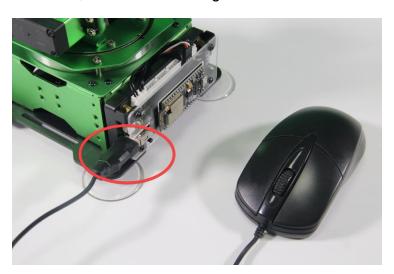


Lesson 2 Mouse Control

1. Preparation

- 1) Refer to "1.Getting Ready/Lesson 2 Start MaxArm" to turn on robot arm.
- 2) Please prepare a mouse (wired or wireless). Connect mouse cable to USB port on expansion board, as shown in the figure below:



2. Operation Instruction

The operation instruction is shown in the following table:

Operation	Outcome
Move mouse in any directions	The suction nozzle moves with the mouse
Press left mouse button + move left and right	The suction nozzle rotates counterclockwise or clockwise
Scroll mouse wheel up and down	The suction nozzle moves up and down along z-axis
Press right mouse button + move in any directions	The air pump starts to pumping (Right-click mouse to stop pumping)