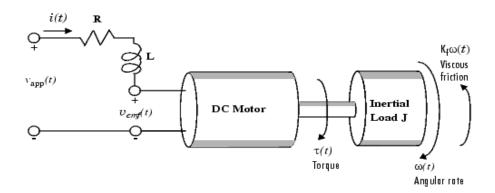
DC Motor



The system (motor driving a load) final equations are

$$\frac{di}{dt} = \frac{V_{app}}{L} - \frac{R}{L}i - \frac{K_{\Phi}}{L}\omega$$

$$\frac{d\omega}{dt} = \frac{K_{\Phi}}{J}i - \frac{b}{J}\omega$$

Where:

→ viscous friction b

J → moment of inertia for the motor load

Κφ →armature or emf constant

The values motor parameters are

L = 0.1 H

$$\begin{split} K\phi &= 0.3\\ J &= 0.1~Kg.m^2 \end{split}$$

b = 0.01

 $R = 2 \Omega$

The motor is masked in this modified version, so double click the motor block and update the parameters.

This text was attached with a Simulink DC Motor model made by: Wesam ELSHAMY

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