Inputs

Computed Values

$$E_A = \frac{Q}{\pi \varepsilon d^2 \left(\frac{h}{d} - \frac{z}{d}\right)^2} \left[\frac{\left(\frac{h}{d} - \frac{z}{d}\right)}{\left\{1 + \left(\frac{z}{d}\right)^2\right\}^{0.5}} + \sinh^{-1}\left(\frac{z}{d}\right) - \sinh^{-1}\left(\frac{h}{d}\right)\right]$$

Uph head protection

Level

Cloud Size Height

First Interroll action

Firs

Table 2: De-rating angles applied in the CVM for tall structures ($H \ge 60 \text{ m}$).

LPL	Interception Efficiency	De-rating Angle		
1	99	26°		
П	97	23°		
III	91	20°		
IV	84	15°		

Table 1: Summary of the key parameters and probabilities associated with the lightning protection levels used to design a lightning protection system (LPS) for ordinary structures.

LPL	Leader charge Q (C)	Peak current I _P (kA)	Striking distance (m)	% strikes > lp (Interception Efficiency)
1	0.16	2.9	20	99
11	0.38	5.4	30	97
III	0.93	10.1	45	91
IV	1.80	15.7	60	84

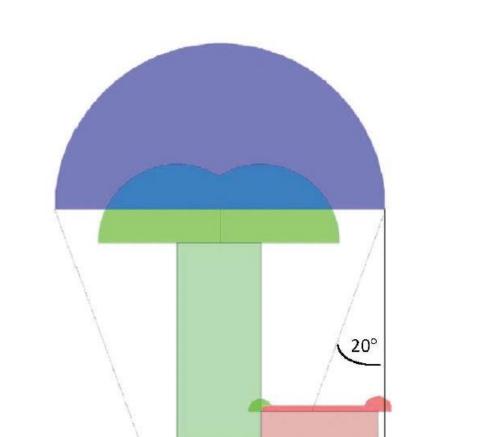


Figure 5: Application of collection volume de-rating to tall structures (example for LPL III). Note that, in this particular example, the lower structure would not have been deemed to be protected anyhow, since the collection volume of the air termination on top of the main building does not overlap the small collection volume of the corners of the lower structure.

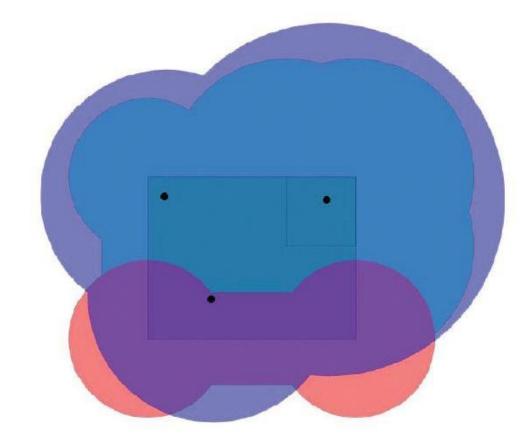
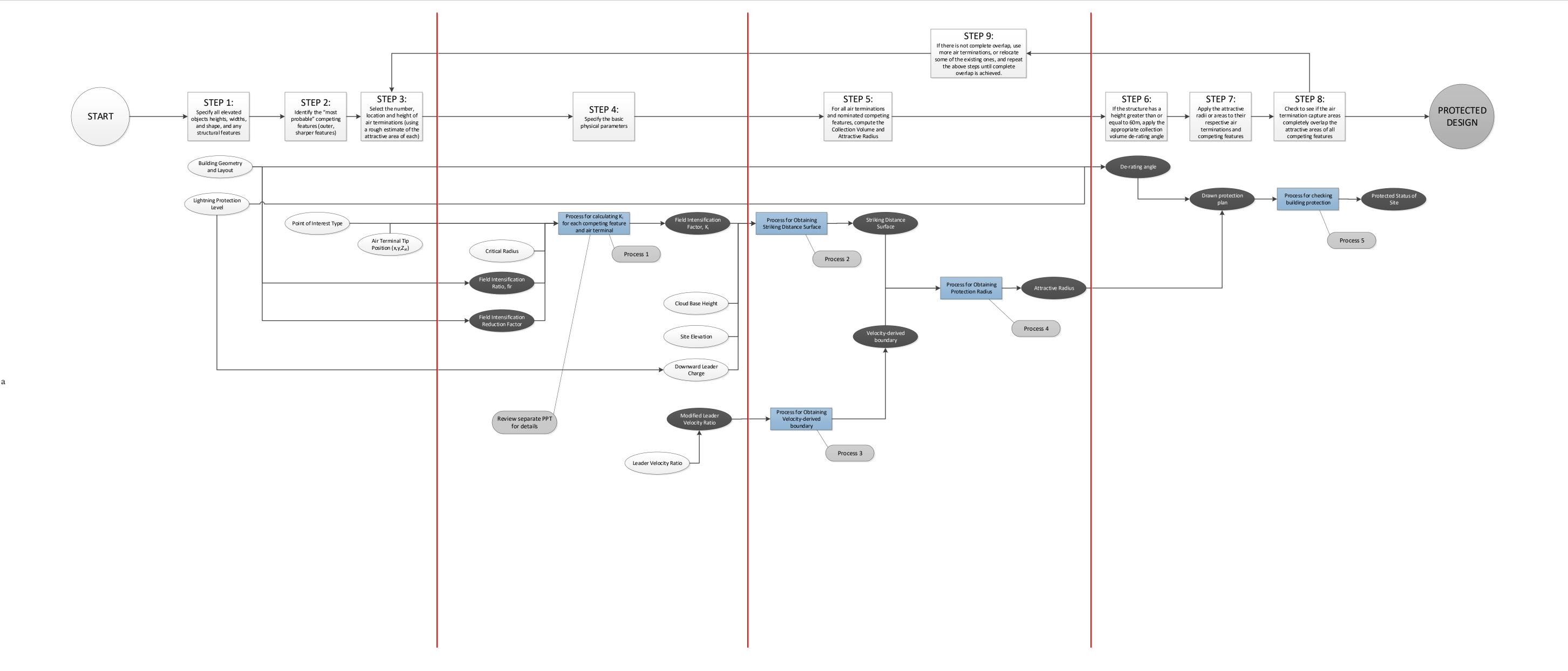
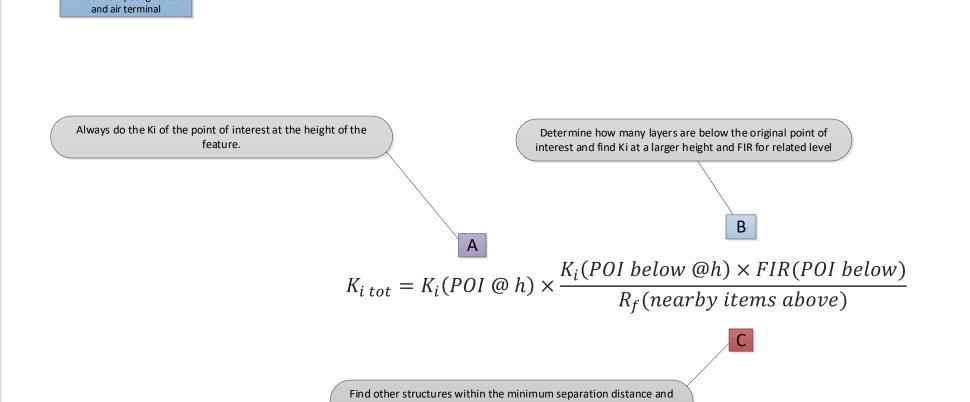
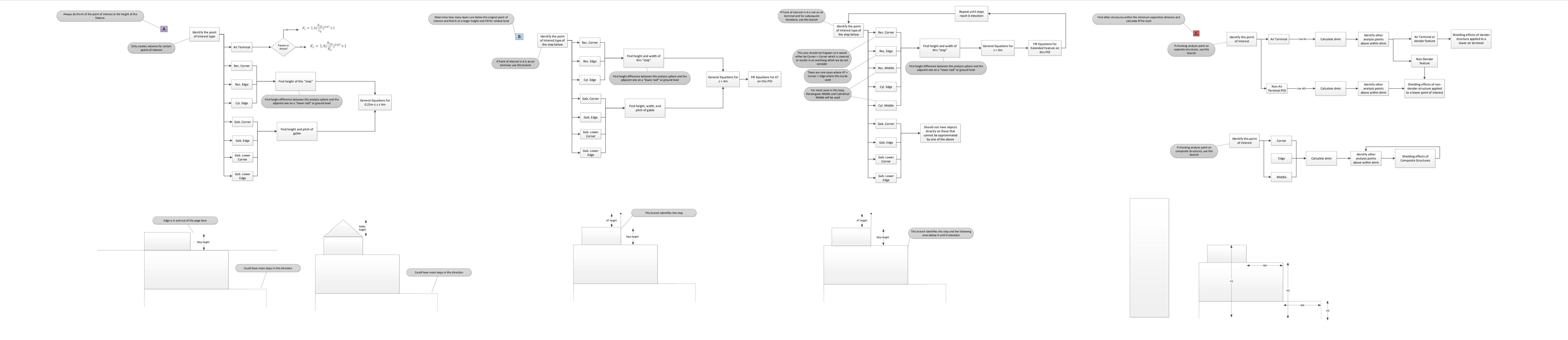


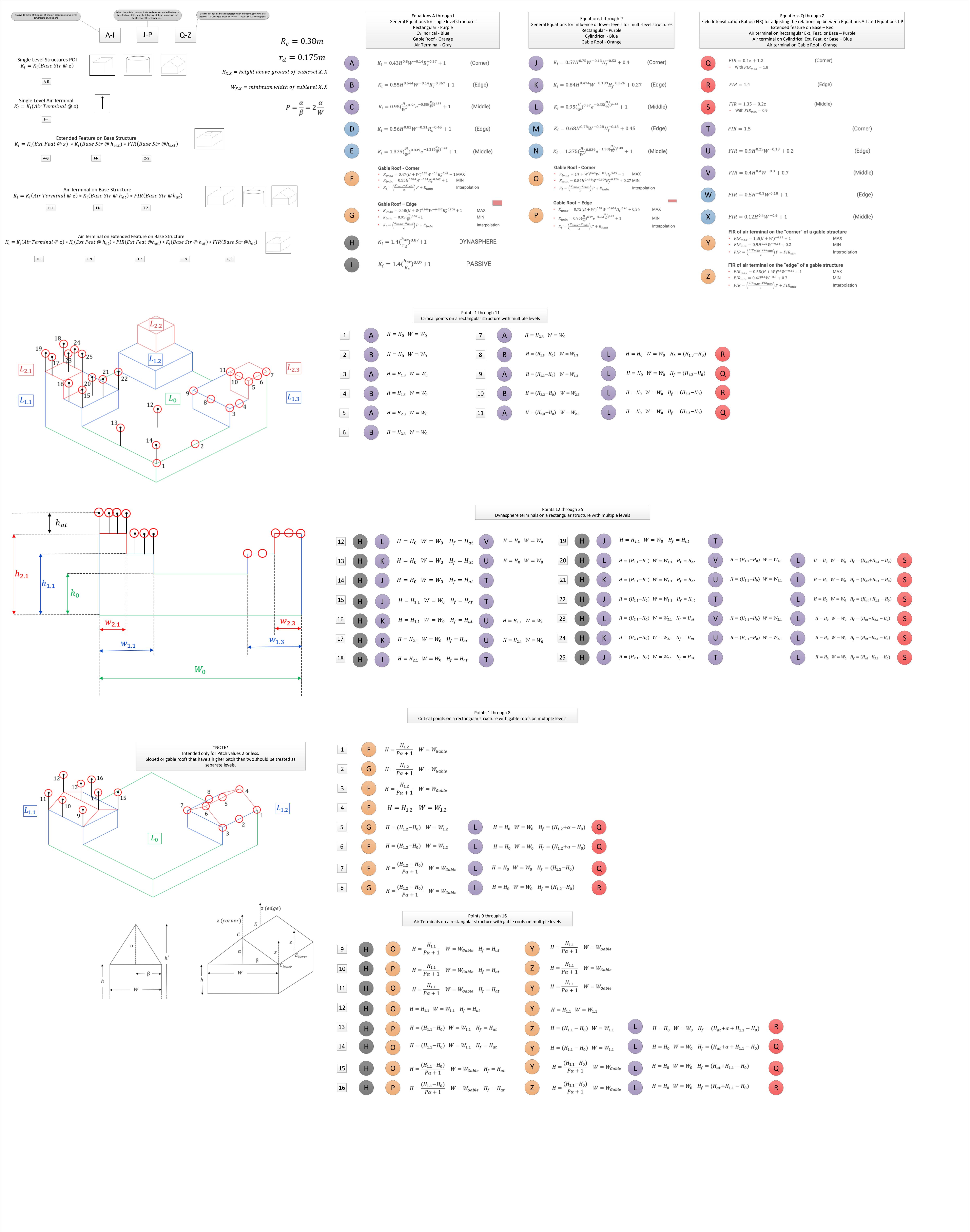
Figure 6: 2D plan view display of the three air termination attractive areas (light blue) and the competing features attractive areas (darker blue), including those not shielded or protected by the air terminations (red areas).

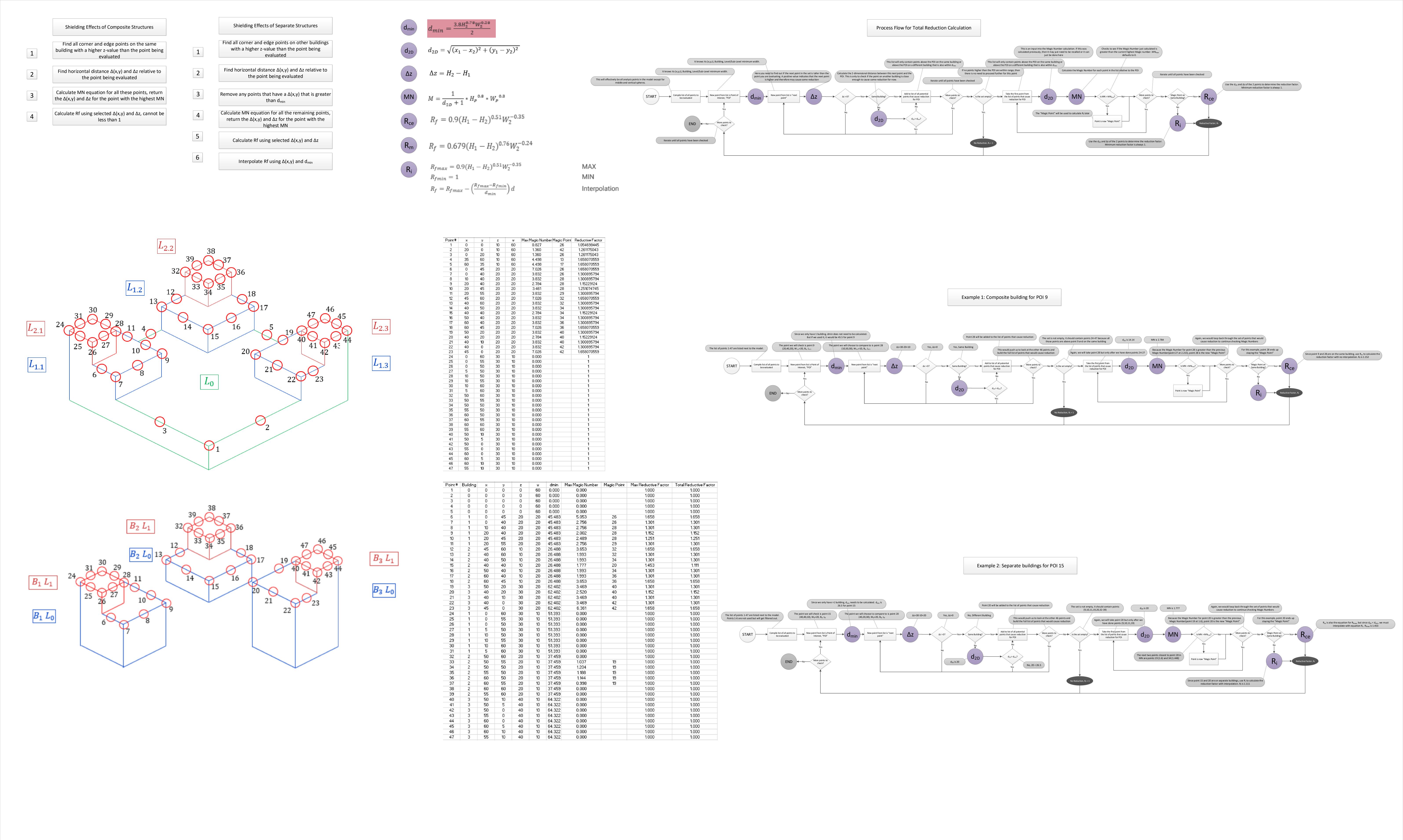




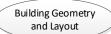
calculate Rf for each



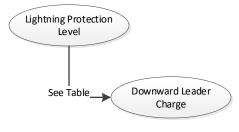




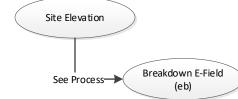
Process for Obtaining Striking Distance Surface



Air Terminal Tip Position (x,y,Z_{at})





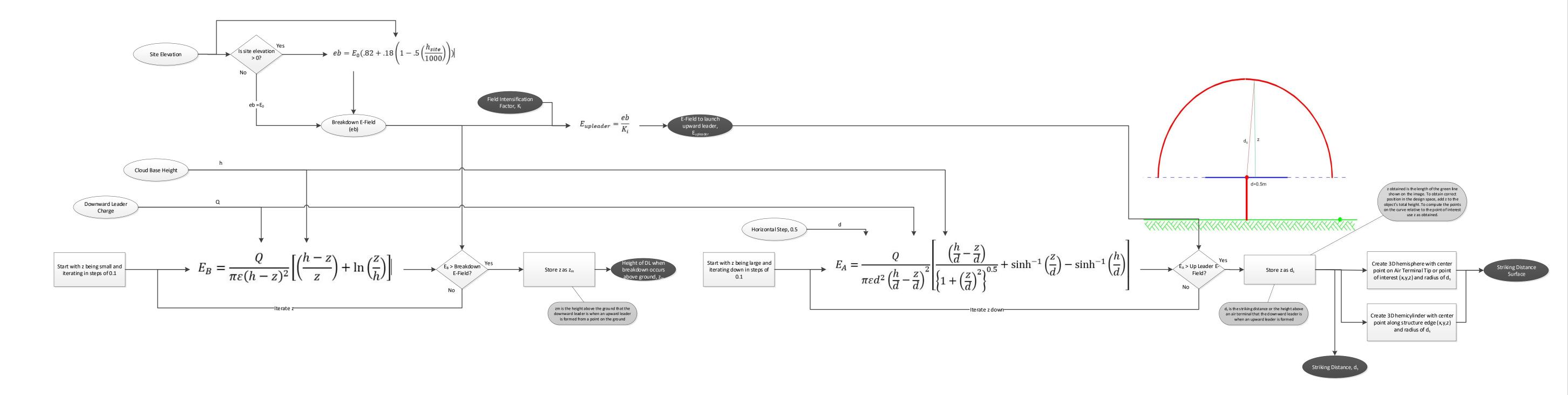


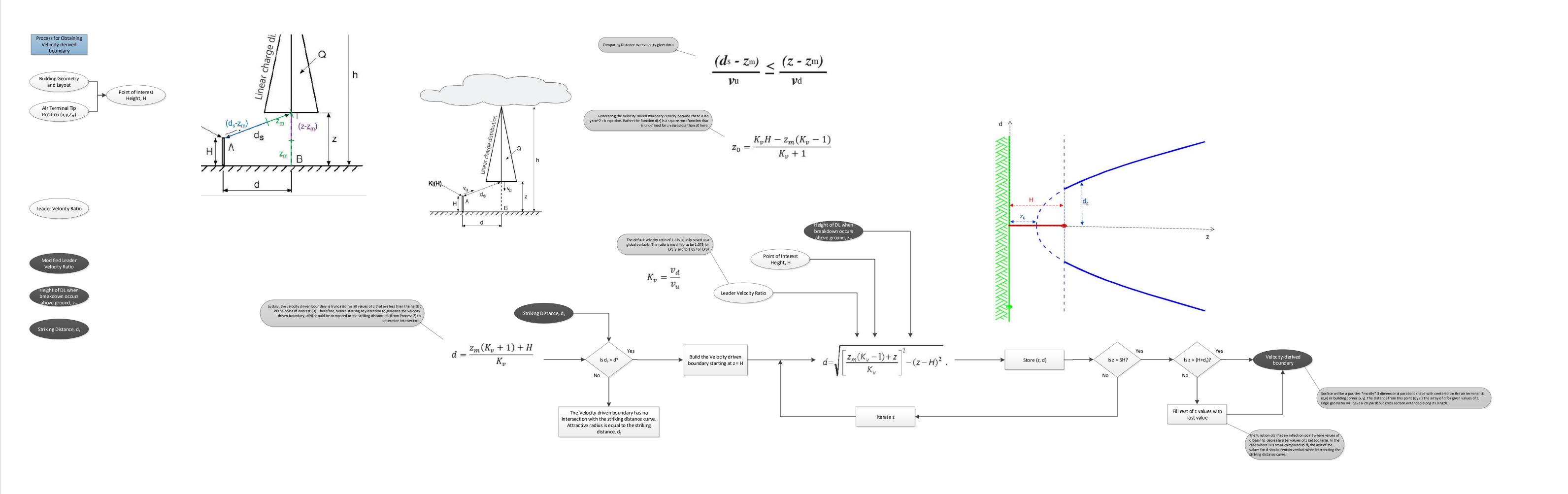
Field Intensification

Default Breakdown E-Field (E₀) 3,100,000

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LPL	Leader charge Q (C)	Peak current I _P (kA)	Striking distance (m)	% strikes > lp (Interception Efficiency)
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Process for Obtaining Protection Radius Striking Distance No Intersection Attractive Radius Surface Intersection Velocity-derived boundary Because both boundaries are circularly symmetric around a single point, their intersection will draw a circle with a constant raduis. This radius is exported as the "attractive radius" Surface will be a *mostly* hemispherical shape with centered on the air terminal tip (x,y,z) or building $comer\,(x,\!y,\!z). \ Edge\ geometry\ will\ have\ a\ semi-circular\ cross\ section\ extended\ along\ its\ length.$ Striking Distance Surface Store "Collection Circles" as a given origin Attractive Radius Check Intersection of Has point at the same (x,y) as the point of both surfaces intersection? (R_a,x,y,z) interest, the (z) of the intersection, and (Ra) as the attractive radius as shown Velocity-derived boundary Surface will be a positive *mostly* 3 dimension al parabolic shape with centered on the air terminal tip (x,y) or building corner (x,y). The distance from this point (x,y) is the array of d for given values of z. Collection Circles for Edge geo metry will have a 2D parabolic cross section extended along its length. Structure Use max radius of the striking distance curve at the feature height (d_s,x,y,h_f)

If no intersection occurs between the striking distance curve and velocity driven boundary, then there are no upward leaders from ground level that will "win the race" against an upward leader from the

point of interest when a downward leader approaches.

Collection Circles for

Terminals

