

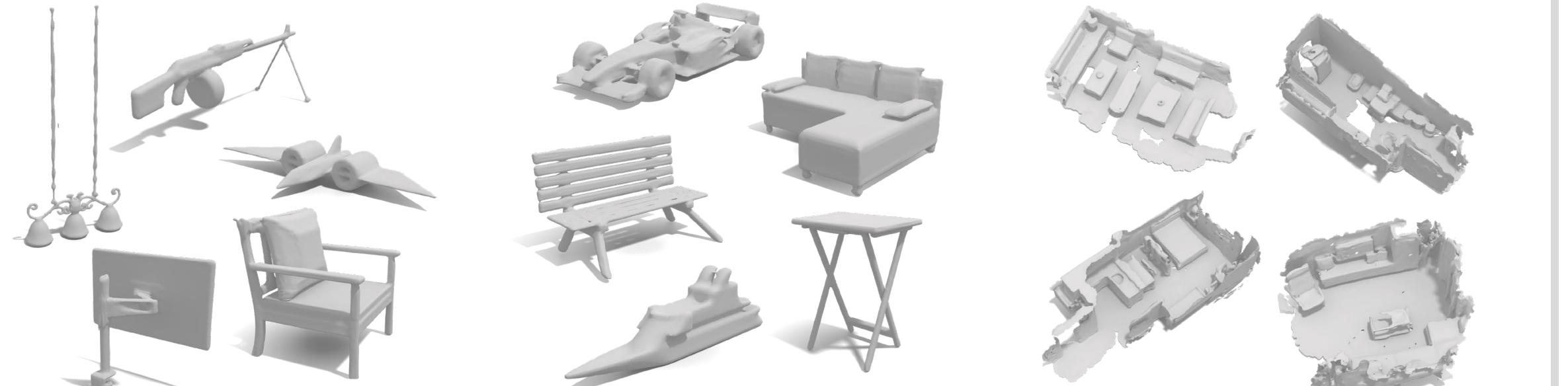
# Neural Fields as Learnable Kernels for 3D Reconstruction

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Project page

## Surface Reconstruction from Sparse Point Clouds


In-category (ShapeNet<sup>[1]</sup> to ShapeNet<sup>[1]</sup>)   Out-of-category (chair to other)   Generalization (ShapeNet<sup>[1]</sup> to ScanNet<sup>[2]</sup>)

## Kernel Ridge Regression

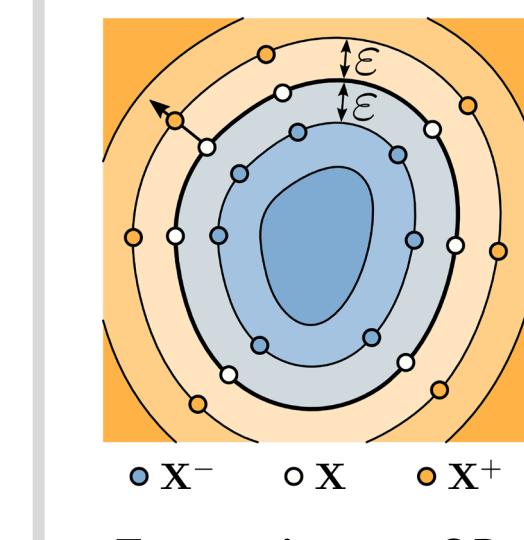
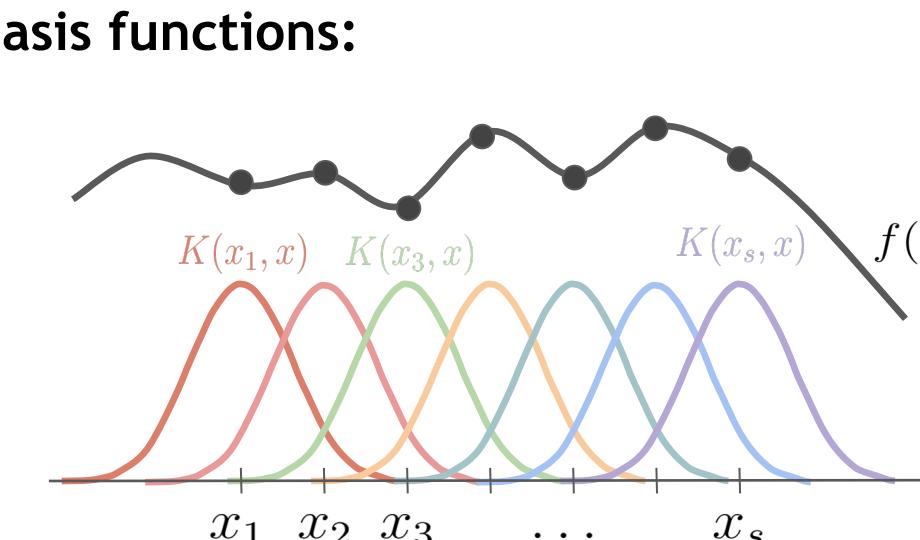
Implicit function as a sum of basis functions:

$$f(x; \theta) = \sum_{j=1}^s \alpha_j K_\infty(x_j, x)$$

$$(K + \lambda I)\alpha = y$$

Solution that minimizes:

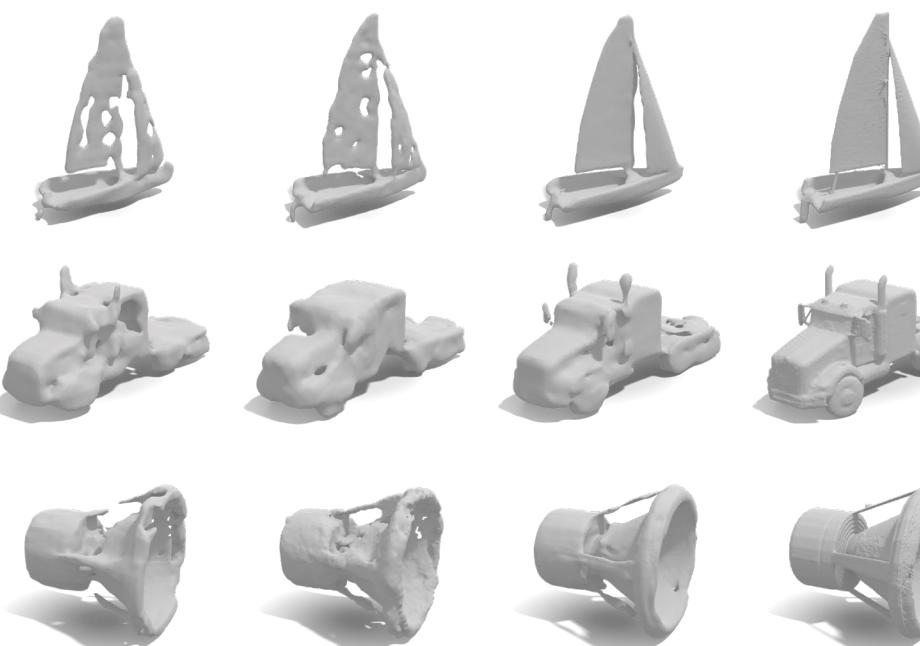
$$\|f\|_K$$



Extension to 3D

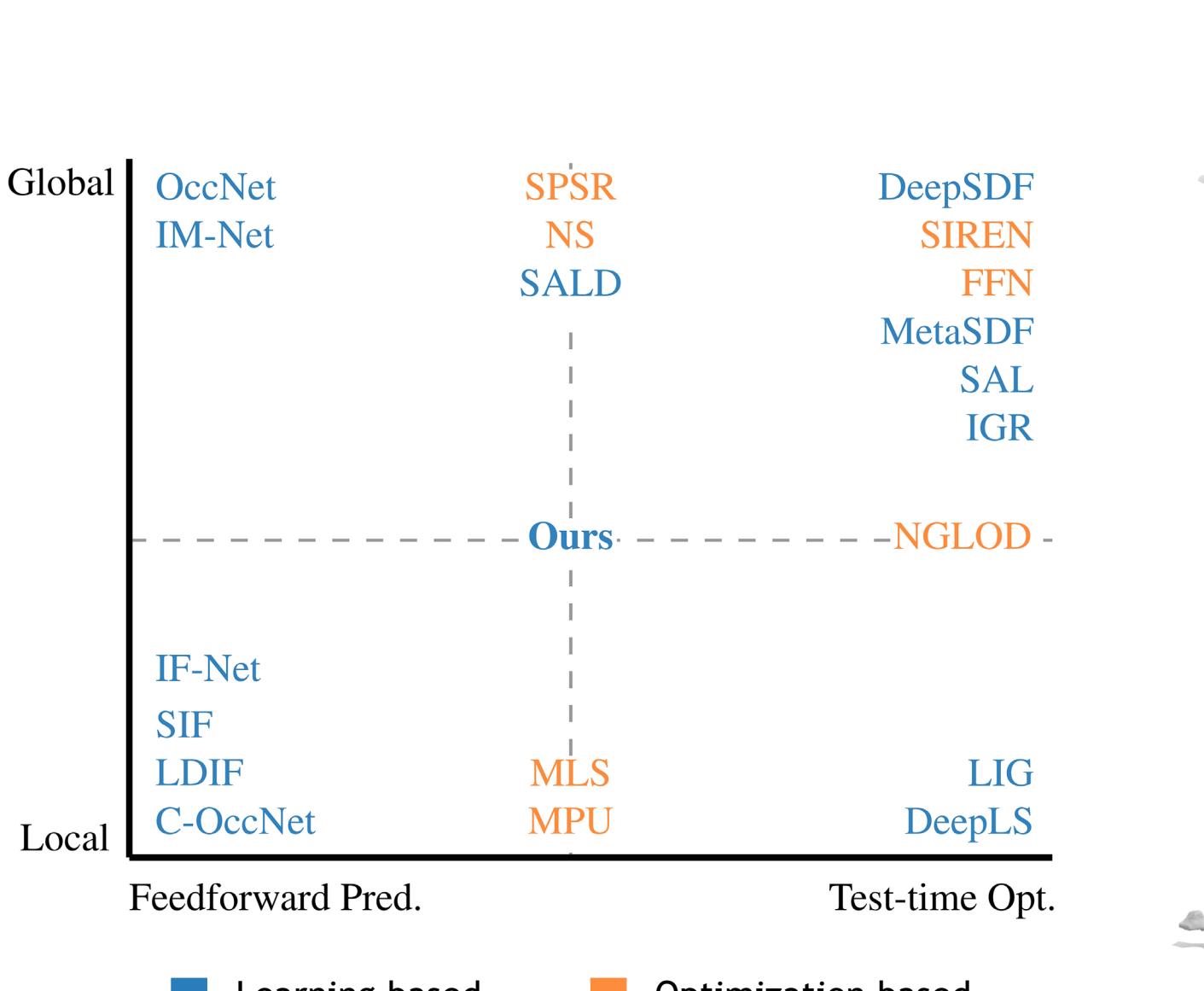
## Generalization Performance

### Half Categories to Other half

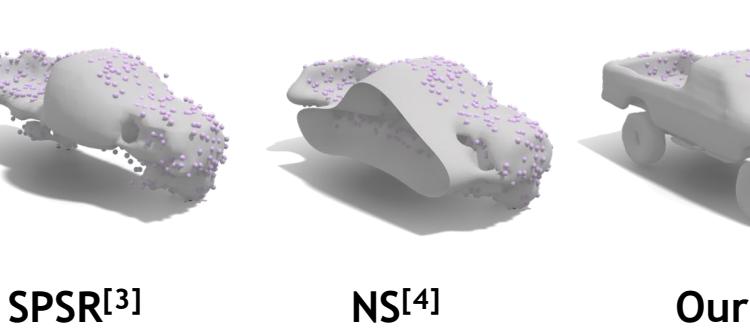

C-OccNet<sup>[6]</sup>   SAP<sup>[8]</sup>   Ours   GT

	IoU ↑	Chamfer ↓	Normal C. ↑
OccNet	0.572 (-38.6%)	0.143 ( <b>0.076</b> )	0.824 (-10.4%)
C-OccNet	0.785 (-6.9%)	0.061 ( <b>0.013</b> )	0.912 (-2.0%)
LIG	0.518 (N.A.)	0.112 (N.A.)	0.536 (N.A.)
NS	0.869 (0.0%)	0.049 (0.000)	0.924 (0.0%)
SAP	0.855 (-2.0%)	0.036 ( <b>0.004</b> )	0.929 (-1.7%)
Ours	<b>0.939 (-1.0%)</b>	<b>0.028 (<b>0.003</b>)</b>	<b>0.939 (-0.9%)</b>
Ours w/o norm.	0.897 (-3.3%)	0.033 ( <b>0.004</b> )	0.922 (-1.6 %)

## Prior Work



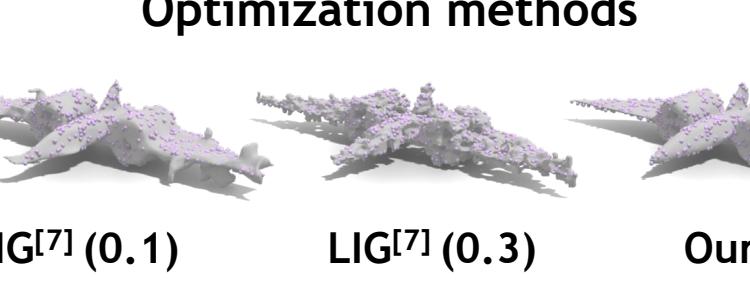
### Data free methods



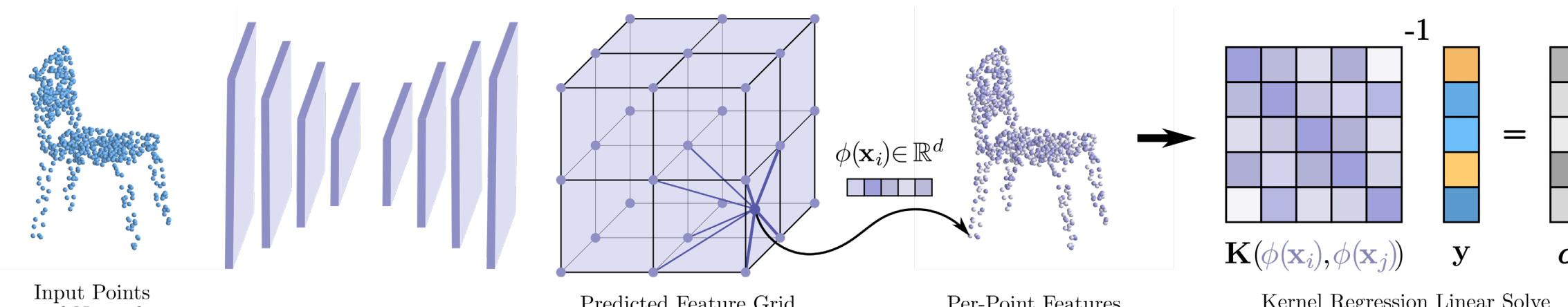
### Feed-forward methods



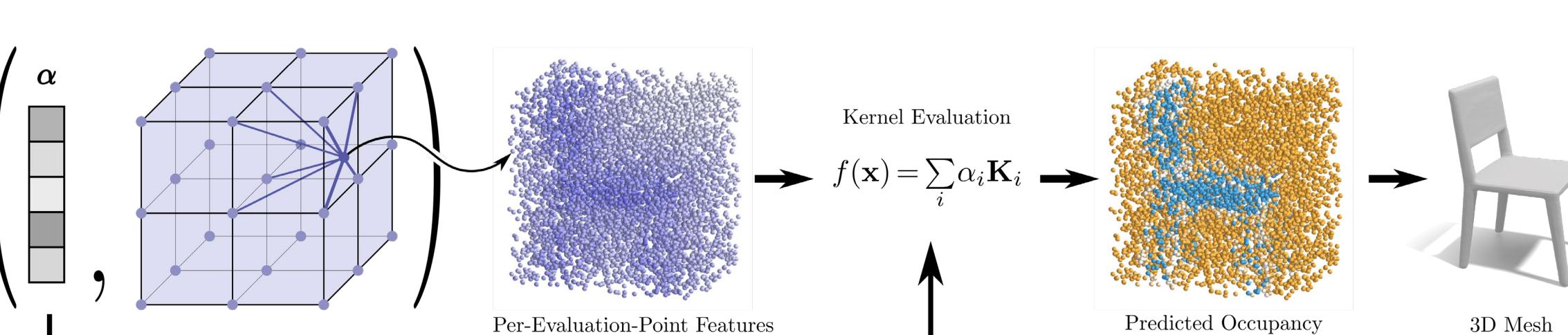
### Optimization methods



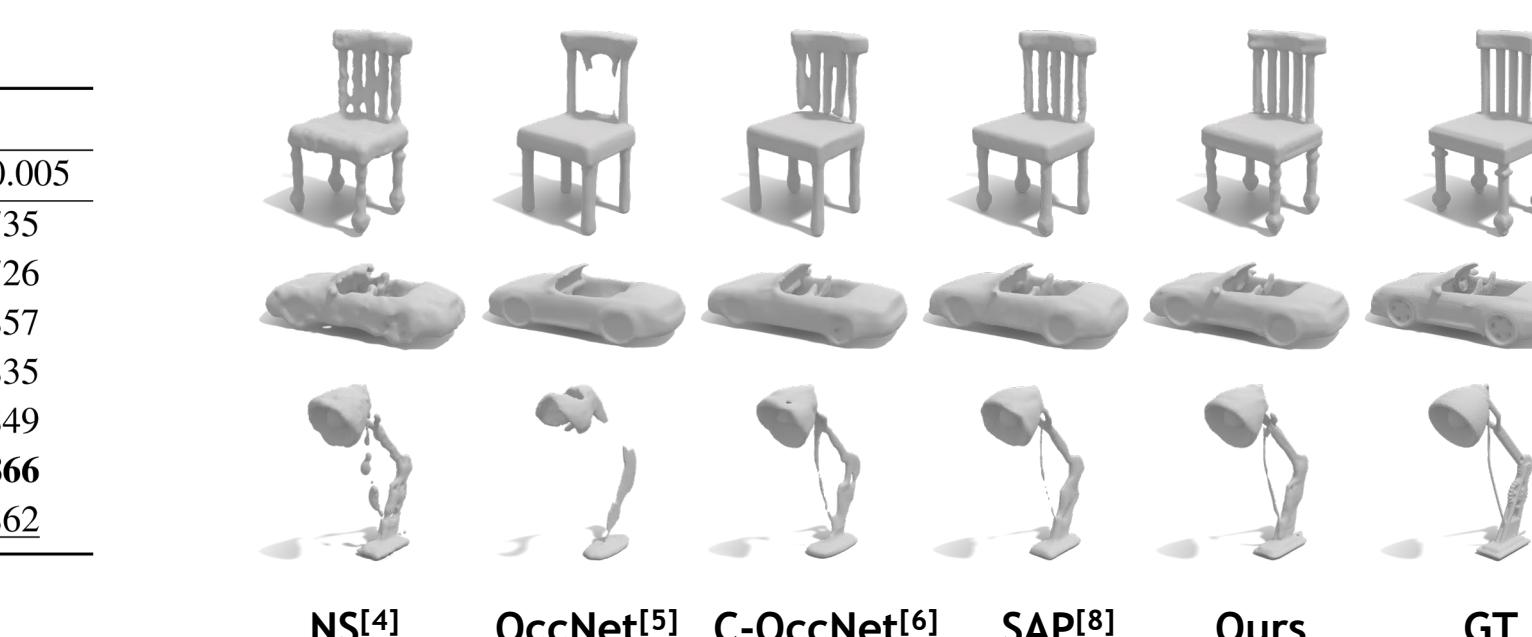
## Prediction:



## Evaluation:



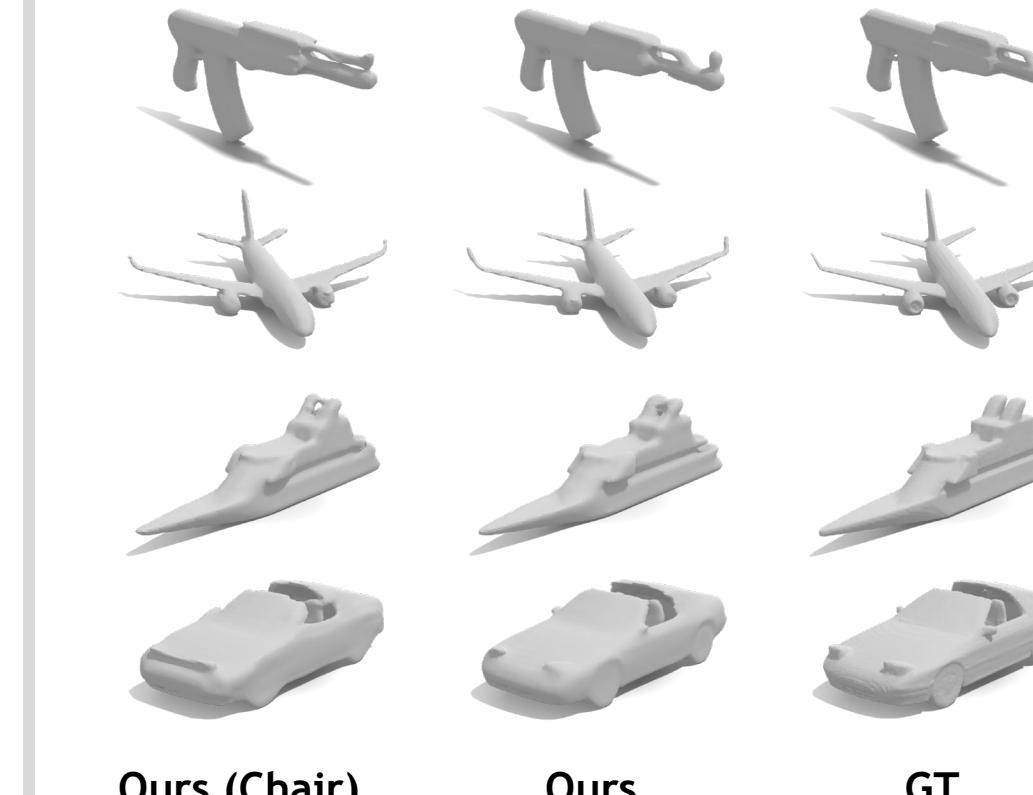
## In-Category Reconstruction


NS<sup>[4]</sup>   OccNet<sup>[5]</sup>   C-OccNet<sup>[6]</sup>   SAP<sup>[8]</sup>   Ours   GT

## References

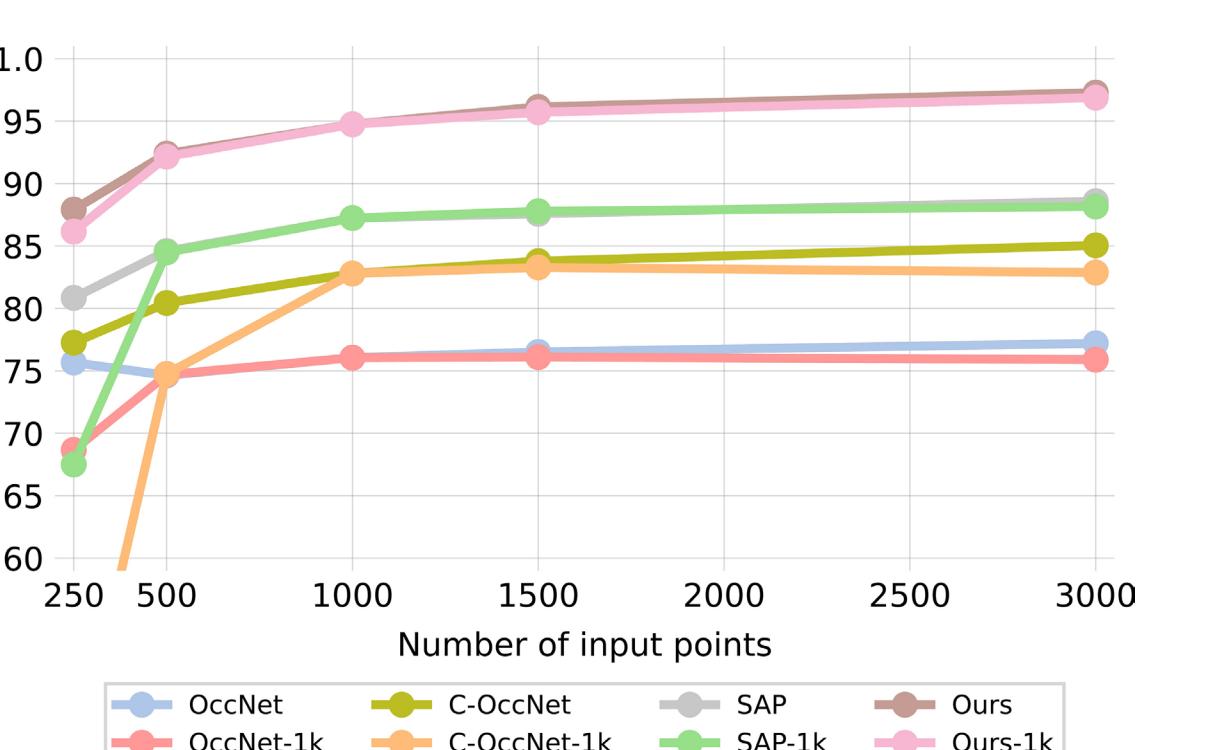
- <sup>[1]</sup> Chang, Angel X., et al. "Shapenet: An information-rich 3d model repository." *arXiv preprint arXiv:1512.03012* (2015).
- <sup>[2]</sup> Dai, A., Chang, A. X., Savva, M., Halber, M., Funkhouser, T., & Nießner, M. (2017). Scannet: Richly-annotated 3d reconstructions of indoor scenes. In *CVPR* (pp. 5828-5839).
- <sup>[3]</sup> Kazhdan, M., & Hoppe, H. (2013). Screened poisson surface reconstruction. *ACM Transactions on Graphics (ToG)*, 32(3), 1-13.
- <sup>[4]</sup> Williams, F., Trager, M., Bruna, J., & Zorin, D. (2021). Neural splines: Fitting 3d surfaces with infinitely-wide neural networks. In *CVPR* (pp. 9949-9958).
- <sup>[5]</sup> Mescheder, L., Oechsle, M., Niemeyer, M., Nowozin, S., & Geiger, A. (2019). Occupancy networks: Learning 3d reconstruction in function space. In *CVPR* (pp. 4460-4470).
- <sup>[6]</sup> Peng, S., Niemeyer, M., Mescheder, L., Pollefeys, M., & Geiger, A. (2020, August). Convolutional occupancy networks. In *ECCV* (pp. 523-540). Springer, Cham.
- <sup>[7]</sup> Jiang, C., Sud, A., Makadia, A., Huang, J., Nießner, M., & Funkhouser, T. (2020). Local implicit grid representations for 3d scenes. In *CVPR* (pp. 6001-6010).
- <sup>[8]</sup> Peng, S., Jiang, C., Liao, Y., Niemeyer, M., Pollefeys, M., & Geiger, A. (2021). Shape as points: A differentiable poisson solver. In *NeurIPS*, 34.

### Chair to Other Categories

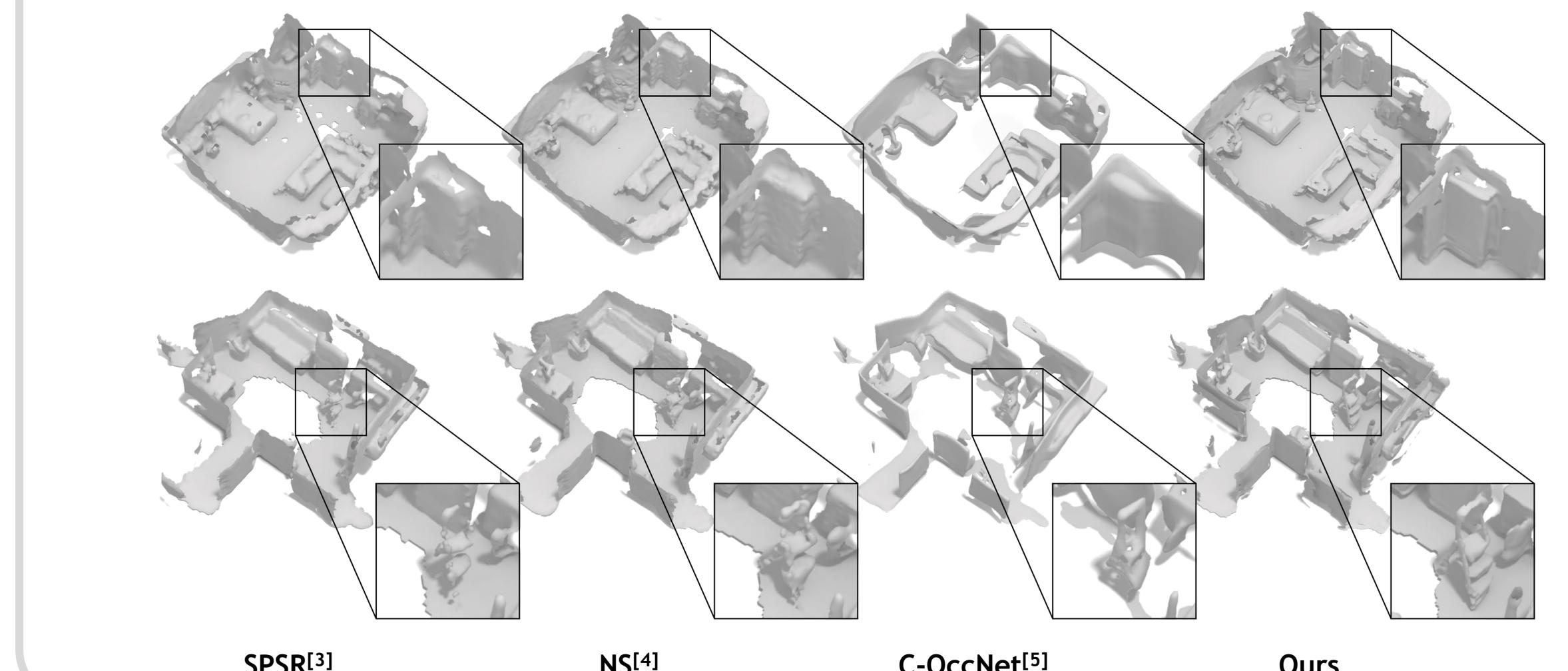


Ours (Chair)   Ours   GT

### Across different number of points



### Generalization from ShapeNet<sup>[1]</sup> to ScanNet<sup>[2]</sup>


SPSR<sup>[3]</sup>   NS<sup>[4]</sup>   C-OccNet<sup>[5]</sup>   Ours