

a6/kmeans/kmeans.c

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1  #include <stdio.h>
2  #include <stdlib.h>
3  #include <mpi.h>
4
5  #include "kmeans.h"
6
7  // square of Euclid distance between two multi-dimensional points
8  inline static double euclid_dist_2(int    numdims, /* no. dimensions */
9                                     double * coord1, /* [numdims] */
10                                    double * coord2) /* [numdims] */
11  {
12      int i;
13      double ans = 0.0;
14
15      for(i=0; i<numdims; i++)
16          ans += (coord1[i]-coord2[i]) * (coord1[i]-coord2[i]);
17
18      return ans;
19  }
20
21  inline static int find_nearest_cluster(int    numClusters, /* no. clusters */
22                                       int    numCoords, /* no. coordinates */
23                                       double * object, /* [numCoords] */
24                                       double * clusters) /* [numClusters][numCoords]
25  */
26  {
27      int index, i;
28      double dist, min_dist;
29
30      // find the cluster id that has min distance to object
31      index = 0;
32      min_dist = euclid_dist_2(numCoords, object, clusters);
33
34      for(i=1; i<numClusters; i++) {
35          dist = euclid_dist_2(numCoords, object, &clusters[i*numCoords]);
36          // no need square root
37          if (dist < min_dist) { // find the min and its array index
38              min_dist = dist;
39              index = i;
40          }
41      }
42      return index;
43  }
44
45  void kmeans(double * objects, /* in: [numObjs][numCoords] */
46             int    numCoords, /* no. coordinates */
47             int    numObjs, /* no. objects */
48             int    numClusters, /* no. clusters */
49             double threshold, /* minimum fraction of objects that change
50 membership */
51             long    loop_threshold, /* maximum number of iterations */
52             int * membership, /* out: [numObjs] */

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51         double * clusters)          /* out: [numClusters][numCoords] */
52     {
53         int i, j;
54         int index, loop=0;
55         double timing = 0;
56
57         /* Every variable has its "rank_" version, which is used to store local data,
58          * and its "new" version, which is used to store global data.
59          */
60         double rank_delta, delta = 0;          // fraction of objects whose clusters
change in each loop
61         int * rank_newClusterSize, * newClusterSize; // [numClusters]: no. objects assigned in
each new cluster
62         double * rank_newClusters, *newClusters;    // [numClusters][numCoords]
63
64         // Get rank of this process
65         int rank;
66         MPI_Comm_rank(MPI_COMM_WORLD, &rank);
67
68         // initialize membership
69         for (i=0; i<numObjs; i++)
70             membership[i] = -1;
71
72         // initialize rank_newClusterSize and rank_newClusters to all 0
73         rank_newClusterSize = (typeof(rank_newClusterSize)) calloc(numClusters,
sizeof(*rank_newClusterSize));
74         rank_newClusters = (typeof(rank_newClusters)) calloc(numClusters * numCoords,
sizeof(*rank_newClusters));
75         newClusterSize = (typeof(newClusterSize)) calloc(numClusters,
sizeof(*newClusterSize));
76         newClusters = (typeof(newClusters)) calloc(numClusters * numCoords,
sizeof(*newClusters));
77
78         timing = wtime();
79         do {
80             // before each loop, set cluster data to 0
81             for (i=0; i<numClusters; i++) {
82                 for (j=0; j<numCoords; j++)
83                     rank_newClusters[i*numCoords + j] = 0.0;
84                 rank_newClusterSize[i] = 0;
85             }
86
87             rank_delta = 0.0;
88
89             for (i=0; i<numObjs; i++) {
90                 // find the array index of nearest cluster center
91                 index = find_nearest_cluster(numClusters, numCoords, &objects[i*numCoords],
clusters);
92
93                 // if membership changes, increase rank_delta by 1
94                 if (membership[i] != index)
95                     rank_delta += 1.0;
96
97                 // assign the membership to object i

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98         membership[i] = index;
99
100        // update new cluster centers : sum of objects located within
101        rank_newClusterSize[index]++;
102        for (j=0; j<numCoords; j++)
103            rank_newClusters[index*numCoords + j] += objects[i*numCoords + j];
104    }
105
106    /*
107    * TODO: Perform reduction of cluster data (rank_newClusters, rank_newClusterSize)
from local arrays to shared.
108    */
109    MPI_Allreduce(rank_newClusters, newClusters, numClusters * numCoords, MPI_DOUBLE,
MPI_SUM, MPI_COMM_WORLD);
110    MPI_Allreduce(rank_newClusterSize, newClusterSize, numClusters, MPI_INT, MPI_SUM,
MPI_COMM_WORLD);
111
112    // average the sum and replace old cluster centers with newClusters
113    for (i=0; i<numClusters; i++) {
114        if (newClusterSize[i] > 0) {
115            for (j=0; j<numCoords; j++) {
116                clusters[i*numCoords + j] = newClusters[i*numCoords + j] /
newClusterSize[i];
117            }
118        }
119    }
120
121    /*
122    * TODO: Perform reduction from rank_delta variable to delta variable, that will
be used for convergence check.
123    */
124    MPI_Allreduce(&rank_delta, &delta, 1, MPI_DOUBLE, MPI_SUM, MPI_COMM_WORLD);
125
126    // Get fraction of objects whose membership changed during this loop. This is used
as a convergence criterion.
127    delta /= numObjs;
128
129    loop++;
130    //printf("\r\tcompleted loop %d", loop);
131    //fflush(stdout);
132    } while (delta > threshold && loop < loop_threshold);
133
134    timing = wtime() - timing;
135    if (rank == 0) fprintf(stdout, "          nloops = %3d    (total = %7.4fs)    (per loop =
%7.4fs)\n", loop, timing, timing/loop);
136
137    free(rank_newClusters);
138    free(rank_newClusterSize);
139    free(newClusters);
140    free(newClusterSize);
141
142 }
143

```