# Black-Box Optimization Benchmarking: Results for the $BayEDA_{cG}$ Algorithm on the Noiseless Function Testbed

Draft version \*

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END

## **ABSTRACT**

## **Categories and Subject Descriptors**

G.1.6 [Numerical Analysis]: OptimizationGlobal Optimization, Unconstrained Optimization; F.2.1 [Analysis of Algorithms and Problem Complexity]: Numerical Algorithms and Problems

### **General Terms**

Algorithms

## **Keywords**

Benchmarking, Black-box optimization, Evolutionary computation  $\,$ 

## 1. INTRODUCTION

This paper presents experimental results for the Bayeddaco continuous optimization algorithm on the BBOB noise free benchmark problem suite as part of the GECCO'09 Workshop.

#### 2. ALGORITHM PRESENTATION

BayEDA $_{cG}$  is an Estimation of Distribution Algorithm that uses Bayesian Inference to learn a posterior distribution over model parameters for the probability density estimation model used [2]. In this algorithm, the distribution is a product of univariate Gaussian distributions and inference is performed over mean and variance parameters for each dimension in the search space. The algorithm is described for a one-dimensional problem in Table 1. Given the factorized probability model, the extension to the multidimensional case is straightforward.

The following description of the algorithm is from [2]:

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#### Table 1: Algorithm: BayEDAcG.

Given: population size M, selection parameter  $\tau$  BEGIN (set t=0) Generate M individuals uniformly in S REPEAT for  $t=1,2,\ldots$  until stopping criterion is met Select  $M_{sel}=\operatorname{Round}(M\cdot\tau)$  individuals via truncation selection Calculate sample mean  $\overline{x}$  and variance  $s^2$  of D to update model Sample M individuals from  $p_t(\mathbf{x}|D,\theta)$ : FOR i=1:MDraw sample variance  $\tilde{\sigma}^2 \sim \operatorname{Inv} - \chi^2(M_{sel}-1,s^2)$ Draw sample mean  $\tilde{\mu} \sim N(\bar{x},\tilde{\sigma}^2/(M_{sel}))$ Draw new individual  $\mathbf{x}_i \sim N(\tilde{\mu},\tilde{\sigma}^2)$ ENDFOR

For a univariate Gaussian (Normal) model distribution, Bayesian inference can readily be carried out: the resulting expressions given here are drawn from Gelman et al. [3]. We consider the simplest case of a noninformative (flat) prior for the model parameters, expressing no preference for any particular values for the model parameters before observing any data. In this case, inference depends only on the data (selected individuals). The standard noninformative prior is uniform on  $(\mu, \log \sigma^2)$  or

$$p(\mu, \sigma^2) \propto (\sigma^2)^{-1}$$

The joint posterior can be factorised as

$$p(\mu, \sigma^2|D) = p(\mu|\sigma^2, D)p(\sigma^2|D)$$

In this case, the marginal density for  $\sigma$  is

$$\sigma^2 | D \sim \text{Inv} - \chi^2 (M_{sel} - 1, s^2)$$
 (1)

where  $s^2$  is the sample variance of the data. The conditional density for  $\mu$  is

$$\mu|D,\sigma^2 \sim N(\overline{x},\sigma^2/M_{sel})$$
 (2)

where  $\overline{x}$  is the sample mean of the data D.

The predictive distribution for  $\tilde{x}$  given the data,  $\mu$  and  $\sigma$  is

$$\tilde{x}|D,\mu,\sigma^2 \sim N(\mu,\sigma^2)$$
 (3)

In the BayEDA<sub>cG</sub> algorithm, sampling from the posterior predictive distribution  $p(\tilde{x}|D)$  can be easily carried out in a three-step process. Firstly, a sample  $\tilde{\sigma}^2$  is drawn from (1),

<sup>\*</sup>Camera-ready paper due April 17th.

then this sample is used to draw a sample  $\tilde{\mu}$  from (2) and finally both samples are used to draw a sample  $\tilde{x}$  from (3). The process is repeated M times to produce the population for use in the next generation.

The algorithm is summarized in Table 1. Note that for implementation purposes, a random draw y from an inverse- $\chi^2$  distribution can be obtained by firstly drawing a sample z from the  $\chi^2$  distribution and applying  $y=s^2/z$ . The  $\chi^2$  distribution is also a special case of the gamma distribution (see [3] for details).

#### 3. EXPERIMENTAL PROCEDURE

The BayEDA<sub>cG</sub> algorithm was run on the current set of BBOB noiseless benchmark functions (see other document for results on noisy functions). No parameter tuning was attempted with respect to the functions. The population size (M) was set to 10 times the dimensionality of the problem. The selection threshold  $\tau$  (for truncation selection) was set (rather arbitrarily) to 0.8. The total number of function evaluations was set to 2000 times the problem dimensionality (making the total number of generations for each run of the algorithm equal to 200).

The *crafting effort* for this set of experiments is zero in this case.

#### 4. RESULTS

Results from experiments according to [4] on the benchmark functions given in [1, 5] are presented in Figures 1 and 2 and in Table 2.

#### 5. CPU TIMING EXPERIMENT

For the timing experiment the BayEDA<sub>cG</sub> algorithm was run as suggested on  $f_8$  until at least 30 seconds has passed. The experiments in this paper were conducted on an Intel Pentium 4 quad core 2.4Ghz processor running Linux 2.6.24-23 SMP and Matlab R2008a. The results were (in seconds per function evaluation) 2.9;3.2;3.8;5.3 and 8.3  $\times 10^{-4}$  for dimension 2;3;5;10 and 20D and 1.4  $\times 10^{-3}$  for 40D.

## 6. CONCLUSION

The results show a wide variety of performance across the different test functions. Some functions seem reasonably well-solved for a range of precision and dimensionality values while others show only modest performance. This is for a reasonably small number of function evaluations. Neverthess, it will be intersting to see comparative analysis at the workshop.

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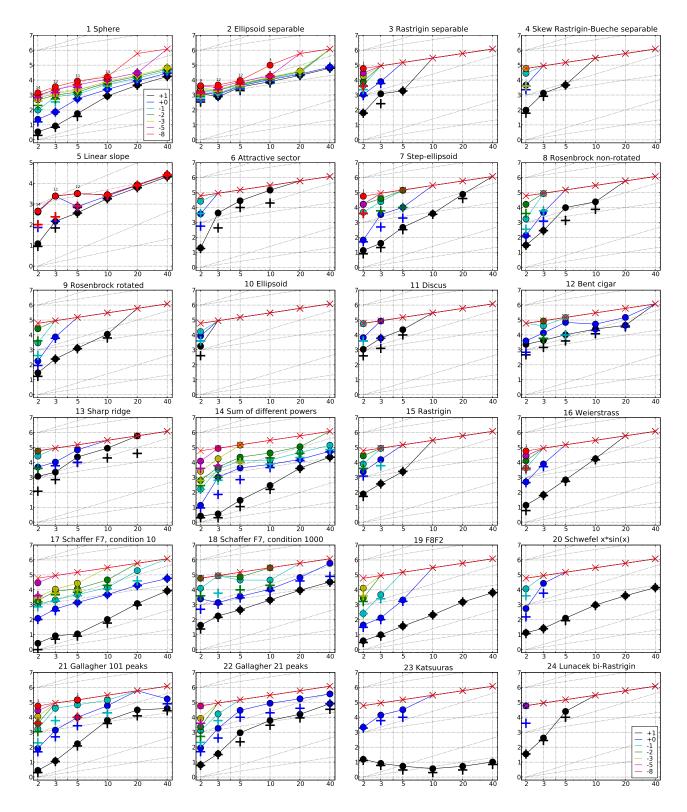


Figure 1: Expected Running Time (ERT, ullet) to reach  $f_{\mathrm{opt}} + \Delta f$  and median number of function evaluations of successful trials (+), shown for  $\Delta f = 10, 1, 10^{-1}, 10^{-2}, 10^{-3}, 10^{-5}, 10^{-8}$  (the exponent is given in the legend of  $f_1$  and  $f_{24}$ ) versus dimension in log-log presentation. The  $\mathrm{ERT}(\Delta f)$  equals to  $\#\mathrm{FEs}(\Delta f)$  divided by the number of successful trials, where a trial is successful if  $f_{\mathrm{opt}} + \Delta f$  was surpassed during the trial. The  $\#\mathrm{FEs}(\Delta f)$  are the total number of function evaluations while  $f_{\mathrm{opt}} + \Delta f$  was not surpassed during the trial from all respective trials (successful and unsuccessful), and  $f_{\mathrm{opt}}$  denotes the optimal function value. Crosses (×) indicate the total number of function evaluations  $\#\mathrm{FEs}(-\infty)$ . Numbers above ERT-symbols indicate the number of successful trials. Annotated numbers on the ordinate are decimal logarithms. Additional grid lines show linear and quadratic scaling.

$\Delta f \mid f1 \text{ in 5-D}, \text{ N=15, mFE=10000} \\ \Delta f \mid \# \text{ ERT } 10\% 90\% \text{ RT}_{\text{Succ}}$		$\Delta f$   f2 in 5-D, N=15, mFE=10000   $\Delta f$   # ERT 10% 90% RT <sub>succ</sub>	f <sub>2</sub> in 20-D, N=15, mFE=40000 # ERT 10% 90% RT <sub>succ</sub>
10 15 5.7e1 3.8e1 8.7e1 5.7e1	15 4.6e3 4.3e3 4.7e3 4.6e3	$\Delta f$ # ERT 10% 90% RT <sub>succ</sub> 10 13 3.4e3 2.2e3 4.7e3 3.1e3	# ERT 10% 90% RT <sub>succ</sub> 15 2.1e4 2.0e4 2.1e4 2.1e4
1   15 5.6e2 5.1e2 5.8e2 5.6e2 1e-1   15 1.1e3 1.1e3 1.2e3 1.1e3	15 8.8e3 8.6e3 8.9e3 8.8e3 15 1.3e4 1.3e4 1.3e4 1.3e4	1   13   4.1e3   3.4e3   4.7e3   3.7e3   1e-1   13   4.6e3   3.5e3   5.7e3   4.1e3	15 2.5e4 2.5e4 2.5e4 2.5e4 15 2.9e4 2.9e4 3.0e4 2.9e4
1e-3 15 2.1e3 2.1e3 2.2e3 2.1e3	15 2.1e4 2.1e4 2.2e4 2.1e4	1e-3 13 5.7e3 4.9e3 6.5e3 5.1e3	14 4.1e4 4.0e4 4.1e4 3.8e4
1e-5 13 4.8e3 4.2e3 5.4e3 4.3e3 1e-8 11 8.5e3 7.6e3 1.0e4 6.8e3	15 3.0 e4 3.0 e4 3.0 e4 3.0 e4 0 61e-9 39e-9 11e-8 3.5 e4	1e-5   12 7.7e3 6.9e3 7.9e3 6.0e3   1e-8   12 9.4e3 8.8e3 1.0e4 7.4e3	0 34e-5 23e-5 42e-5 3.5e4 
f3 in 5-D, N=15, mFE=10000	f3 in 20-D, N=15, mFE=40000	f4 in 5-D, N=15, mFE=10000	f4 in 20-D, N=15, mFE=40000
$\Delta f$ # ERT 10% 90% RT <sub>SUCC</sub> 10 15 1.9e3 1.8e3 2.0e3 1.9e3	# ERT 10% 90% RT <sub>succ</sub>	$\Delta f$ # ERT 10% 90% RT <sub>succ</sub> 10 15 4.7e3 4.3e3 5.3e3 4.7e3	# ERT 10% 90% RT <sub>succ</sub>
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1e-5		1e-5	
1e-8     f5 in 5-D, N=15, mFE=10000	f5 in 20-D, N=15, mFE=12400	1e-8	f6 in 20-D, N=15, mFE=40000
$\Delta f$ # ERT 10% 90% RT <sub>succ</sub>	# ERT 10% 90% RT <sub>succ</sub>	$\Delta f$ # ERT 10% 90% RT <sub>succ</sub>	# ERT 10% 90% RT <sub>succ</sub>
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1e-3   12 3.2e3 2.4e3 4.8e3 3.0e3 1e-5   12 3.2e3 1.8e3 4.8e3 3.0e3	15 8.4e3 8.1e3 9.0e3 8.4e3 15 8.4e3 7.9e3 8.7e3 8.4e3	1e-3	
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10 15 4.7e2 2.9e2 7.8e2 4.7e2	6 7.7e4 6.6e4 8.4e4 2.9e4	10 8 9.9e3 6.5e3 1.3e4 5.6e3	0  48e + 0  18e + 0  81e + 0  4.0e4
1 8 1.0e4 9.3e3 1.1e4 4.6e3 1e-1 1 1.4e5 1.3e5 1.5e5 1.0e4	0 11e+0 48e-1 21e+0 2.5e4	1 0 45e-1 30e-1 28e+0 2.8e3 1e-1	
1e-3 0 73e-2 18e-2 64e-1 2.0e3		1e-3	
1e-5		1e-5	
f9 in 5-D, N=15, mFE=10000	f9 in 20-D, N=15, mFE=40000	f10 in 5-D, N=15, mFE=10000	f10 in 20-D, N=15, mFE=40000
$\Delta f$ # ERT 10% 90% RT <sub>succ</sub> 10 15 1.3e3 1.2e3 1.4e3 1.3e3	# ERT 10% 90% RT <sub>SUCC</sub> 0 18e+0 18e+0 19e+0 4.0e4	$     \begin{array}{c cccccccccccccccccccccccccccccccc$	# ERT 10% 90% RT <sub>succ</sub> 0 42e+3 21e+3 11e+4 3.5e4
1 0 39e-1 30e-1 47e-1 3.5e3		1	
1e-1		1e-1	
1e-5		1e-5	
f11 in 5-D, N=15, mFE=10000	f <sub>11</sub> in 20-D, N=15, mFE=40000	f12 in 5-D, N=15, mFE=10000	f <sub>12</sub> in 20-D, N=15, mFE=40000
$     \begin{array}{c cccccccccccccccccccccccccccccccc$	# ERT 10% 90% RT <sub>SUCC</sub> 0 14e+1 95e+0 15e+1 7.1e3	$\Delta f$ # ERT 10% 90% RT <sub>Succ</sub> 10 9 1.0e4 8.7e3 1.3e4 5.2e3	# ERT 10% 90% RT <sub>SUCC</sub> 12 4.4e4 4.4e4 4.5e4 3.5e4
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1e-5		1e-5	
1e-8	f13 in 20-D, N=15, mFE=40000	1e-8     f14 in 5-D, N=15, mFE=10000	f14 in 20-D, N=15, mFE=40000
$\Delta f$ # ERT 10% 90% RT <sub>succ</sub>	# ERT 10% 90% RT <sub>succ</sub>	$\Delta f$ # ERT 10% 90% RT <sub>succ</sub>	# ERT 10% 90% RT <sub>succ</sub>
10 5 2.3 e4 2.0 e4 2.6 e4 7.3 e3 1 2 6.9 e4 6.6 e4 7.2 e4 6.9 e3	1 5.9e5 5.8e5 6.0e5 4.0e4 0 49e+0 15e+0 11e+1 3.5e4	10 15 2.9e1 1.8e1 4.8e1 2.9e1 1 11 4.3e3 1.6e3 6.2e3 2.3e3	15 4.1e3 3.7e3 4.5e3 4.1e3 15 1.6e4 1.5e4 1.7e4 1.6e4
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1e-5		1e-5 0 12e-2 13e-4 20e-1 3.5e3	
1e-8	f15 in 20-D, N=15, mFE=40000	1e-8     f16 in 5-D, N=15, mFE=10000	f16 in 20-D, N=15, mFE=40000
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10 15 2.4e3 1.8e3 3.1e3 2.4e3 1 0 61e-1 48e-1 78e-1 7.1e3	0 93e+0 83e+0 11e+1 2.8e4	10	0 21e+0 17e+0 24e+0 2.0e4
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1 8 9.9e3 6.3e3 1.3e4 5.7e3 1e-1 2 6.8e4 6.4e4 7.2e4 1.0e4	0 60e-1 20e-1 24e+0 3.5e4 	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	3 1.7e5 1.6e5 1.9e5 4.0e4 0 20e-1 69e-2 13e+0 3.5e4
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f23 in 5-D, N=15, mFE=10000	f23 in 20-D, N=15, mFE=40000	f24 in 5-D, N=15, mFE=10000	f24 in 20-D, N=15, mFE=40000
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Table 2: Shown are, for a given target difference to the optimal function value  $\Delta f$ : the number of successful trials (#); the expected running time to surpass  $f_{\rm opt}+\Delta f$  (ERT, see Figure 1); the 10%-tile and 90%-tile of the bootstrap distribution of ERT; the average number of function evaluations in successful trials or, if none was successful, as last entry the median number of function evaluations to reach the best function value (RT<sub>succ</sub>). If  $f_{\rm opt}+\Delta f$  was never reached, figures in *italics* denote the best achieved  $\Delta f$ -value of the median trial and the 10% and 90%-tile trial. Furthermore, N denotes the number of trials, and mFE denotes the maximum of number of function evaluations executed in one trial. See Figure 1 for the names of functions.

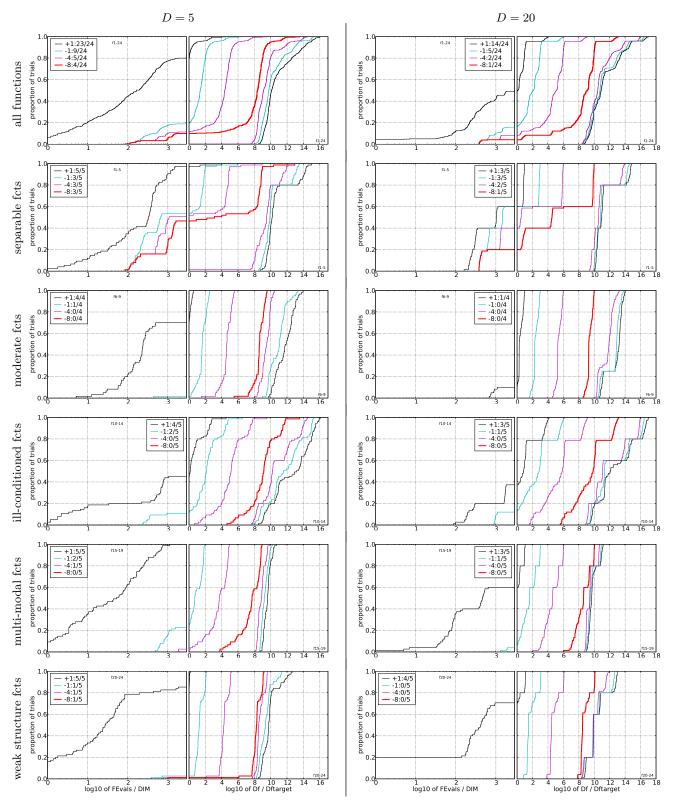


Figure 2: Empirical cumulative distribution functions (ECDFs), plotting the fraction of trials versus running time (left) or  $\Delta f$ . Left subplots: ECDF of the running time (number of function evaluations), divided by search space dimension D, to fall below  $f_{\rm opt} + \Delta f$  with  $\Delta f = 10^k$ , where k is the first value in the legend. Right subplots: ECDF of the best achieved  $\Delta f$  divided by  $10^k$  (upper left lines in continuation of the left subplot), and best achieved  $\Delta f$  divided by  $10^{-8}$  for running times of D, 10D, 100D... function evaluations (from right to left cycling black-cyan-magenta). Top row: all results from all functions; second row: separable functions; third row: misc. moderate functions; fourth row: ill-conditioned functions; fifth row: multi-modal functions with adequate structure; last row: multi-modal functions with weak structure. The legends indicate the number of functions that were solved in at least one trial. FEvals denotes number of function evaluations, D and DIM denote search space dimension, and  $\Delta f$  and Df denote the difference to the optimal function value.