# HW2 Handwritten Assignment

Lecturor: Pei-Yuan Wu TAs: Po-Yang Hsieh, Le-Rong Hsu

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#### Problem 1: (Automatic Differentiation) (0.5%)

Let  $f = f_4 \circ f_3 \circ f_2 \circ f_1$  be a differentiable function defined as

$$f: \mathbb{R}^n \to \mathbb{R}$$
  
 $\mathbf{x} \mapsto f_4(f_3(f_2(f_1(\mathbf{x}))))$ 

where  $f_1: \mathbb{R}^n \to \mathbb{R}^{n_3}$ ,  $f_2: \mathbb{R}^{n_3} \to \mathbb{R}^{n_2}$ ,  $f_3: \mathbb{R}^{n_2} \to \mathbb{R}^{n_1}$ , and  $f_4: \mathbb{R}^{n_1} \to \mathbb{R}$ . We assume n >> 1 and  $n > n_3 > n_2 > n_1 > 1$ .

- 1. (0.2%) Write down the derivative of f with respect to  $\mathbf{x}$  using **chain rule**. Next, express **forward-mode** and **reverse-mode** auto-differentiation respectively with the with the formula you just wrote down. The reverse-mode auto-differentiation is also called **backpropagation**. In this problem, for a function g, the notation  $\frac{dg}{d\mathbf{x}}$  is allowed.
- 2. (0.3%) Which mode is better in terms of efficiency? Why? For the second question, you can, but **don't need to rigorously prove** your answer, meaning you don't have to write out extensive mathematical derivations. Note that if you only answer the first question, you will only get 0.01%.

Through this problem, we want students to tell the difference between the forward mode and the reverse mode, and to understand why the reverse mode is usually preferred for optimization over the forward mode.

#### Problem 2 (Batch Normalization)(1%)

**Batch normalization** is a popular trick for training deep networks nowadays, which aims to preserve the distribution within hidden layers and avoids vanishing gradient issue. The alogrithm can be written as below:

During training we need to backpropagate the gradient of loss  $\ell$  through this transformation, as well as compute the gradients with respect to the parameters  $\gamma$ ,  $\beta$ . Towards this end, please write down the close form expressions for  $\frac{\partial \ell}{\partial x_i}$ ,

#### Algorithm 1 Batch Normalization

```
Input Feature from data points over a mini-batch B = (x_i)_{i=1}^m
    Output y_i = BN_{\gamma,\beta}(x_i)
1: procedure BATCHNORMALIZE(B, \gamma, \beta)
        for i \leftarrow 1 to m do
\hat{x}_i \leftarrow \frac{x_i - \mu_B}{\sqrt{\sigma_B^2 + \epsilon}}
y_i \leftarrow \gamma \hat{x}_i + \beta
                                                                                      ⊳ mini-batch mean
                                                                                  ▷ mini-batch variance
3:
4:
                                                                                                 ▷ normalize
5:
6:
                                                                                          ▷ scale and shift
        end for
7:
        return
8:
9: end procedure
```

 $\frac{\partial \ell}{\partial \gamma}$ ,  $\frac{\partial \ell}{\partial \beta}$  in terms of  $x_i$ ,  $\mu_B$ ,  $\sigma_B^2$ ,  $\hat{x}_i$ ,  $y_i$  (given by the forward pass) and  $\frac{\partial \ell}{\partial y_i}$  (given by the backward pass).

- Hint: You may first write down the close form expressions of  $\frac{\partial \ell}{\partial \hat{x}_i}$ ,  $\frac{\partial \ell}{\partial \sigma_B^2}$ ,  $\frac{\partial \ell}{\partial \mu_B}$ , and then use them to compute  $\frac{\partial \ell}{\partial x_i}$ ,  $\frac{\partial \ell}{\partial \gamma}$ ,  $\frac{\partial \ell}{\partial \beta}$ .

# Problem 3 (Multiclass AdaBoost)(1.5%)

Let  $\mathcal{X}$  be the input space,  $\mathcal{F}$  be a collection of multiclass classifiers that map from  $\mathcal{X}$  to [1, K], where K denotes the number of classes. Let  $\{(x_i, \hat{y}_i)\}_{i=1}^m$  be the training data set, where  $x_i \in \mathcal{X}$  and  $\hat{y}_i \in [1, K]$ . Given  $T \in \mathbb{N}$ , suppose we want to find functions

$$g_{T+1}^k(x) = \sum_{t=1}^T \alpha_t f_t^k(x), \quad k \in [1, K]$$

where  $f_t \in \mathcal{F}$  and  $\alpha_t \in \mathbb{R}$  for all  $t \in [1, T]$ . Here for  $f \in \mathcal{F}$ , we denote  $f^k(x) = \mathbf{1}\{f(x) = k\}$ , where  $\mathbf{1}(\cdot)$  is an indicator function, as the k'th element in the one-hot representation of  $f(x) \in [1, K]$ . The aggregated classifier  $h : \mathcal{X} \to [1, K]$  is defined as

$$x \mapsto \underset{1 \le k \le K}{\operatorname{argmax}} g_{T+1}^k(x)$$

Please apply gradient boosting to show how the functions  $f_t$  and coefficients  $\alpha_t$  are computed with an aim to minimize the following loss function

$$L((g_{T+1}^1, \cdots, g_{T+1}^K) = \sum_{i=1}^m \exp\left(\frac{1}{K-1} \sum_{k \neq \hat{y}_i} g_{T+1}^k(x_i) - g_{T+1}^{\hat{y}_i}(x_i)\right)$$

#### Problem 4 (AdaBoosting)(0.5%)

1. Consider training an Adaboosting classifier using decision stumps on the data set illustrated in Figure 1:



Figure 1: AdaBoost Data set

- (a) Which examples will have their weights increased at the end of the first iteration? Circle them.
- (b) How many iterations will it take to achieve zero training error? Justify your answers and show each iteration step.
- 2. Suppose AdaBoost is run on N training examples, and suppose on each round that the weighted training error  $\epsilon_t$  of the t'th weak hypothesis is at most  $1/2-\gamma$ , for some number  $0<\gamma<1/2$ . After how many iterations, T, will the combined hypothesis be consistent with the N training examples, i.e., achieves zero training error? Your answer should only be expressed in terms of N and  $\gamma$ . (Hint: Recall that exponential loss is an upper bound for 0-1 loss. What is the training error when 1 example is misclassified?)

# Problem 5 (Gradient Descent Convergence) (1.5%)

Suppose the function  $f: \mathbb{R}^n \to \mathbb{R}$  is differentiable. Also, f is  $\beta$ -smoothness and  $\alpha$ -strongly convex.

$$\beta - smoothness: \beta > 0, \forall x, y \in \mathbb{R}^n, \|\nabla f(x) - \nabla f(y)\|_2 \le \beta \|x - y\|_2$$

$$\alpha - strongly\ convex: \alpha > 0, \forall \boldsymbol{x}, \boldsymbol{y} \in \mathbb{R}^n, f(\boldsymbol{x}) - f(\boldsymbol{y}) - \nabla f(\boldsymbol{y})^T(\boldsymbol{x} - \boldsymbol{y}) \geq \frac{\alpha}{2} \|\boldsymbol{x} - \boldsymbol{y}\|_2^2$$

Then we propose a gradient descent algorithm

- 1. Find a initial  $\theta^0$ .
- 2. Let  $\boldsymbol{\theta}^{n+1} = \boldsymbol{\theta}^n \eta \nabla_{\boldsymbol{\theta}} f(\boldsymbol{\theta}^n) \ \forall n \geq 0$ , where  $\eta = \frac{1}{\beta}$ .

The following problems lead you to prove the gradient descent convergence.

1. Prove the property of  $\beta$ -smoothness function

$$orall oldsymbol{x}, oldsymbol{y} \in \mathbb{R}^n, f(oldsymbol{x}) - f(oldsymbol{y}) - 
abla f(oldsymbol{y})^T (oldsymbol{x} - oldsymbol{y}) \leq rac{eta}{2} \|oldsymbol{x} - oldsymbol{y}\|_2^2$$

- (a) Define  $g: \mathbb{R} \to \mathbb{R}, g(t) = f(\boldsymbol{y} + t(\boldsymbol{x} \boldsymbol{y}))$ . Show that  $f(\boldsymbol{x}) f(\boldsymbol{y}) = \int_0^1 g'(t) dt$ .
- (b) Show that  $g'(t) = \nabla f(\boldsymbol{y} + t(\boldsymbol{x} \boldsymbol{y}))^T (\boldsymbol{x} \boldsymbol{y})$ .
- (c) Show that  $|f(\boldsymbol{x}) f(\boldsymbol{y}) \nabla f(\boldsymbol{y})^T(\boldsymbol{x} \boldsymbol{y})| \le \int_0^1 |(\nabla f(\boldsymbol{y} + t(\boldsymbol{x} \boldsymbol{y})) \nabla f(\boldsymbol{y}))^T(\boldsymbol{x} \boldsymbol{y})| dt$ .
- (d) By Cauchy-Schwarz inequality and the definition of  $\beta$ -smoothness, show that  $|f(\boldsymbol{x}) f(\boldsymbol{y}) \nabla f(\boldsymbol{y})^T (\boldsymbol{x} \boldsymbol{y})| \leq \frac{\beta}{2} \|\boldsymbol{x} \boldsymbol{y}\|_2^2$ , hence we get

$$f(oldsymbol{x}) - f(oldsymbol{y}) - 
abla f(oldsymbol{y}) - 
abla f(oldsymbol{y})^T (oldsymbol{x} - oldsymbol{y}) \leq rac{eta}{2} \|oldsymbol{x} - oldsymbol{y}\|_2^2$$

2. Let  $\mathbf{y} = \mathbf{x} - \frac{1}{\beta} \nabla f(\mathbf{x})$  and use 1., prove that

$$f(\boldsymbol{x} - \frac{1}{\beta}\nabla f(\boldsymbol{x})) - f(\boldsymbol{x}) \leq -\frac{1}{2\beta}\|\nabla f(\boldsymbol{x})\|_2^2$$

and

$$f(\boldsymbol{x}^*) - f(\boldsymbol{x}) \le -\frac{1}{2\beta} \|\nabla f(\boldsymbol{x})\|_2^2,$$

where  $\boldsymbol{x}^* = \operatorname*{arg\,min}_{\boldsymbol{x}} f(\boldsymbol{x}).$ 

3. Show that  $\forall n \geq 0$ ,

$$\|\boldsymbol{\theta}^{n+1} - \boldsymbol{\theta}^*\|_2^2 = \|\boldsymbol{\theta}^n - \boldsymbol{\theta}^*\|_2^2 + \eta^2 \|\nabla_{\boldsymbol{\theta}} f(\boldsymbol{\theta}^n)\|_2^2 - 2\eta \nabla_{\boldsymbol{\theta}} f(\boldsymbol{\theta}^n)^T (\boldsymbol{\theta}^n - \boldsymbol{\theta}^*),$$
 where  $\boldsymbol{\theta}^* = \operatorname*{arg\,min}_{\boldsymbol{\theta}} f(\boldsymbol{\theta}).$ 

4. Use 2. and the definition of  $\alpha$ -strongly convex to prove  $\forall n \geq 0$ 

$$\|\boldsymbol{\theta}^{n+1} - \boldsymbol{\theta}^*\|_2^2 \le (1 - \frac{\alpha}{\beta}) \|\boldsymbol{\theta}^n - \boldsymbol{\theta}^*\|_2^2,$$

where  $\theta^* = \underset{\theta}{\operatorname{arg\,min}} f(\theta)$ .

5. Use the above inequality to show that  $\theta^n$  will converge to  $\theta^*$  when n goes to infinity.

# Version Description

1. First Edition: Finish Problem 1 to 5