

# VAN NGUYEN NGUYEN

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**SUMMARY** — I am a Senior Research Scientist at [United Imaging Intelligence \(UII America\)](#). Prior to that, I received my PhD at [IMAGINE team](#) of École des Ponts ParisTech, advised by [Prof. Vincent Lepetit](#). My research focuses on 3D computer vision and robotics.

## EXPERIENCES

<b>United Imaging Intelligence</b> <i>Senior Research Scientist</i> <ul style="list-style-type: none"><li>Working on 3D computer vision and robotics for clinical AI products</li></ul>	<b>Jun 2025 - Now</b> <i>Burlington (MA), USA</i>
<b>Meta Reality Labs</b> <i>Research Intern</i> <ul style="list-style-type: none"><li>Worked on generic 6D object tracking with <a href="#">Tomáš Hodaň</a></li></ul>	<b>Jun 2024 – Feb 2025</b> <i>Zurich, Switzerland</i>
<b>Kyoto University</b> <i>Visiting PhD student, <a href="#">CVLab</a></i> <ul style="list-style-type: none"><li>Worked on articulated object reconstruction with <a href="#">Prof. Ko Nishino</a></li></ul>	<b>Mar 2024 – Apr 2024</b> <i>Kyoto, Japan</i>
<b>Meta Reality Labs</b> <i>Research Intern</i> <ul style="list-style-type: none"><li>Worked on 3D object detection on <a href="#">Project Aria</a> with <a href="#">Pierre Moulon</a></li></ul>	<b>May 2022 – Oct 2022</b> <i>Redmond (WA), USA</i>
<b>EPFL (Ecole Polytechnique Fédérale de Lausanne)</b> <i>Visiting PhD student, <a href="#">CVLab</a></i> <ul style="list-style-type: none"><li>Worked on templates for 3D object pose estimation <a href="#">Mathieu Salzmann</a></li></ul>	<b>Jul 2021 – Aug 2021</b> <i>Lausanne, Switzerland</i>
<b>Ecole des Ponts ParisTech</b> <i>Research Intern, <a href="#">IMAGINE team</a></i> <ul style="list-style-type: none"><li>Worked on 3D scene reconstruction with <a href="#">Mathieu Aubry</a> &amp; <a href="#">Prof. Vincent Lepetit</a></li></ul>	<b>Apr 2020 – Sep 2020</b> <i>Parisian area, France</i>
<b>Siemens Mobility</b> <i>Research Intern, <a href="#">Optiboard Team</a></i> <ul style="list-style-type: none"><li>Worked on robust lane detection for self-driving vehicle with Karim Berkani</li></ul>	<b>Feb 2019 – Jul 2019</b> <i>Parisian area, France</i>
<b>Neogia</b> <i>Research Intern, Research and Development Team</i> <ul style="list-style-type: none"><li>Worked on 3D face reconstruction from a single image with Mathieu Bouyrie</li></ul>	<b>Jul 2018 – Sep 2018</b> <i>Paris, France</i>

## EDUCATION

<b>Ecole des Ponts ParisTech</b> <i>Ph.D. in Computer Vision, advised by <a href="#">Prof. Vincent Lepetit</a></i> <ul style="list-style-type: none"><li>Research topics: 6D object pose estimation and tracking, 3D reconstruction</li></ul>	<b>Oct 2020 – Dec 2024</b> <i>Parisian area, France</i>
<b>Ecole Normale Supérieure Paris-Saclay</b> <i>Master of Science in Mathematics, Vision, Learning (<a href="#">MVA</a>)</i> <ul style="list-style-type: none"><li>Graduated with first-class honors (Mention “Très bien”)</li></ul>	<b>Sep 2019 – Sep 2020</b> <i>Parisian area, France</i>
<b>INSA Toulouse</b> <i>Master of Engineering in Applied Mathematics</i> <ul style="list-style-type: none"><li>Major in Data Science (*Location: 2014-2016 in Vietnam and 2016-2019 in France)</li></ul>	<b>Sep 2014 – Sep 2019</b> <i>Toulouse, France*</i>

## PUBLICATIONS

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### First-author papers:

#### **GoTrack: Generic 6DoF Object Tracking, CVPRW 2025**

*Van Nguyen Nguyen*, Christian Forster, Sindi Shkodrani, Bugra Tekin, Cem Keskin, Tomas Hodan

#### **BOP Challenge 2024 on Model-Based and Model-Free 6D Object Pose Estimation, CVPRW 2025**

*V.N.Nguyen*, S.Tyree, A.Guo, M.Fourmy, A.Gouda, T.Lee, S.Moon, H.Son, L.Ranftl, J.Tremblay, E.Brachmann, B.Drost, V.Lepetit, C.Rother, S.Birchfield, J.Matas, Y.Labbé, M.Sundermeyer, T.Hodan

#### **GigaPose: Fast and Robust Novel Object Pose Estimation via One Correspondence, CVPR 2024**

*Van Nguyen Nguyen*, Thibault Groueix, Mathieu Salzmann, Vincent Lepetit

#### **NOPE: Novel Object Pose Estimation from a Single Image, CVPR 2024**

*Van Nguyen Nguyen*, Thibault Groueix, Georgy Ponimatkin, Yinlin Hu, Renaud Marlet, Mathieu Salzmann, Vincent Lepetit

#### **CNOS: A Strong Baseline for CAD-based Novel Object Segmentation, ICCVW 2023**

*Van Nguyen Nguyen*, Thibault Groueix, Vincent Lepetit, Tomas Hodan

#### **PIZZA: A Powerful Image-only Zero-Shot Zero-CAD Approach to 6DoF Tracking, 3DV 2022 (Oral)**

*Van Nguyen Nguyen\**, Yuming Du\*, Yang Xiao, Michaël Ramamonjisoa, Vincent Lepetit

#### **Templates for 3D Object Pose Estimation Revisited: New Objects and Occlusions, CVPR 2022**

*Van Nguyen Nguyen*, Yinlin Hu, Yang Xiao, Mathieu Salzmann, Vincent Lepetit

### Co-author papers:

#### **OpenStreetView-5M: The Many Roads to Global Visual Geolocation, CVPR 2024**

G.Astruc, N.Dufour, I.Siglidis, C.Aronsohn, N.Bouia, S.Fu, R.Loiseau, V.N. Nguyen, C.Raude, E. Vincent, L.Xu, H.Zhou, L.Landrieu

#### **BOP Challenge 2023 on Detection, Segmentation and Pose Estimation, CVPRW 2024**

T.Hodan, M.Sundermeyer, Y.Labbé, V.N. Nguyen, G. Wang, E.Brachmann, B.Drost, V.Lepetit, C.Rother, J.Matas

## REVIEWING

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- Computer Vision and Pattern Recognition (**CVPR**): 2022, 2023, 2024, 2025
- International Conference on Computer Vision (**ICCV**): 2023, 2025
- European Conference on Computer Vision (**ECCV**): 2022, 2024
- Neural Information Processing Systems (**NeurIPS**): 2024, 2025
- International Conference on Intelligent Robots and Systems (**IROS**): 2024, 2025
- Transactions on Pattern Analysis and Machine Intelligence (**TPAMI**): 2022
- International Conference on 3D Vision (**3DV**): 2024
- Asian Conference on Computer Vision (**ACCV**): 2024
- British Machine Vision Conference (**BMVC**): 2021

## OTHER SERVICES

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- **Teaching**: Image Processing and Artificial Vision (1st Master level) in 2021, 2022
- **Challenges**: Benchmark on 6D Object Pose Estimation, [bop.felk.cvut.cz](http://bop.felk.cvut.cz)
- **Workshops**: Recovering 6D object pose (ECCV 2024), [cmp.felk.cvut.cz/sixd/workshop\\_2024](http://cmp.felk.cvut.cz/sixd/workshop_2024)

## LANGUAGES

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**English:** Fluent

**French:** Fluent

**Vietnamese:** Native