

## Lesson 2 First Start MaxArm

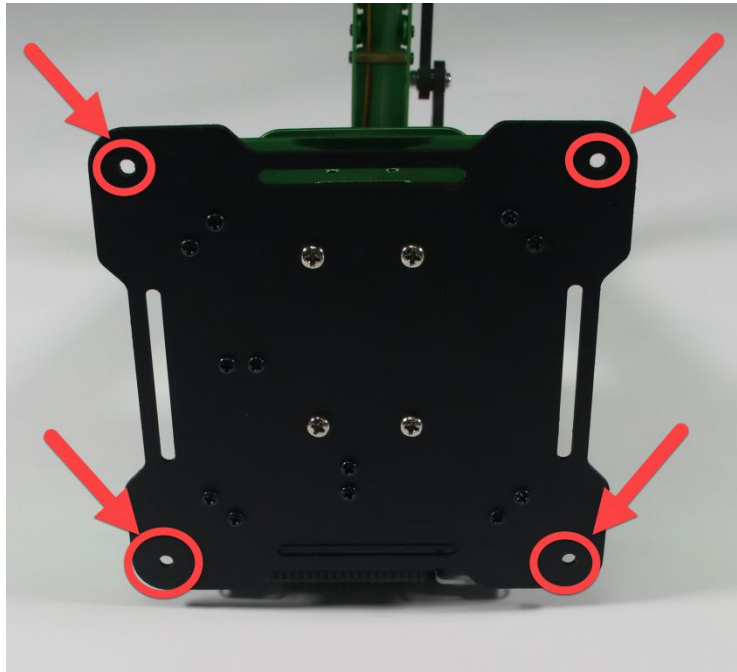
### 1. Suction Cups Assembly

After getting ArmMax, please assemble the suction cups first according to the following operation steps and fix robotic arm on a flat desktop.

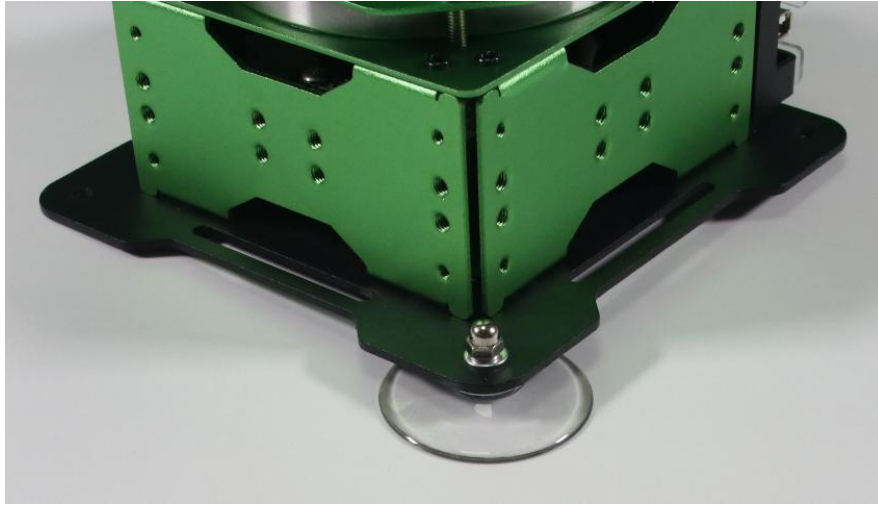
1) Take out the suction cup accessory bag.



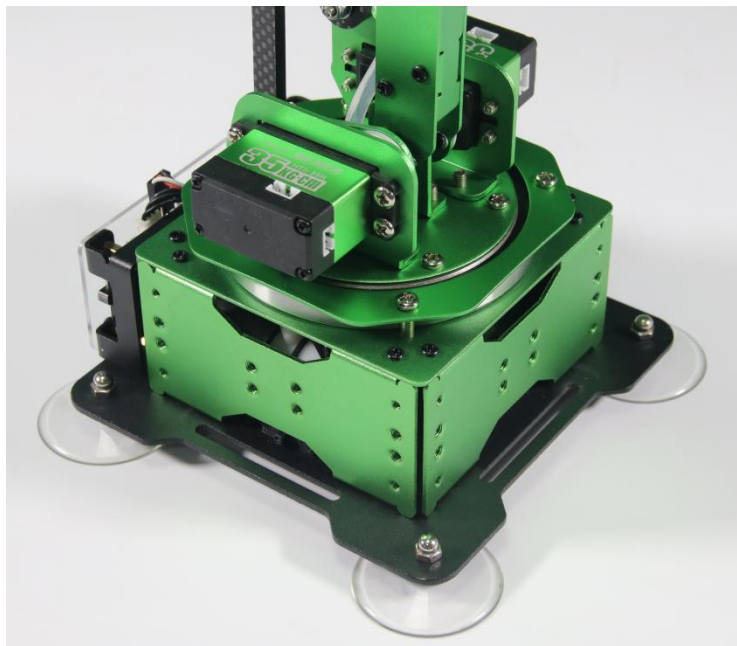
2) Assemble the suction cups into the four holes of the base, as shown in the figure below.



3) Then fix the suction cups with bolts.

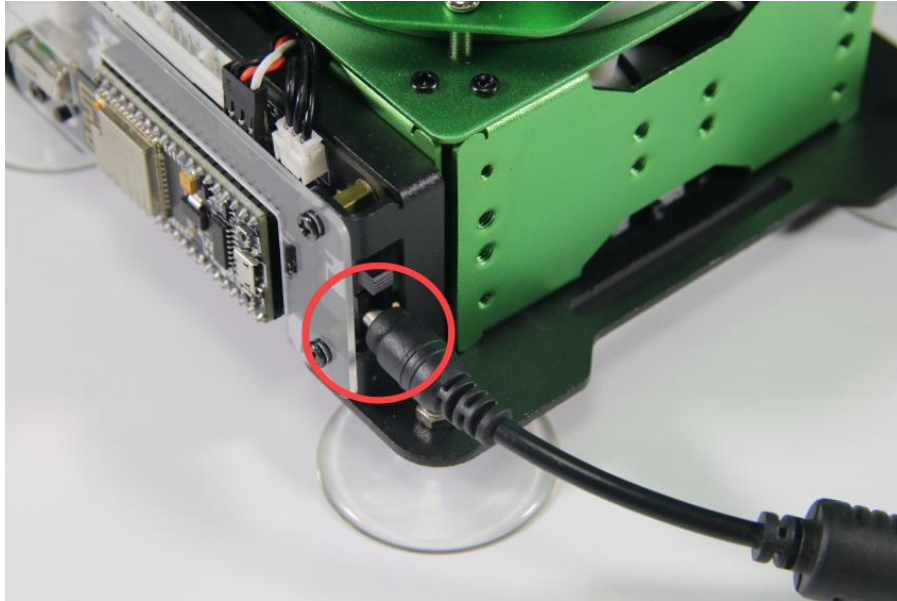


4) The result of the suction cup assembly is shown in the figure below.



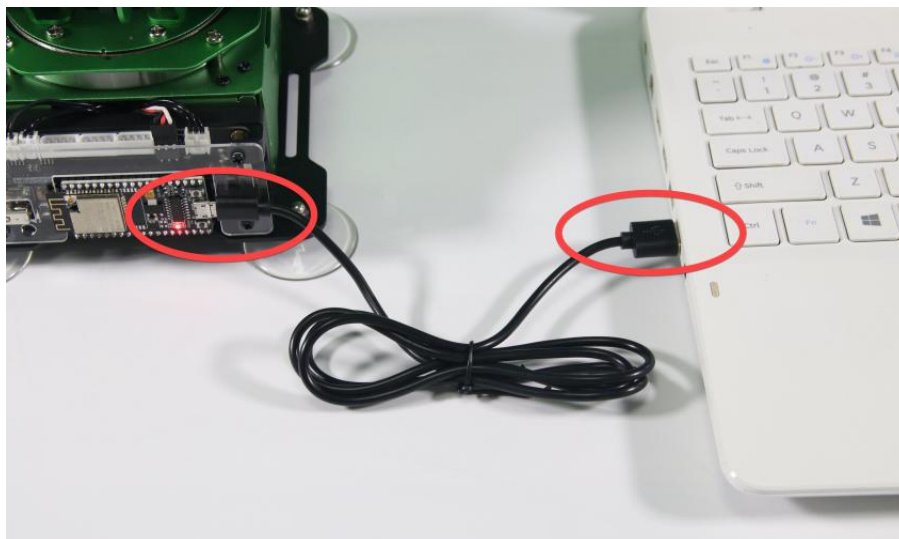
## 2. Power Adapter Connection

Use power adapter to supply robotic arm power. The specification of MaxArm adapter is 12V 5A. Connect the power adapter to the power port of control board, as shown in the figure below.



### 3. Connect USB Cable

Take out the provided USB cable. Connect the controller with your computer, as shown in the figure below.



### 4. Power on

After connecting, turn on the controller (push the switch to “ON”). At this time, the red indicator on controller will light up. When LED1 keeps flashing and buzzer makes “DiDi” sound, MaxArm is powered on successfully, as shown in the figure below:

