## **Report: Panorama**

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## **Equation deduction**

We want to compute the parameters of the homography given by

$$egin{bmatrix} x' \ y' \ z' \end{bmatrix} = egin{bmatrix} h_{11} & h_{12} & h_{13} \ h_{21} & h_{22} & h_{23} \ h_{31} & h_{32} & h_{33} \end{bmatrix} egin{bmatrix} x \ y \ z \end{bmatrix}$$

Where  $(x',y',y')^T \in I_2$  and  $(x,y,y)^T \in I_1$  are points in homogeneous coordinates.

Let  $(x_1, y_1)$  be a point of the image  $I_1$  and  $(x_2, y_2)$  the corresponding point in image  $I_2$ . Note that these points are in inhomogeneous coordinates. If we apply the homography matrix to the point  $(x_1, y_1, 1)^T$  we obtain

$$x_2 = rac{x'}{z'} = rac{h_{11}x_1 + h_{12}y_1 + h_{13}}{h_{31}x_1 + h_{31}y_1 + h_{33}}$$

$$y_2=rac{x'}{z'}=rac{h_{21}x_1+h_{22}y_1+h_{23}}{h_{31}x_1+h_{31}y_1+h_{33}}$$

Let the vector  $h = (h_{11}, h_{12}, h_{13}, h_{21}, h_{22}, h_{23}, h_{31}, h_{32})^T$  and fix  $h_{33} = 1$ . Then we can write the system as

$$egin{bmatrix} x_1 & y_1 & 1 & 0 & 0 & 0 & -x_1x_2 & -y_1x_2 \ 0 & 0 & 0 & x_1 & y_1 & 1 & -x_1y_2 & -y_1y_2 \end{bmatrix} h = egin{bmatrix} x_2 \ y_2 \end{bmatrix}$$

Since we need to determine eight parameters, we need at least four pairs of corresponding points  $(x_1,y_1)\in I_1$  and  $(x_2,y_2)\in I_2$ . Each pair adds two equations to the linear system.

Report: Panorama 1

## Results



Report: Panorama 2