

# COMP 6651

## Algorithm Design Techniques

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COMP 6651

Week 2

Fall 2024

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One very basic type of algorithms that was seen in an elementary algorithms course:

## Divide-and-conquer algorithms

**Divide** the problem into subproblems

**Conquer** each subproblem by solving them recursively (small size subproblems are solved directly)

**Combine** the solutions to the subproblems into a solution of the original problem

### Design issues:

- How many subproblems we divide into,
- what are the “small” sizes solved directly, and
- how to combine solutions of subproblems into a solution of the original problem depends on each individual problem.



## Analyzing run-time of divide-and-conquer algorithms

Assume we have a problem of size  $n$ .

In most cases, when a subproblem is of size  $\leq c$ , it takes a constant time:

$$T(n) = \Theta(1) \text{ if } n \leq c$$

Assume  $n > c$ , and the problem can be divided into  $a$  instances of the same problem of size  $1/b$  of the original size (i.e.,  $a$  subproblems of size  $n/b$ ).

There can be some cost involved in breaking a problem into subproblems:  $D(n)$

There can be some cost involved in combining solutions of subproblems into a solution of the problem:  $C(n)$

$$T(n) = aT(n/b) + D(n) + C(n) \text{ if } n > c$$



## Examples: a) Binary search in a sorted array

**BinSearch**( $x, A, i, j$ )

\ \ Search where  $x$  is in array  $A[i]$  to  $A[j]$

**if**  $i > j$  **then return**  $-1$

$mid = (i+j)/2$

**if**  $x < A[mid]$  **then return** **BinSearch**( $x, A, i, mid-1$ )

**else**

**if**  $x > A[mid]$  **then return** **BinSearch**( $x, A, mid+1, j$ )

**else**

**return**  $mid$



Analysis of run-time for **BinSearch**:

$$a = 1, b = 2,$$

$$D(n) = \Theta(1),$$

$$C(n) = \Theta(1).$$

Then

$$\begin{aligned}
 T(n) &= aT(n/b) + D(n) + C(n) \text{ if } n > c \\
 &= T(n/2) + \Theta(1) + \Theta(1) \text{ if } n \geq 1 \\
 &= T(n/2) + \Theta(1) \text{ if } n \geq 1 \\
 &= T(n/2) + c \text{ if } n \geq 1 \\
 &= \Theta(\log n)
 \end{aligned}$$



## b) Merge-Sort (§2.3)

```

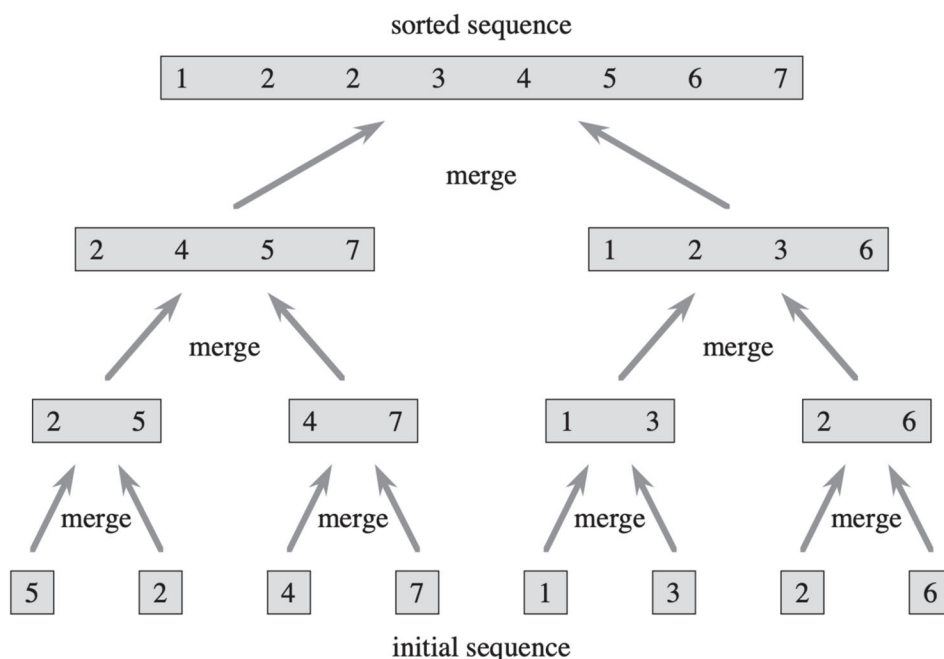
Merge-Sort(A, p, r)
  \ \ Sort A[p] to A[r]
  if p < r then
    mid = (p+r)/2
    Merge-Sort(A,p,mid)
    Merge-Sort(A,mid,r)
    Merge(A,p,mid,r)

```

Worst case analyses:

$a = 2,$   
 $b = 2,$   
 $D(n) = \Theta(1),$   
 $C(n) = \Theta(n),$   
 $T(1) = \Theta(1).$

$T(n) = 2T(n/2) + \Theta(n)$  if  $n > 1$   
 $T(n) = 2T(n/2) + cn$  if  $n > 1$   
 $T(n) = \Theta(n \log n)$

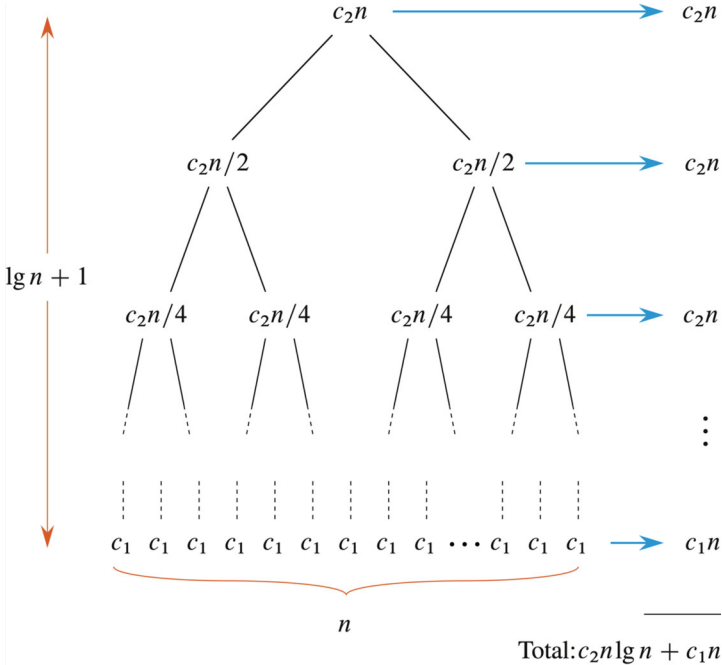
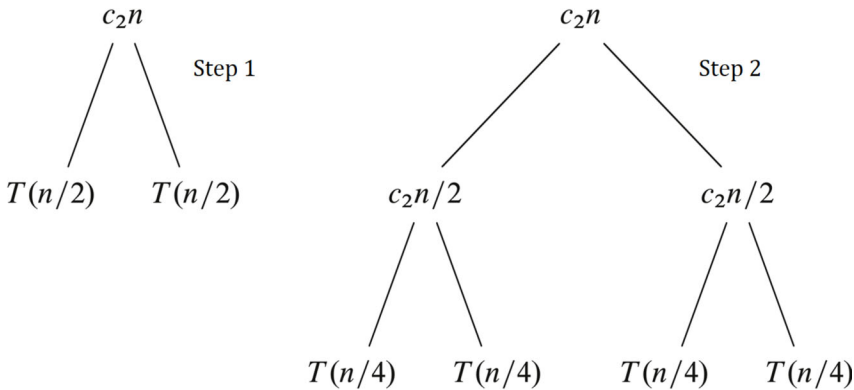


Note: Using recursion tree to understand recurrence

$$T(n) = \begin{cases} \Theta(1) & \text{if } n = 1, \\ 2T(n/2) + \Theta(n) & \text{if } n > 1 \end{cases}$$

We rewrite the recurrence as
$$T(n) = \begin{cases} c_1 & \text{if } n = 1, \\ 2T(n/2) + c_2n & \text{if } n > 1 \end{cases}$$

Recurrence steps:



Disadvantages of merge sort:

- Needs additional space when **Merge**(*A, p, mid, r*) is executed.
- It is not in-place sorting.

Advantages of merge sort:

- Worst case is quite the same as the best case.
- Run-time  $\Theta(n \log n)$  is guaranteed.



c) Integer Multiplication (Not in CLRS 4th Ed.)

**Input:**    *X, Y* – two *n*-digit integers  
**Output:**   *X · Y*

Example:

$$\begin{aligned}
 X &= 4512354 \\
 Y &= 1238970 \\
 X \cdot Y &= 5590671235380 \\
 (n &= 7)
 \end{aligned}$$



X	Y	X · Y
9	9	81
99	99	9801
999	999	998001
9999	9999	99980001
99999	99999	9999800001

Observation: if  $X$  and  $Y$  are  $n$ -digit numbers then  $X \cdot Y$  is at most a  $2n$ -digit number



```

Multiply( $X[1..n]$ ,  $Y[1..n]$ )
   $Z[1..2n] \leftarrow 0$ 
  for  $i \leftarrow n, 1$  do
     $carry \leftarrow 0$ 
    for  $j \leftarrow n, 1$  do
       $m \leftarrow Z[i + j] + carry + X[j] \cdot Y[i]$ 
       $Z[i + j] \leftarrow m \bmod 10$ 
       $carry \leftarrow \lfloor \frac{m}{10} \rfloor$ 
     $Z[i] \leftarrow carry$ 
  return  $Z$ 

```

$$\begin{array}{r}
 2642 \\
 \times 5821 \\
 \hline
 2642 \\
 5284 \phantom{0} \\
 21136 \phantom{00} \\
 13210 \phantom{000} \\
 \hline
 15379082
 \end{array}$$

$$\begin{aligned}
 X &= [2, 6, 4, 2] \\
 Y &= [5, 8, 2, 1] \\
 Z &= [1, 5, 3, 7, 9, 0, 8, 2]
 \end{aligned}$$



**Multiply**( $X[1..n]$ ,  $Y[1..n]$ )

$Z[1..2n] \leftarrow 0$

**for**  $i \leftarrow n, 1$  **do**

$carry \leftarrow 0$

**for**  $j \leftarrow n, 1$  **do**

$m \leftarrow Z[i+j] + carry + X[j] \cdot Y[i]$

$Z[i+j] \leftarrow m \bmod 10$

$carry \leftarrow \lfloor \frac{m}{10} \rfloor$

$Z[i] \leftarrow carry$

**return**  $Z$

*Cost measure:* number of single-digit multiplications

$M(n)$  = worst-case cost of **Multiply** on inputs of length  $n$

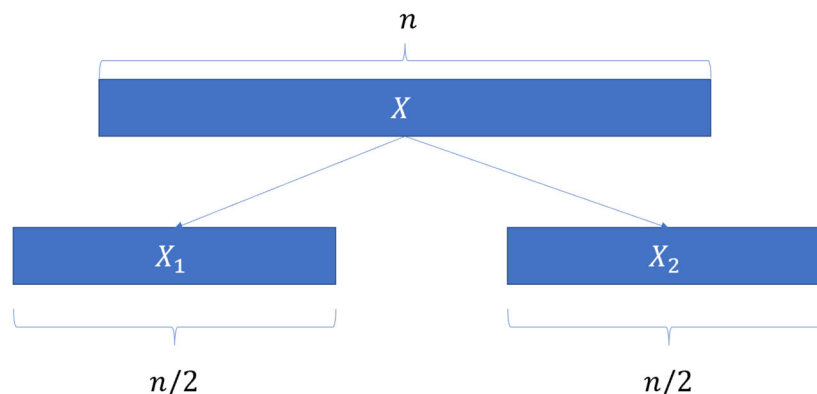
$$M(n) = \Theta(n^2)$$



Can we multiply two integers faster?  
 In 1960s, Kolmogorov conjectured NO  
 Karatsuba disproved the conjecture  
 Karatsuba's idea: divide and conquer!

$$X = 10^{n/2}X_1 + X_2$$

$$Y = 10^{n/2}Y_1 + Y_2$$





$$\begin{aligned}
 X \cdot Y &= (10^{n/2}X_1 + X_2) \cdot (10^{n/2}Y_1 + Y_2) \\
 &= 10^n X_1 \cdot Y_1 + 10^{\frac{n}{2}}(X_1 \cdot Y_2 + X_2 \cdot Y_1) + X_2 \cdot Y_2
 \end{aligned}$$

```

Multiply(X[1..n], Y[1..n])
  if n = 1 then
    return X · Y
  R1 ← Multiply(X1, Y1)
  R2 ← Multiply(X1, Y2)
  R3 ← Multiply(X2, Y1)
  R4 ← Multiply(X2, Y2)
  return 10nR1 + 10 $\frac{n}{2}$ (R2 + R3) + R4
  
```

$M(n)$  = number of single-digit multiplications in this procedure

$$\begin{aligned}
 M(n) &= 4M\left(\frac{n}{2}\right) + \Theta(1) \\
 M(1) &= \Theta(1)
 \end{aligned}$$

Solves to  $M(n) = \Theta(n^2)$   
(See Master's Theorem)

So, no improvement...



Idea:

$$X \cdot Y = 10^n X_1 \cdot Y_1 + 10^{\frac{n}{2}}(X_1 \cdot Y_2 + X_2 \cdot Y_1) + X_2 \cdot Y_2$$

We don't need  $X_1 \cdot Y_2$  and  $X_2 \cdot Y_1$  to be computed separately

We only need  $W = X_1 \cdot Y_2 + X_2 \cdot Y_1$

Can we compute  $W$  with one extra recursive call?

$$(X_1 - X_2) \cdot (Y_1 - Y_2) = X_1 \cdot Y_1 - (X_1 \cdot Y_2 + X_2 \cdot Y_1) + X_2 \cdot Y_2$$

```

R1 ← Multiply(X1, Y1)
R2 ← Multiply(X2, Y2)
R3 ← Multiply(X1 - X2, Y1 - Y2)
  
```

Then:  $W = R_1 + R_2 - R_3$



**Multiply**( $X[1..n]$ ,  $Y[1..n]$ )

**if**  $n = 1$  **then**

**return**  $X \cdot Y$

$R_1 \leftarrow$  **Multiply**( $X_1$ ,  $Y_1$ )

$R_2 \leftarrow$  **Multiply**( $X_2$ ,  $Y_2$ )

$R_3 \leftarrow$  **Multiply**( $X_1 - X_2$ ,  $Y_1 - Y_2$ )

**return**  $10^n R_1 + 10^{\frac{n}{2}}(R_1 + R_2 - R_3) + R_2$  Solves to

$M(n)$  = number of single-digit multiplications in this procedure

$$M(n) = 3M\left(\frac{n}{2}\right) + \Theta(1)$$

$$M(1) = \Theta(1)$$

$$M(n) = \Theta(n^{\log_2 3}) = O(n^{1.585})$$

(See Master's Theorem)



## Notes

- Actual runtime also includes additions, copying arrays, and shifting arrays.

$T(n)$  = worst-case runtime

$$T(n) = 3T\left(\frac{n}{2}\right) + O(n)$$

$$T(1) = \Theta(1)$$

Still solves to  $T(n) = \Theta(n^{\log_2 3})$

- What if  $n$  is not divisible by 2?

There exists  $n \leq n' \leq 2n$  such that  $n'$  is a power of 2

$$T(n) \leq T(n') = O\left((n')^{\log_2 3}\right) = O\left((2n)^{\log_2 3}\right) = O(n^{\log_2 3})$$



### d) Multiplying Square Matrices (§4.1-4.2)

**Input:** Three  $n \times n$  (square) matrices,  $A = (a_{ij})$ ,  $B = (b_{ij})$ , and  $C = (c_{ij})$ .

**Result:** The matrix product  $A \cdot B$  is added into  $C$ , so that

$$c_{ij} = c_{ij} + \sum_{k=1}^n a_{ik} \cdot b_{kj}$$

for  $i, j = 1, 2, \dots, n$ .

If only the product  $A \cdot B$  is needed, then zero out all entries of  $C$  beforehand.

#### Straightforward method

**Matrix-Multiply**( $A, B, C, n$ )

```

1: for  $i \leftarrow 1, n$  do
2:   for  $j \leftarrow 1, n$  do
3:     for  $k \leftarrow 1, n$  do
4:        $c_{ij} \leftarrow c_{ij} + a_{ik} \cdot b_{kj}$ 
    
```



### Simple Divide-and-Conquer Algorithm

For simplicity, assume that  $C$  is initialized to 0, so computing  $C = A \cdot B$ .

If  $n > 1$ , partition each of  $A, B, C$  into four  $n/2 \times n/2$  matrices:

$$A = \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix}, \quad B = \begin{pmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{pmatrix}, \quad C = \begin{pmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{pmatrix}.$$

Rewrite  $C = A \cdot B$  as

$$\begin{pmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{pmatrix} = \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} \cdot \begin{pmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{pmatrix}$$

giving the four equations

$$\begin{aligned}
 C_{11} &= A_{11} \cdot B_{11} + A_{12} \cdot B_{21} \\
 C_{12} &= A_{11} \cdot B_{12} + A_{12} \cdot B_{22} \\
 C_{21} &= A_{21} \cdot B_{11} + A_{22} \cdot B_{21} \\
 C_{22} &= A_{21} \cdot B_{12} + A_{22} \cdot B_{22}
 \end{aligned}$$

Each of these equations multiplies two  $n/2 \times n/2$  matrices and then adds their  $n/2 \times n/2$  products. Assume that  $n$  is an exact power of 2, so that submatrix dimensions are always integer.



Use these equations to get a divide-and-conquer algorithm:

### Matrix-Multiply-Recursive( $A, B, C, n$ )

```

1: if  $n = 1$  then                                ▷ Base case.
2:    $c_{11} \leftarrow c_{11} + a_{11} \cdot b_{11}$ 
3:   return
4: partition  $A, B$ , and  $C$  into                      ▷ Divide.
5:  $n/2 \times n/2$  submatrices  $A_{ij}, B_{ij}, C_{ij}, i, j = 1, 2$ 
6:                                     ▷ Conquer.
7: Matrix-Multiply-Recursive( $A_{11}, B_{11}, C_{11}, n/2$ )
8: Matrix-Multiply-Recursive( $A_{11}, B_{12}, C_{12}, n/2$ )
9: Matrix-Multiply-Recursive( $A_{21}, B_{11}, C_{21}, n/2$ )
10: Matrix-Multiply-Recursive( $A_{21}, B_{12}, C_{22}, n/2$ )
11: Matrix-Multiply-Recursive( $A_{12}, B_{21}, C_{11}, n/2$ )
12: Matrix-Multiply-Recursive( $A_{12}, B_{22}, C_{12}, n/2$ )
13: Matrix-Multiply-Recursive( $A_{22}, B_{21}, C_{21}, n/2$ )
14: Matrix-Multiply-Recursive( $A_{22}, B_{22}, C_{22}, n/2$ )
    
```

#### Aside:

The book briefly discusses the question of how to avoid copying entries when partitioning matrices. Can partition matrices without copying entries by instead using index calculations.

### Analysis

Let  $T(n)$  be the time to multiply two  $n \times n$  matrices.

**Base case:**  $n = 1$ . Perform one scalar multiplication:  $\Theta(1)$ .

**Recursive case:**  $n > 1$ .

- Dividing takes  $\Theta(1)$  time, using index calculations. [Otherwise,  $\Theta(n^2)$  time.]
- Conquering makes 8 recursive calls, each multiplying  $n/2 \times n/2$  matrices  $\implies 8T(n/2)$ .
- No combine step, because  $C$  is updated in place.

Recurrence (omitting the base case) is  $T(n) = 8T(n/2) + \Theta(1)$ . Can use master method to show that it has solution  $T(n) = \Theta(n^3)$ .

## Bushiness of recursion trees:

Compare this recurrence with the **Merge-Sort** recurrence  $T(n) = 2T(n/2) + \Theta(n)$ . If we draw out the recursion trees, the factor of 2 in the merge-sort recurrence says that each non-leaf node has 2 children.

But the factor of 8 in the recurrence  $T(n) = 8T(n/2) + \Theta(1)$  for **Matrix-Multiply-Recursive** says that each non-leaf node has 8 children. Get a bushier tree with many more leaves, even though internal nodes have a smaller cost ( $\Theta(1)$  versus  $\Theta(n)$ ).



## Strassen's Algorithm

**Idea:** Make the recursion tree less bushy. Perform only 7 recursive multiplications of  $n/2 \times n/2$  matrices, rather than 8. Will cost several additions/subtractions of  $n/2 \times n/2$  matrices.

Since a subtraction is a “negative addition,” just refer to all additions and subtractions as additions.

**Example of reducing multiplications:** Given  $x$  and  $y$ , compute  $x^2 - y^2$ . Obvious way uses 2 multiplications and one subtraction. But observe:

$$x^2 - y^2 = x^2 - xy + xy - y^2 = x(x - y) + y(x - y) = (x + y)(x - y)$$

So, at the expense of one extra addition, can get by with only 1 multiplication. Not a big deal if  $x, y$  are scalars, but can make a difference if they are matrices.



## The algorithm:

- 1 If  $n = 1$ , the matrices each contain a single element. Perform a single scalar multiplication and a single scalar addition, as in line 2 of **Matrix-Multiply-Recursive**, taking  $\Theta(1)$  time, and return.
- 2 When  $n > 1$ , partition the input matrices  $A$  and  $B$  and output matrix  $C$  into  $n/2 \times n/2$  submatrices, as in line 2 of **Matrix-Multiply-Recursive**. This step takes  $\Theta(1)$  time by index calculation, just as in **Matrix-Multiply-Recursive**.
- 3 Create  $n/2 \times n/2$  matrices  $S_1, S_2, \dots, S_{10}$ , each of which is the sum or difference of two submatrices from steps 1 and 2. Create and zero the entries of seven  $n/2 \times n/2$  matrices  $P_1, P_2, \dots, P_7$  to hold seven  $n/2 \times n/2$  matrix products. All 17 matrices can be created, and the  $P_i$  initialized, in  $\Theta(n^2)$  time.



## The algorithm, cont.:

- 4 Using the submatrices from steps 1 and 2 and the matrices  $S_1, S_2, \dots, S_{10}$  created in step 3, recursively compute each of the seven matrix products  $P_1, P_2, \dots, P_7$ , taking  $7T(n/2)$  time.
- 5 Update the four submatrices  $C_{11}, C_{12}, C_{21}, C_{22}$  of the result matrix  $C$  by adding or subtracting various  $P_i$  matrices, which takes  $\Theta(n^2)$  time.

## Analysis

Recurrence will be  $T(n) = 7T(n/2) + \Theta(n^2)$ . By the master method, solution is  $T(n) = \Theta(n^{\lg 7})$ . Since  $\lg 7 < 2.81$ , the running time is  $O(n^{2.81})$ , beating the  $\Theta(n^3)$ -time algorithms.



## Details

### Step 3: Create the 10 matrices

$$\begin{aligned}
 S_1 &= B_{12} - B_{22} , \\
 S_2 &= A_{11} + A_{12} , \\
 S_3 &= A_{21} + A_{22} , \\
 S_4 &= B_{21} - B_{11} , \\
 S_5 &= A_{11} + A_{22} , \\
 S_6 &= B_{11} + B_{22} , \\
 S_7 &= A_{12} - A_{22} , \\
 S_8 &= B_{21} + B_{22} , \\
 S_9 &= A_{11} - A_{21} , \\
 S_{10} &= B_{11} + B_{12} .
 \end{aligned}$$

Add or subtract  $n/2 \times n/2$  matrices 10 times  $\Rightarrow$  time is  $\Theta(n^2)$ .



## Details, cont.

### Step 4: Compute the 7 matrices

$$\begin{aligned}
 P_1 &= A_{11} \cdot S_1 = A_{11} \cdot B_{12} - A_{11} \cdot B_{22} , \\
 P_2 &= S_2 \cdot B_{22} = A_{11} \cdot B_{22} + A_{12} \cdot B_{22} , \\
 P_3 &= S_3 \cdot B_{11} = A_{21} \cdot B_{11} + A_{22} \cdot B_{11} , \\
 P_4 &= A_{22} \cdot S_4 = A_{22} \cdot B_{21} - A_{22} \cdot B_{11} , \\
 P_5 &= S_5 \cdot S_6 = A_{11} \cdot B_{11} + A_{11} \cdot B_{22} + A_{22} \cdot B_{11} + A_{22} \cdot B_{22} , \\
 P_6 &= S_7 \cdot S_8 = A_{12} \cdot B_{21} + A_{12} \cdot B_{22} - A_{22} \cdot B_{21} - A_{22} \cdot B_{22} , \\
 P_7 &= S_9 \cdot S_{10} = A_{11} \cdot B_{11} + A_{11} \cdot B_{12} - A_{21} \cdot B_{11} - A_{21} \cdot B_{12} .
 \end{aligned}$$

The only multiplications needed are in the middle column; right-hand column just shows the products in terms of the original submatrices of  $A$  and  $B$ .



Details, cont.

Step 5: Add and subtract the  $P_i$  to construct submatrices of  $C$ :

$$\begin{aligned}
C_{11} &= P_5 + P_4 - P_2 + P_6, \\
C_{12} &= P_1 + P_2, \\
C_{21} &= P_3 + P_4, \\
C_{22} &= P_5 + P_1 - P_3 - P_7.
\end{aligned}$$



Example

Example of how  $C_{11}$  is reconstructed using additions and the previously defined  $P$  and  $S$  matrices. Recall definition of  $C_{11}$ :  $C_{11} = P_5 + P_4 - P_2 + P_6$ . Expanding the right-hand side:

$$\begin{array}{rcl}
& A_{11} \cdot B_{11} + A_{11} \cdot B_{22} + A_{22} \cdot B_{11} + A_{22} \cdot B_{22} & \\
& \qquad \qquad \qquad - A_{22} \cdot B_{11} & + A_{22} \cdot B_{21} \\
& \qquad \qquad \qquad - A_{11} \cdot B_{22} & \qquad \qquad \qquad - A_{12} \cdot B_{22} \\
& \qquad \qquad \qquad \qquad \qquad \qquad - A_{22} \cdot B_{22} - A_{22} \cdot B_{21} + A_{12} \cdot B_{22} + A_{12} \cdot B_{21} & \\
\hline
A_{11} \cdot B_{11} & & + A_{12} \cdot B_{21}
\end{array}$$

All four examples are fully worked out in the text.





Notes

Strassen’s algorithm was the first to beat  $\Theta(n^3)$  time, but it’s not the asymptotically fastest known. A method by Coppersmith and Winograd runs in  $\Theta(n^{2.376})$  time. Current best asymptotic bound (not practical) is  $\Theta(n^{2.37286})$ .

Practical issues against Strassen’s algorithm:

- Higher constant factor than the obvious  $\Theta(n^3)$ -time method.
- Not good for sparse matrices.
- Not numerically stable: larger errors accumulate than in the obvious method.
- Submatrices consume space, especially if copying.

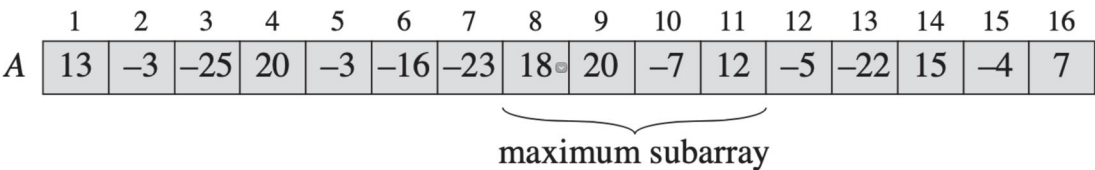


e) Maximum Subarray Problem (§4.1 of 3rd Ed. of CLRS; not in 4th Ed.)

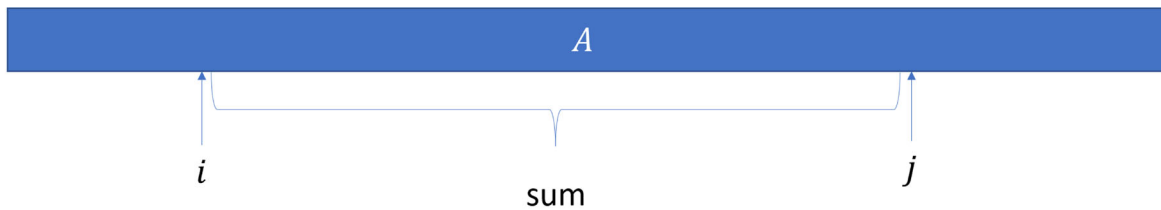
**Input:**     $A[1..n]$  - array of  $n$  integers

**Output:**    $S$  - maximum sum of a contiguous subarray, i.e., there exists  $1 \leq i < j \leq n$  such that  $S = \sum_{k=i}^j A[k]$  and  $S$  is maximized

Example:



## Naive Algorithm



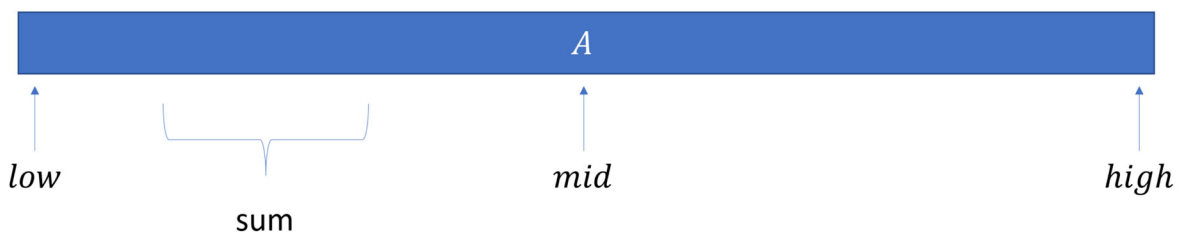
Check every pair of indices  $1 \leq i < j \leq n$

Even if we can compute each such sum in constant time there are still  $\binom{n}{2} = \Theta(n^2)$  such pairs of indices  $i$  and  $j$

Naive algorithm runs in time  $\Omega(n^2)$

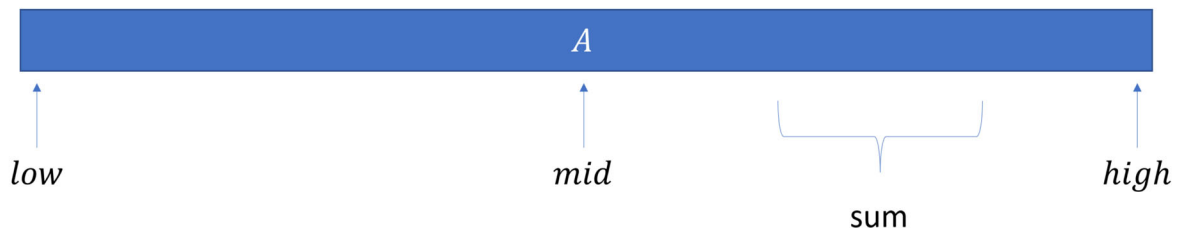


## A Divide and Conquer Algorithm

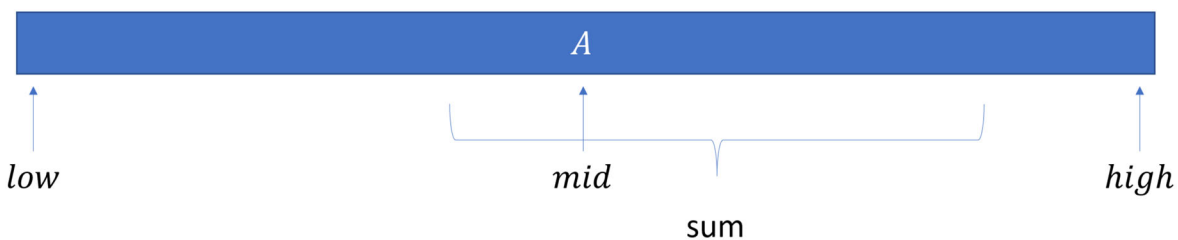


If maximum subarray  $A[i..j]$  doesn't cross  $mid$   
 then it entirely lies in  $A[low..mid]$





If maximum subarray  $A[i..j]$  doesn't cross  $mid$   
 then it entirely lies in  $A[low..mid]$   
 or it entirely lies in  $A[mid + 1..high]$



If maximum subarray  $A[i..j]$  doesn't cross  $mid$   
 then it entirely lies in  $A[low..mid]$   
 or it entirely lies in  $A[mid + 1..high]$   
 OR maximum subarray crosses  $mid$



### MaxCrossingSubarray( $A, low, mid, high$ )

```

 $L \leftarrow -\infty; R \leftarrow -\infty$ 
 $S \leftarrow 0$ 
for  $i \leftarrow mid, low$  do                                ▷ find max sum to left starting at  $A[mid]$ 
     $S \leftarrow S + A[i]$ 
     $L \leftarrow \max(L, S)$ 
 $S \leftarrow 0$ 
for  $i \leftarrow mid + 1, high$  do                        ▷ find max sum to right starting at  $A[mid + 1]$ 
     $S \leftarrow S + A[i]$ 
     $R \leftarrow \max(R, S)$ 
return  $L + R$ 
    
```

Observe that the body of the function does  $O(n)$  work.



### MaxSubarray( $A, mid, high$ )

```

if  $high = low + 1$  then
    return  $A[low] + A[high]$ 
if  $high \leq low$  then
    return  $-\infty$ 
 $mid \leftarrow \left\lfloor \frac{low + high}{2} \right\rfloor$ 
 $left \leftarrow \text{MaxSubarray}(A, low, mid)$ 
 $right \leftarrow \text{MaxSubarray}(A, mid + 1, high)$ 
 $cross \leftarrow \text{MaxCrossingSubarray}(A, low, mid, high)$ 
return  $\max(left, cross, right)$ 
    
```

Initial call: **MaxSubarray**( $A, 1, n$ )

$T(n)$  = worst-case runtime on instances of length  $n$

**MaxSubarray** on input of length  $n$ :

- make 2 recursive calls on inputs of size  $n/2$
- does additional  $O(n)$  work

Thus,  $T(n) = 2T\left(\frac{n}{2}\right) + O(n)$

Base cases:  $T(0), T(1), T(2) = O(1)$

Therefore,  $T(n) = O(n \log n)$



## e) Quick-Sort: (§7)

Quicksort is based on the three-step process of divide-and-conquer.

To sort the subarray  $A[p..r]$ :

**Divide:** Partition  $A[p..r]$  in two (possibly empty) subarrays  $A[p..q-1]$  and  $A[q+1..r]$ , such that each element in the first subarray  $A[p..q-1]$  is  $\leq A[q]$  and  $A[q]$  is  $<$  each element in the second subarray  $A[q+1..r]$ .

**Conquer:** Sort the two subarrays by recursive calls to **Quicksort**.

**Combine:** No work is needed to combine the subarrays, because they are sorted *in place*.

The Divide step is performed using a procedure **Partition**, which returns the index  $q$  that marks the position separating the subarrays.



**Quicksort**( $A, p, r$ )

\\ Sort  $A[p]$  to  $A[r]$

**if**  $p < r$  **then**      ▷ at least 2 values

$q = \text{Partition}(A, p, r)$

    \\ partition  $A$  into two subarrays

    \\ such that  $A[i] \leq A[q]$  for  $i < q$

    \\ and  $A[q] < A[j]$  for  $q < j$

**Quicksort**( $A, p, q-1$ )

**Quicksort**( $A, q+1, r$ )

**Best case:**

$a = 2,$

$b = 2,$

$D(n) = \Theta(n),$

$C(n) = \Theta(1).$

$T(n) = 2T(n/2) + \Theta(n)$  if  $n \geq 1$

$T(n) = 2T(n/2) + cn$  if  $n \geq 1$

$T(n) = \Theta(n \log n)$



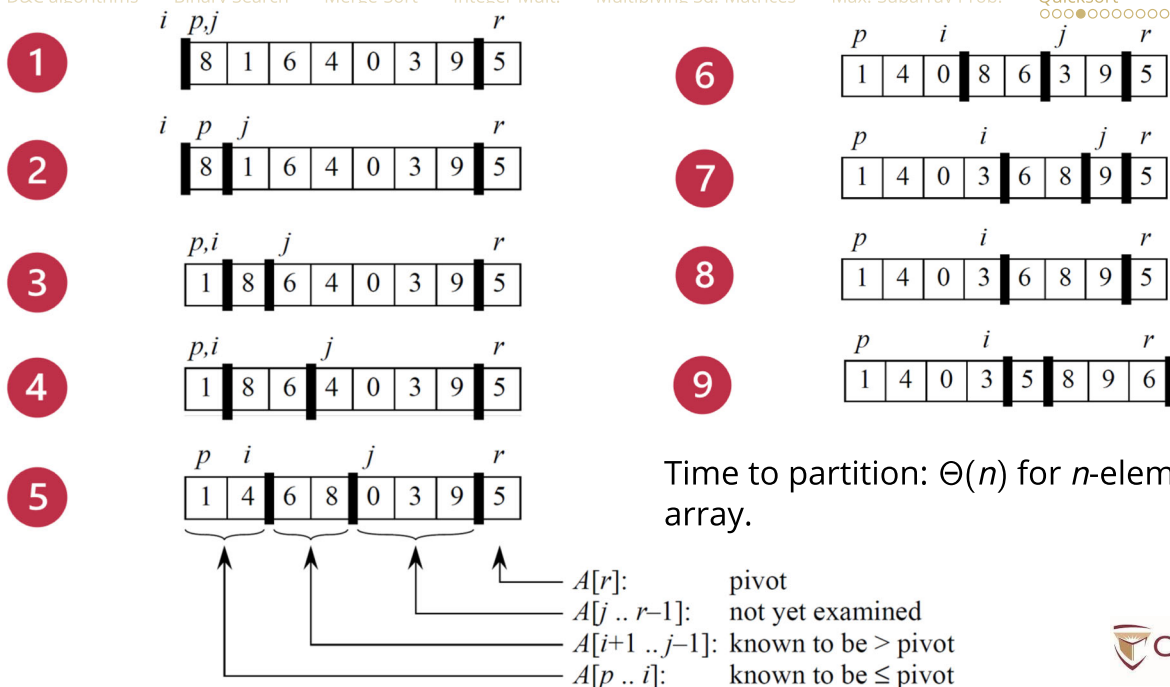
## Partitioning

Partitioning of the subarray  $A[p..r]$  is done by selection one element of the array  $A$  as a **pivot** and this element splits that array into two parts.

### Partition( $A, p, r$ )

```

 $x \leftarrow A[r]$  // the last element is selected as the pivot
 $i \leftarrow p - 1$ 
for  $j \leftarrow p, r - 1$  do
    if  $A[j] \leq x$  then                ▷ All elements  $\leq$  pivot moved to the front
         $i \leftarrow i + 1$ 
        exchange  $A[i]$  with  $A[j]$ 
exchange  $A[i + 1]$  with  $A[r]$ 
return  $i + 1$  // new index of pivot
    
```



## Worst case:

$a = 2$ , (one of two subproblems is empty and the other is of size  $n - 1$ )

$$D(n) = \Theta(n),$$

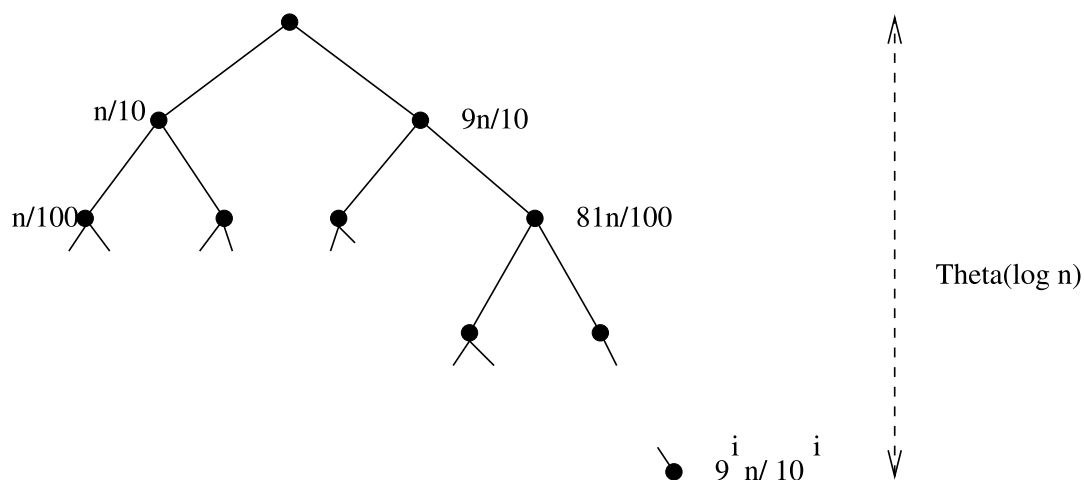
$$C(n) = \Theta(1).$$

$$T(n) = T(n - 1) + T(0) + cn \text{ if } n \geq 1$$

$$T(n) = \Theta(n^2)$$

## What is the **average case**?

Even when the split produces 9/10 elements in one subarray and 1/10 in the other subarray *all the time*, the number of levels in the calls is bounded by  $\Theta(\log n)$ .



We need to repeat the splitting at most  $\log_{10/9} n$  times.

$$\text{Thus, } T(n) = \Theta(n \log n)$$



How to guarantee that we get a “good split” often enough?

## Randomized Quicksort

a) Select the pivot randomly:

In the partition function, generate a random number  $i, p \leq i \leq r$  and swap  $A[i]$  with  $A[r]$  to be used as the pivot.

b) OR before applying Quicksort, permute the elements of the array in random manner:

Assume **Random**( $i, n$ ) is a function that selects an integer between  $i$  and  $n$  with the same probability (e.g., a uniform distribution random function).

### Randomize-In-Place( $A$ )

```

 $n \leftarrow A.length()$ 
for  $i \leftarrow 1, n$  do
  swap( $A[i], A[\text{Random}(i, n)]$ )
  
```



### In Randomize-in-Place:

No additional space is required.

Run time is  $\Theta(n)$ .

Does it produce a random permutation?

Yes, if **Random** is correct:

- Notice that once an element is swapped in position  $A[i]$ , it is not swapped again, the probability of any element being the first is  $1/n$ , any of the remaining element has the same probability of being second, etc.

This procedure is often used for any algorithm when the average run-time of the algorithm is much better than the worst case.

Warning: It is easy to write an incorrect version of randomize!

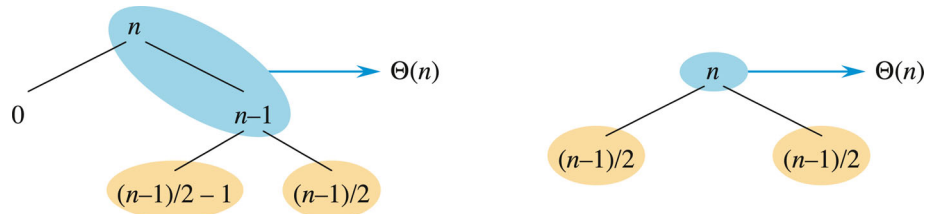




## Intuition for the Average Case

Splits in the recursion tree will not always be constant. There will usually be a mix of good and bad splits throughout the recursion tree.

To see that this doesn't affect the asymptotic running time of quicksort, assume that levels alternate between best-case and worst-case splits.



The extra level in the left-hand figure only adds to the constant hidden in the  $\Theta$ -notation.

There are still the same number of subarrays to sort, and only twice as much work was done to get to that point.



## Theorem

The expected running time of randomized quicksort on a sequence of size  $n$  is  $O(n \log n)$ .

### Proof

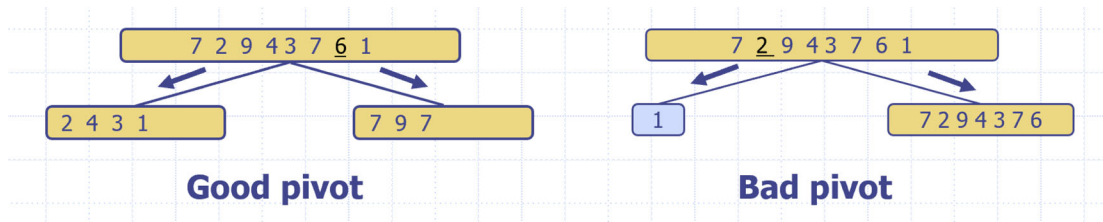
We use the following fact:

*The expected number of times that a fair coin must be flipped until it shows "heads"  $k$  times is  $2k$ .*

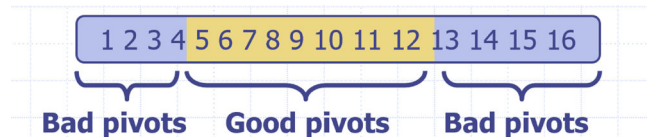
In the randomized quicksort, the probability of getting a split of  $m$  elements with at least  $m/4$  elements in one part and at most  $3m/4$  elements in the other is  $1/2$ . (call this a good split using a good pivot)



Examples:



The probability of getting a good split is  $1/2$ .



The expected number of times splitting should be repeated to get a good split  $\log_{4/3} n$  times is  $2 \log_{4/3} n$ .

Expected run-time is  $O(n \log n)$



## Theorem (§8.1)

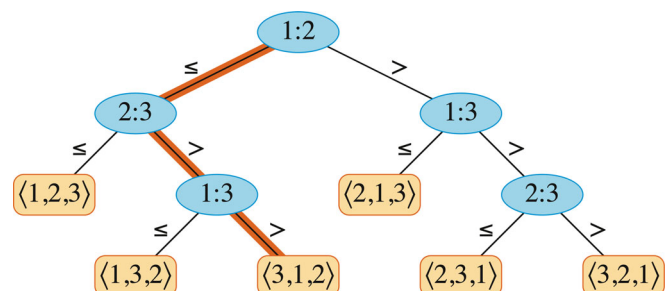
Any comparison-based sorting algorithm requires  $\Omega(n \log n)$  comparisons to sort  $n$  elements in the worst case.

### Proof

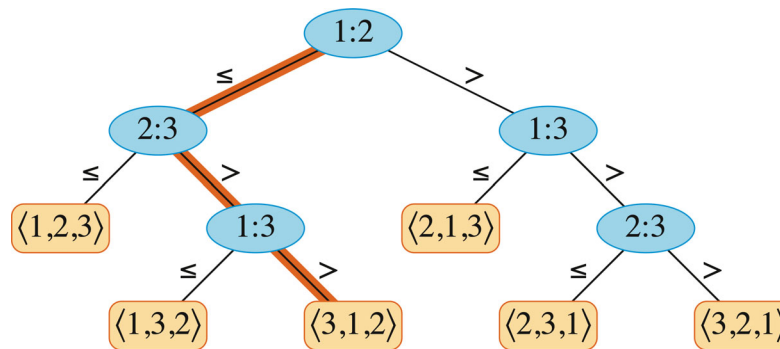
Consider a decision tree corresponding to a comparison-based sorting algorithm.

Each leaf of the decision tree corresponds to one of the permutations of the input.

A path from the root to a leaf correspond to a possible execution of the algorithm.



## Proof, cont.



There are  $n!$  possible permutations of  $n$  elements.

The decision tree must have  $n!$  leafs,

its depth is  $\geq \log n! \approx \log \sqrt{2\pi n} \frac{n^n}{e^n} = cn \log n$



## Sorting faster than $\Theta(n \log n)$ ?

Are there some sorting algorithms that can “beat” the  $\Theta(n \log n)$  barrier of comparison-based algorithms?

We can do better if we know something about either

- the distribution of elements to be sorted, or
- the elements to be sorted.

Radix-sort and similar algorithms (see the textbook if you are not familiar with them):

Their run-time to sort  $n$  elements is  $\Theta(kn)$

where  $k$  is the maximal length of the *keys* used for sorting.

It is better when  $k$  is smaller than  $\log n$  ( $\log n$  is the minimum number of bits to represent  $n$  numbers).

