

Desenho de Algoritmos Programming Project I

An Analysis Tool for Railway Network Management

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INTRODUCTION

In this first programming project we were asked to implement an analysis tool that can support the management team of a railway network to make informed decisions about how to best allocate its resources, both financial as well as physical (e.g., trains).

This tool, which uses a realistic data set, allows management to decide on aspects such as how to best assign selected trains to lines, how to maximize its revenue when multiple levels of service are offered, or even, identify more sensitive sections of its network to failures so as to anticipate service disruption or at least to mitigate its nefarious effects.

IMPLEMENTATION

As the project objective states, the group needed to successfully use the greedy algorithmic approach in the context of maximum-flow problems in order to correctly perform the task that were required.

The first step was then to define the area to be tested and whether we would use the parser available or would we create the files ourselves containing the necessary information. We quickly realized that it would be more practical and instructive to create our own test files that are essentially the same that were given but in a more scaled down version.

Effectively, having the files ready and a well-defined idea of the area to be tested, easily, we have created the necessary functions to read text files, also creating the nodes and edges of our graph.

- Maximum Number of trains that can arrive simultaneously at a given station - Edmonds-Karp per each station: O(V^2 E^2)
- Maximum Number of Trains between two trains - Edmonds-Karp: O(V E^2);
- Maximum Number of Trains between two trains
 (Reduced Connectivity) we allow the user to choose reduction factor therefore the subgraph is generated dynamically Edmonds-Karp: O(V E^2);

• Edmonds-Karp pseudocode:

```
algorithm EdmondsKarp is
    input:
                (graph[v] should be the list of edges coming out of vertex v in the
        graph
                 original graph and their corresponding constructed reverse edges
                 which are used for push-back flow.
                 Each edge should have a capacity, flow, source and sink as parameters,
                 as well as a pointer to the reverse edge.)
                (Source vertex)
        S
                (Sink vertex)
        t
   output:
                (Value of maximum flow)
       flow
   flow := 0
                (Initialize flow to zero)
```

```
repeat
         (Run a breadth-first search (bfs) to find the shortest s-t path.
          We use 'pred' to store the edge taken to get to each vertex,
          so we can recover the path afterwards)
         q := queue()
         q.push(s)
         pred := array(graph.length)
         while not empty(q)
             cur := q.pop()
             for Edge e in graph[cur] do
                 if pred[e.t] = null and e.t ≠ s and e.cap > e.flow then
                     pred[e.t] := e
                     q.push(e.t)
    if not (pred[t] = null) then
        (We found an augmenting path.
        See how much flow we can send)
        df := ∞
        for (e := pred[t]; e \neq null; e := pred[e.s]) do
            df := min(df, e.cap - e.flow)
        (And update edges by that amount)
        for (e := pred[t]; e ≠ null; e := pred[e.s]) do
            e.flow := e.flow + df
            e.rev.flow := e.rev.flow - df
        flow := flow + df
until pred[t] = null (i.e., until no augmenting path was found)
return flow
```

• Pairs of Stations that require the most amount of trains when taking full advantage of the network capacity - Floyd-Warshall (modified): O(V^3)

 Top-k Transportation Needs using K as an optimization for a partial sort - Greedy Algorithm: O(V^2)

```
cnt = 0
tmp[K] = {} //desending array
for each pair(key, pld) in
   if(cnt < K)
       insert_sort(tmp[], pair)
   else
      if(pair.key > tmp[k].key)
            insert_sort(tmp[], pair)
```

 Maximum Number of trains with minimum cost between two stations - Dijkstra (with PQ) + Edmonds Karp: O(V E^2)

```
function Dijkstra(Graph, source):
        dist[source] \leftarrow 0
                                                         // Initialization
        create vertex priority queue Q
       for each vertex v in Graph.Vertices:
            if v \neq source
                 dist[v] \leftarrow INFINITY
                                                        // Unknown distance from source to v
                 prev[v] \leftarrow UNDEFINED
                                                        // Predecessor of v
10
11
            Q.add_with_priority(v, dist[v])
13
14
       while Q is not empty:
                                                        // The main loop
            u \leftarrow Q.\text{extract}_{min}()
                                                        // Remove and return best vertex
15
            for each neighbor v of u:
16
                                                        // Go through all v neighbors of u
                 alt \leftarrow dist[u] + Graph.Edges(u, v)
17
18
                 if alt < dist[v]:
                     dist[v] \leftarrow alt
20
                     prev[v] \leftarrow u
                     Q.decrease_priority(v, alt)
21
22
23
        return dist, prev
```