1 Графический интерфейс

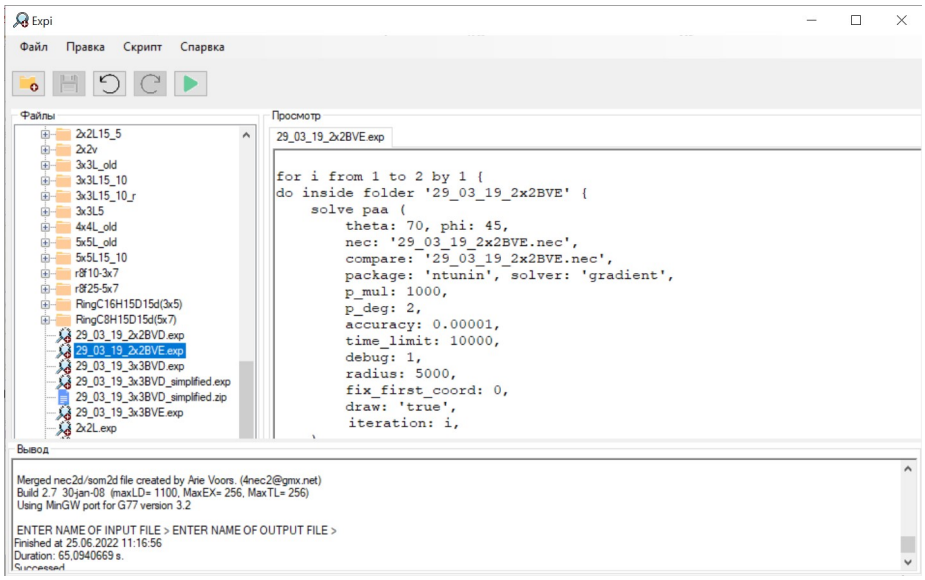

Рис. 1: Редактор исполняемых файлов

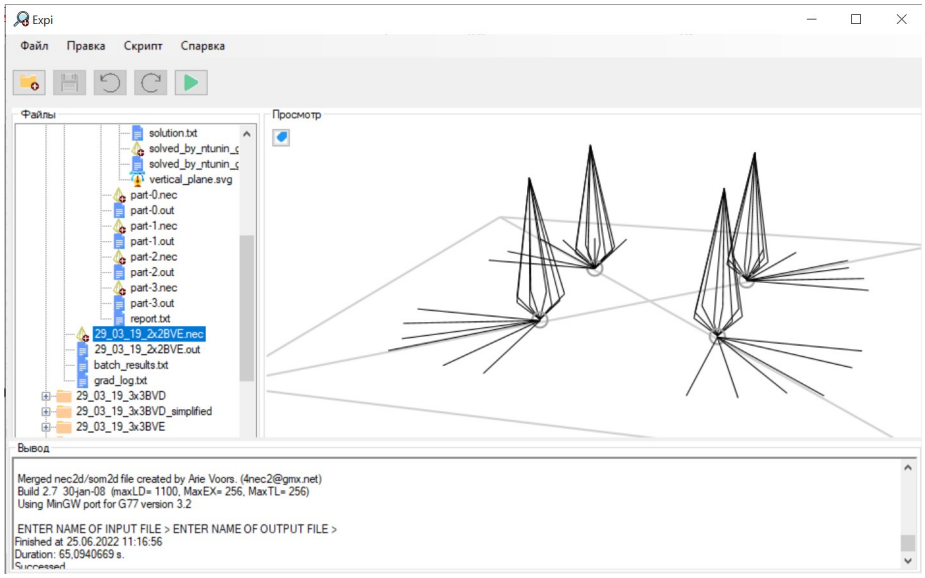

Рис. 2: Предпросмотр геометрии

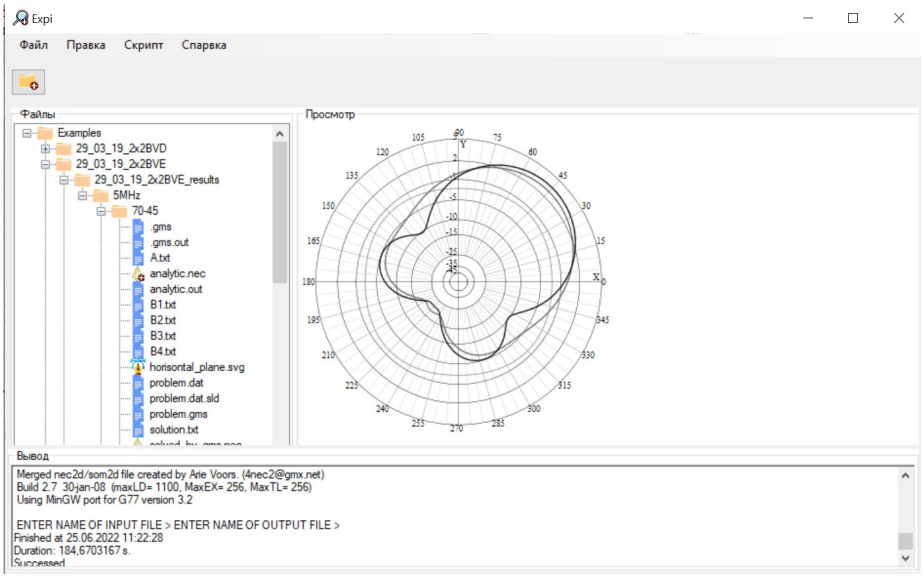

Рис. 3: Предпросмотр результатов

2 Языковые конструкции

Листинг 1: Переменные

```
def x = 1
def point = (0, 0, 1)
```

Листинг 2: Сегментированный провод

```
(0, 0, 0) -> (1, 0, 1) -> (0, 0, 5)
(0, 0, 0) -> (1, 0, 1) ~1v~ (0, 0, 5)
(0, 0, 0) -> (1, 0, 1) ~1+0.5iA~ (0, 0, 5)
```

Листинг 3: Линейные преобразования

```
translate x to 0.5
translate to (0, 0, 1)
rotate around z by pi/2
```

Листинг 4: Циклы

```

for angle from 0 to 2 * pi by pi/8 {
   rotate around z by angle
   (0, 0, 0) -> (1, 0, 0)
```

```
}

for angle from 0 up to 2 * pi by pi/8 {
   rotate around z by angle
   (0, 0, 0) -> (1, 0, 0)
}
```

Листинг 5: Группы команд

```
def Emitter {
    for angle from 0 to 2 * pi by pi/8 {
       rotate around z by angle
       (0, 0, 0) -> (1, 0, 0)
    }
}

translate x to -5
Emitter
translate x to 5
Emitter
```

Листинг 6: Оптимизация направленности ФАР

```
solve paa (
    n: 'bve_2x2.nec',
    theta: 70,
    phi: 45,
    p: 'ntunin',
    s: 'grad',
    c: 'bve.nec',
    p_mul: 1000000,
    p_deg: 4,
    time_limit: 1000,
    accuracy: 0.000001
)
```

Листинг 7: Полный текст примера вычислительного эксперимента

```

def knees = 8
def height = 15
def kneeWidth = 2.5
def base = 0.5
def rize = 2
def radialsCount = 6
def radialLength = 15
def size = 2
def distance = 20

def Drop {
   def step = 2 * pi / knees
   for angle from 0 to 2 * pi by step {
      rotate around z by angle
```

```
16          (0, 0, 0) -> (kneeWidth, 0, kneeWidth) -> (0, 0, height)
17      }
18  }
19
20  def BVE {
21      (0, 0, 0) ~1v~ (0, 0, base)
22      def step = pi / 2 / (radialsCount - 1)
23      for i from 0 to  radialsCount  by 1 {
24          rotate around z by i * step
25          (0, 0, 0) -> (radialLength, 0, 0)
26      }
27      translate z to base
28      Drop
29  }
30
31  def PlaceBVE {
32      translate to (x, y, 0)
33      rotate around z by angle
34      BVE
35  }
36
37  def PAA {
38      def width = (size - 1) * distance
39      def left = -width/2
40      def right = width/2
41      def top = width/2
42      def bottom = -width/2
43
44      PlaceBVE(x: left, y: top, angle: pi / 2)
45      PlaceBVE(x: right, y: top, angle: 0)
46      PlaceBVE(x: right, y: bottom, angle: -pi / 2)
47      PlaceBVE(x: left, y: bottom, angle: pi)
48  }
49
50  def ExportPAA {
51      export nec (n: 'bve_${size}x${size}.nec', f: 5, g: 'real') {
52          translate z to rize
53          PAA
54      }
55  }
56
57  def One {
58      (0, 0, 0) ~1v~ (0, 0, base)
59      def oneRadialsCount = (radialsCount - 1) * 4
60      def step = 2 * pi / (oneRadialsCount - 1)
61      for i from 0 to  oneRadialsCount by 1 {
62          rotate around z by i * step
63          (0, 0, 0) -> (radialLength, 0, 0)
64      }
65      translate z to base
66      Drop
67  }
68
69  def ExportOne {
70      export nec (n: 'bve.nec', f: 5, g: 'real') {
71          translate z to rize
72          One
```

```
    }
}

do inside folder '05.04.22' {
    ExportOne
    ExportPAA

    solve paa (
        n: 'bve_${size}x${size}.nec',
        theta: 70,
        phi: 45,
        p: 'ntunin',
        s: 'grad',
        c: 'bve.nec',
        p_mul: 1000000,
        p_deg: 4,
        time_limit: 1000,
        accuracy: 0.000001
    )
    solve paa (
        n: 'old_bve_${size}x${size}.nec',
        theta: 70,
        phi: 45,
        p: 'ntunin',
        s: 'grad',
        c: 'bve.nec',
        p_mul: 1000000,
        p_deg: 4,
        time_limit: 1000,
        accuracy: 0.000001
    )
}
```