Computational Companion to "Quasi-Symmetric Nets: A Constructive Approach to the Equimodular Elliptic Type of Kokotsakis Polyhedra" — Criterion Helper

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Section 1

Results of Section 1 is used in Lemma 1 (see paper) and in Sections 2 and 3 of this file

```
(*Clear all previous definitions*)
ClearAll [\alpha, \beta, \gamma, \delta, \sigma, \bar{\alpha}, \bar{\beta}, \bar{\gamma}, \bar{\delta}, a, b, c, d, M]
(*Define the angles and variables*)
\sigma = (\alpha + \beta + \gamma + \delta) / 2;
\bar{\alpha} = \sigma - \alpha;
\beta = \sigma - \beta;
\bar{\gamma} = \sigma - \gamma;
\bar{\delta} = \sigma - \delta;
a = Sin[\alpha] / Sin[\bar{\alpha}];
b = Sin[\beta] / Sin[\bar{\beta}];
c = Sin[\gamma] / Sin[\bar{\gamma}];
d = Sin[\delta] / Sin[\bar{\delta}];
M = a * b * c * d;
(*Define the 7 identities*)
expr1 = 1 - a * b = Sin[\sigma] * Sin[\bar{\alpha} - \beta] / (Sin[\bar{\alpha}] * Sin[\bar{\beta}]);
expr2 = 1 - b * c = Sin[\sigma] * Sin[\bar{\gamma} - \beta] / (Sin[\bar{\gamma}] * Sin[\bar{\beta}]);
expr3 = 1 - b * d = Sin[\sigma] * Sin[\bar{\delta} - \beta] / (Sin[\bar{\delta}] * Sin[\bar{\beta}]);
expr4 = c * d - 1 = Sin[\sigma] * Sin[\bar{\alpha} - \beta] / (Sin[\bar{\gamma}] * Sin[\bar{\delta}]);
expr5 = a * d - 1 = Sin[\sigma] * Sin[\bar{\gamma} - \beta] / (Sin[\bar{\alpha}] * Sin[\bar{\delta}]);
expr6 = a * c - 1 = Sin[\sigma] * Sin[\bar{\delta} - \beta] / (Sin[\bar{\alpha}] * Sin[\bar{\gamma}]);
expr7 = 1 - M ==
     Sin[\sigma] * Sin[\bar{\alpha} - \beta] * Sin[\bar{\gamma} - \beta] * Sin[\bar{\delta} - \beta] / (Sin[\bar{\alpha}] * Sin[\bar{\beta}] * Sin[\bar{\gamma}] * Sin[\bar{\delta}]);
(*Store the expressions and labels*)
lhs = {"1 - ab", "1 - bc", "1 - bd", "cd - 1", "ad - 1", "ac - 1", "1 - M"};
    \{"\sin(\sigma)\sin(\bar{\alpha} - \beta) / (\sin(\bar{\alpha})\sin(\bar{\beta}))", "\sin(\sigma)\sin(\bar{\gamma} - \beta) / (\sin(\bar{\beta})\sin(\bar{\gamma}))", \}
     "\sin(\sigma)\sin(\bar{\delta} - \beta) / (\sin(\bar{\beta})\sin(\bar{\delta}))", "\sin(\sigma)\sin(\bar{\alpha} - \beta) / (\sin(\bar{\gamma})\sin(\bar{\delta})",
     "\sin(\sigma)\sin(\bar{\gamma} - \beta) / (\sin(\bar{\alpha})\sin(\bar{\delta}))", "\sin(\sigma)\sin(\bar{\delta} - \beta) / (\sin(\bar{\alpha})\sin(\bar{\gamma}))",
     "\sin(\sigma)\sin(\bar{\alpha} - \beta)\sin(\bar{\gamma} - \beta)\sin(\bar{\delta} - \beta) / (\sin(\bar{\alpha})\sin(\bar{\beta})\sin(\bar{\gamma})\sin(\bar{\delta}))"};
expressions = {expr1, expr2, expr3, expr4, expr5, expr6, expr7};
(*Function to test equality*)
isTrueQ[expr_] := TrueQ[FullSimplify[expr]]
(*Build the result table*)
TableForm[Table[{lhs[i]], rhs[i]], If[isTrueQ[expressions[i]]], "√", "x"]},
    {i, Length[expressions]}],
 TableHeadings → {None, {"LHS", "RHS", "LHS = RHS?"}}]
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```
Out[ • ]//TableForm=
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```
RHS
LHS
                    \sin(\sigma)\sin(\bar{\alpha} - \beta) / (\sin(\bar{\alpha})\sin(\bar{\beta}))
1 – ab
1 - bc
                    \sin(\sigma)\sin(\bar{\mathbf{y}} - \beta) / (\sin(\bar{\mathbf{\beta}})\sin(\bar{\mathbf{y}}))
                    \sin(\sigma)\sin(\bar{\delta} - \beta) / (\sin(\bar{\beta})\sin(\bar{\delta}))
1 - bd
cd - 1
                    \sin(\sigma)\sin(\bar{\alpha} - \beta) / (\sin(\bar{\gamma})\sin(\bar{\delta})
                    \sin(\sigma)\sin(\bar{\mathbf{y}} - \beta) / (\sin(\bar{\mathbf{\alpha}})\sin(\bar{\mathbf{\delta}}))
ad - 1
                    \sin(\sigma)\sin(\bar{\delta} - \beta) / (\sin(\bar{\alpha})\sin(\bar{\gamma}))
ac – 1
                    \sin(\sigma)\sin(\bar{\alpha} - \beta)\sin(\bar{\gamma} - \beta)\sin(\bar{\delta} - \beta) / (\sin(\bar{\alpha})\sin(\bar{\beta})\sin(\bar{\gamma})\sin(\bar{\delta}))
1 - M
```

Section 2

Results of Section 2 is used in the proof of Lemma 6 (see paper)

```
(*Clear all previous definitions*)
ClearAll [\alpha, \beta, \gamma, \delta, \sigma, \bar{\alpha}, \bar{\beta}, \bar{\gamma}, \bar{\delta}, u, x, y, z, d1, d2, d3, d4, d5,
  rhsCosAlpha, rhsCosBeta, rhsCosGamma, rhsCosDelta, rhsCosSigma]
(*Define assumptions for the angles*)
assumptions = \{0 < \alpha < Pi, 0 < \beta < Pi, 0 < \gamma < Pi, \}
     0 < \delta < Pi, 0 < \bar{\alpha} < Pi, 0 < \bar{\beta} < Pi, 0 < \bar{\gamma} < Pi, 0 < \bar{\delta} < Pi};
(*Define the angles and intermediate variables*)
\sigma = (\alpha + \beta + \gamma + \delta) / 2;
\bar{\alpha} = \sigma - \alpha;
\bar{\beta} = \sigma - \beta;
\bar{\gamma} = \sigma - \gamma;
\bar{\mathbf{\delta}} = \sigma - \delta;
\varepsilon = Abs[Sin[\sigma]] / Sin[\sigma];
(*Define Section 1 results*)
OneMinusM =
   Sin[\sigma] * Sin[\bar{\alpha} - \beta] * Sin[\bar{\gamma} - \beta] * Sin[\bar{\delta} - \beta] / (Sin[\bar{\alpha}] * Sin[\bar{\beta}] * Sin[\bar{\gamma}] * Sin[\bar{\delta}]);
rMinusOne = Sin[\sigma] * Sin[\bar{\gamma} - \beta] / (Sin[\bar{\alpha}] * Sin[\bar{\delta}]);
sMinusOne = Sin[\sigma] * Sin[\bar{\alpha} - \beta] / (Sin[\bar{\gamma}] * Sin[\bar{\delta}]);
fMinusOne = Sin[\sigma] * Sin[\bar{\delta} - \beta] / (Sin[\bar{\alpha}] * Sin[\bar{\gamma}]);
u = OneMinusM;
x = 1 / rMinusOne;
y = 1 / sMinusOne;
z = 1 / fMinusOne;
(*Define expressions in denominators*)
d1 = x * z * u * (1 + y) * (1 + u * y);
d2 = y * z * u * (1 + x) * (1 + u * x);
```

```
4 | criterion_helper_Last.nb
        d3 = x * y * u * (1 + z) * (1 + u * z);
        d4 = u * (1 + x) * (1 + y) * (1 + z) * (1 + u * x) * (1 + u * y) * (1 + u * z);
        d5 = x * y * z * u^2 * (1 + x) * (1 + y) * (1 + z);
         (*Define denominators*)
        denAlpha = 2 * FullSimplify[Sqrt[d1], assumptions];
        denBeta = 2 * FullSimplify[Sqrt[d4], assumptions];
        denGamma = 2 * FullSimplify[Sqrt[d2], assumptions];
        denDelta = 2 * FullSimplify[Sqrt[d3], assumptions];
        denSigma = 2 * FullSimplify[Sqrt[d5], assumptions];
         (*Define RHS expressions*)
        rhsCosAlpha = FullSimplify[\varepsilon * (1 - y * z * u + x * z * u - x * y * u) / denAlpha] /.
             Cos[\beta] - Cos[\alpha + \gamma + \delta] \Rightarrow 2 Sin[(\alpha + \beta + \gamma + \delta) / 2] Sin[(\alpha - \beta + \gamma + \delta) / 2];
        rhsCosBeta =
           FullSimplify [\varepsilon * (u * (1+x) * (1+y) * (1+z) + (1+u * x) * (1+u * y) * (1+u * z) -
                     u * x * y * z * (u - 1)^2) / denBeta] /.
             Cos[\alpha] - Cos[\beta + \gamma + \delta] \Rightarrow 2 Sin[(\alpha + \beta + \gamma + \delta) / 2] Sin[(-\alpha + \beta + \gamma + \delta) / 2];
        rhsCosGamma = FullSimplify[\varepsilon * (1 + y * z * u - x * z * u - x * y * u) / denGamma] /.
             Cos[\beta] - Cos[\alpha + \gamma + \delta] \Rightarrow 2 Sin[(\alpha + \beta + \gamma + \delta) / 2] Sin[(\alpha - \beta + \gamma + \delta) / 2];
        rhsCosDelta = FullSimplify[\varepsilon * (1 - y * z * u - x * z * u + x * y * u) / denDelta] /.
             Cos[\beta] - Cos[\alpha + \gamma + \delta] \Rightarrow 2 Sin[(\alpha + \beta + \gamma + \delta) / 2] Sin[(\alpha - \beta + \gamma + \delta) / 2];
        rhsCosSigma = (1 - u * (x * y + x * z + y * z + 2 * x * y * z)) / denSigma;
         (*Define equations to check*)
        exprAlpha = Cos[\alpha] == FullSimplify[rhsCosAlpha, assumptions];
        exprBeta = Cos[β] == FullSimplify[rhsCosBeta, assumptions];
        exprGamma = Cos[γ] == FullSimplify[rhsCosGamma, assumptions];
        exprDelta = Cos[\delta] = FullSimplify[rhsCosDelta, assumptions];
        exprSigma = Cos[σ] == FullSimplify[rhsCosSigma, assumptions];
         (*Build labeled table*)
        lhs = {"\cos(\alpha)", "\cos(\beta)", "\cos(\gamma)", "\cos(\delta)", "\cos(\sigma)"};
        rhs = \{ (1 - yzu + xzu - xyu) / (2\sqrt{(xzu(1 + y)(1 + uy)))} \}
```

```
"\epsilon(u(1 + x)(1 + y)(1 + z) + (1 + ux)(1 + uy)(1 + uz) - uxyz(u - x)
     1)^2) / (2\sqrt{(u(1 + x)(1 + y)(1 + z)(1 + ux)(1 + uy)(1 + uz))})",
   "\epsilon(1 + yzu - xzu - xyu) / (2 / (yzu(1 + x)(1 + ux)))",
   "\epsilon(1 - yzu - xzu + xyu) / (2\sqrt{(xyu(1 + z)(1 + uz)))}",
   "(1 - u(xy + xz + yz + 2xyz)) / (2\sqrt{(xyzu^2(1 + x)(1 + y)(1 + z)))};
expressions = {exprAlpha, exprBeta, exprGamma, exprDelta, exprSigma};
```

```
isTrueQ[expr_] := TrueQ[FullSimplify[expr, assumptions]];
                                     TableForm[Table[{lhs[i], rhs[i], If[isTrueQ[expressions[i]]], "\", "x"]},
                                                   {i, Length[expressions]}],
                                            TableHeadings → {None, {"LHS", "RHS", "LHS = RHS?"}}]
                                       (*(*old version:check equalities*)
                                       (*cos(\alpha)*)
                                      FullSimplify[
                                                     (\varepsilon \ (Sin[\sigma - \beta] \ Sin[\sigma] + Sin[\sigma - \alpha] \ Sin[\sigma - \alpha - \beta] - Sin[\sigma - \gamma] \ Sin[\sigma - \gamma - \alpha]
                                                                                                              \beta] - Sin[\sigma - \delta] Sin[\sigma - \delta - \beta])) / (2 Sin[\gamma] Sin[\delta])=\varepsilon Cos[\alpha]]
                                             (*cos(\beta)*)
                                             FullSimplify[
                                                    (\varepsilon \ (Sin[\sigma - \alpha] \ Sin[\sigma] + Sin[\sigma - \beta] \ Sin[\sigma - \alpha - \beta] + \ Sin[\sigma - \delta] \ Sin[\sigma - \gamma - \beta] + \ Sin[\sigma - \delta] \ Sin[\sigma - \gamma - \beta] + \ Sin[\sigma - \delta] \ Sin[\sigma - \gamma - \beta] + \ Sin[\sigma - \delta] \ Sin[\sigma - \gamma - \beta] + \ Sin[\sigma - \delta] \ Sin[\sigma - \gamma - \beta] + \ Sin[\sigma - \delta] \ Sin[\sigma - \gamma - \beta] + \ Sin[\sigma - \delta] \ Sin[\sigma - \gamma - \beta] + \ Sin[\sigma - \delta] \ Sin[\sigma - \gamma - \beta] + \ Sin[\sigma - \delta] \ Sin[\sigma - \gamma - \beta] + \ Sin[\sigma - \delta] \ Sin[\sigma - \gamma - \beta] + \ Sin[\sigma - \delta] \ Sin[\sigma - \gamma - \beta] + \ Sin[\sigma - \delta] \ Sin[\sigma - \gamma - \beta] + \ Sin[\sigma - \delta] \ Sin[\sigma - \gamma - \beta] + \ Sin[\sigma - \delta] \ Sin[\sigma - \gamma - \beta] + \ Sin[\sigma - \delta] \ Sin[\sigma - \gamma - \beta] + \ Sin[\sigma - \delta] \ Sin[\sigma - \gamma - \beta] + \ Sin[\sigma - \delta] \ Sin[\sigma - \delta] + \ Sin[\sigma - \delta] \ Sin[\sigma - \delta] + \ Sin[\sigma - \delta] \ Sin[\sigma - \delta] + \ Sin[\sigma - \delta] \ Sin[\sigma - \delta] + \ Sin[\sigma - \delta]
                                                                                                              \beta] + Sin[\sigma - \gamma] Sin[\sigma - \delta - \beta])) / (2 Sin[\gamma] Sin[\delta])=\varepsilon Cos[\beta]]
                                             (*cos(x)*)
                                             FullSimplify[
                                                    (\varepsilon \ (Sin[\sigma - \beta] \ Sin[\sigma] - Sin[\sigma - \alpha] \ Sin[\sigma - \alpha - \beta] + Sin[\sigma - \gamma] \ Sin[\sigma - \gamma - \beta]
                                                                                                              \beta] - Sin[\sigma - \delta] Sin[\sigma - \delta - \beta])) / (2 Sin[\alpha] Sin[\delta])=\varepsilon Cos[\gamma]]
                                             (*cos(\delta)*)
                                             FullSimplify[
                                                    (\varepsilon \ (Sin[\sigma - \beta] \ Sin[\sigma] - Sin[\sigma - \alpha] \ Sin[\sigma - \alpha - \beta] - Sin[\sigma - \gamma] \ Sin[\sigma - \gamma - \beta]
                                                                                                              \beta] + Sin[\sigma - \delta] Sin[\sigma - \delta - \beta])) / (2 Sin[\alpha] Sin[\gamma])==\varepsilon Cos[\delta]]
                                             (*cos(\sigma)*)
                                             Full Simplify[(Sin[\sigma - \beta] \ Sin[\sigma] \ ^2 - Sin[\sigma - \alpha] \ Sin[\sigma - \alpha - \beta] \ Sin[\sigma] -
                                                                              Sin[\sigma - \gamma] Sin[\sigma - \gamma - \beta] Sin[\sigma] - Sin[\sigma - \delta] Sin[\sigma - \delta - \beta] Sin[\sigma] -
                                                                              2 Sin[\sigma - \alpha] Sin[\sigma - \gamma] Sin[\sigma - \delta]) /
                                                                  (2 Sin[\alpha] Sin[\gamma] Sin[\delta]) == Cos[\sigma]]*)
Out[ • ]//TableForm=
                                     LHS
                                                                                               \varepsilon \, ( \, 1 \, \, - \, \, yzu \, \, + \, \, xzu \, \, - \, \, xyu ) \  \  \, / \  \, ( \, 2 _{\sqrt{}} ( \, xzu \, ( \, 1 \, \, + \, \, y) \, \, ( \, 1 \, \, + \, \, uy) \, \, ) \, )
                                     \cos(\beta)
                                                                                               \epsilon \left( u \left( 1 \; + \; x \right) \, \left( 1 \; + \; y \right) \, \left( 1 \; + \; z \right) \; + \; \left( 1 \; + \; ux \right) \, \left( 1 \; + \; uy \right) \, \left( 1 \; + \; uz \right) \; - \; uxyz \left( u \; - \; 1 \right) \, ^{\Lambda} 2 \right) \; / \; + \; \left( 1 \; + \; ux \right) \, \left( 1 \; + \; ux \right) \, \left( 1 \; + \; uz \right) \; - \; uxyz \left( u \; - \; 1 \right) \, ^{\Lambda} 2 \right) \; / \; + \; \left( 1 \; + \; ux \right) \, \left( 1 \; + \; uz \right) \; - \; uxyz \left( u \; - \; 1 \right) \, ^{\Lambda} 2 \right) \; / \; + \; \left( 1 \; + \; ux \right) \, \left( 1 \; + \; uz \right) \; - \; \left( 1 \; + \; uz \right) \; - \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; - \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 \; + \; uz \right) \; / \; + \; \left( 1 
                                                                                             \varepsilon (1 + yzu - xzu - xyu) / (2\sqrt{(yzu(1 + x)(1 + ux))})
                                      cos(\gamma)
                                                                                            \epsilon(1 - yzu - xzu + xyu) / (2 / (xyu(1 + z)(1 + uz)))
                                      \cos(\delta)
                                      \cos{(\sigma)} \qquad (1 - u(xy + xz + yz + 2xyz)) \ / \ (2\sqrt{(xyzu^2(1 + x)(1 + y)(1 + z))})
```

Section 3

Results of Section 3 is used in the proof of Lemma 7 (see paper)

```
In[146]:=
       (*Clear previous definitions*)
```

```
ClearAll [\alpha, \beta, \gamma, \delta, \sigma, \bar{\alpha}, \bar{\beta}, \bar{\gamma}, \bar{\delta}, \varepsilon, \theta, A, \xi, \eta, lhs, rhs, expr, thetaIndex];
(*Define assumptions for the angles*)
assumptions = \{0 < \alpha < Pi, 0 < \beta < Pi, 0 < \gamma < Pi, 
     0 < \delta < Pi, 0 < \bar{\alpha} < Pi, 0 < \bar{\beta} < Pi, 0 < \bar{\gamma} < Pi, 0 < \bar{\delta} < Pi;
(*---Definitions---*)
\sigma = (\alpha + \beta + \gamma + \delta) / 2;
\bar{\alpha} = \sigma - \alpha;
\bar{\beta} = \sigma - \beta;
\bar{\gamma} = \sigma - \gamma;
\delta = \sigma - \delta;
\varepsilon = Abs[Sin[\sigma]] / Sin[\sigma];
(*Define Section 1 results*)
OneMinusM =
   Sin[\sigma] * Sin[\bar{\alpha} - \beta] * Sin[\bar{\gamma} - \beta] * Sin[\bar{\delta} - \beta] / (Sin[\bar{\alpha}] * Sin[\bar{\beta}] * Sin[\bar{\gamma}] * Sin[\bar{\delta}]);
rMinusOne = Sin[\sigma] * Sin[\bar{\gamma} - \beta] / (Sin[\bar{\alpha}] * Sin[\bar{\delta}]);
sMinusOne = Sin[\sigma] * Sin[\bar{\alpha} - \beta] / (Sin[\bar{\gamma}] * Sin[\bar{\delta}]);
fMinusOne = Sin[\sigma] * Sin[\bar{\delta} - \beta] / (Sin[\bar{\alpha}] * Sin[\bar{\gamma}]);
u = OneMinusM;
x = 1 / rMinusOne;
y = 1 / sMinusOne;
z = 1 / fMinusOne;
(*Define expressions in denominators*)
dexp = x * y * u * (1 + z) * (1 + u * z);
(*Define denominators*)
den = 2 * FullSimplify[Sqrt[dexp], assumptions];
(*Cyclic index function*)
thetaIndex[k] := Mod[k - 1, 4] + 1;
(*Definition of A[i,j]*)
A[i_{j}] /; 1 \le i \le 4 \& 1 \le j \le 4 :=
   4 \cos[\theta[\text{thetaIndex}[i]] / 2 + (Pi / 4) ij (j - 1) + (Pi / 2) j]^2 *
     Cos[\theta[thetaIndex[i-1]] / 2 + (Pi / 4) (i-1) j (j-1) + (Pi / 2) j]^2;
(*Table[A[i,j],{i,1,4},{j,1,4}];*)
(*Define \xi[i] and \eta[i]*)
\xi[i_?IntegerQ] /; 1 \le i \le 4 :=
   If[OddQ[i], \thetaIndex[i]], \thetaIndex[i-1]]];
\eta[i_?IntegerQ] /; 1 \le i \le 4 := If[OddQ[i], \theta[thetaIndex[i-1]], \theta[thetaIndex[i]]];
\{ \text{*Table}[\{i, \xi[i], \eta[i]\}, \{i, 1, 4\}]; * \}
```

```
(*Define left-hand side and right-hand side expressions*)
lhs[i Integer] := FullSimplify[
                 (A[i, 1] + A[i, 2] * y * z * u + A[i, 3] * x * z * u + A[i, 4] * x * y * u) / den] /.
            Cos[\beta] - Cos[\alpha + \gamma + \delta] \Rightarrow 2 Sin[(\alpha + \beta + \gamma + \delta) / 2] Sin[(\alpha - \beta + \gamma + \delta) / 2];
rhs[i_Integer] :=
        \varepsilon (Cos[\beta] - Cos[\gamma] (Cos[\alpha] Cos[\delta] + Cos[\xi[i]] Sin[\alpha] Sin[\delta]) - Cos[\eta[i]]
                            Sin[\gamma] (Cos[\alpha] Sin[\delta] - Cos[\xi[i]] Sin[\alpha] Cos[\delta])) / (Sin[\alpha] Sin[\gamma]);
expr[i Integer] := FullSimplify[Equal[lhs[i], rhs[i]], assumptions];
 (*---Build labeled result table---*)
lhsList =
        \left\{ "\left(A_{1\,1} \; + \; A_{1\,2}y_{1}z_{1}u_{1} \; + \; A_{1\,3}x_{1}z_{1}u_{1} \; + \; A_{1\,4}x_{1}y_{1}u_{1} \right) \; / \; \left(2\sqrt{\left(x_{1}y_{1}u_{1}\left(1 \; + \; z_{1}\right)\left(1 \; + \; z_{1}\right)\right)}\right) \right\} \left(1 + \left(1 + \left(1 \; + \; z_{1}\right)\right) \left(1 + \left(1 \; + \; z
                     + u_1 z_1))", "(A_{21} + A_{22} y_2 z_2 u_2 + A_{23} x_2 z_2 u_2 +
                    A_{24}x_{2}y_{2}u_{2}) / (2_{1}(x_{2}y_{2}u_{2}(1 + z_{2})(1 + u_{2}z_{2}))'',
            "(A_{31} + A_{32}y_3z_3u_3 + A_{33}x_3z_3u_3 + A_{34}x_3y_3u_3) / (2\sqrt{(x_3y_3u_3(1 +
                    z_3) (1 + u_3z_3))", "(A_{41} + A_{42}y_4z_4u_4 + A_{43}x_4z_4u_4
                    + A_4 x_4 y_4 u_4) / (2 \sqrt{(x_4 y_4 u_4 (1 + z_4) (1 + u_4 z_4))"};
rhsList = \{ (\cos(\beta_1) - \cos(\gamma_1)) \cos(\alpha_1) \cos(\delta_1) + \cos(\gamma_1) \cos(\alpha_2) \}
                    cos(\theta_1)sin(\alpha_1)sin(\delta_1) - cos(\theta_4)sin(\gamma_1)(cos(\alpha_1)sin(\delta_1)
                    - \cos(\theta_1)\sin(\alpha_1)\cos(\delta_1)) / (\sin(\alpha_1)\sin(\gamma_1))",
            "\varepsilon_2 ( (\cos(\beta_2) - \cos(\gamma_2) (\cos(\alpha_2) \cos(\delta_2) + \cos(\theta_1) \sin(\alpha_2) \sin(\delta_2))
                    - cos(\theta_2) sin(\gamma_2) (cos(\alpha_2) sin(\delta_2) -
                    cos(\theta_1)sin(\alpha_2)cos(\delta_2))) / (sin(\alpha_2)sin(\gamma_2))",
            "\varepsilon_3 ((cos(\beta_3) - cos(\gamma_3) (cos(\alpha_3) cos(\delta_3) + cos(\theta_3) sin(\alpha_3) sin(\delta_3))
                    - cos(\theta_2)sin(\gamma_3)(cos(\alpha_3)sin(\delta_3) -
                    cos(\theta_3)sin(\alpha_3)cos(\delta_3))) / (sin(\alpha_3)sin(\gamma_3))",
            "\varepsilon_4 ((cos(\beta_4) - cos(\gamma_4) (cos(\alpha_4) cos(\delta_4) + cos(\theta_3) sin(\alpha_4) sin(\delta_4))
                    - cos(\theta_4) sin(\gamma_4) (cos(\alpha_4) sin(\delta_4) -
                    cos(\theta_3) sin(\alpha_4) cos(\delta_4))) / (sin(\alpha_4) sin(\gamma_4))";
results = Table[If[TrueQ[expr[i]], "\", "x"], {i, 1, 4}];
TableForm[Table[{i, lhsList[i], rhsList[i], results[i]}, {i, 1, 4}],
    TableHeadings → {None, {"i", "LHS", "RHS", "LHS = RHS?"}},
    TableAlignments → Left]
```

Out[174]//TableForm=

i	LHS
1	$\left(A_{11} \ + \ A_{12}y_{1}z_{1}u_{1} \ + \ A_{13}x_{1}z_{1}u_{1} \ + \ A_{14}x_{1}y_{1}u_{1}\right) \ / \ \left(2_{}(x_{1}y_{1}u_{1}\left(1 \ + \ z_{1}\right)\left(1 \ + \ u_{1}z_{1}\right)\right)$
2	$\left(A_{21} \ + \ A_{22}y_{_{2}}z_{_{2}}u_{_{2}} \ + \ A_{2_{3}}x_{_{2}}z_{_{2}}u_{_{2}} \ + \ A_{2_{4}}x_{_{2}}y_{_{2}}u_{_{2}}\right) \ / \ \left(2_{}(x_{_{2}}y_{_{2}}u_{_{2}}(1 \ + \ z_{_{2}}) \left(1 \ + \ u_{_{2}}z_{_{2}}\right)\right)$
3	$\left(A_{31} \ + \ A_{32}y_{_3}z_{_3}u_{_3} \ + \ A_{33}x_{_3}z_{_3}u_{_3} \ + \ A_{_3_4}x_{_3}y_{_3}u_{_3}\right) \ / \ \left(2_{}(x_{_3}y_{_3}u_{_3}(1 \ + \ z_{_3})(1 \ + \ u_{_3}z_{_3})\right)$
4	$\left(A_{41} \ + \ A_{42}y_{_4}z_{_4}u_{_4} \ + \ A_{43}x_{_4}z_{_4}u_{_4} \ + \ A_{_44}x_{_4}y_{_4}u_{_4}\right) \ / \ \left(2_{}(x_{_4}y_{_4}u_{_4}(1 \ + \ z_{_4})(1 \ + \ u_{_4}z_{_4})\right)$