

# Uncertainty Estimation for High-dimensional Nonparametric Forecasting

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**Joint work with :** Rob Hyndman, Xiaoqian Wang

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# Nonparametric forecasting

$$y_t = f(\mathbf{a}_t, \mathbf{a}_{t-1}, \dots, \mathbf{a}_{t-s}, y_{t-1}, \dots, y_{t-k}) + \varepsilon_t,$$

- $y_t$  – observed response at time  $t$
- $f$  – arbitrary function
- $\mathbf{a}_t$  – vector of exogenous variables at time  $t$
- $\varepsilon_t$  – stationary error with mean zero and constant variance  $\sigma^2$ .

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We also define:

- $\mathbf{z}_t = (y_t, \mathbf{x}_t)$  – observation at time  $t$
- $\mathbf{x}_t = (\mathbf{a}_t, \mathbf{a}_{t-1}, \dots, \mathbf{a}_{t-s}, y_{t-1}, \dots, y_{t-k})$  – vector of all predictors at time  $t$ .
- $\hat{y}_t = \hat{f}(\mathbf{x}_t)$  – estimated model
- $e_t = y_t - \hat{y}_t$  – model residuals

# Sparse multiple index (SMI) model

$$y_i = \beta_0 + \sum_{j=1}^p g_j(\alpha_j^T \mathbf{x}_{ij}) + \sum_{k=1}^d f_k(w_{ik}) + \theta^T \mathbf{u}_i + \varepsilon_i, \quad i = 1, \dots, n,$$

- $y_i$  – univariate response
- $\mathbf{x}_{ij} \in \mathbb{R}^{\ell_j}, j = 1, \dots, p$  –  $p$  subsets of predictors entering indices
- $\alpha_j$  –  $\ell_j$ -dimensional vectors of index coefficients
- $g_j, f_k$  – smooth nonlinear functions
- Additional predictors :
  - ▶  $w_{ik}$  – nonlinear
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Allow elements equal to zero in  
 $\alpha_j$  – "Sparse"

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Both "p" and the predictor grouping among indices are unknown.

Overlapping of predictors among indices is not allowed.

# Benchmarks

# Forecast uncertainty

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$$\hat{y}_{t+h|t} \pm z_{\alpha/2} \times \hat{\sigma}_h,$$

where

- ▶  $y$  – time series  $y_1, \dots, y_T$
- ▶  $\hat{y}_{t+h|t}$  –  $h$ -step-ahead point forecast for  $y_{t+h}$  given observations up to  $t$
- ▶  $z_{\alpha/2}$  –  $\alpha/2$  quantile of standard normal distribution
- ▶  $\hat{\sigma}_h$  – estimate of std. deviation of  $h$ -step forecast distribution

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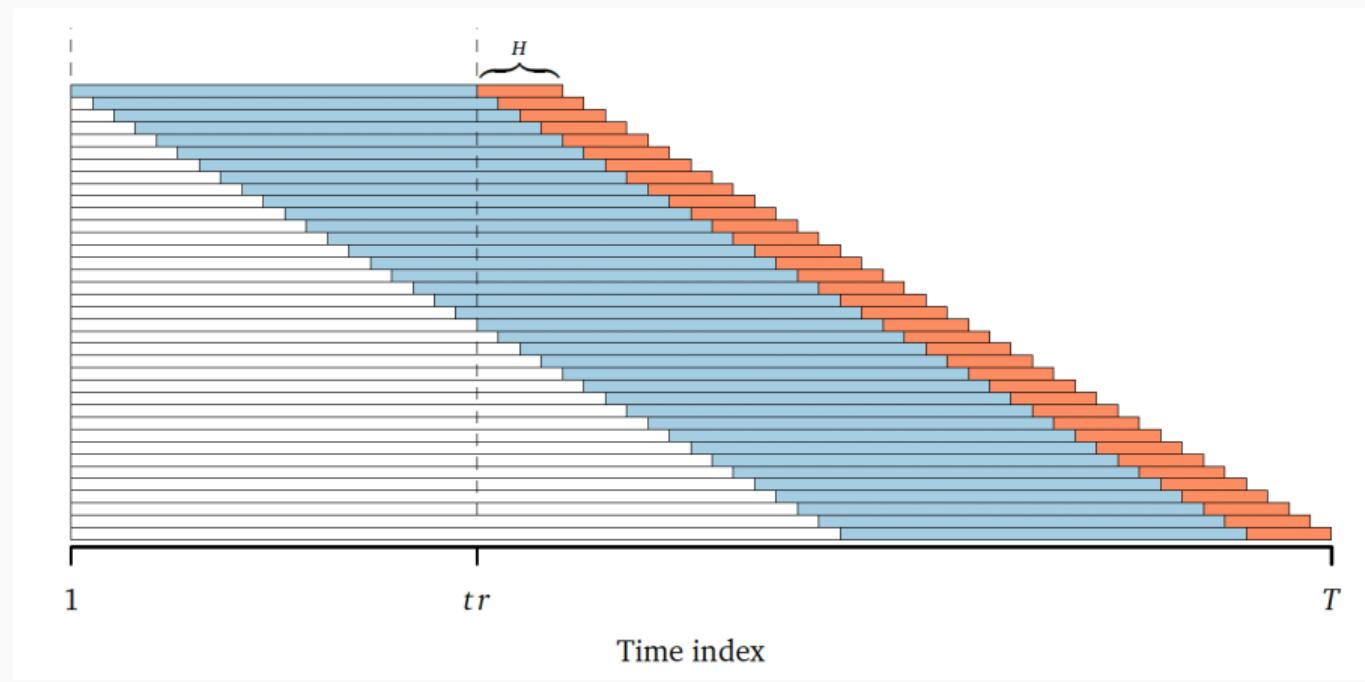
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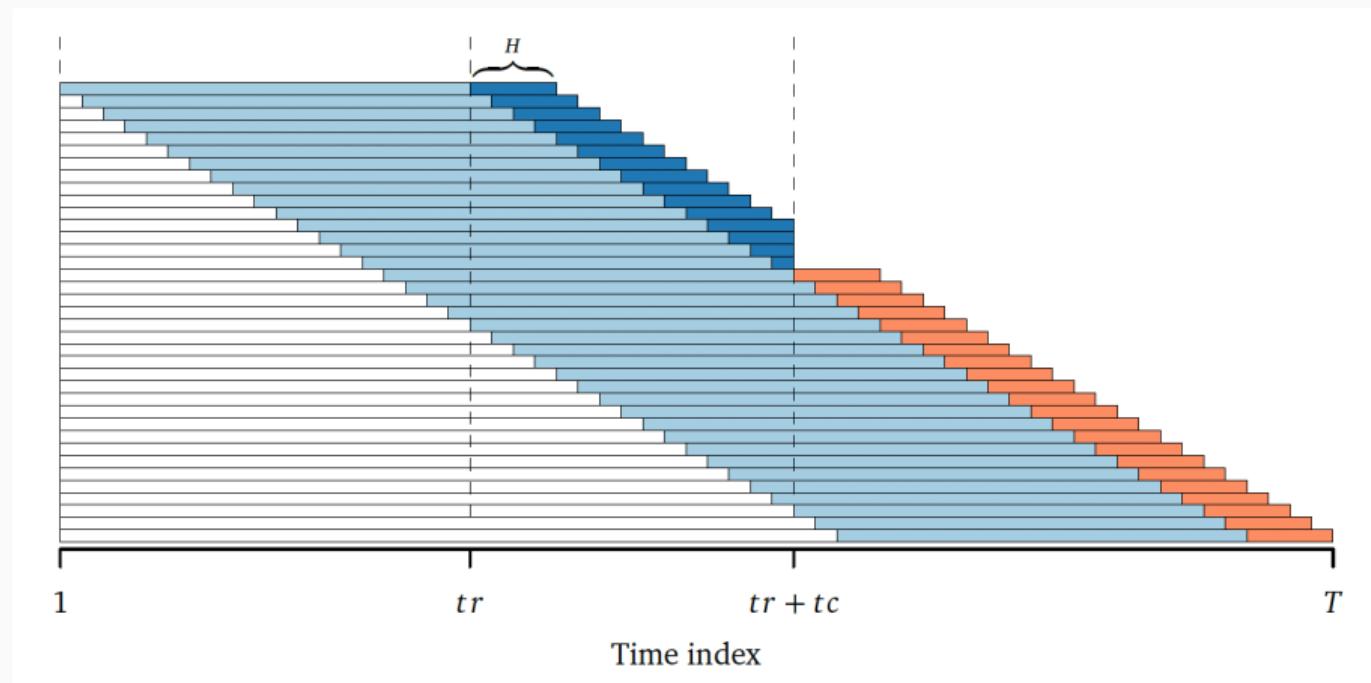
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- Main issue:
  - ▶ Difficult to analytically calculate  $h$ -step forecast variances for  $h > 1$

# Block bootstrap



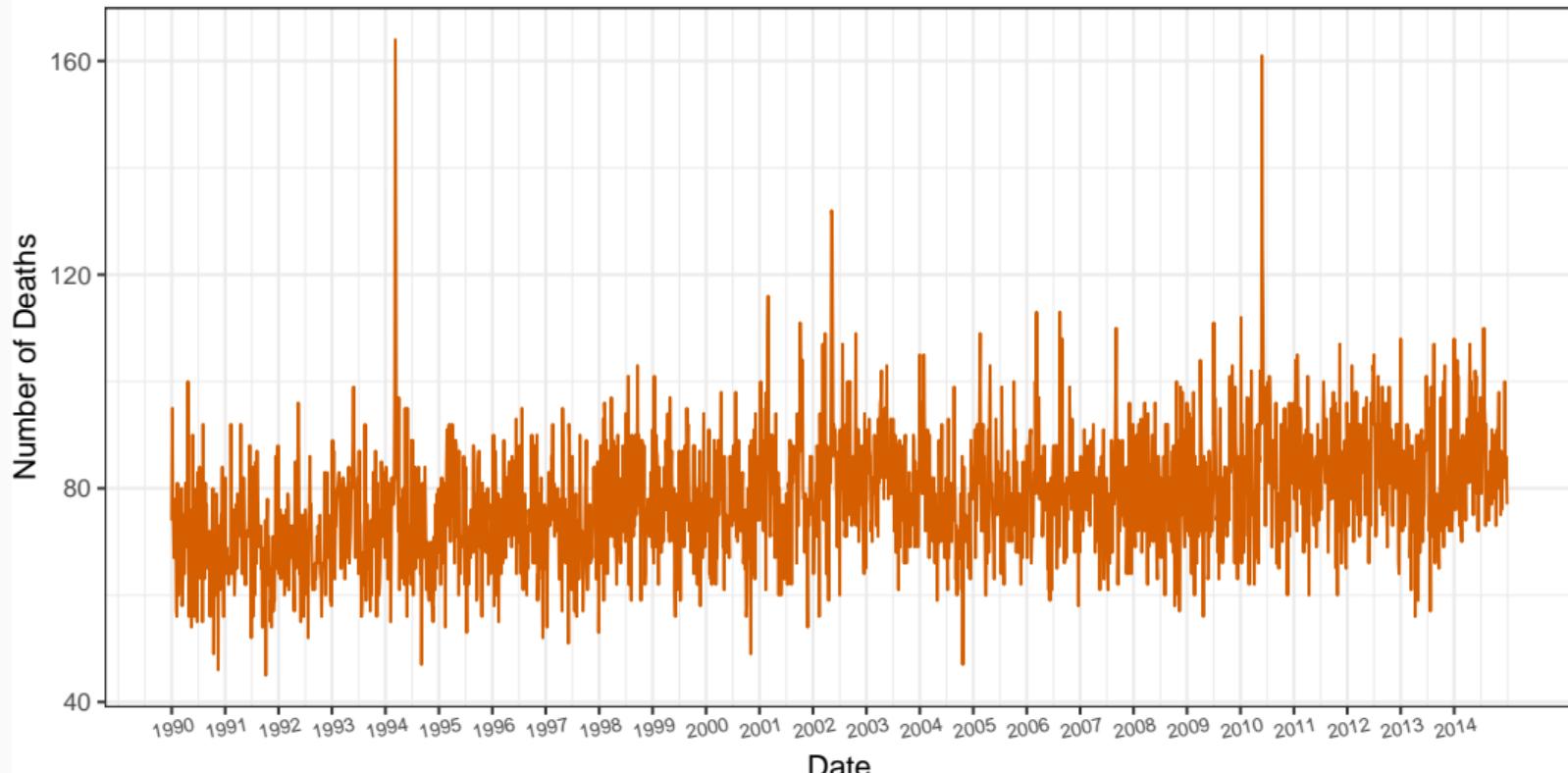
# Conformal prediction



# Conformal bootstrap

# Forecasting heat exposure-related daily mortality

Daily Deaths in Summer – Montreal, Canada



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## Data

- **Response:** Daily deaths in Summer
  - 1990 to 2014 – Montreal, Canada
- **Index Variables:**
  - ▶ Death lags
  - ▶ Max temperature lags
  - ▶ Min temperature lags
  - ▶ Vapor pressure lags
- **Nonlinear:** DOS (day of the season),  
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## Data split

- **Training Set:** 1990 to 2007
- **Validation Set:** 2008
- **Test Set:** 2009 to 2014

# Conclusion

## i Summary of Results (work-in-progress):

- **Block Bootstrap** – Under-coverage; too narrow
- **Conformal Prediction** – Better achieves a target coverage, with acceptable sharpness



## ⚠ Limitations:

- Test set is not long enough for larger forecast horizons
- Hyper-parameter choices

## Find me :

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