

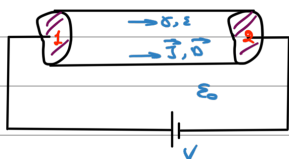
Σχέση R-C

$$\vec{D} \rightarrow \vec{E}$$

$$\epsilon \rightarrow \gamma$$

$$R = \frac{V}{I} = \frac{\int_1^2 \vec{E} \cdot d\vec{l}}{\oint \vec{J} \cdot d\vec{S}}, \quad C = \frac{Q}{V} = \frac{\oint_{S_1} \vec{D} \cdot d\vec{S}}{\int_1^2 \vec{E} \cdot d\vec{l}}$$

$f, \epsilon = 0, \vec{K} = 0$
Διόμοιος



1^η Περίπτωση: $\gamma: \vec{E}, \vec{J}$ Διόμοιος

2^η Περίπτωση: $\epsilon: \vec{E}, \vec{D}$

3^η Περίπτωση: γ, ϵ (ε' $\rho, \sigma \neq 0$)

Αν $\rho \neq 0$, δεν ορίζεται η C

Διόμοιος:

Αντίστοιχοι:

$$\vec{E}, \vec{J}, \gamma, G = 1/R, I \leftrightarrow \oint \vec{J} \cdot d\vec{S}$$

Παρανοήσι:

$$\vec{E}, \vec{D}, \epsilon, C, Q, \sigma$$

$$\hat{n} \cdot (\vec{J}_2 - \vec{J}_1) = -\nabla \cdot \vec{K}$$

$$\vec{\sigma} = \hat{n} \cdot \vec{J}_2 = \hat{n} \cdot \vec{J}_1 - \nabla \cdot \vec{K}$$



$$\epsilon_2 \ll \gamma_1$$

Διόμοιος ισχύει αν ισχύουν και τα 2

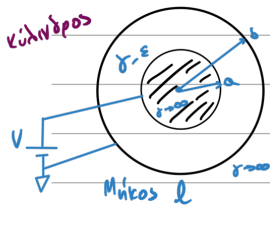
$$\epsilon_2 \ll \epsilon_1$$

* γνκ ο διόμοιος ισχύει εδν έχουμε ίδια γεωμετρία και 1-1 αντιστοιχία στα μεγέθη*

εδν $\epsilon_2 = 0 \neq \epsilon_1$ οπότε δεν θα ισχύει ο διόμοιος, αλλά επειδή ισχύουν ταυτόχρονα οι

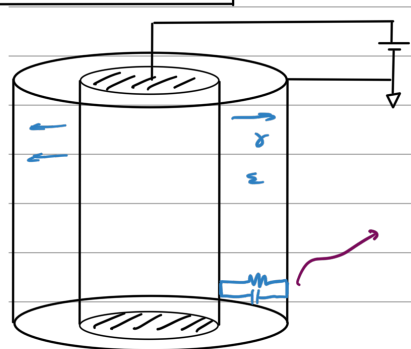
$\epsilon_2 \ll \gamma_1, \epsilon_2 \ll \epsilon_1$ μπορούμε να τον εφαρμόσουμε*

Παράδειγμα 1

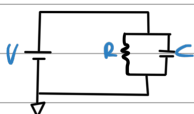


• Είχαμε βρει πως: $R = \frac{\ln(b/a)}{2\pi\gamma l} = \frac{1}{G} \Rightarrow G = \frac{2\pi\gamma l}{\ln(b/a)}$

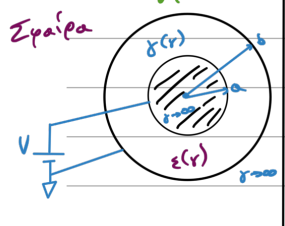
• Από διόμοιο: $G \leftrightarrow C, \gamma \leftrightarrow \epsilon \Rightarrow C = \frac{2\pi\epsilon l}{\ln(b/a)}$



• Υπό την προϋπόθεση: $\rho = \nabla \cdot \vec{D} = 0$



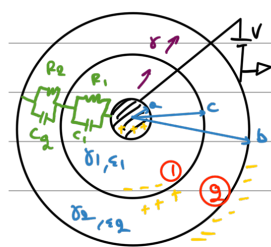
Παράδειγμα 2



• Είχαμε βρει πως: $R = \frac{1}{4\pi} \int_a^b \frac{dr}{\gamma(r)r^2} = \frac{1}{G} \Rightarrow G = \frac{4\pi}{\int_a^b \frac{dr}{\gamma(r)r^2}}$

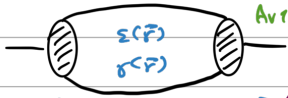
• Από διόμοιο: Θεωρούμε $\epsilon(r) (\leftrightarrow \gamma(r))$: $C = \frac{4\pi}{\int_a^b \frac{dr}{\epsilon(r)r^2}}$

Θα είναι ίδια συνάρτηση! (π.χ. $\gamma(r) = \epsilon(r) = 1+r$)



$$R = R_1 + R_2$$

Ηλεκτρικά φορτία στα Μόνιμα Ηλεκτρικά Πεδία (ΜΗΠ)



Αντιστάσεις

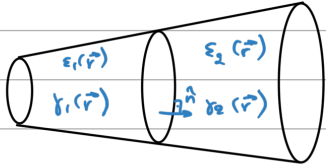
διαν. θέμα
δχι ακριβώς συνεχές γινόμεν!

$$\nabla \cdot \vec{J} = \frac{\partial \rho}{\partial t} = 0$$

$$\rho = \nabla \cdot \vec{D} = \nabla \cdot [\epsilon(\vec{r}) \cdot \vec{E}(\vec{r})] = \nabla \cdot \left[\frac{\epsilon(\vec{r})}{r(\vec{r})} \vec{J}(\vec{r}) \right] = \nabla \cdot \left[\frac{\epsilon(\vec{r})}{\delta(\vec{r})} \right] \cdot \vec{J}(\vec{r}) + \frac{\epsilon(\vec{r})}{\delta(\vec{r})} \cdot \nabla \cdot \vec{J}(\vec{r}) = \nabla \cdot \left[\frac{\epsilon(\vec{r})}{\delta(\vec{r})} \right] \cdot \vec{J}(\vec{r}) \neq 0$$

συν. γιν. πρ. πρ. πρ.

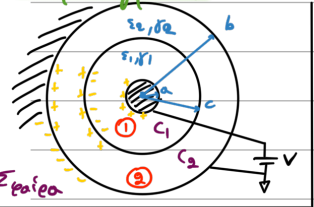
$$\rho = 0 \quad \text{av:} \quad \begin{aligned} &\epsilon_1 \gamma = \sigma \text{ καθ.} \\ &\epsilon = \frac{\epsilon(\vec{r})}{\delta(\vec{r})} = \sigma \text{ καθ} \end{aligned}$$



$$\begin{aligned} &\vec{n} \cdot (\vec{J}_2 - \vec{J}_1) = -\nabla \cdot \vec{E} \\ &\sigma = \vec{n} \cdot (\vec{D}_2 - \vec{D}_1) = \frac{\epsilon_2}{\delta_2} J_{n2} - \frac{\epsilon_1}{\delta_1} J_{n1} = \left(\frac{\epsilon_2}{\delta_2} - \frac{\epsilon_1}{\delta_1} \right) J_n \neq 0 \end{aligned}$$

$$\rightarrow \text{AV} \quad \frac{\epsilon_2}{\delta_2} = \frac{\epsilon_1}{\delta_1} \Rightarrow \sigma = 0$$

Παράδειγμα 1



$$\textcircled{1}, \textcircled{2}: \nabla \cdot \vec{J}_{1,2} = 0 \Rightarrow \vec{J}_{1,2} = \frac{A_{1,2}}{r^2} \hat{r}$$

$$r=c: \vec{r} \cdot (\vec{J}_2 - \vec{J}_1) = 0 \Rightarrow A_1 = A_2 = A$$

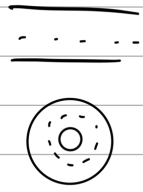
($\vec{E}=0$)

$$\vec{E}_{1,2} = \frac{1}{\delta_{1,2}} \vec{J}_{1,2} = \frac{A}{\delta_{1,2} \cdot r} \hat{r}$$

$$V = \int_a^b \vec{E}_1 \cdot d\vec{r} + \int_c^b \vec{E}_2 \cdot d\vec{r} = \dots = -A \left(\frac{a-c}{\delta_1 \cdot ac} - \frac{c-b}{\delta_2 \cdot bc} \right) \Rightarrow A = \frac{V}{\frac{c-a}{\delta_1 ac} - \frac{b-c}{\delta_2 bc}}$$

$$\rho_{1,2} = \nabla \cdot \vec{D}_{1,2} = \nabla \cdot \left[\frac{\epsilon_{1,2}}{\delta_{1,2}} \right] \cdot \vec{J}_{1,2} = 0$$

Εάν όμως: $\epsilon_1(\vec{r})$ ή/και $\delta_1(\vec{r}) \rightsquigarrow \rho \neq 0$



$$\sigma(r=a) = \vec{r} \cdot \vec{D}_1 = \frac{\epsilon_1}{\delta_1} \frac{A}{a^2} = \sigma_a > 0$$

$$\sigma(r=b) = -\frac{\epsilon_2}{\delta_2} \frac{A}{b^2} = \sigma_b < 0$$

$$\sigma(r=c) = \vec{r} \cdot (\vec{D}_2 - \vec{D}_1) = \vec{r} \cdot \left(\frac{\epsilon_2}{\delta_2} \vec{J}_2 - \frac{\epsilon_1}{\delta_1} \vec{J}_1 \right) = \left(\frac{\epsilon_2}{\delta_2} - \frac{\epsilon_1}{\delta_1} \right) \frac{A}{c^2} = \frac{\epsilon_2}{\delta_2} \frac{A}{c^2} - \frac{\epsilon_1}{\delta_1} \frac{A}{c^2} \equiv \sigma_c$$

$$I_{1,2} = I = \oint \vec{J} \cdot d\vec{S} = A \cdot 4\pi$$

$$C_1 = \frac{Q_1}{V_1} = \frac{\frac{\epsilon_1}{\delta_1} \cdot \frac{A}{a^2} \cdot 4\pi a^2}{A \cdot \frac{1}{\delta_1} \cdot \frac{c-a}{ac}} = \frac{4\pi \epsilon_1 ac}{c-a}$$

$$C_2 = \frac{Q_2}{V_2} = \frac{\sigma_b \cdot 4\pi b^2}{-V_2} = \frac{4\pi \epsilon_2 bc}{b-c}$$

$$R_{\text{ολ}} = \frac{V}{I} = \frac{1}{\frac{\delta_1}{4\pi ac} + \frac{\delta_2}{4\pi bc}}$$

