## **Fully-Connected Neural Nets**

In the previous homework you implemented a fully-connected two-layer neural network on CIFAR-10. The implementation was simple but not very modular since the loss and gradient were computed in a single monolithic function. This is manageable for a simple two-layer network, but would become impractical as we move to bigger models. Ideally we want to build networks using a more modular design so that we can implement different layer types in isolation and then snap them together into models with different architectures.

In this exercise we will implement fully-connected networks using a more modular approach. For each layer we will implement a forward and a backward function. The forward function will receive inputs, weights, and other parameters and will return both an output and a cache object storing data needed for the backward pass, like this:

```
def layer_forward(x, w):
    """ Receive inputs x and weights w """
    # Do some computations ...
    z = # ... some intermediate value
    # Do some more computations ...
    out = # the output

cache = (x, w, z, out) # Values we need to compute gradients
    return out, cache
```

The backward pass will receive upstream derivatives and the cache object, and will return gradients with respect to the inputs and weights, like this:

```
def layer_backward(dout, cache):
    Receive dout (derivative of loss with respect to outputs) and cache,
    and compute derivative with respect to inputs.
    # Unpack cache values
    x, w, z, out = cache

# Use values in cache to compute derivatives
    dx = # Derivative of loss with respect to x
    dw = # Derivative of loss with respect to w

return dx, dw
```

After implementing a bunch of layers this way, we will be able to easily combine them to build classifiers with different architectures.

In addition to implementing fully-connected networks of arbitrary depth, we will also explore different update rules for optimization, and introduce Dropout as a regularizer and Batch/Layer Normalization as a tool to more efficiently optimize deep networks.

### Acknowledgement: This exercise is adapted from Stanford CS231n.

```
# As usual, a bit of setup
from future import print function
import time
import numpy as np
import matplotlib.pyplot as plt
from libs.classifiers.fc net import *
from libs.data utils import get CIFAR10 data
from libs.gradient check import eval numerical gradient,
eval numerical gradient array
from libs.solver import Solver
%matplotlib inline
plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of
plots
plt.rcParams['image.interpolation'] = 'nearest'
plt.rcParams['image.cmap'] = 'gray'
# for auto-reloading external modules
# see http://stackoverflow.com/questions/1907993/autoreload-of-
modules-in-ipython
%load ext autoreload
%autoreload 2
def rel error(x, y):
  """ returns relative error """
  return np.max(np.abs(x - y) / (np.maximum(1e-8, np.abs(x) +
np.abs(y)))
# Load the (preprocessed) CIFAR10 data.
data = get_CIFAR10_data()
for k, v in list(data.items()):
  print(('%s: ' % k, v.shape))
('X_train: ', (49000, 3, 32, 32))
('y_train: ', (49000,))
('X_val: ', (1000, 3, 32, 32))
('y_val: ', (1000,))
('X_test: ', (1000, 3, 32, 32))
('y_test: ', (1000,))
```

## Affine layer: foward

Open the file libs/layers.py and implement the affine\_forward function.

Once you are done you can test your implementaion by running the following:

```
# Test the affine forward function
num inputs = 2
input shape = (4, 5, 6)
output dim = 3
input size = num inputs * np.prod(input shape)
weight size = output dim * np.prod(input shape)
x = np.linspace(-0.1, 0.5, num=input size).reshape(num_inputs,
*input shape)
w = np.linspace(-0.2, 0.3,
num=weight size).reshape(np.prod(input shape), output dim)
b = np.linspace(-0.3, 0.1, num=output dim)
out, = affine forward(x, w, b)
correct_out = np.array([[ 1.49834967, 1.70660132, 1.91485297],
                        [ 3.25553199, 3.5141327, 3.77273342]])
# Compare your output with ours. The error should be around e-9 or
print('Testing affine forward function:')
print('difference: ', rel error(out, correct out))
Testing affine forward function:
difference: 9.769849468192957e-10
```

# Affine layer: backward

Now implement the affine\_backward function and test your implementation using numeric gradient checking.

```
# Test the affine_backward function
np.random.seed(231)
x = np.random.randn(10, 2, 3)
w = np.random.randn(6, 5)
b = np.random.randn(5)
dout = np.random.randn(10, 5)

dx_num = eval_numerical_gradient_array(lambda x: affine_forward(x, w, b)[0], x, dout)
dw_num = eval_numerical_gradient_array(lambda w: affine_forward(x, w, b)[0], w, dout)
```

```
db_num = eval_numerical_gradient_array(lambda b: affine_forward(x, w, b)[0], b, dout)

_, cache = affine_forward(x, w, b)
dx, dw, db = affine_backward(dout, cache)

# The error should be around e-10 or less
print('Testing affine_backward function:')
print('dx error: ', rel_error(dx_num, dx))
print('dw error: ', rel_error(dw_num, dw))
print('db error: ', rel_error(db_num, db))

Testing affine_backward function:
dx error: 5.399100368651805e-11
dw error: 9.904211865398145e-11
db error: 2.4122867568119087e-11
```

#### **ReLU** activation: forward

Implement the forward pass for the ReLU activation function in the relu\_forward function and test your implementation using the following:

### **ReLU activation: backward**

Now implement the backward pass for the ReLU activation function in the relu\_backward function and test your implementation using numeric gradient checking:

```
np.random.seed(231)
x = np.random.randn(10, 10)
dout = np.random.randn(*x.shape)

dx_num = eval_numerical_gradient_array(lambda x: relu_forward(x)[0],
x, dout)

_, cache = relu_forward(x)
dx = relu_backward(dout, cache)

# The error should be on the order of e-12
print('Testing relu_backward function:')
print('dx error: ', rel_error(dx_num, dx))

Testing relu_backward function:
dx error: 3.2756349136310288e-12
```

# "Sandwich" layers

There are some common patterns of layers that are frequently used in neural nets. For example, affine layers are frequently followed by a ReLU nonlinearity. To make these common patterns easy, we define several convenience layers in the file libs/layer\_utils.py.

For now take a look at the affine\_relu\_forward and affine\_relu\_backward functions, and run the following to numerically gradient check the backward pass:

```
from libs.layer utils import affine relu forward, affine relu backward
np.random.seed(231)
x = np.random.randn(2, 3, 4)
w = np.random.randn(12, 10)
b = np.random.randn(10)
dout = np.random.randn(2, 10)
out, cache = affine relu forward(x, w, b)
dx, dw, db = affine relu backward(dout, cache)
dx num = eval numerical gradient array(lambda x:
affine relu forward(x, w, b)[0], x, dout)
dw num = eval numerical gradient array(lambda w:
affine_relu_forward(x, w, b)[0], w, dout)
db_num = eval_numerical_gradient_array(lambda b:
affine relu forward(x, w, b)[0], b, dout)
# Relative error should be around e-10 or less
print('Testing affine relu forward and affine relu backward:')
print('dx error: ', rel_error(dx_num, dx))
print('dw error: ', rel_error(dw_num, dw))
print('db error: ', rel_error(db_num, db))
```

```
Testing affine_relu_forward and affine_relu_backward: dx error: 2.299579177309368e-11 dw error: 8.162011105764925e-11 db error: 7.826724021458994e-12
```

## **Loss layers: Softmax**

You implemented these loss functions in the last assignment, so we'll give them to you for free here. You should still make sure you understand how they work by looking at the implementations in libs/layers.py.

You can make sure that the implementations are correct by running the following:

```
np.random.seed(231)
num_classes, num_inputs = 10, 50
x = 0.001 * np.random.randn(num_inputs, num_classes)
y = np.random.randint(num_classes, size=num_inputs)

dx_num = eval_numerical_gradient(lambda x: softmax_loss(x, y)[0], x,
verbose=False)
loss, dx = softmax_loss(x, y)

# Test softmax_loss function. Loss should be close to 2.3 and dx error should be around e-8
print('\nTesting softmax_loss:')
print('loss: ', loss)
print('dx error: ', rel_error(dx_num, dx))
Testing softmax_loss:
loss: 2.302545844500738
dx error: 9.384673161989355e-09
```

## Two-layer network

In the previous assignment you implemented a two-layer neural network in a single monolithic class. Now that you have implemented modular versions of the necessary layers, you will reimplement the two layer network using these modular implementations.

Open the file libs/classifiers/fc\_net.py and complete the implementation of the TwoLayerNet class. This class will serve as a model for the other networks you will implement in this assignment, so read through it to make sure you understand the API. You can run the cell below to test your implementation.

```
np.random.seed(231)
N, D, H, C = 3, 5, 50, 7
X = np.random.randn(N, D)
y = np.random.randint(C, size=N)
```

```
std = 1e-3
model = TwoLayerNet(input dim=D, hidden dim=H, num classes=C,
weight scale=std)
print('Testing initialization ... ')
W1 std = abs(model.params['W1'].std() - std)
b1 = model.params['b1']
W2 std = abs(model.params['W2'].std() - std)
b2 = model.params['b2']
assert W1_std < std / 10, 'First layer weights do not seem right'</pre>
assert np.all(b1 == 0), 'First layer biases do not seem right'
assert W2 std < std / 10, 'Second layer weights do not seem right'</pre>
assert np.all(b2 == 0), 'Second layer biases do not seem right'
print('Testing test-time forward pass ... ')
model.params['W1'] = np.linspace(-0.7, 0.3, num=D*H).reshape(D, H)
model.params['b1'] = np.linspace(-0.1, 0.9, num=H)
model.params['W2'] = np.linspace(-0.3, 0.4, num=H*C).reshape(H, C)
model.params['b2'] = np.linspace(-0.9, 0.1, num=C)
X = np.linspace(-5.5, 4.5, num=N*D).reshape(D, N).T
scores = model.loss(X)
correct scores = np.asarray(
  [[11.53165108, 12.2917344,
                                13.05181771, 13.81190102,
14.57198434, 15.33206765, 16.09215096],
   [12.05769098, 12.74614105, 13.43459113,
                                              14.1230412.
14.81149128, 15.49994135, 16.18839143],
   [12.58373087, 13.20054771, 13.81736455, 14.43418138,
15.05099822, 15.66781506, 16.2846319 ]])
scores diff = np.abs(scores - correct scores).sum()
assert scores diff < 1e-6, 'Problem with test-time forward pass'
print('Testing training loss (no regularization)')
y = np.asarray([0, 5, 1])
loss, grads = model.loss(X, y)
correct loss = 3.4702243556
assert abs(loss - correct_loss) < 1e-10, 'Problem with training-time</pre>
loss'
model.reg = 1.0
loss, grads = model.loss(X, y)
correct loss = 26.5948426952
assert abs(loss - correct loss) < 1e-10, 'Problem with regularization</pre>
loss'
# Errors should be around e-7 or less
for reg in [0.0, 0.7]:
  print('Running numeric gradient check with reg = ', reg)
  model.reg = reg
  loss, grads = model.loss(X, y)
```

```
for name in sorted(grads):
    f = lambda : model.loss(X, y)[0]
    grad num = eval numerical gradient(f, model.params[name],
verbose=False)
    print('%s relative error: %.2e' % (name, rel error(grad num,
grads[name])))
Testing initialization ...
Testing test-time forward pass ...
Testing training loss (no regularization)
Running numeric gradient check with reg = 0.0
W1 relative error: 1.83e-08
W2 relative error: 3.12e-10
b1 relative error: 9.83e-09
b2 relative error: 4.33e-10
Running numeric gradient check with reg = 0.7
W1 relative error: 2.53e-07
W2 relative error: 2.85e-08
b1 relative error: 1.56e-08
b2 relative error: 7.76e-10
```

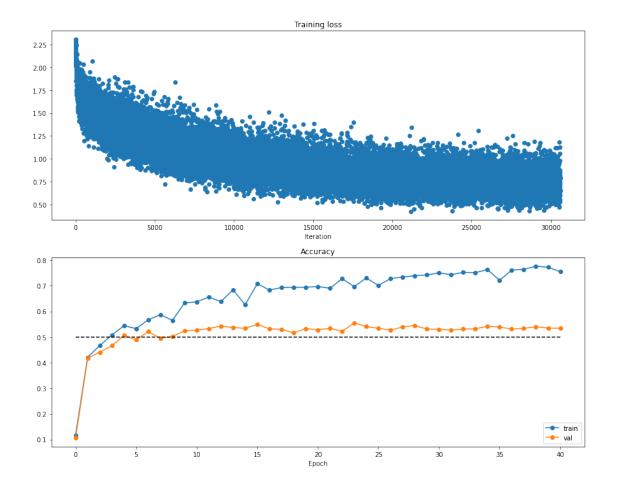
#### Solver

In the previous assignment, the logic for training models was coupled to the models themselves. Following a more modular design, for this assignment we have split the logic for training models into a separate class.

Open the file libs/solver.py and read through it to familiarize yourself with the API. After doing so, use a Solver instance to train a TwoLayerNet that achieves at least 50% accuracy on the validation set.

```
########
# ****START OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE)****
model = TwoLayerNet(reg=1e-2)
solver = Solver(model, data, optim_config={
                    'learning rate': 1e-3,
                  lr decay=0.9, num epochs=40, batch size=64,
num train samples=1000, print every=10000)
solver.train()
acc = solver.check accuracy(data['X val'], data['y val'],
batch size=64)
print(f'Accuracy of model on validation data: {acc}')
# *****END OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE)*****
########
                            END OF YOUR CODE
########
(Iteration 1 / 30600) loss: 2.305068
(Epoch 0 / 40) train acc: 0.116000; val acc: 0.106000
(Epoch 1 / 40) train acc: 0.421000; val acc: 0.417000
(Epoch 2 / 40) train acc: 0.467000; val acc: 0.441000
(Epoch 3 / 40) train acc: 0.508000; val acc: 0.466000
(Epoch 4 / 40) train acc: 0.544000; val acc: 0.506000
(Epoch 5 / 40) train acc: 0.533000; val acc: 0.489000
(Epoch 6 / 40) train acc: 0.567000; val acc: 0.521000
(Epoch 7 / 40) train acc: 0.587000; val acc: 0.495000
(Epoch 8 / 40) train acc: 0.565000; val acc: 0.502000
(Epoch 9 / 40) train acc: 0.633000; val acc: 0.524000
(Epoch 10 / 40) train acc: 0.637000; val acc: 0.527000
(Epoch 11 / 40) train acc: 0.656000; val acc: 0.533000
(Epoch 12 / 40) train acc: 0.638000; val_acc: 0.543000
(Epoch 13 / 40) train acc: 0.684000; val acc: 0.537000
(Iteration 10001 / 30600) loss: 1.035828
(Epoch 14 / 40) train acc: 0.626000; val acc: 0.534000
(Epoch 15 / 40) train acc: 0.708000; val acc: 0.549000
(Epoch 16 / 40) train acc: 0.683000; val_acc: 0.532000
(Epoch 17 / 40) train acc: 0.693000; val acc: 0.530000
(Epoch 18 / 40) train acc: 0.694000; val acc: 0.516000
(Epoch 19 / 40) train acc: 0.694000; val acc: 0.533000
(Epoch 20 / 40) train acc: 0.697000; val acc: 0.528000
(Epoch 21 / 40) train acc: 0.690000; val_acc: 0.534000
(Epoch 22 / 40) train acc: 0.727000; val acc: 0.522000
(Epoch 23 / 40) train acc: 0.697000; val_acc: 0.555000
```

```
(Epoch 24 / 40) train acc: 0.730000; val acc: 0.541000
(Epoch 25 / 40) train acc: 0.701000; val_acc: 0.534000
(Epoch 26 / 40) train acc: 0.728000; val acc: 0.527000
(Iteration 20001 / 30600) loss: 0.829858
(Epoch 27 / 40) train acc: 0.734000; val acc: 0.539000
(Epoch 28 / 40) train acc: 0.739000; val_acc: 0.545000
(Epoch 29 / 40) train acc: 0.742000; val acc: 0.531000
(Epoch 30 / 40) train acc: 0.750000; val acc: 0.530000
(Epoch 31 / 40) train acc: 0.743000; val acc: 0.527000
(Epoch 32 / 40) train acc: 0.752000; val acc: 0.531000
(Epoch 33 / 40) train acc: 0.751000; val acc: 0.532000
(Epoch 34 / 40) train acc: 0.763000; val acc: 0.542000
(Epoch 35 / 40) train acc: 0.721000; val acc: 0.539000
(Epoch 36 / 40) train acc: 0.761000; val acc: 0.531000
(Epoch 37 / 40) train acc: 0.764000; val acc: 0.534000
(Epoch 38 / 40) train acc: 0.776000; val acc: 0.540000
(Epoch 39 / 40) train acc: 0.772000; val acc: 0.535000
(Iteration 30001 / 30600) loss: 0.942095
(Epoch 40 / 40) train acc: 0.755000; val acc: 0.534000
Accuracy of model on validation data: 0.555
# Run this cell to visualize training loss and train / val accuracy
plt.subplot(2, 1, 1)
plt.title('Training loss')
plt.plot(solver.loss history, 'o')
plt.xlabel('Iteration')
plt.subplot(2, 1, 2)
plt.title('Accuracy')
plt.plot(solver.train acc history, '-o', label='train')
plt.plot(solver.val_acc_history, '-o', label='val')
plt.plot([0.5] * len(solver.val acc history), 'k--')
plt.xlabel('Epoch')
plt.legend(loc='lower right')
plt.gcf().set size inches(15, 12)
plt.show()
```



## Multilayer network

Next you will implement a fully-connected network with an arbitrary number of hidden layers.

Read through the FullyConnectedNet class in the file libs/classifiers/fc\_net.py.

Implement the initialization, the forward pass, and the backward pass. For the moment don't worry about implementing dropout or batch/layer normalization; we will add those features soon.

### **Initial loss and gradient check**

As a sanity check, run the following to check the initial loss and to gradient check the network both with and without regularization. Do the initial losses seem reasonable?

For gradient checking, you should expect to see errors around 1e-7 or less.

```
np.random.seed(231)
N, D, H1, H2, C = 2, 15, 20, 30, 10
X = np.random.randn(N, D)
y = np.random.randint(C, size=(N,))
```

```
for reg in [0, 3.14]:
  print('Running check with reg = ', reg)
 model = FullyConnectedNet([H1, H2], input dim=D, num classes=C,
                            reg=reg, weight scale=5e-2,
dtype=np.float64)
  loss, grads = model.loss(X, y)
  print('Initial loss: ', loss)
 # Most of the errors should be on the order of e-7 or smaller.
 # NOTE: It is fine however to see an error for W2 on the order of e-
  # for the check when reg = 0.0
  for name in sorted(grads):
    f = lambda : model.loss(X, y)[0]
    grad num = eval numerical gradient(f, model.params[name],
verbose=False, h=1e-5)
    print('%s relative error: %.2e' % (name, rel error(grad num,
grads[name])))
Running check with reg = 0
Initial loss: 2.3004790897684924
W1 relative error: 1.48e-07
W2 relative error: 2.21e-05
W3 relative error: 3.53e-07
b1 relative error: 5.38e-09
b2 relative error: 2.09e-09
b3 relative error: 5.80e-11
Running check with reg = 3.14
Initial loss: 7.052114776533016
W1 relative error: 6.86e-09
W2 relative error: 3.52e-08
W3 relative error: 1.32e-08
b1 relative error: 1.48e-08
b2 relative error: 1.72e-09
b3 relative error: 1.80e-10
```

As another sanity check, make sure you can overfit a small dataset of 50 images. First we will try a three-layer network with 100 units in each hidden layer. In the following cell, tweak the **learning rate** and **weight initialization scale** to overfit and achieve 100% training accuracy within 20 epochs.

```
# TODO: Use a three-layer Net to overfit 50 training examples by
# tweaking just the learning rate and initialization scale.

num_train = 50
small_data = {
   'X_train': data['X_train'][:num_train],
   'y_train': data['y_train'][:num_train],
```

```
'X val': data['X val'],
  'y val': data['y val'],
weight scale = 1e-1 # Experiment with this!
learning rate = 1e-4 # Experiment with this!
model = FullyConnectedNet([100, 100],
              weight scale=weight scale, dtype=np.float64)
solver = Solver(model, small data,
                print every=10, num epochs=20, batch size=25,
                update rule='sqd',
                optim config={
                  'learning_rate': learning rate,
solver.train()
plt.plot(solver.loss history, 'o')
plt.title('Training loss history')
plt.xlabel('Iteration')
plt.ylabel('Training loss')
plt.show()
(Iteration 1 / 40) loss: 357.428290
(Epoch 0 / 20) train acc: 0.020000; val acc: 0.110000
(Epoch 1 / 20) train acc: 0.040000; val acc: 0.112000
(Epoch 2 / 20) train acc: 0.180000; val acc: 0.108000
(Epoch 3 / 20) train acc: 0.300000; val acc: 0.144000
(Epoch 4 / 20) train acc: 0.300000; val acc: 0.135000
(Epoch 5 / 20) train acc: 0.420000; val acc: 0.157000
(Iteration 11 / 40) loss: 31.172835
(Epoch 6 / 20) train acc: 0.540000; val acc: 0.153000
(Epoch 7 / 20) train acc: 0.560000; val acc: 0.146000
(Epoch 8 / 20) train acc: 0.640000; val acc: 0.147000
(Epoch 9 / 20) train acc: 0.680000; val acc: 0.156000
(Epoch 10 / 20) train acc: 0.740000; val acc: 0.153000
(Iteration 21 / 40) loss: 24.023362
(Epoch 11 / 20) train acc: 0.780000; val acc: 0.152000
(Epoch 12 / 20) train acc: 0.820000; val_acc: 0.147000
(Epoch 13 / 20) train acc: 0.920000; val acc: 0.143000
(Epoch 14 / 20) train acc: 0.920000; val acc: 0.140000
(Epoch 15 / 20) train acc: 0.960000; val acc: 0.138000
(Iteration 31 / 40) loss: 0.030175
(Epoch 16 / 20) train acc: 0.980000; val acc: 0.141000
(Epoch 17 / 20) train acc: 1.000000; val acc: 0.145000
(Epoch 18 / 20) train acc: 1.000000; val_acc: 0.145000
(Epoch 19 / 20) train acc: 1.000000; val acc: 0.145000
(Epoch 20 / 20) train acc: 1.000000; val acc: 0.145000
```

