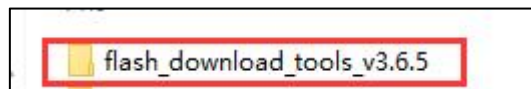


Firmware Download Method

When using robotic arm, game outcome and experience will be interfered with the firmware damage. Please download the firmware according to the following steps.

1. Open Download Tool

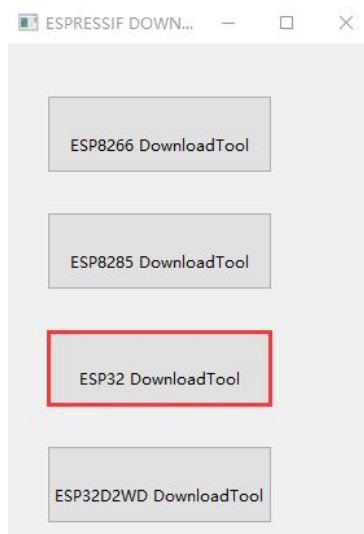
- 1) Connect MaxArm to your computer with USB cable.
- 2) Double click the folder "flash_download_tools_v3.6.5" under the same path.



- 3) Find and open the firmware download tool.

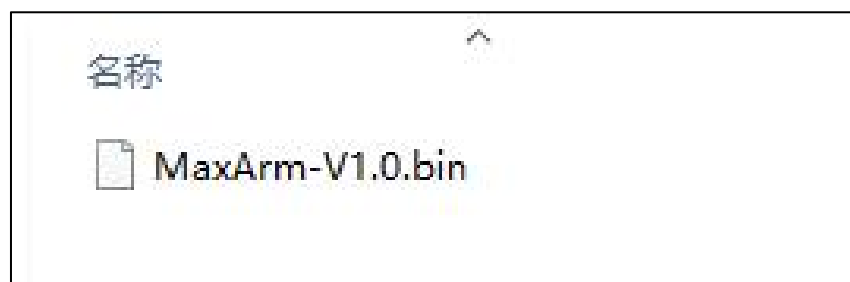
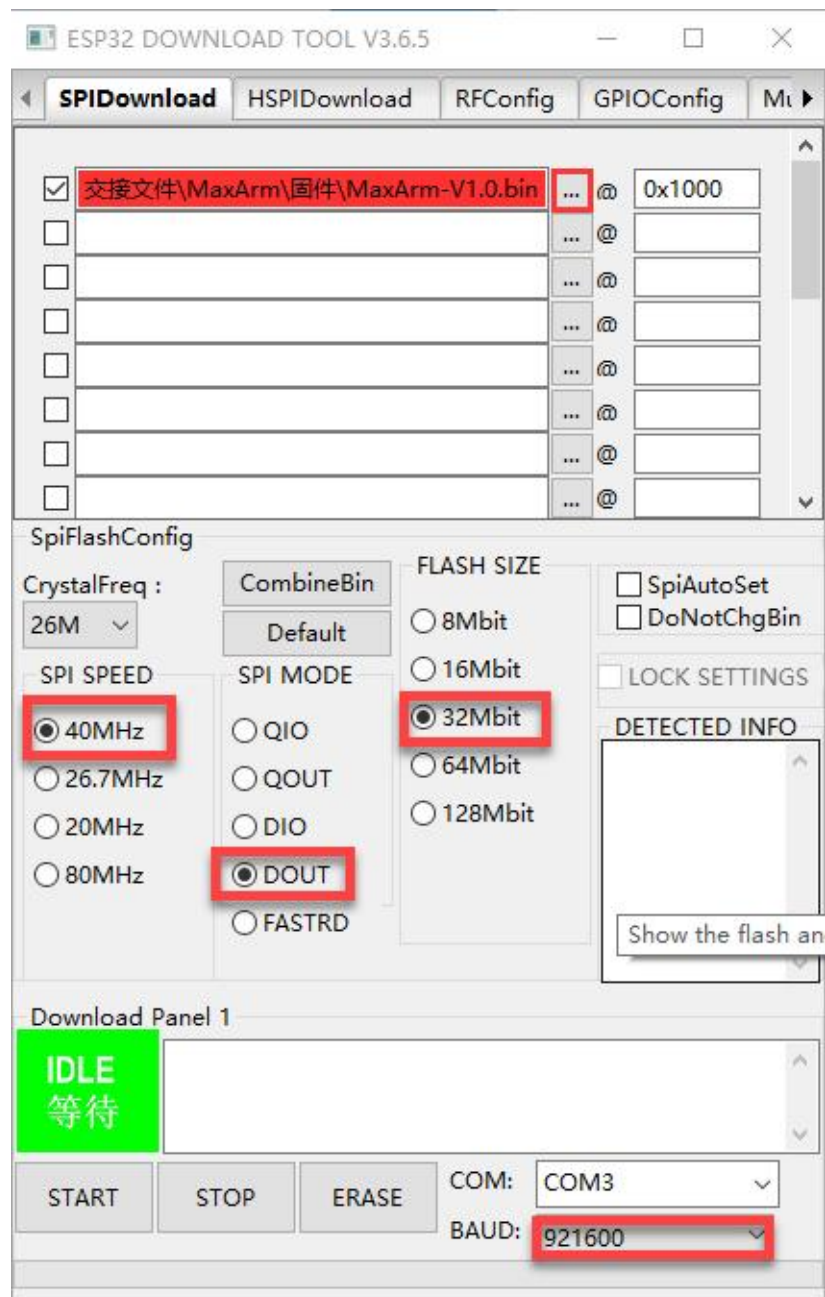


- 4) Wait for a while. Select "ESP32 DownloadTool" in the opening interface.

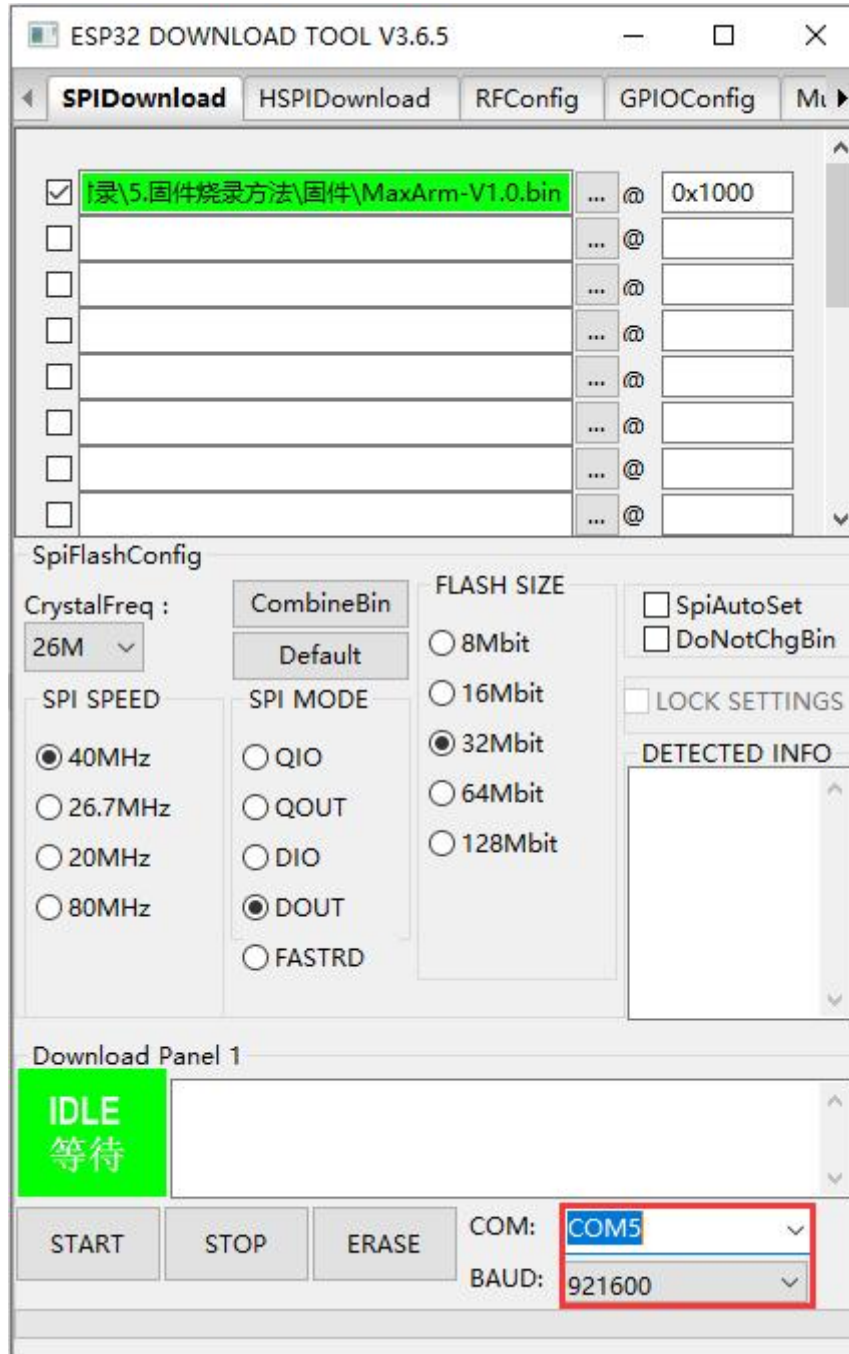


5) Then select the the configuration as shown in the image below, and click

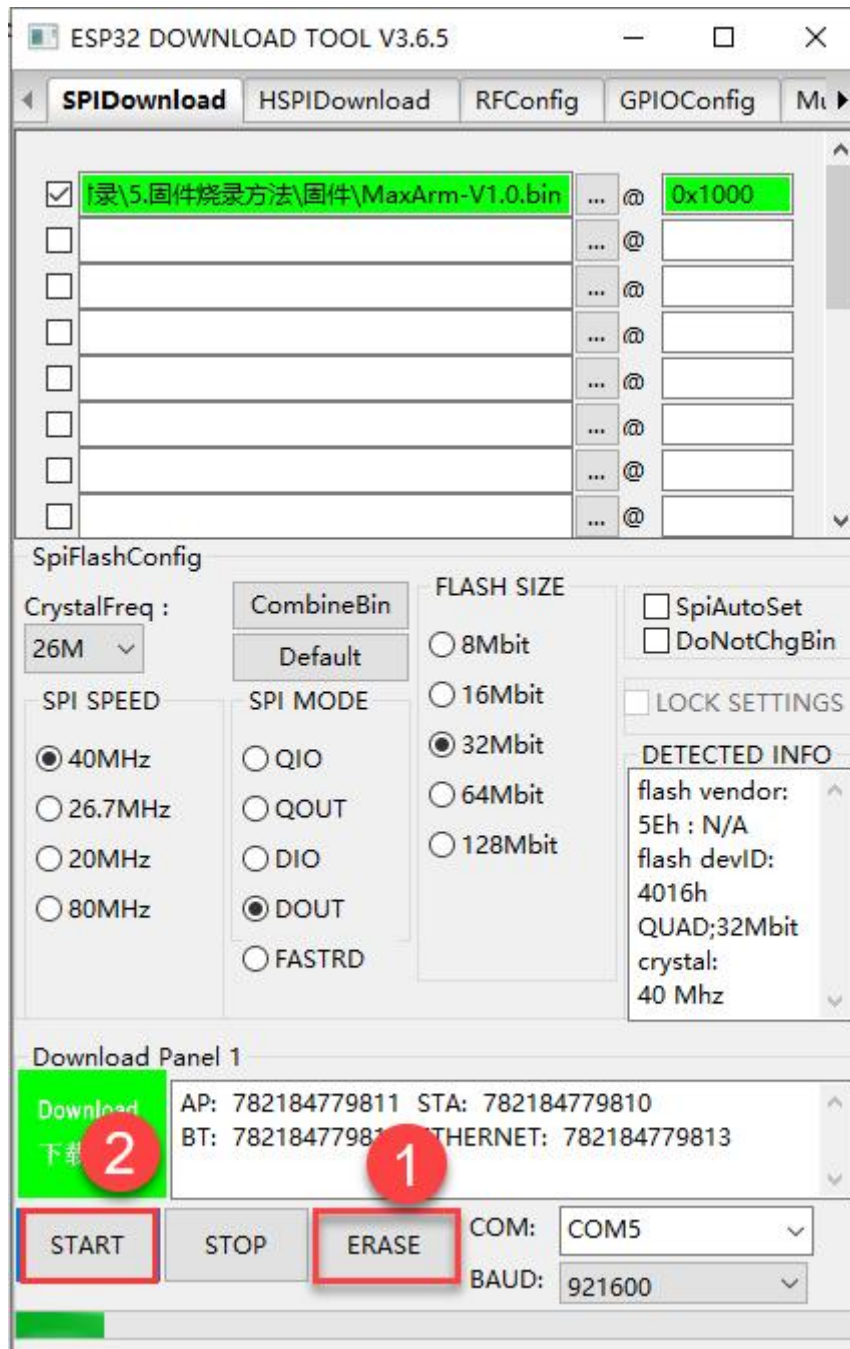
“...” to select the firmware.



6) Select the port number. (the port number here is just for reference, please refer to the actual situation. Do not select COM1, otherwise the firmware download will fail.)



7) Click “ERASE” first to erase the underlying firmware (Do not skip this step), and then click “START”.



8) Wait for a moment, it will prompt "FINISH".

ESP32 DOWNLOAD TOOL V3.6.5

SPIDownload

HSPIDownload

RFConfig

GPIOConfig

MI

☒

录\5.固件烧录方法\固件\MaxArm-V1.0.bin

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SpiFlashConfig

CrystalFreq :
26M

CombineBin

Default

SPI SPEED

SPI MODE

☒ 40MHz

☐ 26.7MHz

☐ 20MHz

☐ 80MHz

☐ QIO

☐ QOUT

☐ DIO

☒ DOUT

☐ FASTRD

FLASH SIZE

☐ 8Mbit

☐ 16Mbit

☒ 32Mbit

☐ 64Mbit

☐ 128Mbit

☐ SpiAutoSet

☐ DoNotChgBin

☐ LOCK SETTINGS

DETECTED INFO

flash vendor:
5Eh : N/A

flash devID:
4016h

QUAD;32Mbit

crystal:
40 Mhz

Download Panel 1

FINISH

完成

AP: 782184779811 STA: 782184779810
BT: 782184779812 ETHERNET: 782184779813

START

STOP

ERASE

COM: COM5

BAUD: 921600

2. Download Library File

After the firmware is downloaded, the library file need to be downloaded to run the game.

- 1) Open Python editor.



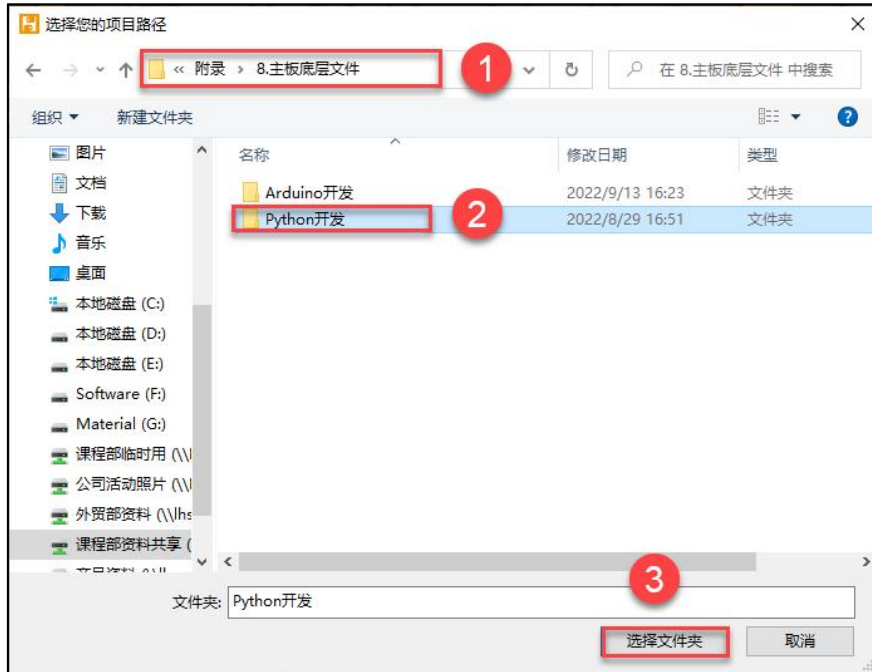
- 2) Click on the following icon to connect.



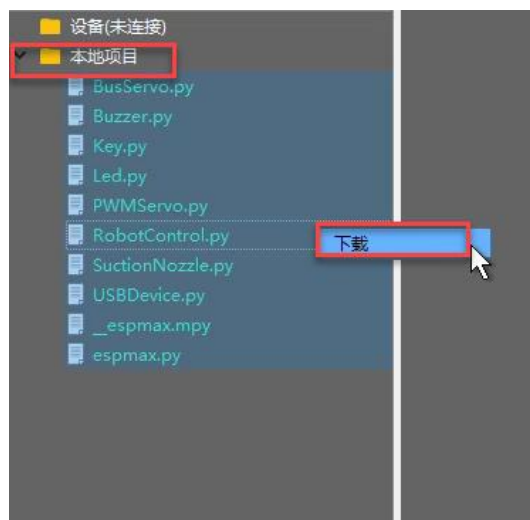
- 3) Right click "Workshop" to show the file selection list.



- 4) Then find and select the folder "Python Development" in "Appendix/8. Underlying File".



5) After importing the library files to the editor, select all the files, right click to select "Download".



6) After downloading, click on the reset icon or press the reset button on ESP32 controller to run program.



