

50.007 Machine Learning Homework 4

Victoria Yong 1004455

Q1.

Transition Table, $\alpha_{uv} = \frac{\text{count}(u,v)}{\text{count}(u)}$

u/v	X	Y	Z	STOP
X	0	0.4	0.4	0.2
Y	0.2	0	0.2	0.6
Z	0.4	0.6	0	0
START	0.5	0	0.5	0

Emission Table, $b_u(o) = \frac{\text{count}(A \rightarrow e)}{\text{count}(A)}$

u/o	A	B	C
X	0.4	0.6	0
Y	0.2	0	0.8
Z	0.2	0.6	0.2

Q2.

START, Z, Y, STOP

From the emission table above, observation b is most likely to have the state X or Z. Observation c is most likely to have the state Y. From the transition table,

$$P(b = X, c = Y) = P(\text{START}, X) * P(X, Y) * P(Y, \text{STOP}) = 2/4 * 2/5 * 3/5 = 0.12$$

$$P(b = Z, c = Y) = P(\text{START}, Z) * P(Z, Y) * P(Y, \text{STOP}) = 2/4 * 3/5 * 3/5 = 0.18$$

Hence it is most likely for b to have the state Z, and c to have the state Y.

Q3.

Layer 1:

For state X,

$$\begin{aligned}
 \text{Transition, } \alpha_x^{(1)} &= \alpha_{START,x}^{(1)} \\
 &= 0.5 \\
 \text{Emission, } \beta_x^{(1)} &= \sum_v \alpha_{u,v} b_u(b) \beta_v(2) \\
 &= \alpha_{x,x} b_x(b) \beta_x(u) + \alpha_{x,y} b_y(b) \beta_y(u) + \alpha_{x,z} b_z(b) \beta_z(u) \\
 &= 0 + (0.4)(0.6)(\alpha_{y,STOP}) b_y(c) + 0 \\
 &= (0.24)(0.6)(0.8) \\
 &= 0.1152
 \end{aligned}$$

For state Y,

$$\begin{aligned}
 \alpha_y^{(1)} &= \alpha_{START,y}^{(1)} \\
 &= 0.0 \\
 \beta_y^{(1)} &= \sum_v \alpha_{u,v} b_u(b) \beta_v(2) \\
 &= 0.0
 \end{aligned}$$

For state Z,

$$\begin{aligned}
 \alpha_z^{(1)} &= \alpha_{START,z}^{(1)} \\
 &= 0.5 \\
 \beta_x^{(1)} &= \sum_v \alpha_{u,v} b_u(b) \beta_v(2) \\
 &= \alpha_{z,x} b_z(b) \beta_x(u) + \alpha_{z,y} b_y(b) \beta_y(u) + \alpha_{z,z} b_z(b) \beta_z(u) \\
 &= (0.4)(0.6)(\alpha_{x,STOP}) b_x(c) + (0.6)^3(0.8) + 0 \\
 &= 0 + 0.1728 \\
 &= 0.1728
 \end{aligned}$$

$$\therefore s_1 = Z$$

Layer 2:

For state X,

$$\begin{aligned}
 \beta_x^{(2)} &= \alpha_{x,STOP}^{(2)} b_x(c) \\
 &= 0 \\
 \alpha_x^{(2)} &= \sum_v \alpha_{vu} \alpha_v(1) b_v(b) \\
 &= 0 + 0 + 0.5(0.4)(0.6) \\
 &= 0.12
 \end{aligned}$$

For state Y,

$$\begin{aligned}
 \beta_y^{(2)} &= \alpha_{y,STOP}^{(2)} b_y(c) \\
 &= (0.6)(0.8) \\
 &= 0.48
 \end{aligned}$$

$$\begin{aligned}
\alpha_y^{(2)} &= \sum_v \alpha_{vu} \alpha_v(1) b_v(b) \\
&= 0.5(0.4)(0.6) + 0 + 0.5(0.6)(0.6) \\
&= 0.3
\end{aligned}$$

For state Z,

$$\begin{aligned}
\beta_z^{(2)} &= \alpha_{z,STOP}^{(2)} b_z(c) \\
&= 0 \\
\alpha_z^{(2)} &= \sum_v \alpha_{vu} \alpha_v(1) b_v(b) \\
&= 0.5(0.4)(0.6) + 0 + 0 \\
&= 0.12
\end{aligned}$$

Hence,

$$\begin{aligned}
\alpha_x^{(2)} \beta_x^{(2)} &= 0 \\
\alpha_y^{(2)} \beta_y^{(2)} &= 0.3(0.48) = 0.144 \\
\alpha_z^{(2)} \beta_z^{(2)} &= 0 \\
\therefore s_2 &= Y
\end{aligned}$$

$$s_1 = Z, \quad s_2 = Y$$

Q4.

Number of states = $|T| + 2$

$$\begin{aligned} P(z_i = u | (x, y); \theta) &= \frac{p(x_1, y_1, \dots, x_{i-1}, y_{i-1}, x_i = u, y_i, \dots, x_n, y_n; \theta)}{p((x, y); \theta)} \\ &= p(x_1, y_1, \dots, x_{i-1}, y_{i-1}) p(x_i y_i, \dots, x_n y_n | z_i = u; \theta) \\ &= [p(x_1, \dots, x_{i-1} | z_i = u; \theta) p(y_1, \dots, y_{i-1} | x; \theta)] [p(x_i, \dots, x_n | z_i = u; \theta) p(y_i, \dots, y_n | x; \theta)] \end{aligned}$$

$$\begin{aligned} \alpha_u(i) &= [p(x_1, \dots, x_{i-1} | z_i = u; \theta) p(y_1, \dots, y_{i-1} | x; \theta)] \\ \beta_u(i) &= [p(x_i, \dots, x_n | z_i = u; \theta) p(y_i, \dots, y_n | x; \theta)] \end{aligned}$$

Forward Step:

$$\text{Since } \alpha_u(i) = [p(x_1, \dots, x_{i-1} | z_i = u; \theta) p(y_1, \dots, y_{i-1} | x; \theta)]$$

$$\alpha_u(1) = \alpha_{START,u}$$

For $i = 1, \dots, n - 1$

$$\alpha_u(i + 1) = [\sum_v \alpha_v(i) x_{v,u} b_v(x_i)] p(y_i | x_i)$$

Backward Step:

$$\text{Since } \beta_u(i) = [p(x_i, \dots, x_n | z_i = u; \theta) p(y_i, \dots, y_n | x; \theta)]$$

$$\beta_u(n) = \alpha_{u,STOP} b_u(x_n) p(y_n | x_n)$$

For $i = n - 1, \dots, 1$

$$\beta_u(i) = [\sum_v \alpha_{u,v} b_v(x_i) \beta_v(i + 1)] p(y_i | x_i)$$

Complexity of algorithm:

The overall time complexity is $O(n|T|^2)$.

Each sentence has length n , and each word in the sentence has $|T|$ possible states. Computing the forward and backwards algorithm involves $|T|$ steps.