

Τετάρτη, 20/10/2022

$$A = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 1 \\ -1 & -1 & 1 & 1 & -1 & 1 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$A - I = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & -1 & 1 \\ -1 & -1 & 0 & 1 & -1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$(A - I)^2 = \begin{bmatrix} 0 \\ -1 \\ -1 \\ 0 \\ 1 \\ 0 \end{bmatrix}$$

$$J = \begin{bmatrix} 1 & 1 & 0 & | & & \\ 0 & 1 & 1 & | & & \\ 0 & 0 & 1 & | & & \\ & & & 1 & 1 & | \\ & & & 0 & 1 & | \\ & & & & & 1 \end{bmatrix}$$

$$(A - I)u_1 = 0 \Rightarrow u_1 \in \text{Ker}(A - I)$$

$$(A - I)u_2 = u_1 \Rightarrow u_1 \in \text{Im}(A - I) \quad (A - I)^2 u_1 = 0 \Rightarrow u_2 \in \text{Ker}[(A - I)^2]$$

$$(A - I)u_3 = u_2 \Rightarrow (A - I)^2 u_2 = 0$$

$$(A - I)u_4 = 0$$

$$(A - I)u_5 = u_4$$

$$(A - I)u_6 = 0$$

$$\text{Im}(Q) = \{y \mid y = Qx\}$$

$$u_1 = \begin{bmatrix} 0 \\ -1 \\ -1 \\ 0 \\ 1 \\ 0 \end{bmatrix}$$

$$(A - I)x = 0 \Rightarrow \begin{cases} -x_2 - x_5 + x_6 = 0 & x_6 = 0 \\ -x_1 - x_2 + x_4 - x_5 + x_6 = 0 & \Rightarrow x_1 = x_4 \\ x_2 + x_5 = 0 & x_2 = -x_5 \end{cases}$$

$$x = \begin{bmatrix} \alpha \\ \beta \\ \gamma \\ \alpha \\ -\beta \\ 0 \end{bmatrix}$$

$$u_2 \in \text{Im}(A - I) \cap \text{Ker}[(A - I)^2]$$

$$L = [ * * * * * 0 ]^T$$

$$u_2 = \alpha' \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + \beta' \begin{bmatrix} 0 \\ -1 \\ -1 \\ 0 \\ 1 \\ 0 \end{bmatrix} + \gamma' \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$u_2 = \begin{bmatrix} 0 \\ \gamma' - \beta' \\ \alpha' - \beta' + \gamma' \\ 0 \\ \beta' \\ 0 \end{bmatrix}, \quad (A - I)u_2 = u_1 = \begin{bmatrix} 0 \\ -1 \\ -1 \\ 0 \\ 1 \\ 0 \end{bmatrix} \Rightarrow$$

$$\Rightarrow \beta' - \gamma' - \beta' = -1 \Rightarrow \gamma = 1$$

$$u_2 = \begin{bmatrix} 0 \\ 1 - \beta' \\ 1 - \beta' + \alpha' \\ 0 \\ \beta' \\ 0 \end{bmatrix}$$

$$(A - I)u_2 = u_2, \quad -u_{21} + u_{24} = \alpha' \\ u_{22} + v_{35} = \beta', \quad u_2 = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}, \quad u_2 = \begin{pmatrix} 0 \\ 1 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$V = \left[ \begin{array}{ccc|cc|c} 0 & 0 & 0 & 0 & 0 & 1 \\ -1 & 1 & 0 & 0 & 0 & 0 \\ -1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \end{array} \right]$$

$$(A - \lambda I)u_5 = u_4$$

$$\beta' = 0, \gamma' = 1, \alpha = -1, u_4 =$$

$$\begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}$$

$$A = V J V^{-1}$$

$$f(A) = V f(J) V^{-1}$$

$$J_2(\lambda) = \begin{pmatrix} \lambda & 1 \\ 0 & \lambda \end{pmatrix}, J_2(\lambda, \epsilon) = \begin{pmatrix} \lambda & 1 \\ 0 & \lambda + \epsilon \end{pmatrix}$$

$$[\lambda_1 I - J_2(\lambda, \epsilon)]u_1 = \begin{bmatrix} 0 & -1 \\ \epsilon & -\epsilon \end{bmatrix} u_1 = 0, u_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$[\lambda_2 I - J_2(\lambda, \epsilon)]u_2 = \begin{bmatrix} \epsilon & -1 \\ 0 & 0 \end{bmatrix} u_2 = 0 \Rightarrow u_2 = \begin{pmatrix} 1 \\ \epsilon \end{pmatrix}$$

$$T = (u_1, u_2) = \begin{pmatrix} 1 & 1 \\ 0 & \epsilon \end{pmatrix}, T^{-1} = \begin{pmatrix} 1 & -1/\epsilon \\ 0 & 1/\epsilon \end{pmatrix}$$

$$f(J_2(\lambda, \epsilon)) = T f(\lambda) T^{-1} = \begin{bmatrix} 1 & 1 \\ 0 & \epsilon \end{bmatrix} \begin{bmatrix} f(\lambda) & 0 \\ 0 & f(\lambda + \epsilon) \end{bmatrix} \begin{bmatrix} 1 & -1/\epsilon \\ 0 & 1/\epsilon \end{bmatrix}$$

$$= \begin{bmatrix} f(\lambda) & \frac{f(\lambda + \epsilon) - f(\lambda)}{\epsilon} \\ 0 & f(\lambda + \epsilon) \end{bmatrix}$$

$$\epsilon \rightarrow 0 \quad f(J_2(\lambda, \cdot)) = \lim_{\epsilon \rightarrow 0} f(J_2(\lambda, \epsilon)) = \begin{bmatrix} f(\lambda) & f'(\lambda) \\ 0 & f(\lambda) \end{bmatrix}$$

$$f(J_k(\lambda)) = \begin{bmatrix} f(\lambda) & f'(\lambda) & f''(\lambda)/2! & \dots & \frac{1}{(k-1)!} f^{(k-1)}(\lambda) \\ & f(\lambda) & f'(\lambda) & & \\ & & \ddots & & f'(\lambda) \\ & & & & f(\lambda) \end{bmatrix}$$

$$f(J_2(\lambda, t) \cdot t) = T f(\lambda t) T^{-1} = \begin{bmatrix} 1 & 1 \\ 0 & \varepsilon \end{bmatrix} \begin{bmatrix} f(\lambda t) & 0 \\ 0 & f((\lambda + \varepsilon)t) \end{bmatrix} \begin{bmatrix} 1 & -1/\varepsilon \\ 0 & 1/\varepsilon \end{bmatrix}$$

$$\left( \begin{matrix} \delta = \varepsilon t \\ \frac{1}{\varepsilon} = \frac{t}{\delta} \end{matrix} \right) = \begin{bmatrix} f(\lambda t) & \frac{t}{\delta} (f(\lambda t + \delta) - f(\lambda t)) \\ 0 & f(\lambda t + \delta) \end{bmatrix}$$

$$f(J_2(\lambda, t, t)) = \lim_{\delta \rightarrow 0} f(J_2(\lambda, t), t) = \begin{bmatrix} f(\lambda t) & t f'(\lambda t) \\ 0 & f(\lambda t) \end{bmatrix}$$

$$f(J_k(\lambda t)) = \begin{bmatrix} f(\lambda t) & t f'(\lambda t) & \frac{t^2}{2!} f''(\lambda t) & \dots & \frac{t^{k-1}}{(k-1)!} f^{(k-1)}(\lambda t) \\ & f(\lambda t) & t f'(\lambda t) & \dots & \frac{t^{k-2}}{(k-2)!} f^{(k-2)}(\lambda t) \\ & & \ddots & & f(\lambda t) \end{bmatrix}$$

$$e^{J_k(\lambda t)} = \begin{bmatrix} e^{\lambda t} & t e^{\lambda t} & \frac{t^2}{2!} e^{\lambda t} & \dots & \frac{t^{(k-1)}}{(k-1)!} e^{\lambda t} \\ 0 & e^{\lambda t} & t e^{\lambda t} & & \frac{t^{(k-2)}}{(k-2)!} e^{\lambda t} \\ 0 & & e^{\lambda t} & & \\ \vdots & & & \ddots & \\ 0 & & & & e^{\lambda t} \end{bmatrix}$$



Για συστήματα διακριτού χρόνου  $x(k+1) = Ax(k) \Rightarrow x(k) = A^k x(0)$

$$A^* = V J^* V^{-1}$$

Χρονικές Απουσίες

$$\dot{x} = Ax + Bu$$

$$y = Cx + Du$$

$$x(t) = e^{At} x(0) + \int_0^t e^{A(t-s)} Bu(s) ds$$

$$y(t) = Ce^{At} x(0) + \int_0^t Ce^{A(t-s)} Bu(s) ds + Du(t)$$

A stable

(Hurwitz)

$$x(t) \rightarrow x^* \quad Ax^* + Bu^* = 0$$

$$y(t) \rightarrow y^* \quad x^* = -A^{-1}Bu^*$$

$$y = [D - CA^{-1}B]u^*$$

$$G(s) = C(sI - A)^{-1}B + D$$

$$Y(s) = G(s)U(s) + C(sI - A)^{-1}x(0)$$

Θεώρημα Τελικής Τιμής:  $\lim_{t \rightarrow \infty} y(t) = \lim_{s \rightarrow 0} sY(s)$  (αν το  $y$  φτάει σε μόνιμη κατάσταση.)

Για βηματική είσοδο:  $u(t) = \begin{cases} 1, & t \geq 0 \\ 0, & t < 0 \end{cases}$

$$\lim_{t \rightarrow \infty} y(t) = \lim_{s \rightarrow 0} G(s) = G(0)$$