ML2024 Fall Homework Assignment 1 Handwritten

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Problem 1 (Preliminary) (1 pt)

In this problem, you need to find the derivative of 2-norm or a scalar with respect to a vector or a matrix. For (b) and (c), you may start by considering

$$\frac{\partial y}{\partial \mathbf{X}} = \begin{bmatrix} \frac{\partial y}{\partial x_{11}} & \cdots & \frac{\partial y}{\partial x_{1n}} \\ \vdots & \ddots & \vdots \\ \frac{\partial y}{\partial x_{n1}} & \cdots & \frac{\partial y}{\partial x_{nn}} \end{bmatrix}.$$

(Hint: Find a partial derivative with respect to the (i, j)-th component and sort out the vector or matrix form.)

- (a) (0.2 pts)
 - (i) (0.1 pts) Given $\mathbf{x}, \mathbf{a} \in \mathbb{R}^n$. Show that

$$\frac{\partial \|\mathbf{x} - \mathbf{a}\|_2}{\partial \mathbf{x}} = \frac{\mathbf{x} - \mathbf{a}}{\|\mathbf{x} - \mathbf{a}\|_2}.$$

(ii) (0.1 pts) Given $\mathbf{a} \in \mathbb{R}^m$, $\mathbf{X} \in \mathbb{R}^{m \times n}$, $\mathbf{b} \in \mathbb{R}^n$. Show that

$$\frac{\partial \mathbf{a}^\mathsf{T} \mathbf{X} \mathbf{b}}{\partial \mathbf{X}} = \mathbf{a} \mathbf{b}^\mathsf{T}.$$

(b) (0.2 pts) Let $\mathbf{X} \in \mathbb{R}^{n \times n}$. Show that

$$\frac{\partial \det(\mathbf{X})}{\partial \mathbf{X}} = \det(\mathbf{X}) \left(\mathbf{X}^{-1}\right)^{\mathsf{T}}.$$

Hint: Recall the cofactor matrix

$$\mathbf{C} = \left[\begin{array}{ccc} C_{11} & \cdots & C_{1n} \\ \vdots & \ddots & \vdots \\ C_{n1} & \cdots & C_{nn} \end{array} \right]$$

where $C_{ij} = (-1)^{i+j} M_{ij}$ and $M_{ij} = \det((x_{mn})_{m \neq i, n \neq j})$. The adjoint matrix is the transpose of the cofactor matrix

$$adj(\mathbf{X}) = \mathbf{C}^{\mathsf{T}}.$$

We have an identity

$$Xadj(X) = det(X).$$

You may check Wikipedia for more details.

(c) (0.6 pts) Prove that

$$\frac{\partial \log(\det(\mathbf{A}))}{\partial a_{ij}} = \mathbf{e}_j^{\mathsf{T}} \mathbf{A}^{-1} \mathbf{e}_i, \tag{1}$$

where
$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1m} \\ a_{21} & a_{22} & \cdots & a_{2m} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mm} \end{bmatrix} \in \mathbb{R}^{m \times m}$$
 is a (non-singular) matrix, and \mathbf{e}_j is the unit vector

along the j-th axis (e.g. $\mathbf{e}_3 = [0,0,1,0,...,0]^T$). It is common to write (1) as

$$\frac{\partial \log(\det(\mathbf{A}))}{\partial \mathbf{A}} = (\mathbf{A}^{-1})^{\mathsf{T}}$$

Hint: Same as (b).

Problem 2 (Classification with Gaussian Mixture Model) (2.4 pts)

In this question, we tackle the binary classification problem through the generative approach, where we assume the data point X (viewed as a \mathbb{R}^d -valued r.v.) and its label Y (viewed as a $\{C_1, C_2\}$ -valued r.v.) are generated according to the generative model (paramerized by θ) as follows:

$$\mathbb{P}_{\theta}[X = \mathbf{x}, Y = \mathcal{C}_k] = \pi_k f_{\mu_k, \Sigma_k}(\mathbf{x}) \quad (k \in \{1, 2\})$$

where $\theta = (\pi_1, \pi_2, \boldsymbol{\mu}_1, \boldsymbol{\mu}_2, \Sigma_1, \Sigma_2)$ for which

$$f_{\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k}(\mathbf{x}) = \frac{1}{(2\pi)^{d/2}} \frac{1}{|\boldsymbol{\Sigma}_k|^{1/2}} \exp\left(-\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu}_k)^\mathsf{T} \boldsymbol{\Sigma}_k^{-1} (\mathbf{x} - \boldsymbol{\mu}_k)\right).$$

Now suppose we observe data points $\mathbf{x}_1,...,\mathbf{x}_N$ and their corresponding labels $y_1,...,y_N$.

- (a) (1.2 pt)
 - (i) (0.3 pt) Please write down the likelihood function $L(\theta)$ that describes how likely the generative model would generate the observed data $\{(\mathbf{x}_i, y_i)\}_{i=1}^N$ in terms of $\theta = (\pi_1, \pi_2, \boldsymbol{\mu}_1, \boldsymbol{\mu}_2, \Sigma_1, \Sigma_2)$.
 - (ii) (0.3 pt) Find the maximum likelihood estimate $\theta^* = (\pi_1^*, \pi_2^*, \boldsymbol{\mu}_1^*, \boldsymbol{\mu}_2^*, \Sigma_1^*, \Sigma_2^*)$ that maximizes the likelihood function $L(\theta)$.
 - (iii) (0.3 pt) Write down $\mathbb{P}_{\theta}[Y = \mathcal{C}_1 | X = \mathbf{x}]$ and $\mathbb{P}_{\theta}[X = \mathbf{x} | Y = \mathcal{C}_1]$ in terms of $\theta = (\pi_1, \pi_2, \boldsymbol{\mu}_1, \boldsymbol{\mu}_2, \Sigma_1, \Sigma_2)$. What are the physical meaning of the aforementioned quantities?
 - (iv) (0.3 pt) Express $\mathbb{P}_{\theta}[Y = \mathcal{C}_1 | X = \mathbf{x}]$ in the form of $\sigma(z)$, where $\sigma(\cdot)$ denotes the sigmoid function, and express z in terms of $\theta = (\pi_1, \pi_2, \boldsymbol{\mu}_1, \boldsymbol{\mu}_2, \Sigma_1, \Sigma_2)$ and x.
- (b) (1.2 pt) Suppose we pose an additional constraint that the covariance matrices of the two Gaussian distributions are identical, namely $\Sigma_1 = \Sigma_2 = \Sigma$, in which the generative model is parameterized by $\vartheta = (\pi_1, \pi_2, \boldsymbol{\mu}_1, \boldsymbol{\mu}_2, \Sigma)$. Redo questions (a) under such setting.

Problem 3 (Closed-Form Linear Regression Solution) (1 pts + Bonus 1.5 pts)

Consider the linear regression model

$$\mathbf{v} = \mathbf{X}\boldsymbol{\theta} + \boldsymbol{\epsilon}.$$

where $\mathbf{y} \in \mathbb{R}^n, \mathbf{X} \in \mathbb{R}^{n \times d}, \boldsymbol{\theta} \in \mathbb{R}^d$ and $\boldsymbol{\epsilon} \in \mathbb{R}^n$. Denote $\mathbf{X}_i \in \mathbb{R}^{1 \times d}$ as the *i*-th row of \mathbf{X} , with the following interpretations:

• If the linear model has the bias term, then write $\boldsymbol{\theta} = [w_1, \dots, w_m, b]^\mathsf{T}$ and $\mathbf{X}_i = [x_{i,1}, x_{i,2}, \dots, x_{i,m}, 1]$, namely d = m + 1.

- If the linear model has no bias term, then write $\boldsymbol{\theta} = [w_1, \dots, w_d]^T$ and $\mathbf{X}_i = [x_{i,1}, x_{i,2}, \dots, x_{i,m}]$, namely d = m.
- (a) Without the bias term, consider the L^2 -regularized loss function:

$$\sum_{i} \kappa_{i} (y_{i} - \boldsymbol{X}_{i} \boldsymbol{\theta})^{2} + \lambda \sum_{j} w_{j}^{2}, \ \lambda > 0.$$

Show that the optimal solution that minimizes the loss function is $\theta^* = (X^T K X + \lambda I)^{-1} X^T K y$, where

$$\boldsymbol{K} = \begin{bmatrix} \kappa_1 & & 0 \\ & \ddots & \\ 0 & & \kappa_n \end{bmatrix}$$

is a diagonal matrix and I is the $d \times d$ identical matrix.

(b) (Bonus, 1.5 pts) With the bias term, the L^2 -regularized loss function becomes

$$\sum_{i} \kappa_{i} (y_{i} - \boldsymbol{X}_{i} \boldsymbol{\theta})^{2} + \lambda \sum_{j} w_{j}^{2}, \ \lambda > 0.$$

Show that the optimal solution that minimizes the loss function is $\theta^* = [w^{\star T}, b^{\star}]^T$, where

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ight), \end{aligned}$$

for which $e = [1 \dots 1]^T$ denotes the all one vector, $\mathbf{X} = [\tilde{\mathbf{X}}e]$, $\text{Tr}(\mathbf{K})$ is the trace of the matrix \mathbf{K} , and that \mathbf{K} and \mathbf{I} are defined as in (a).

Problem 4 (Noise and Regularization) (1 pts)

Consider the linear model $f_{\mathbf{w},b}: \mathbb{R}^k \to \mathbb{R}$, where $\mathbf{w} \in \mathbb{R}^k$ and $b \in \mathbb{R}$, defined as

$$f_{\mathbf{w},b}(x) = \mathbf{w}^T \mathbf{x} + b$$

Given dataset $S = \{(\mathbf{x}_i, y_i)\}_{i=1}^N$, if the inputs $\mathbf{x}_i \in \mathbb{R}^k$ are contaminated with input noise $\boldsymbol{\eta}_i \in \mathbb{R}^k$, we may consider the expected sum-of-squares loss in the presence of input noise as

$$\tilde{L}_{ss}(\mathbf{w}, b) = \mathbb{E}\left[\frac{1}{2N} \sum_{i=1}^{N} \left(f_{\mathbf{w}, b}(\mathbf{x}_i + \boldsymbol{\eta}_i) - y_i\right)^2\right]$$

where the expectation is taken over the randomness of input noises $\eta_1, ..., \eta_N$. Additionally, the inputs (\mathbf{x}_i) and the input noise (η_i) are independent.

Now assume the input noises $\eta_i = [\eta_{i,1}, \eta_{i,2}, ..., \eta_{i,k}]^T$ are random vectors with zero mean $\mathbb{E}[\eta_{i,j}] = 0$, and the covariance between components is given by

$$\mathbb{E}[\eta_{i,j}\eta_{i',j'}] = \delta_{i,i'}\delta_{j,j'}\sigma^2$$

where $\delta_{i,i'} = \begin{cases} 1 & \text{, if } i = i' \\ 0 & \text{, otherwise.} \end{cases}$ denotes the Kronecker delta.

Please show that

$$\tilde{L}_{ss}(\mathbf{w}, b) = \frac{1}{2N} \sum_{i=1}^{N} (f_{\mathbf{w}, b}(\mathbf{x}_i) - y_i)^2 + \frac{\sigma^2}{2} ||\mathbf{w}||^2$$

That is, minimizing the expected sum-of-squares loss in the presence of input noise is equivalent to minimizing noise-free sum-of-squares loss with the addition of a L^2 -regularization term on the weights. (Hint: $\|\mathbf{x}\|^2 = \mathbf{x}^T\mathbf{x} = \mathbf{tr}(\mathbf{x}\mathbf{x}^T)$ and the square of a vector is dot product with itself)

Problem 5 (Gradient descent for Logistic Regression with Vectorized Feature) (0.6 pts)

This problem is related to the appendix of W2_Logistic_Regression.pdf. Consider the following optimization problem

$$\min_{\mathbf{w}} \ell(\mathbf{w}),\tag{3}$$

where

$$\ell(\mathbf{w}) = \frac{1}{d} \sum_{n=1}^{d} \ell^{(n)}(\mathbf{w}), \quad \ell^{(n)}(\mathbf{w}) = \ln\left(1 + \exp\left(-y_n\left(\mathbf{w}^\mathsf{T}\mathbf{x}_n\right)\right)\right).$$

Assume that there are d training data, \mathbf{x}_n is the n-th training data, and the label $y_n = \pm 1$.

- (a) (0.2 pts) Prove that $\frac{1}{\ln 2}\ell^{(n)}(\mathbf{w})$ is an upper bound of $\mathbb{1}\{\operatorname{sign}(\mathbf{w}^\mathsf{T}\mathbf{x}_n)\neq y_n\}$ for any \mathbf{w} , where $\mathbb{1}\{\cdot\}$ is the indicator function. Do not use graph calculator for the arguments.
- (b) (0.2 pts) For a given (\mathbf{x}_n, y_n) , derive its gradient $\nabla \ell^{(n)}(\mathbf{w})$.
- (c) (0.2 pts) Prove that the optimization problem 3 is equivalent to minimizing the following objective function

$$\mathcal{L}(\mathbf{w}) = -\sum_{n=1}^{d} \left(\frac{1+y_n}{2} \ln \frac{1+\tanh\left(\frac{1}{2}\mathbf{w}^\mathsf{T}\mathbf{x}_n\right)}{2} + \frac{1-y_n}{2} \ln \frac{1-\tanh\left(\frac{1}{2}\mathbf{w}^\mathsf{T}\mathbf{x}_n\right)}{2} \right).$$

Problem 6 (Mathematical Background) (0 pt)

Please click the following link https://www.cs.cmu.edu/~mgormley/courses/10601/homework/hw1.zip to download the Homework 1 from CMU 2023 Machine Learning Website. You are encouraged to practice Section 3 to Section 6 of this homework to brush up some of the mathematical background that will be useful for this course. **This problem will not be graded**. However, you are encouraged to consult TA by joining TA hour if you find any questions.

Some Tools You Need to Know

- 1. Orthogonal Matrix
- 2. Positive Definite, Semipositive Definite
- 3. Eigenvalue Decomposition, Singular value decomposition
- 4. Lagrange Multiplier
- 5. Trace

You can find the definition and the usage by yourself. It is also welcome to discuss with TA in TA hour.