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1.1

Consider $C^1(\mathbb{R})$ solutions of the differential equation $\dot{x}(t) = -x(t)$.

- Sketch all solutions in the x-t plane.
- What do they have in common?
- For T > 0, how do $x(0) \mapsto x(T)$ and $x(T) \mapsto x(0)$ differ qualitatively?
- Parameterize the family of solution curves implicitly à la $F(x,t,\lambda)=0$.
- Indicate the "Lie group orbits" $\lambda \mapsto F(x,t,\lambda)$ for various fixed (x,t).
- Find and solve a differential equation for the curve in the x-t plane that goes through (c,0) and is perpendicular to the solution curves.

1.2

A lake with constant volume V [m³] is fed by a river with flow rate r [m³/s]. A factory upstream begins releasing a pollutant into the river at a rate p [m³/s]. Propose and solve a differential equation for the concentration c(t) [m³/m³] of the pollutant in the lake.

1.3

Excerpt from R. Fisher, "The genetical theory of natural selection", 1930, p. 42:

An increase in numbers of any organism will impair its environment in a manner analogous to, and probably more definitely than, an increase in the numbers or efficiency of its competitors. [..] The situation is represented by the differential equation

$$\frac{dM}{dt} + \frac{M}{C} = W - D \tag{1}$$

in which M is the mean of the Malthusian parameter, C is a constant expressing the relation between fitness and population increase [..], W is the rate of actual increase in fitness determined by natural selection, and D is the rate of loss due to the deterioration of the environment. If C, W and D are constant the equation has the solution

$$M = \frac{W - D}{C} + Ae^{-t/C} \tag{2}$$

in which A is an arbitrary constant, dependent on the initial conditions.

Questions:

- What will the value of M approach to?
- What is the fate of the species in this model?

Find, if possible, a differential equation " $\dot{x}(t) = \dots$ " with a nontrivial solution in $C^1([0, \infty))$ for which x(t) = 0 for all t sufficiently large — i.e. x converges in finite time.

1.5

Let γ , g and $a \geq 0$ be continuous real-valued functions on [0, T].

• Sketch the function $s \mapsto A(s) := \exp(\int_s^T a(\tau) d\tau)$.

Suppose

$$\gamma(t) \le g(t) + \int_0^t \gamma(s)a(s)ds \quad \forall t \in [0, T]. \tag{3}$$

Prove

• the Gronwall–Bellman inequality:

$$\gamma(T) \le g(T) + \int_0^T g(s)a(s)A(s)ds. \tag{4}$$

• assuming that g is continuously differentiable, the corollary:

$$\gamma(T) \le g(0)A(0) + \int_0^T g'(s)A(s)ds.$$
 (5)

It may be helpful to start with a differential inequality for $x(t) := \int_0^t \gamma(s) a(s) ds$.

1.6

Fix T > 0, suppose $f: [0,T] \times \mathbb{R} \to \mathbb{R}$ is Lipschitz continuous in the second variable. Assume there exists a solution to the differential equation $\dot{x}(t) = f(t,x(t))$ on the interval (0,T) for any initial value near some fixed x_0 .

- Show that $x(0) \mapsto x(T)$ is Lipschitz continuous. Is your statement sharp?
- Do we need to assume existence?
- Suppose f depends on a parameter p. Fix $x_p(0)$. What is the derivative of the solution $x_p(T)$ w.r.t. p? Propose conditions on f for the derivative to exist.

Develop a solution formula to the initial value problem

$$\dot{x}(t) = g(t)h(x(t)), \qquad x(t_0) = x_0,$$
 (6)

in terms of the given functions g and h. Apply to

- $\dot{x}(t) = t x(t)$,
- $\dot{x}(t) = t/x(t)$,
- $\bullet \ \dot{x}(t) = x^2(t),$
- $\dot{x}(t) = \sqrt{x(t)}$,
- $\dot{x}(t) = (1+t^2)(1+x^2(t)),$
- $\dot{x}(t) = x(t) \log x(t)$.

What is the maximal temporal interval of existence in each case?

1.8

The following are simple (and simplistic) models for the volume of a growing tumor:

- $\dot{V} = aV$ (Exponential)
- $\dot{V} = aV^b$ (Mendelsohn)
- $\dot{V} = aV(1 \frac{1}{b}V)$ (Logistic)
- $\dot{V} = aV(b+V)^{-1}$ (Linear)
- $\dot{V} = aV(b+V)^{-1/3}$ (Surface)
- $\dot{V} = aV \log \frac{b}{c+V}$ (Gompertz)
- $\dot{V} = aV^{2/3} bV$ (Bertalanffy)

Herein, a, b and c are positive constants. For each model, answer the following questions:

- 1. What is the maximum size of the tumor?
- 2. What is the condition on the constants for positive growth?
- 3. What is then the doubling time?
- 4. What a possible motivation for the model?

Now add a term " $-\gamma V$ ".

- 5. Interpret this term.
- 6. What is now the maximum size of the tumor?
- 7. What is the minimum concentration γ for complete cure?

Using the experimental data from

https://www.nature.com/articles/s41598-019-39109-1/figures/4 select a suitable model for Fig. 4a and 4b and estimate the parameters.

1.9

Give the maximal interval of existence $(0, t^*)$ for the initial value problem $\dot{x}(t) = x^2(t)$ with $x(0) := x_0 > 0$.

- Why is t^* called the "blow up time"?
- Can you continue the solution past the blow up time?

Now consider $\dot{z}(t) = z^2(t)$, t > 0, for a complex-valued function z with the intial value $z(0) = x_0 + i\epsilon$, where $x_0 > 0$ and $\epsilon \neq 0$ are real. Where needed, assume $x_0 = 1$.

- What happens to the blow up time?
- Decomposing z = x + iy, write down the differential equations for x and y.
- Argue that $x^2(t) + (y(t) R_0)^2 = R_0^2$ for a certain real constant R_0 and comment.
- Sketch the evolution in (t, x, y)-space for a small $\epsilon > 0$. What happens for $\epsilon \searrow 0$?

1.10

Develop a solution formula to the initial value problem

$$\dot{x}(t) = a(t)x(t) + b(t), \qquad x(t_0) = x_0,$$
 (7)

in terms of the given functions a and b.

- Suppose a and b are independent of t. Investigate the limits $a \to 0$ and $b \to 0$.
- Apply your formula to $t \dot{x}(t) = 2x(t) + t$. Don't forget to discuss t = 0.
- Check your formula on examples of your choice.
- Is this a good model for global seafood stock?
- Via a suitable transformation, solve $\dot{y}(t) = y(t) y^{\alpha}(t)$, where $\alpha \in \mathbb{R}$. What is remarkable about this "Bernoulli differential equation"?
- Solve the "logistic differential equation" $\dot{y}(t) = y(t)(1 y(t))$ with $0 \le y(0) \le 1$. Explain this model in terms of "growth" and "competition".
- Propose a better model for global seafood stock.

Derive the Tsiolkovsky equation

$$\Delta v = v_{\text{exhaust}} \log \frac{m_{\text{before}}}{m_{\text{after}}} \tag{8}$$

that gives the velocity acquired by a propulsion rocket (no external forces).

1.12

Propose a nontrivial system of differential equations " $\dot{x}(t) = \dots$," $\dot{y}(t) = \dots$ " together with an initial condition at t = 0 for which the function

$$t \mapsto v(t) := x^2(t) + y^2(t) \tag{9}$$

satisfies, for all t > 0,

- $\dot{v}(t) = -2v(t)$.
- $\dot{v}(t) = 0$.
- $\dot{v}(t) = 2x(t) + 2y(t)$.

In each case, comment graphically on the possible trajectories $t \mapsto (x(t), y(t))$ in \mathbb{R}^2 .

1.13

On the "spatial" interval I:=(0,1) define the functions $\varphi_k:=\sqrt{2}\sin(\pi k\cdot)$. Check whether the set $\Phi:=\{\varphi_k:k=1,2,3,\ldots\}$ is

- orthonormal in the Lebesgue space $L_2(I)$,
- a basis thereof.

Now consider the heat equation

$$\partial_t u(t,x) - \partial_{xx} u(t,x) = f(t,x), \qquad t > 0, \quad x \in I, \tag{10}$$

with the initial condition $u(0, \cdot) = g$ and the boundary conditions $u|_{\partial I} = 0$.

- What is the physical motivation for this PDE?
- Solve the PDE formally by expansion in a suitable spatial basis.
- What qualitative properties of u can you infer?
- Can you propose a suitable functional framework?
- Does the solution u depend continuously on the data f and g?

Let $A \in \mathbb{R}^{N \times N}$ be a symmetric positive definite matrix. Let J := (0, T) be a nontrivial interval. Let $g \in \mathbb{R}^N$ and $f : J \to \mathbb{R}^N$ continuous. Consider the bilinear form

$$B(u,v) := \int_{J} \{ \langle Au, v \rangle + \langle A^{-1}\dot{u}, \dot{v} \rangle \} dt + \langle u(T), v(T) \rangle$$
 (11)

and the functional

$$F(v) := \int_{J} \langle f, v + A^{-1} \dot{v} \rangle dt + \langle g, v(0) \rangle, \tag{12}$$

defined for arbitrary continuously differentiable $u, v \colon J \to \mathbb{R}^N$.

- What can you say about the functional $\mathcal{J}(u) := \frac{1}{2}B(u,u) F(u)$?
- Does \mathcal{J} have a minimum?
- What is the variational first order condition for the minimum of \mathcal{J} ?
- What is the differential equation satisfied by the minimum?
- What are practical implications?

1.15

Consider the first order system of differential equations for N functions $\mathbf{x}_i \colon \mathbb{R} \to \mathbb{R}^d$,

$$\dot{\mathbf{x}}_i = \frac{1}{N} \sum_{j \neq i} \phi(|\mathbf{x}_j - \mathbf{x}_i|)(\mathbf{x}_j - \mathbf{x}_i), \quad i = 1, \dots, N,$$
(13)

where ϕ is the "influence function", say $\phi(r) := (1+r)^{-s}$ for some s > 0.

- Explain qualitatively the behavior of the model.
- What could this be a model for?
- Find an invariant.
- What do you expect to happen in the long run?
- Can you verify your hypothesis?

Consider the modified system

$$\dot{\mathbf{x}}_i = \frac{1}{N} \sum_{j \neq i} \frac{\phi_{ij}}{\sum_k \phi_{ik}} (\mathbf{x}_j - \mathbf{x}_i), \tag{14}$$

where $\phi_{ij} := \phi(|\mathbf{x}_j - \mathbf{x}_i|)$.

- What could be the motivation for this modification?
- How does this system differ from the previous one in an essential way?

These days, papers are published with a short abstract or even with a few "highlights" as bullet points. Write the "highlights" emphasizing the role of differential equations for

R. M. Solow, A contribution to the theory of economic growth, The quarterly journal of economics, 70 (1956), pp. 65–94.

according to Elsevier's guidelines:

https://www.elsevier.com/authors/journal-authors/highlights

1.17

The following is from the IMO 2011, a problem by Geoffrey Smith (UK):

Let S be a set of $N \geq 2$ points in the plane (no three points are collinear). A windmill is a process that starts with a line ℓ_0 through a single point $P_0 \in S$. The line rotates clockwise about the pivot P_0 until it meets some other point $P_1 \in S$. This point takes over as the new pivot, and so on.

Describe this windmill as a differential equation.

Optionally, solve the problem itself:

Show that there is a choice of P_0 and ℓ_0 for which the resulting windmill meets each point of S infinitely many times.

1.18

The Navier–Stokes equations in cylindrical coordinates for a fluid flowing through a round pipe reduce (under reasonable assumptions of steady, symmetric, laminar and fully developed flow) to

$$\frac{1}{r}\frac{d}{dr}\left(r\mu\frac{du}{dr}\right) = \frac{dp}{dz},\tag{15}$$

where u is the axial velocity along the pipe (independent of z) and p is the pressure (independent of r), as functions of the radial coordinate r and the axial coordinate z. We use SI units; the constant μ is the dynamic viscosity $[Pa \times s]$ of the fluid that expresses its resistance to flow. The "no-slip" boundary conditions dictate that the velocity must be zero at the wall.

- Why are both sides equal to some constant, and what is the physical meaning of this constant?
- The pressure drop across the pipe of length L is $\Delta P < 0$. What is the flow rate $[\text{m}^3/\text{s}]$ of the fluid through the pipe?
- Estimate the flow rate at the water tap and thus the pressure at the source.

For each natural N, let $(X_t^{(N)})_{t\geq 0}$ be a family of random variables. Define a second family by $Y_t^{(N)}:=X_t^{(N)}/N$. Set $y(t):=\lim_{N\to\infty}\mathbb{E}[Y_t^{(N)}]$, assuming the limit exists. Derive a differential equation for y where the process $X_t^{(N)}$ is

- the Poisson process with rate $\lambda > 0$;
- \bullet the queue with Poisson arrivals at rate N and exponential service times of mean 1.

1.20

Let J be the $n \times n$ matrix

$$J := \lambda I + N \quad \text{where} \quad \lambda \in \mathbb{C} \quad \text{and} \quad N := \begin{pmatrix} 0 & 1 \\ & \ddots & \ddots \\ & & 0 & 1 \end{pmatrix}.$$
 (16)

Derive an expression for $\exp(tJ)$, $t \in \mathbb{R}$.