

Για ιδανική χορδή (ρ, τ) : $T \frac{\partial^2 y}{\partial x^2} = \rho \frac{\partial^2 y}{\partial t^2}$, $c = \sqrt{\frac{T}{\rho}} = \frac{k}{\omega}$

↳ Lösung: $y(x,t) = \underbrace{A \sin(kx + \varphi)}_{f(x)} \cos(\omega t)$

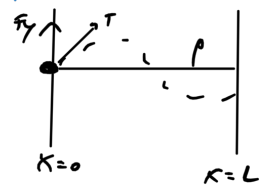
Ακρόντητο σημείο:

$$\psi(x_0, t) = 0 \Rightarrow f(x_0) = 0 \Rightarrow \varphi = -k x_0$$

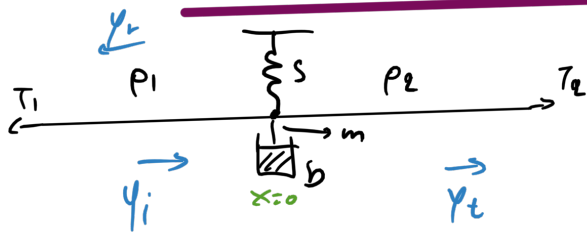
2^o v. N:

$\hookrightarrow \varepsilon \delta \omega \quad x_0 = L$

$$m \left(\frac{\partial^2 y}{\partial t^2} \right)_{x=0} = T \left(\frac{\partial y}{\partial x} \right)_{x=0} - F_y$$



$$F_y = F_0 \cos(\omega t)$$



Προσέτιπτον: $y_i = A e^{i(kx - \omega t)}$

Ανακάλυψη: $y_r = Be^{i(-k_1 x - \omega t)}$

Dispersão: $y_t = e^{i(k_2 x - \omega t)}$

$\Sigma_{\mu\nu} \partial_\mu \psi \partial_\nu \psi$ αὐτὴν ἔχει $\pi=0$

when σ_{mv} approaches $\pi=0$

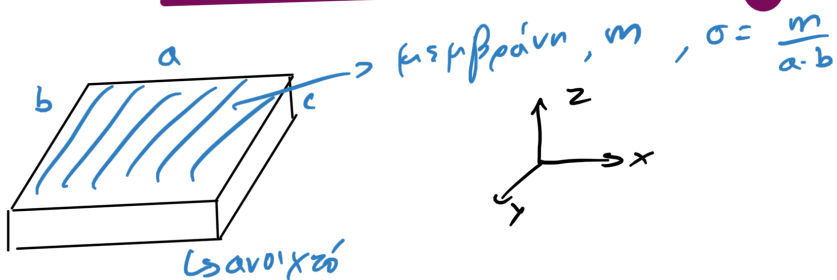
$$(y_i + y_r)_{x=0} = (y_t)_{x=0} \Rightarrow \dots \Rightarrow A+B=C \Rightarrow 1+r=t$$

$$k_1 = \frac{\omega}{c} = \frac{\omega}{\sqrt{\frac{T_1}{\rho_1}}}$$

$$k_2 = \frac{\omega}{c_2} = \frac{\omega}{\sqrt{\frac{\gamma_e}{\rho_2}}}$$

g^{oo} v. N.

$$\frac{2^{20} \cdot v \cdot N}{m \left(\frac{\partial^2 y_2}{\partial t^2} \right)_{x=0}} = T_2 \left(\frac{\partial y_t}{\partial x} \right)_{x=0} - T_1 \left(\frac{\partial (y_i + y_r)}{\partial x} \right)_{x=0} - S(y_t)_{x=0} - k \left(\frac{\partial y_t}{\partial t} \right)_{x=0}$$



Μεμβράνη

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Θεωρούμε λύση: $z(x, y, t) = \frac{A \sin(k_x \cdot x + \theta)}{x(x)} \cdot \frac{B \sin(k_y \cdot y + \rho)}{y(y)} \cdot \omega(\omega t)$

Οριακές συνθήκες:

$$\begin{cases} X(x=0) = 0 \Rightarrow \theta = 0 \\ Y(y=0) = 0 \Rightarrow \varphi = 0 \end{cases}$$

$$\chi(x=a)=0 \Rightarrow k_n = \frac{n\pi}{a}$$

$$Y(y=b) = 0 \Rightarrow k_y = m \frac{\pi}{b}$$

αρθρόνητα
ακρα

$$W_p = c_p \sqrt{k_x^2 + k_y^2} = c_p \pi \sqrt{\frac{n^2}{a^2} + \frac{m^2}{b^2}}$$

Αντιπαράθεση

Θεωρούμε λύσεις: $f(x, y, z, t) = \underbrace{A \sin(k_x x + \theta)}_{X(x)} \underbrace{B \sin(k_y y + \rho)}_{Y(y)} \underbrace{C \sin(k_z z + \varphi)}_{Z(z)} \cos(\omega t)$

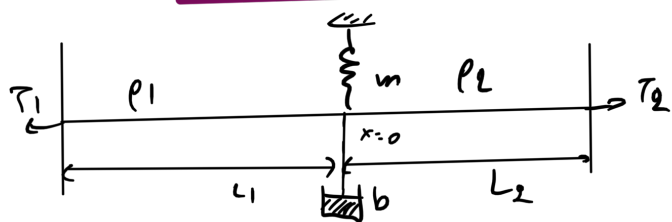
Οριακές συνθήκες:

$$\left. \begin{aligned} X(x=0) &= 0 \Rightarrow \theta = 0 \\ Y(y=0) &= 0 \Rightarrow \rho = 0 \\ Z(z=0) &= 0 \Rightarrow z = 0 \end{aligned} \right\} \begin{aligned} X(x=a) &= 0 \Rightarrow k_x = n \frac{\pi}{a} \\ Y(y=b) &= 0 \Rightarrow k_y = m \frac{\pi}{b} \end{aligned} \left. \vphantom{\begin{aligned} X(x=0) \\ Y(y=0) \\ Z(z=0) \end{aligned}} \right\} \begin{aligned} &\text{αελαίνοντα} \\ &\text{άκρα} \end{aligned}$$

$$\left\{ \left(\frac{\partial Z}{\partial z} \right)_{z=L} = 0 \Rightarrow k_z = \frac{(2l-1)\pi}{L} \right\} \begin{aligned} &\text{ελαστικό} \\ &\text{άκρο} \end{aligned}$$

$$\omega_{\text{αντ}} = c_{\text{ηχ}} \sqrt{k_x^2 + k_y^2 + k_z^2}$$

Δύναμη ανά μονάδα επιφάνειας: $T = c_{\text{ηχ}}^2 \cdot \sigma$



Θεωρούμε λύσεις: $y_{1,2}(x) = f_{1,2}(x) \cos(\omega t)$

$$f_{1,2}(x) = A_{1,2} \sin(k_{1,2} x + \varphi_{1,2})$$

Οριακές συνθήκες

$$f_1(-L_1) = 0 \Rightarrow \varphi_1 = k_1 L_1$$

$$f_2(L_2) = 0 \Rightarrow \varphi_2 = k_2 L_2$$

$$f_1(0) = f_2(0) \Rightarrow A_1 \sin \varphi_1 = A_2 \sin \varphi_2$$

2ος v.N.

$$m \left(\frac{\partial^2 y_1}{\partial t^2} \right)_{x=0} = T_2 \left(\frac{\partial y_2}{\partial x} \right)_{x=0} - T_1 \left(\frac{\partial y_1}{\partial x} \right)_{x=0} - S(y_1)_{x=0} - b \left(\frac{\partial y_1}{\partial x} \right)_{x=0}$$

$$\vec{\nabla} \times \vec{E} = - \frac{\partial \vec{B}}{\partial t}$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \left(\vec{j} + \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right)$$

$$c_0 = \frac{1}{\sqrt{\epsilon_0 \mu_0}}$$

$$\vec{S} = \frac{1}{\mu_0} \vec{E} \times \vec{B}$$

$$\frac{dW}{dV} \cdot c_0 = |\vec{S}|$$

$$k = \frac{\omega}{c} = \frac{2\pi f}{c}$$

$$\frac{dW}{dV} = \frac{\frac{1}{2} \epsilon_0 E^2}{\frac{dW_e}{dV}} + \frac{\frac{1}{2\mu_0} B^2}{\frac{dW_m}{dV}}$$

Γραμμική: $\vec{E} = (\hat{x} E_0 \cos \theta + \hat{y} E_0 \sin \theta) \cos(kz - \omega t)$

Κυκλική: $\vec{E} = \hat{x} E_0 \cos(kz - \omega t) + \hat{y} E_0 \sin(kz - \omega t)$

Ελλειπτική: $\vec{E} = \hat{x} E_{0x} \cos(kz - \omega t) + \hat{y} E_{0y} \sin(kz - \omega t)$

Τυχαία: $\vec{E} = \left[\hat{x} E_0 \cos \varphi(t) + \hat{y} E_0 \sin \varphi(t) \right] \cos(kz - \omega t)$
 \downarrow τυχαία μεταβ. συνάρτ.