

ETC3250/5250: Introduction to Machine Learning

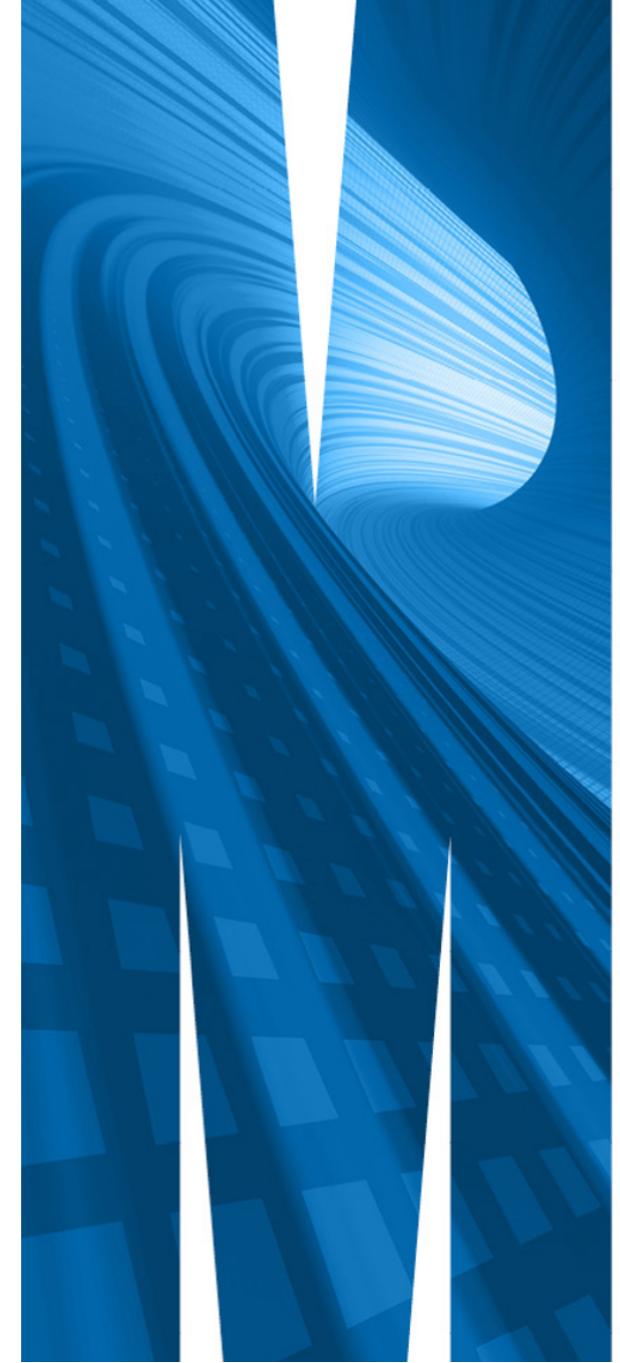
Visualisation of multivariate data

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CALENDAR
Week 5a



Why is visualisation important?

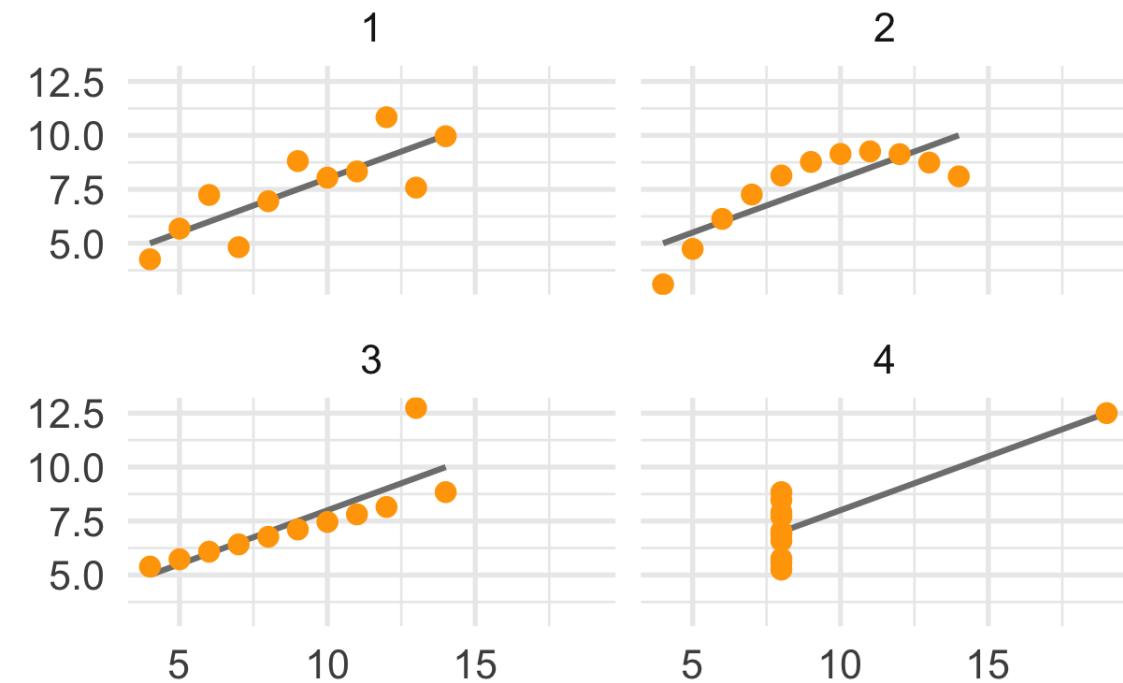
Consider the following datasets, known as [Anscombe's quartet](#), which all have the same numerical statistical summaries.

set	mx	my	sx	sy	r
1	9	7.5	3.32	2.03	0.82
2	9	7.5	3.32	2.03	0.82
3	9	7.5	3.32	2.03	0.82
4	9	7.5	3.32	2.03	0.82

Why is visualisation important?

Consider the following datasets, known as [Anscombe's quartet](#), which all have the same numerical statistical summaries.

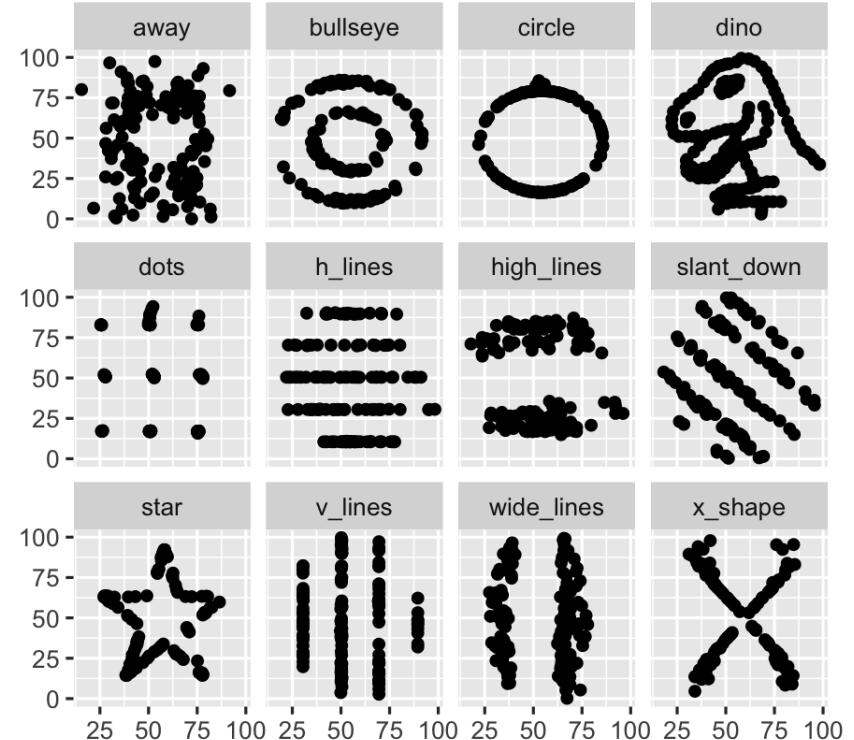
Plots provide a more detailed statistical summary.



Why is visualisation important?

Very **different data** can have the same numerical summaries.

Datasaurus dozen: all have the same means, standard deviations and correlation, also.



Why is visualisation important?

In machine learning visualisation is used for:

- **Initial data analysis**: to examine whether the data
 - satisfies assumptions required for the method
 - has unexpected complications like outliers or nonlinearity
- **Assess the model fit**:
 - predicted vs observed
 - residuals
 - boundaries between classes

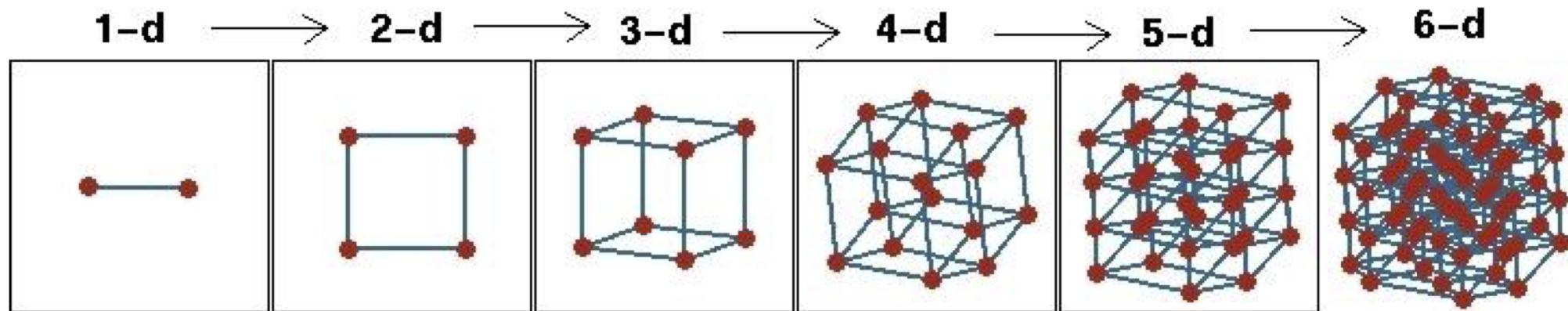
High dimensional visualisation

Common methods for visualising high-dimensions

- ➊ Tour
- ➋ Parallel coordinate plot
- ➌ Scatterplot matrix
- ➍ Mosaic plot

Most of what you find when you google "visualising high-dimensions" is awful, e.g. use colour and symbol after 3D to show 5D; PCA, MDS, tSNE, are visualisation methods; "you can't see beyond 3D".... Rubbish!

Dimensionality



- When you add another variable, you implicitly add another orthogonal axis.
- The space is effectively a p -dimensional cube
- The data might not fill the cube, and then dimension reduction might make it a $k (< p)$ -dimensional cube

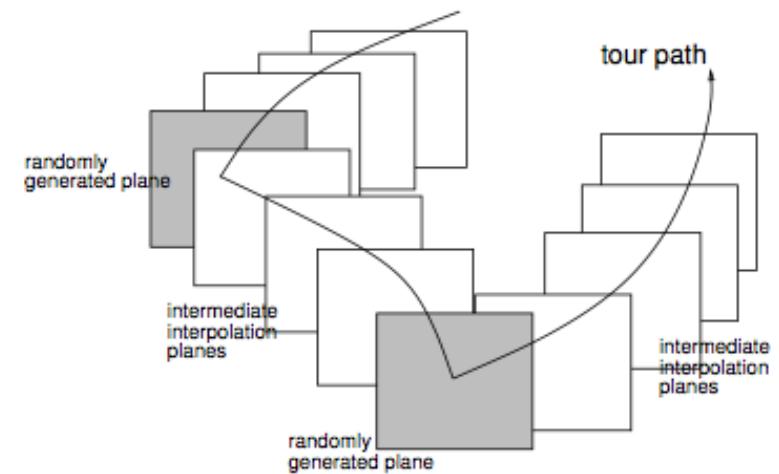
Grand tours

A **grand tour** is by definition a movie of low-dimensional projections constructed in such a way that it comes arbitrarily close to showing all possible low-dimensional projections; in other words, a grand tour is a space-filling curve in the manifold of low-dimensional projections of high-dimensional data spaces.



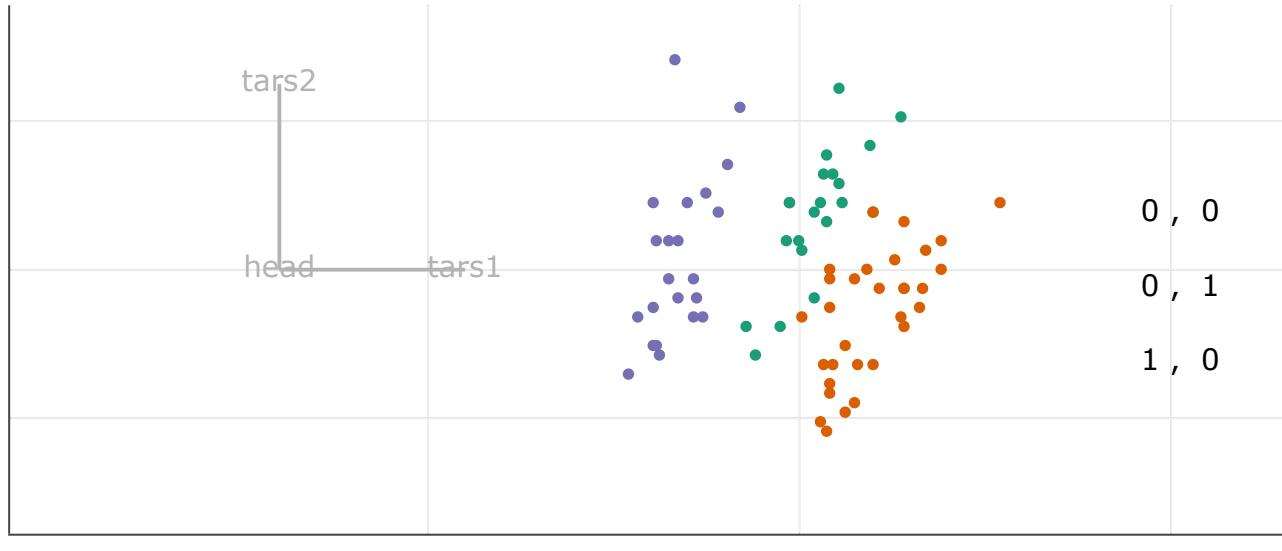
Notation

- $\mathbf{x}_i \in \mathcal{R}^p$, i^{th} data vector
- d projection dimension
- F is a $p \times d$ orthonormal basis, $F'F = I_d$
- The projection of \mathbf{x} onto F is $\mathbf{y}_i = F'\mathbf{x}_i$.
- Its a movie, so the tour is indexed by time, $F(t)$, where $t \in [a, z]$. Starting and target frame denoted as $F_a = F(a), F_z = F(t)$.
- The animation of the projected data is given by a path $\mathbf{y}_i(t) = F'(t)\mathbf{x}_i$.



Examples

$p = 3, d = 2$



Play

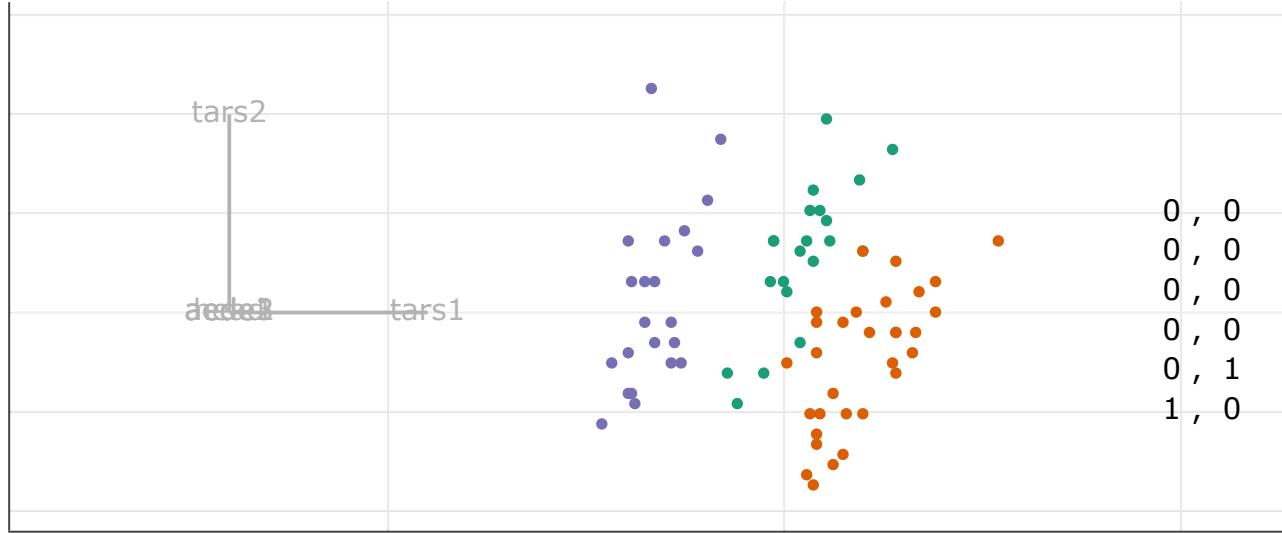


11 17 23 29 35 41 47 53 59 65 71 77 83 89 95 101 107 113

~indx: 11

Examples

$p = 6, d = 2$



Play

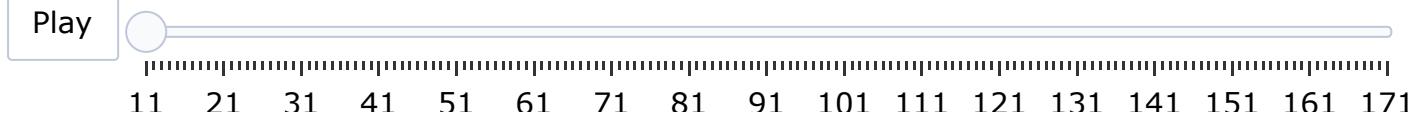
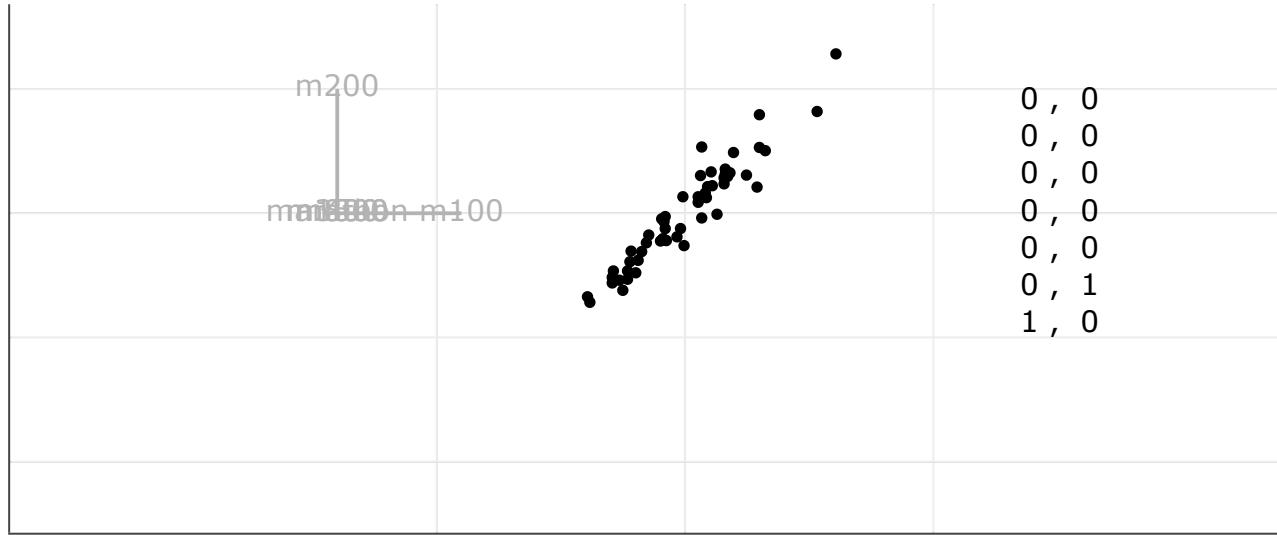


~indx: 11

11 20 29 38 47 56 65 74 83 92 101 110 119 128 137 146 155

Examples

$p = 7, d = 2$



Examples

With the grand tour, you can get a good overall sense of the distribution (shape) of the data in its p -dimensional space:

- In the first data set, the primary shape are **three well separated clusters**
- In the track data, the primary shape is that it lives in essentially a **1-D** subspace, with a small amount of variation in other directions. It is also possible to see several **outliers**.

Guided tours

Remember: projection pursuit

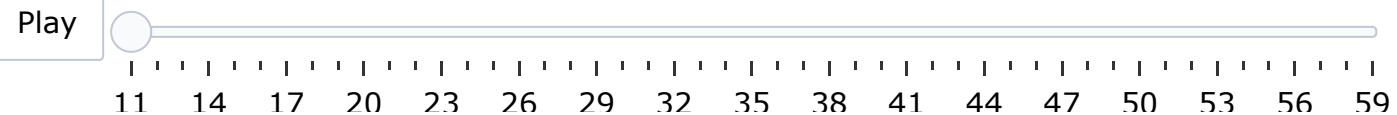
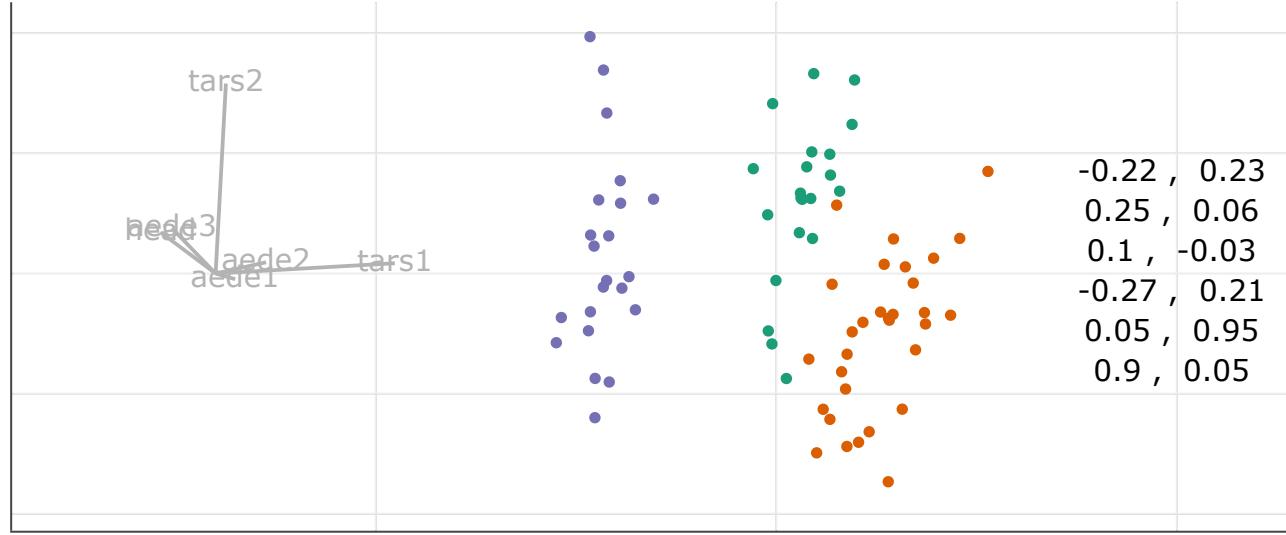
$$\underset{\phi_{11}, \dots, \phi_{p1}}{\text{maximize}} f \left(\sum_{j=1}^p \phi_{j1} x_{ij} \right) \text{ subject to } \sum_{j=1}^p \phi_{j1}^2 = 1$$

The guided tour chooses new target projections by optimising a function of interest:

- **holes**: This is an inverse Gaussian filter, which is optimised when there is not much data in the center of the projection, i.e. a "hole" or donut shape in 2D.
- **central mass**: The opposite of holes, high density in the centre of the projection, and often "outliers" on the edges.
- **LDA**: An index based on the linear discrimination dimension reduction, optimised by projections where the named classes are most separated.

Guided tours

$p = 6, d = 2$, guidance using the LDA index



Usage - in R

To run a tour live:

```
library(tourr)
# On a Mac use this graphics device
# quartz()
animate_xy(flea[, 1:6])
animate(flea[, 1:6], tour_path=grand_tour(),
       display=display_xy(axes = "bottomleft"))
library(RColorBrewer)
pal <- brewer.pal(3, "Dark2")
col <- pal[as.numeric(flea$species)]
animate_xy(flea[,-7], col=col)
```

Others

- **Little**: Interpolates between all possible pairs of variables. Like the scatterplot matrix, but animated between them.
- **Local**: Rocks back and forth from a given projection, so shows all possible projections within a radius.
- **Frozen**: Fixes some of the values of the orthonormal projection matrix and allows the others to vary freely according to any of the other tour methods.
- **Manual**: Control the contribution of a single variable, and move along this axis. This is really useful to examine the sensitivity of structure (e.g. clustering) to the contribution of a variable. Maybe the variable can be "zero'd out" and the structure would not be affected, thus simplifying the "model". This is available in the **spinifex** package.

Rendering

The projection dimension d can be 1, 2, 3, ... It is just a projection of the data, and then you need to decide how to *render* the data.

- $d=1$: The projected data can be displayed as a dotplot, density, histogram, boxplot, ...
- $d>2$: Use stereo (for $d=3$) or a scatterplot matrix (or parallel coordinate plot)



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