

# Polar Plot

It is a graphical representation of the frequency response of a system. It displays the magnitude and phase of the system's transfer function as a function of frequency.

## frequency response

↳ How system responds to different frequencies

## Transfer function

↳ mathematical representation that describes the relationship b/w the input and output of the system in the frequency domain

## frequency domain ( $j\omega$ )

## Laplace domain ( $\sigma + j\omega$ )

# Differential Equation

## ⇒ Time Domain

↳ These equations are generated to describe the behaviour of dynamic systems such as mechanical systems, electrical ccts.

These equations typically represent how system variables such as position, velocity, displacement, voltage, current, temperature and pressure change over time in response to the input & disturbance.

eg:- (1) In Simple Mechanical system like a "Mass - Spring - Damper" system, Newton's 2<sup>nd</sup> law yields a second order ordinary differential equation (ODE) that describes the motion of the mass.

(2) In Electrical system, circuit containing resistors, capacitors, inductors, and Kirchhoff's Law yield differential equations governing the voltage and current relationships in the circuit.

(Graphical explanation)