

This is the same asymptotic distribution as ML. When  $R$  rises faster than  $\sqrt{N}$ , MSL is consistent, asymptotically normal and efficient, asymptotically equivalent to ML.

Suppose that  $R$  rises with  $N$  but at a rate that is slower than  $\sqrt{N}$ . In this case, the ratio  $\sqrt{N}/R$  grows larger as  $N$  rises. There is no limiting distribution for  $\sqrt{N}(\hat{\theta} - \theta^*)$  because the bias term,  $(\sqrt{N}/R)\mathcal{Z}$  rises with  $N$ . However, the estimator itself converges on the true value.  $\hat{\theta}$  depends on  $(1/R)\mathcal{Z}$ , not multiplied by  $\sqrt{N}$ . This bias term disappears when  $R$  rises at any rate. Therefore, the estimator converges on the true value, just like its non-simulated counterpart, which means that  $\hat{\theta}$  is consistent. However, the estimator is not asymptotically normal since  $\sqrt{N}(\hat{\theta} - \theta^*)$  has no limiting distribution. Standard errors cannot be calculated, and confidence intervals cannot be constructed.

When  $R$  is fixed, the bias rises as  $N$  rises.  $\sqrt{N}(\hat{\theta} - \theta^*)$  does not have a limiting distribution. Moreover, the estimator itself,  $\hat{\theta}$ , contains bias  $B = (1/R)\mathcal{Z}$  that does not disappear as sample size rises with fixed  $R$ . The MSL estimator is neither consistent nor asymptotically normal when  $R$  is fixed.

The properties of MSL can be summarized as follows:

1. If  $R$  is fixed, MSL is inconsistent.
2. If  $R$  rises slower than  $\sqrt{N}$ , MSL is consistent but not asymptotically normal.
3. If  $R$  rises faster than  $\sqrt{N}$ , MSL is consistent, asymptotically normal and efficient, equivalent to ML.

### 10.5.2 Method of simulated moments

For MSM with fixed instruments,  $\check{g}_n(\theta) = \sum_j [d_{nj} - \check{P}_{nj}(\theta)]z_{nj}$ , which is unbiased for  $g_n(\theta)$  since the simulated probability enters linearly. The bias term is zero. The distribution of the estimator is determined only by term  $A$ , which is the same as in the traditional MOM without simulation, and term  $C$ , which reflects simulation noise:

$$\sqrt{N}(\hat{\theta} - \theta^*) = -\check{D}^{-1}\sqrt{N}(A + C).$$

Suppose that  $R$  is fixed. Since  $\check{D}$  converges to its expectation  $\mathbf{D}$ , we have  $-\sqrt{N}\check{D}^{-1}A \xrightarrow{d} N(0, \mathbf{D}^{-1}\mathbf{W}\mathbf{D}^{-1})$  and  $-\sqrt{N}\check{D}^{-1}C \xrightarrow{d} N(0, \mathbf{D}^{-1}(\mathbf{S}/R)\mathbf{D}^{-1})$ , such that

$$\sqrt{N}(\hat{\theta} - \theta^*) \xrightarrow{d} N(0, \mathbf{D}^{-1}[\mathbf{W} + \mathbf{S}/R]\mathbf{D}^{-1}).$$

The asymptotic distribution of the estimator is then

$$\hat{\theta} \stackrel{a}{\sim} N(\theta^*, \mathbf{D}^{-1}[\mathbf{W} + \mathbf{S}/R]\mathbf{D}^{-1}/N).$$

The estimator is consistent and asymptotically normal. Its variance is greater than its non-simulated counterpart by  $\mathbf{D}^{-1}\mathbf{S}\mathbf{D}^{-1}/RN$ , reflecting simulation noise.

Suppose now that  $R$  rises with  $N$  at any rate. The extra variance due to simulation noise disappears, such that  $\hat{\theta} \stackrel{a}{\sim} N(\theta^*, \mathbf{D}^{-1}\mathbf{W}\mathbf{D}^{-1}/N)$ , the same as its non-simulated counterpart. When non-ideal instruments are used,  $\mathbf{D}^{-1}\mathbf{W}\mathbf{D}^{-1} \neq -\mathbf{H}^{-1}$  and so the estimator (in either its simulated or non-simulated form) is less efficient than ML.

If simulated instruments are used in MSM, then the properties of the estimator depend on how the instruments are simulated. If the instruments are simulated without bias and independently of the probability that enters the residual, then this MSM has the same properties as MSM with fixed weights. If the instruments are simulated with bias and the instruments are not ideal, then the estimator has the same properties as MSL except that it is not asymptotically efficient since the information identity does not apply. MSM with simulated ideal instruments is MSS, which we discuss next.

### 10.5.3 Method of simulated scores

With MSS using unbiased score simulators,  $\check{g}_n(\theta)$  is unbiased for  $g_n(\theta)$ , and, moreover,  $g_n(\theta)$  is the score such that the information identity applies. The analysis is the same as for MSM except that the information identity makes the estimator efficient when  $R$  rises with  $N$ . As with MSM, we have

$$\hat{\theta} \stackrel{a}{\sim} N(\theta^*, \mathbf{D}^{-1}[\mathbf{W} + \mathbf{S}/R]\mathbf{D}^{-1}/N)$$

which, since  $g_n(\theta)$  is the score, becomes

$$\hat{\theta} \stackrel{a}{\sim} N(\theta^*, \mathbf{H}^{-1}[\mathbf{V} + \mathbf{S}/R]\mathbf{H}^{-1}/N) = N(\theta^*, -\mathbf{H}^{-1}/N + \mathbf{H}^{-1}\mathbf{S}\mathbf{H}^{-1}/RN)$$

When  $R$  is fixed, the estimator is consistent and asymptotically normal, but its covariance is larger than with ML because of simulation noise. If  $R$  rises at any rate with  $N$ , then we have

$$\hat{\theta} \stackrel{a}{\sim} N(0, -\mathbf{H}^{-1}/N).$$

MSS with unbiased score simulators is asymptotically equivalent to ML when  $R$  rises at any rate with  $N$ .

This analysis shows that MSS with unbiased score simulators has better properties than MSL in two regards. First, for fixed  $R$ , MSS is consistent and asymptotically normal while MSL is neither. Second, for  $R$  rising with  $N$ , MSS is equivalent to ML no matter how fast  $R$  is rising, while MSL is equivalent to ML only if the rate is faster than  $\sqrt{N}$ .

As we discussed in section (10.2.3), finding unbiased score simulators with good numerical properties is difficult. MSS is sometimes applied with biased score simulators. In this case, the properties of the estimator are the same as MSL: the bias in the simulated scores translates into bias in the estimator which disappears from the limiting distribution only if  $R$  rises faster than  $\sqrt{N}$ .

## 10.6 Numerical Solution

The estimators are defined as the value of  $\theta$  that solves  $\check{g}(\theta) = 0$ , where  $\check{g}(\theta) = \sum_n \check{g}_n(\theta)/N$  is the sample average of a simulated statistic  $\check{g}_n(\theta)$ . Since  $\check{g}_n(\theta)$  is a vector, we need to solve the set of equations for the parameters. The question arises: how are these equations solved numerically to obtain the estimates?

Chapter 8 describes numerical methods for maximizing a function. These procedures can also be used for solving a set of equations. Let  $T$  be the negative of the inner product of the defining term for an estimator:  $T = -\check{g}(\theta)' \check{g}(\theta) = -(\sum_n \check{g}_n(\theta))'(\sum_n \check{g}_n(\theta))/N^2$ .  $T$  is necessarily less than or equal to zero, since  $T$  is the negative of a sum of squares.  $T$  has a highest value of 0, which is attained only when the squared terms that compose it are all 0. That is, the maximum of  $T$  is attained when  $\check{g}(\theta) = 0$ . Maximizing  $T$  is equivalent to solving the equation  $\check{g}(\theta) = 0$ . The approaches described in Chapter 8, with the exception of BHHH, can be used for this maximization. BHHH cannot be used because that method assumes that the function being maximized is a sum of observation-specific terms, whereas  $T$  takes the square of each sum of observation-specific terms. The other approaches, especially BFGS and DFP, have proven very effective at locating the parameters at which  $\check{g}(\theta) = 0$ .

With MSL, it is usually easier to maximize the simulated likelihood function rather than  $T$ . BHHH can be used in this case, as well as the

other methods.

## Chapter 11

# Individual-Level Parameters

### 11.1 Introduction

Mixed logit and probit models allow random coefficients whose distribution in the population is estimated. Consider, for example, the model in Chapter 6, of angler's choice among fishing sites. The sites are differentiated on the basis of whether campgrounds are available at the site. Some anglers like having campgrounds at the fishing sites since they can use the grounds for overnight stays. Other anglers dislike the crowds and noise that are associated with campgrounds and prefer fishing at more isolated spots. To capture these differences in tastes, a mixed logit model was specified that included random coefficients for the campground variable and other site attributes. The distribution of coefficients in the population was estimated. Figure 11.1 gives the estimated distribution of the campground coefficient. The distribution was specified to be normal. The mean was estimated as 0.116, and the standard deviation was estimated as 1.655. This distribution provides useful information about the population. For example, the estimates imply that 47 percent of the population dislike having campgrounds at their fishing sites, while the other 53 percent like having them.

The question arises: where in the distribution of tastes does a particular angler lie? Is there a way to determine whether a given person tends to like or dislike having campgrounds at fishing sites?

A person's choices reflect their own tastes. Stated in reverse, a person's choices reveal something about their tastes, which the researcher

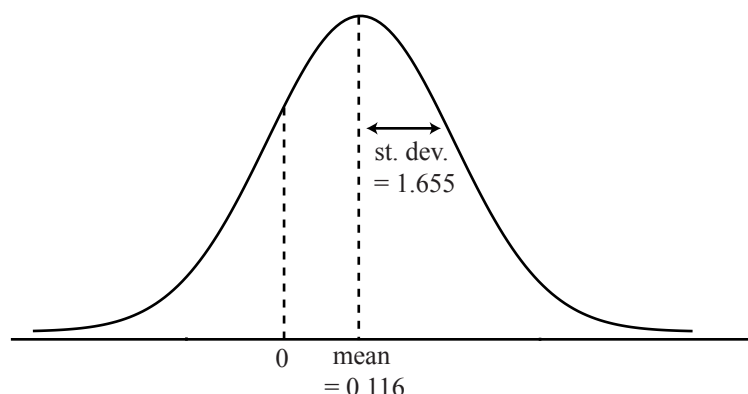


Figure 11.1: Distribution of coefficient of campgrounds in population of all anglers.

can, in principle, discover. If the researcher observes that a particular angler consistently chooses sites without campgrounds, even when the cost of driving to these sites is higher, then the researcher can reasonably infer that this angler dislikes campgrounds. There is a precise way for performing this type of inference, given by Revelt and Train (2000).

We explain the procedure in the context of a mixed logit model; however, any behavioral model that incorporates random coefficients can be used, including probit. The central concept is a distinction between two distributions: the distribution of tastes in the population, and the distribution of tastes in the subpopulation of people who make particular choices. Denote the random coefficients as vector  $\beta$ . The distribution of  $\beta$  in the population of all people is denoted  $g(\beta \mid \theta)$  where  $\theta$  is the parameters of this distribution, such as the mean and variance.

A choice situation consists of several alternatives described collectively by variables  $x$ . Consider the following thought experiment. Suppose everyone in the population faced the same choice situation described by the same variables  $x$ . Some portion of the population will choose each alternative. Consider the people who choose alternative  $i$ . The tastes of these people are not all the same: there is a distribution of coefficients among these people. Let  $h(\beta \mid i, x, \theta)$  denote the distribution of  $\beta$  in the subpopulation of people who, when faced with the

choice situation described by variables  $x$ , would choose alternative  $i$ .

$g(\beta \mid \theta)$  is the distribution of  $\beta$  in the entire population.  $h(\beta \mid i, x, \theta)$  is the distribution of  $\beta$  in the subpopulation of people who would choose alternative  $i$  when facing a choice situation described by  $x$ .

We can generalize the notation to allow for repeated choices. Let  $y$  denote a sequence of choices in a series of situations described collectively by variables  $x$ . The distribution of coefficients in the subpopulation of people who would make the sequences of choices  $y$  when facing situations described by  $x$  is denoted  $h(\beta \mid y, x, \theta)$ .

Note that  $h(\cdot)$  conditions on  $y$ , while  $g(\cdot)$  does not. It is sometimes useful to call  $h$  the conditional distribution and  $g$  the unconditional distribution. Two such distributions are depicted in Figure 11.2. If we knew nothing about a person's past choices, then the best we could do in describing the person's tastes is to say that the person's coefficients lie somewhere in  $g(\beta \mid \theta)$ . However, if we have observed that the person made choices  $y$  when facing situations described by  $x$ , then we know that that person's coefficients are in distribution  $h(\beta \mid y, x, \theta)$ . Since  $h$  is tighter than  $g$ , we have better information about the person's tastes by conditioning on their past choices.

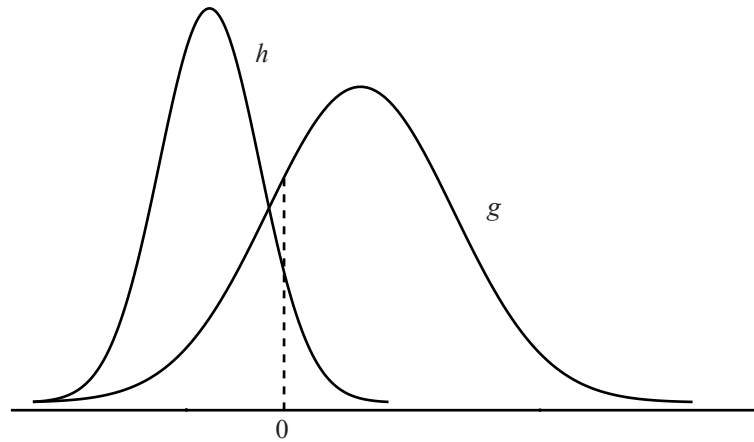


Figure 11.2: Unconditional (population) distribution  $g$  and condition (subpopulation) distribution  $h$  for subpopulation of anglers who chose sites without campgrounds.

Inference of this form has long been conducted with linear regres-

sion models, where the dependent variable and the distribution of coefficients are both continuous (Griffiths, 1972; Judge, Hill, Griffiths, Lutkepohl and Lee, 1988). Regime-switching models, particularly in macroeconomics, have used an analogous procedure to assess the probability that an observation is within a given regime (Hamilton and Susmel, 1994; Hamilton, 1996). In these models, the dependent variable is continuous and the distribution of coefficients is discrete (representing one set of coefficients for each regime.) In contrast to both of these traditions, our models have discrete dependent variables. DeSarbo, Ramaswamy and Cohen (1995) developed an approach in the context of a discrete choice model with a discrete distribution of coefficients (that is, a latent class model). They used maximum likelihood procedures to estimate the coefficients for each segment, and then calculated the probability that an observation is within each segment based on the observed choices of the observation. The approach that we describe here applies to discrete choice models with continuous or discrete distributions of coefficients and uses maximum likelihood (or other classical methods) for estimation. The model of DeSarbo et al. (1995) is a special case of this more general method. Bayesian procedures have been also developed to perform this inference within discrete choice models (Rossi, McCulloch and Allenby, 1996; Allenby and Rossi, 1999). We describe the Bayesian methods in Chapter 12.

## 11.2 Derivation of conditional distribution

The relation between  $h$  and  $g$  can be established precisely. Consider a choice among alternatives  $j = 1, \dots, J$  in choice situations  $t = 1, \dots, T$ . The utility that person  $n$  obtains from alternative  $j$  in situation  $t$  is

$$U_{njt} = \beta_n' x_{njt} + \varepsilon_{njt}$$

where  $\varepsilon_{njt} \sim \text{iid extreme value}$ , and  $\beta_n \sim g(\beta \mid \theta)$  in the population. The variables  $x_{njt}$  can be denoted collectively for all alternatives and choice situations as  $x_n$ . Let  $y_n = \langle y_{n1}, \dots, y_{nT} \rangle$  denote the person's sequence of chosen alternatives. If we knew  $\beta_n$ , then the probability of the person's sequence of choices would be a product of logits:

$$P(y_n \mid x_n, \beta) = \prod_{t=1}^T L_{nt}(y_{nt} \mid \beta)$$



where

$$L_{nt}(y_{nt} | \beta) = \frac{e^{\beta' x_{nynt}}}{\sum_j e^{\beta' x_{njt}}}.$$

Since we do not know  $\beta_n$ , the probability of the person's sequence of choices is the integral of  $P(y_n | x_n, \beta)$  over the distribution of  $\beta$ :

$$P(y_n | x_n, \theta) = \int P(y_n | x_n, \beta) g(\beta | \theta) d\beta. \quad (11.1)$$

This is the mixed logit probability that we discussed in Chapter 6.

We can now derive  $h(\beta | y_n, x_n, \theta)$ . By Bayes' rule,

$$h(\beta | y_n, x_n, \theta) \times P(y_n | x_n, \theta) = P(y_n | x_n, \beta) \times g(\beta | \theta).$$

This equation simply states that the joint density of  $\beta$  and  $y_n$  can be expressed as the probability of  $y_n$  times the probability of  $\beta$  conditional on  $y_n$  (which is the left hand side), or with the other direction of conditioning, as the probability of  $\beta$  times the probability of  $y_n$  conditional on  $\beta$  (which is the right hand side.) Rearranging:

$$h(\beta | y_n, x_n, \theta) = \frac{P(y_n | x_n, \beta) g(\beta | \theta)}{P(y_n | x_n, \theta)}. \quad (11.2)$$

We know all the terms on the right hand side. From these, we can calculate  $h$ .

Equation (11.2) also provides a way to interpret  $h$  intuitively. Note that the denominator  $P(y_n | x_n, \theta)$  is the integral of the numerator, as given by the definition in (11.1). As such, the denominator is a constant that makes  $h$  integrate to 1, as required for any density. Since the denominator is a constant,  $h$  is proportional to the numerator,  $P(y_n | x_n, \beta) g(\beta | y_n, x_n, \theta)$ . This relation makes interpretation of  $h$  relatively easy. Stated in words: the density of  $\beta$  in the subpopulation of people who would choose sequence  $y_n$  when facing  $x_n$  is proportional to the density of  $\beta$  in the entire population *times* the probability that  $y_n$  would be chosen if the person's coefficients were  $\beta$ .

Using (11.2), various statistics can be derived conditional on  $y_n$ . The mean  $\beta$  in the subpopulation of people who would choose  $y_n$  when facing  $x_n$  is

$$\bar{\beta}_n = \int \beta \cdot h(\beta | y_n, x_n, \theta) d\beta.$$

This mean generally differs from the mean  $\beta$  in the entire population. Substituting the formula for  $h$ ,

$$\begin{aligned}\bar{\beta}_n &= \frac{\int \beta \cdot P(y_n | x_n, \beta) g(\beta | \theta) d\beta}{P(y_n | x_n, \theta)} \\ &= \frac{\int \beta \cdot P(y_n | x_n, \beta) g(\beta | \theta) d\beta}{\int P(y_n | x_n, \beta) g(\beta | \theta) d\beta}\end{aligned}\quad (11.3)$$

The integrals in this equation do not have a closed form; however, they can be readily simulated. Take draws of  $\beta$  from the population density  $g(\beta | \theta)$ . Calculate the weighted average of these draws, with the weight for draw  $\beta^r$  being proportional to  $P(y_n | x_n, \beta^r)$ . The simulated subpopulation mean is

$$\check{\beta}_n = \sum_r w^r \beta^r$$

where the weights are

$$w^r = \frac{P(y_n | x_n, \beta^r)}{\sum_r P(y_n | x_n, \beta^r)}.\quad (11.4)$$

Other statistics can also be calculated. Suppose the person faces a new choice situation described by variables  $x_{njT+1} \forall j$ . If we had no information on the person's past choices, then we would assign the following probability to his choosing alternative  $i$ :

$$P(i | x_{nT+1}, \theta) = \int L_{nT+1}(i | \beta) g(\beta | \theta) d\beta \quad (11.5)$$

where

$$L_{nT+1}(i | \beta) = \frac{e^{\beta' x_{niT+1}}}{\sum_j e^{\beta' x_{njT+1}}}.$$

This is just the mixed logit probability using the population distribution of  $\beta$ . If we observed the past choices of the person, then the probability can be conditioned on these choices. The probability becomes:

$$P(i | x_{nT+1}, y_n, x_n, \theta) = \int L_{nT+1}(i | \beta) h(\beta | y_n, x_n, \theta) d\beta. \quad (11.6)$$

This is also a mixed logit probability, but using the conditional distribution  $h$  instead of the unconditional distribution  $g$ . When we do

not know the person's previous choices, we mix the logit formula over density of  $\beta$  in the entire population. However, when we know the person's previous choices, we can improve our prediction by mixing over the density of  $\beta$  in the subpopulation who would have made the same choices as this person.

To calculate this probability, we substitute the formula for  $h$  from (11.2):

$$P(i \mid x_{nT+1}, y_n, x_n, \theta) = \frac{\int L_{nT+1}(i \mid \beta) P(y_n \mid x_n, \beta) g(\beta \mid \theta) d\beta}{\int P(y_n \mid x_n, \beta) g(\beta \mid \theta) d\beta}.$$

The probability is simulated by taking draws of  $\beta$  from the population distribution  $g$ , calculating the logit formula for each draw, and taking a weighted average of the results:

$$\check{P}_{niT+1}(y_n, x_n, \theta) = \sum_r w^r L_{nT+1}(i \mid \beta^r)$$

where the weights are given by (11.4).

### 11.3 Implications of estimation of $\theta$

The population parameters  $\theta$  are estimated in any of the ways described in Chapter 10. The most common approach is maximum simulated likelihood, with the simulated value of  $P(y_n \mid x_n, \theta)$  entering the log-likelihood function. An estimate of  $\theta$ , labeled  $\hat{\theta}$ , is obtained. We know that there is sampling variance in the estimator. The asymptotic covariance of the estimator is also estimated, which we label  $\hat{W}$ . The asymptotic distribution is therefore estimated to be  $N(\hat{\theta}, \hat{W})$ .

The parameter  $\theta$  describes the distribution of  $\beta$  in the population, giving, for example, the mean and variance of  $\beta$  over all decision-makers. For any value of  $\theta$ , equation (11.2) gives the conditional distribution of  $\beta$  in the subpopulation of people who would make choices  $y_n$  when faced with situations described by  $x_n$ . This relation is exact in the sense that there is no sampling or other variance associated with it. Similarly, any statistic based on  $h$  is exact given a value of  $\theta$ . For example, the mean of the conditional distribution,  $\bar{\beta}_n$ , is exactly equation (11.3) for a given value of  $\theta$ .

Given this correspondence between  $\theta$  and  $h$ , the fact that  $\theta$  is estimated can be handled in two different ways. The first approach is to use the point estimate of  $\theta$  to calculate statistics associated with

the conditional distribution  $h$ . Under this approach, the mean of the condition distribution,  $\bar{\beta}_n$ , is calculated by inserting  $\hat{\theta}$  into (11.3). The probability in a new choice situation is calculated by inserting  $\hat{\theta}$  into (11.6). If the estimator of  $\theta$  is consistent, then this approach is consistent for statistics based on  $\theta$ .

The second approach is to take the sampling distribution of  $\hat{\theta}$  into consideration. Each possible value of  $\theta$  implies a value of  $h$ , and hence a value of any statistic associated with  $h$ , such as  $\bar{\beta}_n$ . The sampling variance in the estimator of  $\theta$  induces sampling variance in the statistics that are calculated on the basis of  $\theta$ . This sampling variance can be calculated through simulation, by taking draws of  $\theta$  from its estimated sampling distribution and calculating the corresponding statistic for each of these draws.

For example, to represent the sampling distribution of  $\hat{\theta}$  in the calculation of  $\bar{\beta}_n$ , the following steps are taken.

1. Take a draw from  $N(\hat{\theta}, \hat{W})$ , which is the estimated sampling distribution of  $\hat{\theta}$ . This step is accomplished as follows. Take  $K$  draws from a standard normal density and label the vector of these draws  $\eta^r$ , where  $K$  is the length of  $\theta$ . Then create  $\theta^r = \hat{\theta} + L\eta^r$ , where  $L$  is the Choleski factor of  $\hat{W}$ .
2. Calculate  $\bar{\beta}_n^r$  based on this  $\theta^r$ . Since the formula for  $\bar{\beta}_n$  involves integration, we simulate it using formula (11.3).
3. Repeat steps 1 and 2 many times, with the number of times labeled  $R$ .

The resulting values are draws from the sampling distribution of  $\bar{\beta}_n$  induced by the sampling distribution of  $\hat{\theta}$ . The average of  $\bar{\beta}_n^r$  over the  $R$  draws of  $\theta^r$  is the mean of the sampling distribution of  $\bar{\beta}_n$ . The standard deviation of the draws gives the asymptotic standard error of  $\bar{\beta}_n$  that is induced by the sampling variance of  $\hat{\theta}$ .

Note that this process involves simulation within simulation. For each draw of  $\theta^r$ , the statistic  $\bar{\beta}_n^r$  is simulated with multiple draws of  $\beta$  from the population density  $g(\beta | \theta^r)$ .

Suppose either of these approaches is used to estimate  $\bar{\beta}_n$ . The question arises: can the estimate of  $\bar{\beta}_n$  be considered an estimate of  $\beta_n$ ? That is: is the estimated mean of the conditional distribution  $h(\beta | y_n, x_n, \theta)$ , which is conditioned on person  $n$ 's past choices, an estimate of person  $n$ 's coefficients?

There are two possible answers, depending on how the researcher views the data generation process. If the number of choice situations that the researcher can observe for each decision-maker is fixed, then the estimate of  $\bar{\beta}_n$  is not a consistent estimate of  $\beta_n$ . When  $T$  is fixed, consistency requires that the estimate converge to the true value when sample size rises without bound. If sample size rises, but the choice situations faced by person  $n$  is fixed, then the conditional distribution and its mean does not change. Insofar as person  $n$ 's coefficients do not happen to coincide with the mean of the conditional distribution (an essentially impossible event), the mean of the conditional distribution will never equal the person's coefficients no matter how large the sample is. Raising sample size improves the estimate of  $\theta$  and hence provides a better estimate of the mean of the conditional distribution, since this mean depends only on  $\theta$ . However, raising sample size does not make the conditional mean equal to the person's coefficients.

When the number of choice situations is fixed, then the conditional mean has the same interpretation as the population mean, but for a different, and less diverse, group of people. When predicting the future behavior of the person, one can expect to obtain better predictions using the conditional distribution, as in (11.6), than the population distribution. In the case study presented below, we show that the improvement can be large.

If the number of choice situations that a person faces can be considered to rise, then the estimate of  $\bar{\beta}_n$  can be considered to be an estimate of  $\beta_n$ . Let  $T$  be the number of choice situations that person  $n$  faces. If we observe more choices by the person (i.e.,  $T$  rises), then we are better able to identify the person's coefficients. Figure 11.3 gives the conditional distribution  $h(\beta \mid y_n, x_n, \theta)$  for three different values of  $T$ . The conditional distribution tends to move toward the person's own  $\beta_n$  as  $T$  rises, and to become more concentrated. As  $T$  rises without bound, the conditional distribution collapses onto  $\beta_n$ . The mean of the conditional distribution converges to the true value of  $\beta_n$  as the number of choice situations rises without bound. The estimate of  $\bar{\beta}_n$  is therefore consistent for  $\beta_n$ .

In Chapter 12, we describe the Bernstein-von Mises theorem. This theorem states that, under fairly mild conditions, the mean of a posterior distribution for a parameter is asymptotically equivalent to the maximum of the likelihood function. The conditional distribution  $h$  is a posterior distribution: by (11.2)  $h$  is proportional to a density  $g$ ,

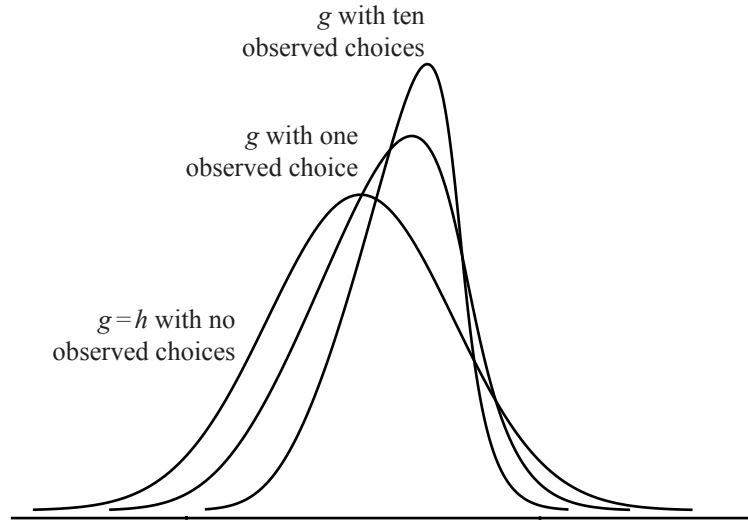


Figure 11.3: Conditional distribution with  $T = 0, 1$ , and  $10$ .

which can be interpreted as a prior distribution on  $\beta_n$ , *times* the likelihood of person  $n$ 's  $T$  choices given  $\beta_n$ , which is  $P(y_n | x_n, \beta_n)$ . By the Bernstein-von Mises theorem, the mean of  $h$  is therefore an estimator of  $\beta_n$  that is asymptotically equivalent to the maximum likelihood estimator of  $\beta_n$ , where the asymptotics are defined as  $T$  rising. These concepts are described more fully in Chapter 12; we mention them now simply to provide another interpretation of the mean of the conditional distribution.

## 11.4 Monte Carlo illustration

To illustrate the concepts, I constructed a hypothetical data set where the true population parameters  $\theta$  are known as well as the true  $\beta_n$  for each decision-maker. These data allow us to compare the mean of the conditional distribution for each decision-maker's choices,  $\bar{\beta}_n$ , with the  $\beta_n$  for that decision-maker. It also allows us to investigate the impact of increasing the number of choice situations on the conditional distribution. For this experiment, I constructed data sets consisting of 300 "customers" each facing  $T = 1, 10, 20$ , and  $50$  choice situations. There are three alternatives and four variables in each data set. The coeffi-

cients for the first two variables are held fixed for the entire population at 1.0, and the coefficients for the last two variables are distributed normal with a mean and variance of 1.0. Utility is specified to include these variables plus a final iid term that is distributed extreme value, such that the model is a mixed logit. The dependent variable for each customer was created by taking a draw from the density of the random terms, calculating the utility of each alternative with this draw, and determining which alternative had the highest utility. To minimize the effect of simulation noise in the creation of the data, I constructed 50 datasets for each level of  $T$ . The results that are reported are the average over these 50 datasets.

The mean of the conditional distribution for each customer,  $\bar{\beta}_n$ , was calculated. The standard deviation of  $\bar{\beta}_n$  over the 300 customers was calculated, as well as the average absolute deviation of  $\bar{\beta}_n$  from the customer's  $\beta_n$  (i.e., the average over  $n$  of  $|\bar{\beta}_n - \beta_n|$ ). Table 11.1 presents these statistics. Consider first the standard deviation. If there were no observed choice situations on which to condition ( $T = 0$ ), then the conditional distribution for each customer would be the unconditional (population) distribution. Each customer would have the same  $\bar{\beta}_n$  equal to the population mean of  $\beta$ . In this case, the standard deviation of  $\bar{\beta}_n$  would be zero, since all customers have the same  $\bar{\beta}_n$ . At the other extreme, if we observed an unboundedly large number of choice situations ( $T \rightarrow \infty$ ), then the conditional distribution for each customer would collapse to their own  $\beta_n$ . In this case, the standard deviation of  $\bar{\beta}_n$  would equal the standard deviation of the population distribution of  $\beta_n$ , which is 1 in this experiment. For  $T$  between 0 and  $\infty$ , the standard deviation of  $\bar{\beta}_n$  is between 0 and the standard deviation of  $\beta_n$  in the population.

In Table 11.1, we see that conditioning on only a few choice situations captures a large share of the variation in  $\beta$ 's over customers. With only one choice situation, the standard deviation of  $\bar{\beta}_n$  is over .4. Since the standard deviation of  $\beta_n$  in the population is 1 in this experiment, this result means that conditioning on one choice situation captures over 40 percent of the variation in  $\beta_n$ . With 10 choices situations, over 80 percent of the variation is captured. There are strongly decreasing return to observing more choice situations. Doubling from  $T = 10$  to  $T = 20$  only increases the percent of variation captured from about .83 to about .89. Increasing  $T$  to 50 raises the percent to about .95.

Table 11.1: Monte Carlo Illustration

	1st coef.	2nd coef.
1 choice situation		
Standard deviation of $\bar{\beta}_n$	0.413	0.416
Absolute difference between $\bar{\beta}_n$ and $\beta_n$	0.726	0.718
10 choice situation		
Standard deviation of $\bar{\beta}_n$	0.826	0.826
Absolute difference between $\bar{\beta}_n$ and $\beta_n$	0.422	0.448
20 choice situation		
Standard deviation of $\bar{\beta}_n$	0.894	0.886
Absolute difference between $\bar{\beta}_n$ and $\beta_n$	0.354	0.350
50 choice situation		
Standard deviation of $\bar{\beta}_n$	0.951	0.953
Absolute difference between $\bar{\beta}_n$ and $\beta_n$	0.243	0.243

Consider now the absolute difference between the mean of the customer's conditional distribution,  $\bar{\beta}_n$ , and the customer's actual  $\beta_n$ . With no conditioning ( $T = 0$ ), the average absolute difference would be 0.8, which is the expected absolute difference for deviates that follow a standard normal as we have in our experiment. With perfect conditioning ( $T \rightarrow \infty$ ),  $\bar{\beta}_n = \beta_n$  for each customer, and so the absolute difference is 0. With only one choice situation, the average absolute deviation drops from 0.8 (without conditioning) to about 0.72, for a 10 percent improvement. The absolute deviation drops further as the number of choice situations rises.

Notice that the drop in the absolute deviation is smaller than the increase in the standard deviation. For example, with one choice situation the absolute deviation moves 10 percent of the way from no conditioning to perfect knowledge (from .80 with  $T = 0$  to .72 with  $T = 1$ , which is 10 percent of the way to 0 with  $T \rightarrow \infty$ ). Yet the standard deviation moves about 40 percent of the way from no conditioning to perfect knowledge (.4 with  $T = 1$  is 40 percent of the distance from 0 with  $T = 0$  to 1 with  $T \rightarrow \infty$ ). This difference is due to the fact that the standard deviation incorporates movement of  $\bar{\beta}_n$  away from  $\beta_n$  as well as movement towards  $\beta_n$ . This fact is important to recognize when evaluating the standard deviation of  $\bar{\beta}_n$  in empirical applications, where the absolute difference cannot be calculated since  $\beta_n$  is not known. That is, the standard deviation of  $\bar{\beta}_n$  expressed



as a percent of the estimated standard deviation in the population, is an overestimate of the amount of information that is contained in the  $\bar{\beta}_n$ 's. With ten choice situations, the average standard deviation in  $\bar{\beta}_n$  is over 80 percent of the value that it would have with perfect knowledge, and yet the absolute deviation is less than half as high as would be attained without conditioning.

## 11.5 Average conditional distribution

For a correctly specified model at the true population parameters, the conditional distribution of tastes, aggregated over all customers, equals the population distribution of tastes. Given a series of choice situations described by  $x_n$ , there is a set of possible sequences of choices. Label these possible sequences as  $y_s$  for  $s = 1, \dots, S$ . Denote the true frequency of  $y_s$  as  $m(y_s | x_n, \theta^*)$ , which depends on the true parameters  $\theta^*$ . If the model is correctly specified and consistently estimated, then  $P(y_s | x_n, \hat{\theta})$  approaches  $m(y_s | x_n, \theta^*)$  asymptotically. Conditional on the explanatory variables, the expected value of  $h(\beta | y_s, x_n, \hat{\theta})$  is then:

$$\begin{aligned} E_y h(\beta | y, x_n, \hat{\theta}) &= \sum_s \frac{P(y_s | x_n, \beta) g(\beta | x_n, \hat{\theta})}{P(y_s | x_n, \hat{\theta})} m(y_s | x_n, \theta^*) \\ &\rightarrow \sum_s P(y_s | x_n, \beta) g(\beta | x_n, \hat{\theta}) \\ &= g(\beta | x_n, \hat{\theta}). \end{aligned}$$

This relation provides a diagnostic tool (Allenby and Rossi, 1999). If the average of the sampled customers' conditional taste distributions is similar to the estimated population distribution, the model is correctly specified and accurately estimated. If they are not similar, the difference could be due to: (1) specification error, (2) an insufficient number of draws in simulation, (3) an inadequate sample size, and/or (4) the maximum likelihood routine converging at a local rather than global maximum.

## 11.6 Case study: choice of energy supplier

### Population distribution

We obtained stated-preference data on residential customers' choice of electricity supplier. Surveyed customers were presented with 8-12

hypothetical choice situations called experiments. In each experiment, the customer was presented with four alternative suppliers with different prices and other characteristics. The suppliers differed on the basis of price (fixed price at a given cents per kWh, time-of-day prices with stated prices in each time period, or seasonal prices with stated prices in each time period), the length of the contract (during which the supplier is required to provide service at the stated price and the customer would need to pay a penalty for leaving the supplier), and whether the supplier was their local utility, a well-known company other than their local utility, or an unfamiliar company. The data were collected by Research Triangle Institute (1997) for the Electric Power Research Institute and have been used by Goett (1998) to estimate mixed logits. We utilize a specification similar to Goett's, but we eliminate or combine variables that he found to be insignificant.

Two mixed logit models were estimated on these data, based on different specifications for the distribution of the random coefficients. All choices except the last situation for each customer are used to estimate the parameters of the population distribution, and the customer's last choice situation was retained for use in comparing the predictive ability of different models and methods.

Table 11.2 gives the estimated population parameters. The price coefficient in both models is fixed across the population such that the distribution of willingness to pay for each non-price attribute (which is the ratio of the attribute's coefficient to the price coefficient) has the same distribution as the attribute's coefficient. For model 1, all of the non-price coefficients are specified to be normally distributed in the population. The mean  $m$  and standard deviation  $s$  of each coefficient are estimated. For model 2, the first three non-price coefficients are specified to be normal, and the fourth and fifth are log-normal. The fourth and fifth variable are indicators of time-of-day and seasonal rates, and their coefficients must logically be negative for all customers. The log-normal distribution (with the signs of the variable reversed) provides for this necessity. The log of these coefficients is distributed normal with mean  $m$  and standard deviation  $s$ , which are the parameters that are estimated. The coefficients themselves have mean  $\exp(m + (s^2/2))$  and standard deviation equal to the mean times  $\sqrt{\exp(s^2) - 1}$ .

The estimates provide the following qualitative results:

- The average customer is willing to pay about a fifth to a quarter

Table 11.2: Mixed logit model of energy supplier choice

	Model 1	Model 2
Price, in cents per kWh	-0.8574 (0.0488)	-0.8827 (0.0497)
Contract length, in years		
<i>m</i>	-0.1833 (0.0289)	-0.2125 (0.0261)
<i>s</i>	0.3786 (0.0291)	0.3865 (0.0278)
Local utility		
<i>m</i>	2.0977 (0.1370)	2.2297 (0.1266)
<i>s</i>	1.5585 (0.1264)	1.7514 (0.1371)
Known company		
<i>m</i>	1.5247 (0.1018)	1.5906 (0.0999)
<i>s</i>	0.9520 (0.0998)	0.9621 (0.0977)
TOD rate*		
<i>m</i>	-8.2857 (0.4577)	2.1328 (0.0543)
<i>s</i>	2.5742 (0.1676)	0.4113 (0.0397)
Seasonal rate*		
<i>m</i>	-8.5303 (0.4468)	2.1577 (0.0509)
<i>s</i>	2.1259 (0.1604)	0.2812 (0.0217)
Log-likelihood at convergence	-3646.51	-3618.92

Standard errors in parentheses.

TOD rates: 11c/kWh 8am-8pm, 5c/kWh 8pm-8am

Seasonal rates: 10c/kWh summer, 8c/kWh winter, 6c/kWh spring-fall

cent per kWh in higher price, depending on the model, in order to have a contract that is shorter by one year. Stated conversely, a supplier that requires customers to sign a four to five-year contract must discount its price by one cent per kWh to attract the average customer.

- There is considerable variation in customers' attitudes towards contract length, with a sizeable share of customers preferring a longer contract to a shorter contract. A long-term contract constitutes insurance for the customer against price increases with the supplier being locked into the stated price for the length of the contract. Such contracts prevent the customer from taking advantage of lower prices that might arise during the term of the contract. Apparently, many customers value the insurance against higher prices more than they mind losing the option to take advantage of potentially lower prices. The degree of customer heterogeneity implies that the market can sustain contracts of different lengths with suppliers making profits by writing contracts that appeal to different segments of the population.
- The average customer is willing to pay a whopping 2.5 cents per kWh more for its local supplier than for an unknown supplier. Only a small share of customers prefer an unknown supplier to their local utility. This finding has important implications for competition. It implies that entry in the residential market by previously unknown suppliers will be very difficult, particularly since the price discounts that entrants can potentially offer in most markets are fairly small. The experience in California, where only 1 percent of residential customers have switched away from their local utility after several years of open access, is consistent with this finding.
- The average customer is willing to pay 1.8 cents per kWh for a known supplier relative to an unknown one. The estimated values of  $s$  imply that a sizeable share of customers would be willing to pay more for a known supplier than for their local utility, presumably because of a bad experience or a negative attitude toward the local energy utility. These results imply that companies that are known to customers, such as their long distance carriers, lo-

cal telecommunications carriers, local cable companies, and even retailers like Sears and Home Depot, may be successful in attracting customers for electricity supply relative to companies that were unknown prior to their entry as an energy supplier.

- The average customer evaluates the TOD rates in a way that is fairly consistent with time-of-day usage patterns. In model 1, the mean coefficient of the dummy variable for the TOD rates implies that the average customer considers these rates to be equivalent to a fixed price of 9.7 cents per kWh. In model 2, the estimated mean and standard deviation of the log of the coefficient imply a median willingness to pay of 8.4 cents and a mean of 10.4 cents, which span the mean from model 1. 9.5 cents is the average price that a customer would pay under the TOD rates if 75 percent of its consumption occurred during the day (between 8AM and 8PM) and the other 25 percent occurred at night. These shares, while perhaps slightly high for the day, are not unreasonable. The estimated values of  $s$  are highly significant, reflecting heterogeneity in usage patterns and perhaps in customers' ability to shift consumption in response to TOD prices. These values are larger than reasonable implying that a non-negligible share of customers treat the TOD prices as being equivalent to a fixed price that is higher than the highest TOD price or lower than the lowest TOD price.
- The average customer seems to avoid seasonal rates for reasons beyond the prices themselves. The average customers treats the seasonal rates as being equivalent to a fixed ten cents per kWh, which is the highest seasonal price. A possible explanation for this result relates to the seasonal variation in customers' bills. In many areas, electricity consumption is highest in the summer, when air-conditioners are being run, and energy bills are therefore higher in the summer than in other seasons, even under fixed rates. The variation in bills over months without commensurate variation in income makes it more difficult for customers to pay for their summer bills. In fact, nonpayment for most energy utilities is most frequent in the summer. Seasonal rates, which apply the highest price in the summer, increase the seasonal variation in bills. Customers would rationally avoid a rate plan that exacerbates an already existing difficulty. If this interpretation is cor-

rect, then seasonal rates combined with bill-smoothing (by which the supplier carries a portion of the summer bills over to the winter) could provide an attractive arrangement for customers and suppliers alike.

Model 2 attains the a higher log-likelihood value than model 1, presumably because the lognormal distribution assures negative coefficients for the TOD and seasonal variables.

### Conditional distributions

We now use the estimated models to calculate customers' conditional distributions and the means of these distributions. We calculate  $\bar{\beta}_n$  for each customer in two ways. First, we calculate  $\bar{\beta}_n$  using equation (11.3) with the point estimates of the population parameters,  $\hat{\theta}$ . Second, we use the procedure in section (11.3) to integrate over the sampling distribution of the estimated population parameters.

The means and standard deviations of  $\bar{\beta}_n$  over the sampled customers calculated by these two methods are given in Tables 11.3 and 11.4, respectively. The price coefficient is not listed in Table 11.3 since it is fixed across the population. Table 11.4 incorporates the sampling distribution of the population parameters, which includes variance in the price coefficient.

Consider the results in Table 11.3 first. The mean of  $\bar{\beta}_n$  is very close to the estimated population mean given in Table 11.2. This similarity as expected for a correctly specified and consistently estimated model. The standard deviation of  $\bar{\beta}_n$  would be zero if there were no conditioning and would equal the population standard deviation if each customer's coefficient were known exactly. The standard deviations in Table 11.3 are considerably above zero and are fairly close to the estimated population standard deviations in Table 11.2. For example, in model 1, the conditional mean of the coefficient of contract length has a standard deviation of 0.318 over customers, and the point estimate of the standard deviation in the population is 0.379. Thus, variation in  $\bar{\beta}_n$  captures more than 70 percent of the total estimated variation in this coefficient. Similar results are obtained for other coefficients. This result implies that the mean of a customer's conditional distribution captures a fairly large share of the variation in coefficients across customers and has the potential to be useful in distinguishing customers.

Table 11.3: Average  $\bar{\beta}_n$  using point estimate  $\hat{\theta}$ 

	Model 1	Model 2
Contract length		
Mean	-0.2028	-0.2149
Std dev	0.3175	0.3262
Local utility		
Mean	2.1205	2.2146
Std dev	1.2472	1.3836
Known company		
Mean	1.5360	1.5997
Std dev	0.6676	0.6818
TOD rate		
Mean	-8.3194	-9.2584
Std dev	2.2725	3.1051
Seasonal rate		
Mean	-8.6394	-9.1344
Std dev	1.7072	2.0560

As discussed in section (11.5), a diagnostic check on the specification and estimation of the model is obtained by comparing the sample average of the conditional distributions with the estimated population distribution. The means in Table 11.3 represent the means of the sample average of the conditional distributions. The standard deviation of the sample-average conditional distribution depends on the standard deviation of  $\bar{\beta}_n$  which is given in Table 11.3, plus the standard deviation of  $\beta_n - \bar{\beta}_n$ . When this latter portion is added, the standard deviation of each coefficient matches very closely the estimated population standard deviation. This equivalence suggests that there is not significant specification error and that the estimated population parameters are fairly accurate. This suggestion is somewhat tempered, however, by the results in Table 11.4.

Table 11.4 gives the sample mean and standard deviation of the mean of the sampling distribution of  $\bar{\beta}_n$  that is induced by the sampling distribution of  $\hat{\theta}$ . The means in Table 11.4 represent the means of the sample average of  $h(\beta | y_n, x_n, \hat{\theta})$  integrated over the sampling distribution of  $\hat{\theta}$ . For model 1, a discrepancy occurs that indicates possible misspecification. In particular, the means of the TOD and seasonal rates coefficients in Table 11.4 exceed their estimated popula-

Table 11.4: Average  $\bar{\beta}_n$  with sampling dist. of  $\hat{\theta}$ 

	Model 1	Model 2
Price		
Mean	-0.8753	-0.8836
Std dev	0.5461	0.0922
Contract length		
Mean	-0.2004	-0.2111
Std dev	0.3655	0.3720
Local utility		
Mean	2.1121	2.1921
Std dev	1.5312	1.6815
Known company		
Mean	1.5413	1.5832
Std dev	0.9364	0.9527
TOD rate		
Mean	-9.1615	-9.0216
Std dev	2.4309	3.8785
Seasonal rate		
Mean	-9.4528	-8.9408
Std dev	1.9222	2.5615



Table 11.5: Condition means for three customers

	Population	Customer 1	Customer 2	Customer 3
Contract length	-0.213	0.198	-0.208	-0.401
Local utility	2.23	2.91	2.17	0.677
Known company	1.59	1.79	2.15	1.24
TOD rates	-9.19	-5.59	-8.92	-12.8
Seasonal rates	-9.02	-5.86	-11.1	-10.9

tion means in Table 11.2. Interestingly, the means for these coefficients in Table 11.4 for model 1 are closer to the analogous means for model 2 than to the estimated population means for model 1 in Table 11.2. Model 2 has the more reasonably shaped lognormal distribution for these coefficients and obtains a considerably better fit than model 1. The conditioning in model 1 appears to be moving the coefficients closer to the values in the better-specified model 2 and away from its own misspecified population distributions. This is an example of how a comparison of the estimated population distribution with the sample average of the conditional distribution can reveal information about specification and estimation.

The standard deviations in Table 11.4 are larger than those in Table 11.3. This difference is due to the fact that the sampling variance in the estimated population parameters is included in the calculations for Table 11.4 but not for Table 11.3. The larger standard deviations do not mean that the portion of total variance in  $\beta_n$  that is captured by variation in  $\bar{\beta}_n$  is larger when the sampling distribution is considered than when not.

Useful marketing information can be obtained by examining the  $\bar{\beta}_n$  of each customer. The value of this information for targeted marketing has been emphasized by Rossi et al. (1996). Table 11.5 gives the calculated  $\bar{\beta}_n$  for the first three customers in the data set, along with the population mean of  $\beta_n$ .

The first customer wants to enter a long-term contract, compared with the vast majority of customers who dislike long-term contracts. He is willing to pay a higher energy price if the price is guaranteed through a long-term contract. He evaluates TOD and seasonal rates very generously, as if all of his consumption were in the lowest-priced period (note that the lowest price under TOD rates is 5 cents per kWh and the lowest price under seasonal rates is 6 cents per kWh.) That