# SPSA on the BBOB 2009 Noise-free Testbed

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## **ABSTRACT**

This paper benchmarks the Simultaneous Perturbation Stochastic Algorithm (SPSA) [4] on the BBOB 2009 noise-free testbed. SPSA is a widely used optimization algorithm with its main application in noisy optimization. But it is also of interest how the algorithm behaves in an noise-free environment. The paper presents briefly the algorithm and used parameters for the testbed.

# **Categories and Subject Descriptors**

G.1.6 [Numerical Analysis]: Optimization—global optimization, unconstrained optimization; F.2.1 [Analysis of Algorithms and Problem Complexity]: Numerical Algorithms and Problems

#### **General Terms**

Algorithms

## **Keywords**

Benchmarking, Black-box optimization, evolutionary computation, stochastic optimization

## 1. INTRODUCTION

The SPSA algorithm is a very common and widely used optimization algorithm [5] and primarily designed for noisy optimization. Nevertheless, the performance in an noise-free environment is of interest. Further to the knowledge of the author, there is no paper where SPSA is extensively benchmarked and compared with other common (not necessarily stochastic) optimization algorithm. In this paper the basic variant with a simple multistart procedure is presented. The main feature of SPSA is the use of just 2 function evaluations to determine the gradient, independent of the search space dimension DIM. As shown in [4, 6] this is advantageous (especially for large DIM) compared with common stochastic approximation algorithm which use  $2 \times \text{DIM}$  function evaluations to approximate the gradient. The here presented

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GECCO'09, July 8–12, 2009, Montréal Québec, Canada. Copyright 2009 ACM 978-1-60558-505-5/09/07 ...\$5.00. algorithm is coupled with a simple multistart procedure to effectively use the given number of maximal function evaluations, similar to Fig. 3 in [2].

## 2. ALGORITHM PRESENTATION

In Fig. 1 the main algorithm is presented.

The gain ak is used for the update of the current search point, while the gain ck is used for the test step of the gradient approximation. The determination of their initial values is shown in Fig. 2. To improve the performance of SPSA, lambda gradient approximations are averaged within one iteration before the update of the current search point. Thus, the here presented SPSA uses  $2 \times lambda$  function evaluations per iteration. The parameter lambda is increased during the multistart procedure.

To effectively use the allowed number of function evaluations a simple multistart procedure was implemented. It is shown in Fig. 3. To prevent infinite runs the procedure terminates if the maximal number of restarts is reached.

## 3. EXPERIMENTAL PROCEDURE

The gain rates were set to their recommended values alpha =0.602 and gamma =0.101, instead of the respective optimal values. All other parameters were set as recommended in [6]. Since the recommendation for c0 is to set approximately to the standard deviation at the initial point, a fixed value of c0 =0.001 is used in the experiments. The experiments were conducted on a Cluster with 2.44 GHz CPUs (machine\_type x86\_64) under Octave 3.0.2.

#### 4. RESULTS

Results from experiments according to [2] on the benchmark functions given in [1, 3] are presented in Figures 4 and 5 and in Table 1.

#### 5. CPU TIMING EXPERIMENT

For the timing experiment the same multistart algorithm was run on  $f_8$  and restarted until at least 30 seconds had passed (according to Figure 2 in [2]). The results were 1.2; 1.2; 1.2; 1.3 and  $1.3 \times 10^{-4}$  seconds per function evaluation in dimension 2; 3; 5; 10; 20 and 40, respectively. The dependency of CPU time on the search space dimensionality is small.

## 6. CONCLUSION

This paper reports the result for the basic SPSA on the BBOB 2009 noise-free testbed.

```
% simple spsa function
function [x,termvalue] = alg(FUN, x, parameter, maxGenerations, ftarget,...
                              DIM, maxfunevals)
   % intialze counters
   k = 1;
   % initialize algorithm parameter
   a0 = parameter(1);
    alpha = parameter(2);
   c0 = parameter(3);
   gamma = parameter(4);
   A = parameter(5);
   lambda = parameter(6);
   while 1
        % gain sequences ak and ck
        ak = a0 * (A + k)^{-alpha};
        ck = c0 * k^(-gamma);
        % gradient approximation with averaging of several approximations
        delta = 2*round(rand(DIM,lambda))-1;
        X = repmat(x,1,lambda);
        yplus = FUN(X + ck.*delta);
        yminus = FUN(X - ck.*delta);
        Gk = mean(repmat((yplus-yminus),DIM,1)./(2*ck.*delta),2);
       % update objectVector
        x = x - ak*Gk;
       % termination criterions
        fit = FUN(x);
        \mbox{\%} stop if target or maxfunevals is reached
        if fit <= ftarget || feval(FUN, 'evaluations') >= maxfunevals
            termvalue = 1;
            break;
        end
        \% stop if maxGenerations or fit is larger 1e30 (probably divergent
        if k > maxGenerations || fit > 1e30
            termvalue = 0;
            break;
        end
        % stop if x has nan or inf entries
        if max(isnan(x)) == 1 \mid \mid max(isinf(x)) == 1
            termvalue = 0;
            break;
        end
        % increase k
        k = k + 1;
    end % of while loop
end % of function
```

Λ f	f1 in 5-D, N=15, mFE=503 # ERT 10% 90% RT <sub>succ</sub>	f1 in 20-D, N=15, mFE=2015 # ERT 10% 90% RTsucc	$\Delta f \mid f2 \text{ in 5-D}, \text{ N=15}, \text{mFE=503} \mid f2 \text{ in 20-D}, \text{ N=15}, \text{mFE=2015} \\ \Delta f \mid \# \text{ ERT}  10\%  90\%  \text{RT}_{\text{succ}} \mid \# \text{ ERT}  10\%  90\%  \text{RT}_{\text{succ}}$
$\frac{\Delta f}{10}$	# ER1 10% 90% K1 succ 13 2.9 e2 2.4 e2 3.5 e2 2.6 e2	# ERT 10% 90% RT <sub>succ</sub> 12 9.4e2 6.7e2 1.2e3 6.8e2	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$
$\frac{1}{1e-1}$	6 1.0e3 8.7e2 1.1e3 3.8e2 5 1.3e3 1.2e3 1.4e3 3.8e2	11 1.4e3 1.0e3 1.7e3 9.4e2 10 1.8e3 1.4e3 2.1e3 1.2e3	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$
1e-3	2 3.6e3 3.5e3 3.8e3 4.2e2	9 2.3e3 2.0e3 2.6e3 1.4e3	1e-3
1e-5 1e-8	1 7.5e3 7.5e3 7.5e3 4.9e2 0 15e-1 13e-6 14e+0 5.0e2	8 3.0e3 2.7e3 3.3e3 1.7e3 4 6.8e3 6.3e3 7.2e3 2.0e3	1e-5
10-0	f3 in 5-D, N=15, mFE=503	f3 in 20-D, N=15, mFE=2015	f4 in 5-D, N=15, mFE=503 f4 in 20-D, N=15, mFE=2015
$\Delta f$	# ERT 10% 90% RT <sub>succ</sub>	# ERT 10% 90% RT <sub>succ</sub>	$\Delta f$ # ERT 10% 90% RT <sub>succ</sub> # ERT 10% 90% RT <sub>succ</sub>
10 1	0 18e+1 52e+0 60e+1 4.5e2	0 43e+1 24e+1 72e+1 1.8e3	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$
1e-1			1e-1
1e - 3 1e - 5			$\begin{array}{cccccccccccccccccccccccccccccccccccc$
1e-8			1e-8
$\Delta f$	f5 in 5-D, N=15, mFE=503 # ERT 10% 90% RT <sub>succ</sub>	f5 in 20-D, N=15, mFE=2015 # ERT 10% 90% RT <sub>succ</sub>	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$
10	10 5.2e2 4.3e2 6.0e2 3.2e2	13 1.2e3 1.0e3 1.5e3 1.0e3	10 1 7.4e3 7.2e3 7.5e3 5.0e2 0 $30e+1$ $13e+1$ $34e+3$ 2.0e3
1 1e-1	2 3.4e3 3.1e3 3.8e3 5.0e2 2 3.5e3 3.2e3 3.8e3 5.0e2	8 2.7e3 2.3e3 3.1e3 1.1e3 8 2.7e3 2.3e3 3.1e3 1.1e3	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$
1e-3	2 3.5e3 3.3e3 3.8e3 5.0e2	8 2.8e3 2.3e3 3.1e3 1.2e3	1e-3
1e-5 1e-8	2 3.5e3 3.2e3 3.8e3 5.0e2 2 3.5e3 3.2e3 3.8e3 5.0e2	8 2.8e3 2.3e3 3.1e3 1.2e3 8 2.8e3 2.4e3 3.1e3 1.2e3	1e-5
	f7 in 5-D, N=15, mFE=533	f7 in 20-D, N=15, mFE=2015	f8 in 5-D, N=15, mFE=503 f8 in 20-D, N=15, mFE=2015
$\frac{\Delta f}{10}$	# ERT 10% 90% RT <sub>succ</sub> 2 3.5e3 3.1e3 3.9e3 5.2e2	# ERT 10% 90% RT <sub>SUCC</sub> 0 17e+2 61e+1 28e+2 7.9e1	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$
1	0 64e+0 64e-1 32e+1 7.9e1		1
1e-1 1e-3			$\begin{array}{cccccccccccccccccccccccccccccccccccc$
1e-5			1e-5
1e-8	fg in 5-D, N=15, mFE=503	fg in 20-D, N=15, mFE=2015	1e-8
$\Delta f$	# ERT 10% 90% RT <sub>succ</sub>	# ERT 10% 90% RT <sub>succ</sub>	$\Delta f$ # ERT 10% 90% RT <sub>succ</sub> # ERT 10% 90% RT <sub>succ</sub>
10 1	1 7.5e3 7.5e3 7.5e3 5.0e2 0 54e+1 13e+0 78e+2 5.0e2	0 43e+1 28e+1 13e+2 2.0e3	10 0 23e+4 26e+3 21e+5 5.0e2 0 12e+4 56e+3 64e+4 2.0e3 1
$1\mathrm{e}-1$			1e-1
1e-3 1e-5			$egin{array}{cccccccccccccccccccccccccccccccccccc$
$1\mathrm{e}-8$			1e-8
$\Delta f$ :	f <sub>11</sub> in 5-D, N=15, mFE=503 # ERT 10% 90% RT <sub>succ</sub>	f11 in 20-D, N=15, mFE=2015 # ERT 10% 90% RT <sub>succ</sub>	$\Delta f$   $f$ 12 in 5-D, N=15, mFE=503   $f$ 12 in 20-D, N=15, mFE=2015   $f$ 4 ERT 10% 90% RT <sub>Succ</sub>   $f$ 4 ERT 10% 90% RT <sub>succ</sub>
	1 7.5e3 7.5e3 7.5e3 5.0e2	0 24e+1 18e+1 39e+2 1.6e3	10 0 99e+5 40e+1 11e+7 5.0e2 2 1.5e4 1.5e4 1.5e4 2.0e3
$\frac{1}{1e-1}$	0 87e+0 14e+0 12e+4 3.2e2		$\begin{array}{cccccccccccccccccccccccccccccccccccc$
1e-3			1e-3
1e-5 1e-8			1e-5
	f13 in 5-D, N=15, mFE=503	$f_{13}$ in 20-D, N=15, mFE=2015	f <sub>14</sub> in 5-D, N=15, mFE=503   f <sub>14</sub> in 20-D, N=15, mFE=2015
$\frac{\Delta f}{10}$ :	# ERT 10% 90% RT <sub>succ</sub> 0 10e+1 23e+0 16e+1 4.5e2	# ERT 10% 90% RT <sub>succ</sub> 0 30e+1 11e+1 13e+2 1.6e3	$\Delta f$ # ERT 10% 90% RT <sub>succ</sub> # ERT 10% 90% RT <sub>succ</sub> 10 10 4.3e2 3.3e2 5.2e2 3.9e2 13 1.3e3 1.0e3 1.5e3 1.2e3
1			1 2 3.5e3 3.3e3 3.8e3 5.0e2 4 6.8e3 6.3e3 7.3e3 1.8e3
1e-1 1e-3			$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$
1e-5			1e-5
1e-8	f <sub>15</sub> in 5-D, N=15, mFE=503	f <sub>15</sub> in 20-D, N=15, mFE=2015	le-8
$\Delta f$ :	# ERT 10% 90% RT <sub>succ</sub>	# ERT 10% 90% RT <sub>succ</sub>	$\Delta f$ # ERT 10% 90% RT <sub>succ</sub> # ERT 10% 90% RT <sub>succ</sub>
10 1	0 94e+0 44e+0 36e+1 4.0e2 	0 41e+1 34e+1 60e+1 1.8e3	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$
1e-1			1e-1
1e - 3 1e - 5			$\begin{array}{cccccccccccccccccccccccccccccccccccc$
1e-8			1e-8
$\Delta f$ :	f17 in 5-D, N=15, mFE=503 # ERT 10% 90% RT <sub>succ</sub>	f17 in 20-D, N=15, mFE=2015 # ERT 10% 90% RT <sub>succ</sub>	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$
10	9 4.8e2 3.6e2 5.9e2 2.6e2	5 5.2e3 4.7e3 5.6e3 1.5e3	10 0 $31e+0$ $16e+0$ $16e+1$ $3.2e2$ 0 $44e+0$ $33e+0$ $68e+0$ $1.4e3$
1e-1	0 93e-1 37e-1 18e+0 4.0e2 	0 10e+0 76e-1 25e+0 1.3e3 	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$
1e - 3 1e - 5			$egin{array}{cccccccccccccccccccccccccccccccccccc$
$1\mathrm{e}-8$			1e-8
$\Delta f$		f19 in 20-D, N=15, mFE=2015 # ERT 10% 90% RT <sub>succ</sub>	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$
10	5 1.0e3 8.1e2 1.2e3 2.2e2	1 2.9e4 2.8e4 3.0e4 2.0e3	10 2 3.4e3 3.0e3 3.6e3 5.0e2 9 2.3e3 2.0e3 2.7e3 1.6e3
$\frac{1}{1e-1}$	0 13e+0 50e-1 23e+0 7.9e1 	0 26e+0 12e+0 36e+0 3.1e1 	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
1e-3			1e-3
1e-5 1e-8			$\begin{array}{cccccccccccccccccccccccccccccccccccc$
i	f21 in 5-D, N=15, mFE=503	f21 in 20-D, N=15, mFE=2015	f22 in 5-D, N=15, mFE=503 f22 in 20-D, N=15, mFE=2015
		# ERT 10% 90% RT <sub>succ</sub> 0 51e+0 32e+0 81e+0 3.5e2	Δf # ERT 10% 90% RT <sub>Succ</sub> # ERT 10% 90% RT <sub>Succ</sub> 10 5 1.2e3 1.0e3 1.4e3 5.0e2 1 2.9e4 2.8e4 3.0e4 2.0e3
1	1 7.4e3 7.2e3 7.5e3 5.0e2		1 0 $18e+0$ $21e-1$ $67e+0$ $5.0e2$ 1 $2.9e4$ $2.8e4$ $3.0e4$ $2.0e3$
1e-1 1e-3	0 74e-1 11e-1 36e+0 5.0e2 		$ \begin{array}{cccccccccccccccccccccccccccccccccccc$
1e-5			1e-5
1e-8			1e-8
$\Delta f$	# ERT 10% 90% RT <sub>succ</sub>	# ERT 10% 90% RT <sub>succ</sub>	$\Delta f$ # ERT 10% 90% RT <sub>succ</sub> # ERT 10% 90% RT <sub>succ</sub>
		12 5.3e2 2.0e2 8.7e2 3.6e2 0 68e-1 45e-1 13e+0 3.9e1	10 0 80e+0 54e+0 99e+0 2.5e2 0 46e+1 36e+1 55e+1 1.1e3 1
1e-1			1e-1
1e-3 1e-5			$\begin{array}{cccccccccccccccccccccccccccccccccccc$
$1\mathrm{e}-8$			1e-8

Table 1: Shown are, for a given target difference to the optimal function value  $\Delta f$ : the number of successful trials (#); the expected running time to surpass  $f_{\rm opt} + \Delta f$  (ERT, see Figure 4); the 10%-tile and 90%-tile of the bootstrap distribution of ERT; the average number of function evaluations in successful trials or, if none was successful, as last entry the median number of function evaluations to reach the best function value (RT<sub>succ</sub>). If  $f_{\rm opt} + \Delta f$  was never reached, figures in *italics* denote the best achieved  $\Delta f$ -value of the median trial and the 10% and 90%-tile trial. Furthermore, N denotes the number of trials, and mFE denotes the maximum of number of function evaluations executed in one trial. See Figure 4 for the names of functions.

```
function [a0,c0] = DetermineParameter(A,alpha,x,step,FUN,DIM)
   \% generate matrix with trial vectors
   X = repmat(x,1,10);
   % c0
   c0 = 1e-3;
   % a0
   % generation of the simultaneous perturbation vector
   delta = 2*round(rand(DIM,10))-1;
   % function evaluation
   yplus = FUN(X + c0.*delta);
   yminus = FUN(X - c0.*delta);
   % gradient approximation
   gApprox = mean(repmat((yplus-yminus),DIM,1)./(2*c0.*delta),2);
   % mean of the magnitude of gradient element
   gMeanElement = abs(mean(gApprox));
   % determine parameter a
   a0 = step*(1+A)^alpha/gMeanElement;
end % of function
```

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```
function x = spsa(FUN, DIM, ftarget, maxfunevals)
    % make sure to terminate
    if isinf(maxfunevals) || maxfunevals > 1e5*DIM
        kmax = 1e5*DIM;
    else
        kmax = maxfunevals;
   % constant parameter
   A = 0.1*kmax;  % A approx 10% of max generations gamma = 0.101;  % reduction rate for ck (as recommended)
    alpha = 0.602; % reduction rate for ak (as recommended)
   \mbox{\ensuremath{\mbox{\%}}} multistart such that ftarget is reached with reasonable prob.
   for ilaunch = 1:100 % relaunch optimizer up to 100 times
        % restarts
        if ilaunch == 1
                                             % initial scenario
           xstart = 8 * rand(DIM, 1) - 4;  % random start solution
                                             % parameter to determine a0
           step = 0.1;
                                             \% number of gradient approximations
           lambda = 10;
           [a0,c0] = DetermineParameter(A,alpha,xstart,step,FUN,DIM);
        else
            choice = round(3*rand) + 1;
            \% if the xstart is changing, parameter a0 has to be newly
            % calcualeted
            switch choice
                            % new point
                case 1
                     xstart = 8 * rand(DIM, 1) - 4;
                     [a0,c0] = DetermineParameter(A,alpha,xstart,step,FUN,DIM);
                 case 2
                            % improve old point
                     xstart = x;
                     [a0,c0] = DetermineParameter(A,alpha,xstart,step,FUN,DIM);
                           % half the step size
                     step = step/2;
                     [a0,c0] = DetermineParameter(A,alpha,xstart,step,FUN,DIM);
                           % increase lambda
                     lambda = ceil(lambda * sqrt(2));
            end % switch case
        end
        % try spsa
        parameter = [a0,alpha,c0,gamma,A,lambda];
        [x,termvalue] = alg(FUN,xstart,parameter,kmax,ftarget,DIM,maxfunevals);
        if termvalue == 1
            break;
        end
    end
end % of function
```

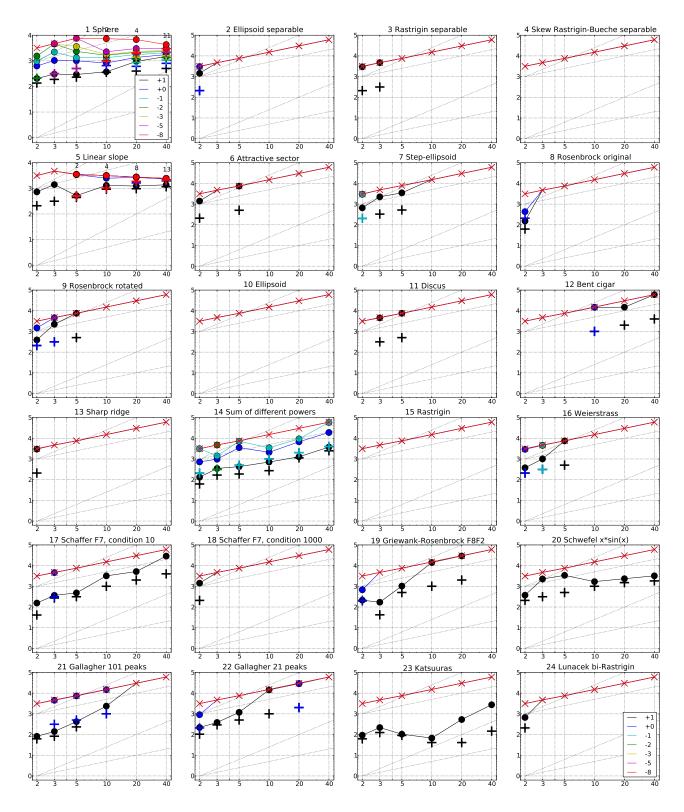


Figure 4: Expected Running Time (ERT, ullet) to reach  $f_{\mathrm{opt}} + \Delta f$  and median number of function evaluations of successful trials (+), shown for  $\Delta f = 10, 1, 10^{-1}, 10^{-2}, 10^{-3}, 10^{-5}, 10^{-8}$  (the exponent is given in the legend of  $f_1$  and  $f_{24}$ ) versus dimension in log-log presentation. The  $\mathrm{ERT}(\Delta f)$  equals to  $\#\mathrm{FEs}(\Delta f)$  divided by the number of successful trials, where a trial is successful if  $f_{\mathrm{opt}} + \Delta f$  was surpassed during the trial. The  $\#\mathrm{FEs}(\Delta f)$  are the total number of function evaluations while  $f_{\mathrm{opt}} + \Delta f$  was not surpassed during the trial from all respective trials (successful and unsuccessful), and  $f_{\mathrm{opt}}$  denotes the optimal function value. Crosses (×) indicate the total number of function evaluations  $\#\mathrm{FEs}(-\infty)$ . Numbers above ERT-symbols indicate the number of successful trials. Annotated numbers on the ordinate are decimal logarithms. Additional grid lines show linear and quadratic scaling.

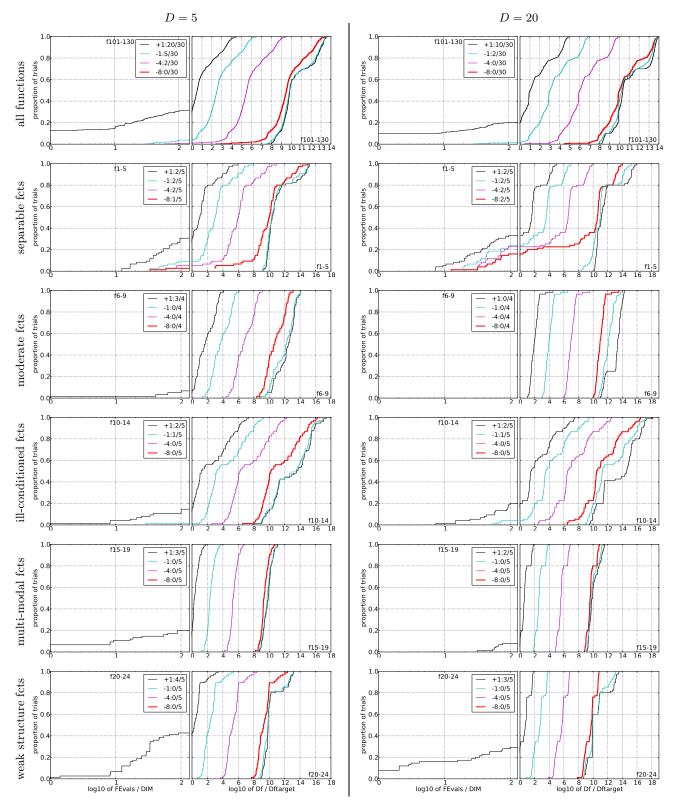


Figure 5: Empirical cumulative distribution functions (ECDFs), plotting the fraction of trials versus running time (left subplots) or versus  $\Delta f$  (right subplots). The thick red line represents the best achieved results. Left subplots: ECDF of the running time (number of function evaluations), divided by search space dimension D, to fall below  $f_{\rm opt} + \Delta f$  with  $\Delta f = 10^k$ , where k is the first value in the legend. Right subplots: ECDF of the best achieved  $\Delta f$  divided by  $10^k$  (upper left lines in continuation of the left subplot), and best achieved  $\Delta f$  divided by  $10^{-8}$  for running times of D, 10D, 10D... function evaluations (from right to left cycling black-cyan-magenta). Top row: all results from all functions; second row: separable functions; third row: misc. moderate functions; fourth row: ill-conditioned functions; fifth row: multi-modal functions with adequate structure; last row: multi-modal functions with weak structure. The legends indicate the number of functions that were solved in at least one trial. FEvals denotes number of function evaluations, D and DIM denote search space dimension, and  $\Delta f$  and Df denote the difference to the optimal function value.