Final Exam

1. Please traverse the tree shown in Fig. 1a using preorder and inorder (8%)

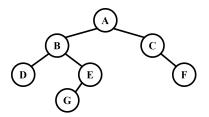


Fig.1a: tree traversal (Q1)

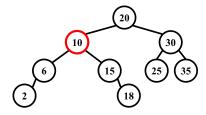


Fig.1b: binary search tree deletion (Q2)

Preorder: $A \rightarrow B \rightarrow D \rightarrow E \rightarrow G \rightarrow C \rightarrow F$ Inorder: $D \rightarrow B \rightarrow G \rightarrow E \rightarrow A \rightarrow C \rightarrow F$

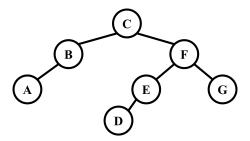
2. Please describe the algorithm for **deleting a non-leaf node with two children** in a **binary search tree** using the **node 10** in Fig. 1b as an example (6%)

We can swap the node 10 with its successor: the minimum node of the right subtree

(or the maximum node of the left subtree) (3%). After that, we can simply cut and reconnect the rest of the tree (2%) because the successor must have a degree of 1 or 0 (1%).

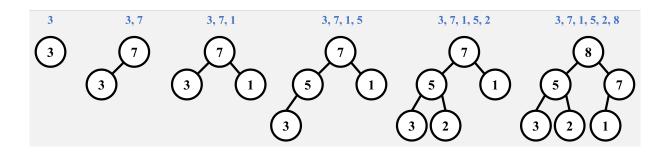
3. A binary search tree can be uniquely decided given its **preorder** or **postorder** traversal result. Please draw the tree if its **preorder** is $C \to B \to A \to F \to E \to D \to G$ (6%)

The answer is shown in below figure:



- 4. Please answer the following questions about **Heap**:
 - (a) Explain which data structure (array or pointer) is more suitable to implement a heap. (4%) Array is more suitable. Heap is a complete binary tree so no space will be wasted when using array (2%). Most importantly, using arrays allows faster access to the parent and children of a node, which is cruical for heap operations (2%).
 - (b) Please build a max heap for the input sequence: 3, 7, 1, 5, 2, 8. You should draw the tree after **each** number is inserted into the heap (6%)

The answer is shown in below figures: 1% for each figure



5. Please transform the **forest** in Fig. 2a into a single **binary tree** using the **left-child-right-sibling** approach. (6%)

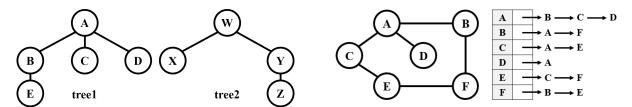
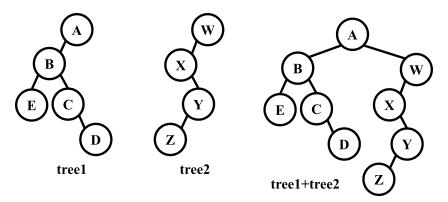


Fig.2a: forest (Q5)

Fig.2b: graph traversal (Q6)

The answer is shown in below figures: drawing correct tree1+tree2 can get 6%. If tree1+tree2 is incorrect, any correct figure of tree1 and tree2 can get 2%



6. Traverse the graph (starting from **A**) shown in Fig. 2b using **depth-first search (DFS)** and **breadth-first search (BFS)**. The traversal order should depend on the adjacency list (8%)

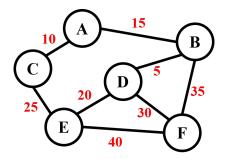
DFS: $A \rightarrow B \rightarrow F \rightarrow E \rightarrow C \rightarrow D$ BFS: $A \rightarrow B \rightarrow C \rightarrow D \rightarrow F \rightarrow E$

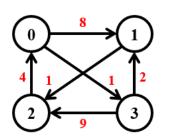
- 7. Consider an array of 8 elements being sorted using quicksort. It has just finished the first pass of partitioning and pivot swapping, thus the original array into [7, 11, 16, 10, 17, 1, 18, 30]. Write down all possible elements that could have been the pivot in the first pass (6%) 18, 30
- 8. Please describe how to use straight-radix sort (sorting from the least significant bit) to sort the following numbers: 63, 49, 783, 7, 543, 132, 898 (6%)

First run: sort with the digits: 132 o 63 o 783 o 543 o 7 o 898 o 49

Second run: sort with the ten digits while preserving the previous order of digits: 7 \rightarrow 132 \rightarrow 543 \rightarrow 49 \rightarrow 63 \rightarrow 783 \rightarrow 898

Third run: sort with the hundred digits while preserving the previous orders of ten digits and digits: $7 \to 49 \to 63 \to 132 \to 543 \to 783 \to 898$





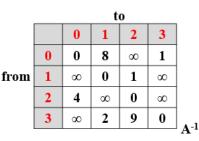
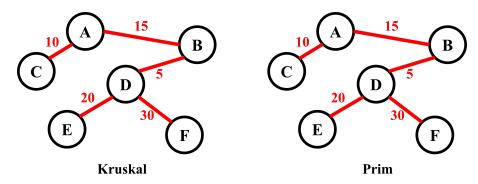


Fig.3a: minimum cost spanning tree (Q9)

Fig.3b: shortest paths (Q10)

9. Please find the minimum cost spanning tree of the graph shown in Fig. 3a using (a) Kruskal's algorithm and (b) Prim's algorithm (starting from A). You can just draw the results. (8%) The answer is shown in below figures: 4% for each figure



- 10. Consider the directed graph shown in Fig. 3b, answering the following questions:
 - (a) Write down each step of **Dijkstra's algorithm** to find the shortest path from vertex **0** to vertex **2**. (6%)

The answer is shown in below figures: 2%, 2%, 1%, 1% for the four passes

Pass	Explored Set	0	1	2	3
1	{0 }	0	8	∞	1
2	{ 0 , 3 }	0	3	10	1
3	{0, 3, 1 }	0	3	4	1
4	{0, 3, 1, 2 }	0	3	4	1

(b) The matrix A^{-1} shows the initial values to find all-pairs shortest paths with Floyd-Warshall's algorithm. Derive A^0 , A^1 , A^2 , and A^3 (8%) The answer is shown in below figures: 2% for each pass

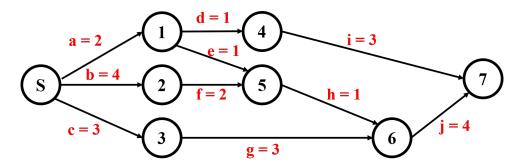
	0	1	2	3
0	0	8	∞	1
1	∞	0	1	- x
2	4	12	0	5
3	∞	2	9	0
A 0				

	0	1	2	3
0	0	8	9	1
1	∞	0	1	∞
2	4	12	0	5
3	∞	2	3	0
		A	1	

	0	1	2	3
0	0	8	9	1
1	5	0	1	6
2	4	12	0	5
3	7	2	3	0
		A	2	

	0	1	2	3
0	0	3	4	1
1	5	0	1	6
2	4	7	0	5
3	7	2	3	0
\mathbf{A}^3				

11. The following figure shows an **active-on-edge (AOE)** network, please determining the earliest completion time of **node5**, **node6**, and **node7** (6%)

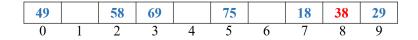


node5: 6 (2%); node6: 7 (2%); node7: 11 (2%)

12. The following figure shows a **10-bucket hash table** implemented with a **circular array** and each bucket can store only **one** record. A hash function h(K) = K%N is used with N being the number of buckets. To handle collision, **quadratic probing** with the following modified hash function $H_i(K) = (h(K) + i^2)\%N$ is used with i being the times of collisions. Please insert the following numbers into the hash table in order: 38, 29, 58, 49, 69, 18, 75 (6%)



The answer is shown in below figures: 1% for 29, 58, 49, 69, 18, 75



- 13. Select all correct statements about sorting a list of numbers with an increasing order (10%)
 - (a) Insertion sort encounters its worst case if the input list is in decreasing order
 - (b) If average-case time complexity is the main consideration, quick sort is a good choice
 - (c) If worst-case time complexity is important, merge sort is more suitable than quick sort
 - (d) When using **heap sort**, it is better to use a **max-heap** for sorting numbers in an **increasing order**
 - (e) All comparison-based sorting algorithms have a time complexity $\Omega(n \log n)$ abcde