

Toan Khoa Nguyen

CONTACT INFORMATION	<p>Phone: (+866) 974 063 466</p> <p>Email: toankhoabk@gmail.com</p> <p>Homepage: www.linkedin.com/in/toankhoa</p> <p>GitHub: github.com/ntkhoa95</p>
EDUCATION	<p>National Taiwan University of Science and Technology, Taipei, Taiwan 2020 - Present</p> <p>Master of Electrical Engineering</p> <ul style="list-style-type: none"> • Research Interest: Image Processing, Computer Vision, Image Segmentation • Advisor: Professor Chung-Hsien Kuo and Professor Shun-Feng Su • GPA: 4.27/4.3 <p>Ho Chi Minh University of Technology, HCMc, Vietnam 2013 - 2018</p> <p>Bachelor of Automotive Engineering</p>
RESEARCH EXPERIENCE	<p>Autonomous & Soft Robotics Laboratory, National Taiwan University 2020 - Present</p> <ul style="list-style-type: none"> • Research Topics: Segmentation technologies for Autonomous mobile robots • Skilled gained: Developing a self-supervised learning method for drivable area and road anomalies segmentation. Providing an automatic system to generate segmentation labels for drivable area and road obstacles. Training the self-supervised labels with semantic segmentation neural networks to perform robust prediction in real-time on mobile robots.
RESEARCH INTERESTS	<p>My current research focuses mainly on Semantic Segmentation for applications on mobile robots, in which I utilize various techniques from traditional image processing to taking the advantages of deep learning methods to develop an efficient automatic labeling method. In addition, I used different attention-based methods to enrich the feature map in fusing the RGB-D input data to enhance the performance of the automatic labeling system.</p>
PUBLICATIONS	<ul style="list-style-type: none"> • Minh-Quang Tran, Meng-Kun Liu, Quoc-Viet Tran, Toan-Khoa Nguyen. Effective Fault Diagnosis Based on Wavelet and Convolutional Attention Neural Network for Induction Motors. <ul style="list-style-type: none"> ◦ <i>IEEE Transactions on Instrumentations and Measurement</i>, Volume 71 • Ming-Hong Hsu, Phuc Thanh-Thien Nguyen, Dai-Dong Nguyen, Toan-Khoa Nguyen, Chung-Hsien Kuo. Fabrication and Image Servo Tracking Study of a Continuum Robot Prototype. <ul style="list-style-type: none"> ◦ <i>International Journal of iRobotics</i>, 2021, Volume 4, No. 2
HONORS AND AWARDS	<ul style="list-style-type: none"> • Phase 1 Finalist, OpenCV AI competition 2021 • Full Scholarship of National Taiwan University of Science and Technology 2020
OTHER ACTIVITIES	<ul style="list-style-type: none"> • Teaching Assistant at Industrial Internet of Things Programming and Practice Course <ul style="list-style-type: none"> ◦ Instructor: Professor Minh-Quang Tran • Teaching Assistant at Fundamental of Self-Driving Cars Course <ul style="list-style-type: none"> ◦ Instructor: Professor Shu-Hao Liang
TECHNICAL SKILLS	<ul style="list-style-type: none"> • <i>System</i>: Windows, Linux • <i>Programming Languages</i>: Python, MATLAB • <i>Framework</i>: OpenCV, Tensorflow, Pytorch, Git

LANGUAGES	<ul style="list-style-type: none"> • Vietnamese: Native • English: Proficient (IELTS Overall 6.0)
REFERENCES	<p>Dr. Chung-Hsien Kuo Professor, Department of Mechanical Engineering, National Taiwan University, Taiwan President, Robotics Society of Taiwan (RST)/ 台灣機器人學會理事長 Email: chunghsien@ntu.edu.tw</p> <p>Dr. Shu-Hao Liang Professor, Industry 4.0 Center, National Taiwan University of Science and Technology, Taiwan Email: shuhaoliang@mail.ntust.edu.tw</p> <p>Dr. Minh-Quang Tran Professor, Industry 4.0 Center, National Taiwan University of Science and Technology, Taiwan Email: minhquang.tran@mail.ntust.edu.tw</p>