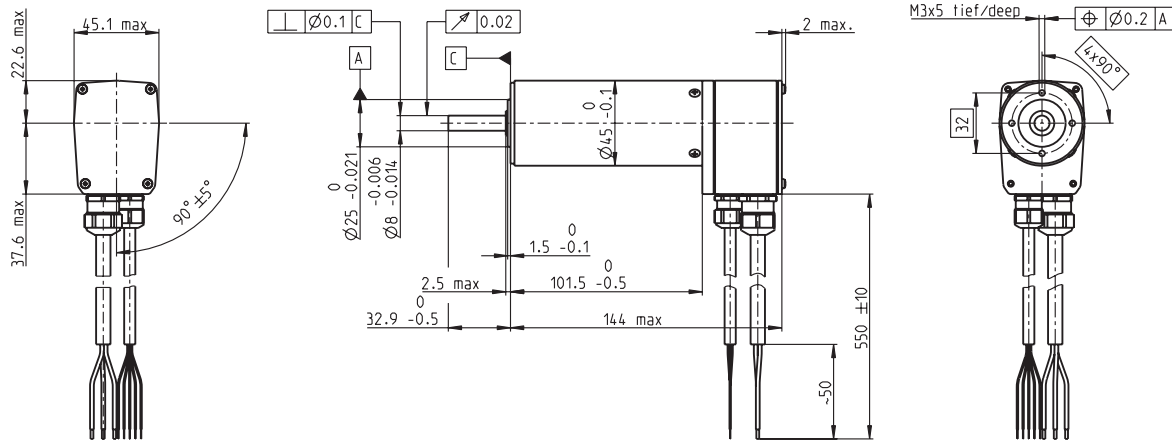


# EC 45 Ø45 mm, brushless, 250 Watt



M 1:4

- Stock program
- Standard program
- Special program (on request)

## Part Numbers

136210 136207 136211 136208 136212 136209

## Motor Data

Values at nominal voltage							
1 Nominal voltage	V	24	24	36	36	48	48
2 No load speed	rpm	8670	5000	10400	6010	10700	6160
3 No load current	mA	897	341	834	312	656	244
4 Nominal speed	rpm	7970	4300	9730	5320	10000	5490
5 Nominal torque (max. continuous torque)	mNm	311	331	312	341	316	347
6 Nominal current (max. continuous current)	A	12.5	7.51	10.2	6.21	7.94	4.86
7 Stall torque	mNm	4400	2540	5750	3320	6110	3530
8 Stall current	A	167	55.8	175	58.3	143	47.7
9 Max. efficiency	%	86	85	87	86	87	87
Characteristics							
10 Terminal resistance phase to phase	Ω	0.143	0.43	0.206	0.617	0.336	1.01
11 Terminal inductance phase to phase	mH	0.0565	0.17	0.0883	0.265	0.149	0.448
12 Torque constant	mNm/A	26.3	45.5	32.8	56.9	42.7	73.9
13 Speed constant	rpm/V	364	210	291	168	224	129
14 Speed/torque gradient	rpm/mNm	1.98	1.98	1.82	1.82	1.76	1.76
15 Mechanical time constant	ms	4.34	4.34	3.99	3.99	3.85	3.85
16 Rotor inertia	gcm <sup>2</sup>	209	209	209	209	209	209

## Specifications

Thermal data		
17 Thermal resistance housing-ambient	1.7 K/W	
18 Thermal resistance winding-housing	1.1 K/W	
19 Thermal time constant winding	31 s	
20 Thermal time constant motor	1570 s	
21 Ambient temperature	-20...+100°C	
22 Max. winding temperature	+125°C	

Mechanical data (preloaded ball bearings)		
23 Max. speed	12000 rpm	
24 Axial play at axial load < 20 N	0 mm	
24 Axial play at axial load > 20 N	max. 0.15 mm	
25 Radial play	preloaded	
26 Max. axial load (dynamic)	16 N	
27 Max. force for press fits (static)	182 N	
27 Max. force for press fits (static) (static, shaft supported)	5000 N	
28 Max. radial load, 5 mm from flange	180 N	

Other specifications		
29 Number of pole pairs	1	
30 Number of phases	3	
31 Weight of motor	1150 g	
Protection to	IP54*	

Values listed in the table are nominal.

### Connection motor (Cable AWG 16)

Cable 1	Motor winding 1
Cable 2	Motor winding 2
Cable 3	Motor winding 3

### Connection sensors (Cable AWG 24)<sup>1)</sup>

white	Hall sensor 3
brown	Hall sensor 2
green	Hall sensor 1
yellow	GND
grey	V <sub>Hall</sub> 4.5...24 VDC

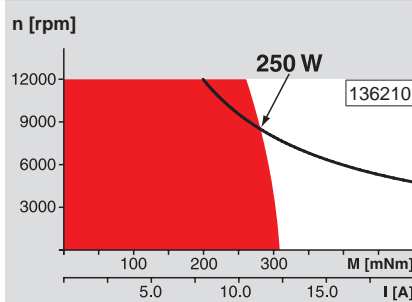
Wiring diagram for Hall sensors see p. 33

<sup>1)</sup> Not lead through in combination with resolver.

### Option

Temperature monitoring, PTC resistance Micropille  
110°C, R 25°C < 0.5 kΩ, R 105°C = 1.2...1.5 kΩ,  
R 115°C = 7...13 kΩ, R 120°C = 18...35 kΩ

## Operating Range



## Comments

■ **Continuous operation**  
In observation of above listed thermal resistance (lines 17 and 18) the maximum permissible winding temperature will be reached during continuous operation at 25°C ambient.  
= Thermal limit.

**Short term operation**  
The motor may be briefly overloaded (recurring).

— **Assigned power rating**

## maxon Modular System

Overview on page 20–25

### Planetary Gearhead

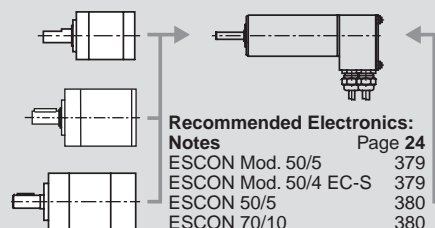
Ø42 mm  
3 - 15 Nm  
Page 314

### Planetary Gearhead

Ø52 mm  
4 - 30 Nm  
Page 319

### Planetary Gearhead

Ø62 mm  
8 - 50 Nm  
Page 320



### Recommended Electronics:

Notes	Page 24
ESCON Mod. 50/5	379
ESCON Mod. 50/4 EC-S	379
ESCON 50/5	380
ESCON 70/10	380
DEC Module 50/5	382
EPOS2 50/5, 70/10	387
EPOS3 70/10 EtherCAT	393
MAXPOS 50/5	396

### Encoder HEDL 9140

500 CPT,  
3 channels  
Page 368

### Resolver Res 26

Ø26 mm  
10 V  
Page 374

### Brake AB 28

24 VDC  
0.4 Nm  
Page 409

\*Protection level only when installed with flange-side seal.