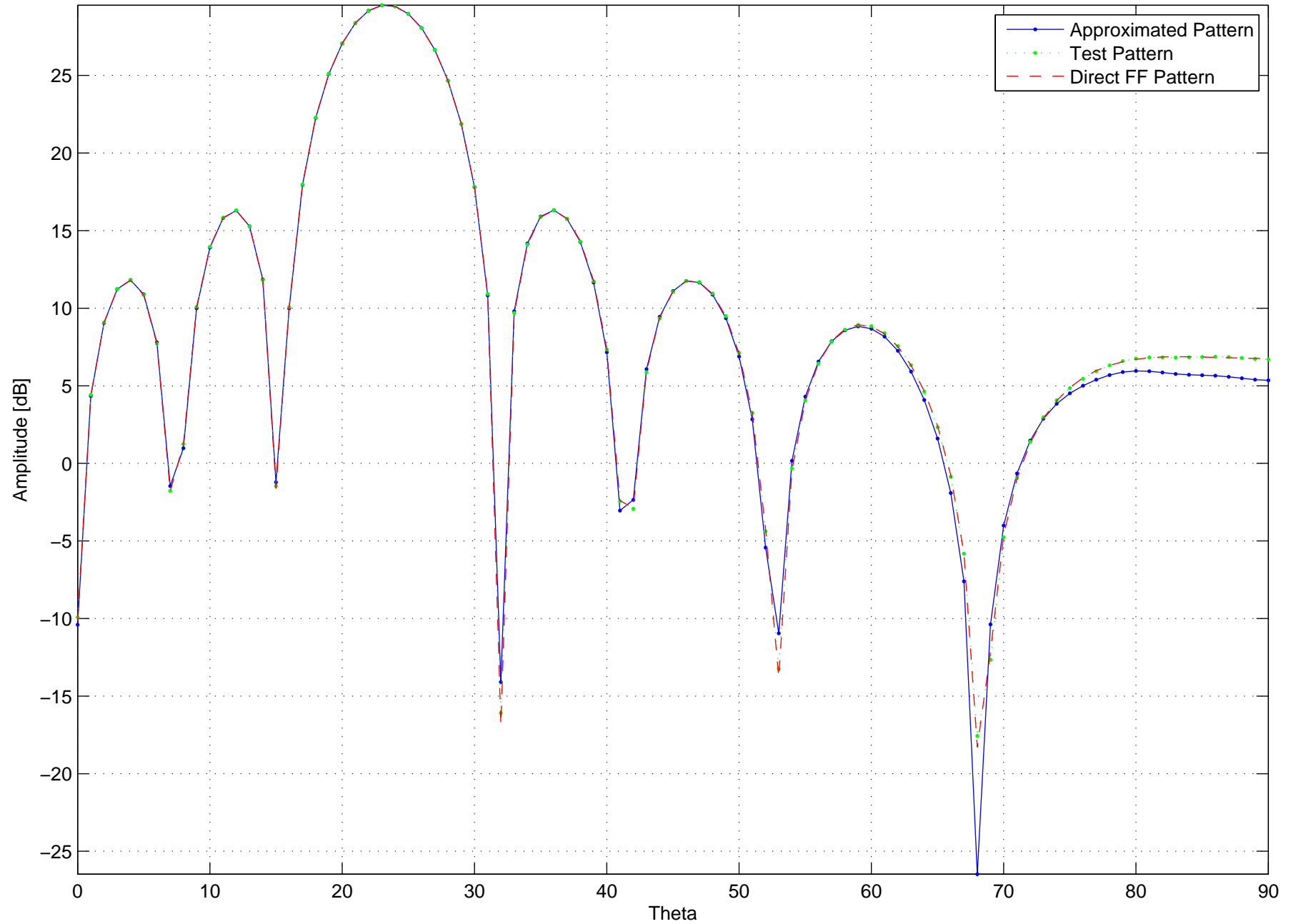


Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 11, Nbr of Vectors : 129
Nbr of point sources : 30

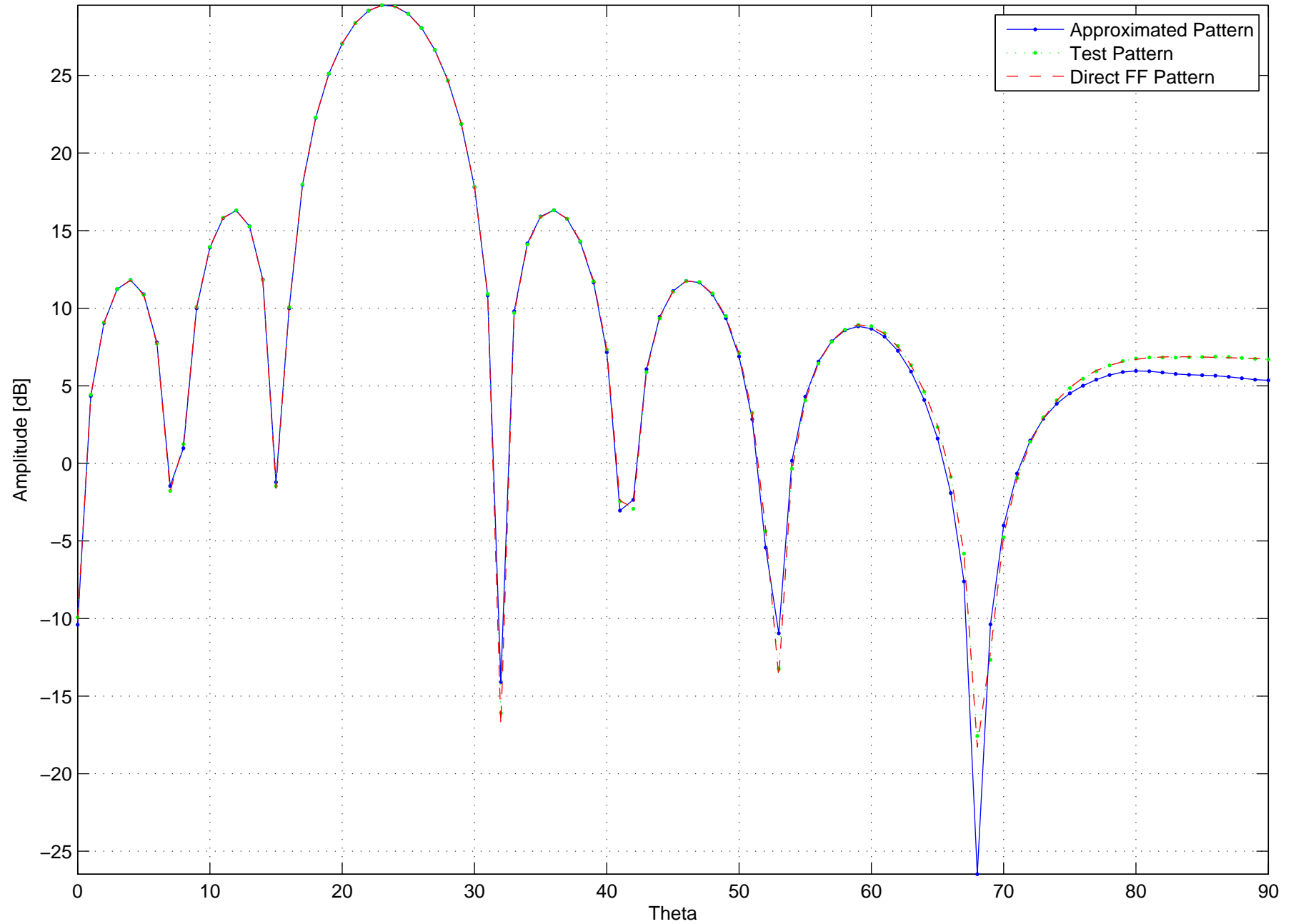




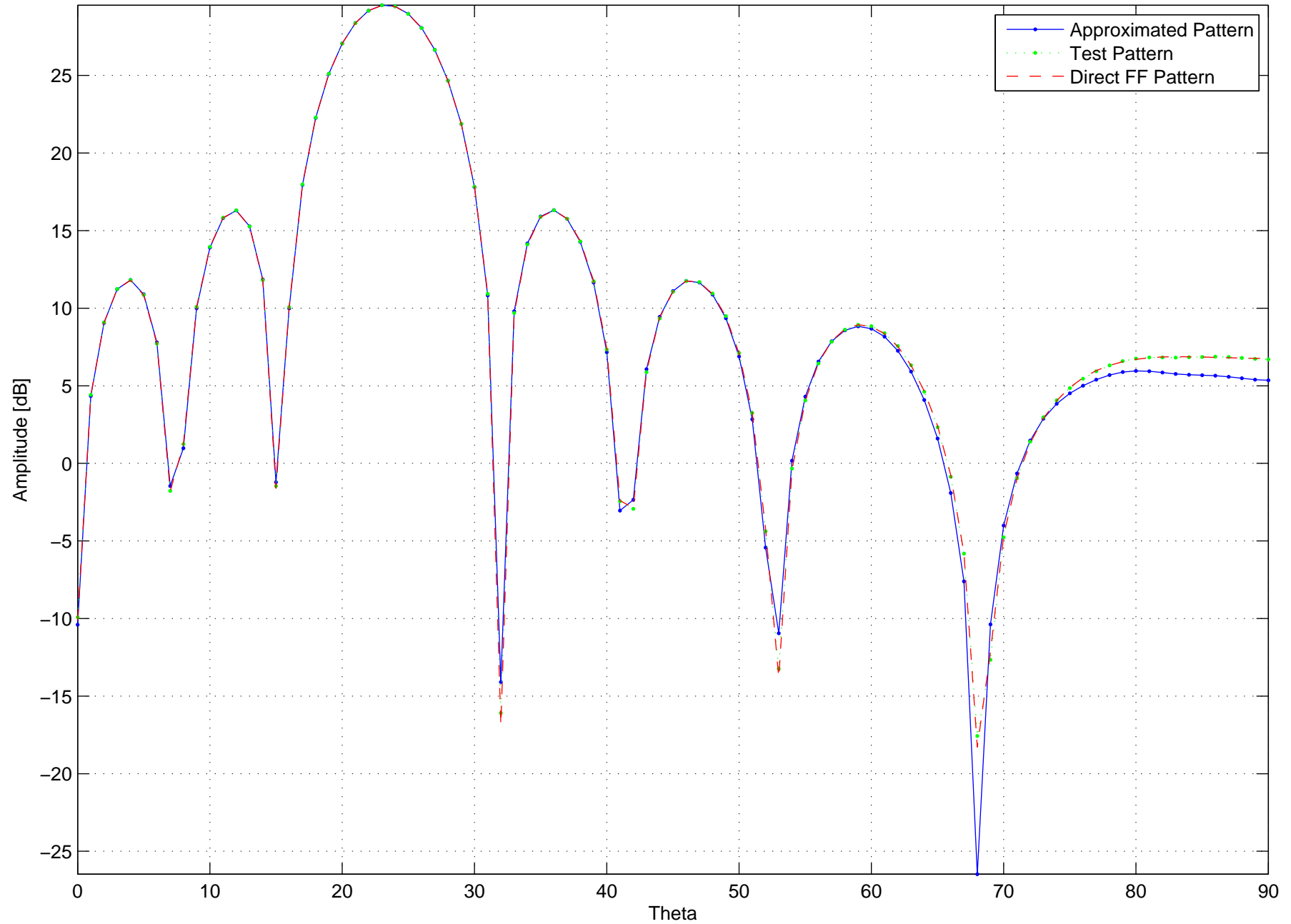
Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 10, Nbr of Vectors : 33
Nbr of point sources : 30

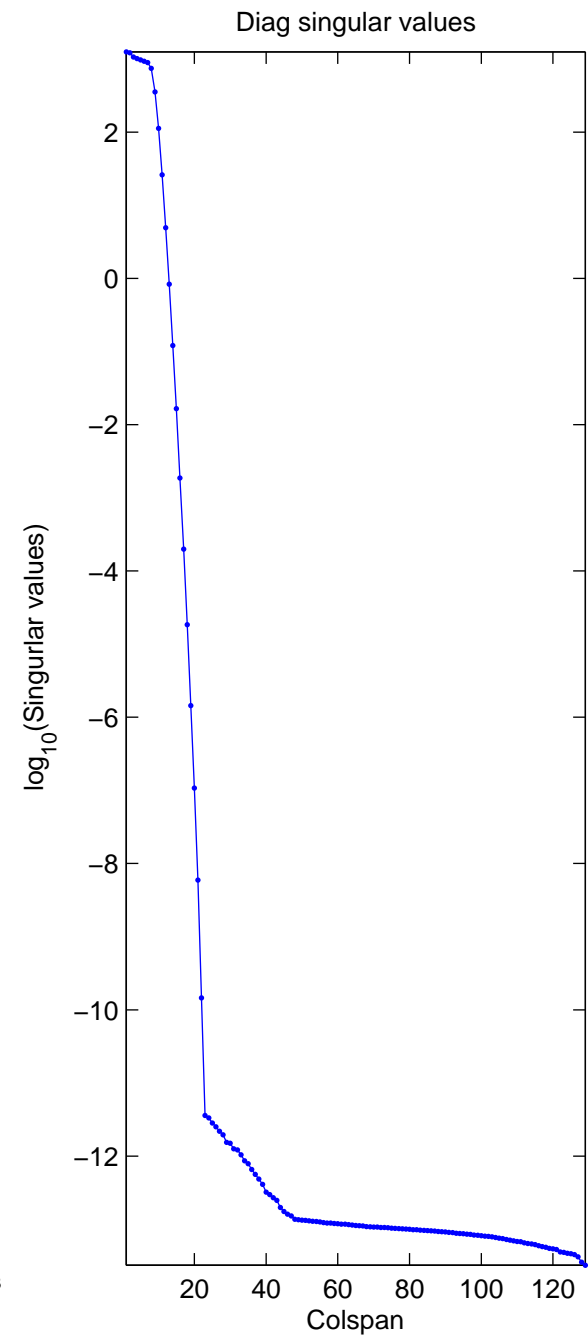
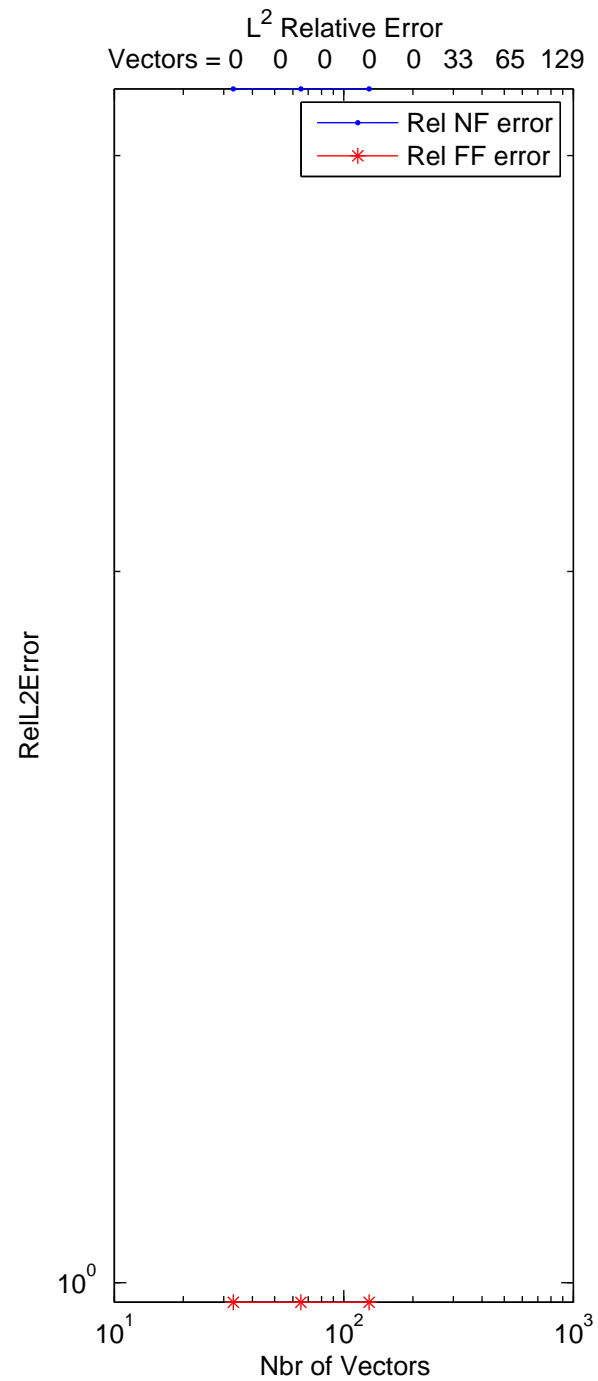
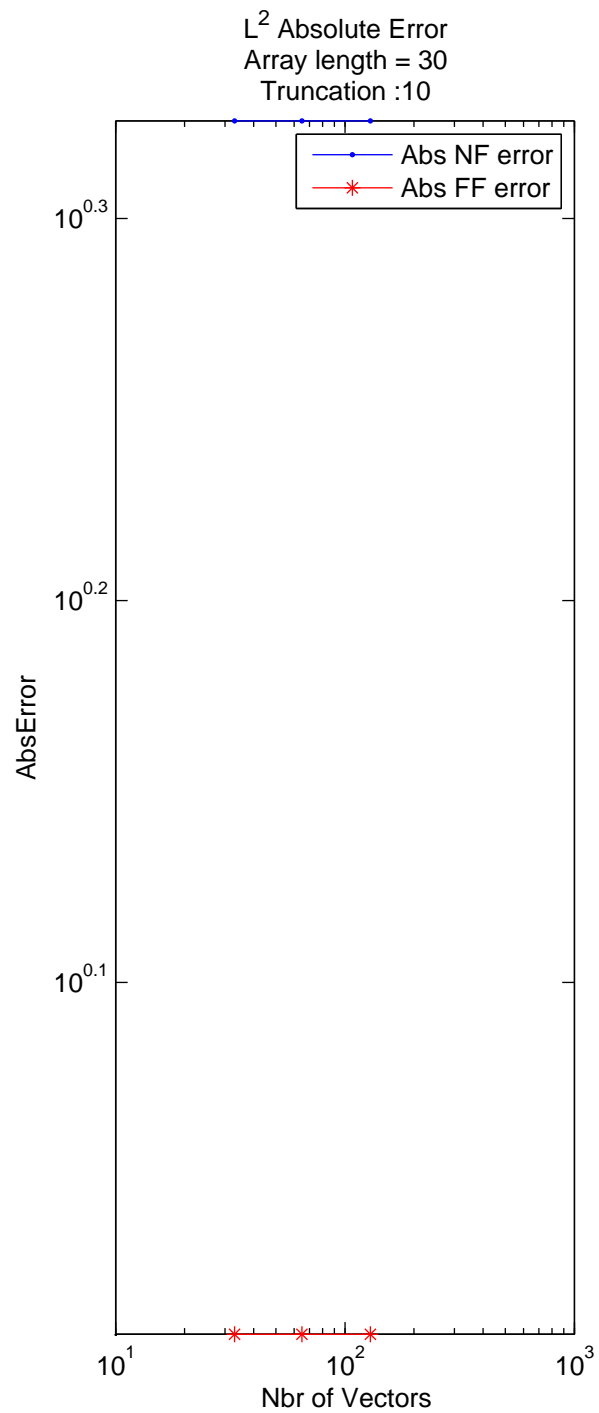


Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 10, Nbr of Vectors : 65
Nbr of point sources : 30

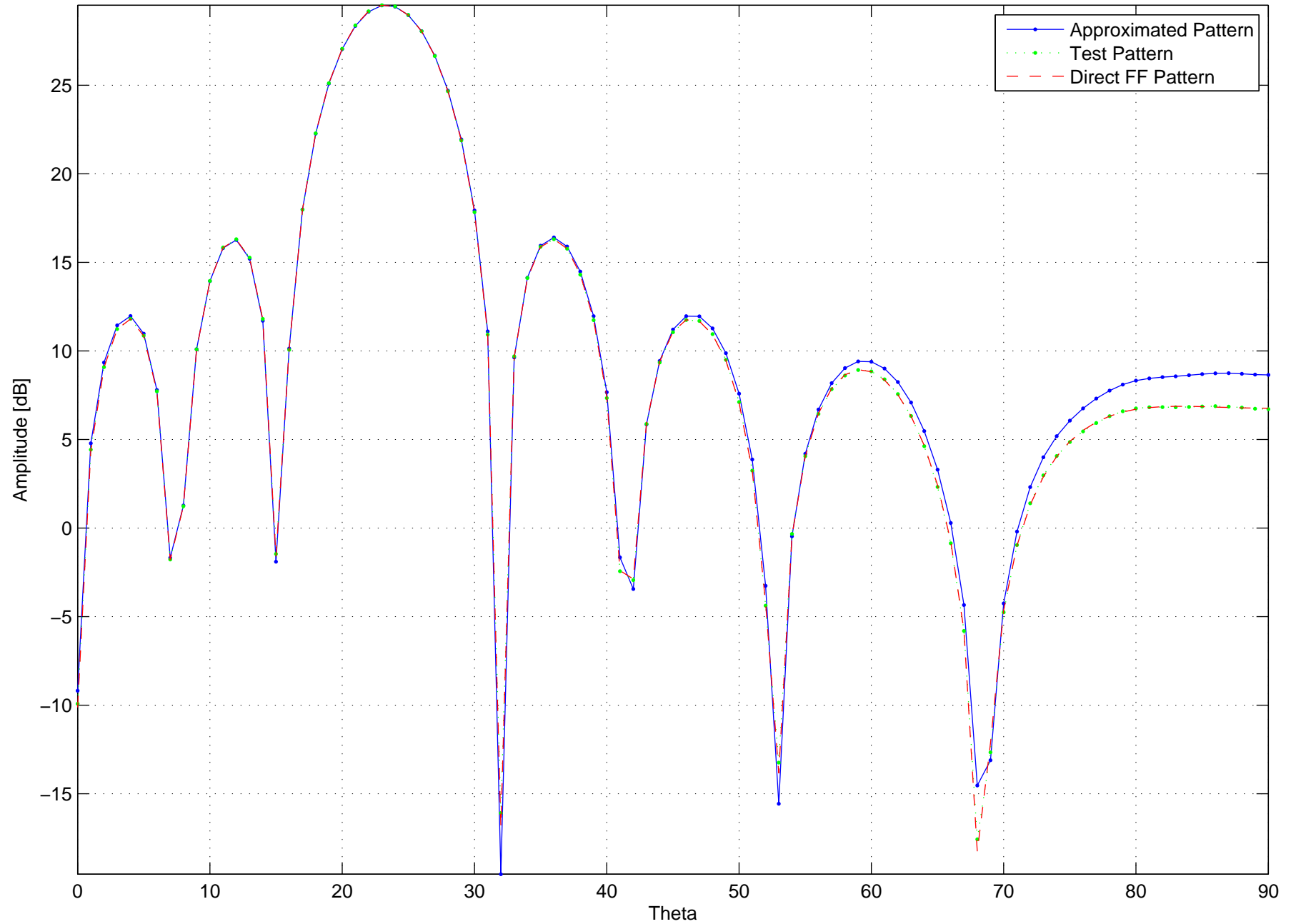


Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 10, Nbr of Vectors : 129
Nbr of point sources : 30

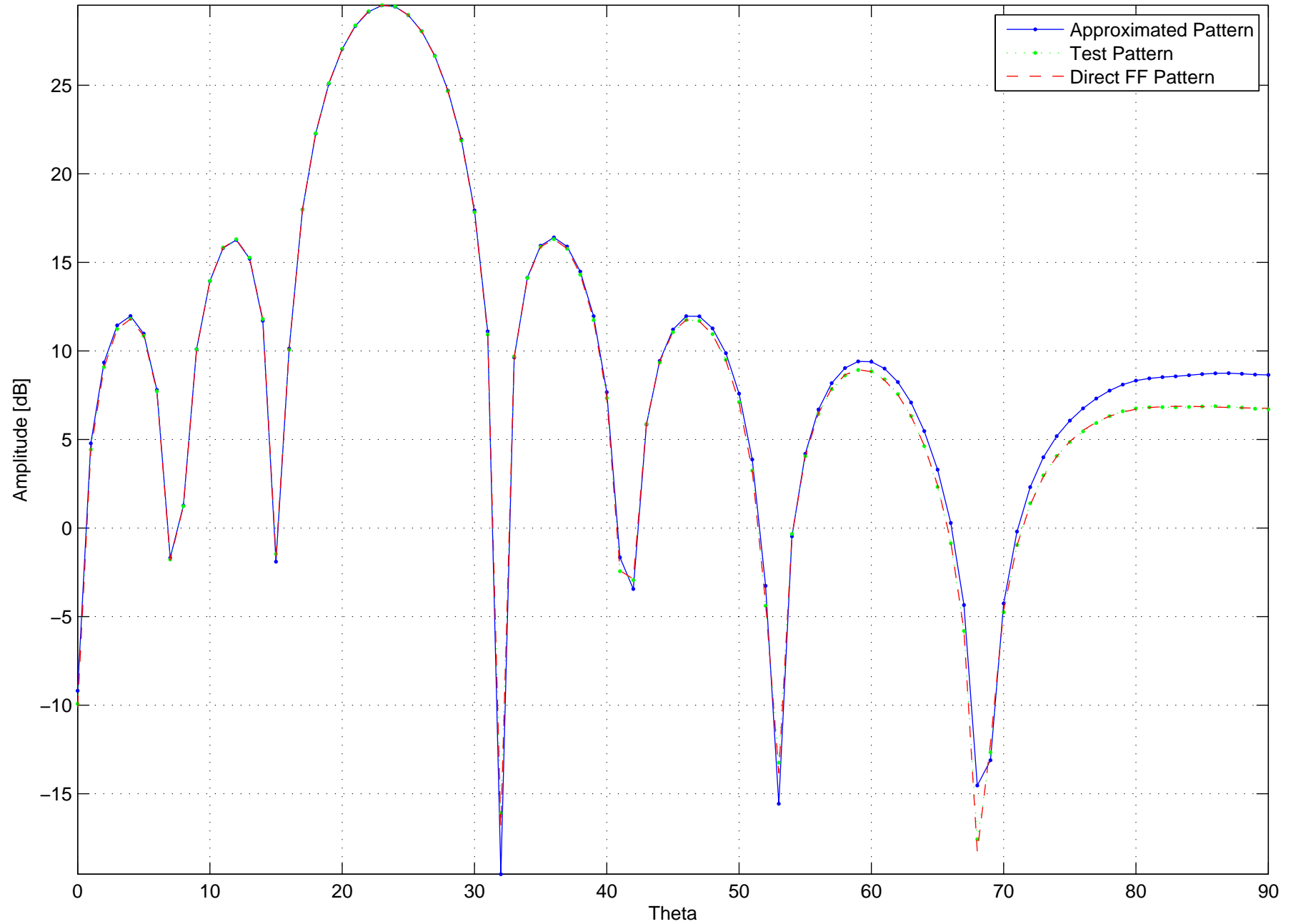




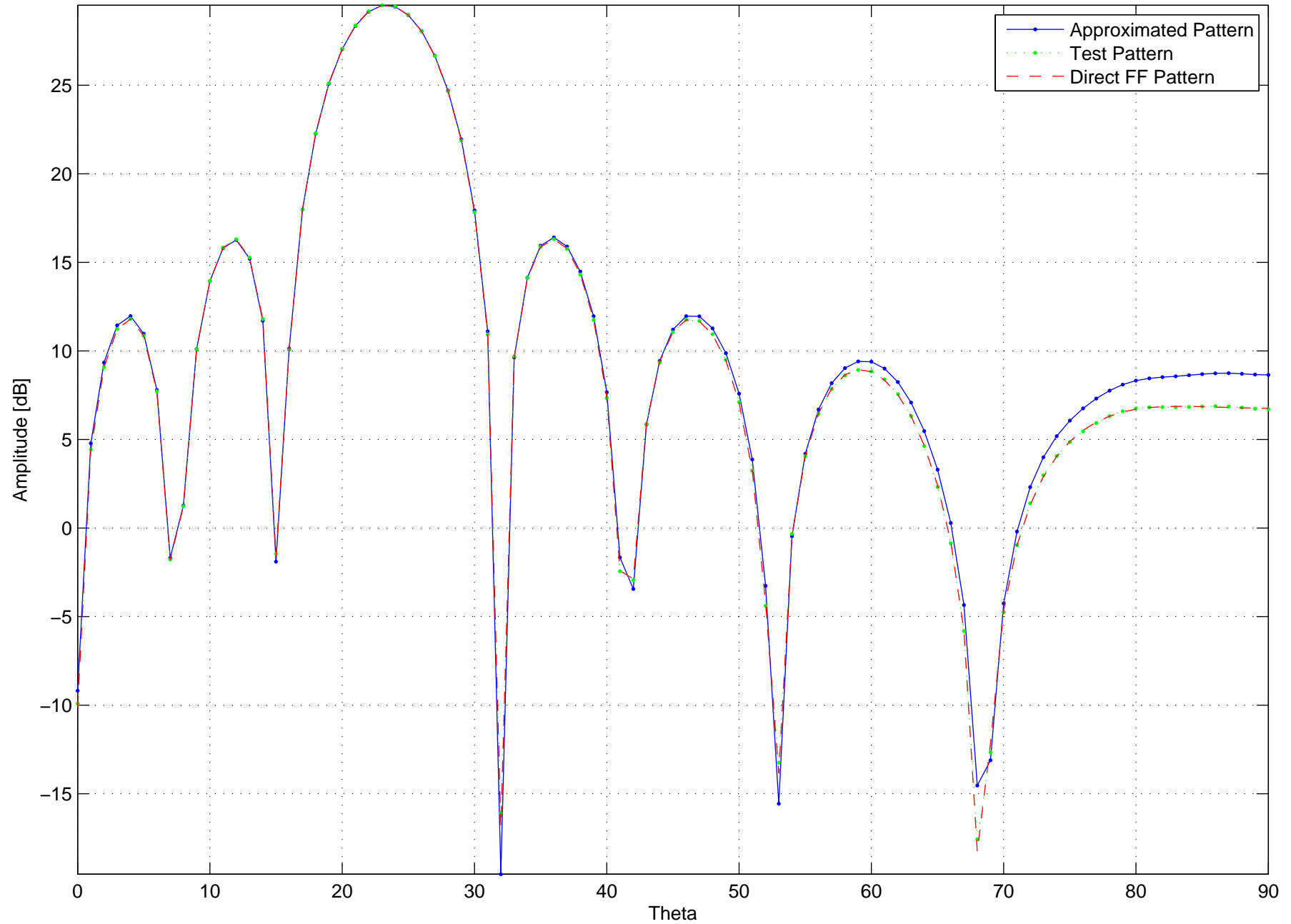
Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 9, Nbr of Vectors : 33
Nbr of point sources : 30

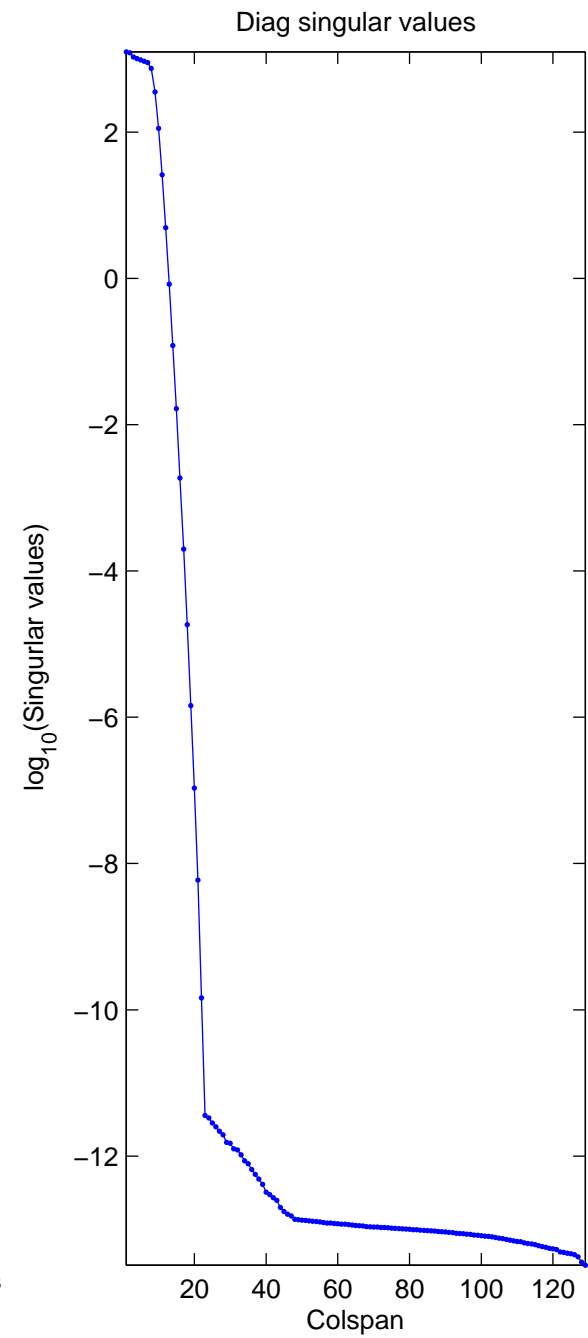
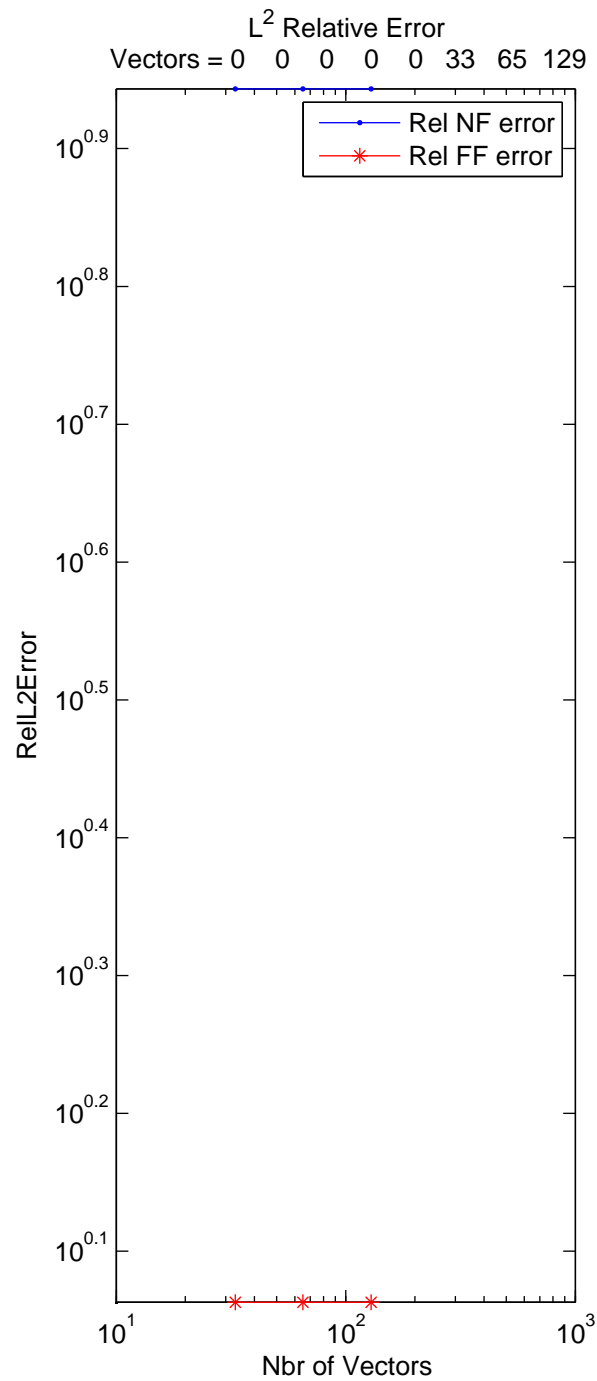
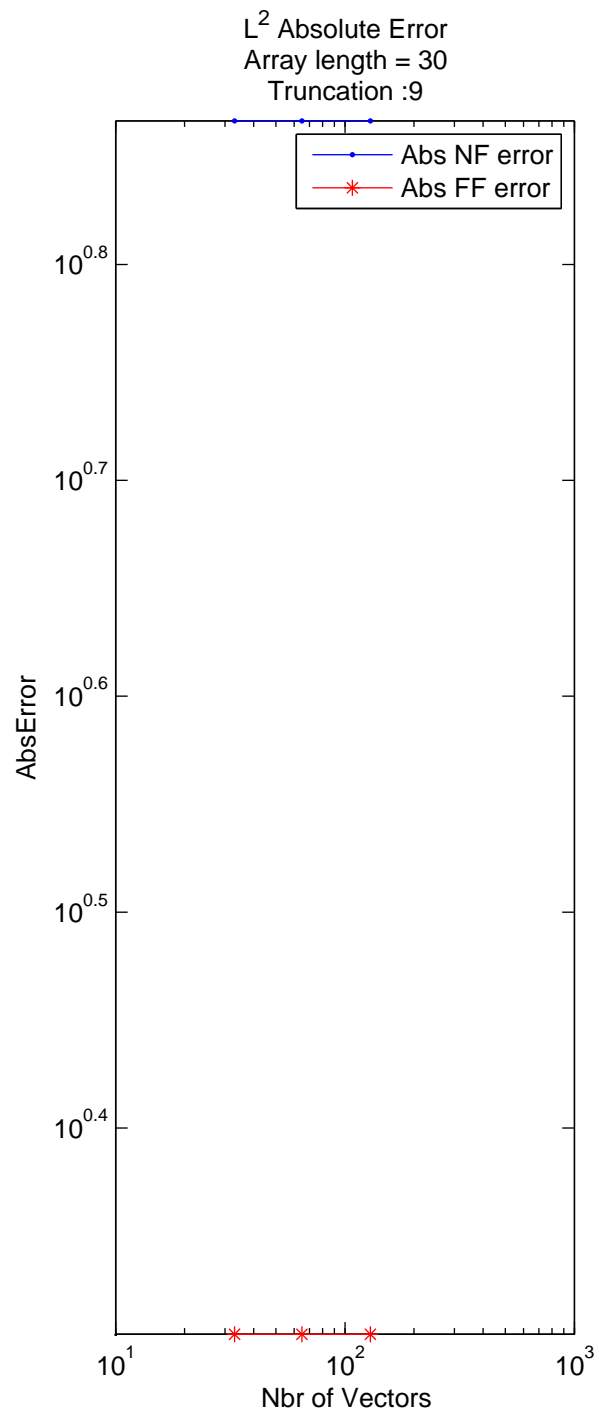


Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 9, Nbr of Vectors : 65
Nbr of point sources : 30

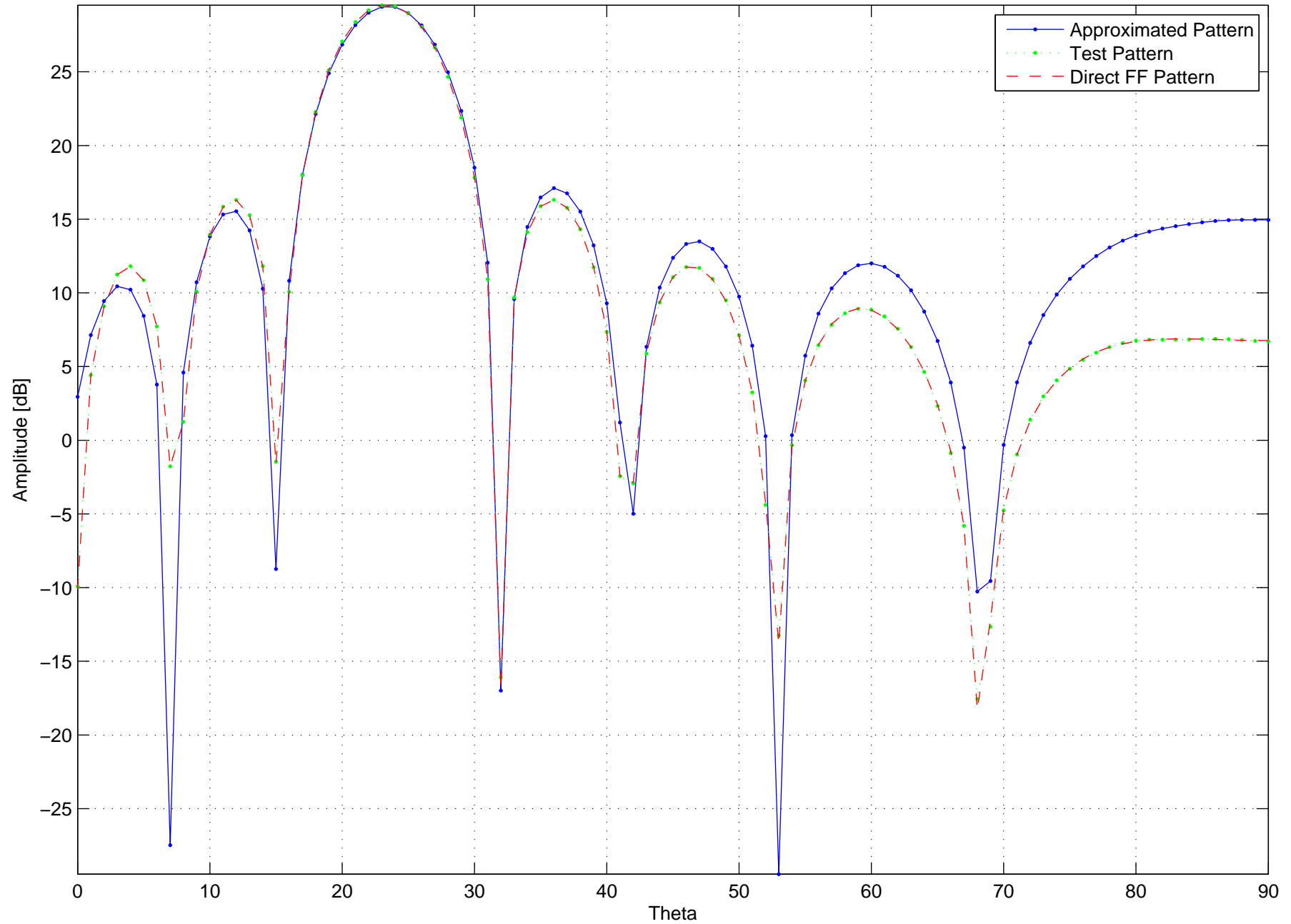


Patterns – $\Phi = 0^\circ$. Steering angle : 23.3251°
Truncation : 9, Nbr of Vectors : 129
Nbr of point sources : 30

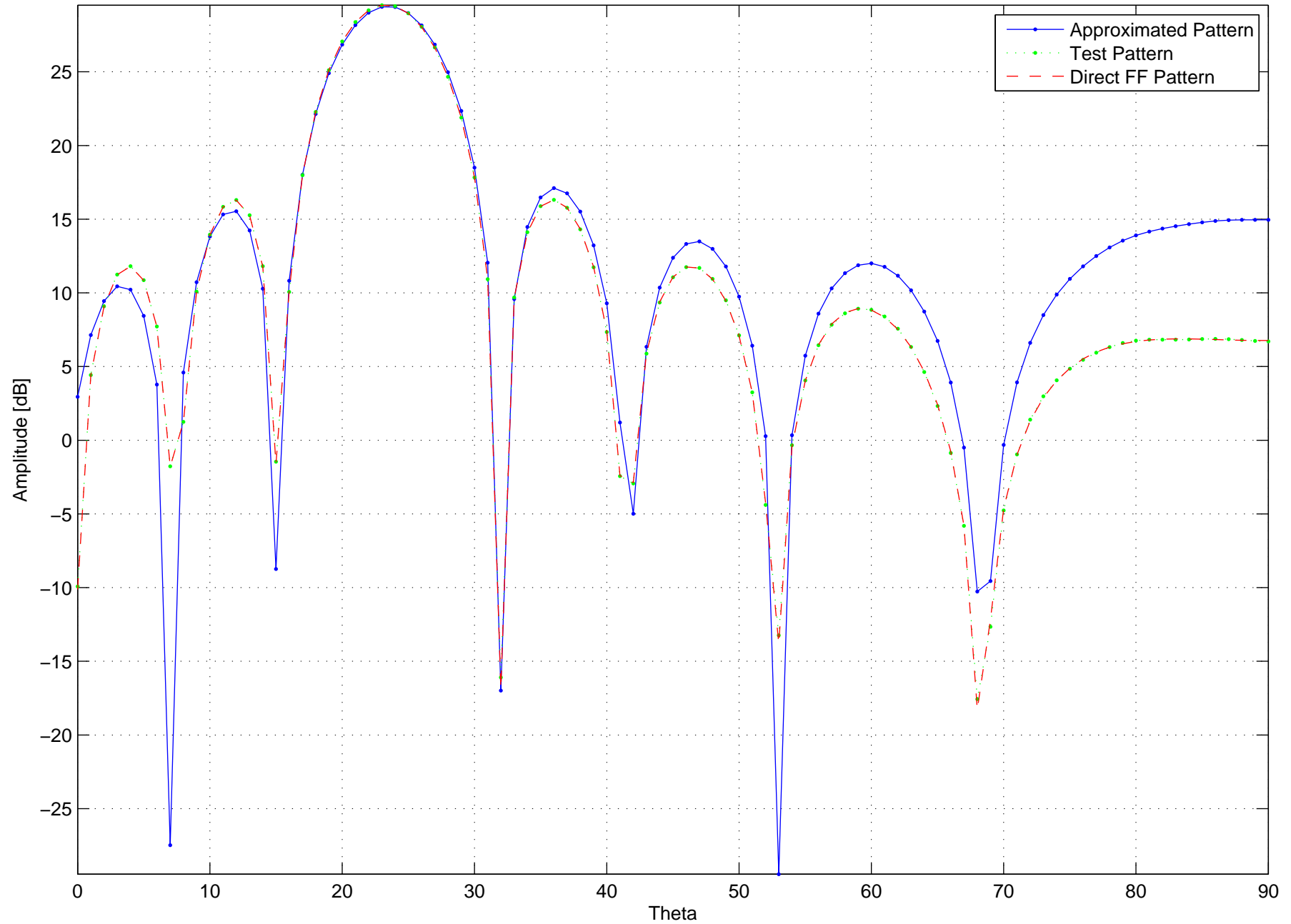




Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 8, Nbr of Vectors : 33
Nbr of point sources : 30



Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 8, Nbr of Vectors : 65
Nbr of point sources : 30



Patterns – Phi = 0°. Steering angle : 23.3251°
Truncation : 8, Nbr of Vectors : 129
Nbr of point sources : 30

