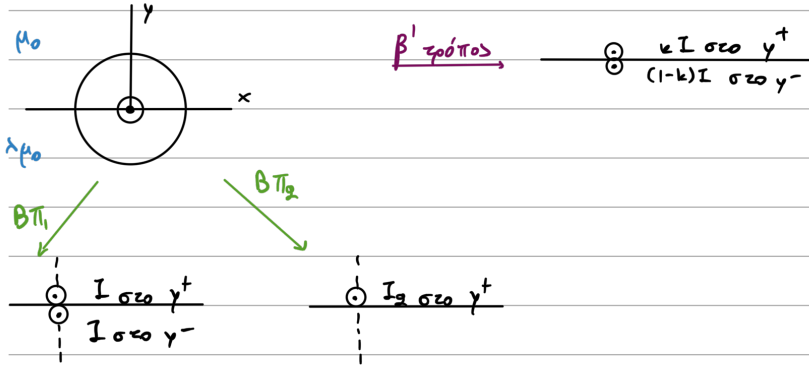


### Παράδειγμα 1



$B \pi_1$  :  $I_1 = \frac{\lambda - 1}{\lambda + 1} I$

$I_{0\lambda} = I + \frac{\lambda - 1}{\lambda + 1} I = \frac{2\lambda}{\lambda + 1} I$

$2\pi r H_1 = \frac{2\lambda}{\lambda + 1} \Rightarrow \vec{H}_1 = \frac{2\lambda}{\lambda + 1} \cdot \frac{I}{2\pi r} \Rightarrow \vec{B}_1 = \frac{2\lambda}{\lambda + 1} \cdot \frac{\mu_0 I}{2\pi r}$

$B \pi_2$  :  $I_2 = \frac{2}{\lambda + 1} I$

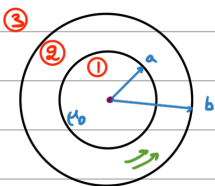
$\vec{H}_2 = \frac{2}{\lambda + 1} \cdot \frac{I}{2\pi r} \Rightarrow \vec{B}_2 = \frac{2}{\lambda + 1} \cdot \frac{\lambda \mu_0 I}{2\pi r}$

$(\text{Μπορούμε να πάρουμε } \oint \vec{H} \cdot d\vec{l} = I \dots)$

$\oint \vec{B} \cdot d\vec{l} = \mu_0 (I + I_m) + \mu_0 I$  ,  $I_m = \lim_{r \rightarrow 0} [r \int_0^{2\pi} \vec{M} \cdot \hat{\varphi} d\varphi]$

$\vec{M} = \frac{\vec{B}}{\mu_0} - \vec{H} = \frac{\lambda - 1}{\lambda + 1} \cdot \frac{I}{\pi r} \hat{\varphi}$

### Παράδειγμα 3 ii SOS!! (ίδιο παρ. με πύλωση!)



$\vec{M}_2 = M_0 \frac{r^2}{a^2} \hat{\varphi}$

$B, H, A?$

$\vec{A}(r=a) = 0$

$\vec{J}_{M1} = \vec{J}_{M3} = 0$

$\vec{J}_{M2} = \nabla \times \vec{M}_2 = \frac{1}{r} \frac{d}{dr} \left( r M_0 \frac{r^2}{a^2} \right) = \frac{3 M_0 r}{a^2} \hat{\varphi}$

$\vec{K} = \hat{n} \times (\vec{M}_2 - \vec{M}_1)$

$\vec{K}(r=a) = \vec{r} \times (\vec{M}_2 - \vec{M}_1) = M_0 \hat{z}$

$\vec{K}(r=b) = \vec{r} \times (\vec{M}_3 - \vec{M}_2) = -M_0 \frac{b^2}{a^2} \hat{z}$

↳ Επίλυση με ολοκληρωτικές για το  $\vec{B}$ :

$$\frac{\partial \phi}{\partial y} = 0 = \frac{\partial \phi}{\partial z}$$

$$\oint_C \vec{B} \cdot d\vec{l} = \mu_0 (I + I_p)$$

$$B_1 \cdot 2\pi r = \mu_0 \int_0^r J_{M1} \cdot 2\pi r' dr' \Rightarrow \vec{B}_1 = 0$$

$$B_2 \cdot 2\pi r = \mu_0 K_M(r=a) \cdot 2\pi a + \mu_0 \int_a^r J_{M2} \cdot 2\pi r' dr' \Rightarrow \vec{B}_2 = \mu_0 M_0 \frac{r^2}{a^2} \hat{\phi}$$

$$B_3 \cdot 2\pi r = \mu_0 K_M(r=a) \cdot 2\pi a + \mu_0 \int_a^b J_{M2} \cdot 2\pi r' dr' + \mu_0 K_M(r=b) \cdot 2\pi b = 0 \Rightarrow \vec{B}_3 = 0$$

$$\vec{B} = \mu_0 (\vec{H} + \vec{M}), \quad \vec{H} = \vec{B} - \vec{M}$$

$$\vec{H}_1 = 0, \quad \vec{H}_2 = \frac{\vec{B}_2}{\mu_0} - \vec{M}_2 = 0, \quad \vec{H}_3 = 0$$

$$\vec{A} = A(r) \hat{z} \quad (\text{διότι τα ρεύματα ρέουν ως προς z})$$

$$\vec{\nabla} \times \vec{A} = \vec{B} = -\frac{dA}{dr} \hat{\phi} \Rightarrow A_{1,2,3} = -\int B_{1,2,3} dr + C_{1,2,3}$$

$$A_1 = C_1, \quad A_2 = -\mu_0 M_0 \frac{r^3}{3a^2} + C_2, \quad A_3 = C_3$$

$$\hookrightarrow A_1(r=a) = 0 \Rightarrow C_1 = 0$$

$$\hookrightarrow A_2(r=a) = -\mu_0 M_0 \frac{a}{3} + C_2 = 0 \Rightarrow C_2 = \mu_0 M_0 \frac{a}{3}$$

$$\hookrightarrow A_3(r=b) = A_2(r=b) \Rightarrow C_3 = -\mu_0 M_0 \frac{b^3 - a^3}{3a^2}$$

## Κεφάλαιο 6: Laplace

$$\Delta \phi = g$$

$\Delta$ : Διαφορικός ή ολοκληρωτικός τελεστής

$$a \phi_{xx} + b \phi_{xy} + c \phi_{yy} + d \phi_x + e \phi_y + f \phi = g, \quad \phi_{xx} = \frac{\partial^2 \phi}{\partial x^2}$$

$a, b, c$ : κατηγοριοποίηση των ΜΔΕ

$$\text{Γενικώς: } a=a(\phi), \quad b=b(\phi), \quad c=c(\phi) \quad \text{μη γραμμική}$$

$$\hookrightarrow b^2 - 4ac: \begin{cases} < 0: \text{ελλειπτική} \\ > 0: \text{υπερβολική} \\ = 0: \text{παραβολική} \end{cases}$$

Η κατηγοριοποίηση αναφέρεται σε  $\Delta$ ,  $a, b, c$  σταθερές

$a, b, c$ : συνάρτηση της  $\vec{r}$

$$\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = 0 \quad \text{Laplace (*)}$$

Η Σ προβλήματα  
Μ Σ προβλήματα

$$\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = g(x, y) \quad \text{Poisson} \quad g = \frac{\rho}{\epsilon} (*)$$

↳ Θα δούμε  $2D, 3D \rightarrow$  καρτεσιανές συντεταγμένες

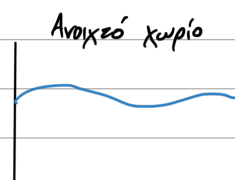
$$a=1, c=1, b=0, \Delta < 0 \rightarrow \text{ελλ. τύπου}$$

ελαστικό  
κωρύ

•  $\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + k^2 \phi = 0$ : Helmholtz

↳ Υπερβολικού τύπου:  $k^2 \frac{\partial^2 \phi}{\partial x^2} - \frac{\partial^2 \phi}{\partial t^2} = 0$  κυματική εξίσωση

↳ Παραβολικού τύπου:  $\frac{\partial \phi}{\partial x} - k \frac{\partial \phi}{\partial t} = 0$  εξίσωση διάχυσης



3Δ

$\rho=0 \Rightarrow \nabla^2 \phi = 0$ ,  $\phi(x,y,z) = X(x) \cdot Y(y) \cdot Z(z) \Rightarrow \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2} = 0 \Rightarrow$

$\Rightarrow yz \frac{d^2 X}{dx^2} + xz \frac{d^2 Y}{dy^2} + xy \frac{d^2 Z}{dz^2} = 0 \Rightarrow \frac{1}{xyz} \left[ x \frac{d^2 X}{dx^2} + y \frac{d^2 Y}{dy^2} + z \frac{d^2 Z}{dz^2} \right] = 0 \Rightarrow K_x + K_y + K_z = 0$

•  $X = A_1 x + A_2$ ,  $K_x = 0$

•  $X = A_3 \cos k_x x + A_4 \sin k_x x$ ,  $K_x < 0$ ,  $K_x = -k_x^2 < 0$   
 $= \hat{A}_3 e^{jk_x x} + \hat{A}_4 e^{-jk_x x}$

•  $X = A_5 e^{k_x x} + A_6 e^{-k_x x}$ ,  $K_x > 0$ ,  $K_x = k_x^2 > 0$   
 $= \hat{A}_5 \cosh(k_x x) + \hat{A}_6 \sinh(k_x x)$

2Δ

$K_z = 0$ ,  $K_x + K_y = 0$

$\phi = xy = (A_1 x + A_2)(B_1 y + B_2) = A_{xy} + B_x + \Gamma_y + \Delta$ ,  $K_x = K_y = 0$

$\phi = \left\{ \begin{matrix} e^{\pm i} \\ \sinh \\ \cosh \\ \sin \\ \cos \\ e^{\pm i} \end{matrix} \right\} (k_x) \left\{ \begin{matrix} e^{\pm i} \\ \sinh \\ \cosh \\ \sin \\ \cos \\ e^{\pm i} \end{matrix} \right\} (k_y)$ ,  $k_x = k_y = k$

