Running Probabilistic Programs Backward

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1

Abstract

Problem: doesn't exist: Turing-equivalent, probabilistic programming language with a semantics and implementation that supports any kind of probability measure and—critically—can do probabilistic conditioning

Why problem: Solution: Why solution:

Categories and Subject Descriptors XXX-CR-number [XXX-subcategory]: XXX-third-level

General Terms XXX, XXX

Keywords XXX, XXX

1. Introduction

XXX: motivate conditional probability XXX: densities fail:

- 1. infinite or variable-length data
- 2. discontinuities in random variables
- 3. nonlinear conditions

XXX: measures instead of densities, preimage measure Purely functional languages do not allow effects, including randomness. (Of course, to be Turing-equivalent, "pure" languages usually allow divergence, which is an applicative effect.) Programmers must write probabilistic programs as functions from a random source to outputs. Monads and other categorical classes such as idioms and arrows can make doing so easier. The strength of this approach lies in how it factors each probabilistic program into an effectful part and a pure part.

It seems this approach should make interpreting probabilistic programs in measure theory easy. For a probabilistic program $f:X\Rightarrow Y$, the probability measure over output sets $B\subseteq Y$ should be defined by preimages of B under f and the probability measure over X. Unfortunately, it is difficult to make a compositional semantics from this simple-sounding idea, for the following reasons.

- "Preimage under f" is a senseless phrase unless f has an observable domain of definition. Lambdas do not. Hash tables do, but their domains are finite.
- Probability measures can be defined only for measurable subsets of X and of Y. Thus, f is constrained: preimages of measurable subsets of Y must be measurable subsets of X. Proving the conditions under which this is true is difficult, especially when f may diverge.
- Probability measures cannot be defined for function types without imposing difficult restrictions.

Implementing a language based on such a semantics is complicated by these facts:

- Contemporary mathematics is unlike any implementation's host language.
- It requires running programs backward, efficiently, on possibly infinite sets of outputs.

XXX: rewrite the following In this paper, we

- 1. Define the *bottom arrow*, type X →_⊥ Y, as a compilation target for first-order functions that may raise errors.
- 2. Derive the *mapping arrow* from the bottom arrow, type $X_{\widetilde{map}}$ Y. Prove that its instances return extensional functions, or mappings, that compute the same values as corresponding bottom arrow computations.
- 3. Derive the *preimage arrow* from the mapping arrow, type X _{pre} Y. Prove that its instances compute preimages under corresponding mapping (or bottom) arrow instances.
- 4. Define an arrow transformer via a natural transformation η to thread random stores and avoid divergence.
- 5. Define a computable approximation of the transformed preimage arrow and report on its implementation.

Most of our correctness theorems can be described in terms of the following commutative diagram:

We prove that all the functions between arrow types in (1) are homomorphisms, which implies that $X_{\widetilde{pre}}Y$ and $X_{\widetilde{pre}}Y$ instances compute preimages correctly.

XXX: something about how we know the approximations are correct

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2. Operational Metalanguage

From here on, significant terms are introduced in **bold**, and significant terms we invent are introduced in **bold italics**.

We write all of the programs in this paper in $\lambda_{\rm ZFC}$ [2], an untyped, call-by-value lambda calculus designed for deriving implementable programs from contemporary mathematics.

Contemporary mathematics is generally done in **ZFC**: **Zermelo-Fraenkel** set theory extended with the axiom of **Choice** (equivalently unique **Cardinality**). ZFC has only first-order functions and no general recursion, which makes implementing a language defined by a transformation into contemporary mathematics quite difficult. The problem is exacerbated if implementing the language requires approximation. Targeting $\lambda_{\rm ZFC}$ instead allows creating a precise mathematical specification and deriving an approximating implementation without changing languages.

In $\lambda_{\rm ZFC}$, essentially every set is a value, as well as every lambda and every set of lambdas. All operations, including operations on infinite sets, are assumed to complete instantly if they terminate.¹

Almost everything definable in contemporary mathematics can be formally defined by a finite $\lambda_{\rm ZFC}$ program, except objects that most mathematicians would agree are nonconstructive. More precisely, any object that *must* be defined by a statement of existence and uniqueness without giving a bounding set is not definable by a *finite* $\lambda_{\rm ZFC}$ program.

Because $\lambda_{\rm ZFC}$ includes an inner model of ZFC, essentially every contemporary theorem applies to $\lambda_{\rm ZFC}$'s set values without alteration. Further, proofs about $\lambda_{\rm ZFC}$'s set values apply to contemporary mathematical objects.²

In $\lambda_{\rm ZFC}$, algebraic data structures are encoded as sets; e.g. a *primitive ordered pair* of x and y is $\{\{x\}, \{x,y\}\}$. Only the *existence* of encodings into sets is important, as it means data structures inherit a defining characteristic of sets: strictness. More precisely, the lengths of paths to data structure leaves is unbounded, but each path must be finite. Less precisely, data may be "infinitely wide" (such as \mathbb{R}) but not "infinitely tall" (such as infinite trees and lists).

We assume data structures, including pairs, are encoded as *primitive* ordered pairs with the first element a unique tag, so that they can be distinguished by checking tags. Accessors such as fst and snd are trivial to define.

 $\lambda_{\rm ZFC}$ is untyped so its users can define an auxiliary type system that best suits their application area. For this work, we use an informal, manually checked, polymorphic type system characterized by these rules:

- A free lowercase type variable is universally quantified.
- A free uppercase type variable is a set.
- A set denotes a member of that set.
- $x \Rightarrow y$ denotes a partial function.
- $\langle x, y \rangle$ denotes a pair of values with types x and y.
- Set x denotes a set with members of type x.

The type Set X denotes the same values as the powerset $\mathcal{P} X$, or *subsets* of X. Similarly, the type $\langle X, Y \rangle$ denotes the same values as the product set $X \times Y$.

We write $\lambda_{\rm ZFC}$ programs in heavily sugared λ -calculus syntax, with an if expression and these additional primitives:

$$\begin{array}{lll} \mathsf{true} : \mathsf{Bool} & (\in) : \mathsf{x} \Rightarrow \mathsf{Set} \; \mathsf{x} \Rightarrow \mathsf{Bool} \\ \mathsf{false} : \mathsf{Bool} & \mathcal{P} : \mathsf{Set} \; \mathsf{x} \Rightarrow \mathsf{Set} \; (\mathsf{Set} \; \mathsf{x}) \\ \varnothing : \mathsf{Set} \; \mathsf{x} & \bigcup : \mathsf{Set} \; (\mathsf{Set} \; \mathsf{x}) \Rightarrow \mathsf{Set} \; \mathsf{x} \\ \omega : \mathsf{Ord} & \mathsf{image} : (\mathsf{x} \Rightarrow \mathsf{y}) \Rightarrow \mathsf{Set} \; \mathsf{x} \Rightarrow \mathsf{Set} \; \mathsf{y} \\ \mathsf{take} : \mathsf{Set} \; \mathsf{x} \Rightarrow \mathsf{x} & |\cdot| : \mathsf{Set} \; \mathsf{x} \Rightarrow \mathsf{Ord} \end{array} \tag{2}$$

Shortly, \varnothing is the empty set, ω is the cardinality of the natural numbers, take $\{x\}$ reduces to x and diverges for non-singleton sets, $x \in A$ decides membership, \mathcal{P} A reduces to the set of subsets of A, $\bigcup \mathcal{A}$ reduces to the union of the sets in \mathcal{A} , image f A applies f to each member of A and reduces to the set of results, and |A| reduces to the cardinality of A.

We assume literal set notation such as $\{0, 1, 2\}$ is already defined in terms of the set primitives.

We import contemporary theorems as lemmas.

2.1 Internal and External Equality

Set theory extends first-order logic with an axiom that defines equality to be extensional, and with axioms that ensure the existence of sets in the domain of discourse. $\lambda_{\rm ZFC}$ is defined the same way as any other operational λ -calculus: by (conservatively) extending the domain of discourse with expressions and defining a reduction relation.

While $\lambda_{\rm ZFC}$ does not have an equality primitive, set theory's extensional equality can be recovered internally using (\in). *Internal* extensional equality is defined by

$$x = y := x \in \{y\} \tag{3}$$

which means

2

$$(=) := \lambda x. \lambda y. x \in \{y\}$$
 (4)

Thus, 1=1 reduces to $1\in\{1\}$, which reduces to true.³ Because of the particular way $\lambda_{\rm ZFC}$'s lambda terms are defined, for two lambda terms f and g, f = g reduces to true when f and g are structurally identical modulo renaming. For example, $(\lambda x. x) = (\lambda y. y)$ reduces to true, but $(\lambda x. 2) = (\lambda x. 1 + 1)$ reduces to false.

We understand any $\lambda_{\rm ZFC}$ term e used as a truth statement as shorthand for "e reduces to true." Therefore, while the terms $(\lambda x.x)$ 1 and 1 are (externally, extensionally) unequal, we can say that $(\lambda x.x)$ 1 = 1.

Any truth statement e implies that e converges. In particular, the truth statement $e_1 = e_2$ implies that both e_1 and e_2 converge. However, we often want to say that e_1 and e_1 are equivalent when they both diverge. In these cases, we use a slightly weaker equivalence.

Definition 2.1 (observational equivalence). Two λ_{ZFC} terms e_1 and e_2 are observationally equivalent, written $e_1 \equiv e_2$, when $e_1 = e_2$ or both e_1 and e_2 diverge.

It could be helpful to introduce even coarser notions of equivalence, such as applicative or logical bisimilarity. However, we do not want internal equality and external equivalence to differ too much. We therefore introduce type-specific notions of equivalence as needed.

2.2 Additional Functions and Forms

We assume a desugaring pass over $\lambda_{\rm ZFC}$ expressions, which automatically curries (including for the two-argument primitives (\in) and image), and interprets special binding forms

 $^{^1}$ An example of a nonterminating $\lambda_{\rm ZFC}$ function is one that attempts to decide whether other $\lambda_{\rm ZFC}$ programs halt.

² Assuming the existence of an inaccessible cardinal.

 $[\]overline{{}^{3}}$ Technically, λ_{ZFC} has a big-step semantics, and the derivation tree for 1=1 contains the derivation tree for $1\in\{1\}$.

such as indexed unions $\bigcup_{x \in e_A} e$, destructuring binds as in swap $\langle x, y \rangle := \langle y, x \rangle$, and comprehensions like $\{x \in A \mid x \in B\}$. (We may be rather informal with the latter two binding forms when the meaning is clear.) We assume we have logical operators, bounded quantifiers (unbounded quantifiers are not λ_{ZFC} -definable), and typical set operations.

A less typical set operation we use is disjoint union:

(
$$\uplus$$
): Set $x \Rightarrow$ Set $x \Rightarrow$ Set $x \Rightarrow$ A \uplus B := if (A \cap B = \varnothing) (A \cup B) (take \varnothing) (5)

 $A \uplus B$ diverges when A and B overlap.

In set theory, functions are encoded as sets of inputoutput pairs. The increment function for the natural numbers, for example, is $\{\langle 0,1\rangle,\langle 1,2\rangle,\langle 2,3\rangle,...\}$. To distinguish these huge tables from lambdas, we call them *mappings*, and use the word **function** to mean a lambda or mapping.

Syntax for defining unnamed mappings is defined by

$$\lambda x_a \in e_A. e_b :\equiv \text{ mapping } (\lambda x_a. e_b) e_A$$
 (6)

mapping :
$$(X \Rightarrow Y) \Rightarrow Set X \Rightarrow (X \rightarrow Y)$$

mapping f A := image $(\lambda a. \langle a, f a \rangle)$ A (7)

For convenience, as with lambdas, we use adjacency (e.g. (f x)) to apply mappings.

Figure 1 defines a few common operations on mappings: domain, range, preimage, restrict, pairing, composition, and disjoint union. The latter three are particularly important in the preimage arrow's derivation, and preimage is critical in measure theory's account of probability. For symmetry with partial functions $x \Rightarrow y$, they are defined on $X \rightharpoonup Y$, where $X \rightharpoonup Y$ is the set of all partial mappings from any domain set X to any codomain set Y.

The set $X \to Y$ contains all the *total* mappings from X to Y. We use total mappings as possibly infinite vectors, with application for indexing. Projections are produced by

$$\pi: J \Rightarrow (J \to X) \Rightarrow X$$

$$\pi \mid f := f \mid$$
(8)

which will be useful when f is unnamed.

Pairs $\langle A, f \rangle$: $\langle Set \, x, x \Rightarrow y \rangle$ are like functions with an observable domain and range; we call them *lazy mappings*. We do not use them in this paper, but we define a similar function-like type in Section 5 for computing preimages.

3. Arrows and First-Order Semantics

XXX: really short arrow intro (XXX: cite Hughes, Lindley et al)

3.1 Alternative Arrow Definitions

For every arrow a in this paper, we do not give a typical minimal definition. Instead of first_a, we define (&&a)—typically called fanout, but its use will be clearer if we call it pairing—which applies two functions to an input and returns the pair of their outputs. Though first_a may be defined in terms of (&&a) and vice-versa [1], we give (&&a) definitions in this paper because the applicable contemporary theorems are in terms of pairing functions.

One way to strengthen an arrow a is to define an additional combinator left_a, which can be used to choose an arrow computation based on the result of another. Again, we define a different combinator, ifte_a, to make it easier to apply contemporary theorems.

In a nonstrict λ -calculus, simply defining a choice combinator allows writing recursive functions using nothing but

arrow combinators and lifted, pure functions. However, any strict λ -calculus (such as $\lambda_{\rm ZFC}$) requires an extra combinator to defer computations in conditional branches.

For example, suppose we define the **function arrow** with choice, by defining

$$\begin{array}{rcl} & \text{arr } f := f \\ (f_1 \ggg f_2) \ a := f_2 \ (f_1 \ a) \\ (f_1 \ggg f_2) \ a := \langle f_1 \ a, f_2, a \rangle \\ & \text{ifte } f_1 \ f_2 \ f_3 \ a := \text{if } (f_1 \ a) \ (f_2 \ a) \ (f_3 \ a) \end{array} \tag{9}$$

and try to define the following recursive function:

$$halt-on-true := ifte (arr id) (arr id) halt-on-true (10)$$

The defining expression diverges in a strict λ -calculus. In a nonstrict λ -calculus, it diverges only when applied to false.

Using lazy f a := f 0 a, which receives thunks and returns arrow computations, we can write halt-on-true as

halt-on-true := ifte (arr id) (arr id) (lazy
$$\lambda$$
0. halt-on-true) (11

which diverges only when applied to false in any λ -calculus.

Definition 3.1 (arrow with choice). A binary type constructor (\sim_a) and the combinators

$$\operatorname{arr}_{a}: (x \Rightarrow y) \Rightarrow (x \leadsto_{a} y)$$

$$(\ggg_{a}): (x \leadsto_{a} y) \Rightarrow (y \leadsto_{a} z) \Rightarrow (x \leadsto_{a} z)$$

$$(\&\&\&_{a}): (x \leadsto_{a} y) \Rightarrow (x \leadsto_{a} z) \Rightarrow (x \leadsto_{a} \langle y, z \rangle)$$

$$(12)$$

define an **arrow** if certain monoid, homomorphism, and structural laws hold. The additional combinators

$$\begin{aligned} &\text{ifte}_{a}: (x \leadsto_{a} \mathsf{Bool}) \Rightarrow (x \leadsto_{a} y) \Rightarrow (x \leadsto_{a} y) \Rightarrow (x \leadsto_{a} y) \\ &\mathsf{lazy}_{a}: (1 \Rightarrow (x \leadsto_{a} y)) \Rightarrow (x \leadsto_{a} y) \end{aligned} \tag{13}$$

define an arrow with choice if certain additional homomorphism and structural laws hold.

From here on, as all of our arrows are arrows with choice, we simply call them arrows.

The necessary homomorphism laws ensure that arr_a distributes over function arrow combinators. These laws can be put in terms of more general homomorphism properties that deal with distributing an arrow-to-arrow lift, which we use extensively to prove correctness.

Definition 3.2 (arrow homomorphism). A function lift_b: $(x \leadsto_a y) \Rightarrow (x \leadsto_b y)$ is an arrow homomorphism from arrow a to arrow b if the following distributive laws hold for appropriately typed f, f₁, f₂ and f₃:

$$lift_b (arr_a f) \equiv arr_b f$$
 (14)

$$\mathsf{lift_b} \; (\mathsf{f_1} > \!\! >_{\mathsf{a}} \mathsf{f_2}) \; \equiv \; (\mathsf{lift_b} \; \mathsf{f_1}) > \!\! >_{\mathsf{b}} \; (\mathsf{lift_b} \; \mathsf{f_2})$$
 (15)

$$\mathsf{lift_b} (\mathsf{f_1} \&\& \mathsf{k_a} \mathsf{f_2}) \equiv (\mathsf{lift_b} \mathsf{f_1}) \&\& \mathsf{k_b} (\mathsf{lift_b} \mathsf{f_2}) \tag{16}$$

$$\mathsf{lift_b} \; (\mathsf{ifte_a} \; \mathsf{f_1} \; \mathsf{f_2} \; \mathsf{f_3}) \; \equiv \; \mathsf{ifte_b} \; (\mathsf{lift_b} \; \mathsf{f_1}) \; (\mathsf{lift_b} \; \mathsf{f_2}) \; (\mathsf{lift_b} \; \mathsf{f_3}) \; \; (17)$$

$$lift_b (lazy_a f) \equiv lazy_b \lambda 0. lift_b (f 0)$$
 (18)

The homomorphism laws state that arr_a must be a homomorphism from the function arrow to arrow a.

The monoid and structural arrow laws play little role in our semantics or its correctness. For the arrows we define, then, we elide the proofs of these arrow laws, and concentrate on homomorphisms.

XXX: actually, need to prove some of them, to prove that the natural transformation for the applicative store-passing arrow transformer is a homomorphism

2013/7/22

3

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\langle \cdot, \cdot \rangle_{\mathsf{map}} : (\mathsf{X} \rightharpoonup \mathsf{Y}_1) \Rightarrow (\mathsf{X} \rightharpoonup \mathsf{Y}_2) \Rightarrow (\mathsf{X} \rightharpoonup \mathsf{Y}_1 \times \mathsf{Y}_2)
domain : (X \rightarrow Y) \Rightarrow Set X
domain := image fst
                                                                                                                     \langle g_1, g_2 \rangle_{map} := \text{let } A := (\text{domain } g_1) \cap (\text{domain } g_2)
                                                                                                                                                             in \lambda a \in A. \langle g_1 a, g_2 a \rangle
range : (X \rightarrow Y) \Rightarrow Set Y
                                                                                                                    (\circ_{\mathsf{map}}): (\mathsf{Y} \rightharpoonup \mathsf{Z}) \Rightarrow (\mathsf{X} \rightharpoonup \mathsf{Y}) \Rightarrow (\mathsf{X} \rightharpoonup \mathsf{Z})
range := image snd
                                                                                                                     g_2\circ_{\mathsf{map}} g_1 \ := \ \mathsf{let} \ \mathsf{A} := \mathsf{preimage} \ g_1 \ (\mathsf{domain} \ g_2)
                                                                                                                                                            in \lambda a \in A. g_2(g_1 a)
preimage : (X \rightarrow Y) \Rightarrow Set Y \Rightarrow Set X
preimage f B := \{a \in domain f \mid f a \in B\}
                                                                                                                    (\uplus_{\mathsf{map}}): (\mathsf{X} \rightharpoonup \mathsf{Y}) \Rightarrow (\mathsf{X} \rightharpoonup \mathsf{Y}) \Rightarrow (\mathsf{X} \rightharpoonup \mathsf{Y})
                                                                                                                    g_1 \uplus_{\mathsf{map}} g_2 := \mathsf{let} \ \mathsf{A} := (\mathsf{domain} \ g_1) \uplus (\mathsf{domain} \ g_2)
\mathsf{restrict} : (\mathsf{X} \rightharpoonup \mathsf{Y}) \Rightarrow \mathsf{Set} \; \mathsf{X} \Rightarrow (\mathsf{X} \rightharpoonup \mathsf{Y})
                                                                                                                                                             in \lambda a \in A. if (a \in domain g_1) (g_1 a) (g_2 a)
restrict f A := \lambdaa \in (A \cap domain f). f a
```

Figure 1: Operations on mappings.

4

3.2 First-Order Let-Calculus Semantics

XXX: Figure 2...

XXX: Stack machine...

XXX: Roughly, first-order application (x e) runs arrow computation x with a fresh stack with e at the head. The binding form (let $e_0 \ e_b$) pushes e_0 onto the stack. Variables are referenced using (env n) with (env 0) referring to the head.

4. The Bottom and Mapping Arrows

We are certain that the preimage arrow correctly computes preimages under some function f because we ultimately derive it from a simpler arrow used to construct f.

One obvious candidate for the simpler arrow is the function arrow, defined in (9). However, we will need to explicitly handle divergence, so we need a slightly more complicated arrow for which running computations may raise an error.

Figure 3 defines the **bottom arrow**. Its computations are of type $x \leadsto_{\perp} y ::= x \Rightarrow y_{\perp}$, where the inhabitants of y_{\perp} are the error value \perp as well as the inhabitants of y. The type Bool_{\perp} , for example, denotes the members of $\mathsf{Bool} \cup \{\bot\}$.

Theorem 4.1. $\operatorname{arr}_{\perp}$, (&& $_{\perp}$), (>>> $_{\perp}$), ifte $_{\perp}$ and $\operatorname{lazy}_{\perp}$ define an arrow.

Proof. The bottom arrow is the Maybe monad's Kleisli arrow with Nothing = \bot .

4.1 Deriving the Mapping Arrow

Contemporary theorems about functions are about mappings, not lambdas. As in intermediate step toward the preimage arrow, then, we need an arrow whose computations produce mappings or are mappings themselves.

To parameterize mapping arrow computations on a domain, we define the *mapping arrow* computation type as

$$X \underset{\text{map}}{\leadsto} Y ::= Set X \Rightarrow (X \rightarrow Y)$$
 (19)

Notice that \bot is absent in Set $X \Rightarrow (X \rightharpoonup Y)$. This will make it easier to disregard diverging inputs when computing preimages further on. (XXX: section)

A computation $g:X_{\stackrel{\leadsto}{map}}Y$ must meet the following *restriction law*. For all $A\subseteq X$ for which g A converges, and for all $A'\subseteq A$,

$$g A' = restrict (g A) A'$$
 (20)

Roughly, g must act as if it returns restricted mappings.

To make the correspondence between bottom arrow and mapping arrow computations as clear as possible, we start by defining a function lift_{map}: $(X \leadsto_{\bot} Y) \Rightarrow (X \leadsto_{map} Y)$ to lift bottom arrow computations. It must restrict its argument f's domain to a subset of X for which f does not return \bot . It is helpful to have a standalone function domain $_{\bot}$ that computes such domains, so we define that first, and then define lift_{map} in terms of it:

$$\begin{aligned} \mathsf{domain}_{\perp} : (\mathsf{X} \leadsto_{\perp} \mathsf{Y}) &\Rightarrow \mathsf{Set} \; \mathsf{X} \Rightarrow \mathsf{Set} \; \mathsf{X} \\ \mathsf{domain}_{\perp} \; \mathsf{f} \; \mathsf{A} \; := \; \{ \mathsf{a} \in \mathsf{A} \mid \mathsf{f} \; \mathsf{a} \neq \bot \} \end{aligned} \tag{21}$$

$$\begin{split} & \mathsf{lift}_{\mathsf{map}} : (\mathsf{X} \leadsto_{\perp} \mathsf{Y}) \Rightarrow (\mathsf{X} \underset{\mathsf{map}}{\leadsto} \mathsf{Y}) \\ & \mathsf{lift}_{\mathsf{map}} \mathsf{f} \mathsf{A} := \mathsf{mapping} \mathsf{f} \; (\mathsf{domain}_{\perp} \mathsf{f} \mathsf{A}) \end{split} \tag{22}$$

The clearest way to ensure that mapping arrow computations mean what we think they mean is to derive each combinator in a way that makes lift_{map} distribute over bottom arrow computations; i.e. it must be an arrow homomorphism (Definition 3.2). If lift_{map} is a homomorphism, then $\llbracket e \rrbracket_{map} \equiv \text{lift}_{map} \ \llbracket e \rrbracket_{\perp}$ for any let-calculus expression e, because lift_{map} distributes through its expansion.

To meet the homomorphism laws, we need equivalence to be more extensional for mapping computations.

Definition 4.2 (mapping arrow equivalence). Two mapping arrow computations $g_1 : X_{\widetilde{m}\widetilde{p}} Y$ and $g_2 : X_{\widetilde{m}\widetilde{p}} Y$ are equivalent, or $g_1 \equiv g_2$, when $g_1 A \equiv g_2 A$ for all $A \subseteq X$.

Clearly $\mathsf{arr_b} := \mathsf{lift_b} \circ \mathsf{arr_a}$ meets the first homomorphism identity (14), so we define $\mathsf{arr_{map}}$ as a composition. The following subsections derive (&&_{map}), (>>>_{map}), ifte_{map} and $\mathsf{lazy_{map}}$ from their corresponding bottom arrow combinators, in a way that ensures $\mathsf{lift_{map}}$ is an arrow homomorphism. Figure 4 contains the resulting definitions.

Figure 2: Transformation from a let-calculus with first-order definitions and De-Bruijn-indexed bindings to computations in arrow a.

$$\begin{array}{lll} x \rightsquigarrow_{\perp} y & ::= & x \Rightarrow y_{\perp} & \text{ifte}_{\perp} : (x \rightsquigarrow_{\perp} Bool) \Rightarrow (x \rightsquigarrow_{\perp} y) \Rightarrow (x \rightsquigarrow_{\perp} y) \\ \text{arr}_{\perp} : (x \Rightarrow y) \Rightarrow (x \rightsquigarrow_{\perp} y) & \text{ifte}_{\perp} : f_{1} \; f_{2} \; f_{3} \; a \; := \; case \; f_{1} \; a \\ & \text{true} \; \implies f_{2} \; a \\ \text{false} \; \implies f_{3} \; a \\ \text{else} \; \implies \perp & \\ (\ggg_{\perp}) : (x \rightsquigarrow_{\perp} y) \Rightarrow (y \rightsquigarrow_{\perp} z) \Rightarrow (x \rightsquigarrow_{\perp} z) \\ (f_{1} \ggg_{\perp} f_{2}) \; a \; := \; \text{if} \; (f_{1} \; a = \perp) \; \perp \; (f_{2} \; (f_{1} \; a)) \\ & \text{lazy}_{\perp} : (1 \Rightarrow (x \rightsquigarrow_{\perp} y)) \Rightarrow (x \rightsquigarrow_{\perp} y) \\ & \text{lazy}_{\perp} : (1 \Rightarrow (x \rightsquigarrow_{\perp} y)) \Rightarrow (x \rightsquigarrow_{\perp} y) \\ & \text{lazy}_{\perp} \; f \; a \; := \; f \; 0 \; a \\ & \text{lazy}_{\perp} \; f \; a \; := \; f \; f \; a \; a \; a \\ & \text{lazy}_{\perp} \; f \; a \; := \; f \; f \; a \; a \; a \\ & \text{lazy}_{\perp} \; f \; a \; a \; a \\ & \text{lazy}_{\perp} \; f \; a \; a \; a \\ & \text{lazy}_{\perp} \; f \; a \;$$

Figure 3: Bottom arrow definitions.

$$\begin{array}{llll} X_{\stackrel{\longrightarrow}{map}}Y ::= & \mathsf{Set} \ \mathsf{X} \Rightarrow (\mathsf{X} \rightharpoonup \mathsf{Y}) & & \mathsf{ifte_{map}} : (\mathsf{X}_{\stackrel{\longrightarrow}{map}} \mathsf{Bool}) \Rightarrow (\mathsf{X}_{\stackrel{\longrightarrow}{map}} \mathsf{Y}) \Rightarrow (\mathsf{X}_{\stackrel{\longrightarrow}{map}} \mathsf{Y}) \Rightarrow (\mathsf{X}_{\stackrel{\longrightarrow}{map}} \mathsf{Y}) \\ \mathsf{arr}_{\mathsf{map}} : (\mathsf{X} \Rightarrow \mathsf{Y}) \Rightarrow (\mathsf{X}_{\stackrel{\longrightarrow}{map}} \mathsf{Y}) & & \mathsf{ifte_{map}} : (\mathsf{X}_{\stackrel{\longrightarrow}{map}} \mathsf{Bool}) \Rightarrow (\mathsf{X}_{\stackrel{\longrightarrow}{map}} \mathsf{Y}) \Rightarrow (\mathsf{X}_{\stackrel{\longrightarrow}{map}} \mathsf{Y}) \\ \mathsf{arr}_{\mathsf{map}} : (\mathsf{X} \Rightarrow \mathsf{Y}) \Rightarrow (\mathsf{X}_{\stackrel{\longrightarrow}{map}} \mathsf{Y}) & & \mathsf{ifte_{map}} : (\mathsf{X}_{\stackrel{\longrightarrow}{map}} \mathsf{Bool}) \Rightarrow (\mathsf{X}_{\stackrel{\longrightarrow}{map}} \mathsf{Y}) \Rightarrow (\mathsf{X}_{\stackrel{\longrightarrow}{map}} \mathsf{Y}) \\ \mathsf{ifte_{map}} : (\mathsf{X} \Rightarrow \mathsf{Y}) \Rightarrow (\mathsf{X}_{\stackrel{\longrightarrow}{map}} \mathsf{Y}) & & \mathsf{ifte_{map}} : (\mathsf{I} \Rightarrow \mathsf{I} \Rightarrow \mathsf{I}) \\ \mathsf{g}_3 := \mathsf{g}_3 \ (\mathsf{preimage} \ \mathsf{g}_1' \ \{\mathsf{false}\}) \\ \mathsf{in} \ \mathsf{g}_2' := \mathsf{g}_2 \ (\mathsf{preimage} \ \mathsf{g}_1' \ \{\mathsf{false}\}) \\ \mathsf{g}_3 := \mathsf{g}_3 \ (\mathsf{preimage} \ \mathsf{g}_1' \ \{\mathsf{false}\}) \\ \mathsf{g}_3 := \mathsf{g}_3 \ (\mathsf{preimage} \ \mathsf{g}_1' \ \{\mathsf{false}\}) \\ \mathsf{g}_3 := \mathsf{g}_3 \ (\mathsf{preimage} \ \mathsf{g}_1' \ \{\mathsf{false}\}) \\ \mathsf{g}_3 := \mathsf{g}_3 \ (\mathsf{preimage} \ \mathsf{g}_1' \ \{\mathsf{false}\}) \\ \mathsf{g}_3 := \mathsf{g}_3 \ (\mathsf{preimage} \ \mathsf{g}_1' \ \{\mathsf{false}\}) \\ \mathsf{g}_3 := \mathsf{g}_3 \ (\mathsf{preimage} \ \mathsf{g}_1' \ \{\mathsf{false}\}) \\ \mathsf{g}_3 := \mathsf{g}_3 \ (\mathsf{preimage} \ \mathsf{g}_1' \ \{\mathsf{false}\}) \\ \mathsf{g}_3 := \mathsf{g}_3 \ (\mathsf{preimage} \ \mathsf{g}_1' \ \{\mathsf{false}\}) \\ \mathsf{g}_3 := \mathsf{g}_3 \ (\mathsf{preimage} \ \mathsf{g}_1' \ \{\mathsf{false}\}) \\ \mathsf{g}_3 := \mathsf{g}_3 \ (\mathsf{preimage} \ \mathsf{g}_1' \ \{\mathsf{false}\}) \\ \mathsf{g}_3 := \mathsf{g}_3 \ (\mathsf{preimage} \ \mathsf{g}_1' \ \{\mathsf{false}\}) \\ \mathsf{g}_3 := \mathsf{g}_3 \ (\mathsf{preimage} \ \mathsf{g}_1' \ \{\mathsf{false}\}) \\ \mathsf{g}_3 := \mathsf{g}_3 \ (\mathsf{preimage} \ \mathsf{g}_1' \ \{\mathsf{false}\}) \\ \mathsf{g}_3 := \mathsf{g}_3 \ (\mathsf{preimage} \ \mathsf{g}_1' \ \{\mathsf{false}\}) \\ \mathsf{g}_3 := \mathsf{g}_3 \ (\mathsf{preimage} \ \mathsf{g}_1' \ \{\mathsf{false}\}) \\ \mathsf{g}_3 := \mathsf{g}_3 \ (\mathsf{preimage} \ \mathsf{g}_1' \ \{\mathsf{false}\}) \\ \mathsf{g}_3 := \mathsf{g}_3 \ (\mathsf{preimage} \ \mathsf{g}_1' \ \{\mathsf{false}\}) \\ \mathsf{g}_3 := \mathsf{g}_3 \ (\mathsf{preimage} \ \mathsf{g}_1' \ \{\mathsf{false}\}) \\ \mathsf{g}_3 := \mathsf{g}_3 \ (\mathsf{preimage} \ \mathsf{g}_1' \ \{\mathsf{false}\}) \\ \mathsf{g}_3 := \mathsf{g}_3 \ (\mathsf{preimage} \ \mathsf{g}_1' \ \{\mathsf{false}\}) \\ \mathsf{g}_3 := \mathsf{g}_3 \ (\mathsf{g}_3 := \mathsf{g}_3' \ \mathsf{g}_3$$

Figure 4: Mapping arrow definitions.

5

4.2 Case: Pairing

Starting with the left side of (16), we first expand definitions. For any $f_1: X \leadsto_{\perp} Y$, $f_2: X \leadsto_{\perp} Z$, and $A \subseteq X$,

$$\begin{array}{l} \mathsf{lift}_{\mathsf{map}} \ \big(\mathsf{f}_1 \ \&\& \bot \ \mathsf{f}_2 \big) \ \mathsf{A} \\ & \equiv \ \mathsf{lift}_{\mathsf{map}} \ \big(\lambda \, \mathsf{a}. \, \mathsf{if} \ \big(\mathsf{f}_1 \ \mathsf{a} = \bot \ \mathsf{or} \ \mathsf{f}_2 \ \mathsf{a} = \bot \big) \ \bot \ \big\langle \mathsf{f}_1 \ \mathsf{a}, \mathsf{f}_2 \ \mathsf{a} \big\rangle \big) \ \mathsf{A} \\ & \equiv \ \mathsf{let} \ \ \mathsf{f} := \lambda \, \mathsf{a}. \, \mathsf{if} \ \big(\mathsf{f}_1 \ \mathsf{a} = \bot \ \mathsf{or} \ \mathsf{f}_2 \ \mathsf{a} = \bot \big) \ \bot \ \big\langle \mathsf{f}_1 \ \mathsf{a}, \mathsf{f}_2 \ \mathsf{a} \big\rangle \\ & \quad \mathsf{in} \ \ \mathsf{mapping} \ \mathsf{f} \ \big(\mathsf{domain}_\bot \ \mathsf{f} \ \mathsf{A} \big) \end{array} \tag{23}$$

Next, we replace the definition of A' with one that does not depend on f, and rewrite in terms of $lift_{map}$ f_1 and $lift_{map}$ f_2 :

$$\begin{array}{l} \mathsf{lift}_{\mathsf{map}} \; \big(\mathsf{f}_1 \; \&\&\&_\perp \; \mathsf{f}_2 \big) \; \mathsf{A} \\ & \equiv \; \mathsf{let} \; \; \mathsf{A}_1 := (\mathsf{domain}_\perp \; \mathsf{f}_1 \; \mathsf{A}) \\ & \; \mathsf{A}_2 := (\mathsf{domain}_\perp \; \mathsf{f}_2 \; \mathsf{A}) \\ & \; \mathsf{A}' := \mathsf{A}_1 \cap \mathsf{A}_2 \\ & \mathsf{in} \; \; \lambda \mathsf{a} \in \mathsf{A}' \cdot \langle \mathsf{f}_1 \; \mathsf{a}, \mathsf{f}_2 \; \mathsf{a} \rangle \\ & \equiv \; \mathsf{let} \; \; \mathsf{g}_1 := \mathsf{lift}_{\mathsf{map}} \; \mathsf{f}_1 \; \mathsf{A} \\ & \; \mathsf{g}_2 := \mathsf{lift}_{\mathsf{map}} \; \mathsf{f}_2 \; \mathsf{A} \\ & \; \mathsf{A}' := (\mathsf{domain} \; \mathsf{g}_1) \cap (\mathsf{domain} \; \mathsf{g}_2) \\ & \mathsf{in} \; \; \lambda \mathsf{a} \in \mathsf{A}' \cdot \langle \mathsf{g}_1 \; \mathsf{a}, \mathsf{g}_2 \; \mathsf{a} \rangle \\ & \equiv \; \langle \mathsf{lift}_{\mathsf{map}} \; \mathsf{f}_1 \; \mathsf{A}, \mathsf{lift}_{\mathsf{map}} \; \mathsf{f}_2 \; \mathsf{A} \rangle_{\mathsf{map}} \end{array} \tag{24} \end{array}$$

Substituting g_1 for $lift_{map}$ f_1 and g_2 for $lift_{map}$ f_2 gives a definition for (&& μ_{map}) (Figure 4) for which (16) holds.

4.3 Case: Composition

The derivation of (\ggg_{map}) is similar to that of $(\&\&\&_{map})$ but a little more involved.

XXX: include it?

4.4 Case: Conditional

Starting with the left side of (17), we expand definitions, and simplify f by restricting it to a domain for which f_1 $a \neq \bot$:

$$\begin{array}{l} \text{lift}_{\text{map}} \text{ (ifte}_{\perp} \text{ } f_1 \text{ } f_2 \text{ } f_3 \text{) } A \\ & \equiv \text{ let } \text{ } f := \lambda \text{a. } \text{case } \text{ } f_1 \text{ a} \\ & \text{ true } \implies \text{ } f_2 \text{ a} \\ & \text{ false } \implies \text{ } f_3 \text{ a} \\ & \text{ else } \implies \bot \\ & \text{ in } \text{ mapping } f \text{ (domain}_{\perp} \text{ } f \text{ } A) \\ & \equiv \text{ let } \text{ } g_1 := \text{ mapping } f \text{ } A \\ & A_2 := \text{ preimage } g_1 \text{ } \{ \text{true} \} \\ & A_3 := \text{ preimage } g_1 \text{ } \{ \text{false} \} \\ & \text{ } f := \lambda \text{ a. if } (f_1 \text{ a}) (f_2 \text{ a}) (f_3 \text{ a}) \\ & \text{ in } \text{ mapping } f \text{ (domain}_{\perp} \text{ } f \text{ } (A_2 \uplus A_3)) \end{array}$$

We finish by converting bottom arrow computations to the mapping arrow and rewriting in terms of (\biguplus_{map}) :

$$\begin{array}{l} \mathsf{lift}_{\mathsf{map}} \ (\mathsf{ifte}_\perp \ f_1 \ f_2 \ f_3) \ \mathsf{A} \\ & \equiv \ \mathsf{let} \ \ \mathsf{g}_1 := \mathsf{lift}_{\mathsf{map}} \ f_1 \ \mathsf{A} \\ & \mathsf{g}_2 := \mathsf{lift}_{\mathsf{map}} \ f_2 \ (\mathsf{preimage} \ \mathsf{g}_1 \ \{\mathsf{true}\}) \\ & \mathsf{g}_3 := \mathsf{lift}_{\mathsf{map}} \ f_3 \ (\mathsf{preimage} \ \mathsf{g}_1 \ \{\mathsf{false}\}) \\ & \mathsf{A}' := (\mathsf{domain} \ \mathsf{g}_2) \uplus (\mathsf{domain} \ \mathsf{g}_3) \\ & \mathsf{in} \ \ \mathsf{Aa} \in \mathsf{A}'. \mathsf{if} \ (\mathsf{a} \in \mathsf{domain} \ \mathsf{g}_2) \ (\mathsf{g}_2 \ \mathsf{a}) \ (\mathsf{g}_3 \ \mathsf{a}) \\ & \equiv \ \mathsf{let} \ \ \mathsf{g}_1 := \mathsf{lift}_{\mathsf{map}} \ f_1 \ \mathsf{A} \\ & \mathsf{g}_2 := \mathsf{lift}_{\mathsf{map}} \ f_2 \ (\mathsf{preimage} \ \mathsf{g}_1 \ \{\mathsf{true}\}) \\ & \mathsf{g}_3 := \mathsf{lift}_{\mathsf{map}} \ f_3 \ (\mathsf{preimage} \ \mathsf{g}_1 \ \{\mathsf{false}\}) \\ & \mathsf{in} \ \ \mathsf{g}_3 \ \forall \mathsf{hom} \ \mathsf{g}_3 \ \forall \mathsf{hom} \ \mathsf{g}_3 \ \mathsf{g}_3 \ \mathsf{g}_3 \\ & \mathsf{g}_3 \ \mathsf{g}_3 \ \mathsf{g}_3 \ \mathsf{g}_3 \ \mathsf{g}_3 \ \mathsf{g}_3 \ \mathsf{g}_3 \\ & \mathsf{g}_3 \ \mathsf{g}_3 \\ & \mathsf{g}_3 \ \mathsf{g}_3 \$$

Substituting g_1 for $lift_{map}$ f_1 , g_2 for $lift_{map}$ f_2 , and g_3 for $lift_{map}$ f_3 gives a definition for ifte_{map} (Figure 4) for which (17) holds.

4.5 Case: Laziness

Starting with the left side of (18), we first expand definitions:

$$lift_{map} (lazy_{\perp} f) A$$

$$\equiv let A' := domain_{\perp} (\lambda a. f 0 a) A$$

$$in mapping (\lambda a. f 0 a) A'$$

 λ_{ZFC} does not have an η rule (i.e. $\lambda x. e \ x \not\equiv e$ because e may diverge), but we can use weaker facts. If $A \neq \emptyset$, then domain $_{\perp}$ (λ a. f 0 a) $A \equiv \mathrm{domain}_{\perp}$ (f 0) A. Further, it diverges iff f 0 diverges, and iff mapping (f 0) A' diverges. Therefore, if $A \neq \emptyset$, we can replace λ a. f 0 a with f 0. If $A = \emptyset$, then lift_{map} (lazy $_{\perp}$ f) $A = \emptyset$ (the empty mapping), so

$$\begin{split} & \mathsf{lift}_{\mathsf{map}} \; (\mathsf{lazy}_{\bot} \; f) \; \mathsf{A} \\ & \equiv \; \mathsf{if} \; (\mathsf{A} = \varnothing) \; \varnothing \; (\mathsf{mapping} \; (\mathsf{f} \; 0) \; (\mathsf{domain}_{\bot} \; (\mathsf{f} \; 0) \; \mathsf{A})) \\ & \equiv \; \mathsf{if} \; (\mathsf{A} = \varnothing) \; \varnothing \; (\mathsf{lift}_{\mathsf{map}} \; (\mathsf{f} \; 0) \; \mathsf{A}) \end{split}$$

Substituting g 0 for lift_{map} (f 0) gives a definition for $lazy_{map}$ (Figure 4) for which (18) holds.

4.6 Correctness

Theorem 4.3 (mapping arrow correctness). lift $_{map}$ is an arrow homomorphism.

Proof. By construction.
$$\Box$$

 $\begin{array}{ll} \textbf{Corollary 4.4} \ \ (\text{semantic correctness}). \ \ \textit{If} \ \llbracket e \rrbracket_{\bot} : \mathsf{X} \leadsto_{\bot} \mathsf{Y}, \\ \textit{then } \mathsf{lift}_{\mathsf{map}} \ \llbracket e \rrbracket_{\bot} \equiv \llbracket e \rrbracket_{\mathsf{map}} \ \textit{and} \ \llbracket e \rrbracket_{\mathsf{map}} : \mathsf{X} \bowtie_{\mathsf{map}} \mathsf{Y}. \end{array}$

5. Lazy Preimage Mappings

On a computer, we will not often have the luxury of testing each function input to see whether it belongs to a preimage set. Even for finite domains, doing so is often intractable.

If we wish to compute with infinite sets in the language implementation, we will need an abstraction that makes it easy to replace computation on points with computation on sets. Therefore, in the preimage arrow, we will confine computation on points to *lazy preimage mappings*, or just *preimage mappings*. Further on, we will need their ranges to be observable, so we define their type as

$$X \xrightarrow{\text{pre}} Y ::= \langle \text{Set } Y, \text{Set } Y \Rightarrow \text{Set } X \rangle$$
 (27)

Converting a mapping to a lazy preimage mapping:

pre :
$$(X \rightarrow Y) \Rightarrow (X \xrightarrow{pre} Y)$$

pre g := let Y' := range g
 $p := \lambda B$. preimage g B
in $\langle Y', p \rangle$ (28)

Applying a preimage mapping to any subset of its codomain:

The necessary property here is that using pre-ap to compute preimages is the same as computing them from a mapping using preimage.

Lemma 5.1. Let $g \in X \rightharpoonup Y$. For all $B \subseteq Y$ and Y' such that range $g \subseteq Y' \subseteq Y$, preimage $g (B \cap Y') = \text{preimage } g B$.

Theorem 5.2 (pre-ap computes preimages). Let $g \in X \rightharpoonup Y$. For all $B \subseteq Y$, pre-ap (pre g) $B = \text{preimage } g \ B$.

Proof. Expand definitions and apply Lemma 5.1 with $\mathsf{Y}'=\mathsf{range}\;\mathsf{g}.$

Figure 5 defines more operations on preimage mappings, including pairing, composition, and disjoint union operations corresponding to the mapping operations in Figure 1. The next three theorems establish that pre is a homomorphism (though not an arrow homomorphism): it distributes over mapping operations to yield preimage mapping operations. We will use these facts to derive the preimage arrow from the mapping arrow.

First, we need a new notion of equivalence.

Definition 5.3. Two preimage mappings $h_1: X \xrightarrow[pritop]{} Y$ and $h_2: X \xrightarrow[pritop]{} Y$ are equivalent, or $h_1 \equiv h_2$, when pre-ap $h_1 B = pre$ -ap $h_2 B$ for all $B \subseteq Y$.

XXX: define equivalence in terms of equivalence, check observational equivalence in the proofs (specifically divergence)

5.1 Preimage Mapping Pairing

XXX: moar wurds in this section

6

Lemma 5.4 (preimage distributes over $\langle \cdot, \cdot \rangle_{map}$ and (\times)). Let $g_1 \in X \rightharpoonup Y_1$ and $g_2 \in X \rightharpoonup Y_2$. For all $B_1 \subseteq Y_1$ and $B_2 \subseteq Y_2$, preimage $\langle g_1, g_2 \rangle_{map}$ $(B_1 \times B_2) = (preimage \ g_1 \ B_1) \cap (preimage \ g_2 \ B_2)$.

Theorem 5.5 (pre distributes over $\langle \cdot, \cdot \rangle_{map}$). Let $g_1 \in X \rightarrow Y_1$ and $g_2 \in X \rightarrow Y_2$. Then pre $\langle g_1, g_2 \rangle_{map} \equiv \langle \text{pre } g_1, \text{pre } g_2 \rangle_{pre}$.

```
\begin{array}{lll} X \underset{\overline{pre}}{\rightharpoonup} Y ::= \langle Set \ Y, Set \ Y \Rightarrow Set \ X \rangle & \langle \cdot, \cdot \rangle_{pre} : (X \underset{\overline{pre}}{\rightharpoonup} Y_1) \Rightarrow (X \underset{\overline{pre}}{\rightharpoonup} Y_2) \Rightarrow (X \underset{\overline{pre}}{\rightharpoonup} Y_1 \times Y_2) \\ & \langle (Y_1', p_1), (Y_2', p_2) \rangle_{pre} := let \ Y' := Y_1' \times Y_2' \\ & p := \lambda B. \bigcup_{(b_1, b_2) \in B} (p_1 \ \{b_1\}) \cap (p_2 \ \{b_2\}) \\ & pre-ap : (X \underset{\overline{pre}}{\rightharpoonup} Y) \Rightarrow Set \ Y \Rightarrow Set \ X \\ & pre-ap \ \langle Y', p \rangle \ B := p \ (B \cap Y') & \langle (Y_1', p_1), (Y_2', p_2) \rangle_{pre} := let \ Y' := Y_1' \times Y_2' \\ & p := \lambda B. \bigcup_{(b_1, b_2) \in B} (p_1 \ \{b_1\}) \cap (p_2 \ \{b_2\}) \\ & (o_{pre}) : (Y \underset{\overline{pre}}{\rightharpoonup} Z) \Rightarrow (X \underset{\overline{pre}}{\rightharpoonup} Y) \Rightarrow (X \underset{\overline{pre}}{\rightharpoonup
```

Figure 5: Lazy preimage mappings and operations.

7

Proof. Let $\langle Y_1', p_1 \rangle := pre \ g_1$ and $\langle Y_2', p_2 \rangle := pre \ g_2$. Starting from the right side, for all $B \in Y_1 \times Y_2$,

5.2 Preimage Mapping Composition

XXX: moar wurds in this section

Lemma 5.6 (preimage distributes over (\circ_{map})). Let $g_1 \in X \rightharpoonup Y$ and $g_2 \in Y \rightharpoonup Z$. For all $C \subseteq Z$, preimage $(g_2 \circ_{map} g_1)$ $C = preimage <math>g_1$ (preimage g_2 C).

Theorem 5.7 (pre distributes over (\circ_{map})). Let $g_1 \in X \rightharpoonup Y$ and $g_2 \in Y \rightharpoonup Z$. Then pre $(g_2 \circ_{map} g_1) \equiv (pre g_2) \circ_{pre} (pre g_1)$.

Proof. Let $\langle Z',p_2\rangle:=pre\ g_2.$ Starting from the right side, for all $C\subseteq Z,$

$$\begin{array}{ll} \mathsf{pre-ap} \; ((\mathsf{pre} \; \mathsf{g}_2) \circ_{\mathsf{pre}} (\mathsf{pre} \; \mathsf{g}_1)) \; \mathsf{C} \\ &= \; \mathsf{let} \; \; \mathsf{h} := \lambda \, \mathsf{C}. \, \mathsf{pre-ap} \; (\mathsf{pre} \; \mathsf{g}_1) \; (\mathsf{p}_2 \; \mathsf{C}) \\ &= \; \mathsf{n} \; \mathsf{h} \; (\mathsf{C} \cap \mathsf{Z}') \\ &= \; \mathsf{pre-ap} \; (\mathsf{pre} \; \mathsf{g}_1) \; (\mathsf{p}_2 \; (\mathsf{C} \cap \mathsf{Z}')) \\ &= \; \mathsf{pre-ap} \; (\mathsf{pre} \; \mathsf{g}_1) \; (\mathsf{pre-ap} \; (\mathsf{pre} \; \mathsf{g}_2) \; \mathsf{C}) \\ &= \; \mathsf{preimage} \; \mathsf{g}_1 \; (\mathsf{preimage} \; \mathsf{g}_2 \; \mathsf{C}) \\ &= \; \mathsf{preimage} \; (\mathsf{g}_2 \circ_{\mathsf{map}} \mathsf{g}_1) \; \mathsf{C} \\ &= \; \mathsf{pre-ap} \; (\mathsf{pre} \; (\mathsf{g}_2 \circ_{\mathsf{map}} \mathsf{g}_1)) \; \mathsf{C} \end{array}$$

5.3 Preimage Mapping Disjoint Union

XXX: moar wurds in this section

Lemma 5.8 (preimage distributes over (\uplus_{map})). Let $g_1 \in X \rightharpoonup Y$ and $g_2 \in X \rightharpoonup Y$ be disjoint mappings. For all $B \subseteq Y$, preimage $(g_1 \uplus_{map} g_2)$ $B = (preimage <math>g_1 B) \uplus (preimage g_2 B)$.

Theorem 5.9 (pre distributes over (\uplus_{map})). Let $g_1 \in X \rightharpoonup Y$ and $g_2 \in X \rightharpoonup Y$ have disjoint domains. Then pre $(g_1 \uplus_{map} g_2) \equiv (pre g_1) \uplus_{pre} (pre g_2)$.

Proof. Let $Y_1' := range g_1$ and $Y_2' := range g_2$. Starting from the right side, for all $B \subseteq Y$,

$$\begin{array}{ll} \mathsf{pre-ap} \; ((\mathsf{pre} \; g_1) \; \uplus_{\mathsf{pre}} \; (\mathsf{pre} \; g_2)) \; \mathsf{B} \\ &= \; \mathsf{let} \; \mathsf{Y}' := \mathsf{Y}_1' \cup \mathsf{Y}_2' \\ &\; \; \mathsf{h} \; := \; \mathsf{\lambda} \, \mathsf{B}. \; (\mathsf{pre-ap} \; (\mathsf{pre} \; g_1) \; \mathsf{B}) \; \uplus \; (\mathsf{pre-ap} \; (\mathsf{pre} \; g_2) \; \mathsf{B}) \\ &\; \mathsf{in} \; \; \mathsf{h} \; (\mathsf{B} \cap \mathsf{Y}') \\ &= \; (\mathsf{pre-ap} \; (\mathsf{pre} \; g_1) \; (\mathsf{B} \cap (\mathsf{Y}_1' \cup \mathsf{Y}_2'))) \; \uplus \\ &\; \; (\mathsf{pre-ap} \; (\mathsf{pre} \; g_2) \; (\mathsf{B} \cap (\mathsf{Y}_1' \cup \mathsf{Y}_2'))) \\ &= \; (\mathsf{preimage} \; g_1 \; (\mathsf{B} \cap (\mathsf{Y}_1' \cup \mathsf{Y}_2'))) \; \uplus \\ &\; \; (\mathsf{preimage} \; g_2 \; (\mathsf{B} \cap (\mathsf{Y}_1' \cup \mathsf{Y}_2'))) \\ &= \; \mathsf{preimage} \; (g_1 \; \uplus_{\mathsf{map}} \; g_2) \; (\mathsf{B} \cap (\mathsf{Y}_1' \cup \mathsf{Y}_2')) \\ &= \; \mathsf{preimage} \; (g_1 \; \uplus_{\mathsf{map}} \; g_2) \; \mathsf{B} \\ &= \; \mathsf{pre-ap} \; (\mathsf{pre} \; (g_1 \; \uplus_{\mathsf{map}} \; g_2)) \; \mathsf{B} \end{array}$$

6. Deriving the Preimage Arrow

XXX: intro

$$X \underset{\text{pre}}{\leadsto} Y ::= \text{Set } X \Rightarrow (X \underset{\text{pre}}{\leadsto} Y)$$
 (30)

$$\begin{aligned} & \mathsf{lift}_{\mathsf{pre}} : (\mathsf{X}_{\mathsf{map}} \, \mathsf{Y}) \Rightarrow (\mathsf{X}_{\mathsf{pre}} \, \mathsf{Y}) \\ & \mathsf{lift}_{\mathsf{pre}} \; \mathsf{g} \; \mathsf{A} \; := \; \mathsf{pre} \; (\mathsf{g} \; \mathsf{A}) \end{aligned} \tag{31}$$

Definition 6.1 (Preimage arrow equivalence). Two preimage arrow computations $h_1: X_{\widetilde{pre}} Y$ and $h_2: X_{\widetilde{pre}} Y$ are equivalent, or $h_1 \equiv h_2$, when $h_1 A \equiv h_2 A$ for all $A \subseteq X$.

As with $\mathsf{arr}_{\mathsf{map}}$, defining $\mathsf{arr}_{\mathsf{pre}}$ as a composition meets (14). The following subsections derive (\&&_{\mathsf{pre}}), (>>>_{\mathsf{pre}}), ifte_{\mathsf{pre}} and $\mathsf{lazy}_{\mathsf{pre}}$ from their corresponding mapping arrow combinators,

Figure 6: Preimage arrow definitions.

in a way that ensures $lift_{pre}$ is an arrow homomorphism from the mapping arrow to the preimage arrow. Figure 6 contains the resulting definitions.

6.1 Case: Pairing

Starting with the left side of (16), we expand definitions, apply Theorem 5.5, and rewrite in terms of lift_{pre}:

$$\begin{array}{l} \text{pre-ap (lift}_{\text{pre}} \; (g_1 \; \&\&\&_{\text{map}} \; g_2) \; A) \; B \\ & \equiv \; \text{pre-ap (pre} \; \langle g_1 \; A, g_2 \; A \rangle_{\text{map}}) \; B \\ & \equiv \; \text{pre-ap (pre} \; (g_1 \; A), \text{pre} \; (g_2 \; A) \rangle_{\text{pre}} \; B \\ & \equiv \; \text{pre-ap (lift}_{\text{pre}} \; g_1 \; A, \text{lift}_{\text{pre}} \; g_2 \; A \rangle_{\text{pre}} \; B \end{array}$$

Substituting h_1 for lift_{pre} g_1 and h_2 for lift_{pre} g_2 , and removing the application of pre-ap from both sides of the equivalence gives a definition of (&&pre) (Figure 6) for which (16) holds.

6.2 Case: Composition

Starting with the left side of (15), we expand definitions, apply Theorem 5.7 and rewrite in terms of lift_{pre}:

$$\begin{array}{lll} \text{pre-ap (lift}_{\text{pre}} \; (g_1 \ggg_{\text{map}} g_2) \; A) \; C \\ & \equiv \; \text{let} \; \; g_1' \; := \; g_1 \; A \\ & \; \; \; g_2' \; := \; g_2 \; (\text{range} \; g_1') \\ & \; \; \; \text{in pre-ap (pre } (g_2' \circ_{\text{map}} g_1')) \; C \\ & \equiv \; \text{let} \; \; g_1' \; := \; g_1 \; A \\ & \; \; \; g_2' \; := \; g_2 \; (\text{range} \; g_1') \\ & \; \; \text{in pre-ap ((pre \; g_1') \circ_{\text{pre}} (\text{pre} \; g_2'))} \; C \\ & \equiv \; \text{let} \; \; h_1 \; := \; \text{lift}_{\text{pre}} \; g_1 \; A \\ & \; \; h_2 \; := \; \text{lift}_{\text{pre}} \; g_2 \; (\text{pre-range} \; h_1) \\ & \; \; \text{in pre-ap (} h_2 \circ_{\text{pre}} h_1) \; C \\ \end{array} \tag{32}$$

Substituting h_1 for lift_{pre} g_1 and h_2 for lift_{pre} g_2 , and removing the application of pre-ap from both sides of the equivalence gives a definition of (\gg_{pre}) (Figure 6) for which (15) holds.

6.3 Case: Conditional

Starting with the left side of (17), we expand terms, apply Theorem 5.9, rewrite in terms of lift_{pre}, and apply Theo-

rem 5.2 in the definitions of h_2 and h_3 :

$$\begin{array}{l} \text{pre-ap (lift}_{\text{pre}} \text{ (ifte}_{\text{map}} \ g_1 \ g_2 \ g_3) \ A) \ B} \\ \equiv \text{ let } \ g_1' := g_1 \ A \\ \qquad g_2' := g_2 \text{ (preimage } g_1' \text{ {true}}) \\ \qquad g_3' := g_3 \text{ (preimage } g_1' \text{ {false}}) \\ \qquad \text{in pre-ap (pre } (g_2' \uplus_{\text{map}} g_3')) \ B} \\ \equiv \text{ let } \ g_1' := g_1 \ A \\ \qquad g_2' := g_2 \text{ (preimage } g_1' \text{ {true}}) \\ \qquad g_3' := g_3 \text{ (preimage } g_1' \text{ {false}}) \\ \qquad \text{in pre-ap ((pre } g_2') \uplus_{\text{pre}} \text{ (pre } g_3')) \ B} \\ \equiv \text{ let } \ h_1 := \text{ lift}_{\text{pre}} \ g_1 \ A \\ \qquad h_2 := \text{ lift}_{\text{pre}} \ g_2 \text{ (pre-ap } h_1 \text{ {true}}) \\ \qquad h_3 := \text{ lift}_{\text{pre}} \ g_3 \text{ (pre-ap } h_1 \text{ {false}}) \\ \qquad \text{in pre-ap (} \ h_2 \uplus_{\text{pre}} \ h_3 \text{) B} \end{array}$$

Substituting h_1 for lift_{pre} g_1 , h_2 for lift_{pre} g_2 and h_3 for lift_{pre} g_3 , and removing the application of pre-ap from both sides of the equivalence gives a definition of ifte_{pre} (Figure 6) for which (17) holds.

6.4 Case: Laziness

Starting with the left side of (18), expand definitions, distribute pre over the branches of if, and rewrite in terms of lift_{pre} $(g\ 0)$:

$$\begin{array}{l} \mathsf{pre\text{-}ap} \; (\mathsf{lift}_{\mathsf{pre}} \; (\mathsf{lazy}_{\mathsf{map}} \; \mathsf{g}) \; \mathsf{A}) \; \mathsf{B} \\ \equiv \; \mathsf{let} \; \; \mathsf{g}' \; := \; \mathsf{if} \; (\mathsf{A} = \varnothing) \; \varnothing \; (\mathsf{g} \; \mathsf{0} \; \mathsf{A}) \\ \qquad \qquad \mathsf{in} \; \; \mathsf{pre\text{-}ap} \; (\mathsf{pre} \; \mathsf{g}') \; \mathsf{B} \\ \equiv \; \mathsf{let} \; \; \mathsf{h} \; := \; \mathsf{if} \; (\mathsf{A} = \varnothing) \; (\mathsf{pre} \; \varnothing) \; (\mathsf{pre} \; (\mathsf{g} \; \mathsf{0} \; \mathsf{A})) \\ \qquad \qquad \mathsf{in} \; \; \mathsf{pre\text{-}ap} \; \mathsf{h} \; \mathsf{B} \\ \equiv \; \mathsf{let} \; \; \mathsf{h} \; := \; \mathsf{if} \; (\mathsf{A} = \varnothing) \; (\mathsf{pre} \; \varnothing) \; (\mathsf{lift}_{\mathsf{pre}} \; (\mathsf{g} \; \mathsf{0}) \; \mathsf{A}) \\ \qquad \qquad \mathsf{in} \; \; \mathsf{pre\text{-}ap} \; \mathsf{h} \; \mathsf{B} \end{array}$$

Substituting h 0 for lift_{pre} (g 0) and removing the application of pre-ap from both sides of the equivalence gives a definition for lazy_{pre} (Figure 6) for which (18) holds.

6.5 Correctness

8

Theorem 6.2 (preimage arrow correctness). lift_{pre} is an arrow homomorphism.

Corollary 6.3 (semantic correctness). *If* $\llbracket e \rrbracket_{\mathsf{map}} : \mathsf{X}_{\stackrel{\sim}{\mathsf{map}}} \mathsf{Y}$, then $\mathsf{lift}_{\mathsf{pre}} \ \llbracket e \rrbracket_{\mathsf{map}} \equiv \llbracket e \rrbracket_{\mathsf{pre}} \ and \ \llbracket e \rrbracket_{\mathsf{pre}} : \mathsf{X}_{\stackrel{\sim}{\mathsf{pre}}} \mathsf{Y}$.

In particular, $[\![e]\!]_{\sf pre}$ correctly computes preimages under the interpretation of e as a function from a random source.

7. Preimages Under Partial Functions

Probabilistic functions that may diverge, but converge with probability 1, are common. They come up not only when practitioners want to build data with random size or structure, but in simpler circumstances as well.

Suppose random retrieves a number $r j \in [0,1]$ from a uniform random source r. The following recursive function, which defines the well-known **geometric distribution** with parameter p, counts the number of times random < p is false:

geometric
$$p := if (random < p) 0 (1 + geometric p)$$
 (33)

For any p>0, geometric p may diverge, but the probability of always taking the false branch is $(1-p)\times(1-p)\times(1-p)\times\cdots=0$. Divergence with probability 0 simply does not happen in practice.

Suppose we interpret (33) as $h:R_{\widetilde{PR}}\mathbb{N}$, a preimage arrow computation from random sources in R to natural numbers, and that we have a probability measure $P\in\mathcal{P}$ $R\to[0,1]$. We could compute the probability of any output set $N\subseteq\mathbb{N}$ using P (h R' N), where R' \subseteq R and P R' = 1. We have three hurdles to overcome:

- 1. Ensuring h R' converges.
- 2. Ensuring each $r \in R$ contains enough random numbers.
- 3. Determining how random indexes numbers in r.

Ensuring h R' converges is the most difficult, but doing the other two will provide structure that makes it much easier.

7.1 Threading and Indexing

We clearly need a new arrow that threads a random source through its computations. To ensure it contains enough random numbers, the source should be infinite.

In a pure λ -calculus, random sources are typically infinite streams, threaded monadically: each computation receives and produces a random source. A new combinator is defined that removes the head of the random source and passes the tail along. This is likely preferred because pseudorandom number generators are almost universally monadic.

A little-used alternative is for the random source to be a tree, threaded applicatively: each computation receives, but does not produce, a random source. Multi-argument combinators split the tree and pass sub-trees to sub-computations.

We have tried both ways with arrows defined using pairing. The resulting definitions are large, making them conceptually difficult and hard to manipulate. Fortunately, assigning each sub-computation a unique index into a tree-shaped random source, and passing it unchanged, is relatively easy.

We need a way to assign unique indexes to expressions.

Definition 7.1 (binary indexing scheme). Let J be an index set, $j_0 \in J$ a distinguished element, and left: $J \Rightarrow J$ and right: $J \Rightarrow J$ be total functions. These define a binary indexing scheme if

- Every finite composition next of left and right is injective.
- For all $j \in J$, $j = next j_0$ for some finite composition next.

For example, let J be the set of lists of $\{0,1\},\ j_0:=\langle\rangle,$ and left $j:=\langle0,j\rangle$ and right $j:=\langle1,j\rangle.$

Alternatively, let J be the set of dyadic rationals in (0,1) (i.e. those with power-of-two denominators), $j_0 := \frac{1}{2}$ and

left
$$(p/q) := (p - \frac{1}{2})/q$$

right $(p/q) := (p + \frac{1}{2})/q$ (34)

With this alternative, left-to-right evaluation order can be made to correspond with the natural order (<) over J.

In any case, J is always countable.

7.2 Applicative, Associative Store

XXX: **arrow transformer**: an arrow whose combinators are defined entirely in terms of another arrow

XXX: computations receive an index and return an arrow from a store of type s paired with x, to y:

AStore s
$$(x \leadsto_a y) ::= J \Rightarrow (\langle s, x \rangle \leadsto_a y)$$
 (35)

XXX: motivational wurds for definition of lift:

$$\eta_{\mathsf{a}^*} : (\mathsf{x} \leadsto_{\mathsf{a}} \mathsf{y}) \Rightarrow \mathsf{AStore} \ \mathsf{s} \ (\mathsf{x} \leadsto_{\mathsf{a}} \mathsf{y})$$

$$\eta_{\mathsf{a}^*} \ \mathsf{f} \ \mathsf{j} \ := \ \mathsf{arr}_{\mathsf{a}} \ \mathsf{snd} \ggg_{\mathsf{a}} \mathsf{f}$$
(36)

Figure 7 defines the AStore arrow transformer. As with the other arrows, proving that its lift is a homomorphism allows us to prove that programs interpreted as its computations are correct. Again, to do so, we need to extend equivalence to be more extensional for arrows AStore s ($x \leadsto_a y$).

Definition 7.2 (AStore arrow equivalence). Two AStore arrow computations k_1 and k_2 are equivalent, or $k_1 \equiv k_2$, when $k_1 j \equiv k_2 j$ for all $j \in J$.

XXX: need to define equivalence for the bottom arrow for this to make sense

Theorem 7.3 (AStore arrow correctness). Let $x \leadsto_{a^*} y ::= AStore s (x \leadsto_a y)$. Then η_{a^*} is an arrow homomorphism.

Proof. Defining arr_{a^*} as a composition clearly meets the first homomorphism identity (14).

Composition. Starting with the right side of (15), expand definitions and use (arr_a f &&&_a f_1) >>>>_a arr_a snd $\equiv f_1$:

$$\begin{array}{l} (\eta_{a^*} \ f_1 \ggg_{a^*} \ \eta_{a^*} \ f_2) \ j \\ & \equiv \ (\mathsf{arr_a} \ \mathsf{fst} \ \&\&\&_a \ (\mathsf{arr_a} \ \mathsf{snd} \ \ggg_a \ f_1)) \ggg_a \ \mathsf{arr_a} \ \mathsf{snd} \ \ggg_a \ f_2 \\ & \equiv \ \mathsf{arr_a} \ \mathsf{snd} \ \ggg_a \ f_1 \ggg_a \ f_2 \\ & \equiv \ \eta_{a^*} \ (\mathsf{f_1} \ggg_a \ \mathsf{f_2}) \ j \end{array}$$

Pairing. Starting with the right side of (16), expand definitions and use the arrow law arra f $\ggg_a (f_1 \&\&\&_a f_2) \equiv (arr_a f \ggg_a f_1) \&\&\&_a (arra f \ggg_a f_2)$:

$$\begin{array}{l} \left(\eta_{a^*} \ f_1 \ \&\&\&_{a^*} \ \eta_{a^*} \ f_2\right) \ j \\ & \equiv \ \left(\text{arr}_a \ \text{snd} \ >\!\!>>_a \ f_1\right) \ \&\&\&_a \ \left(\text{arr}_a \ \text{snd} \ >\!\!>>_a \ f_2\right) \\ & \equiv \ \text{arr}_a \ \text{snd} \ >\!\!>>_a \ \left(f_1 \ \&\&\&_a \ f_2\right) \\ & \equiv \ \eta_{a^*} \ \left(f_1 \ \&\&\&_a \ f_2\right) \ j \end{array}$$

Conditional. Starting with the right side of (17), expand definitions and use the arrow law arr_a $f \gg a$ ifte_a $f_1 f_2 f_3 \equiv$ ifte_a (arr_a $f \gg a f_1$) (arr_a $f \gg a f_2$) (arr_a $f \gg a f_3$):

2013/7/22

9

Figure 7: AStore (associative store) arrow transformer definitions.

Laziness. Starting with the right side of (18), expand definitions, β -expand within the outer thunk, and use the arrow law arra f >>>>a lazya f₁ \equiv lazya λ 0. arra f >>>>a f₁ 0:

XXX: all of these rely on arrow laws that aren't proved for the mapping and preimage arrows \Box

Corollary 7.4 (semantic correctness). Let $x \leadsto_{a^*} y ::= AS$ tore s $(x \leadsto_a y)$. If $\llbracket e \rrbracket_a : x \leadsto_a y$, then $\eta_{a^*} \ \llbracket e \rrbracket_a \equiv \llbracket e \rrbracket_{a^*}$ and $\llbracket e \rrbracket_{a^*} : x \leadsto_{a^*} y$.

In particular, Corollary 7.4 implies that, if a pure let-calculus expression is interpreted as a computation k: AStore S (X $_{\widehat{\text{pre}}}\,Y)$, then k jo correctly computes preimages. We still need to know that preimages under functions that access the store are computed correctly, which we will get to after defining stores and combinators that access them.

7.3 Probabilistic Programs

Definition 7.5 (random source). Let $R := J \rightarrow [0,1]$. A random source is a total mapping $r \in R$; equivalently, an infinite vector of random numbers indexed by J.

Let $x \leadsto_{a^*} y := \mathsf{AStore}\ \mathsf{R}\ (x \leadsto_a y).$ The following combinator returns the number at its own index in the random source:

We extend the let-calculus semantic function with

$$[random]_{a^*} :\equiv random_{a^*}$$
 (38)

for arrows a^* for which $random_{a^*}$ is defined.

7.4 Partial Programs

The most effective and ultimately implementable way we have found to avoid divergence in computing preimages is to use the store to dictate which branch of each conditional, if any, is allowed to be taken.

Definition 7.6 (branch trace). A branch trace is a total mapping (i.e. vector) $t \in J \to \mathsf{Bool}_\perp$ such that $t \ j = \mathsf{true}$ or $t \ j = \mathsf{false}$ for no more than finitely many $j \in J$.

Let $T \subset J \to \mathsf{Bool}_{\perp}$ be the set of all branch traces, and $x \leadsto_{\mathsf{a}^*} y ::= \mathsf{AStore}\ T\ (x \leadsto_{\mathsf{a}} y)$. The following combinator returns $t\ j$ using its own index j:

branch_{a*} :
$$x \leadsto_{a^*} Bool$$

branch_{a*} $j := arr_a \text{ (fst } \ggg \pi \text{ j)}$

Using $branch_{a^*}$, we define an additional if-then-else combinator, which ensures its conditional expression agrees with the branch trace:

$$\begin{split} \mathsf{agrees} : \langle \mathsf{Bool}, \mathsf{Bool} \rangle \Rightarrow \mathsf{Bool}_{\perp} \\ \mathsf{agrees} \; \langle \mathsf{b}_1, \mathsf{b}_2 \rangle \; := \; \mathsf{if} \; \big(\mathsf{b}_1 = \mathsf{b}_2 \big) \; \mathsf{b}_1 \; \bot \end{split} \tag{40}$$

$$\begin{split} & \text{ifte}_{a^*}^{'}: (\mathsf{x} \leadsto_{\mathsf{a}^*} \mathsf{Bool}) \Rightarrow (\mathsf{x} \leadsto_{\mathsf{a}^*} \mathsf{y}) \Rightarrow (\mathsf{x} \leadsto_{\mathsf{a}^*} \mathsf{y}) \Rightarrow (\mathsf{x} \leadsto_{\mathsf{a}^*} \mathsf{y}) \\ & \text{ifte}_{a^*}^{'} \ k_1 \ k_2 \ k_3 \ := \\ & \text{ifte}_{\mathsf{a}^*} \ ((\mathsf{k}_1 \&\&\&_{\mathsf{a}^*} \mathsf{branch}_{\mathsf{a}^*}) \ggg_{\mathsf{a}^*} \mathsf{arr}_{\mathsf{a}^*} \mathsf{agrees}) \ k_2 \ k_3 \end{split}$$

If the branch trace agrees with the conditional expression, it computes a branch; otherwise, it returns an error.

Every computation defined using the let-calculus semantic function $\llbracket \cdot \rrbracket_a$, whose defining expression converges, must have its recurrences guarded by an if. Thus, if we stick to well-defined let-calculus programs, we need only replace ifte_{a*} with ifte'_{a*} to ensure computations always converge. Therefore, we can define a semantic function $\llbracket \cdot \rrbracket'_{a*}$ for let-calculus programs whose computations always converge by overriding only the if rule:

$$\begin{aligned}
& [\text{if } e_c \ e_t \ e_f]|_{\mathsf{a}^*}' \ :\equiv \ & [\text{ifte}_{\mathsf{a}^*}' \ [e_c]|_{\mathsf{a}^*} \\
& ([\mathsf{lazy}_{\mathsf{a}} \ \lambda 0. \ [e_t]]_{\mathsf{a}^*}) \\
& ([\mathsf{azy}_{\mathsf{a}} \ \lambda 0. \ [e_f]]_{\mathsf{a}^*}) \end{aligned} \tag{42}$$

7.5 Partial, Probabilistic Programs

Let $S ::= R \times T$ and $x \leadsto_{a^*} y ::= AStore S$ $(x \leadsto_a y)$, and update the $random_{a^*}$ and $branch_{a^*}$ combinators to reflect

that the store is now a pair:

random_{a*} :
$$x \leadsto_{a^*} [0,1]$$

random_{a*} $j := arr_a (fst \ggg fst \ggg \pi j)$ (43)

branch_{a*} :
$$x \leadsto_{a^*} Bool$$

branch_{a*} $j := arr_a (fst \ggg snd \ggg \pi j)$ (44)

The ifte' combinator's definition remains the same.

From here on, let $x \leadsto_{i} y ::= \mathsf{AStore} \mathsf{S}(x \leadsto_{\perp} y)$; similarly for $X_{\stackrel{\leadsto}{map*}} Y$ and $X_{\stackrel{\leadsto}{pre*}} Y$.

7.6 Correctness

Theorem 7.7 (natural transformation). Let $x \leadsto_{a^*} y ::=$ AStore s (x \leadsto_a y) and x \leadsto_{b^*} y ::= AStore s (x \leadsto_{b^*} y). Let lift_b: $(x \leadsto_a y) \Rightarrow (x \leadsto_b y)$ be an arrow homomorphism, and

$$\begin{aligned} & \text{lift}_{b^*} : (\mathsf{x} \leadsto_{\mathsf{a}^*} \mathsf{y}) \Rightarrow (\mathsf{x} \leadsto_{\mathsf{b}^*} \mathsf{y}) \\ & \text{lift}_{b^*} \mathsf{f} \mathsf{j} := \mathsf{lift}_{\mathsf{b}} \mathsf{(f} \mathsf{j}) \end{aligned} \tag{45}$$

The following diagram commutes:

 $\mbox{i.e. for all } f: x \leadsto_a y, \ \eta_{b^*} \ \mbox{(lift}_b \ f) \equiv \mbox{lift}_{b^*} \ \mbox{(η_{a^*} f). Further},$ lift_{b*} is an arrow homomorphism.

Proof. Starting from the right side of the equivalence, expand definitions and apply homomorphism identities (15) and (14) for lift_b:

$$\begin{split} \mathsf{lift_{b^*}} \; (\eta_{\mathsf{a^*}} \; \mathsf{f}) \; &\equiv \; \lambda \mathsf{j.} \, \mathsf{lift_b} \; (\mathsf{arr_a} \; \mathsf{snd}) \ggg_{\mathsf{b}} \mathsf{lift_b} \; \mathsf{f} \\ &\equiv \; \lambda \mathsf{j.} \, \mathsf{lift_b} \; (\mathsf{arr_a} \; \mathsf{snd}) \ggg_{\mathsf{b}} \mathsf{lift_b} \; \mathsf{f} \\ &\equiv \; \lambda \mathsf{j.} \, \mathsf{arr_b} \; \mathsf{snd} \ggg_{\mathsf{b}} \mathsf{lift_b} \; \mathsf{f} \\ &\equiv \; \eta_{\mathsf{b^*}} \; (\mathsf{lift_b} \; \mathsf{f}) \end{split}$$

Further, because η_{a^*} , η_{b^*} , and lift are homomorphisms, lift is a homomorphism by composition.

XXX: not sure I'm allowed to invoke converse of composition of homomorphisms without extra conditions

Corollary 7.8 (mapping* and preimage* arrow correctness). The following diagram commutes:

Further, lift_{map*} and lift_{pre*} are arrow homomorphisms.

Corollary 7.9 (semantic correctness). If $[e]_{+}$: $X \leadsto_{\perp} Y$, then $\operatorname{lift}_{\mathsf{map}^*} \ \llbracket e \rrbracket_{\perp^*} \equiv \llbracket e \rrbracket_{\mathsf{map}^*} \ and \ \operatorname{lift}_{\mathsf{pre}^*} \ \llbracket e \rrbracket_{\mathsf{map}^*} \equiv \llbracket e \rrbracket_{\mathsf{pre}^*}.$

Corollary 7.10 (semantic' correctness). If $[e]'_{+*} : X \leadsto_{\perp^*} Y$, then $\operatorname{lift_{map^*}} \ [\![e]\!]_{\perp^*}' \equiv [\![e]\!]_{\operatorname{map^*}}' \ and \ \operatorname{lift_{pre^*}}' [\![e]\!]_{\operatorname{map^*}}' \equiv [\![e]\!]_{\operatorname{pre^*}}'$

In particular, $[\![e]\!]_{\mathsf{pre}^*}$ and $[\![e]\!]'_{\mathsf{pre}^*}$ correctly compute preimages under the interpretation of e as a function from an implicit random source. We will make stronger statements about $[\cdot]_{\text{pre}^*}$ after proving its computations always converge.

Theorem 7.11 (divergence implies error). Let $f := [e]_{+}$ and $f' := [e]'_{\perp^*}$ converge, where $f : x \leadsto_{\perp^*} y$. For all $r \in \overline{R}$, $t \in T$ and a : x,

1. If $f(\langle r,t\rangle,a\rangle = b$, then $f'(\langle r,t'\rangle,a\rangle = b$ for some $t' \in T$. 2. If $f(\langle r,t\rangle,a\rangle)$ diverges, $f'(\langle r,t'\rangle,a\rangle) = \bot$ for all $t' \in T$.

Proof. Let $m : J \Rightarrow J$ invertibly map sub-computation indexes in f' to corresponding sub-computation indexes in f. (Defining m formally is tedious and unilluminating. XXX: check this)

Case 1. Define $t' \in J \to \mathsf{Bool}_{\perp}$ such that t' j = z if the sub-computation with index m j in f is an if condition that returns z, otherwise t' $j=\bot$. Because f $\langle\langle r,t\rangle,a\rangle$ converges, t' $j\ne\bot$ for at most finitely many j, so $t'\in T$. Exists t'.

Case 2. Let $t'\in T$. There exists an infinite suffix $J'\subset J$

closed under left and right, such that for all $j' \in J', t', j' = \bot$. Because $f(\langle r,t\rangle,a\rangle)$ diverges, the indexes of its if conditions are unbounded; there is therefore a condition with index j such that $m^{-1} \in J'$. It returns \bot , so $f' (\langle r, t' \rangle, a) = \bot$.

To compare preimages computed by arrow instances produced by $[\![\cdot]\!]_{\mathsf{pre}^*}$ and $[\![\cdot]\!]_{\mathsf{pre}^*}^7,$ we need a set of inputs on which they should obviously always agree.

Definition 7.12 (halting set). A computation's halting set is the largest $A^* \subseteq (R \times T) \times X$ for which

- $$\begin{split} \bullet \ \mathit{For} \ f : X \leadsto_{\underline{\,}^*} Y, \ f \ j_0 \ x \neq \bot \ \mathit{for} \ \mathit{all} \ x \in A^*. \\ \bullet \ \mathit{For} \ g : X_{\stackrel{\mathsf{map}^*}{ap^*}} Y, \ \mathsf{domain} \ (g \ j_0 \ A^*) = A^*. \end{split}$$
- For h: $X \xrightarrow[\text{pre}]{\text{res}} Y$, pre-ap (h j₀ A*) $Y = A^*$.

Recall truth statements like f j₀ x $\neq \perp$ imply convergence.

That $lift_{map^*}$ and $lift_{pre^*}$ are arrow homomorphisms allows transporting halting set definitions and theorems between arrow types.

Theorem 7.13 (halting set equality). Let $f: X \leadsto_{\perp^*} Y$, and $g: X_{\stackrel{\longrightarrow}{map^*}} Y \text{ and } h: X_{\stackrel{\longrightarrow}{pre^*}} Y \text{ such that } g \equiv \mathsf{lift}_{\mathsf{map}^*} \ \mathsf{f} \text{ and}$ $h \equiv lift_{pre^*}$ g. Then f, g and h have the same halting set.

 $\begin{array}{l} \textbf{Corollary 7.14 (computed halting set).} \ \ \mathit{Let} \ \llbracket e \rrbracket_{\underline{\bot}^*} : \mathsf{X} \leadsto_{\underline{\bot}^*} \mathsf{Y} \\ \mathit{converge.} \ \ \mathit{Then} \ \mathsf{A}^* = \mathsf{pre-ap} \ (\llbracket e \rrbracket'_{\mathsf{pre}^*} \ \ \mathsf{j_0} \ (\mathsf{S} \times \mathsf{X})) \ \mathsf{Y}. \end{array}$

 $\begin{array}{lll} \textbf{Corollary 7.15} & (\text{semantic correctness (final)}). & \textit{Let } \llbracket e \rrbracket_{\bot^*} : \\ X \leadsto_{\bot^*} Y & \textit{converge, with halting set } A^*. & \textit{For } A \subseteq X \textit{ and } B \subseteq Y, \end{array}$ pre-ap ($\llbracket e \rrbracket'_{\mathsf{pre}^*}$ j₀ A) B = preimage ($\llbracket e \rrbracket_{\mathsf{map}^*}$ j₀ (A \cap A*)) B.

In other words, preimages computed using $[\cdot]_{pre^*}'$ always converge, never include inputs that give rise to errors or divergence, and are correct.

Measurability 8.

We have not assigned probabilities to any sets yet.

Recall that, for a mapping $g: X \rightarrow Y$, the probability of an output set $\mathsf{B}\subseteq\mathsf{Y}$ is

$$P (preimage g B)$$
 (48)

where $P \in \mathcal{P} \times A \rightarrow [0,1]$ is a probability measure on X. This was the motivation for defining arrows to compute preimages in the first place. Note again that ${\sf P}$ is a partial function. We had left domain P, and which $B \subseteq Y$ have preimages in domain P, as technical conditions to be proved later. Now we determine those conditions.

To save space, we assume readers are familiar with either topology or measure theory. (Readers unfamiliar with both

may wish to skip to the next section.) Many concepts in measure theory can be understood by analogy to topology.

The analogue of a topology is a σ -algebra.

Definition 8.1 (σ -algebra, measurable set). A collection of sets $A \subseteq P X$ is called a σ -algebra on X if it contains Xand is closed under complements and countable unions. The sets in A are called measurable sets.

 $X\setminus X=\emptyset$, so $\emptyset\in\mathcal{A}$. Additionally, it follows from De Morgan's law that \mathcal{A} is closed under countable intersections. The analogue of continuity is measurability.

Definition 8.2 (measurable mapping). Let A and B be σ algebras respectively on X and Y. A mapping $g:X \rightharpoonup Y$ is A-B-measurable if for all $B \in \mathcal{B}$, preimage $g B \in \mathcal{A}$.

Measurability is usually a weaker condition than continuity. For example, with respect to the σ -algebra generated from \mathbb{R} 's standard topology, measurable $\mathbb{R} \to \mathbb{R}$ functions may have countably many discontinuities. Likewise, real equality and inequality functions are measurable.

Product spaces are defined the same way as in topology.

Definition 8.3 (finite product σ -algebra). Let A_1 and $\mathcal{A}_2 \ \textit{be} \ \sigma\textit{-algebras} \ \textit{on} \ X_1 \ \textit{and} \ X_2, \ \textit{and} \ X \ := \ \langle X_1, X_2 \rangle. \ \textit{The}$ **product** σ -algebra $A_1 \otimes A_2$ is the smallest σ -algebra for which mapping fst X and mapping snd X are measurable.

Definition 8.4 (arbitrary product σ -algebra). Let \mathcal{A} be a σ -algebra on X. The **product** σ -algebra $\mathcal{A}^{\otimes J}$ is the smallest σ -algebra for which, for all $j \in J$, mapping (πj) $(J \to X)$ is measurable.

8.1Measurable Pure Computations

It is easier to prove measurability of pure computations than to prove measurability of probabilistic ones. Further, we can use the resulting theorems to prove that probabilistic computations are measurable.

A single mapping arrow computation can produce many mappings, which, it seems, could complicate proving measurability. Fortunately, we need only consider the mapping produced when applying a computation to its halting set.

 $\begin{array}{ll} \textbf{Definition 8.5} \ \ (\text{halting set}). \ \ \textit{Let} \ g : X_{\stackrel{\text{wap}}{map}} Y. \ \textit{Its halting} \\ \textit{set is the largest} \ A^* \subseteq X \ \textit{for which } domain \ (g \ A^*) = A^*. \end{array}$

Definition 8.6 (measurable mapping arrow computation). Let A and B be σ -algebras on X and Y. A computation $g: X\underset{\text{\tiny map}}{\leadsto} Y \text{ is \mathcal{A}-\mathcal{B}-} \textbf{\textit{measurable}} \text{ if } g \text{ } A^* \text{ is an \mathcal{A}-\mathcal{B}-} \textbf{\textit{measurable}}$ mapping, where A^* is g's halting set.

The definition of halting set implies preimage (g A^*) Y = A^* . Because $Y \in \mathcal{B}$, $A^* \in \mathcal{A}$.

Lemma 8.7. Let $g: X \rightarrow Y$ be an A- \mathcal{B} -measurable mapping. For any $A \in \mathcal{A}$, restrict g A is A-B-measurable.

Theorem 8.8. Let $g: X_{\stackrel{\leadsto}{map}} Y$ be an A-B-measurable mapping arrow computation. Then for all $A \in \mathcal{A}$, g A is an A-B-measurable mapping.

Proof. Use the mapping arrow restriction law (20) and Lemma 8.7.

Roughly, if the largest mapping that can be produced by a computation is measurable, any mapping it can produce that we care about is measurable.

That all programs interpreted by $[\![\cdot]\!]_a$ are measurable will be proved by structural induction. We therefore need a case for each arrow combinator.

8.1.1 Case: Composition

Proving compositions are measurable takes the most work. The main complication is that, under measurable mappings, while preimages of measurable sets are measurable, images of measurable sets may not be. We need the following four extra theorems to get around this.

Lemma 8.9 (images of preimages). Let $g: X \rightarrow Y$ and $B \subseteq Y$. Then image g (preimage g B) $\subseteq B$.

 $\begin{array}{l} \textbf{Lemma 8.10} \; (\text{expanded post-composition}). \; \mathit{Let} \; g_1 : X \rightharpoonup Y \\ \mathit{and} \; g_2 : Y \rightharpoonup Z \; \mathit{such that} \; \mathsf{range} \; g_1 \subseteq \mathsf{domain} \; g_2, \; \mathit{and let} \\ g_2' : Y \rightharpoonup Z \; \mathit{such that} \; g_2 \subseteq g_2'. \; \mathit{Then} \; g_2 \circ_{\mathsf{map}} g_1 = g_2' \circ_{\mathsf{map}} g_1. \end{array}$

Theorem 8.11 (mapping arrow monotonicity). Let g: $X \underset{\text{map}}{\longleftrightarrow} Y$. For any $A \subseteq X$, domain $(g \ A) \subseteq A$. For any $A' \subseteq A$, $g \ A' \subseteq g \ A$.

 $\begin{array}{lll} \textbf{Theorem 8.12} & (\text{halting subsets}). & \textit{Let } g : X_{\stackrel{\leadsto}{\text{map}}}Y & \textit{with} \\ \textit{halting set } A^*. & \textit{For any } A \subseteq A^*, \ domain \ (g \ A) = A. \end{array}$

Proof. Use the mapping arrow restriction law (20).

Now we can prove measurability.

Lemma 8.13 (measurability under \circ_{map}). If $g_1: X \rightharpoonup Y$ is A-B-measurable and $g_2: Y \rightharpoonup Z$ is B-C-measurable, then $g_2 \circ_{map} g_1$ is A-C-measurable.

 $\begin{array}{l} \textbf{Theorem 8.14} \ (\text{measurability under } (\ggg_{map})). \ \textit{If } g_1 : \\ X\underset{map}{\leadsto} Y \ \textit{is \mathcal{A}-\mathcal{B}-measurable and } g_2 : Y\underset{map}{\leadsto} Z \ \textit{is \mathcal{B}-\mathcal{C}-measurable,} \\ \textit{then } g_1 \ggg_{map} g_2 \ \textit{is \mathcal{A}-\mathcal{C}-measurable.} \end{array}$

Proof. Let $A^* \in \mathcal{A}$ and $B^* \in \mathcal{B}$ be respectively g_1 's and g_2 's halting sets. The halting set of $g_1 \ggg_{map} g_2$ is $A^{**} :=$ preimage $(g_1 A^*) B^*$, which is in A. By definition,

By Theorem 8.8, g'_1 is an A-B-measurable mapping. Unfortunately, g'_2 may not be \mathcal{B} - \mathcal{C} -measurable when range $g'_1 \notin \mathcal{B}$.

Let $g_2'' := g_2 B^*$, which is a $\mathcal{B}\text{-}\mathcal{C}\text{-measurable mapping.}$ By Lemma 8.13, $g_2'' \circ_{\mathsf{map}} g_1'$ is $\mathcal{A}\text{-}\mathcal{C}\text{-measurable}$. We need only show that $g_2' \circ_{\mathsf{map}} g_1' = g_2'' \circ_{\mathsf{map}} g_1'$, which by Lemma 8.10 is true if range $g_1' \subseteq \text{domain } g_2' \text{ and } g_2' \subseteq g_2''$. By Theorem 8.12, $A^{**} \subseteq A^*$ implies domain $g_1' = A^{**}$. By

Theorem 8.11 and Lemma 8.9,

$$\begin{array}{ll} \mathsf{range}\ \mathsf{g}_1' \ = \ \mathsf{image}\ (\mathsf{g}_1\ \mathsf{A}^*)\ (\mathsf{preimage}\ (\mathsf{g}_1\ \mathsf{A}^*)\ \mathsf{B}^*) \\ \ = \ \mathsf{image}\ (\mathsf{g}_1\ \mathsf{A}^*)\ (\mathsf{preimage}\ (\mathsf{g}_1\ \mathsf{A}^*)\ \mathsf{B}^*) \\ \ \subseteq \ \mathsf{B}^* \end{array}$$

range $g_1' \subseteq B^*$ implies (by Theorem 8.12) that domain $g_2' = \text{range } g_1'$, and (by Theorem 8.11) that $g_2' \subseteq g_2''$.

8.1.2 Case: Pairing

12

Lemma 8.15 (measurability under $\langle \cdot, \cdot \rangle_{map}$). If $g_1 : X \rightharpoonup Y_1$ is $\mathcal{A}\text{-}\mathcal{B}_1\text{-}measurable$ and $g_2 : X \rightharpoonup Y_2$ is $\mathcal{A}\text{-}\mathcal{B}_2\text{-}measurable$, then $\langle g_1, g_2 \rangle_{map}$ is $\mathcal{A}\text{-}(\mathcal{B}_1 \otimes \mathcal{B}_2)\text{-}measurable$.

 $\begin{array}{lll} \textbf{Theorem} & \textbf{8.16} & (\text{measurability under (\&\&\&_{map})}). & \textit{If } g_1 : \\ X\underset{\text{map}}{\sim} Y_1 & \textit{is } \mathcal{A}\text{-}\mathcal{B}_1\text{-}\textit{measurable} & \textit{and } g_2 : X\underset{\text{map}}{\sim} Y_2 & \textit{is } \mathcal{A}\text{-}\mathcal{B}_2\text{-}\\ \textit{measurable}, & \textit{then } g_1 &\&\&_{map} g_2 & \textit{is } \mathcal{A}\text{-}(\mathcal{B}_1 \otimes \mathcal{B}_2)\text{-}\textit{measurable}. \end{array}$

Proof. Let A_1^* and A_2^* be respectively g_1 's and g_2 's halting sets. The halting set of g_1 & g_2 is $A^{**} := A_1^* \cap A_2^*$, which is in \mathcal{A} . By definition, $(g_1 \&\&\&_{map} g_2) A^{**} = \langle g_1 A^{**}, g_2 A^{**} \rangle_{map}$, which by Lemma 8.15 is \mathcal{A} -($\mathcal{B}_1 \otimes \mathcal{B}_2$)-measurable.

8.1.3 Case: Conditional

Lemma 8.17 (measurability under \uplus_{map}). If $g_1: X \rightarrow Y$ and $g_2: X \rightarrow Y$ are $\mathcal{A}\text{-}\mathcal{B}\text{-}measurable}$ and have disjoint domains, $g_1 \uplus_{map} g_2$ is $\mathcal{A}\text{-}\mathcal{B}\text{-}measurable}$.

Theorem 8.18 (measurability under ifte_{map}). If g_1 : $X \underset{map}{\sim} Bool$ is $A-(\mathcal{P} Bool)$ -measurable, and g_2 : $X \underset{map}{\sim} Y$ and g_3 : $X \underset{map}{\sim} Y$ are $A-\mathcal{B}$ -measurable, then ifte_{map} g_1 g_2 g_3 is $A-\mathcal{B}$ -measurable.

Proof. Let \mathcal{A}_1^* , \mathcal{A}_2^* and \mathcal{A}_3^* be respectively g_1 's, g_2 's and g_3 's halting sets. The halting set of ifte_{map} g_1 g_2 g_3 is defined by

$$\begin{array}{lll} \mathsf{A}_2^{**} &:= \mathsf{A}_2^* \cap \mathsf{preimage} \left(\mathsf{g}_1 \ \mathcal{A}_1^* \right) \left\{ \mathsf{true} \right\} \\ \mathsf{A}_3^{**} &:= \mathsf{A}_3^* \cap \mathsf{preimage} \left(\mathsf{g}_1 \ \mathcal{A}_1^* \right) \left\{ \mathsf{false} \right\} \\ \mathsf{A}^{**} &:= \mathsf{A}_2^{**} \uplus \mathsf{A}_3^{**} \end{array} \tag{50}$$

Because preimage $(g_1 \mathcal{A}_1^*) B \in \mathcal{A}$ for any $B \subseteq Bool$, $A^{**} \in \mathcal{A}$. By definition,

$$\begin{array}{ll} \mathsf{ifte_{map}} \ g_1 \ g_2 \ g_3 \ \mathsf{A}^{**} \ = \ \mathsf{let} \ \ g_1' := g_1 \ \mathsf{A}^{**} \\ g_2' := g_2 \ (\mathsf{preimage} \ g_1' \ \{\mathsf{true}\}) \\ g_3' := g_3 \ (\mathsf{preimage} \ g_1' \ \{\mathsf{false}\}) \\ \mathsf{in} \ \ g_2' \uplus_{\mathsf{map}} g_3' \end{array}$$

By hypothesis, g'_1 , g'_2 and g'_3 are measurable mappings, and the mapping arrow restriction law (20) imples g'_2 and g'_3 have disjoint domains. Apply Lemma 8.17.

8.1.4 Case: Laziness

Lemma 8.19 (measurability of \varnothing). For any σ -algebras \mathcal{A} and \mathcal{B} , the empty mapping \varnothing is \mathcal{A} - \mathcal{B} -measurable.

Theorem 8.20 (measurability under $|azy_{map}\rangle$. Let $g:1\Rightarrow (X_{map}^{\sim}Y)$. If g 0 is A-B-measurable, then $|azy_{map}|g$ is A-B-measurable.

Proof. The halting set A^{**} of $lazy_{map}$ g is the same as that of g 0. By definition,

$$lazy_{map} g A^{**} = if (A^{**} = \varnothing) \varnothing (g 0 A^{**})$$
 (52)

If $A^{**}=\varnothing$, then $\mathsf{lazy_{map}}\ g\ A^{**}=\varnothing$; apply Lemma 8.19. If $A^{**}\neq\varnothing$, then $\mathsf{lazy_{map}}\ g=g\ 0$, which is $\mathcal{A}\text{-}\mathcal{B}\text{-}$ measurable. \square

8.2 Measurable Probabilistic Computations

We are now prepared to lift the previous theorems to probabilistic computations.

Definition 8.21 (measurable mapping* arrow computation). Let \mathcal{A} and \mathcal{B} be σ -algebras on $(R \times T) \times X$ and Y. A computation $g: X_{\text{map}^*} Y$ is \mathcal{A} - \mathcal{B} -measurable if $g \not j_0 A^*$ is an \mathcal{A} - \mathcal{B} -measurable mapping, where A^* is g's halting set.

To make general measurability statements about computations, whether they have flat or product types, it helps to have a notion of a standard σ -algebra.

Definition 8.22 (standard σ -algebra). For a set X used as a type, Σ X denotes its **standard** σ -**algebra**, which must be defined under the following constraints:

$$\Sigma \langle \mathsf{X}_1, \mathsf{X}_2 \rangle = \Sigma \; \mathsf{X}_1 \otimes \Sigma \; \mathsf{X}_2 \tag{53}$$

$$\Sigma (J \to X) = (\Sigma X)^{\otimes J}$$
 (54)

$$|X| \le \omega \implies \Sigma X = \mathcal{P} X$$
 (55)

$$X' \in \Sigma X \implies \Sigma X' = \{X' \cap A \mid A \in \Sigma X\}$$
 (56)

The predicate "is measurable" means "is measurable with respect to standard σ -algebras."

Examples: by (55), Σ Bool = \mathcal{P} Bool. By both (53) and (55), Σ (Bool, Bool) = \mathcal{P} (Bool × Bool). By (56), Σ [0, 1] is a sub- σ -algebra of Σ \mathbb{R} .

Theorem 8.23. arr_{map^*} fst and arr_{map^*} snd are measurable.

Proof. Follows from
$$(53)$$
 and Definition 8.3.

Theorem 8.24 (AStore measurability transfer). Every AStore arrow combinator produces measurable mapping* computations from measurable mapping* computations.

Proof. AStore's combinators are defined in terms of the base arrow's combinators and arr_{map^*} fst and arr_{map^*} snd.

Theorem 8.25. For all $j \in J$, $arr_{map^*}(\pi j)$ is measurable.

Proof. Follows from (54) and Definition 8.4.

Corollary 8.26. random_{map*} and branch_{map*} are measurable.

Theorem 8.27. ifte'_{map*} is measurable.

Proof. branch_{map*} is measurable, and arr_{map*} agrees is measurable by (55).

Theorem 8.28 (probabilistic programs are measurable). If $[\![e]\!]_{\mathsf{map}^*}$ converges, it is measurable. If $[\![e]\!]'_{\mathsf{map}^*}$ converges, it is measurable.

Proof. By structural induction over e and the above measurability theorems.

Of course, Theorem 8.28 remains true when $\llbracket \cdot \rrbracket_a$ is extended with any rule whose right side is measurable. Examples include arithmetic, equalities and inequalities, and lambda expressions transformed into closures.

8.3 Random Store Probabilities

Preimages under probabilistic programs are measurable subsets of $(R \times T) \times X$. While it is possible to put probability measures on such domains, doing so would be surprising for end-users. For example, the probabilities of outputs of the geometric function defined in (33) would depend not only on the probability of random < p, but also on some arbitrary probability that each branch is taken. It would not define the geometric distribution.

We therefore have to measure *projections* of subsets of $(R \times T) \times X$. Unfortunately, projected sets are generally not measurable. Fortunately, ours is a special case: the excluded dimensions are countable.

As previously, we start with measuring the halting set.

Definition 8.29 (standard probability measure). For a type X, a standard probability measure is a probability measure $P \in \mathcal{P} \times [0,1]$ where domain $P = \Sigma \times [0,1]$

Definition 8.30 (halting probability). Let $g: X_{map} Y$ be measurable, with A^* its halting set. Let $P \in \mathcal{P}$ $R \longrightarrow [0,1]$ be a standard probability measure over random stores. The halting probability of g is P (image (fst $\gg f$ st) A^*).

Theorem 8.31 (measurable finite projections). Let $A \in \Sigma \langle X_1, X_2 \rangle$. If X_2 is at most countable, image fst $A \in A_1$.

Proof. Because Σ $X_2 = \mathcal{P}$ X_2 , A is a countable union of rectangles of the form $A_1 \times \{a_2\}$, where $A_1 \in \Sigma$ X_1 and $a_2 \in X_2$. Because image fst distributes over unions, image fst A is a countable union of sets in Σ X_1 .

Theorem 8.32. Let $g: X_{\widetilde{map}^*} Y$ be measurable. If X is at most countable, g's halting probability is well-defined.

Proof. T is countable; apply Theorem 8.31 twice.

In particular, for programs interpreted using $\llbracket \cdot \rrbracket_{\mathsf{map}^*}$, $X = \{\langle \rangle \}$ (the empty list/stack), so their halting probabilities are well-defined.

Corollary 8.33. Let $g: X_{\substack{m \ni p^* \\ m \ni p^*}} Y$ be measurable and $A \subseteq A^*$ a measurable set. P (image (fst > > fst) A), the probability of A, is well-defined.

In particular, for any converging $g:=\llbracket e\rrbracket'_{\mathsf{map}^*},$ preimages A of measurable subsets B are measurable, and the random store component of A has a well-defined probability.

9. Implementable Approximation

XXX: arrpre is generally uncomputable, but we don't need that many lifts; Figure 8 has the rest of the non-arithmetic ones we'll need

 $\mathbf{XXX} :$ figure out a good way to present the following info Figure 4:

- pre: can't implement
- pre-ap: need ∩
- $\langle \cdot, \cdot \rangle_{\mathsf{pre}}$: approximate; need \times and \cap
- \bullet \circ_{pre} : no change
- \bullet \uplus_{pre} : approximate; need join

Figure 6:

- arr_{pre} (and lift_{pre}): can't implement
- >>>pre: no change
- **&&** pre: use approximating $\langle \cdot, \cdot \rangle_{pre}$
- \bullet ifte_{pre}: need {true} and {false}; use approximating \uplus_{pre}
- lazy_{pre}: need (= \varnothing), (pre \varnothing)

Figure 8:

- \bullet id_{pre} : no change
- const_{pre}: need $\{y\}$, $(=\varnothing)$, \varnothing
- \bullet fst_{pre} and $snd_{pre} :$ need projections, i, \times
- π_{pre} : need projections, \cap , arbitrary products

10. Computable Approximation

References

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- [2] N. Toronto and J. McCarthy. Computing in Cantor's paradise with λ -ZFC. In Functional and Logic Programming Symposium (FLOPS), pages 290–306, 2012.

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\begin{array}{lll} \text{id}_{\text{pre}}: X \underset{\text{pre}}{\times} X & \text{fst}_{\text{pre}}: \langle X, Y \rangle_{\text{pre}}{\times} X \\ \text{id}_{\text{pre}} A := \langle A, \lambda B, B \rangle & \text{fst}_{\text{pre}}: \langle A, \lambda B, B \rangle \\ & \text{const}_{\text{pre}}: Y \Rightarrow X_{\text{pre}}{\times} Y & \text{fst}_{\text{pre}}: A := \text{let } A_1 := \text{image fst } A \\ & A_2 := \text{image snd } A \\ & \text{in } \langle A_1, \lambda B, A \cap (B \times A_2) \rangle \\ \text{const}_{\text{pre}}: Y \Rightarrow X \Rightarrow_{\text{pre}}{\times} Y & \text{snd}_{\text{pre}}: \langle X, Y \rangle_{\text{pre}}{\times} Y \\ & \text{snd}_{\text{pre}}: \langle X, Y \rangle_{\text{pre}}{\times} Y \\ \text{snd}_{\text{pre}}: A := \text{let } A_1 := \text{image fst } A \\ & \text{snd}_{\text{pre}}: A := \text{let } A_1 := \text{image fst } A \\ & A_2 := \text{image snd } A \\ & \text{in } \langle A_2, \lambda B, A \cap (A_1 \times B) \rangle \\ & \text{in } \langle A_2, \lambda B, A \cap (A_1 \times B) \rangle \end{array}
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Figure 8: Specific instances of arr_{pre} f