

# AEC Project: Quadrature Down Converter

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**Abstract**—In this project, we are making a Quadrature Down Converter (QDC) that is commonly used in modern day wireless receivers. The main purpose of the Quadrature down converter is to do frequency down conversion of the signal (which is already up converted and also have some noise with it). We first simulated the circuit using LTSpice software, and then implemented the circuit on a breadboard.

## I. INTRODUCTION(UTILITY OF THE CIRCUIT)

Direct-conversion receivers offer advantages like lower current drain and simpler image-rejection tasks, making them suitable for digital cellular telephones and miniature radio messaging systems. This process enables efficient signal processing, spectral efficiency, and easier modulation/demodulation, crucial for modern wireless communication systems. The I and Q components are orthogonal to each other, meaning they are independent and do not interfere with each other. This orthogonality facilitates the transmission of more data within the same bandwidth, effectively doubling the achievable data rate. Moreover, by separating the signal into these orthogonal components, it becomes easier to distinguish and decode multiple signals in complex communication environments.

## II. QUADRATURE OSCILLATOR DESIGN

### A. Description of the circuit

A quadrature oscillator circuit is a type of electronic oscillator that generates two output signals that are 90 degrees out of phase with each other. This phase relationship is often referred to as being "in quadrature."

This oscillator consists of two Op-amps, producing two sinusoidal signals at 90 degrees phase difference at their outputs respectively. The circuit oscillates at a particular frequency, which is picked up from the thermal noise in the circuit.

It consists of two integrator blocks, positive and negative integrator respectively. The sine wave generated at one input is integrated into a cosine wave and this cosine wave is again integrated into a sine wave.

There are resistors and capacitors across the feedback path.

### B. Topology and Calculations

The circuit topology consists of two integrator blocks, connected together.

Let us label the Op-amps as 1 and 2 respectively, and call the outputs at their output ports to be  $V_{os}$  and  $V_{oc}$  respectively, denoting sine and cosine waves.

$$V_{+2} = \frac{V_{os}}{1 + R_2 C_2 S} \quad (1)$$

$$V_{oc} = V_{+2} \cdot (1 + \frac{1}{R_3 C_3 S}) \quad (2)$$

$$V_{os} = \frac{-V_{oc}}{R_1 S C_1} \quad (3)$$

For stable oscillations the closed loop gain should be unity.

$$\left(\frac{1}{1 + R_2 C_2 S}\right) \cdot \left(\frac{R_3 C_3 S + 1}{R_3 C_3 S}\right) \cdot \left(\frac{-1}{R_1 C_1 S}\right) = 1 \quad (4)$$

Now for frequency domain  $S = j\omega$   
If we choose  $R_1 C_1 = R_2 C_2 = R_3 C_3 = RC$ .

$$\frac{-1}{(RCj\omega)^2} = 1 \quad (5)$$

$$\omega = \frac{1}{RC} \quad (6)$$

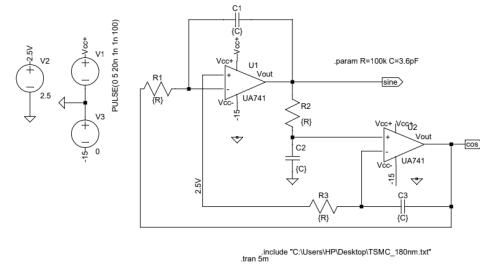


Fig. 1. Quadrature Oscillator

For our goal of 100 kHz frequency signal, we choose  $R$  and  $C$  as 102.75 kΩ and 6.5 pF respectively.

But, we observe less frequency than the desired at the output due to op-amp imperfection. To fix this issue, from calculated values of  $R$  and  $C$ , we can decrease the resistance keeping capacitance constant till we observe the desired output frequency.

### C. LT Spice Simulations

The following is the time domain output of the quadrature oscillator.

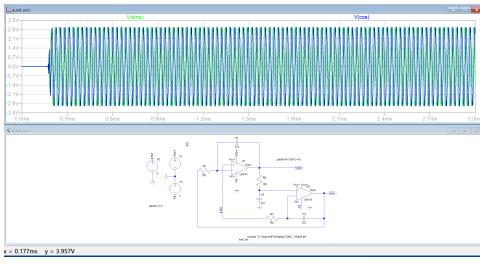


Fig. 2. Quadrature Oscillator output

It generated two sinusoidal waves at a phase shift of 90 degrees.

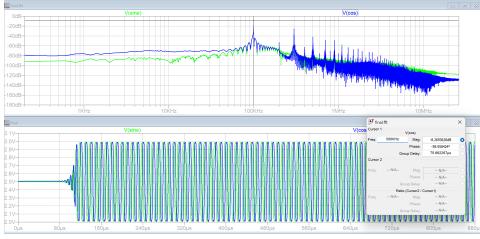


Fig. 3. Quadrature Oscillator output

### III. SWITCH(MIXER) DESIGN

#### A. Description

A simple MOSFET can be used as a switch (mixer), where the oscillator signal is applied to the gate of the device, input is applied at the source and the intermediate frequency output is taken at the drain end. The basic idea behind the circuit is to take benefit of the switching action on the transistor.

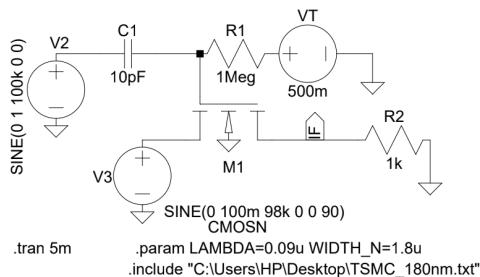


Fig. 4. Quadrature Oscillator

#### B. Topology and calculations

We have used the NMOS in the following configuration. A coupling capacitor is used to allow only ac signals to pass through. We have used a large value of  $R_{bias} = 1M\Omega$  to stop any leakage current that might occur. This  $R_{bias}$  and coupling capacitor form a high pass filter, so we have chosen the value of capacitor such that our frequency of interest is above the cutoff. We used Capacitor value to be 10 pF. The coupling capacitor is used so that the DC noise from the oscillator is blocked. The bias voltage is taken approximately equal to the threshold value, which helps in

achieving mixing operation. The  $V_t$  value was taken from the assignment done earlier. The design parameters of the mosfet are LAMBDA=0.09u and WIDTH\_N= 1.8u

#### C. Working of the mixer

The DC bias of the mosfet is  $V_t$ . The gate voltage can be considered as a super-imposition of the DC bias and the AC input signal.

$$V_{gs} = V_t + V_{osc} \quad (7)$$

For mosfet to turn on  $V_{gs} \geq V_t$  Thus we can say that Mosfet is turned on when:

$$V_{osc} \geq 0 \quad (8)$$

When the mosfet is on ( $V_{osc} \geq 0$ , positive half cycle of the oscillator input) it acts like a switch , and the signal at source terminal appears at the drain terminal, which is taken at the output.

$$V_d = \frac{V_s R_l}{R_l + R_{on}} \quad (9)$$

$$V_d = \frac{V_s}{1 + \frac{1}{k(V_{gs} - V_{th})R_l}} \quad (10)$$

$$V_d = \frac{1}{1 + \frac{1}{k(V_{gs} - V_{th})R_l}} \quad (11)$$

Let's call  $kR_l = M$

$$V_{out} = \frac{V_{in}}{1 + \frac{1}{MV_{osc}}} \quad (12)$$

Since  $M \ll 1$

$$V_{out} = V_{in} V_{osc} M$$

When the mosfet is off, ground voltage appears at the output.

Due to high frequency with which the mosfet is turning on and off. The mixing action can be seen as multiplication of  $V_{in}$  with a square wave with frequency as that of  $V_{osc}$  going from 0 to 1.

The square wave essentially contains the frequency components of the Oscillator signal. This switching action is equivalent to multiplication as we get frequency of output as  $(\omega_{osc} - \omega_{in}), (\omega_{osc} + \omega_{in})$  and the multiplication of odd harmonics of  $V_{osc}$ .

Writing equations for the mosfet when on in Linear mode:

#### D. LT Spice Simulations

The following are the output of mixing  $V_{in}$  and  $V_{osc}$  both in time domain and frequency domain.

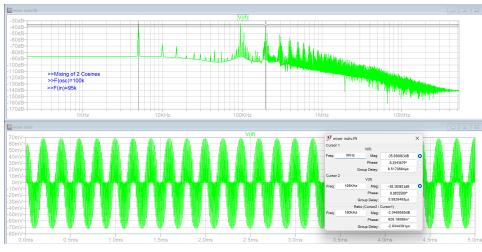


Fig. 5. Cosine waves of 100k and 95k frequency

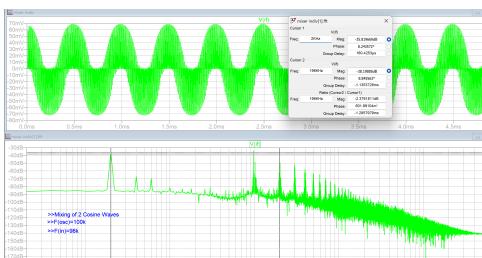


Fig. 6. Cosine waves of 100k and 98k frequency

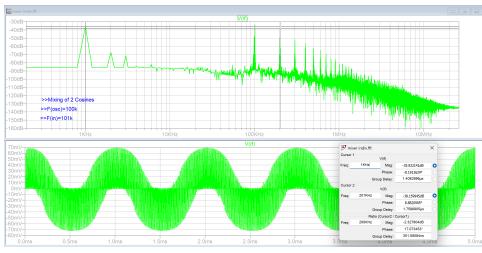


Fig. 7. Cosine waves of 100k and 101k frequency

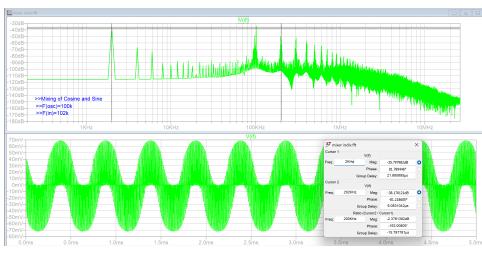


Fig. 8. sine wave of 100k and cosine of 102k frequency

We observed the desired output as expected in both FFT and time domain plots.

#### IV. LOW PASS FILTER DESIGN

##### A. Description

A basic low pass filter can be designed using a resistor and a capacitor with cutoff frequency of  $\frac{1}{2\pi RC}$

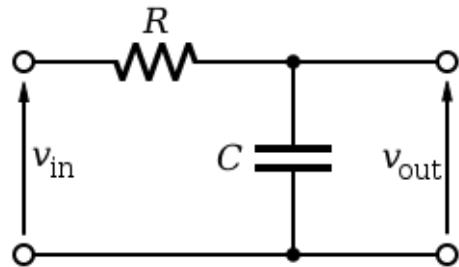


Fig. 9. basic low pass filter

##### B. Topology and Calculations

The circuit consists of a resistor connected in series along with a capacitor. The input is applied at the one of the resistor and output taken at the node between capacitor and resistor.  $V_{out} = V_{in} \cdot \frac{1}{1+RSC}$

For frequency analysis we put  $S = j\omega$ .

If  $|j\omega RC| \ll 1$ , we get  $V_{out} = V_{in}$

For 3dB frequency  $|j\omega RC| = 1$ , at this instant  $V_{out} = \frac{1}{\sqrt{2}} V_{in}$

For cutoff frequency at 2kHz we chose  $R = 7.5 \text{ M}\Omega$  and  $C = 10.61 \text{ pF}$ . We chose a high value of resistance so that it doesn't affect the output of the mixer being a high impedance value, lower values were causing a change in mixer output due to low input impedance.

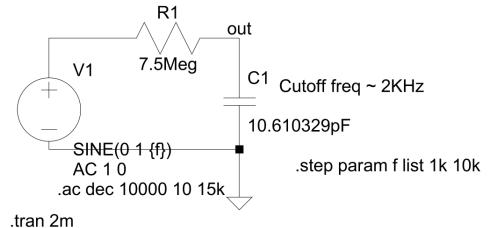


Fig. 10. low pass filter

##### C. LT spice simulations

The following is the bode magnitude plot of the low pass filter.

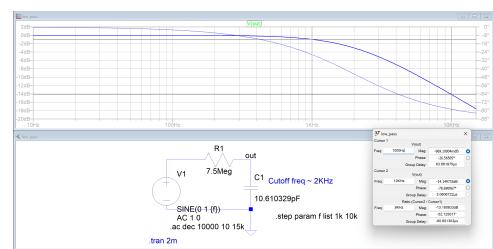


Fig. 11. bode plot of LPF with cutoff frequency at 2Khz

The following is the transient response for input frequencies at 1Khz and 10khz, we can clearly see low pass filter action from it.

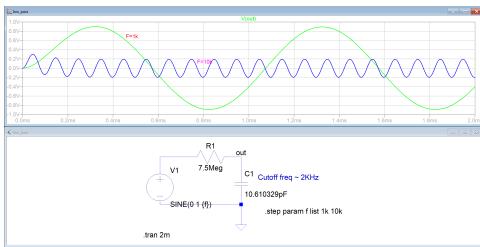


Fig. 12. Transient analysis for two input signals at 1khZ and 10Khz

#### D. Mixer and Filter connected together

We had already made mixer in previous section. We now feed the output of the mixer into the input of the low pass filter.

From our previous knowledge of the mixer we know that the output of it had frequency components at  $(\omega_{osc} - \omega_{in})$  and  $(\omega_{osc} + \omega_{in})$

Now thorough the low pass filter only that frequency will pass which is below the cutoff frequency of the low pass filter, the rest of the frequencies will be blocked. For our frequencies of interest of the input signal and oscillator output the frequency of  $\omega_{osc} - \omega_{in}$  will pass through.

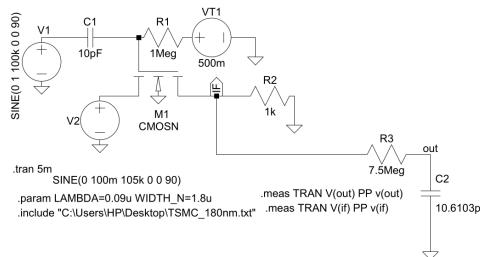


Fig. 13. Mixer connected with low pass filter

#### E. Lt spice simulations

The following are the time and frequency domain response of the circuit

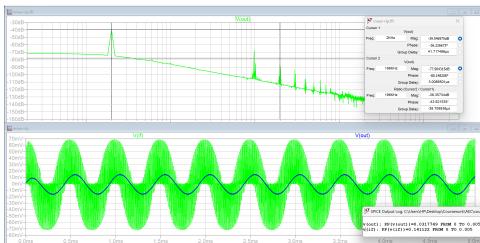


Fig. 14. Cosine waves of 100k and 98k frequency

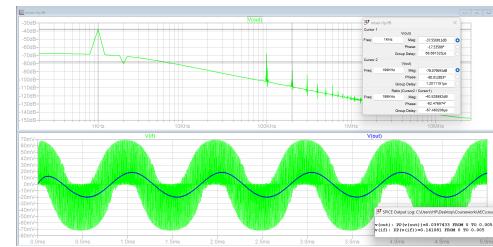


Fig. 15. Cosine waves of 100k and 99k frequency

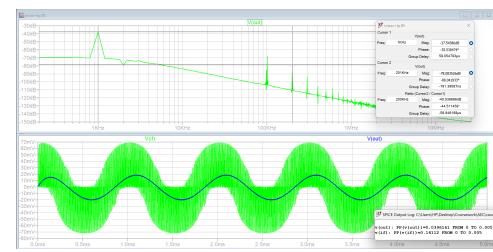


Fig. 16. Cosine waves of 100k and 101k frequency

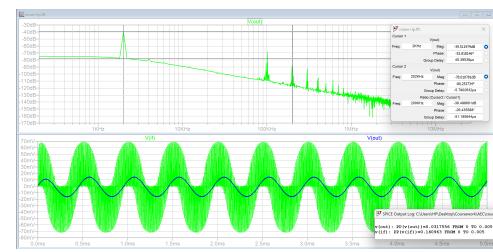


Fig. 17. Cosine waves of 100k and 102k frequency

We observe the frequency component of  $|\omega_{osc} - \omega_{in}|$  to be dominant and the frequency of  $|\omega_{osc} + \omega_{in}|$  to be suppressed by the low pass filter.

#### V. COMPLETE CIRCUIT PROTOTYPE DESIGN

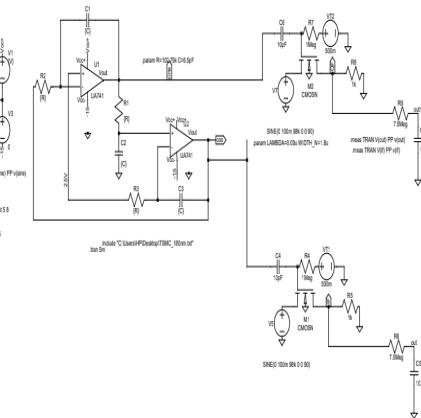


Fig. 18. Complete circuit with all the components connected together

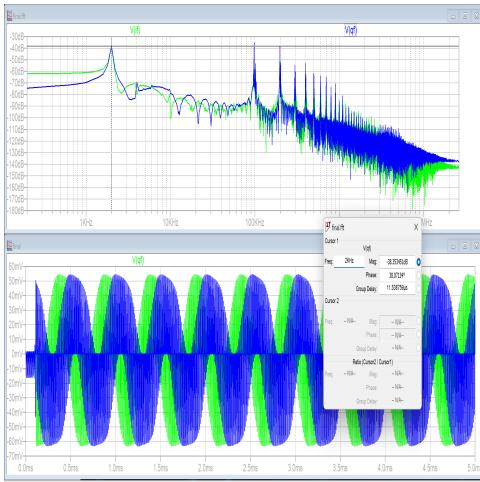


Fig. 19. IF,IQ

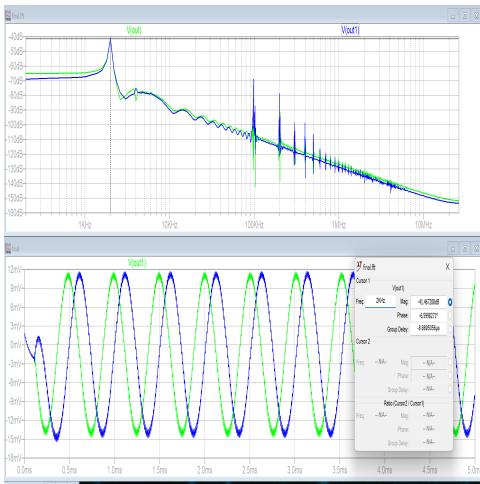


Fig. 20. IF final,QF final

## VI. HARDWARE RESULTS

### A. Quadrature oscillator

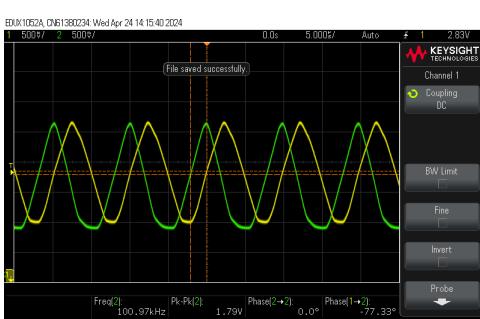


Fig. 21. Quadrature oscillator output with 2 sinusoids at 100kHz

### B. Mixer

Mixer circuit

TABLE I  
COMPARISON BETWEEN SIMULATION AND HARDWARE

Quantity	Measured	Simulated
Amplitude	$1.79V_{pp}$	$2V_{pp}$
Frequency	100.97 kHz	100kHz
Phase	77.13	89

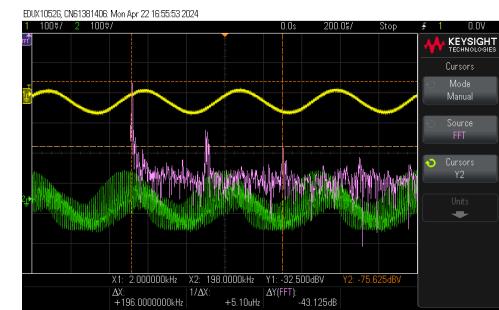


Fig. 22. Mixing of two signals at 100kHz and 98kHz

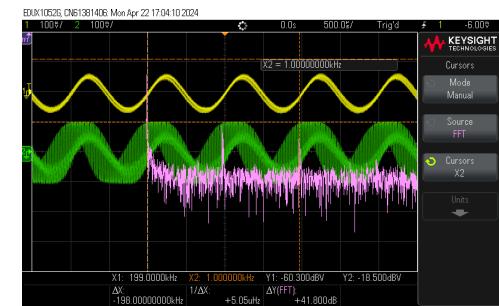


Fig. 23. Mixing of two signals at 100kHz and 99kHz

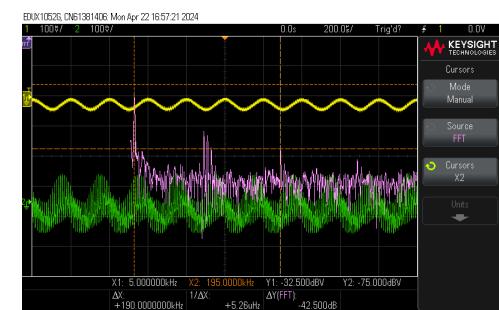


Fig. 24. Mixing of two signals at 100kHz and 105kHz

We could clearly observe the frequency component below 2Khz to be dominant.

### C. Low pass filter

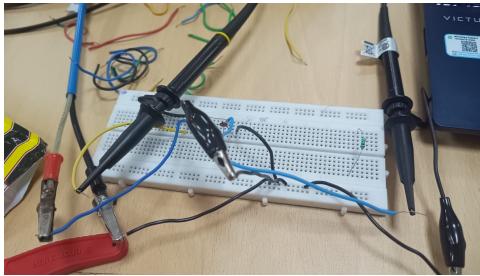


Fig. 25. Lab circuit

### D. Final circuit with all components connected together

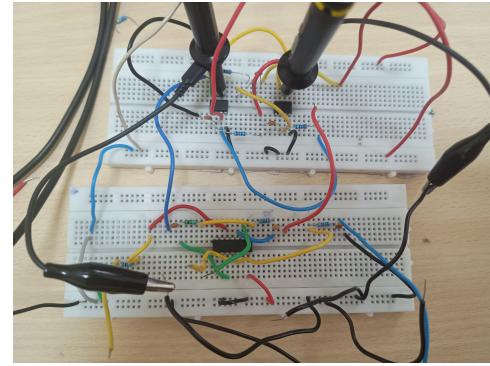


Fig. 29. Lab circuit



Fig. 26. Bode plot of Low pass filter

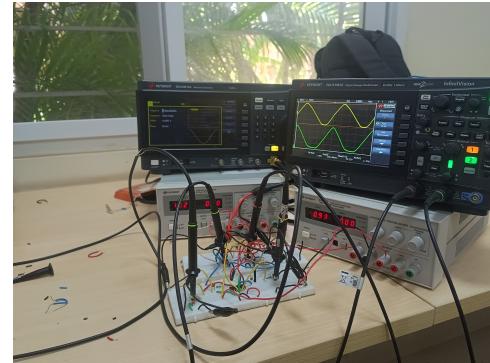


Fig. 30. Lab circuit and  $V_{IfI}$  and  $V_{IfQ}$

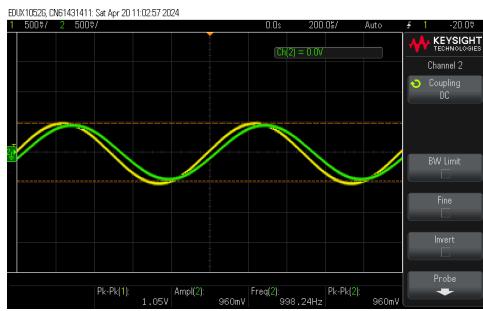


Fig. 27. Output and input signal for input at 1kHz

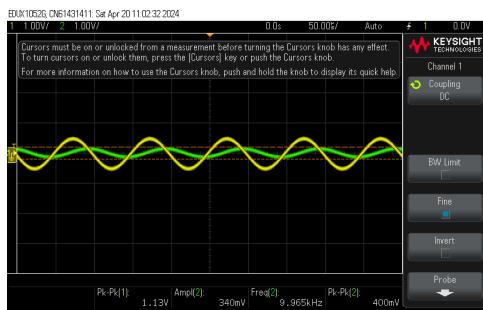


Fig. 28. Output and input signal for input at 10Hz

We could clearly observe the low pass filter action for 1kHz and 10kHz input frequencies.

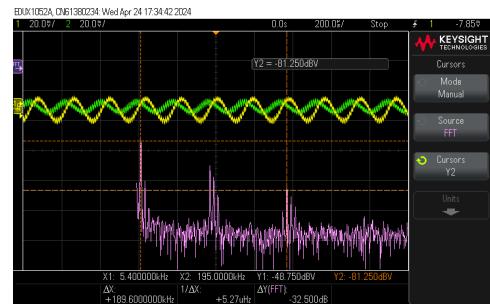


Fig. 31. Input signal at 95kHz

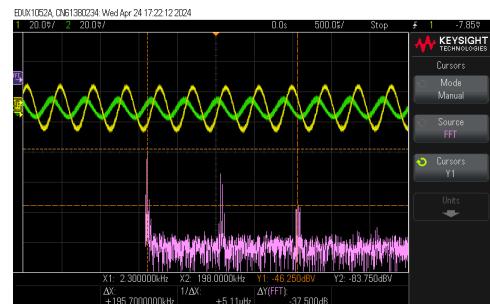


Fig. 32. Input signal at 98kHz

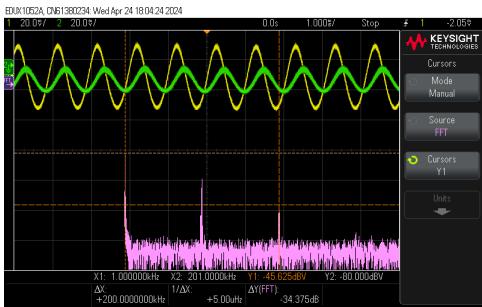


Fig. 33. Input signal at 99kHz

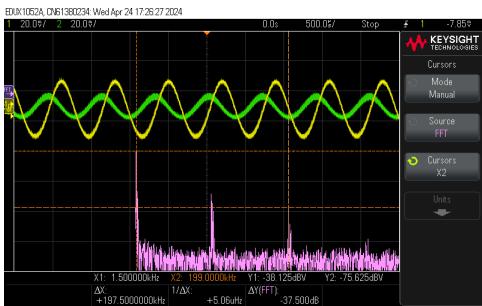


Fig. 34. Input signal at 99kHz

TABLE II  
PERFORMANCE SUMMARY AND COMPARISON

Parameters	Simulated	Measured
Oscillator Frequency	100.97 kHz	100Khz
Oscillator Amplitude(I-phase)	$2V_{pp}$	$1.79V_{pp}$
Oscillator Amplitude(Q-phase)	$2V_{pp}$	$1.79V_{pp}$
Input frequency	99.98kHz	100Khz
Supply	10.69V	5V
$V_{bias}$	980mV	500mV
$C_c$	10pF	10pF

## REFERENCES

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- [2] Behzad Razavi, Fundamental of Microelectronics
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