System Busses / Networks-on-Chip

EECE 579 - Advanced Topics in VLSI Design Spring 2009 Brad Quinton

Outline

Simple systems busses

- Overview
- AMBA APB
- Advantages/Limitations

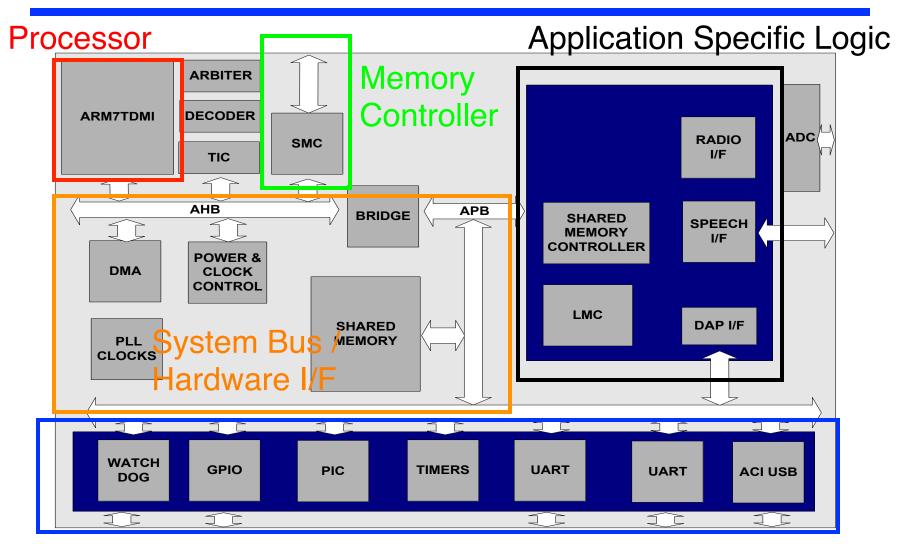
2. Complex systems busses

- Overview
- AMBA AHB
- Advantages/Limitations

3. Networks-on-Chip (NoC)

- Overview
- AMBA AXI
- Research Topics: Topology, Protocol, VLSI Implementation...
- Review: "A Generic Architecture for On-Chip Packet-Switched Interconnections"

Bluetooth "Platform" SoC



Simple System Busses

Simple System Busses

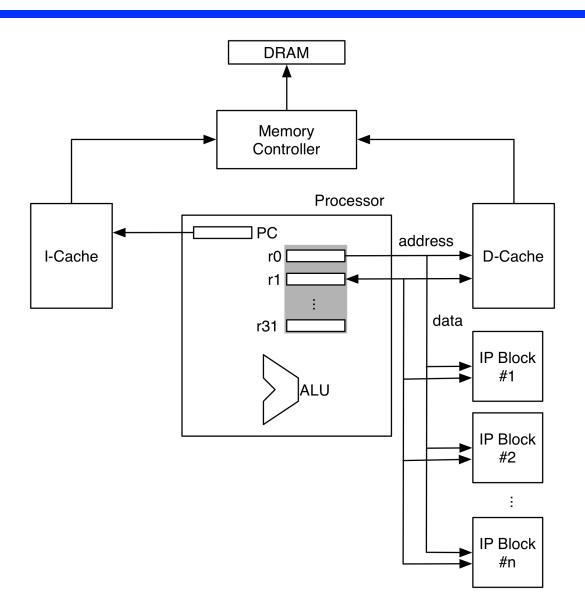
 The primary goal of a simple system bus is to allow software (running on a processor) to communicate with other hardware in the SoC

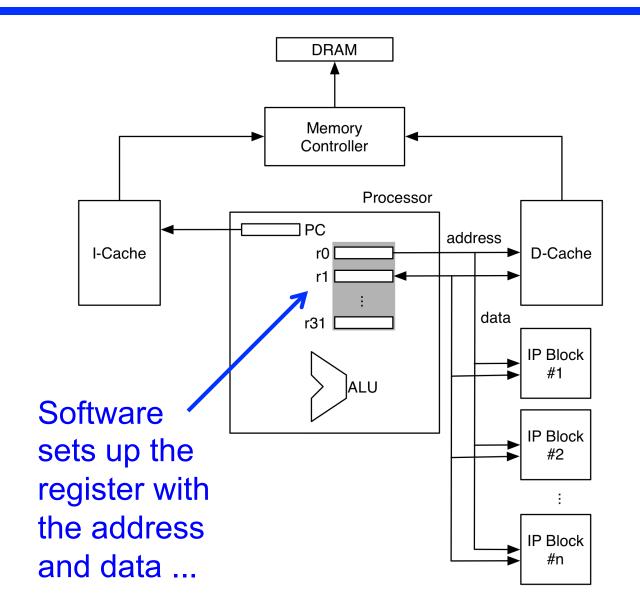
 There are many different implementation ... but they are all very similar

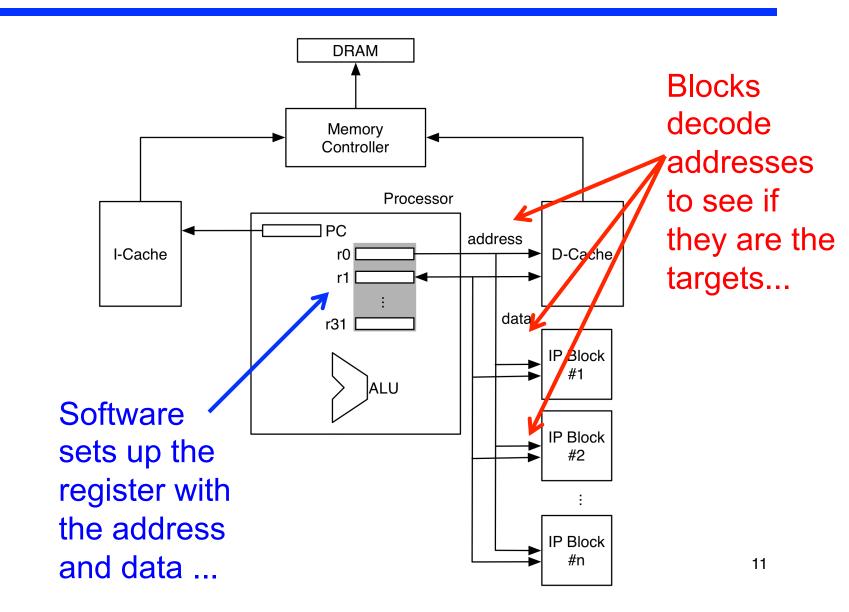
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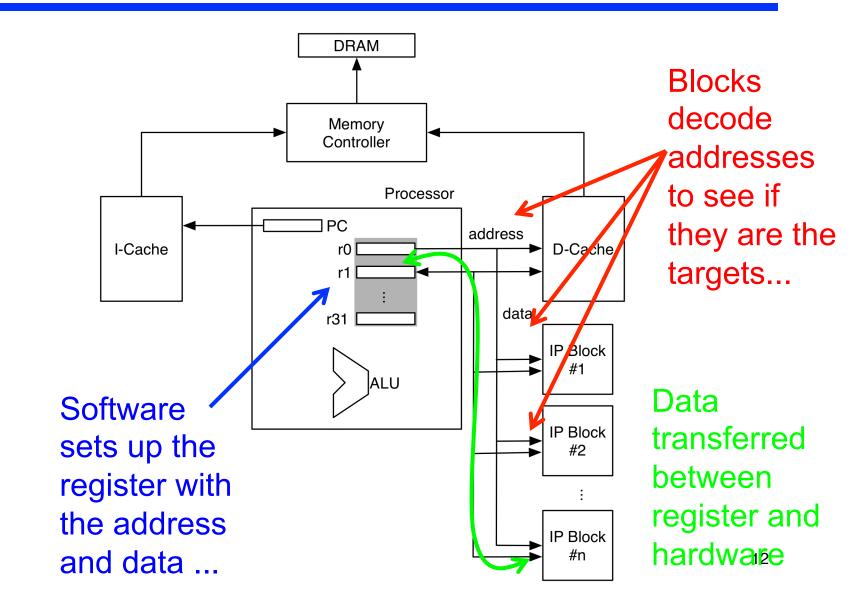
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 - Load Operation: Copies a word of data from a specific address to a *local register*
 - Store Operation: Copies a word of data from a local register to a specific address

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- The simple system bus is just a direct extension of this model









- AMBA: Advanced Microcontroller Bus Architecture
- Created by ARM to enable standardized interfaces to their embedded processors
- Actually three standards: APB, AHB, and AXI
- Very commonly used for commercial IP cores

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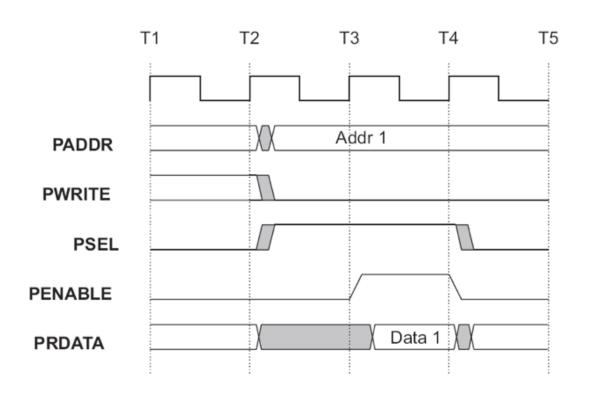
Simple Bus Complex Bus

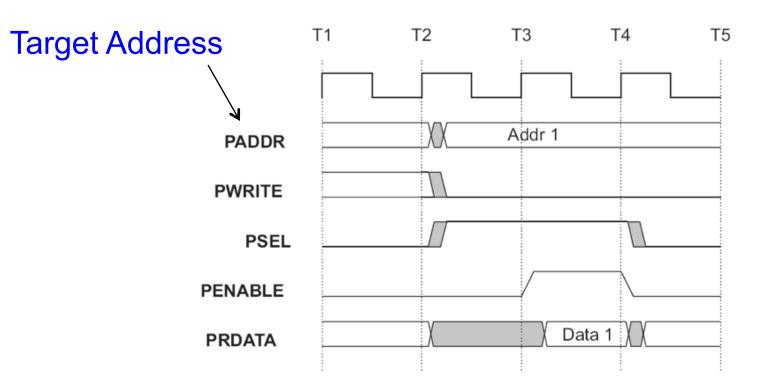
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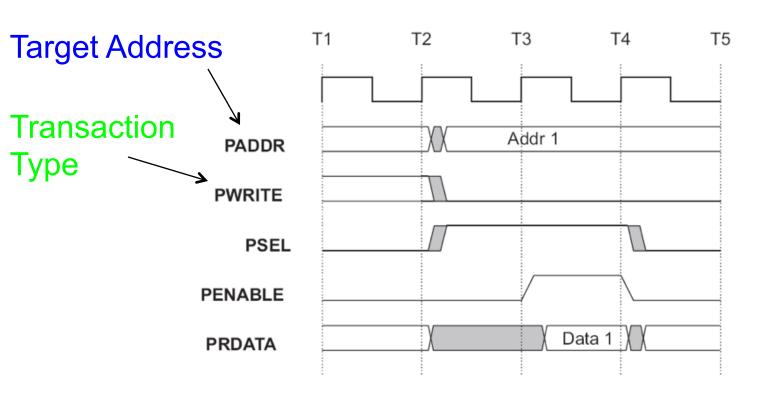
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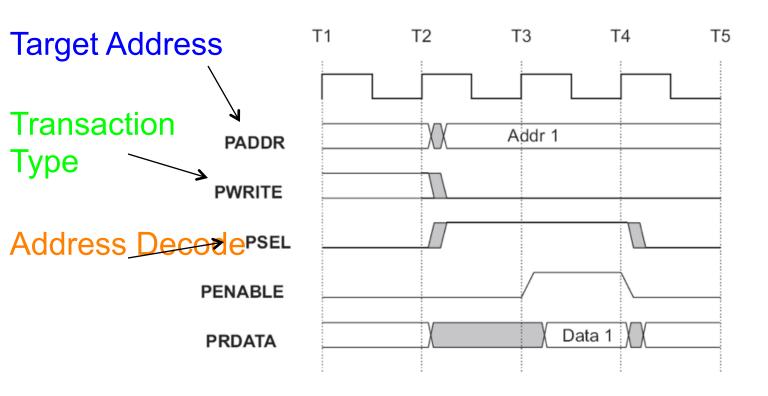
Simple Bus Complex Bus NoC

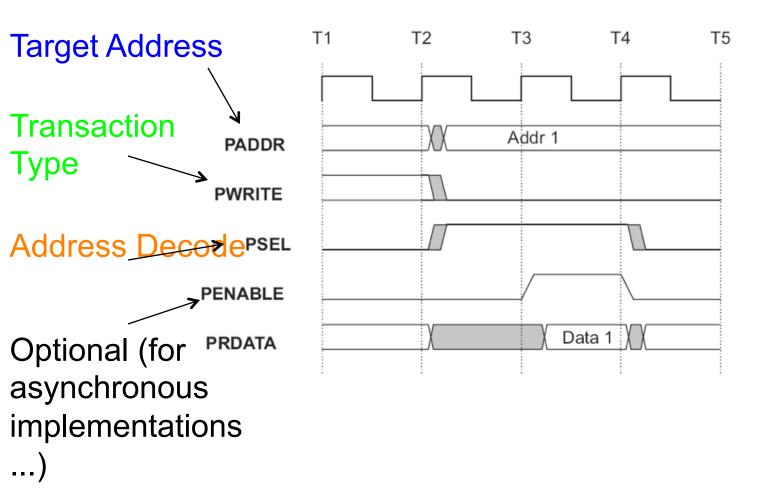
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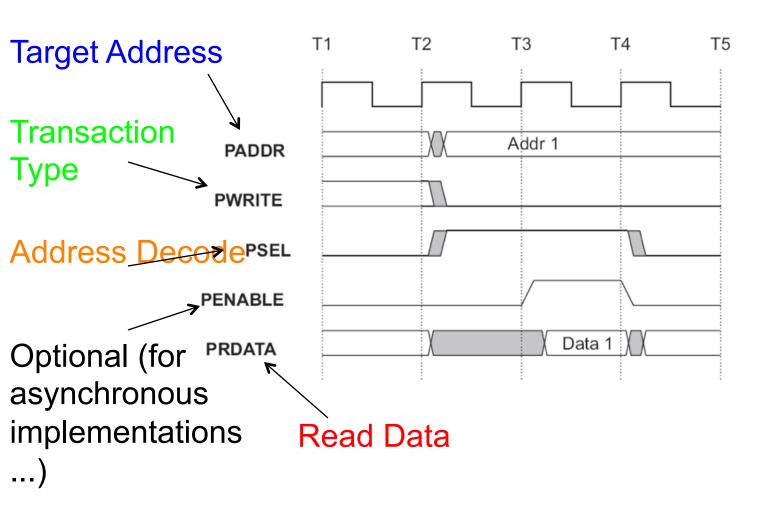




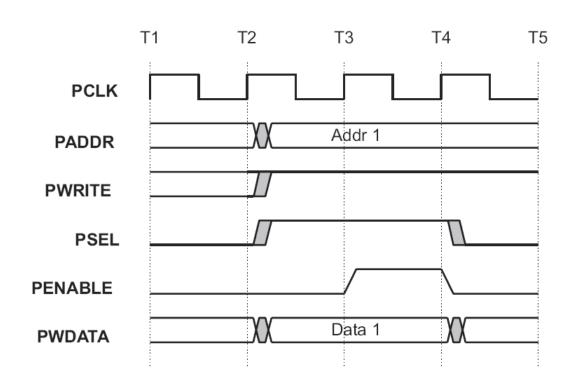






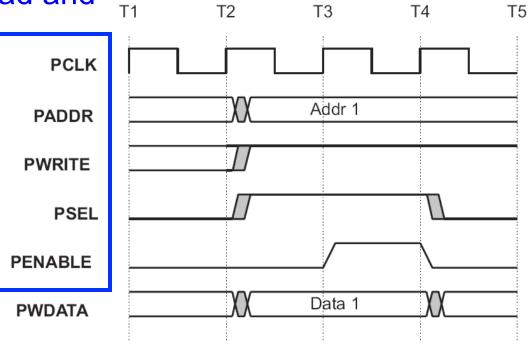


AMBA APB: Write Operation

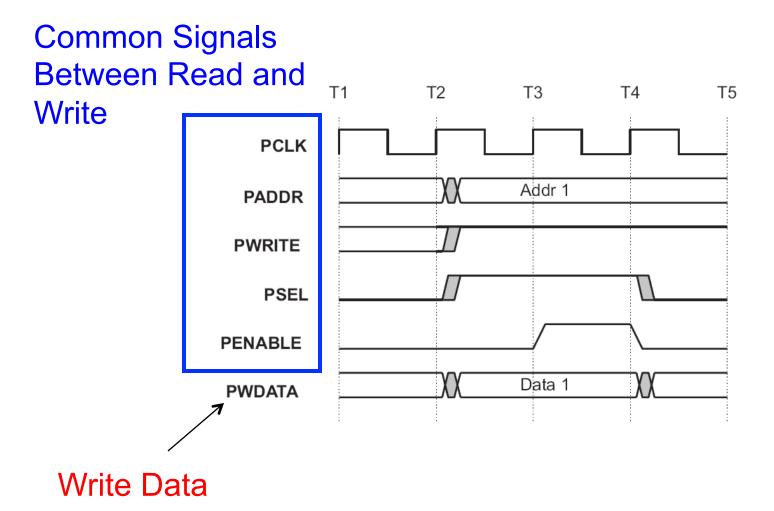


AMBA APB: Write Operation

Common Signals
Between Read and
Write

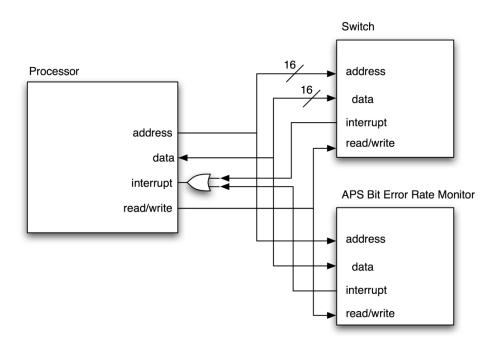


AMBA APB: Write Operation



Remember Our Case Study

Simple generic processor interface:



- data width: 16 bits

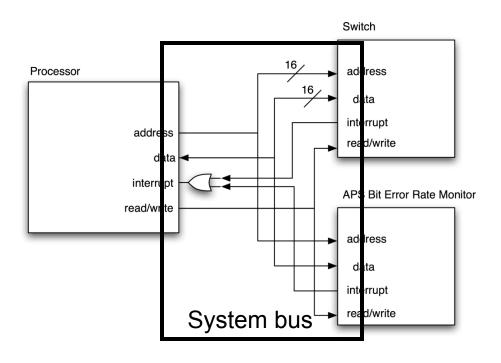
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Remember Our Case Study

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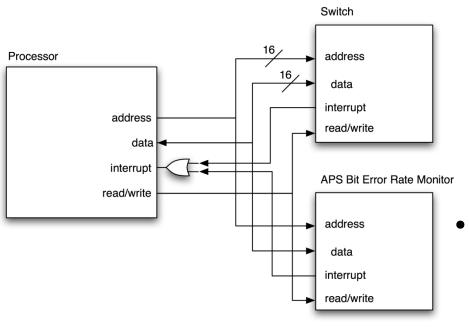
Simple Bus Advantages

- Simple to implement
- Easy to understand
- Simple programming model
- Easy to add new hardware blocks
- Minimal hardware requirements (most of the signals are shared)

Simple Bus Limitations

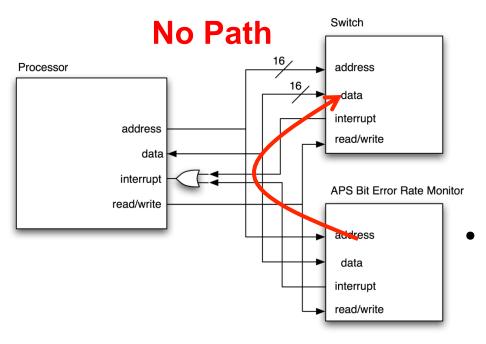
- Single Master limits parallelism
- Scalability performance suffers as bus is loaded...
- Single outstanding request poor throughput and multi-threading performance bottleneck

Case Study: Single Master



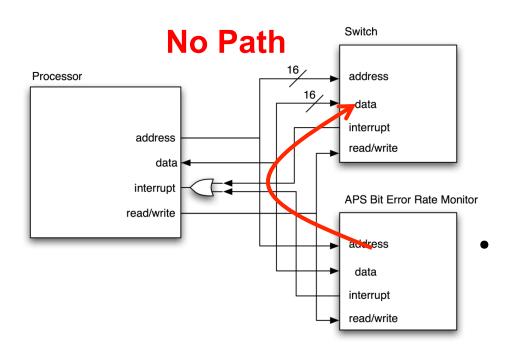
- Imagine a new partition:
 - APS Bit Error
 Monitor
 communicates
 directly with Switch
 - Simple bus doesn't work...

Case Study: Single Master



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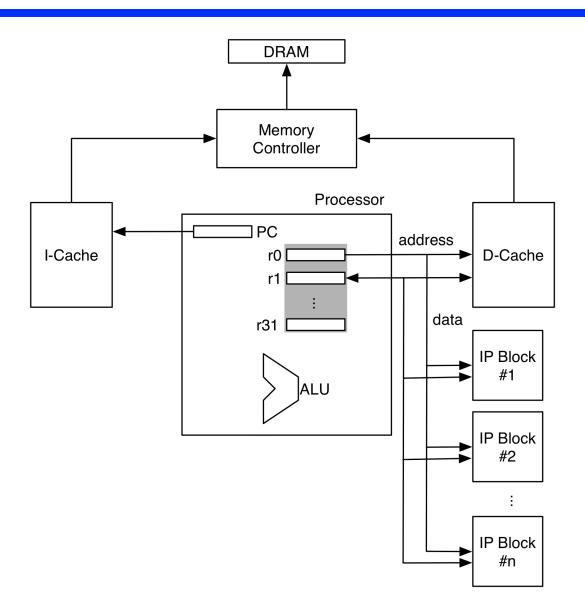
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This can make software the bottleneck in the system....

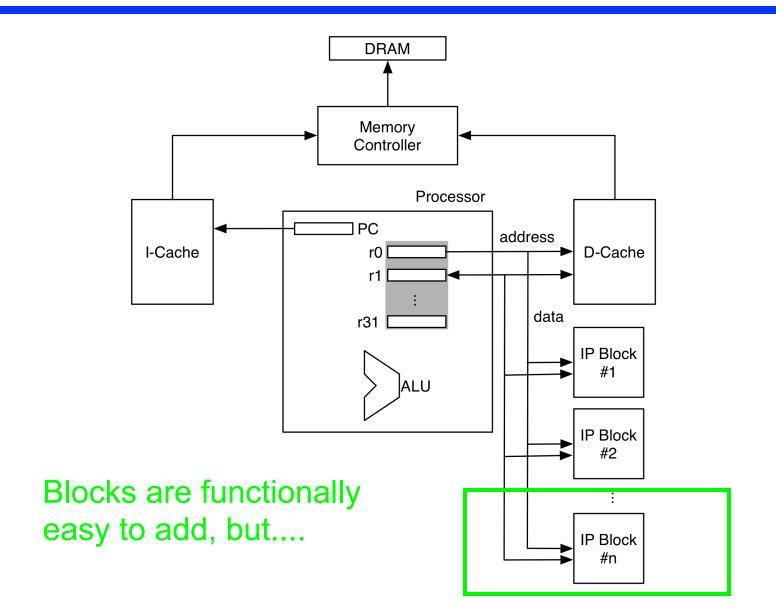
Single Master Summary

- A bus that is limited to a single master:
 - Makes inter-block communication inefficient
 - Limits parallelism between hardware and software
 - Increases reliance on interrupts
 - Creates software performance bottlenecks
 - Is not compatible with multiple processors

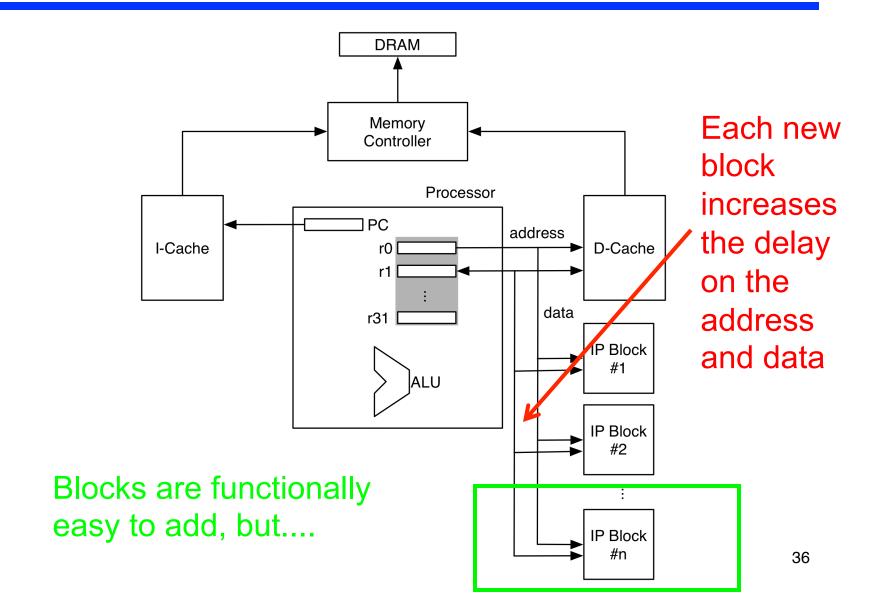
Scalability



Scalability



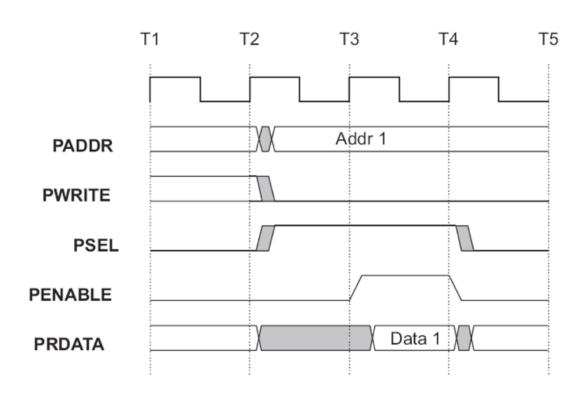
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Scalability Summary

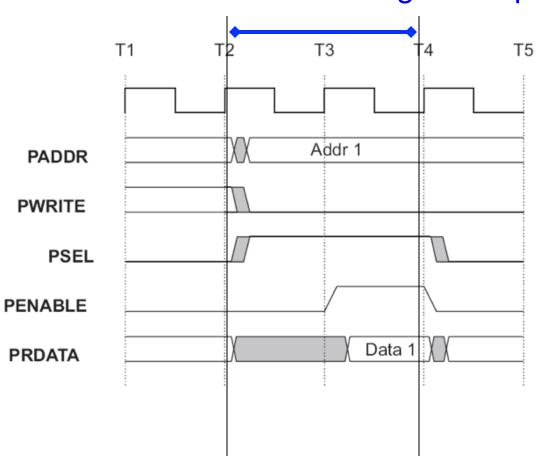
- Simple busses are not scaleable because:
 - The address and data "fan-out" to each target
 - Adding a new block increases the load on the bus
 - Increased fanout + greater load = reduce performance

Single Outstanding Request



Single Outstanding Request

Processor is stalled waiting for response...



Single Outstanding Request

Processor is stalled waiting for response...



Single Outstanding Request Summary

- Busses limited to a single outstanding request:
 - Reduce software performance since the software must "stall" on the first transaction
 - Are not able to achieve full bus throughput since the data bus is idle during the address phase

Complex System Busses

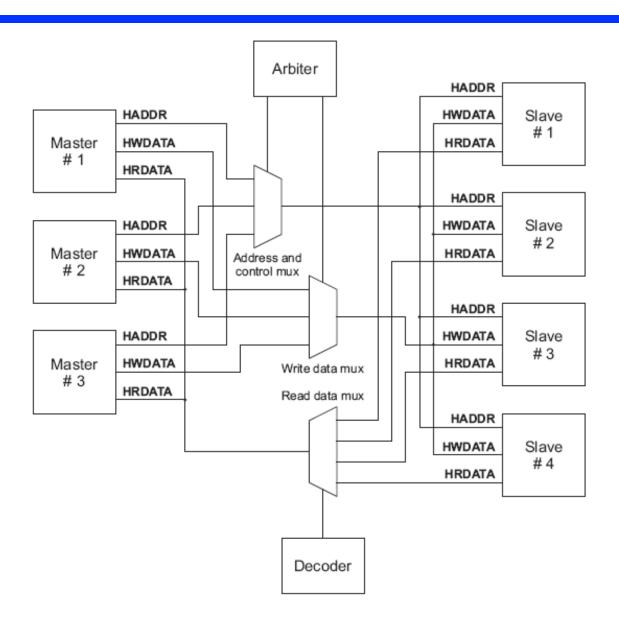
Complex Systems Busses

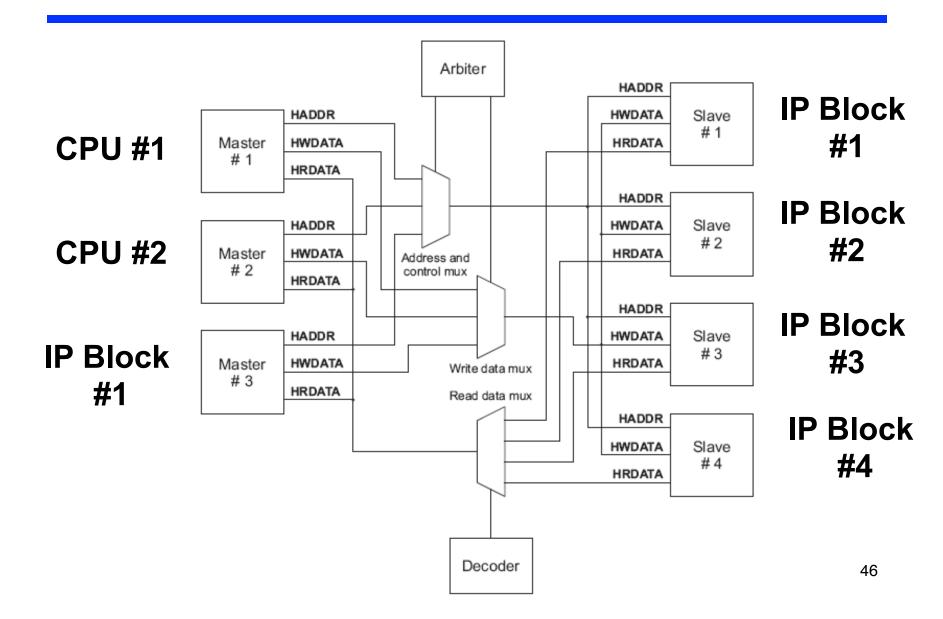
- The complex system bus is attempts to address some of the issues with the simple bus:
 - Multi-master
 - Pipelined transactions

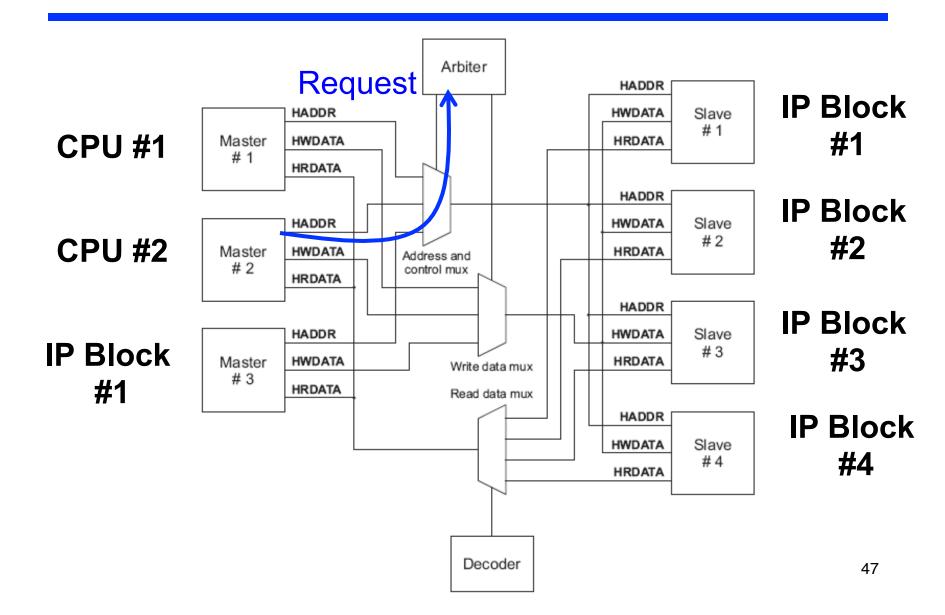
There are many different ways to go about this...

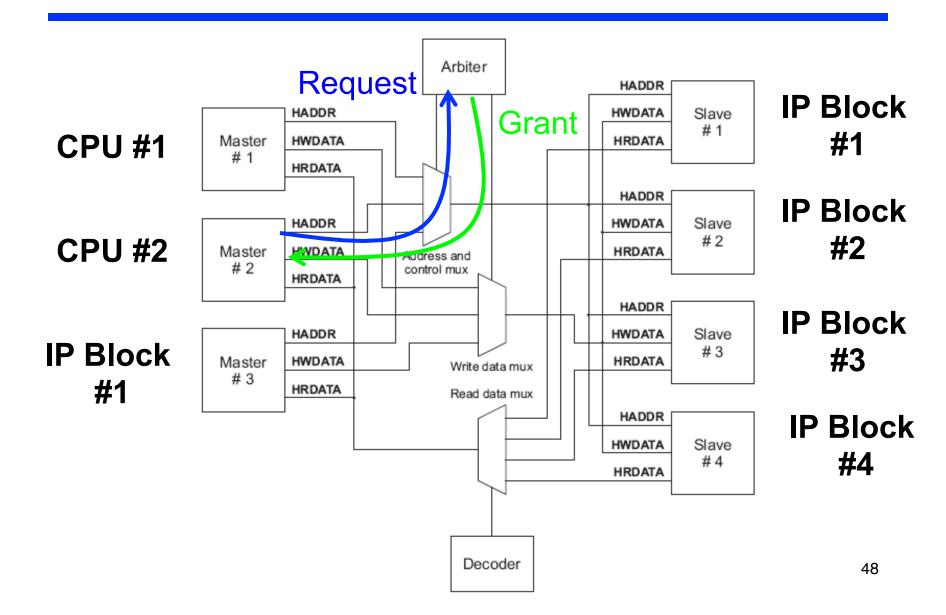
AMBA AHB

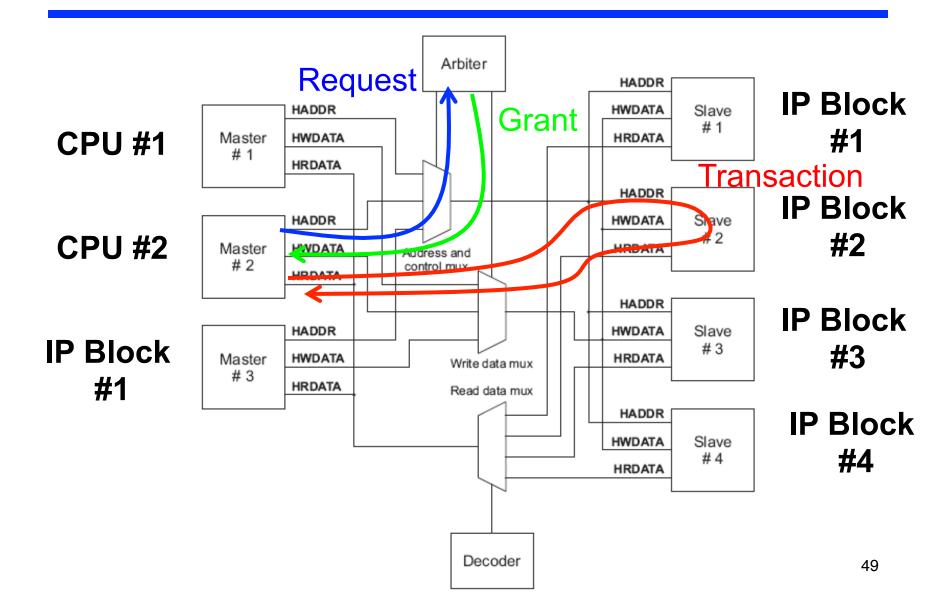
- AHB addresses many of the limitations of APB:
 - multi-master
 - multiple outstanding transactions (sort of...)
 - back-to-back transactions
- Unfortunately, this adds significant complexity





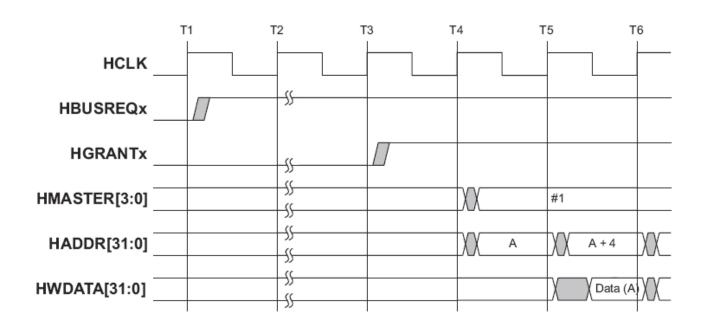


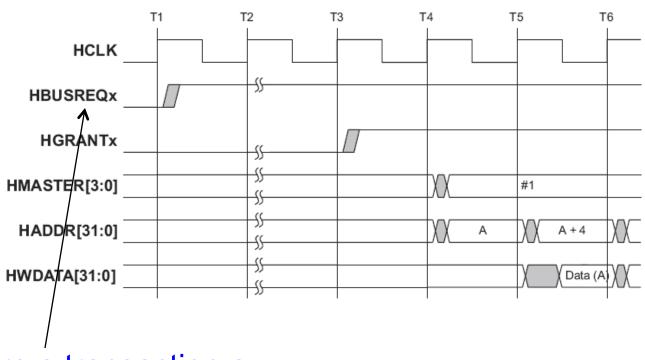




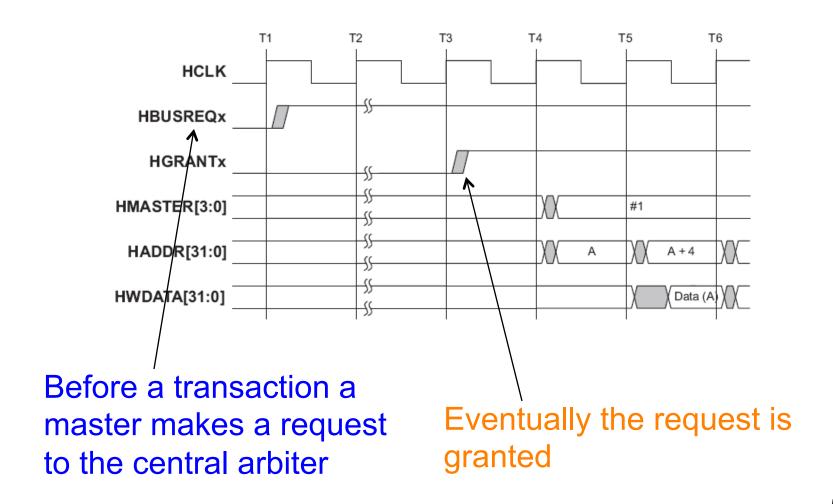
Bus Arbitration

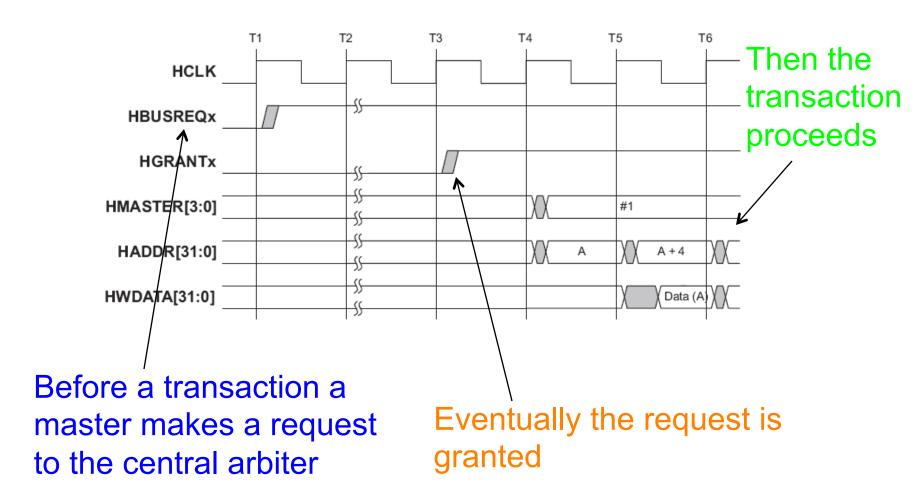
- When multiple masters share a bus there must be some central resource to manage the bus: an arbiter
- Once there is competition for the bus, it is possible that it is not ready when you need it: backpressure
- Backpressure adds complexity and hurt performance

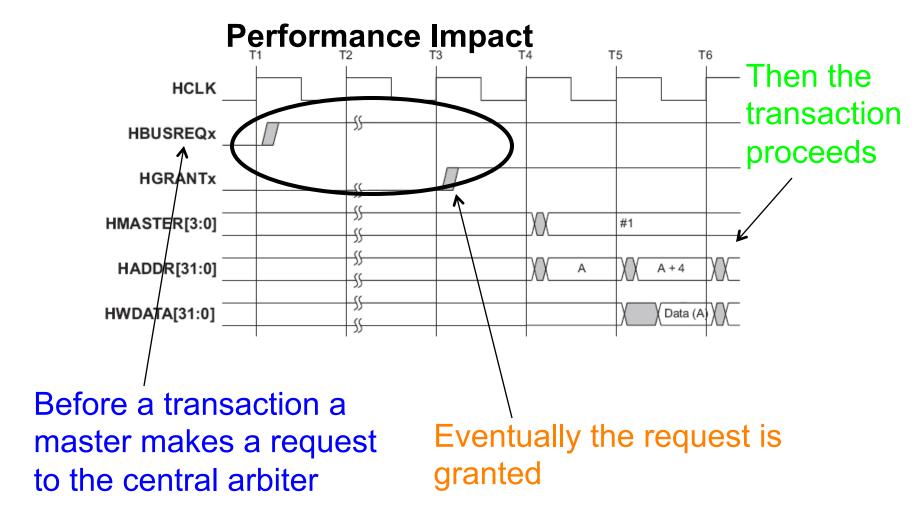




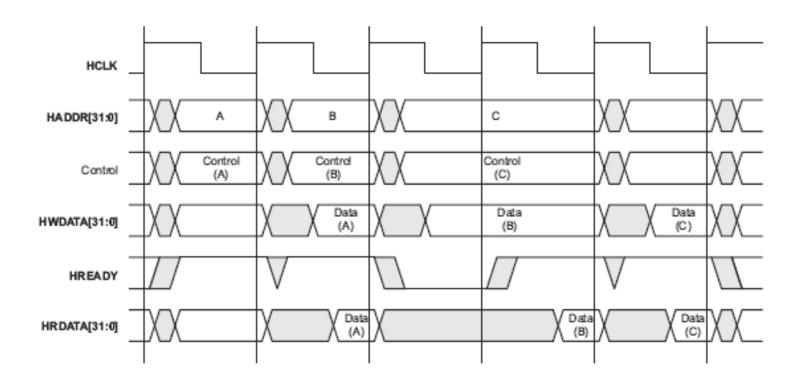
Before a transaction a master makes a request to the central arbiter

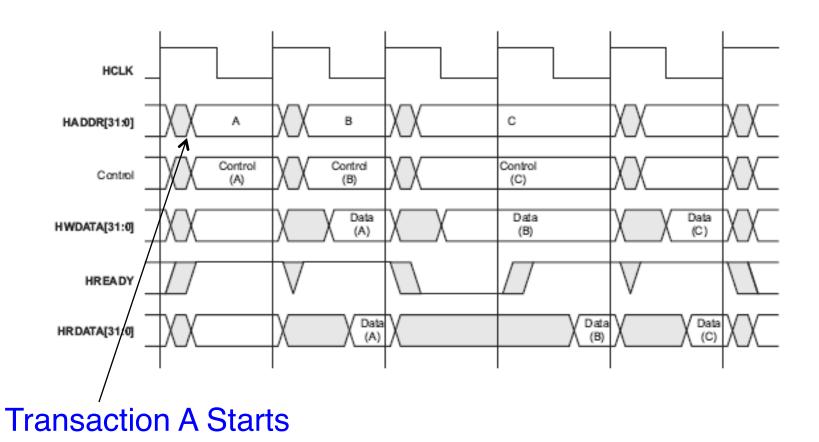


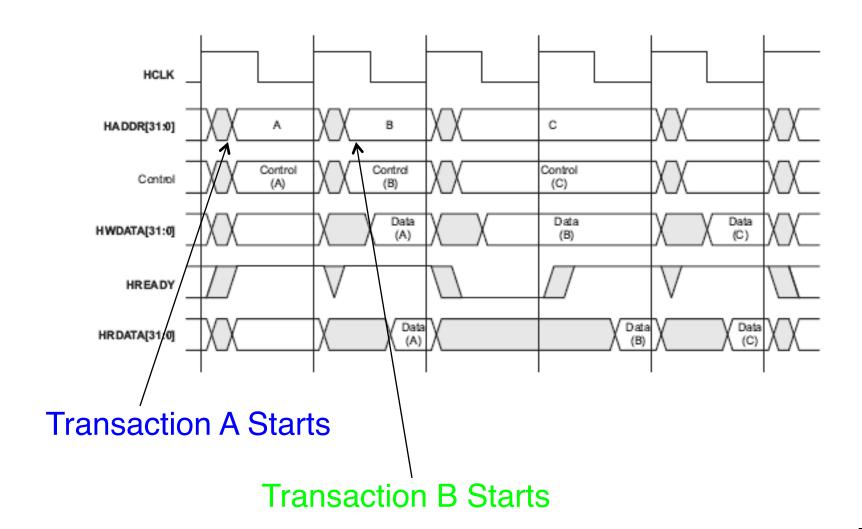


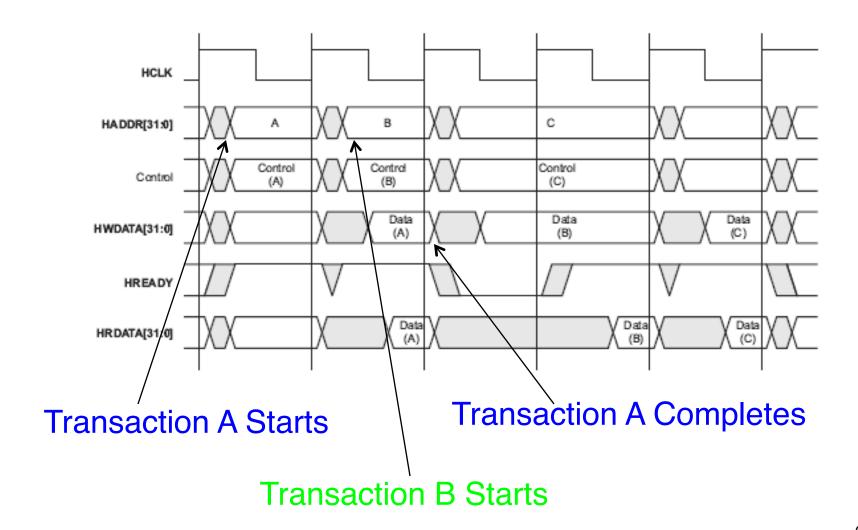


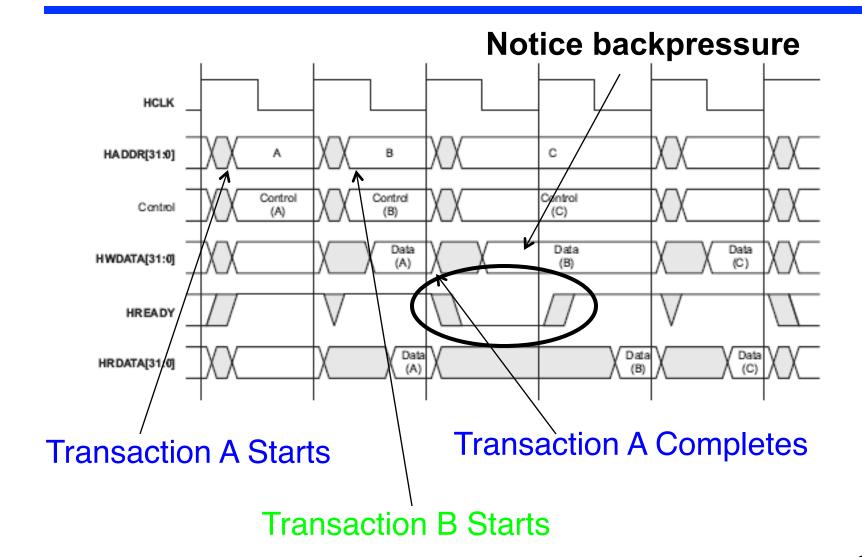
- To help improve bus efficiency the transactions on the bus can be pipelined
- This is really a simple implementation of multiple outstanding transactions
- The address for one transaction can be presented before the data from the previous transaction has been completed











Advantages

- Relatively easy to add new blocks
- Still has the familiar bus structure
- Low hardware cost
- Bus arbitration "solves" many ordering problems

Disadvantages

- Busses that require arbitration:
 - must route signals to the arbitration logic and back
 - must find a "fair" way to share the bus
 - slaves are not always available => backpressure
 - difficult to provide performance guarantees...
- Still potentially a bandwidth bottleneck
- Still doesn't scale well when blocks are added
- Multiple outstanding transactions not handled well - no ordering information

Networks-on-Chip (NoCs)

Networks-on-Chip

- It is clear that even with significant design effort the bus-style interconnect is not going to sufficient for large SoCs:
 - the physical implementation does not scale: bus fanout, loading, arbitration depth all reduce operating frequency
 - the available bandwidth does not scale: the single bus must be shared by all masters and slaves

Networks-on-Chip

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- Lets start again: Leverage research from data networking

What do we want?

- The SoCs of the future will:
 - have 100s of hardware blocks,
 - have billions of transistors,
 - have multiple processors,
 - have large wire-to-gate delay ratios,
 - handle large amounts of high-speed data,
 - need to support "plug-and-play" IP blocks
- Our NoC needs to be ready for these SoCs...

The Ideal Network

- What would the ideal network look like?:
 - Low area overhead
 - Simple implementation
 - High-speed operation
 - Low-latency
 - High-bandwidth
 - Operate at a constant frequency even with additional blocks
 - Increase available bandwidth as blocks are added
 - Provide performance guarantees
 - Have a "universal" interface

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These are competing requirements: Design a network that is the "best" fit.

What do we need to decide?

- Network Interface
- Network Protocol / Transaction Format
- Network Topology
- VLSI Implementation

Network Interface

- We want our network to be "plug-and-play" so industry standardization is key
- However the standard be universal enough to address many different needs

AMBA AXI is an example of an attempt at this

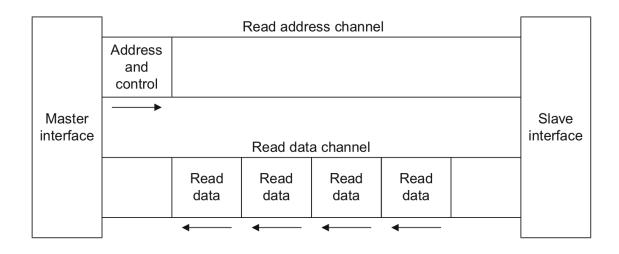
AMBA AXI

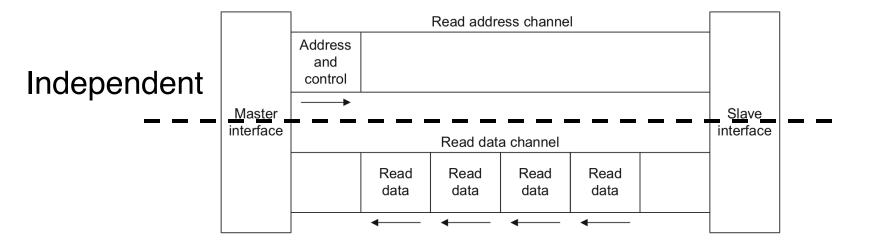
- ARM added the AXI specification to Version 3.0 of the AMBA standard
- New approach: define the interface and leave the interconnect up to the designers
- Good plan since a specific bus implementation is no longer required
- It is possible to use AXI to build many different NoCs

AMBA AXI

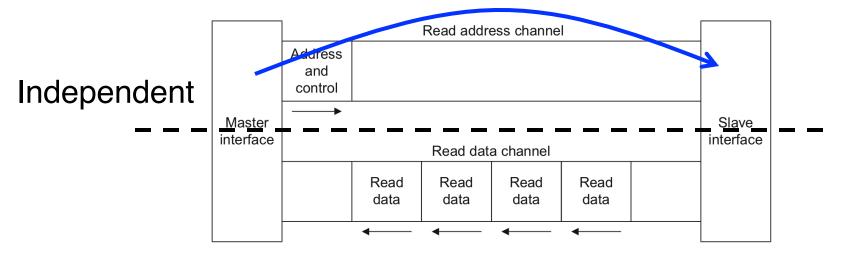
- Interface divided into 5 channels:
 - Write Address
 - Write Data
 - Write Response
 - Read Address
 - Read Data/Response

 Each channel is independent and use twoway flow control

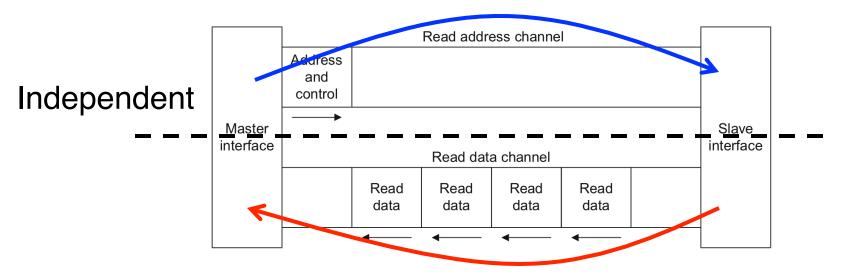




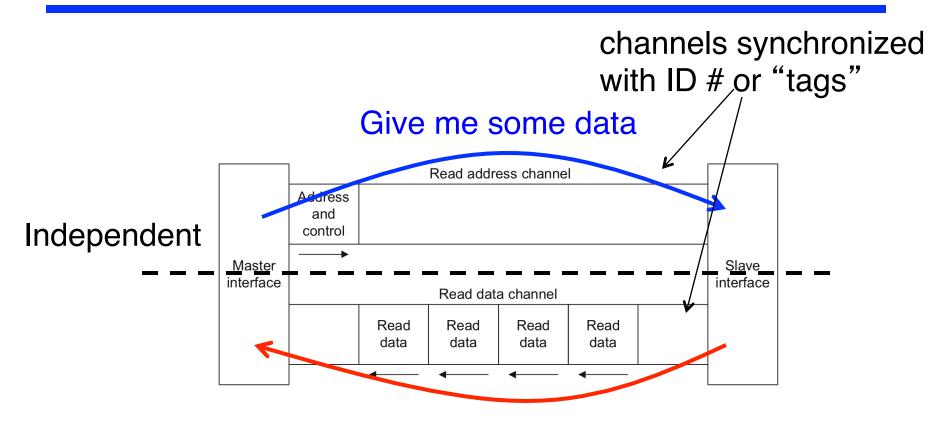
Give me some data



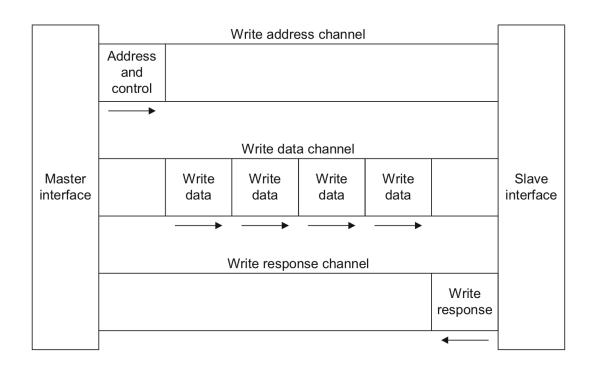
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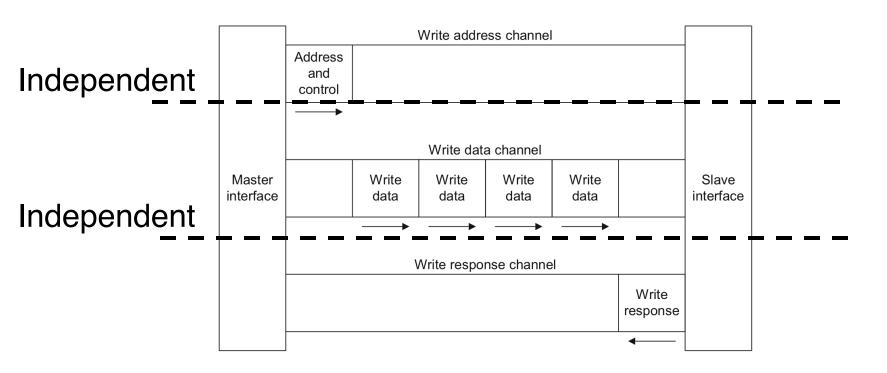


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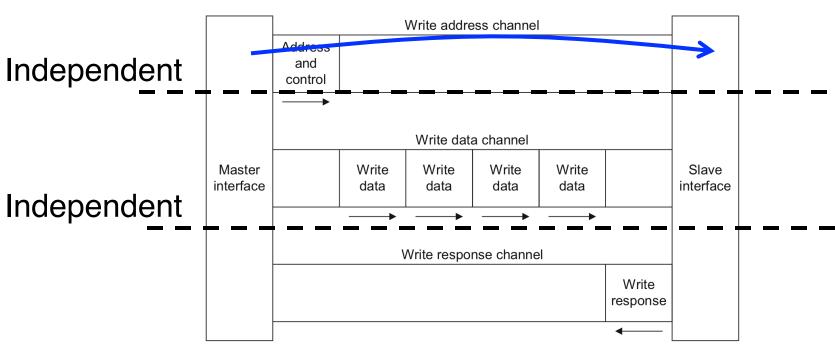


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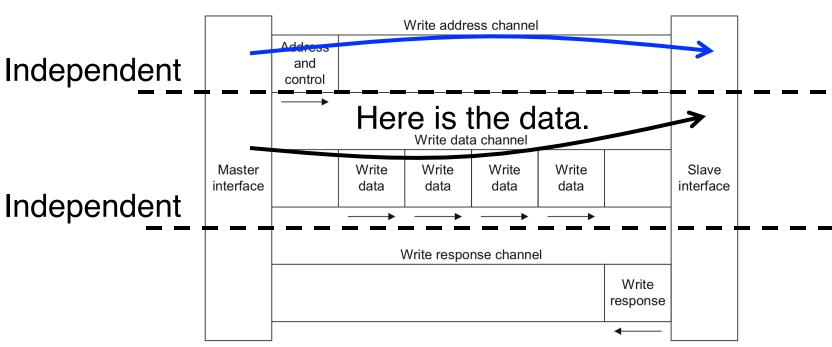




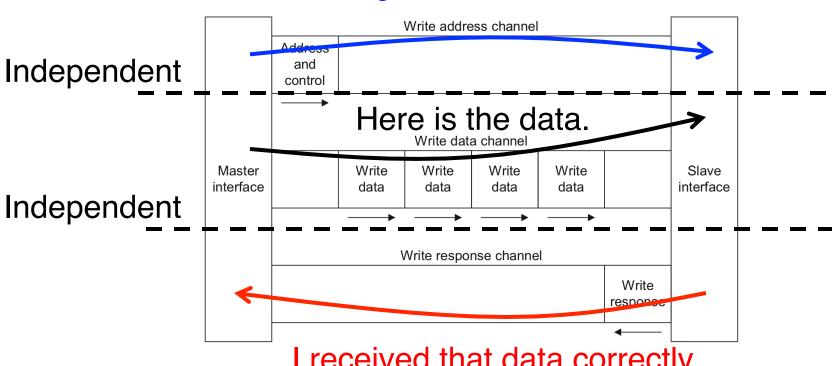
I'm sending data. Please store it.



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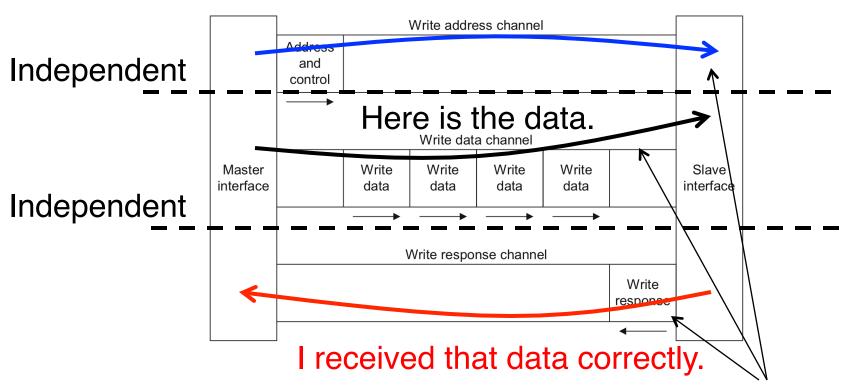


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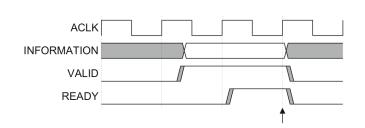
I received that data correctly.

I'm sending data. Please store it.

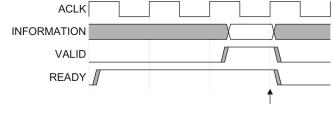


channels synchronized with ID # or "tags" 84

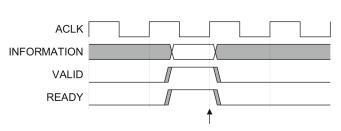
 Information moves only when:



- Source is Valid, and
- Destination is Ready

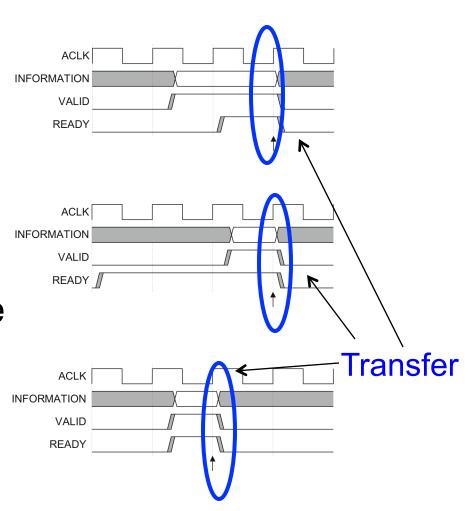


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Very flexible

- Information moves only when:
 - Source is Valid, and
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- Very flexible

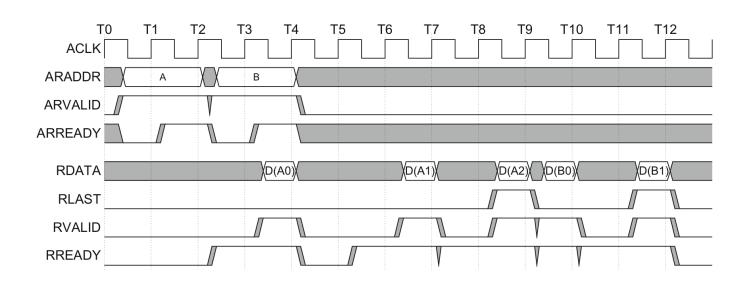


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 DEADLOCK

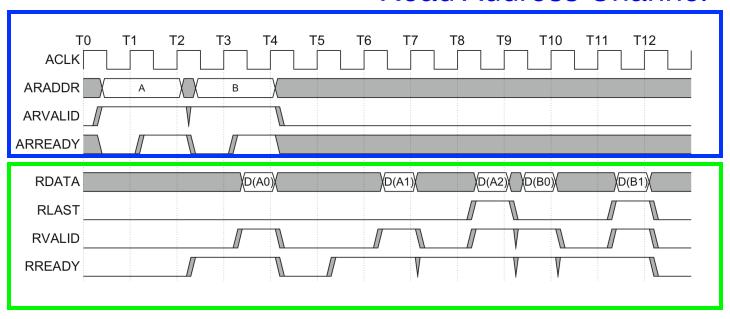
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 DEADLOCK
- On a write transaction the master must not wait for AWREADY before asserting WVALID

AMBA AXI Read



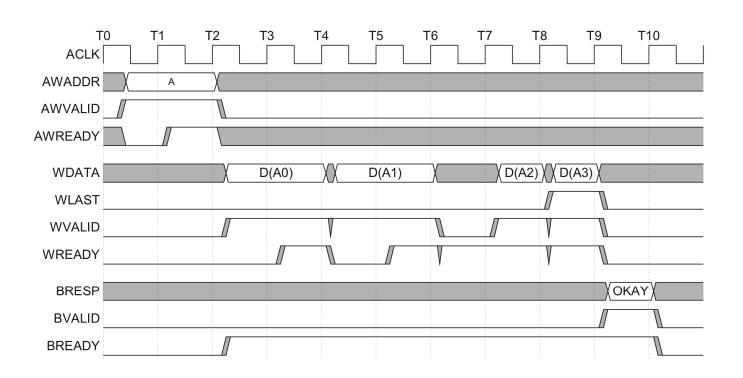
AMBA AXI Read

Read Address Channel

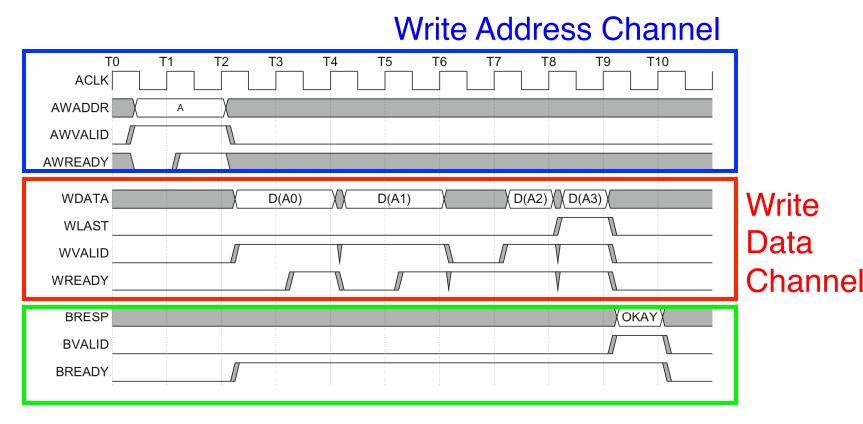


Read Data Channel

AMBA AXI Write



AMBA AXI Write



Write Response Channel

A True Interface Specification

 Because of the channel independence and the two-way flow-control the interface does not dictate the network protocol, transaction format, network topology, or VLSI implementation

For example:

- if you want to build a packet-based network, you can "backpressure" the data channel while you build the packet header from the address channel information,
- you can use store-and-forward, or cut-through,
- **etc.** 94

Network Protocol / Transaction Format

- There are many choice for network protocols and transactions formats:
 - circuit-switched : plan and provision a connection before communication starts
 - packet-switched : issues packets which compete for network resources
 - hybrids: schedule connectivity (dynamic or static)

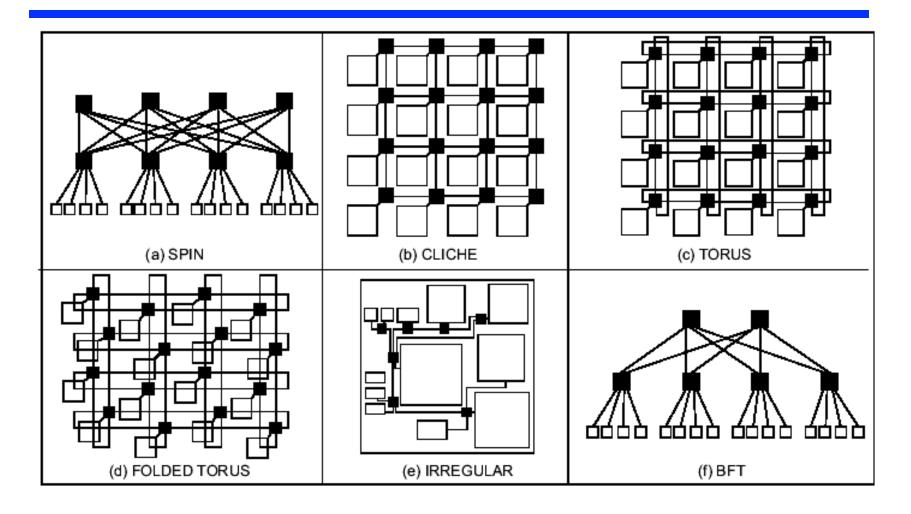
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 - hybrids: schedule connectivity (dynamic or static)
- There is still lots of research here....

Network Topology

- How should your network elements be interconnected:
 - Fully Connected (N²): high area cost, high performance
 - Mesh: low area cost, potential poor performance
 - Hypercube: medium area, traffic dependent performance
 - Fat-tree: medium area, traffic dependent performance
 - Torus: medium area, traffic dependent performance

Network Topology



There is lots of research here....

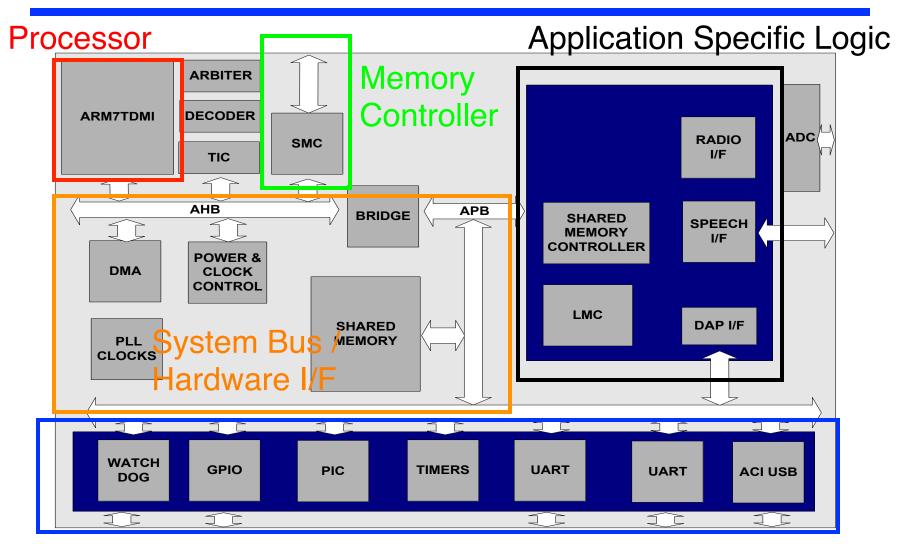
Network Topology - Caveat

- There has been a lot of research on topologies for NoCs, however it is important to realize that the performance of a topology is highly dependent on the traffic patterns!
- Traffic patterns in an SoC that you are designing yourself are NOT random, therefore much of the topology research is not applicable to most SoCs!

VLSI Implementation

- Once you have a topology there is still the mater of implementing it on your SoC
- There are many considerations:
 - Clocking: Synchronous, Asynchronous
 - Buffer Insertion: Trade-off power, area, performance
 - Register Insertion / Pipelining: Trade-off clock frequency, area, and latency
 - Packet Buffers: Trade-off area, latency and throughput
- Again, lots of research on-going...

Bluetooth "Platform" SoC



Research Paper

Lets look at:

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Guerrier, P.; Greiner, A., "A generic architecture for on-chip packet-switched interconnections," Design, Automation and Test in Europe Conference and Exhibition 2000.

Proceedings, vol., no., pp.250-256, 2000
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