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Section: 07 Group No. 5

```
#include"tishitu_root.h"
void main(void)
{
unsigned int read=0;
unsigned int c=1;
P0_0=0x00;
P0_1=0x00;
init_lcd();
loading(100);
secondline();
 display("Auto water tank controller");
 msdelay(2000);
while(1)
if((P2_3==0)&&(P2_0==1))
{
P0_0=0;
P0_1=1;
firstline();
display("motor off ");
secondline();
display("alarm on");
```

```
msdelay(1000);
if((P2_3==0)&&(P2_0==0))
{P0_0=0;
P0_1=1;
firstline();
display("motor off ");
secondline();
display("alarm on");
msdelay(1000);
}
if(c==1)
if((P2_3==1)&&(P2_2==1)&&(P2_1==1)&&(P2_0==1)&&(c==1))
{P0_0=0;
P0_1=0;
firstline();
display("motor off ");
secondline();
display("alarm off");
msdelay(1000);
if((P2_3==1)&&(P2_2==1)&&(P2_1==1)&&(P2_0==0)&&(c==1))
{P0_0=1;
P0_1=0;
firstline();
display("motor on ");
secondline();
display("alarm off");
msdelay(1000);
```

```
}
if((P2_3==1)&&(P2_2==0)&&(P2_1==1)&&(P2_0==1)&&(c==1))
{P0_0=0;
P0_1=1;
firstline();
display("motor off ");
secondline();
display("alarm on");
msdelay(1000);
if((P2_3==1)&&(P2_2==0)&&(P2_1==1)&&(P2_0==0)&&(c==1))
{P0_0=0;
P0_1=1;
firstline();
display("motor off ");
secondline();
display("alarm on");
msdelay(1000);
}
if((P2_3==1)&&(P2_2==1)&&(P2_1==0)&&(P2_0==1)&&(c==1))
{P0_0=0;
P0_1=0;
firstline();
display("motor off ");
secondline();
display("alarm off");
msdelay(1000);
if((P2_3==1)&&(P2_2==1)&&(P2_1==0)&&(P2_0==0)&&(c==1))
{P0_0=1;
```

```
P0_1=0;
firstline();
display("motor on ");
secondline();
display("alarm off");
msdelay(1000);
}
if(P2_2==0)
{c=0;}
if(c==0)
if((P2_3==1)&&(P2_2==0)&&(P2_1==0)&&(P2_0==1)&&(c==0))
{P0_0=0;
P0_1=0;
firstline();
display("motor off ");
secondline();
display("alarm off");
msdelay(1000);
if((P2_3==1)&&(P2_2==0)&&(P2_1==0)&&(P2_0==0)&&(c==0))
{P0_0=0;
P0_1=0;
firstline();
display("motor off ");
secondline();
display("alarm off");
msdelay(1000);
}
```

```
if((P2_3==1)&&(P2_2==1)&&(P2_1==0)&&(P2_0==1)&&(c==0))
{P0_0=0;
P0_1=0;
firstline();
display("motor off ");
secondline();
display("alarm off");
msdelay(1000);
if((P2_3==1)&&(P2_2==1)&&(P2_1==0)&&(P2_0==0)&&(c==0))
{P0_0=0;
P0_1=0;
 firstline();
display("motor off ");
secondline();
display("alarm off");
msdelay(1000);
}
if(P2_1==1)
c=1;
}
}
```