

Lecture 2: Arrays

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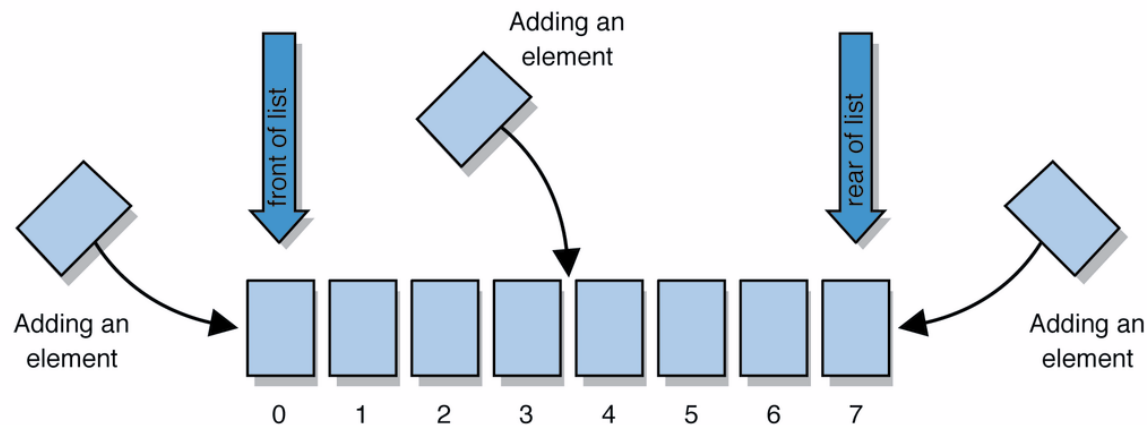
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Tsz-Chiu Au, and Myeongjae Jeon, and Kasey Champion (UW)

Outline

- Basic Concepts
- Arrays
- Examples of representing other ADTs
 - Polynomial
 - Sparse matrices

Abstract Data Type (ADT)

- A definition for expected operations and behavior
- Examples: list - a collection storing an ordered sequence of elements.
 - Operations:



Data Structure

- How we organize/storing the data points.
- Determines how each operation would behave.
- One ADT can be implemented many ways.
- One data structure can be used for multiple ADTs.

ADT first, then data structure

- Wrong way:
 - I'll represent my data A as an Array.
- Right way:
 - I'll be frequently accessing a random data point of my data A: I need operation `[]`.
 - I'll thus use Array.

Outline

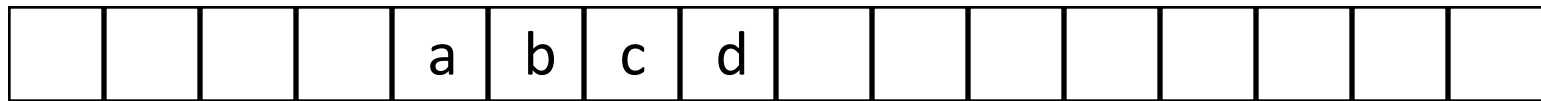
- Basic Concepts
- **Arrays**
- Examples of representing other ADTs
 - Polynomials
 - Sparse matrices

Today's focus: Array

- Continuous memory space with a same data type
- Accessing by index is efficient.
- `type name [elements];` C/C++
- Example
 - `int a[100];`
 - `float b[10][20];`
 - `mytype c[5];` // user-defined data type

1D Array Representation In C

1D Memory Space



base

$$x[0] = \text{base} + 0 = \text{a}$$

- 1-dimensional array $x = [a, b, c, d]$
- map into contiguous memory locations
- $\text{location}(x[i]) = \text{base} + i$

Array as a data structure for List

- Operations
 - Insert/Delete
 - Access by index
 - Access by value
 - Sort
 - Swap
- Memory: no/small metadata

2D Arrays

- The elements of a 2-dimensional array x declared as:
- `int x[3][4];`
- may be shown as a table

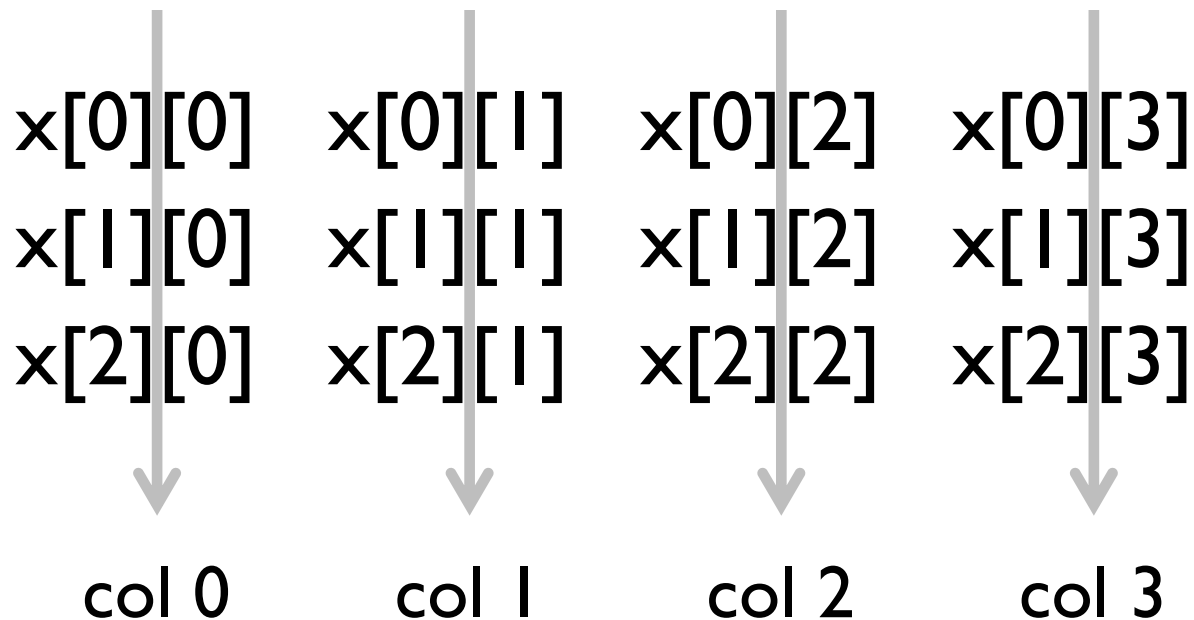
$x[0][0]$	$x[0][1]$	$x[0][2]$	$x[0][3]$
$x[1][0]$	$x[1][1]$	$x[1][2]$	$x[1][3]$
$x[2][0]$	$x[2][1]$	$x[2][2]$	$x[2][3]$

Rows Of A 2D Array

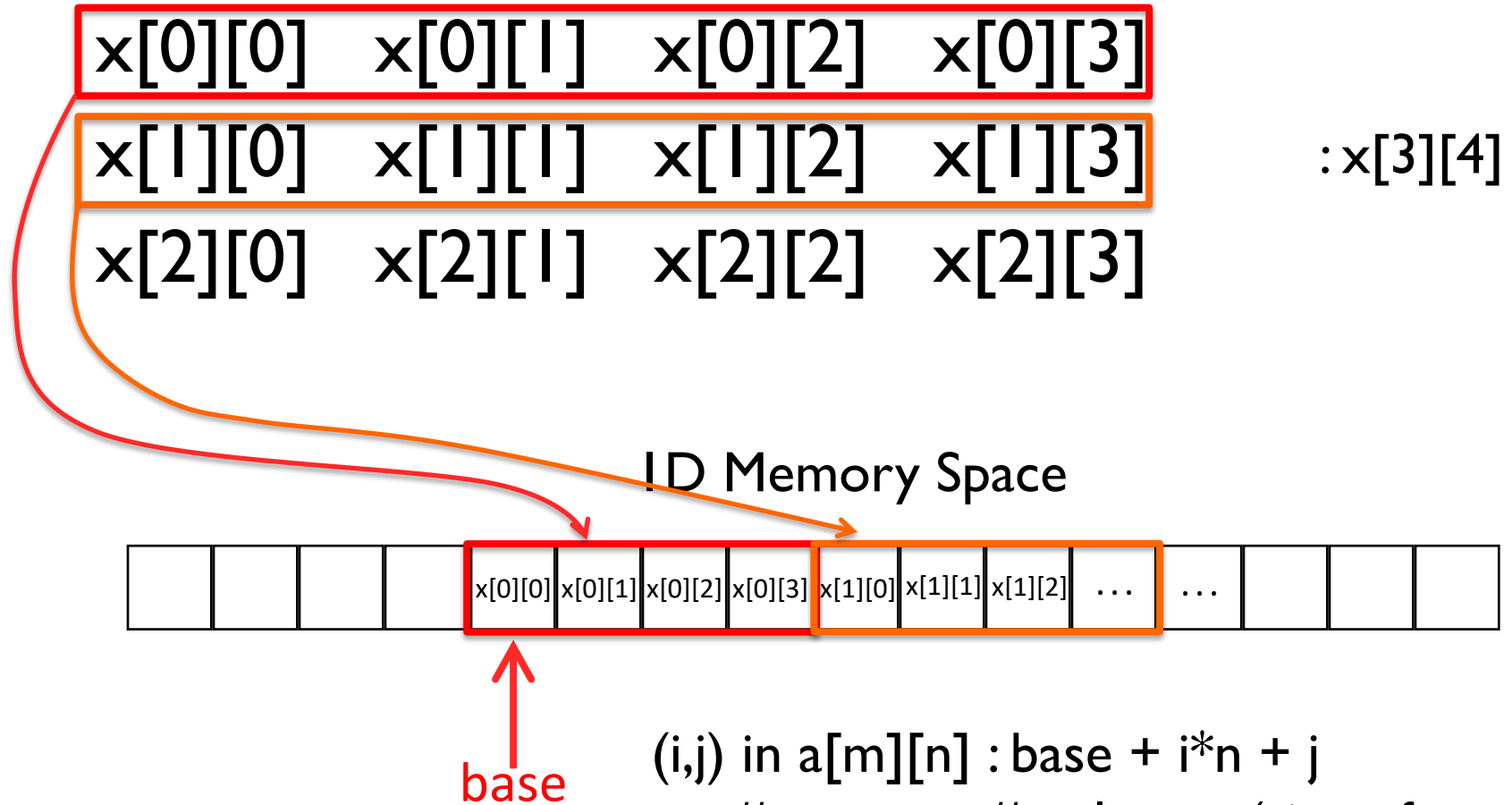
$x[i][j]$: j th element of an array $x[i]$

$x[0][0]$	$x[0][1]$	$x[0][2]$	$x[0][3]$	→ row 0
$x[1][0]$	$x[1][1]$	$x[1][2]$	$x[1][3]$	→ row 1
$x[2][0]$	$x[2][1]$	$x[2][2]$	$x[2][3]$	→ row 2

Columns Of A 2D Array



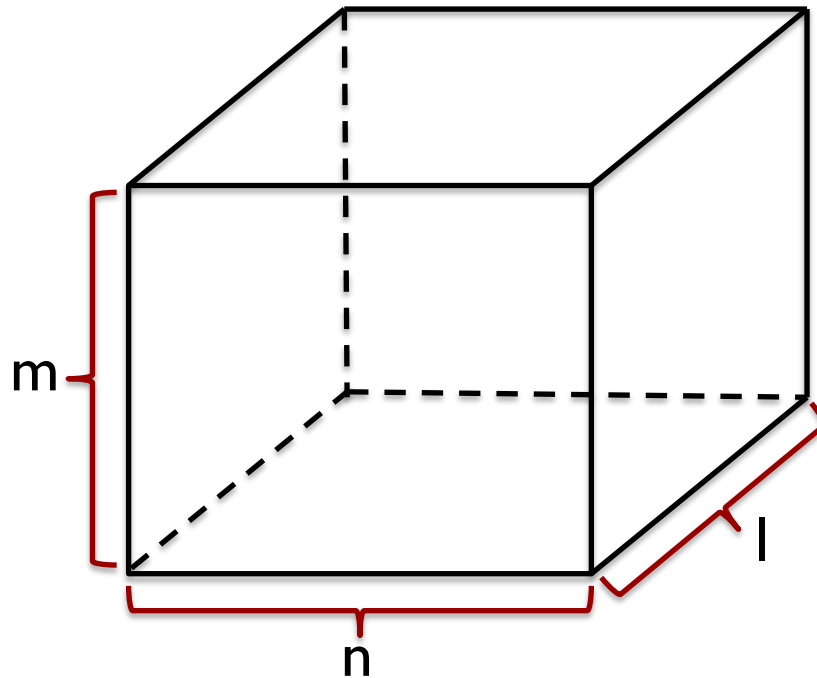
1D Indexing of 2D Array



(i,j) in $a[m][n]$: $\text{base} + i * n + j$
 m : # rows, n : # columns (size of a row)
 i : row index, j : column index

1D Indexing of 3D Array

- (i,j,k) in $x[l][m][n]$: $\text{base} + i*m*n + j*n + k$



Array can also be an ADT

- An ADT defined with array-like operations.
- Doesn't need to be implemented with pure array!
- Mapping between index and value
- Operators to retrieve and store value
- We can use operator overloading to make it looks and feels like a raw array.

```

class GeneralArray {
// A set of pairs <index, value> where for each
// value of index in index set there is a value of
// type float
public:
    // Constructor.
    // j : dimension, list : range of each dimension.
    // initValue : initial value
    GeneralArray(int j,
                  RangeList list,
                  float initValue);

    // Return the float associate with i if i is in
    // the index set. Otherwise throw an exception
    float Retrieve(const index i);
    float& operator[] (const int index);
    // Replace the old value associate with i if i is
    // in the index set. Otherwise throw an exception
    void Store(index I, float x)
}

```


Outline

- Basic Concepts
- Arrays
- Examples of representing other ADTs
 - Polynomial
 - Sparse matrices

Polynomial Abstract Data Type

- Data
 - Set of ordered pairs of $\langle e, c \rangle$ where e is exponent and c is coefficient of terms of the polynomial

$$a(x) = \overset{\text{coefficient}}{\underset{\text{exponent}}{3x^2}} + 2x - 4$$

Degree: 2, Order : 3

- Operations
 - Addition, subtraction, multiplication, evaluation, ...

Polynomial Representation

- Version 1: plain-static
 - Exponent is implicitly represented
 - Max degree has to be known, waste space if $\text{degree} \ll \text{MaxDegree}$

$$a(x) = \sum a_i x^i$$

```
private:
    int degree;
    float coef[MaxDegree + 1];
```

```
a.degree = n
a.coef[i] = an-i , 0 ≤ i ≤ n
```

Polynomial Representation

- Version 2: plain-dynamic
 - Dynamically allocate coefficients, no need to know max degree
 - Waste memory if most of coefficients are zero

```
private:  
    int degree;  
    float *coef;
```

$$a(x) = \sum a_i x^i$$

```
Polynomial:Polynomial(int d)  
{  
    degree = d;  
    coef = new float[degree+1];  
}
```

Polynomial Representation

- Version 3: nonzero-dynamic
 - Dynamically allocate coefficients & exponents
 - Store only **nonzero** terms
 - Waste memory if most of coefficients are nonzero

$$a(x) = \sum a_i x^i$$

```
class Term {  
private:  
    float coef;  
    int exp;  
};  
  
private:  
    Term *termArray;  
    int capacity, terms;
```

Example

- $a(x) = 2x^{1000} + 1$
 - Plain-dynamic uses 1 int & 1001 float = 1002 words
 - Nonzero-dynamic uses 4 int (2+2) & 2 float = 6 words
- $a(x) = 3x^4 + 6x^3 - 5x^2 + 2x - 1$
 - Plain-dynamic uses 1 int & 5 float = 6 words
 - Nonzero-dynamic uses 7 int (2+5) & 5 float = 12 words
 - If all terms are nonzero, nonzero-dynamic uses about twice more memory (b/c exponent is stored explicitly)

Polynomial Add

- $C = A + B$
- Add terms that have the same exponent
- Only store nonzero terms to output

```

Polynomial Polynomial::Add(Polynomial B){
    Polynomial C; int a = Start; int b = B.Start;
    C.Start = free; float c;
    while ((a<=Finish) && (b<=B.Finish))
        switch (compare(termArray[a].exp, termArray[b].exp)) // compare exponent
        {
            case '=':
                c = termArray[a].coef + termArray[b].coef;
                if (c) C.NewTerm(c, termArray[a].exp); // if sum is nonzero
                a++; b++; break;
            case '<':
                C.NewTerm(termArray[b].coef, termArray[b].exp);
                b++; break;
            case '>':
                C.NewTerm(termArray[a].coef, termArray[a].exp);
                a++;
        }
    for (; a<=Finish; a++)
        C.NewTerm(termArray[a].coef, termArray[a].exp);
    for (; b<=B.Finish; b++)
        C.Newterm(termArray[b].coef, termArray[b].exp);
    C.Finish = free - 1; return C;
}

```


Matrices

- $A[m][n]$
 - $m \times n$ matrix A
 - m : # of rows
 - n : # of column
 - $m*n$: # of elements
- Accessing an element at i -th row and j -th col
 - $A[i][j]$
- 2D array is often used to represent matrices

Row Major vs. Column Major

- 2D- \rightarrow 1D layout
- Row major
 - Store each row in contiguous memory
- Column major
 - Store each column in contiguous memory

Sparse Matrices

- Mostly zero

$$\begin{array}{c}
 \begin{array}{ccc}
 & 0 & 1 & 2 \\
 \begin{array}{c} 0 \\ 1 \\ 2 \\ 3 \\ 4 \end{array} & \left[\begin{array}{ccc}
 -27 & 3 & 4 \\
 6 & 82 & -2 \\
 109 & -64 & 11 \\
 12 & 8 & 9 \\
 48 & 27 & 47
 \end{array} \right]
 \end{array}$$

(a) Dense Matrix

$$\begin{array}{c}
 \begin{array}{cccccc}
 & 0 & 1 & 2 & 3 & 4 & 5 \\
 \begin{array}{c} 0 \\ 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{array} & \left[\begin{array}{cccccc}
 15 & 0 & 0 & 22 & 0 & -15 \\
 0 & 11 & 3 & 0 & 0 & 0 \\
 0 & 0 & 0 & -6 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 \\
 91 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 28 & 0 & 0 & 0
 \end{array} \right]
 \end{array}$$

(b) Sparse Matrix

Sparse Matrix Representation

- Array of triples $\langle \text{row}, \text{col}, \text{value} \rangle$ for nonzero elements

```
class SparseMatrix;
class MatrixTerm {
    friend class SparseMatrix
private:
    int row, col, value;
};

private:
    int rows, cols, terms, capacity;
    MatrixTerm * smArray;
```

Sparse Matrix Representation

- Space requirement for nxn matrix
 - Dense : n^2
 - Sparse diagonal matrix : $3*n$
 - Sparse tridiagonal matrix : $9*n - 6$

$$f_n = \begin{vmatrix} a_1 & b_1 & & & \\ c_1 & a_2 & b_2 & & \\ & c_2 & \ddots & \ddots & \\ & & \ddots & \ddots & b_{n-1} \\ & & & c_{n-1} & a_n \end{vmatrix}.$$

Example

							row	col	val		
							smArray	[0]	0	0	15
								[1]	0	3	22
0	0	1	2	3	4	5		[2]	0	5	-15
0 1 2 3 4 5	15	0	0	22	0	-15		[3]	1	1	11
	0	11	3	0	0	0		[4]	1	2	3
	0	0	0	-6	0	0		[5]	2	3	-6
	0	0	0	0	0	0		[6]	4	0	91
	91	0	0	0	0	0		[7]	5	2	28
	0	0	28	0	0	0					

Row-major ordering

Sparse Matrix Transpose

- Exchange (i,j) to (j,i)
- For each row i , store (i,j) to (j,i)

– Problem

$(0, 0, 15) \rightarrow (0, 0, 15)$

$(0, 3, 22) \rightarrow (3, 0, 22)$

$(0, 5, -15) \rightarrow (5, 0, -15)$

$(1, 1, 11) \rightarrow (1, 1, 11)$ **X**

Violate row-major order

Sparse Matrix Transpose

- Algorithm
 - Use column major order traversal
 - After transpose, matrix is row-major order

for (all element in **column** j)
store (i,j,value) of the original matrix as (j,i,value) of transposed matrix


Example

		row	col	val			row	col	val
smArray	[0]	0	0	15	→ smArray →	[0]	0	0	15
	[1]	0	3	22		[1]	0	4	91
	[2]	0	5	-15		[2]			
	[3]	1	1	11		[3]			
	[4]	1	2	3		[4]			
	[5]	2	3	-6		[5]			
	[6]	4	0	91		[6]			
	[7]	5	2	28		[7]			

for Column 0

Example

		row	col	val			row	col	val
smArray	[0]	0	0	15	smArray	[0]	0	0	15
	[1]	0	3	22		[1]	0	4	91
	[2]	0	5	-15		[2]	1	1	11
	[3]	1	1	11		[3]			
	[4]	1	2	3		[4]			
	[5]	2	3	-6		[5]			
	[6]	4	0	91		[6]			
	[7]	5	2	28		[7]			



for Column 1

Example

		row	col	val			row	col	val
smArray	[0]	0	0	15	smArray	[0]	0	0	15
	[1]	0	3	22		[1]	0	4	91
	[2]	0	5	-15		[2]	1	1	11
	[3]	1	1	11		[3]	2	1	3
	[4]	1	2	3		[4]	2	5	28
	[5]	2	3	-6		[5]			
	[6]	4	0	91		[6]			
	[7]	5	2	28		[7]			

for Column 2

Example

		row	col	val			row	col	val
smArray	[0]	0	0	15	smArray	[0]	0	0	15
	[1]	0	3	22		[1]	0	4	91
	[2]	0	5	-15		[2]	1	1	11
	[3]	1	1	11		[3]	2	1	3
	[4]	1	2	3		[4]	2	5	28
	[5]	2	3	-6		[5]	3	0	22
	[6]	4	0	91		[6]	3	2	-6
	[7]	5	2	28		[7]			

for Column 3


Example

		row	col	val			row	col	val
smArray	[0]	0	0	15	smArray	[0]	0	0	15
	[1]	0	3	22		[1]	0	4	91
	[2]	0	5	-15		[2]	1	1	11
	[3]	1	1	11		[3]	2	1	3
	[4]	1	2	3		[4]	2	5	28
	[5]	2	3	-6		[5]	3	0	22
	[6]	4	0	91		[6]	3	2	-6
	[7]	5	2	28		[7]			

for Column 4 : No Match

Example

		row	col	val			row	col	val
smArray	[0]	0	0	15	smArray	[0]	0	0	15
	[1]	0	3	22		[1]	0	4	91
	[2]	0	5	-15		[2]	1	1	11
	[3]	1	1	11		[3]	2	1	3
	[4]	1	2	3		[4]	2	5	28
	[5]	2	3	-6		[5]	3	0	22
	[6]	4	0	91		[6]	3	2	-6
	[7]	5	2	28		[7]	5	0	-15



for Column 5

```

SparseMatrix SparseMatrix::Transpose(){
    SparseMatrix b;    // b : output (transposed matrix)
    b.Rows = Cols;     // b rows = a cols
    b.Cols = Rows;     // b cols = a rows
    b.Terms = Terms;   // # of elements is same

    if (Terms > 0){    // non empty matrix
        int CurrentB = 0;
        for (int c = 0; c < Cols; c++)    // per each column
            for (int i = 0; i < Terms; i++)    // for all nonzero elements in sparse
                if (smArray[i].col == c) {    // matrix
                    b.smArray[CurrentB].row = c;
                    b.smArray[CurrentB].col = smArray[i].row;
                    b.smArray[CurrentB].value = smArray[i].value;
                    CurrentB++;
                }
    }
    return b;
}

```

cols+1
 cols*(terms+1)
 cols*terms
 cols*(0 ~ terms)

Complexity?

Sparse Matrix Transpose

- Fast algorithm ($A^T=B$)
 - Count elements in each column in A (# of rows in B)
 - Compute starting position of rows in B
 - Copy A from B

ROW_SIZE		ROW_START
[0]	2	0
[1]	1	2
[2]	2	3
[3]	2	5
[4]	0	7
[5]	1	7
# of nonzero terms in B's row (A's col)		starting position of B's row

	row	col	val
smArray [0]	0	0	15
[1]	0	3	22
[2]	0	5	-15
[3]	1	1	11
[4]	1	2	3
[5]	2	3	-6
[6]	4	0	91
[7]	5	2	28

Example

		row	col	val		row	col	val
smArray	[0]	0	0	15		[0]	0	15
	[1]	0	3	22		[1]		
	[2]	0	5	-15		[2]		
	[3]	1	1	11		[3]		
	[4]	1	2	3		[4]		
	[5]	2	3	-6		[5]		
	[6]	4	0	91		[6]		
	[7]	5	2	28		[7]		

RowStart[0] = 0;
RowStart[0]++;

ROW_SIZE	ROW_START
[0] 2	0
[1] 1	2
[2] 2	3
[3] 2	5
[4] 0	7
[5] 1	7
# of terms in B's row (A's col)	starting position of B's row

for Column 0

Example

		row	col	val			row	col	val	
smArray	[0]	0	0	15			[0]	0	15	
	[1]	0	3	22			[1]			
	[2]	0	5	15			[2]			
	[3]	1	1	11			[3]			
	[4]	1	2	3			[4]			
	[5]	2	3	-6			[5]	3	0	22
	[6]	4	0	91			[6]			
	[7]	5	2	28			[7]			

1

2

3

5

7

7

rows

row (A's col)

ROW_START

starting position of B's row

RowStart[3] = 5;

RowStart[3]++;

ROW_SIZE	ROW_START
[0] 2	1
[1] 1	2
[2] 2	3
[3] 2	5
[4] 0	7
[5] 1	7
# of terms in B's row (A's col)	starting position of B's row

RowStart[3] = 5;
RowStart[3]++;

for Column 0

Example

		row	col	val			row	col	val	
smArray	[0]	0	0	15			[0]	0	15	
	[1]	0	3	22			[1]			
	[2]	0	5	-15			[2]			
	[3]	1	1	11			[3]			
	[4]	1	2	3			[4]			
	[5]	2	3	-6			[5]	3	0	22
	[6]	4	0	91			[6]			
	[7]	5	2	28			[7]	5	0	-15

1

2

3

6

7

7

rows

starting position

row (A's col)

of B's row

RowStart[5] = 7;
RowStart[5]++;

ROW_SIZE	ROW_START
[0] 2	1
[1] 1	2
[2] 2	3
[3] 2	6
[4] 0	7
[5] 1	7
# of terms in B's row (A's col)	starting position of B's row

RowStart[5] = 7;
RowStart[5]++;

for Column 0

```

SparseMatrix SparseMatrix::FastTranspose(){
    // transpose a(*this) to b, O(terms+columns).
    int *RowSize = new int[Cols];
    int *RowStart = new int[Cols];
    SparseMatrix b;
    b.Rows = Cols;      b.cols = Rows;  b.Terms = Terms;

    if (Terms>0) {
        for (int i = 0; i<Cols; i++)  RowSize[i] = 0;  // initialize
        for (i = 0; i<Terms; i++)    RowSize[smArray[i].col]++;
        RowStart[0] = 0;
        for (i = 1; i<Cols; i++)  RowStart[i] = RowStart[i-1] + RowSize[i-1];

        for (i = 0; i<Terms; i++) {    // transpose
            int j = RowStart[smArray[i].col];
            b.smArray[j].row = smArray[i].col;      b.smArray[j].col = smArray[i].row;
            b.smArray[j].value = smArray[i].value; RowStart[smArray[i].col]++;
        }
        delete [] RowSize; delete [] RowStart;
        return b;
    }
}

```

cols+1

terms+1

1

cols+1

terms+1

Complexity?

Questions?