

# Embedded Systems Summary

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# 1 Scheduling

## 1.1 Definitions

- $J = \{j_1, j_2, \dots, j_n\}$  is a set of tasks.
- $a_i$  or  $r_i$  is the arrival / release time of task  $i$ .
- $d_i$  is the deadline of task  $i$ .
- $C_i$  is the total computation time of task  $i$ .
- $c_i(t)$  is the the remaining execution time of task  $i$  at time  $t$ .
- $s_i$  is the start time of task  $i$ .
- $f_i$  is the finish time of task  $i$ .
- $L_i = f_i - d_i$  is the lateness of task  $i$ .
- $E_i = \max(0, L_i)$  is the exceeding time or tardyness of task  $i$ .
- $X_i = d_i - a_i - C_i$  is the laxity or slack of task  $i$ .

## 1.2 Generic Time Triggered Cyclic Executive Scheduler

Let  $f$  denote the frame length,  $P$  the full period,  $D(k)$  the relative deadline of task  $k$ , and  $p(k)$  the period of task  $k$  (how often it occurs). Then the following conditions have to be satisfied:

- $\forall k. f \leq p(k)$  (at most one execution within a frame)
- $P = \text{lcm}_k(p(k))$
- $\forall k. f \geq C_k$  (processes start and complete within single frame)
- $\forall k. 2f - \text{gcd}(p(k), f) \leq D(k)$  (between release time and deadline of every task there is at least one frame boundary)

## 1.3 Aperiodic Scheduling

	Equal arrival, non-preemptive	Arbitrary arrival, preemptive
Independent Tasks	EDD	EDF
Dependent Tasks	LDF	EDF*

### 1.3.1 EDD

Schedule the tasks in order of non-decreasing deadlines. This minimizes the maximal lateness.

### 1.3.2 EDF

Always execute the task with the earliest absolute deadline. Schedulability test:

$$\forall i \in [n]. t + \sum_{k=1}^i c_k(t) \leq d_i$$

**1.3.3 LDF**

Among all tasks without successors select the task with the latest deadline. Put it in a stack. Repeat until no more tasks. Now execute tasks as they are on the stack.

**1.3.4 EDF\***

Modify arrival and deadline of each task and use EDF on modified tasks.

$$r_j^* = \max_j \left( r_j, \max_i (r_i^* + C_i | J_i \rightarrow J_j) \right)$$
$$d_i^* = \min_i \left( d_i, \min_j (d_j^* - C_j | J_i \rightarrow J_j) \right)$$