

Muhammad Mursaleen

Mechatronics Engineer
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Objective

I want to be an entrepreneur so that I can contribute in the prosperity of my beloved country. In the initial of my career, I want to be able to utilize my knowledge and skills, in a responsible and appropriate manner resulting in a value add to the organization and to enhance my knowledge and expertise.

■ Work Experience

July 2017 - August 2017

Chakwal

Heritage International College Chakwal

Lecturer

- Basic Electronics
- Applied Physics

June 2016 - August 2016

Islamabad

Intern

ATS ENGINEERING

- Solar Home Solution Installation and Troubleshooting
- Solar Water Pump Solution Installation and Troubleshooting

Education

August 2014 - July 2018

Chakwal

University of Engineering and Technology Taxila Sub Campus Chakwal

BSc Mechatronics Engineering

• CGPA 3.24

• Design, Control and Implementation of Orthotic Arm (*Final Year Project*)

July 2012 - July 2014

Chakwal

Kallar Kahar Science College Kallar Kahar

Passed with A-1 Grade

HSSC (Pre Engineering)

■ Key Skills

> Software Tools

- Auto CAD
- Matlab

Dev-Cpp

- Lab View
- Proteous

Arduino

Computer Languages

- C++
- Python
- > Jobs Skills
 - Leader Ship
- Time Management
- Multi-tasking

Anaconda

- Creativity
- Strong interpersonal skill to work effectively with diverse communities/cultures.
- Languages
 - English
- Urdu
- Punjabi

■ Awards & Activities

•	Best Engineering Design Award	NERC'18 Robotics Competition	College of EME-Nust	July 2018
•	Winner of Roboline	RoboTron'18 Robotics Competition	UET Chakwal	May 2018
•	Winner of Maze Solver	APTO'18 Robotics Competition	UET Taxila	April 2018
•	Winner of Roboline	TechnoScience'18 Robotics Competition	UET Faisalabad	April 2018
•	Best Design Airbot Award	Air TECH'17 Robotics Competition	Air University	Dec 2017
•	Best Engineering Design Award	NERC'17 Robotics Competition	College of EME-Nust	Aug 2017

Projects

> Design, Control and Implementation of Orthotic Arm (Final Year Project)

It was design to assist the patients for rehabilitation and to support the weak persons to achieve their routine work. The input signal that was used to actuate the particular motion was based on electromyography (EMG) signals.

➤ Autonomous Robots (Robotics Competitions)

I have designed many autonomous robots based on artificial intelligence. Their basic operations are to pick a product from a specific place and place it to a targeted place or to solve a maze by using **line following, wall following, distance through walls and colors detection techniques** based on artificial intelligence. By following this passion, I have won several national Robotics Competitions.

Extra-curricular Activities

> Sports

- Table Tennis
- Volley Ball (Captain)
- Tug of War (Captain)

Societies

•	Technical Head	Mechatronics Club	UET Chakwal
•	Member	Environmental Protection Society	UET Chakwal

> Achievements

•	Winner	Double Table Tennis	UET Chakwal	2018
•	Winner	Double Table Tennis	UET Chakwal	2017
•	Winner	Tug of War (Captain)	UET Chakwal	2016
•	Runner-up	Tug of War (Captain)	UET Chakwal	2015

Interest

Robotics and Automation
 Energy Solutions Technology
 Business