State dependent wild turkey brood habitat selection and recursive movement metadata

ID = collar number for individual

sl\_ = step length

ta\_ = turn angle

coords.x1 = UTM Easting

coords.x2 = UTM Northing

revisits = number of revisits to the GPS location

residence time = hours spent at GPS location

avg\_time\_between = days between last visit to GPS location

date = date GPS location was taken

day = day individual was brooding

state = behavioral state individual was in (1 and 2 = foraging, 3 = walking, 4 = roosting)

yr = year the individual was captured

step\_id\_ = identification of the step

case\_ = identification of the used and unused location (TRUE = used, FALSE = unused)

residence\_raster\_walking = residence time in area while walking

revisit\_raster\_walking = number of revisits back to the location while walking

residence\_raster\_foraging = residence time in area while foraging

revisit\_raster\_foraging = number of revisits back to the location while foraging

residence\_raster\_roosting = residence time in area while roosting

revisit\_raster\_roosting = number of revisits back to the location while roosting

proads = distance to primary roads

sroads = distance to secondary roads

dist\_hw = distance to hardwoods

dist\_infra = distance to infrastructure

dist\_mixed = distance to mixed pine hardwood

dist\_open = distance to open areas

dist\_pine = distance to pine

dist\_shrub = distance to shrubland

dist\_water = distane to water

ndvi = normalized difference vegetation index

cos\_ta\_ = cosine of turn angle

log\_sl\_ = log of the step length