

Benchmarking of MCS on the Noisy Function Testbed

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ABSTRACT

Benchmarking results with the MCS algorithm for bound-constrained global optimization on the noisy BBOB 2009 testbed are described.

Categories and Subject Descriptors

G.1.6 [Numerical Analysis]: Optimization; Global Optimization, Unconstrained Optimization; F.2.1 [Analysis of Algorithms and Problem Complexity]: Numerical Algorithms and Problems

General Terms

Algorithms

Keywords

Benchmarking, Black-box optimization

1. INTRODUCTION

Inspired by the DIRECT method by Jones et al. [5], the global optimization algorithm MCS (multilevel coordinate search) [4] was developed to minimize an objective function on a box $[u, v]$ with finite or infinite bounds. The algorithm proceeds by splitting the search space into smaller boxes, and each box contains a point whose function value is known. In the partitioning procedure parts where low function values are expected to be found are preferred.

2. ALGORITHM PRESENTATION

Like DIRECT, the MCS algorithm combines global search (splitting boxes with large unexplored territory) and local search (splitting boxes with good function values). The key to balancing global and local search is the multilevel approach. As a rough measure of the number of times a box has been processed, a level $s \in \{1, \dots, s_{\max}\}$ is assigned to each box, where boxes with level s_{\max} are considered too small for further splitting. Whenever a box of level s ($0 < s < s_{\max}$)

is split, its descendants get level $s + 1$ or $\min(s + 2, s_{\max})$. After an initialization procedure, the algorithm proceeds by a series of sweeps through the levels, i.e., it splits one box at each level, starting with the smallest non-empty level (i.e., with the largest boxes). We split along a single coordinate in each step, and information gained from already sampled points is used to determine the splitting coordinate as well as the position of the split. Since it does not make sense to apply local search to a noisy function, we use MCS without local search, where the points and function values belonging to boxes of level s_{\max} are put into the so-called shopping basket (containing ‘useful’ points) without processing them further.

The algorithm starts with a so-called initialization procedure producing an initial set of boxes. For each coordinate $i = 1, \dots, n$, at least three values $x_i^1 < x_i^2 < \dots < x_i^{L_i}$ in $[u_i, v_i]$, are needed, where n denotes the dimension of the problem and $L_i \geq 3$. Moreover, the pointers $l_i \in \{1, \dots, L_i\}$ point to the initial point x_i^0 , i.e., $x_i^0 = x_i^{l_i}$. The values x_i^j , $j = 1, \dots, L_i$, l_i , and L_i , $i = 1, \dots, n$, constitute the so-called initialization list.

The version of the software used can be downloaded from <http://www.mat.univie.ac.at/~neum/software/mcs/>.

3. EXPERIMENTAL PROCEDURE

For all control variables in the algorithm meaningful default values can be chosen that work simultaneously for most problems. MCS essentially contains the following parameters: the number s_{\max} of levels, a limit nf_{\max} on the overall number of function calls, an additional stopping criterion, and the initialization list. The limit on function calls in each local search is set to 0 (no local search). We use the default value $s_{\max} = 5n + 10$, and the additional stopping criterion is given by reaching a target function value f_{target} .

Five kinds of initialization lists are incorporated into the MCS software. The safeguarded version for infinite box bounds was not considered since all the box bounds in our problems are finite, $u = (-5, \dots, -5)^T$ and $v = (5, \dots, 5)^T$. The default initialization list for finite u and v consists of boundary points and midpoint, with the midpoint as starting point, i.e., $L_i = 3$, $l_i = 2$, $x_i^1 = u_i$, $x_i^2 = \frac{1}{2}(u_i + v_i)$, and $x_i^3 = v_i$, $i = 1, \dots, n$. Another initialization list for finite bounds uses $x_i^1 = \frac{5}{6}u_i + \frac{1}{6}v_i$ and $x_i^3 = \frac{1}{6}u_i + \frac{5}{6}v_i$ instead of the boundaries (all other quantities are the same). There is also an option to generate an initialization list with the aid of line searches (described in detail Section 7.6 of [4]). We call the MCS algorithm with these three kinds of initialization lists MCS1, MCS2, and MCS3, respectively. Finally, it

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GECCO'09, July 8–12, 2009, Montréal Québec, Canada.
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is possible to use a self-defined initialization list.

In each call to MCS, we use $nf_{\max} = 500 \max(n, 10)$ (i.e., $nf_{\max} = 5000$ for $n = 2, 3, 5, 10$ and $nf_{\max} = 10000$ for $n = 20$), and nf_{\max} might be slightly exceeded since the algorithm does not contain a check whether nf_{\max} has been reached after each function call. Each trial consists of first applying the predefined initialization lists MCS1, MCS2, and MCS3 to the problem and then using a self-defined initialization list with $L_i = 3$, $l_i = 2$, and the values x_i^j , $j = 1, 2, 3$, drawn uniformly from $[u_i, v_i]$ for $i = 1, \dots, n$ for at most 7 times for dimensions $n = 2, 3, 5$ and at most 5 times for dimensions $n = 10, 20$ (in order to save CPU time). I.e., each trial consists of at most 10 (or 8) attempts to solve the problem with MCS, and each call to MCS does not use any results from the previous calls. If the target function value f_{target} is reached, the trial is terminated and the subsequent calls to MCS are not made any more. So at most 50000 function calls (possibly a few more) are made in each trial for $n = 2, 3, 5$ and $4000 \max(n, 10)$ for $n = 10, 20$. Three trials are made for the 5 function instances of each function.

4. CPU TIMING EXPERIMENT

For the timing experiment according to [2], the experimental procedure described above was run on f_8 with at most 1000 function evaluations in each call to MCS and restarted until at least 30 seconds had passed. The timing experiment was carried out on an Intel Xeon 3.4 GHz under SuSE Linux with MATLAB 7.3.0.298, where the benchmarking tests were run. The results were 22, 7.4, 4.8, 4.0, 19, and 6.2×10^{-8} seconds per function evaluation in dimensions 2, 3, 5, 10, 20, and 40, respectively.

5. RESULTS

Results from experiments according to [2] on the benchmarks functions given in [1, 3] are presented in Figures 1 and 2 and in Tables 1 and 2.

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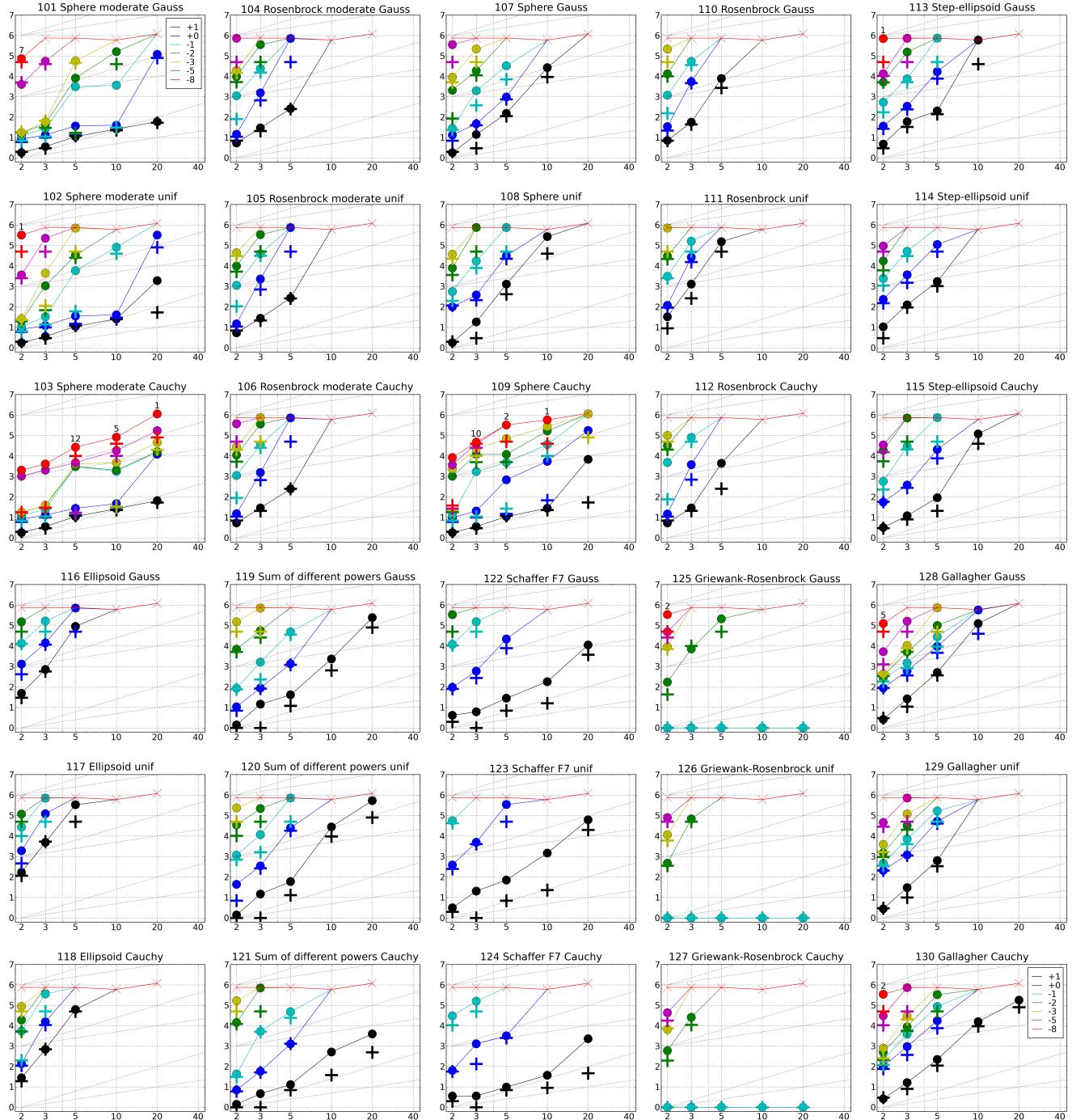


Figure 1: Expected Running Time (ERT, ●) to reach $f_{\text{opt}} + \Delta f$ and median number of function evaluations of successful trials (+), shown for $\Delta f = 10, 1, 10^{-1}, 10^{-2}, 10^{-3}, 10^{-5}, 10^{-8}$ (the exponent is given in the legend of f_{101} and f_{130}) versus dimension in log-log presentation. The $\text{ERT}(\Delta f)$ equals to $\#\text{FEs}(\Delta f)$ divided by the number of successful trials, where a trial is successful if $f_{\text{opt}} + \Delta f$ was surpassed during the trial. The $\#\text{FEs}(\Delta f)$ are the total number of function evaluations while $f_{\text{opt}} + \Delta f$ was not surpassed during the trial from all respective trials (successful and unsuccessful), and f_{opt} denotes the optimal function value. Crosses (x) indicate the total number of function evaluations $\#\text{FEs}(-\infty)$. Numbers above ERT-symbols indicate the number of successful trials. Annotated numbers on the ordinate are decimal logarithms. Additional grid lines show linear and quadratic scaling.

<i>f₁₀₁</i> in 5-D, N=15, mFE=50009							<i>f₁₀₁</i> in 20-D, N=15, mFE=80037							<i>f₁₀₂</i> in 5-D, N=15, mFE=50014							<i>f₁₀₂</i> in 20-D, N=15, mFE=80033						
Δf	#	ERT	10%	90%	RT _{succ}	#	ERT	10%	90%	RT _{succ}	#	ERT	10%	90%	RT _{succ}	#	ERT	10%	90%	RT _{succ}	#	ERT	10%	90%	RT _{succ}		
10	15	1.1e1	1.1e1	1.1e1	1.1e1	15	5.9e1	5.5e1	6.4e1	5.9e1	10	15	1.1e1	1.1e1	1.2e1	1.1e1	15	1.9e3	3.3e2	3.6e3	1.9e3	10	15	1.1e1	1.1e1	1.2e1	1.1e1
1	15	3.7e1	2.2e1	5.2e1	3.7e1	6	1.2e5	8.0e4	2.0e5	5.3e4	1	15	3.5e1	2.3e1	4.9e1	3.5e1	3	3.2e5	1.9e5	9.6e5	8.0e4	1	15	3.5e1	2.3e1	4.9e1	3.5e1
le-1	15	3.1e3	1.7e3	4.4e3	3.1e3	0	1e-1	2e-2	2e-1	1.1e4	le-1	15	5.9e3	2.8e3	9.2e3	5.9e3	0	25e-1	5e-2	57e-1	6.3e3	le-1	15	5.9e3	2.8e3	9.2e3	5.9e3
le-3	8	5.7e4	4.8e4	7.4e4	4.5e4	le-3	1	7.0e5	3.3e5	>7e5	2.0e1	le-3	1	7.0e5	3.3e5	>7e5	2.0e1
le-5	0	82e-5	22e-5	31e-4	1.0e4	le-5	0	58e-4	13e-4	21e-3	2.8e4	le-5	0	58e-4	13e-4	21e-3	2.8e4
le-8	le-8	le-8		
<i>f₁₀₃</i> in 5-D, N=15, mFE=50006							<i>f₁₀₃</i> in 20-D, N=15, mFE=80024							<i>f₁₀₄</i> in 5-D, N=15, mFE=50006							<i>f₁₀₄</i> in 20-D, N=15, mFE=80032						
Δf	#	ERT	10%	90%	RT _{succ}	#	ERT	10%	90%	RT _{succ}	#	ERT	10%	90%	RT _{succ}	#	ERT	10%	90%	RT _{succ}	#	ERT	10%	90%	RT _{succ}		
10	15	1.1e1	1.1e1	1.1e1	1.1e1	15	6.5e1	5.9e1	7.2e1	6.5e1	10	15	2.6e2	2.3e2	2.9e2	2.6e2	0	20e+1	16e+1	88e+1	1.0e4	10	15	2.6e2	2.3e2	2.9e2	2.6e2
1	15	2.8e1	1.9e1	3.6e1	2.8e1	15	1.2e4	9.4e3	1.5e4	1.2e4	1	15	7.1e5	3.4e5	>7e5	5.0e4	1	15	7.1e5	3.4e5	>7e5	5.0e4
le-1	15	3.0e3	1.7e3	4.4e3	3.0e3	15	1.6e4	1.3e4	1.9e4	1.6e4	le-1	0	23e-1	13e-1	42e-1	2.5e4	le-1	0	23e-1	13e-1	42e-1	2.5e4
le-3	15	4.0e3	2.7e3	5.4e3	4.0e3	11	4.6e4	2.9e4	6.7e4	2.7e4	le-3	le-3	
le-5	15	4.7e3	3.4e3	6.0e3	4.7e3	5	1.7e5	1.1e5	3.3e5	5.2e4	le-5	le-5	
le-8	12	2.7e4	1.9e4	3.5e4	2.7e4	1	1.1e6	5.2e5	16e6	8.0e4	le-8	le-8	
<i>f₁₀₅</i> in 5-D, N=15, mFE=50018							<i>f₁₀₅</i> in 20-D, N=15, mFE=80026							<i>f₁₀₆</i> in 5-D, N=15, mFE=50008							<i>f₁₀₆</i> in 20-D, N=15, mFE=80023						
Δf	#	ERT	10%	90%	RT _{succ}	#	ERT	10%	90%	RT _{succ}	#	ERT	10%	90%	RT _{succ}	#	ERT	10%	90%	RT _{succ}	#	ERT	10%	90%	RT _{succ}		
10	15	2.7e2	2.4e2	3.1e2	2.7e2	0	19e+1	15e+1	11e+2	6.3e3	10	15	2.4e2	2.2e2	2.7e2	2.4e2	0	20e+1	13e+1	12e+2	1.4e4	10	15	2.4e2	2.2e2	2.7e2	2.4e2
1	1	7.4e5	3.7e5	>7e5	5.0e4	1	1	7.1e5	3.4e5	>7e5	5.0e4	1	1	7.1e5	3.4e5	>7e5	5.0e4
le-1	0	32e-1	11e-1	47e-1	3.2e4	le-1	0	27e-1	10e-1	44e-1	1.6e4	le-1	0	27e-1	10e-1	44e-1	1.6e4
le-3	le-3	le-3		
le-5	le-5	le-5		
le-8	le-8	le-8		
<i>f₁₀₇</i> in 5-D, N=15, mFE=50025							<i>f₁₀₇</i> in 20-D, N=15, mFE=80038							<i>f₁₀₈</i> in 5-D, N=15, mFE=50022							<i>f₁₀₈</i> in 20-D, N=15, mFE=80041						
Δf	#	ERT	10%	90%	RT _{succ}	#	ERT	10%	90%	RT _{succ}	#	ERT	10%	90%	RT _{succ}	#	ERT	10%	90%	RT _{succ}	#	ERT	10%	90%	RT _{succ}		
10	15	1.5e2	1.1e2	2.0e2	1.5e2	0	64e+0	45e+0	79e+0	1.8e4	10	15	1.3e3	8.0e2	1.8e3	1.3e3	0	69e+0	52e+0	84e+0	1.8e4	10	15	1.3e3	8.0e2	1.8e3	1.3e3
1	15	9.6e2	1.9e1	1.4e3	6.9e2	5	1.8e5	1.1e5	3.2e5	5.6e4	1	12	3.1e4	2.3e4	4.1e4	2.6e4	1	12	3.1e4	2.3e4	4.1e4	2.6e4
le-1	10	3.3e4	2.1e4	4.8e4	2.1e4	le-1	1	7.4e5	3.6e5	>7e5	5.0e4	le-1	1	7.4e5	3.6e5	>7e5	5.0e4
le-3	0	81e-3	34e-3	16e-2	6.3e3	le-3	0	54e-2	19e-2	12e-1	3.2e4	le-3	0	54e-2	19e-2	12e-1	3.2e4
le-5	le-5	le-5		
le-8	le-8	le-8		
<i>f₁₀₉</i> in 5-D, N=15, mFE=50009							<i>f₁₀₉</i> in 20-D, N=15, mFE=80030							<i>f₁₁₀</i> in 5-D, N=15, mFE=50021							<i>f₁₁₀</i> in 20-D, N=15, mFE=80040						
Δf	#	ERT	10%	90%	RT _{succ}	#	ERT	10%	90%	RT _{succ}	#	ERT	10%	90%	RT _{succ}	#	ERT	10%	90%	RT _{succ}	#	ERT	10%	90%	RT _{succ}		
10	15	1.1e1	1.1e1	1.1e1	1.1e1	15	6.8e3	1.4e3	1.3e4	6.8e3	10	15	7.9e3	4.4e3	1.2e4	7.9e3	0	14e+3	57e+2	36e+3	1.6e4	10	15	7.9e3	4.4e3	1.2e4	7.9e3
1	15	6.9e2	1.9e1	1.4e3	6.9e2	5	1.8e5	1.1e5	3.2e5	5.6e4	1	12	3.1e4	2.3e4	4.1e4	2.6e4	1	12	3.1e4	2.3e4	4.1e4	2.6e4
le-1	15	4.7e3	2.0e3	7.6e3	4.7e3	1	1.1e6	5.2e5	>1e6	8.0e4	le-1	1	7.4e5	3.6e5	>7e5	5.0e4	le-1	1	7.4e5	3.6e5	>7e5	5.0e4
le-3	7	6.9e4	4.6e4	1.1e5	3.1e4	1	1.1e6	5.2e5	16e6	8.0e4	le-3	0	54e-2	19e-2	12e-1	3.2e4	le-3	0	54e-2	19e-2	12e-1	3.2e4
le-5	2	3.3e5	1.6e5	>7e5	2.5e4	0	13e-1	56e-2	41e-1	2.0e4	le-5	le-5	
le-8	2	3.3e5	1.6e5	>7e5	2.5e4	le-8	le-8	
<i>f₁₁₃</i> in 5-D, N=15, mFE=50020							<i>f₁₁₃</i> in 20-D, N=15, mFE=80039							<i>f₁₁₄</i> in 5-D, N=15, mFE=50032							<i>f₁₁₄</i> in 20-D, N=15, mFE=80042						
Δf	#	ERT	10%	90%	RT _{succ}	#	ERT	10%	90%	RT _{succ}	#	ERT	10%	90%	RT _{succ}	#	ERT	10%	90%	RT _{succ}	#	ERT	10%	90%	RT _{succ}		
10	15	2.0e2	1.4e2	2.7e2	2.0e2	0	22e+1	10e+1	56e+1	2.2e4	10	15	1.7e3	9.6e2	2.5e3	1.7e3	0	30e+1	18e+1	77e+1	2.0e4	10	15	1.7e3	9.6e2	2.5e3	1.7e3
1	13	1.7e4	1.2e4	2.3e4	1.6e4	1	5	1.1e5	7.5e4	2.0e5	4.2e4	1	5	1.1e5	7.5e4	2.0e5	4.2e4
le-1	1	7.4e5	3.7e5	>7e5	5.0e4	le-1	0	13e-1	35e-2	29e-1	8.9e3	le-1	0	13e-1	35e-2	29e-1	8.9e3
le-3	0	48e-2	21e-2	12e-1	2.5e4	le-3	le-3	
le-5	le-5	le-5		
le-8	le-8	le-8		
<i>f₁₁₅</i> in 5-D, N=15, mFE=50019							<i>f₁₁₅</i> in 20-D, N=15, mFE=80041							<i>f₁₁₆</i> in 5-D, N=15, mFE=50025													

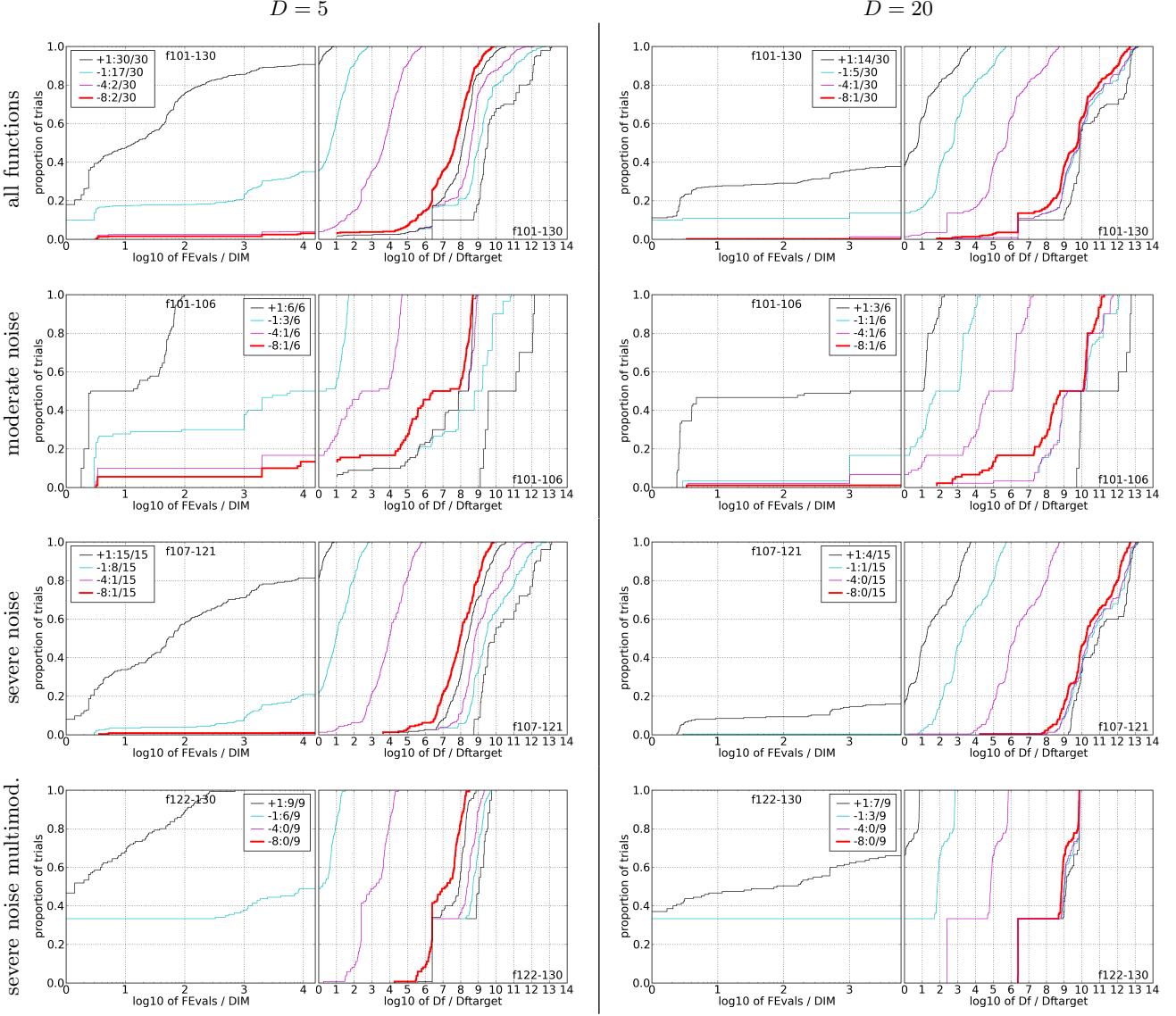


Figure 2: Empirical cumulative distribution functions (ECDFs), plotting the fraction of trials versus running time (left) or Δf . Left subplots: ECDF of the running time (number of function evaluations), divided by search space dimension D , to fall below $f_{\text{opt}} + \Delta f$ with $\Delta f = 10^k$, where k is the first value in the legend. Right subplots: ECDF of the best achieved Δf divided by 10^k (upper left lines in continuation of the left subplot), and best achieved Δf divided by 10^{-8} for running times of $D, 10D, 100D \dots$ function evaluations (from right to left cycling black-cyan-magenta). Top row: all results from all functions; second row: moderate noise functions; third row: severe noise functions; fourth row: severe noise and highly-multimodal functions. The legends indicate the number of functions that were solved in at least one trial. FEvals denotes number of function evaluations, D and DIM denote search space dimension, and Δf and Df denote the difference to the optimal function value.

f121 in 5-D, N=15, mFE=50011							f121 in 20-D, N=15, mFE=80026							f122 in 5-D, N=15, mFE=50026							f122 in 20-D, N=15, mFE=80037											
Δf	#	ERT	10%	90%	RT _{succ}		#	ERT	10%	90%	RT _{succ}		#	ERT	10%	90%	RT _{succ}		#	ERT	10%	90%	RT _{succ}		#	ERT	10%	90%	RT _{succ}			
10	15	1.3e1	8.0e0	1.8e1	1.3e1		15	3.9e3	2.3e3	5.5e3	3.9e3		10	15	2.8e1	1.3e1	4.5e1	2.8e1		15	1.1e4	4.3e3	1.9e4	1.1e4		15	1.1e4	4.3e3	1.9e4	1.1e4		
1	15	1.3e3	9.8e2	1.6e3	1.3e3		0	60e-1	39e-1	87e-1	1.0e4		1	13	2.2e4	1.5e4	3.1e4	1.8e4		0	77e-1	62e-1	90e-1	2.0e4								
1e-1	9	4.8e4	3.5e4	6.8e4	3.1e4			1e-1	0	54e-2	36e-2	11e-1	8.9e3			
le-3	0	88e-3	45e-3	20e-2	8.9e3			le-3		
le-5		le-5		
le-8		le-8		
f123 in 5-D, N=15, mFE=50024							f123 in 20-D, N=15, mFE=80043							f124 in 5-D, N=15, mFE=50016							f124 in 20-D, N=15, mFE=80033											
Δf	#	ERT	10%	90%	RT _{succ}		#	ERT	10%	90%	RT _{succ}		#	ERT	10%	90%	RT _{succ}		#	ERT	10%	90%	RT _{succ}		#	ERT	10%	90%	RT _{succ}			
10	15	7.1e1	1.8e1	1.3e2	7.1e1		9	6.2e4	4.0e4	9.1e4	4.0e4		10	15	9.7e0	7.1e0	1.2e1	9.7e0		15	2.3e3	7.7e2	4.0e3	2.3e3		15	2.3e3	7.7e2	4.0e3	2.3e3		
1	2	3.4e5	1.6e5	>7e5	2.6e4		0	87e-1	66e-1	16e+0	2.2e4		1	15	3.2e3	2.2e3	4.2e3	3.2e3		0	66e-1	49e-1	73e-1	2.0e4								
1e-1	0	16e-1	93e-2	18e-1	1.6e4			1e-1	0	55e-2	27e-2	84e-2	1.3e4			
le-3		le-3		
le-5		le-5		
le-8		le-8		
f125 in 5-D, N=15, mFE=50014							f125 in 20-D, N=15, mFE=80039							f126 in 5-D, N=15, mFE=50021							f126 in 20-D, N=15, mFE=80038											
Δf	#	ERT	10%	90%	RT _{succ}		#	ERT	10%	90%	RT _{succ}		#	ERT	10%	90%	RT _{succ}		#	ERT	10%	90%	RT _{succ}		#	ERT	10%	90%	RT _{succ}			
10	15	1.0e0	1.0e0	1.0e0	1.0e0		15	1.0e0	1.0e0	1.0e0	1.0e0		10	15	1.0e0	1.0e0	1.0e0	1.0e0		15	1.0e0	1.0e0	1.0e0	1.0e0		15	1.0e0	1.0e0	1.0e0	1.0e0		
1	15	1.0e0	1.0e0	1.0e0	1.0e0		15	1.0e0	1.0e0	1.0e0	1.0e0		1	15	1.0e0	1.0e0	1.0e0	1.0e0		15	1.0e0	1.0e0	1.0e0	1.0e0		15	1.0e0	1.0e0	1.0e0	1.0e0		
1e-1	15	1.0e0	1.0e0	1.0e0	1.0e0		15	1.0e0	1.0e0	1.0e0	1.0e0		1e-1	15	1.0e0	1.0e0	1.0e0	1.0e0		15	1.0e0	1.0e0	1.0e0	1.0e0		15	1.0e0	1.0e0	1.0e0	1.0e0		
le-3	0	15e-3	63e-4	25e-3	1.1e4		0	25e-3	25e-3	25e-3	1.0e0		le-3	0	25e-3	24e-3	25e-3	1.0e0		0	25e-3	25e-3	25e-3	1.0e0								
le-5		le-5		
le-8		le-8		
f127 in 5-D, N=15, mFE=50025							f127 in 20-D, N=15, mFE=80039							f128 in 5-D, N=15, mFE=50024							f128 in 20-D, N=15, mFE=80040											
Δf	#	ERT	10%	90%	RT _{succ}		#	ERT	10%	90%	RT _{succ}		#	ERT	10%	90%	RT _{succ}		#	ERT	10%	90%	RT _{succ}		#	ERT	10%	90%	RT _{succ}			
10	15	1.0e0	1.0e0	1.0e0	1.0e0		15	1.0e0	1.0e0	1.0e0	1.0e0		10	15	5.1e2	3.7e2	6.4e2	5.1e2		0	66e+0	60e+0	71e+0	2.8e4								
1	15	1.0e0	1.0e0	1.0e0	1.0e0		15	1.0e0	1.0e0	1.0e0	1.0e0		1	15	9.6e3	5.5e3	1.4e4	9.6e3			
1e-1	15	1.0e0	1.0e0	1.0e0	1.0e0		15	1.0e0	1.0e0	1.0e0	1.0e0		le-1	11	2.8e4	2.0e4	3.7e4	2.6e4			
le-3	0	25e-3	20e-3	25e-3	1.0e0		0	25e-3	25e-3	25e-3	1.0e0		le-3	1	7.4e5	3.6e5	>7e5	5.0e4			
le-5		le-5	0	49e-3	31e-4	18e-2	2.2e4		
le-8		le-8		
f129 in 5-D, N=15, mFE=50021							f129 in 20-D, N=15, mFE=80038							f130 in 5-D, N=15, mFE=50011							f130 in 20-D, N=15, mFE=80033											
Δf	#	ERT	10%	90%	RT _{succ}		#	ERT	10%	90%	RT _{succ}		#	ERT	10%	90%	RT _{succ}		#	ERT	10%	90%	RT _{succ}		#	ERT	10%	90%	RT _{succ}			
10	15	6.3e2	3.7e2	9.3e2	6.3e2		0	67e+0	58e+0	71e+0	2.0e4		10	15	2.2e2	1.4e2	3.0e2	2.2e2		5	1.8e5	1.2e5	3.3e5	7.2e4								
1	9	5.2e4	3.6e4	8.0e4	2.6e4			1	13	1.7e4	1.1e4	2.4e4	1.7e4		0	12e+0	73e-1	35e+0	2.8e4								
1e-1	4	1.7e5	1.0e5	3.5e5	4.5e4			le-1	6	8.7e4	5.7e4	1.5e5	3.4e4			
le-3	0	64e-2	52e-3	21e-1	1.8e4			le-3	0	35e-2	32e-4	11e-1	7.9e3			
le-5		le-5		
le-8		le-8		

Table 2: Shown are, for functions f_{121} - f_{130} and for a given target difference to the optimal function value Δf : the number of successful trials (#); the expected running time to surpass $f_{\text{opt}} + \Delta f$ (ERT, see Figure 1); the 10%-tile and 90%-tile of the bootstrap distribution of ERT; the average number of function evaluations in successful trials or, if none was successful, as last entry the median number of function evaluations to reach the best function value (RT_{succ}). If $f_{\text{opt}} + \Delta f$ was never reached, figures in *italics* denote the best achieved Δf -value of the median trial and the 10% and 90%-tile trial. Furthermore, N denotes the number of trials, and mFE denotes the maximum of number of function evaluations executed in one trial. See Figure 1 for the names of functions.