

# Vector Network Coding Gap Sizes for the Generalized Combination Network

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# Outline

- 1 Motivation
- 2 What is Network Coding?
  - Initial Idea
  - Network as Matrix Channel
  - Generalized Combination Network
  - Introduction of Gap
- 3 Combinatorial Results
  - $(\epsilon = 1, \ell = 1) - \mathcal{N}_{h=3, r, s=4}$  Network
  - $(\epsilon = 1, \ell = 1) - \mathcal{N}_{h, r, s}$  Network
  - $(\epsilon = 1, \ell \geq 2) - \mathcal{N}_{h=2\ell, r, s=2\ell+1}$  Network
- 4 Computational Results
  - $(\epsilon = 1, \ell = 1) - \mathcal{N}_{h=3, r, s=4}$  Network
- 5 Conclusions

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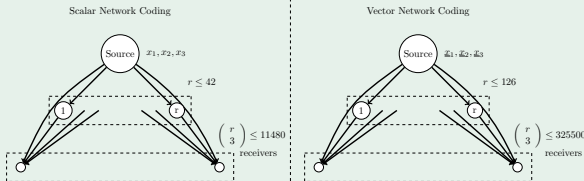
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# Motivation

- General vector solutions for the Generalized Combination Network was not found.

## Example (A multicast network with 3 messages)

Figure 1: Vector Network Coding Outperforms Scalar Network Coding



⇒ Vector Network Coding provides a higher number of receivers.

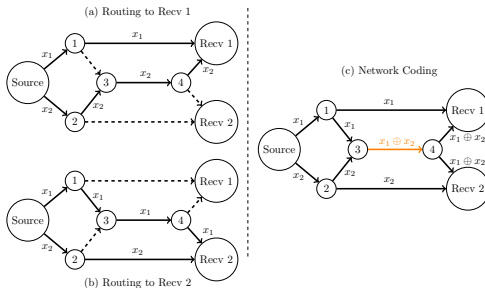
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## Initial Idea

- *Network coding* was first introduced in Ahlswede et al.'s seminal paper [1] with the well-known butterfly network.

Figure 2: The butterfly network



⇒ Network coding gives a potential gain in throughput by communicating more information with fewer packet transmissions compared to the routing method.

# Network as Matrix Channel

- In our study, we formulate networks as matrix channels.

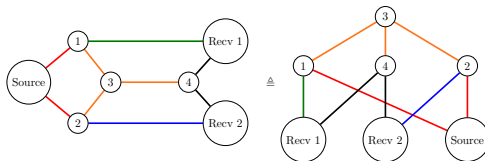
$$\begin{array}{c|c}
 \text{Scalar} & \text{Vector} \\
 \hline
 \underbrace{\begin{bmatrix} y_{j_1} \\ \vdots \\ y_{j_s} \end{bmatrix}}_{\mathbb{F}_{q_s}^s} = \underbrace{\mathbf{A}_j}_{\mathbb{F}_{q_s}^{s \times h}} \cdot \underbrace{\begin{bmatrix} x_1 \\ \vdots \\ x_h \end{bmatrix}}_{\mathbb{F}_{q_s}^h} & \underbrace{\begin{bmatrix} \mathbf{y}_{j_1} \\ \vdots \\ \mathbf{y}_{j_s} \end{bmatrix}}_{\mathbb{F}_q^{st}} = \underbrace{\mathbf{A}_j}_{\mathbb{F}_q^{st \times th}} \cdot \underbrace{\begin{bmatrix} \mathbf{x}_1 \\ \vdots \\ \mathbf{x}_h \end{bmatrix}}_{\mathbb{F}_q^{th}}
 \end{array} \quad (1)$$

$$\begin{array}{c|c}
 \text{Scalar} & \text{Vector} \\
 \hline
 \mathbf{A}_j = \begin{bmatrix} \mathbf{a}_{j_1} \\ \vdots \\ \mathbf{a}_{j_{\alpha\ell}} \\ \vdots \\ \mathbf{a}_{j_{\alpha\ell+\epsilon}} \end{bmatrix} & \mathbf{A}_j = \begin{bmatrix} \mathbf{A}_{j_1} \\ \vdots \\ \mathbf{A}_{j_{\alpha\ell}} \\ \vdots \\ \mathbf{A}_{j_{\alpha\ell+\epsilon}} \end{bmatrix}
 \end{array}$$

# Generalized Combination Network

- We choose to use the Generalized Combination Network to analyze its network coding problems. The well-known butterfly network is isomorphic to  $\mathcal{N}_{h,r=3,s=2}$ , if we consider it as an undirected network [2]

Figure 3: The butterfly network is represented as a combination network

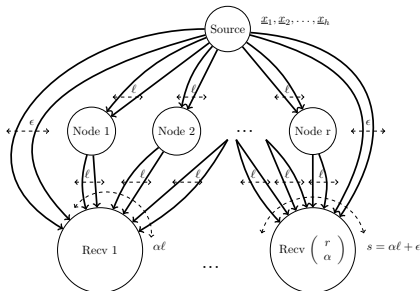




## Generalized Combination Network [cont.]

- A generalized combination network  $(\epsilon, \ell) - \mathcal{N}_{h,r,s}$  consists of 3 components over 3 layers from top to bottom: “Source” in the first layer, “Intermediate Nodes” in the middle layer, and “Receiver” in the third layer.

Figure 4: The generalized network  $(\epsilon, \ell) - \mathcal{N}_{h,r,s}$



# Generalized Combination Network [cont.]

Table 1: Parameters of network coding

$h$	The number of source messages
$r$	The number of nodes in the middle layer
$\binom{r}{\alpha}$	The number of receivers
$\ell$	The source connects to each node by $\ell$ parallel links, and each node also connects to one receiver by $\ell$ parallel links
$\alpha$	A receiver is connected by any $\alpha$ nodes in the middle layer
$\epsilon$	The source additionally connects to each receiver by $\epsilon$ direct parallel links
$s$	Each receiver is connected by $s$ links in total, with $s = \alpha\ell + \epsilon$ .

# Introduction of Gap

- The gap represents the difference between the smallest field (alphabet) size for which a scalar linear solution exists and the smallest alphabet size for which we can construct a vector solution.
- $r_{\max, \text{vector}} \geq f_1(q, t, \alpha, h)$ , with  $f_1 : \mathbb{Z} \mapsto \mathbb{Z}$
- $r_{\text{scalar}} \leq f_2(q_s)$ , with  $f_2 : \mathbb{Z} \mapsto \mathbb{Z}$
- $r_{\max, \text{scalar}} = f_2(q_s) = f_1(q, t, \alpha, h) = \min \{r_{\max, \text{vector}}\}$ . Finally, we calculate the gap by  $g = q_s - q_v = q_s - q^t$ .

# Introduction of Gap [cont.]

Table 2: New gap found in this study

Network	Gap Bounds for a specific vector solution [3]	This study proves an existence of these gaps
$(\epsilon = 0, \ell = 1) - \mathcal{N}_{h,r,s}$	N/A	N/A
$(\epsilon \geq 1, \ell = 1) - \mathcal{N}_{h,r,s}$	Unknown	$q^{\frac{\alpha-h+1}{(\alpha-1)(\alpha-h+2)(h-2)}t^2 + \mathcal{O}(t)}$ (*)
$(\epsilon = 1, \ell \geq 2) - \mathcal{N}_{h=2\ell, r, s=2\ell+1}$	$q^{t^2/2 + \mathcal{O}(t)}$	$q^{t^2/4 + \mathcal{O}(t)}$
$(\epsilon = \ell - 1, \ell) - \mathcal{N}_{h=2\ell, r, s=3\ell-1}$	$q^{t^2/2 + \mathcal{O}(t)}$	N/A

(\*): We only consider the  $(\epsilon = 1, \ell = 1) - \mathcal{N}_{h,r,s}$  network.

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# $(\epsilon = 1, \ell = 1) - \mathcal{N}_{h=3,r,s=4}$ Network

## Lemma (Symmetric Lovász local lemma (LLL) [4])

*A set of events  $\mathcal{E}_i$ , with  $i = 1, \dots, n$ , such that each event occurs with probability at most  $p$ . If each event is independent of all others except for at most  $d$  of them and  $4dp \leq 1$ , then:*

$$Pr \left[ \bigcap_{i=1}^n \bar{\mathcal{E}}_i \right] > 0.$$

# $(\epsilon = 1, \ell = 1) - \mathcal{N}_{h=3,r,s=4}$ Network [cont.]

## Lemma

Let  $Pr[\mathcal{E}_i] = Pr \left[ rk \begin{bmatrix} \mathbf{A}_j^{(r_1)} \\ \mathbf{A}_j^{(r_2)} \\ \mathbf{A}_j^{(r_3)} \end{bmatrix} < 2t \right] \leq p, \forall 1 \leq r_1 < r_2 < r_3 \leq r$ , and  $\mathbf{A}_j^{(r_1)}, \dots, \mathbf{A}_j^{(r_3)} \in \mathbb{F}_q^{t \times 3t}$ , then,

$$p \leq \Theta \left( q^{-t^2 - 2t - 1} \right), \forall t \geq 2.$$

## Lemma

Let  $Pr[\mathcal{E}_i] = Pr \left[ rk \begin{bmatrix} \mathbf{A}_j^{(r_1)} \\ \mathbf{A}_j^{(r_2)} \\ \mathbf{A}_j^{(r_3)} \end{bmatrix} < 2t \right] \leq p, \forall 1 \leq r_1 < r_2 < r_3 \leq r$  with  $\mathbf{A}_j^{(r_1)}, \dots, \mathbf{A}_j^{(r_3)} \in \mathbb{F}_q^{t \times 3t}$ , and each event  $\mathcal{E}_i$  is independent of all others except for at most  $d$  of them, then  $d \leq \frac{3}{2}r^2$ .

# $(\epsilon = 1, \ell = 1) - \mathcal{N}_{h=3,r,s=4}$ Network [cont.]

## Theorem

*If  $r \leq \Omega\left(q^{t^2/2+\mathcal{O}(t)}\right)$ , then there exists a vector solution for the  $(\epsilon = 1, \ell = 1) - \mathcal{N}_{h=3,r,s=4}$  network.*

## Corollary

*The  $(\epsilon = 1, \ell = 1) - \mathcal{N}_{h=3,r,s=4}$  network has a vector solution with a gap  $q^{t^2/4+\mathcal{O}(t)}$ .*



# $(\epsilon = 1, \ell = 1) - \mathcal{N}_{h,r,s}$ Network

- Item 1
- Item 2
- Item 3

# $(\epsilon = 1, \ell \geq 2) - \mathcal{N}_{h=2\ell, r, s=2\ell+1}$ Network

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# $(\epsilon = 1, \ell = 1) - \mathcal{N}_{h=3,r,s=4}$ Network

Table 3:  $r$  over variations of  $t$

t	Scalar Solution	Vector Solution
1	$r_{scalar} \leq 14$	$r_{vector} \geq 3$
2	$r_{scalar} \leq 42$	$r_{vector} \geq 7$ (67*, 89**)
3	$r_{scalar} \leq 146$	$r_{vector} \geq 62$ (166*)
4	$r_{scalar} \leq 546$	$r_{vector} \geq 1317$
5	$r_{scalar} \leq 2114$	$r_{vector} \geq 58472$
6	$r_{scalar} \leq 8322$	$r_{vector} > 10^6$

\*, \*\*: computational results in construction 1 and construction 2 respectively

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## Conclusions and Outlook

- If  $r \leq \Omega \left( q^{t^2/2 + \mathcal{O}(t)} \right)$ , there always exists a vector solution for the  $(\epsilon = 1, \ell = 1) - \mathcal{N}_{h=3, r, s=4}$  network.
- The general gap  $g = q^{t^2/4 + \mathcal{O}(t)}$  can be achieved for the  $(\epsilon = 1, \ell = 1) - \mathcal{N}_{h=3, r, s=4}$  network
- For the  $(\epsilon = 1, \ell = 1) - \mathcal{N}_{h=3, r, s=4}$  network. Similarly we derived the gaps for the  $(\epsilon = 1, \ell = 1) - \mathcal{N}_{h, r, s}$  network and the  $(\epsilon = 1, \ell > 1) - \mathcal{N}_{h=2\ell, r, s=2\ell+1}$  network, respectively with  $g = q^{\frac{\alpha-h+1}{(\alpha-1)(\alpha-h+2)(h-2)} t^2 + \mathcal{O}(t)}$  and  $g = q^{t^2/2\ell + \mathcal{O}(t)}$ .
- An improved bound  $89 \leq \mathcal{A}_2(6, 4, 3; 2) \leq 126$ .
- A new bound  $166 \leq \mathcal{A}_2(9, 6, 3; 2) \leq 537$ .

# Thank you! Questions?

## References:

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