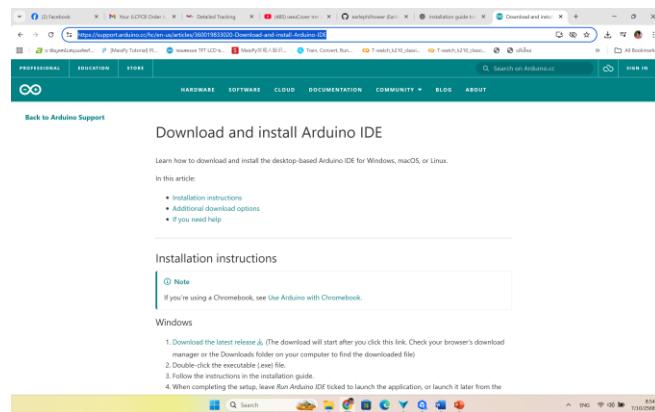


## Introduction

This guide explains the importance of installing the Earle F. Philhower package to enable RP2040 / RP2350 boards to work seamlessly with Arduino IDE 2.x.

### 1. Preparing Arduino IDE 2.x

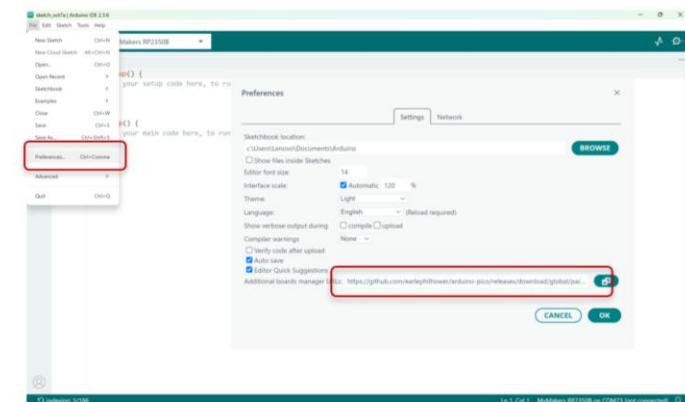
1. Download and install Arduino IDE 2.x from the official website. [?](#)
2. Open the program and verify the version. 



### 2. Adding Board Package URL

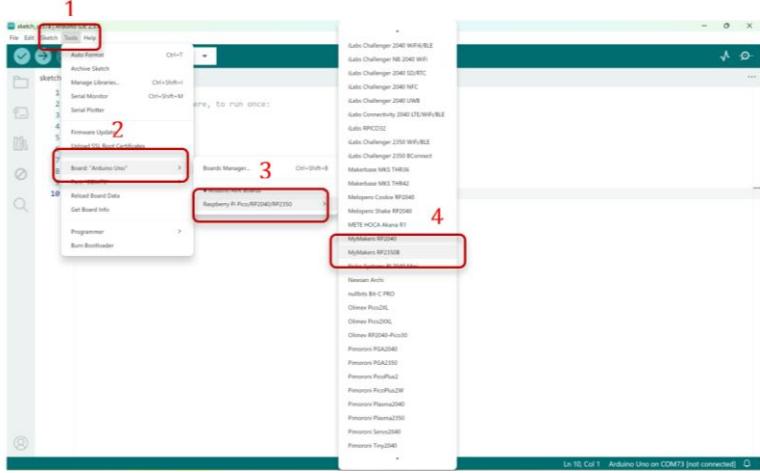
1. Go to **File > Preferences**. 
2. In the '**Additional Boards Manager URLs**' field, enter:

[https://github.com/earlephilhower/arduino-pico/releases/download/global/package\\_rp2040\\_index.json](https://github.com/earlephilhower/arduino-pico/releases/download/global/package_rp2040_index.json)



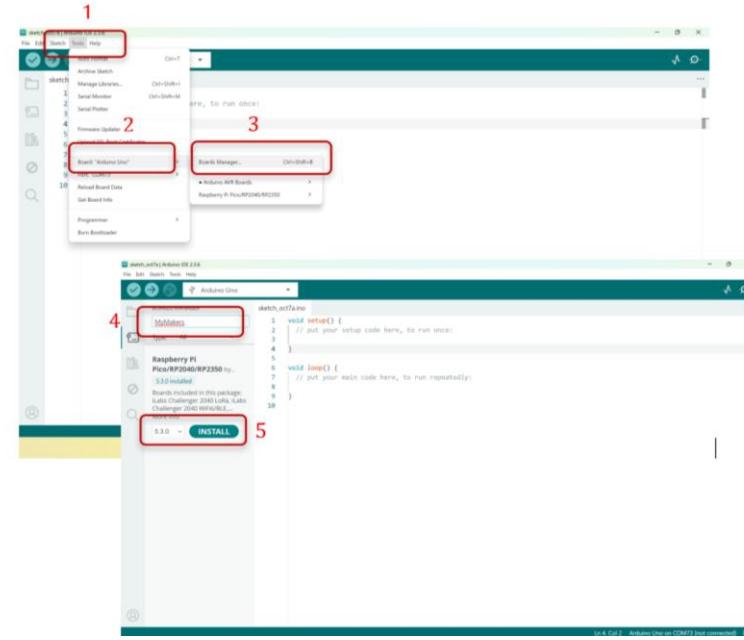
### 3. Selecting Board

1. Go to **Tools > Board > Raspberry Pi RP2040 Boards > MyMakers RP2350B.** 



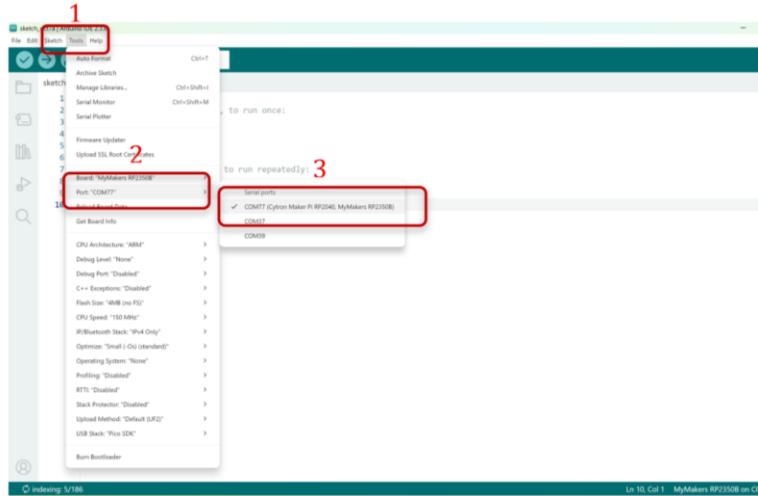
### 4. Installing MyMakers RP2350B Boards

1. Open **Tools > Board > Boards Manager.** 
2. Search for '**Raspberry Pi RP2040**'. 
3. Click **Install.** 



## 5. Selecting Port

1. Go to **Tools > Port** and select the USB port connected to the board. 🌐



## 6. Testing Blink Program

1. Open **File > Examples > 01.Basics > Blink**. ⬇
2. Click **Upload** to flash the program. ⬆
3. Verify that the onboard LED blinks according to the example. ✓

## Conclusion and Credits

Installation is complete. You can now start programming **MY RP-PRO V2.0** immediately. ✓ Special thanks to **Earle F. Philhower** for developing the Arduino-Pico package. 🙏

A screenshot of a GitHub user profile for "earlephilhower". The profile picture shows a man with short hair. The bio area includes links for "arduinopico", "efeo", "ESP3265SAM", and "pico-quick-toolchain". The "Contributions" section shows a heatmap of activity from October 2022 to September 2023. The "Achievements" section lists various GitHub milestones.

# Installation Guide for MyRP-Pro V2.0 Robot Library

(Professional Technical Edition – Blue/Grey Theme)

## Introduction

The MyRP-Pro V2.0 robot is designed and developed to help learners understand robot programming in a simple yet powerful way. Installing the library is an essential step that enables users to fully utilize the robot's functions efficiently and conveniently.

## Importance of Installing the Library

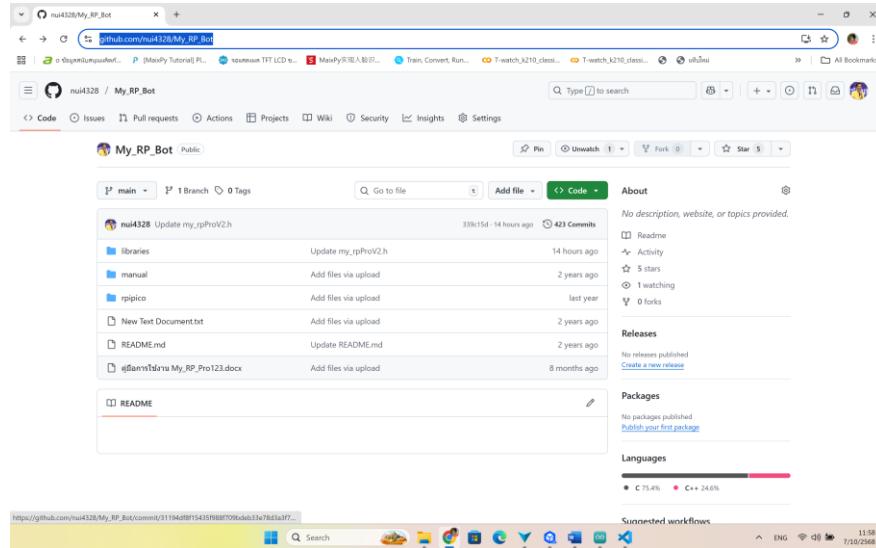
Installing the MyRP-Pro V2.0 library helps learners to:

- Write robot control programs more easily without starting from scratch.
- Reduce programming errors.
- Save development time.
- Use built-in functions such as motor control, sensor reading, PID control, and line following.
- Be suitable for both beginners and advanced competition-level users.

## Library Installation Steps

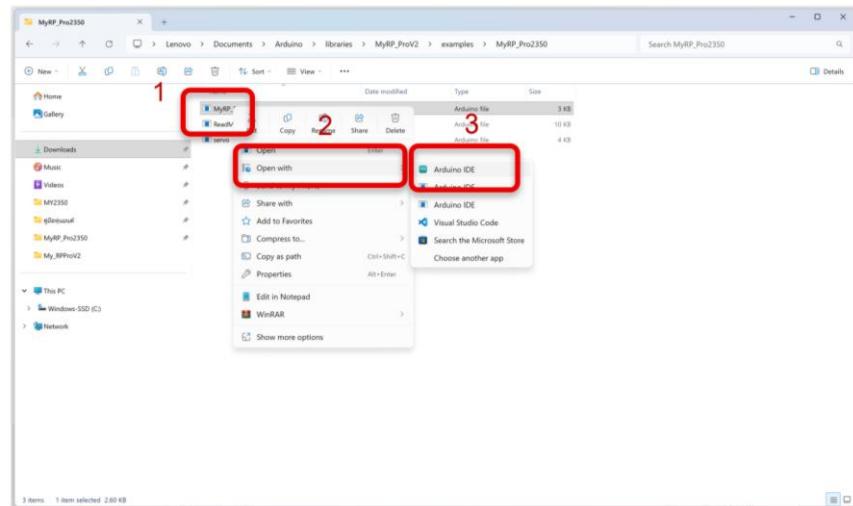
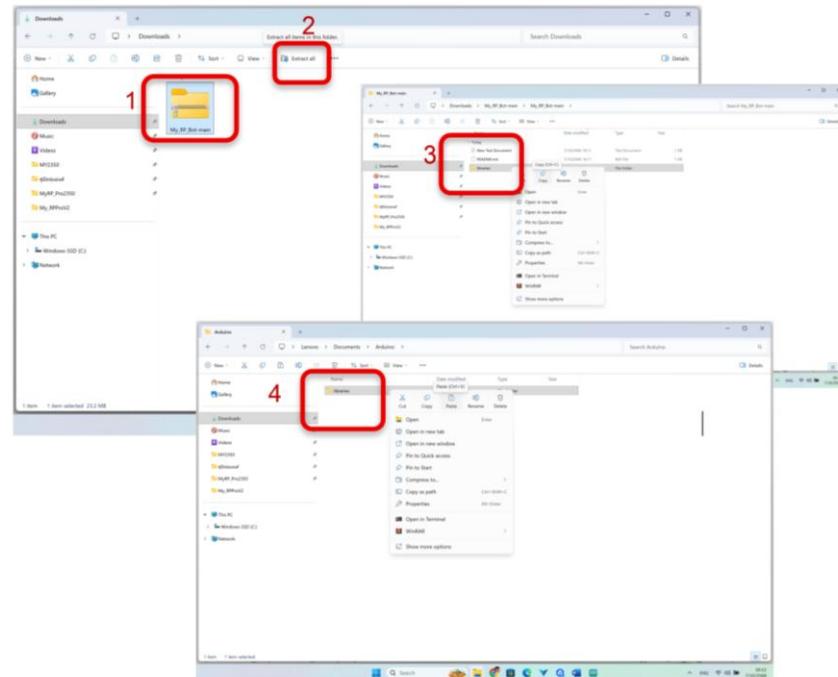
### Step 1: Download the Library from GitHub

1. Open your web browser and go to:  
[https://github.com/nui4328/My\\_RP\\_Bot](https://github.com/nui4328/My_RP_Bot)
2. Click the \*\*Code\*\* button → choose  
\*\*Download ZIP\*\* to download the complete



## Step 2: Extract and Copy the Library Folder

1. After downloading, right-click the file **\*\*My\_RP\_Bot-main.zip\*\*** → select **\*\*Extract All...\*\***
2. Open the extracted folder.
3. Copy the folder named **\*\*libraries\*\***.

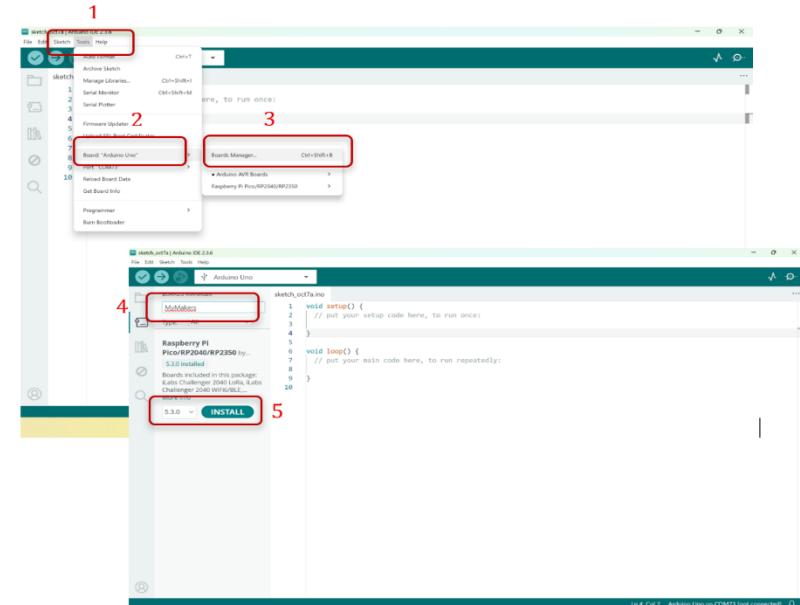
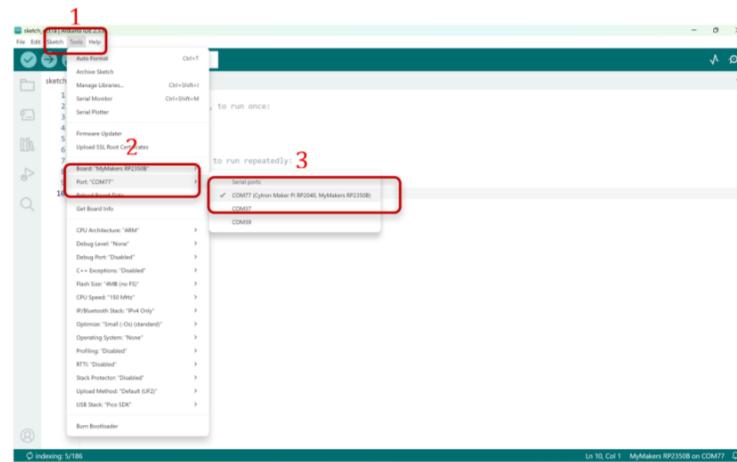


## Step 3: Open the Example Code for MyRP-Pro V2.0

1. Navigate to the folder:  
**C:\Users\<YourUserName>\Documents\Arduino\libraries\MyRP\_ProV2\examples\MyRP\_Pro2350**
2. Choose any example file (e.g., **\*\*MvRP\_Pro2350\_LineFollow.ino\*\***)

## Step 4: Configure the Board and Port in Arduino IDE

1. Open \*\*Arduino IDE\*\*.
2. Go to \*\*Tools > Board > MyMakers Boards > MyMakers RP2350B\*\*.
3. Then go to \*\*Tools > Port\*\* and select the port connected to your board.



## Step 5: Verify and Upload the Code

1. Click the \*\*check mark icon ( $\checkmark$ )\*\* to \*\*Verify\*\* the code.
2. If no errors appear, click the \*\*Upload icon ( $\uparrow$ )\*\* to upload the program to your board.
3. Save your file in a convenient location, such as:  
C:\Users\<YourUserName>\Desktop

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## Additional Tips

- If an error such as “library not found” appears, make sure the folder \*\*MyRP\_ProV2\*\* is inside Documents\Arduino\libraries.
- Ensure that the selected board is \*\*MyMakers RP2350B\*\*.
- Use the \*\*Serial Monitor (Ctrl + Shift + M)\*\* to view data from the board.

## Conclusion

Installing the MyRP-Pro V2.0 library is a fundamental but crucial step for operating the MyRP-Pro robot. After completing all the steps, learners can immediately use built-in functions such as controlling motors, reading sensors, applying PID control for line following, and many more advanced features.

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- Prepared by:

MyMakers Robotics Education – Thailand (English Version)

(For MyRP-Pro V2.0 Robot Educational Kit)