ETC3250/5250: Regression Trees

Semester 1, 2020

Professor Di Cook

Econometrics and Business Statistics Monash University Week 6 (b)

Predicting Salary

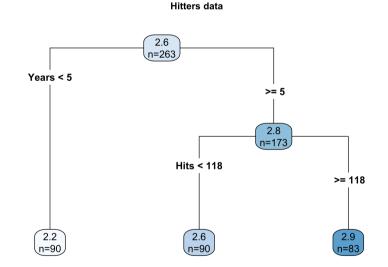
Using the function rpart, we can build a regression tree to predict the logSalary of a baseball player, given their Years of playing and number of Hits.

```
## n= 263
##
## node), split, n, deviance, yval
##     * denotes terminal node
##
## 1) root 263 39.071620 2.574160
## 2) Years< 4.5 90 7.988302 2.217851 *
## 3) Years>=4.5 173 13.713070 2.759523
## 6) Hits< 117.5 90 5.298802 2.605063 *
## 7) Hits>=117.5 83 3.938792 2.927009 *
```

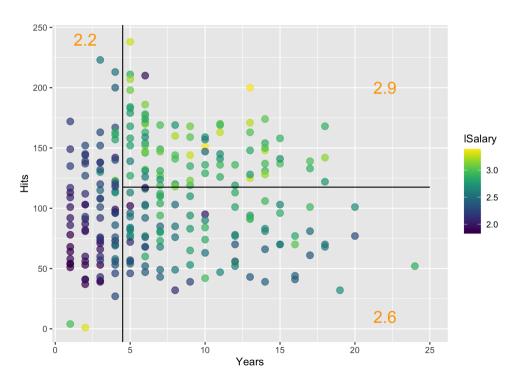
Predicting Salary

Using the function rpart, we can build a regression tree to predict the logSalary of a baseball player, given their Years of playing and number of Hits.

rpart.plot can be used to visualise the fitted tree.

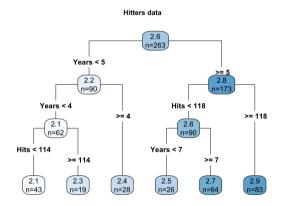


Regions of the decision tree

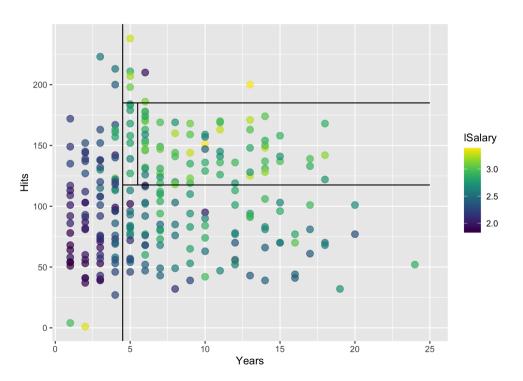


Deeper trees

By decreasing the value of the complexity parameter **cp**, we can build deeper trees.



Regions



Regression trees - construction

We divide the predictor space - that is, the set of possible values for X_1, X_2, \ldots, X_p - into J distinct and non-overlapping regions, R_1, R_2, \ldots, R_M .

The regions could have any shape. However, for simplicity and for ease of interpretation, we divide the predictor space into high-dimensional rectangles.

lacktriangle We model the response as a constant c_i in each region

$$f(x) = \sum_{j=1}^J c_j \ I(x \in R_m)$$

e.g.

$$R_1 = \{X | \text{Years} < 4.5\} R_2 = \{X | \text{Years} \ge 4.5, \text{Hits} < 117.5\}$$

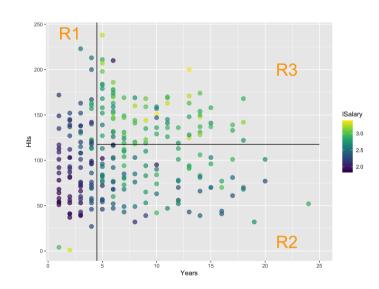
 $R_3 = \{X | \text{Years} \ge 4.5, \text{Hits} \ge 117.5\}$

Leaves and Branches

 R_1, R_2, R_3 are terminal nodes or leaves.

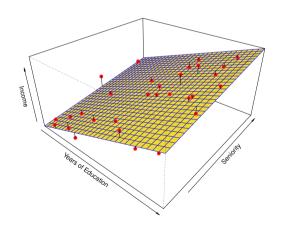
The points where we split are internal nodes.

The segments that connect the nodes are branches.



Linear regression

$$f(X)=eta_0+\sum_{j=1}^p X_jeta_j$$



Regression trees

$$f(X) = \sum_{m=1}^M c_m \ I(X \in R_m)$$

Determining the c_m values and splits

Q1) Given a partition R_1,R_2,\ldots,R_M , what are the optimal values of c_m if we want to minimize $\sum_i (y_i-f(x_i))^2$ (the MSE)?

Q2) How do we construct the regions R_1, \ldots, R_M ?

Determining the c_m values and splits

Q1) Given a partition R_1, R_2, \ldots, R_M , what are the optimal values of c_m if we want to minimize $\sum_i (y_i - f(x_i))^2$ (the MSE)?

The best c_m is just the average of y_i in region R_m : $\hat{c}_m = \operatorname{average}(y_i|x_i \in R_m)$.

Q2) How do we construct the regions R_1, \ldots, R_M ?

Finding the best binary partition in terms of minimum sum of squares is generally *computationally infeasible*. For this reason, we take a *top-down*, *greedy* approach that is known as recursive binary splitting.

Strategy for finding good splits

Top-down: it begins at the top of the tree (all observations belong to a single region) and then successively splits the predictor space; each split is indicated via two new branches further down on the tree.

Greedy: at each step of the tree-building process, the best split is made at that particular step, rather than looking ahead and picking a split that will lead to a better tree in some future step.

Algorithm

- 1. Start with a single region R_1 (entire input space), and iterate:
 - a. Select a region R_m , a predictor X_j , and a splitting point s, such that splitting R_m with the criterion $X_j < s$ produces the largest decrease in RSS
 - b. Redefine the regions with this additional split.
- 2. Continues until stopping criterion reached.

Stopping criterion

```
In N_m < a: Number of observations in R_m is too small to further splitting (minsplit). (There is usually another control criteria, even if N_m is large enough, you can't split it small number of observations off, e.g. 1 and N_m - 1, minbucket.)
```

RSS < tol: If reduction of error is too small to bother splitting further. (cp parameter in rpart measures this as a proportional dropsee earlier examples displaying the change in this parameter.)

Diagnostics

Residual Sum of Squared Error

$$ext{RSS}(T) = \sum_{m=1}^{|T|} N_m Q_m(T), \;\; N_m = \#\{x_i \in R_m\},$$

where $Q_m(T)=rac{1}{N_m}\sum_{x_i\in R_m}(y_i-\hat{c}_m)^2$ and |T| is the number of terminal nodes in T.

Size of tree

It is possible to produce good predictions on the **training set**, but is likely to overfit the data (trees are very flexible).

Lill A smaller tree with fewer splits (that is, fewer regions) might lead to lower variance and better interpretation at the cost of a little bias.

Lill Tree size is a tuning parameter governing the model's complexity, and the optimal tree size should be adaptively chosen from the data

Lill Produce splits only if RSS decrease exceeds some (high) threshold can mean that a low gain split early on, might stop the fitting, even though there may be a very good split later.

Pruning

Grow a big tree, T_0 , and then **prune** it back. The *pruning* procedure is:

In Starting with with the initial full tree T_0 , replace a subtree with a leaf node to obtain a new tree T_1 . Select subtree to prune by minimizing

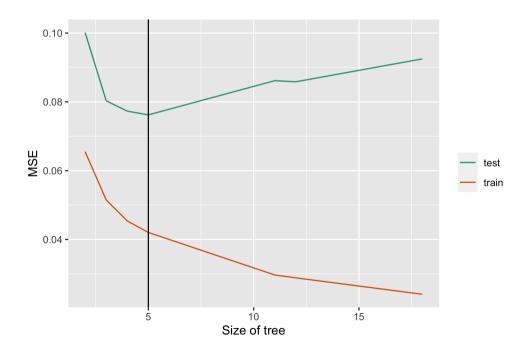
$$\frac{\mathrm{RSS}(T_1) - \mathrm{RSS}(T_0)}{|T_1| - |T_0|}$$

Iteratively prune to obtain a sequence $T_0, T_1, T_2, \ldots, T_R$ where T_R is the tree with a single leaf node.

lacktriangle Select the optimal tree T_m by cross validation

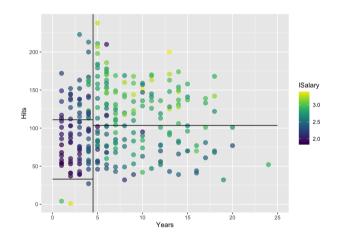
Model selection

Using a 50-50 training test set split.

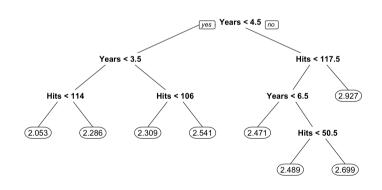


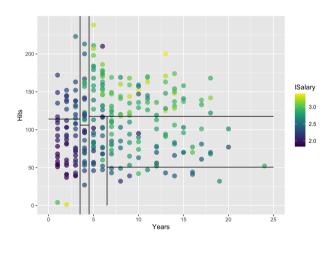
Yielding this model:





Cross-validation recommendation suggests more.







Made by a human with a computer

Slides at https://iml.numbat.space.

Code and data at https://github.com/numbats/iml.

Created using R Markdown with flair by xaringan, and kunoichi (female ninja) style.



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