

Computational Companion to “Flexible 3×3 Nets of Equimodular Elliptic Type” — PROOF OF THE EXISTENCE CRITERION

Author: Abdukhomid Nurmatov

Tested on: Mathematica 14.0

Section 1

Results of Section 1 is used in Lemma 1

```
In[ ]:= (*define*)
σ = (α + β + γ + δ) / 2;
a = Sin[α] / Sin[σ - α];
b = Sin[β] / Sin[σ - β];
c = Sin[γ] / Sin[σ - γ];
d = Sin[δ] / Sin[σ - δ];
M = a b c d;

(*check equalities*)
FullSimplify[1 - a b - Sin[σ] Sin[σ - α - β] / (Sin[σ - α] Sin[σ - β]) == 0]
FullSimplify[1 - b c - Sin[σ] Sin[σ - γ - β] / (Sin[σ - γ] Sin[σ - β]) == 0]
FullSimplify[1 - b d - Sin[σ] Sin[σ - δ - β] / (Sin[σ - δ] Sin[σ - β]) == 0]

FullSimplify[c d - 1 - Sin[σ] Sin[σ - α - β] / (Sin[σ - γ] Sin[σ - δ]) == 0]
FullSimplify[a d - 1 - Sin[σ] Sin[σ - γ - β] / (Sin[σ - α] Sin[σ - δ]) == 0]
FullSimplify[a c - 1 - Sin[σ] Sin[σ - δ - β] / (Sin[σ - α] Sin[σ - γ]) == 0]

FullSimplify[1 - M - Sin[σ] Sin[σ - α - β] Sin[σ - γ - β]
Sin[σ - δ - β] / (Sin[σ - α] Sin[σ - β] Sin[σ - γ] Sin[σ - δ]) == 0]

Out[ ]:=
True

Out[ ]:=
True
```

```
Out[ ]=
      True
```

```
Out[ ]=
      True
```

```
Out[ ]=
      True
```

```
Out[ ]=
      True
```

```
Out[ ]=
      True
```

Section 2

Results of Section 2 is used in Proof of Proposition 2

```

In[*]:= (*define*)

$$\sigma = (\alpha + \beta + \gamma + \delta) / 2;$$


(*check equalities*)
(*Cos[α]*)
FullSimplify[
  (ε (Sin[σ - β] Sin[σ] + Sin[σ - α] Sin[σ - α - β] - Sin[σ - γ] Sin[σ - γ - β] -
    Sin[σ - δ] Sin[σ - δ - β])) / (2 Sin[γ] Sin[δ]) == ε Cos[α]]

(*Cos[β]*)
FullSimplify[
  (ε (Sin[σ - α] Sin[σ] + Sin[σ - β] Sin[σ - α - β] + Sin[σ - δ] Sin[σ - γ - β] +
    Sin[σ - γ] Sin[σ - δ - β])) / (2 Sin[γ] Sin[δ]) == ε Cos[β]]

(*Cos[γ]*)
FullSimplify[
  (ε (Sin[σ - β] Sin[σ] - Sin[σ - α] Sin[σ - α - β] + Sin[σ - γ] Sin[σ - γ - β] -
    Sin[σ - δ] Sin[σ - δ - β])) / (2 Sin[α] Sin[δ]) == ε Cos[γ]]

(*Cos[δ]*)
FullSimplify[
  (ε (Sin[σ - β] Sin[σ] - Sin[σ - α] Sin[σ - α - β] - Sin[σ - γ] Sin[σ - γ - β] +
    Sin[σ - δ] Sin[σ - δ - β])) / (2 Sin[α] Sin[γ]) == ε Cos[δ]]

(*Cos[σ]*)
FullSimplify[(Sin[σ - β] Sin[σ] ^2 - Sin[σ - α] Sin[σ - α - β] Sin[σ] -
  Sin[σ - γ] Sin[σ - γ - β] Sin[σ] - Sin[σ - δ] Sin[σ - δ - β] Sin[σ] -
  2 Sin[σ - α] Sin[σ - γ] Sin[σ - δ]) / (2 Sin[α] Sin[γ] Sin[δ]) == Cos[σ]]

```

Out[*]=

True

Out[*]=

True

Out[*]=

True

Out[*]=

True

Out[*]=

True

Section 3

Results of Section 3 is used in Proof of Lemma 7

```

In[*]:= (*define*)
 $\sigma = (\alpha + \beta + \gamma + \delta) / 2;$ 
thetaIndex[k_] := Mod[k - 1, 4] + 1; (*cyclic index:1..4*)
A[i_, j_] /; 1 ≤ i ≤ 4 && 1 ≤ j ≤ 4 :=
  4 Cos[ $\theta$ [thetaIndex[i]] / 2 + (Pi / 4) i j (j - 1) + (Pi / 2) j]^2 *
  Cos[ $\theta$ [thetaIndex[i - 1]] / 2 + (Pi / 4) (i - 1) j (j - 1) + (Pi / 2) j]^2;
(*Table[A[i,j],{i,1,4},{j,1,4}];*)
 $\xi[i\_?IntegerQ]$  /; 1 ≤ i ≤ 4 :=
  If[OddQ[i],  $\theta$ [thetaIndex[i]],  $\theta$ [thetaIndex[i - 1]]];
 $\eta[i\_?IntegerQ]$  /; 1 ≤ i ≤ 4 := If[OddQ[i],  $\theta$ [thetaIndex[i - 1]],  $\theta$ [thetaIndex[i]]];
(*Table[{i, $\xi$ [i], $\eta$ [i]},{i,1,4}];*)

(*check equalities*)
lhs[i_Integer] :=  $\varepsilon$  (A[i, 1] Sin[ $\sigma - \beta$ ] Sin[ $\sigma$ ] + A[i, 2] Sin[ $\sigma - \gamma$ ] Sin[ $\sigma - \gamma - \beta$ ] +
  A[i, 3] Sin[ $\sigma - \alpha$ ] Sin[ $\sigma - \alpha - \beta$ ] +
  A[i, 4] Sin[ $\sigma - \delta$ ] Sin[ $\sigma - \delta - \beta$ ]) / (2 Sin[ $\alpha$ ] Sin[ $\gamma$ ]);
rhs[i_Integer] :=
   $\varepsilon$  (Cos[ $\beta$ ] - Cos[ $\gamma$ ] (Cos[ $\alpha$ ] Cos[ $\delta$ ] + Cos[ $\xi$ [i]] Sin[ $\alpha$ ] Sin[ $\delta$ ]) - Cos[ $\eta$ [i]]
  Sin[ $\gamma$ ] (Cos[ $\alpha$ ] Sin[ $\delta$ ] - Cos[ $\xi$ [i]] Sin[ $\alpha$ ] Cos[ $\delta$ ])) / (Sin[ $\alpha$ ] Sin[ $\gamma$ ]);
expr[i_Integer] := FullSimplify[Equal[lhs[i], rhs[i]]];
(*---Evaluate for i=1..4---*)
Table[{i, expr[i]}, {i, 1, 4}]

Out[*]=
{{1, True}, {2, True}, {3, True}, {4, True}}
```

Section 4

Result of Section 4 is used in Proof of Lemma 9 in Appendix D

```
In[*]:= (*define*)
σ = (α2 + β2 + γ2 + δ2) / 2;
(*D_{α2 θ1}*)
Dα2θ1 =
  Sqrt[Sin[θ1]^2 Sin[α2]^2 + (Cos[α2] Sin[δ2] - Cos[θ1] Sin[α2] Cos[δ2])^2];
(*R_{α2 γ2 θ1} =
  (cos β2 - cos γ2 (cos α2 cos δ2 + cos θ1 sin α2 sin δ2)) / (D_{α2 θ1} sin γ2)*)
Rα2γ2θ1 = (Cos[β2] - Cos[γ2] (Cos[α2] Cos[δ2] + Cos[θ1] Sin[α2] Sin[δ2])) /
  (Dα2θ1 Sin[γ2]);

(*check equality*)
FullSimplify[Rα2γ2θ1^2 - 1 == (4 Sin[α2]^2 Sin[δ2]^2) / (Dα2θ1^2 Sin[γ2]^2) *
  (Sin[θ1/2]^2 - (Sin[σ - α2 - β2] Sin[σ - δ2 - β2]) / (Sin[α2] Sin[δ2])) *
  (Sin[θ1/2]^2 - (Sin[σ - α2] Sin[σ - δ2]) / (Sin[α2] Sin[δ2]))]
```

Out[*]=

True