FIG 1

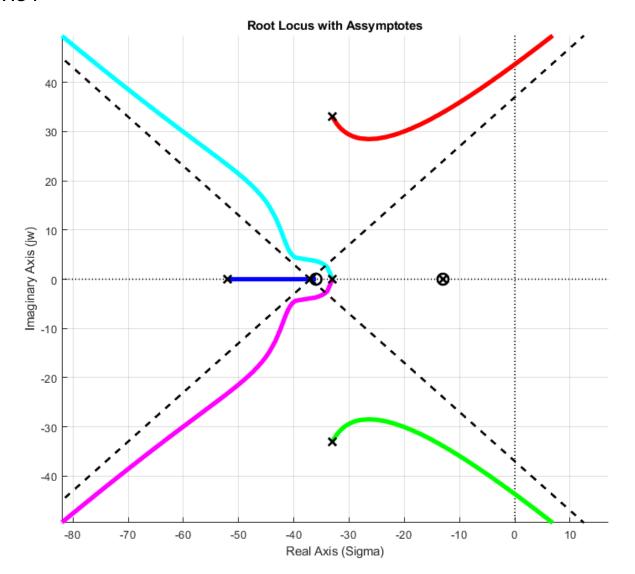
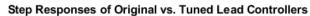


FIG 2



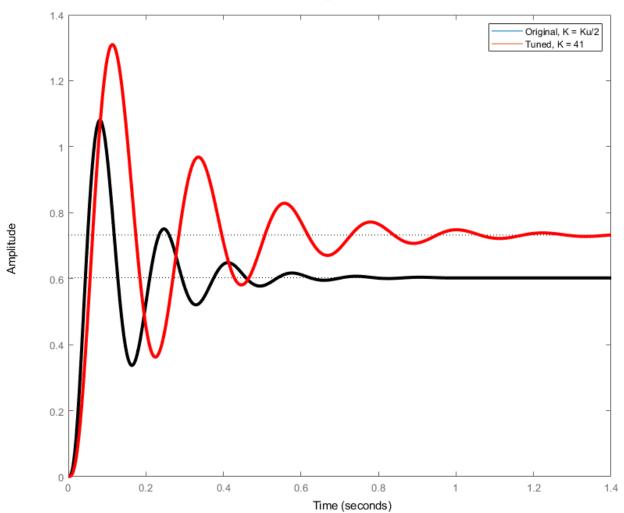
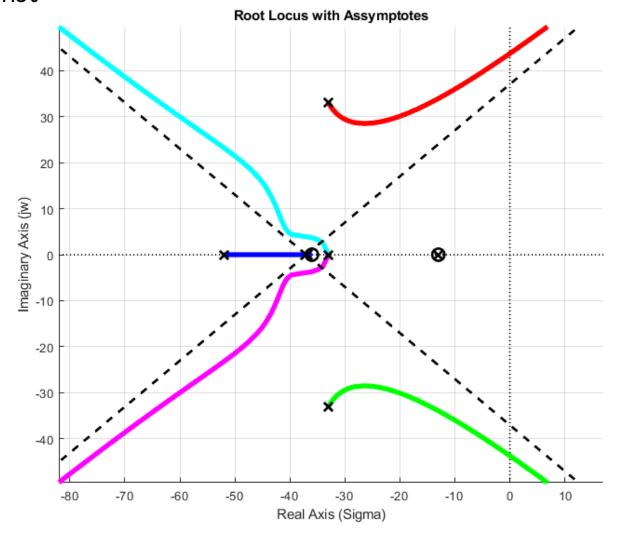


FIG 3



## Tuned 'Totally not PID' controller vs. Untuned Step Responses

