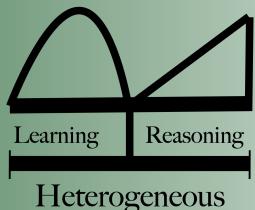




# Compositional Reasoning over Natural Language Leveraging Neuro-Symbolic AI

**Parisa Kordjamshidi**  
kordjams@msu.edu

Michigan State University, USA



Feb 26th, 2024  
Nuclear Workshop

# Deep Learning Challenges



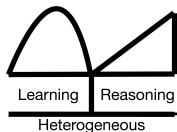
Visual Question Answering

Example from GQA (Hudson, and Manning, CVPR-2019)

**Question 1: Is the red bike to the right or to the left of the Asian people?**

GroundTruth: right

Prediction (a SOTA deep model in 2019): right ([correct](#))



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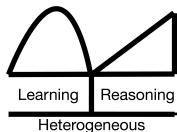
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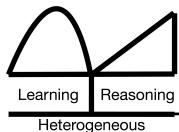
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Does the model understand?

Objects? Attributes? Relations?

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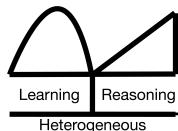
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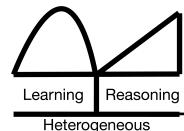


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## Visual Question Answering

Does the model understand?

**Objects? Attributes? Relations?**

- Larger VL models?
- Increase data?
- Augment Examples?
- ...

**Old times...**

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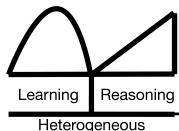
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A woman with an apple in her left hand standing to the right of a car.



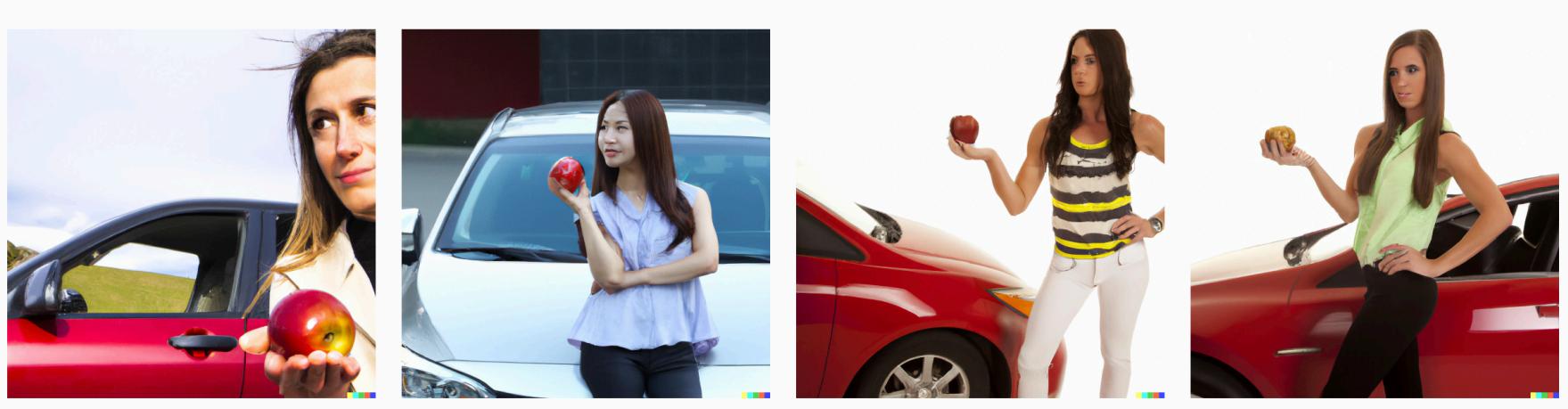
DALL·E

DALL-E is a multimodal implementation of GPT-3 with 12 billion parameters.  
(Example from April 2023)



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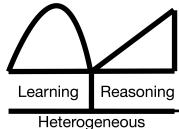
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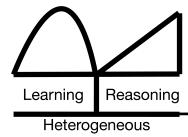
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Still old?

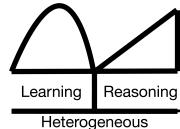


# Key Point?



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- + These models are improving as the observations increase and models enlarge.

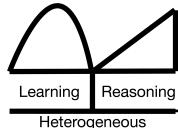


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+ These models are improving as the observations increase and models enlarge.

– Mostly, Neural Solutions suffer from:

- Lack of Generalizability in Basic Reasoning Skills
- Lack of Interpretability
- Need for huge amounts of data



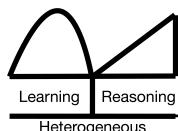
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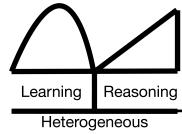
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Problematic in many applications of natural language processing and computer vision for which these models have been considered, *in some sense*, very successful.

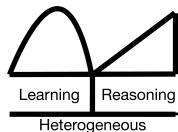


# Contributions of HLR team



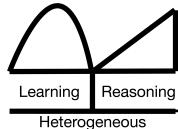
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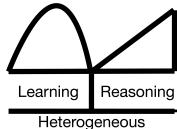
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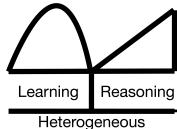
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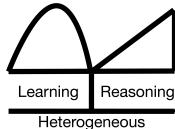
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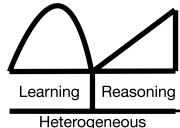
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- **Application problems:** *Information extraction by spatial/temporal reasoning over procedural text, Spatial QA, Causal QA, Long-document QA, Commonsense QA, Visual QA, KB-Visual QA, Probabilistic QA, VLN-navigation, Grounded concept learning.*



# Outline

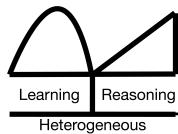
- **Evaluation and Integration of explicit Spatial Reasoning in LLMs**
- Evaluation and Integration of explicit Probabilistic Reasoning in LLMs
- DomiKnowS framework for Integration of symbolic reasoning in Neural Models



# SpartQA, SpaRTUN, ReSQ



- Spatial Question Answering
- Spatial Role Labeling
  - Spatial concepts (landmarks, trajectors, ...)
  - Spatial relationships (topological relation, directional relations, ...)
- Chain of reasoning



[R. Mirzaee, P. Kordjamshidi. **Transfer Learning with Synthetic Corpora for Spatial Role Labeling and Reasoning**, EMNLP-2022]

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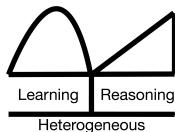
(a) SPARTUN - A synthetic large dataset provided as source of supervision

A **grey car** is parking **in front of a grey house with brown window frames** and **plants on the balcony**.

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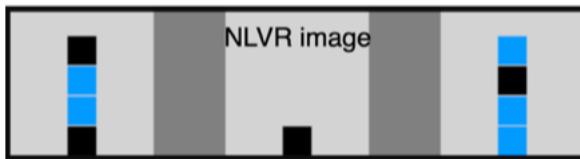
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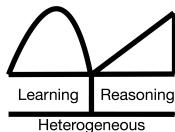
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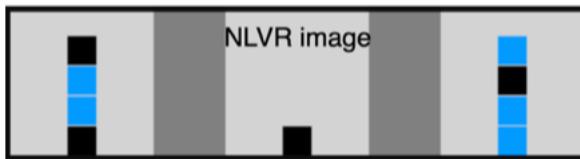
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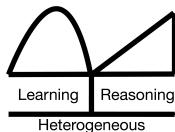
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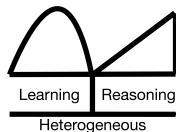
# Spatial Reasoning over Text

## SpartQA

#	Models	FB			FR			CO			YN		
		Seen	Unseen	Human*									
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2	BERT	87.13	69.38	62.5	85.68	73.71	46.66	71.44	61.09	32.71	78.29	76.81	47.42
3	ALBERT	97.66	83.53	56.73	91.61	83.70	44.76	95.20	84.55	49.53	79.38	75.05	41.75
4	XLNet	<b>98.00</b>	<b>84.85</b>	<b>73.07</b>	<b>94.60</b>	<b>91.63</b>	<b>57.14</b>	<b>97.11</b>	<b>90.88</b>	<b>50.46</b>	<b>79.91</b>	<b>78.54</b>	39.69
5	Human		85	91.66		90	95.23		94.44	91.66		90	90.69

- Find Blocks (FB), Find Relations (FR), Choose Objects (CO), Yes/No (YN)

## Concluding message



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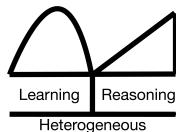
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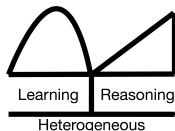
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**SpartQA and SPARTUN datasets help transferring spatial reasoning knowledge.**



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# Integration of Spatial Logic in Training

## Context:

The white rectangle is on an orange rectangle. There is also the red rectangle, which is above the white rectangle.

## Question:

Is the orange object below the red rectangle?

**Initial facts:** (red-r, white-r, above), (white-r, orange-r, above)

## Rules:

- Converse  
 $(a, b, right) \Rightarrow (b, a, left)$

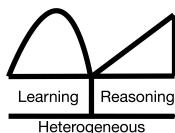
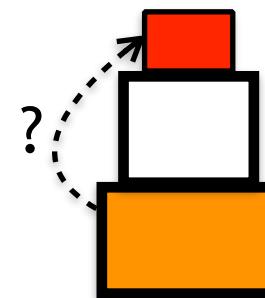
- Symmetric  
 $(b, c, near) \Rightarrow (c, b, near)$

- Transitive  
 $(x, b, above), (b, c, above) \Rightarrow (x, c, above)$

- Transitive + topological

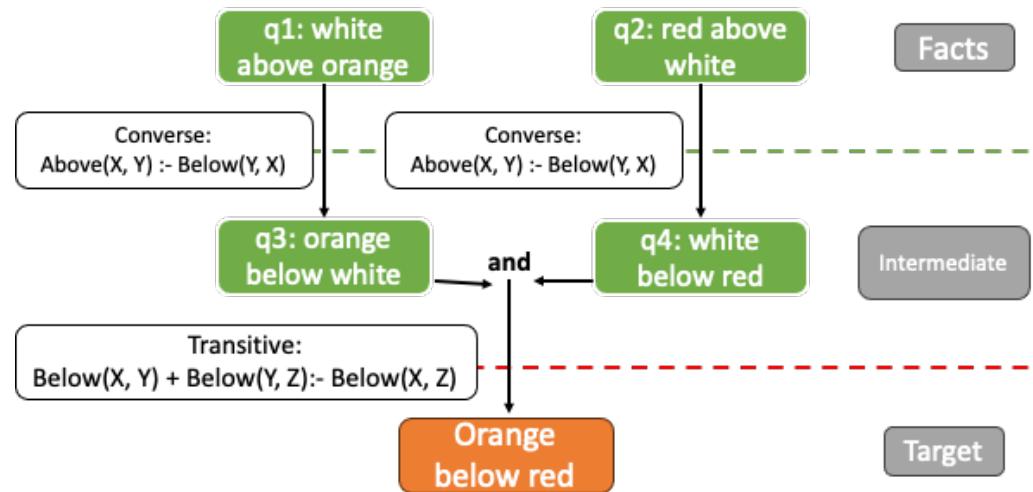
- $(x, y, inside), (y, z, inside), (y, z, front) \Rightarrow (x, z, front)$

**Target Query:** (orange-r, red-r, below)?

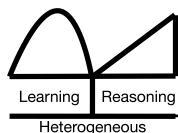
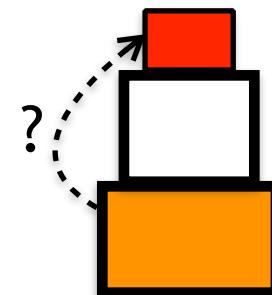


[Tanawan Premsri, P. Kordjamshidi, *Transferring Spatial Reasoning Knowledge by Neuro-symbolic Training, 2024, under review.*]

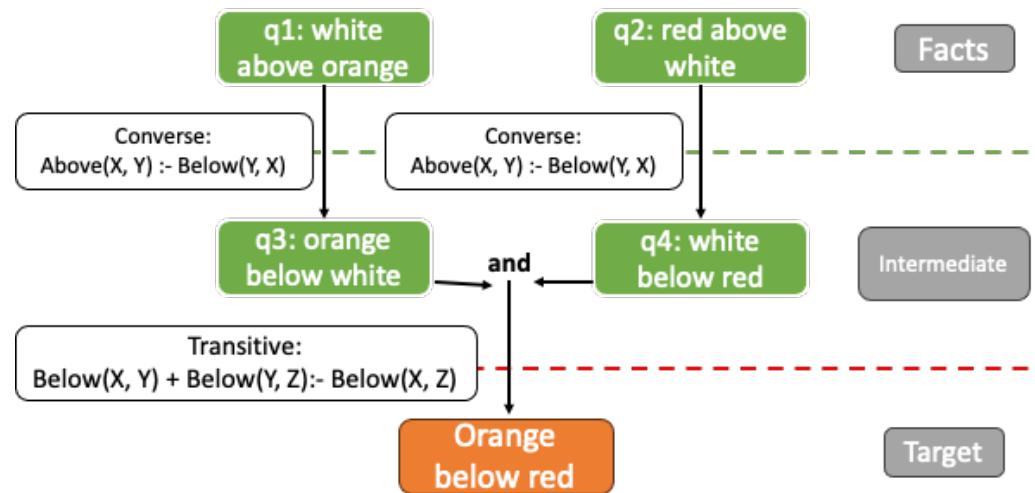
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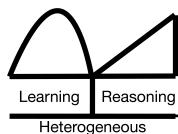
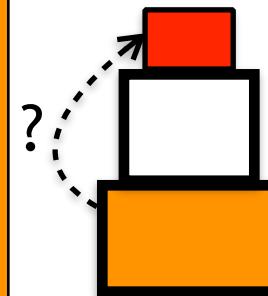


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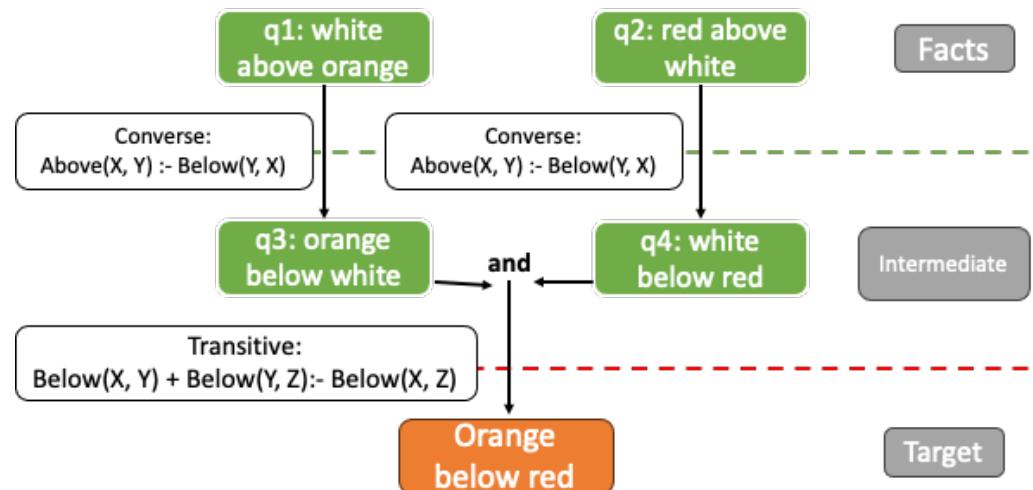


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 $(x, y, inside), (y, z, inside), (y, z, front) \Rightarrow (x, z, front)$

- Constraints for this example:
- C1:  $(q1 \Rightarrow q3)$
  - C2:  $(q2 \Rightarrow q4)$
  - C3:  $(q3 \text{ and } q4 \Rightarrow \text{target})$



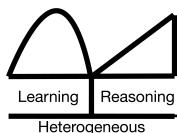
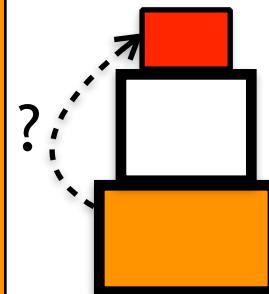
# Integration of Spatial Logic in Training



The intermediate annotations are not needed for inference, the entailment rules are translated to consistency constraints for every specific situation. The constraints are used only during training.

- Converse  
 $(a, b, right) \Rightarrow (b, a, left)$
- Symmetric  
 $(b, c, near) \Rightarrow (c, b, near)$
- Transitive  
 $(x, b, above), (b, c, above) \Rightarrow (x, c, above)$   
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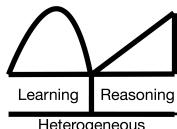
# Integration of Spatial Logic in Training

## Training

$$Loss = TaskLoss + \sum_{i=1}^m \lambda_j * C_i$$

Constraint Loss

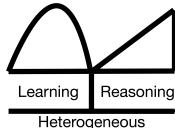
- This training objective can be used for tuning both generative and encoder-based language models when adapted to the classification task.



# Integration of Spatial Logic in Training

Model	ResQ			
	k=1	k=2	null	All
BERT	70.67	56.85	60.66	60.98
BERT-T	76.00	54.79	61.18	61.15
BERT-T+Q-Chain	72.00	<b>58.90</b>	59.90	61.31
T5	74.67	56.16	61.44	61.80
T5-T	81.33	54.79	61.44	62.30
T5-T+Q-Chain	<b>81.33</b>	57.53	<b>63.75</b>	<b>64.43</b>
GPT-3 (zero-shot)	74.67	60.95	66.58	66.22
GPT-3 (few-shot)	84.00	68.49	68.12	70.16
GPT-3 (COT)	<b>86.67</b>	67.12	68.64	70.49
GPT-4 (zero-shot)	84.00	<b>73.97</b>	<b>76.86</b>	<b>77.05</b>

Overall performance on **Realistic ResQ** dataset (All). Performance per reasoning steps (k) required for the question to be answered. Null indicates the cases in which k was not clear.



# Integration of Spatial Logic in Training

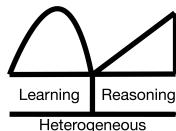
A grey car is parking **in front of** a grey house **with brown window frames** and **plants on** the balcony.

Q: Are **the plants in front of the car?** No ; ChatGPT: No

Q: Are **the plants in the house?** Yes; ChatGPT: No

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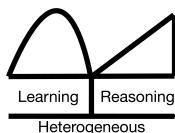
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Model	k=1	k=2	k=3	k=4	k=5	k=6	k=7	k=8	k=9	k=10
BERT	98.51	95.53	91.68	66.71	49.11	41.47	41.47	32.09	28.94	28.16
BERT-T	98.50	95.32	93.26	76.78	66.36	58.76	53.70	46.27	42.71	40.12
BERT-T+Q-Chain	98.70	96.45	93.03	74.58	64.95	59.04	54.38	49.23	45.36	44.05
T5	98.51	96.97	89.71	78.47	71.11	65.49	61.18	55.89	52.20	50.34
GPT3 (few-shot)	55.00	37.00	25.00	30.00	32.00	29.00	21.00	22.00	34.00	31.00
GPT3 (COT)	61.00	45.00	30.00	35.00	35.00	27.00	22.00	24.00	23.00	25.00

Accuracy of various models on STEPGAME including result of GPT3 model reported in  
 Zhun Y., et.al., 2023. Coupling large language models with logic programming for robust and general reasoning from text.

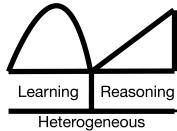


[Tanawan Prem Sri, P. Kordjamshidi, Transferring Spatial Reasoning Knowledge by Neuro-symbolic Training, 2024, in progress.]

# Spatial QA

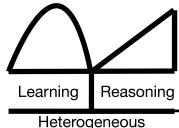
## Findings

- Pre-trained Large Language models comparatively weak in spatial reasoning
- We created benchmarks to evaluate them with spatial QA
- Synthetic data can help transfer learning to realistic domain.
- Logic-based training helped complex multi-hop reasoning
- GPT models are better in commonsense reasoning.



# Outline

- Evaluation and Integration of explicit Spatial Reasoning in LLMs
- **Evaluation and Integration of explicit Probabilistic Reasoning in LLMs**
- Grounding language in visual perception and Navigation
- DomiKnowS framework for Integration of symbolic reasoning in Neural Models



# Reasoning over Uncertain Text

## Logical Reasoning

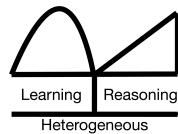
Dave is big.  
If someone is big, then they are green.  
If someone is green, then they are round.

## Probabilistic Logical Reasoning

Dave is big.  
Usually, If someone is big, then they are green.  
Normally, If someone is green, then they are round.

Conclusion: David is round.

Conclusion: David is round with a probability of 72%.



[Aliakbar Nafar, Kristen Brent Venable, Parisa Kordjamshidi, **Teaching Probabilistic Logical Reasoning to Transformers**, EACL-2024 Findings]

[Aliakbar Nafar, Kristen Brent Venable, Parisa Kordjamshidi, **Probabilistic Reasoning in Generative Large Language Models**, under review, arxived]

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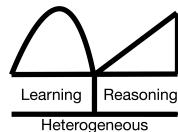
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Motivation: Scientific text specially medical domain:  
Combining uncertain evidences and applying uncertain rules.



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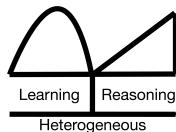
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*People with diabetes often have many of the same risk factors associated with heart disease ...*

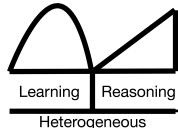
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# Reasoning over Uncertain Text

RuleBERT	RuleTaker-pro
(Fact 1) David is a cousin of Ann. (Fact 2) Mike is a child of Ann. (Rule 1, 0.90) If A is a spouse of B and C is a child of B, then C is a child of A. (Rule 2, 0.15) If A is a cousin of B, then A is a spouse of B.	(Fact 1) Dave is big. (Fact 2) Erin is sad. (Rule 1) Usually, If someone is big then they are green. (Rule 2) Normally, If someone is green then they are round. (Rule 3) Seldom, If someone is sad then they are round.
(Query) Mike is a child of David.	(Query) Dave is round.
Required Steps of Reasoning to Answer	
Fact 1 (1.00) & Rule 2 (0.15) $\implies$ Fact 3: David is a spouse of Ann. (0.15) (Inferred) Fact 3 (0.15) & Fact 2 (1.00) & Rule 1 (0.90) $\implies$ Fact 4: Mike is a child of David. (0.135) (Inferred) <b>Answer: 0.135</b>	Fact 1 (1.00) & Rule 1 (0.90) $\implies$ Fact 3: Dave is green. (0.90) (Inferred) Fact 3 (0.90) & Rule 2 (0.80) $\implies$ Fact 4: Dave is round. (0.72) (Inferred) <b>Answer: 0.72</b>

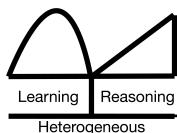


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Approach: Converting Probabilistic Reasoning Steps to Equality Constraints	
Constraint 1: $P(\text{Fact 1}) * 0.15 = P(\text{Fact 3})$ Constraint 2: $P(\text{Fact 3}) * P(\text{Fact 2}) * 0.90 = P(\text{Fact 4})$	Constraint 1: $P(\text{Fact 1}) * 0.90 = P(\text{Fact 3})$ Constraint 2: $P(\text{Fact 3}) * 0.80 = P(\text{Fact 4})$



# Integration of Probabilistic Reasoning in Training

## Training

$$Loss = TaskLoss + \sum_{i=1}^m \lambda_j * C_i$$

Approach: Converting Probabilistic Reasoning Steps to Equality Constraints

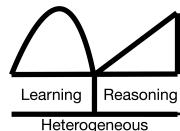
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## Examples of constraints



[Aliakbar Nafar, Kristen Brent Venable, Parisa Kordjamshidi, **Teaching Probabilistic Logical Reasoning to Transformers**, EACL-2024 Findings, <https://arxiv.org/pdf/2305.13179.pdf>]

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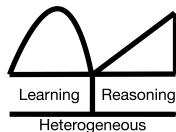
Constraint 2:  $P(\text{Fact 3}) * 0.80 = P(\text{Fact 4})$

## Examples of constraints

- This training approach improves the PLMs, in particular for deeper reasoning networks.
- It can better transfer probabilistic reasoning from one domain to another.

[Aliakbar Nafar, Kristen Brent Venable, Parisa Kordjamshidi, **Teaching Probabilistic Logical Reasoning to Transformers**, EACL-2024 Findings, <https://arxiv.org/pdf/2305.13179.pdf>]

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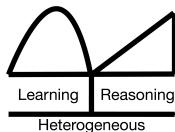
# Integration of Probabilistic Reasoning in Training

- Using probabilistic constraints during training helps in more complex and deeper reasoning steps.
- This result is on newly created Rule-take-pro with example-specific Rules.

D/M	RoBERTa			
	M1	M2	M3	Mmax
Total	38.2	38.3	20.4	33.8
D1	56.0	52.7	29.6	43.7
D2	36.4	38.2	20.3	32.8
D3	29.3	31.3	14.9	28.3
D4	27.4	28.5	14.0	27.1
D5	24.9	26.7	14.7	28.2
CS1	47.8	35.7	16.2	20.7

	RoBERTa + PCT			
	Total	38.0	39.5	41.1
D1	53.3	50.8	50.5	46.9
D2	37.4	40.4	42.2	37.0
D3	26.4	32.9	36.0	32.4
D4	26.5	31.9	33.9	31.8
D5	23.3	30.4	33.4	31.4
CS1	44.9	42.6	34.5	35.2

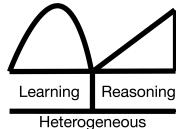


[Aliakbar Nafar, Kristen Brent Venable, Parisa Kordjamshidi, **Teaching Probabilistic Logical Reasoning to Transformers**, EACL-2024 Findings]

# Integration of Probabilistic Reasoning in Inference

Context: Green event is True with probability of 80%. If Green event is True, then Pink event is True with probability of 10%. If Green event is True, then Pink event is False with probability of 90%. If Green event is False, then Pink event is True with probability of 20%. If Green event is False, then Pink event is False with probability of 80%.

Query: What is the probability that Green event is True and Pink event is True?



[Aliakbar Nafar, Kristen Brent Venable, Parisa Kordjamshidi, **Probabilistic Reasoning in Generative Large Language Models, 2024, arxiv**]

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Query: What is the probability that Green event is True and Pink event is True?

**BQA**

**BQA Instruction:** Solve the following probabilistic question and generate the probability of the answer by only providing a number from 0 to 100.

Context    Query

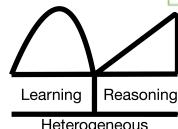
**Answer:** 8%

**COT**

**COT Instruction:** Solve the following probabilistic question and provide a detailed explanation of the mathematical reasoning. At the end, write a sentence that will give the final answer rounded to an integer.

Context    Query

**Answer:**  
This probability can be found using the conditional probability:  
 $P(g, p) = P(g) * P(p|g) =$   
 $0.80 * 0.10 = 0.08$   
The final answer is 8%.



[Aliakbar Nafar, Kristen Brent Venable, Parisa Kordjamshidi, **Probabilistic Reasoning in Generative Large Language Models, 2024, arxiv**]

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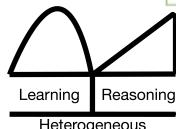
**ProbLog**

**ProbLog Instruction:** Solve the following probabilistic question by writing a Problog code that represents the probabilities, and the query.

Context    Query

**Answer:**

```
0.8::green.  
0.2::pink:-\+green.  
0.1::pink:- green.  
  
q1:- green, pink.
```



# Integration of Probabilistic Reasoning in Inference

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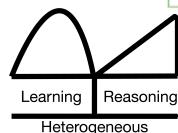
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Context    Query

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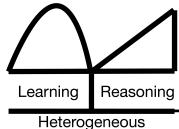
```
0.8::green.  
0.2::pink:-\+green.  
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```

- Mapping to code is always better here and the best results obtained from mapping to **probabilistic logical programming** code in ProbLog language.



# Outline

- Evaluation and Integration of explicit Spatial Reasoning in LLMs
- Evaluation and Integration of explicit Probabilistic Reasoning in LLMs
- DomiKnowS framework for Integration of symbolic reasoning  
in Neural Models



# Motivation

- In complex intelligent systems:
  - There are many models: basic concepts, relations, types of relations, compositional concepts...
  - Decisions depend on models and their interactions, we need to reason based on models.

This kind of modeling seems to be challenging with current tools.

# Typical show case: Entity Mention Relation Extraction

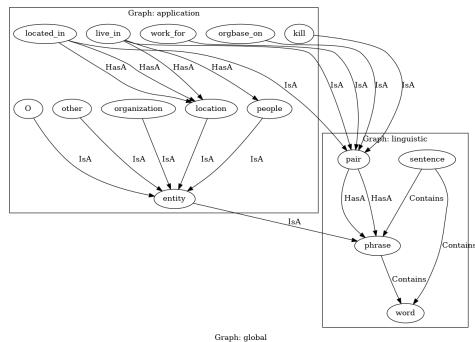
other	0.05
location	0.92
people	0.90

other	0.05
location	0.33
org	0.82

Inference helps to improve local predictions.

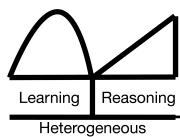
Models can be trained locally or globally using soft and hard constraints.

Washington covers Seattle for Associated Press.



irrelevant	0.10
lives_in	0.35
works_for	0.85

Relation	Entity 1	Entity 2
kill	people	people
works_for	people	org
live_in	people	location
orgbase_on	org	location
locate_in	location	location



[Rajaby Faghihi, Guo, Uszok, Nafar, Raisi, Kordjamshidi, **DomiKnowS: A Library for Integration of Symbolic Domain Knowledge in Deep Learning**, Demo Track, EMNLP-2021]

[Guo, Rajaby Faghihi, Zhang, and Kordjamshidi. **Inference-masked loss for structured output learning**. IJCAI-2020]

# Typical show case: Entity Mention Relation Extraction

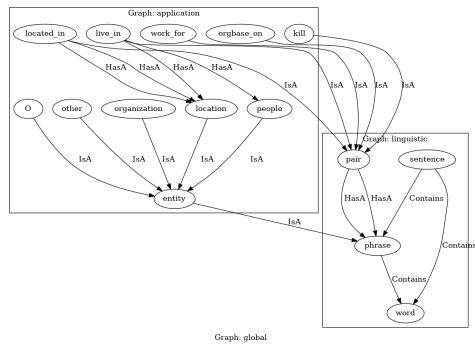
other	0.05
location	0.92
people	0.90

other	0.05
location	0.33
org	0.82

Inference helps to improve local predictions.

Models can be trained locally or globally using soft and hard constraints.

Washington covers Seattle for Associated Press.

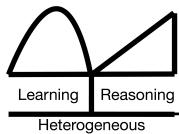


irrelevant	0.10
lives_in	0.35
works_for	0.85

Relation	Entity 1	Entity 2
kill	people	people
works_for	people	org
live_in	people	location
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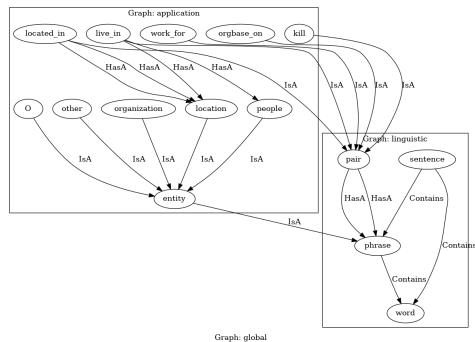
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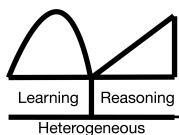


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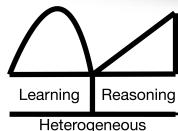
[Guo, Rajaby Faghihi, Zhang, and Kordjamshidi. **Inference-masked loss for structured output learning**. IJCAI-2020]



# Ideal Language Components for Declarative Modeling

- Data Modeling
- Knowledge Representation and Reasoning
- Learning from Data
  - Dealing with uncertainty in Data and Knowledge
  - Data Representations
- Designing Learning and Inference Paradigms

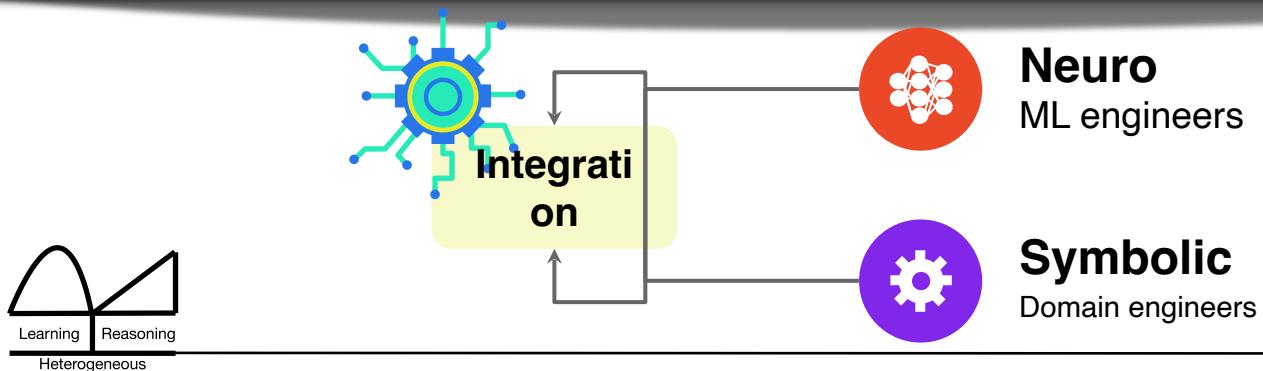
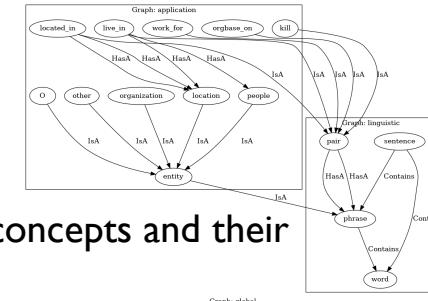
Finding the right abstraction and primitives for an easy integration of all of these components is a challenge!



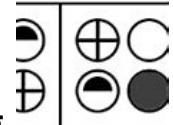
[Kordjamshidi, Kersting and Roth, Declarative Learning Based Programming as an Interface to AI systems, Frontiers in Artificial Intelligence, 2022]

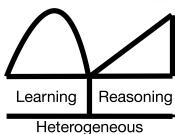
# What is DomiKnowS?

- Current deep learning libraries (  ) are the backbone of DomiKnowS.
- The interface is a symbolic representation of concepts and relationships.
- Knowledge in the form of Logical expressions can be expressed over named concepts and their instantiations.
- Names/symbols are connected to deep learning modules.
- We can reason over symbols and integrate explicit reasoning over output structures or latent variables into Deep learning
- Knowledge is used in various types of reasoning and as hard or soft constraints on the output concepts of the deep models based on a variety of algorithms.



# Why knowledge integration? Why symbols? Why DomiKnows?

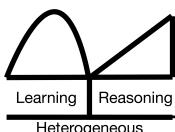
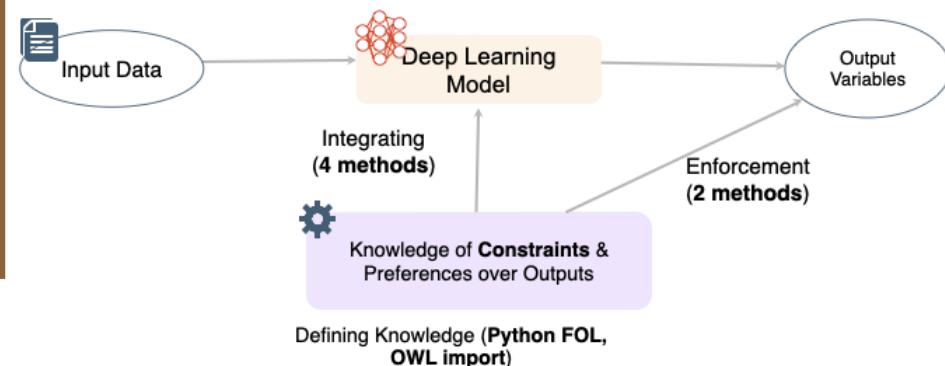
- Deep Learning is data hungry and Labeled data is expensive.
- Domain Knowledge (DK) can directly provide the level of abstraction needed for reasoning.
- DK potentially reduces the need for large amounts of data
- DK is often expressed symbolically & Symbolic reasoning is more interpretable
- Cover the gap between current deep learning tools  and symbolic reasoning



# Program Components

- Declarative Problem Specification
  - Graph-based Data Modeling
  - Knowledge Representation
- Defining computational units
  - Wrapping feature generation modules
  - Wrapping deep learning architectures
  - Connecting the Symbolic and sub-symbolic layers
- Deep Constraint-Based Learning and Prediction
  - Various algorithms for applying soft and hard constraints during training
  - Using integer linear programming for inference during prediction [which will be extended further]

- Data Modeling
- Knowledge Representation and Reasoning
- Learning from Data
  - Dealing with uncertainty in Data and Knowledge
  - Data Representations
- Designing Learning and Inference Paradigm



# DomiKnowS Development

## ■ Domain Declaration (Concepts, Relationships)

```
word = Concept(name='word')
phrase = Concept(name='phrase')
sentence = Concept(name='sentence')
sentence.contains(word)
sentence.contains(phrase)
phrase.contains(word)

pair = Concept(name='pair')
pair.has_a(arg1=word, arg2=word)

people = word(name='people')
organization = word(name='organization')
location = word(name='location')
other = word(name='other')
o = word(name='0')
```

DEMO

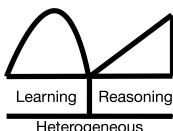
<https://hlr.github.io/domiknows-nlp/>

## ■ Constraints Declaration

```
disjoint(people, organization, location, other, o)
```

```
nandL(people, organization)
```

+ Automatically compile OWL ontologies



[DomiKnowS: A library for integration of symbolic domain knowledge in deep learning. **Hossein Rajaby Faghihi, Quan Guo, Andrzej Uszok, Darius Nafar, Elaheh Raisi, and Parisa Kordjamshidi**. EMNLP-2021 Demo Track]

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```
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organization = word(name='organization')
location = word(name='location')
other = word(name='other')
o = word(name='0')
```

```
paragraph = Concept(name='paragraph')
question = Concept(name='question')
para_quest_contains, = paragraph.contains(question)
...
question[is_more] = ModuleLearner("robert_emb",
module=RobertaClassificationHead(roberta_model.last_layer_size))
...
ifL(is_more, V(name='x'), is_less, V(name='y', v=( 'x',
symmetric, s_arg2.name)))
```

DEMO

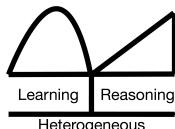
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# Underlying algorithms

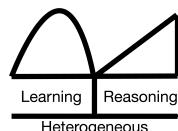
- **Inference masked loss:** Using integer linear programming formulation of the inference to find the best output subject to constraints in the loop of training.
- **Sampling loss/Semantic loss:** sampling the outputs and reduce the probability of violations as a part of the loss based on the samples.
- **Dual formulation:** Forming a dual formulation of the objective and adding a differentiable surrogate of the constraints to the loss.
- **Prediction time Inference:** In all cases ILP can be used in the inference time to find the most probable output.

If the constraint violation is a part of the loss, the model learns to respect the constraints, however, those can be still violated at the end. Using ILP at inference time ensures consistent results with domain knowledge. Constraints can be used for unsupervised learning too.

—Guo, Rajaby Faghihi, Zhang, and Kordjamshidi. Inference-masked loss for structured output learning. IJCAI-2020

—Hossein Rajaby Faghihi, Parisa Kordjamshidi, Consistent Joint Decision-Making with Heterogeneous Learning Models, The 2024 European conference in the field of computational linguistics (EACL-2024 findings)

—Yatin Nandwani, Abhishek Pathak, Mausam, and Parag Singla. 2019a. A primal dual formulation for deep learning with constraints. In NeurIPS.



—J. Xu, Z. Zhang, T. Friedman, Y. Liang, and G. Van den Broeck. 2018. A semantic loss function for deep learning with symbolic knowledge. Volume 80 of Proceedings of Machine Learning Research, pages 5502–5511. PMLR.

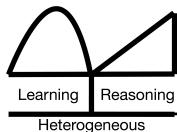
—Dan Roth and Wen-tau Yih, "A Linear Programming Formulation for Global Inference in Natural Language Tasks." CoNLL, (2004)

# Building a Benchmark Using DomiKnowS

## GLUECons

- The first collection of the benchmarks to evaluate constraint integration in Deep Models
- Providing a set of metrics for in-depth evaluation of constraint integration methods
- A set of baselines for such integration during both inference and training
- Releasing a boilerplate code and evaluation of all tasks to facilitate future research and comparisons

GLUECons: A Generic Benchmark for Learning Under Constraints, **Hossein Rajaby Faghihi, Aliakbar Nafar, Chen Zheng, Roshanak Mirzaee, Yue Zhang, Andrzej Uszok, Alexander Wan, Tanawan Premsri, Dan Roth, and Parisa Kordjamshidi.** The 37th Conference of Artificial Intelligence (AAAI-2023)



# Selected Tasks

-Classification with label dependencies

Mutual Exclusivity  
(MNIST)

Hierarchical constraints  
(CIFAR 100)

-Self-Consistency in decisions

What-If  
question  
answering  
(WIQA)

Natural  
language  
inference (NLI)

BeliefBan  
k

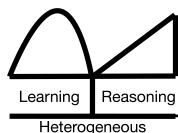
-Consistency with external knowledge

Entity and relation extraction  
(CONLL2003) (EMR)

-Constraints in (un/semi)supervised setting

MNIST  
arithmetic

Sudoku



-Structural Consistency

BIO  
Tagging

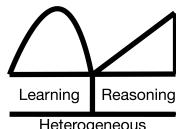


# DomiKnowS's Natural Language interface

- Explain the graph and constraints in natural language
- Interactively prompt GPT (using Langchain)
- Convert Natural language to declarative language!
- DomiKnowS release as an independent package

```
pip install DomiKnowS
```

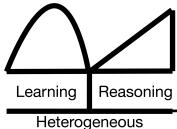
<https://hlr.github.io/domiknows/>



Prompt2DeModel: Declarative Neuro-Symbolic Modeling with Natural Language, **Hossein Rajaby Faghihi**, Aliakbar Nafar, Andrzej Uszok, Hamid Karimian, Parisa Kordjamshidi, 2024, under-review

# Summary Results

- Evaluation of Reasoning Skills of Language Models
- Integration of Explicit Reasoning in form of Constraints in Training and Inference –spatial and uncertainty reasoning
- Building tools (DimiKnowS ) and benchmarks (GLUECons) for integration of logic in learning.
- Natural language interface to declarative programming.



# Acknowledgments and Thanks

Thanks to Andrzej Uszok from IHMC and all my students, post-docs at ***Heterogenous Learning and Reasoning (HLR)*** Lab who helped in developing DomiKnowS.

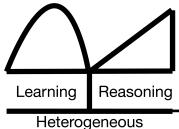


<https://hlr.github.io>.  
[kordajms@msu.edu](mailto:kordajms@msu.edu)



**Michigan State University**  
Computer Science and Engineering Department

I am actively **seeking** motivated **PhD students and post-doctoral researchers**. my research focus within the fields of Natural Language Processing (NLP), Vision and Language (V&L) and Neuro-symbolic modeling,



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