

```

1
2
3  /*
4  *      TRIANGULOS E CIRCULOS
5  *
6  */
7
8
9
10 struct circle{
11     pv c;
12     double r;
13     circle(){c=pv(); r=0.0;}
14     circle(pv a, double p) : c(a), r(p) {}
15 };
16
17
18
19 bool inside_circle(pv a, circle C){
20
21     double c1_sq = (a.x - C.p.x)*(a.x - C.p.x);
22     double c2_sq = (a.y - C.p.y)*(a.y - C.p.y);
23     return (c1_sq + c2_sq) <= C.r*C.r;
24
25 }
26
27
28
29
30 double rCircumCircle(point a, point b, point c) {
31
32     double ab = dist(a, b), bc = dist(b, c), ac = dist(a, c);
33
34
35     double area = 0.5*cross(b-a, c-a);
36     double ans = (ab * bc * ac) / (4.0 * area);
37
38     return ans;
39 }
40
41
42
43 bool center_circum_circle(pv o, pv p, pv q, pv &c){
44
45     if(colinear(o, p, q)) return false;
46
47     pv meio_op = o + ((p-o)*0.5);
48     pv perp_op = perp_vec(p-o);
49     line l1 = line(meio_op, perp_op); //mediatriz do segmento op
50
51
52     pv meio_pq = p + ((q-p)*0.5);
53     pv perp_pq = perp_vec(q-p);
54     line l2 = line(meio_pq, perp_pq); //mediatriz do segmento pq
55
56
57     line_intersection(l1, l2, c);
58     return true;
59 }
60

```

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61
62
63 bool center_in_circle(pv a, pv b, pv c, pv &ans){
64
65     if(colinear(a, b, c)) return false;
66
67     line l1 = bisettriz(a, b, c);
68     line l2 = bisettriz(b, c, a);
69
70     line_intersection(l1, l2, ans);
71     return true;
72 }
73
74
75
76
77 bool center_2ptsR(pv a, pv b, double r, pv &c1, pv &c2){
78
79     pv meio = a + ((b-a)*0.5);
80     pv p = unit_vec(perp_vec(b-a));
81     double d = dist(a, b), aux = r*r - ((d*d)*0.25);
82
83     if(aux < 0.0) return false;//raio muito pequeno
84
85     //r2 = d2/4.0 + h2
86
87
88     double h = sqrt( aux );
89     c1 = meio + (p*h);
90     c2 = meio + (p*(-h));
91     return true;
92 }
93

```