Running Probabilistic Programs Backward

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Abstract

It is primarily Bayesian statistical practice that drives probabilistic language development. Unfortunately, languages developed by programming language researchers most often lack probabilitic conditioning, making them nearly useless in Bayesian practice. Languages developed by Bayesian practitioners can be useful, but they lack specifications and are limited in seemingly arbitrary ways.

We develop a mathematical specification for a first-order language with recursion, extended with probabilistic choice and conditioning. Our semantics interprets programs as functions that compute preimages of sets of outputs. Distributions over outputs are defined by the probabilities of their preimages, a measure-theoretic approach that ensures the language is not artificially limited.

Measurability is a basic property similar to continuity that is critical, but often neglected. As part of proving correctness, we prove that all programs, including partial programs with real arithmetic, are measurable.

Functions that compute preimages are generally uncomputable, so we develop an additional approximating semantics for computing rectangular covers of preimages. We implement the approximating semantics directly in Typed Racket and Haskell.

Categories and Subject Descriptors XXX-CR-number [XXX-subcategory]: XXX-third-level

General Terms XXX, XXX

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XXX: consider using paragraph headers instead of subsections and subsubsections

1. Introduction

There is currently no efficient probabilistic language implementation that simultaneously

- 1. Places no extraneous restrictions on legal programs.
- 2. Allows **conditioning**, or restricting the output in a way that preserves relative probabilities.
- 3. Has a semantics, or a mathematical specification.

In the field of programming language research, there are a few examples of languages that do not restrict legal programs and have a semantics (XXX: cite all). Unfortunately, most of the demand for probabilistic languages comes from Bayesian practice, which requires conditioning.

Bayesian practitioners have implemented many probabilistic languages with conditioning (XXX: cite all). Almost all lack a semantics, so it is impossible to distinguish between implementation errors and errors in users' understanding. Almost all place restrictions on programs, most commonly disallowing recursion, allowing only continuous distributions, and allowing only very limited forms of conditioning.

These common restrictions arise from reasoning about probability using **densities**, which are functions from random values to *changes* in probability. While simple and convenient, densities have many limitations. Densities for random values with different dimension are incomparable. Densities cannot be defined on infinite products. Densities can only be used to reason about conditioning in limited cases. (XXX: make the last sentence more specific, or remove it because it communicates nothing extra)

Densities cannot define distributions of discontinuous functions of random variables. For example, suppose we want to model a thermometer that reports in the range [0,100], and that the temperature it would report (if it could) is distributed according to a bell curve. We might encode the process like this:

$$\mathbf{t}' := \mathbf{let} \ \mathbf{t} := \mathbf{normal} \ \mu \ 1$$
$$\mathbf{in} \ \mathbf{max} \ 0 \ (\mathbf{min} \ 100 \ \mathbf{t})$$
 (1)

While t's distribution has a density (a standard bell curve at mean μ), the distribution of t' does not.

The restrictions placed on programs are indeed onerous, if such benign uses of min and max must be disallowed. We cannot even model measuring devices correctly.

1.1 Measure-Theoretic Probability

Measure-theoretic probability [13] is widely believed to be able to define everything reasonable that densities cannot. It mainly does this by assigning probabilities to sets instead of assigning changes in probability to values.

If P assigns probabilities to subsets of X and $f: X \to Y$, then the **preimage measure**

defines the distribution over subsets B of Y, where preimage returns the subset of f's domain X for which f yields a value in B. In the thermometer example (1), f would be an interpretation of the program as a function, X would be the set of all random sources, and Y would be the set of the

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program's possible outputs. For any $B \subseteq Y$, preimage f B would be well-defined, regardless of discontinuities.

Unfortunately, there is a complicated technical restriction: only *measurable* subsets of X and Y can be assigned probabilities. Conditioning on zero-probability sets can also be quite difficult. These complexities tend to drive practitioners to densities, even though they are so limited.

1.2 Measure-Theoretic Semantics

Because purely functional languages do not allow side-effects (except usually divergence), programmers must write probabilistic programs as functions from a random source to outputs. Monads and other categorical classes such as idioms and arrows can make doing so easier. (XXX: cite me, bunch of others)

It seems this approach should make it easy to interpret probabilistic programs measure-theoretically. For a probabilistic program $f:X\to Y$, the probability measure on output sets $B\subseteq Y$ should be defined by preimages of B under f and the probability measure on X. Unfortunately, it is difficult to turn this simple-sounding idea into a compositional semantics, for the following reasons.

- Preimages can be defined only for functions with observable domains, which excludes lambdas.
- Requiring subsets of X and Y to be measurable constrains
 f: preimages of measurable subsets of Y must be measurable subsets of X. Proving the conditions under which
 this is true is difficult, especially when f may diverge.
- 3. It is very difficult to define probability measures for arbitrary spaces of measurable functions [3].

Implementing a language based on such a semantics is complicated because

- 4. Contemporary mathematics is unlike any implementation's host language.
- 5. It requires running Turing-equivalent programs backward, efficiently, on possibly uncountable sets of outputs.

We address both 1 and 4 by developing our semantics in $\lambda_{\rm ZFC}$ [25], a λ -calculus with infinite sets, and both extensional and intensional functions. We address 5 by deriving and implementing a *conservative approximation* of the semantics.

There seems to be no way to simplify difficulty 2, so we work through it in Section 8. The outcome is worth it: we prove that all probabilistic programs are measurable, regardless of which inputs they diverge on. This includes uncomputable programs; for example, those that contain real equality tests and limits. We believe this result is the first of its kind, and is general enough to apply to almost all past and future work on probabilistic programming languages.

For difficulty 3, we have discovered that the "first-orderness" of arrows [9] is a perfect fit for the "first-orderness" of measure theory.

1.3 Arrow Solution Overview

Using arrows, we define an *exact* semantics and an *approximating* semantics. Our exact semantics consists of

- A semantic function which, like the semantic function for the arrow calculus [17], transforms first-order programs into the computations of an arbitrary arrow.
- Arrows for evaluating expressions in different ways.

This commutative diagram describes the relationships among the arrows used to define the exact semantics:

From top-left to top-right, $X \leadsto_{\perp} Y$ computations are intensional functions that may raise errors, $X_{\max} Y$ computations produce extensional functions, and $X_{\max} Y$ computations compute preimages. The computations of the arrows in the bottom row are like those in the top, except they thread an infinite store of random values, and always converge. (We can do this because in $\lambda_{\rm ZFC}$, Turing-uncomputable programs are definable.) Most of our correctness theorems rely on proofs that every lift and η in (3) is a homomorphism.

Our approximating semantics consists of the same semantic function and an arrow $X_{\widetilde{pre}^*}'Y$, derived from $X_{\widetilde{pre}^*}Y$, for computing conservative approximations of preimages.

An implementation implements (XXX: badness) the semantic function, and the $X \leadsto_{\perp} Y$ and $X \underset{pre}{\leadsto}' Y$ arrows' combinators.

From here on, significant terms are introduced in **bold**, with those we invent introduced in **bold** italics.

2. Operational Metalanguage

We write all of the programs in this paper in $\lambda_{\rm ZFC}$ [25], an untyped, call-by-value λ -calculus designed for deriving implementable programs from contemporary mathematics.

Generally, contemporary mathematics—measure theory in particular—is done in **ZFC**: **Zermelo-Fraenkel** set theory extended with the axiom of **Choice** (equivalently unique **Cardinality**). ZFC has only first-order functions and no general recursion, which makes implementing a language defined by a transformation into ZFC quite difficult. The problem is exacerbated if implementing the language requires approximation. Targeting $\lambda_{\rm ZFC}$ instead allows creating a precise mathematical specification and deriving an approximating specification without changing languages.

In $\lambda_{\rm ZFC}$, essentially every set is a value, as well as every lambda and every set of lambdas. All operations, including operations on infinite sets, are assumed to complete instantly if they converge.

Almost everything definable in ZFC can be formally defined by a finite $\lambda_{\rm ZFC}$ program, except objects that most mathematicians would agree are nonconstructive. More precisely, any set that must be defined by a statement of existence and uniqueness without giving a bounding set is not definable by a $finite\ \lambda_{\rm ZFC}$ program.

Because $\lambda_{\rm ZFC}$ includes an inner model of ZFC, essentially every ZFC theorem applies to $\lambda_{\rm ZFC}$'s set values without alteration. Further, proofs about $\lambda_{\rm ZFC}$'s set values apply directly to ZFC sets, assuming the existence of a single inaccessible cardinal.¹

In $\lambda_{\rm ZFC}$, algebraic data structures are encoded as sets; e.g. $\langle x,y \rangle$ can be encoded as $\{\{x\},\{x,y\}\}$. Only the *existence* of encodings into sets is important, as it means data structures inherit a defining characteristic of sets: strictness. More precisely, the lengths of paths to data structure leaves is unbounded, but each path must be finite. Less precisely,

 $^{^1}$ A mild assumption, as ZFC+ κ is a smaller theory than Coq's [4], and algebraic geometers assume a proper class of inaccessibles.

data may be "infinitely wide" (such as \mathbb{R}) but not "infinitely tall" (such as infinite trees and lists).

 $\lambda_{\rm ZFC}$ is untyped so its users can define an auxiliary type system that best suits their application area. For this work, we use a manually checked, polymorphic type system characterized by these rules:

- A free lowercase type variable is universally quantified.
- A free uppercase type variable is a set.
- A set denotes a member of that set.
- $x \Rightarrow y$ denotes a partial function.
- $\langle x, y \rangle$ denotes a pair of values with types x and y.
- Set x denotes a set with members of type x.

Because the type Set X denotes the same values as the set \mathcal{P} X (i.e. subsets of X) we regard them as equivalent. Similarly, the type $\langle X, Y \rangle$ is equivalent to the set $X \times Y$.

We write $\lambda_{\rm ZFC}$ programs in heavily sugared λ -calculus syntax, with an if expression and these additional primitives:

true : Bool
$$(\in) : \mathsf{x} \Rightarrow \mathsf{Set} \; \mathsf{x} \Rightarrow \mathsf{Bool}$$
 false : Bool $\mathcal{P} : \mathsf{Set} \; \mathsf{x} \Rightarrow \mathsf{Set} \; (\mathsf{Set} \; \mathsf{x})$ $\varnothing : \mathsf{Set} \; \mathsf{x}$ $\bigcup : \mathsf{Set} \; (\mathsf{Set} \; \mathsf{x}) \Rightarrow \mathsf{Set} \; \mathsf{x}$ $\omega : \mathsf{Ord}$ image : $(\mathsf{x} \Rightarrow \mathsf{y}) \Rightarrow \mathsf{Set} \; \mathsf{x} \Rightarrow \mathsf{Set} \; \mathsf{y}$ take : $\mathsf{Set} \; \mathsf{x} \Rightarrow \mathsf{x}$ $|\cdot| : \mathsf{Set} \; \mathsf{x} \Rightarrow \mathsf{Ord}$

Shortly, \varnothing is the empty set, ω is the cardinality of the natural numbers, take $\{x\}$ reduces to x and diverges for non-singleton sets, $x \in A$ decides membership, \mathcal{P} A reduces to the set of subsets of A, $\bigcup \mathcal{A}$ reduces to the union of the sets in \mathcal{A} , image f A applies f to each member of A and reduces to the set of results, and |A| reduces to the cardinality of A.

We assume literal set notation such as $\{0,1,2\}$ is already defined in terms of the set primitives.

We import applicable ZFC theorems as lemmas.

2.1 Internal and External Equality

Set theory extends first-order logic with an axiom that defines equality to be extensional, and with axioms that ensure the existence of sets in the domain of discourse. $\lambda_{\rm ZFC}$ is defined the same way as any other operational λ -calculus: by (conservatively) extending the domain of discourse with expressions and defining a reduction relation.

While $\lambda_{\rm ZFC}$ does not have an equality primitive, set theory's extensional equality can be recovered internally using (\in). *Internal* extensional equality is defined by either of the following equivalent statements:

$$x = y := x \in \{y\}$$

$$(=) := \lambda x. \lambda y. x \in \{y\}$$

$$(5)$$

Thus, 1=1 reduces to $1 \in \{1\}$, which reduces to true.² Because of the particular way $\lambda_{\rm ZFC}$'s lambda terms are defined, for two lambda terms f and g, f = g reduces to true when f and g are structurally identical modulo renaming. For example, $(\lambda x. x) = (\lambda y. y)$ reduces to true, but $(\lambda x. 2) = (\lambda x. 1 + 1)$ reduces to false.

We understand any $\lambda_{\rm ZFC}$ term e used as a truth statement as shorthand for "e reduces to true." Therefore, while the terms $(\lambda x.x)$ 1 and 1 are (externally, extensionally) unequal, we can say that $(\lambda x.x)$ 1 = 1.

Any truth statement e implies that e converges. In particular, the truth statement $e_1 = e_2$ implies that both e_1 and e_2 converge. However, we often want to say that e_1 and e_1 are equivalent when they both diverge. In these cases, we use something slightly weaker.

Definition 2.1 (observational equivalence). Two λ_{ZFC} terms e_1 and e_2 are **observationally equivalent**, written $e_1 \equiv e_2$, when $e_1 = e_2$ or both e_1 and e_2 diverge.

It might seem helpful to introduce even coarser notions of equivalence, such as applicative bisimilarity [2]. However, we do not want internal equality and external equivalence to differ too much, and we want the flexibility of extending " \equiv " with type-specific rules.

2.2 Additional Functions and Forms

We assume a desugaring pass over $\lambda_{\rm ZFC}$ expressions, which automatically curries (including for the two-argument primitives (\in) and image), and interprets special binding forms such as indexed unions $\bigcup_{x \in e_A} e$, destructuring binds as in swap $\langle x, y \rangle := \langle y, x \rangle$, and comprehensions like $\{x \in A \mid x \in B\}$. We assume we have logical operators, bounded quantifiers, and typical set operations.

A less typical set operation we use is disjoint union:

(
$$\uplus$$
) : Set $x \Rightarrow$ Set $x \Rightarrow$ Set $x \Rightarrow$ A \uplus B := if (A \cap B = \varnothing) (A \cup B) (take \varnothing) (6)

 $A \uplus B$ diverges when A and B overlap.

In set theory, functions are extensional—everything about them is observable—because they are encoded as sets of input-output pairs. The increment function for the natural numbers, for example, is $\{\langle 0,1\rangle,\langle 1,2\rangle,\langle 2,3\rangle,...\}$. We call extensional functions **mappings** and intensional functions **lambdas**, and use the word **function** to mean either. For convenience, as with lambdas, we use adjacency (e.g. (f x)) to apply mappings.

Syntax for unnamed mappings is defined by

$$\lambda x_a \in e_A. e_b :\equiv \mathsf{mapping} (\lambda x_a. e_b) e_A$$
 (7)

mapping :
$$(X \Rightarrow Y) \Rightarrow Set X \Rightarrow (X \rightharpoonup Y)$$

mapping f A := image $(\lambda a. \langle a, f a \rangle)$ A (8)

Figure 1 defines other common operations on mappings: domain, range, preimage, restrict, pairing, composition, and disjoint union. The latter three are particularly important in the preimage arrow's derivation, and preimage is critical in measure theory's account of probability. For symmetry with partial functions $x \Rightarrow y$, they are defined on $X \rightharpoonup Y$, where $X \rightharpoonup Y$ is the set of all partial mappings from any domain set X to any codomain set Y.

The set $X \to Y$ contains all the *total* mappings from X to Y. We use total mappings as possibly infinite vectors, with application for indexing. Indexing functions are produced by

$$\pi: J \Rightarrow (J \to X) \Rightarrow X$$

$$\pi j f := f j$$
(9)

which is particularly useful when f is unnamed.

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3. Arrows and First-Order Semantics

Like monads and idioms [19, 26], arrows [9] are used in functional programming to thread effects through computations in a way that imposes structure on the computations. Unlike monad and idiom computations, arrow computations are always

² Technically, $\lambda_{\rm ZFC}$ has a big-step semantics, and the derivation tree for 1=1 contains the derivation tree for $1\in\{1\}$.

```
\langle \cdot, \cdot \rangle_{\mathsf{map}} : (\mathsf{X} \rightharpoonup \mathsf{Y}_1) \Rightarrow (\mathsf{X} \rightharpoonup \mathsf{Y}_2) \Rightarrow (\mathsf{X} \rightharpoonup \mathsf{Y}_1 \times \mathsf{Y}_2)
domain : (X \rightarrow Y) \Rightarrow Set X
domain := image fst
                                                                                                                 \langle g_1, g_2 \rangle_{map} := \text{let } A := (\text{domain } g_1) \cap (\text{domain } g_2)
                                                                                                                                                        in \lambda a \in A. \langle g_1 a, g_2 a \rangle
range : (X \rightarrow Y) \Rightarrow Set Y
                                                                                                                 (\circ_{\mathsf{map}}): (\mathsf{Y} \rightharpoonup \mathsf{Z}) \Rightarrow (\mathsf{X} \rightharpoonup \mathsf{Y}) \Rightarrow (\mathsf{X} \rightharpoonup \mathsf{Z})
range := image snd
                                                                                                                 g_2 \circ_{\mathsf{map}} g_1 := \mathsf{let} \ \mathsf{A} := \mathsf{preimage} \ \mathsf{g}_1 \ (\mathsf{domain} \ \mathsf{g}_2)
                                                                                                                                                      in \lambda a \in A.g_2 (g<sub>1</sub> a)
preimage : (X \rightarrow Y) \Rightarrow Set Y \Rightarrow Set X
preimage f B := \{a \in domain f \mid f a \in B\}
                                                                                                                (\uplus_{\mathsf{map}}): (\mathsf{X} \rightharpoonup \mathsf{Y}) \Rightarrow (\mathsf{X} \rightharpoonup \mathsf{Y}) \Rightarrow (\mathsf{X} \rightharpoonup \mathsf{Y})
                                                                                                                 g_1 \uplus_{\mathsf{map}} g_2 := \mathsf{let} \ \mathsf{A} := (\mathsf{domain} \ g_1) \uplus (\mathsf{domain} \ g_2)
restrict : (X \rightarrow Y) \Rightarrow Set X \Rightarrow (X \rightarrow Y)
                                                                                                                                                       in \lambda a \in A. if (a \in domain g_1) (g_1 a) (g_2 a)
restrict f A := \lambdaa \in (A \cap domain f). f a
```

Figure 1: Operations on mappings.

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- Function-like: An arrow computation of type x → y must behave like a corresponding function of type x ⇒ y (in a sense we explain shortly in terms of homomorphisms).
- First-order: There is no way to derive a computation $app : \langle x \leadsto y, x \rangle \leadsto y$ from an arrow's minimal definition.

The first property makes arrows a perfect fit for a compositional translation from expressions to intensional or extensional functions—or, as we will see, to computations that compute preimages. The second property makes them a perfect fit for a measure-theoretic semantics in particular, as app in the function arrow is generally not measurable [3]. Targeting arrows in the semantics therefore gives some assurance that we can meet measure theory's requirement that preimage measure be defined only for measurable functions. We prove in Section 8 that it is sufficient.

3.1 Alternative Arrow Definitions and Laws

We do not give typical minimal arrow definitions. For each arrow a, instead of first_a, we define (&&a)—typically called fanout, but its use will be clearer if we call it pairing—which applies two functions to an input and returns the pair of their outputs. Though first_a may be defined in terms of (&&a) and vice-versa [9], we give (&&a) definitions because the applicable measure-theoretic theorems are in terms of pairing functions.

One way to strengthen an arrow a is to define an additional combinator left_a, which can be used to choose an arrow computation based on the result of another. Again, we define a different combinator, ifte_a ("if-then-else"), to make applying measure-theoretic theorems easier.

In a nonstrict λ -calculus, simply defining a choice combinator allows writing recursive functions using nothing but arrow combinators and lifted, pure functions. However, any strict λ -calculus (such as $\lambda_{\rm ZFC}$) requires an extra combinator to defer computations in conditional branches.

For example, define the **function arrow** with choice:

$$\begin{array}{rcl} & \text{arr } f := f \\ (f_1 \ggg f_2) \ a := f_2 \ (f_1 \ a) \\ (f_1 \&\&\& f_2) \ a := \langle f_1 \ a, f_2, a \rangle \\ & \text{ifte } f_1 \ f_2 \ f_3 \ a := if \ (f_1 \ a) \ (f_2 \ a) \ (f_3 \ a) \end{array} \tag{10}$$

and try to define the following recursive function:

$$halt-on-true := ifte (arr id) (arr id) halt-on-true (11)$$

The defining expression diverges in a strict λ -calculus. In a nonstrict λ -calculus, it diverges only when applied to false.

Using lazy f a := f 0 a, which receives thunks and returns arrow computations, we can write halt-on-true as

halt-on-true := ifte (arr id) (arr id) (lazy
$$\lambda 0$$
. halt-on-true) (12)

which diverges only when applied to false in any λ -calculus.

Definition 3.1 (arrow with choice). A binary type constructor (\sim_a) and the combinators

$$\operatorname{arr}_{a} : (x \Rightarrow y) \Rightarrow (x \leadsto_{a} y)$$

$$(\ggg_{a}) : (x \leadsto_{a} y) \Rightarrow (y \leadsto_{a} z) \Rightarrow (x \leadsto_{a} z)$$

$$(\&\&\&_{a}) : (x \leadsto_{a} y) \Rightarrow (x \leadsto_{a} z) \Rightarrow (x \leadsto_{a} \langle y, z \rangle)$$

$$(13)$$

define an **arrow** if certain monoid, homomorphism, and structural laws hold. The additional combinators

$$\begin{aligned} &\text{ifte}_{a}: (x \leadsto_{a} \mathsf{Bool}) \Rightarrow (x \leadsto_{a} y) \Rightarrow (x \leadsto_{a} y) \Rightarrow (x \leadsto_{a} y) \\ &\text{lazy}_{a}: (1 \Rightarrow (x \leadsto_{a} y)) \Rightarrow (x \leadsto_{a} y) \end{aligned} \tag{14}$$

where $1 = \{0\}$, define an **arrow with choice** if certain additional homomorphism and structural laws hold.

From here on, as all of our arrows are arrows with choice, we simply call them arrows.

The necessary homomorphism laws can be put in terms of more general homomorphism properties that deal with distributing an arrow-to-arrow lift, which we use extensively to prove correctness.

Definition 3.2 (arrow homomorphism). A function lift_b: $(x \leadsto_a y) \Rightarrow (x \leadsto_b y)$ is an arrow homomorphism from arrow a to arrow b if the following distributive laws hold for appropriately typed f, f₁, f₂ and f₃:

$$lift_b (arr_a f) \equiv arr_b f \tag{15}$$

$$\mathsf{lift_b} \; (\mathsf{f_1} \ggg_{\mathsf{a}} \mathsf{f_2}) \; \equiv \; (\mathsf{lift_b} \; \mathsf{f_1}) \ggg_{\mathsf{b}} \; (\mathsf{lift_b} \; \mathsf{f_2})$$
 (16)

$$\mathsf{lift_b} \ (\mathsf{f_1} \ \&\&\&_\mathsf{a} \ \mathsf{f_2}) \ \equiv \ (\mathsf{lift_b} \ \mathsf{f_1}) \ \&\&\&_\mathsf{b} \ (\mathsf{lift_b} \ \mathsf{f_2}) \tag{17}$$

$$\mathsf{lift_b}\ (\mathsf{ifte_a}\ \mathsf{f_1}\ \mathsf{f_2}\ \mathsf{f_3}) \ \equiv \ \mathsf{ifte_b}\ (\mathsf{lift_b}\ \mathsf{f_1})\ (\mathsf{lift_b}\ \mathsf{f_2})\ (\mathsf{lift_b}\ \mathsf{f_3})\ (18)$$

$$lift_b (lazy_a f) \equiv lazy_b \lambda 0. lift_b (f 0)$$
 (19)

The arrow homomorphism laws state that $arr_a: (x \Rightarrow y) \Rightarrow (x \leadsto_a y)$ must be a homomorphism from the function arrow (10) to arrow a. Roughly, arrow computations that do not use additional combinators can be transformed into arr_a applied to a pure computation. They must be function-like.

Only a few of the other arrow laws play a role in our semantics and its correctness. We need associativity of (>>>>a):

$$(f_1 \ggg_a f_2) \ggg_a f_3 \equiv f_1 \ggg_a (f_2 \ggg_a f_3)$$
 (20)

a pair extraction law:

$$(arr_a f_1 \&\& a f_2) >\gg_a arr_a snd \equiv f_2$$
 (21)

and distribution of pure computations over effectful:

$$\mathsf{arr}_\mathsf{a} \ \mathsf{f}_1 \ggg_\mathsf{a} \big(\mathsf{f}_2 \And_\mathsf{a} \mathsf{f}_3\big) \ \equiv \ \big(\mathsf{arr}_\mathsf{a} \ \mathsf{f}_1 \ggg_\mathsf{a} \mathsf{f}_2\big) \And_\mathsf{a} \ (22) \\ \big(\mathsf{arr}_\mathsf{a} \ \mathsf{f}_1 \ggg_\mathsf{a} \mathsf{f}_3\big)$$

$$\operatorname{\mathsf{arr}_a} \mathsf{f}_1 \ggg_{\mathsf{a}} \operatorname{\mathsf{ifte}_a} \mathsf{f}_2 \mathsf{f}_3 \mathsf{f}_4 \equiv \operatorname{\mathsf{ifte}_a} (\operatorname{\mathsf{arr}_a} \mathsf{f}_1 \ggg_{\mathsf{a}} \mathsf{f}_2) \qquad (23)$$

$$(\operatorname{\mathsf{arr}_a} \mathsf{f}_1 \ggg_{\mathsf{a}} \mathsf{f}_3)$$

$$(\operatorname{\mathsf{arr}_a} \mathsf{f}_1 \ggg_{\mathsf{a}} \mathsf{f}_4)$$

$$\mathsf{arr_a}\ \mathsf{f}_1\ggg_{\mathsf{a}}\mathsf{lazy_a}\ \mathsf{f}_2\ \equiv\ \mathsf{lazy_a}\ \lambda 0.\,\mathsf{arr_a}\ \mathsf{f}_1\ggg_{\mathsf{a}}\mathsf{f}_2\ 0 \tag{24}$$

Equivalence between different arrow representations is usually proved in a strongly normalizing λ -calculus [16, 17], in which every function is free of effects, including divergence. Such a λ -calculus has no need for lazy_a, so we could not derive (24) from existing arrow laws. But (XXX: justify).

The pair extraction law (21), which can be derived from existing arrow laws, is a little more problematic, in nonstrict λ -calculii as well as $\lambda_{\rm ZFC}$. If f_1 can diverge, using (21) to transform a computation can turn a diverging expression into a converging one, or vice-versa. We could condition the pair extraction law on f_1 's totality. Instead, we require every argument to arra to be total, which simplifies more proofs.

Rather than prove each necessary arrow law, we prove the arrows are epimorphic (not necessarily isomorphic) to arrows for which the laws hold.

Definition 3.3 (arrow epimorphism). An arrow homomorphism lift_b : $(x \leadsto_a y) \Rightarrow (x \leadsto_b y)$ that has a right inverse (equiv. surjective) is an arrow epimorphism from a to b.

Theorem 3.4. If lift_b: $(x \leadsto_a y) \Rightarrow (x \leadsto_b y)$ is an arrow epimorphism and the combinators of a define an arrow, then the combinators of b define an arrow.

Proof. For the pair extraction law (21), rewrite in terms of lift_b, apply homomorphism laws, and apply the pair extraction law for arrow a:

The proofs for every other law are similar.

3.2 First-Order Let-Calculus Semantics

Figure 2 defines a transformation $\llbracket \cdot \rrbracket_a$ from a first-order letcalculus to arrow computations for any arrow a.

A program is a sequence of definition statements followed by a final expression. $[\![\cdot]\!]_a$ compositionally transforms each defining expression and the final expression into arrow computations. Functions are named, but local variables and arguments are not. Instead, variables are referred to by De Bruijn indexes, with 0 referring to the innermost binding.

Perhaps unsurprisingly, the interpretation acts like a stack machine. The final expression has type $\langle \rangle \leadsto_a y$, where y is the type of the program's value, and $\langle \rangle$ denotes an empty

list. Let-bindings push values onto the stack. First-order functions have type $\langle x, \langle \rangle \rangle \sim_a y$ where x is the argument type and y is the return type. Application sends a stack containing just an x.

Unless there is a reason to distinguish programs and expressions, we regard programs as if they were their final expressions. Thus, the following definition applies to both.

Definition 3.5 (well-defined expression). An expression e is well-defined under arrow a if $[e]_a : x \leadsto_a y$ for some xand y, and $[e]_a$ converges.

From here on, we assume all expressions are well-defined. (The arrow a will be clear from context.) This does not guarantee that running any given interpretation converges; it just simplifies unqualified statements about expressions.

An example is the following theorem, on which most of our semantic correctness theorems rely.

Theorem 3.6 (homomorphisms distribute over expressions). Let lift_b: $(x \rightsquigarrow_a y) \Rightarrow (x \rightsquigarrow_b y)$ be an arrow homomorphism. For all expressions e, $[\![e]\!]_b \equiv \mathsf{lift_b}$ $[\![e]\!]_a$.

Proof. By structural induction.

Bases cases proceed by expansion and using $arr_b \equiv lift_b \circ$ arr_a (15). For example, for constants:

$$\begin{aligned} \llbracket v \rrbracket_{\mathsf{b}} & \equiv \; \mathsf{arr}_{\mathsf{b}} \; (\mathsf{const} \; v) \\ & \equiv \; \mathsf{lift}_{\mathsf{b}} \; (\mathsf{arr}_{\mathsf{a}} \; (\mathsf{const} \; v)) \\ & \equiv \; \mathsf{lift}_{\mathsf{b}} \; \llbracket v \rrbracket_{\mathsf{a}} \end{aligned}$$

Inductive cases proceed by expansion, applying the inductive hypothesis on subterms, and applying one or more distributive laws (16)–(19). For example, for pairing:

$$\begin{split} \left[\!\left[\langle e_1, e_2 \rangle\right]\!\right]_{\mathsf{b}} &\equiv & \left[\!\left[e_1\right]\!\right]_{\mathsf{b}} & \&\&_{\mathsf{b}} & \left[\!\left[e_2\right]\!\right]_{\mathsf{b}} \\ &\equiv & \left(\mathsf{lift}_{\mathsf{b}} & \left[\!\left[e_1\right]\!\right]_{\mathsf{a}}\right) & \&\&_{\mathsf{b}} & \left(\mathsf{lift}_{\mathsf{b}} & \left[\!\left[e_2\right]\!\right]_{\mathsf{a}}\right) \\ &\equiv & \left.\mathsf{lift}_{\mathsf{b}} & \left(\left[\!\left[e_1\right]\!\right]_{\mathsf{a}} & \&\&_{\mathsf{a}} & \left[\!\left[e_2\right]\!\right]_{\mathsf{a}}\right) \\ &\equiv & \left.\mathsf{lift}_{\mathsf{b}} & \left[\!\left[\langle e_1, e_2 \rangle\right]\!\right]_{\mathsf{c}} \end{split}$$

It is not hard to check the remaining cases.

If we assume that $lift_b$ defines correct behavior for arrow bin terms of arrow a, and prove that lift_b is a homomorphism, then by Theorem 3.6, $[\cdot]_b$ is correct.

The Bottom and Mapping Arrows

Using the diagram in (3) as a sort of map, we are starting in the upper-left corner:

$$\begin{array}{ccccc}
X \sim_{\perp} Y & \xrightarrow{\text{lift}_{map}} & X \underset{\mathsf{map}}{\sim} Y & \xrightarrow{\text{lift}_{pre}} & X \underset{\mathsf{pre}}{\sim} Y \\
\eta_{\perp^{*}} \downarrow & & \downarrow \eta_{\mathsf{map}^{*}} & \downarrow \eta_{\mathsf{pre}^{*}} \\
X \sim_{\perp^{*}} Y & \xrightarrow{\text{lift}_{\mathsf{map}^{*}}} & X \underset{\mathsf{map}}{\sim} Y & \xrightarrow{\text{lift}_{\mathsf{pre}^{*}}} & X \underset{\mathsf{pre}^{*}}{\sim} Y
\end{array} \tag{25}$$

Through Section 6, we move across the top to $X \underset{\text{pre}}{\sim} Y$.

To use Theorem 3.6 to prove correct the interpretations of expressions as preimage arrow computations, we need the preimage arrow to be homomorphic to a simpler arrow whose behavior is well-understood. One obvious candidate is the function arrow (10). However, we will need to explicitly handle divergence as an error value, so we need a slightly more complicated arrow for which running computations may raise an error.

Figure 3 defines the **bottom arrow**. Its computations are of type $x \leadsto_{\perp} y ::= x \Rightarrow y_{\perp}$, where the inhabitants of y_{\perp} are

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p ::\equiv x := e; \dots; e
                                                                                             e ::\equiv x \ e \mid \mathsf{let} \ e \ e \mid \mathsf{env} \ n \mid \langle e, e \rangle \mid \mathsf{fst} \ e \mid \mathsf{snd} \ e \mid \mathsf{if} \ e \ e \ e \mid v \mid \cdots
                                                                                             v ::\equiv [first-order constants]
\llbracket x := e; \dots; e_{body} \rrbracket_{\mathsf{a}} :\equiv x := \llbracket e \rrbracket_{\mathsf{a}}; \dots; \llbracket e_{body} \rrbracket_{\mathsf{a}}
                                                                                                                                                                                                                 \llbracket \langle e_1, e_2 \rangle \rrbracket_{\mathbf{a}} \ :\equiv \ \llbracket e_1 \rrbracket_{\mathbf{a}} \ \&\&\&_{\mathbf{a}} \ \llbracket e_2 \rrbracket_{\mathbf{a}}
                                        [x \ e]_a :\equiv [\langle e, \langle \rangle \rangle]_a >\gg_a x
                                                                                                                                                                                                                         \llbracket \mathsf{fst} \ e \rrbracket_{\mathsf{a}} :\equiv \llbracket e \rrbracket_{\mathsf{a}} > _{\mathsf{a}} \mathsf{arr}_{\mathsf{a}} \mathsf{fst}
                    \llbracket \mathsf{let}\ e\ e_{body} \rrbracket_{\mathsf{a}}\ :\equiv\ \bigl(\llbracket e \rrbracket_{\mathsf{a}}\ \&\&\&_{\mathsf{a}}\ \mathsf{arr}_{\mathsf{a}}\ \mathsf{id}\bigr) >\!\!>_{\mathsf{a}}\ \llbracket e_{body} \rrbracket_{\mathsf{a}}
                                                                                                                                                                                                                       [\![\mathsf{snd}\ e]\!]_\mathsf{a}\ :\equiv\ [\![e]\!]_\mathsf{a}\ >\!\!>\!\!>_\mathsf{a}\ \mathsf{arr}_\mathsf{a}\ \mathsf{snd}
                                  [[env \ 0]]_a :\equiv arr_a fst
                                                                                                                                                                                                         \llbracket \mathsf{if} \ e_c \ e_t \ e_f \rrbracket_{\mathsf{a}} \ :\equiv \ \mathsf{ifte_a} \ \llbracket e_c \rrbracket_{\mathsf{a}} \ (\mathsf{lazy_a} \ \lambda 0. \, \llbracket e_t \rrbracket_{\mathsf{a}}) \ (\mathsf{lazy_a} \ \lambda 0. \, \llbracket e_f \rrbracket_{\mathsf{a}})
                [[env (n+1)]]_a :\equiv arr_a snd >>>>_a [[env n]]_a
                                                                                                                                                                                                                                   \llbracket v \rrbracket_{\mathtt{a}} :\equiv \operatorname{arr}_{\mathtt{a}} (\operatorname{const} v)
                                                      id := \lambda a. a
                                      const b := \lambdaa.b
                                                                                                                                                                                                                subject to [p]_a:\langle\rangle\leadsto_a y for some y
```

Figure 2: Transformation from a let-calculus with first-order definitions and De-Bruijn-indexed bindings to computations in arrow a.

```
\begin{array}{lll} x \rightsquigarrow_{\perp} y & ::= & x \Rightarrow y_{\perp} & \text{ifte}_{\perp} : (x \rightsquigarrow_{\perp} Bool) \Rightarrow (x \rightsquigarrow_{\perp} y) \Rightarrow (x \rightsquigarrow_{\perp} y) \\ \text{arr}_{\perp} : (x \Rightarrow y) \Rightarrow (x \rightsquigarrow_{\perp} y) & \text{ifte}_{\perp} : f_{1} \ f_{2} \ f_{3} \ a & := \ case \ f_{1} \ a \\ & \text{true} \ \longrightarrow \ f_{2} \ a \\ & \text{false} \ \longrightarrow \ f_{3} \ a \\ & \perp \ \longrightarrow \ \perp \end{array} (\ggg_{\perp}) : (x \rightsquigarrow_{\perp} y) \Rightarrow (y \rightsquigarrow_{\perp} z) \Rightarrow (x \rightsquigarrow_{\perp} z) \\ (f_{1} \ggg_{\perp} f_{2}) \ a & := \ \text{if} \ (f_{1} \ a = \bot) \ \bot \ (f_{2} \ (f_{1} \ a)) \\ & \text{lazy}_{\perp} : (1 \Rightarrow (x \rightsquigarrow_{\perp} y)) \Rightarrow (x \rightsquigarrow_{\perp} y) \\ & \text{lazy}_{\perp} \ f \ a & := \ f \ 0 \ a \\ \\ (\&\&\&_{\perp}) : (x \rightsquigarrow_{\perp} y_{1}) \Rightarrow (x \rightsquigarrow_{\perp} y_{2}) \Rightarrow (x \rightsquigarrow_{\perp} \langle y_{1}, y_{2} \rangle) \\ & (f_{1} \&\&\&_{\perp} f_{2}) \ a & := \ \text{if} \ (f_{1} \ a = \bot \ \text{or} \ f_{2} \ a = \bot) \ \bot \ \langle f_{1} \ a, f_{2} \ a \rangle \end{array}
```

Figure 3: Bottom arrow definitions.

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the error value \bot as well as the inhabitants of y. The type Bool_\bot , for example, denotes the members of $\mathsf{Bool} \uplus \{\bot\}$.

If we wish to claim that $x \leadsto_{\perp} y$ computations obey the arrow laws, we need a notion of equivalence for lambdas that is coarser than observational equivalence.

Definition 4.1 (bottom arrow equivalence). Two bottom arrow computations $f_1: x \leadsto_{\perp} y$ and $f_2: x \leadsto_{\perp} y$ are equivalent, or $f_1 \equiv f_2$, when $f_1 \equiv f_2$ a for all a: x.

Theorem 4.2. $\operatorname{arr}_{\perp}$, (&& $_{\perp}$), (>>> $_{\perp}$), ifte $_{\perp}$ and $\operatorname{lazy}_{\perp}$ define

Proof. The bottom arrow is the Maybe monad's Kleisli arrow with Nothing = \bot . The proof of (24) (pure computations distribute over $|azy_{\bot}\rangle$ is trivial.

4.1 Deriving the Mapping Arrow

Theorems about functions in set theory tend to be about mappings, not about lambdas that may raise errors. As in intermediate step, then, we need an arrow whose computations produce mappings or are mappings themselves.

It is tempting to try to make the mapping arrow's computations mapping-valued; i.e. define it using $X\underset{map}{\sim}Y:=X \rightharpoonup Y$, with $f_1 \ggg_{map} f_2 := f_2 \circ_{map} f_1$ and $f_1 \ggg_{map} f_2 := \langle f_1, f_2 \rangle_{map}$. Unfortunately, we could not define $arr_{map}: (X \Rightarrow Y) \Rightarrow (X \rightharpoonup Y)$: to define a mapping, we need a domain, but lambdas' domains are unobservable.

To parameterize mapping arrow computations on a domain, we define the *mapping arrow* computation type as

$$X \underset{map}{\leadsto} Y ::= Set X \Rightarrow (X \rightarrow Y)$$
 (26)

The fact that \bot is absent from Y in Set X \Rightarrow (X \rightharpoonup Y) will make it easier to exclude diverging inputs. Its absence and the fact that the type parameters denote sets will make it easier to apply well-known theorems from measure theory, which know nothing of lambda types and propagating error values.

To use Theorem 3.6 to prove that expressions interpreted using $[\![\cdot]\!]_{\mathsf{map}}$ behave correctly, we need to define correctness using a lift from the bottom arrow to the mapping arrow. It is helpful to have a standalone function domain_{\perp} that computes the subset of A on which f does not return \bot . We define that first, and then define lift_map in terms of it:

$$domain_{\perp} : (X \leadsto_{\perp} Y) \Rightarrow Set X \Rightarrow Set X$$
$$domain_{\perp} f A := \{ a \in A \mid f \ a \neq \bot \}$$
 (27)

$$lift_{map} : (X \leadsto_{\perp} Y) \Rightarrow (X \underset{map}{\leadsto} Y) \\
lift_{map} f A := mapping f (domain_{\perp} f A)$$
(28)

So lift_{map} f A is like mapping f A, but without inputs that produce errors—a good notion of correctness.

If $\mathsf{lift}_{\mathsf{map}}$ is to be a homomorphism, mapping arrow computation equivalence needs to be more extensional.

$$\begin{array}{llll} X_{\stackrel{\longrightarrow}{map}}Y & ::= \; \mathsf{Set} \; X \Rightarrow (\mathsf{X} \rightharpoonup \mathsf{Y}) & & & & & & & \\ \mathsf{arr}_{\mathsf{map}} : (\mathsf{X} \Rightarrow \mathsf{Y}) \Rightarrow (\mathsf{X}_{\stackrel{\longrightarrow}{map}} \mathsf{Y}) \Rightarrow (\mathsf{X}_{\stackrel{\longrightarrow}{$$

Figure 4: Mapping arrow definitions.

 $\begin{array}{lll} \textbf{Definition 4.3} \ (\text{mapping arrow equivalence}). \ \textit{Two mapping arrow computations } g_1: X_{\stackrel{\longleftrightarrow}{\text{map}}}Y \ \textit{and } g_2: X_{\stackrel{\longleftrightarrow}{\text{map}}}Y \ \textit{are equivalent, or } g_1 \equiv g_2, \ \textit{when } g_1 \ A \equiv g_2 \ A \ \textit{for all } A \subseteq X. \end{array}$

Clearly $\operatorname{\mathsf{arr}_{\mathsf{map}}} := \operatorname{\mathsf{lift}_{\mathsf{map}}} \circ \operatorname{\mathsf{arr}_{\perp}}$ meets the first homomorphism law (15). The following subsections derive (&&_{\mathsf{map}}), (>>>_{\mathsf{map}}), ifte_{\mathsf{map}} and $\operatorname{\mathsf{lazy}_{\mathsf{map}}}$ from bottom arrow combinators, in a way that ensures $\operatorname{\mathsf{lift}_{\mathsf{map}}}$ is an arrow homomorphism. Figure 4 contains the resulting definitions.

4.1.1 Case: Pairing

Starting with the left side of (17), we first expand definitions. For any $f_1: X \leadsto_{\perp} Y$, $f_2: X \leadsto_{\perp} Z$, and $A \subseteq X$,

$$\begin{array}{l} \mbox{lift}_{\mbox{\scriptsize map}} \; (f_1 \; \&\&\&_\perp \; f_2) \; A \\ & \equiv \; \mbox{lift}_{\mbox{\scriptsize map}} \; (\lambda \, a. \, \mbox{if} \; (f_1 \; a = \bot \; \mbox{or} \; f_2 \; a = \bot) \; \bot \; \langle f_1 \; a, f_2 \; a \rangle) \; A \\ & \equiv \; \mbox{let} \; \; f := \lambda \, a. \, \mbox{if} \; (f_1 \; a = \bot \; \mbox{or} \; f_2 \; a = \bot) \; \bot \; \langle f_1 \; a, f_2 \; a \rangle \\ & \quad \mbox{in} \; \; \mbox{mapping} \; f \; (\mbox{domain}_\perp \; f \; A) \end{array} \label{eq:lift}$$

Next, we replace the definition of A' (XXX: fix) with one that does not depend on f, and rewrite in terms of $lift_{map}$ f_1 and $lift_{map}$ f_2 :

$$\begin{array}{l} \mathsf{lift}_{\mathsf{map}} \; \big(\mathsf{f}_1 \; \&\&\&_\perp \; \mathsf{f}_2 \big) \; \mathsf{A} \\ & \equiv \; \mathsf{let} \; \; \mathsf{A}_1 \; := \; \big(\mathsf{domain}_\perp \; \mathsf{f}_1 \; \mathsf{A} \big) \\ & \; \; \mathsf{A}_2 \; := \; \big(\mathsf{domain}_\perp \; \mathsf{f}_2 \; \mathsf{A} \big) \\ & \; \; \mathsf{A}' \; := \; \mathsf{A}_1 \cap \mathsf{A}_2 \\ & \; \mathsf{in} \; \; \mathsf{\lambda} \mathsf{a} \in \mathsf{A}' \cdot \langle \mathsf{f}_1 \; \mathsf{a}, \mathsf{f}_2 \; \mathsf{a} \rangle \\ & \equiv \; \mathsf{let} \; \; \mathsf{g}_1 \; := \; \mathsf{lift}_{\mathsf{map}} \; \mathsf{f}_1 \; \mathsf{A} \\ & \; \; \mathsf{g}_2 \; := \; \mathsf{lift}_{\mathsf{map}} \; \mathsf{f}_2 \; \mathsf{A} \\ & \; \; \; \mathsf{A}' \; := \; \big(\mathsf{domain} \; \mathsf{g}_1 \big) \cap \big(\mathsf{domain} \; \mathsf{g}_2 \big) \\ & \; \mathsf{in} \; \; \mathsf{\lambda} \mathsf{a} \in \mathsf{A}' \cdot \langle \mathsf{g}_1 \; \mathsf{a}, \mathsf{g}_2 \; \mathsf{a} \rangle \\ & \equiv \; \langle \mathsf{lift}_{\mathsf{map}} \; \mathsf{f}_1 \; \mathsf{A}, \mathsf{lift}_{\mathsf{map}} \; \mathsf{f}_2 \; \mathsf{A} \rangle_{\mathsf{map}} \end{array} \tag{30}$$

Substituting g_1 for $lift_{map}$ f_1 and g_2 for $lift_{map}$ f_2 gives a definition for (&& map) (Figure 4) for which (17) holds.

4.1.2 Case: Composition

The derivation of $(\gg)_{map}$ is similar to that of $(\&\&\&_{map})$ but a little more involved.

XXX: add this, maybe cut later

4.1.3 Case: Conditional

Starting with the left side of (18), we expand definitions, and simplify f by restricting it to a domain for which f_1 a $\neq \bot$:

$$\begin{array}{l} \mathsf{lift}_{\mathsf{map}} \; (\mathsf{ifte}_{\bot} \; f_1 \; f_2 \; f_3) \; \mathsf{A} \\ & \equiv \; \mathsf{let} \; \; \mathsf{f} := \lambda \mathsf{a}. \, \mathsf{case} \; \; f_1 \; \mathsf{a} \\ & \; \mathsf{true} \; \longrightarrow \; f_2 \; \mathsf{a} \\ & \; \mathsf{false} \; \longrightarrow \; f_3 \; \mathsf{a} \\ & \; \bot \; \longrightarrow \; \bot \\ & \mathsf{in} \; \; \mathsf{mapping} \; \mathsf{f} \; (\mathsf{domain}_{\bot} \; \mathsf{f} \; \mathsf{A}) \\ & \equiv \; \mathsf{let} \; \; \mathsf{g}_1 := \mathsf{mapping} \; \mathsf{f} \; \mathsf{A} \\ & \; \mathsf{A}_2 := \mathsf{preimage} \; \mathsf{g}_1 \; \{\mathsf{true}\} \\ & \; \mathsf{A}_3 := \mathsf{preimage} \; \mathsf{g}_1 \; \{\mathsf{false}\} \\ & \; \mathsf{f} := \lambda \mathsf{a}. \, \mathsf{if} \; (f_1 \; \mathsf{a}) \; (f_2 \; \mathsf{a}) \; (f_3 \; \mathsf{a}) \\ & \; \mathsf{in} \; \; \mathsf{mapping} \; \mathsf{f} \; (\mathsf{domain}_{\bot} \; \mathsf{f} \; (\mathsf{A}_2 \uplus \mathsf{A}_3)) \end{array}$$

We finish by converting bottom arrow computations to the mapping arrow and rewriting in terms of (\uplus_{map}) :

$$\begin{array}{l} \mathsf{lift}_{\mathsf{map}} \ (\mathsf{ifte}_\bot \ f_1 \ f_2 \ f_3) \ \mathsf{A} \\ & \equiv \ \mathsf{let} \ \ \mathsf{g}_1 := \mathsf{lift}_{\mathsf{map}} \ f_1 \ \mathsf{A} \\ & \mathsf{g}_2 := \mathsf{lift}_{\mathsf{map}} \ f_2 \ (\mathsf{preimage} \ \mathsf{g}_1 \ \{\mathsf{fue}\}) \\ & \mathsf{g}_3 := \mathsf{lift}_{\mathsf{map}} \ f_3 \ (\mathsf{preimage} \ \mathsf{g}_1 \ \{\mathsf{false}\}) \\ & \mathsf{A}' := (\mathsf{domain} \ \mathsf{g}_2) \uplus (\mathsf{domain} \ \mathsf{g}_3) \\ & \mathsf{in} \ \ \lambda \mathsf{a} \in \mathsf{A}'. \mathsf{if} \ (\mathsf{a} \in \mathsf{domain} \ \mathsf{g}_2) \ (\mathsf{g}_2 \ \mathsf{a}) \ (\mathsf{g}_3 \ \mathsf{a}) \\ & \equiv \ \mathsf{let} \ \ \mathsf{g}_1 := \mathsf{lift}_{\mathsf{map}} \ f_1 \ \mathsf{A} \\ & \mathsf{g}_2 := \mathsf{lift}_{\mathsf{map}} \ f_2 \ (\mathsf{preimage} \ \mathsf{g}_1 \ \{\mathsf{fue}\}) \\ & \mathsf{g}_3 := \mathsf{lift}_{\mathsf{map}} \ \mathsf{g}_3 \ (\mathsf{preimage} \ \mathsf{g}_1 \ \{\mathsf{false}\}) \\ & \mathsf{in} \ \ \mathsf{g}_2 \uplus_{\mathsf{map}} \ \mathsf{g}_3 \end{array}$$

Substituting g_1 for $lift_{map}$ f_1 , g_2 for $lift_{map}$ f_2 , and g_3 for $lift_{map}$ f_3 gives a definition for ifte_{map} (Figure 4) for which (18) holds.

4.1.4 Case: Laziness

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Starting with the left side of (19), we first expand definitions:

$$\begin{array}{l} \mathsf{lift}_{\mathsf{map}} \; \big(\mathsf{lazy}_{\perp} \; \mathsf{f} \big) \; \mathsf{A} \\ & \equiv \; \mathsf{let} \; \; \mathsf{A}' := \mathsf{domain}_{\perp} \; \big(\lambda \, \mathsf{a.f} \; 0 \; \mathsf{a} \big) \; \mathsf{A} \\ & \mathsf{in} \; \; \mathsf{mapping} \; \big(\lambda \, \mathsf{a.f} \; 0 \; \mathsf{a} \big) \; \mathsf{A}' \end{array}$$

 $\lambda_{\rm ZFC}$ does not have an η rule (i.e. $\lambda x. e \ x \not\equiv e$ because e may diverge), but we can use weaker facts. If $A \neq \varnothing$, then domain $_{\perp}$ (λ a. f 0 a) $A \equiv {\sf domain}_{\perp}$ (f 0) A. Further, it diverges if and only if mapping (f 0) A' diverges. Therefore, if $A \neq \varnothing$, we can replace λ a. f 0 a with f 0. If $A = \varnothing$, then

$$\begin{split} & \mathsf{lift}_{\mathsf{map}} \ \big(\mathsf{lazy}_{\bot} \ f \big) \ \mathsf{A} = \varnothing \ (\mathsf{the \ empty \ mapping}), \ \mathsf{so} \\ & \mathsf{lift}_{\mathsf{map}} \ \big(\mathsf{lazy}_{\bot} \ f \big) \ \mathsf{A} \\ & \equiv \ \mathsf{if} \ (\mathsf{A} = \varnothing) \ \varnothing \ \big(\mathsf{mapping} \ (\mathsf{f} \ 0) \ \big(\mathsf{domain}_{\bot} \ (\mathsf{f} \ 0) \ \mathsf{A} \big) \big) \\ & \equiv \ \mathsf{if} \ (\mathsf{A} = \varnothing) \ \varnothing \ \big(\mathsf{lift}_{\mathsf{map}} \ (\mathsf{f} \ 0) \ \mathsf{A} \big) \end{split}$$

Substituting g 0 for lift_{map} (f 0) gives a definition for $lazy_{map}$ (Figure 4) for which (19) holds.

4.1.5 Correctness

Theorem 4.4 (mapping arrow correctness). lift an arrow homomorphism.

Proof. By construction. \Box

Corollary 4.5 (semantic correctness). For all expressions e, $\llbracket e \rrbracket_{\mathsf{map}} \equiv \mathsf{lift}_{\mathsf{map}} \ \llbracket e \rrbracket_{\perp}$.

Without restrictions, mapping arrow computations can be quite unruly. For example, the following computation is well-typed, but returns the identity mapping on Bool when applied to an empty domain, and the empty mapping when applied to any other domain:

nonmonotone : Bool
$$\underset{\text{map}}{\text{map}}$$
 Bool nonmonotone A := if (A = \varnothing) (mapping id Bool) \varnothing (33)

It would be nice if we could be sure that every $X_{\text{map}} Y$ is not only monotone, but acts as if it returned restricted mappings. The following equivalent property is easier to state, and makes proving the arrow laws simple.

Definition 4.6 (mapping arrow law). Let $g: X_{\widetilde{map}} Y$. If there exists an $f: X \leadsto_{\perp} Y$ such that $g \equiv lift_{map} f$, then g obeys the mapping arrow law.

XXX: mapping arrow restriction theorem

We assume from here on that the mapping arrow law holds for all $g: X_{\widehat{map}} Y$. By homomorphism of $lift_{map}$, mapping arrow combinators return computations that obey this law.

Theorem 4.7. lift_{map} is an arrow epimorphism.

Proof. Follows from Theorem 4.4 and Definition 4.6. \Box

Corollary 4.8. arr_{map} , (&&map), (>>>map), iftemap and lazymap define an arrow.

5. Lazy Preimage Mappings

On a computer, we do not often have the luxury of testing each function input to see whether it belongs to a preimage set. Even for finite domains, doing so is often intractable.

If we wish to compute with infinite sets in the language implementation, we will need an abstraction that makes it easy to replace computation on points with computation on sets whose representations allow efficient operations. Therefore, in the preimage arrow, we will confine computation on points to instances of

$$X \xrightarrow{\text{pre}} Y ::= \langle \text{Set } Y, \text{Set } Y \Rightarrow \text{Set } X \rangle$$
 (34)

Like a mapping, an $X \xrightarrow[pre]{} Y$ has an observable domain—but computing the table of input-output pairs is delayed. We therefore call these *lazy preimage mappings*.

Converting a mapping to a lazy preimage mapping requires constructing a delayed application of preimage:

pre :
$$(X \rightarrow Y) \Rightarrow (X \xrightarrow{pre} Y)$$

pre g := $\langle \text{range g}, \lambda B. \text{ preimage g B} \rangle$ (35)

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Applying a preimage mapping to any subset of its codomain: (XXX: unclear prose)

$$\begin{array}{l} \mathsf{ap}_{\mathsf{pre}} : (\mathsf{X} \underset{\mathsf{pre}}{\longrightarrow} \mathsf{Y}) \Rightarrow \mathsf{Set} \; \mathsf{Y} \Rightarrow \mathsf{Set} \; \mathsf{X} \\ \mathsf{ap}_{\mathsf{pre}} \; \langle \mathsf{Y}', \mathsf{p} \rangle \; \mathsf{B} \; := \; \mathsf{p} \; (\mathsf{B} \cap \mathsf{Y}') \end{array} \tag{36}$$

The necessary property here is that using ap_{pre} to compute preimages is the same as computing them from a mapping using preimage.

Imported Lemma 5.1. Let $g \in X \to Y$. For all $B \subseteq Y$ and Y' such that range $g \subseteq Y' \subseteq Y$, preimage $g (B \cap Y') = P$ preimage $g \in Y$.

Theorem 5.2 (ap_{pre} computes preimages). Let $g \in X \rightharpoonup Y$. For all $B \subseteq Y$, ap_{pre} (pre g) $B = \text{preimage } g \ B$.

Proof. Expand definitions and apply Lemma 5.1 with Y' = range g.

Figure 5 defines more operations on preimage mappings, including pairing, composition, and disjoint union operations corresponding to the mapping operations in Figure 1. The next three theorems establish that pre is a homomorphism (though not an arrow homomorphism): it distributes over mapping operations to yield preimage mapping operations. We will use these facts to derive the preimage arrow from the mapping arrow.

First, we need preimage mappings to be equivalent when they compute the same preimages.

Definition 5.3 (preimage mapping equivalence). Two preimage mappings $h_1: X \xrightarrow{pre} Y$ and $h_2: X \xrightarrow{pre} Y$ are equivalent, or $h_1 \equiv h_2$, when $ap_{pre} \ h_1 \ B \equiv ap_{pre} \ h_2 \ B$ for all $B \subseteq Y$.

The following subsections prove distributive laws for preimage mapping pairing, composition, and disjoint union.

XXX: moar text in following subsections

5.1 Preimage Mapping Pairing

Imported Lemma 5.4 (preimage distributes over $\langle \cdot, \cdot \rangle_{map}$ and (\times)). Let $g_1 \in X \rightharpoonup Y_1$ and $g_2 \in X \rightharpoonup Y_2$. For all $B_1 \subseteq Y_1$ and $B_2 \subseteq Y_2$, preimage $\langle g_1, g_2 \rangle_{map}$ $(B_1 \times B_2) =$ (preimage $g_1 \ B_1) \cap$ (preimage $g_2 \ B_2$).

Theorem 5.5 (pre distributes over $\langle \cdot, \cdot \rangle_{\mathsf{map}}$). Let $\mathsf{g}_1 \in \mathsf{X} \rightharpoonup \mathsf{Y}_1$ and $\mathsf{g}_2 \in \mathsf{X} \rightharpoonup \mathsf{Y}_2$. Then pre $\langle \mathsf{g}_1, \mathsf{g}_2 \rangle_{\mathsf{map}} \equiv \langle \mathsf{pre} \ \mathsf{g}_1, \mathsf{pre} \ \mathsf{g}_2 \rangle_{\mathsf{pre}}$.

Proof. Let $\langle Y_1', p_1 \rangle := pre g_1$ and $\langle Y_2', p_2 \rangle := pre g_2$. Starting from the right side, for all $B \in Y_1 \times Y_2$,

$$\begin{array}{l} \mathsf{ap}_{\mathsf{pre}} \ \langle \mathsf{pre} \ \mathsf{g}_1, \mathsf{pre} \ \mathsf{g}_2 \rangle_{\mathsf{pre}} \ \mathsf{B} \\ & \equiv \ \mathsf{let} \ \ \mathsf{Y}' := \mathsf{Y}_1' \times \mathsf{Y}_2' \\ & \mathsf{p} := \lambda \, \mathsf{B}. \ \bigcup_{\substack{\langle y_1, y_2 \rangle \in \mathsf{B} \\ \langle y_1, y_2 \rangle \in \mathsf{B} \cap \{\mathsf{Y}_1' \times \mathsf{Y}_2' \}}} (\mathsf{p}_1 \ \{y_1\}) \cap (\mathsf{p}_2 \ \{y_2\}) \\ & \equiv \ \bigcup_{\substack{\langle y_1, y_2 \rangle \in \mathsf{B} \cap \{\mathsf{Y}_1' \times \mathsf{Y}_2' \} \\ \langle y_1, y_2 \rangle \in \mathsf{B} \cap \{\mathsf{Y}_1' \times \mathsf{Y}_2' \}}} (\mathsf{preimage} \ \mathsf{g}_1 \ \{y_1\}) \cap (\mathsf{preimage} \ \mathsf{g}_2 \ \{y_2\}) \\ & \equiv \ \bigcup_{\substack{\langle y_1, y_2 \rangle \in \mathsf{B} \cap \{\mathsf{Y}_1' \times \mathsf{Y}_2' \} \\ \langle y_1, y_2 \rangle \in \mathsf{B} \cap \{\mathsf{Y}_1' \times \mathsf{Y}_2' \}}} (\mathsf{preimage} \ \langle \mathsf{g}_1, \mathsf{g}_2 \rangle_{\mathsf{map}} \ \{y\}) \\ & \equiv \ \mathsf{preimage} \ \langle \mathsf{g}_1, \mathsf{g}_2 \rangle_{\mathsf{map}} \ \mathsf{B} \\ & \equiv \ \mathsf{ap}_{\mathsf{pre}} \ (\mathsf{pre} \ \langle \mathsf{g}_1, \mathsf{g}_2 \rangle_{\mathsf{map}}) \ \mathsf{B} \end{array}$$

$$\begin{array}{lll} X \underset{\overrightarrow{pre}}{\rightharpoonup} Y ::= \langle Set \ Y, Set \ Y \Rightarrow Set \ X \rangle & \langle \cdot, \cdot \rangle_{pre} : (X \underset{\overrightarrow{pre}}{\rightharpoonup} Y_1) \Rightarrow (X \underset{\overrightarrow{pre}}{\rightharpoonup} Y_1 \times Y_2) \\ & \langle (Y_1', p_1), \langle Y_2', p_2 \rangle \rangle_{pre} := let \ Y' := Y_1' \times Y_2' \\ & p := \lambda B. \ \bigcup_{\langle b_1, b_2 \rangle \in B} (p_1 \ \{b_1\}) \cap (p_2 \ \{b_2\}) \\ & p_1 = \lambda B. \ \bigcup_{\langle b_1, b_2 \rangle \in B} (p_1 \ \{b_1\}) \cap (p_2 \ \{b_2\}) \\ & p_2 = \lambda B. \ \bigcup_{\langle b_1, b_2 \rangle \in B} (p_1 \ \{b_1\}) \cap (p_2 \ \{b_2\}) \\ & p_2 = \lambda B. \ \bigcup_{\langle b_1, b_2 \rangle \in B} (p_1 \ \{b_1\}) \cap (p_2 \ \{b_2\}) \\ & p_2 = \lambda B. \ (p_2 \ C) \rangle \\ & p_2 = \lambda B. \ (p_2 \ C) \rangle \\ & p_2 = \lambda B. \ (p_2 \ C) \rangle \\ & p_2 = \lambda B. \ (p_2 \ C) \rangle \\ & p_2 = \lambda B. \ (p_2 \ C) \rangle \\ & p_2 = \lambda B. \ (p_2 \ C) \rangle \\ & p_2 = \lambda B. \ (p_2 \ C) \rangle \\ & p_2 = \lambda B. \ (p_2 \ C) \rangle \\ & p_2 = \lambda B. \ (p_2 \ C) \rangle \\ & p_2 = \lambda B. \ (p_2 \ C) \rangle \\ & p_2 = \lambda B. \ (p_2 \ C) \rangle \\ & p_3 = \lambda B. \ (p_2 \ C) \rangle \\ & p_4 = \lambda B. \ (p_2 \ C) \rangle \\ & p_4 = \lambda B. \ (p_2 \ C) \rangle \\ & p_5 = \lambda B. \ (p_2 \ C) \rangle \\ & p_6 = \lambda B. \ (p_2 \ C) \rangle \\ & p_6 = \lambda B. \ (p_2 \ C) \rangle \\ & p_6 = \lambda B. \ (p_2 \ C) \rangle \\ & p_6 = \lambda B. \ (p_2 \ C) \rangle \\ & p_7 = \lambda B. \ (p_2 \ C) \rangle \\ & p_7 = \lambda B. \ (p_7 \ C) \rangle \\ & p_7 = \lambda$$

Figure 5: Lazy preimage mappings and operations.

5.2 Preimage Mapping Composition

Imported Lemma 5.6 (preimage distributes over (o_{map})). Let $g_1 \in X \rightharpoonup Y$ and $g_2 \in Y \rightharpoonup Z$. For all $C \subseteq$ preimage $(g_2 \circ_{map} g_1) C = preimage g_1 (preimage g_2 C).$

Theorem 5.7 (pre distributes over (\circ_{map})). Let $g_1 \in X \rightharpoonup Y$ and $g_2 \in Y \rightarrow Z$. Then pre $(g_2 \circ_{\mathsf{map}} g_1) \equiv (\mathsf{pre} g_2) \circ_{\mathsf{pre}} (\mathsf{pre} g_1)$.

Proof. Let $\langle \mathsf{Z}', \mathsf{p}_2 \rangle := \mathsf{pre} \; \mathsf{g}_2$. Starting from the right side, for all $C \subseteq Z$,

$$\begin{array}{l} \mathsf{ap}_{\mathsf{pre}} \; ((\mathsf{pre} \; \mathsf{g}_2) \circ_{\mathsf{pre}} (\mathsf{pre} \; \mathsf{g}_1)) \; \mathsf{C} \\ \equiv \; \mathsf{let} \; \; \mathsf{h} := \lambda \, \mathsf{C}. \, \mathsf{ap}_{\mathsf{pre}} \; (\mathsf{pre} \; \mathsf{g}_1) \; (\mathsf{p}_2 \; \mathsf{C}) \\ \qquad \qquad \mathsf{in} \; \; \mathsf{h} \; (\mathsf{C} \cap \mathsf{Z}') \\ \equiv \; \mathsf{ap}_{\mathsf{pre}} \; (\mathsf{pre} \; \mathsf{g}_1) \; (\mathsf{p}_2 \; (\mathsf{C} \cap \mathsf{Z}')) \\ \equiv \; \mathsf{ap}_{\mathsf{pre}} \; (\mathsf{pre} \; \mathsf{g}_1) \; (\mathsf{ap}_{\mathsf{pre}} \; (\mathsf{pre} \; \mathsf{g}_2) \; \mathsf{C}) \\ \equiv \; \mathsf{preimage} \; \mathsf{g}_1 \; (\mathsf{preimage} \; \mathsf{g}_2 \; \mathsf{C}) \\ \equiv \; \mathsf{preimage} \; (\mathsf{g}_2 \circ_{\mathsf{map}} \mathsf{g}_1) \; \mathsf{C} \\ \equiv \; \mathsf{ap}_{\mathsf{pre}} \; (\mathsf{pre} \; (\mathsf{g}_2 \circ_{\mathsf{map}} \mathsf{g}_1)) \; \mathsf{C} \end{array}$$

Preimage Mapping Disjoint Union

Imported Lemma 5.8 (preimage distributes over (\uplus_{map})). Let $g_1 \in X \rightharpoonup Y$ and $g_2 \in X \rightharpoonup Y$ have disjoint domains. For all $B \subseteq Y$, preimage $(g_1 \uplus_{map} g_2) B = (preimage g_1 B) \uplus$ (preimage g_2 B).

Theorem 5.9 (pre distributes over (\uplus_{map})). Let $g_1 \in X \rightharpoonup Y$ and $g_2 \in X \rightarrow Y$ have disjoint domains. Then pre $(g_1 \uplus_{map}$ $g_2) \equiv (\text{pre } g_1) \uplus_{\text{pre}} (\text{pre } g_2).$

Proof. Let $Y'_1 := \text{range } g_1 \text{ and } Y'_2 := \text{range } g_2$. Starting from the right side, for all $B \subseteq Y$,

$$\begin{array}{l} \mathsf{ap}_{\mathsf{pre}} \; ((\mathsf{pre} \; \mathsf{g}_1) \uplus_{\mathsf{pre}} \; (\mathsf{pre} \; \mathsf{g}_2)) \; \mathsf{B} \\ \equiv \; \mathsf{let} \; \mathsf{Y}' := \mathsf{Y}_1' \cup \mathsf{Y}_2' \\ \qquad \qquad \qquad \mathsf{h} := \lambda \mathsf{B}. \; (\mathsf{ap}_{\mathsf{pre}} \; (\mathsf{pre} \; \mathsf{g}_1) \; \mathsf{B}) \uplus (\mathsf{ap}_{\mathsf{pre}} \; (\mathsf{pre} \; \mathsf{g}_2) \; \mathsf{B}) \\ \qquad \qquad \mathsf{in} \; \mathsf{h} \; (\mathsf{B} \cap \mathsf{Y}') \\ \equiv \; (\mathsf{ap}_{\mathsf{pre}} \; (\mathsf{pre} \; \mathsf{g}_1) \; (\mathsf{B} \cap (\mathsf{Y}_1' \cup \mathsf{Y}_2'))) \uplus \\ \qquad (\mathsf{ap}_{\mathsf{pre}} \; (\mathsf{pre} \; \mathsf{g}_2) \; (\mathsf{B} \cap (\mathsf{Y}_1' \cup \mathsf{Y}_2'))) \\ \equiv \; (\mathsf{preimage} \; \mathsf{g}_1 \; (\mathsf{B} \cap (\mathsf{Y}_1' \cup \mathsf{Y}_2'))) \\ \equiv \; \mathsf{preimage} \; (\mathsf{g}_1 \uplus_{\mathsf{map}} \; \mathsf{g}_2) \; (\mathsf{B} \cap (\mathsf{Y}_1' \cup \mathsf{Y}_2')) \\ \equiv \; \mathsf{preimage} \; (\mathsf{g}_1 \uplus_{\mathsf{map}} \; \mathsf{g}_2) \; \mathsf{B} \\ \equiv \; \mathsf{ap}_{\mathsf{pre}} \; (\mathsf{pre} \; (\mathsf{g}_1 \uplus_{\mathsf{map}} \; \mathsf{g}_2)) \; \mathsf{B} \end{array}$$

Deriving the Preimage Arrow

We are ready to define an arrow that runs expressions backward on sets of outputs. Its computations should produce preimage mappings or be preimage mappings themselves.

As with the mapping arrow and mappings, we cannot have $X \underset{pre}{\sim} Y ::= X \underset{pre}{\sim} Y$: we run into trouble trying to define $\mathsf{arr}_{\mathsf{pre}}$ because a preimage mapping needs an observable range. To get one, it is easiest to parameterize preimage computations on a Set X; therefore the preimage arrow type constructor is

$$X \underset{\text{pre}}{\leadsto} Y ::= \text{Set } X \Rightarrow (X \underset{\text{pre}}{\leadsto} Y)$$
 (37)

or Set $X \Rightarrow \langle Set Y, Set Y \Rightarrow Set X \rangle$. To deconstruct the type, a preimage arrow computation computes a range first, and returns the range and a lambda that computes preimages.

To use Theorem 3.6, we need to define correctness using a lift from the mapping arrow to the preimage arrow:

$$\begin{aligned}
& \mathsf{lift}_{\mathsf{pre}} : (\mathsf{X}_{\mathsf{map}} \mathsf{Y}) \Rightarrow (\mathsf{X}_{\mathsf{pre}} \mathsf{Y}) \\
& \mathsf{lift}_{\mathsf{pre}} \; \mathsf{g} \; \mathsf{A} \; := \; \mathsf{pre} \; (\mathsf{g} \; \mathsf{A})
\end{aligned} \tag{38}$$

By Theorem 5.2, for all $g: X_{man} Y$, $A \subseteq X$ and $B \subseteq Y$,

$$ap_{pre}$$
 (lift_{pre} g A) B \equiv preimage (g A) B (39)

Roughly, lifted mapping arrow computations compute correct preimages, exactly as we should expect them to.

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Again, we need a coarser notion of equivalence.

Definition 6.1 (Preimage arrow equivalence). Two preimage arrow computations $h_1: X \underset{\widetilde{pre}}{\sim} Y$ and $h_2: X \underset{\widetilde{pre}}{\sim} Y$ are equivalent, or $h_1 \equiv h_2$, when $h_1 \triangleq h_2$ A for all $A \subseteq X$.

As with $\mathsf{arr}_{\mathsf{map}}$, defining $\mathsf{arr}_{\mathsf{pre}}$ as a composition meets (15). The following subsections derive (\mathbb{\text{\$\omega}\$}\mathbb{\text{\$\emptyre}\$}_{\mathsf{pre}}), (>>>_{\mathsf{pre}}), ifte_{\mathsf{pre}} and $\mathsf{lazy}_{\mathsf{pre}}$ from mapping arrow combinators, in a way that ensures lift_{\mathsf{pre}} is an arrow homomorphism from the mapping arrow to the preimage arrow. Figure 6 contains the resulting definitions.

XXX: try paragraph headings instead of subsections

6.1 Case: Pairing

Starting with the left side of (17), we expand definitions, apply Theorem 5.5, and rewrite in terms of lift_{pre}:

$$\begin{array}{l} \mathsf{ap}_\mathsf{pre} \; \big(\mathsf{lift}_\mathsf{pre} \; \big(\mathsf{g}_1 \; \&\!\!\&_\mathsf{map} \; \mathsf{g}_2 \big) \; \mathsf{A} \big) \; \mathsf{B} \\ & \equiv \; \mathsf{ap}_\mathsf{pre} \; \big(\mathsf{pre} \; \langle \mathsf{g}_1 \; \mathsf{A}, \mathsf{g}_2 \; \mathsf{A} \rangle_\mathsf{map} \big) \; \mathsf{B} \\ & \equiv \; \mathsf{ap}_\mathsf{pre} \; \langle \mathsf{pre} \; (\mathsf{g}_1 \; \mathsf{A}), \mathsf{pre} \; (\mathsf{g}_2 \; \mathsf{A}) \rangle_\mathsf{pre} \; \mathsf{B} \\ & \equiv \; \mathsf{ap}_\mathsf{pre} \; \langle \mathsf{lift}_\mathsf{pre} \; \mathsf{g}_1 \; \mathsf{A}, \mathsf{lift}_\mathsf{pre} \; \mathsf{g}_2 \; \mathsf{A} \rangle_\mathsf{pre} \; \mathsf{B} \end{array}$$

Substituting h_1 for lift_{pre} g_1 and h_2 for lift_{pre} g_2 , and removing the application of ap_{pre} from both sides of the equivalence gives a definition of (&&&_{pre}) (Figure 6) for which (17) holds.

6.2 Case: Composition

Starting with the left side of (16), we expand definitions, apply Theorem 5.7 and rewrite in terms of lift_{pre}:

Substituting h_1 for lift_{pre} g_1 and h_2 for lift_{pre} g_2 , and removing the application of ap_{pre} from both sides of the equivalence gives a definition of (\gg_{pre}) (Figure 6) for which (16) holds.

6.3 Case: Conditional

Starting with the left side of (18), we expand terms, apply Theorem 5.9, rewrite in terms of lift_{pre}, and apply Theorem 5.2 in the definitions of h_2 and h_3 :

Substituting h_1 for lift_{pre} g_1 , h_2 for lift_{pre} g_2 and h_3 for lift_{pre} g_3 , and removing the application of ap_{pre} from both sides of the equivalence gives a definition of ifte_{pre} (Figure 6) for which (18) holds.

6.4 Case: Laziness

Starting with the left side of (19), expand definitions, distribute pre over the branches of if, and rewrite in terms of lift_{pre} (g 0):

$$\begin{array}{l} \mathsf{ap}_\mathsf{pre} \; \big(\mathsf{lift}_\mathsf{pre} \; \big(\mathsf{lazy}_\mathsf{map} \; \mathsf{g} \big) \; \mathsf{A} \big) \; \mathsf{B} \\ & \equiv \; \mathsf{let} \; \; \mathsf{g'} \; := \; \mathsf{if} \; (\mathsf{A} = \varnothing) \; \varnothing \; (\mathsf{g} \; 0 \; \mathsf{A}) \\ & \quad \mathsf{in} \; \; \mathsf{ap}_\mathsf{pre} \; \big(\mathsf{pre} \; \mathsf{g'} \big) \; \mathsf{B} \\ & \equiv \; \mathsf{let} \; \; \mathsf{h} \; := \; \mathsf{if} \; (\mathsf{A} = \varnothing) \; \big(\mathsf{pre} \; \varnothing \big) \; \big(\mathsf{pre} \; \big(\mathsf{g} \; 0 \; \mathsf{A} \big) \big) \\ & \quad \mathsf{in} \; \; \mathsf{ap}_\mathsf{pre} \; \mathsf{h} \; \mathsf{B} \\ & \equiv \; \mathsf{let} \; \; \mathsf{h} \; := \; \mathsf{if} \; \big(\mathsf{A} = \varnothing \big) \; \big(\mathsf{pre} \; \varnothing \big) \; \big(\mathsf{lift}_\mathsf{pre} \; \big(\mathsf{g} \; 0 \big) \; \mathsf{A} \big) \\ & \quad \mathsf{in} \; \; \mathsf{ap}_\mathsf{pre} \; \mathsf{h} \; \mathsf{B} \end{array}$$

Substituting h 0 for lift_{pre} (g 0) and removing the application of ap_{pre} from both sides of the equivalence gives a definition for lazy_{pre} (Figure 6) for which (19) holds.

6.5 Correctness

Theorem 6.2 (preimage arrow correctness). lift_{pre} is an arrow homomorphism.

Proof. By construction.
$$\Box$$

Corollary 6.3 (semantic correctness). For all expressions e, $\llbracket e \rrbracket_{\mathsf{pre}} \equiv \mathsf{lift}_{\mathsf{pre}} \ \llbracket e \rrbracket_{\mathsf{map}}.$

As with the mapping arrow, preimage arrow computations can be unruly. We would like to assume that each $h: X_{\stackrel{\sim}{pre}} Y$ acts as if it always computes preimages under restricted mappings. The following equivalent property is easier to state, and makes proving the arrow laws simple.

Definition 6.4 (preimage arrow law). Let $h: X_{pre} Y$. If there exists $a g: X_{map} Y$ such that $h \equiv lift_{pre} g$, then h obeys the **preimage arrow law**.

We assume from here on that the preimage arrow law holds for all $h: X_{\widetilde{pre}} Y$. By homomorphism of lift_{pre}, preimage arrow combinators return computations that obey this law.

Theorem 6.5. lift_{pre} is an arrow epimorphism.

Proof. Follows from Theorem 6.2 and Definition 6.4. \Box

Corollary 6.6. arr_{pre}, (&&pre), (>>>pre), ifte_{pre} and lazy_{pre} define an arrow.

7. Preimages Under Partial Functions

We have defined everything on the top of our roadmap:

and proved that $lift_{map}$ and $lift_{pre}$ are homomorphisms. Now we move down from all three top arrows simultaneously, and prove every morphism in (41) is an arrow homomorphism.

Figure 6: Preimage arrow definitions.

7.1 Motivation

Probabilistic functions that may diverge, but converge with probability 1, are common. They come up not only when practitioners want to build data with random size or structure, but in simpler circumstances as well.

Suppose random retrieves a number $r \in [0,1]$ at index j in an implicit random source r. The following function, which defines the well-known **geometric distribution** with parameter p, counts the number of times random < p is false:

geometric
$$p := if (random < p) 0 (1 + geometric p)$$
 (42)

For any p > 0, geometric p may diverge, but the probability of always taking the false branch is $(1 - p) \times (1 - p) \times (1 - p) \times \cdots = 0$. Therefore, for p > 0, geometric p converges with probability 1.

Suppose we interpret (42) as $h:R\underset{pre}{\leadsto}\mathbb{N}$, a preimage arrow computation from random sources in R to natural numbers, and that we have a probability measure $P\in\mathcal{P}$ $R\longrightarrow[0,1]$. We could compute the probability of any output set $N\subseteq\mathbb{N}$ using P (h R' N), where $R'\subseteq R$ and P R'=1. We have three hurdles to overcome:

- 1. Ensuring h R' converges.
- 2. Ensuring each $r \in R$ contains enough random numbers.
- 3. Determining how random indexes numbers in r.

Ensuring h R' converges is the most difficult, but doing the other two will provide structure that makes it much easier.

7.2 Threading and Indexing

XXX: 'Prior to defn 7.1, you need a transition that communicates "I've just given you the intuition, now let's do the work"'

We clearly need a new arrow that threads a random source through its computations. To ensure it contains enough random numbers, the source should be infinite.

In a pure λ -calculus, random sources are typically infinite streams, threaded monadically: each computation receives and produces a random source. A new combinator is defined that removes the head of the random source and passes the tail along. This is likely preferred because pseudorandom number generators are almost universally monadic.

A little-used alternative is for the random source to be a tree, threaded applicatively: each computation receives, but does not produce, a random source. Multi-argument combinators split the tree and pass subtrees to subcomputations. With either alternative, for arrows defined using pairing, the resulting definitions are large, conceptually difficult, and hard to manipulate. Fortunately, assigning each subcomputation a unique index into a tree-shaped random source, and passing the random source unchanged, is relatively easy.

We need a way to assign unique indexes to expressions.

Definition 7.1 (binary indexing scheme). Let J be an index set, $j_0 \in J$ a distinguished element, and left: $J \Rightarrow J$ and right: $J \Rightarrow J$ be total, injective functions. If for all $j \in J$, j = next j_0 for some finite composition next of left and right, then J, j_0 , left and right define a binary indexing scheme.

For example, let J be the set of lists of $\{0,1\}$, $j_0 := \langle \rangle$, and left $j := \langle 0, j \rangle$ and right $j := \langle 1, j \rangle$.

Alternatively, let J be the set of dyadic rationals in (0,1) (i.e. those with power-of-two denominators), $j_0 := \frac{1}{2}$ and

left
$$(p/q) := (p - \frac{1}{2})/q$$

right $(p/q) := (p + \frac{1}{2})/q$ (43)

With this alternative, left-to-right evaluation order can be made to correspond with the natural order (<) over J.

In any case, the index set J is always countable, and can be thought of as a set of indexes into an infinite binary tree. Values of type $J \to A$ encode an infinite binary tree of A values as an infinite vector (i.e. total mapping).

7.3 Applicative, Associative Store Transformer

We thread a random store through bottom, mapping, and preimage arrow computations by defining an **arrow transformer**: a type constructor that receives and produces an arrow type, and combinators for arrows of the produced type. (XXX: ask Dan B for a cite or Brent Yorgey (tell him I'm Jay's student, who is friends with his advisor))

The applicative store arrow transformer's type constructor takes a store type s and an arrow type $x \leadsto_a y$:

AStore s
$$(x \leadsto_a y) ::= J \Rightarrow (\langle s, x \rangle \leadsto_a y)$$
 (44)

Reading the type, we see that computations receive an index $j \in J$ and produce a computation that receives a store as well as an x. Lifting extracts the x from the input pair and sends it on to the original computation:

$$\eta_{\mathsf{a}^*} : (\mathsf{x} \leadsto_{\mathsf{a}} \mathsf{y}) \Rightarrow \mathsf{AStore} \ \mathsf{s} \ (\mathsf{x} \leadsto_{\mathsf{a}} \mathsf{y})$$

$$\eta_{\mathsf{a}^*} \ \mathsf{f} \ \mathsf{j} \ := \ \mathsf{arr}_{\mathsf{a}} \ \mathsf{snd} \ggg_{\mathsf{a}} \mathsf{f}$$

$$(45)$$

Because f never accesses the store, j is ignored.

Figure 7: AStore (associative store) arrow transformer definitions.

Figure 7 defines the remaining combinators. Each subcomputation receives left j, right j, or some other unique binary index. We thus think of programs interpreted as AStore arrows as being completely unrolled into an infinite binary tree, with each expression labeled with its tree index.

7.4 Partial, Probabilistic Programs

We interpret partial and probabilistic programs using combinators that read a store at an expression index.

Probabilitic Programs To interpret probabilitic programs, we use a random tree as the store.

Definition 7.2 (random source). Let $R := J \rightarrow [0,1]$. A random source is any infinite binary tree $r \in R$.

Let $x \leadsto_{a^*} y ::= AStore R (x \leadsto_a y)$. This combinator returns the number at its tree index in the random source:

$$\operatorname{random}_{a^*} : \mathsf{x} \leadsto_{a^*} [0, 1] \\
\operatorname{random}_{a^*} \mathsf{j} := \operatorname{arr}_{\mathsf{a}} (\operatorname{fst} \ggg \pi \mathsf{j})$$
(46)

We extend the let-calculus semantic function with

$$[random]_{a*} :\equiv random_{a*}$$
 (47)

for arrows a^* for which $random_{a^*}$ is defined.

Partial Programs One utimately implementable way to avoid divergence is to use the store to dictate which branch of each conditional, if any, is allowed to be taken.

Definition 7.3 (branch trace). A branch trace is any $t \in J \to \mathsf{Bool}_\perp$ such that $t \ j = \mathsf{true}$ or $t \ j = \mathsf{false}$ for no more than finitely many $j \in J$.

Let $T \subset J \to Bool_{\perp}$ be the set of all branch traces, and $x \leadsto_{a^*} y ::= \mathsf{AStore}\ T \ (x \leadsto_a y)$. The following combinator returns t j using its own index j:

$$\begin{array}{lll} \mathsf{branch_{a^*}} : \mathsf{x} \leadsto_{\mathsf{a^*}} \mathsf{Bool} \\ \\ \mathsf{branch_{a^*}} \ \mathsf{j} \ := \ \mathsf{arr_a} \ (\mathsf{fst} \ggg \pi \ \mathsf{j}) \end{array} \tag{48}$$

Using $branch_{a^*}$, we define an if-then-else combinator that ensures its test expression agrees with the branch trace:

$$\begin{split} \mathsf{agrees} : \langle \mathsf{Bool}, \mathsf{Bool} \rangle \Rightarrow \mathsf{Bool}_\perp \\ \mathsf{agrees} \ \langle \mathsf{b}_1, \mathsf{b}_2 \rangle \ := \ \mathsf{if} \ \big(\mathsf{b}_1 = \mathsf{b}_2 \big) \ \mathsf{b}_1 \ \bot \\ \mathsf{ifte}_{\mathsf{a}^*}^{\Downarrow} : \big(\mathsf{x} \leadsto_{\mathsf{a}^*} \mathsf{Bool} \big) \Rightarrow \big(\mathsf{x} \leadsto_{\mathsf{a}^*} \mathsf{y} \big) \Rightarrow \big(\mathsf{x} \leadsto_{\mathsf{a}^*} \mathsf{y} \big) \Rightarrow \big(\mathsf{x} \leadsto_{\mathsf{a}^*} \mathsf{y} \big) \\ \mathsf{ifte}_{\mathsf{a}^*}^{\Downarrow} \ \mathsf{k}_1 \ \mathsf{k}_2 \ \mathsf{k}_3 \ \mathsf{j} \ := \\ \mathsf{ifte}_{\mathsf{a}} \ \big(\big(\mathsf{left} \ \mathsf{j} \big) \&\&\&_{\mathsf{a}} \ \mathsf{branch}_{\mathsf{a}^*} \ \mathsf{j} \big) \ggg_{\mathsf{a}} \mathsf{arr}_{\mathsf{a}} \ \mathsf{agrees} \big) \\ \big(\mathsf{k}_2 \ \big(\mathsf{left} \ (\mathsf{right} \ \mathsf{j} \big) \big) \big) \\ \big(\mathsf{k}_3 \ \big(\mathsf{right} \ (\mathsf{right} \ \mathsf{j} \big) \big) \big) \big) \\ \big(\mathsf{k}_3 \ \big(\mathsf{right} \ (\mathsf{right} \ \mathsf{j} \big) \big) \big) \big) \\ \big(\mathsf{50} \big) \end{split}$$

If the branch trace agrees with the test expression, it computes a branch; otherwise, it returns an error.

We assume every expression is well-defined (Definition 3.5), so every expression must have its recurrences guarded by if. Thus, to ensure running their interpretations always converges, we should only need to replace ifte_{a*} with ifte³/_{a*}. We define a new semantic function $\llbracket \cdot \rrbracket^{\downarrow}_{a*}$ by

with the remaining rules similar to those of $[\cdot]_{a^*}$.

Partial, Probabilistic Programs Let $S := R \times T$ and $x \leadsto_{a^*} y := AStore S (x \leadsto_a y)$, and update the random_{a*} and branch_{a*} combinators to reflect that the store is now a pair:

$$\begin{array}{ll} \mathsf{branch_{a^*}} : \mathsf{x} \leadsto_{\mathsf{a^*}} \mathsf{Bool} \\ \mathsf{branch_{a^*}} \ \mathsf{j} \ := \ \mathsf{arr_a} \ (\mathsf{fst} \ggg \mathsf{snd} \ggg \pi \ \mathsf{j}) \end{array} \tag{53}$$

The definitions of ifte^{\downarrow}_{a*} and $[\cdot]^{\downarrow}$ _{a*} remain the same.

7.5 Correctness

We have two arrow lifts to prove homomorphic: one from pure computations to effectful (i.e. from those that do not access the store to those that do), and one from effectful computations to effectful. For both, we need AStore arrow equivalence to be more extensional.

Definition 7.4 (AStore arrow equivalence). Two AStore arrow computations k_1 and k_2 are equivalent, or $k_1 \equiv k_2$, when $k_1 j \equiv k_2 j$ for all $j \in J$.

Pure Expressions Proving η_{a^*} is a homomorphism proves $[\cdot]_{-*}$ correctly interprets pure expressions. Because AStore accepts any arrow type $x \rightsquigarrow_a y$, we can do so using only general properties. From here on, we assume every AStore arrow's base type's combinators obey the arrow laws listed in Section 3.1.

Theorem 7.5 (pure AStore arrow correctness). η_{a^*} is an arrow homomorphism.

Proof. Defining arr_{a*} as a composition clearly meets the first homomorphism law (15). For homomorphism laws (16–18), start from the right side, expand definitions, and use arrow laws (21–23) to factor out arra snd.

For (19), additionally β -expand within the outer thunk, then use the lazy distributive law (24) to extract arr_a snd. \Box

Corollary 7.6 (pure semantic correctness). For all pure expressions e, $\llbracket e \rrbracket_{\mathsf{a}^*} \equiv \eta_{\mathsf{a}^*} \quad \llbracket e \rrbracket_{\mathsf{a}} \quad and \, \llbracket e \rrbracket_{\mathsf{a}^*}^{\downarrow} \equiv \eta_{\mathsf{a}^*} \quad \llbracket e \rrbracket_{\mathsf{a}}^{\downarrow}$

Effectful Expressions To prove all interpretations of effectful expressions correct, we need a lift between AStore arrows. Let $x \leadsto_{a^*} y ::= \mathsf{AStore} \ \mathsf{s} \ (x \leadsto_a y) \ \mathrm{and} \ x \leadsto_{b^*} y ::=$ AStore s (x \leadsto_{b^*} y). Define

$$lift_{b^*} : (x \leadsto_{a^*} y) \Rightarrow (x \leadsto_{b^*} y)$$

$$lift_{b^*} f j := lift_b (f j)$$
(54)

where $lift_b : (x \leadsto_a y) \Rightarrow (x \leadsto_b y)$.

The relationships are more clearly expressed by

$$\begin{array}{ccccc} x \leadsto_{a} y & \xrightarrow{\quad \text{lift}_{b} \quad} x \leadsto_{b} y \\ & & & & \downarrow \eta_{b^{*}} \\ & & & & \downarrow \eta_{b^{*}} \end{array}$$

$$\times \leadsto_{a^{*}} y & \xrightarrow{\quad \text{lift}_{1,*} \quad} x \leadsto_{b^{*}} y$$

$$(55)$$

At minimum, we should expect to produce equivalent $x \leadsto_{b^*}$ y computations from $x \leadsto_{a} y$ computations whether a lift or an η is done first.

Theorem 7.7 (natural transformation). If lift_b is an arrow homomorphism, then (55) commutes.

Proof. Expand definitions and apply homomorphism laws (16) and (15) for lift_b:

$$\begin{split} \mathsf{lift_{b^*}} \; \big(\eta_{\mathsf{a^*}} \; \mathsf{f} \big) \; &\equiv \; \lambda \mathsf{j.} \, \mathsf{lift_b} \; \big(\mathsf{arr_a} \; \mathsf{snd} \; \ggg_{\mathsf{a}} \; \mathsf{f} \big) \\ &\equiv \; \lambda \mathsf{j.} \, \mathsf{lift_b} \; \big(\mathsf{arr_a} \; \mathsf{snd} \big) \; \ggg_{\mathsf{b}} \; \mathsf{lift_b} \; \mathsf{f} \\ &\equiv \; \lambda \mathsf{j.} \; \mathsf{arr_b} \; \mathsf{snd} \; \ggg_{\mathsf{b}} \; \mathsf{lift_b} \; \mathsf{f} \\ &\equiv \; \eta_{\mathsf{b^*}} \; \big(\mathsf{lift_b} \; \mathsf{f} \big) \end{split}$$

Theorem 7.8 (effectful AStore arrow correctness). If lift_b is an arrow homomorphism, then lift_{b*} is an arrow homomorphism.

Proof. XXX: do this
$$\Box$$

Corollary 7.9 (effectful semantic correctness). If lift is an arrow homomorphism, then for all expressions e, $[\![e]\!]_{b^*} \equiv$ $\mathsf{lift_{b^*}} \ \llbracket e \rrbracket_{\mathsf{a^*}} \ and \ \llbracket e \rrbracket_{\mathsf{b^*}}^{\Downarrow} \equiv \mathsf{lift_{b^*}} \ \llbracket e \rrbracket_{\mathsf{a^*}}^{\Downarrow}.$

From here on, let $x \leadsto_{\underline{I}^*} y ::= \mathsf{AStore} \ (\mathsf{R} \times \mathsf{T}) \ (x \leadsto_{\underline{I}} y)$, called the $\mathit{bottom}^* \mathit{arrow}$; similarly for $X_{\mathsf{map}^*} \mathsf{Y}$ (the map ping* arrow) and $X_{pre*} Y$ (the preimage* arrow).

Corollary 7.10 (mapping* and preimage* arrow correctness). The following diagram commutes:

Further, lift_{map*} and lift_{pre*} are arrow homomorphisms.

Corollary 7.11 (effectful semantic correctness). For all expressions e,

$$\begin{aligned}
&[e]_{\mathsf{pre}^*} \equiv \mathsf{lift}_{\mathsf{pre}^*} \; (\mathsf{lift}_{\mathsf{map}^*} \; [e]_{\perp^*}) \\
&[e]_{\mathsf{pre}^*}^{\Downarrow} \equiv \mathsf{lift}_{\mathsf{pre}^*} \; (\mathsf{lift}_{\mathsf{map}^*} \; [e]_{\mid_*}^{\Downarrow})
\end{aligned} \tag{57}$$

7.6 Convergence

To relate $\llbracket e \rrbracket_{\mathsf{a}^*}^{\Downarrow}$ computations to $\llbracket e \rrbracket_{\mathsf{a}^*}$ computations, we need to find the largest domain on which they should agree.

Definition 7.12 (maximal domain). A computation's maximal domain is the largest A* for which

- $For f : X \leadsto_{\perp} Y$, $domain_{\perp} f A^* = A^*$.
- For g: $X \underset{\text{pre}}{\text{map}} Y$, domain (g A^*) = A^* . For h: $X \underset{\text{pre}}{\text{pre}} Y$, domain_{pre} (h A^*) = A^* .

The maximal domain of $k : X \leadsto_{a^*} Y$ is that of $k j_0$.

Because the above statements imply convergence, A* is a subset of the largest domain for which the computations converge. It is not too hard to show (but is a bit tedious) that lifting computations preserves the maximal domain; e.g. the maximal domain of $lift_{map}$ f is the same as f's, and the maximal domain of $lift_{pre^*}$ g is the same as g's.

To ensure maximal domains exist, we need the domain operations above to have certain properties.

Theorem 7.13 (domain closure operators). If $f: X \leadsto_{\perp} Y$, $\mathsf{g}:\mathsf{X}_{\,\overset{\longleftarrow}{\mathsf{map}}}\,\mathsf{Y}\ \mathit{and}\ \mathsf{h}:\mathsf{X}_{\,\overset{\longleftarrow}{\mathsf{pre}}}\,\mathsf{Y},\ \mathit{then}\ \mathsf{domain}_{\perp}\ \mathsf{f},\ \mathsf{domain}\circ\mathsf{g},\ \mathit{and}$ domain_{pre} o h are monotone, decreasing, and idempotent in the subdomains on which they converge.

Proof. These properties follow from the same properties of selection, restriction, and of preimages of images.

For any input for which $[\![e]\!]_{\perp^*}$ converges, there should be a branch trace for which $\llbracket e \rrbracket^{\downarrow}_{+}$ returns the correct output; it should otherwise return \perp .

Theorem 7.14. Let $f := [e]_{\perp^*} : X \leadsto_{\perp^*} Y$ with maximal $\mbox{domain A^*, and $f':=[\![e]\!]^{\!\!\downarrow}_{\!\!\!\perp^*}$. For all $\langle\langle r,t\rangle,a\rangle\in A^*$, there exists a $T'\subseteq T$ such that}$

- $$\begin{split} \bullet \; \mathit{If} \; t' \in \mathsf{T'} \; \mathit{then} \; \mathsf{f'} \; \mathsf{j}_0 \; \langle \langle \mathsf{r}, \mathsf{t'} \rangle, \mathsf{a} \rangle &= \mathsf{f} \; \mathsf{j}_0 \; \langle \langle \mathsf{r}, \mathsf{t} \rangle, \mathsf{a} \rangle. \\ \bullet \; \mathit{If} \; t' \in \mathsf{T} \backslash \mathsf{T'} \; \mathit{then} \; \mathsf{f'} \; \mathsf{j}_0 \; \langle \langle \mathsf{r}, \mathsf{t'} \rangle, \mathsf{a} \rangle &= \bot. \end{split}$$

Proof. Define T' as the set of all $\mathsf{t}' \in \mathsf{J} \to \mathsf{Bool}_\perp$ such that t' j = z if the subcomputation with index j is an if whose test returns z. Because f j_0 $\langle\langle r,t\rangle,a\rangle$ converges, t' $j\neq \bot$ for at most finitely many j, so each $t' \in T$.

Let $t' \in T'$. Because the test of every if subcomputation at index j agrees with t' j and f ignores branch traces, $f' j_0 \langle \langle r, t' \rangle, a \rangle = f j_0 \langle \langle r, t \rangle, a \rangle.$

Let $\mathbf{t}' \in \mathsf{T} \backslash \mathsf{T}'$. There exists an if subexpression with a test that does not agree with \mathbf{t}' ; therefore \mathbf{f}' j₀ $\langle \langle \mathbf{r}, \mathbf{t}' \rangle, \mathbf{a} \rangle = \bot$. \square

For any input for which $[\![e]\!]_{\perp^*}$ diverges or returns \bot , $[\![e]\!]_{\perp^*}$ should return \bot . Proving this is a little easier if we first identify subsets of J that correspond with finite prefixes of an infinite binary tree.

Definition 7.15 (index prefix/suffix). A finite $J' \subset J$ is an index prefix if $J' = \{j_0\}$ or, for some index prefix J'' and $j \in J''$, $J' = J'' \uplus \{\text{left } j\}$ or $J' = J'' \uplus \{\text{right } j\}$. $J \setminus J'$ is the corresponding index suffix.

It is not hard to show that every index suffix is closed under left and right.

For a given $t \in T$, an index prefix J' serves as a convenient bounding set for the finitely many indexes j for which $t \ j \neq \bot$. Applying left and/or right repeatedly to any $j \in J'$ eventually yields a $j' \in J \setminus J'$, for which $t \ j' = \bot$.

Theorem 7.16. Let $f := [\![e]\!]_{\perp^*} : X \leadsto_{\perp^*} Y$ with maximal domain A^* , and $f' := [\![e]\!]_{\perp^*}^{\downarrow}$. For all $a \in ((R \times T) \times X) \setminus A^*$, $f' \mid_{0} a = \bot$.

Proof. Let t := snd (fst a) be the branch trace element of a. Suppose f j_0 a converges. If an if subcomputation's test does not agree with t, then f' j_0 $a = \bot$. If every if's test agrees, f' j_0 a = f j_0 $a = \bot$.

Suppose f j_0 a diverges. The set of all indexes j for which t $j \neq \bot$, because it is finite, is contained within an index prefix J'. By hypothesis, there is an if subcomputation at some index j' such that $j' \in J \setminus J'$. Because t $j' = \bot$, $f' \mid_{0} a = \bot$.

Corollary 7.17. For all expressions e, the maximal domain of $[\![e]\!]_{+}^{\downarrow}$ is a subset of that of $[\![e]\!]_{+}^{\downarrow}$.

Corollary 7.18. Let $f':=[\![e]\!]_{\perp^*}^{\downarrow}:X\leadsto_{\perp^*}Y$ with maximal domain A^* , and $f:=[\![e]\!]_{\perp^*}$. For all $a\in A^*$, f' jo a=f jo a.

Corollary 7.19 (correct convergence everywhere). Suppose $\llbracket e \rrbracket_{\perp^*}^{\downarrow} : X \leadsto_{\perp^*} Y$ has maximal domain A^* . Let $X' := (R \times T) \times X$. For all $a \in X'$, $A \subseteq X'$ and $B \subseteq Y$,

In other words, preimages computed using $[\cdot]_{pre}^{\psi}$ always converge, never include inputs that give rise to errors or divergence, and are correct.

8. Output Probabilities and Measurability

We have not assigned probabilities to any output sets yet. Typically, for $g \in X \rightarrow Y$, the probability of $B \subseteq Y$ is

where $P \in \mathcal{P} \times A \rightarrow [0, 1]$.

However, a mapping* computation's domain is $(R \times T) \times X$, not X. We assume each $r \in R$ is randomly chosen, but not each $t \in T$ nor each $x \in X$; therefore, neither T nor X should affect the probabilities of output sets. We clearly must measure *projections* of preimage sets, or

P (image (fst
$$\gg$$
fst) A) (60)

for preimage sets $A \subseteq (R \times T) \times X$.

Not all preimage sets have sensible measures. Sets that do are called *measurable*. Computing preimages and projecting them onto R must preserve measurability.

8.1 Measurability

We assume readers are familiar with topology. Readers unfamiliar with topology or measure theory may wish to skip to Section 9.

Many topological concepts have analogues in measure theory; e.g. the analogue of a topology is a σ -algebra.

Definition 8.1 (σ -algebra, measurable set). A collection of sets $\mathcal{A} \subseteq \mathcal{P} \times \mathcal{A}$ is called a σ -algebra on $\times \mathcal{A}$ if it contains $\times \mathcal{A}$ and is closed under complements and countable unions. The sets in \mathcal{A} are called **measurable sets**.

 $X \setminus X = \emptyset$, so $\emptyset \in A$. Additionally, it follows from De Morgan's law that A is closed under countable intersections. The analogue of continuity is measurability.

Definition 8.2 (measurable mapping). Let \mathcal{A} and \mathcal{B} be σ -algebras respectively on X and Y. A mapping $g: X \longrightarrow Y$ is \mathcal{A} - \mathcal{B} -measurable if for all $B \in \mathcal{B}$, preimage $g: \mathcal{B} \in \mathcal{A}$.

Measurability is usually a weaker condition than continuity. For example, with respect to the σ -algebra generated from \mathbb{R} 's standard topology, measurable $\mathbb{R} \to \mathbb{R}$ functions may have countably many discontinuities. Likewise, real equality and inequality functions are measurable.

Product spaces are defined the same way as in topology.

Definition 8.3 (finite product σ -algebra). Let A_1 and A_2 be σ -algebras on X_1 and X_2 , and $X := \langle X_1, X_2 \rangle$. The **product** σ -algebra $A_1 \otimes A_2$ is the smallest σ -algebra for which mapping fst X and mapping snd X are measurable.

Definition 8.4 (arbitrary product σ -algebra). Let \mathcal{A} be a σ -algebra on X. The **product** σ -algebra $\mathcal{A}^{\otimes J}$ is the smallest σ -algebra for which, for all $j \in J$, mapping $(\pi \ j) \ (J \to X)$ is measurable.

8.2 Measurable Pure Computations

It is easier to prove measurability of pure computations than to prove measurability of partial, probabilistic ones. Further, we can use the resulting theorems to prove that the interpretations of all partial, probabilistic expressions are measurable.

We first need to define what it means for a computation to be measurable.

Definition 8.5 (measurable mapping arrow computation). Let \mathcal{A} and \mathcal{B} be σ -algebras on X and Y. A computation $g: X_{\widehat{map}} Y$ is \mathcal{A} - \mathcal{B} -measurable if $g A^*$ is an \mathcal{A} - \mathcal{B} -measurable mapping, where A^* is g's maximal domain.

Theorem 8.6 (maximal domain measurability). Let $g: X \underset{map}{\sim} Y$ be an A-B-measurable mapping arrow computation. Its maximal domain A^* is in A.

Proof. By definition, $g A^*$ is a measurable mapping. $Y \in \mathcal{B}$, and preimage $(g A^*) Y = \text{domain } (g A^*) = A^*$.

Of course, mapping arrow computations can be applied to sets other than their maximal domains. We need to ensure doing so yields a measurable mapping, at least for measurable subsets of A^* . Fortunately, that is true without any extra conditions.

Imported Lemma 8.7. Let $g : X \rightarrow Y$ be an A-Bmeasurable mapping. For any $A \in \mathcal{A}$, restrict g A is \mathcal{A} - \mathcal{B} -

Theorem 8.8. Let $g: X \underset{map}{\leadsto} Y$ be an A- \mathcal{B} -measurable mapping arrow computation with maximal domain A*. For all $A \subseteq A^*$ with $A \in \mathcal{A}$, g A is an A- \mathcal{B} -measurable mapping.

Proof. Use the mapping arrow law (Definition 4.6) and Lemma 8.7.

We do not need to prove that all interpretations using $[\cdot]_{a}$ are measurable. However, we do need to prove that all the mapping arrow combinators preserve measurability.

8.2.1 Case: Composition

Proving compositions are measurable takes the most work. The main complication is that, under measurable mappings, while preimages of measurable sets are measurable, images of measurable sets may not be. We need the following four extra theorems to get around this.

Imported Lemma 8.9 (images of preimages). Let $g: X \rightarrow$ Y and $B \subseteq Y$. Then image g (preimage g B) $\subseteq B$.

Imported Lemma 8.10 (expanded post-composition). Let $g_1: X \rightarrow Y$ and $g_2: Y \rightarrow Z$ such that range $g_1\subseteq$ domain g_2 , and let $g_2': Y \rightarrow Z$ such that $g_2\subseteq g_2'$. Then $g_2 \circ_{\mathsf{map}} g_1 = g_2' \circ_{\mathsf{map}} g_1.$

Theorem 8.11 (mapping arrow monotonicity). Let g: $X \underset{\text{map}}{\longrightarrow} Y$. For any $A' \subseteq A \subseteq A^*$, $g A' \subseteq g A$.

Proof. Follows from Definition 4.6.

Theorem 8.12 (maximal domain subsets). Let $g: X_{map} \rightarrow Y$. For any $A \subseteq A^*$, domain (g A) = A.

Proof. Follows from Theorem 7.13.

Now we can prove measurability.

Imported Lemma 8.13 (measurability under \circ_{map}). If $g_1 \ : \ X \ \rightharpoonup \ Y \ \mathit{is} \ \mathcal{A}\text{-}\mathcal{B}\text{-}\mathit{measurable} \ \mathit{and} \ g_2 \ : \ Y \ \rightharpoonup \ Z \ \mathit{is} \ \mathcal{B}\text{-}\mathcal{C}\text{-}$ measurable, then $g_2 \circ_{\mathsf{map}} g_1$ is $\mathcal{A}\text{-}\mathcal{C}\text{-}measurable$.

Theorem 8.14 (measurability under (\ggg_{map})). If g_1 : $X_{\stackrel{\leadsto}{map}} \ Y \ \mathit{is} \ \mathcal{A}\text{-}\mathcal{B}\text{-}\mathit{measurable} \ \mathit{and} \ g_2 : Y_{\stackrel{\leadsto}{map}} \ Z \ \mathit{is} \ \mathcal{B}\text{-}\mathcal{C}\text{-}\mathit{measurable},$ then $g_1 \gg_{map} g_2$ is A-C-measurable.

Proof. Let $A^* \in \mathcal{A}$ and $B^* \in \mathcal{B}$ be respectively g_1 's and g_2 's maximal domains. The maximal domain of $g_1 \ggg_{\mathsf{map}} g_2$ is $\mathsf{A}^{**} := \mathsf{preimage} \; (\mathsf{g}_1 \; \mathsf{A}^*) \; \mathsf{B}^*, \; \mathrm{which \; is \; in} \; \mathcal{A}. \; \mathrm{By \; definition},$

$$(g_1 \ggg_{map} g_2) A^{**} = \text{let } g'_1 := g_1 A^{**}$$
 $g'_2 := g_2 \text{ (range } g'_1)$
 $\text{in } g'_2 \circ_{map} g'_1$
 (61)

By Theorem 8.8, \mathbf{g}_1' is an \mathcal{A} - \mathcal{B} -measurable mapping. Unfortunately, g_2' may not be \mathcal{B} - \mathcal{C} -measurable when range $g_1' \notin \mathcal{B}$.

Let $g_2'' := g_2 B^*$, which is a \mathcal{B} - \mathcal{C} -measurable mapping. By Lemma 8.13, $g_2'' \circ_{\mathsf{map}} \mathsf{g}_1'$ is $\mathcal{A}\text{-}\mathcal{C}\text{-}$ measurable. We need only show that $\mathsf{g}_2' \circ_{\mathsf{map}} \mathsf{g}_1' = \mathsf{g}_2'' \circ_{\mathsf{map}} \mathsf{g}_1'$, which by Lemma 8.10 is true if range $\mathsf{g}_1' \subseteq \mathsf{domain} \mathsf{g}_2'$ and $\mathsf{g}_2' \subseteq \mathsf{g}_2''$.

By Theorem 8.12, $\mathsf{A}^{**} \subseteq \mathsf{A}^*$ implies domain $\mathsf{g}_1' = \mathsf{A}^{**}$. By

Theorem 8.11 and Lemma 8.9,

$$\begin{array}{ll} \mathsf{range}\ \mathsf{g}_1' &=& \mathsf{image}\ (\mathsf{g}_1\ \mathsf{A}^{**})\ (\mathsf{preimage}\ (\mathsf{g}_1\ \mathsf{A}^*)\ \mathsf{B}^*) \\ &=& \mathsf{image}\ (\mathsf{g}_1\ \mathsf{A}^*)\ (\mathsf{preimage}\ (\mathsf{g}_1\ \mathsf{A}^*)\ \mathsf{B}^*) \\ &\subseteq& \mathsf{B}^* \end{array}$$

range $g_1' \subseteq B^*$ implies (by Theorem 8.12) that domain $g_2' =$ range g'_1 , and (by Theorem 8.11) that $g'_2 \subseteq g''_2$.

8.2.2 Case: Pairing

Imported Lemma 8.15 (measurability under $\langle \cdot, \cdot \rangle_{map}$). If $g_1: X \rightharpoonup Y_1 \text{ is } A\text{-}\mathcal{B}_1\text{-measurable and } g_2: X \rightharpoonup Y_2 \text{ is } A\text{-}\mathcal{B}_2\text{-}$ measurable, then $\langle g_1, g_2 \rangle_{map}$ is A- $(\mathcal{B}_1 \otimes \mathcal{B}_2)$ -measurable.

 $\begin{array}{lll} \textbf{Theorem} & \textbf{8.16} & (\text{measurability under ($\&\&$_{map})}). & \textit{If } g_1 : \\ X_{\stackrel{\leftrightarrow}{map}} Y_1 & \textit{is } \mathcal{A}\text{-}\mathcal{B}_1\text{-}\textit{measurable} & \textit{and } g_2 : X_{\stackrel{\leftrightarrow}{map}} Y_2 & \textit{is } \mathcal{A}\text{-}\mathcal{B}_2\text{-}\\ \textit{measurable}, & \textit{then } g_1 & \&\&_{map} g_2 & \textit{is } \mathcal{A}\text{-}(\mathcal{B}_1 \otimes \mathcal{B}_2)\text{-}\textit{measurable}. \end{array}$

Proof. Let A_1^* and A_2^* be respectively g_1 's and g_2 's maximal domains. The maximal domain of g_1 && $_{map}$ g_2 is $A^{**} := A_1^* \cap A_2^*$, which is in \mathcal{A} . By definition, $(g_1$ && $_{map}$ g_2) $A^{**} =$ $\langle g_1 A^{**}, g_2 A^{**} \rangle_{map}$, which by Lemma 8.15 is \mathcal{A} - $(\mathcal{B}_1 \otimes \mathcal{B}_2)$ measurable.

8.2.3Case: Conditional

Imported Lemma 8.17 (union of disjoint, measurable mappings). Let $G : Set(X \rightarrow Y)$ be a countable set of A-Bmeasurable mappings with disjoint domains. Their union is A-B-measurable.

Theorem 8.18 (measurability under iftemap). If $g_1 : X \underset{map}{\sim} Bool$ is \mathcal{A} -(\mathcal{P} Bool)-measurable, and $g_2 : X \underset{map}{\sim} Y$ and $g_3 : X \underset{map}{\sim} Y$ are \mathcal{A} - \mathcal{B} -measurable, then iftemap $g_1 \ g_2 \ g_3$ is

Proof. Let \mathcal{A}_1^* , \mathcal{A}_2^* and \mathcal{A}_3^* be g_1 's, g_2 's and g_3 's maximal domains. The maximal domain of iftemap g₁ g₂ g₃ is

$$\begin{array}{lll} \mathsf{A}_2^{**} &:= \mathsf{A}_2^* \cap \mathsf{preimage} \; (\mathsf{g}_1 \; \mathcal{A}_1^*) \; \{\mathsf{true}\} \\ \mathsf{A}_3^{**} &:= \mathsf{A}_3^* \cap \mathsf{preimage} \; (\mathsf{g}_1 \; \mathcal{A}_1^*) \; \{\mathsf{false}\} \\ \mathsf{A}^{**} &:= \mathsf{A}_2^{**} \uplus \mathsf{A}_3^{**} \end{array} \tag{62}$$

Because preimage $(g_1 A_1^*) B \in A$ for any $B \subseteq Bool, A^{**} \in A$. By definition,

$$\begin{array}{ll} \mathsf{ifte_{\mathsf{map}}} \ g_1 \ g_2 \ g_3 \ \mathsf{A}^{**} \ = \ \mathsf{let} \ \ g_1' := g_1 \ \mathsf{A}^{**} \\ g_2' := g_2 \ (\mathsf{preimage} \ g_1' \ \{\mathsf{true}\}) \\ g_3' := g_3 \ (\mathsf{preimage} \ g_1' \ \{\mathsf{false}\}) \\ \mathsf{in} \ \ g_2' \uplus_{\mathsf{map}} g_3' \end{array}$$

By hypothesis, g'_1 , g'_2 and g'_3 are measurable mappings, and the mapping arrow law imples g'_2 and g'_3 have disjoint domains. Apply Lemma 8.17.

8.2.4 Case: Laziness

Theorem 8.19 (measurability of \varnothing). For any σ -algebras \mathcal{A} and \mathcal{B} , the empty mapping \varnothing is $\mathcal{A}\text{-}\mathcal{B}\text{-}measurable$.

Proof. For any $B \in \mathcal{B}$, preimage \emptyset $B = \emptyset$, and $\emptyset \in \mathcal{A}$.

Theorem 8.20 (measurability under $lazy_{map}$). Let $g: 1 \Rightarrow$ $(X_{\underset{\mathsf{map}}{\longrightarrow}} Y)$. If g 0 is A- \mathcal{B} -measurable, then lazy_{map} g is A- \mathcal{B} measurable.

Proof. The maximal domain A^{**} of $lazy_{map}$ g is the same as that of g 0. By definition,

$$lazy_{map} g A^{**} = if (A^{**} = \emptyset) \emptyset (g 0 A^{**})$$
 (64)

If $A^{**} = \emptyset$, then $lazy_{map} g A^{**} = \emptyset$; apply Theorem 8.19. If $A^{**} \neq \emptyset$, then $lazy_{map} g = g 0$, which is A-B-measurable. \square

8.3 Measurable Probabilistic Computations

As before, we first need to define what it means for a computation to be measurable.

Definition 8.21 (measurable mapping* arrow computation). Let \mathcal{A} and \mathcal{B} be σ -algebras on $(\mathbb{R} \times \mathbb{T}) \times \mathbb{X}$ and \mathbb{Y} . A computation $g: X_{\widetilde{map}^*} \times \mathbb{Y}$ is $\mathcal{A}\text{-}\mathcal{B}\text{-}measurable}$ if $g \mid_{0}$ is an $\mathcal{A}\text{-}\mathcal{B}\text{-}measurable}$ mapping arrow computation.

Clearly, if any g j is measurable, so are g (left j) and g (right j). By induction, if g is a measurable mapping* arrow computation, then for any $j \in J$, g j is an $\mathcal{A}\text{-}\mathcal{B}\text{-}$ measurable mapping arrow computation.

To make general measurability statements about computations, whether they have flat or product types, it helps to have a notion of a standard σ -algebra.

Definition 8.22 (standard σ -algebra). For a set X used as a type, Σ X denotes its **standard** σ -algebra, which must be defined under the following constraints:

$$\Sigma \langle \mathsf{X}_1, \mathsf{X}_2 \rangle = \Sigma \; \mathsf{X}_1 \otimes \Sigma \; \mathsf{X}_2 \tag{65}$$

$$\Sigma (J \to X) = (\Sigma X)^{\otimes J}$$
 (66)

The predicate "is measurable" means "is measurable with respect to standard σ -algebras."

So that we can measure boolean singletons and any set of branch traces, we define

$$\Sigma$$
 Bool ::= \mathcal{P} Bool (67)

$$\Sigma \mathsf{T} ::= \mathcal{P} \mathsf{T} \tag{68}$$

Imported Lemma 8.23 (measurable mapping arrow lifts). arr_{map} id, arr_{map} fst and arr_{map} snd are measurable. arr_{map} (const b) is measurable if $\{b\}$ is a measurable set. For all $j \in J$, arr_{map} (π j) is measurable.

Corollary 8.24. arr_{map^*} id, arr_{map^*} fst and arr_{map^*} snd are measurable. arr_{map^*} (const b) is measurable if {b} is a measurable set. $random_{map^*}$ and $branch_{map^*}$ are measurable.

Theorem 8.25 (AStore measurability transfer). Every AStore arrow combinator produces measurable mapping* computations from measurable mapping* computations.

Proof. AStore's combinators are defined in terms of the base arrow's combinators and arr_{map} fst and arr_{map} snd.

Theorem 8.26. ifte $_{map^*}^{\downarrow}$ is measurable.

Proof. branch_{map*} is measurable, and arr_{map} agrees is measurable by (67).

Definition 8.27 (finite expression). A finite expression is any expression for which no subexpression is a first-order application.

Theorem 8.28 (all finite expressions are measurable). For all finite expressions e, $[\![e]\!]_{map^*}$ is measurable.

Proof. By structural induction and the above theorems. \Box

Theorem 8.29 (approximation with finite expressions). Let $g := [\![e]\!]_{map^*}^{\Downarrow} : X_{\widehat{map}^*} Y$. For all $t \in T$, there is a finite expression e' for which $[\![e']\!]_{map^*}$ $j_0 A = g j_0 A$, where $A := (R \times \{t\}) \times X$.

Proof. Let the index prefix J' contain every j for which $t \ j \ne \bot$. To construct e', exhaustively apply first-order functions in e, but replace any ifte whose index j is not in J with the equivalent expression \bot . Because e is well-defined, recurrences must be guarded by if, so this process terminates after finitely many applications.

Theorem 8.30 (all probabilistic expressions are measurable). For all expressions e, $[e]_{\mathsf{map}^*}^{\downarrow}$ is measurable.

Proof. Let $g := [\![e]\!]_{map^*}^{\downarrow}$ and $g' := g \ j_0$ ((R × T) × X). By Corollary 7.19, $g' = g \ j_0$ A* where A* is g's maximal domain; thus we need only show that g' is a measurable mapping.

By mapping arrow monotonicity (XXX?) (Theorem 8.11),

$$g' = \bigcup_{t \in T} g j_0 ((R \times \{t\}) \times X)$$
 (69)

By Theorem 8.29, for every $t \in T$, there is an expression that computes $g((R \times \{t\}) \times X)$. By (68) and Theorem 8.28, each is measurable. By the mapping arrow law (Definition 4.6), each is disjoint. By Lemma 8.17, their union is measurable.

Theorem 8.30 remains true when $[\cdot]_a$ is extended with any rule whose right side is measurable, including rules for real arithmetic, equality, inequality and limits. More generally, any continuous or (countably) piecewise continuous function can be made available as a language primitive, as long as its domain's and codomain's standard σ -algebras are generated from their topologies.

It is not difficult to compose $\llbracket \cdot \rrbracket_a$ with another semantic function that lifts and defunctionalizes lambda expressions. Thus, the interpretations of all expressions in higher-order languages are measurable.

8.4 Measurable Projections

If $g := \llbracket e \rrbracket_{\mathsf{map}^*}^{\psi} : X_{\widetilde{\mathsf{map}^*}}^{\circ} Y$, then the probability of a measurable output set $B \in \Sigma Y$ is

P (image (fst
$$\gg >$$
 fst) (preimage (g j₀ A*) B)) (70)

if domain $P = \Sigma$ R. Unfortunately, projected sets are generally not measurable. Fortunately, for interpretations of programs $\llbracket p \rrbracket_{\mathsf{map}^*}^{\psi}$, for which $X = \{\langle \rangle \}$, we have a special case.

Theorem 8.31 (measurable finite projections). Let $A \in \Sigma \langle X_1, X_2 \rangle$. If X_2 is at most countable and $\Sigma X_2 = \mathcal{P} X_2$, then image fst $A \in \mathcal{A}_1$.

Proof. Because Σ $X_2 = \mathcal{P}$ X_2 , A is a countable union of rectangles of the form $A_1 \times \{a_2\}$, where $A_1 \in \Sigma$ X_1 and $a_2 \in X_2$. Because image fst distributes over unions, image fst A is a countable union of sets in Σ X_1 .

Theorem 8.32. Let $g: X_{\widetilde{map}^*}Y$ be measurable. If X is at most countable and $\Sigma X = \mathcal{P} X$, then for all $B \in \Sigma Y$,

image (fst
$$> > fst$$
) (preimage (g j₀ A*) B) $\in \Sigma$ R (71)

Proof. T is countable and Σ T = \mathcal{P} T by definition (68); apply Theorem 8.31 twice.

In particular, for any $[p]^{\downarrow}_{\mathsf{map}^*}: \{\langle \rangle \}_{\underset{\mathsf{map}^*}{\Longrightarrow}} \mathsf{Y}$, the probabilities of measurable output sets are well-defined.

9. Approximating Semantics

If we were to confine preimage computation to finite sets, we could implement the preimage arrow directly. But we would like something that works efficiently on infinite sets, even if it means approximating.

Trying to generalize all useful approximation methods would result in a specification that cannot be directly implemented. Instead, we focus on a specific method: approximating product sets with covering rectangles. We recover some generality by stating correctness theorems in terms of general properties such as monotonicity.

9.1 Implementable Lifts

We would like to be able to compute preimages of uncountable sets, such as real intervals. This would seem to be a show-stopper: preimage g B is uncomputable for most uncountable sets B no matter how cleverly they are represented. Further, because pre, lift_{pre} and arr_{pre} are ultimately defined in terms of preimage, we cannot implement them.

Fortunately, we need only certain lifts. Figure 2 (which defines $[\cdot]_a$) lifts id, const b, fst and snd. Section 7.4, which defines the combinators used to interpret partial, probabilistic programs, lifts π j and agrees. Measurable functions made available as language primitives of course must be lifted to the preimage arrow.

Figure 8 gives expressions equivalent to $\mathsf{arr}_{\mathsf{pre}}$ id, $\mathsf{arr}_{\mathsf{pre}}$ fst, $\mathsf{arr}_{\mathsf{pre}}$ snd, $\mathsf{arr}_{\mathsf{pre}}$ (const b) and $\mathsf{arr}_{\mathsf{pre}}$ (π j). (We will deal with agrees separately.) By inspecting these expressions, we see that we need to model sets in a way that the following are representable and can be computed in finite time:

- $A \cap B$, \emptyset , {true}, {false} and {b} for every const b
- $A_1 \times A_2$, proj_{fst} A and proj_{snd} A

• J
$$\rightarrow$$
 X, project j A and unproject j A B (72)

A = ∅

Before addressing computability, we need to define families of sets under which these operations are closed.

Definition 9.1 (rectangular family). For a set X used as a type, Rect X denotes the **rectangular family** of subsets of X. For nonproduct X, $\varnothing \in \text{Rect } X$ and $X \in \text{Rect } X$, and Rect X must be closed under finite intersections. Products must satisfy the following rules:

$$Rect \langle X_1, X_2 \rangle = (Rect X_1) \boxtimes (Rect X_2)$$
 (73)

$$Rect (J \to X) = (Rect X)^{\boxtimes J}$$
 (74)

where

$$\mathcal{A}_{1} \boxtimes \mathcal{A}_{2} := \left\{ \mathsf{A}_{1} \times \mathsf{A}_{2} \mid \mathsf{A}_{1} \in \mathcal{A}_{1}, \mathsf{A}_{2} \in \mathcal{A}_{2} \right\}$$

$$\mathcal{A}^{\boxtimes \mathsf{J}} := \bigcup_{\mathsf{J}' \subset \mathsf{J}} \left\{ \prod_{\mathsf{j} \in \mathsf{J}} \mathsf{A}_{\mathsf{j}} \mid \mathsf{A}_{\mathsf{j}} \in \mathcal{A}, \mathsf{j} \in \mathsf{J}' \iff \mathsf{A}_{\mathsf{j}} \subset \bigcup \mathcal{A} \right\}$$

$$(76)$$

lift cartesian products to sets of sets.

For example, if $\mathsf{Rect}\ \mathbb{R}$ contains all the closed real intervals, then by (73), $[0,2] \times [1,\pi] \in \mathsf{Rect}\ \langle \mathbb{R}, \mathbb{R} \rangle$.

We additionally define Rect Bool $:= \mathcal{P}$ Bool. It is easy to show that every product rectangular family Rect X contains \emptyset and X, and that the collection of all rectangular families is closed under products, projections, and unproject.

Further, all of the operations in (72) can be exactly implemented if finite sets are modeled directly, sets in an ordered space (such as \mathbb{R}) are modeled by intervals, and sets in Rect $\langle X_1, X_2 \rangle$ are modeled by pairs of type

 $\langle \text{Rect } X_1, \text{Rect } X_2 \rangle$. By (74), sets in Rect ($J \to X$) have no more than finitely many axes that are proper subsets of X. They can be modeled by *finite* binary trees, whose nodes contain axes for an index prefix $J' \subset J$ (Definition 7.15). Axes with indexes in the suffix $J \setminus J'$ are implicitly X.

The set of branch traces T is nonrectangular, containing every $t \in J \to \mathsf{Bool}_\perp$ for which $t \ j \ne \bot$ for no more than finitely many J. Fortunately, we can model T subsets by $J \to \mathsf{Bool}_\perp$ rectangles, implicitly intersected with T.

Theorem 9.2 (rectangular T projection). *If* $T' \in \mathsf{Rect}(J \to \mathsf{Bool}_\perp)$, *then* project j $(T' \cap T) = \mathsf{project}\ j$ T' *for all* $j \in J$.

Proof. The subset case is by projection monotonicity. For the superset, let $b \in \text{project } j \ T'$. Define t by t j' = b if j' = j, t $j' = \bot$ if $\bot \in \text{project } j' \ T'$, and t $j' \in \text{project } j' \ T'$ otherwise.

For no more than finitely many $j' \in J$, $t \ j' \neq \bot$, so $t \in T$; also $t \in T'$ by construction. Thus, there exists a $t \in T' \cap T$ such that $t \ j = b$, so $b \in \text{project } j \ (T' \cap T)$.

Corollary 9.3. Under the same conditions, for all $B \subseteq Bool$, unproject j $(T' \cap T)$ B = unproject j T' $B \cap T$.

9.2 Approximate Preimage Mapping Operations

Implementing lazy_{pre} (defined in Figure 6) requires computing pre, but only for the empty mapping, which is trivial: pre $\emptyset \equiv \langle \varnothing, \lambda \, B. \, \varnothing \rangle$. Implementing the other combinators requires implementing the preimage mapping operations (\circ_{pre}) , $\langle \cdot, \cdot \rangle_{pre}$ and (\uplus_{pre}) .

From the preimage mapping definitions (Figure 5), we see that ap_{pre} is defined in terms of (\cap) and that (\circ_{pre}) is defined in terms of ap_{pre} , so (\circ_{pre}) is directly implementable. Unfortunately, we hit a snag with $\langle \cdot, \cdot \rangle_{pre}$: it loops over possibly uncountably many members of B in a big union. At this point, we need to approximate.

Theorem 9.4 (pair preimage overapproximation). Let $g_1 \in X \rightharpoonup Y_1$ and $g_2 \in X \rightharpoonup Y_2$. For all $B \subseteq Y_1 \times Y_2$, preimage $\langle g_1, g_2 \rangle_{map}$ $B \subseteq \text{preimage } g_1 \text{ (proj}_{fst} \text{ B)} \cap \text{preimage } g_2 \text{ (proj}_{snd} \text{ B)}$.

Proof. By monotonicity of preimages and projections, and by Lemma 5.4.

It is not hard to use Theorem 9.4 to show that

$$\langle \cdot, \cdot \rangle_{\mathsf{pre}}' : (\mathsf{X} \xrightarrow{\mathsf{pre}} \mathsf{Y}_1) \Rightarrow (\mathsf{X} \xrightarrow{\mathsf{pre}} \mathsf{Y}_2) \Rightarrow (\mathsf{X} \xrightarrow{\mathsf{pre}} \mathsf{Y}_1 \times \mathsf{Y}_2)$$

$$\langle \langle \mathsf{Y}_1', \mathsf{p}_1 \rangle, \langle \mathsf{Y}_2', \mathsf{p}_2 \rangle \rangle_{\mathsf{pre}}' := \tag{77}$$

$$\langle \mathsf{Y}_1' \times \mathsf{Y}_2', \lambda \mathsf{B}. \, \mathsf{p}_1 \, (\mathsf{proj}_{\mathsf{fst}} \, \mathsf{B}) \cap \mathsf{p}_2 \, (\mathsf{proj}_{\mathsf{snd}} \, \mathsf{B}) \rangle$$

computes covering rectangles of preimages under pairing.

For (\uplus_{pre}) , we need an approximating replacement for (\cup) under which rectangular families are closed. In other words, we need a lattice join (\vee) with respect to (\subseteq) , with the following additional properties:

$$(A_1 \times A_2) \vee (B_1 \times B_2) = (A_1 \vee B_1) \times (A_2 \vee B_2)$$

$$(\prod_{i \in I} A_j) \vee (\prod_{i \in I} B_j) = \prod_{i \in I} A_j \vee B_j$$

$$(78)$$

If for every nonproduct type X, Rect X is closed under (\vee) , then rectangular families are clearly closed under (\vee) . Further, for any A and B, $A \cup B \subseteq A \vee B$.

Replacing each union in (\uplus_{pre}) with a join results in

```
\begin{array}{lll} \text{id}_{\text{pre}} \ A \ := \ \text{arr}_{\text{pre}} \ \text{id} \ A \ \equiv \ \langle A, \lambda B. B \rangle \\ \text{fst}_{\text{pre}} \ A \ := \ \text{arr}_{\text{pre}} \ \text{fst} \ A \ \equiv \ \langle \text{proj}_{\text{fst}} \ A, \text{unproj}_{\text{fst}} \ A \rangle \\ \text{snd}_{\text{pre}} \ A \ := \ \text{arr}_{\text{pre}} \ \text{fst} \ A \ \equiv \ \langle \text{proj}_{\text{snd}} \ A, \text{unproj}_{\text{fst}} \ A \rangle \\ \text{snd}_{\text{pre}} \ A \ := \ \text{arr}_{\text{pre}} \ \text{fst} \ A \ \equiv \ \langle \text{project} \ j \ A, \text{unproject} \ j \ A \rangle \\ \text{project} \ : \ J \Rightarrow Set \ (J \to X) \Rightarrow Set \ X \\ \text{project} \ : \ J \Rightarrow Set \ (J \to X) \Rightarrow Set \ X \\ \text{unproj}_{\text{fst}} \ := \ \text{image} \ (\pi \ j) \ A \\ \text{unproj}_{\text{fst}} \ := \ \text{preimage} \ (\text{mapping} \ \text{fst} \ A) \ B \\ \equiv \ A \cap (B \times \text{proj}_{\text{snd}} \ A) \ B \\ \equiv \ A \cap \prod_{i \in J} \text{if} \ (j = i) \ B \ (\text{project} \ j \ A) \end{array}
```

Figure 8: Preimage arrow lifts needed to interpret probabilistic programs. The definition of unproj_{snd} is like unproj_{fst}'s.

which overapproximates (\uplus_{pre}) .

To interpret programs that may diverge, or that converge with probability 1, we need to approximate ifter $^{\Downarrow}_{pre^*}$ (50).

Directly implementing ifte $_{pre^*}^{\downarrow}$ in terms of agrees cannot work: the preimage of Bool under agrees (as a mapping) is $\{\langle true, true \rangle, \langle false, false \rangle\}$, which is not rectangular. A lengthy (elided) sequence of substitutions to the defining expression for ifte $_{pre^*}^{\downarrow}$ results in

$$\begin{array}{l} \text{ifte}_{\text{pre*}}^{\Downarrow} \ k_1 \ k_2 \ k_3 \ j \ A \ \equiv \ \text{let} \ \langle C_k, p_k \rangle := k_1 \ j_1 \ A \\ \langle C_b, p_b \rangle := \text{branch}_{\text{pre*}} \ j \ A \\ C_2 := C_k \cap C_b \cap \{\text{true}\} \\ C_3 := C_k \cap C_b \cap \{\text{false}\} \\ A_2 := p_k \ C_2 \cap p_b \ C_2 \\ A_3 := p_k \ C_3 \cap p_b \ C_3 \\ \text{in} \ (k_2 \ j_2 \ A_2) \uplus_{\text{pre}} (k_3 \ j_3 \ A_3) \end{array}$$

where $j_1 = \text{left } j$ and so on. This does not use agrees and preserves rectangularity if k_1 , k_2 and k_3 do. Unfortunately, if A_2 or A_3 overapproximates \varnothing , it takes unnecessary branches, which can cause divergence. In the exact semantics, expressions interpreted using ifte $^{\parallel}_{pre^*}$ never diverge.

 C_b is the branch trace projection at j (with \bot removed). The set of indexes for which C_b is either {true} or {false} is finite, so it is bounded by an index prefix, outside of which branch trace projections are {true, false}. Therefore, if the approximating ifte_{pre*}^{\downarrow} takes no branches when $C_b = \{true, false\}$, but approximates with a finite computation, expressions interpreted using ifte_{pre*}^{\downarrow} will always converge.

We need an overapproximation for the non-branching case. In the exact semantics, the returned preimage mapping's range is a subset of Y, and it returns subsets of $A_2 \uplus A_3$. Therefore, ifte $^{\Downarrow}_{pre^*}$ may return $\langle Y, \lambda B, A_2 \lor A_3 \rangle$ when $C_b = \{ true, false \}$. We cannot refer to the type Y in the function definition, so we represent it using \top in the approximating semantics. Implementations can model it by a singleton "universe" instance for every Rect Y.

Figure 9 defines the final approximating preimage arrow. This arrow, the lifts in Figure 8, and the semantic function $\llbracket \cdot \rrbracket_a$ in Figure 2 define an approximating semantics for partial, probabilistic programs.

9.3 Correctness

From here on, $[\cdot]_{pre^*}^{\downarrow}$ interprets programs as approximating preimage* arrow computations using ifte $_{pre^*}^{\downarrow}$. The following

theorems assume $\mathsf{h} := \llbracket e \rrbracket^{\psi}_{\mathsf{pre}^*} : \mathsf{X}_{\stackrel{\leadsto}{\mathsf{pre}^*}} \mathsf{Y}$ and $\mathsf{h}' := \llbracket e \rrbracket^{\psi}_{\mathsf{pre}^*} ' : \mathsf{X}_{\stackrel{\leadsto}{\mathsf{pre}^*}} \mathsf{Y}$ for some expression e.

Theorem 9.5 (approximation). For all $A \in \text{Rect } \langle \langle R, T \rangle, X \rangle$ and $B \in \text{Rect } Y$, ap_{pre} (h j₀ A) $B \subseteq ap'_{pre}$ (h' j₀ A) B.

Proof. By construction.
$$\Box$$

To use structural induction on the interpretation of e, we need a theorem that allows representing it as a finite expression (Definition 8.27). Because ifte $^{\downarrow}_{pre^*}$ does not branch when either branch could be taken, an equivalent finite expression exists for each rectangular domain subset A.

Theorem 9.6 (equivalent finite expression). Let $A \in \text{Rect } \langle \langle R, T \rangle, X \rangle$. There is a finite expression e' for which ap'_{pre} (h'' j_0 A) $B = ap'_{pre}$ (h' j_0 A) B for all $B \in \text{Rect } Y$, where $h'' := \llbracket e' \rrbracket_{pre^*}^{\Downarrow}$.

Proof. Let $\mathsf{T}' := \mathsf{proj}_{\mathsf{snd}}$ ($\mathsf{proj}_{\mathsf{fst}}$ A), and the index prefix J' contain every j' for which ($\mathsf{project}$ j' T')\{ \bot } is either { true } or { false }. To construct e', exhaustively apply first-order functions in e, but replace any if e_1 e_2 e_3 whose index is not in J' with the equivalent expression if e_1 \bot \bot . Because e is well-defined, recurrences must be guarded by if, so this process terminates after finitely many applications.

Corollary 9.7 (convergence). For all $A \in Rect \langle \langle R, T \rangle, X \rangle$ and $B \in Rect Y$, ap'_{pre} (h' j_0 A) B converges.

Theorem 9.8 (monotonicity). ap'_{pre} (h' j_0 A) B is monotone in both A and B.

Proof. Lattice operators (\cap) and (\vee) are monotone, as is (\times). Therefore, id_{pre} and the other lifts in Figure 8 are monotone, and each approximating preimage arrow combinator preserves monotonicity. Approximating preimage* arrow combinators, which are defined in terms of approximating preimage arrow combinators (Figure 9) likewise preserve monotonicity, as does η'_{pre^*} ; therefore id_{pre^*} and other lifts are monotone.

The definition of ifte $^{\mu}_{pre^*}$ can be written in terms of lattice operators and approximating preimage arrow combinators for any A for which $C_b \subset \{true, false\}$, and thus preserves monotonicity in that case. If $C_b = \{true, false\}$, which is an upper bound for C_b , the returned value is an upper bound.

For monotonicity in A, let $A' \in \text{Rect } \langle \langle R, T \rangle, X \rangle$, and e' be a finite expression equivalent to e for A' (Theorem 9.3). Monotonicity for rectangular subsets of A' follows from structural induction on the interpretation of e'.

$$\begin{array}{lll} X \underset{\mathsf{pre}}{\rightharpoonup}' Y ::= \langle \mathsf{Rect} \ \mathsf{Y}, \mathsf{Rect} \ \mathsf{Y} \Rightarrow \mathsf{Rect} \ \mathsf{X} \rangle & \langle \cdot, \cdot \rangle_{\mathsf{pre}}' : (X \underset{\mathsf{pre}}{\rightharpoonup}' Y_1) \Rightarrow (X \underset{\mathsf{pre}}{\rightharpoonup}' Y_2) \Rightarrow (X \underset{\mathsf{pre}}{\rightharpoonup}' Y_1 \times Y_2) \\ & \langle \mathsf{Y}_1', \mathsf{p}_1 \rangle, \langle \mathsf{Y}_2', \mathsf{p}_2 \rangle \rangle_{\mathsf{pre}}' := \\ & \langle \mathsf{Y}_1' \times \mathsf{Y}_2', \lambda \mathsf{B}. \ \mathsf{p}_1 \ (\mathsf{proj}_{\mathsf{fst}} \ \mathsf{B}) \cap \mathsf{p}_2 \ (\mathsf{proj}_{\mathsf{snd}} \ \mathsf{B}) \rangle \\ & \langle \mathsf{Y}_1' \times \mathsf{Y}_2', \lambda \mathsf{B}. \ \mathsf{p}_1 \ (\mathsf{proj}_{\mathsf{fst}} \ \mathsf{B}) \cap \mathsf{p}_2 \ (\mathsf{proj}_{\mathsf{snd}} \ \mathsf{B}) \rangle \\ & \langle \mathsf{Y}_1' \times \mathsf{Y}_2', \lambda \mathsf{B}. \ \mathsf{p}_1 \ (\mathsf{proj}_{\mathsf{fst}} \ \mathsf{B}) \cap \mathsf{p}_2 \ (\mathsf{proj}_{\mathsf{snd}} \ \mathsf{B}) \rangle \\ & \langle \mathsf{Y}_1' \times \mathsf{Y}_2', \lambda \mathsf{B}. \ \mathsf{p}_1 \ (\mathsf{proj}_{\mathsf{fst}} \ \mathsf{B}) \cap \mathsf{p}_2 \ (\mathsf{proj}_{\mathsf{snd}} \ \mathsf{B}) \rangle \\ & \langle \mathsf{Y}_1' \times \mathsf{Y}_2', \lambda \mathsf{B}. \ (\mathsf{proj}_{\mathsf{fst}} \ \mathsf{B}) \cap \mathsf{p}_2 \ (\mathsf{proj}_{\mathsf{snd}} \ \mathsf{B}) \rangle \\ & \langle \mathsf{Y}_1', \mathsf{p}_1 \rangle \oplus_{\mathsf{pre}}' \ \mathsf{Y}_2', \lambda \mathsf{B}. \ (\mathsf{proj}_{\mathsf{fst}} \ \mathsf{Y}) \Rightarrow (\mathsf{X} \underset{\mathsf{pre}}{\rightharpoonup}' \ \mathsf{Y}) \\ & \langle \mathsf{Y}_1', \mathsf{p}_1 \rangle \oplus_{\mathsf{pre}}' \ \mathsf{Y}_2', \lambda \mathsf{B}. \ (\mathsf{proj}_{\mathsf{fst}} \ \mathsf{Y}) \Rightarrow (\mathsf{X} \underset{\mathsf{pre}}{\rightharpoonup}' \ \mathsf{Y}) \rangle \\ & \langle \mathsf{Y}_1', \mathsf{p}_1 \rangle \oplus_{\mathsf{pre}}' \ \mathsf{Y}_2', \lambda \mathsf{B}. \ (\mathsf{proj}_{\mathsf{fst}} \ \mathsf{B}) \cap \mathsf{p}_2 \ (\mathsf{proj}_{\mathsf{snd}} \ \mathsf{B}) \rangle \\ & \langle \mathsf{Y}_1' \times \mathsf{Y}_2', \lambda \mathsf{B}. \ (\mathsf{proj}_{\mathsf{fst}} \ \mathsf{B}) \cap \mathsf{p}_2 \ (\mathsf{proj}_{\mathsf{snd}} \ \mathsf{B}) \rangle \\ & \langle \mathsf{Y}_1' \times \mathsf{Y}_2', \lambda \mathsf{B}. \ (\mathsf{proj}_{\mathsf{fst}} \ \mathsf{B}) \cap \mathsf{p}_2 \ (\mathsf{proj}_{\mathsf{snd}} \ \mathsf{B}) \rangle \\ & \langle \mathsf{Y}_1', \mathsf{p}_1 \rangle \oplus_{\mathsf{pre}}' \ \mathsf{Y}_2', \lambda \mathsf{B}. \ (\mathsf{proj}_{\mathsf{fst}} \ \mathsf{B}) \cap \mathsf{p}_2 \ (\mathsf{proj}_{\mathsf{snd}} \ \mathsf{B}) \rangle \\ & \langle \mathsf{Y}_1' \times \mathsf{Y}_2', \lambda \mathsf{B}. \ (\mathsf{proj}_{\mathsf{fst}} \ \mathsf{B}) \cap \mathsf{p}_2 \ (\mathsf{proj}_{\mathsf{snd}} \ \mathsf{B}) \rangle \\ & \langle \mathsf{Y}_1', \mathsf{p}_1 \rangle \oplus_{\mathsf{pre}}' \ \mathsf{Y}_2', \lambda \mathsf{B}. \ (\mathsf{proj}_{\mathsf{pre}}' \ \mathsf{Y}_2', \mathsf{p}_2 \rangle \otimes \mathsf{pre}' \ \mathsf{Y}_2' \rangle \otimes \mathsf{pre}' \ \mathsf{Pre}' \ \mathsf{Y}_2' \rangle \otimes \mathsf{pre}' \ \mathsf{Pre}' \ \mathsf{Y}_2' \rangle \otimes \mathsf{pre}' \ \mathsf{Pre}' \ \mathsf{Pre}' \ \mathsf{Y}_2' \rangle \otimes \mathsf{Pre}' \ \mathsf{Pre}' \$$

(a) Definitions for approximating preimage mappings that compute rectangular preimage covers.

$$\begin{split} X_{\overrightarrow{pre}}'Y ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (\ggg_{\mathsf{pre}}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (\ggg_{\mathsf{pre}}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (\ggg_{\mathsf{pre}}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (\ggg_{\mathsf{pre}}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (\ggg_{\mathsf{pre}}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (\ggg_{\mathsf{pre}}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \Rightarrow (X \xrightarrow{pre}'Y) \\ (X \xrightarrow{pre}'Y) ::= & \mathsf{Rect} \ X \Rightarrow (X \xrightarrow{pre}'Y) \Rightarrow$$

(b) An approximating preimage arrow, defined in terms of approximating preimage mappings.

$$\begin{array}{lll} X \underset{\text{pre*}}{\sim} 'Y & ::= & J \Rightarrow (\langle S, X \rangle_{p \overrightarrow{re}} 'Y) & \text{ifte}'_{p re^*} : (X \underset{\text{pre}}{\sim} 'Bool) \Rightarrow (X \underset{\text{pre}}{\sim} 'Y) \Rightarrow (X \underset{\text{pre}}{\sim} 'Y) \Rightarrow (X \underset{\text{pre}}{\sim} 'Y) \\ S & ::= & (J \rightarrow [0,1]) \times (J \rightarrow Bool_{\perp}) & \text{ifte}'_{p re^*} : (X \underset{\text{pre}}{\sim} 'Bool) \Rightarrow (X \underset{\text{pre}}{\sim} 'Y) \Rightarrow (X \underset{\text{pre}}{\sim} 'Y) \Rightarrow (X \underset{\text{pre}}{\sim} 'Y) \\ (k_2 & (left (right j)) & (k_2 & (left (right j))) \\ (k_3 & (right (right j))) & (k_3 & (right (right j))) \\ (k_1 & \ggg'_{p re^*} k_2) \ j & := \\ (fst_{p re^*}$$

(c) An approximating preimage* arrow, defined in terms of the approximating preimage arrow.

$$\begin{split} & \mathsf{random'_{pre^*}} : \mathsf{X} \underset{\mathsf{pre^*}}{\sim}'[0,1] \\ & \mathsf{random'_{pre^*}} : \mathsf{fst_{pre}} \ggg'_{\mathsf{pre}} \mathsf{fst_{pre}} \ggg'_{\mathsf{pre}} \mathsf{fst_{pre}} \ggg'_{\mathsf{pre}} \mathsf{fst_{pre}} \ggg'_{\mathsf{pre}} \mathsf{fst_{pre}} \implies'_{\mathsf{pre}} \mathsf{fst_{pre}} \ggg'_{\mathsf{pre}} \mathsf{fst_{pre}} \implies'_{\mathsf{pre}} \mathsf{fst_{pre}} \ggg'_{\mathsf{pre}} \mathsf{fst_{pre}} \implies'_{\mathsf{pre}} \mathsf{fst_{pre}} \implies'_{\mathsf$$

Figure 9: Implementable arrows that approximate preimage arrows. Because $\mathsf{arr}_{\mathsf{pre}}$ is generally uncomputable, there is no corresponding $\mathsf{arr}'_{\mathsf{pre}}$ combinator. However, specific lifts such as $\mathsf{fst}_{\mathsf{pre}} := \mathsf{arr}_{\mathsf{pre}}$ fst are computable, and are defined in Figure 8.

For monotonicity in B, let e' be the finite expression equivalent to e for any fixed A. Monotonicity follows from structural induction on the interpretation of e'.

Theorem 9.9 (approximate preimages are decreasing). For $A \in \text{Rect } \langle \langle R, T \rangle, X \rangle$ and $B \in \text{Rect } Y$, ap'_{pre} (h' j_0 A) $B \subseteq A$.

⁽d) Additional preimage* arrow combinators, for retrieving random numbers and branch traces, and computing without diverging.

Proof. Because they compute exact preimages of rectangular sets under restriction to rectangular domains, $\mathsf{id}_{\mathsf{pre}}$ and the other lifts in Figure 8 are decreasing.

By definition and applying basic lattice properties,

$$\begin{array}{lll} \mathsf{ap}_{\mathsf{pre}}' \; ((\mathsf{h}_1 \ggg_{\mathsf{pre}}' \mathsf{h}_2) \; \mathsf{A}) \; \mathsf{B} \; \equiv \; \mathsf{ap}_{\mathsf{pre}}' \; (\mathsf{h}_1 \; \mathsf{A}) \; \mathsf{B}' \; \; \mathsf{for some} \; \mathsf{B}' \\ \mathsf{ap}_{\mathsf{pre}}' \; ((\mathsf{h}_1 \; \&\&\&_{\mathsf{pre}}' \mathsf{h}_2) \; \mathsf{A}) \; \mathsf{B} \; \equiv \; \mathsf{ap}_{\mathsf{pre}}' \; (\mathsf{h}_1 \; \mathsf{A}) \; (\mathsf{proj}_{\mathsf{fst}} \; \mathsf{B}) \; \cap \\ \mathsf{ap}_{\mathsf{pre}}' \; (\mathsf{ifte}_{\mathsf{pre}}' \mathsf{h}_1 \; \mathsf{h}_2 \; \mathsf{h}_3 \; \mathsf{A}) \; \mathsf{B} \; \equiv \; \mathsf{let} \; \; \mathsf{A}_2 := \mathsf{ap}_{\mathsf{pre}}' \; (\mathsf{h}_1 \; \mathsf{A}) \; \{\mathsf{true}\} \\ \mathsf{A}_3 := \mathsf{ap}_{\mathsf{pre}}' \; (\mathsf{h}_1 \; \mathsf{A}) \; \{\mathsf{false}\} \\ \mathsf{in} \; \; \mathsf{ap}_{\mathsf{pre}}' \; (\mathsf{h}_2 \; \mathsf{A}_2) \; \mathsf{B} \; \vee \\ \mathsf{ap}_{\mathsf{pre}}' \; (\mathsf{h}_3 \; \mathsf{A}_3) \; \mathsf{B} \\ \\ \mathsf{ap}_{\mathsf{pre}}' \; (\mathsf{lazy}_{\mathsf{pre}}' \; \mathsf{h} \; \mathsf{A}) \; \mathsf{B} \; \equiv \; \mathsf{if} \; (\mathsf{A} = \varnothing) \; \varnothing \; (\mathsf{ap}_{\mathsf{pre}}' \; (\mathsf{h} \; 0 \; \mathsf{A}) \; \mathsf{B}) \end{array}$$

Thus, approximating preimage arrow combinators return decreasing computations when given decreasing computations. This property transfers trivially to approximating preimage* arrow combinators.

Let e' be the finite expression equivalent to e for A; that approximate preimages are decreasing follows from structural induction on the interpretation of e'.

Corollary 9.10 (approximate preimages preserve disjointness). *If* $A_1 \cap A_2 = \emptyset$, *then* ap'_{pre} (h' $j_0 A_1$) $B \cap ap'_{pre}$ (h' $j_0 A_2$) $B = \emptyset$.

9.4 Preimage Refinement Algorithm

With disjointness and monotonicity properties proved, it is natural to suppose that we can compute probabilities of preimages of B by computing preimages with respect to increasingly fine discretizations of A.

Definition 9.11 (preimage refinement algorithm). Let $h' := [e]_{pre^*}^{\downarrow \downarrow} : X_{pre^*}^{\leadsto} Y$, $B \in \text{Rect Y}$, and define

refine : Rect
$$\langle \langle R, T \rangle, X \rangle \Rightarrow \text{Rect } \langle \langle R, T \rangle, X \rangle$$

refine A := ap'_{pre} (h' i_0 A) B

Define partition : Rect $\langle \langle R, T \rangle, X \rangle \Rightarrow$ Set (Rect $\langle \langle R, T \rangle, X \rangle$) to produce positive-measure, disjoint rectangles, and define

$$\begin{split} \text{refine}^* : & \mathsf{Set} \; \big(\mathsf{Rect} \; \langle \langle \mathsf{R}, \mathsf{T} \rangle, \mathsf{X} \rangle \big) \Rightarrow \mathsf{Set} \; \big(\mathsf{Rect} \; \langle \langle \mathsf{R}, \mathsf{T} \rangle, \mathsf{X} \rangle \big) \\ & \mathsf{refine}^* \; \mathcal{A} := \mathsf{image} \; \mathsf{refine} \; \left(\bigcup_{\mathsf{A} \in \mathcal{A}} \mathsf{partition} \; \mathsf{A} \right) \end{split} \tag{82}$$

For any $A \in \text{Rect } \langle \langle R, T \rangle, X \rangle$, iterate refine* on $\{A\}$.

Theorem 9.8 (monotonicity) guarantees that the union of preimage refinements of a partition of A is never larger than the refinement of A itself. Corollary 9.10 (disjointness) guarantees that the refinements of a partition of A are a partition; thus, its measure is the sum of the measures of the rectangles that comprise it. Theorem 9.5 guarantees that the algorithm is **sound**: the true preimage of B is always contained in the covering partition refine* returns.

We would like it to be **complete** up to null sets; i.e. covering partitions' measures should converge to the true preimage measure. Unfortunately, preimage refinement appears to compute the **Jordan outer measure** of a preimage, which is not always its measure. A counterexample is the expression rational? random, where rational? returns true when its argument is rational and diverges otherwise. (This is definable using a (\leq) primitive.) The preimage of {true} has measure 0, but its Jordan outer measure is 1.

We conjecture that a minimal requirement for preimage refinement's measures to converge is that a program must converge with probability 1. There are certainly other requirements. We leave these and proof of convergence of measures for future work.

For now, we use algorithms that depend only on preimage refinement's soundness.

10. Implementations

We have four implementations: one of the exact semantics, two direct implementations of the approximating semantics, and a less direct but more efficient implementation of the approximating semantics, which we call *Dr. Bayes*.

10.1 Direct Implementations

If sets are restricted to be finite, the arrows used as translation targets in the exact semantics, defined in Figures 1, 3, 4, 5, 6 and 7, can be implemented directly in any practical λ -calculus with a set data type. Computing exact preimages is very inefficient, even under the interpretations of very small programs. However, we have found our Typed Racket [24] implementation useful for finding theorem candidates.

Given a rectangular set library, the approximating preimage arrows defined in Figures 8 and 9 can be implemented with few changes in any practical λ -calculus. We have done so in Typed Racket and Haskell [1]. Both implementations' arrow combinator definitions are almost line-for-line transliterations from the figures.

Making the rectangular set type polymorphic seems to require the equivalent of a typeclass system. In Haskell, it also requires multi-parameter typeclasses or indexed type families [6] to associate set types with the types of their members. Using indexed type families, the only significant differences between the Haskell implementation and the approximating semantics are type contexts, newtype wrappers for arrow types, and using Maybe types as bottom arrow return types.

Typed Racket has no typeclass system on top of its type system, so the rectangular set type is monomorphic; thus, so are the arrow types. The lack of type variables in the combinator types is the only significant difference between the implementation and the approximating semantics.

All three direct implementations can currently be found at XXX: URL.

10.2 Dr. Bayes

Our main implementation, $Dr.\ Bayes$, is written in Typed Racket. It consists of the semantic function $[\cdot]_{a^*}$ from Figure 2 and its extension $[\cdot]_{a^*}^{\downarrow}$, the bottom* arrow as defined in Figures 3 and 7, the approximating preimage and preimage* arrows as defined in Figures 8 and 9, and algorithms to compute approximate probabilities. We use it to test the feasibility of solving real-world problems by computing approximate preimages.

Dr. Bayes's arrows operate on a monomorphic rectangular set data type. It includes floating-point intervals to overapproximate real intervals, with which we compute approximate preimages under arithmetic and inequalities. Finding the smallest covering rectangle for images and preimages under $\mathsf{add}: \langle \mathbb{R}, \mathbb{R} \rangle \Rightarrow \mathbb{R}$ and other monotone functions is fairly straightforward. For piecewise monotone functions, we dis-

tinguish cases using iftepre; e.g.

$$\begin{array}{l} \mathsf{mul}_{\mathsf{pre}} := \mathsf{ifte}_{\mathsf{pre}} \; \big(\mathsf{fst}_{\mathsf{pre}} > \!\!\!>_{\mathsf{pre}} \mathsf{positive?}_{\mathsf{pre}} \big) \\ & \big(\mathsf{ifte}_{\mathsf{pre}} \; \big(\mathsf{snd}_{\mathsf{pre}} > \!\!\!>_{\mathsf{pre}} \mathsf{positive?}_{\mathsf{pre}} \big) \\ & \mathsf{mul}_{\mathsf{pre}}^{++} \\ & \big(\mathsf{ifte}_{\mathsf{pre}} \; \big(\mathsf{snd}_{\mathsf{pre}} > \!\!\!>_{\mathsf{pre}} \mathsf{negative?}_{\mathsf{pre}} \big) \\ & \mathsf{mul}_{\mathsf{pre}}^{+-} \\ & \big(\mathsf{const}_{\mathsf{pre}} \; 0 \big) \big) \big) \\ & \dots \end{array}$$

To support data types, the set type includes tagged rectangles; for ad-hoc polymorphism, it includes disjoint unions.

Section 9.4 outlines preimage refinement: a discretization algorithm that seems to converge for programs that halt with probability 1, consisting of repeatedly shrinking and repartitioning a program's domain. We do not use this algorithm directly in our main implementation because it is inefficient. Good accuracy requires fine discretization, which is *exponential* in the number of discretized axes. For example, a nonrecursive program that contains only 10 uses of random would need to partition 10 axes of R, the set of random sources. Splitting each axis into only 4 disjoint intervals yields a partition of R of size $4^{10} = 1,048,576$.

Fortunately, Bayesian practitioners tend to be satisified with sampling methods, which are usually much more efficient than exact methods based on enumeration.

Let $g:X_{\widetilde{map}}Y$ be the interpretation of a program as a mapping arrow computation. A Bayesian is primarily interested in the probability of $B'\subseteq Y$ given some condition set $B\subseteq Y$. If A:= preimage $(g\:X)\:B$ and A':= preimage $(g\:X)\:B'$, the probability of B' given B is

$$Pr[B'|B] := P(A' \cap A)/PA$$
 (84)

This can be approximated using **rejection sampling**. Given a nonempty list of samples xs from any superset of A, the conditional probability in (84) is approximately

$$Pr[B'|B] \approx \frac{length (filter (\in A' \cap A) xs)}{length (filter (\in A) xs)}$$
(85)

where ' \approx ' (rather loosely) denotes convergence as the length of xs increases. The probability that any given element of xs is in A is often extremely small, so it would clearly be best to sample only within A. While we cannot do that, we can easily sample from a partition covering A.

For a fixed number d of uses of random, n samples, and m repartitions that split each rectangle in two, enumerating and sampling from a covering partition has time complexity $O(2^{md} + n)$. Fortunately, we do not have to enumerate the rectangles in the partition: we sample them instead, and sample one x from each rectangle, which is O(mdn).

We cannot directly compute $a \in A$ or $a \in A' \cap A$ in (85), but we can use the fact that A and A' are preimages, and use the interpretation of the program as a bottom arrow computation $f: X \leadsto_{\perp} Y$:

filter (
$$\in$$
 A) xs = filter (\in preimage (g X) B) xs
= filter (λ a. g X a \in B) xs
= filter (λ a. f a \in B) xs

Substituting into (85) gives

$$Pr[B'|B] \approx \frac{length (filter (\lambda a. f a \in B' \cap B) xs)}{length (filter (\lambda a. f a \in B) xs)}$$
(87)

which converges to the probability of B' given B as the number of samples xs from the covering partition increases.

For simplicity, the preceding discussion does not deal with projecting preimages from the domain of programs $(R \times T) \times \{\langle \rangle \}$ onto the set of random sources R. Shortly, Dr. Bayes samples rectangles from covering partitions of $(R \times T) \times \{\langle \rangle \}$ subsets, weights each rectangle by the inverse of the probability with which it is sampled, and projects onto R. This alogorithm is a variant of **importance sampling** [7, Section 12.4], where the candidate distribution is defined by the sampling algorithm's partitioning choices, and the target distribution is P.

XXX: specific problems

11. Loosely Related Work

XXX: possible citations:

- labeling/numbering expressions (check CFA lit.)
- bananas and lenses
- isomorphic data structure transformations
- prolog stuff
- constraint-functional programming

12. Related Work

XXX: copy citations below to appropriate places in the introduction

XXX: moar citations

XXX: rework prose below to fit paper better

Koller and Pfeffer [14] efficiently compute exact distributions for the outputs of programs in a Scheme-like language. BUGS [18] focuses on efficient approximate computation for probabilistic theories with a finitely many statements, with distributions that practitioners typically use. BLOG [20] exists specifically to allow stating distributions over countably infinite vectors. BLAISE [5] allows stating both distribution and approximation method for each random variable. Church [8] is a Scheme-like probabilistic language with approximate inference, and focuses on expressiveness.

Kiselyov [12] embeds a probabilistic language in O'Caml for efficient computation. It uses continuations to enumerate or sample random variable values, and has a fail construct for the *complement* of conditioning. The sampler looks ahead for fail and can handle it efficiently. This may be justified by commutativity (Thm. ??), depending on interaction with other language features.

There is a fair amount of semantics work in probabilistic languages. Most of it is not motivated by Bayesian concerns, and thus does not define conditioning. Kozen [15] defines the meaning of bounded-space, imperative "while" programs as functions from probability measures to probability measures. Hurd [10] proves properties about programs with binary random choice by encoding programs and portions of measure theory in HOL.

Jones [11] develops a domain-theoretic variation of probability theory, and with it defines the probability monad, whose discrete version is a distribution-valued variation of the set or list monad. Ramsey and Pfeffer [23] define the probability monad measure-theoretically and implement a language for finite probability. We do not build on this work because the probability monad does not build a probability space, making it difficult to reason about conditioning.

Pfeffer also develops IBAL [22], apparently the only lambda calculus with finite probabilistic choice that also defines conditional queries. Park [21] extends a lambda calculus with probabilistic choice, defining it for a very general

class of probability measures using inverse transform sampling.

13. Conclusions and Future Work

XXX: todo

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