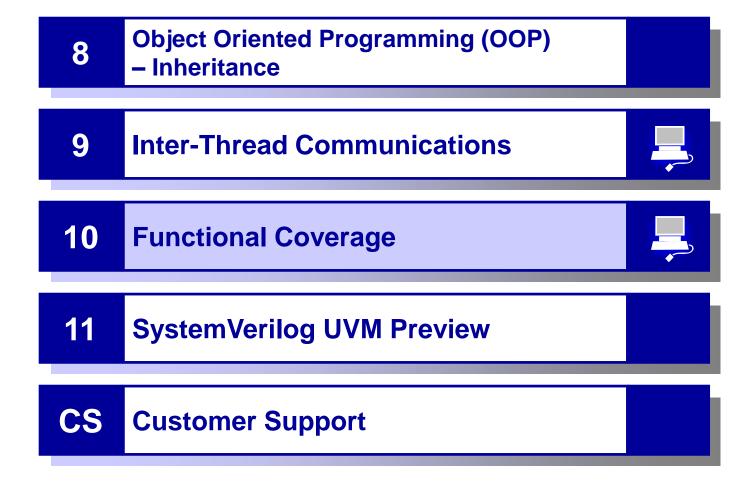
## **Agenda**





### **Unit Objectives**

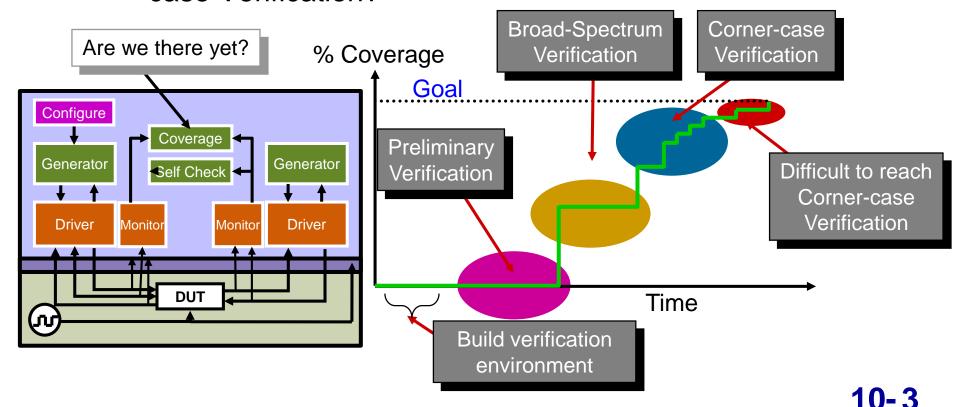
After completing this unit, you should be able to:

- Define functional coverage structures
  - Specify the coverage sample mechanisms
  - Define signals and variables to be sampled
  - Specify expected values that indicate functionality
  - Use parameters to make coverage instances unique
  - Use coverage attributes to customize individual coverage structures
- Measure coverage dynamically
- Generate coverage reports after running VCS

#### **Phases of Functional Verification**

#### Implement functional coverage to answer

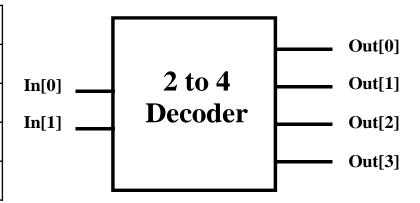
- Has verification goal been reached?
- When to switch to corner-case Verification?
- When to write directed tests for difficult to reach cornercase Verification?



### **Combinational Logic Example**

#### Goal: Check all combinations of input and output patterns

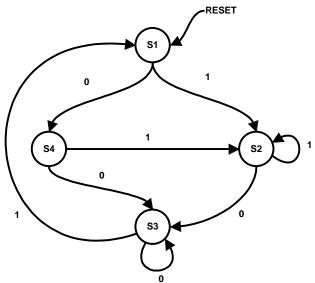
In[1]	In[0]	Out[3]	Out[2]	Out[1]	Out[0]
0	0	0	0	0	1
0	1	0	0	1	0
1	0	0	1	0	0
1	1	1	0	0	0



- Create state coverage bins to track input & output bit patterns
- Define sample timing for coverage bins
- Track state coverage bin results

### **State Transition Example**

Goal: Check temporal state transitions



- Create state coverage bins to monitor states
- Create transition coverage bins to monitor state transitions

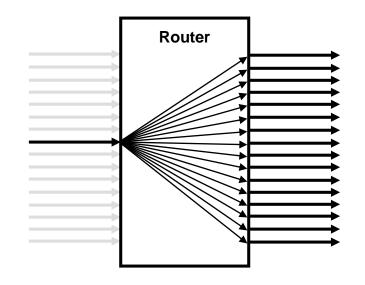
$$S1 \Rightarrow S2 \Rightarrow S3 \Rightarrow S1 \Rightarrow S4 \Rightarrow S2 \Rightarrow S2 \Rightarrow S3 \Rightarrow S1$$

- Define sample timing for coverage bins
- Track transition coverage bin results

### **Cross Correlation Example**

#### Goal: Check all input ports have driven all output ports

Input port	Output port	
0	0	
0	1	
0	2	
15	14	
15	15	



- Create cross coverage bins to correlate activities of input ports with respect to output ports
- Define sample timing for coverage bins
- Track cross coverage bin results

## Functional Coverage in SystemVerilog

- Create a covergroup
  - Standalone Recommended for reusability
  - Inside classes
- Covergroup encapsulates:
  - Coverage bins definitions
    - State
    - ◆ Transition
    - Cross correlation
  - Coverage bins sample timing definition
  - Coverage attributes e.g. coverage goal
- Instantiate coverage object(s) from covergroup using new()
  - Scope of variable visibility is same as subroutines
- Query coverage object to determine progress of verification
- Only 2-state values covered
  - Sampled values with X or Z <u>excluded</u> from coverage

### **Functional Coverage Example**

#### Create coverage group

```
program \( \text{comatic test:} \)
 covergroup fcov() @(port event);
 coverpoint sa;
 coverpoint da;
 endgroup: fcov
bit[3:0] sa, da;
 event port event;
                               Declare & construct coverage object
 real coverage = 0.0;
                                           (required)
 fcov port fc = new();
 initial while (coverage < 99.5) begin
  sa = pkt ref.sa;
                     Query coverage result
  da = pkt ref.da;
  ->port event;
                           // alternative form of updating of bins
// port fc.sample();
   coverage = port fc.get inst coverage(); // instance coverage
 end
endprogram: test
```

#### **State Bin Creation (Automatic)**

SystemVerilog can automatically create state bins

```
bit [3:0] sa,da;
covergroup cov1 @ (posedge rtr_io.clock);
  coverpoint sa; //16 bins
  coverpoint da; //16 bins
  compare: coverpoint (sa > da); // 2 bins
  concat: coverpoint {sa, da} { // 256 bins
   option.auto_bin_max = 256; // else 64 bins default
  }
endgroup: cov1
```

- Bin name is "auto[value\_range]"
  - The value\_range are the value range which triggered that bin
- Maximum number of bins is set by auto\_bin\_max
  - Controlled using the auto\_bin\_max attribute
  - Bins are allocated with equal number of states

## **Measuring Coverage**

#### Without auto binning:

Coverage is:

```
# of bins covered (have at_least hits)
# of total bins
```

#### With auto binning:

auto\_bin\_max limit the number of bins used in the coverage calculation

Coverage is:

```
# of bins covered (have at_least hits)
min( possible values for data type | auto_bin_max)
```

### **Automatic State Bin Creation Example**

```
bit[3:0] sa, da;
covergroup cov addr @(rtr io.cb);
  coverpoint sa;
  coverpoint da;
  option.auto bin max = 2; // maximum of 2 auto-created bins
endgroup: cov addr
                                                        Var
                                                              Bin
                                                                    #Hit
                                                            auto[0:7]
                                                        sa
                                                                     1
                                         (50% covered)
cov addr cov1 = new();
                                                            auto[8:15]
                                                        da
                                                                     1
sa = 1; da = 8;
                                                        Var
                                                              Bin
                                                                    #Hit
@(rtr io.cb);
$display("%0d covered", $get_coverage());
                                                            auto[0:7]
                                                        sa
                                         (75% covered)
                                                            auto[8:15]
                                                                     1
sa = 9; da = 9;
                                                            auto[8:15]
                                                        da
                                                                     2
@(rtr io.cb); -
$display("%0d covered", $get coverage());
                                                              Bin
                                                                    #Hit
                                                        Var
                                                            auto[0:7]
                                        (100% covered)
                                                        sa
sa = 3; da = 5;
                                                            auto[8:15]
                                                                     1
@(rtr io.cb); -
                                                            auto[0:7]
                                                        da
$display("%0d covered", $get_coverage());
                                                            auto[8:15]
                                                                     2
```

#### State and Transition Bin Creation (User)

- Define state bins using ranges of values
- Define transition bins using state transitions

```
covergroup MyCov() @(cov event);
  coverpoint port number {
    bins s0 = \{ 0 \};
                                           // one bin for port number == 0
                                           // creates one state bin
    bins lo = { [0:7] };
    bins hi[] = { [8:15] };
                                      // creates 8 state bins
                                           // hi 8 through hi f
    ignore_bins ignore = { 16, 20 };  // ignore if hit
    illegal_bins bad = default;  // terminates simulation if hit
                                           // default refers to undefined values
    bins t0 = (0 \Rightarrow 8, 9 \Rightarrow 0); // creates one transition bin
    bins t1[] = (8, [0:7] \Rightarrow [8:15]); // creates 72 transition bins
    bins other trans = default sequence; // all other single state transitions
    illegal bins bad trans = default sequence; // terminates simulation
endgroup: MyCov
```

## **Cross Coverage Bin Creation**

VCS can automatically create cross coverage bins

```
covergroup cov1() @(rtr_io.cb);
  coverpoint sa;
  coverpoint da;
  cross sa, da;
  cross p_cnt, mde; //implicit bins for p_cnt,mde
endgroup: cov1
```

Users can also define cross bins to cover\*

```
src: coverpoint sa; //can label coverpoints
dest: coverpoint da { bins d1 = { 0 }; bins d2 = default; }
cx: cross src, dest {
  bins lo = binsof(src) intersect {[0:4]};
  bins mid = binsof(src) && binsof(dest.d1); //expression
  bins hi = ! binsof(src) intersect {[0:7]};
}
```

#### **Wildcard Bins**

#### Can use wildcards to express bin ranges

- Use wildcard keyword in bin definition
- Similar to ==? operator
- ?, x or z may be used as wildcard
  - ? preferred to avoid confusion when covering 4-state variables

## Bin Coverage - with

#### Use with to limit values that are included in a bin

- The with clause specifies that only those values that satisfy the given expression (for which the expression evaluates to true) are included in the bin
- Expression has access to sampled value via item

```
covergroup cg0; true to update bin(s)

gfc\_cp: coverpoint gfc {
    bins lo[] = \{[0:8'h0f]\} with (item \% 2 == 0);
    bins med[] = \{[8'h10:8'hc0]\} with (item \% 3 == 0);
}
endgroup

Creates 8 bins for lo
Creates 60 bins for med
```

## **Specifying Sample Event Timing**

```
covergroup definition_name [(argument_list)] [sample_event];
  [label:] coverpoint coverage_point { ... }
}
```

- sample\_event defaults to with function sample()
  - Can be overridden with one of:
    - user defined arguments to sample() method
    - @([specified\_edge] signals | variables)
- Bins are updated asynchronously as the sample\_event occurs
  - To update bins at end of simulation time slot
    - ◆ set type option.strobe\* = 1 in covergroup

### **Parameterized Sample Method**

Can override sample() with a triggering function sample() that accepts arguments

```
covergroup pkt_cg with function sample(Packet pkt);
```

- Allows sampling of coverage data from contexts other than the scope enclosing the covergroup declaration
- Can be called from
  - automatic task or function.
  - sequence or property of a concurrent assertion
  - procedural block
- Formal arguments of the sample method should
  - only designate a coverpoint or conditional guard expression
  - be different from list of covergroup arguments since they belong to the same lexical scope as the formal arguments to the covergroup
  - not designate an output direction

#### Parameterized Sample Method: Example

```
covergroup pkt_cg with function sample(Packet pkt);
  src: coverpoint pkt.sa;
  dst: coverpoint pkt.da;
  cross src, dst;
endgroup: pkt cg
pkt_cg p_cg = new();
function bit Packet::check();
  if (actual_pkt.compare(ref_pkt, message)) begin
    p_cg.sample(actual_pkt);
endfunction: check
```

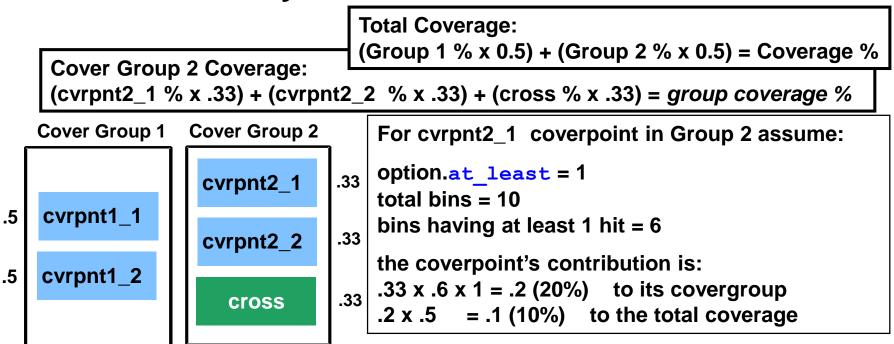
## **Determining Coverage Progress**

\$get\_coverage() returns testbench coverage percentage as a real value

```
covergroup cov1(ref int x, int y) @(rtr io.cb);
   mode1: coverpoint x {
   bins S 1[] = \{ [34:78], [1:27] \}; \}
endgroup: cov1
program automatic Main;
  int a;
  real cov percent;
  cov1 c obj1 = new(a, b);
  initial forever begin
    cov percent = $get coverage();
    $display("%0d covered\n", cov_percent);
  end
endprogram: Main
```

### **Coverage Measurement Example**

- Each covergroup contributes equally to total coverage
- Each coverpoint/cross block contributes equally to the covergroup's coverage
- Attributes may affect contributions



## **Coverage Attributes (1/2)**

- Coverage attributes are defined for entire coverage groups or for individual coverpoints
  - Defined using option or type\_option keyword
  - Attributes at the coverage group level may be overridden at the sample and cross level
  - Attributes may be different for each instance of a coverage object by passing arguments

```
covergroup cov1(int var1) @(cov_event);
  option.auto_bin_max = var1; // entire group

coverpoint x {
    option.auto_bin_max = 4; // just for x
    bins lower = { [1:8] };
    ...
}
endgroup: cov1
```

## **Coverage Attributes (2/2)**

#### Coverage attributes are of two kinds

- Instance-specific coverage attributes
  - option.<attribute> = <value>;
- Type-specific (static) coverage attributes
  - ◆ type\_option.<attribute> = <value>;

#### Attributes available for both kinds - weight, comment

- option.<common\_attr>
  - ♦ Will work only if attribute option.per\_instance = 1
  - Will save separate instance based coverage
- Use type\_option.<attr> for cumulative coverage attributes

```
covergroup cov1 @(cov_event);
  coverpoint sa { type_option.weight = 0; }
  coverpoint da { type_option.weight = 0; }
  cross sa, da; //only cross is covered
  endgroup: cov1
```

### **Major Coverage Attributes**

- at\_least (1):
  - Minimum hits for a bin to be considered covered
- auto\_bin\_max (64):
  - Maximum number automatically created bins
    - Each bin contains equal number of values
- comment\*:
  - A comment that is saved in the database and appears in the report
     \* also available as a
- weight (1)\*:
  - Multiplier for coverage bins
- per\_instance (0):
  - Specifies whether to also collect coverage statistics per instance for a coverage group

type option

Cumulative statistics always collected

### **Control and Query of Covergroups**

#### Methods for control and query of covergroups

- sample() only works on a covergroup instance
- All others work on covergroup, coverpoint or cross

Method	Function		
<pre>void sample()</pre>	Triggers sampling of the covergroup – only works on covergroup		
real get_coverage()	Calculates type coverage number (0100)		
<pre>real get_inst_coverage() (Not supported yet by VCS)</pre>	Calculates the coverage number (0100) - Must set type_option.merge_instances = 1		
<pre>void start()</pre>	Starts collecting coverage information		
<pre>void stop()</pre>	Stops collecting coverage information		

#### Parameterized Coverage Group

- Variables passed by reference or value
- Variables used in guard expressions

```
must be ref – covered variable
 covergroup MyCov(ref reg[3:0] data, ←
                   reg reset 1, ←
pass by value
                 →input reg[3:0] middle)
                                            reset 1 – guard variable
    coverpoint data { // sampled parameter
                                            can be ref or pass by value
       bins s lo (0:middle);
       bins s hi[] (middle+1:15) iff (reset 1);
                                                       guard expression
 endgroup: MyCov
 program automatic Example(router io.TB rtr io);
    reg [3:0] mydata; reg reset 1;
                                            Bin s lo (0:7),
    MyCov cov1;
                                            8 bins s_hi[8]...s_hi[15]
    initial begin
    cov1 = new(mydata, reset 1, 7);
                                            data not sampled when
    reset 1 = 0; mydata=3;
                                            reset_l=0
    cov1.sample();←
    #1 reset 1 = 1; cov1.sample(); end
 endprogram: Example
                                            data sampled this time
```

### **Coverage Result Reporting Utilities**

- VCS writes coverage data to a binary database file
  - The database directory is named simv.vdb
- Generate HTML report:

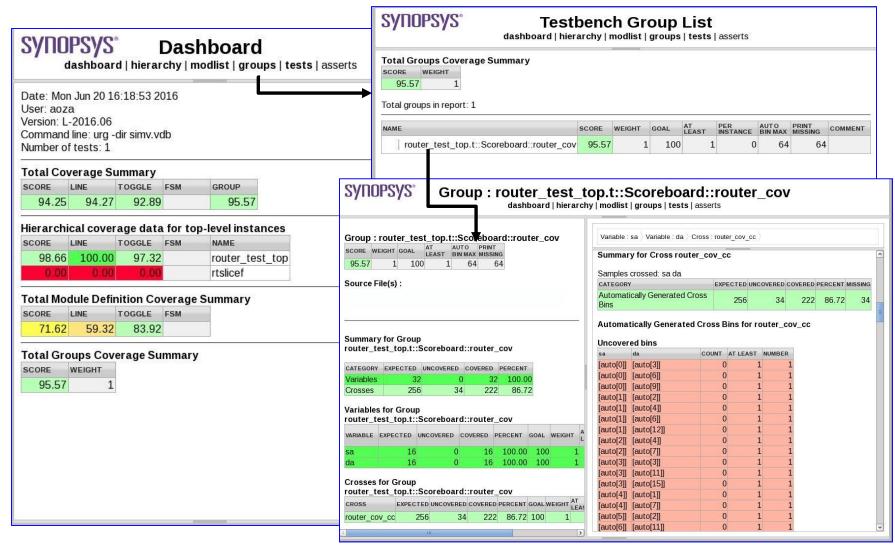
```
urg -dir <directory>
example: urg -dir simv.vdb
```

Generate Text Report:

```
urg -dir <directory> -format text
example: urg -dir simv.vdb -format text
```

The data in all coverage database files in that directory are merged and reported

## Sample URG HTML Report

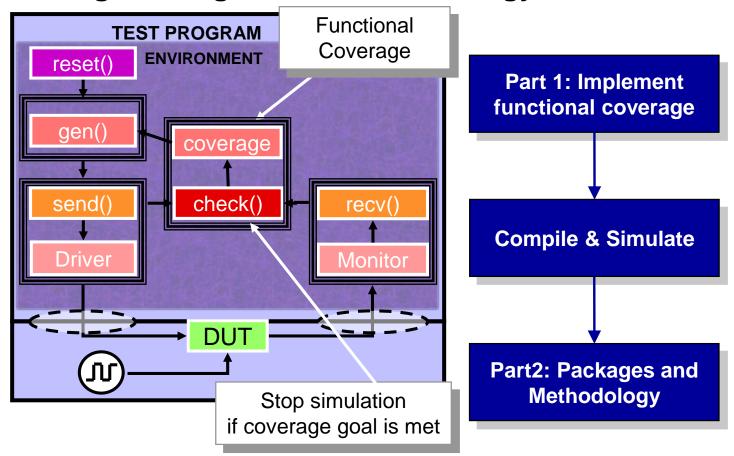


#### **Lab 6 Introduction**



60 min

Implement Functional Coverage, Packages using an OOP Methodology



### **Unit Objectives Review**

#### Having completed this unit, you should be able to:

- Define functional coverage structures
  - Specify the coverage sample mechanisms
  - Define signals and variables to be sampled
  - Specify expected values that indicate functionality
  - Use parameters to make coverage instances unique
  - Use coverage attributes to customize individual coverage structures
- Measure coverage dynamically
- Generate coverage reports after running VCS

## **Appendix**

**Advanced Coverage Topics** 

**Merging Coverage Results** 

**Covergroup Exclusion** 

**Test Grading** 

### **Merging Coverage Results**

### **Merging Coverage Results**

# Providing multiple coverage directories to URG creates merged result

- % urg -dir test1/simv.vdb -dir test2/simv.vdb -dir ...
- Does <u>not</u> merge the database

#### Merge Database using

- % urg -dbname mrgdb -dir t1.vdb -dir t2.vdb
- merged database looks as if single test produced the results

#### Recommendation

- Create separate coverage database for each test
- Only merge coverage databases of tests that <u>passed</u>
- Re-run all tests to collect coverage if design/testbench has changed a lot

## Merging Coverage Results - Parallel Merging

#### Parallel Merging

- Distributes the merging operations on several machines
  - Can specify a set of machines as a list
  - Can use the LSF or GRID options
- Can provide improvement in performance for merge
  - e.g. improved the time from 3 hrs to 27 min (6.7x) using 8 CPUs

```
% urg -parallel \
    -noreport \
    -dir test1/simv.vdb \
    -dir test2/simv.vdb \

    urg -parallel \
    use -noreport to
    merge databases, but
    avoid generating URG
    report.
```

#### For help

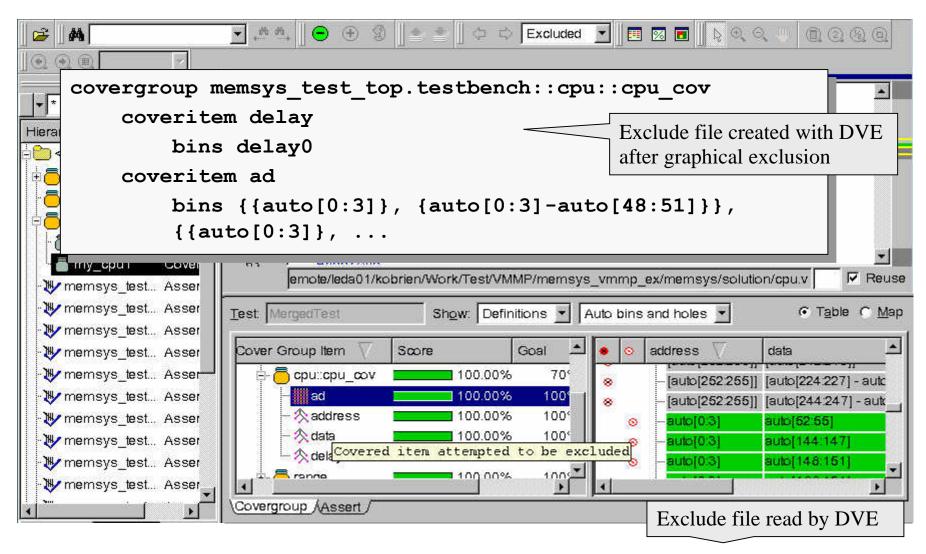
```
%> urg -parallel -help
```

## **Covergroup Exclusion**

## **Covergroup Exclusion**

- Part of common methodology excluding various types of coverage (code, assert, covergroup,...) as needed
  - Exclude file passed to URG post-simulation
    - Graphically create exclude file using DVE
    - User-created exclude file
  - Exclude don't-care objects
  - Exclude uncoverable objects
- Allow exclusion of covergroups, coverpoints, crosses, and bins
  - Instance and module level groups
  - User-defined and automatic bins and bin ranges
- URG prints summary of excluded data

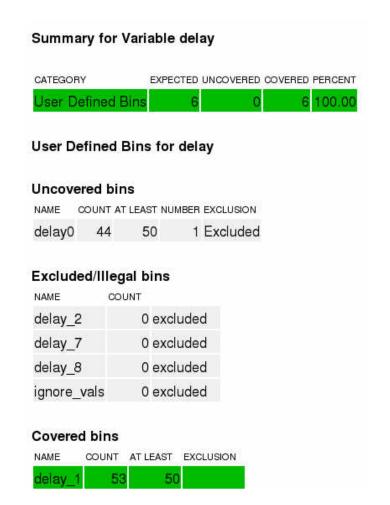
## **Exclusion through DVE**



% dve -cov -covdir simv.vdb -elfile test1.el

## **Exclusion through URG**

```
% urg -dir simv.vdb -elfile test.el
    reports excluded bins
 //sample test.el file
 covergroup test.delay cov
    coveritem delay
     bins delay0
     bins delay 2
     bins delay 7
     bins delay 8
     bins ignore vals
```



## **Test Grading**

## **Test Grading**

- For given set of tests with coverage results, provide a minimal set of tests that give the highest coverage score
  - Useful for building "dead-or-alive" (/ "sanity" / "approval" /) test set
    - Run before checking-in design/TB changes, to perform basic verification
  - First set of tests to run (highest priority) as a basic regression set
- Run URG with -grade option
  - % urg -grade [ quick | greedy | score ]
  - "Tests" page show tests in graded order
    - Scores show incremental contribution for each test
  - Remember: test score is combination of test & seed
    - High scoring test with seed X might get low score with seed Y
  - URG doesn't consider simulation time
    - Test with best score might be the longest
      - Refer to 'Simulation Time' column in URG report

### Test Grading: -grade options

#### greedy (default)

- Tests put in a best-first order based on test usefulness
- Shows cumulative, standalone, and incremental scores for each test
- Grading algorithm is quadratic in the number of tests: O(N²)
- Takes long time to complete

#### quick

- Tests put in a best-first order based on test usefulness
- Shows cumulative and incremental scores for each test
- Grading algorithm is linear in the number of tests: O(N)

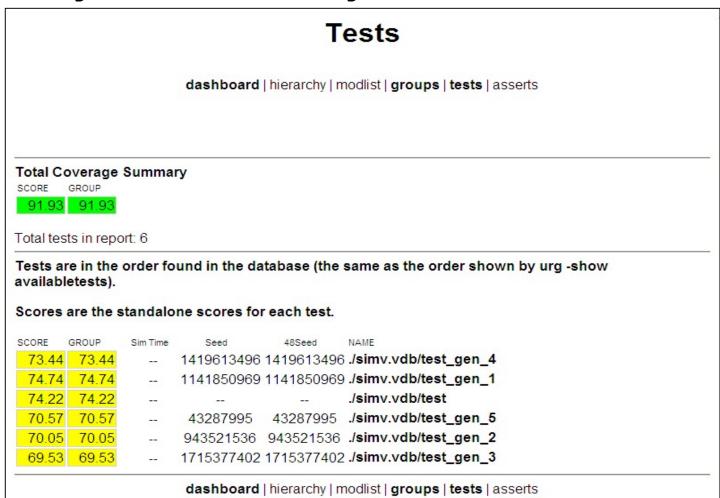
#### score

- Tests put in default order
- Shows standalone scores only
- Grading algorithm is linear in the number of tests: O(N)

### **Test Grading: Example**

Tests report example with per-test grading (score)

% urg -dir ./simv.vdb -grade score



## **Test Grading: Additional Options**

#### ■ goal [<*R*>]

- Stops grading when the cumulative score reaches R
- If not specified, the program will process all specified tests

#### timelimit <N>

- Stops grading after N minutes have passed
- Only those tests that are graded before the time limit is hit are included in the graded list

#### maxtests <N>

Stops after N tests have been graded

#### minincr <R>

 Stops grading when no remaining tests would add at least R percentage points to the total cumulative score. Only used for the greedy algorithm

#### reqtests <file>

 When used with greedy, specifies reading a list of test names from file for inclusion in the grading report. These tests are included at the top of the graded list, regardless of their scores or effectiveness for coverage