## Homework 4

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## 1

Let  $G \leq S_n$  be a subgroup of the permutation group  $S_n$  acting on the index set  $X = \{1, 2, ..., n\}$  where n is a finite natural number. An element g acts on a vector  $v \in \mathbb{R}^n$  on the coordinate i by  $(gv)_i = v_{g^{-1}(i)}$ . Consider a G-linear transformation  $T : \mathbb{R}^n \to \mathbb{R}^n$ . Thus, T(gv) = gT(v). Therefore, T must fulfill Tgv = gTv for all  $g \in G$  and  $v \in \mathbb{R}^n$ . As a result Tg = gT and equivalently,  $g^{-1}Tg = T$  for all  $g \in G$  (in the lectures we used W). Applying g from the right on the columns of T and  $g^{-1}$  from the left on the rows of T results in the following condition:

$$T_{i,j} = T_{q^{-1}(i),q^{-1}(j)}. (1)$$

g acts on T and on each orbit of T the requirement is that T is constant. Thus, the condition requires that  $T_{i,j} = T_{l,m}$  if  $Orb_G((i,j)) = Orb_G((l,m))$ . Therefore the number of free parameters is the number of orbits.

We define  $U = X \times X$ . Burnside's Lemma states that

$$|U/G| = \frac{1}{|G|} \sum_{g \in G} |U^g| = \frac{1}{|G|} \sum_{g \in G} |X^g|^2 = \frac{1}{|G|} \sum_{g \in G} \chi_\rho(g)^2, \tag{2}$$

where |U/G| is the number of orbits and  $U^g = \{u \in U \mid gu = u\}$  is the set of elements in U that g doesn't change. We have the property of  $|U^g| = \chi_{\sigma}(g)$ ,

# 2 Question 2

#### 2.1

The natural group here is the cross product of the permutation groups  $S_n \times S_m$  acts on the Netflix rating matrices  $A \in \mathbb{R}^{n \times m}$ . It can be explained by the fact that the order of the m movies and the order of the n users is arbitrary and both can be changed independently.

### 2.2

Since we look at the G-linear transformation from matrices in  $\mathbb{R}^{n\times m}$  to itself, it will be more convenient to consider the vectorization of these matrices. Thus

 $\operatorname{vec}(A) = [a_{1,1}, \dots, a_{n,1}, \dots, a_{1,m}, \dots, a_{n,m}]^T \in \mathbb{R}^{nm}$ . Let  $g = (g_l, g_r) \in S_n \times S_m$  be a group element where  $g_l \in S_n$  is a left action that acts on the rows of A and  $g_r \in S_m$  acts on the columns of A as follows:

$$gA = g_l A g_r^T = P_l A P_r^T, (3)$$

where  $P_l \in \mathbb{R}^{n \times n}$  and  $P_r \in \mathbb{R}^{m \times m}$  are the permutations of  $g_l$  and  $g_r$ , respectively. Define  $v = \text{vec}(A) \in \mathbb{R}^{nm}$ . We are actually looking on the isomorphic group  $G \leq S_{nm}$ , which acts on the indexes of the vectorization of A. We will use G and  $S_n \times S_m$  interchangeably. In index notation we have  $(gA)_{i,j} = A_{g_l^{-1}(i),g_r^{-1}(j)}$ . We are looking at the affine transformation that is equivariant, thus f(v) = Wv + b, that fulfills for all  $g \in S_n \times S_m$  and  $v \in \mathbb{R}^{nm}$ 

$$f(gv) = W(gv) + b = g(Wv + b)$$
  

$$\Rightarrow Wgv + b = gWv + gb$$
(4)

Since (4) needs to be fulfilled for all  $v \in \mathbb{R}^{nm}$  it leads to Wg = gW and equivalently  $gWg^T = W$ . Moreover, it requires that gb = b for all  $g \in G$ . We have

$$gA = g_l A g_r^T = P_l A P_r^T. (5)$$

By vectorizing the above we obtain

$$\operatorname{vec}\left(P_{l}AP_{r}^{T}\right) = \left(P_{r} \otimes P_{l}\right)\operatorname{vec}(A) \Rightarrow P_{nm} = \left(P_{r} \otimes P_{l}\right) \tag{6}$$

For b, we can see from (4) that this means that b is constant,  $b = c \cdot 1$ . This can be seen by applying the inverse vectorization operation on b. Since the condition (4) requires that b will be invariant to the action of g, and by acting on b we can replace each index  $\text{vec}^{-1}(b_{i,j})$  with any other index. Therefore, all values of b required to be the same.

Let us look at the action of the permutation  $g^{-1} = (g_l^{-1}, g_r^{-1})$  on the vector v. We take the inverse  $g^{-1}$  for convenience of notation. Originally, the element with the index  $A_{i,j}$  moves to  $v_{i+n(j-1)}$ , therefore

$$(g^{-1}A)_{i,j} = A_{g_l(i),g_r(j)} = v_{g_l(i)+n(g_r(j)-1)}. (7)$$

Consequently, for an index  $1 \le k \le nm$ , define j = k//n as the truncating integer division and i = k%n as the modulo operation, thus  $\left(g^{-1}v\right)_k = v_{g_l(i)+n\cdot(g_r(j)-1)}$ . Let k,l be indexes in  $[1,\ldots,nm]$  with the decomposition  $k=i_1+n(j_1-1)$  and  $l=i_2+n(j_2-1)$ . Then  $\left(g^{-1}Wg\right)_{k,l} = W_{g_l(i_1)+n\cdot(g_r(j_1)-1),g_l(i_2)+n(g_r(j_2)-1)}$ .

#### 2.2.1 Orbit analysis

Let us look at the possible orbits in the index set  $X^2 = \{1, 2, ..., nm\}^2$ . Indexes (k', l') can be on the same orbits as (k, l) if and only if there exists a permutation  $(g_l, g_r) \in S_n \times S_m$  such that

$$\begin{cases} k' = g_l(i_1) + n(g_r(j_1) - 1) \\ l' = g_l(i_2) + n(g_r(j_2) - 1) \end{cases}$$
 (8)

Define  $i_3, i_4, j_3, j_4$  such that  $k' = i_3 + n(j_3 - 1)$  and  $l' = i_4 + n(j_4 - 1)$ . It is clear that we can create equivalence groups by the rule:

$$(i_1 \stackrel{\neq}{=} i_2) \wedge (j_1 \stackrel{\neq}{=} j_2). \tag{9}$$

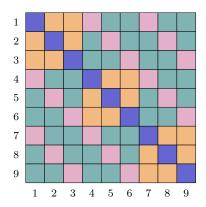
It is clear that  $i_3 = i_4$  holds if and only if  $i_1 = i_2$ , since by applying  $g_l$  we have  $g_l(i_1) = g_l(i_2) = i_3 = i_4$ , and since  $g_l$  is a bijection. The same goes for  $j_3 = j_4$ .

These are the orbits and the explanation for why they are the only orbits is as follows: if  $i_1 = i_2$  then we can move to any other k', l' that has  $i_3 = i_4$  by applying the right  $g_l(i_1) = i_3$ . If  $i_1 \neq i_2$  we can move to any other indexes  $i_3 \neq i_4$  since  $S_n$  is 2-transitive. The same goes for the indexes j. Therefore, we will have only these 4 orbits:

$$\begin{split} O_{=i=j} &: i_1 = i_2, j_1 = j_2 \\ O_{=i \neq j} &: i_1 = i_2, j_1 \neq j_2 \\ O_{\neq i=j} &: i_1 \neq i_2, j_1 = j_2 \\ O_{\neq i \neq j} &: i_1 \neq i_2, j_1 \neq j_2 \end{split}$$

## 2.3

For n=m=3 we will obtain  $W \in \mathbb{R}^{9 \times 9}$  and  $b \in \mathbb{R}^9 = c \cdot \mathbf{1}$ 



#### 2.4

In the case of a linear invariant layer, for all  $v \in \mathbb{R}^{nm}$  and  $g \in G$  we have:

$$f(gv) = f(v)$$

$$\Rightarrow w^{T}gv + b = w^{T}v + b$$

$$\Rightarrow g^{T}w = w$$

For  $w \in \mathbb{R}^{nm}$ , this condition is equivalent to the condition on b in the previous clause. Therefore,  $w = c_2 \cdot \mathbf{1}$ .

In the case of 3-tensors with the symmetric group is  $S_{N_1} \times S_{N_2} \times S_{N_3}$  applied independently to each index axis of the tensor. We have:

$$v = \text{vec}(A) \ v_k = a_{i_1, i_2, i_3},$$
 (10)

where  $k = i_1 + N_1(i_2 - 1) + N_1N_2(i_3 - 1)$ . Define  $k = i_1^k + N_1(i_2^k - 1) + N_1N_2(i_3^k - 1)$  and  $l = i_1^l + N_1(i_2^l - 1) + N_1N_2(i_3^l - 1)$ . We will have the same derivation as in the previous clause 2.2, thus

$$W_{k,l} = W_{g(k),g(l)}$$

The indexes (k, l) can transform to

$$k' = g_1(i_1^k) + N_1(g_2(i_2^k) - 1) + N_1N_2(g_3(i_3^k) - 1)$$
  
$$l' = g_1(i_1^l) + N_1(g_2(i_2^l) - 1) + N_1N_2(g_3(i_3^l) - 1)$$

where the equivalence relations follow the same pattern as before, thus the orbits are

$$\bigwedge_{n=1}^{3} i_{n=1}^{k \neq l} i_{n}^{l}. \tag{11}$$

As a result, the orbits are:

$$\begin{split} O_{=i_1=i_2=i_3}: i_1^k &= i_1^l, i_2^k = i_2^l, i_3^k = i_3^l \\ O_{=i_1=i_2\neq i_3}: i_1^k &= i_1^l, i_2^k = i_2^l, i_3^k \neq i_3^l \\ O_{=i_1\neq i_2=i_3}: i_1^k &= i_1^l, i_2^k \neq i_2^l, i_3^k = i_3^l \\ &\vdots \\ O_{\neq i_1\neq i_2\neq i_3}: i_1^k \neq i_1^l, i_2^k \neq i_2^l, i_3^k \neq i_3^l \end{split}$$

For  $N_1 = N_2 = N_3 = 3$ , we obtain  $W \in \mathbb{R}^{27 \times 27}$  and  $b \in \mathbb{R}^{27}$ .

